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Smoothness of Directed Chain Stochastic Differential Equations and its Applications

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1 Introduction

On a filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$, we shall consider the following system of stochastic differential equations for a pair $(X^\theta, \tilde{X}^\theta)$ of N -dimensional stochastic processes:

$$X_t^\theta = \theta + \int_0^t V_0(s, X_s^\theta, \text{Law}(X_s^\theta), \tilde{X}_s) ds + \sum_{i=1}^d \int_0^t V_i(s, X_s^\theta, \text{Law}(X_s^\theta), \tilde{X}_s) dB_s^i \quad (1)$$

for $t \geq 0$ with the distributional constraint

$$[X_t^\theta, t \geq 0] := \text{Law}(X_t^\theta, t \geq 0) = \text{Law}(\tilde{X}_t, t \geq 0) =: [\tilde{X}_t, t \geq 0], \quad (2)$$

where $V_i : [0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N \rightarrow \mathbb{R}^N$, $i = 0, 1, \dots, d$ are some smooth coefficients, $B := (B^1, \dots, B^d)$ is the standard d -dimensional Brownian motion. We assume the initial value $\theta \in \mathcal{P}_2(\mathbb{R}^N)$ is independent of B and \tilde{X}_0 , and \tilde{X}_0 is independent of B . Here, $\mathcal{P}_2(\mathbb{R}^N)$ is the set of probability measures on \mathbb{R}^N with finite second moments. We equip $\mathcal{P}_2(\mathbb{R}^N)$ with the 2-Wasserstein metric, W_2 . For a general metric space (M, d) , we define the 2-Wasserstein metric on $\mathcal{P}_2(M)$ by $W_2(\mu, \nu) := \inf_{\Pi \in \mathcal{P}_{\mu, \nu}} (\int_{M \times M} d^2(x, y) \Pi(dx, dy))^{1/2}$, where $\mathcal{P}_{\mu, \nu}$ denotes the class of probability measures on $M \times M$ with marginals μ and ν . Note that the law $[X^\theta]$ of X^θ depends on the law $[\tilde{X}]$ of \tilde{X} and they are the same marginal law. Setting $B_t^0 \equiv t$, $t \geq 0$, the above equation is rewritten as

$$X_t^\theta = \theta + \sum_{i=0}^d \int_0^t V_i(s, X_s^\theta, [X_s^\theta], \tilde{X}_s) dB_s^i; \quad t \geq 0, \quad (3)$$

$$[\tilde{X}_t, t \geq 0] = \text{Law}(\tilde{X}_t, t \geq 0) = \text{Law}(X_t^\theta, t \geq 0) = [X_t^\theta, t \geq 0].$$

We call the system (1) with the constraint (2) the system of *directed chain stochastic differential equation*.

For example, with $N = 1$, $u \in [0, 1]$, and some smooth functions $b_{0,i} : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, for $i = 0, 1, \dots, d$, we define the coefficients

$$V_i(t, x, \mu, y) := u b_{0,i}(t, x, y) + (1 - u) \int_{\mathbb{R}} b_{0,i}(t, x, z) d\mu(z)$$

as a linear combination of two terms. When $u = 0$, the equation becomes a McKean-Vlasov equation; When $u = 1$, there is no contribution from the distribution $[X^\theta]$.

Proposition 1 (Uniqueness of weak solution). *Let $\mu_0 \in \mathcal{P}_2(\mathbb{R}^N)$ be a fixed reference measure. Suppose that V_i , $i = 0, 1, \dots, d$ are Lipschitz continuous and grow at most linearly in the sense that for every $T > 0$, there exists a constant c_T such that for every $0 \leq t \leq T$, $x_1, y_1, x, y \in \mathbb{R}^N$, $\mu_1, \mu_2 \in \mathcal{P}_2(\mathbb{R}^N)$,*

$$\sup_i |V_i(t, x_1, \mu_1, y_1) - V_i(t, x_2, \mu_2, y_2)| \leq c_T (|x_1 - x_2| + |y_1 - y_2| + W_2(\mu_1, \mu_2)), \quad (4)$$

$$\sup_i \sup_{0 \leq t \leq T} |V_i(t, x, \mu, y)| \leq c_T (1 + |x| + |y| + W_2(\mu, \mu_0)). \quad (5)$$

Then there exists a unique weak solution (X^θ, \tilde{X}, B) $(\Omega, \mathcal{F}, (\mathcal{F}_t), \mathbb{P})$ to the system (1) of stochastic differential equations with the distributional constraint (2).

The analysis of the special case with $N = d = 1$, $V_1 \equiv 1$ is considered in [DFI]. The name, directed chain, is coined from the fact that the joint distribution of (X^θ, \tilde{X}) in (1) can be approximated by the limit of the joint distribution of (X^1, X^2) from a finite particle system on the vertexes $i = 1, \dots, n$, where the process X^i at vertex i depends on X^{i+1} at vertex $i + 1$ via the equation $dX_t^i = V_0(t, X_t^i, \bar{\mu}_t, X_t^{i+1})dt + dB^i(t)$ with the empirical measure $\bar{\mu}_t := n^{-1} \sum_{i=1}^n \delta_{X_t^i}$ of the particle system for $i = 1, \dots, n - 1$ and $dX_t^n = V_0(t, X_t^n, \bar{\mu}_t, X_t^1)dt + dB^n(t)$, $t \geq 0$. Here, δ_x is the Dirac measure at the point x . Under some reasonable assumptions, the joint distribution of (X^1, X^2) converges weakly to that of (X^θ, \tilde{X}) in (1), as $n \rightarrow \infty$.

The motivation of studying (1) comes from the interacting particles of sparse network [2], [10], [16] as well as the mean field games [5], [7], [11], [13], [18], particularly on the infinite random graph. In this short note, we discuss the smoothness of the joint distribution. Smoothness of solution to MCKEAN-VLASOV equation has been studied by [1], [8], [9].

2 Smoothness

2.1 LION'S DERIVATIVES IN THE WASSERSTEIN SPACE \mathcal{P}_2

Let us recall the Wasserstein distance between two measures $\mu, \nu \in \mathcal{P}_2(\mathbb{R})$ is written as

$$W_2(\mu, \nu) := \inf\{\|X - Y\|_2 : [X] = \mu, [Y] = \nu\}.$$

For a function $u : \mathcal{P}_2 \rightarrow \mathbb{R}$, we denote by U “extension” (or lift) to $L^2(\Omega', \mathcal{F}', \mathbb{P}')$ defined by

$$U(X) = u(\text{Law}(X)), \quad \text{Law}(X) = [X] = \mu.$$

Here, $(\Omega', \mathcal{F}', \mathbb{P}')$ is an atomless Polish space. Following [6], we say u is differentiable at $[X] \in \mathcal{P}$, if there exists X' such that $[X'] = [X]$ and the lift U is Fréchet differentiable at X' .

For example, when $u : \mathcal{P}_2(\mathbb{R}^N) \rightarrow \mathbb{R}$ is given by

$$u(\mu) := \prod_{i=1}^n \int_{\mathbb{R}^N} \varphi_i(x) d\mu(x)$$

for some smooth functions $\varphi_i \in C_c^\infty(\mathbb{R}^N)$, then $U(X)$ and its gradient $\mathcal{D}U(X)$ are given by

$$U(X) := \prod_{i=1}^n \mathbb{E}[\varphi_i(X)]; \quad [X] = \mu, \quad \mathcal{D}U(X) = \sum_{i=1}^n \left(\prod_{j \neq i} \mathbb{E}[\varphi_j(X)] \right) D\varphi_i(X),$$

and hence, for every $v \in \mathbb{R}^N$, $\mu \in \mathcal{P}_2(\mathbb{R}^N)$,

$$\mathcal{D}_\mu u(\mu)(v) = \sum_{i=1}^n \left(\prod_{j \neq i} \int_{\mathbb{R}^N} \varphi_j(z) d\mu(z) \right) D\varphi_i(v),$$

which does not depend on the random vector X .

2.2 Smoothness of coefficients

We say $V : \mathbb{R}_+ \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N \rightarrow \mathbb{R}^N$ belongs to $\mathcal{C}_{b, \text{Lip}}^{1,1,1}$, if each component V^i of $V = (V^1, \dots, V^N)$ has bounded, Lipschitz continuous derivatives $\partial_x V^i$, $\tilde{\partial} V^i$ in the second and fourth variables, respectively, in the sense of P.L. LIONS [6] with at most linear growth property, i.e., there exists a constant $c > 0$ such that

$$|\partial_x V^i(t, x, \mu, y, v)| + |\tilde{\partial} V^i(t, x, \mu, y, v)| + |\partial_\mu V^i(t, x, \mu, y, v)| \leq c,$$

$$|\partial_\mu V^i(t, x, \mu, y, v) - \partial_\mu V^i(t, x', \mu', y', v)| \leq c(|x - x'| + |y - y'| + |v - v'| + W_2(\mu, \mu'))$$

for $(t, x, \mu, y, v), (t, x', \mu', y', v') \in [0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N$. Moreover, we say V belongs to $\mathcal{C}_{b, \text{Lip}}^{k, k, k}$, if it has bounded, Lipschitz, k times derivatives $\partial_x^\gamma \partial_v^\beta \partial_\mu^\alpha V^i$ in multi-indexes $(\alpha, \beta, \gamma, \tilde{\gamma})$, $|\alpha| + |\beta| + |\gamma| + |\tilde{\gamma}| \leq k$ with at most linear growth property.

Now we consider the pathwise-unique, strong solution to auxiliary stochastic equation

$$X_t^{x, [\theta]} = x + \sum_{i=0}^d \int_0^t V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s) dB_s^i, \quad (6)$$

given the solution pair (X^θ, \tilde{X}) in (1). More specifically, we set $\tilde{X}_0 =: \tilde{\theta}$ and

$$X_t^{x, [\theta], \tilde{\theta}} = x + \sum_{i=0}^d \int_0^t V_i(s, X_s^{x, [\theta], \tilde{\theta}}, [X_s^\theta], \tilde{X}_s) dB_s^i. \quad (7)$$

Then by the pathwise uniqueness, we have $X_s^{x, [\theta], \tilde{\theta}}|_{x=\theta} = X_s^\theta; 0 \leq s \leq T$.

2.3 Flow property

For different initial points $x, x' \in \mathbb{R}^N$, the corresponding solutions $X^{x, [\theta], \tilde{\theta}}$ and $X^{x', [\theta], \tilde{\theta}}$ in (7) satisfy that for every $T > 0$, there exists a constant $c_T > 0$ such that

$$\mathbb{E}[\sup_{t \leq s \leq T} |X^{x, [\theta], \tilde{\theta}} - X^{x', [\theta], \tilde{\theta}}|^2] \leq c_T |x - x'|^2$$

by Lipschitz continuity and Burkholder-Davis-Gundy inequality. With a slightly abuse of notation, we write $X^{t, x, [\theta], \tilde{\theta}}$ for the process $X^{x, [\theta], \tilde{\theta}}$ with $X_t^{t, [\theta], \tilde{\theta}} = x$, and $(X^{t, \theta}, \tilde{X}^{t, \tilde{\theta}})$ for the process $(X^\cdot, \tilde{X}^\cdot)$ with $(X_t^{t, \theta}, \tilde{X}_t^{t, \tilde{\theta}}) = (\theta, \tilde{\theta})$, we have the flow property

$$(X_r^{x, X_s^{t, x, [\theta], \tilde{\theta}}, [X_s^{t, \theta}], \tilde{X}_s^{t, \tilde{\theta}}}, X_r^{x, X_s^{t, \theta}}, \tilde{X}_r^{x, \tilde{X}_s^{t, \tilde{\theta}}}) = (X_r^{t, x, [\theta], \theta}, X_r^{t, \theta}, \tilde{X}_r^{t, \tilde{\theta}}); \quad 0 \leq t \leq s \leq r \leq T.$$

2.4 Partial Malliavin Calculus

Let us consider the Malliavin derivative operator D and its adjoint operator δ . Let σ be the $N \times d$ matrix with columns V_1, \dots, V_d . If there is **no** interaction with the neighborhood process \tilde{X} , the McKean-Vlasov equation in (6) has the derivative

$$\partial_x X_t^{x, [\theta]} = D_r X_t^{x, [\theta]} \sigma^\top (\sigma \sigma^\top)^{-1} (r, X_r^{x, [\theta]}, [X_r^\theta]) \partial_x X_r^{x, [\theta]}; \quad r \leq t,$$

however, because of the interaction with \tilde{X} , in general,

$$\partial_x X_t^{x, [\theta]} \neq D_r X_t^{x, [\theta]} \sigma^\top (\sigma \sigma^\top)^{-1} (r, X_r^{x, [\theta]}, [X_r^\theta], \tilde{X}_r) \partial_x X_r^{x, [\theta]}; \quad r \leq t,$$

To overcome this difficulty, we shall apply the following partial Malliavin derivatives from [15], [19].

Let us take the rational numbers $\mathbb{Q}_T := \mathbb{Q} \cap [0, T]$ in $[0, T]$ and define the σ -field $\mathcal{G} := \sigma(\{\tilde{X}_t, t \in \mathbb{Q}_T\})$ (countably generated) and the family of subspaces defined by the orthogonal complement

$$K(\omega) := \langle D \tilde{X}_t(\omega), t \in \mathbb{Q}_T \rangle^\perp$$

to the subspace generated by $\{D\tilde{X}_t(\omega), t \in \mathbb{Q}_T\}$. Then the family $\mathcal{H} := \{K(\omega), \omega \in \Omega\}$ has a measurable projection. We define the partial derivative operator $D^{\mathcal{H}} : \mathbb{D}^{1,2} \rightarrow L^2(\Omega, \mathcal{H})$, namely, for $F \in \mathbb{D}^{1,2}$, $D^{\mathcal{H}}F = \text{Proj}_{\mathcal{H}}(DF) = \text{Proj}_{K(\omega)}(DF)(\omega)$ with associated norm

$$\|F\|_{\mathbb{D}_{\mathcal{H}}^{k,p}} := (\mathbb{E}[|F|^p])^{1/p} + \sum_{j=1}^k \mathbb{E}[\|D^{\mathcal{H},(j)}F\|_{\mathcal{H}}^p]^{1/p},$$

where $D^{(j)}$ is the j -th order derivative and $D^{\mathcal{H},(j)}F := \text{Proj}_{\mathcal{H}}(D^{(j)}F) = \text{Proj}_{K(\omega)}(D^{(j)}F)(\omega)$.

Similar to the Malliavin calculus, there is an adjoint operator $\delta_{\mathcal{H}}(u) := \delta(\text{Proj}_{\mathcal{H}}(u))$ of $D^{\mathcal{H}}$ if $\text{Proj}_{\mathcal{H}}u \in \text{Dom}(\delta)$, as well as the integration by parts formula $\mathbb{E}[\langle u, D^{\mathcal{H}}F \rangle] = \mathbb{E}[\langle \text{Proj}_{\mathcal{H}}u, DF \rangle] = \mathbb{E}[F \delta_{\mathcal{H}}u]$ for any $u \in \text{Dom}(\delta_{\mathcal{H}})$, $F \in \mathbb{D}^{1,2}$.

Let E be a separable Hilbert space. For $r \in \mathbb{R}, q, M \in \mathbb{N}$ let us define the family $\mathbb{K}_r^q(E, M)$ of processes $\Psi : [0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \rightarrow \mathbb{D}^{M, \infty}(E)$ satisfying the following:

$$(t, x, [\theta]) \mapsto \partial_x^\gamma \partial_v^\beta \partial_\mu^\alpha \Psi(t, x, [\theta], v) \in L^p(\Omega)$$

exists and continuous for all $p \geq 1$ and multi-indexes (α, β, γ) with $|\alpha| + |\beta| + |\gamma| \leq M$, and

$$\sup_{v \in (\mathbb{R}^N)^{\#\beta}} \sup_{t \in [0, T]} \frac{1}{t^{r/2}} \|\partial_x^\gamma \partial_v^\beta \partial_\mu^\alpha \Psi(t, x, [\theta], v)\|_{\mathbb{D}_{\mathcal{H}}^{m,p}(E)} \leq C(1 + |x| + \|\theta\|_2)^q$$

for every $p \geq 1$, $m \in \mathbb{N}$ and multi-indexes (α, β, γ) with $|\alpha| + |\beta| + |\gamma| + m \leq M$. This is a modification of \mathbb{K}_r^q in [9] for the smoothness of the density function of $X^{x, [\theta]}$.

Proposition 2. Assume $V_i \in C_{b, \text{Lip}}^{1,1,1}(\mathbb{R}_+ \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N; \mathbb{R}^N)$. There exists a modification of $X^{x, [\theta]}$ such that the map $x \mapsto X_t^{x, [\theta]}$ is almost surely differentiable, and for $t \geq 0$,

$$\partial_x X_t^{x, \theta} = Id_N + \sum_{i=0}^d \int_0^t \partial V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s) \partial_x X_s^{x, [\theta]} dB_s^i.$$

The maps $\theta \mapsto X_t^\theta$, $\theta \mapsto X_t^{x, [\theta]}$ are Fréchet differentiable in $L^2(\Omega)$ with gradients $\mathcal{D}X_t^{x, [\theta]}$ and $\mathcal{D}X_t^{x, [\theta]}$ satisfying

$$\mathcal{D}X_t^{x, [\theta]}(\gamma) = \sum_{i=0}^d \int_0^t [\partial V_i \mathcal{D}X_s^{x, [\theta]} + \tilde{\partial} V_i \mathcal{D}\tilde{X}_s(\gamma) + \mathcal{D}V_i'(\mathcal{D}X_s^\theta(\gamma))] dB_s^i,$$

$$\mathcal{D}X_t^\theta(\gamma) = \gamma + \sum_{i=0}^d \int_0^t [\partial V_i \mathcal{D}X_s^\theta(\gamma) + \tilde{\partial} V_i \mathcal{D}\tilde{X}_s(\gamma) + \mathcal{D}V_i'(\mathcal{D}X_s^\theta(\gamma))] dB_s^i,$$

for $\gamma \in L^2(\Omega)$, $t \geq 0$.

Moreover, the map $[\theta] \mapsto X_t^{x, [\theta]}$ is differentiable with the derivative $\partial_\mu X_t^{x, [\theta]}$ satisfying

$$\begin{aligned} \partial_\mu X_t^{x, [\theta]}(v) &= \sum_{i=0}^d \int_0^t \left\{ \partial V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s) \partial_\mu X_s^{x, [\theta]}(v) \right. \\ &\quad + \tilde{\partial} V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s) \partial_\mu \tilde{X}_s(v) \\ &\quad + \mathbb{E}' \left[\partial_\mu V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s, (X_s^{v, [\theta]})') \partial_x (X_s^{v, [\theta]})' \right] \\ &\quad \left. + \mathbb{E}' \left[\partial_\mu V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s, (X_s^{\theta'})') \partial_\mu (X_s^{\theta', [\theta]})'(v) \right] \right\} dB_s^i, \end{aligned}$$

where $(X_s^{\theta'})'$ is a copy of X_s^θ , $\partial_x(X_s^{v, [\theta]})'$ is a copy of $\partial_x X_s^{v, [\theta]}$ and $\partial_\mu(X_s^{\theta', [\theta]})' = \partial_\mu(X_s^{x, [\theta]})'_{x=\theta'}$ on a probability space with $\mathcal{D}X_t^{x, [\theta]}(\gamma) = \mathbb{E}'[\partial_\mu X_t^{x, [\theta]}(\theta')\gamma']$. Furthermore, $X_t^{x, [\theta]}, X_t^\theta \in \mathbb{D}^{1, \infty}$, and $D_r^{\mathcal{H}} X_t^{x, [\theta]} = (D_r^{\mathcal{H}, j}(X_t^{x, [\theta]})^i)_{1 \leq j \leq N, 1 \leq i \leq d}$ satisfies, for $0 \leq r \leq t$

$$D_r^{\mathcal{H}} X_t^{x, [\theta]} = \sigma(r, X_r^{x, [\theta]}, [X_r^\theta], \tilde{X}_r) + \sum_{i=0}^d \int_r^t \left(\partial V_i(s, X_s^{x, [\theta]}, [X_s^\theta], \tilde{X}_s) D_r^{\mathcal{H}} X_s^{x, [\theta]} \right) dB_s^i,$$

where $\sigma(r, X_r^{x, [\theta]}, [X_r^\theta], \tilde{X}_r)$ is the $N \times d$ matrix with columns V_1, \dots, V_d .

2.5 Characterization of the auxiliary process

Assume $V_i \in C_{b, \text{Lip}}^{k, k, k}([0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N; \mathbb{R}^N)$ for $i = 1, \dots, d$. Then the map satisfies

$$(t, x, [\theta]) \mapsto X_t^{x, [\theta]} \in \mathbb{K}_0^1(\mathbb{R}^N, k).$$

If, in addition, V_i are uniformly bounded, then $(t, x, [\theta]) \mapsto X_t^{x, [\theta]} \in \mathbb{K}_0^0(\mathbb{R}^N, k)$. Proof is based on the first order derivatives (cf. [9]).

Now we define operators $I_{(i)}^j$, $j = 1, 2, 3$, $\mathcal{I}_{(i)}^1$, $\mathcal{I}_{(i)}^3$ on $\Psi \in \mathbb{K}_r^q(\mathbb{R}, n)$ with $\alpha = (i)$, $(t, x, [\theta]) \in [0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N)$,

$$\begin{aligned} I_{(i)}^1(\Psi)(t, x, [\theta]) &:= \frac{1}{\sqrt{t}} \delta_{\mathcal{H}}(r \mapsto \Psi(t, x, [\theta]) (\sigma^\top (\sigma \sigma^\top)^{-1}(r, X_r^{x, \theta}, [X_r^\theta], \tilde{X}_r) \partial_x X_r^{x, \mu})_i), \\ I_{(i)}^2(\Psi)(t, x, [\theta]) &:= \sum_{j=1}^N I_{(j)}^1((\partial_x X_t^{x, \mu})_{j, i}^{-1} \Psi(t, x, [\theta])), \\ I_{(i)}^3(\Psi)(t, x, [\theta]) &:= I_{(i)}^1(\Psi)(t, x, [\theta]) + \sqrt{t} \partial^i \Psi(t, x, [\theta]) \\ \mathcal{I}_{(i)}^1(\Psi)(t, x, [\theta], v_1) &:= \frac{1}{\sqrt{t}} \delta_{\mathcal{H}} \left(r \mapsto (\sigma^\top (\sigma \sigma^\top)^{-1}(r, X_r^{x, \mu}, [X_r^\theta], \tilde{X}_r), \right. \\ &\quad \left. \partial_x X_r^{x, \mu} (\partial_x X_t^{x, \mu})^{-1} \partial_\mu X_t^{x, [\theta]}(v_1)_i \Psi(t, x, [\theta]) \right), \\ \mathcal{I}_{(i)}^3(\Psi)(t, x, [\theta], v_1) &:= \mathcal{I}_{(i)}^1(\Psi)(t, x, [\theta], v_1) + \sqrt{t} (\partial_\mu \Psi)_i(t, x, [\theta], v_1). \end{aligned} \tag{8}$$

2.6 Integration-by-parts formulae

Assume $V_i \in C_{b, \text{Lip}}^{k, k, k}([0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N; \mathbb{R}^N)$ and also the uniform ellipticity of the diffusion coefficients. For $f \in C_b^\infty(\mathbb{R}^N, \mathbb{R})$, $\Psi \in \mathbb{K}_r^q(\mathbb{R}, n)$, we have

- If $|\alpha| \leq n \wedge k$, then

$$\mathbb{E}[\partial_x^\alpha (f(X_t^{x, [\theta]})) \Psi(t, x, [\theta])] = t^{-|\alpha|/2} \mathbb{E}[f(X_t^{x, [\theta]}) I_\alpha^1(\Psi)(t, x, [\theta])];$$

- If $|\alpha| \leq n \wedge (k - 2)$, then

$$\mathbb{E}[(\partial^\alpha f)(X_t^{x, [\theta]}) \Psi(t, x, [\theta])] = t^{-|\alpha|/2} \mathbb{E}[f(X_t^{x, [\theta]}) I_\alpha^2(\Psi)(t, x, [\theta])];$$

- If $|\alpha| \leq n \wedge k$, then

$$\partial_x^\alpha \mathbb{E}[f(X_t^{x, [\theta]}) \Psi(t, x, [\theta])] = t^{-|\alpha|/2} \mathbb{E}[f(X_t^{x, [\theta]}) I_\alpha^3(\Psi)(t, x, [\theta])];$$

- If $|\alpha| + |\beta| \leq n \wedge (k - 2)$, then

$$\partial_x^\alpha \mathbb{E}[(\partial^\beta f)(X_t^{x, [\theta]}) \Psi(t, x, [\theta])] = t^{-(|\alpha|+|\beta|)/2} \mathbb{E}[f(X_t^{x, [\theta]}) I_\alpha^3((I_\beta^2 \Psi))(t, x, [\theta])].$$

For $f \in C_b^\infty(\mathbb{R}^N, \mathbb{R})$ and $\Psi \in \mathbb{K}_r^q(\mathbb{R}, n)$, we have

- If $|\beta| \leq n \wedge (k-2)$, then

$$\mathbb{E}[\partial_\mu^\beta (f(X_t^{x, [\theta]}))(\mathbf{v}) \Psi(t, x, [\theta])] = t^{-|\beta|/2} \mathbb{E}[f(X_t^{x, [\theta]}) \mathcal{I}_\beta^1(\Psi)(t, x, [\theta], \mathbf{v})];$$

- If $|\beta| \leq n \wedge (k-2)$, then

$$\partial_\mu^\beta \mathbb{E}[f(X_t^{x, [\theta]}) \Psi(t, x, [\theta])](\mathbf{v}) = t^{-|\beta|/2} \mathbb{E}[f(X_t^{x, [\theta]}) \mathcal{I}_\beta^3(\Psi)(t, x, [\theta], \mathbf{v})];$$

- If $|\alpha| + |\beta| \leq n \wedge (k-2)$, then

$$\partial_\mu^\beta \mathbb{E}[(\partial^\alpha f)(X_t^{x, [\theta]}) \Psi(t, x, [\theta])](\mathbf{v}) = t^{-(|\alpha|+|\beta|)/2} \mathbb{E}\left[f(X_t^{x, [\theta]}) \mathcal{I}_\beta^3(I_\alpha^2(\Psi))(t, x, [\theta], \mathbf{v})\right].$$

For every $f \in C_k^\infty(\mathbb{R}^N; \mathbb{R})$, multi-index α on $\{1, \dots, N\}$ with $|\alpha| \leq k-2$,

$$\partial_x^\alpha \mathbb{E}[f(X_t^{x, \delta_x})] = \frac{1}{t^{|\alpha|/2}} \mathbb{E}[f(X_t^{x, \delta_x}) \cdot J_\alpha(1)(t, x)],$$

where δ_x is a Dirac point mass at $x \in \mathbb{R}^N$, and

$$J_{(i)}(\Phi)(t, x) := I_{(i)}^3(\Phi)(t, x, \delta_x) + \mathcal{I}_{(i)}^3(t, x, \delta_x); \quad t \geq 0$$

with $J_\alpha(\Phi) := J_{\alpha_n} \circ J_{\alpha_{n-1}} \circ \dots \circ J_{\alpha_1}(\Phi)$. Particularly, there exists a constant $c > 0$ such that

$$|\partial_x^\alpha \mathbb{E}[f(X_t^{x, \delta_x})]| \leq c \|f\|_\infty \cdot \frac{(1 + |x|)^{4|\alpha|}}{t^{|\alpha|/2}}$$

for $0 \leq t \leq T$, $x \in \mathbb{R}^N$. Moreover, with $|\alpha| + |\beta| \leq k-2$,

$$\partial_x^\alpha \mathbb{E}[(\partial^\beta f)(X_t^{x, \delta_x})] = \frac{1}{t^{\frac{|\alpha|+|\beta|}{2}}} \mathbb{E}[f(X_t^{x, \delta_x}) I_\beta^2(J_\alpha(1))(t, x)]$$

and $I_\beta^2(J_\alpha(1)) \in \mathbb{K}_0^{4|\alpha|+3|\beta|}(\mathbb{R}, k-2-|\alpha|-|\beta|)$. Thus, $X_t^{x, \delta_x} = X_t^\theta|_{\theta=x}$ has a probability density function $p(t, x, z)$ such that $(x, z) \mapsto \partial_x^\alpha \partial_z^\beta p(t, x, z)$ exists and is continuous.

2.7 Smoothness of the joint density

Proposition 3. *Let α, β be multi-indices on $\{1, \dots, N\}$ and $k \geq |\alpha| + |\beta| + N + 2$. Under these assumptions of the uniform ellipticity of σ and the smoothness of coefficients $V_i \in C_{b, \text{Lip}}^{k, k, k}$, the solution X_t^θ to the directed chain SDE (1) with $\theta \equiv x \in \mathbb{R}^N$ at time $t \geq 0$ has a density $p(t, x, \cdot)$ such that $(x, z) \mapsto \partial_x^\alpha \partial_z^\beta p(t, x, z)$ exist and is continuous. Moreover, there exists a constant C which depends on T, N and bounds on the coefficients, such that*

$$|\partial_x^\alpha \partial_z^\beta p(t, x, z)| \leq C(1 + |x|)^{4|\alpha|+3|\beta|+3N} t^{-(N+|\alpha|+|\beta|)/2} \quad (9)$$

for $t \in (0, T]$, $x, z \in \mathbb{R}^N$. Furthermore, if V_i , $i = 0, \dots, d$ are bounded, then

$$|\partial_x^\alpha \partial_z^\beta p(t, x, z)| \leq C t^{-(N+|\alpha|+|\beta|)/2} \exp\left(-\frac{C|x-z|^2}{t}\right) \quad (10)$$

for $t \in (0, T]$, $x, z \in \mathbb{R}^N$.

The above existence and smoothness results on the marginal density $p(t, x, z)$ of a single particle can be extended to the joint distribution of adjacent particles. That is, We extend the pair (X^θ, \tilde{X}) to consider the system $(\tilde{X}^0, \tilde{X}^1, \dots, \tilde{X}^m)$, such that the joint distribution of adjacent pair is determined by the directed chain stochastic differential equation 1, namely, $[\tilde{X}^{k-1}, \tilde{X}^k] = [X^\theta, \tilde{X}]$ for $k = 1, \dots, m$.

Corollary. *Under the same assumptions on the coefficients, the joint density of $(\tilde{X}_t^0, \tilde{X}_t^1, \dots, \tilde{X}_t^m)$ exists and is continuous for $t \geq 0$. Particularly, the joint density of (X^θ, \tilde{X}) exists and is continuous.*

The applications of the smoothness of the joint distribution are the recursive factorization of the first order Markov random field [16], some connection to a class of non-linear partial differential equations, smoothness of the filtering equation and the analysis of master equation of the mean-field game and the mean-field control problems on the directed chain graph.

2.8 Relation to PDE

Let us consider time-homogeneous coefficients. For the function $U(t, x, [\theta]) := \mathbb{E}[g(X_t^{x, [\theta]}, [X_t^\theta])]$, $t \in [0, T]$, $x \in \mathbb{R}^N$, by the flow property, we have

$$U(t+h, x, [\theta]) = \mathbb{E}[g(X_{t+h}^{x, [\theta]}, [X_{t+h}^\theta])] = \mathbb{E}[U(t, X_h^{x, [\theta]}, [X_h^\theta])]$$

for $t \geq 0$, $0 \leq t \leq T-h$. Then we come up with a PDE of the form

$$(\partial_t - \mathcal{L})U(t, x, [\theta]) = 0, \quad (t, x, [\theta]) \in (0, T] \times \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N),$$

$$U(0, x, [\theta]) = g(x, [\theta]), \quad (x, [\theta]) \in \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N),$$

for some function $g : \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \rightarrow \mathbb{R}$, where the operator \mathcal{L} acts on smooth enough functions $F : \mathbb{R}^N \times \mathcal{P}_2(\mathbb{R}^N) \times \mathbb{R}^N$ defined by

$$\begin{aligned} \mathcal{L}F(x, [\theta]) := & \mathbb{E} \left[\sum_{i=1}^N V_0^i(x, [\theta], \tilde{\theta}) \partial_{x_i} F(x, [\theta]) + \frac{1}{2} \sum_{i,j=1}^N [\sigma \sigma^\top(x, [\theta], \tilde{\theta})]_{i,j} \partial_{x_i} \partial_{x_j} F(x, [\theta]) \right] \\ & + \mathbb{E} \left[\sum_{i=1}^N V_0^i(\theta, [\theta], \tilde{\theta}) \partial_\mu F(x, [\theta], \theta)_i + \frac{1}{2} \sum_{i,j=1}^N [\sigma \sigma^\top(\theta, [\theta], \tilde{\theta})]_{i,j} \partial_{v_j} \partial_\mu F(x, [\theta], \theta)_i \right] \end{aligned} \quad (11)$$

cf. [4], [9] for MCKEAN-VLASOV SDE.

2.9 Relation to Mimicking problem

The mimicking problem is to obtain the marginal distribution of some non-Markovian process by a unique strong solution to the stochastic differential equation

$$dY_t = b_0(Y_t)dt + b_1(Y_t)dB^y(t); \quad t \geq 0, \quad Y_0 := \xi \quad (12)$$

for Y with some smooth functions $b_0 : \mathbb{R}^N \rightarrow \mathbb{R}^N$, $b_1 : \mathbb{R}^N \rightarrow \mathbb{R}^{N \times N}$. B^y is the n -dimensional standard Brownian motion. cf. [3], [12], [17].

Conversely, it follows from the smoothness of the solution in Proposition 3 that there exist (X, \tilde{X}) and functions V_i , $i = 0, 1$, such that (X_0, \tilde{X}_0) are independent and

$$[Y] = [X] = [\tilde{X}],$$

where the pair (X, \tilde{X}) satisfies the directed chain equation

$$dX_t = V_0(X_t, \tilde{X}_t)dt + V_1(X_t, \tilde{X}_t)dB_t; \quad t \geq 0, \quad (13)$$

driven by another standard Brownian motion B independent of \tilde{X} .

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