

COUPLING THE DISCRETE ELEMENT METHOD WITH THE FINITE ELEMENT METHOD TO SIMULATE ROCKFALL IMPACT EXPERIMENTS

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Key words: DEM, FEM, Impact, Multi-Physics Problems, Partitioned Coupled Simulation, Natural Hazards, Rockfall, Flexible Tension Structures, Mapping, Interface

Abstract. To numerically simulate rockfall impact on flexible protection structures two different numerical methods are coupled within the open-source multi-physics code KRATOS. The impacting object is modeled with the help of a cluster of spherical discrete elements and its movement and contact forces are simulated using the Discrete Element Method (DEM). To realize a partitioned coupling simulation the contact forces are subsequently transferred to the light-weight protection structure which is analyzed and simulated using the Finite Element Method (FEM). To allow a stable simulation even in the case of large contact forces and/or large time steps a strong coupling Gauss-Seidel algorithm is presented. Subsequently the applicability of the method is shown by calculating experiments and finally the inclusion of digital terrain data is demonstrated.

1 INTRODUCTION

Rockfall events can cause serious damage to populated areas and infrastructure located in mountainous regions. To properly secure these vulnerable zones a variety of different protection structures are used. They can be divided in two main groups: active and passive constructions. Active protection structures represent near-surface steel nets and

prevent the detachment of individual rocks. Passive protection structures do not prevent the rockfall event but either catch the falling rock or guide it to a safe zone. While active structures are easier to dimension as there is no dynamic load case to consider, the analysis of passive protection structures is demanding and subject of this work. Similar to the assessment of the influence of other natural hazards on structures, like wind [21, 23] and debris-flow [18, 19] the impact loads from rockfall events are highly non-linear because the structural response itself influences the load in return. First investigated by [17], many other works have since been done on it. A special element to numerically model the heavily used ring-elements has been developed by [24] while others like [20, 25, 26, 27] have been investigating the numerical simulation of rockfall impacts and the respective structural response. Recently [13] discussed the combination of DEM and FEM to model the impact scenario on the bases of the work of [10, 11]. This allows to use two stand-alone solvers to be combined in a co-simulation environment and use the strengths of the respective participants. While the DEM is used to model and simulate the impacting object and its contact forces with the structure, the FEM is employed to analyze the respective structural response. The highly non-linear nature of this impact scenario calls for an effective handling of the interface and the appropriate transfer and mapping of state variables. [12] has employed this strategy to simulate rockfall impact experiments performed by the Swiss company Geobrugg. The study showed the successful application of the aforementioned coupling strategy. The current work will give a brief summary and revision of the two publications [12, 13] and add a discussion about the inclusion of terrain data into the simulation of rockfall events. The data is obtained from drone images and can support a thorough analyze of worst-case rockfall events.

The structure of the paper is as follows:

- Section 2 describes the theoretical background of the proposed coupling strategy and its participants. Subsection 2.1 gives a brief description of the discrete element method. Subsequently, subsection 2.2 gives a brief description of the finite element method. Finally the partitioned coupling strategy and two different algorithms are presented in subsection 2.3.
- Section 3 discusses a rockfall impact experiment performed by the Swiss company Geobrugg and the results of the numerical simulation.
- Section 4 demonstrates the inclusion of terrain data in the workflow of the coupled simulation and discusses the advantages that come with it.
- Finally, Section 5 concludes this work with final words, a summary and an outlook to future research questions.

2 COUPLING ENVIRONMENT

As described by [13] the proposed coupling strategy utilizes the combination of two stand-alone numerical methods, namely the DEM and the FEM. While the DEM is used

to model and simulate the motion of discrete objects and their interaction with boundaries discretized by surface, line, and vertex entities, the FEM is employed to analyze the respective structural response to the impact loads. The coupling of this co-simulation is realized in the open source multi-physics code KRATOS [6, 7, 8]. The open-source character of this software is beneficial for the development of further improvements and the general availability to the public. In the following subsection the respective participants are briefly introduced and their coupling is explained. For more detailed explanations the reader is kindly redirected to [10, 13].

2.1 DEM

First described by [5] the DEM has been widely adopted to simulate the motion and interaction of discrete elements. It represents a particle method and thanks to its efficient handling of discrete elements it proves to be suitable for the analysis of rockfall events [12]. Important investigations of the proper handling of impact/contact have been done by [4, 15, 16].

The general workflow for a DEM simulation can be simplified to: Contact detection, analysis of contact forces, integration of motion, and subsequent advancement in time.

A detailed discussion of the single steps is out of the scope of this work, which is why some suitable sources are given in the following. For a detailed and well elaborated discussion of contact detection, please see [10, 11]. The evaluation of the contact forces is heavily dependent on the chosen contact law. In the present study a Hertz-Mindlin spring-dashpot contact model was used (abbreviated with HM+D) is used. The respective algorithmic parameters, k_n, k_t (contact stiffness in normal and tangential direction), c_n, c_t (damping coefficients in normal and tangential direction) and the friction coefficient μ as shown in Figure 1 must be properly calculated [10, 13]. Finally the integration of motion is performed based on Newton's second law of motion. A variety of different time integration schemes can be used while this work employs a central-difference scheme [28]. Special care must be taken if the rotation needs to be properly integrated as described by [9].

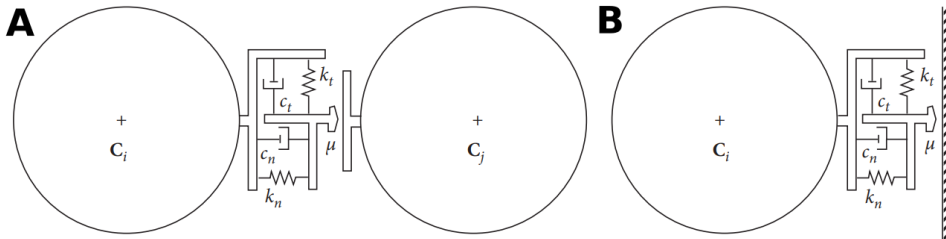


Figure 1: DEM-DEM and DEM-FEM rheological models. (A) DEM-DEM [10]. (B) DEM-FEM [10].

2.2 FEM

The FEM is used to analyze the structural response to the impact loads. With reference to a variety of interesting publications, among which we would like to emphasize [1], the virtual work,

$$\delta W = \delta W_{int} + \delta W_{kin} - \delta W_{ext} = 0, \quad (1)$$

is calculated, including the internal δW_{int} , the kinetic δW_{kin} , and the external δW_{ext} virtual work. To solve for the equilibrium, Newton's type iterative schemes are applied, for which δW has to be linearized. In order not to exceed the scope of this paper, we will not go into further detail in the following.

2.3 PARTITIONED COUPLING

With the DEM and the FEM at hand, the respective advantages can be used while bringing both methods together in a partitioned coupling simulation. The usage of FEM to model the structure allows the use of advanced element formulations like shell and membrane elements for the wire mesh [20], ring elements [24], and sliding cable formulations [17, 22]. Both solvers are called successively and their respective solution data is exchanged. This procedure is schematically visualized in Figure 2.

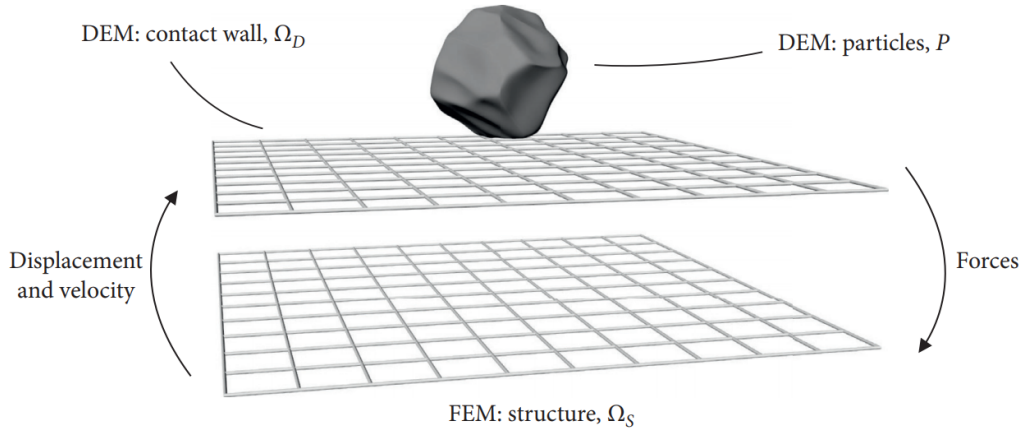


Figure 2: Transfer of forces and displacements and velocities at the interface, adapted from [13, 14].

The contact forces are calculated by the DEM and subsequently transferred to the FEM part. The structural response is then solved using the FEM and the state variables (displacement, and velocity) is transferred back to the DEM boundary. This procedure allows to use two standalone applications without the need to change any code in the respective solvers. To transfer the data a mapper is applied which handles the interface [29]. Depending on the problem setup two different coupling schemes can be applied and are summarized in a simplified form below [13].

2.3.1 Weak Coupling

As described in [13, 21, 23] the weak coupling algorithm describes the direct exchange of data and a subsequent advancement in time and is depicted in Figure 3. This algorithm can easily become unstable if the contact forces or time steps become too large.

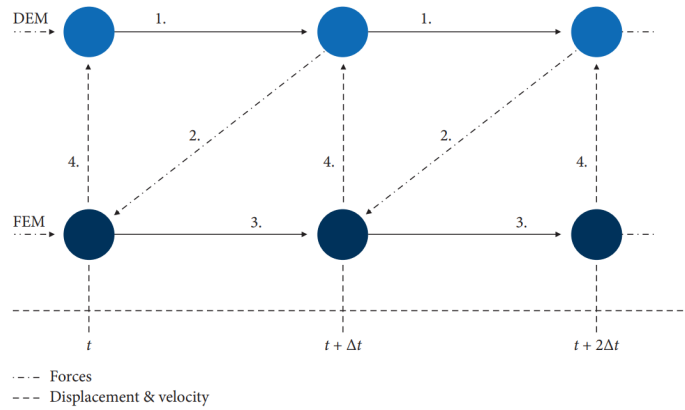


Figure 3: Staggered weak coupling procedure, between DEM and FEM, adapted from [13].

2.3.2 Strong Coupling

As a remedy to the possible instability, described in subsection 2.3.1 [13] proposes a staggered strong coupling algorithm, which includes a Gauss-Seidel loop within each time step (see Figure 4). The data can be relaxed before being transferred with e.g. an Aitken relaxation [30]. The additional loops within each time step enforce the interface conditions [13] to be fulfilled with respect to an user defined interface residual.

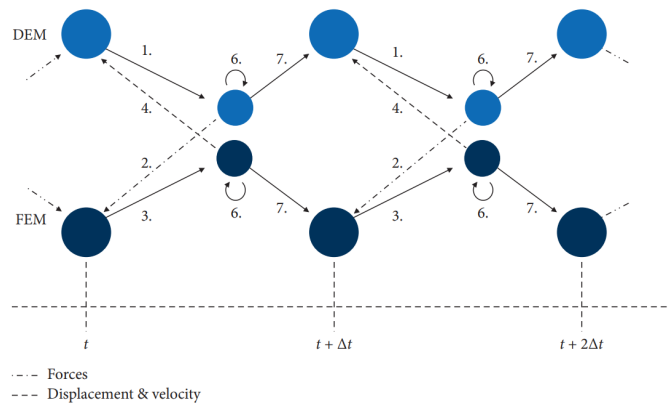


Figure 4: Staggered strong coupling procedure, between DEM and FEM, adapted from [13].

3 Rockfall Experiment

To proof the applicability of the proposed coupling strategy [12] simulated the rockfall impact on a test setup. The experiment was carried out in 2018 in Walenstadt, Switzerland, according to the Swiss guideline (SAEFL) by the company Geobrugg. A standardized concrete cube (mass: $180.0kg$, edge length: $0.41m$) was dropped from a height of $2.0m$ on a wire mesh spanned between a test steel frame of $3.9 \times 3.9m^2$, see Figure 5A,B. The experiment was repeated twice, ones for an initial sag due to dead load of $0.05m$ (exp_1) and ones for $0.10m$ (exp_2). The properties of the structural model were taken from laboratory tests and the unknowns were tuned to fit the initial sag of exp_1.

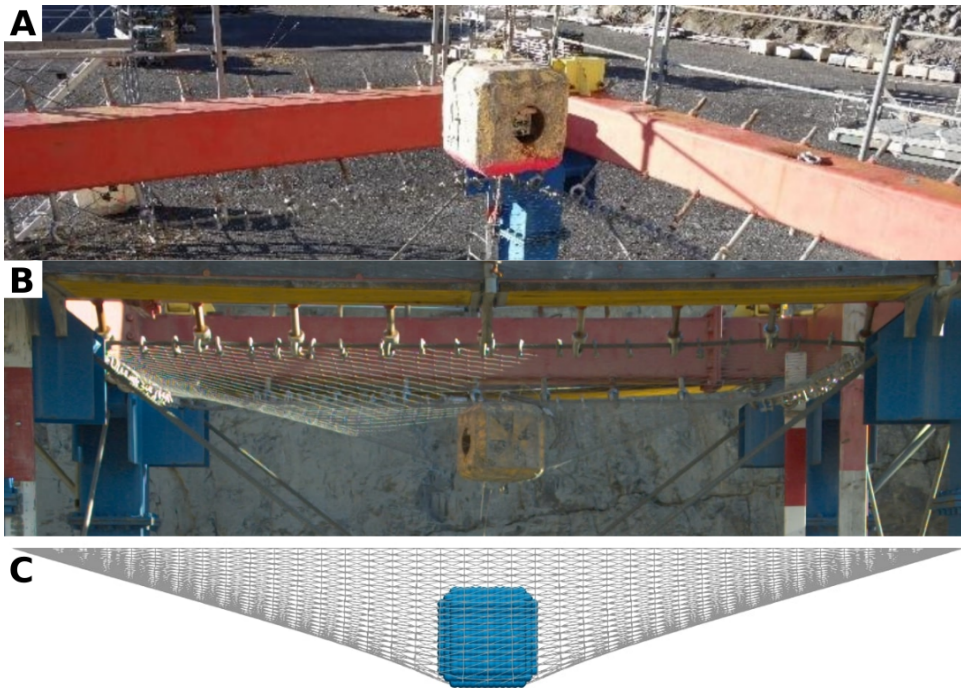


Figure 5: (A) Experimental set-up. (B) Experiment - deformation at maximum deflection. (C) Simulation - deformation at maximum deflection. Adapted from [12].

[12] models the impacting object as a cluster of spheres to approximate the real geometry while keeping the efficient contact algorithms for spheres. The clusters were created with the algorithms provided by [2, 3]. For the simulation of the experiment the cluster refinement was varied from 1 sphere (c1) to 22,232 spheres (c7). The results of [12] are presented in Figure 6. Figure 6A visualizes the displacement, Figure 6B the velocity, and Figure 6C the reaction forces, measured in the support posts.

A general good agreement with the results of the experiments can be seen in Figures 6A-C. The deviations for the single sphere are due to the poor distribution of the contact force. The detailed study and more information on this topic can be found in [13].

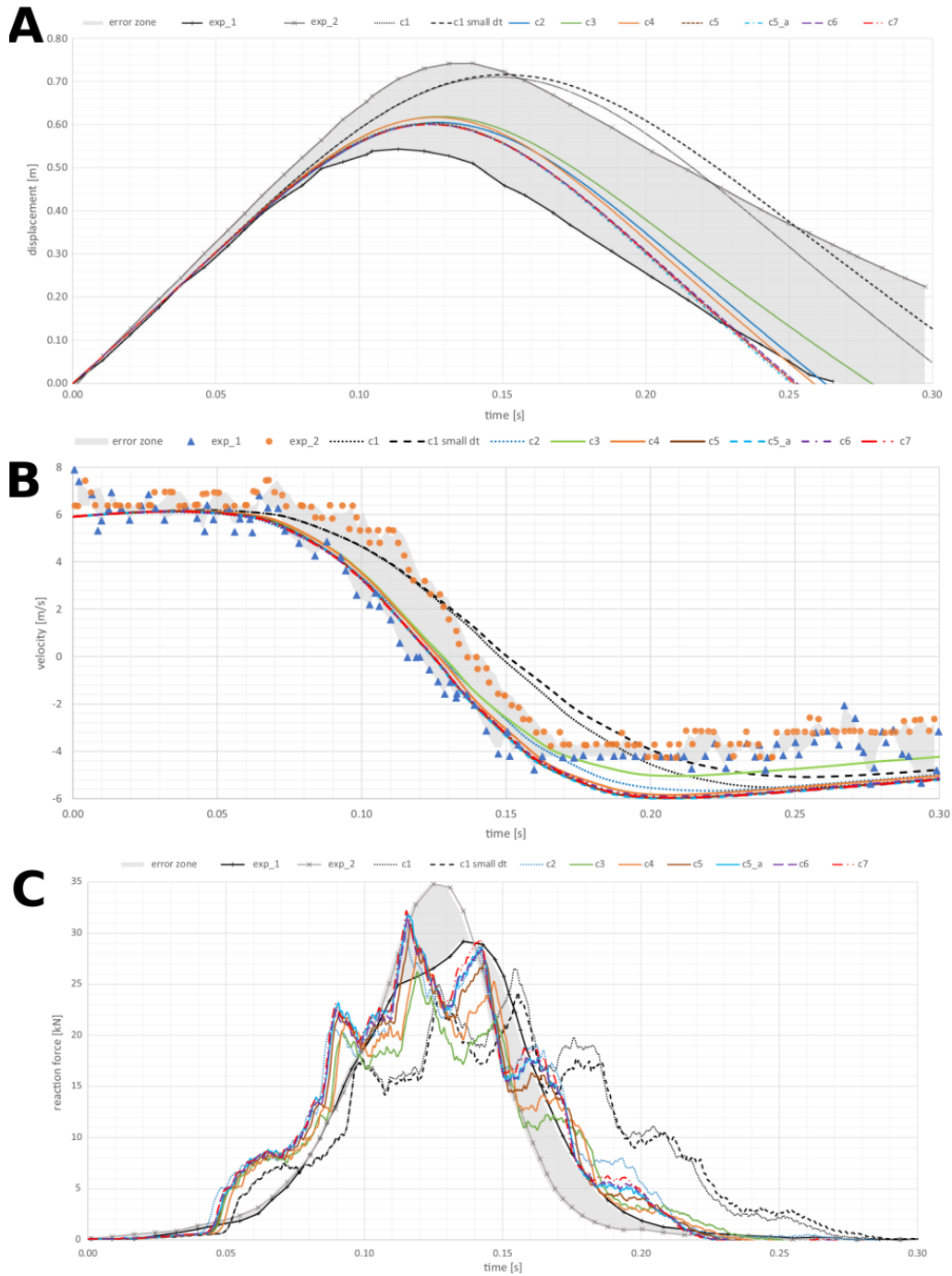


Figure 6: Simulation results for (A) Displacement, (B) Velocity, (C) Reaction forces. The study has been repeated for different levels of cluster refinement (c1-c7). All Figures are taken from [12].

4 INCLUSION OF TERRAIN DATA

The design of rockfall protection structures is highly dependent on the environmental conditions of the particular location and initial impact state, which, contrasting the

numerically replicated experiment, is generally impossible to precisely know in advance. A practically flexible alternative is to incorporate site terrain data into the simulation and numerically predict the rockfall’s path from its initial detachment until post-impact. The method of coupling DEM and FEM, which is used in this work, is robustly capable of incorporating virtual terrain models as a fixed triangulated boundary condition and in conjunction with the arbitrary rock description (via sphere clusters), facilitates the location-specific simulation of any rockfall event. In this way, the FEM model of the protective structure can be integrated very easily into the terrain model which, in the present example will be waived for clarity. The two rock shapes in Figure 7 are used to simulate a possible rockfall event, whereby the rock in Figure 7C is positioned so that it impacts with its edge. Both rocks are dropped from near the terrain surface with an initial velocity in gravity direction of $10m/s$ at the same place on the terrain slope, which is shown in Figure 8A. The trajectories of the rocks are illustrated in Figure 8B, which clearly shows the rocks intermittently contacting the terrain between accelerative freefall. Further simulations with several rock shapes would allow the user to analyze the worst case scenarios on the present slope.

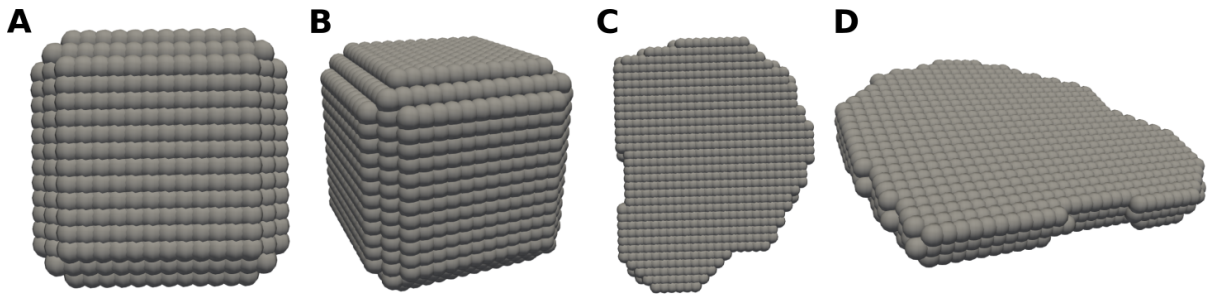


Figure 7: Different rock shapes modeled as clusters. (A) Regular cubic shape - front view. (B) Regular cubic shape - perspective view, (C) Arbitrary shape - front view. (D) Arbitrary shape - perspective view.

5 CONCLUSIONS

The simulation and analysis of rockfall impact on protection structures is a challenging and highly-nonlinear task. While a lot of design decisions are still based on field experiments the numerical analysis can be beneficial to get an efficient and cost-effective overview of the structural response to a given impact scenario. This work introduces and summarizes the recent advances by [12, 13]. The proposed method couples two numerical methods, namely the DEM and the FEM to model and simulate the impact of rocks on flexible protection structures. Due to the large deformations which occur in the flexible protection structures the problem is highly nonlinear and needs a suitable method to realize a two-way coupled multi-physics simulation. This co-simulation is done in the open source multi-physics software KRATOS [6, 7, 8] which allows the combination of multiple stand-alone applications. This study briefly explains the two algorithms for coupling the

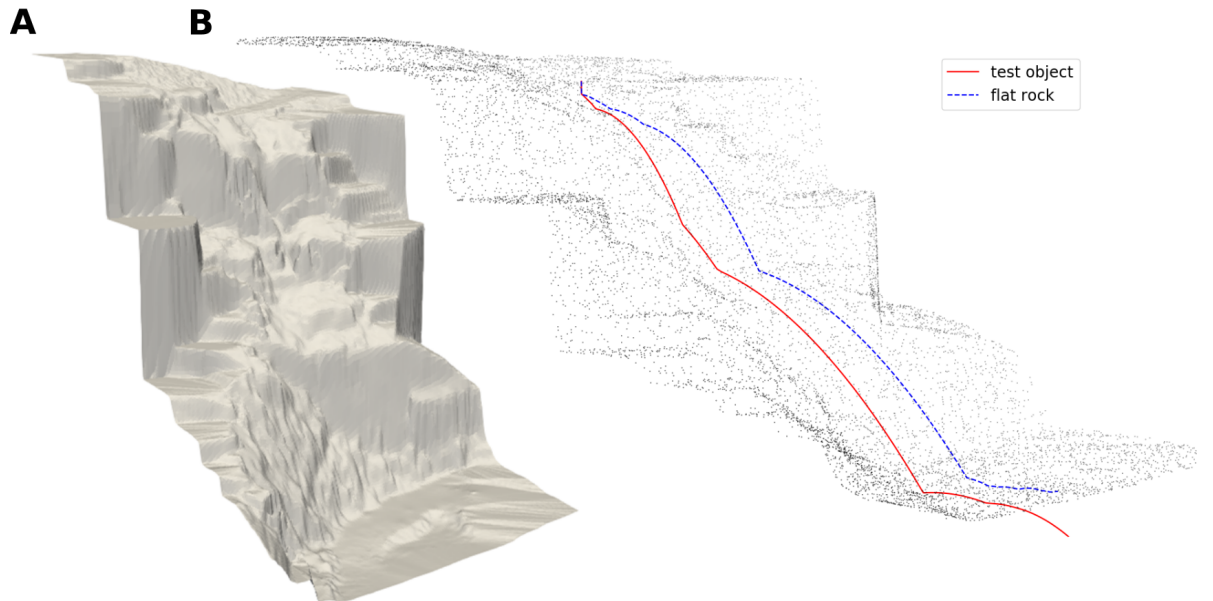


Figure 8: (A) Virtual terrain model as triangulated surface. (B) Trajectories of rockfall events including point-cloud of the terrain model. The red line represents the path of the rock visualized in Figures 7A,B, while the blue line shows the path of the rock visualized in Figures 7C,D.

DEM and the FEM which is explained in detail in [13]. Additionally the results from [12] are presented to show the applicability and effectiveness of the proposed coupling method by simulating two rockfall experiments performed by the Swiss company Geobrugg. Finally the inclusion of a virtual terrain model is demonstrated, which allows to include the influence of the surrounding terrain into the rockfall simulation. This enables the user to find the worst case scenarios for rock detachments and to find the most suitable position for the installation of protection systems. Considered as a whole, the coupling environment in KRATOS, in conjunction with the developments and advances in the individual applications, thus provides an effective simulation environment for both analyzing the structural response to impacting rocks and taking into account the boundary conditions of the environment.

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