DOI: 10.1002/pamm.202100200

Recursion relations for *hp***-FEM Element Matrices on quadrilaterals**

Tim Haubold^{1,*}, Veronika Pillwein², and Sven Beuchler^{1,3}

¹ Leibniz University Hannover, Institute for Applied Mathematics, Welfengarten 1, D-30167 Hannover

² Johannes Kepler Universität Linz, Research Institute for Symbolic Computation, Altenbergerstraße 69, A-4040 Linz

³ DFG Cluster of Excellence PhoenixD (Photonics, Optics, and Engineering – Innovation Across Disciplines), D-30167 Hannover

In this paper we consider higher order shape functions for finite elements on quadrilaterals. Using tensor products of suitable Jacobi polynomials, it can be proved that the corresponding mass and stiffness matrices are sparse with respect to polynomial degree p. Due to the orthogonal relations between Jacobi polynomials the exact values of the entries of mass and stiffness matrix can be determined. Using symbolic computation, we can find simple recurrence relations which allow us to compute the remaining nonzero entries in optimal arithmetic complexity. Besides the H^1 case also the conformal basis functions for H(Div) and H(Curl) are investigated.

© 2021 The Authors. Proceedings in Applied Mathematics & Mechanics published by Wiley-VCH GmbH.

1 Formulation of the problem in H^1

For a polygonal Lipschitz domain $\Omega \in \mathbb{R}^2$ and given $f \in L^2(\Omega)$, we consider the model problem

$$-\operatorname{div}(D\operatorname{grad} u)) + \kappa u = f \quad \text{in } \Omega, \quad u = 0 \quad \text{on } \partial\Omega, \tag{1}$$

with an elementwise constant diffusion matrix $D \in \mathbb{R}^{2\times 2}$ and coefficient κ . For simple notation we assume a Dirichlet boundary condition. Problem (1) is discretized by means of the *hp*-version of finite elements, see e.g. [1]. Denote by $\Phi = [\phi_1, \ldots, \phi_N]$ a basis for the finite element space contained in $H_0^1(\Omega)$. Following [2] the shape functions can be separated into three groups ϕ_v, ϕ_e and ϕ_I using a vertex (v), edge (e), interior (I) ansatz.

2 Discretization - Shape functions for H^1

For the definition of our ansatz functions, Legendre polynomials and their integrals are required. They are defined by the Rodriguez formula, see e.g. [3]. More precisely, they and their integrals are given by

$$L_n(x) = \frac{1}{2^n n!} \frac{\mathrm{d}^n}{\mathrm{d}x^n} \left((x^2 - 1)^n \right), \quad n \in \mathcal{N}_0, \quad \text{and} \quad \hat{L}_n(x) = \int_1^x L_{n-1}(t) \, \mathrm{d}t, \quad n \ge 1,$$

respectively. Let $C = (-1, 1)^2$ be the reference square, see [4] for the triangular case. The H^1 interior basis functions on C are given by

$$P_{n,k}(x,y) = \hat{L}_n(x)\hat{L}_k(y) \text{ with their gradients } \nabla P_{n,k}(x,y) = \begin{pmatrix} L_{n-1}\hat{L}_k(y)\\ \hat{L}_n(x)L_{k-1}(y) \end{pmatrix} , n,k=2,\ldots,p.$$
(2)

In addition the vertex and edge bubbles are defined accordingly, see [1], [5]. By using a Kronecker product formulation, we only need to evaluate the integrals $I_1^{(n,m)} \coloneqq \int_{-1}^1 \hat{L}_n(t) \hat{L}_m(t) \, dt$, $I_2^{(n,m)} \coloneqq \int_{-1}^1 L_{n-1}(t) L_{m-1}(t) \, dt$ and the mixed integral $I_3^{(n,m)} \coloneqq \int_{-1}^1 L_{n-1}(t) \hat{L}_m(t) \, dt$.

Corollary 2.1 For the integrals $I_i^{(n,m)}$, i = 1, 2, 3, the following recursion formulas hold

$$I_1^{(n+1,m+1)} = \frac{m+n-3}{m+n+3}I_1^{(n,m)}, \quad I_2^{(n+1,m+1)} = \frac{2m-1}{2m+1}I_2^{(n,m)}, \quad and \quad I_3^{(n+1,m+1)} = \frac{m+n-2}{m+n+2}I_3^{(n,m)}.$$
 (3)

An extension to the cube is straightforward. Since the H^1 basis functions are given by

$$P_{n,m,k}(x,y,z) = \widehat{P}_n^{(0,0)}(x)\widehat{P}_m^{(0,0)}(y)\widehat{P}_k^{(0,0)}(z),$$

we can again factor the integrals and use a Kronecker product formulation. Thus the recursion formulas stay the same.

© 2021 The Authors. Proceedings in Applied Mathematics & Mechanics published by Wiley-VCH GmbH.

^{*} Corresponding author: e-mail haubold@ifam.uni-hannover.de

This is an open access article under the terms of the Creative Commons Attribution License, which permits use,

distribution and reproduction in any medium, provided the original work is properly cited.

www.gamm-proceedings.com

3 H(Div) and H(Curl) on the square

In this section, the differential equations $-\nabla \nabla \cdot u + \kappa u = f$ and $-\nabla \times \nabla \times u + \kappa u = f$ for vector valued functions are discretized. These are H(Div) and H(Curl) model problems, respectively. For ease of notation, only the interior bubble functions on the reference element are presented.

3.1 H(Div)-conformal functions

Following e.g. [6], the basis functions for H(Div) on the reference square are defined as

$$P_{n,k}^{(I)}(x,y) = \frac{1}{2} \begin{pmatrix} -\hat{L}_n(x)L_{k-1}(y) \\ L_{n-1}(x)\hat{L}_k(y) \end{pmatrix}, \qquad P_{n,k}^{(II)}(x,y) = \frac{1}{2} \begin{pmatrix} \hat{L}_n(x)L_{k-1}(y) \\ L_{n-1}(x)\hat{L}_k(y) \end{pmatrix}, \qquad n,k = 2,\dots,p,$$

$$P_{1,k}^{(II)}(x,y) = \begin{pmatrix} 0 \\ \hat{L}_k(y) \end{pmatrix}, \qquad P_{n,1}^{(II)}(x,y) = \begin{pmatrix} \hat{L}_n(x) \\ 0 \end{pmatrix}, \qquad n,k = 2,\dots,p.$$

For the mass matrix one can reuse the recursion formulas (3), but there exists another result.

Theorem 3.1 With $A, B \in \{I, II\}$, let $I_{n_1,k_1,n_2,k_2}^{(A,B)} \coloneqq \int_C P_{n_1,k_1}^{(A)}(x,y) P_{n_2,k_2}^{(B)}(x,y) \, dx \, dy$. For $n_1, n_2, k_1, k_2 \ge 3$, we have

$$I_{n_{1},k_{1},n_{2},k_{2}}^{(A,B)} = \frac{n_{1} + k_{1} + n_{2} + k_{2} + 8}{n_{1} + k_{1} + n_{2} + k_{2}} I_{n_{1}-1,k_{1}-1,n_{2}-1,k_{2}-1}^{(A,B)} + \frac{n_{1} - k_{1} + n_{2} - k_{2} - 4}{n_{1} + k_{1} + n_{2} + k_{2}} I_{n_{1}-1,k_{1},n_{2}-1,k_{2}}^{(A,B)} + \frac{-n_{1} + k_{1} - n_{2} + k_{2} - 4}{n_{1} + k_{1} + n_{2} + k_{2}} I_{n_{1},k_{1}-1,n_{2},k_{2}-1}^{(A,B)}.$$
(4)

Proof. The formula can be found using the Mathematica package Guess [7] and proven using the closed form.

For the stiffness matrix one needs to assemble $\int_C \text{Div}(P_{n_1,k_1}^{(I/II)}(x,y)) \text{Div}(P_{n_1,k_1}^{(I/II)})(x,y) \, dx \, dy$. Although the divergence of the basis functions is rather simple, i.e. $\text{Div} P_{n,k}^{(I)}(x,y) = 0$ and $\text{Div} P_{n,k}^{(II)}(x,y) = L_{n-1}(x)L_{k-1}(y)$ one can still reuse (3) for a fast assembly.

3.2 H(Curl) conformal basis functions

The two types of basis functions for H(Curl) on the reference square are given by

$$P_{n,k}^{(I)}(x,y) = \frac{1}{2} \begin{pmatrix} L_{n-1}(x)\bar{L}_k(y)\\ \hat{L}_n(x)L_{k-1}(y) \end{pmatrix}, \qquad P_{n,k}^{(II)}(x,y) = \frac{1}{2} \begin{pmatrix} L_{n-1}(x)\bar{L}_k(y)\\ -\hat{L}_n(x)L_{k-1}(y) \end{pmatrix}, \quad n,k = 2,\dots,p,$$

$$P_{1,k}^{(II)}(x,y) = \begin{pmatrix} \hat{L}_k(y)\\ 0 \end{pmatrix}, \qquad P_{n,1}^{(II)}(x,y) = \begin{pmatrix} 0\\ \hat{L}_n(x) \end{pmatrix}, \quad n,k = 2,\dots,p.$$

Again the recursion formulas (3) come in handy. Additionally recursion formula (4) and similar formulas can be used as well. For the stiffness part, we need to solve integrals of the form $\int_C \operatorname{curl}(P_{n_1,k_1}^{(I/II)}(x,y)) \operatorname{curl}(P_{n_2,k_2}^{(I/II)})(x,y) \, dx \, dy$. Therefore we first compute the curl of the basis functions, i.e. $\operatorname{curl} P_{n,k}^{(I)}(x,y) = 0$ and $\operatorname{curl} P_{n,k}^{(II)}(x,y) = -L_{n-1}(x)L_{k-1}(y)$. Up to sign, these are the same functions as in the divergence for the $H(\operatorname{Div})$ case. Thus we can compute the $H(\operatorname{Curl})$ in the same way as the $H(\operatorname{Div})$ case.

Acknowledgements The research of the second author was partially funded by the Austrian Science Fund (FWF): W1214-N15, project DK15. The last author has been supported by the Deutsche Forschungsgemeinschaft (DFG) under Germany's Excellence Strategy within the Cluster of Excellence PhoenixD (EXC 2122, Project ID 390833453). Open access funding enabled and organized by Projekt DEAL.

References

- [1] C. Schwab, *p* and *hp*-finite element methods, Numerical Mathematics and Scientific Computation (The Clarendon Press, Oxford University Press, New York, 1998), Theory and applications in solid and fluid mechanics.
- [2] B. Szabó and I. Babuška, Finite element analysis, A Wiley-Interscience Publication (John Wiley & Sons, Inc., New York, 1991).
- [3] G. E. Andrews, R. Askey, and R. Roy, Special functions, Encyclopedia of Mathematics and its Applications, Vol. 71 (Cambridge University Press, Cambridge, 1999).
- [4] T. Haubold, V. Pillwein, and S. Beuchler, PAMM 19(1), e201900446 (2019).
- [5] G.E. Karniadakis and S.J. Sherwin, Spectral/*hp* element methods for CFD, second edition, Numerical Mathematics and Scientific Computation (Oxford University Press, Oxford, 2013).
- [6] S. Zaglmayr, High Order Finite Elements for Electromagnetic Field Computation, PhD thesis, JKU Linz, 2006.
- [7] M. Kauers, Guessing Handbook, Tech. Rep. 09-07, Research Institute for Symbolic Computation (RISC).