

Constant Mean Curvature Surfaces Based on Fundamental Quadrilaterals

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Abstract

We describe the construction of CMC surfaces with symmetries in \mathbb{S}^3 and \mathbb{R}^3 using a CMC quadrilateral in a fundamental tetrahedron of a tessellation of the space. The fundamental piece is constructed by the generalized Weierstrass representation using a geometric flow on the space of potentials.

Keywords CMC surface · Flat connections · DPW method · Tesselations

Mathematics Subject Classification (2010) 53A10 · 53C42 · 53C43

1 Introduction

Surfaces with constant mean curvature (CMC) in euclidean 3-space and in the round 3-sphere can be investigated by methods of integrable systems. Their Gauss equation is the elliptic sinh-Gordon equation

$$\Delta u + \sinh u = 0 \quad , \tag{1.1}$$

which is one of the basic examples of integrable equations. Similar to minimal surfaces in euclidean 3-space, CMC surfaces possess 1-parameter (denoted usually by λ) families of isometric associated surfaces obtained by rotating their Hopf differential.

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This allows CMC surfaces to be described in terms of loop groups [4], so that analytic methods of the theory of integrable systems can be applied. One of the powerful methods of the construction of CMC surfaces is the generalized Weierstrass representation (DPW) by Dorfmeister-Pedit-Wu [6]. It starts with an analytic differential equation for the holomorphic frame $\Phi_z = \Phi \xi$ with a meromorphic DPW potential $\xi(z,\lambda)$ and the subsequent loop group factorization of Φ , leading to immersion formulas for the CMC surfaces. Control of the monodromy of the holomorphic frame is of crucial importance for the construction of CMC surfaces with non-trivial topology and symmetries.

A particularly important class of potentials is given by Fuchsian systems $\xi(z)$, those with only simple poles. In the simplest case of three singularities it reduces to the hypergeometric equation (see, for example, [7]), whose monodromy group can be described explicitly from the local residues. This leads to CMC surfaces based on fundamental triangles [25]. From the geometric point of view, CMC surfaces constructed from fundamental quadrilaterals are more natural, since they come from the curvature line parametrization. But for Fuchsian systems with more then three singularities the monodromy cannot be computed explicitly in terms of the coefficients of the system, introducing accessory parameters. Then the simplest holomorphic frame equation is a Fuchsian system with four singularities on the Riemann sphere

$$\Phi_z = \Phi \sum_{k=0}^{3} \frac{A_k}{z - z_k} \ . \tag{1.2}$$

In Section 5 of this paper we show how all periodic and compact surfaces based on fundamental quadrilaterals can be constructed from the system (1.2). Our constructions make explicit use of this Fuchsian DPW form. The relation of the monodromy and the coefficients of the Fuchsian system is the famous Hilbert's 21st problem, which was intensely studied [1]. There exist many important partial results in the simplest non-trivial case of four singularities. This case was investigated mostly within the theory of isomonodromic deformations [7] and the Painlevé VI equation, where the problem is to describe the coefficients A_k as functions of the poles z_j when the monodromy group is preserved. The holomorphic frame $\Phi(z,\lambda)$ of a CMC surface lies in a loop group, and the main analytic problem is to construct solutions whose monodromy group is unitary on the unit circle $|\lambda|=1$, giving global solutions of the Gauss equation on the four-punctured sphere.

In general, it is a hard problem to control the intrinsic and extrinsic closing conditions to obtain closed surfaces or surfaces with prescribed global properties. In recent years, important progress has been made using a flow of DPW potentials [13, 27, 28] or similar methods on spectral data [12]. By the very nature of these techniques, only surfaces which are small perturbations of spheres or tori have been reached [13].

In [18] Lawson constructed the first compact minimal surfaces in the round 3-sphere of genus $g \ge 2$. A fundamental piece of a Lawson surface is obtained by the Plateau solution of a specific geodesic polygon. The compact surface is then built from the fundamental 4-gon by the finite group generated by rotations around



the geodesic edges of the polygon. Later, Karcher-Pinkall-Sterling [16] constructed new minimal surfaces in the 3-sphere by starting with a tessellation of the 3-sphere into tetrahedra. The minimal surfaces are obtained from fundamental minimal 4-gons within such a tetrahedron which reflect across the geodesic boundaries. Constant mean curvature (CMC) surfaces in \mathbb{R}^3 have been constructed by adapting these methods [8]; see also [10, 22] for related computer experiments.

This paper constructs such fundamental patches of surfaces (Section 4) based on the deformation of DPW potentials. In this paper the following new surfaces are numerically constructed: triply periodic surfaces (Figs. 1b and 2a) and doubly periodic surfaces (Figs. 16b, 17b and 18), new doubly periodic surfaces with Delaunay ends (Fig. 21), new surfaces with Delaunay ends of positive genus (Figs. 28, 29, 30 and 42) as well as new KPS-type surfaces (Fig. 38). We also reconstruct by these methods previously constructed surfaces based on doubly-periodic hexagonal, square and triangular tilings of the plane, triply periodic cubic examples, cylinders with ends [8, 9], and the Lawson and KPS surfaces [16, 18] (Figs. 3, 4, 5, 6, 7, 8, 9, 10, 11, 12 and 13).

The 3D-data of the surfaces constructed in this paper are available in the DGD Gallery [5].

2 Geometric Construction

2.1 The Construction

This paper reports on the experimental construction of CMC surfaces in \mathbb{R}^3 with non-trivial topology with and without Delaunay ends via the generalized Weierstrass

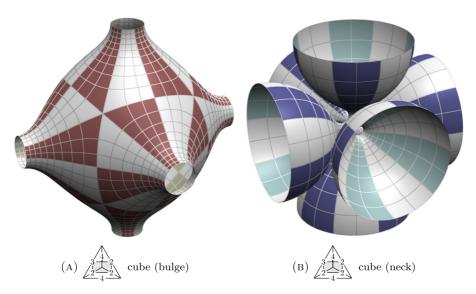


Fig. 1 Triply periodic CMC surfaces in \mathbb{R}^3

representation (DPW) [6]. The construction starts with a tetrahedron in \mathbb{R}^3 as shown which tessellates \mathbb{R}^3 by the group generated by the reflections in the four planes containing its faces. Each of the six edges of the tetrahedron is marked with an integer $n \in \mathbb{N}_{\geqslant 1} \cup \{\infty\}$ specifying that the internal dihedral angle between the two planes meeting at that edge is π/n . The tetrahedron can be degenerate in the following ways:

- vertex at ∞
- parallel planes, with opposite outward normals: the edge of the tetrahedron between the two planes is marked with ∞
- coincident planes, with the same outward normal: the edge of the tetrahedron between the two planes is marked with 1.

In this tetrahedron construct a CMC quadrilateral as shown, such that

- each of the four edges of the quadrilateral lies in a plane of the tetrahedron, and the surface reflects smoothly across this plane
- at each of the four vertices of the quadrilateral, application of the tessellation group results in a surface with either an immersed point of the surface or a oncewrapped Delaunay end at the vertex.

Then the surface constructed by application of the tessellation group is a CMC immersion with optional Delaunay ends and the symmetries of that group. Its genus is finite if the tessellation group is finite, and infinite if the group is infinite. These surfaces are described in detail at the end of this section.

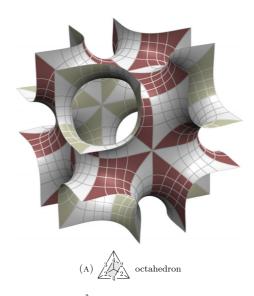


Fig. 2 Triply periodic CMC surfaces in \mathbb{R}^3



The quadrilateral is constructed via a Fuchsian DPW potential on $\mathbb{C}P^1$ with four simple poles on \mathbb{S}^1 (Section 4.1) and a reflection symmetry across \mathbb{S}^1 . The unit disk is the domain of a CMC quadrilateral which reflects in planes containing its boundaries. The simple poles with constant or Delaunay residue eigenvalues insure that each vertex of the quadrilateral after reflection is either immersed or a Delaunay end. The four dihedral angles of the tetrahedron at the corners of the quadrilateral are controlled by the four local monodromies of the potential, and the two remaining dihedral angles by two global monodromies.

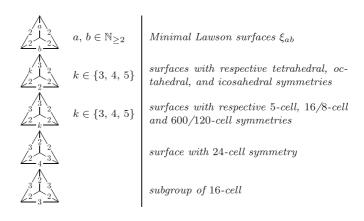
The potential has two accessory parameters which are computed by the unitary flow (Section 4.3). Starting with an initial surface (Section 4.2) which satisfies the intrinsic closing condition (unitary monodromy on \mathbb{S}^1_λ), the unitary flow, which preserves this condition, is run through the space of potentials until the dihedral angles of the planes reach the values prescribed by the tessellation. The dihedral angles are controlled by certain monodromy traces at the evaluation point. The unitary flow is not known in general to exist, but short time existence can be shown in some cases [12]. Hence we construct the surfaces numerically, giving evidence that the unitary flow has long time existence.

The Lawson surfaces [18] (Figs. 33 and 34) and the surfaces of Karcher-Pinkall-Sterling [16] (Figs. 35, 36, 37, 38, 39, 40 and 41) have been constructed by solutions of Plateau problems. The cubic lattice and some of the 2-dimensional lattices were shown to exist by similar methods [8].

2.2 Tetrahedral Tessellations

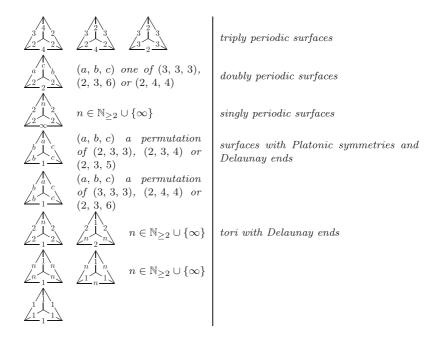
The following theorem classifies the tetrahedral tessellation of \mathbb{S}^3 (which are compact) and of \mathbb{R}^3 (which are compact, paracompact or degenerate). The tetrahedral tessellation of \mathbb{H}^3 , which can be determined by the same methods, are omitted for simplicity.

Theorem 2.1 (1) The tetrahedral tessellations of \mathbb{S}^3 are as follows:





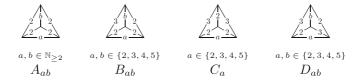
(2) The tetrahedral tessellations of \mathbb{R}^3 are as follows:



Proof Necessary conditions that a compact tetrahedron tessellates one of the space-forms \mathbb{S}^3 , \mathbb{R}^3 or \mathbb{H}^3 are the following.

- Each edge of the tetrahedron is marked with an integer $n \in \mathbb{N}_{\geq 2}$ denoting that the internal dihedral angle between the two faces meeting at that edge is π/n .
- At each vertex of the tetrahedron, the three integers marking the three edges meeting at the vertex are $(2, 2, n), n \in \mathbb{N}_{\geq 2}$ or $(2, 3, k), k \in \{3, 4, 5\}$.
- The Gram matrix $T \in M_{n \times n}(\mathbb{R})$ defined by $T_{ij} = -\cos \pi/n_{ij}$ has signature $(\delta, 1, 1, 1)$, where $\delta = 1, 0$ or -1 for \mathbb{S}^3 , \mathbb{R}^3 and \mathbb{H}^3 respectively.

The compact tetrahedra in \mathbb{S}^3 , \mathbb{R}^3 and \mathbb{H}^3 are the following:



with identifications $A_{ba} = A_{ab}$, $B_{ba} = B_{ab}$, $D_{ba} = D_{ab}$ and

$$A_{23} = B_{22}$$
, $A_{33} = D_{22}$, $B_{23} = C_2$, $B_{33} = D_{23}$. (2.1)



To see this, first consider those tetrahedra with at least one edge marked with 4 or 5. Then at each of the vertices at the endpoints of that edge, the other two edges meeting the vertex must be marked with 2 and 3. Hence all such tetrahedra with at least one 4 or 5 is one of the four types A_{ab} , B_{ab} , C_a or D_{ab} . The remaining tetrahedra have only 2 or 3 at each face. There are seven of these, namely A_{22} , $A_{23} = B_{22}$, $B_{23} = C_2$, C_3 , $A_{33} = D_{22}$, $B_{33} = D_{23}$ and D_{33} .

Since its Gram matrix has positive determinant, the tetrahedron A_{ab} is in \mathbb{S}^3 . The spaceforms for the other tetrahedra B_{ab} , C_a and D_{ab} are determined by the signs of the determinant of the Gram matrix as follows:

The [+] in the above tables denotes entries which are redundant due to the identifications (2.1)

Hence the tetrahedra which tessellate \mathbb{S}^3 are A_{ab} and the seven tetrahedra B_{23} , B_{24} , B_{25} , B_{33} , B_{34} , B_{35} and D_{24} . These tessellate \mathbb{S}^3 because they tessellate either a sphere or a n-cell, which in turn tessellates \mathbb{S}^3 .

The compact tetrahedra which tessellate \mathbb{R}^3 are the three tetrahedra B_{44} , C_4 and D_{33} . The first two tessellate a cube and the third tessellates a rhombic dodecahedron, each of which in turn tessellates \mathbb{R}^3 .

The paracompact tetrahedral tessellations of \mathbb{R}^3 are classified similarly except that the integer triple at each vertex is as in the compact case or one of (3, 3, 3), (2, 4, 4) or (2, 3, 6).

The degenerate tetrahedral tessellations of \mathbb{R}^3 are classified similarly except that the integer triple at each vertex is as in the paracompact case or one of $(2, 2, \infty)$ or $(1, n, n), n \in \mathbb{N}_{\geq 1} \cup \{\infty\}$.

2.3 The surfaces

This section describes the experimentally constructed minimal surfaces in \mathbb{S}^3 and CMC surfaces in \mathbb{R}^3 . They are of the types:

In \mathbb{R}^3 :

- triply periodic CMC surfaces \mathbb{R}^3 without ends (Figs. 1, 2, 14 and 15)
- doubly periodic CMC surfaces \mathbb{R}^3 without ends (e.g. Figs. 16, 17, 18, 19 and 20)
- doubly periodic CMC surfaces \mathbb{R}^3 with ends (Fig. 21)
- single periodic CMC surfaces in \mathbb{R}^3 with Delaunay ends (cylinders, Figs. 22 and 23)
- CMC surfaces in \mathbb{R}^3 with dihedral symmetry and Delaunay ends (tori, Figs. 24, 25, 26 and 27)
- CMC surfaces in \mathbb{R}^3 with Platonic symmetries and Delaunay ends (Figs. 28, 29, 30 and 31)
- CMC spheres in \mathbb{R}^3 with four Delaunay ends (fournoids, Figs. 30 and 32).



In \mathbb{S}^3 :

- Lawson surfaces ξ_{ab} in \mathbb{S}^3 (Figs. 33 and 34)
- minimal surfaces in \mathbb{S}^3 with Platonic symmetries (Figs. 35, 36, 37 and 38)
- minimal surfaces in \mathbb{S}^3 with *n*-cell symmetries (Figs. 39, 40, and 41)
- minimal tori in \mathbb{S}^3 with Delaunay ends (Fig. 42).

In all shown figures the lines on the surfaces are curvature lines. The surfaces in \mathbb{S}^3 are stereographically projected to \mathbb{R}^3 .

Triply periodic surfaces in \mathbb{R}^3 The simplest triply periodic surfaces can be thought of as tubes along the edges of the standard cubic lattice in \mathbb{R}^3 (Fig. 4). The genus of those surfaces modulo translation is 3.

The triply periodic surfaces are constructed from the three compact tetrahedra which tessellate \mathbb{R}^3 . Since the CMC quadrilateral can be situated in each tetrahedron in three ways, this gives nine different configurations, of which two are redundant due to symmetry (Fig. 3).

Of these, a_3 and b_2 are not possible under our symmetry constraints (compare with (4.2)), c_1 seems to devolve to a_1 , and the flow for c_2 degenerates (Figs. 2, 14, 15 and 16).

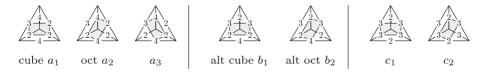


Fig. 3 The tetrahedra for the seven possible triply periodic examples



Fig. 4 The simplest triply periodic surface and its tetrahedron



lattice	(a, b, c)	genus
hexagon	(2, 3, 6)	2
square	(2, 3, 6)	2
triangle	(2, 3, 6)	3
alt hexagon	(3, 3, 3)	2
alt square	(4, 4, 2)	2
rhombus	(3, 6, 2)	2



Fig. 5 Left: tetrahedron for doubly periodic surface, where (a, b, c) is a permutation of (3, 3, 3), (2, 3, 6) or (2, 4, 4). Middle: table of 2-dimensional lattices. The genus listed in the table is that of the surface modulo translations. Right: fundamental piece for a 2-dimensional lattice



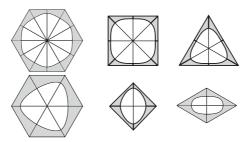


Fig. 6 The six 2-dimensional lattices

Doubly periodic surfaces in \mathbb{R}^3 The doubly periodic surfaces can be thought of as tubes along the edges of a triangle tessellations of \mathbb{R}^2 . The six 2-dimensional lattices are constructed with the tetrahedron below where (a, b, c) are the indices of a triangle tessellation of \mathbb{R}^2 , that is, a permutation of (3, 3, 3), (2, 4, 4) or (2, 3, 6) (Figs. 16, 17, 18, 19 and 20).

Doubly periodic surfaces in \mathbb{R}^3 **with Delaunay ends** The doubly periodic surfaces with Delaunay ends are obtained from triangle tessellations of \mathbb{R}^2 . Additional freedom is given by the choice of vertices corresponding to Delaunay ends (Fig. 21).

Cylinders in \mathbb{R}^3 with ends Cylinders with Delaunay ends can be constructed from a degenerate tetrahedron with two parallel planes. Of course, the same construction without Delaunay ends give the classical rotational symmetric periodic surfaces, i.e., Delaunay cylinders (Figs. 22 and 23).

Tori in \mathbb{R}^3 with Delaunay ends The torus with n ends is constructed via the diagram below (Figs. 24, 25, 26 and 27). For large n, existence of those tori can be shown by growing Delaunay ends in equidistance on one side of a cylinder.

Surfaces in \mathbb{R}^3 with Platonic symmetry and Delaunay ends Given a triangle tessellations of \mathbb{S}^2 , the surface is the orbit of a tube along one edge of the triangle with a Delaunay end at a vertex of the triangle. Equivalently, the surface is built from tubes along the edges of one of the five Platonic solids, with ends emanating from the vertices. The five tetrahedra are as in the diagram below, with (a, b, c) a permutation of $(2, 3, k), k \in \{3, 4, 5\}$ (Figs. 28, 29 and 30).



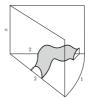


Fig. 7 Left: tetrahedron for a torus in \mathbb{R}^3 with n Delaunay ends and order n cyclic symmetry and n ends. Right: fundamental piece of this torus



surface	(a, b, c)	genus
tetrahedron	(2, 3, 6)	3
octahedron	(2, 3, 6)	7
icosahedron	(2, 3, 6)	19
cube	(2, 3, 6)	5
${\it dodecahedron}$	(2, 3, 6)	11



Fig. 8 Left: Tetrahedron for Platonic surfaces in \mathbb{R}^3 , where (a, b, c) is a permutation of (2, 3, k). Right: fundamental piece of the surfaces with Platonic symmetry and Delaunay ends

Lawson surfaces Classically, the Lawson surfaces [18] are constructed from Plateau solutions of a geodesic polygon by reflection. The tetrahedron A_{ab} and its inscribed fundamental piece admit a rotational order 2 symmetry around a geodesic through the vertices labeled by a and b. The geodesic arc is contained in the fundamental piece. This observation relates the original construction with the construction carried out in the present work, see also [16] (Figs. 33 and 34).

Surfaces in \mathbb{S}^3 with Platonic symmetries Minimal surfaces in \mathbb{S}^3 with Platonic symmetries have been constructed by Karcher-Pinkall-Sterling [16]. These surfaces can be thought of as tubes along one edge of a triangle which tessellates \mathbb{S}^2 . Note that [16] does not list all possible surfaces, e.g. the alternate octahedron of genus 11 and the alternate icosahedron of genus 29 are missing (Figs. 35, 36, 37 and 38).



Fig. 9 Tetrahedron for Lawson surface $\zeta_{a-1,b-1}$



symmetry	genus
tetrahedron	3
cube	5
octahedron	7
alt octahedron	11
dodecahedron	11
icosahedron	19
alt icosahedron	29

Fig. 10 Left: tetrahedron for surfaces in \mathbb{S}^3 with Platonic symmetries. Right: table of these surfaces





Fig. 11 Triangle tessellations of \mathbb{S}^2 . Left to right: cyclic of order 5, dihedral of order 10, tetrahedral, octahedral and icosahedra



symmetry	genus
5-cell	6
16-cell	17
24-cell	73
600-cell	601

Fig. 12 Left: tetrahedron for surfaces in \mathbb{S}^3 with n-cell symmetries. Right: table of these surfaces



Fig. 13 The 5-, 8-, 16-, 24-, 120- and 600-cell tessellations of \mathbb{S}^3 , stereographically projected to \mathbb{R}^3

Surfaces in \mathbb{S}^3 with *n*-cell symmetries For each of the *n*-cell tessellations of \mathbb{S}^3 there is a surface which can be thought of as tubes along the edges of the cells. These minimal surfaces have also been constructed by Karcher-Pinkall-Sterling [16] (Figs. 39, 40 and 41).

3 CMC Polygons via the DPW Method

3.1 The generalized Weierstrass representation (DPW)

Define the following loop groups (see [24] for details):

 $\Lambda = \text{smooth maps (loops) from } \mathbb{S}^1_\lambda \text{ to } SL_2\mathbb{C}$

 Λ_u = the subgroup loops in Λ which are in SU₂ on \mathbb{S}^1

 Λ_+ = the subgroup loops in Λ which extend to the interior unit disk in $\mathbb{C}P^1_{\lambda}$

 Λ_{-} = the subgroup of loops in Λ which extend to the exterior unit disk in $\mathbb{C}P_{\lambda}^{1}$



 $\mathring{\Lambda}_{-}$ = the subgroup of $g \in \Lambda_{-1}$ such that g(0) is upper triangular with diagonal in \mathbb{R}^{+} .

These can be generalized to loops on a circle of radius $r \in (0, 1)$; see [20].

A *DPW potential* ξ on a Riemann surface Σ is a $\Lambda \mathfrak{sl}(2, \mathbb{C})$ valued holomorphic differential form on Σ with $\xi = \sum_{k=-1}^{\infty} \xi_k \lambda^k$, det $\xi_{-1} = 0$. A meromorphic DPW potential is defined analogously.

A CMC surface is constructed from a DPW potential as follows. Let Φ be the *holomorphic frame* solving $d\Phi = \Phi \xi$; Φ generally has monodromy. Let $\Phi = FB \in \Lambda_u \mathring{\Lambda}_+$ be the Iwasawa factorization into the *unitary frame F* and positive part B (see [24]); for our case of SU₂ this factorization always exists. The CMC surface is constructed via the formulas first obtained in [4]:

$$\mathbb{S}^3: \quad f(\lambda_0, \lambda_1) = F(\lambda_0)F^{-1}(\lambda_1) , \quad \lambda_0, \lambda_1 \in \mathbb{S}^1$$
 (3.1a)

$$\mathbb{H}^3: \quad f(\lambda_0, \lambda_1) = F(\lambda_0)F^{-1}(\lambda_1) \ , \quad \lambda_1 = \lambda_0^{-1} \in \mathbb{C} \setminus \mathbb{S}^1$$
 (3.1b)

$$\mathbb{R}^3$$
: $f(\lambda_0) = -\frac{2}{H}\dot{F}(\lambda_0)F(\lambda_0)^{-1}$, $\lambda_0 = 1 \text{ or } -1$ (3.1c)

where in the case of \mathbb{R}^3 the dot denotes the derivative with respect to θ , $\lambda = e^{\mathrm{i}\theta}$. The unitary frame F yields a unitary potential $\mu = F^{-1}\mathrm{d}F$ which is well-defined on the (Riemann) surface as opposed to F which is well-defined only on the universal covering. The unitary potential is also known as the associated family of flat connections, see [14] and the literature therein.

A DPW potential $\xi = \sum_{k=-1}^{\infty} \xi_k \lambda^k$ is *adapted* if ξ_{-1} is upper triangular (and hence has zero diagonal because det $\xi_{-1} = 0$). For adapted DPW potentials, the *Hopf differential* is $Q = \langle \xi_{-1}, \xi_0 \rangle$. For non-adapted potentials, the formula for Q is more complicated.

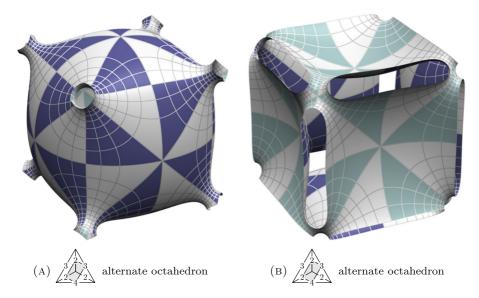


Fig. 14 Triply periodic CMC surfaces in \mathbb{R}^3



If ξ is holomorphic at z_0 , the induced CMC surface is *immersed* at z_0 if and only if ξ_{-1} does not vanish at z_0 .

This representation differs from the original representation [6] in that the potential and loops are not twisted. It is slightly looser than the representation [25] in that it does not require the DPW potential to be adapted.

3.2 Delaunay ends

A Delaunay eigenvalue is

$$\nu = \frac{1}{2}\sqrt{1 + \lambda^{-1}(\lambda - \lambda_0)(\lambda - \lambda_1)w} . \tag{3.2}$$

where the evaluation points λ_0 , λ_1 and the *end weight* $w \in \mathbb{R}^{\times}$ chosen so that ν is real on \mathbb{S}^1 . A DPW potential with a simple pole, unitary monodromy, and Delaunay eigenvalues of the residue induces a surface asymptotic to a half Delaunay cylinder [17].

To construct surfaces, two types of closing conditions must be satisfied by a DPW potential:

- The *intrinsic closing condition* is the condition that the monodromy group is unitarizable on \mathbb{S}^1 (or more generally, r-unitarizable on an circle of radius $r \in (0, 1)$). For the Fuchsian DPW potentials, this condition is not directly satisfiable except in the case of 3 or 2 geometric poles; more than 3 requires the *unitary flow*, which by definition preserves the intrinsic closing condition.
- The *extrinsic closing conditions* are conditions on the DPW potential on the monodromy at the evaluation points, chosen to control the desired geometry of the surface via (3.1). For surfaces constructed via tessellations these conditions are given in Theorem 3.3.

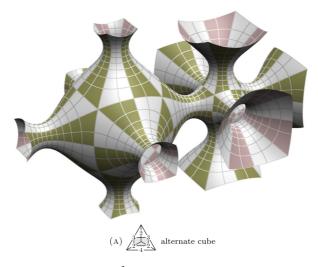


Fig. 15 Triply periodic CMC surfaces in \mathbb{R}^3

3.3 Gauge

Consider a holomorphic DPW potential ξ and a holomorphic map $g \colon \Sigma \to \Lambda$. The gauge action is

$$\xi \mapsto g^{-1}\xi g + g^{-1}dg$$
 (3.3)

The point of the gauge action is that if $d\Phi = \Phi \xi$ then $d(\Phi g) = (\Phi g)(\xi g)$. We allow gauges to have monodromy ± 1 along paths; such multivalued gauges nevertheless map single-values potentials to single-valued potentials.

A *DPW gauge* is one which maps DPW potentials to DPW potentials, that is, $g: \Sigma \to \Lambda_+$ is holomorphic in λ . If ξ is a DPW potential and g is DPW gauge, then ξ and $\xi.g$ induce the same surface in the sense that Φ and Φg do. A DPW gauge g is adapted if it preserves adapted DPW potentials, that is, $g|_{\lambda=0}$ is upper triangular.

Let ξ be a holomorphic DPW potential on Σ . A meromorphic DPW gauge is given by a meromorphic map $g \colon \Sigma \to \Lambda_+$. Then, $\xi . g$ is a meromorphic DPW potential with so-called apparent singularities at the singular points of g. In general, the singularities of a meromorphic DPW potential are not apparent.

3.4 Spin

For a DPW gauge g define the group homomorphism

$$spin: H_1(\Sigma) \to \mathbb{Z}_2 = \{\pm 1\} , \qquad (3.4a)$$

$$spin_{\gamma} g = \begin{cases}
+1 & \text{if } g \text{ has monodromy } +1 \text{ along } \gamma \\
-1 & \text{if } g \text{ has monodromy } -1 \text{ along } \gamma
\end{cases}$$
(3.4b)

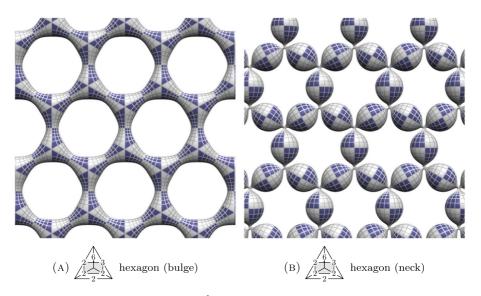


Fig. 16 Doubly periodic CMC surfaces in \mathbb{R}^3



that is, $\operatorname{spin}_{\gamma} g = +1$ (resp. -1) if g returns to itself (resp. its negative) along γ . Then $\operatorname{spin}_{\gamma} gh = \operatorname{spin}_{\gamma} g \cdot \operatorname{spin}_{\gamma} h$.

To define spin for DPW potentials consider the double cover

$$\mathbb{C}^2 \setminus \{0\} \to \{x \in \mathfrak{sl}(2, \mathbb{C}) \setminus \{0\} \mid \det x = 0\} , \quad \begin{bmatrix} u \\ v \end{bmatrix} \mapsto \begin{bmatrix} u \\ v \end{bmatrix} \begin{bmatrix} -v \ u \end{bmatrix} . \tag{3.5}$$

For a DPW potential ξ on a Riemann surface Σ , let ξ_{-1} be its λ^{-1} coefficient. Define the group homomorphism

$$spin: H_1(\Sigma) \to \mathbb{Z}_2 = \{\pm 1\} , \qquad (3.6a)$$

$$\sup_{\gamma} \xi = \begin{cases} +1 & \text{if the lift of } \xi_{-1} \text{ along } \gamma \text{ is a closed cuvve} \\ -1 & \text{otherwise} \end{cases}$$
(3.6b)

That is, $\mathrm{spin}_{\gamma}\,\xi$ is +1 (resp. -1) if the lift of ξ_{-1} returns to itself (resp. its negative) along γ . Then $\mathrm{spin}_{\gamma}\,\xi . g = \mathrm{spin}_{\gamma}\,\xi \cdot \mathrm{spin}_{\gamma}\,g$.

The spin can similarly be defined for unitary potentials using the lift of the coefficient of λ^{-1} . If $\Phi = FB$ is the holomorphic frame with potential ξ , and F is the corresponding unitary frame with potential η , then spin $\eta = \text{spin } \xi$ because spin $B|_{\lambda=0} = 1$ since $B|_{\lambda=0} \in \mathring{\Lambda}_+$.

A geometric interpretation for the spin of a potential can be given in terms of a coordinate frame, that is, a unitary frame G satisfying

$$N = Ge_0G^{-1}$$
, $f_x/v = Ge_1G^{-1}$, $f_y/v = Ge_2G^{-1}$ (3.7)

where e_0 , e_1 , e_2 is a positively oriented orthonormal basis for \mathfrak{su}_2 , f is the CMC immersion, v is the metric of f, and N is its normal. Then spin $\xi = \text{spin } u$, where $u = F^{-1}G$ is the gauge between the unitary frame F and a coordinate frame G.

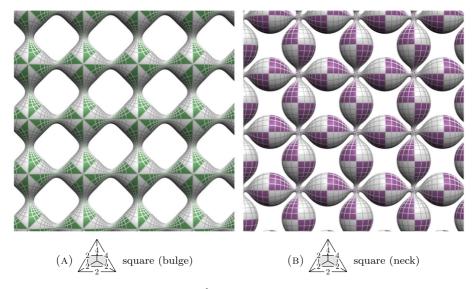


Fig. 17 Doubly periodic CMC surfaces in \mathbb{R}^3

Consider a meromorphic DPW potential ξ on Σ . For $z \in \Sigma$ write $\text{spin}_z \xi$ to mean $\text{spin}_{\gamma} \xi$ along a small circle γ encircling z. If ξ is regular at z then $\text{spin}_z \xi = 1$. For a DPW potential ξ on $\mathbb{C}P^1$ with finitely many singularities we have the total spin

$$\prod_{z \in \mathbb{CP}^1} \sup_{z} \xi = 1 . \tag{3.8}$$

As an application of spin, when we construct CMC polygons whose boundaries reflect in planes in Section 3.6, the spin is used to distinguish the internal and external dihedral angles of the planes.

3.5 Symmetry

The following theorem and lemma detail how a symmetry of the potential descends to a symmetry of the meromorphic frame, the unitary frame, and the CMC immersion via (3.1).

Theorem 3.1 Let ξ be a DPW potential.

1. If for a holomorphic automorphism τ of the domain, $\tau^*\xi = \xi.g$, then $\tau^*\Phi = R\Phi g$ for some $R \in \Lambda$. If R is unitary, then the CMC immersion has the orientation preserving symmetry

$$\mathbb{S}^3 \text{ and } \mathbb{H}^3 : \tau^* f = R f R^{-1}$$
 (3.9a)

$$\mathbb{R}^3 : \tau^* f = R f R^{-1} - \frac{2}{H} \dot{R} R ,$$
 (3.9b)

where in the case of \mathbb{R}^3 the dot denotes the derivative with respect to θ , $\lambda = e^{i\theta}$.

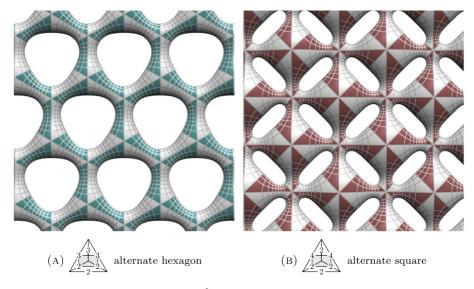


Fig. 18 Doubly periodic CMC surfaces in \mathbb{R}^3



2. If for an antiholomorphic automorphism τ of the domain, $\tau^*\xi(\lambda) = \xi(\overline{\lambda}).g$, then $\tau^*\Phi(\lambda) = R\overline{\Phi(\overline{\lambda})}g$ for some $R \in \Lambda$. If R is unitary, then the CMC immersion has the orientation reversing symmetry

$$\mathbb{S}^3$$
 and \mathbb{H}^3 : $\tau^* f(\lambda_0, \lambda_1) = R \overline{f(\overline{\lambda_0}, \overline{\lambda_1})} R^{-1}$, (3.10a)

$$\mathbb{R}^3: \tau^* f(\lambda_0) = -R \overline{f(\overline{\lambda_0})} R^{-1} - \frac{2}{H} \dot{R} R . \tag{3.10b}$$

In the orientation reversing case of the above theorem, the symmetry (3.10) relates two associate CMC surfaces, which are the same surface if $\lambda_1 = \overline{\lambda_0}$ (for \mathbb{S}^3), $\lambda_0 \in \mathbb{R}$ and $\lambda_1 \in \mathbb{R}$ (for \mathbb{H}^3) and $\lambda_0 \in \{\pm 1\}$ (for \mathbb{R}^3).

Theorem 3.1 is of limited use without the knowledge that R in that theorem is unitary. One necessary condition that R is unitary is given in the following lemma:

Lemma 3.2 If ξ in Theorem 3.1 extends to \mathbb{S}^1_{λ} and has irreducible unitary monodromy, then R in that theorem is unitary.

Proof Let $f: U \to \Sigma$ be the universal cover, and τ a lift of τ to the universal cover, so $f\tau = \tau \circ f$. Let σ be a deck transformation, so $f\sigma = f$. Then $f\tau\sigma\tau^{-1} = f$ implying that $\tau\sigma\tau^{-1}$ is a deck transformation.

Let M_{σ} the monodromy of Φ with respect to σ . and $\text{spin}_{\sigma} \mathbb{1} \in \{\pm \mathbb{1}\}$ the monodromy of g with respect to σ . For the orientation reversing case,

$$\sigma^* \tau^* \Phi = \sigma^* (R \overline{\Phi} g) = (\underset{\sigma}{\text{spin }} g) R \overline{M}_{\sigma} \overline{\Phi} g = (\underset{\sigma}{\text{spin }} g) R \overline{M}_{\sigma} R^{-1} \tau^* \Phi$$
 (3.11)

so

$$\tau^{-1*}\sigma^*\tau^*\Phi = (\sup_{\sigma} g)R\overline{M}_{\sigma}R^{-1}\Phi . \qquad (3.12)$$

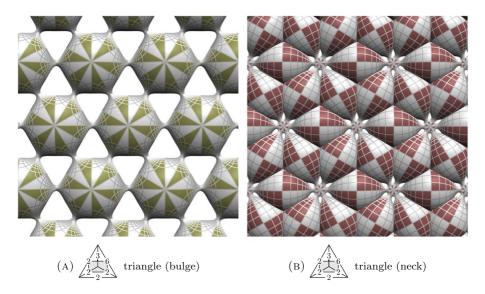


Fig. 19 Doubly periodic CMC surfaces in \mathbb{R}^3

Since $\tau \sigma \tau^{-1}$ is a deck transformation, its monodromy is given by $N_{\sigma} := (\mathrm{spin}_{\sigma} \, g) R \overline{M}_{\sigma} \, R^{-1}$. Since by assumption the monodromy group is irreducible and unitary, then $N_{\sigma} \in \Lambda_u$ for every deck transformation σ . Using that ξ extends to \mathbb{S}^1_{λ} , this implies $R \in \Lambda_u$.

The proof for the orientation preserving case is the same without the overline. \Box

3.6 CMC Polygons

Let $\mathbb{R} \cup \{\infty\}$ be divided into n segments s_1, \ldots, s_n at n distinct consecutive points z_{ij} dividing s_i and s_j . Let ξ be a meromorphic DPW potential on $\mathbb{C}P^1$ with singularities at these points z_{ij} . With b a basepoint in the upper halfplane, for $i, j \in \{1, \ldots, n\}$ let γ_{ij} be a simple closed counterclockwise curve based at b which crosses the segments s_i and s_j , and let M_{ij} , $i, j \in \{1, \ldots, n\}$, i < j be the monodromy along γ_{ij} . The n local monodromies are those along paths which enclose one singularity; the remaining monodromies are called global.

Theorem 3.3 Let ξ be a meromorphic DPW potential satisfying the conditions of Lemma 3.2 with n singularities on $\mathbb{R} \cup \{\infty\}$ as above. Assume ξ admits the reflection symmetry $\tau^*\xi(\lambda) = \overline{\xi(\overline{\lambda})}$ for $\tau(z) = \overline{z}$. Let $\theta_{ij} \in [0, \pi]$, $i, j \in \{1, ..., n\}$, i < j. If the monodromies M_{ij} satisfy

$$\frac{1}{2} \operatorname{tr} M_{ij}|_{\lambda_0} = -(\sup_{\gamma_{ij}} \xi) \cos \theta_{ij} , \quad i, \ j \in \{1, \dots, n\} , \quad i < j$$
 (3.13)

then the CMC surface induced by ξ with the upper halfplane as domain is a n-gon whose boundaries reflect in n planes (respectively totally geodesic spheres) P_1, \ldots, P_n , with internal dihedral angles θ_{ij} between P_i and P_j .

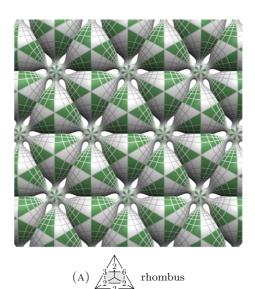


Fig. 20 Doubly periodic CMC surfaces in \mathbb{R}^3



Proof Let F be the unitary frame, G a coordinate frame, with respect to a basis \hat{e}_0 , \hat{e}_1 , $\hat{e}_2 \in \mathfrak{sl}(2, \mathbb{C})$ and u the unitary λ -independent gauge between them, so F = Gu. By the proof of Theorem 3.1 (2), $\tau_k^* F = P_k \overline{F}$, $k \in \{1, \ldots, n\}$ so

$$\tau_k^* G = P_k \overline{G} Q_k^{-1} , \quad \tau^* u = Q_k \overline{u} . \tag{3.14}$$

Then with ρ_{ij} and $\sigma_{ij} = \operatorname{spin}_{\gamma_{ii}} u$,

$$u = \tau_k^* \tau_k^* u = Q_k \overline{Q}_k u \quad \Longrightarrow \quad Q_k \overline{Q}_k = 1$$
 (3.15a)

$$\sigma_{ij}u = \rho^* u = \tau_j \tau_i u = Q_j Q_i^{-1} u \quad \Longrightarrow \quad Q_j = \sigma_{ij} Q_i \quad . \tag{3.15b}$$

With p_k a fixed point of τ_k , define $u_k = u(p_k)$ so $u_k = \underline{Q_k \overline{u_k}}$. Then for $i, j \in \{1, \ldots, n\}, i \neq j, u_j = Q_j \overline{u_j} = \sigma_{ij} Q_i \overline{u_j}$. Thus $u_i^{-1} u_j = \sigma_{ij} u_i^{-1} u_j$. so

$$\sigma_{ij} = 1 : u_i^{-1} u_j = \overline{u_i^{-1} u_j} \implies u_i^{-1} u_j e_1 = e_1 u_i^{-1} u_j$$
 (3.16a)

$$\sigma_{ij} = -1 : u_i^{-1} u_j = -\overline{u_i^{-1} u_j} \implies u_i^{-1} u_j e_1 = -e_1 u_i^{-1} u_j .$$
 (3.16b)

Hence $u_i^{-1}u_j = \sigma_{ij}e_1u_i^{-1}u_j$ so $u_je_1u_j^{-1} = \sigma_{ij}u_ie_1u_i^{-1}$.

Let $e_1 = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$. Since G is a coordinate frame, we have $(f_y)_k = G_k \hat{e}_2 G_k^{-1}$. Define $\sigma_k \in \{\pm 1\}$ by $P_k e_1 = \sigma_k (f_y)_k$. Then

$$N_k := P_k e_1 = F_k \overline{F}_k^{-1} e_1 = F_k e_1 F_k^{-1} = G_k u_k e_1 u_k^{-1} G_k^{-1} = \sigma_k G_k \hat{e}_2 G_k^{-1}$$
 (3.17)

so

$$u_k e_1 u_k^{-1} = \sigma_k \hat{e}_2 . {(3.18)}$$

Hence $\sigma_i \sigma_j = \sigma_{ij}$.

Since $\frac{d}{dy}$ is pointing into the upper half plane, $(f_y)_k$ is an internal normal to the plane. Thus $\sigma_k = 1$ if N_k is internal, and $\sigma_k = -1$ if N_k is external. Thus $\sigma_{ij} = -1$

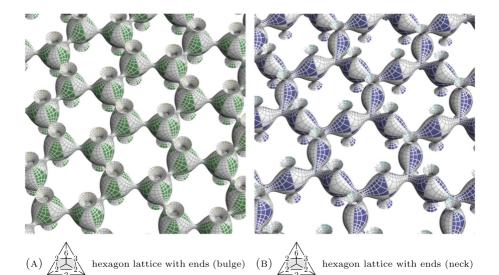


Fig. 21 Doubly periodic CMC surfaces in \mathbb{R}^3 with Delaunay ends

 $\sigma_i \sigma_j = 1$ if and only if N_i and N_j are both internal or both internal, and $\sigma_{ij} = \sigma_i \sigma_j = -1$ if and only if one of N_i and N_j is internal and one external.

This means

$$\langle N_i, N_j \rangle = -\sigma_{ij} \cos \theta_{ij} \tag{3.19}$$

where θ_{ij} is the internal angle between planes i and j. Since $M_{ij} = P_j P_i^{-1}$, then

$$\frac{1}{2}\operatorname{tr} M_{ij}|_{\lambda=\lambda_0} = \langle N_i, N_j \rangle = -\sigma_{ij}\cos\theta_{ij} . \tag{3.20}$$

Remark 3.4 Planes with dihedral angle $\theta_{ij} = \pi$ are parallel. Constraining the planes to coincide (for example, for the CMC torus with ends in \mathbb{R}^3) requires that the extrinsic conditions of Theorem 3.3 be augmented with the additional condition

$$\frac{\mathrm{d}}{\mathrm{d}\lambda} M_{ij}|_{\lambda=\lambda_0} = 0 \ . \tag{3.21}$$

It remains to control the vertices of the CMC polygon constructed in Theorem 3.3. For this we use a DPW potential with simple poles:

Theorem 3.5 Let ξ a DPW potential as in Theorem 3.3, z_k a simple pole of ξ on \mathbb{R} , and ν the eigenvalue of $\operatorname{res}_{z=z_k} \xi$.

- (1) If v = 1/(2n) or $v = \frac{1}{2} 1/(2n)$, $n \in \mathbb{N}_{\geqslant 2}$, and ξ_{-1} has a simple pole at z_k , then the CMC surface constructed from ξ with 2n reflections around the vertex is immersed at the vertex.
- (2) If $v = v_{Del}/n$, $n \in \mathbb{N}_{\geqslant 2}$, where v_{Del} is a Delaunay eigenvalue (3.2), then the CMC surface constructed from ξ with 2n reflections around the vertex is a once-wrapped Delaunay end.

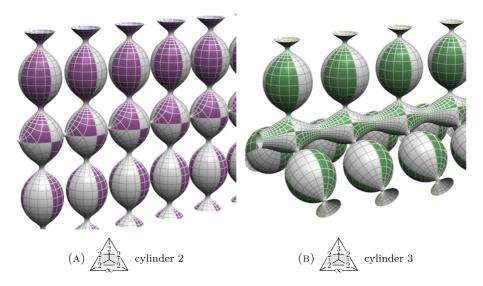


Fig. 22 CMC cylinders in \mathbb{R}^3 with Delaunay ends

Proof Assuming $z_k = 0$, write $\xi = A_{-1} dz/z + A_0 dz + \dots$ The pullback with respect to the local covering map $f(w) = w^n$ is

$$f^*\xi = nA_{-1}dw/w + nA_0w^{n-1}dw + \dots {3.22}$$

Proof of Eq. 3.5: Since by assumption A_{-1} has a pole at $\lambda = 0$, by a z-independent local gauge of ξ it may be assumed

$$A_{-1} = \begin{bmatrix} 1/(2n) & \lambda^{-1} \\ 0 & -1/(2n) \end{bmatrix} . \tag{3.23}$$

Then the local gauge $g = \text{diag}(w^{-1/2}, w^{1/2})$ removes the simple pole of $f^*\xi$ at w = 0, and

$$(f^*\xi).g = \begin{bmatrix} 0 & n\lambda^{-1} \\ 0 & 1 \end{bmatrix} dw + \dots$$
 (3.24)

Since $(f^*\xi).g$ is holomorphic at w=0 and its λ^{-1} coefficient does not vanish at w=0, then the CMC surface induced by $(f^*\xi).g$ is immersed at w=0. The proof for $\nu=\frac{1}{2}-1/(2n)$ is analogous.

Proof of Eq. 3.5: Since the eigenvalue of A_{-1} is v_{Del}/n , then the eigenvalue of nA_{-1} is v_{Del} , Unitary monodromy implies this is a once-wrapped Delaunay end. \square

4 Symmetric CMC Surfaces with Non-Trivial Topology

4.1 The potential

By applying a Möbius transformation we assume that the singular points of the CMC polygon are on the unit circle. As the fundamental piece is a CMC quadrilateral, we

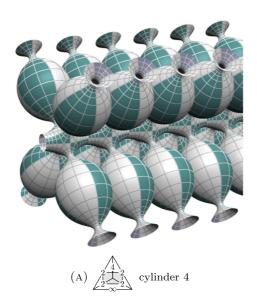


Fig. 23 CMC cylinders in \mathbb{R}^3 with Delaunay ends

restrict to the 4-punctured sphere in the following. We will see in Section 5 that, at least for surfaces without Delaunay ends, we can restrict without loss of generality to a Fuchsian DPW potential of the 4-punctured sphere. The means it has four simple poles and no pole at $z = \infty$, and is of the form

$$\xi = \sum_{k=0}^{3} \frac{A_k}{z - z_k} dz \tag{4.1}$$

as follows:

- The poles are $z_0 \in \mathbb{S}^1$ in the open first quadrant, and (z_1, z_2, z_3) is a permutation of $(1/z_0, -z_0, -1/z_0)$.
- The residues are

$$A_0 = \begin{bmatrix} y & \lambda^{-1} p \\ \frac{\lambda(\nu_0^2 - y^2)}{p} & -y \end{bmatrix} , \quad A_2 = \begin{bmatrix} -y & \frac{(\nu_1^2 - y^2)}{x} \\ x & y \end{bmatrix} , \quad (4.2a)$$

$$A_1 = \sigma A_0 \sigma^{-1}$$
, $A_3 = \sigma A_2 \sigma^{-1}$, $\sigma = \text{diag}(i, -i)$. (4.2b)

• For surfaces without Delaunay ends, the eigenvalue v_0 of A_0 and A_1 and v_1 of A_2 and A_3 are constants in (0, 1/2). For surfaces with Delaunay ends, v_0 is of the form cv_{Del} with $c \in (0, 1)$ and v_{Del} is the eigenvalue of a Delaunay unduloid

$$\nu_{\text{Del}} = \frac{1}{2} \sqrt{1 + \frac{1}{4} \lambda^{-1} (\lambda - 1)^2 w} , \quad w \in (0, 1] .$$
 (4.3)

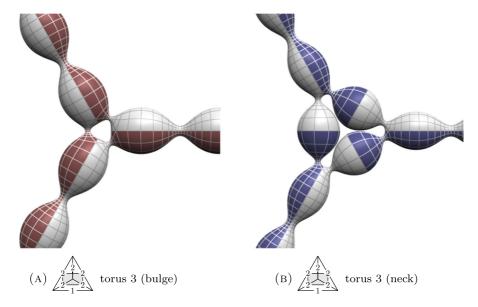


Fig. 24 CMC tori in \mathbb{R}^3 with Delaunay ends



- The accessory parameters x and y are holomorphic functions of λ on an open disk \mathcal{D}_r of radius r > 0 centered at the origin satisfying $x(\overline{\lambda}) = \overline{x(\lambda)}$ and $y(\overline{\lambda}) = \overline{y(\lambda)}$. The function p is a monic polynomial in λ satisfying $p(\overline{\lambda}) = \overline{p(\lambda)}$.
- The quotients $\lambda(v_0^2 y^2)/p$ and $(v_1^2 y^2)/x$ are holomorphic functions of λ on \mathcal{D}_r .

The need for the last condition is as follows. The unitary flow, which preserves the unitarizability of the monodromy of ξ , is implemented by evaluating the monodromy of ξ directly on the unit circle, and not by the numerically more problematic procedure of computing the monodromy on an r < 1 circle and then extending it to the unit circle.

Let M_k ($k \in \{0, ..., 3\}$) be the local monodromy around z_k based at z = 1.

The surfaces are constructed by running the unitary flow (see Section 4.3 below) so that at the end of the flow for k = 0, 1

$$v_0|_{\lambda=\lambda_k} = \frac{1}{2n_0} , \quad v_1|_{\lambda=\lambda_k} = \frac{1}{2} - \frac{1}{2n_1} ,$$
 (4.4a)

$$\operatorname{tr} M_0 M_1|_{\lambda = \lambda_k} = -\cos\frac{2\pi}{r} \ , \quad \frac{1}{2} \operatorname{tr} M_1 M_2|_{\lambda = \lambda_k} = \cos\frac{\pi}{s} \,. \tag{4.4b}$$

Then, by Theorem 3.3 and 3.5, the unit *z*-disk maps to a CMC quadrilateral whose edges reflect in planes (respectively geodesic 2-spheres) with internal dihedral angles specified by the figure at right, and whose vertices after these reflections are either immersed points or once-wrapped Delaunay ends.

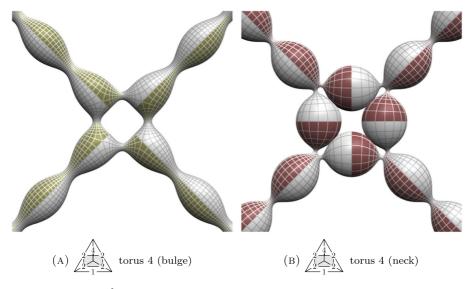


Fig. 25 CMC tori in \mathbb{R}^3 with Delaunay ends

In the special case $v_0 + v_1 = \frac{1}{2}$, the surfaces are constructed by running the unitary flow so that at the end of the flow for k = 0, 1

$$v_0|_{\lambda=\lambda_k} = \frac{1}{2n_0}$$
 , $v_1|_{\lambda=\lambda_k} = \frac{1}{2} - \frac{1}{2n_0}$, (4.5a)

$$\operatorname{tr} M_0 M_1|_{\lambda = \lambda_k} = -\cos\frac{2\pi}{r} , \quad \frac{1}{2} \operatorname{tr} M_1 M_2|_{\lambda = \lambda_k} = \cos\frac{2\pi}{s}$$
 (4.5b)

Then the quarter disk in the first quadrant maps to a CMC quadrilateral whose edges reflect in planes with internal dihedral angles specified by the figure at right, and whose vertices after these reflections are immersed.



4.2 The initial condition

4.2.1 The initial condition

The initial condition for the unitary flow is a potential ξ_0 of the form in Section 4.1 with eigenvalues $\nu_0 = \nu_1 = \frac{1}{4}$ with unitary monodromy on \mathbb{S}^1 which induces a Delaunay surface.

Lemma 4.1 (1) For CMC tori of spectral genus 0 the spectral curve $\pi: \mathbb{C}P^1 \to \mathbb{C}P^1$ can be chosen to be $\pi(\xi) = \xi^2$. The involutions are

$$\sigma(\xi) = -\xi$$
, $\rho(\xi) = \overline{\xi}^{-1}$, $\kappa(\xi) = \overline{\xi}$. (4.6)

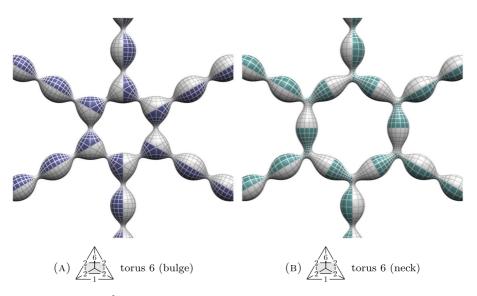


Fig. 26 CMC tori in \mathbb{R}^3 with Delaunay ends



The monodromy eigenvalues of the vacuum are $\exp(\pm v_1 + 2i\pi \mathbb{Z})$, $\exp(\pm v_2 + 2i\pi \mathbb{Z})$ $2i\pi\mathbb{Z}$) where

$$\nu_1(\xi) := i\pi \frac{\xi - \xi^{-1}}{\xi_0 - \xi_0^{-1}} , \quad \nu_2(\xi) := i\pi \frac{\xi + \xi^{-1}}{\xi_0 + \xi_0^{-1}}$$
 (4.7)

and $\pi(\pm \xi_0)$, $\pi(\pm \xi_0^{-1}) \in \mathbb{S}^1$ are the evaluation points. For some ℓ , $m \in \mathbb{Z}^+$ the monodromy eigenvalues of a Delaunay cylinder are $\exp(\pm \nu_1 + 2i\pi \mathbb{Z}), \exp(\pm \nu_2 + 2i\pi \mathbb{Z})$ where

$$v_1(u) := i\pi \frac{f_1(u) - f_2(u)}{f_1(u_0) - f_2(u_0)} , \qquad (4.8a)$$

$$v_2(u) = \frac{1}{2}\ell(f_1(u) + f_2(u)) , \quad v_2(u_0) = i\pi m ,$$
 (4.8b)

where $\pi(\pm u_0)$, $\pi(\pm \overline{u_0} + \frac{1}{2}\omega_1) \in \mathbb{S}^1$ are the evaluation points, and f_1 , f_2 are as in Eq. 4.9.

On the torus $\mathbb{C}/(\mathbb{Z} + \tau \mathbb{Z})$, Let \wp be the Weierstrass function and let $\zeta := -\int \wp$. Let $\{\omega_1, \ \omega_2, \ \omega_3\} = \{\frac{1}{2}, \ \frac{1}{2} + \frac{\tau}{2}, \ \frac{\tau}{2}\}.$ Define on some torus with modulus τ_{spec}

$$h_1(u) := \eta_1 u - \omega_1 \zeta(u) , \quad h_2(u) := f_1(u - \frac{1}{2}\omega_1) .$$
 (4.9)

The theta function

$$\theta(x, \tau) := \sum_{k \in \mathbb{Z}} \exp\left(2i\pi \left(\frac{1}{2}n^2\tau + n(x - \omega_2)\right)\right) \tag{4.10}$$

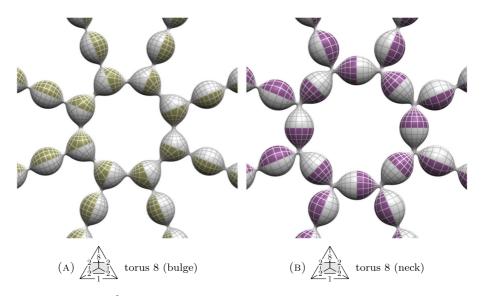


Fig. 27 CMC tori in \mathbb{R}^3 with Delaunay ends

is an entire function $\mathbb{C} \to \mathbb{C}$ with simple zeros at lattice points $\mathbb{Z} + \tau \mathbb{Z}$ and no other zeros, satisfying

$$\theta(x+1) = \theta(x)$$
, $\theta(x+\tau) = -\exp(-2i\pi x)\theta(x)$, $\theta(\tau-x) = \theta(x)$ (4.11)

for all $x \in \mathbb{C}$. Define

$$\frac{1}{2}g_0(\frac{1}{2}x) = \frac{\theta'(x)}{\theta(x)} - \frac{2\theta'(\frac{1}{2}x)}{\theta(\frac{1}{2}x)} + i\pi , \qquad (4.12a)$$

$$\frac{1}{2}g_k(\frac{1}{2}x) = \exp\left(2i\pi x \frac{\omega_k - \overline{\omega_k}}{\tau - \overline{\tau}}\right) \frac{\theta(x + \omega_k)\theta'(0)}{\theta(x)\theta(\omega_k)} , \quad k \in \{1, 2, 3\} . \quad (4.12b)$$

The initial condition is the potential in Section 4.1 with

$$x = \lambda(y + v_0)(y + v_1)\frac{1 - u}{1 + u} , \quad y(b, a) = -\frac{\frac{2i\pi}{\tau - \overline{\tau}}(b + a) + f_0(b)}{2g_2(\frac{1}{2}b)}$$
(4.13a)

$$u(b) = -\frac{g_1(\frac{1}{2}b)}{g_3(\frac{1}{2}b)} , \quad v(b, a) = \frac{\frac{2i\pi}{\tau - \overline{\tau}}(b+a) + f_0(b)}{g_2(\frac{1}{2}b)}$$
(4.13b)

$$a = \frac{2i\pi}{\tau - \overline{\tau}} \frac{1}{2} h_1$$
, $b = \frac{2i\pi}{\tau - \overline{\tau}} \frac{1}{2} h_2$ (4.13c)

$$v_0 = v_1 = \frac{1}{4}$$
, $[z_0, z_1, z_2, z_3] = u(\omega_2)^2$, $p = 1$. (4.13d)

The initial condition is computed numerically from Eq. 4.13a as Laurent series on \mathbb{S}^1 by computing its Fourier coefficients. The initial data can be computed from Lemma (4.1) using results from [11]

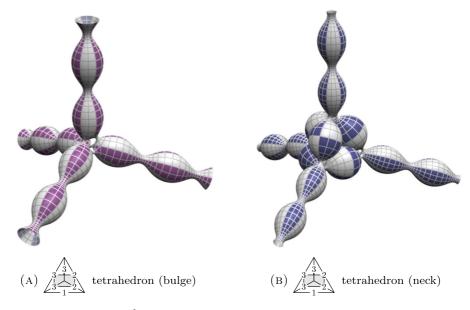


Fig. 28 CMC surfaces in \mathbb{R}^3 with Platonic symmetry and Delaunay ends



4.2.2 Configurations of the initial condition

Permuting the lattice generators in the initial condition creates different arrangements of residues of the DPW potential on the Delaunay cylinder. For the configurations used in this report, the two circle arcs (z_0, z_1) and (z_2, z_3) are mapped to semicircles (resp. profile curves) on the Delaunay surface, while the other two circle arcs (z_1, z_2) and (z_3, z_0) are mapped to profile curves (resp. semicircles) on the Delaunay surface. The first of these configurations is used to compute the 2-dimensional lattices and the cubic lattices; the second is used to compute the tori and Platonic surfaces with ends.

4.2.3 Neck and bulge

For the initial potential ξ_0 above, the poles of the Fuchsian DPW potential are at necks of the Delaunay surface. The initial potential with poles at bulges is constructed as a gauge of ξ_0 by the gauge diag($(\lambda - \lambda_0)^{-1/2}$, $(\lambda - \lambda_0)^{1/2}$), where the λ_0 is a common zero of x and $y^2 - 1/16$. This gauge is not a DPW gauge, but a so-called dressing transformation.

4.3 The unitary flow

4.3.1 The unitary flow

The unitary flow is a flow through the space of potentials of Section 4.1 preserving the intrinsic closing condition. It starts at a potential in the space with unitary monodromy, and flows until the monodromy at the evaluation points reach some desired extrinsic closing conditions.

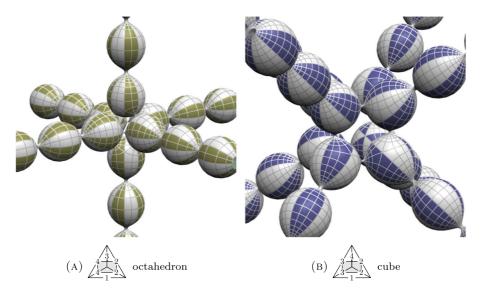


Fig. 29 CMC surfaces in \mathbb{R}^3 with Platonic symmetry and Delaunay ends



Given a smooth function $F = F(t, \vec{x}) : \mathbb{R}^{1+n} \to \mathbb{R}^n$ encoding n conditions on a flow parameter $t \in [0, 1]$ and n variables \vec{x} , if $\det \frac{\mathrm{d}F}{\mathrm{d}x} \neq 0$, then x(t) satisfying F(t, x(t)) = 0 can be computed by the implicit ODE $\frac{\mathrm{d}F}{\mathrm{d}r} + \frac{\mathrm{d}F}{\mathrm{d}x} \frac{\mathrm{d}x}{\mathrm{d}r} = 0$. The solution for the infinite case can be computed numerically by truncating to $F : \mathbb{R}^{1+n} \to \mathbb{R}^m$, $m \geqslant n$, and solving the resulting finite dimensional ODE by least squares methods. The variables \vec{x} parametrizing the potential consists of:

- the conformal type $[z_0, z_1, z_2, z_3]$
- the local eigenvalues $v_0|_{\lambda=1}$ and $v_1|_{\lambda=1}$
- the end weight w_0
- the polynomial *p*
- the accessory parameters x and y.

The accessory parameters, which are holomorphic functions of λ , are approximated by truncating their power series at $\lambda=0$. We always assume that these functions extend to a disc D_r with r>1 so that the first bullet point below can be checked directly on the unit circle.

The constraints F = 0 are of two types:

- the intrinsic closing conditions: the halftraces $t_{ij} = \frac{1}{2} \operatorname{tr} M_i M_j$, $i, j \in \{0, \dots, 3\}$, i < j are real on \mathbb{S}^1 . This is a necessary condition by Theorem 4.4.
- geometric constraints which choose a path through the space of geometric parameters to reach the desired extrinsic closing conditions at the end of the flow.

By Theorem 4.4 the monodromy is unitarizable if all halftraces along the unit circle are real and of absolute value less or equal to 1. As the components of irreducible

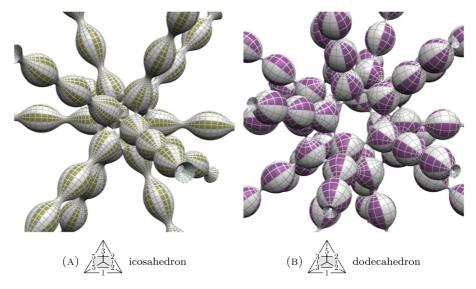


Fig. 30 CMC surfaces in \mathbb{R}^3 with Platonic symmetry and Delaunay ends



 $SL(2, \mathbb{C})$ -representations of the 4-punctured sphere with real traces consists entirely of either $SL(2, \mathbb{R})$ or SU(2) representations, and since ξ_0 is unitarizable, we can ignore the condition that all traces are of absolute value less or equal to 1 during the unitary flow.

The intrinsic closing conditions on \mathbb{S}^1_{λ} are approximated by evaluation at finitely many equally spaced sample points on \mathbb{S}^1_{λ} . In the following we describe the other constraints in more detail:

4.3.2 Geometric constraints

The simplest configuration of the geometric constraints are as follows. The two local and two global eigenvalues depend linearly on the flow parameter t to reach the desired values at t=1. If the surface has no ends, the end weight w_0 is set to 0; otherwise it depends linearly on t starting at 0 and reaching a heuristically chosen value at t=1. In this configuration the conformal type is fixed during the flow.

It is possible that the flow with this simple configuration breaks down, in which case the path must be modified in some heuristically determined way, for example by making the conformal type depend on the flow parameter.

In practice each geometric parameter is of one of three types:

- fixed during the flow
- depending linearly on the flow parameter t
- free (unconstrained).

Then the fixed variables, and the variables depending on t, being computable from t, can be omitted from \vec{x} .

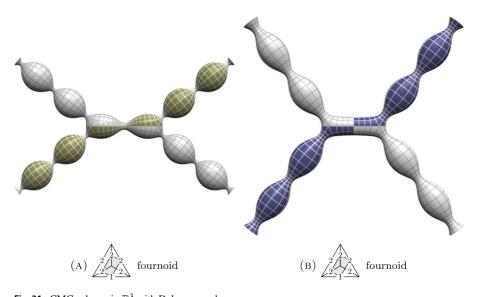


Fig. 31 CMC spheres in \mathbb{R}^3 with Delaunay ends

4.4 Irreducibility and unitarizability

For a subgroup $\mathcal{G} \subset SL_2\mathbb{C}$ generated by three elements, this section proves

- a necessary and sufficient condition for the irreducibility of \mathcal{G} , and
- a necessary condition for the SU_2 unitarizability of \mathcal{G} , assuming \mathcal{G} is irreducible.

Here, a group \mathcal{G} is *reducible* if all elements have a common eigenline, and is SU_2 unitarizable if there exists $C \in SL_2\mathbb{C}$ such that $C\mathcal{G}C^{-1} \subset SU_2$. The methods used in the proofs can be generalized to any finitely generated group.

The proof depends on the following Lemma 4.2, which determines to what extend three elements of \mathbb{C}^3 are determined by their standard \mathbb{C}^3 inner products.

With $\langle -, - \rangle$ the standard inner product on \mathbb{C}^3 , let $\mathcal{L} = \{v \in \mathbb{C}^3 \mid \langle v, v \rangle = 0\}$. Let $X = (x_0, x_1, x_2) \in M_{3 \times 3}\mathbb{C}$, with columns $x_0, x_1, x_2 \in \mathbb{C}^3$. Let $W = X^\top X \in \mathrm{Sym}_n\mathbb{C}$, so $W_{ij} = \langle x_i, x_j \rangle$.

Lemma 4.2 With X and W as above,

- (1) $\ker X^{\top} \cap \mathcal{L} = \{0\}$ if and only if rank $W \ge 2$.
- (2) Assuming (a), if for some $Y \in M_{3\times 3}\mathbb{C}$, $X^{\top}X = Y^{\top}Y$ and $\det X = \det Y$, then there exists a unique $S \in SO_3\mathbb{C}$ such that Y = SX.

Proof By the rank-nullity theorem applied to $X^{\top}|_{\text{image }X}$,

$$\operatorname{rank} X = \dim(\ker X^{\top} \cap \operatorname{image} X) + \operatorname{rank} W \tag{4.14}$$

from which it follows that rank $X \ge \operatorname{rank} W$, and rank W = 3 if rank X = 3.

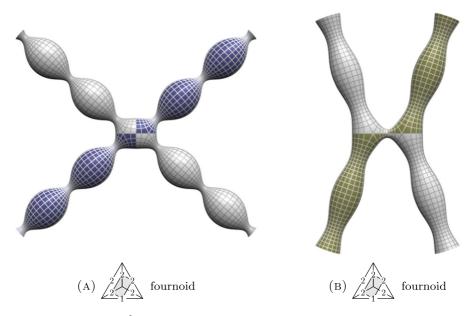


Fig. 32 CMC spheres in \mathbb{R}^3 with Delaunay ends



Moreover, if rank $X \ge 2$, then

$$\ker X^{\top} \cap \operatorname{image} X = \ker X^{\top} \cap \mathcal{L} . \tag{4.15}$$

To prove (4.2), assume rank $W \geqslant 2$, so rank X = 2. By Eq. 4.14, dim(ker $X^{\top} \cap$ image X) = 0. By Eq. 4.15, ker $X^{\top} \cap \mathcal{L} = \{0\}$.

Conversely, assume $\ker X^{\top} \cap \mathcal{L} = \{0\}$. Then rank $X \geqslant 2$ because every 2-dimensional subspace of \mathbb{C}^3 intersects \mathcal{L} . By Eq. 4.15, $\ker X^{\top} \cap \mathcal{L} = \{0\}$. By Eq. 4.14, rank $W = \operatorname{rank} X \geqslant 2$.

To prove (4.2) in the case rank W = 3, since rank $X = \operatorname{rank} Y = 3$, define $S := YX^{-1}$. Then $S \in \operatorname{SO}_3\mathbb{C}$ by $X^\top X = Y^\top Y$ and det $X = \det Y$.

To prove (4.2) in the case rank W=2, let x_a , x_b be two independent columns of X and let $\hat{X}=(x_a, x_b, x_a \times x_b)$ and $\hat{Y}=(y_a, y_b, y_a \times y_b)$. Since $x_a \times x_b \in \ker X^\top$, then by the assumption and Lemma 4.2 (4.2), $x_a \times x_b \notin \mathcal{L}$. Then det $\hat{X}=\langle x_a \times x_b, x_a \times x_b \rangle \neq 0$ so rank $\hat{X}=3$. Moreover, since $\langle x_a \times x_b, x_a \times x_b \rangle = \langle y_a \times y_b, y_a \times y_b \rangle$, then $\hat{X}^\top \hat{X}=\hat{Y}^\top \hat{Y}$. Then $S:=\hat{Y}\hat{X}^{-1}$ is in SO₃C, and Y=SX.

Identify \mathbb{C}^4 with $\mathfrak{gl}(2, \mathbb{C})$ by identifying the standard basis E_0 , E_1 , E_2 , E_3 with \mathbb{I} , e_0 , e_1 , e_2 , where

$$e_0 := \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$$
, $e_1 := \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$, $e_2 := \begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix}$. (4.16)

Under this identification, the standard inner product on \mathbb{C}^4 is

$$\langle x, y \rangle = \frac{1}{2} \operatorname{tr} x \operatorname{adj}(y) , \operatorname{adj} \begin{bmatrix} a & b \\ c & d \end{bmatrix} := \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$
 (4.17)

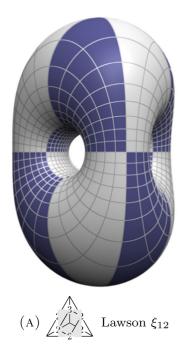
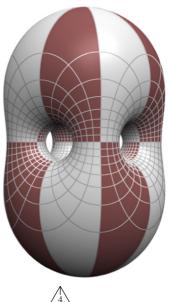


Fig. 33 Minimal Lawson surfaces in \mathbb{S}^3







and $SU_2 \subset SL_2\mathbb{C}$ is identified with $\mathbb{R}^4 \subset \mathbb{C}^4$. In particular, for $X, Y \in \mathfrak{sl}(2, \mathbb{C})$ it holds $\langle x, y \rangle = -\frac{1}{2} \operatorname{tr} xy$.

In order to treat irreducibility, the following lemma translates the notion of eigenline to a more convenient form. With $\begin{bmatrix} a \\ b \end{bmatrix}^{\perp} := \begin{bmatrix} -b & a \end{bmatrix}$ consider the double cover

$$\hat{x} \in \mathbb{C}^2 \setminus \{0\} \to \{x \in \mathfrak{sl}(2, \mathbb{C}) \mid \det x = 0\} , \quad \hat{x} \mapsto x = \hat{x}\hat{x}^{\perp} .$$
 (4.18)

Lemma 4.3 $\ell \in \mathbb{C}^2 \setminus \{0\}$ is an eigenvector of the invertible matrix $x \in SL_2\mathbb{C}$ if and only if $\langle x, \ell \ell^{\perp} \rangle = 0$.

Proof For any $p, q \in \mathbb{C}^2 \setminus \{0\}$,

$$\operatorname{tr} q p^{\perp} = p^{\perp} q = \det(p, q) . \tag{4.19}$$

So with $p = \ell$, $q = x\ell$, and $y = \ell\ell^{\perp}$

$$2\langle x, y \rangle = 2\langle x, \ell \ell^{\perp} \rangle = \det(x\ell, \ell) \tag{4.20}$$

so $\langle x, y \rangle = 0$ if and only if $x\ell$ and ℓ are dependent, that is, if and only if ℓ is an eigenline of x.

Let \mathcal{P} be the group generated by $P_0 = \mathbb{1}$, P_1 , P_2 , $P_3 \in SL_2\mathbb{C}$. Under the above identification $\mathbb{C}^4 \cong \mathfrak{gl}(2, \mathbb{C})$ let $P = (P_0, P_1, P_2, P_3) \in M_{4\times 4}\mathbb{C}$ be a matrix with columns $P_k \in \mathbb{C}^4$. Let $T = P^\top P \in \text{Sym}_4\mathbb{C}$, so $T_{ij} = \langle P_i, P_j \rangle$.

Theorem 4.4 With P and T as above,

(1) \mathcal{P} is irreducible if and only if rank $T \geq 3$.

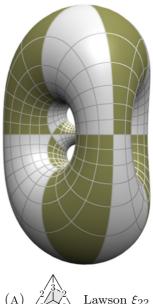




Fig. 34 Minimal Lawson surface in \mathbb{S}^3



Proof We have the factorization

$$T = \begin{bmatrix} \mathbb{1} & 0 \\ V^{\top} & \mathbb{1} \end{bmatrix} \begin{bmatrix} \mathbb{1} & 0 \\ 0 & X^{\top} \end{bmatrix} \begin{bmatrix} \mathbb{1} & 0 \\ 0 & X \end{bmatrix} \begin{bmatrix} \mathbb{1} & V \\ 0 & \mathbb{1} \end{bmatrix} , \quad P = \begin{bmatrix} 1 & V \\ 0 & X \end{bmatrix} . \tag{4.21}$$

To prove (4.4), let $X = (x_0, x_1, x_2) \in M_{3\times 3}\mathbb{C}$ be the lower right 3×3 submatrix of P, that is the matrix with columns given by the tracefree parts of P_1 , P_2 , P_3 , and let $Y := X^\top X$. By Lemma 4.3, \mathcal{P} is irreducible if and only if $\ker X^\top \cap \mathcal{L} = \{0\}$. By Lemma 4.2 this is if and only if $\operatorname{rank} Y \geqslant 2$. Since $\operatorname{rank} T = 1 + \operatorname{rank} Y$, this is if and only if $\operatorname{rank} T \geqslant 3$.

To prove (4.4), if \mathcal{P} is SU_2 unitarizable, it may be assumed without loss of generality that $\mathcal{P} \subset SU_2$. Then $P \in M_{4\times 4}\mathbb{R}$, so $T = T^\top T \in Sym_4\mathbb{R}$ is real positive semidefinite.

Conversely, if T is real positive semidefinite, then $W = X^{\top}X = Y^{\top}Y$ for some $Y \in M_{3\times 3}\mathbb{R}$. Replacing $Y \mapsto -Y$ if necessary, then det $X = \det Y$, so by Lemma 4.2 (4.2), there exists $S \in SO_3\mathbb{C}$ such that X = SY. Let $C \in SL_2\mathbb{C}$ be a lift of S via the double cover $SL_2\mathbb{C} \mapsto SO_3\mathbb{C}$ defined with respect to \mathbb{I} , e_1 , e_2 , e_3 . Note that this double cover is given by conjugation on $\mathfrak{sl}(2,\mathbb{C}) \cong \mathbb{C}^3$. Then C unitarizes \mathcal{P} .

4.5 Constructing the surface

Once the potential for a surface is obtained via the unitary flow, the surface is constructed as follows:

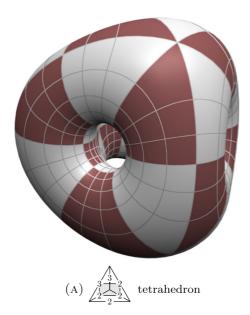


Fig. 35 Minimal surface in \mathbb{S}^3 with Platonic symmetry

- Compute the unitarizer of the monodromy.
- Compute curvature lines.
- Compute the fundamental piece of the surface via the DPW construction
- Build the surface from the fundamental piece by reflections.

4.5.1 The unitarizer

Due to the symmetry (4.2) of the potential and of the monodromies with basepoint z = 1 the unitarizer is diagonal and can be computed as follows. With the notation $a^*(\lambda) = \overline{a(1/\overline{\lambda})}$ write

$$M_0 = \begin{bmatrix} a & b \\ c & a^* \end{bmatrix} . (4.22)$$

By the unitarizability of M_0 by a diagonal loop, $p := -c^*/b = -c/b^*$ takes values in \mathbb{R}_+ along \mathbb{S}^1 away from its zeros and poles, which are even. Let $f = \prod (\lambda - \alpha)/\prod (\lambda - \beta)$ so that f^*f has the same zeros and poles as p. Then $q = p/(f^*f)$ takes values in \mathbb{R}_+ along \mathbb{S}^1 without zeros or poles. Let $y^*y = q$ be the scalar $GL_1\mathbb{C}$ Birkhoff factorization, so y is holomorphic in the unit disk. Then with x = fy the loop diag $(x^{1/2}, x^{-1/2})$ is the required unitarizer, holomorphic on the open unit disk.

4.5.2 Curvature lines

Let $Q = q(z)dz^2$ the Hopf differential of the CMC surface. The curvature line coordinate v satisfies $dv^2 = Q(z)dz^2$. Curvature line coordinates can be computed by computing $\int \sqrt{Q(z)} dz$ over the domain.

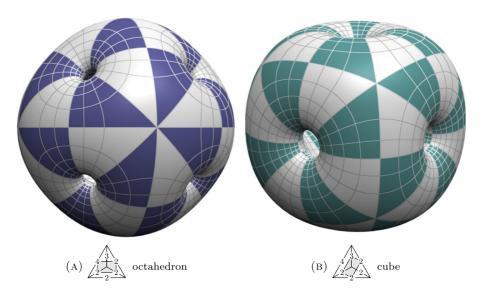


Fig. 36 Minimal surfaces in \mathbb{S}^3 with Platonic symmetry



The surface is computed numerically by dividing the domain into polygons (triangles or quadrilaterals) and mapping via the CMC immersion these triangles to \mathbb{R}^3 . In the computation of curvature lines described above, the polygon edges are unrelated to the curvature lines.

Quadrilaterals whose edges are along curvature lines can be computed as follows. Divide the domain into quadrilaterals whose edges are curvature lines and such that the umbilics are at corners of the quadrilaterals. For each quadrilateral, pull back the potential to curvature line coordinates.

This computation is complicated by the fact that the maps from curvature lines rectangles to the domain are singular at the umbilics, and the potential is singular at the umbilics. The potential can be desingularized locally at an umbilic z_0 by a coordinate change of the form $z = z_0 + w^n$ and a gauge.

4.5.3 Building the surface

In general the position of the surface in space is not controlled, so to build the surface it must first be put into a standard position, where a group of standard reflections can be applied. To do so, compute the four generating reflections R_k in the isometry group Iso \mathbb{R}^3 of \mathbb{R}^3 . Conjugate them to standard reflections S_k via $CR_kC^{-1} = S_k$. Then the surface after being moved via $x \mapsto Cx$ has the standard reflections S_k as symmetries.

4.5.4 The bulge count for families of CMC surfaces

The surfaces constructed in this paper allow for non-trivial 1-parameter deformations within the space of CMC surfaces with the same combinatorics. A natural question,

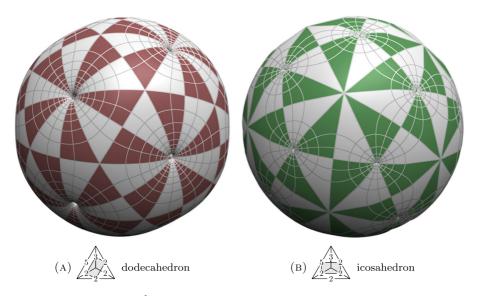


Fig. 37 Minimal surfaces in \mathbb{S}^3 with Platonic symmetry

also considered by [8], is whether different surfaces with the same combinatorics, but which swap neck and bulge, belong to the same family of CMC surfaces, for example Figs. 1a, b and 16a, b. It turns out that these examples belong to different families. We denote by a leg of the surface a cylindrical piece obtained from the trajectories of the Hopf differential, that is from the curvature line parametrisation. Although the images are labeled according to whether there are bulges or necks where the legs meet, in this section we rather count the number of bulges on each leg.

We show that this number is an invariant in the case of surfaces without ends. Note that in this case, there is a covering $\Sigma \to \mathbb{C}P^1$ by a compact Riemann surface Σ on which the pullback of the DPW potential has only apparent singularities. Phrased differently, Σ is the surface on which the first and second fundamental forms are well-defined and smooth, that is for compact CMC surfaces in the 3-sphere, Σ is just the underlying Riemann surface, and in the case of periodic CMC surfaces in \mathbb{R}^3 , Σ is the Riemann surface quotient of the CMC surface by the translational symmetries.

We construct surfaces starting from Delaunay cylinders by deforming the eigenvalues ν_i . In the case of cylinders without umbilics, all four eigenvalues are $\nu_i = \frac{1}{4}$. At the starting point, Σ is a torus and the relevant moduli space of flat connections ∇ on Σ has only reducible points. The underlying holomorphic bundles (equipped with the (0, 1)-parts $\bar{\partial}^{\nabla}$ of the connections) are semistable, i.e. if they admit holomorphic line subbundles of degree 0. A holomorphic structure (on a rank 2 bundle over a compact Riemann surface of degree 0) is called unstable if there exist a holomorphic line subbundle of positive degree and they are called stable if every holomorphic line subbundle has negative degree. This notion is relevant to us since an unstable holomorphic structure does not admit a flat unitary connection. Spectral parameters λ at which the holomorphic structure is unstable are isolated in the spectral plane.

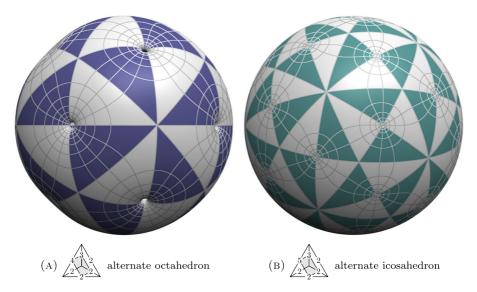


Fig. 38 Minimal surfaces in \mathbb{S}^3 with Platonic symmetry



Moreover, for CMC surfaces based on quadrilaterals, the number of those values of spectral parameters within a bounded region is always finite and can only change during a deformation by values crossing the boundary of that region. Values of the spectral parameter at which the holomorphic structure is unstable cannot cross the unit circle, as the connections on the unit circle are unitary. For the initial torus the bundle is semistable for all spectral values. The number of values at which the holomorphic bundle becomes unstable within infinitesimal deformation of the eigenvalues v_i can be identified with the number of bulges on the leg of the initial Delaunay cylinder; for more details see [12]. Actually this number coincides with the number of zeros of the holomorphic function x in Eq. 4.2 inside the unit circle; see also

5 Fuchsian DPW potentials

The aim of this section is to prove the existence of Fuchsian DPW potentials of the form Eq. 4.1 for CMC quadrilaterals without Delaunay ends. This generalizes previous work by the second author [14] for the Lawson genus 2 surface. Similar results have been obtained by Manca [19]. Our arguments are more geometric and prove the existence of a Fuchsian potential on a 4-punctured sphere for all surfaces obtained by CMC quadrilaterals.

5.1 Setup

[11, 15]

Let $f: \Sigma \to M$ (where $M \in \{\mathbb{S}^3, \mathbb{R}^3\}$) be a complete CMC surface without Delaunay ends. Assume that f is build from a fundamental piece P by the group G generated by the reflections across totally geodesic subspaces along geodesic arcs contained in P. Assume that P has the topology of a (closed) disc.

The surface f is equivariant with respect to the (discrete) group G acting on Σ by conformal transformations and on the ambient space M by a representation ρ into the space of isometries. Let $G^o \subset G$ be the subgroup of orientation preserving (i.e. holomorphic) symmetries on Σ .

5.2 Local theory

The first step in our derivation of a Fuchsian DPW potential is the converse of Theorem 3.5. This means that at fixed points of a rotational symmetry there always exists DPW potentials with Fuchsian singularity on the quotient.

Let $p \in \Sigma$ be a fixed point of some rotation given by an element in G^o . Then there exists $k \in \mathbb{N}$ and $g \in G^o$ of order k such that g(p) = p and such that for any $h \in G^o$ with h(p) = p there exists $l \in \mathbb{N}$ with $g^l = h$.

Lemma 5.1 There exists $D \in SU_2$ of order 2k and a local DPW potential η for f on an open g-invariant neighbourhood of p such that

$$g^* \eta = D \eta D^{-1} \ . \tag{5.1}$$



Proof Consider Dorfmeister's normalized potential (see for example [29]) which takes the form

$$\eta^{nor} = \begin{bmatrix} 0 & \lambda^{-1} f(z, 0) \\ \frac{q}{f(z, 0)} & 0 \end{bmatrix} dz$$
 (5.2)

where z is a local holomorphic coordinate centered in p such that $g^*z=e^{\frac{2\pi i}{k}}z$, $Q=q(dz)^2$ is the Hopf differential and f(z,w) is a holomorphic function such that $f(z,\bar{z})dzd\bar{z}$ is the induced metric of the surface. As $g^*dz=e^{\frac{2\pi i}{k}}dz$ and $g^*d\bar{z}=e^{\frac{2\pi i}{k}}d\bar{z}$ the result follows.

Proposition 5.2 There exists a local meromorphic DPW potential of f on Σ/G^o with a Fuchsian singularity at $p \mod G^o$. The eigenvalues of the residue are $\pm \frac{1}{2k}$, independently of λ , where k is the order of the stabilizer group of p.

Likewise, there exists a local meromorphic DPW potential of f on Σ/G^o with Fuchsian singularity at $p \mod G^o$ such that the eigenvalues of the residue are $\pm \frac{k-1}{2k}$.

Proof Consider $w=z^k$ which is a holomorphic coordinate centered at $p \mod G^o \in \Sigma/G^o$. Consider the positive gauge $e=\operatorname{diag}\left(\sqrt{z},\frac{1}{\sqrt{z}}\right)$ of spin -1. Then

$$(d + \eta^{nor}).e = d + e^{-1}de + e^{-1}\eta^{nor}e$$
 (5.3)

is a well-defined meromorphic DPW potential with apparent Fuchsian singularity at p. As this potential is clearly invariant under pull-back by g we have proven the first part of the proposition.

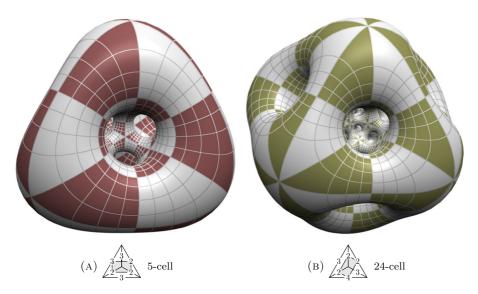


Fig. 39 Minimal surfaces in \mathbb{S}^3 with *n*-cell symmetry



For the second part and k=2l+1 consider the gauge $\tilde{e}=\operatorname{diag}(z^{-l},z^l)$ while for k=2l consider the gauge $\tilde{e}=\operatorname{diag}(z^{-l+\frac{1}{2}},z^{l-\frac{1}{2}})$, and proceed as in the first part of the proof.

5.3 Global theory

Our aim is to construct a DPW potential on the Σ/G^o . Recall that by assumption the fundamental piece P of the Riemann surface Σ is of the topological type of a disc.

Lemma 5.3 *The Riemann surface* Σ/G^o *is the projective line.*

Proof By the Riemann mapping theorem there exists a holomorphic map from P to the unit disc. Schwarzian reflection yields a holomorphic map from Σ to $\mathbb{C}P^1$, branched at the fixed points of G^o . By its construction, this map is invariant under G^o .

For simplicity of the arguments, we will assume that *n* is even in the following.

Lemma 5.4 Let n be even. There exists a unitary potential μ on the n-punctured Riemann sphere such that

- μ is singular exactly at the branch values of $\Sigma \to \Sigma/G^o = \mathbb{C}P^1$;
- the pull-back of μ generates f on the covering Σ .

Proof Let $\{z_1, \ldots, z_n\} \subset \mathbb{C}P^1$ be the branch values of $\Sigma \to \Sigma/G^o = \mathbb{C}P^1$ and $S \subset \Sigma$ its preimage. Denote the reflection planes of the fundamental piece by

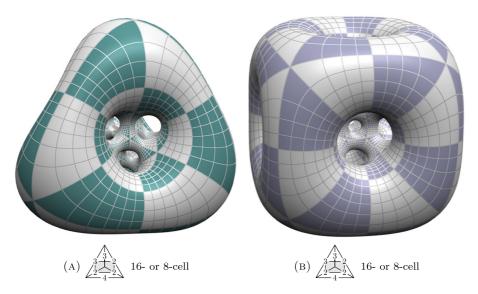


Fig. 40 Minimal surfaces in \mathbb{S}^3 with *n*-cell symmetry

 P_0, \ldots, P_{n-1} , with outward oriented unit normals N_0, \ldots, N_{n-1} , respectively, such that

$$z_m \in P_{m-1} \cap P_m \quad \forall m \in \{1, \dots, n\}$$
 (5.4)

Denote by g_m the compositions of the reflection across P_{m-1} and P_m . Then G^0 is generated by $\{g_m \mid m \in \{1, ..., n\}\}$.

Let M be euclidean 3-space or the 3-sphere, and let d=3 and d=4 accordingly, so that $Iso(M)=SO_4\mathbb{R}$ or $Iso(M)=SO_3\mathbb{R}\ltimes\mathbb{R}^3$.

Consider the group

$$H \subset \operatorname{Spin}_n \times \operatorname{Iso}(M)$$
 (5.5)

generated by the elements

$$\hat{g}_m := (N_m \cdot N_{m-1}, g_m), \quad m = 1, \dots, n$$
 (5.6)

where · denotes Clifford multiplication. This gives a group extension

$$\{id\} \to \mathbb{Z}_2 \to H \to G^0 \to \{id\}$$
 (5.7)

Note that \hat{g}_m has order 2k if g_m has order k. Similarly, since n is even, the product $\hat{g}_n \dots \hat{g}_1$ is trivial. Consequently, we have a representation

$$h: \pi_1(\mathbb{C}\mathrm{P}^1 \setminus \{z_1, \dots, z_n\}, *) \to H . \tag{5.8}$$

As

$$\Sigma \setminus S \to \mathbb{C}P^1 \setminus \{z_1, \dots, z_n\}$$
 (5.9)

is a (unbranched) covering, the fundamental group of $\Sigma \setminus S$ (with appropriate base point) is a subgroup of the first fundamental group of $\mathbb{C}P^1 \setminus \{z_1, \ldots, z_n\}$ with corresponding base point. By construction, the induced representation of $\pi_1(\Sigma \setminus S, *) \to G^0$ is trivial, and the induced representation of h takes values in

$$\mathbb{Z}_2 = \mathbb{Z}_2 \times \{ id \} \subset \mathrm{Spin}_d \times \mathrm{Iso}(M) \tag{5.10}$$

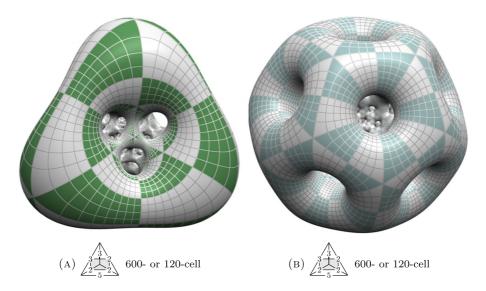


Fig. 41 Minimal surfaces in \mathbb{S}^3 with *n*-cell symmetry



such that a simple closed curve around any one of the points in S is mapped to the non-trivial element in \mathbb{Z}_2 .

By Riemann surface covering theory, we obtain a 2-fold covering

$$\hat{\Sigma} \to \Sigma$$
 , (5.11)

branched over the points in S, with an action of H by holomorphic automorphisms on $\hat{\Sigma}$ such that

$$\hat{\Sigma} \to \hat{\Sigma}/H = \mathbb{C}P^1 \tag{5.12}$$

is branched over $\{z_1, \ldots, z_n\}$. Denote its preimage of S by $\hat{S} \subset \hat{\Sigma}$. Note that H acts faithfully on $\hat{\Sigma} \setminus \hat{S}$.

Consider the pull-back ω on $\hat{\Sigma}$ of the unitary potential $\eta = F^{-1} dF$ of f. Note that, for minimal $f: \Sigma \to \mathbb{S}^3$ the unitary potential is given by

$$\eta = \lambda^{-1}\Phi + \Phi - \Phi^* - \lambda\Phi^* \tag{5.13}$$

where

$$\Phi = \frac{1}{2}(f^{-1}df)^{1,0}$$
 and $\Phi^* = \frac{1}{2}(f^{-1}df)^{0,1}$ (5.14)

and similarly for CMC surfaces $f: \Sigma \to \mathbb{R}^3$. Let $\pi: H \to SU_2$ be the projection to the rotational part of the symmetry. From the construction (5.13) of the unitary potential,

$$h^* \eta_{\lambda} = \eta_{\lambda} . \pi(h) \tag{5.15}$$

for a holomorphic automorphism $h \in H$ (where, on the right hand side, the gauge action of the constant matrix $\pi(h)$ is given by conjugation).

Consider the free action of H on $\hat{\Sigma} \setminus \hat{S} \times \mathbb{C}^2$ given by

$$(p, v).h = (p.h, \pi(h^{-1})(v)) . (5.16)$$

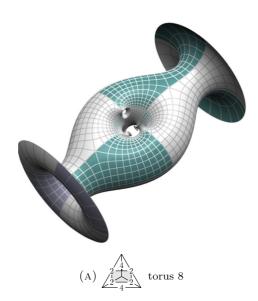


Fig. 42 Minimal torus in \mathbb{S}^3 with Delaunay ends

The quotient

$$V = (\hat{\Sigma} \setminus \hat{S} \times \mathbb{C}^2)/H \tag{5.17}$$

is a trivial smooth vector bundle of rank 2 over $\mathbb{C}P^1 \setminus \{z_1, \ldots, z_n\}$. We claim that the unitary potential ω yields a well-defined potential μ on this vector bundle: in fact, the connection 1-form acts on $[p, v] \in (\hat{\Sigma} \setminus \hat{S} \times \mathbb{C}^2)/H$ as

$$[p, \omega_p(v)] \tag{5.18}$$

which is well-defined since

$$(p, \omega_p(v)).h = (ph, h^{-1}\omega_p h h^{-1}(v)) = (ph, \omega_{ph}(h^{-1}v)) . \tag{5.19}$$

Proposition 5.5 Let n be even. There exist a meromorphic DPW potential ξ on $\mathbb{C}P^1$ with simple poles at z_1, \ldots, z_n and possible apparent singularity at $z = \infty$.

Proof From Lemma 5.4 we obtain a unitary potential μ on the n-punctured sphere. Let $l \in \{1, \ldots, n\}$. By Proposition 5.2 there exist a DPW gauge locally well-defined on a punctured disc around z_l which gauges μ into a meromorphic potential with a Fuchsian singularity at z_l . Of course, the holomorphic structures (i.e. the (0, 1)-part) of a meromorphic potential extends to the singular points. Note that these gauges are well-defined (i.e. have spin 1) as we have chosen the representation $s: \pi_1(\Sigma \setminus S, \mathbb{Z}_2)$ to have local monodromy -1 around every point in S.

Using these gauges as cocycles, we obtain a holomorphic \mathbb{C}^* -family of flat $SL_2\mathbb{C}$ -connections $d + \hat{\mu}$ with the following properties:

- the induced family of holomorphic structures extends to $\lambda=0$ to give a holomorphic rank 2 bundle $\mathcal{E}_0\to\mathbb{C}P^1$ with trivial holomorphic determinant;
- the connections $d + \hat{\mu}$ have Fuchsian singularities with λ -independent eigenvalues $\pm \frac{1}{2k}$;
- the complex linear part of the family of connections has a first order pole at $\lambda = 0$, i.e., $\lambda \mapsto \lambda(\hat{\mu})^{1,0}(\lambda)$ extends to $\lambda = 0$.

Note that all bundles have trivial determinant. Hence, by the Birkhoff-Grothendieck theorem, the bundle type of \mathcal{E}_0 is $\mathcal{O}(d) \oplus \mathcal{O}(-d)$ for some $d \in \mathbb{N}$.

First consider the case d=0. Then, the bundle type \mathcal{E}_{λ} is locally constant on an open disc near $\lambda=0$. In particular, there exists a smooth positive family of gauge transformations g_{λ} (holomorphic in λ) such that

$$((d+\hat{\mu}).g_{\lambda})^{0,1} = d^{0,1} \tag{5.20}$$

is the trivial holomorphic structure on the rank 2 vector bundle $\mathbb{C}^2 \to \mathbb{C}P^1.$ Thus

$$d + \xi := (d + \hat{\mu}).g_{\lambda} \tag{5.21}$$

is the meromorphic DPW potential which has only Fuchsian singularities and no apparent singularity at ∞ .

Let d > 0. Let $z : \mathbb{C}P^1 \setminus \{\infty\} \to \mathbb{C}$ be an affine holomorphic coordinate and assume without loss of generality that $z_l \neq \infty \quad \forall \ l \in \{1, ..., n\}$. There exists an integer $0 \leq s \leq d$ such that on a punctured disc $\mathcal{D} \setminus \{0\}$ around $\lambda = 0$ all bundles



are of the holomorphic type $\mathcal{O}(s) \oplus \mathcal{O}(-s)$. By the family version of Birkhoff-Grothendieck, there exists a holomorphic function $r \colon \mathcal{D} \to \mathbb{C}$ with r(0) = 0 such that the holomorphic bundle $((d + \hat{\mu}).g_{\lambda})^{0,1}$ has the cocycle (for the covering $\mathcal{U}_+ := \mathbb{C}, \mathcal{U}_- := \mathbb{C}P^1 \setminus \{\infty\}$ of $\mathbb{C}P^1$)

$$\begin{bmatrix} z^{-d} & z^s r(\lambda) \\ 0 & z^d \end{bmatrix} = \begin{bmatrix} r(\lambda)z^s & 0 \\ z^d & \frac{1}{r(\lambda)}z^{-s} \end{bmatrix} \begin{bmatrix} \frac{1}{r(\lambda)}z^{-d-s} & 1 \\ -1 & 0 \end{bmatrix} , \qquad (5.22)$$

where the equality obviously holds only for $r(\lambda) \neq 0$. Again, there exists a DPW gauge g_{λ} which gauges \mathcal{E}_{λ} into the above form Eq. 5.22. This means that there exists a pair $(g_{\lambda}^+, g_{\lambda}^-)$ of DPW gauges on \mathcal{U}_+ respectively \mathcal{U}_- which differ by the gauge (5.22) and gauge $(d + \hat{\mu})^{0,1}$ on \mathcal{U}_{\pm} to the trivial holomorphic structure on $\mathbb{C}^2 \to \mathcal{U}_+$. Then,

$$(d + \hat{\mu}).g_{\lambda}^{+} =: d + \xi \tag{5.23}$$

yields the meromorphic potential ξ with Fuchsian singularities at z_k and an apparent singularity at ∞ .

5.3.1 CMC quadrilaterals

Finally, we consider the case of CMC quadrilaterals, i.e., n=4. We show that these are always determined by a Fuchsian DPW potential (4.1), which, assuming an additional symmetry, is of the form (4.2).

Lemma 5.6 For n = 4 the bundle type of \mathcal{E}_0 is either trivial or $\mathcal{O}(1) \oplus \mathcal{O}(-1) \to \mathbb{C}P^1$.

Proof Assume the bundle type at $\lambda = 0$ is $\mathcal{O}(d) \oplus \mathcal{O}(-d) \to \mathbb{C}\mathrm{P}^1$ for some d > 1. The Higgs field $\Phi := \mathrm{res}_{\lambda=0}\xi$ is a meromorphic section of the bundle

$$K \otimes \operatorname{End}_0(\mathcal{E}_0) \to \mathbb{C}P^1$$
 (5.24)

where $K = \mathcal{O}(-2)$ is the canonical bundle of $\mathbb{C}P^1$ and $\operatorname{End}_0(\mathcal{E}_0)$ denotes the trace-free endomorphisms of \mathcal{E}_0 . Moreover, Φ is nilpotent as the immersion is conformal, has at most simple poles at z_1, \ldots, z_4 by construction and does not vanish on $\mathbb{C}P^1$ as f is an immersion. Using the decomposition $\mathcal{E}_0 = \mathcal{O}(d) \oplus \mathcal{O}(-d)$ the Higgs field is of the form

$$\Phi = \begin{bmatrix} a & b \\ c & -a \end{bmatrix} \tag{5.25}$$

where a, b, c are meromorphic sections in $\mathcal{O}(-2)$, $\mathcal{O}(-2+2d)$, $\mathcal{O}(-2-2d)$, respectively, with at most simple poles at z_1, \ldots, z_4 . Hence c = 0. As Φ is nilpotent a = 0 as well. For d > 1, -2 + 2d > 0 and b would have a zero contradicting the fact that Φ is nowhere vanishing.

Theorem 5.7 Let f be a complete CMC surface without Delaunay ends in \mathbb{S}^3 or \mathbb{R}^3 . If f is built from a CMC quadrilateral in a fundamental tetrahedron of a tessellation of the ambient space then it is obtained from a Fuchsian DPW potential (4.1) on the 4-punctured sphere.



Proof We give a proof by contradiction. Assume that the bundle type at $\lambda = 0$ is

$$\mathcal{E}_0 = \mathcal{O}(-1) \oplus \mathcal{O}(1) . \tag{5.26}$$

By the proof of Proposition 5.2 the nilpotent λ^{-1} -part $\Phi = \xi_{-1}$ of the meromorphic potential has no zeros, and poles of order 1 at the 4 branch points z_1, \ldots, z_4 . Thus, with respect to Eq. 5.26, it must be of the form

$$\Phi = \begin{bmatrix} 0 & s_{-D} \\ 0 & 0 \end{bmatrix} \tag{5.27}$$

where $s_{-D} \in \mathcal{M}(\mathbb{C}P^1, \mathcal{O}(-4))$ is the unique meromorphic section (up to scaling) with simple poles at $D = z_1 + \cdots + z_4$. Moreover, the positive eigenvalues v_i of the residues of the connections are contained in the respective kernels of the residues of ξ_{-1} . This equips \mathcal{E}_0 with a parabolic structure (see for example [3, 11, 21, 23, 26] for definitions and further references) which is unstable. We denote the parabolic bundle also by \mathcal{E}_0 . The pair (\mathcal{E}_0, Φ) is a stable strongly parabolic Higgs pair. Note that

$$\sum_{i} \nu_i < 1 . \tag{5.28}$$

It is easy to see (compare with [11]) that (\mathcal{E}_0, Φ) is the only stable strongly parabolic Higgs pair with nilpotent Higgs field on the 4-punctured sphere with unstable underlying parabolic bundle. Consider the compact Riemann surface $X \to \mathbb{C}P^1$ on which the rotational symmetry is trivial. Its Fuchsian monodromy (given by uniformization) corresponds by the Hitchin-Kobayashi correspondence to a stable nilpotent Higgs pair

$$\left(S^* \oplus S , \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right) , \tag{5.29}$$

where $S^2 = K_X$. Its underlying holomorphic structure is unstable. As the rotational symmetries act on X we obtain, in the same manner as for f, an strongly parabolic nilpotent Higgs pair with underlying parabolic structure. As the holomorphic structure is unstable, the parabolic structure must be unstable as well; see [2], and hence it must be (\mathcal{E}_0, Φ) . Thus, the holomorphic Higgs pair of f, i.e., $(\partial^{\nabla}, \Phi)$ would be gauge equivalent to $(S^* \oplus S, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix})$. This is only possible if the Hopf differential of the minimal (respectively CMC) surface vanishes (compare with [14, sections 2 and 3]), which gives a contradiction.

Finally, we show under which conditions the Fuchsian DPW potential ξ can be gauged into the form (4.2).

Note that a Fuchsian potential for a CMC quadrilateral defining a compact embedded CMC surface cannot be adapted if all the 4 positive eigenvalues of the residues are contained in $(0, \frac{1}{4})$.

Corollary 5.8 Assume that the potential of Corollary 5.7 has equal pairs of eigenvalues. Then, there exist a coordinate change and a gauge such that the potential is of the form (4.2).



Proof We only sketch the proof. Assume that the eigenvalues at z_0 and z_1 , respectively z_2 and z_3 are equal. First, apply a so-called flip gauge which flips the eigenvalues at z_2 and z_3 by adding $\mp \frac{1}{2}$. This can be achieved by conjugating the potential by a DPW gauge which is constant in z such that the residues at z_2 and z_3 are lower respectively upper triangular, and then gauge with diag $\left(\sqrt{\frac{z-z_2}{z-z_3}}, \sqrt{\frac{z-z_3}{z-z_2}}\right)$.

Denote the residues of the potential $\tilde{\xi}$ obtained in this way by R_k , and find T such that $R_3 = TD^{-1}T^{-1}R_2TDT^{-1}$. Then, $T^{-1}\tilde{\xi}T$ turns out to be of the form (4.2). \square

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