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Error-correction coding in the MagiCtwin Diode

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Eindhoven University of Technology Department of Mathematics and Computer Science

Error-correction coding in the MagiCtwin Diode

Bachelor final project Applied Mathematics

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Chapter 1

Introduction

This thesis is the final submission for the bachelor's program Applied Mathematics at Eindhoven University of Technology. It is supervised by Benne de Weger from research group Coding theory & Cryptology at Eindhoven University of Technology. The assessment committee was formed by Benne de Weger and Altan Kiliç. In addition, Alex Pellegrini has been of help in mathematical support. This thesis focuses on coding theory and the implementation of coding theory in a Dutch company called Computatica. The project was overseen by Berry Busser, the direct supervisor at Computica, and Ries van Son, Chief Technology Officer and Computatica's primary supervisor of this thesis.

In this thesis, we will elaborate on how Computatica currently implements error-correcting coding in one of their products: the MagiCtwin Diode. The company had some questions as to how efficient the implemented error-correcting code in the MagiCtwin Diode is, and whether there were any paths towards improvement. We will therefore evaluate the efficiency of their implementation of errorcorrecting coding, and discuss various ways to make the coding more efficient. We will conclude with recommendations for improvements, possible substitutes and suggestions for further research.

In order to introduce error-correcting coding in the MagiCtwin Diode and make a meaningful assessment of the code's efficiency and its possible substitutes later in this thesis, we will kick off by introducing information theory. Information theory formalizes communication in a scientific manner. In this thesis we interpret communication as the transmission of information via a certain channel. After that, we will continue with a mathematical explanation of error-correcting coding, the detection and restoration of erasures in particular. Also, we will briefly touch the topic of interleaving. Subsequently, more details about Compumatica and the MagiCtwin Diode will be provided. This is directly followed by a thorough explanation of Compumatica's implementation of a Cauchy Reed-Solomon error-correcting code. Thereafter, we will assess the code's efficiency, suggest improvements and propose possible substitutes for the Cauchy Reed-Solomon code. We will conclude with a recommendation on how Compumatica can improve the efficiency of error-correcting coding in the MagiCtwin Diode.

Note: This report assumes the reader has a mathematical background that is comparable to that of a bachelor's student Applied Mathematics. This includes a working knowledge of linear algebra, algorithmic algebra and finite field arithmetic.

Chapter 2

Preliminaries

In this thesis we make use of finite fields of order p^m , where p is prime and $m \in \mathbb{N}_{>0}$. Finite fields are also called Galois Fields (Edwards, 1984). The mathematical notation for a finite field of order p^m is \mathbb{F}_{p^m} . A computer scientists might denote this same field by $GF(p^m)$ (Galois Field of order p^m), but in this thesis we will adopt the mathematical notation \mathbb{F}_{p^m} .

In this thesis, we will consider the case where p = 2 and m = 8, meaning we look at $\mathbb{F}_{2^8} = \mathbb{F}_{256}$.

The finite field \mathbb{F}_{256} is usually denoted by having a zero-element and elements that are powers of a primitive element α in the following way.

$$\mathbb{F}_{256} = \{0, 1, \alpha, \alpha^2, \dots, \alpha^{254}\}$$
(2.1)

However, in this thesis we denote the finite field \mathbb{F}_{256} and its elements in another way: using an isomorphism between \mathbb{F}_{256} and \mathbb{F}_2^8 . For this, first consider integers $0, 1, \ldots, 254, 255$ and their respective binary forms 00000000, 00000001, ..., 11111110, 11111111. We can put the binary forms in a vector $(a_7, a_6, a_5, a_4, a_3, a_2, a_1, a_0)$, this vector is an element in \mathbb{F}_2^8 . We define the following isomorphism to formally represent mapping an element $a \in \mathbb{F}_{256}$ to a binary vector of length 8 in \mathbb{F}_2^8 .

$$\varphi: \mathbb{F}_{256} \xrightarrow{\sim} \mathbb{F}_2^8, \quad a \mapsto (a_7, a_6, a_5, a_4, a_3, a_2, a_1, a_0) \tag{2.2}$$

Additionally, we can express an element $a \in \mathbb{F}_{256}$ as a polynomial in the indeterminate x by using a_7, \ldots, a_0 as coefficients in the following way.

$$a = a_7 x^7 + a_6 x^6 + a_5 x^5 + a_4 x^4 + a_3 x^3 + a_2 x^2 + a_1 x + a_0 \text{ with } a_i \in \mathbb{F}_2$$
(2.3)

Integer	Binary form	Binary vector $\varphi(a)$	Polynomial								
0	00000000	$(0,\!0,\!0,\!0,\!0,\!0,\!0,\!0,\!0)$								0	
1	00000001	(0,0,0,0,0,0,0,1)								1	
2	00000010	$(0,\!0,\!0,\!0,\!0,\!0,\!1,\!0)$							x		
:		:				:					
254	11111110	(1, 1, 1, 1, 1, 1, 1, 0)	x^7	$+x^{6}$	$+x^{5}$	$+x^4$	$+x^{3}$	$+x^{2}$	+x		
255	11111111	(1, 1, 1, 1, 1, 1, 1, 1)	x^7	$+x^{6}$	$+x^{5}$	$+x^4$	$+x^{3}$	$+x^2$	+x	+1	

We have summarized the notations in Table 2.1.

Table 2.1: Notation of the finite field \mathbb{F}_{256} .

The finite field \mathbb{F}_{256} has 16 primitive, irreducible (generator) polynomials (Planteen, 2019) which we denote by F_1, F_2, \ldots, F_{16} . The primitive, irreducible (generator) polynomial of \mathbb{F}_{256} that is used in

this thesis is $F_4(x) = x^8 + x^6 + x^3 + x^2 + 1$, meaning that the binary vectors contain the coefficients of the polynomials in the ring $\mathbb{F}_{256} = \mathbb{F}_2[x]/_{(x^8+x^6+x^3+x^2+1)}$. The other 15 primitive, irreducible polynomials are included in Appendix A.

We will now briefly show how finite field arithmetic in \mathbb{F}_{256} is done when using the notation introduced above. Let $a, b \in \mathbb{F}_{256}$ and consider their binary vector forms $\varphi(a), \varphi(b) \in \mathbb{F}_2^8$.

Adding a + b and subtracting a - b are done in the same way: by a bitwise exclusive OR-operation (XOR-operation) on the binary vector forms $\varphi(a)$ and $\varphi(b)$. The results of an XOR-operation are included in Table 2.2.

a_i	b_i	$XOR(a_i, b_i))$
0	0	0
0	1	1
1	0	1
1	1	0

Table 2.2: Results of the XOR-operator on elements $a_i, b_i \in \mathbb{F}_2$.

In order to explain multiplication and division, we introduce exp and log tables. For these tables we need generator polynomial $F_4(x) = x^8 + x^6 + x^3 + x^2 + 1$.

We create an exp table by putting $i = 0, \ldots, 254$ in the first column and value exp(i) in the second column, here exp(i) is a value between 0 and 255. For i = 0, we use the convention that exp(0) = 1. The other values exp(i) are constructed from exp(i-1) as follows. We consider the binary vector representation of exp(i-1) and shift all digits one position to the left. This corresponds to multiplying exp(i-1) with 2. If $exp(i-1) \leq 127$, the next value exp(i) will still have a binary vector representation of length 8, and exp(i) is the integer value corresponding to that binary vector representation. However, if $exp(i-1) \geq 128$, the next value exp(i) will have a binary vector representation of length 9 or greater. This means the binary vector representation is not an element of \mathbb{F}_2^8 , so the integer value is not between 0 and 255. In this case we use generator polynomial $F_4(x)$ by applying a XOR-operation on the binary vector representation of exp(i) and on (1, 0, 1, 0, 0, 1, 1, 0, 1); the binary vector representation of $F_4(x)$. We translate the result of this XOR-operation back to an integer value, which is now between 0 and 255. A short representation of the exp table for \mathbb{F}_{256} based on generator polynomial $F_4(x)$ is included below in Table 2.3a. The full exp table can be found in Appendix B.

The log table is created from the exp table. We use the values exp(i) from the exp table and put them in the first column of the log table. We put their corresponding values i in the second column, and then sort the rows in the table such that the values in the first column are increasing. In other words, in the log table we have j = exp(i) and log(j) = log(exp(i)) = i. A short representation of the log table for \mathbb{F}_{256} based on generator polynomial $F_4(x)$ is included below in Table 2.3b. The full log table can be found in Appendix B.

i	exp(i)	j	
)	1	0	
1	2	1	
2	4	2	
3	8	3	
÷	•		
53	83	253	
54	166	254	
55	*	255	
) e	xp table	(b) <i>i</i>	l

Table 2.3: exp and log tables for \mathbb{F}_{256} with generator polynomial $F_4(x) = x^8 + x^6 + x^3 + x^2 + 1$.

Note that in the exp table, there is no value for exp(i) when i = 255, since exp(255) = 1, which is already the value for i = 0. We denote this by exp(i) = * for i = 255. Similarly, there is no value i such that exp(i) = 0, which we denote by * in the first row of the log table.

Using the exp and log tables, we will now explain how multiplication and division are done in \mathbb{F}_{256} . Let v and w denote the integer values of two elements a and b in \mathbb{F}_{256} (first column in Table 2.1). For multiplication $v \cdot w$, we first add (according to 'normal' arithmetic) values log(v) and log(w) which we can find in the log table and reduce them modulo 255. We then find the exp value for that reduced result in the exp table.

For division $\frac{v}{w}$ we first subtract (according to 'normal' arithmetic) values log(v) and log(w), which we can find in the log table, then reduce them modulo 255. We then find the exp value for the reduced result in the exp table.

A summary of addition and subtraction of finite field elements a and b, and multiplication and division of their integer forms v and w is shown below.

Addition:	a+b	$= \operatorname{XOR}(\varphi(a), \varphi(b))$
Subtraction:	a-b	$= \operatorname{XOR}(\varphi(a), \varphi(b))$
Multiplication:	$v \cdot w$	$= exp(log(v) + log(w) \pmod{255})$
Division:	$\frac{v}{w}$	$= exp(log(v) - log(w) \pmod{255})$

Chapter 3

Information theory

In the 1940s, Claude Shannon published a seminal paper on the mathematical theory of communication (Shannon, 1948). He was the first to mathematically formalize communication theory. Nowadays, we refer to Shannon's theory of communication as *information theory*.

Information theory is a multidimensional topic in mathematics which has evolved from more than just Shannon's communication theory. For example, set theory, measure theory and probability theory also play a crucial role in today's information theory (Alencar, 2014). This combination of mathematical fields makes it an interesting, yet complicated specialty.

Countless applications of information theory exist, among which intelligence uses (Kahn, 1996), cryptography (Lagarias, 1993), cognitive neuroscience (Maurer, 2021) and coding theory (Clark & Cain, 1981). Coding theory is a mathematical field that provides ways to restore messages that have suffered errors during transmission from sender to receiver. In order to focus on coding theory, we will first treat relevant aspects of communication theory.

Let us start with a visual explanation of what we mean by *communication* by walking through a graphical representation of a communication system. In Figure 3.1, we show a schematic diagram of a general communication system, inspired by the schemes presented in Shannon's paper (Shannon, 1948) and Yates's tutorial on coding theory (Yates, 2009).



Figure 3.1: Schematic diagram of a communication system.

The communication process is initiated when the **information source** produces a *message* intended

for the receiver. The message then goes to the **transmitter**, which generally consists of three components. First, the **source encoder** compresses the data. Then the **channel encoder** improves the success of transmission of the source-encoded data through the channel by adding redundant data with an error-correcting code. The message and the redundant data together are called a *codeword*. Thirdly, the **modulator** converts the codeword into an output *signal* suitable for the communication channel. Examples of conversions that happen in the modulator are changing sound waves or text messages into electrical signals or light signals. Subsequently, the signal is sent over the **communication channel**. This channel is a medium, for example a pair of wires or a cable. This communication channel might be subject to noise coming from an external noise source, or noise generated by imperfections of the channel.

At the end of the (noisy) communication channel, the signal arrives at the **receiver**. This *received* signal might be different from the original signal because errors may have occurred. The receiver consists of the three similar components as the transmitter, but they are applied in the reverse order. First, the **demodulator** converts the received signal back to a codeword, the **channel decoder** detects errors and decodes the codeword back to a message using the same error-correcting code. It is possible that too many errors have occurred (see Proposition 1, in that case the message is not decoded but some error message is returned instead. The **source decoder** then decompresses the message. Finally, the receiver sends the original *message* to the **destination**.

Let us now take a more detailed look at the information source and the communication channel from a mathematical viewpoint.

3.1 Information source

The information source produces a message. This message contains certain content intended for the receiver. This content can be expressed and classified in different ways. We can distinguish *discrete* and *continuous* messages. The term 'discrete' refers to a system in which the message is a sequence of discrete symbols, for example letters, numbers, dots, dashes or spaces (Shannon, 1948). The set of discrete symbols of which a message is composed is called the input alphabet \mathcal{X} . In contrast, there exist continuous systems where the message is represented by a continuous function. Examples of this are classical, non-digital forms of communication such as radio and television (Shannon, 1948). In this thesis, we will focus on discrete information sources.

From now on we view the input alphabet \mathcal{X} as a vector space and denote a message m of k symbols by a row-vector of length k over vector space \mathcal{X} , so $m = (m_0, \ldots, m_{k-1})$, with $m_i \in \mathcal{X}$.

3.2 Communication channel

According to Shannon, a communication channel can be fully expressed by a collection of probabilities. We give the following definition of a communication channel, based on Ravagnani's lecture notes on coding theory (Ravagnani, 2022).

Definition 3.2.1. (Communication channel). The triple $\mathcal{K} = (\mathcal{X}, \mathcal{Y}, \mathbb{P})$ (uniquely) describes a communication channel. Here \mathcal{X} is a finite non-empty set called the **input alphabet**, and \mathcal{Y} is a finite non-empty set called the **output alphabet**. $\mathbb{P} : \mathcal{Y} \times \mathcal{X} \to \mathbb{R}$ is a function satisfying the following two properties:

- 1. Let $x \in \mathcal{X}$ and $y \in \mathcal{Y}$. Then $0 \leq \mathbb{P}(y \mid x) \leq 1$ meaning that the probability that y is received when x was sent lies between 0 and 1.
- 2. Let $x \in \mathcal{X}$. Then $\sum_{y \in \mathcal{Y}} \mathbb{P}(y \mid x) = 1$, meaning that if we send input symbol x, the symbol we receive must be in \mathcal{Y} .

The communication channel may have imperfections, be subject to noise from an external source, and be vulnerable to attacks from the outside. The consequence is that the message that the destination receives may not be the exact one that the information source sent; errors may have occurred. We distinguish two different types of errors that can occur to data when transmitted over a communication channel. The first type of error is when a symbol turns into another symbol: *symbol alterations*. The second type of error is when a symbol is not altered but gets lost completely: called a *symbol erasure*. In particular situations, depending on what redundant data is sent along with the message by the error-correcting code, the receiver can determine the position where a symbol was erased. This is not guaranteed by all error-correcting codes. This thesis will assume knowing the position of an erased symbol. We will elaborate on this in Section 4.1.2.

The probabilities in Definition 3.2.1 describe how likely it is for a symbol x from the input alphabet \mathcal{X} to turn into another symbol y from the output alphabet \mathcal{Y} when transmitted over the communication channel $\mathcal{K} = (\mathcal{X}, \mathcal{Y}, \mathbb{P})$. In other words, this describes symbol alterations. The probabilities in the second property of Definition 3.2.1 sum to 1, therefore the communication channel that is defined only allows for symbol alterations, not for symbol erasures. This can be solved by adding an extra symbol that represents an erased symbol, for example '?', to the output alphabet \mathcal{Y} . This is done in this thesis as well.

A communication channel has several interesting features. One feature of interest is the quality of the communication channel. Literature often quantifies quality by looking at the signal-to-noise ratio, which we want to be as large as possible (Price & Goble, 1993). This ratio takes into account the power of a signal and the power of noise. Noise is defined as anything that interferes with communication over a channel. For the mathematical purposes of considering a communication channel, power is not an interesting quantity. What we will consider instead, is the ratio between the amount of data that is transmitted over the channel and the amount of data that is affected by noise, i.e. that suffer symbol alterations or erasures.

Definition 3.2.2. (Signal-to-noise ratio.) Let n be the number of symbols in the data that is sent over the communication channel. Let t be the number of symbols that have suffered errors (erasures or alterations) after transmission over the channel. Then the signal-to-noise ratio SNR is defined as follows:

$$SNR = \frac{n}{t}$$

In practice, source and destination often agree on a certain restriction on the set of admissible messages. In other words, the messages are composed from some admissible alphabet (Ravagnani, 2022). If the received message is not a message from the admissible alphabet, the receiver immediately knows something has gone wrong in the communication process. However, it may be that the received message does not exactly match the sent message, but is still a message that could have been admitted, i.e. is an element of the admissible alphabet. How can the receiver know now that the received message is incorrect?

One possibility is that the information source and the destination agree on some protocol to check whether their messages are the same. Such protocols require communication back and forth between source and destination. However, in some cases it is not possible or undesired for the destination to contact the information source due to security reasons. An example is when only one way of communication is enabled. This is the case in the MagiCtwin Diode. In situations like these, coding theory provides a way to detect and correct errors, without requiring back-and-forth communication between sender and receiver.

Chapter 4

Coding theory

When a communication channel is subject to noise from the outside or has imperfections in its design or hardware, errors can occur. For each codeword, the noise and imperfections cause a chance that during transmission over a channel, some symbols are altered or lost, resulting in errors in the received codeword (Clark & Cain, 1981). Depending on the use of the communication channel, and depending on the type of data sent over the channel, errors can raise a negligible or a far-reaching problem. Either way, errors are unwanted.

Making the communication channel perfect is an unfeasible task (Alzubi, Alzubi, & Chen, 2014), and improving it to minimize the impact of imperfections is costly (Mackay, 1995). Therefore we look for a solution that accepts the noisy, imperfect channel. This solution is error-correction coding. Errorcorrecting codes enforce reliable communication over an imperfect, noisy communication channel (Mackay, 1995).

4.1 Error-correcting coding

Error-correcting codes add redundant data to the message produced by the information source. This step happens in the channel encoder within the transmitter. This redundancy is used by the channel decoder to infer what the original message was. From here on we will focus on the channel encoder and channel decoder components from Figure 3.1. The redundant data both enables *detection* and *correction* of erroneous symbols.

Let us first establish that throughout this thesis, when mentioning (error-correcting) codes, we mean *linear* error-correcting codes. Linear codes have the property that any linear combination of codewords is also a codeword (Yates, 2009). Further details on linear codes are not relevant for the purpose of this thesis.

Let's take a look at the following definition of a linear error-correcting code, which is a combined version of definitions from Ravagnani's lecture notes (Ravagnani, 2022) and Bocklandt's lecture notes (Bocklandt, n.d.).

Definition 4.1.1. (Linear error-correcting code). Suppose we have a communication channel $\mathcal{K} = (\mathcal{X}, \mathcal{Y}, \mathbb{P})$. Let $q = p^m$ for p prime and $m \in \mathbb{N}$. Let $n, k \in \mathbb{N}$. A linear error-correcting code $\mathcal{C} \subseteq \mathcal{X}$ over the finite field \mathbb{F}_q is a k-dimensional subspace of \mathbb{F}_q^n . The code \mathcal{C} contains q^k distinct elements, which are called codewords. We say such a code \mathcal{C} has length n and is an (n, k) linear code.

We will now give two important definitions that we need later in the thesis. They regard the distance between two codewords (van Lint, 1991) and the minimum distance of a code (van Lint, 1991).

Definition 4.1.2. (Distance). Let \mathcal{X} be a finite non-empty set. Let $x, y \in \mathcal{X}^n$ be two elements of the vector space \mathcal{X}^n . The (Hamming) distance d(x, y) between x and y is defined as follows.

$$d(x, y) = |\{i \mid 1 \le i \le n, x_i \ne y_i\}|$$

Definition 4.1.3. (Minimum distance). Let C be a linear (n, k) code. Then the minimum distance d_{min} of code C is the following.

$$d_{min} = min\{d(x, y) \mid x \in \mathcal{C}, y \in \mathcal{C}, x \neq y\}$$

A linear code can be represented in two manners: by a generator matrix or by a generator polynomial (Geisel, 2012). In this thesis we will adopt the matrix notation, because it is best suited for hard-ware and software implementations of error-correcting codes (Geisel, 2012), which is what we focus on in this thesis. Definition 4.1.4 and 4.1.5 characterize how a code is represented using matrices (Ravagnani, 2022).

Definition 4.1.4. (Generator matrix). Suppose we have an (n, k) linear error-correcting code C. A $k \times n$ matrix G with entries in \mathbb{F}_q is a generator matrix of code C if it has full rank and if its rows generate C over \mathbb{F}_q . In other words, the rows of the generator matrix are a basis of C. We then say that code C is generated by G.

Definition 4.1.5. (Standard generator matrix). Suppose we have an (n, k) linear error-correcting code C that is represented by a generator matrix G. The reduced row-echolon form of G, denoted as G_{RREF} , is called the standard generator matrix of C.

The generator matrix G of a code C is not unique, as C can be represented by different generator matrices G. This changes when considering the reduced row-echelon form of G: G_{RREF} is unique for a code C (Bocklandt, n.d.).

We distinguish different types of linear error-correcting codes. The first distinction we consider is between *block codes* and *convolutional codes*. Block codes encode messages that have a fixed length k, whereas convolutional codes can encode symbol streams of arbitrary lengths. This thesis focuses on block codes. One particular category of linear block codes are Reed-Solomon error-correcting codes (or RS codes for short) (Reed & Solomon, 1960). A formal definition can be found in paragraph 6.8 from (van Lint, 1991). We do not include it here because it is too cumbersome for the purposes of this thesis. One thing that is relevant to mention is that the minimum distance d_{min} of Reed-Solomon code C is $d_{min} = n - k + 1$.

Instead of giving the full definition, we will give an example of an RS code in Example 4.1.1.

Example 4.1.1. (Reed-Solomon code). Let $m \in \mathbb{N}$, take p = 2 and consider the finite field $\mathbb{F}_{p^m} = \mathbb{F}_{2^m}$. Let \mathcal{C} be an (n,k) Reed-Solomon code over \mathbb{F}_{2^m} . Then one example of its generator matrix is a $k \times n$ Vandermonde matrix (Moorhouse, 2008), as shown below.

$$G = \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ \alpha_0 & \alpha_1 & \alpha_2 & \cdots & \alpha_{n-1} \\ \alpha_0^2 & \alpha_1^2 & \alpha_2^2 & \cdots & \alpha_{n-1}^2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \alpha_0^{k-1} & \alpha_1^{k-1} & \alpha_2^{k-1} & \cdots & \alpha_{n-1}^{k-1} \end{pmatrix} \text{ where } \alpha_i \in \mathbb{F}_{2^m}$$

Reducing G to its Row-Reduced Echelon Form (RREF) we obtain the following $k \times n$ standard generator matrix G_{RREF} .

$$G_{\text{RREF}} = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 & g_{0,k} & \cdots & g_{0,n-1} \\ 0 & 1 & 0 & \cdots & 0 & g_{1,k} & \cdots & g_{1,n-1} \\ 0 & 0 & 1 & \cdots & 0 & g_{2,k} & \cdots & g_{2,n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & g_{k-1,k} & \cdots & g_{k-1,n-1} \end{pmatrix} \text{ where } g_{i,j} \in \mathbb{F}_{2^m}$$

The error-correcting code that is implemented in the MagiCtwin Diode is a specialized form of a Reed-Solomon code: a *Cauchy Reed-Solomon code*. Cauchy Reed-Solomon (CRS) codes have the

same parameters n and k (Plank, 2005). The differences between a CRS code and an RS code lie in the format of data it encodes and in how the generator matrix is established, which will be explained in the Section 4.1.1.

We will not focus on the encoding and decoding steps of CRS codes.

4.1.1 Encoding

Suppose we have an (n, k) Cauchy Reed-Solomon code with standard generator matrix G_{RREF} . Let $m = (m_0, \ldots, m_k)$ be a message. When considering regular Reed-Solomon coding, each element $m_i \in$ would be one input digit. For Cauchy Reed-Solomon coding, we consider messages where each m_i is a block of b words of w binary digits (*bits*) (Blomer et al., 1999).

When we say we encode a message m with an (n, k) Cauchy Reed-Solomon code C that is represented by a standard generator matrix G_{RREF} , we mean that we assign to the message m a unique codeword c. This is done by viewing the message $m = (m_0, \ldots, m_{k-1})$ as a row vector and multiplying it by the $k \times n$ standard generator matrix G_{RREF} of C. The result of this multiplication is a codeword $c = (c_0, \ldots, c_{n-1})$ (Bocklandt, n.d.). The codeword also consists of blocks c_i that are composed of bwords of w bits each (Blomer et al., 1999). This encoding step is shown below.

$$c = m \cdot G_{\text{RREF}} = (m_0, \dots, m_{k-1}) \cdot \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 & g_{0,k} & \cdots & g_{0,n-1} \\ 0 & 1 & 0 & \cdots & 0 & g_{1,k} & \cdots & g_{1,n-1} \\ 0 & 0 & 1 & \cdots & 0 & g_{2,k} & \cdots & g_{2,n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & g_{k-1,k} & \cdots & g_{k-1,n-1} \end{pmatrix} = (c_0, \dots, c_{n-1})$$

Here $g_{j,i}$ are elements of \mathbb{F}_{2^m} . Note that because the first part of G_{RREF} is the $k \times k$ identity matrix, the first k blocks of c correspond to the original message blocks m_0, \ldots, m_{k-1} .

At this point, we make an important observation. The elements $g_{j,i}$ in the second part of matrix G_{RREF} are elements of \mathbb{F}_{2^m} , while the elements in the message m are data blocks of $b \cdot w$ bits. Multiplication of a message block with a field element is not straightforward. We will not explain how such a multiplication is done, but refer to section 1B of (Hou & Han, 2016) for a description.

In the encoding step we recognize how the redundancy is added. The message m originally had length k, and is mapped to a codeword c of length n. The n - k redundant blocks are added due to the length of the code.

It is important to realize that for this encoding step, the standard matrix G_{RREF} has to have the same number of rows as the number of blocks in the message m. This is the reason why we consider block coding. For block coding, an original message of length larger than k is divided up into multiple slices of length k (and one last slice that has less than k elements in case the message length is not divisible by k). Each block can be seen as a message $m = (m_0, \ldots, m_{k-1})$. Now the matrix multiplication can be done for each of the slices, encoding the original message per k message blocks at once. Each of the codewords is then sent over the communication channel (Yates, 2009).

We will now express some mathematical properties of an (n, k) code C. This lies a foundation for a meaningful assessment of a code's quality. Let us start with a measure of efficiency of error-correcting codes, that compares the size of the original message m and the size of the generated codeword c (Clark & Cain, 1981).

Definition 4.1.6. (Code rate). Consider an (n, k) linear code C. The code rate R of code C is

$$R = \frac{k}{n}$$

The next definition that we will give is that of the Singleton bound (Xambó-Descamps, 2003).

Definition 4.1.7. (Singleton bound). For an (n, k) code C with minimum distance d_{min} , we have

$$k + d_{min} \le n + 1$$

When the equality in the Singleton bound is satisfied, so when $k + d_{min} = n + 1$, we say that code C is maximum distance separable.

Reed-Solomon codes have minimum distance $d_{min} = n - k + 1$ (Ravagnani, 2022), as do Cauchy Reed-Solomon codes (Blomer et al., 1999). In other words, CRS codes satisfy the equality of the Singleton bound. Thus, CRS codes are maximum distance separable. This is particularly interesting for the implementation of CRS codes for the MagiCtwin Diode. We will give more details on this in Section 5.2.1.

4.1.2 Decoding

When the received codeword arrives at the receiver, either block alterations or block erasures may have taken place. The original message now needs to be restored. The error-correcting code is applied again, this time in the channel decoder within the receiver.

There is not one general technique for decoding. There are different approaches for decoding received codewords containing *alterations* and for codewords containing *erasures* (Rao, 2019). We will focus on decoding erasures. In Section 5.2.2 it will become clear why we treat erasures only.

Suppose a codeword $c = (c_0, \ldots, c_{n-1})$ was originally sent, but a codeword $c' = (c'_0, \ldots, c'_{n-1})$, with $c'_i \in \{c_0, \ldots, c_{n-1}, ?\}$ was received. Decoding can only be done if "enough" blocks are still intact. We will give an upper bound on the number of blocks that may have been altered or erased (Clark & Cain, 1981).

Proposition 1. (Error-correction capability). Let C be an (n, k) linear code with minimum distance d_{min} . Its error-correction capability t, the number of block *alterations* the code can correct, is bounded from above by the following upper bound:

$$t \le \left\lfloor \frac{d_{min} - 1}{2} \right\rfloor$$

The number of block *erasures* that an error-correcting code can correct, the *erasure-correcting capa-bility*, is 2t (Riley & Richardson, 2001).

A proof of error-correction capability t from Proposition 1 can be found in (Clark & Cain, 1981). Note that since the number of block erasures that a code can correct is twice as big as the number of block alterations it can correct, we get the following.

$$2t \le 2\left\lfloor \frac{d_{min} - 1}{2} \right\rfloor = d_{min} - 1 = n - k + 1 - 1 = n - k \tag{4.1}$$

So an (n,k) CRS code C with minimum distance d_{min} can correct up to n-k block erasures.

In other words, decoding can only be done successfully when at most n - k blocks in the received codeword c' are erased (i.e. are '?'). If more than n - k blocks have been erased, there is more than one possible original codeword c (Didier, 2009), and the decoding process to determine the original codeword is not as straightforward. In this thesis, we will only elaborate on how to determine the original codeword when at most n - k erasures have taken place.

Suppose we have received some codeword c' of which we know that M block erasures have occurred, assuming $M \leq n - k$. We know on what positions an erasure has occurred because the element on that position in the codeword equals '?'. We know how many erasures have occurred by counting the number of '?'s, which will result in a number for M.

The occurrence of erasures can be represented by a matrix multiplication in the following way. The received codeword c' with M block erasures equals the original message multiplied by some $k \times n$ matrix G' as shown below (Rao, 2019).

$$c' = mG' = (m_0, \dots, m_{k-1}) \begin{pmatrix} g'_{0,0} & \cdots & g'_{0,n-1} \\ \vdots & \ddots & \vdots \\ g'_{n-1,0} & \cdots & g'_{n-1,n-1} \end{pmatrix} = (c'_0, \dots, c'_{n-1})$$

Here, matrix G' corresponds to at least n - M columns of matrix G, and decoding corresponds to finding the unique value of m such that mG' = c'.

4.2 Interleaving

Finally, we will describe an additional technique in error-correcting coding: interleaving. Interleaving is done to improve the error-correcting capability of a code, as we will see in Proposition 2. Similar to error-correcting codes, we can distinguish *block* interleaving and *convolutional* interleaving. Since this thesis treats block codes, we will also focus on block interleaving.

A (block) interleaver is a device that rearranges the order of a sequence of input blocks at the transmitter in order to distribute errors at the receiver (Clark & Cain, 1981). This makes interleaving particularly useful for burst errors.

Interleaving can be done either periodically or randomly. In this thesis, we will only look at periodically interleaved codes. Periodically interleaved codes have an interleave factor s that determines in what way the sequence of input blocks is rearranged at the transmitter. A schematic overview of a message m going through an interleaver and deinterleaver with interleave factor s is included in Figure 4.1.

Interleaver

Input $write \longrightarrow$ Output $(m_0, m_1, \dots, m_{k-2}, m_{k-1}) \rightarrow \begin{pmatrix} m_0 & m_1 & \dots & m_{s-1} \\ m_s & m_{s-1} & \dots & m_{2s-1} \\ \vdots & \vdots & \ddots & \vdots \\ m_{\alpha s} & m_{\alpha s-1} & \dots & m_{k-1} \end{pmatrix} \rightarrow (m_0, m_s, \dots, m_{k-2}, m_{k-1})$

Deinterleaver

 $\begin{array}{cccc} \text{Input} & read \longrightarrow & \text{Output} \\ (m_0, m_s, \dots, m_{k-2}, m_{k-1}) \rightarrow & & & \\ \begin{pmatrix} m_0 & m_1 & \dots & m_{s-1} \\ m_s & m_{s-1} & \dots & m_{2s-1} \\ \vdots & \vdots & \ddots & \vdots \\ m_{\alpha s} & m_{\alpha s-1} & \dots & m_{k-1} \end{pmatrix} & \rightarrow (m_0, m_1, \dots, m_{k-2}, m_{k-1}) \end{array}$

Figure 4.1: A schematic overview of an interleaver and deinterleaver with interleave factor s. The interleaver writes symbols $m_0, m_1, \ldots, m_{k-1}$ into a matrix with s columns row by row. The interleaver rearranges the message symbols by reading them from the matrix column by column.

The deinterleaver performs the inverse operation: It writes message symbols $m_0, m_s, \ldots, m_{k-1}$ into the same matrix format column by column, then rearranges the symbols by reading them out row by row.

The interleaving procedure can take place both before and after applying an error-correcting code C to a message m. Figure 4.1 shows the interleaving and deinterleaving procedure happening be-

for applying error-correction coding. When interleaving happens before coding, a message m first goes through an interleaver in the transmitter, the interleaved message then gets encoded into an interleaved codeword. The interleaved codeword is transmitted over the channel. In the receiver, the interleaved codeword will first be decoded to an interleaved message by the error-correcting code. It then continues through a deinterleaver, outputting the original message.

When interleaving happens after encoding, the transmitter first applies the error-correcting code, converting a message m into a codeword c. The codeword c then goes through an interleaver and the interleaved codeword is sent over a communication channel. In the receiver, the interleaved codeword first passes through a deinterleaver, outputting the original codeword. Decoding the codeword into the original message is the final step.

We will mention the important property of a periodic interleaver with interleave factor s, namely its effect on the erasure-correcting capability of a code.

Proposition 2. (Error-correcting capability of an interleaved code). Suppose we have an (n, k) linear code C with error-correcting capability t. When applying a periodic interleaver with interleave factor s, we create an $(s \cdot n, s \cdot k)$ linear code with error-correcting capability $s \cdot t$.

A proof of Proposition 2 can be found in (Moon, 2005). A code with error-correcting capability st has erasure-correcting capability $2 \cdot st$. In other words, an (n, k) Cauchy Reed-Solomon code that is interleaved with factor s is able to restore $s \cdot 2t = s \cdot n - s \cdot k$ erasures.

An interleaved (n, k) Caucy Reed-Solomon code has the same code rate (see Proposition 4.1.6) and same 3.2.2. The advantage of interleaving lies purely in increasing the error-correcting capability, and therefore the erasure-correcting capability, of a code when it is applied on a communication channel where burst errors happen.

Chapter 5

Compumatica

Computation is a Dutch cybersecurity manufacturer based in Uden. They develop, produce and implement security solutions for network encryption, e-mail encryption, network security and network segmentation. The customers of Computation are governments and Top 500 companies. Their main customer industries are the military, government, transport & logistics, factories, and the electric power industry.

Many organizations separate operational technology (OT) and information technology (IT) (Piggin, 2014), Computatica's customers included. Often, communication from OT to IT is wanted, but communication in the reverse direction is undesired. To enable secure one-way communication for its clients, Computatica offers the MagiCtwin Diode: a device that connects two networks, and only allows one-way communication of data. A few examples of how Computatica's clients implement the MagiCtwin Diode are the following. Suppose user data from operational systems need to be sent to an IT department. Then a communication in the direction from OT to IT must be facilitated. However, it is not necessary for an IT department to be able to remotely access OT systems. In fact, such returning communication creates a vulnerability, as this communication direction may also be targeted by malicious external parties.

Another way in which the MagiCtwin Diode can be used, is to protect back-ups from threats like ransomware from happening. With the MagiCtwin Diode implemented, ransomware cannot reach the back-ups and therefore cannot encrypt them, nor perform any other threatening actions.

A third example is enabling information classification. When different information classification levels are specified, the MagiCtwin Diode can be used to share information with a network that has a higher or lower classification level. Because of the one-way communication, information can even be filtered. The final case we illustrate is the implementation of a MagiCtwin Diode in a system to protect underlying (either out-of-date or vulnerable) systems against threats from the outside, while still enabling an information stream from those systems to security operation centres.

It is important to realize that this does not mean that there are no possibilities of communication from receiver to sender whatsoever. In the first illustrated case for example, OT systems may still be accessed by a third party physically or through wireless connections like 4G or 5G. In the second use case, the data back-up will have to be made by someone, and has to be stored somewhere. These persons and locations may still be reached in other (physical) manners by malicious actors. For the third and fourth use case we can reason in a similar way that the MagiCtwin Diode can be bypassed in different ways.

Nevertheless, the use of a MagiCtwin Diode (or another device that enables one-way communication from sender to receiver for that matter) decreases the possibility that OT systems, back-ups, a certain information classification level, or underlying vulnerable systems can be targeted by third (malevolent) parties. The downside of this one-way communication is that the receiver cannot check with the sender whether errors have occurred during transmission. This is the reason that errorcorrecting coding has been deployed in the MagiCtwin Diode.

5.1 Information theory in the MagiCtwin Diode

We will now outline the MagiCtwin Diode in more details. We refer back to the introduction of communication theory in Chapter 3. The front of the MagiCtwin Diode can be seen in Figure 5.1. It consists of two independent compartments.



Figure 5.1: The front of the MagiCtwin Diode. On the left we have a power button and connection gates of the TX (transmitter) side. On the right we see the same for the RX (receiver) side.

A user network connects to one of the gates of the TX (transmitter) side, shown on the left of Figure 5.1. Another user network connects to one of the gates of the RX (receiver) side, shown on the right of Figure 5.1. The MagiCtwin Diode then only enables one-way communication of data, namely from left to right (so from transmitter to receiver). When the transmitting user network wants to send a data file, it has to upload the file to an FTP TX Daemon located on the TX side. This Daemon applies the error-correcting code as well. The coded data is then sent from TX to RX by means of the communication channel, and arrives at an FTP RX Daemon. This RX Daemon uses the error-correcting code to decode the received data. A receiving user network then connects to the RX Daemon using FTP to retrieve the data file.

The MagiCtwin Diode's hardware restricts the communication to only one way. Sending data from TX to RX uses an internal connection. The communication channel between them transfers data as light signals.

Referring back to the communication scheme in Figure 3.1, the **info source** is a user network that connects on the TX side of the MagiCtwin Diode, and the **destination** is a user network that connects on the RX side of it. All elements in the transmitter environment of Figure 3.1 are located on the left side, the TX side, of the MagiCtwin Diode, whereas all elements in the receiver environment are located on the RX side of the device. The communication channel is a light channel.

We will now express the information source and communication channel in the MagiCtwin Diode to our definitions from Sections 3.1 and 3.2.

Information source

First, we will elaborate on modelling the information source of the original data files that arrive at the TX Daemon. A data file is sliced into multiple slices, each slice can be seen as a message m. In the MagiCtwin Diode, one message m consists of k = 128 blocks, so $m = (m_0, \ldots, m_{127})$ with $m_i \in \mathcal{X}$. Each m_i consists of b = 1456 words of w = 8 bits. In other words, each block m_i consists of b = 1456 bytes. There are $2^8 = 256$ different bytes. The input alphabet \mathcal{X} therefore contains 256^{1456} distinct elements. The output alphabet \mathcal{Y} contains one more element and equals $\mathcal{Y} = \mathcal{X} \cup \{?\}$.

Communication channel

The MagiCtwin's communication channel can be denoted as $\mathcal{K}_{diode} = (\mathcal{X}, \mathcal{Y}, \mathbb{P}_{diode})$ where \mathcal{X} and \mathcal{Y} are defined as above. Due to imperfections of the channel, there are several probabilities that errors occur. \mathbb{P}_{diode} defines a collection of probabilities that symbol (data block) alterations or erasures occur. The error-correcting code that is implemented in the MagiCtwin Diode is an erasure code, meaning block alterations cannot directly be corrected (Luby, Mitzenmacher, Shokrollahi, & Spielman, 2001). However, block alterations can be corrected in an indirect way. In order to handle them, erroneous data blocks are treated as erasures in the following way. A checksum that is implemented earlier in the communication process in the MagiCtwin Diode checks for block alterations. If a bit alteration is detected, the whole data block in which the alteration was detected will not be passed on to the channel encoder. The decoding part of the error-correcting application then registers this as a block erasure. In this way, alterations are treated as erasures.

To determine (approximate) values for the collection of probabilities \mathbb{P}_{diode} , experiments within the MagiCtwin Diode must be conducted. The probability strongly depends on external factors like bottlenecks on the Central Processing Unit (CPU), which makes it difficult to arrive at a definite collection of values. This is not possible within the scope of this thesis, so we will leave this for further research.

5.2 Coding theory in the MagiCtwin Diode

In 2016, one of Computatica's employees implemented a Cauchy Reed-Solomon error-correcting code in the MagiCtwin Diode to detect and correct block erasures that occur during data transmission over the communication channel. The process of selecting this code and exact implementation was not well documented. Because of this, Computatica is not able to substantiate the appropriateness and/or efficiency of the current RS code implementation. In other words, the current implementation might be subject to improvement, or there might be alternative error-correcting codes that are better suited for the MagiCtwin Diode. In this section, we will shed light on the limited information there is on the selection process, show how the code is implemented, and determine what properties it has.

5.2.1 Why a CRS code?

There is no documentation on why Computatica decided to implement a CRS code, but we can reason why they are appropriate for the MagiCtwin Diode. First of all, (C)RS codes can correct single block erasures, but also burst erasures (Geisel, 2012). Burst erasures are erasures of multiple consecutive blocks. The reason that RS codes are particularly useful for burst errors is because they are maximum distance separable (van Lint, 1991). Within the MagiCtwin Diode, burst errors are a common type of error. They might occur when the Central Processing Unit (CPU) is overloaded, when the MagiCtwin Diode is overheated, or when some other hardware component fails. According to Computatica, such hardware influences are the most probable reasons for errors. Therefore, it makes sense to choose an error-correcting code that is suitable for burst errors.

Secondly, the code rate (see Definition 4.1.6) of Reed-Solomon codes is relatively high compared to other error-correcting codes, making a Reed-Solomon code suitable for applications like data storage and data transmission (Tanwar, 2015). These are very important purposes of the MagiCtwin Diode, as explained at the beginning of Chapter 5.

Also, it was not documented why Computatica chose to treat alterations in a block as erasures. However, erasures are easier to decode then alterations (Rao, 2019). It is plausible that this is the reason that alterations in a block are treated as full block erasures.

Additionally, there are mathematical advantages of (C)RS codes. Namely, that it operates over a relatively small finite field; "only" 256 elements (Yan, Sprintson, & Zelenko, 2014). This means that the mathematical operations are not so expensive in time and storage. Moreover, CRS codes ensure a large minimum distance d_{min} (Sklar, n.d.). This directly relates to the error-correcting capability of a code; the larger the minimum distance, the bigger the error-correcting capability (see Proposition 1).

The final advantage of (Cauchy) Reed-Solomon codes over other error-correcting codes is that CRS codes are among the codes that allow for interleaving (Clark & Cain, 1981), which increases the error-correcting capability (see Proposition 2). Periodic interleaving is implemented in the MagiCtwin Diode to be even more prepared for burst errors. The interleaver structure that is used has interleaving factor s = 8.

We consider l consecutive messages. Let m_i^j denote data block i of message j, with $i \in \{0, \ldots, 128\}$ and $j \in \{0, \ldots, l\}$. Figure 5.2 shows how the data blocks in l consecutive messages are interleaved and deinterleaved.

Interleaver

Deinterleaver

Figure 5.2: A schematic overview of the interleaver and deinterleaver with interleave factor 8 that is implemented in the MagiCtwin Diode. The interleaver writes data blocks $m_0^0, m_1^0, \ldots, m_{126}^{l-1}, m_{127}^{l-1}$ into a matrix with 8 columns row by row. The interleaver rearranges the blocks by reading them from the matrix column by column.

The deinterleaver performs the inverse operation: It writes data blocks $m_0^0, m_8^0, \ldots, m_{119}^{l-1}, m_{127}^{l-1}$ into the same matrix format, but now column by column. Then it rearranges the blocks by reading them out row by row.

As explained in Section 4.2, interleaving can happen either before or after encoding. In the MagiCtwin Diode, messages are interleaved before they are encoded (and deinterleaved after they are decoded).

5.2.2 Implementation of the CRS code

The currently used code is not developed by Computatica employees, but is an open-source code called *Fast GF(256) Cauchy MDS Block Erasure Codec in C* (CM256 for short) that can be found on https://github.com/catid/cm256. It was slightly altered by Computatica for GCC (Gnu Compiler Collection) and Linux support. Also, the interleaving protocol was specified by Computatica. The exact error-correcting code as implemented in the MagiCtwin Diode cannot be included in this report.

CM256 library

We will briefly give an outline of the code in the CM256 library, which consists of several files. Five of them are relevant for the purposes of this thesis: README.md, cm256.h, cm256.cpp, gf256.h and gf256.cpp.

The README.md file provides some general details on the library, such as its parameters, its performance and an example usage. The cm256.h is the header of the cm256.cpp file. The header declares functions for encoding and decoding. The cm256.cpp contains the encoding and decoding steps. First, the library is initialized by performing some checks. Then, the functions for encoding a block, encoding a set of blocks, and decoding received blocks are defined. The structure of the decoder is defined, and finally a decoder function is defined. All mathematical computations during encoding and decoding are done in finite fields. The functions that describe how to do the mathematical computations at bit level are declared in the gf256.h header file. Lastly, the gf256.cpp file contains the function definitions that enable all mathematical computations on the finite field \mathbb{F}_{256} , which are specified for different CPU's. Almost all mathematical computations use lookup tables, which are created using finite field arithmetic as explained in Chapter 2. Addition and subtraction do not require lookup tables, as they are performed by a XOR-operation.

In the MagiCtwin Diode's settings we find three standard settings, each with three parameters specified in the following form: $s \times f/d$. Here s is the amount of stripes, which is relevant for the memory organization within a computer (*Main Memory Organization Computer Systems Structure*, n.d.) and is also the interleave factor s. Next, f denotes the number of redundant blocks generated by the code, it corresponds with the value n - k in an (n, k) linear code. Finally, d is the number of blocks of original data, which corresponds to k in an (n, k) linear code. The possible settings are $8 \times 16/128$, $8 \times 16/64$ and $8 \times 8/64$. The setting 8x16/128 is used by default.

The C++ code in the CM256 library is specified by three parameters: OriginalCount, RecoveryCount and BlockBytes. Here, OriginalCount is the number of original data blocks, it corresponds to parameter k of a linear (n, k) code, and to the parameter d of CM256. Its default value is 128. This means that all data are sliced into slices with k = 128 data blocks each. Next, RecoveryCount is the number of recovery blocks that are generated by the error-correcting code. It corresponds to n - k in an (n, k) code, and to f in the CM256 library. Its standard value is 16, meaning there are n - k = 16recovery blocks generated per 128 original data blocks. We can conclude that n = 128 + 16 = 144. Finally, BlockBytes is the number of bytes per block. This is the same for both the original data blocks and the recovery blocks: 1456 bytes per block. We conclude that an (n, k) = (144, 128) linear Cauchy Reed-Solomon error-correcting code is used in the MagiCtwin.

Note that this means that the original data that is encoded in every use of the error-correcting code is at most $128 \cdot 1456 = 186.368$ bytes (186 kB). When considering a simple text file, assuming one character is represented by one byte, this corresponds to roughly 90 A4 pages of text, or almost two low-resolution photographs (Sheldon, 2021).

Encoding

A data file sent over the MagiCtwin Diode is usually bigger than a 90 page text document or two low-resolution photographs. Therefore the data file must be sliced into slices of 128 data blocks each. Each slice can be denoted as a message $m = (m_0, \ldots, m_{127})$ where each m_i is a data block from input alphabet \mathcal{X} as defined at the start of Section 5.1.

Let $G_{\text{RREF}} = (I_{128} | A)$ denote the standard generator matrix used in Computatica's error-correcting code. Here I_{128} denotes the 128×128 identity matrix. Matrix A is based on Cauchy matrices. In a Cauchy matrix C, element c_{ij} on row i and column j is based on some x_i and y_j as follows.

$$c_{ij} = \frac{1}{x_i - y_j} \tag{5.1}$$

In the CM256 library, $x_i = i$, so each x_i corresponds to the row number in the matrix and to the index of the original data block *i* in message *m*. This means the values range from $0, \ldots, k-1 = 0, \ldots, 127$. For y_j we have $y_j = j + 128$, so the y_j corresponds to the column number in generator matrix *G* and to the index of the recovery block in the codeword. This means the values range from $k, \ldots n-1 = 128, \ldots, 143$.

All matrix elements a_{ij} in A are divided by the element in the first column of row i, so divided by element $a_{i0} = \frac{1}{x_0 - y_i}$, resulting in the following matrix elements.

$$a_{ij} = \frac{x_0 - y_j}{x_i - y_j} \tag{5.2}$$

In the computation of matrix elements a_{ij} , the values $0, \ldots, 127$ and $128, \ldots, 143$ for x_i and y_j respectively are integer values between 0 and 255, so they are elements as in the first column of Table 2.1. The integers are put in their binary vector form to perform the subtraction by means of an XOR-operation in both the numerator and the denominator. The results of the numerator and denominator are put in their integer forms again, and division is done by using the exp and log tables to determine $exp(log(x_0 - y_j) - log(x_i - y_j) \pmod{255})$ as explained in Chapter 2.

We will now continue with a step-by-step determination of the 128×16 matrix A that is used in $G_{\text{RREF}} = (I_{128} \mid A)$ in the CM256 library. First, we show in 5.3 how the matrix elements on row *i* and column *j* of matrix A are based on x_0, x_i and y_j .

$$\begin{pmatrix} \frac{x_0 - y_0}{x_0 - y_0} & \cdots & \frac{x_0 - y_{15}}{x_0 - y_{15}} \\ \vdots & \ddots & \vdots \\ \frac{x_0 - y_0}{x_{127} - y_0} & \cdots & \frac{x_0 - y_{15}}{x_{127} - y_{15}} \end{pmatrix}$$
(5.3)

Then, as shown in 5.4, the corresponding values $x_0 = 0$, $x_i = i$ and $y_j = j + 128$ in are filled in on each row *i* and column *j*.

$$\begin{pmatrix} \frac{0-128}{0-128} & \cdots & \frac{0-143}{0-143} \\ \vdots & \ddots & \vdots \\ \frac{0-128}{127-128} & \cdots & \frac{0-143}{127-143} \end{pmatrix}$$
(5.4)

The subtractions in the numerator and denominator correspond to XOR-operations on the binary vector forms of the integers, as shown below.

Which in integer forms equal:

$$\begin{pmatrix} \frac{128}{128} & \cdots & \frac{143}{143} \\ \vdots & \ddots & \vdots \\ \frac{128}{255} & \cdots & \frac{143}{240} \end{pmatrix}$$
(5.6)

The divisions $\frac{a}{b}$ in 5.6 are done by using the exp and log tables to determine $exp(log(a)-log(b) \pmod{255})$, which results in the following calculation.

$$\begin{pmatrix} exp(log(128) - log(128) \pmod{255}) & \dots & exp(log(143) - log(143) \pmod{255}) \\ \vdots & \ddots & \vdots \\ exp(log(128) - log(255) \pmod{255}) & \dots & exp(log(143) - log(240) \pmod{255}) \end{pmatrix}$$

$$= \begin{pmatrix} exp(7-7 \pmod{255}) & \dots & exp(252-252 \pmod{255}) \\ \vdots & \ddots & \vdots \\ exp(7-161 \pmod{255}) & \dots & exp(252-73 \pmod{255}) \end{pmatrix}$$
$$= \begin{pmatrix} exp(0) & \dots & exp(0) \\ \vdots & \ddots & \vdots \\ exp(101) & \dots & exp(179) \end{pmatrix}$$
(5.7)

Finally, this results in the 128×16 matrix A as shown below. The full matrix A is included in Appendix C.

$$A = \begin{pmatrix} 1 & \dots & 1 \\ \vdots & \ddots & \vdots \\ 133 & \dots & 222 \end{pmatrix}$$
(5.8)

The 128×144 standard generator matrix G_{RREF} is shown in 5.9.

$$G_{\text{RREF}} = (I_{128} \mid A) = \begin{pmatrix} 1 & \dots & 0 & 1 & \dots & 1 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 1 & 133 & \dots & 222 \end{pmatrix}$$
(5.9)

The data blocks in the codeword are generated by multiplying the blocks $m = (m_0, \ldots, m_{k-1})$ by the standard generator matrix G_{RREF} . Since G is a 128×144 matrix, the result of this multiplication is a row vector of 144 elements: the codeword blocks $c = (c_0, \ldots, c_{143})$.

$$c = m \cdot G = (m_0, \dots, m_{127}) \cdot \begin{pmatrix} 1 & \dots & 0 & 1 & \dots & 1 \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 1 & 133 & \dots & 222 \end{pmatrix} = (c_0, \dots, c_{127}, c_{128}, \dots, c_{143})$$

Where

$$c_{0} = m_{0}$$

$$\vdots$$

$$c_{127} = m_{127}$$

$$c_{128} = m_{0} + \dots + 133m_{127}$$

$$\vdots$$

$$c_{143} = m_{0} + \dots + 222m_{127}$$

We again refer to (Hou & Han, 2016) for details on the procedure of multiplying matrix elements with data blocks.

Suppose the data file was sliced into l slices. This encoding step is done for each of the slices of the original data file. The l codewords are sent over the diode with interleave factor s = 8.

Decoding

The channel decoder uses the error-correcting code to reconstruct the original message m from received codeword c'. Recall that at most $2t \le n - k$ erasures can be restored, meaning that at most n - k = 144 - 128 = 16 blocks in c' may be '?'.

We will now explain how the reconstruction process of $M \leq 16$ erasures takes place. As explained in Section 4.1.2, the received codeword c' with M block erasures equals the original message multiplied by some $k \times n$ matrix G' in the following way.

$$c' = mG' = (m_0, \dots, m_{k-1}) \begin{pmatrix} g'_{0,0} & \cdots & g'_{0,n-1} \\ \vdots & \ddots & \vdots \\ g'_{n-1,0} & \cdots & g'_{n-1,n-1} \end{pmatrix} = (c'_0, \dots, c'_{n-1})$$

Here, matrix G' corresponds to at least n - M columns of matrix G. Decoding corresponds to finding the unique value of m such that mG' = c', so it is a matter of solving a system of linear equations.

In the decoding functions of CM256, two cases are distinguished: the case where M = 1 (only one bit erasure has taken place), and the case where M > 1 (more than one bit erasure has taken place). For M = 1, finding *m* is relatively easy. However, if M > 1, solving for *m* becomes more complicated. The CM256 library applied LDU-decomposition for finding *m*. The function for LDU-decomposition in CM256 uses Algorithm 2.5 (GS-direct-Cauchy) from (Boros, Kailath, & Olshevsky, 2002). We will not elaborate any further on the contents of this algorithm.

5.2.3 Properties of the CRS code

In Chapter 4, we treated some properties of error-correcting codes. We will now evaluate each of these properties for the error-correcting code that Computation has implemented.

Erasure-correcting capability

In Proposition 1 we stated that an error-correcting code could correct at most 2t = n - k block erasures. Since the MagiCtwin Diode uses an (n,k) = (144, 128) linear Cauchy Reed-Solomon code, n-k = 144 - 128 = 16 block erasures can be restored solely by the CRS code. In case more than 16 block erasures have taken place, the error-correcting code will not restore the original codeword and corresponding message, but it will output to the receiver that the transmission was not successful. If we also take into account the interleaving protocol that was implemented, we consider the Cauchy Reed-Solomon code as an $(s \cdot n, s \cdot k) = (8 \cdot 144, 8 \cdot 128) = (1152, 1024)$ linear code with error-restoring capability $s \cdot 2t = s \cdot (n-k) = 8 \cdot (144 - 128) = 128$. Therefore, 128 consecutive block erasures can be restored, provided that 1024 data blocks around it have been transmitted correctly.

Signal-to-noise ratio

In the MagiCtwin Diode, the signals are sent from the transmitter to the receiver in the form of light. This is one of the most reliable types of communication channels, but still bit errors occur (Alzubi et al., 2014). For an assessment of the code, it would be interesting to know how many errors occur on average in the MagiCtwin Diode in a customer environment. A small experiment in a test environment at Computatica was done to investigate how many errors occur on average during data transmission through the MagiCtwin Diode.

MagiCtw				Data Diode RX	(1)							
General	Transfers					Save Cancel Help						
Network Users	Time period: Today	* Protoco	FTP & E-mail V	Status: OK & failed V Filename pattern:		Display						
Data Diode RX	Date	Protocol	Status	File	Received [bytes]	Packet loss						
Services	Tue, 11-10-2022 01:03:10 PM	ftp	Failed	ftp-bbu/vic-3.0.12-win32.exe	41435696 / 41436128	0 / 32044						
SCADA	Tue, 11-10-2022 01:03:00 PM	ftp	Failed	ftp-bbu/Git-2.33.0.2-64-bit.exe	50100592 / 50101024	0 / 38763						
Ven	Tue, 11-10-2022 01:20:56 PM	ftp	Failed	ftp-bbu/ccsetup601.exe	49617752 / 49618184	0 / 38432						
VPN	Tue, 11-10-2022 01:20:57 PM	ftp	Ok	ftp-bbu/vlc-3.0.12-win32.exe	41436128	0/31916						
Host-IDS	Tue, 11-10-2022 01:21:53 PM	ftp	Ok	ftp-bbu/TC31-Full-Setup.3.1.4024.20.zip	1043822244	0 / 806512						
Maintenance	Tue, 11-10-2022 01:23:28 PM	ftp	Ok	ftp-bbu/TC31-Full-Setup.3.1.4024.20.zip	1043822244	0 / 806512						
Diagnostics	Tue, 11-10-2022 01:28:09 PM	ftp	Ok	ftp-bbu/cd1_bessy_v7.40.1.iso	1990639616	0 / 1538079						
Logout	Tue, 11-10-2022 01:44:09 PM	ftp	Ok	ftp-bbu/Rufus_USB_boot_v750.i	21868544	0 / 16813						
Logout	Tue, 11-10-2022 01:44:41 PM	ftp	Ok	ftp-bbu/cd1_mbonds.i	507510784	0 / 392087						
	Tue, 11-10-2022 01:55:16 PM	ftp	Ok	ftp-bbu/file_10gb	10737418240	0 / 8296330						
	Tue, 11-10-2022 01:57:32 PM	ftp	Ok	ftp-bbu/file_1gb	1073741824	813 / 828809						

Figure 5.3: A screenshot of the interface for the MagiCtwin data diode, after 11 test files were sent.

A user connection was established with the FTP server on the TX side and the FTP server on the RX side. Then, 8 tests were performed. In Figure 5.3, a screenshot of the diode's interface is shown. It shows 11 files sent by the user, of which the first 3 were not relevant for this small experiment.

The first three data files can be ignored for the purposes of evaluation the signal-to-noise ratio. The next 7 data files were uploaded to the FTP server on the TX side, using Filezilla. In Appendix E, a screenshot of the Filezilla interface is included in order to illustrate how this is done. All 7 data files arrived at the RX side completely, this is seen because the column 'Packet loss' indicates 0 lost packets for each of the 7 files. The last file transfer was manipulated by simulating a 0.1% packet loss, using Network Emulator (*Traffic Control Manual For Lab1*, n.d.).

We would like to know how many errors occur on average. The 8 experiments that were done do not provide a definite and usable number. Experimenting by simulation takes too much time, and designing a rigorous experiment to find out a definite signal-to-noise ratio is outside the scope of this thesis. A theoretically acceptable value of the signal-to-noise ratio in wireless communication is 15dB (Ab-Rahman, Shuhaimi, Al-Hakim Azizan, & Hassan, 2012). We will convert this value back to a ratio, using the following conversion formula from (Price & Goble, 1993).

$$SNR = 10 \cdot \log_{10} \left(\frac{S}{N}\right)$$
 [dB] (5.10)

Using this conversion formula, we calculate that a ratio of 15dB corresponds to the following signalto-noise ratio $\frac{S}{N}$.

$$10 \cdot \log\left(\frac{S}{N}\right) = 15 \text{ dB} \iff \frac{S}{N} = 10^{0.1 \cdot \log(S/N)} = 10^{1.5} \approx 31.6$$

In other words, for a codeword of S = n = 144 blocks that is sent over the data diode, we can expect $\lceil N \rceil \approx \left\lceil \frac{144}{31.6} \right\rceil \approx \lceil 4.6 \rceil = 5$ blocks to be erased.

Code rate

In Definition 4.1.6 we gave a formula for a code's rate. Let us look at the code rate of the errorcorrecting code that Computatica currently uses. We use the default parameters k = 128 and n = 144 to compute the code rate: $R = \frac{k}{n} = \frac{128}{144} \approx 0.89$.

Chapter 6

Improving Computatica's code

We now know how the CM256 library is implemented for error-correcting purposes in the MagiCtwin Diode. We also know its relevant properties. This lays a foundation for discussing several options to improve it. There are several paths to improvements at this point. First of all, the CM256 library could be improved in terms of its efficiency. Secondly, a different default setting might improve the MagiCtwin's efficiency while still having a large enough erasure-correcting capability. Finally, another class of error-correcting codes could be implemented. We will discuss all three options.

6.1 Improving the CM256 library

When looking at the CM256 library, different improvements come to mind. First of all, the matrixvector multiplication in the function cm256_encode_block (cm256.cpp lines 166-190) can be done faster than it is being done now. One exemplary way in which it can be optimized is by implementing a Fast-Fourier-Transform algorithm (Rao, 2019).

The developer of the CM256 library has also compared CM256 with two different Cauchy Reed-Solomon code libraries, namely Intel(R) Intelligent Storage Acceleration Library (ISA-L for short, code can be accessed via https://github.com/intel/isa-1) and Longhair (code can be accessed via https://github.com/catid/longhair.). The ISA-L library is more efficient in this matrix multiplication, so another option to optimize the matrix-vector multiplication in Computatica's implementation of the error-correcting code is to be inspired by the approach taken in ISA-L.

During decoding, the LDU-decomposition that is used to solve mG' = c' for m is a way of performing Gaussian elimination. Gaussian elimination will always work, but it is slow compared to other solving techniques. Gaussian elimination has complexity $\mathcal{O}(n^3)$ (Boros et al., 2002). A faster decoding technique can be implemented via a Berlekamp-Massey decoding algorithm, which has complexity $\mathcal{O}(kn)$ (Shum, 2016).

Computation currently limits the transmission speed of data through the diode at 400 megabits per second (Mbits/sec), corresponding to 50 megabytes per second (Mbytes/sec), while the total bandwidth of the diode is 1000 Mbits/sec (125 Mbytes/sec). This is done for several reasons. First of all, in this way they make sure that the amount of data transmitted per time unit stays limited in case of hardware failures. Secondly, hardware limitations are taken into account in this manner. For instance, the CPU at the RX side must be able to decode the worst case scenario faster than the TX side is able to encode and send new information. The speed of the CPU forms such a hardware limitation.

It makes sense to wonder whether the transmission speed limit can be relieved now that we know that we can restore over three times as much errors than we expect to happen, or at least increased. However, this remaining bandwidth of 600 Mbits/sec (75 Mbytes/sec) is also necessary for sending other data and protocols. Computational does not know at this moment how much bandwidth these remaining data and protocols take up exactly, therefore we cannot study to what limit the transmission speed may be increased during this thesis.

Finally, if Computatica would want to improve the CM256 library in terms of functions it has,

they might want to look into the possibility of incorporating encryption. This is a relevant function when developing a MagiCtwin Diode that offers customers to implement the TX and RX side in two physically different locations. When looking for encryption possibilities, the ISA-L library could be of interest. It is a Cauchy Reed-Solomon erasure code, meaning it is the same type of code as the one in the CM256 library, but also allows for cryptological functions. The ISA-L library that contains crypto functions can be accessed via https://github.com/intel/isa-l_crypto).

6.2 Comparing different settings

Currently, Computatica uses the same default setting 8x16/128 for all file sizes that are to be transmitted from the TX to RX side. It is plausible that one of the other two standard settings generates less but still sufficient redundant data, therefore being more efficient.

Assuming the 3.5% of erasures from (Ab-Rahman et al., 2012), we can significantly reduce the number of generated recovery blocks for messages of 128 blocks. When looking at one sequence of 8 codewords again, we expect $\lceil 0.035 \cdot 8n \rceil$ data blocks to be erased and know that we can restore at most $s \cdot 2t = 8 \cdot (n-k)$ erased data blocks, meaning we need 8(n-k) recovery blocks. Taking k = 128, we solve $0.035 \cdot 8n = 8(n-k)$ and get $\lceil 8n \rceil = 133$, meaning that n - k = 133 - 128 = 5. In other words, only 5 recovery blocks have to be generated for a total of 8 messages of 128 blocks each. This corresponds to $\left\lceil \frac{5}{8} \right\rceil = 1$ recovery block per message, so a total codeword length of 128 + 1 = 129. It seems like a totally new setting would be more efficient than either one of the three current settings. We suggest to up to 8 recovery blocks per 128 data blocks in order to agree with the interleaving protocol with interleave factor s = 8. Therefore, creating a new setting 8x8/128 seems sufficient.

Let us assess the three standard settings and the newly suggested setting by calculating their code rates, expected number of block erasures and error-correcting capabilities with and without inter-leaving. The comparison is shown in Table 6.1.

MagiCtwin Diode setting		8x16/128	8x16/64	8x8/64	8x8/128
Corresponding parameters	(n,k)	(144, 128)	(80, 64)	(72, 64)	(136, 128)
Code rate R	$\frac{k}{n}$	$\frac{8}{9}$	$\frac{4}{5}$	$\frac{8}{9}$	$\frac{16}{17}$
Fraction converted to percentage		89%	80%	89%	94%
Expected erasures (blocks)	$\lceil 0.035 \cdot n \rceil$	6	3	3	5
Percentage of n		4.2%	3.8%	4.2%	3.7%
Erasure-correcting capability $2t$ (blocks)	n-k	16	16	8	8
Percentage of n		11.1~%	20%	11.1%	5.9%
Erasure-correcting capability $2st$ with	8(n-k)	128	128	64	64
interleaving factor 8 (blocks)					
Percentage of $8 \cdot n$		11.1~%	20%	11.1%	5.9%

Table 6.1: A comparison of the code rate, expected block erasures and erasure-correcting capability with and without periodic interleaving for four possible settings of the MagiCtwin Diode.

In Table 6.1, the 8x16/128 setting that Computatica currently uses is denoted by the gray column. The 8x8/128 that we suggest in this thesis is shown in the cyan column. We see that 8x8/128 has a higher code rate than the three settings the MagiCtwin Diode can now adapt. Also, we see that the erasure-correcting capability percentage of the new setting is much closer compared to the expected number of block erasures than in the other three settings, meaning it uses available bandwidth more efficiently. We consider the new setting to be more efficient since it generates less, but still enough, redundant data.

An interesting question that Computation posed is whether the efficiency of transmitting different file sizes might profit from different standard settings. Since the average file that is sent over the diode in the MagiCtwin Diode is significantly larger than 186 kB, the setting that is used to apply

the error-correcting code does not influence the efficiency any differently for different file sizes. For any file size, new setting 8x8/128 is most efficient.

6.3 Alternative suitable codes

We have explained in Section 5.2.1 why we presume a Cauchy Reed-Solomon error-correcting code was chosen. We will now present some suitable alternatives. Any of the alternatives require further investigation in order to implement them successfully in the MagiCtwin Diode, but they provide Computation with a starting point.

A suitable MDS burst erasure correcting code can be a low-density parity-check (LDPC) code, for example by implementing Construction 5 or Construction 6 proposed in (Johnson, 2009). LDPC codes also allow for interleaving (Sridharan, Kumarasubramanian, Thangaraj, & Bhashyam, 2008), and are therefore compatible with the interleaver in the MagiCtwin Diode as well.

Another class of error-correcting codes that could replace the Cauchy Reed-Solomon code are Fire codes (Fire, 1959). They are very efficient for burst errors (Moon, 2005). A good starting point might be Construction 1 as proposed in (Zhou, Lin, & Abdel-Ghaffar, 2014).

The final error-correcting code that we propose that is suited for the purposes in the MagiCtwin Diode is a Turbo code. Turbo codes have good erasure correcting capabilities and have good performance when code rates are high (Mizuochi, 2006). Construction algorithms for Turbo codes are given in (Biradar & Sasi, 2018).

Chapter 7

Discussion and future research

We started this thesis by giving a structured description of information theory and a mathematical explanation of coding theory. We have introduced (Cauchy) Reed-Solomon codes and we have shown how information theory and CRS codes are implemented by MagiCtwin Diode. We have pointed out why choosing a CRS code is appropriate for the purposes and implementation of error-correcting coding in the MagiCtwin Diode. We then proposed different improvements regarding efficiency of the CM256 library, and we suggested a fourth standard setting that has advantages over the current three standard settings. Finally, we put forward three classes of alternative error-correcting codes that might be suitable for the MagiCtwin Diode.

There are several notes that we have to make before we give Computatica a definite recommendation regarding the efficiency of the error-correcting code that is currently implemented in the MagiCtwin Diode.

In this thesis we have considered symbol alterations and symbol erasures. In practice, symbol additions are also possible (Bours, 1994). Whether this can happen in the diode is not investigated in this thesis. Also, we are not aware whether this is implemented in the CM256 library.

Definition 3.2.1 gives a mathematical definition of a communication channel, which is expressed for the MagiCtwin Diode in Section 5.1. It assumes a *memoryless* communication channel, which means that what happens in one channel use is independent from what happens in the other channel uses (Ravagnani, 2022). Whether the diode in the MagiCtwin Diode is a memoryless communication channel is not known. However, since most of the errors that happen are burst errors, so not random errors, the resulting behaviour of the communication system of the MagiCtwin Diode does not resemble a memoryless communication channel (Clark & Cain, 1981).

LDPC codes are well-suited for burst erasure channels, but specifically for memoryless burst erasure channels (Johnson, 2009). Some research into LDPC codes for burst erasure channels with memory has been done, but it is has not reached a level of implementation yet (Paolini & Chiani, 2006).

We have explained that due to the average size of customer files, the diode has to be used multiple times when transmitting a data file over the data diode. This makes it relevant to consider the communication channel as a non-memoryless channel. This affects the collection of probabilities \mathbb{P}_{diode} . Besides, the number of 3.5% expected erasures is based on random errors and a memoryless channel. Since the communication channel does not behave as a memoryless channel and the errors do not happen randomly but in burst, this 3.5% is not an accurate estimate.

Another issue with the percentage is that it only gives an estimate for errors that have occurred in the communication channel. In practice, errors might also happen during conversion from message to codeword, from codeword to light signal, from received signal back to received codeword, and from received codeword back to original message. Error-correcting coding does not cover these types of errors, so they are not included in this thesis. However, in the MagiCtwin Diode these errors might actually happen, so we feel obligated that this aspect must be brought to light here as well.

The suitability of a (Cauchy) Reed-Solomon error-correcting code for the MagiCtwin Diode is backed up by literature (Geisel, 2012; van Lint, 1991; Tanwar, 2015; Rao, 2019; Yan et al., 2014; Sklar, n.d.; Clark & Cain, 1981) as explained in Section 5.2.1. Each of the three alternative classes of error-correcting codes that seem suitable for the MagiCtwin Diode is supported by scientific papers as well (Sridharan et al., 2008; Zhou et al., 2014; Mizuochi, 2006). However, the alternatives have been insufficiently researched to be able to say that they will perfectly suit the MagiCtwin Diode.

While we believe that the results of this thesis are useful for Computatica, future research should be conducted, starting with an investigation into the collection of probabilities \mathbb{P}_{diode} that express the probabilities of data block alterations and erasures. With this collection of probabilities, we would have an accurate estimate of the expected number of alterations and erasures that we can expect to happen when a codeword c is transmitted over the diode in the MagiCtwin Diode. $\mathbb{P}_{diode}f$ would be significantly more appropriate to use than the 3.5% from (Ab-Rahman et al., 2012), and would give a useful value for the signal-to-noise ratio of the diode. Further research at the customer side of the MagiCtwin Diode can be done to learn how much time the MagiCtwin Diode is out of running on average, so how many consecutive block erasures actually happen. In case this is significantly less than 3.7 ms every 29.8 ms, changes can be made.

The combination of the collection of probabilities and the duration of failure of the MagiCtwin Diode should be used as a benchmark for the required erasure-correction capability of an error-correcting code.

Furthermore, one aspect of efficiency that we did not focus on in this paper is the delay that happens during the decoding of codewords with burst erasures. Particularly when applying block interleaving in combination with RS codes, we are faced with a sub-optimal decoding delay (Li, Khisti, & Girod, 2011). Several linear code constructions that achieve the Singleton bound as well as the lowest possible decoding delay are presented in (Li et al., 2011). These constructions are theoretical and therefore not yet ready implementation-wise. We suggest further research into these code constructions in order to see if one is suited for and applicable in the MagiCtwin Diode.

The Fast-Fourier-Transform algorithm is one way to accelerate matrix multiplication during encoding, but many more fast multiplication techniques exist. We suggest further research into fast (matrix) multiplication techniques for elements in finite fields. The same goes for the suggested Berlekamp-Massey algorithm that is a fast decoding technique for Cauchy Reed-Solomon codes.

Some explanations, like how to multiply a data block with a finite field element and the exact definition of a Reed-Solomon code, are not given in this thesis. It would be beneficial for the mathematical understanding of the implementation of error-correction coding in the MagiCtwin Diode to understand those details, but doing so does not make a difference on our recommendations for Computatica. Given the limited scope of this thesis, it was therefore not included in this thesis.

Chapter 8

Recommendation

We have proposed different options to improve the efficiency of error-correcting coding in the MagiCtwin Diode in Chapter 6 and critically discussed the findings and limitations of this thesis in Chapter 7. We now have all tools to formulate a definite recommendation regarding the efficiency of error-correcting coding in the MagiCtwin Diode.

We will first advise on the approach to improve the currently implemented CM256 library. Regardless of other improvements, a faster multiplication algorithm for the vector-matrix multiplication during encoding should be implemented. For this, Computatica may want to look at either the Fast-Fourier-Transform algorithm from (Rao, 2019), the ISA-L library from https://github.com/intel/isa-1 or start a new research into fast multiplication. Similarly, a faster algorithm for decoding can be implemented. Computatica may choose to look at a Berlekamp-Massey algorithm as in (Boros et al., 2002) or may choose to explore other decoding methods.

Besides this, one of the following two improvements can be implemented. One advise would be to create a new (fourth) standard setting that is 8x8/128, so that generates 8 recovery blocks for each slice of 128 data blocks, keeping interleave factor 8. Possibly, there can be a fifth new setting with an even higher code rate, depending on further research determining the collection of probabilities \mathbb{P}_{diode} .

The last recommendation regarding the currently implemented code regards cryptological functions of the MagiCtwin Diode. If the possibility of incorporating encryption into the MagiCtwin Diode is of interest as well, the ISA-L library could be an example of how to do so.

Finally, Computatica may decide to implement a different class of codes instead of Cauchy Reed-Solomon, rather than improve its currently implemented code. In this case, we advise Computatica to do more (documented) research into the suitability and implementation methods of their preferred alternative class of codes. We suggest starting by looking at an LDPC code inspired by Construction 5 or 6 from (Johnson, 2009) or a Fire code similar to Construction 1 from (Zhou et al., 2014). Alternatively, Computatica can look into construction methods for a Turbo code (Biradar & Sasi, 2018) or Li's code (Li et al., 2011).

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Appendix A

Generator polynomials for \mathbb{F}_{256}

Below, we present a table that shows all 16 primitive, irreducible polynomials of \mathbb{F}_{256} . The polynomials are often characterized by a hexadecimal, which is included for each polynomial as well. The highlighted row is the polynomial that is used in the CM256 code.

Hexadecimal	Generator polynomial
0x8e	$F_1(x) = x^8 + x^4 + x^3 + x^2 + 1$
0x95	$F_2(x) = x^8 + x^5 + x^3 + x + 1$
0x96	$F_3(x) = x^8 + x^5 + x^3 + x^2 + 1$
0xa6	$F_4(x) = x^8 + x^6 + x^3 + x^2 + 1$
Oxaf	$F_5(x) = x^8 + x^6 + x^4 + x^3 + x^2 + x + 1$
0xb1	$F_6(x) = x^8 + x^6 + x^5 + x + 1$
0xb2	$F_7(x) = x^8 + x^6 + x^5 + x^2 + 1$
0xb4	$F_8(x) = x^8 + x^6 + x^5 + x^3 + 1$
0xb8	$F_9(x) = x^8 + x^6 + x^5 + x^4 + 1$
0xc3	$F_{10}(x) = x^8 + x^7 + x + 2 + x + 1$
0xc6	$F_{11}(x) = x^8 + x^7 + x^3 + x^2 + 1$
0xd4	$F_{12}(x) = x^8 + x^7 + x^5 + x^3 + 1$
0xe1	$F_{13}(x) = x^8 + x^7 + x^6 + x + 1$
0xe7	$F_{14}(x) = x^8 + x^7 + x^6 + x^3 + x^2 + x + 1$
0xf3	$F_{15}(x) = x^8 + x^7 + x^6 + x^5 + x^2 + x + 1$
Oxfa	$F_{16}(x) = x^8 + x^7 + x^6 + x^5 + x^4 + x^2 + 1$

Appendix B

Exp and log tables for \mathbb{F}_{256}

The exp table for finite field \mathbb{F}_{256} based on generator polynomial $F_4(x) = x^8 + x^6 + x^3 + x^2 + 1$ is shown below.

i	exp(i)	i	exp(i)	i	exp(i)	i	exp(i)	i	exp(i)	i	exp(i)	i	exp(i)	i	exp(i)
0	1	32	227	64	235	96	93	128	171	160	217	192	181	224	158
1	2	33	139	65	155	97	186	129	27	161	255	193	39	225	113
2	4	34	91	66	123	98	57	130	54	162	179	194	78	226	226
3	8	35	182	67	246	99	114	131	108	163	43	195	156	227	137
4	16	36	33	68	161	100	228	132	216	164	86	196	117	228	95
5	32	37	66	69	15	101	133	133	253	165	172	197	234	229	190
6	64	38	132	70	30	102	71	134	183	166	21	198	153	230	49
7	128	39	69	71	60	103	142	135	35	167	42	199	127	231	98
8	77	40	138	72	120	104	81	136	70	168	84	200	254	232	196
9	154	41	89	73	240	105	162	137	140	169	168	201	177	233	197
10	121	42	178	74	173	106	9	138	85	170	29	202	47	234	199
11	242	43	41	75	23	107	18	139	170	171	58	203	94	235	195
12	169	44	82	76	46	108	36	140	25	172	116	204	188	236	203
13	31	45	164	77	92	109	72	141	50	173	232	205	53	237	219
14	62	46	5	78	184	110	144	142	100	174	157	206	106	238	251
15	124	47	10	79	61	111	109	143	200	175	119	207	212	239	187
16	248	48	20	80	122	112	218	144	221	176	238	208	229	240	59
17	189	49	40	81	244	113	249	145	247	177	145	209	135	241	118
18	55	50	80	82	165	114	191	146	163	178	111	210	67	242	236
19	110	51	160	83	7	115	51	147	11	179	222	211	134	243	149
20	220	52	13	84	14	116	102	148	22	180	241	212	65	244	103
21	245	53	26	85	28	117	204	149	44	181	175	213	130	245	206
22	167	54	52	86	56	118	213	150	88	182	19	214	73	246	209
23	3	55	104	87	112	119	231	151	176	183	38	215	146	247	239
24	6	56	208	88	224	120	131	152	45	184	76	216	105	248	147
25	12	57	237	89	141	121	75	153	90	185	152	217	210	249	107
26	24	58	151	90	87	122	150	154	180	186	125	218	233	250	214
27	48	59	99	91	174	123	97	155	37	187	250	219	159	251	225
28	96	60	198	92	17	124	194	156	74	188	185	220	115	252	143
29	192	61	193	93	34	125	201	157	148	189	63	221	230	253	83
30	205	62	207	94	68	126	223	158	101	190	126	222	129	254	166
31	215	63	211	95	136	127	243	159	202	191	252	223	79	255	*

							• (.)						. (.)		• (.)
j	log(j)	j	log(j)	j	log(j)	j	log(j)	j	log(j)	j	log(j)	j	log(j)	j	log(j)
0	*	32	5	64	6	96	28	128	7	160	51	192	29	224	88
1	0	33	93	65	212	97	123	129	222	161	68	193	61	225	251
2	1	34	135	66	37	98	231	130	213	162	105	194	124	226	226
3	23	35	108	67	210	99	59	131	120	163	146	195	235	227	32
4	2	36	155	68	94	100	142	132	38	164	45	196	232	228	100
5	46	37	183	69	39	101	158	133	101	165	82	197	233	229	208
6	24	38	193	70	136	102	116	134	211	166	254	198	60	230	221
7	83	39	49	71	102	103	244	135	209	167	22	199	234	231	119
8	3	40	43	72	109	104	55	136	95	168	169	200	143	232	173
9	106	41	167	73	214	105	216	137	227	169	12	201	125	233	218
10	47	42	163	74	156	106	206	138	40	170	139	202	159	234	197
11	147	43	149	75	121	107	249	139	33	171	128	203	236	235	64
12	25	44	152	76	184	108	131	140	137	172	165	204	117	236	242
13	52	45	76	77	8	109	111	141	89	173	74	205	30	237	57
14	84	46	202	78	194	110	19	142	103	174	91	206	245	238	176
15	69	47	27	79	223	111	178	143	252	175	181	207	62	239	247
16	4	48	230	80	50	112	87	144	110	176	151	208	56	240	73
17	92	49	141	81	104	113	225	145	177	177	201	209	246	241	180
18	107	50	115	82	44	114	99	146	215	178	42	210	217	242	11
19	182	51	54	83	253	115	220	147	248	179	162	211	63	243	127
20	48	52	205	84	168	116	172	148	157	180	154	212	207	244	81
21	166	53	130	85	138	117	196	149	243	181	192	213	118	245	21
22	148	54	18	86	164	118	241	150	122	182	35	214	250	246	67
23	75	55	86	87	90	119	175	151	58	183	134	215	31	247	145
24	26	56	98	88	150	120	72	152	185	184	78	216	132	248	16
25	140	57	171	89	41	121	10	153	198	185	188	217	160	249	113
26	53	58	240	90	153	122	80	154	9	186	97	218	112	250	187
27	129	59	71	91	34	123	66	155	65	187	239	219	237	251	238
28	85	60	79	92	77	124	15	156	195	188	204	220	20	252	191
29	170	61	14	93	96	125	186	157	174	189	17	221	144	253	133
30	70	62	189	94	203	126	190	158	224	190	229	222	179	254	200
31	13	63	6	95	228	127	199	159	219	191	114	223	126	255	161

The log table for \mathbb{F}_{256} }	based on generator polynomial	$F_4(x) = x^8 + x^6 -$	$+x^3 + x^2 + 1$ is shown below.
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The second columns of the exp and log tables were calculated using the following Wolfram Mathematica code.

```
ln[1]:= list = { {0, 1} };
```

For[i = 1, i ≤ 254, i++, AppendTo[list, {i, If[list[-1, 2]] ≤ 127, 2 list[-1, 2]], BitXor[2 list[-1, 2]] - 256, 77]]}]];
exp = list[[All, 2]];
log = SortBy[list, Last][[All, 1]];

Appendix C

Matrix A for CM256

Matrix A in generator matrix $G = (I_{128} | A)$ that is used in the CM256 library is included below. The elements are integers between 0 and 255, as in the first column of Table 2.1 from Chapter 2.

´ 1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	١
138	146	34	179	181	211	4	83	97	216	128	147	20	212	9	44	
40	71	106	90	165	11	232	36	104	78	254	193	91	17	230	43	
100	154	209	249	14	247	144	58	207	250	161	39	25	118	62	51	
158	75	4	21	215	183	83	141	130	85	181	33	178	204	211	159	
255	76	16	86	60	68	174	225	64	87	41	152	172	107	30	65	
160	31	119	110	122	203	188	236	239	49	101	127	186	208	77	12	
26	242	218	165	232	200	103	47	57	194	106	176	81	40	108	148	
42	214	232	112	74	169	36	65	224	32	165	84	114	149	11	41	
182	243	241	122	188	159	73	9	171	115	119	23	33	160	44	89	
129	63	213	22	126	81	173	131	140	18	139	123	175	35	155	176	
190	19	118	12	89	83	150	120	49	62	240	24	38	253	4	73	
201	253	144	97	153	27	58	238	237	223	14	61	54	150	247	216	
232	28	105	189	123	64	111	168	107	63	56	92	29	165	251	69	
202	113	46	215	83	161	102	219	170	55	4	250	222	158	93	205	
121	231	194	251	32	193	187	191	50	248	78	214	189	108	70	206	
45	164	83	243	70	249	141	176	172	192	215	79	234	29	183	139	
28	218	115	217	80	127	90	112	45	178	49	6	233	44	170	96	
10	190	142	153	58	41	52	230	56	179	144	87	84	201	43	184	
62	128	33	121	195	199	79	13	205	233	186	142	232	131	76	237	
162	199	174	207	38	222	225	105	37	26	60	15	212	163	68	250	
110	155	37	83	102	209	233	107	238	227	46	235	78	202	132	149	
25	86	208	216	184	36	133	227	223	77	228	191	171	6	232	52	
188	228	113	233	164	50	91	114	108	8	75	34	120	122	217	246	
92	6	188	104	57	19	236	206	59	80	122	138	195	133	203	78	
235	66	22	109	231	255	239	59	232	204	10	240	44	250	164	54	
83	148	96	145	15	140	248	182	35	199	152	109	124	215	177	154	
234	130	124	126	173	216	66	62	71	169	213	111	61	129	51	136	
246	20	103	74	36	101	47	221	39	187	232	49	48	42	200	16	/

224	48	107	176	136	58	163	254	18	30	219	21	146	199	144	66
132	8	55	177	192	33	24	242	95	168	85	164	145	93	147	23
41	83	69	241	95	17	31	6	66	162	13	108	221	27	175	100
134	180	36	190	147	110	65	250	175	146	74	217	137	124	169	60
78	58	246	124	134	208	63	67	7	151	42	44	211	222	145	255
148	46	179	13	69	61	21	243	134	114	223	245	5	43	39	111
102	204	247	15	248	71	27	86	129	224	96	231	134	83	192	112
210	25	73	57	236	139	9	211	152	90	188	18	79	92	159	194
241	145	252	75	113	80	155	81	245	207	191	234	201	119	49	249
77	254	84	132	185	67	217	50	16	5	54	73	83	105	63	59
59	79	108	23	11	225	200	101	168	70	230	97	154	53	174	7
34	67	173	239	171	48	131	96	82	202	126	100	17	128	81	49
214	26	28	203	159	252	205	213	48	238	44	38	104	82	244	83
97	68	82	36	47	119	5	35	206	244	103	115	85	246	151	29
183	7	177	106	218	121	140	82	188	150	137	219	51	87	245	212
186	22	150	78	194	141	120	244	80	247	89	242	56	245	83	9
185	237	227	192	24	250	7	30	31	19	55	91	15	132	65	11
58	89	20	5	180	95	178	234	93	53	214	106	227	153	13	76
244	108	170	67	172	210	127	138	240	95	130	149	209	187	182	177
109	245	58	130	170	86	238	23	189	69	153	40	185	120	27	85
193	60	160	184	133	47	92	157	179	44	208	252	131	25	103	3
115	198	207	157	8	129	237	189	83	149	210	228	43	49	180	195
228	241	169	158	202	123	110	104	109	54	18	67	3	51	56	20
36	205	111	118	100	37	168	10	163	67	123	157	99	74	64	31
30	161	61	28	17	53	40	42	184	3	175	99	188	242	231	37
137	224	99	38	225	78	198	77	75	249	174	248	138	162	12	235
171	250	245	230	108	99	121	151	203	83	3	14	90	239	29	157
76	91	102	70	141	14	219	136	127	24	83	223	251	45	161	213
173	221	190	3	245	45	186	195	44	46	253	209	254	126	158	210
172	251	35	250	235	236	128	181	26	155	221	112	71	67	188	198
3	201	12	178	222	243	78	32	185	152	68	140	8	52	21	57
151	53	187	64	146	84	191	113	117	182	32	180	118	200	193	87
206	55	114	163	162	3	137	218	101	240	255	83	252	39	117	67
139	36	154	142	117	204	253	245	198	34	50	93	136	19	212	160
22	147	117	58	52	16	3	108	105	181	142	183	49	10	148	133
197	255	141	25	193	97	176	49	212	71	70	13	220	99	249	126
177	39	197	225	198	194	196	44	113	14	99	27	18	137	89	128
85	236	76	99	197	150	199	98	252	209	45	43	11	48	118	129
48	57	45	174	99	89	197	196	191	161	29	247	23	114	240	35
205	103	90	50	154	138	112	190	197	234	80	226	107	159	127	248
192	206	199	198	196	120	98	28	155	144	197	41	169	177	150	34
47	149	203	100	168	75	19	22	162	172	111	8	197	36	146	243
96	179	195	200	151	196	88	241	139	219	121	58	74	152	197	72)

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231	186	52	170	238	60	230	11	123	21	58	26	217	109	41	55 \
140	61	196	105	77	187	44	159	91	153	198	86	202	218	194	181
142	118	30	214	20	69	68	222	226	239	242	137	92	144	223	110
24	211	224	196	98	109	175	17	51	142	199	16	101	192	201	220
247	181	79	151	88	98	13	95	213	107	195	52	36	96	199	189
196	162	176	54	84	130	49	80	204	214	193	95	46	198	97	171
189	217	93	87	183	131	161	14	182	147	211	104	31	72	173	252
254	196	38	8	237	234	56	123	102	42	207	208	148	115	178	79
106	98	225	237	56	251	105	111	233	246	38	160	204	254	222	223
248	21	88	101	119	44	241	73	126	136	151	238	147	15	196	240
164	202	148	27	41	30	16	174	251	206	43	171	130	233	7	36
127	32	129	235	128	9	34	4	249	51	35	74	242	172	73	196
104	81	233	141	219	144	107	163	23	7	102	179	32	76	209	124
221	124	19	201	10	164	22	239	106	212	168	72	196	65	75	25
169	252	64	4	46	132	37	233	58	133	220	221	12	18	226	17
98	137	136	84	49	170	115	90	158	20	176	31	37	196	153	131
54	207	133	85	55	65	227	7	69	203	184	113	152	226	36	230
71	87	98	77	44	244	28	205	81	58	196	60	110	140	120	4
88	59	244	146	191	49	252	155	253	86	187	178	100	151	176	183
12	144	26	149	42	145	246	63	227	121	40	196	9	68	59	164
236	184	91	107	255	117	114	137	200	72	164	4	244	57	50	63
213	47	112	117	253	158	190	186	196	220	154	132	163	139	138	182
7	93	39	98	175	231	61	40	228	117	224	29	119	24	10	64
70	41	15	228	208	103	160	92	235	196	145	244	173	243	218	117
157	226	236	224	39	22	206	87	145	154	57	158	88	227	19	32
242	183	175	44	28	2	17	149	216	52	98	174	122	71	109	46
33	126	201	194	120	219	109	2	90	43	150	30	105	186	102	156
49	225	210	227	157	35	8	72	215	205	92	51	247	84	5	121
179	62	239	2	53	162	59	145	36	29	231	89	159	223	255	185
52	150	68	180	178	31	222	251	132	59	20	218	157	58	69	104
89	142	249	42	246	15	97	130	157	195	26	98	156	12	152	91
200	2	32	220	64	54	146	75	142	160	251	5	240	11	25	61
141	16	248	208	160	82	182	210	128	98	15	2	66	70	140	253
82	40	44	111	203	191	159	139	114	170	77	207	76	103	187	215
155	101	138	148	204	72	158	45	194	156	212	66	58	113	8	82
153	12	214	47	5	241	180	129	211	2	82	254	55	97	88	45
220	172	66	171	131	85	62	247	214	110	173	168	40	34	216	115
53	195	230	127	23	38	11	169	100	243	238	246	50	2	60	24
56	49	226	211	93	66	132	209	27	36	156	122	21	237	124	2
124	5	74	253	190	202	147	33	98	64	112	185	162	213	18	86
63	178	47	147	65	122	221	235	61	191	36	80	177	134	101	174
165	44	56	72	189	220	123	100	219	134	237	133	16	90	234	13 /

÷

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:

 $\mathbf{6}$

Above matrix A is calculated by the following Mathematica code.

```
In[12]= list = { {0, 1} };
For[i = 1, i ≤ 254, i++, AppendTo[list, {i, If[list[[-1, 2]] ≤ 127, 2list[[-1, 2]], BitXor[2list[[-1, 2]] - 256, 77]] }]];
exp = list[[All, 2];
log = SortBy[list, Last] [[All, 1]];
In[16]:= div[a_, b_] := exp[[Mod[log[[a]] - log[[b]], 255] + 1]]
In[17]:= For[i = 0, i ≤ 127, i++, x[i] = i]
For[j = 0, j ≤ 15, j++, y[j] = 128 + j]
In[21]:= A = Array[div[BitXor[x[0], y[#2 - 1]], BitXor[x[#1 - 1], y[#2 - 1]]] &, {128, 16}]
alog = Map[log[[#]] &, A, {2}]
```

Appendix D

Example usage of CM256 library in C++

The error-correcting code that is used is from https://github.com/catid/cm256. The C++ code below is the example usage code from Github, containing adjustments that allow us to gain insight into statuses of objects during running. Full code is not included to avoid unnecessarily lengthy appendices.

```
#include "cm256.h"
 1
 2
      #include <iostream>
      #include <iomanip>
 3
      #include <bitset>
 4
      #include <string>
 5
      #include <typeinfo>
 6
      #include <cstring>
      #include <climits>
 8
 9
      using namespace std;
10
11
      bool main()
12
13
      {
14
           if (cm256_init())
15
           ſ
                cout << "error while initializing cm256 library" << endl;</pre>
16
17
           exit(1);
18
19
20
           cm256_encoder_params params;
21
          int blockbytes = 5;
params.BlockBytes = 5; // Number of bytes per file block
params.OriginalCount = 6; // Number of blocks
params.RecoveryCount = 3; // Number of additional recovery blocks generated by encoder
22
^{23}
^{24}
^{25}
26
           // Size of the original file
27
           static const int OriginalFileBytes = params.OriginalCount * params.BlockBytes;
28
29
           // Allocate and fill the original file data
30
           uint8_t* originalFileData = new uint8_t[OriginalFileBytes];
31
        memset(originalFileData, 'a', OriginalFileBytes-1);
memset(originalFileData, 'z', 8);
memset(originalFileData, 'b', 4);
memset(originalFileData, 'c', 2);
32
33
34
35
36
37
           // print originalFileData
           cout << "originalFileData = " <<originalFileData<< " (" <<OriginalFileBytes<< " bytes)\n" << endl;</pre>
38
                                                                                                      Ascii" << endl;
           cout << "Index Memory loc Bits
39
           cout << "--
                                                                                                        -----" << endl;
40
        for (int i = 0; i < OriginalFileBytes; ++i)</pre>
41
42
           {
43
                if (i % 5 == 0)
44
                {
                     cout << setfill('0') << setw(5) << i;</pre>
^{45}
46

    ∏ printing memory (pointer) location

                                  Ox" << static_cast<void *>(&originalFileData[i]) << " ";</pre>
                     cout << "
47
^{48}
                if (i % 5 == 4)
    cout << " " << originalFileData[i - 4] << originalFileData[i - 3] << originalFileData[i - 2]</pre>
49
50
                     << originalFileData[i - 1] << originalFileData[i] << endl;
51
```

```
52
          }
 53
            // print encoder params
cout << "\nThe encoder's parameters are: \n " << params.BlockBytes << " bytes per block\n " <<
params.OriginalCount << " original blocks of data\n " << params.RecoveryCount <<</pre>
 54
 55
 56
               additionally generated recovery blocks.\n" << endl;
 57
 58
             // create blocks
 59
             cm256_block blocks[256];
 60
            61
 62
 63
 64
             // print blocks
 65
            cout << "i Pointer Value " << endl;
cout << "- ----- " << endl;</pre>
 66
 67
            for (int i = 0; i < params.OriginalCount; ++i)</pre>
 68
 69
             ſ
 70
                  cout << i << " 0x" << blocks[i].Block << " ";</pre>
                  for (int j = 0; j < params.BlockBytes; ++j)</pre>
 71
                       cout << reinterpret_cast<char*>(blocks[i].Block)[j];
 72
                  cout << endl;</pre>
 73
            }
 74
            cout << "\n" << endl;</pre>
 75
 76
 77
             // Print recoveryBlocks (only created, no data in there yet)
 78
             uint8_t* recoveryBlocks = new uint8_t[params.RecoveryCount * params.BlockBytes];
            cout << "Empty array 'recoveryBlocks' created (initialized) with room for " <<
params.RecoveryCount * params.BlockBytes << " elements:" << endl;
cout << "Index Memory loc Bits " << endl;
cout << "----- " << endl;</pre>
 79
 80
 81
 82
 83
            for (int i = 0; i < params.RecoveryCount * params.BlockBytes; ++i)</pre>
 84
             {
 85
                  recoveryBlocks[i] = 0
                 cout << setfill('0') << setw(5) << i;
cout << " 0x" << static_cast<void*>(&recoveryBlocks[i]);
cout << " " << bitset<8>(recoveryBlocks[i]) << endl;</pre>
 86
 87
 88
            }
 89
 90
             // Generate recovery data
 91
 92
             if (cm256_encode(params, blocks, recoveryBlocks))
 93
            {
                  cout << "cm256_encode(params,blocks,recoveryBlocks) was not 0, exit code." << endl;</pre>
 94
             exit(1);
 95
 96
 97
            // print blocks (1/3)
cout << "filled recoveryBlocks:</pre>
 98
                                                            " << endl;
 99
            cout << "Index Memory loc Bits " << endl;
cout << "----- " << endl;</pre>
100
101
             for (int i = 0; i < params.RecoveryCount * params.BlockBytes; ++i)</pre>
102
103
104
                  cout << setfill('0') << setw(5) << i;</pre>
                  cout << " 0x" << static_cast<void*>(&recoveryBlocks[i]);
cout << " " << bitset<8>(recoveryBlocks[i]) << endl;</pre>
105
106
            }
107
108
109
             // Initialize the indices
            cout << "" << endl;
cout << "We now initialize the indices." << endl;</pre>
110
111
            for (int i = 0; i < params.OriginalCount; ++i)</pre>
112
113
            ſ
                  blocks[i].Index = cm256_get_original_block_index(params, i);
114
                               blocks[" << i << "].Index is " << int(blocks[i].Index) << endl;</pre>
115
                  cout << "
            }
116
117
            cout << "" << endl:
118
             cout << "Will now simulate loss of data." << endl;</pre>
119
             cout << "Originally, blocks[0].Block points to memory address Ox" << blocks[0].Block <<
120
               and blocks[0].Index was " << int(blocks[0].Index) << endl;
121
             //// Simulate loss of data, subsituting a recovery block in its place ////
122
123
            blocks[0].Block = recoveryBlocks; // First recovery block
            blocks[0].Index = cm256_get_recovery_block_index(params, 0); // First recovery block index
124
            //// Simulate loss of data, subsituting a recovery block in its place ////
cout << "After simulating loss of data blocks[0].Block memory address 0x" << blocks[0].Block <<
" and blocks[0].Index is " << int(blocks[0].Index) << endl;</pre>
125
126
127
128
             // print blocks (2/3)
129
            cout << "i Pointer Value Index" << endl;
cout << "- -----" << endl;</pre>
130
131
            for (int i = 0; i < params.OriginalCount; ++i)</pre>
132
133
             {
134
                  cout << i << " 0x" << blocks[i].Block << " ";</pre>
                  for (int j = 0; j < params.BlockBytes; ++j)</pre>
135
                       cout << reinterpret_cast<char*>(blocks[i].Block)[j];
136
```

```
cout << " " << (int)blocks[i].Index << endl;</pre>
137
           }
138
139
           cout << "\n" << endl;</pre>
140
           cout << "Now on to the decoding." << endl;</pre>
141
           if (cm256_decode(params, blocks))
142
143
           ſ
                cout << "cm256_decode(params, blocks) was not 0, exiting." << endl;</pre>
144
                exit(1);
145
146
           }
147
           // print blocks (3/3)
148
           cout << "i Pointer Value Index" << endl;
cout << "_______"</pre>
149
           cout << "- ---
                                                -----" << endl;
150
151
           for (int i = 0; i < params.OriginalCount; ++i)</pre>
152
           {
                cout << i << " 0x" << blocks[i].Block << " ";</pre>
153
                for (int j = 0; j < params.BlockBytes; ++j)
    cout << reinterpret_cast<char*>(blocks[i].Block)[j];
154
155
                cout << " " << (int)blocks[i].Index << endl;</pre>
156
           }
157
           cout << "\n" << endl;</pre>
158
159
           // blocks[0].Index will now be 0.
160
161
           delete[] originalFileData;
162
163
           delete[] recoveryBlocks;
164
165
           return true;
      }
166
```

I ran the error-correcting code using C++ developer command prompt by executing the following commands in the directory where the cm256.cpp, cm256.h, gf256.cpp, gf256.h and main.cpp files are stored (for me those files were stored at c:/cm256code).



Appendix E

Example of MagiCtwin FTP server interface

A screenshot of a user connecting to the FTP Daemon in the MagiCtwin, using FileZilla. Other FTP applications can be used as well. In this case, a PNG file called compuwall_high_availability.png, a text document called compuwall.txt, an application called Handler.exe and two files called file_10gb and file_1gb are located on the users device. One file called file_10gb is already uploaded onto the FTP Daemon, and a file called file_1gb is currently being uploaded from the user's device onto the FTP Daemon. Dragging a file from left to right corresponds to uploading a data file from the user's device to the MagiCtwin's FTP Daemon on the TX side.

Connecting to the RX side can be done in a similar way. A different host, and a corresponding port number, should be entered. It is important that the username (and corresponding password) are the same for the TX and RX FTP server connections. Via a connection to the RX side's FTP server, the transmitted files can be retrieved.

E ftp://ftp-bbu@10.5.2.1:221	- FileZilla						_		×				
File Edit View Transfer	The Fifth View Transfer Server Bookmarks Heln												
Host: 10.5.2.1	sername: ftp-bbu	Pass <u>w</u> ord:	<u>P</u> ort: 221	Quickconnect	•								
Status: Directory listing of "/" Status: Starting upload of C:\U Status: File transfer successful, Status: Retrieving directory list	Attus: Directory listing of "/" successful ^ tatus: Starting upload of C:\Users\blub.Desktop\file_1gb ^ tatus: File transfer successful, transfered 1,073,741,824 bytes in 50 seconds ^ tatus: Retrieving directory listing of "/" ^												
									~				
Local site C\Users\bbu\Desktop\ v Remote site: /													
Appli	cation Data		^										
	acts ies												
	projects		~										
Filename	Filesize Filetype	Last modified	^	Filename	Filesize Filetype	Last modified	Permissions	Owner/G	iroup				
compuwall_high_availabil	45,590 PNG File	03/31/22 12:28:08		.									
compuwall.txt	2,304 Text Documer	nt 08/10/22 15:04:43		ile_10gb	10,737,418 File	10/11/22 13:51:	0644	611 2					
Handler.exe	897,024 Application	01/11/21 09:40:30											
file_10gb	10,737,418, File	10/11/22 13:39:11											
file_1gb	1,073,741,8 File	10/11/22 13:38:42	~										
Selected 1 file. Total size: 1,073,7	741,824 bytes			1 file. Total size: 10,737,418,240 bytes									
Server/Local file	Direction Remote file	Size	Priority Stat	us									
ftp://ftp-bbu@10.5.2.1:221													
C:\Users\bbu\Desktop\fil>> /file_1qb 1,073,741,8 Normal Transferring													
00:00:04 elapsed 00:00:11 left 31.8% 342,097,920 bytes (70.8 MiB/s)													
Queued mes (1) Palled transfers Successful transfers (13)													
						\$ @	Queue: 1024.0	MiB 🦸	🧕				