



## Effect of biological polymers on mobility and run-out distance of cohesive and non-cohesive sediment gravity flows

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# 1 Effect of biological polymers on mobility and run-out distance 2 of cohesive and non-cohesive sediment gravity flows

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## 6 7 ABSTRACT

8 Lock-exchange experiments were carried out to investigate the effect of biologically cohesive  
9 extracellular polymeric substances (EPS) on the mobility of sediment gravity flows laden with  
10 physically cohesive clay, non-cohesive coarse silt and non-cohesive fine sand. The results reveal  
11 significant differences in the head velocity, run-out distance and deposit shape of these flows related  
12 to differences in physical cohesion, particle size, and EPS content. These differences are captured in a  
13 three-way coupling model of turbulent forces, cohesive forces, and particle settling velocity. In  
14 general, biological cohesion reduces flow mobility, demonstrated most clearly by a progressive  
15 decrease in the run-out distance of the silt and clay flows, as the EPS concentration is increased. This  
16 reduction in flow mobility is caused by the dominance of cohesive forces over turbulent forces, which  
17 comprise turbulence attenuation and the bulk settling of a biologically cohesive gel in which EPS form  
18 a pervasive network of bonds between the sediment particles. However, sand-laden gravity flows  
19 were found to behave in a markedly different way, in that the head velocity and run-out distance first  
20 increase and then decrease, as the EPS concentration is increased. The increase in sand flow mobility  
21 is inferred to be caused by a reduction in the settling velocity of the sand particles, as the EPS cause  
22 an increase in flow viscosity at EPS concentrations that are sufficiently low to maintain turbulent flow.  
23 Once the EPS concentration is high enough for turbulence attenuation, the sand flows start to agree

24 with the silt and clay flows in establishing a negative correlation between flow mobility and EPS  
25 concentration caused by gelling. The experimental data also uncovered that deposits formed by EPS-  
26 rich, turbulence-attenuated flows are shorter and thicker and have more abrupt terminations than  
27 deposits formed by EPS-free or EPS-poor turbulent flows. The larger thickness of these deposits is  
28 partly caused by the ability of EPS to retain water and form matrix-supported textures. Earlier work  
29 has shown that EPS is common in many sedimentary environments, including those where sediment  
30 transport takes place regularly by particulate density currents. Combined with the increasing rate at  
31 which man-made structures, such as pylons and communication cables, appear in these  
32 environments, we argue that there is a need to incorporate the results of this study in applied models  
33 that aim to mitigate damage to such structures by sediment gravity flows.

34

35 *Key words:* Sediment gravity flows; Physical experiments; EPS; cohesion; clay; silt; sand

36

## 37 **1. Introduction**

38

39 Sediment gravity flows (SGFs) comprise mixtures of water and sediment driven by excess density and  
40 gravity forces (Middleton and Hampton, 1973). Bottom-hugging SGFs originate from sediment-laden  
41 river flows that plunge after entering seas and lakes, i.e., hyperpycnal flows, and from slope failures  
42 caused by, for example, earthquakes, storm waves, slope oversteepening after rapid sedimentation,  
43 and fishing gear dragged across a loose substrate (Postma, 2011). SGFs are a global phenomenon, with  
44 the capacity of transporting large volumes of sediment, carbon, nutrients, and pollutants (e.g.  
45 microplastics) to the deep ocean (Postma, 2011; Baker et al., 2017; Heerema et al., 2019; Craig et al.,  
46 2020). These flows can cause serious damage to subaqueous communication cables and other deep-  
47 water engineering infrastructure (Inman et al., 1976; Talling et al., 2015), and they have been linked  
48 to the formation of tsunamis (Johnson et al., 2017). Moreover, three-dimensionally stacked deposits

49 of SGFs create submarine fans that are amongst the largest reservoirs of oil and gas on Earth (Reading  
50 and Richards, 1994; Heerema et al., 2019). Despite recent successes in studying SGFs in modern lakes  
51 and oceans (Talling et al., 2013; Zabala et al., 2017), and valuable understanding gained from  
52 traditional outcrop and core studies of SGF deposits, laboratory simulations remain a valued method  
53 for obtaining a physical understanding of the dynamics of SGFs and the style of their deposits (e.g.  
54 Baker et al., 2017; Craig et al., 2020). Laboratory experiments are unique in allowing the parameters  
55 that control the complex dynamics of SGFs to be studied in isolation. This includes SGFs that are  
56 cohesive because of the presence of physically active clay particles (Baker et al., 2017) and biologically  
57 active extracellular polymeric substances (EPS) (Craig et al., 2020). The effect of biological cohesion  
58 on the mobility of clay, silt, and sand flows is the principal target of the present study.

59

## 60 **2. Background and rationale of study**

61

### 62 *2.1. Types of sediment gravity flow*

63

64 SGFs have been classified using rheology and particle support mechanism (Middleton and Southard,  
65 1984; Postma, 1986; Dasgupta, 2003; Haughton et al., 2009). In its simplest form, the rheological  
66 properties of a SGF can be characterized by yield strength, the resistance to deformation, and dynamic  
67 viscosity, the dependence of shear rate on applied shear stress (George and Qureshi, 2013;  
68 Widyatmoko, 2016). Turbidity currents are relatively dilute SGFs that exhibit Newtonian rheological  
69 behaviour (Middleton, 1993), i.e., without a yield strength and with a constant molecular viscosity  
70 (Chereskin and Price, 2001). Examples of denser SGFs with non-Newtonian behaviour are subaqueous  
71 debris flows, mud flows, and slides (Iverson, 1997). These flows may have a yield strength and a  
72 viscosity that decreases or increases as the shear stress is increased (Allen, 2009; Sumner et al., 2009;  
73 Manica, 2012). The main particle support mechanism in turbidity currents is turbulence (Middleton  
74 and Hampton, 1973; Heerema et al., 2019). Particles in debris flows, mud flows, and slides are

75 supported mostly by matrix strength (Lowe, 1979; Dasgupta, 2003), provided by non-cohesive silt,  
76 physically cohesive clay (Baker et al., 2017) and biologically cohesive EPS (Craig et al., 2020). Cohesive  
77 forces tend to attenuate or fully suppress turbulent forces (Baker et al., 2017; Craig et al., 2020), often  
78 leading to a reduction in SGF mobility. Here, mobility is defined as the ability of SGFs to transport  
79 suspended load over a certain maximum distance, referred to as the run-out distance. Flow mobility  
80 is also governed by other processes, such as sediment erosion and deposition, mixing with ambient  
81 fluid, and particle settling velocity, as coarser particles are more likely to be deposited and less likely  
82 to be eroded from the sediment bed than finer particles, especially if these particles are non-cohesive.

83 The change from turbulent to turbulence-suppressed SGF depends on the flow velocity and the  
84 suspended sediment type and concentration, with high-velocity, low-viscosity flows more likely to be  
85 turbulent than low-velocity, high-viscosity flows. It is therefore not possible to define a single  
86 threshold sediment concentration for changes between turbidity current and mud or debris flow  
87 (Baker et al., 2017; Heerema et al., 2019). A range of transitional flows with both turbulent and laminar  
88 behaviour has been defined, including high-density turbidity currents (Middleton and Hampton, 1973;  
89 Lowe, 1982; Baker et al., 2017), lower and upper transitional plug flows (Baas et al., 2009, 2011),  
90 hybrid flows (Haughton et al., 2009), and top-transitional plug flows (Hermidas et al., 2018; Craig et  
91 al., 2020). Particularly relevant to this study are the high-density turbidity currents and top-transitional  
92 plug flows, which have a lower region of attenuated turbulence separated from a fully turbulent upper  
93 region where mixing with the ambient fluid takes place. Such flows are intermediate between fully  
94 turbulent, low-density turbidity currents and laminar mud or debris flows (called plug flows by  
95 Hermidas et al. [2018] and Craig et al. [2020]).

96

97 *2.2. Sediment type and physical and biological cohesion*

98

99 In the laboratory experiments with clay-laden and silt-laden SGFs of Baker et al. (2017), cohesion  
100 started to affect the flow mobility at a volumetric concentration of 10%. Above 10%, the head  
101 velocities of the flows started to diverge; the silt flows retained a higher velocity than the clay flows.  
102 This threshold concentration will vary with flow velocity, but this difference in flow mobility signifies  
103 a stronger network of particle bonds in the clay flows and therefore a stronger turbulence attenuation  
104 (e.g. Kuenen, 1965; Felix et al., 2005). Frictional forces started to reduce the mobility, and also the  
105 run-out distance, of the non-cohesive silt flows at concentrations that were at least three times  
106 greater than those of the clay flows (Baker et al., 2017; their figure 10).

107 More recent research by Craig et al. (2020) showed that biological cohesion can have a similar effect  
108 on the mobility of SGFs as physical cohesion, but at concentrations that are several orders of  
109 magnitude lower. Biological cohesion is caused by EPS secreted by microorganisms, such as diatoms  
110 and bacteria, mainly for protection, communication and interaction, carbon storage, nutrient  
111 entrapment, and aggregation (Wingender et al., 1999; Wolfaardt et al., 1999; Sandhya and Ali, 2015;  
112 Wang et al., 2015; Costa, 2018). These polymers form a gel-like, three-dimensional structure that  
113 stabilises the microbial aggregates via different physicochemical mechanisms, including dispersion  
114 forces, electrostatic interactions, and hydrogen bonds (Flemming et al., 2000). The microorganisms  
115 and their EPS are found in many depositional environments, from rivers and estuaries to hypersaline  
116 lakes and deep-sea hydrothermal vents (Decho and Gutierrez, 2017). EPS also act as a cohesive binder  
117 between the organisms and the surrounding sediment particles (Chenu, 1995; Wolfaardt et al., 1999),  
118 forming biofilms on the sediment surface that are resistant to erosion by overriding flows (Malarkey  
119 et al., 2015). Moreover, EPS induce more pervasive cohesion in muddy and sandy substrates below  
120 biofilms (e.g. Malarkey et al., 2015; Hope et al., 2020) and assist in flocculation and gelling of clay in  
121 suspension flows (Flemming and Wingender, 2010; Gerbersdorf and Wieprecht, 2014). Craig et al.  
122 (2020) found that the mobility of SGFs carrying 15%, 22% and 23% kaolinite clay was reduced  
123 significantly by adding between 0.052% and 0.265% by weight of EPS, matching concentrations  
124 measured by Craig et al. (2020) in surficial deep-water sediment offshore New Zealand.

125

### 126 2.3. Research aims

127

128 The present study aims: (a) to determine the effect of non-cohesive silt and sand on the mobility of  
129 SGFs with and without EPS; (b) to compare the effect of EPS on flow mobility between physically  
130 cohesive and non-cohesive SGFs. Craig et al. (2020) used mixtures of clay and EPS, but SGFs also carry  
131 non-cohesive silt and sand (Kuenen, 1951; Britter and Simpson, 1978; Parker et al., 1987; Middleton  
132 and Neal, 1989; Baas et al., 2005). Like clay-laden SGFs, silt and sand flows may contain EPS supplied  
133 from the source area or eroded from the basin floor during transport. We hypothesise that EPS change  
134 the flow properties from Newtonian turbidity currents to non-Newtonian transitional flows and mud  
135 or debris flows with attenuated turbulence, which in turn reduces the flow velocity and run-out  
136 distance, and modifies the properties of their deposits, as for the mixed clay–EPS flows of Craig et al.  
137 (2020). Testing this hypothesis is essential for mitigating damage to subaqueous engineering  
138 infrastructure, forecasting the dispersal of nutrients and pollutants in the deep sea, and predicting the  
139 three-dimensional architecture of submarine fans.

140

## 141 3. Methods

142

143 Eleven laboratory experiments were conducted using a lock-exchange tank, 5 m long, 0.2 m wide and  
144 0.5 m deep, in the Hydrodynamic Laboratory, School of Ocean Sciences, Bangor University (Fig. 1). The  
145 0.31-m long reservoir behind the lock gate was filled with 0.3 m of a sediment–water or sediment–  
146 EPS–water mixture, while the channel downstream of the lock gate was filled with water only to the  
147 same depth. All experiments used natural seawater (density,  $\rho = 1027 \text{ kg m}^{-3}$ ; salinity,  $s = 35 \text{ PSU}$ )  
148 sourced from the Menai Strait, a tidal strait next to the Hydrodynamic Laboratory. Three different  
149 sediment types were used: cohesive kaolin clay (median size,  $D_{50} = 0.0091 \text{ mm}$ ); non-cohesive, very

150 well-sorted, silt-sized, spherical glass beads ( $D_{50} = 0.050$  mm); and non-cohesive, very well-sorted,  
151 sand-sized glass beads ( $D_{50} = 0.213$  mm). All experiments used a volumetric sediment concentration  
152 of 15% and weight concentrations of EPS of 0%, 0.15%, and 0.3%. The sand experiments used  
153 additional EPS concentrations of 0.05% and 0.2%. Xanthan gum was used to represent natural EPS (cf.,  
154 Malarkey et al., 2015; Craig et al., 2020). These sediment and xanthan gum concentrations were  
155 informed by the SGF experiments of Baker et al. (2017) and Craig et al. (2020).

156 Each starting suspension in the reservoir was prepared in the same way to account for any time-  
157 dependent behaviour, following procedures described by Baker et al. (2017) and Craig et al. (2020).  
158 First, the xanthan gum and sediment were mixed in dry form in a concrete mixer for 10 minutes. The  
159 seawater was then added to the dry material and mixed for another 10 minutes. Subsequently, the  
160 wet slurry was decanted into a large bucket and mixed for another 3 minutes with a handheld mixer  
161 to break up any remaining clumps of sediment. The slurry was then left to rest for 60 minutes, before  
162 being mixed a third time for 3 minutes (except for the silt–water mixture which required 6 minutes of  
163 mixing). Thereafter, a 180-ml subsample was taken from the slurry (except for 0.2% EPS sand) for  
164 subsequent particle settling velocity analysis and the slurry was added to the reservoir in the lock-  
165 exchange tank and mixed for 30 seconds with the handheld mixer, before lifting the lock gate and thus  
166 generating a bottom-hugging SGF. The moving head of each SGF was recorded using a high-definition  
167 video camera, with the aim to document changes in head shape, internal flow structure, and head  
168 velocity, following procedures described by Baker et al. (2017). Deposit thicknesses were recorded  
169 along the sidewall of the tank for the SGFs that halted before reaching the end of the tank. Replicates  
170 of three sand experiments showed that head velocities and run-out distances of the SGFs were  
171 reproducible (Table 1).

172 The 180-ml subsamples were used to determine particle settling velocities of the 15% pure sediment  
173 and mixed EPS–sediment suspensions. This involved timing the falling interface between clear water



174 and the settling suspension in the sampling container, after fully homogenising the starting  
175 suspension, following the procedure described by Baas et al. (2022, their figure 1).

176 Head velocities of the SGFs were calculated from the video footage at a spatial resolution of 0.1 m  
177 along the tank using Microsoft Movie Maker. With the exception of the clay flows laden with 0.3%  
178 EPS, each SGF could be subdivided into a period of constant head velocity followed by a period of  
179 waning head velocity. The period of constant head velocity was characterised by the mean pre-  
180 deceleration head velocity between 23% and 64% of either the run-out distance (red segment of the  
181 blue curve in Fig. 2) or 4.6 m for flows that reflected off the end of the tank (Fig. 2). For most SGFs that  
182 stopped before reaching the end of the tank — referred to as the main flow below — a dilute cloud  
183 bypassed the deposit of the main flow. This cloud, referred to as the bypassing flow below, continued  
184 to move down the tank at a slower rate than the main flow. The velocity of these bypassing flows was  
185 measured using the same method as for the main flow (orange curve in Fig. 2).

186

## 187 **4. Results**

188

### 189 *4.1. Settling velocity experiments*

190

#### 191 *4.1.1. EPS-free sediment*

192 The EPS-free 15% kaolin clay suspension had a settling velocity at  $0.0025 \text{ mm s}^{-1}$  (Fig. 3). This was two  
193 orders of magnitude lower than the settling velocity of the EPS-free 15% coarse silt suspension. As  
194 expected, the EPS-free 15% fine sand suspension had the highest settling velocity of  $4.7 \text{ mm s}^{-1}$  (Fig.  
195 3).

196

#### 197 *4.1.2. EPS-sediment mixtures*

198 All EPS-laden suspensions had a lower settling velocity than the equivalent EPS-free suspensions, and  
199 the settling velocity decreased, as the EPS concentration was increased, for all sediment types (Fig. 3).  
200 This decrease stretched over five orders of magnitude for the non-cohesive silt and sand suspensions,  
201 but the decrease was confined to a factor of only 4.5 for the cohesive clay suspensions between 0%  
202 and 0.30% EPS. Moreover, Fig. 3 shows that the greatest decrease in settling velocity for the silt  
203 suspensions was between 0% and 0.15% EPS, whereas the decrease in the settling velocity for the  
204 sand suspensions was relatively small between 0% and 0.05% EPS. At 0.30% EPS, the settling velocities  
205 were within one order of magnitude for the three sediment types (Fig. 3). Hence, the particle settling  
206 was less dependent on sediment type and size at 0.30% EPS than at lower EPS concentrations.

207

#### 208 4.2. *Visual observations and flow type classification*

209

210 Five out of the eleven experimental runs conducted, i.e., all EPS-free flows and flows Sa-0.05 and Sa-  
211 0.15 (Table 1), were characterised by fully turbulent behaviour. The head of these flows had a pointed,  
212 semi-elliptical shape with a prominent nose in a vertical section parallel to the flow direction (Fig. 4A;  
213 Table 1). These flow properties match the low-density turbidity currents of Baker et al. (2017; their  
214 table 3) and the turbidity currents s.s. of Craig et al. (2020; their table 2).

215 Flows Cl-0.15, Si-0.3 and Sa-0.3 consisted of a dense lower layer, in which turbulence attenuation was  
216 clearly visible, and a more dilute, lighter-coloured and fully turbulent, upper layer, characterised by  
217 mixing with the ambient water (Fig. 4B; Table 1). In combination with hydroplaning at the base of the  
218 head of these flows (Fig. 4B), the presence of linear coherent fluid entrainment structures (*sensu* Baker  
219 et al., 2017; Figs. 4C, D) and a more rounded flow front than the low-density turbidity currents, these  
220 flows resemble the high-density turbidity currents of Baker et al. (2017; their table 3) and the top-  
221 transitional plug flows of Hermidas et al. (2018) and Craig et al. (2020; their table 2). High-density  
222 turbidity currents Cl-0.15, Si-0.3 and Sa-0.3 also included a dilute turbulent flow released from the

223 upper part of the main flow after it stopped moving (Figs. 4E, F). These bypassing flows moved slowly  
224 down the tank.

225 Flows Si-0.15 and Sa-0.2 (Table 1) started as fully turbulent low-density turbidity current but they  
226 changed to stratified high-density turbidity current in the final phase of movement by vertical settling  
227 of sediment particles into the lower part of the flow. Flow Sa-0.2 exhibited coherent fluid entrainment  
228 structures, but fewer than in the high-density turbidity currents.

229 Finally, flow Cl-0.3 slid out of the reservoir as a coherent mass of sediment; it was devoid of any  
230 internal turbulence (Figs. 4G, H; Table 1). This viscous flow, which showed little mixing at the top and  
231 lacked hydroplaning, is classified as a slide (Baker et al., 2017 [their table 3]; Craig et al., 2020 [their  
232 table 2]). Immediately after the slide had stopped moving, a dilute turbidity current formed at the top  
233 of the slide. This current bypassed the front of the slide and then moved slowly towards the  
234 downstream end of the tank.

235 The flow types defined in this paper are plotted as a function of EPS concentration and sediment type  
236 in Fig. 5. This flow-type phase diagram reveals that the boundaries between low-density turbidity  
237 currents, transitional low-density to high-density turbidity currents, high-density turbidity currents,  
238 and slides move to higher EPS concentrations, as the sediment type changes from clay via coarse silt  
239 to fine sand. Fig. 5 also shows a stability field for mud flows, in the case of suspended clay, or debris  
240 flows, in the case of suspended silt or sand (*sensu* Baker et al., 2017), equivalent to the plug flows of  
241 Hermidas et al. (2018) and Craig et al. (2020; their table 2). These flow types were not observed in the  
242 present experiments, but they are expected in clay flows that contain between c. 0.2% and 0.25% EPS.

243

### 244 4.3. *Flow velocity and run-out distance*

245

#### 246 4.3.1. *EPS-free control experiments*

247 The EPS-free clay and silt flows behaved in a similar manner hydrodynamically. Both flows had a mean  
248 pre-deceleration head velocity of  $0.35 \text{ m s}^{-1}$  down to a distance,  $x$ , of 3 m along the tank (Figs. 6A, 7).  
249 The head velocity of these flows then gradually decreased to c.  $0.2 \text{ m s}^{-1}$ , before the flows reflected  
250 off the end of the tank (Figs. 6A,B, 8).

251 In contrast, the EPS-free sand flow decelerated earlier than flows CI-0 and Si-0. After maintaining a  
252 mean pre-deceleration head velocity of  $0.34 \text{ m s}^{-1}$  for 1.2 m, flow Sa-0 waned quickly, reaching a run-  
253 out distance of 2.5 m (Figs. 6C, 7, 8). A weak bypassing flow formed after the main flow had stopped,  
254 but it lost forward momentum quickly and ran out at  $x = 3 \text{ m}$  (Fig. 6C).

255

#### 256 4.3.2. *Mixed sediment–EPS experiments*

257 The head velocity profiles and run-out distances of the EPS-laden flows varied with sediment type and  
258 EPS concentration (Figs. 6–8). Except for slide CI-0.3, which started to decelerate immediately after  
259 leaving the reservoir, all flows were similar to the EPS-free control flows in that the head velocity was  
260 constant for a certain distance along the tank, before the flow started to decelerate exponentially.  
261 The differences in mean pre-deceleration head velocity were small, ranging from  $0.32 \text{ m s}^{-1}$  to  $0.37 \text{ m}$   
262  $\text{s}^{-1}$  across all sediment types and EPS concentrations, again excluding slide CI-0.3 (Fig. 7; Table 1). Yet,  
263 Fig. 7 reveals that the mean pre-deceleration head velocity in the mixed clay–EPS and silt–EPS flows  
264 decreased slightly, as the EPS concentration was increased and the flows changed from low-density  
265 to high-density turbidity current in the silt runs and from low-density turbidity current to slide in the  
266 clay runs. In contrast, the mean pre-deceleration head velocity in the mixed sand–EPS flows increased  
267 from 0% to 0.05% EPS and decreased from 0.15% to 0.30% EPS (Fig. 7). These trends are mimicked by  
268 changes in the location at which the flows started to decelerate, and, particularly, by changes in the  
269 run-out distance of the flows (cf. Figs. 7, 8). The run-out distance of the mixed clay–EPS and silt–EPS  
270 flows decreased, as the EPS concentration was increased, and the run-out distance in the mixed sand–  
271 EPS flows reached a maximum value of 4.4 m around 0.15% EPS (Fig. 8). Fig. 8 also shows that the run-

272 out distance of the clay flows decreased more rapidly with increasing EPS concentration than the run-  
273 out distance of the silt flows and that the run-out distances of flows Si-0.20 and Si-0.30 merge with  
274 those of flows Sa-0.20 and Sa-0.30 (Fig. 8). This merging of run-out distances thus appears to be  
275 confined to the turbulence-attenuated turbidity currents carrying non-cohesive coarse silt and fine  
276 sand.

277

#### 278 4.4. *Deposit properties*

279

280 The shape and thickness distribution of the deposits formed by the experimental flows varied with  
281 sediment type and EPS concentration, and therefore with flow type. The deposit of slide Cl-0.30 was  
282 short and thick; it dipped steeply and almost uniformly from the point of entry into the tank (Fig. 9A).  
283 The deposits of the low-density turbidity currents and the transitional low-density to high-density  
284 turbidity currents tended to be wedge-shaped, with a gradual termination near the location of run-  
285 out (e.g. flows Sa-0 and Sa-0.20; Fig 9B). The high-density turbidity current deposits had a more abrupt  
286 termination, which is most apparent in the deposit of flow Cl-0.15 (Fig. 9A). The EPS-free and low-EPS  
287 silt and sand flows formed firm deposits, whereas adding large amounts of EPS to these flows resulted  
288 in soft, water-rich and gel-like beds. Such EPS-rich beds were significantly thicker than the EPS-free  
289 and EPS-poor beds (e.g. Fig. 9B).

290

## 291 **5. Discussion**

292

### 293 *5.1. Controlling factors on the mobility of the biologically cohesive flows*

294

295 The amount of EPS added to the flows was two orders of magnitude lower than the sediment  
296 concentration, i.e., 0–0.3% EPS versus 15% sediment. The density difference with the ambient water,  
297 which drives the mobility of sediment gravity flows (Middleton and Hampton, 1973; Kneller and  
298 Buckee, 2000), was therefore nearly constant and unable to explain the observed variations in flow  
299 mobility and run-out distance. Other factors that controlled the flow mobility and run-out distance in  
300 the experiments were: (1) drag-induced turbulent forces; (2) cohesive forces of physical and biological  
301 origin, caused by kaolin clay and EPS, respectively; (3) particle settling velocity; and (4) hydroplaning  
302 (e.g. Middleton and Hampton, 1973; Lowe, 1982; Mohrig *et al.*, 1998; Baker *et al.*, 2017; Craig *et al.*,  
303 2020). Upward-directed turbulent forces tend to promote flow mobility by keeping particles in  
304 suspension and therefore maintaining the density difference with the ambient water (Middleton and  
305 Hampton, 1973). However, turbulent forces are counteracted by cohesive forces and particle settling,  
306 which both tend to hinder flow mobility and promote deposition. The settling velocity of single  
307 particles increases with increasing particle size, but it decreases with increasing particle concentration,  
308 because of the hindered settling effect (e.g. Richardson and Zaki, 1954; Baas *et al.*, 2022). However,  
309 the effect of hindered settling on flow mobility is expected to have been small in the experiments,  
310 because all flows carried the same volumetric concentration of sediment particles. Hydroplaning  
311 reduces the drag at the base of dense SGFs and it therefore promotes flow mobility and run-out  
312 distance (Mohrig *et al.*, 1998). Below, the combined effect of turbulent forces, cohesive forces, particle  
313 settling velocity, and hydroplaning is used to explain the differences in mobility between the  
314 experimental flows.

315

## 316 *5.2. Comparison of flow mobility: EPS-free control flows*

317

318 All the EPS-free SGFs behaved as fully turbulent, low-density turbidity currents (*sensu* Baker *et al.*  
319 2017). However, the mean pre-deceleration head velocity of flow Sa-0 was slightly lower than that of

320 flow Cl-0 and Si-0 ( $0.34 \text{ m s}^{-1}$  and  $0.35 \text{ m s}^{-1}$ , respectively; Table 1) and flow Sa-0 started to decelerate  
321 c. 1.5 m earlier than the finer-grained flows (Fig. 6). These differences are inferred to reflect the higher  
322 single particle settling velocity of the fine sand (Fig. 3), which worked against the upward-directed  
323 particle support by turbulence and caused the flow Sa-0 to have a significantly shorter run-out  
324 distance than flows Cl-0 and Si-0 (Fig. 8). The role of physical cohesion in flow Cl-0 was small,  
325 considering that the non-cohesive silt flow and the cohesive clay flow had almost identical head  
326 velocity profiles (Fig. 6). This agrees with Baker et al. (2017), who found that their 15% fine silt and  
327 kaolin flows had similar mean head velocities.

328

### 329 *5.3. Comparison of flow mobility: Biologically cohesive flows*

330

331 Our hypothesis that biologically cohesive EPS reduce the flow mobility, i.e., the run-out distance (Fig.  
332 8), is supported for the silt and clay flows. This reduction is also expressed by a lower mean pre-  
333 decelerating head velocity (Fig. 7). The biologically cohesive forces induced by the EPS attenuated the  
334 turbulence and changed the low-density turbidity currents to high-density turbidity currents (*sensu*  
335 Lowe, 1982), and eventually to slides (Mohrig and Marr, 2003) at the maximum EPS concentration in  
336 the clay flows (Table 1). These changes in flow type were accompanied by a reduction in the run-out  
337 distance through a change in the settling behaviour from single particle settling and hindered settling  
338 to bulk, 'en-masse', settling of gel-like substances, in which the EPS form a volume-filling network of  
339 bonds between the clay or silt particles (Craig et al., 2020). Flow transformation along the tank from  
340 low-density to high-density turbidity current, i.e., from fully turbulent flow to top transitional plug  
341 flow (Hermidas et al., 2018; Craig et al., 2020), signifies a downflow shift in the force balance from  
342 dominantly turbulent to dominantly cohesive during the deceleration phase, resulting in bulk settling.

343 In contrast to the similarities in the mobility of the pure silt and clay flows, described above, the clay–  
344 EPS flows started to decelerate earlier and had shorter run-out distances than the silt–EPS flows (Fig.  
345 6). These differences in the influence of biological cohesion may have two possible causes. Firstly, as  
346 for clay concentration, EPS concentration has an exponential relationship with flow viscosity and yield  
347 strength (e.g. Wan, 1982). Therefore, adding EPS to an already weakly cohesive clay flow may lead to  
348 a larger reduction in flow mobility than adding the same amount of EPS to a non-cohesive silt flow,  
349 even if this difference in physical cohesion is not reflected in a significant difference in the head  
350 velocity profile between these EPS-free flows (Figs. 6A, B). This interpretation assumes that sediment  
351 particles and EPS act independently in changing the cohesion of the flows. This assumption is not  
352 necessarily valid, because different types of sediment and EPS may interact in yet unknown ways in  
353 gravity flows. Further work is needed to explore such interactive processes. Secondly, the total particle  
354 surface area in clay flows is larger than in silt flows, because of the larger number of particles for a  
355 given concentration, which might increase the ease with which to establish particle bonds by EPS in  
356 the clay flows and thus a stronger network of particle bonds (Craig et al., 2020).

357 The sand flows are more complex than our hypothesis advocates, because the run-out distance, in  
358 particular, in the EPS-free sand flow was shorter than in the sand flows with low EPS concentrations.  
359 This can be explained by a three-way coupling between turbulence, cohesion, and settling velocity.  
360 EPS increase the viscosity of the water (Craig et al., 2020), which decreases the settling velocity of  
361 sand particles and allows the sand to be kept in suspension for longer. In turn, this promotes the run-  
362 out distance. However, this is valid only for flows in which the EPS concentration is low, so that the  
363 flow remains turbulent. At high EPS concentrations, the sand flow becomes transitional or laminar and  
364 behaves in a similar way to the silt and clay flows, despite the even lower settling velocity of sand in  
365 these EPS-rich flows. In other words, particle size is less important in controlling flow mobility in EPS-  
366 rich high-density turbidity currents, mud or debris flows, and slides. This is supported by the results of  
367 the settling experiments, which show that the clay, silt, and sand flows had more similar settling  
368 velocities at 0.3% EPS than at lower EPS concentrations (Fig. 3) and that the run-out distances of the



369 silt and sand flows merged at 0.2% and 0.3% EPS (Fig. 8). As in the silt-laden and clay-laden high-  
370 density turbidity currents and slides, bulk settling of a cohesive gel with pervasively bonded sand  
371 particles explains why the EPS-rich sand-laden high-density turbidity currents became less mobile and  
372 had a shorter run-out distance (Fig. 8).

373 Hydroplaning was confined to high-density turbidity currents in the experiments. This phenomenon  
374 occurs when the weight per unit area of material, here sediment and EPS, in the head of a flow is  
375 exceeded by the dynamic pressure generated by the fluid just below the head (Mohrig et al., 1998;  
376 Mohrig et al., 1999). Moreover, it is essential to prevent mixing of the overridden water with the flow  
377 above, thus the permeability of the base of the flow has to be sufficiently low (Talling, 2013). This was  
378 achieved fully in all the high-density turbidity currents, because of the high physical and biological  
379 cohesive strength of these flows. Hydroplaning, however, did not occur in the low-density turbidity  
380 currents, because the turbulence caused immediate mixing of water getting underneath the head of  
381 these flows (cf., Baker et al., 2017). The base of the mixed clay–EPS slide probably was sufficiently  
382 impermeable, but it did not allow hydroplaning either, because its low flow velocity prevented  
383 ambient water from being forced underneath the head of the slide. Hydroplaning in the high-density  
384 turbidity currents should have reduced the drag with the bed, but the shorter run-out distance of  
385 these flows compared to the low-density turbidity currents suggest that the effect of increased  
386 cohesion outweighed that of hydroplaning.

387

#### 388 *5.4. Comparison of deposits*

389

390 The deposits of all the low-density turbidity currents that stopped before reaching the end of the lock-  
391 exchange tank were thin and wedge-shaped (Fig. 9), which is typical for turbulent flows that comprise  
392 progressive single-particle settling and hindered settling (Baker et al., 2017). This includes the low-EPS

393 sand flows that were more mobile than the EPS-free sand flow, thus confirming that the EPS  
394 concentration in these flows was sufficiently low to prevent the flow from turning into a cohesive gel.  
395 The high-density turbidity currents and the slide, on the other hand, produced relatively thick deposits  
396 with a more abrupt termination, typical for bulk settling of cohesive gels (Baker et al., 2017; Fig. 9).  
397 The unusually large thickness of the EPS-rich deposits (Fig. 9) is testament to the ability of the EPS to  
398 retain water in the cohesive gel and prevent the deposit from attaining a grain-supported texture  
399 (Craig et al., 2020). As in physically cohesive clay beds (Mehta, 2013), such fluid-mud like deposits may  
400 take many months to consolidate to firm deposits.

401

#### 402 *5.5. Implications for natural biologically cohesive flows and deposits*

403

404 The present laboratory experiments show that EPS have a significant influence on the mobility and  
405 run-out distance of cohesive and non-cohesive SGFs and on the shape of their deposits. As such, our  
406 experiments extend the SGF experiments with mixed clay–EPS of Craig *et al.* (2020) to mixed silt–EPS  
407 and sand–EPS SGFs, and provide evidence that particle size, in addition to turbulence and cohesion,  
408 needs to be considered in predicting the behaviour of biologically cohesive SGFs (Fig. 10). The inferred  
409 three-way coupling between particle settling velocity, turbulent forces and cohesive forces dictates  
410 that EPS can increase the flow mobility, if EPS increase the flow viscosity whilst keeping the flow  
411 turbulent, and decrease the flow mobility, if EPS attenuate the turbulence and change the flow to a  
412 cohesive gel (Fig. 10). Within the parameter space of the experiments, mobility enhancement is  
413 characteristic of sandy low-density turbidity currents, and mobility reduction is typical of high-density  
414 currents, slides, and probably also mud flows and debris flows (Fig. 10).

415 These fundamental physical outcomes should also be relevant to natural flows. However, scaling of  
416 the experimental flows to natural prototypes is not possible at present, because standard scaling

417 methods do not allow for the inclusion of physical and biological cohesion in SGFs. Moreover, natural  
418 SGFs are more complex than the experimental flows simulated here; for example, single-particle size  
419 flows moving across a smooth, horizontal bed are an exception, rather than rule, in nature. In regard  
420 to flow velocity, the experimental SGFs are suitable analogues for hyperpycnal flows at river mouths  
421 and weak, single-surge, submarine SGFs triggered by earthquakes (Talling et al., 2013), sustained SGFs  
422 with a frontal high-density basal layer (Zabala et al., 2017), and natural SGFs that have decelerated to  
423 a similar velocity as in the experiments. It should also be mentioned that the experiments used a single  
424 type of clay and EPS. The rheological properties of clay and EPS vary with chemical composition. For  
425 example, kaolin clay has a lower cation exchange capacity, a key parameter for describing cohesive  
426 properties (Yong et al., 2012), than illite and montmorillonite, which are also common in prototype  
427 flows and deposits. Under given hydrodynamic conditions and clay concentration, SGFs laden with  
428 illite or montmorillonite should therefore lose mobility at lower EPS concentrations than kaolinite-  
429 laden flows, and thus be more prone to change from low-density turbidity current to high-density  
430 turbidity current, mud flows and slide.

431 The maximum EPS concentration of 0.3% used in the experiments was informed by the maximum EPS  
432 concentration found in the seabed offshore New Zealand (Craig et al., 2020). Unless higher EPS  
433 concentrations can be established elsewhere,  $\leq 0.3\%$  EPS contained in faster flows should have a  
434 smaller effect on flow mobility, since turbulent forces are positively correlated with flow velocity.  
435 Some support is provided by the experiments of Craig et al. (2020), since their SGFs laden with 15%  
436 kaolin clay were faster than in the present study ( $0.42 \text{ m s}^{-1}$  versus  $0.35 \text{ m s}^{-1}$ ), and the reduction in  
437 run-out distance for EPS concentrations up to 0.265% was less than in the present experiments. The  
438 exception may be the increased mobility of sandy SGFs with low concentrations of EPS, as the  
439 behaviour of these flows is more dependent on the particle settling velocity than on turbulence  
440 attenuation.

441 The shape of deposits of natural SGFs are expected to mimic that of the experimental SGFs. EPS  
442 generally cause SGF deposits to become shorter and thicker, except for deposits formed by high-  
443 mobility SGF laden with sand and low concentrations of EPS. These differences in shape can be  
444 expressed at first order by a deposit steepness parameter,  $S$ :

$$445 \quad S = \arctan\left(\frac{h_{max}}{X_R}\right), \quad (1)$$

446 where  $h_{max}$  is the maximum deposit thickness,  $X_R$  is the run-out distance, and  $S$  is given in degrees. The  
447 deposit steepness parameter is plotted against EPS concentration in Fig. 11 for the deposits of all flows  
448 that stopped before reaching the end of the tank. Short and thick deposits are expressed by relatively  
449 high  $S$  values, whereas long and thin deposits have low  $S$  values. Fig. 11 shows that EPS-laden clay  
450 flows form steeper deposits than sand and silt flows, because of their lower mobility induced by  
451 combined physical and biological cohesion. Natural deposits of EPS-free sand flows are expected to  
452 have higher  $S$  values than deposits of low-EPS sand flows, here for 0.05–0.2% EPS, because of their  
453 low viscosity and high sand settling velocity. At high EPS concentrations, here for 0.2% and 0.3% EPS,  
454 the deposit steepness increases with increasing EPS concentration for SGFs laden with clay or sand  
455 (Fig. 11), and presumably also for silt-laden flows, because of reduced flow mobility caused by greater  
456 biological cohesion. The steepness of deposits of low-EPS sand flows, here for 0.05–0.2% EPS, is  
457 proportional to EPS concentration on a logarithmic scale (Fig. 11). Despite the observed increase in  
458 mobility of these flows, which would cause the deposits to become longer and thinner and thus  $S$  to  
459 become lower, anomalously high increases in deposit thickness lead the increase in the steepness  
460 parameter, because of the above-mentioned development of soft, water-rich and gel-like beds.  
461 However, such beds may be unstable and bed consolidation by water expulsion may lead to a rapid  
462 decrease in deposit thickness, and therefore deposit steepness, under natural conditions. For natural  
463 hydrodynamic conditions comparable to those simulated in the experiments, the  $S$  values of deposits  
464 formed by high-EPS sand-laden and silt-laden SGFs, here for 0.3% EPS, are expected to be similar (Fig.

465 11). This supports the above interpretation that the size of non-cohesive particles becomes less  
466 important as the EPS concentration increases.

467 Because SGFs in nature can have run-out distances of hundreds to even thousands of kilometres, the  
468 results of this study should be included in the mitigation of possible damage to subaqueous  
469 infrastructure that is in the path of SGFs. If the sediment in the source area of these SGFs, as well as  
470 the sediment eroded from the bed during transport, is dominated by silt or clay, the presence of EPS  
471 in these flows can be expected to reduce the risk of damage to, for example, subaqueous pylons and  
472 communication cables. Although turbulent sand-rich SGFs generally are less mobile than turbulent  
473 silt-rich and clay-rich SGFs, and therefore, less likely to reach subaqueous infrastructure from the same  
474 source area, the enhanced mobility of sand flows carrying small amount of EPS may lead to a false  
475 sense of security, because such flows may travel further than expected.

476

## 477 **6. Conclusions**

478

479 The laboratory experiments presented in this paper reveal that the mobility of biologically cohesive  
480 sediment gravity flows and the shape of their deposits depend on the type and size of suspended  
481 particles, i.e., physically cohesive clay versus non-cohesive silt and sand, and the concentration of  
482 extracellular polymeric substances. Upon the addition of EPS at concentrations typical of deep-marine  
483 environments, the induced biological cohesion causes fine-grained EPS-free flows to become  
484 turbulence-attenuated, leading to a reduction in flow mobility. This reduction in mobility is reflected  
485 in the progressive shortening of the run-out distance of the flows, as the EPS concentration is  
486 increased. In contrast to clay and silt flows, the mobility of sand flows is affected not only by the  
487 balance between turbulent and cohesive forces, but also by the high settling velocity of the sand  
488 particles. The high settling velocity causes a low flow mobility under EPS-free conditions, reflected in  
489 a short run-out distance. However, the presence of EPS in sand flows induces a considerable increase

490 in run-out distance by increasing the flow viscosity, provided that the EPS concentration is sufficiently  
491 low to prevent turbulence attenuation in these flows. Above a certain threshold EPS concentration,  
492 sand flows become less mobile and behave in a similar way to silt flows and clay flows, because the  
493 formation of a biologically cohesive gel renders the settling velocity of subordinate importance. Since  
494 EPS has been shown to be pervasive in depositional environments where sediment gravity flows are  
495 expected to occur and where engineering infrastructure is being constructed at an increasing rate,  
496 these results need to be incorporated in models that aim to mitigate damage to such infrastructure.

497

498 All experimental data are available on FigShare via DOI 10.6084/m9.figshare.19960151 and URL  
499 [https://figshare.com/articles/dataset/Data\\_tables\\_for\\_Figs\\_3\\_6\\_9\\_docx/19960151](https://figshare.com/articles/dataset/Data_tables_for_Figs_3_6_9_docx/19960151).

500

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508

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677 **Figure captions**

678 **Table 1.** Summary of experimental data. LDTC = low-density turbidity current; HDTC = high-density  
679 turbidity current, LDTC>HDTC = low-density changing to high-density turbidity current near location  
680 of run-out.

681 **Fig. 1.** Top: Lock exchange tank. Bottom: Schematic diagram of the laboratory set up from the side.  
682 HD = high-definition.

683 **Fig. 2.** Procedure used to calculate the mean pre-deceleration head velocity. The red curve delimits  
684 the 23% and 64% locations along the flow path, on which the mean pre-deceleration head velocity  
685 calculations are based, where 0% is the gate location and 100% is the run-out distance of the flow or  
686 the end of the tank for flows that reflected off the end wall.

687 **Fig. 3.** Particle settling velocity against EPS concentration for the kaolin clay, coarse silt and fine sand  
688 used in the lock-exchange experiments.

689 **Fig. 4.** Typical examples of the experimental sediment gravity flows. A) Head of low-density turbidity  
690 current Si-0, characterised by pervasive turbulence, a pointed flow front, and lack of hydroplaning  
691 (arrow). B) Head of high-density turbidity current Cl-0.15, characterised by pronounced hydroplaning  
692 at the base (arrow) and a dense, turbulence-attenuated layer overlain by a more dilute, turbulent  
693 layer; note the distinct density interface (dashed line). C, D) examples of coherent fluid entrainment  
694 structures (arrows) in flows Si-0.15 and Si-0.3, respectively. E, F) examples of bypassing flow in high-  
695 density turbidity currents Cl-0.15 and Si-0.3. G, H) Slide Cl-0.3 after moving for 0.12 m and 0.74 m in  
696 the tank, respectively. Note the lack of hydroplaning, the viscous flow character, and the minor mixing  
697 with the ambient fluid. Flow is from left to right in all pictures. Scale at bottom of images is in  
698 centimetres.

699 **Fig. 5.** Flow-type phase diagram for different EPS concentrations and sediment types. LDTC = low-  
700 density turbidity current; HDTC = high-density turbidity current, LDTC>HDTC = low-density changing

701 to high-density turbidity current near location of run-out; MF/DF = mud or debris flow. Dashed lines  
702 denote estimated boundaries between flow types for the clay flows. The question mark refers to a  
703 mud and debris flow phase that was observed in previous work (e.g. Baker et al., 2017; Craig et al.,  
704 2020), but that was not captured within the limited resolution of EPS concentrations in the present  
705 experiments. Note that 18.5%, 26%, and 28% clay, instead of EPS, would have to be added to the clay  
706 flows to cross the boundaries between LDTC, HDTC, MF, and slide, respectively (Baker et al., 2017).  
707 These clay concentrations are two orders of magnitude higher than the boundary EPS concentrations,  
708 demonstrating the strong cohesive properties of EPS.

709 **Fig. 6.** Head velocity against distance along tank for all flows laden with (A) kaolin clay, (B) coarse silt,  
710 and (C) fine sand, with and without EPS. The head velocities of the bypassing part of flows are given  
711 in orange.

712 **Fig. 7.** Mean pre-deceleration head velocity and standard deviation of the mean (vertical lines) against  
713 EPS concentration for kaolin clay, coarse silt, and fine sand. LDTC = low-density turbidity current; HDTC  
714 = high-density turbidity current.

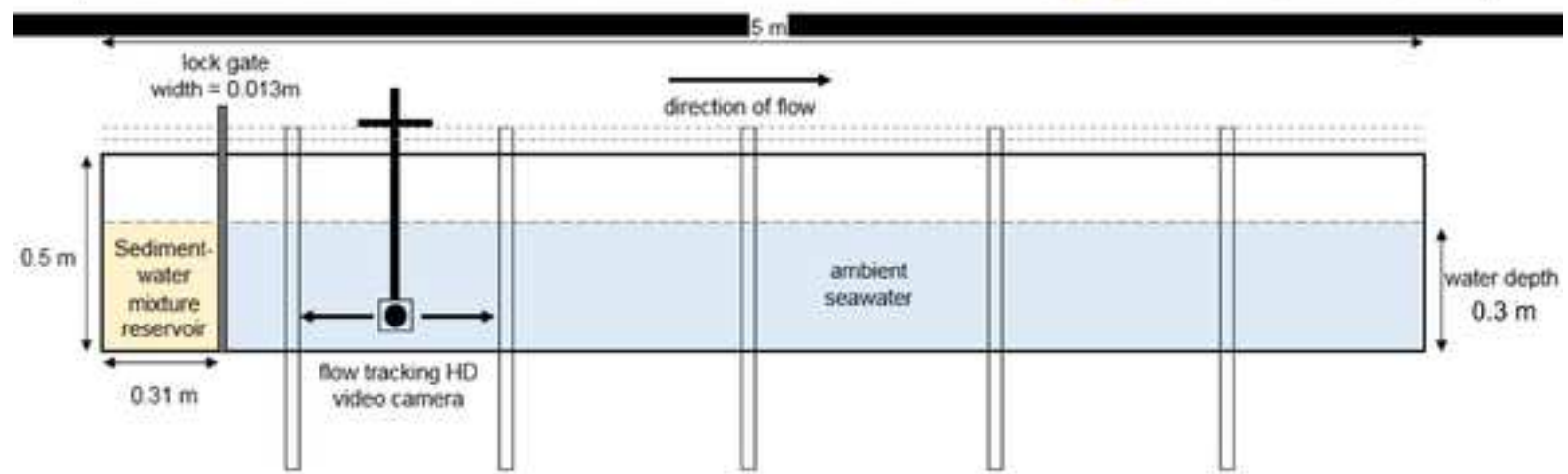
715 **Fig. 8.** Run-out distance against EPS concentration for kaolin clay, coarse silt and fine sand flows.  
716 Dashed blue line and green data point at 0% EPS denote minimum run-out distances, limited by the  
717 4.6-m length of the lock-exchange tank. Note that the plotted run-out distances exclude the bypassing  
718 part of the flows.

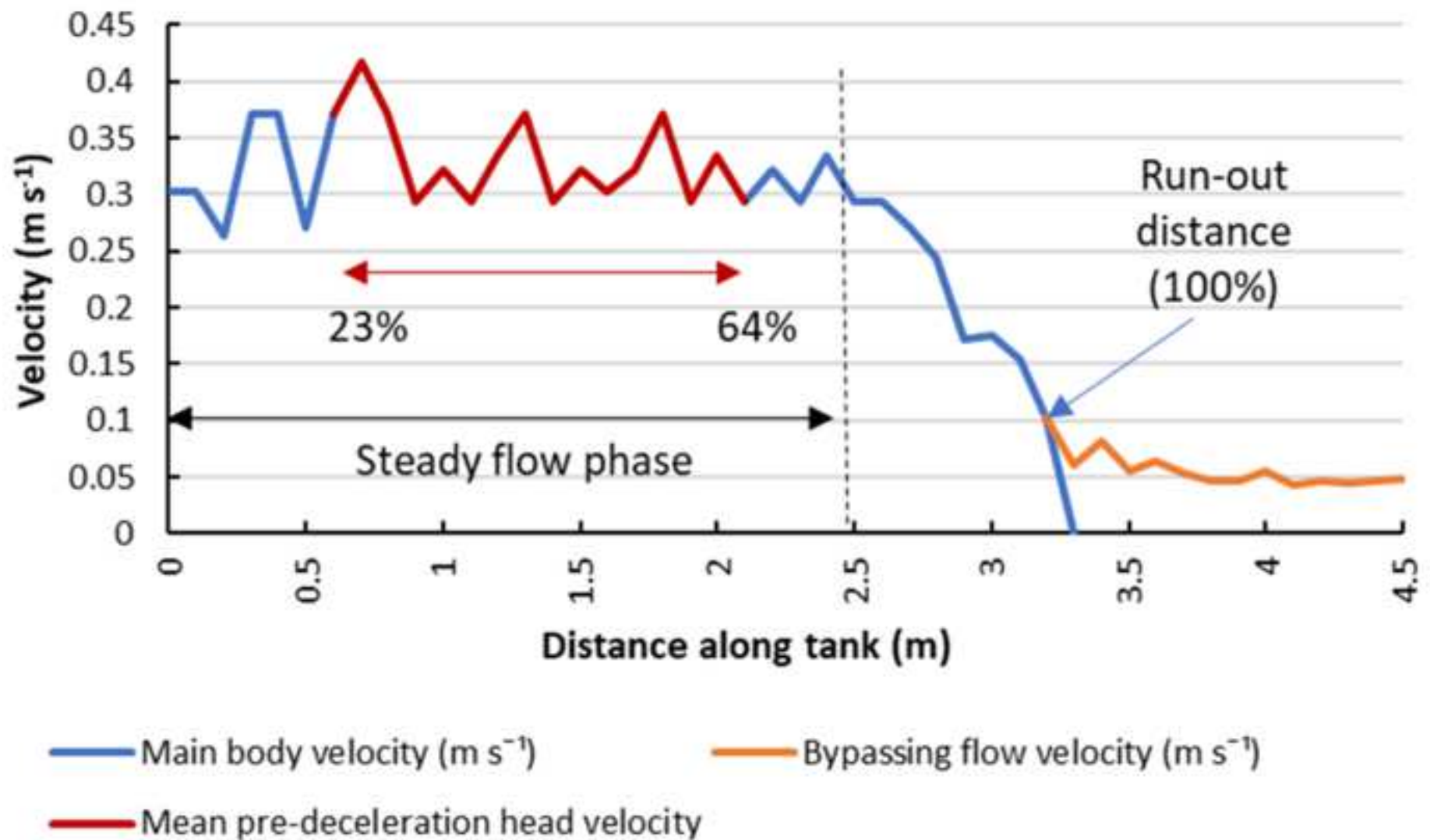
719 **Fig. 9.** Deposit thickness trends for all flows that did not reflect off the end of the lock-exchange tank.  
720 A) Kaolin clay and coarse silt deposits. B) Fine sand deposits.

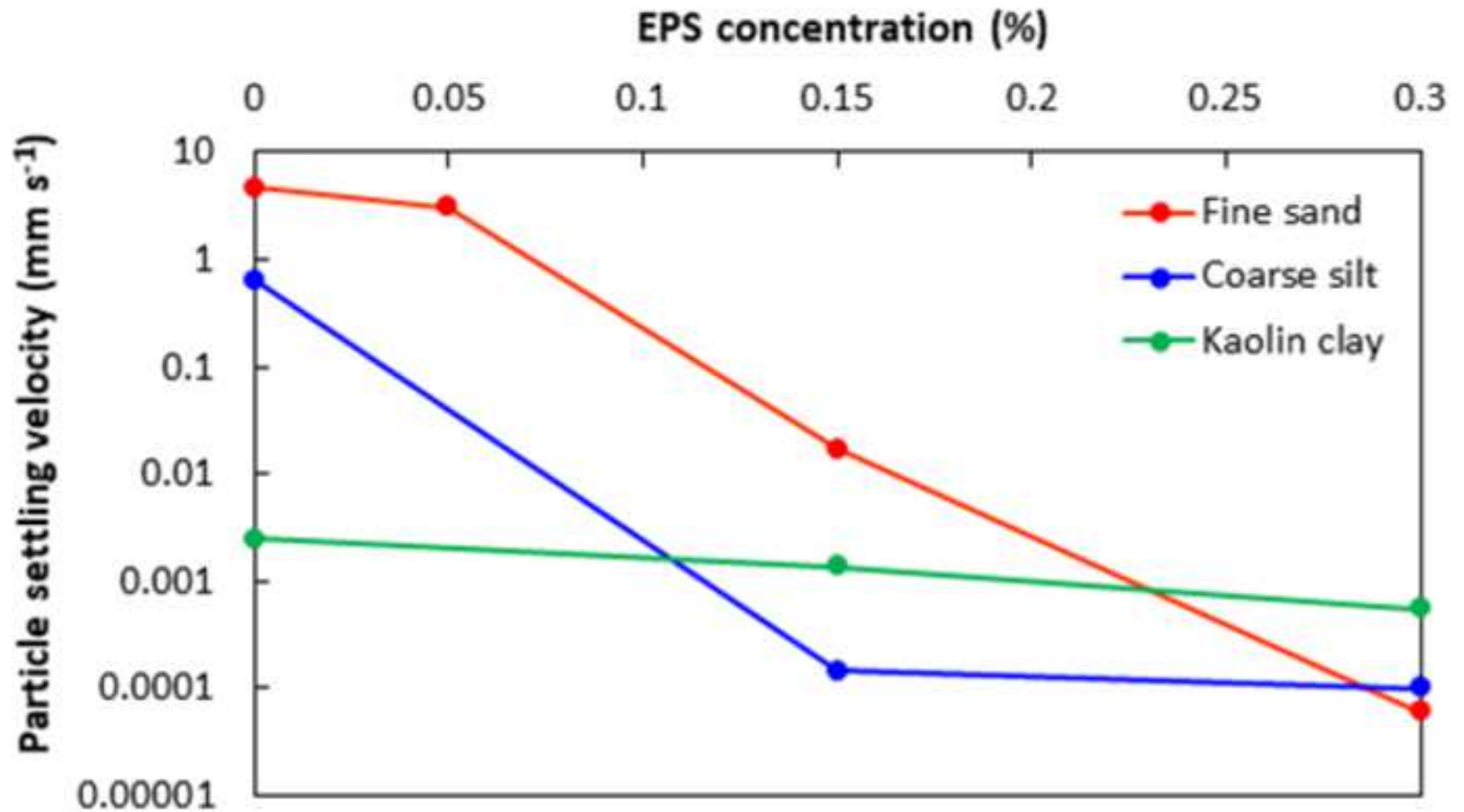
721 **Fig. 10.** Conceptual model summarising the effect of key parameters on flow mobility (top) and the  
722 dependence of type and run-out distance of sediment gravity flows on these parameters, informed by  
723 the laboratory experiments (bottom). The column labelled 'Dominant process' provides the dominant  
724 physical or biological controls on run-out distance.

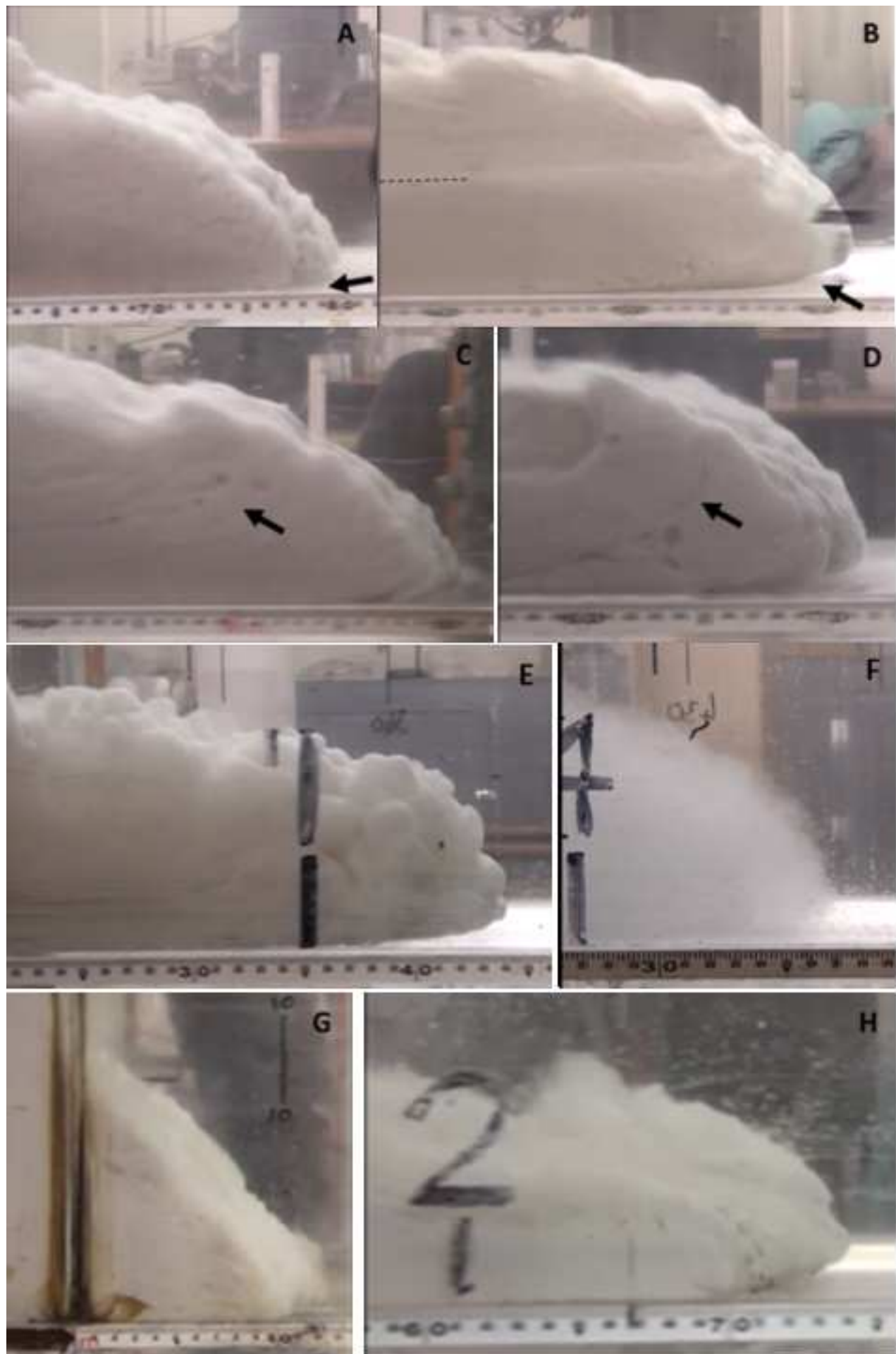


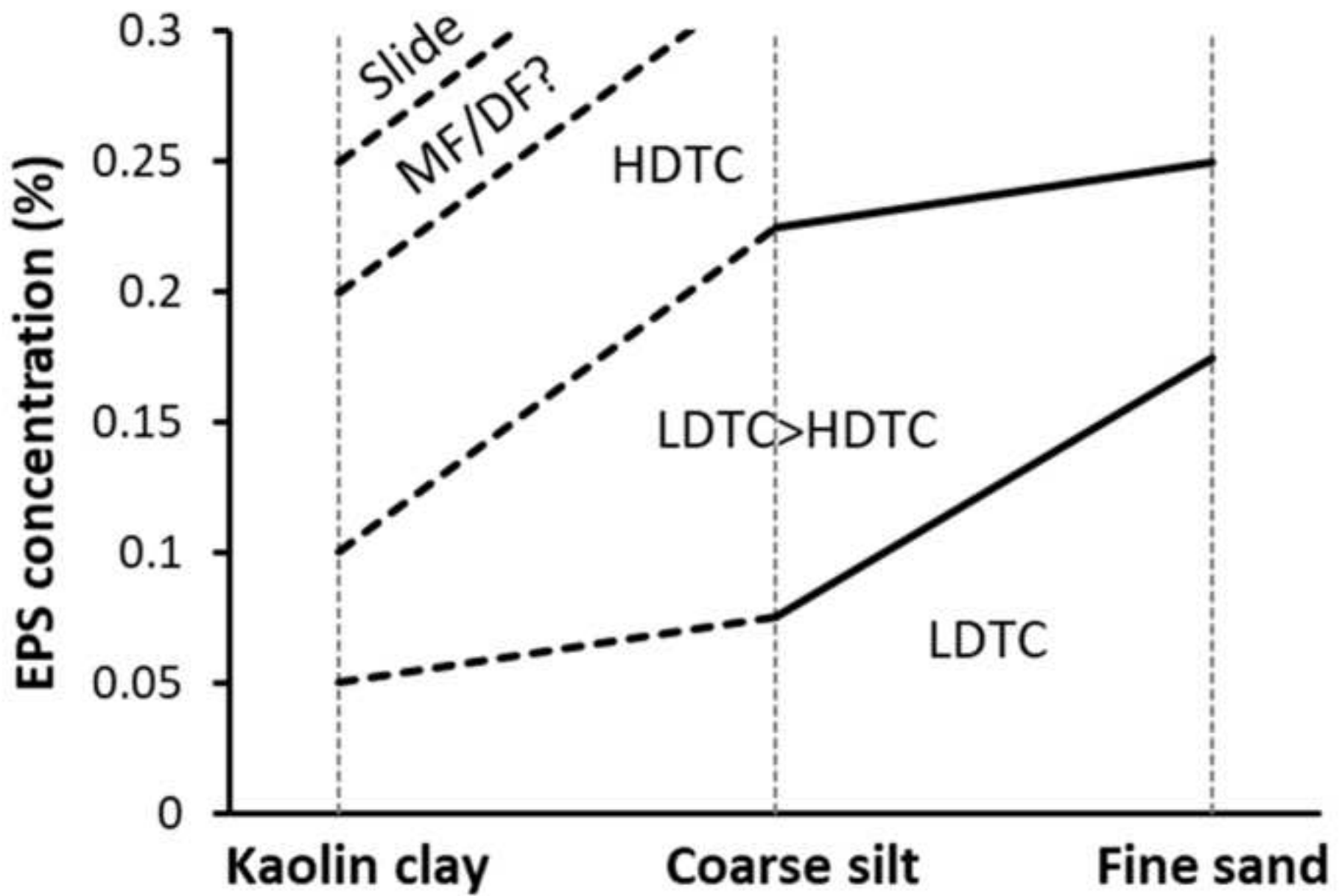
725 **Fig. 11.** Deposit steepness against EPS concentration for all flows that did not reflect off the end of  
726 the lock-exchange tank.

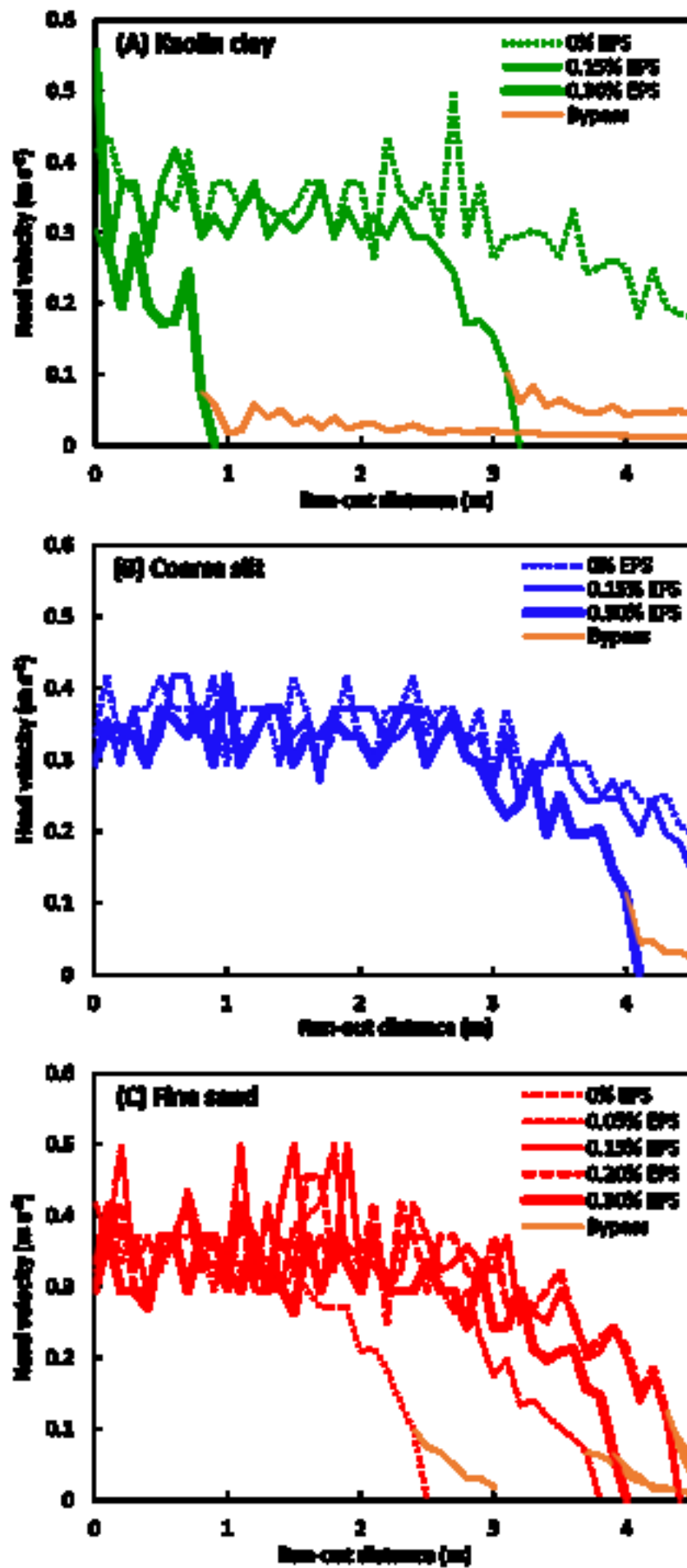


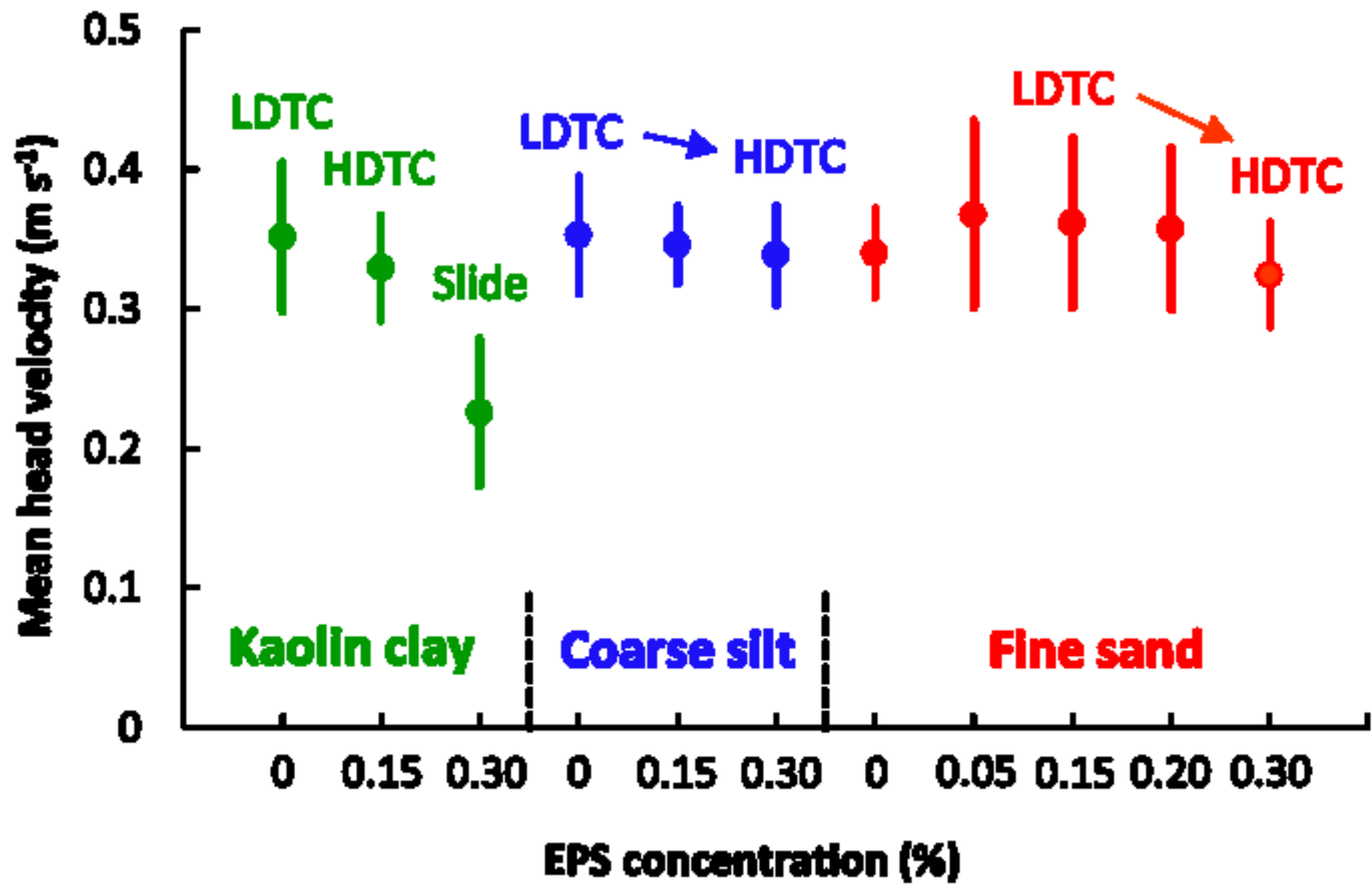




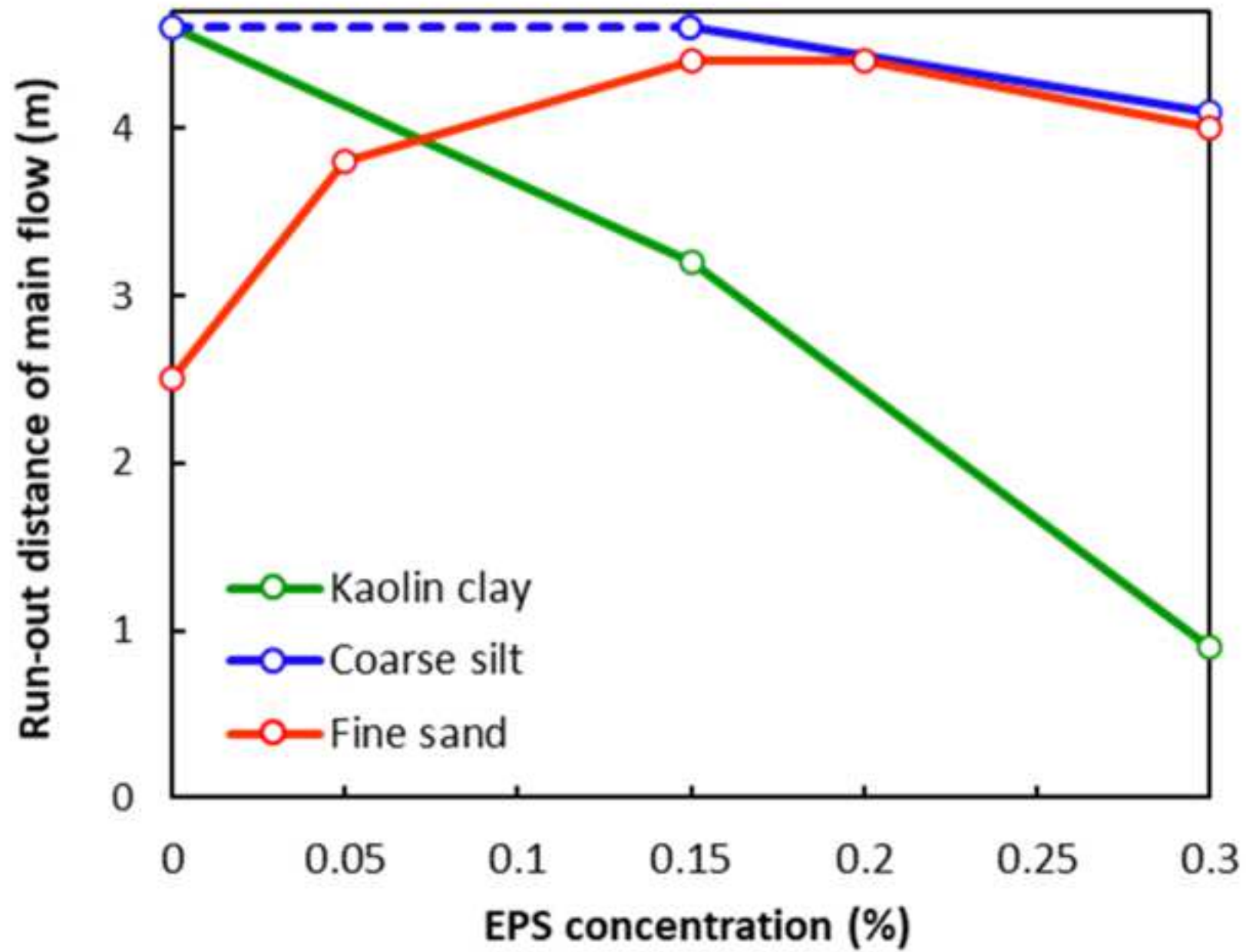


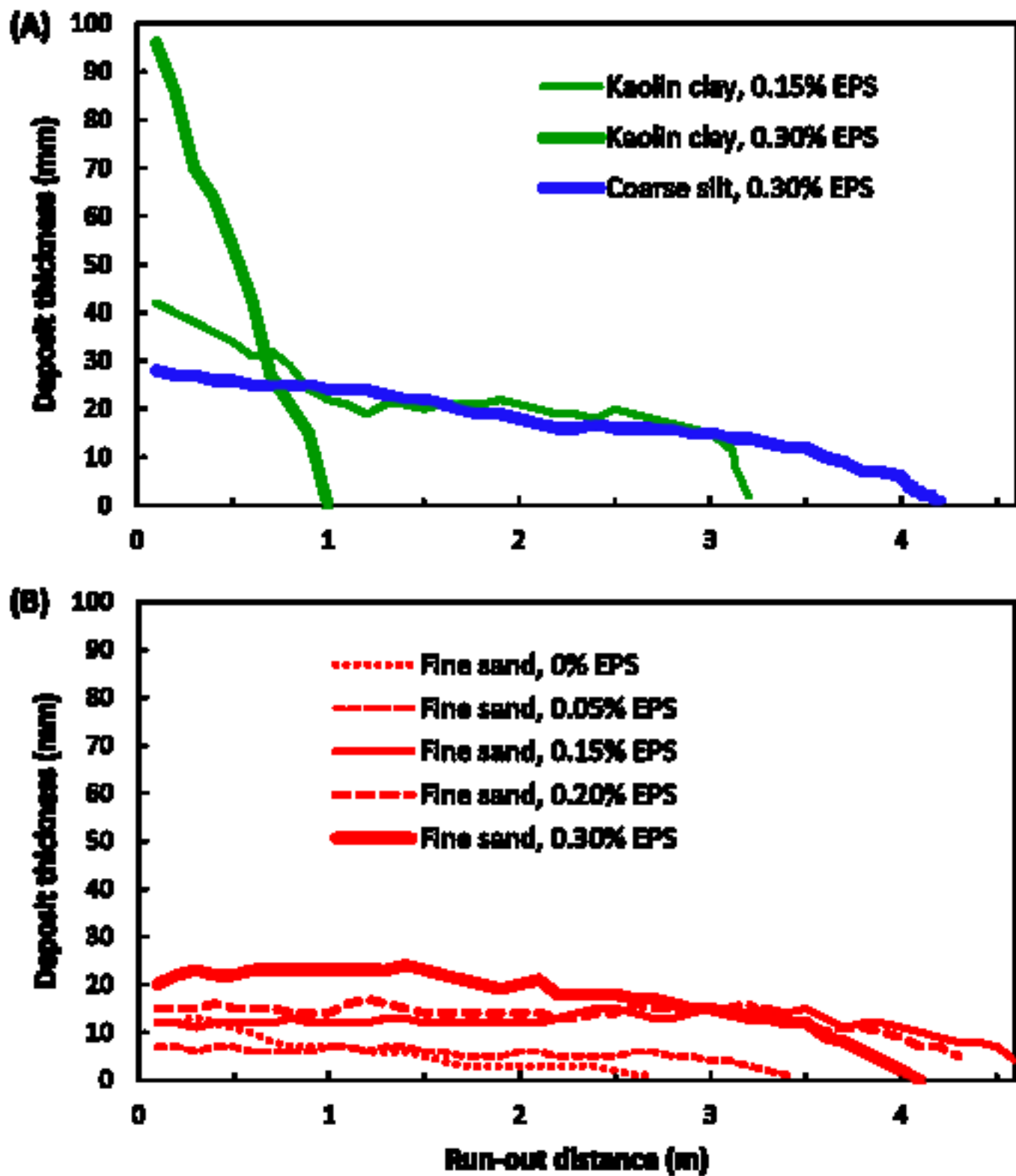


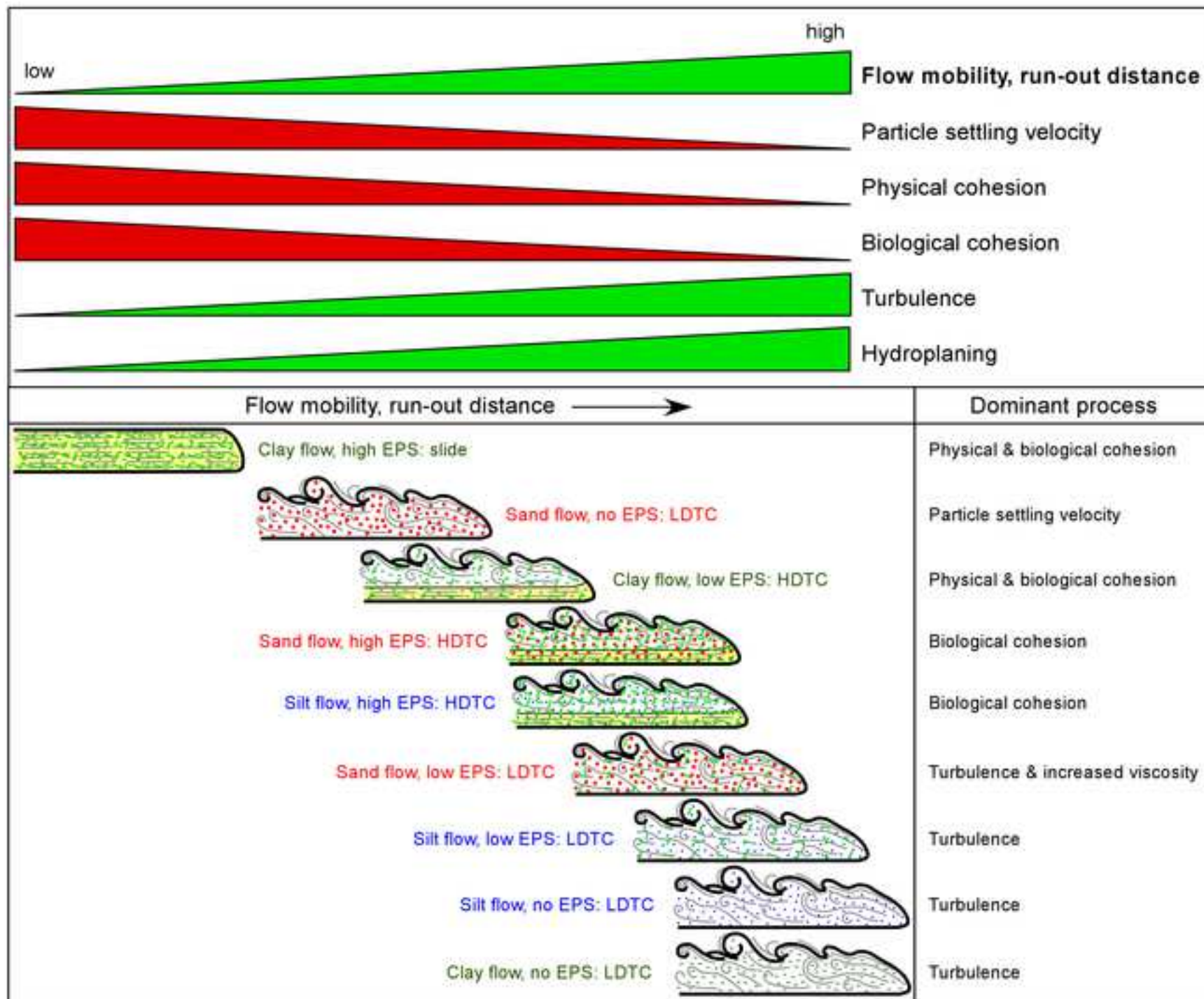


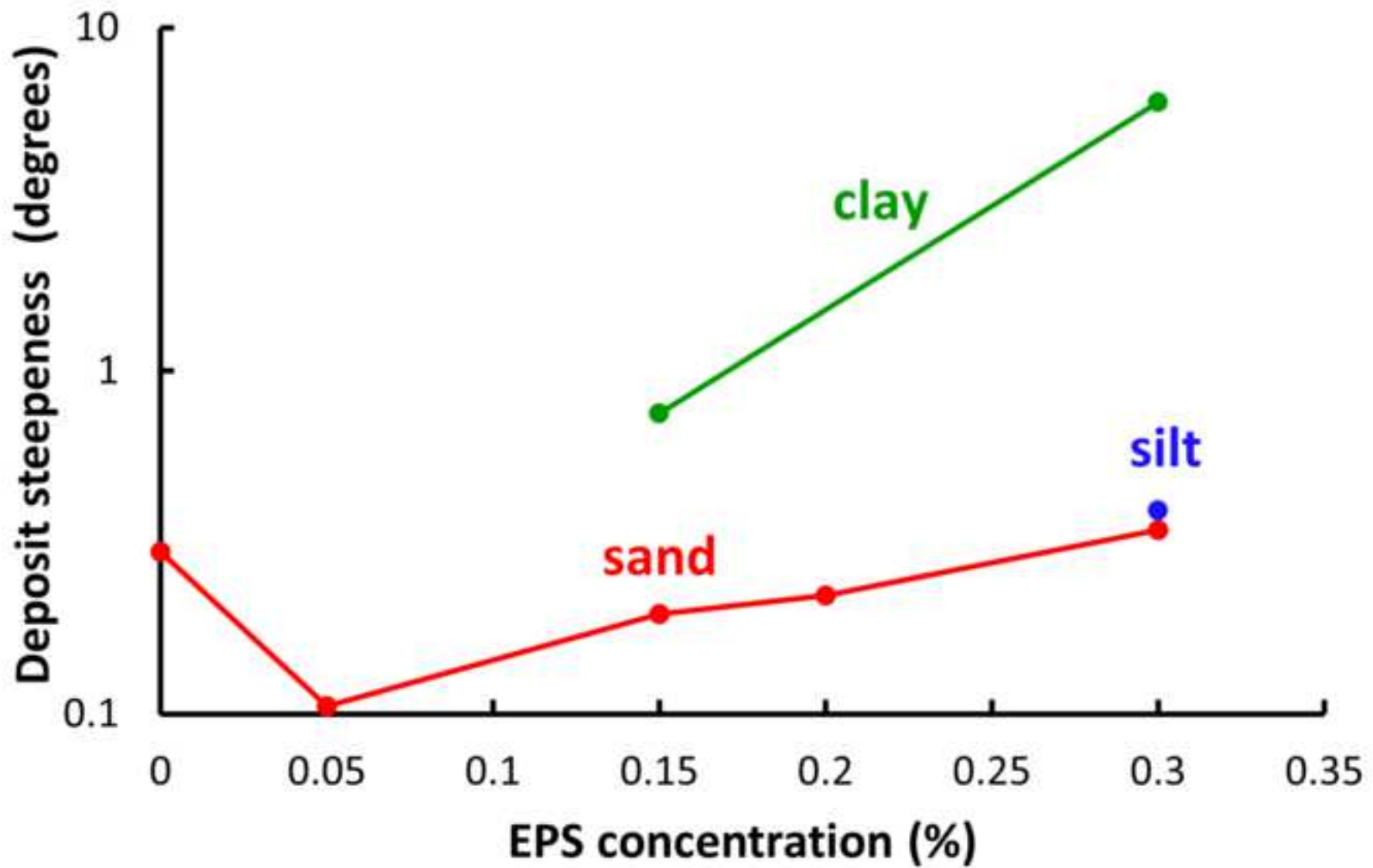












1 **Table 1.** Summary of experimental data. LDTC = low-density turbidity current; HDTC = high-density  
 2 turbidity current, LDTC>HDTC = low-density changing to high-density turbidity current near location  
 3 of run-out.

Experimental run	Sediment type	EPS concentration (%)	Pre-deceleration velocity (m s <sup>-1</sup> )	Froude number*	Run-out distance (m)	Flow type
Cl-0	Clay	0	0.351	0.66	> 4.6**	LDTC
Cl-0.15	Clay	0.15	0.329	0.62	3.2	HDTC
Cl-0.3	Clay	0.3	0.226	0.82	0.9	Slide
Si-0	Coarse silt	0	0.353	0.70	> 4.6**	LDTC
Si-0.15	Coarse silt	0.15	0.346	0.65	> 4.6**	LDTC> HDTC
Si-0.3	Coarse silt	0.3	0.338	0.64	4.1	HDTC
Sa-0	Fine sand	0	0.340	0.75	2.5 (2.6)***	LDTC
Sa-0.05	Fine sand	0.05	0.368	0.71	3.8	LDTC
Sa-0.15	Fine sand	0.15	0.362	0.71	4.4 (4.6)***	LDTC
Sa-0.2	Fine sand	0.2	0.357	0.74	4.4	LDTC> HDTC
Sa-0.3	Fine sand	0.3	0.324	0.66	4 (4)***	HDTC

4 \* Densimetric Froude number was calculated from flow thickness at x = 1.5 m (except for Cl-03: x =  
 5 0.5 m), mean pre-deceleration head velocity, and initial flow density.

6 \*\* Flow reached the end of lock-exchange tank.

7 \*\*\* Run-out distances between brackets are based on replicate experiments.

**Declaration of interests**

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests: