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OPTIMAL EXPERIMENTAL PLANNING
OF RELIABILITY EXPERIMENTS
BASED ON COHERENT SYSTEMS

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OPTIMAL EXPERIMENTAL PLANNING
OF RELIABILITY EXPERIMENTS
BASED ON COHERENT SYSTEMS

A Dissertation Presented to the Graduate Faculty of the

Dedman College

Southern Methodist University

in

Partial Fulfillment of the Requirements

for the degree of

Doctor of Philosophy

with a

Major in Statistical Science

by

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Optimal Experimental Planning
of Reliability Experiments
based on Coherent Systems

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In industrial engineering and manufacturing, assessing the reliability of a product or system is an important topic. Life-testing and reliability experiments are commonly used reliability assessment methods to gain sound knowledge about product or system lifetime distributions. Usually, a sample of items of interest is subjected to stresses and environmental conditions that characterize the normal operating conditions. During the life-test, successive times to failure are recorded and lifetime data are collected. Life-testing is useful in many industrial environments, including the automobile, materials, telecommunications, and electronics industries.

There are different kinds of life-testing experiments that can be applied for different purposes. For instance, accelerated life tests (ALTs) and censored life tests are commonly used to acquire information in reliability and life-testing experiments with the presence of time and resource limitations. Statistical inference based on the data obtained from a life test and effectively planning a life-testing experiment subject to some constraints are two important problems statisticians are interested in. The experimental design problem for a life test has long been studied; however, the experimental planning considering putting the experimental units into systems for a life-test has not been studied. In this thesis, we study the optimal experimental planning problem in multiple stress levels life-testing experiments

and progressively Type-II censored life-testing experiments when the test units can be put into coherent systems for the experiment.

Based on the notion of system signature, a tool in structure reliability to represent the structure of a coherent system, under different experimental settings, models and assumptions, we derive the maximum likelihood estimators of the model parameters and the expected Fisher information matrix. Then, we use the expected Fisher information matrix to obtain the asymptotic variance-covariance matrix of the maximum likelihood estimators when n -component coherent systems are used in the life-testing experiment. Based on different optimality criteria, such as D -optimality, A -optimality and V -optimality, we obtain the optimal experimental plans under different settings. Numerical and Monte Carlo simulation studies are used to demonstrate the advantages and disadvantages of using systems in life-testing experiments.

Keywords. Accelerated life tests; Multi-level stress testing; Coherent systems; System structure; Constant-stress accelerated life tests; Step-stress accelerated life tests; Cumulative exposure model; Type-II censoring; Progressive Type-II censoring; Extreme value distribution; Fisher information; Lognormal distribution; Maximum likelihood estimators; Monte Carlo simulation; Weibull distribution

TABLE OF CONTENTS

LIST OF FIGURES	xii	
LIST OF TABLES	xiii	
CHAPTER		
1	Introduction	1
1.1.	Problems of Interest	1
1.2.	System Structure, Coherent System and System Signature	2
1.2.1.	System structure and coherent system	2
1.2.2.	System signature	4
1.3.	Censoring Schemes	5
1.3.1.	Type-I censoring	6
1.3.2.	Type-II censoring	7
1.3.3.	Progressive Type-II censoring	7
1.3.4.	Progressive Type-I censoring	8
1.4.	Location-scale Family of Distributions and Log-location-scale Family of Distributions	9
1.5.	Statistical Inference Based on System Lifetime Data	11
1.6.	Experimental Planning for Accelerated Life Tests	12
1.6.1.	Optimality criteria	13
1.6.2.	Constant-stress ALTs	13
1.6.3.	Step-stress ALTs	15
1.7.	Scope of the Thesis	17
2	Optimal Experimental Planning for Constant-Stress Accelerated Life-Testing Experiments based on Coherent Systems	20

2.1.	Introduction	20
2.2.	Models and Optimality Criteria.....	21
2.2.1.	Multi-level constant-stress experiment with Type-II censoring	21
2.2.2.	Parameter estimation	24
2.2.2.1.	Maximum likelihood estimation	24
2.2.2.2.	Fisher information and asymptotic variance-covariance matrices	26
2.2.3.	Optimality criteria	27
2.2.4.	Settings for optimal experimental planning	29
2.3.	Using n -component Series Systems for Experiments	31
2.3.1.	Lognormal distributed components	35
2.3.2.	Weibull distributed components	38
2.4.	Numerical Illustrations for Series Systems.....	41
2.4.1.	Two-stress-level case	41
2.4.2.	Four-stress-level case	48
2.4.3.	Discussion	51
2.5.	Monte Carlo Simulation Study.....	52
2.6.	Illustrative Example.....	58
2.7.	Concluding Remarks	66
3	Optimal Experimental Planning for Progressively Type-II Censored Experiments based on Coherent Systems.....	68
3.1.	Introduction	68
3.2.	Progressively Type-II Censored Experiments with Coherent Systems.....	71
3.3.	Maximum Likelihood Estimation	72
3.3.1.	Maximum likelihood estimation of model parameters.....	73

3.3.2.	Fisher information and asymptotic variance-covariance matrices	75
3.4.	Experimental Planning and Optimality Criteria	76
3.4.1.	Settings for optimal experimental planning	76
3.4.2.	Optimality criteria	79
3.5.	Specific Coherent Systems Being Considered	81
3.5.1.	l -out-of- n systems	82
3.5.1.1.	Series system: $l = 1$	83
3.5.1.2.	Parallel system: $l = n$	84
3.5.1.3.	2-out-of- n system	86
3.5.1.4.	3-out-of- n	87
3.5.2.	Series-parallel and parallel-series systems for $n = 3$	88
3.5.2.1.	Series-parallel systems for $n = 3$	89
3.5.2.2.	Parallel-series systems for $n = 3$	90
3.6.	Numerical Illustrations	92
3.6.1.	Lognormal distributed components	92
3.6.2.	Weibull distributed components	97
3.6.3.	Discussions	101
3.7.	Practical Example	103
3.8.	Concluding Remarks	107
4	Concluding Remarks and Future Research Directions	108
4.1.	Summaries and Concluding Remarks	108
4.1.1.	Major contributions of Chapter 2	108
4.1.2.	Major contributions of Chapter 3	109
4.2.	Future Research Directions	109
4.2.1.	Extensions to other experimental schemes	110

4.2.1.1.	Step-stress ALT with Type-II censoring	110
4.2.1.2.	Cumulative exposure model	111
4.2.2.	Consider systems with a larger number of components	114
4.2.3.	Consider non-location-scale family of distributions	115

APPENDIX

A	Appendix A: Terms Involved in Second Partial Derivatives of the Log-likelihood Function	116
B	Appendix B: First and second derivatives of the PDF and CDF of standard normal distribution.....	126
C	Appendix C: First and second derivatives of the PDF and CDF of standard SEV distribution	127
D	Appendix D: Fisher Information Matrix for Series Systems	128
E	Appendix E: First and second derivatives of the PDF and CDF of standard Normal distribution	131
F	Appendix F: First and second derivatives of the PDF and CDF of standard SEV distribution	132
G	Appendix G: Detailed Formula for LogNormal Distribution with Various Types of Systems	133
	G.1. $l = 1$	133
	G.2. $l = n$	134
	G.3. 2-out-of- n	135
	G.4. 3-out-of- n for $n = 4$	140
	G.5. Series-parallel systems	143
	G.6. Parallel-series systems	146
H	Appendix H: Detailed Formula for Weibull Distribution with Various Types of Systems.....	149

H.1. $l = 1$	149
H.2. $l = n$	153
H.3. 2-out-of- n	157
H.4. 3-out-of- n for $n = 4$	161
H.5. Series-Parallel Systems	164
H.6. Parallel-Series Systems	168

LIST OF FIGURES

Figure	Page
1.1 Series and parallel n -component systems	3
4.1 Illustration of the CDF of lifetime distribution under step-stress testing with three stress levels based on cumulative exposure model	112

LIST OF TABLES

Table	Page
2.1	Optimal allocations for n -component series systems with lognormal distributed components when $N = 40$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 43
2.2	Optimal allocations for n -component series systems with Weibull distributed components when $N = 40$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 44
2.2	(Continue) 45
2.3	Optimal allocations for n -component series systems with lognormal distributed components when $N = 60$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 17(1)20$ with $n = 1, 2$ and 3 46
2.4	Optimal allocations for n -component series systems with Weibull distributed components when $N = 60$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 17(1)20$ with $n = 1, 2$ and 3 47
2.5	Optimal allocations for n -component series systems with lognormal distributed components when $N = 40$, $K = 4$, $(y_1, y_2, y_3, y_4) = (-1.0, -0.5, 0.5, 1.0)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 48
2.5	(Continue) 49
2.6	Optimal allocations for n -component series systems with Weibull distributed components when $N = 40$, $K = 4$, $(y_1, y_2, y_3, y_4) = (-1.0, -0.5, 0.5, 1.0)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 50
2.7	Simulation results for the optimal allocations for n -component series systems with lognormal distributed components when $N = 40$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3] (referring to Table 2.1) 54
2.8	Simulation results for the optimal allocations for n -component series systems with Weibull distributed components when $N = 40$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3] (referring to Table 2.2) 55

2.9	Simulation results for the optimal allocations for n -component series systems with lognormal distributed components when $N = 40$, $K = 4$, $(y_1, y_2, y_3, y_4) = (-1.0, -0.5, 0.5, 1.0)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3]	56
2.10	Simulation results for the optimal allocations for n -component series systems with Weibull distributed components when $N = 40$, $K = 4$, $(y_1, y_2, y_3, y_4) = (-1.0, -0.5, 0.5, 1.0)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3] (referring to Table 2.6)	57
2.11	Optimal allocations for n -component series systems with Weibull distributed components when $N = 180$, $K = 3$, $(y_1, y_2, y_3) = (-1.12, 0.33, 0.79)$ by fixing $R = 15, 12$ and 9 with $n = 12, 10, 5$ and 3	60
2.11	(Continue)	61
2.12	Optimal allocations for n -component series systems with lognormal distributed components when $N = 180$, $K = 3$, $(y_1, y_2, y_3) = (-1.12, 0.33, 0.79)$ by fixing $R = 15, 12$, and 9 with $n = 12, 10, 5$ and 3	63
2.12	(Continue)	64
2.13	Relative efficiency of the optimal experimental plans obtained when the assumed distribution is Weibull and the true distribution is lognormal for n -component series systems with $N = 180$, $K = 3$, $(y_1, y_2, y_3) = (-1.12, 0.33, 0.79)$ by fixing $R = 15, 12, 9$ and 42 with $n = 12, 10, 5$ and 3 under setting [M2] (referring to Table 2.11)	65
3.1	Optimal progressive censoring schemes for n -component systems with lognormal distributed components when $N = 30$, by fixing $n = 1, 2$, and 3 under setting [M1] and [M2]	94
3.2	Optimal progressive censoring schemes for n -component systems with lognormal distributed components when $N = 24$, by fixing $n = 1, 2, 3$, and 4 under setting [M1] and [M2]	95
3.3	Optimal progressive censoring schemes for n -component systems with lognormal distributed components when $N = 18$, by fixing $n = 1, 2$, and 3 , $R_{\max} = 8$ under setting [M1] and [M2]	96
3.4	Optimal progressive censoring schemes for n -component systems with Weibull distributed components when $N = 30$, by fixing $n = 1, 2$, and 3 under setting [M1] and [M2]	98

3.5	Optimal progressive censoring schemes for n -component coherent systems with Weibull distributed components when $N = 24$, by fixing $n = 1, 2, 3$, and 4 under setting [M2]	99
3.6	Optimal allocations for n -component systems with Weibull distributed components when $N = 18$, by fixing $R_{\max} = 8$ with $n = 1$ and 2 under setting [M1] and [M2]	100
3.7	Optimal progressive censoring schemes for n -component series systems with Weibull distributed components when $N = 19$, by fixing $r = 8$ with $n = 1$ and 2 under settings [M1] and [M2]	105
3.8	Optimal progressive censoring schemes for n -component series systems with lognormal distributed components when $N = 19$, by fixing $r = 8$ with $n = 1$ and 2 under settings [M1] and [M2]	106

I dedicate this dissertation to my family.

CHAPTER 1

Introduction

1.1. Problems of Interest

In industrial and system engineering, continuous improvement of product or system reliability is an important topic. A manufacturer of products will be interested in assessing the reliability of the product. To measure reliability and gain a sound knowledge about the failure-time distribution of the product or system, life-testing and reliability experiments are carried out before and while products are put on the market or while the systems are in use. In a life-testing experiment, a sample of the items of interest is usually tested under different stresses and environmental conditions, and successive failure times of the items are recorded. Life testing experiment is useful in many industrial settings and products such as batteries, light bulbs, and automobile tires, etc.

Due to the time and resource limitations, it is almost impossible or it takes an extremely long time period to observe the lifetime of the product or system in their normal operating environment. For this reason, researchers developed accelerated life tests (ALT) to shorten the time requires to obtain useful information about the product reliability within a reasonable period of time. As a summary of the early work of ALT, [Yurkowsky et al. \(1967\)](#) introduced the definition of ALT and its related methods and statistical models. The basic idea of ALT is to subjects the test sample to higher stress levels to stress the product to failure, then suitable statistical model and methods are used to estimate the reliability characteristics of the product at the normal operating condition. Planning an effective ALT experiment, especially with limited resources, to obtain reliability information is an impor-

tant topic in statistics and reliability engineering. Experimental planning for different kinds of ALTs is the main focus of this thesis.

In many situations, the life testing experiment can be done by using the individual items and/or by using a system that made up of those items. For example, in a reliability study for joints used in case furniture presented in [Kłos et al. \(2018\)](#), the experiment was performed using 10 joints connected in series. The numbers of working cycles until the failures of those 10-component series systems are recorded in order to determine the durability and safety of the joints. On the other hand, putting the test units into a system for a life testing experiment has the advantage of saving the experimental time because of the longest lifetime among n components is always greater than or equal to the lifetime of a n -component system with the same n components. Therefore, it is important to study the experimental planning based on systems as well as based on individual items.

In this chapter, we provide some preliminaries and background knowledge on system structure, censoring methodology, location-scale family of statistical distributions, experimental planning for ALTs. Then, we provide the scope of the thesis.

1.2. System Structure, Coherent System and System Signature

1.2.1. System structure and coherent system

In engineering, a system is a collection of components arranged in some fashion in order to achieve desired functions. Consider a system with n individual components and each component can have two possible states: functioning and failed. The state of the i -th component in the system can be represented by a binary variable β_i , called the *state variable*, defined as

$$\beta_i = \begin{cases} 1, & \text{if the } i\text{-th component is functioning,} \\ 0, & \text{if the } i\text{-th component is failed.} \end{cases}$$

Then, $\boldsymbol{\beta} = (\beta_1, \beta_2, \dots, \beta_n)$, is the state vector of the system and the state of the system can be described by the *structure function* defined as

$$\phi(\boldsymbol{\beta}) = \phi(\beta_1, \beta_2, \dots, \beta_n).$$

In Figure 1.1, we illustrate the series and parallel systems with structure functions

$$\phi(\boldsymbol{\beta}) = \beta_1\beta_2\cdots\beta_n = \prod_{i=1}^n \beta_i,$$

and

$$\phi(\boldsymbol{\beta}) = 1 - \prod_{i=1}^n (1 - \beta_i),$$

respectively. The state of the series system is $\phi(\boldsymbol{\beta}) = 1$ (i.e., functioning) if and only if all the n components in the system are functioning (i.e., $\beta_i = 1$ for all $i = 1, 2, \dots, n$). The state of the parallel system is $\phi(\boldsymbol{\beta}) = 1$ (i.e., functioning) if at least one of the n components in the system is functioning (i.e., $\beta_i = 1$ for at least one $i = 1, 2, \dots, n$).

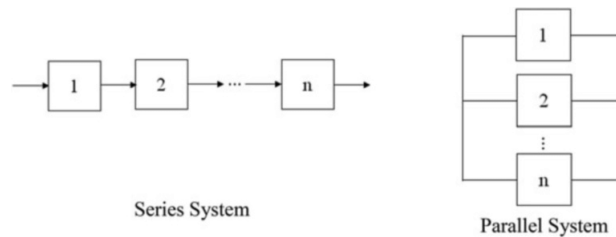


Figure 1.1: Series and parallel n -component systems

A component inside a system is said to be relevant if the status of the system depends on all the components in the system, and a system structure function is said to be monotone if repairing a failed component in the system will not make the system worse. A coherent system is a system that is relevant and its structure function is monotone. For example, a system with a spare component would not be categorized as a coherent system because the status of the system does not depend on the spare component. In addition to the structure

function $\phi(\boldsymbol{\beta})$, there are different ways to represent the structure of a system such as minimal path sets and minimal cut sets, etc. (see, for example, [Proschan and Barlow, 1965](#); [Rausand and Hoyland, 2004](#)). In this thesis, we consider a n -component coherent system consisting of n independent and identically distributed (i.i.d.) components and the system structure is represented by using system signature and minimal signature.

1.2.2. System signature

Suppose the n -component coherent system consists of n i.i.d. components with lifetimes X_1, \dots, X_n , and we denote the ordered component lifetime as $X_{1:n} < X_{2:n} < \dots < X_{n:n}$ and the lifetime of the n -component system as T . We also assume that the component lifetimes follow a common absolutely continuous distribution with cumulative distribution function (CDF) $F_X(\cdot)$, probability density function (PDF) $f_X(\cdot)$, and survival function (SF) $\bar{F}_X(\cdot) = 1 - F_X(\cdot)$. We further denote the CDF, PDF and SF of the i -th order statistics by $F_{i:n}(\cdot)$, $f_{i:n}(\cdot)$ and $\bar{F}_{i:n}(\cdot)$, respectively, and the CDF, PDF and SF of the n -component coherent system by $F_T(\cdot)$, $f_T(\cdot)$ and $\bar{F}_T(\cdot)$, respectively.

Let I be a random variable that indicates the corresponding ordered component lifetimes of the system failure, i.e., $I = i$ if the n -component system fails at the i -th ordered component failure. In this case, we have $T = X_{i:n}$. For some systems, the value of I is fixed (i.e., $\Pr(I = i) = 1$). For example, for a l -out-of- n system $\Pr(I = l) = 1$, and $l = 1$ corresponds to the series system and $l = n$ corresponds to the parallel system (see, [Figure 1.1](#)). Suppose the random variable I is not observable, then we consider the probability mass function of I as $\Pr(I = i) = \Pr(T = X_{i:n}) = s_i$, $0 \leq s_i \leq 1$, $i = 1, 2, \dots, n$, with $\sum_{i=1}^n s_i = 1$. The n -dimensional probability vector $\boldsymbol{s} = (s_1, s_2, \dots, s_n)$ is called the system signature, proposed by [Samaniego \(1985\)](#) (see also, [Samaniego, 2007](#)), which is a nonparametric representation of the system structure that does not depend on the underlying lifetime distribution of

the components. For the series and parallel systems illustrated in Figure 1.1), the system signatures are $\mathbf{s} = (1, 0, \dots, 0)$ and $\mathbf{s} = (0, \dots, 0, 1)$, respectively.

From Samaniego (1985), the PDF and SF of system lifetime T can be expressed in terms of the CDF and PDF of the component lifetime as

$$f_T(t) = \sum_{i=1}^n s_i \binom{n}{i} i f_X(t) [F_X(t)]^{i-1} [\bar{F}_X(t)]^{n-i} \quad (1.1)$$

and

$$\bar{F}_T(t) = \sum_{i=1}^n s_i \sum_{j=0}^{i-1} \binom{n}{j} [F_X(t)]^j [\bar{F}_X(t)]^{n-j}. \quad (1.2)$$

Navarro et al. (2007) considered another representation called *minimal signature* of the system by expressing the SF of the system lifetime T as a generalized mixture of the SFs of i -component series system lifetimes ($i = 1, 2, \dots, n$), i.e. $\bar{F}_{1:i}(\cdot)$:

$$\bar{F}_T(t) = \sum_{i=1}^n a_i \bar{F}_{1:i}(t) = \sum_{i=1}^n a_i [\bar{F}(t)]^i, \quad (1.3)$$

for some integers (which can be positive or non-positive) a_1, a_2, \dots, a_n that do not depend on the underlying lifetime distribution of the components with $\sum_{i=1}^n a_i = 1$. The n -dimensional vector $\mathbf{a} = (a_1, a_2, \dots, a_n)$ is called the minimal signature of the system. For example, the minimal signature of a n -component series system is $\mathbf{a} = (0, \dots, 0, 1)$. The minimal signature of a system can be obtained from its system signature and vice versa Navarro et al. (2007).

1.3. Censoring Schemes

In an ideal scenario, researchers would have a complete sample in a life-testing experiment without any censoring, which means that they observe all the failure times of the items in the experiment (Ng, 2010). Nevertheless, this is generally difficult to achieve in

practice due to the limitations of time and experimental resources. Therefore, it is important to consider statistical analysis and inference based on censored life-testing experiments. Typically, Type-I and Type-II censoring schemes, also known as time-censoring and item-censoring schemes, respectively, are widely used in life testing experiments. In the past several decades, generalizations of Type-I and Type-II censoring schemes, namely progressive Type-I and Type-II censoring schemes, have been studied extensively. For reviews and the details of progressive censoring, one can refer to the books by [Balakrishnan and Aggarwala \(2000\)](#) and [Balakrishnan and Cramer \(2014\)](#), and the review paper by [Balakrishnan \(2007\)](#).

Suppose m systems are placed on a life testing experiment, we denote the lifetimes of the systems by T_1, T_2, \dots, T_m and the corresponding order statistics by $T_{1:m} < T_{2:m} < \dots < T_{m:m}$. Assume that the lifetimes of these m systems follow a distribution with CDF $F_T(\cdot; \boldsymbol{\theta})$, PDF $f_T(\cdot; \boldsymbol{\theta})$ and SF $\bar{F}_T(\cdot; \boldsymbol{\theta})$, where $\boldsymbol{\theta}$ is an unknown parameter vector. In this subsection, we review the Type-I, Type-II, progressive Type-I and progressive Type-II censoring schemes and provide corresponding expressions of the likelihood functions.

1.3.1. Type-I censoring

Type-I censoring is also called time-censoring. In a life testing experiment starting with m systems, the researchers only observe the failures that occur before a pre-fixed time τ . All failures after time τ would be censored. The number of failures observed in a Type-I censored experiment is a random variable which follows a binomial distribution with m trials and probability of success $F_T(\tau; \boldsymbol{\theta})$, denoted as $Bin(m, F_T(\tau; \boldsymbol{\theta}))$. The likelihood function based on an observed Type-I censored sample with r observed failures $t_{1:m} < t_{2:m} < \dots < t_{r:m} \leq \tau$ is

$$L(\boldsymbol{\theta}) = \frac{n!}{(n-r)!} \left[\prod_{j=1}^r f_T(t_{j:m}; \boldsymbol{\theta}) \right] [\bar{F}_T(\tau; \boldsymbol{\theta})]^{m-r}, \quad t_{1:m} < t_{2:m} < \dots < t_{r:m}.$$

The advantage of this censoring scheme is that the experimenters can control the experimental time. However, one of the drawbacks is that an inappropriate choice of τ may lead to few or an insufficient observed failures.

1.3.2. Type-II censoring

Type-II censoring is also called item-censoring. In contrast to an experiment with Type-I censoring, the number of failed systems r ($\leq m$) instead of the termination time of the experiment is pre-specified. The life testing experiment will be terminated once the r -th failure is observed. In this case, the number of observed failures is fixed while the termination time of the experiment is a random variable $T_{r:m}$. The likelihood function based on an observed Type-II censored sample $t_{1:m} < t_{2:m} < \dots < t_{r:m}$ is

$$L(\boldsymbol{\theta}) = \frac{n!}{(n-r)!} \left[\prod_{j=1}^r f_T(t_{j:m}; \boldsymbol{\theta}) \right] [\bar{F}_T(t_{r:m}; \boldsymbol{\theta})]^{m-r}, \quad t_{1:m} < t_{2:m} < \dots < t_{r:m}.$$

The advantage of Type-II censoring is the number of observed failures is fixed. Nevertheless, a large r may take a long experimental time, which is the main disadvantage of this censoring scheme.

1.3.3. Progressive Type-II censoring

Since the conventional Type-I and Type-II censoring schemes described in Sections 1.3.1 and 1.3.2 do not have the flexibility of allowing removal of units at points other than the terminal point of the experiment, a more general censoring scheme called *progressive censoring* was proposed. Suppose we place m systems on a life test and plan to fail r of them. Then a progressive Type-II censored experiment can be described as follows. At the time of the first failure, denoted as $T_{1:r:m}$, R_1 functioning systems are randomly selected and censored or removed from the life test. Then, the life test continues with $n-1-R_1$ systems. When the sec-

ond failure occurs, denoted as $T_{2:r:m}$, R_2 functioning systems are randomly selected and censored or removed from the life test. The life test continues in this manner. At the time of the r -th system failure, denoted as $T_{r:r:m}$, all the remaining $R_r = n - r - R_1 - R_2 - \dots - R_{r-1}$ systems are withdrawn from the test. The pre-fixed values (R_1, R_2, \dots, R_r) with $\sum_{j=1}^r R_j = n - r$ is called the progressive Type-II censoring scheme. The likelihood function based on an observed progressively Type-II censored sample $t_{1:r:m} < t_{2:r:m} < \dots < t_{r:r:m}$ with censoring scheme (R_1, R_2, \dots, R_r) is

$$L(\boldsymbol{\theta}) = n(n - R_1 - 1) \dots (n - R_1 - R_2 - \dots - R_{r-1} - r + 1) \\ \times \prod_{j=1}^r f_T(t_{j:r:m}; \boldsymbol{\theta}) [\bar{F}_T(t_{j:r:m}; \boldsymbol{\theta})]^{R_j}, \quad t_{1:r:m} < t_{2:r:m} < \dots < t_{r:r:m}.$$

The progressive Type-II censoring with censoring scheme $(R_1, R_2, \dots, R_r) = (0, 0, \dots, 0, n - r)$ is equivalent to the conventional Type-II censoring scheme described in Section 1.3.2.

1.3.4. Progressive Type-I censoring

The progressive Type-I censoring scheme is a union of Type-I censoring and progressive censoring. A progressive Type-I censored sample, in which the censoring occurs at K different pre-fixed time points $\tau_1 < \tau_2 < \dots < \tau_K$, is collected as follows. Let m_j be the number of systems failed in the time interval $(\tau_{j-1}, \tau_j]$, $t_{j,l}$ be the l -th ordered failure time of those m_j systems for $l = 1, 2, \dots, m_j$, c_j be the number of units randomly removed at time τ_j , and M_j be the number of functioning units on the test at the beginning of the j -th time interval $(\tau_{j-1}, \tau_j]$, i.e.,

$$M_j = M - \sum_{j=1}^{k-1} m_j - \sum_{j=1}^{k-1} c_j.$$

Suppose $m = M_1$ systems are placed on a life test at time $\tau_0 = 0$, the failure times of the systems are observed sequentially. At time τ_1 , c_1 functioning systems are randomly selected

and removed from the experiment. The experiment is continued on $M_2 = m - m_1 - c_1$ remaining units until τ_2 , at which point c_2 functioning units are randomly removed from the experiment, and so on. The experiment is terminated at time τ_K and the remaining functioning systems, $c_k = M_k - m_k$, are censored, or at the time that all the systems in the life testing experiment are failed/censored. Note that m_j is a random variable following $Bin(M_j, F_T(\tau_j) - F_T(\tau_{j-1}))$ and hence, the number of functioning systems at time τ_j can be smaller than the pre-fixed value c_j . Therefore, the life testing experiment can be terminated before reaching the planned experimental time c_K , and we define the actual number of systems being removed at time τ_j as $c_j^* = \min(c_j, M_j - m_j)$, $j = 1, 2, \dots, K - 1$.

The observed progressive Type-I censored data includes the actual number of systems being removed at time $\tau_1 < \tau_2 < \dots < \tau_K$, i.e., $(c_1^*, c_2^*, \dots, c_K^*)$, the number of system failures in failure times $(\tau_{j-1}, \tau_j]$, $j = 1, 2, \dots, K$, i.e., (m_1, m_2, \dots, m_K) , and the actual failure times of the systems $(t_{j,1}, t_{j,2}, \dots, t_{j,m_j})$, $j = 1, 2, \dots, K$. Based on the observed progressive Type-I censored data, the likelihood function can be expressed as

$$L(\boldsymbol{\theta}) = \mathcal{C} \prod_{j=1}^K \left[\prod_{l=1}^{m_j} f_T(t_{j,l}; \boldsymbol{\theta}) \right] [\bar{F}_T(\tau_j; \boldsymbol{\theta})]^{c_j^*},$$

where \mathcal{C} is the normalizing constant. When there is no censoring before time τ_K , i.e., $c_1 = c_2 = \dots = c_{K-1} = 0$, the censoring scheme reduces to the conventional Type-I censoring scheme described in Section 1.3.1.

1.4. Location-scale Family of Distributions and Log-location-scale Family of Distributions

In this thesis, we consider a general model that the lifetimes of the components are i.i.d. with a distribution that belongs to the log-location-scale family of distributions, then the log-transformed component lifetimes, denoted as $U = \ln X$, follow a distribution belong to the location-scale family of distributions. A distribution in the location-scale family of

distributions has PDF, CDF and SF, respectively,

$$\begin{aligned}
f_U(u; \mu, \sigma) &= \frac{1}{\sigma} f^* \left(\frac{u - \mu}{\sigma} \right) = \frac{1}{\sigma} f^*(z), \\
F_U(u; \mu, \sigma) &= F^* \left(\frac{u - \mu}{\sigma} \right) = F^*(z), \\
\bar{F}_U(u; \mu, \sigma) &= 1 - F^* \left(\frac{u - \mu}{\sigma} \right) = 1 - F^*(z),
\end{aligned} \tag{1.4}$$

where $-\infty < \mu < \infty$ is the location parameter and $\sigma > 0$ is the scale parameter, $z = (u - \mu)/\sigma$, $f^*(\cdot)$ and $F^*(\cdot)$ are the PDF and CDF of the standardized distribution (i.e., $\mu = 0$ and $\sigma = 1$) of the corresponding distribution in the location-scale family. The location-scale family contains many commonly used distributions including the normal, smallest extreme-value, largest extreme value, and logistic distributions. These distributions are often used for modeling log-transformed lifetime data. For example, if the component lifetime X follows a lognormal distribution, then $U = \ln X$ follows the normal distribution, which belongs to the location-scale family. If the component lifetime X follows a Weibull distribution, then $U = \ln X$ follows the smallest extreme value (SEV) distribution, which belongs to the location-scale family.

Let $V = \ln T$ be the log-transformed n -component system lifetime with i.i.d. component X_1, X_2, \dots, X_n and the corresponding log-transformed component lifetime $U_i = \ln X_i$, $i = 1, 2, \dots, n$. We further denote the PDF, CDF and SF of the log-transformed component lifetime as $f_U(\cdot)$, $F_U(\cdot)$ and $\bar{F}_U(\cdot)$, respectively, and the PDF, CDF and SF of the log-transformed system lifetime as $f_V(\cdot)$, $F_V(\cdot)$ and $\bar{F}_V(\cdot)$, respectively. Based on the system signature $\mathbf{s} = (s_1, s_2, \dots, s_n)$ described in Section 1.2.2, the SF of the log-transformed system lifetime can be expressed in terms of the distribution of the log-transformed component as

$$\bar{F}_V(v) = 1 - F_V(v) = \sum_{i=1}^n s_i \sum_{j=0}^{i-1} \binom{n}{j} [F_U(v)]^j [\bar{F}_U(v)]^{n-j}. \tag{1.5}$$

In terms of the minimal signature \mathbf{a} instead, the above equation can be rewritten as

$$\bar{F}_V(v) = \sum_{i=1}^n a_i \bar{F}_{1:i}^U(v) = \sum_{i=1}^n a_i [\bar{F}_U(v)]^i, \quad (1.6)$$

where $\bar{F}_{1:i}^U(\cdot)$ is the SF of the first order statistic $U_{1:i}$ arising out of i log-transformed component lifetimes U_1, \dots, U_i .

1.5. Statistical Inference Based on System Lifetime Data

In life testing experiments, the test units can be expensive since they are usually products under development. Moreover, the time allowed for the experiment is always a constraint. Observing the lifetimes of systems formed by different numbers of components makes it possible for researchers to save time, save surviving items for future use and improve the accuracy of parameter estimation.

Researchers have discussed and studied using systems in life testing procedures. For example, for progressively censored life testing experiments, [Wu and Kuş \(2009\)](#), [Hermanns and Cramer \(2017\)](#) and [Hermanns and Cramer \(2018\)](#) used the series systems, the parallel systems, and the l -out-of- n systems, respectively, for the life testing experiments. These authors also developed the statistical inference under those experiments with different kinds of systems.

When n -component systems are used in a life testing experiment, there have been several studies on the estimation of parameters of the lifetime distributions of components based on system lifetime data. With known signatures and Type-II censored data, [Balakrishnan et al. \(2011b\)](#) discussed linear inference for the lifetime distributions of components and derived the best linear unbiased estimators (BLUE) for the parameters. [Fan and Wang \(2011\)](#) established a cumulative exposure model for series system with masking and Type-I censoring, and gave inferences on functions of the unknown parameters of the assumed Weibull distribution.

[Aslett et al. \(2015\)](#) studied Bayesian inference for systems and networks based on signature. [Zhang et al. \(2015\)](#) studied the statistical inference and estimation of parameters using the maximum likelihood estimation method and regression-based method. [Yang et al. \(2016\)](#) proposed the stochastic expectation-maximization (SEM) algorithm to estimate the model parameters with complete and censored system lifetimes. Similarly, with unknown system structure, [Yang et al. \(2019\)](#) adopted the expectation-maximization (EM) algorithm to do inference and gave illustration based on a two-parameter Weibull distribution. [Hermanns et al. \(2020\)](#) developed EM algorithms for ordered and censored system lifetime data under a proportional hazard rate model. [Fallah et al. \(2020\)](#) developed the tools for statistical inference of component lifetime distribution based on system lifetime data under a proportional reversed hazard model. [Tavangar and Asadi \(2020\)](#) considered different estimation methods for the reliability of components of the system when progressively censored system failure times are observed.

In addition to parametric inference, nonparametric statistical inference has been developed in the literature. For example, [Bhattacharya and Samaniego \(2010\)](#) considered the nonparametric maximum likelihood estimate of the CDF of component lifetimes based on the observed system failure times and characterized its asymptotic behavior. [Balakrishnan et al. \(2011a\)](#) developed exact nonparametric inference for component lifetime distribution in the form of confidence intervals for population quantiles and tolerance limits, and [Coolen and Al-nefaiee \(2012\)](#) discussed nonparametric predictive inference for system lifetimes with exchangeable components. [Hall et al. \(2015\)](#) and [Jin et al. \(2017\)](#) studied the nonparametric estimation of a common component reliability function using independent samples from coherent systems when the system design is known and unknown, respectively.

1.6. Experimental Planning for Accelerated Life Tests

In experimental planning for ALT, experimental designs are optimized with respect to some statistical criterion. The optimality of an experimental design depends on the sta-

tistical model used to analyze the experimental data and it is assessed with respect to a statistical criterion. In this section, we describe two commonly used optimality criteria, D -optimality and A -optimality, and some other optimality criteria will be discussed in the subsequent chapters. Moreover, we review the literature on optimal experimental planning in two different ALTs namely constant-stress ALT (CSALT) and step-stress ALT (SSALT).

1.6.1. Optimality criteria

Suppose we are interested in the estimation of the model parameters and control the time used in the life testing experiment, to discuss the optimal experimental planning, we consider the following optimality criteria:

- D -optimality: Maximization of the determinant of the Fisher information matrix, i.e., maximizing the differential Shannon information contained in the MLEs and minimizing the volume of the Wald-type joint confidence region for the model parameters;
- A -optimality: Minimization of the trace of the variance-covariance matrix of the MLEs, i.e., minimizing the sum of the asymptotic variances of the MLEs.

In addition to these commonly used optimality criteria, other optimality criteria can be considered. For example, the total time of the experiment and the total time on test, which focus on controlling the total time of the experiment and the average time that each experimental unit spent in the experiment, can be considered in optimal planning of life testing experiments.

1.6.2. Constant-stress ALTs

One of the commonly used ALTs is the constant-stress accelerated life test (CSALT). As the name implies, each test unit is tested under a pre-fixed stress level throughout the life-

testing experiment. Usually, multiple stress levels are considered in a CSALT in which the products are tested at multiple constant stress levels. Based on the lifetime data obtained from a multi-level CSALT, a statistical model (e.g., a lifetime regression model) that relates the life distribution and the stress factor is used to predict the reliability characteristics of the product at normal operating condition.

There have been numerous studies on optimal experimental planning with the CSALT. One of the optimal experimental planning problems is the optimal allocation of experimental units to the pre-specified stress levels. [Ng et al. \(2007\)](#) formally established this result based on complete sample by providing a mathematical proof. Taking censoring into consideration, [Ka et al. \(2011\)](#), [Chan et al. \(2016\)](#) and [Chan et al. \(2020\)](#) discussed the optimal allocation problems with Type-I and Type-II censored data. In addition, considering that the conventional Type-I and Type-II censoring schemes restrict our ability to observe extreme failure times, [Ng et al. \(2017\)](#) proposed an improved experimental scheme under progressive Type-II extremal censoring. There are also other research works on the optimal design problem based on different settings, different censoring schemes, and/or different lifetime distribution. For example, under progressive Type-II censoring scheme, [Huang and Wu \(2017\)](#) studied the optimal sample size allocation for accelerated life test with competing risks. [Monroe and Pan \(2008\)](#) explored different criteria for effectively planning an accelerated life test in electronic industry. For example, [Yue and Shi \(2013\)](#) discussed the optimal design of multi-level stress experiment under progressive hybrid interval censoring. [Pan et al. \(2015\)](#) proposed an approach to designing accelerated life test plans that are good at selecting the best acceleration model among rival models. [El-Raheem \(2019\)](#) discussed the optimal design of multiple constant-stress testing for generalized half-normal distribution.

1.6.3. Step-stress ALTs

Another widely used ALT is the step-stress accelerated life testing (SSALT) that allows for different stresses at various intermediate stages of the experiment. In a multi-level SSALT with K stress levels, m identical n -component coherent systems are placed on a life test at the initial stress level y_1 . At pre-fixed time points $\tau_1 < \tau_2 < \dots < \tau_{K-1}$, the stress levels are increased to $y_2 < y_3 < \dots < y_K$, respectively. A simple SSALT is a SSALT that has two stress level, y_1 and y_2 with one stress change point $\tau = \tau_1$. A SSALT can be terminated at a pre-fixed time point (i.e., Type-I censoring), or at the time of observing the r th failure (i.e., Type-II censoring).

To analyze data from a SSALT, a model that relates the lifetime distribution under the step-stress mechanism to the distribution under constant stresses is required. Cumulative exposure model (CE-M), originally proposed by [Sediakin \(1966\)](#), assumes that the residual life of the experimental units depends only on the cumulative exposure of the units without any memory of how the exposure accumulated. For statistical analysis of SSALT data under CE-M, [Nelson \(1980\)](#) described the statistical model and derived the maximum likelihood estimates (MLEs) under the CE-M for Weibull and inverse power law distributions. [Balakrishnan et al. \(2007\)](#) studied the point and interval estimation of a simple step-stress model with Type-II censoring when the experimental units are assumed to follow exponential distribution. [Balakrishnan and Xie \(2007a,0\)](#); [Balakrishnan and Han \(2008\)](#); [Balakrishnan \(2008\)](#) studied the exact inference for step-stress model under different kind of censoring for exponentially distributed experimental units. [Alkhalafan \(2012\)](#) and [Alam \(2017\)](#) studied the statistical inference for multiple step-stress models for gamma and generalized Birnbaum-Saunders distributions, respectively.

For SSALT, the optimal experimental planning problem can be formulated as choosing the optimal time points $\tau_1 < \tau_2 < \dots < \tau_{K-1}$ for the changing of stresses. There has also been a great development on the optimal experimental planning problem in the past decades. Most

of these research articles focus on exponentially distributed experimental units. For example, [Miller and Nelson \(1983\)](#) explored the optimal plans under the A -optimality criterion for a simple SSALT. [Bai et al. \(1989\)](#) extended the results of [Miller and Nelson](#) by involving a pre-fixed censoring time. [Gouno et al. \(2004\)](#) investigated the optimal changing time points for a multi-level SSALT with a large progressively Type-I censored sample. To reduce the complexity of the problem, [Gouno et al. \(2004\)](#) adopted a simplified model with equal duration for each testing stage, i.e., $\tau_k = k\tau$ for $k = 1, 2, \dots, K - 1$. [Balakrishnan and Han \(2009\)](#) modified the model studied in [Gouno et al. \(2004\)](#) by determining the censoring rate based on the remaining items at every stress change instead of using a global censoring rate. By relaxing the setting of equal duration for each testing stage, [Guan and Tang \(2012\)](#) obtained the optimum planning for multivariate exponential distribution under Type-I censoring scheme. [Lin et al. \(2013\)](#) and [Lin et al. \(2020\)](#) investigated the optimal choice of the time-changing points for a multi-level SSALT with unequal stress steps for log-location-scale distributions under Type-I and Type-I hybrid censoring schemes, respectively.

In addition to the exponential distribution, other more flexible distributions have also been discussed as the lifetime distribution under different settings. [Alhadeed and Yang \(2005\)](#) obtained the optimal planning for a simple SSALT with lifetimes follow lognormal distribution. Taking the exponential and the Weibull as special cases, [Bobotas and Kateri \(2019\)](#) tackled the optimality problem under interval censoring. [Hakamipour \(2018\)](#) considered a simple bivariate SSALT with log-normally distributed lifetimes. They discussed how to find the two optimal changing points under the D -optimality and A -optimality with using the particle swarm optimization (PSO) algorithm.

In addition to the CE-M, [Khamis and Higgins \(1998\)](#) proposed another model called Khamis-Higgins model (KH-M) for SSALT to relate the lifetime distribution of the experimental units at one stress level to the life distribution of the experimental units at the next stress level. Compared with the CE-M, [Khamis and Higgins](#) claimed that the mathematical

form of KH-M made it easier to derive the MLE, for which they used the Weibull distribution as an illustration. Under the KH-M, [Li and Fard \(2007\)](#) explored the optimal changing time points for a bivariate step-stress life testing using the maximum likelihood estimation and Fisher information matrix methods. A sensitivity analysis was included in their research to study the effect of using different parameter on the optimal plans.

For a comprehensive review of ALT, one can refer to the books by [Nelson \(1990\)](#) and [Bagdonavicius and Nikulin \(2002\)](#), and the papers by [Nelson \(2005\)](#) and [Nelson \(2015\)](#). For comparisons between the CSALT and SSALT, [Han and Ng \(2013\)](#) and [Han and Ng \(2014\)](#) compared the optimal multi-level CSALT and SSALT with complete and Type-I censored samples under the exponential distribution. They concluded that the SSALT seemed to be more efficient than the constant-stress one under the optimal designs. At the meanwhile, however, the SSALT might require longer termination time than the latter did in the case with more than two stress levels.

1.7. Scope of the Thesis

In this thesis, we develop algorithms to obtain the optimal experimental planning for reliability experiments using coherent systems. In the design of experiments in reliability engineering, minimizing the cost of conducting the experiment and maximizing the information collected from the experiment are usually the major objectives. In practice, using well-designed experiments with censoring is one of the approaches to achieve these objectives. When the experimental units (components) can be put into a system and the experiment is done based on those systems instead of the individual experimental units, some interesting and fundamental research questions are: (i) how to put the experimental units into a system to maximize the information collected from the experiment and minimize the cost of the experiment? (ii) what are the advantages and disadvantages to putting the components into a system for reliability experiments? The purpose of this thesis is to address these important research questions.

Although the idea of using systems instead of components in a life testing experiment has been discussed in the literature, to the best of our knowledge, a thorough study of the experimental planning and evaluation of the efficiency of using systems in a multi-level stress ALT experiment has not been done. In this thesis, we aim to fill this gap by providing a thorough study of the experimental planning based on systems formed by test units. The organization of the thesis is as follows.

In Chapter 2, we discuss the optimal experimental planning problem for multi-level constant-stress testing with Type-II censoring when the test units can be put into coherent systems for the experiment. Based on the notion of system signatures of coherent systems and assuming the lifetime of the test units follows a distribution in a general log-location-scale family of distributions, the maximum likelihood estimators of the model parameters and the Fisher information matrix are derived. For the optimal experimental planning, in addition to some commonly used optimality criteria, such as D -optimality, A -optimality and V -optimality, we also consider the total time of the experiment and the total time on test. Then, motivated by a real-life application in reliability study of furniture joints, we focus the study on using series systems in multi-level stress experiments. The methodology is illustrated by considering lognormal and Weibull distributed test units. Numerical and Monte Carlo simulation studies are used to demonstrate the advantages and disadvantages of using series systems in life-testing experiments. A numerical example based on furniture joints with sensitivity analysis is used to elucidate how the proposed methods can be used in planning a life testing experiment.

In Chapter 3, we investigate the optimal planning of a progressive Type-II censored experiment based on coherent systems formed by components that follow a log-location-scale distribution. We aim to determine the optimal censoring plan (R_1, \dots, R_r) for a given number of items under different optimality criteria. Specifically, we analyze the expected Fisher information and the asymptotic variance-covariance matrix for the maximum likelihood esti-

mates (MLEs) obtained from a progressively Type-II censored sample with coherent systems. The methodology is illustrated by considering lognormal and Weibull distributed components with different coherent systems. The goal is to gain insights into the effectiveness of different coherent systems and determine which system type yields the most favorable results based on the chosen optimality criteria.

In Chapter 4, we summarize major results in Chapter 2 and Chapter 3 and provide three potential directions for future research. One possible direction is to explore the optimal experimental planning for multi-level step-stress testing with Type-II censoring when systems can be used for the life testing experiment. The other two involve a larger number of components and non location-scale family distributions.

This thesis focuses on the optimal experimental planning problem based on coherent systems. The statistical methods and techniques developed in this thesis will provide engineers and statisticians some efficient ways to perform lab testing that can save both time and cost of the experiment as well as obtain high efficiency of statistical inference, which is important for decision making in the engineering process.

CHAPTER 2

Optimal Experimental Planning for Constant-Stress Accelerated Life-Testing Experiments based on Coherent Systems

2.1. Introduction

For multi-level stress experiments with Type-II censoring, [Elperin and Gertsbakh \(1987\)](#) discussed the maximum likelihood estimation in a Weibull regression model with Type-I censoring and [Paul and Thiagarajah \(1996\)](#) derived the asymptotic variances and covariances of the maximum likelihood estimates of the model parameters for an extreme value regression model with Type-I censoring. [Chan et al. \(2008\)](#) also studied the point and interval estimation of the model parameters when the extreme-value regression model is used for the data analysis. The optimal experimental planning for multi-level stress experiments has long been studied, as we review in Chapter 1.

This chapter is organized as follows. In Section 2.2, we present the model for multi-level constant-stress experiments with coherent systems and different optimality criteria. Specifically, we review the notation of the system signature and the location-scale family of distributions. Maximum likelihood estimators (MLEs) of the model parameters and the corresponding Fisher information matrix are derived. Different optimality criteria, including some commonly used optimality criteria including the D -optimality, the A -optimality and the V -optimality, and different settings for optimal experimental planning are discussed. Then, in Section 2.3, a special case which series systems are used in the multi-level constant-stress experiments is considered. The computational formulas for lognormal and Weibull distributed components are used to illustrate the methodology developed in Section 2.4. Numerical illustrations with two- and four-stress levels are used to demonstrate the advan-

tages and disadvantages of using series systems in multi-level constant-stress experiments. In Section 2.5, a Monte Carlo simulation study is used to evaluate the validity of the numerical results based on the asymptotic properties of MLEs. An illustrative example based on furniture joints testing is used in Section 2.6 to show how the proposed method can be used to effectively plan an experiment based on series system. Sensitivity analysis for the furniture joints testing example is also presented in Section 2.6. Finally, some concluding remarks and discussions about future research directions are provided in Section 2.7.

2.2. Models and Optimality Criteria

In this chapter, our analysis focuses on the n -component coherent systems under the general model as we describe in Section 1.2.2. Also, we assume that the underlying distribution of the component lifetimes comes from the location-scale family as we described in Section 1.4.

2.2.1. Multi-level constant-stress experiment with Type-II censoring

Consider a multi-level constant stress life testing experiment based on systems with K stress levels denoted as $y_1 < \dots < y_K$, and m_k n_k -component systems with system signature $\mathbf{s}_k = (s_{k1}, s_{k2}, \dots, s_{kn_k})$ are placed on the life test at the k -th stress level. In other words, we consider that the systems placed at the k -th stress level are assumed to have the same number of components and the same system structure, but systems placed at different stress levels can have different numbers of components and/or different system structures. To obtain a Type-II censored sample at the k -th stress level, we observed the first r_k ($r_k \leq m_k$) system failures out of the m_k systems at the k -th stress level and denote the ordered system lifetimes as $T_{1:m_k} < T_{2:m_k} < \dots < T_{r_k:m_k}$ and the observed values as $t_{1:m_k} < t_{2:m_k} < \dots < t_{r_k:m_k}$. We assume that the component that causes the system failure for each failed system is not observable. Hence, $n_k \times m_k$ components are used in the life test at the k -th stress level,

the total number of components used in the life test is $N = \sum_{k=1}^K n_k m_k$ and the total number of observed system failures is $\sum_{k=1}^K r_k$. For the special case when $n_k = 1$, the life testing experiment is done at the component level in which m_k components are placed on the life test at the k -th stress level and the life testing experiment at the k -th stress level is terminated as soon as the r_k -th component failure is observed.

Based on the multi-level constant-stress life testing experiment with Type-II censoring, the observed system-level lifetime data are $(t_{1:m_k} < t_{2:m_k} < \dots < t_{r_k:m_k})$, $k = 1, 2, \dots, K$. We denote the PDF, CDF and SF of the log-lifetimes of components in the systems under the k -th stress level as $f_{U_k}(\cdot, \boldsymbol{\theta}_k)$, $F_{U_k}(\cdot, \boldsymbol{\theta}_k)$ and $\bar{F}_{U_k}(\cdot, \boldsymbol{\theta}_k)$, respectively, where $\boldsymbol{\theta}_k$ is the parameter vector depending on the stress level y_k , and the PDF, CDF and SF of the log-transformed system lifetimes under the k -th stress level as $f_{V_k}(\cdot, \boldsymbol{\theta}_k)$, $F_{V_k}(\cdot, \boldsymbol{\theta}_k)$ and $\bar{F}_{V_k}(\cdot, \boldsymbol{\theta}_k)$, respectively. Assume that the log-lifetimes of components in the systems under the k -th stress level follow a location-scale family of distribution described in Eq. (1.4) with location parameter μ_k and scale parameter σ , and a linear relationship between the location parameter μ_k and the stress level y_k , i.e.,

$$\mu_k = \beta_0 + \beta_1 y_k, k = 1, \dots, K, \quad (2.1)$$

then the model parameter vector can be expressed as $\boldsymbol{\theta} = (\beta_0, \beta_1, \sigma)$ and $\boldsymbol{\theta}_k = (\mu_k, \sigma) = (\beta_0 + \beta_1 y_k, \sigma)$, $k = 1, 2, \dots, K$. Then, the CDF and the PDF of the log-transformed system

lifetime at the k -th stress level can be written as

$$\begin{aligned}
F_{V_k}(v; \boldsymbol{\theta}) &= 1 - \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} [F_{U_k}(v; \boldsymbol{\theta}_k)]^j [\bar{F}_{U_k}(v; \boldsymbol{\theta}_k)]^{n_k-j} \\
&= 1 - \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} \left[F^* \left(\frac{v - \mu_k}{\sigma} \right) \right]^j \left[\bar{F}^* \left(\frac{v - \mu_k}{\sigma} \right) \right]^{n_k-j} \\
&= 1 - \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} \left[F^* \left(\frac{v - (\beta_0 + \beta_1 y_k)}{\sigma} \right) \right]^j \left[\bar{F}^* \left(\frac{v - (\beta_0 + \beta_1 y_k)}{\sigma} \right) \right]^{n_k-j} \\
&= 1 - \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} [F^*(z_k)]^j [\bar{F}^*(z_k)]^{n_k-j}, k = 1, \dots, K, \tag{2.2}
\end{aligned}$$

and

$$\begin{aligned}
f_{V_k}(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^* \left(\frac{v - \mu_k}{\sigma} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[F^* \left(\frac{v - \mu_k}{\sigma} \right) \right]^{i-1} \left[\bar{F}^* \left(\frac{v - \mu_k}{\sigma} \right) \right]^{n_k-i} \\
&= \frac{1}{\sigma} f^*(z_k) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_k)]^{i-1} [\bar{F}^*(z_k)]^{n_k-i}, k = 1, \dots, K, \tag{2.3}
\end{aligned}$$

where

$$z_k = \frac{v - \mu_k}{\sigma} = \frac{v - (\beta_0 + \beta_1 y_k)}{\sigma}.$$

Note that the distribution of the system lifetime at the k -th stress level depends on the system signature of the systems used in the k -th stress level (\mathbf{s}_k) and the number of components in each system n_k . Here, for simplicity, we suppress the notations \mathbf{s}_k and n_k in the CDF and PDF of the lifetime distributions.

2.2.2. Parameter estimation

2.2.2.1. Maximum likelihood estimation

Based on the log-transformed observed system-level lifetime data $\{(v_{1:m_k} < v_{2:m_k} < \dots < v_{r_k:m_k}), k = 1, 2, \dots, K\}$ obtained from a multi-level constant-stress life testing experiment with Type-II censoring and assuming the log-lifetime of the components follow a location-scale distribution, the likelihood function can be expressed as

$$L(\boldsymbol{\theta}) = L(\beta_0, \beta_1, \sigma) = \prod_{k=1}^K \frac{m_k!}{(m_k - r_k)!} \left\{ \prod_{\ell=1}^{r_k} f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta}) \right\} [\bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})]^{m_k - r_k} \quad (2.4)$$

and the log-likelihood function is

$$l(\boldsymbol{\theta}) = \ln L(\beta_0, \beta_1, \sigma) = \text{constant} + \sum_{k=1}^K \sum_{\ell=1}^{r_k} \ln f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta}) + \sum_{k=1}^K (m_k - r_k) \ln \bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta}). \quad (2.5)$$

Taking the first partial derivatives of the log-likelihood function, we can obtain the likelihood equations

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \beta_0} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \frac{1}{f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})} \frac{\partial f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \beta_0} \\ &+ \sum_{k=1}^K \frac{m_k - r_k}{\bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})} \frac{\partial \bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})}{\partial \beta_0} = 0, \end{aligned} \quad (2.6)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \beta_1} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \frac{1}{f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})} \frac{\partial f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \beta_1} \\ &+ \sum_{k=1}^K \frac{m_k - r_k}{\bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})} \frac{\partial \bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})}{\partial \beta_1} = 0, \end{aligned} \quad (2.7)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \frac{1}{f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})} \frac{\partial f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \sigma} \\ &+ \sum_{k=1}^K \frac{m_k - r_k}{\bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})} \frac{\partial \bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta})}{\partial \sigma} = 0. \end{aligned} \quad (2.8)$$

The MLEs of the parameters β_0 , β_1 and σ , denoted as $\hat{\beta}_0$, $\hat{\beta}_1$ and $\hat{\sigma}$, can be obtained by solving Eqs. (2.6)–(2.8) simultaneously. Using the relations in Eqs. (2.2) and (2.3), we can express the first derivatives of the SF of the system lifetime with respect to the parameters in terms of the component lifetime distributions as

$$\begin{aligned}
\frac{\partial \bar{F}_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \beta_0} &= \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} \left(f^*(z_{\ell:m_k}) \frac{\partial z_{\ell:m_k}}{\partial \beta_0} \right) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \\
&\quad \left. + [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \left(-f^*(z_{\ell:m_k}) \frac{\partial z_{\ell:m_k}}{\partial \beta_0} \right) \right] \\
&= \left[-\frac{1}{\sigma} f^*(z_{\ell:m_k}) \right] \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \\
&\quad \left. - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right], \tag{2.9}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial \bar{F}_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \beta_1} &= \left[-\frac{y_k}{\sigma} f^*(z_{\ell:m_k}) \right] \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \\
&\quad \left. - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right], \tag{2.10}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial \bar{F}_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \sigma} &= \left[-\frac{z_{\ell:m_k}}{\sigma} f^*(z_{\ell:m_k}) \right] \sum_{i=1}^{n_k} s_{ki} \sum_{j=0}^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \\
&\quad \left. - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right]. \tag{2.11}
\end{aligned}$$

Similarly, using the relations in Eqs. (2.2) and (2.3), we can express the first partial derivatives of the PDF of the system lifetime with respect to the parameters in terms of the component lifetime distributions as

$$\begin{aligned}
\frac{\partial f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \beta_0} &= \frac{1}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \\
&\quad - \frac{1}{\sigma^2} (f^*(z_{\ell:m_k}))^2 \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
&\quad \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k - i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right], \tag{2.12}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \beta_1} &= \frac{1}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \\
&\quad - \frac{y_k}{\sigma^2} (f^*(z_{\ell:m_k}))^2 \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
&\quad \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k - i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right], \tag{2.13}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \sigma} &= \left[-\frac{1}{\sigma^2} f^*(z_{\ell:m_k}) + \frac{1}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} \right] \\
&\quad \times \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \\
&\quad - \frac{z_{\ell:m_k}}{\sigma^2} (f^*(z_{\ell:m_k}))^2 \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
&\quad \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k - i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right]. \tag{2.14}
\end{aligned}$$

2.2.2.2. Fisher information and asymptotic variance-covariance matrices

To measure the amount of information in the observed lifetime data and to qualify the uncertainty in the MLEs, we consider the expected Fisher information matrix of $\boldsymbol{\theta} = (\beta_0, \beta_1, \sigma)$, denoted as $\mathbf{I}(\beta_0, \beta_1, \sigma)$, which is defined as

$$\mathbf{I}(\beta_0, \beta_1, \sigma) = - \begin{bmatrix} E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0^2} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} \right) \\ E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1^2} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} \right) \\ E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} \right) \end{bmatrix}. \tag{2.15}$$

The second partial derivatives of the log-likelihood function involved in the Fisher information matrix can be expressed in terms of the PDF and CDF of the component lifetimes as described in Section 2.2.2.1 and these expressions are presented in Appendix A. The asymp-

otic variance-covariance matrix of the MLEs can be obtained as the inverse of the Fisher information matrix as

$$\mathbf{V}(\beta_0, \beta_1, \sigma) = \mathbf{I}^{-1}(\beta_0, \beta_1, \sigma) = \begin{bmatrix} \text{Var}(\hat{\beta}_0) & \text{Cov}(\hat{\beta}_0, \hat{\beta}_1) & \text{Cov}(\hat{\beta}_0, \hat{\sigma}) \\ & \text{Var}(\hat{\beta}_1) & \text{Cov}(\hat{\beta}_1, \hat{\sigma}) \\ & & \text{Var}(\hat{\sigma}) \end{bmatrix}. \quad (2.16)$$

2.2.3. Optimality criteria

Suppose we are interested in the estimation of the model parameters and controlling the time used in the life testing experiment. To discuss the optimal experimental planning, we consider the following optimality criteria:

[C1] *D*-optimality: Maximization of the determinant of the Fisher information matrix, \mathbf{I} , i.e., maximizing the differential Shannon information contained in the MLEs and minimizing the volume of the Wald-type joint confidence region for the model parameter $(\beta_0, \beta_1, \sigma)$;

[C2] *A*-optimality: Minimization of the trace of the variance-covariance matrix of the MLEs, $V(\beta_0, \beta_1, \sigma)$, i.e., minimizing the sum of the asymptotic variances of the MLEs:

$$\text{Var}(\hat{\beta}_0) + \text{Var}(\hat{\beta}_1) + \text{Var}(\hat{\sigma});$$

[C3] *V*-optimality: Minimization of the variance of the estimator of β_1 , $\text{Var}(\hat{\beta}_1)$. With the linear relationship between the mean lifetime and the stress level, it is important in estimating the slope parameter β_1 accurately. Therefore, this criterion minimizes the variance of the estimate of the slope parameter;

[C4] Minimization of the expected total time of the experiment, denoted as TTE , which is defined as

$$E(TTE) = E \left\{ \max_k [\exp(V_{r_k:m_k})] \right\} = \max_k \{E[\exp(V_{r_k:m_k})]\}.$$

Using the relationship between $Z_{\ell:m_k}$ and $V_{\ell:m_k}$:

$$Z_{\ell:m_k} = \frac{V_{\ell:m_k} - \mu_k}{\sigma} = \frac{V_{\ell:m_k} - (\beta_0 + \beta_1 y_k)}{\sigma}.$$

The TTE can be expressed in terms of $Z_{\ell:m_k}$, which is the ordered standardized log-transformed failure time, as

$$E(TTE) = \max_k (\exp(\beta_0 + \beta_1 y_k) E[\exp(\sigma Z_{r_k:m_k})]). \quad (2.17)$$

Based on the multi-level constant-stress experiment with Type-II censoring described in Section 2.2.1, the experiment terminates at the last observed failure. This criterion aims to minimize the termination time of the experiment.

[C5] Minimization of the expected total time for all the components spending on the experiment, denoted as TTT , which is defined as

$$\begin{aligned} E(TTT) &= nE \left\{ \sum_{k=1}^K \left[\sum_{\ell=1}^{r_k} \exp(V_{\ell:m_k}) + (m_k - r_k) \exp(V_{r_k:m_k}) \right] \right\} \\ &= n \sum_{k=1}^K \left\{ \sum_{\ell=1}^{r_k} E[\exp(V_{\ell:m_k})] + (m_k - r_k) E[\exp(V_{r_k:m_k})] \right\} \\ &= n \sum_{k=1}^K \exp(\beta_0 + \beta_1 y_k) \left\{ \sum_{\ell=1}^{r_k} E[\exp(\sigma Z_{\ell:m_k})] + (m_k - r_k) E[\exp(\sigma Z_{r_k:m_k})] \right\}. \end{aligned}$$

Since the components that not fail in the life testing experiment can be used in the future for other purposes, the shorter the time those components spent in the exper-

iment, the longer they can be used for other purposes. Therefore, this criterion aims to minimize the total time the components spent in the experiment.

2.2.4. Settings for optimal experimental planning

In this section, we consider different settings to plan the multi-level constant-stress experiment with Type-II censoring described in Section 2.2.1. Suppose there are N components available for a multi-level constant-stress experiment with K stress levels $y_1 < y_2 < \dots < y_K$. We are interested in finding the optimal way to perform the experiment based on the optimality criteria presented in Section 2.2.3 when putting the components together as a system for the life testing experiment is possible. To simplify the problem, we consider the case that the system structures of the systems assigned to different stress levels are the same, i.e., the N components are put into $M = N/n$ n -component systems with system signature $\mathbf{s} = (s_1, \dots, s_n)$. Then, m_k systems are assigned to stress level y_k , and the first r_k system failures are observed. We have $\sum_{k=1}^K m_k = M$ and the expected number of failed components in the failed systems (denoted as R) as

$$E(R) = \sum_{k=1}^K \left[\sum_{i=1}^n i s_i \right] r_k.$$

It is noteworthy that, except for the series system, some of the components in the systems being censored may still be failed. In that case, the expected number of failed components in a censored system depends on the termination time of the experiment in a Type-II censored experiment, which also depends on the underlying lifetime distribution of the components. We consider the expected number of failed components in the failed systems only because this expected value is independent of the component lifetime distribution and it depends on the system structure (i.e., the system signature \mathbf{s}) and the experimental planning (i.e.,

the values of r_k , $k = 1, 2, \dots, K$) only. For instance, for l -out-of- n system, R is fixed as

$$R = l \sum_{k=1}^K r_k.$$

Suppose that N , K , (y_1, \dots, y_K) and $E(R)$ are pre-fixed, since the number of components in a system n , the number of systems/components assigned to the K stress levels (m_1, m_2, \dots, m_K) and the number of observed components/system failures at the K stress levels (r_1, r_2, \dots, r_K) can be adjusted, the following settings are considered:

- [M1] Fix $m_1 = m_2 = \dots = m_k$ and $r_1 = r_2 = \dots = r_k$ for $k = 1, \dots, K$, and determine the values of n and \mathbf{s} , the number of components in the system and the system structure that optimize the specific objective function. In this setting, we assign the same number of systems and fix the same number of observed system failures at all the K stress level.
- [M2] Fix $m_1 = m_2 = \dots = m_k$ for $k = 1, \dots, K$ and fix $E(R)$, and then determine the values of r_k (number of observed system failures at stress level k), the values of n (number of components in the system) and \mathbf{s} (system structure) that optimize the specific objective function. In this setting, we assign the same number of systems to each level and fix the expected number of failed components in those failed systems, and then we allow the censoring proportion at each stress level to be different.
- [M3] No specific constraints on m_k and r_k for $k = 1, \dots, K$ with fixed $\sum_{k=1}^K m_k = M$ and $E(R)$, then determine the values of (m_1, \dots, m_K) and (r_1, \dots, r_K) that optimize the specific objective function.

Since the optimal allocation cannot be found in a closed-form and there are a finite number of possible experimental plans, a discrete search method can be used to obtain the optimal plans of the experiment under different settings for different optimality criteria.

2.3. Using n -component Series Systems for Experiments

Motivated by the reliability study for joints used in case furniture presented in [Kłos et al. \(2018\)](#) in which n furniture joints are connected in series and the breakdown time of the weakest link of the n -component system is recorded, we consider a special situation that series systems are used in a multi-level constant-stress life testing experiment with Type-II censoring. In other words, we fixed the system signature as $\mathbf{s} = (1, 0, \dots, 0)$ and $n_1 = \dots = n_k = n$. As mentioned in [Section 2.1](#), using series system in life testing experiments with censoring has been considered in the literature. For example, the progressive first-failure censoring scheme proposed by [Wu and Kuş \(2009\)](#) is equivalent to using series systems in a progressive censored life testing experiment. Based on the multi-level constant-stress life testing experiment with Type-II censoring described in [Section 2.2.1](#) with series systems, the expected number of failed components in the failed systems is $R = \sum_{k=1}^K r_k$.

For a n -component series system, the SF and PDF of the log-transformed system failure times at the k -th stress level are, respectively,

$$\begin{aligned}\bar{F}_{V_k}(v; \boldsymbol{\theta}) &= [\bar{F}^*(z_k)]^n, \\ \text{and } f_{V_k}(v; \boldsymbol{\theta}) &= \frac{n}{\sigma} f^*(z_k) [\bar{F}^*(z_k)]^{n-1},\end{aligned}$$

$k = 1, \dots, K$. The log-likelihood functions in [Eq. \(2.5\)](#) can be simplified as

$$l(\boldsymbol{\theta}) = \text{constant} + \sum_{k=1}^K \sum_{\ell=1}^{r_k} \ln f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta}) + \sum_{k=1}^K (m_k - r_k) \ln \bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta}),$$

where

$$\begin{aligned}\ln f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta}) &= \ln \left\{ \frac{n}{\sigma} f^*(z_{\ell:m_k}) [\bar{F}^*(z_{\ell:m_k})]^{n-1} \right\} \\ &= \ln n - \ln \sigma + \ln f^*(z_{\ell:m_k}) + (n-1) \ln \bar{F}^*(z_{\ell:m_k}) \\ \text{and } \ln \bar{F}_{V_k}(v_{r_k:m_k}; \boldsymbol{\theta}) &= \ln \left\{ [\bar{F}^*(z_{r_k:m_k})]^n \right\} = n \ln \bar{F}^*(z_{r_k:m_k}).\end{aligned}$$

For notation simplicity, we define the following notations for the first and second derivatives of the PDF and CDF of standardized distribution:

$$\begin{aligned}
P_{10}(z) &= \frac{\partial f^*(z)}{\partial \beta_0}, & P_{20}(z) &= \frac{\partial f^*(z)}{\partial \beta_1}, & P_{30}(z) &= \frac{\partial f^*(z)}{\partial \sigma}, \\
P_{11}(z) &= \frac{\partial^2 f^*(z)}{\partial \beta_0^2}, & P_{22}(z) &= \frac{\partial^2 f^*(z)}{\partial \beta_1^2}, & P_{33}(z) &= \frac{\partial^2 f^*(z)}{\partial \sigma^2}, \\
P_{12}(z) &= \frac{\partial^2 f^*(z)}{\partial \beta_0 \partial \beta_1}, & P_{13}(z) &= \frac{\partial^2 f^*(z)}{\partial \beta_0 \partial \sigma}, & P_{23}(z) &= \frac{\partial^2 f^*(z)}{\partial \beta_1 \partial \sigma}, \\
C_{10}(z) &= \frac{\partial F^*(z)}{\partial \beta_0}, & C_{20}(z) &= \frac{\partial F^*(z)}{\partial \beta_1}, & C_{30}(z) &= \frac{\partial F^*(z)}{\partial \sigma}, \\
C_{11}(z) &= \frac{\partial^2 F^*(z)}{\partial \beta_0^2}, & C_{22}(z) &= \frac{\partial^2 F^*(z)}{\partial \beta_1^2}, & C_{33}(z) &= \frac{\partial^2 F^*(z)}{\partial \sigma^2}, \\
C_{12}(z) &= \frac{\partial^2 F^*(z)}{\partial \beta_0 \partial \beta_1}, & C_{13}(z) &= \frac{\partial^2 F^*(z)}{\partial \beta_0 \partial \sigma}, & C_{23}(z) &= \frac{\partial^2 F^*(z)}{\partial \beta_1 \partial \sigma}.
\end{aligned}$$

Based on the assumption that the log-transformed component lifetimes follow a distribution in the location-scale family, from the relations in Eq. (1.4), we can obtain

$$\begin{aligned}
\frac{\partial z}{\partial \beta_0} &= -\frac{1}{\sigma}, & \frac{\partial z}{\partial \beta_1} &= -\frac{y}{\sigma}, & \frac{\partial z}{\partial \sigma} &= -\frac{z}{\sigma}, \\
\frac{\partial \bar{F}^*(z)}{\partial z} &= -\frac{\partial F^*(z)}{\partial z} = -f^*(z).
\end{aligned}$$

Then, the partial derivatives of $l(\boldsymbol{\theta})$ with respect to the parameters β_0 , β_1 , and σ in Eqs. (2.6), (2.7), (2.8) can be simplified as

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \beta_0} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left[\frac{P_{10}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} + (n-1) \frac{-C_{10}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right] \\ &\quad + \sum_{k=1}^K (m_k - r_k) \left[\frac{n(-C_{10}(z_{r_k:m_k}))}{\bar{F}^*(z_{r_k:m_k})} \right], \end{aligned} \quad (2.18)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \beta_1} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left[\frac{P_{20}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} + (n-1) \frac{-C_{20}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right] \\ &\quad + \sum_{k=1}^K (m_k - r_k) \left[\frac{n(-C_{20}(z_{r_k:m_k}))}{\bar{F}^*(z_{r_k:m_k})} \right], \end{aligned} \quad (2.19)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left[-\frac{1}{\sigma} + \frac{P_{30}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} + (n-1) \frac{-C_{30}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right] \\ &\quad + \sum_{k=1}^K (m_k - r_k) \left[\frac{n(-C_{30}(z_{r_k:m_k}))}{\bar{F}^*(z_{r_k:m_k})} \right], \end{aligned} \quad (2.20)$$

respectively. Similarly, we can obtain the second partial derivatives of $l(\boldsymbol{\theta})$ as

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0^2} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left\{ - \left(\frac{P_{10}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right)^2 + \left(\frac{P_{11}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right) \right. \\ &\quad \left. + (n-1) \left[- \left(\frac{C_{10}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right)^2 - \left(\frac{C_{11}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right) \right] \right\} \\ &\quad + \sum_{k=1}^K n(m_k - r_k) \left[- \left(\frac{C_{10}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right)^2 - \left(\frac{C_{11}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right) \right], \end{aligned} \quad (2.21)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1^2} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left\{ - \left(\frac{P_{20}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right)^2 + \left(\frac{P_{22}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right) \right. \\ &\quad \left. + (n-1) \left[- \left(\frac{C_{20}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right)^2 - \left(\frac{C_{22}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right) \right] \right\} \\ &\quad + \sum_{k=1}^K n(m_k - r_k) \left[- \left(\frac{C_{20}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right)^2 - \left(\frac{C_{22}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right) \right], \end{aligned} \quad (2.22)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left\{ \frac{1}{\sigma^2} - \left(\frac{P_{30}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right)^2 + \left(\frac{P_{33}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right) \right. \\ &\quad \left. + (n-1) \left[- \left(\frac{C_{30}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right)^2 - \left(\frac{C_{33}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right) \right] \right\} \\ &\quad + \sum_{k=1}^K n(m_k - r_k) \left[- \left(\frac{C_{30}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right)^2 - \left(\frac{C_{33}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right) \right], \end{aligned} \quad (2.23)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left\{ - \left(\frac{P_{10}(z_{\ell:m_k}) P_{20}(z_{\ell:m_k})}{(f^*(z_{\ell:m_k}))^2} \right) + \left(\frac{P_{12}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right) \right. \\ &\quad \left. + (n-1) \left[- \left(\frac{C_{10}(z_{\ell:m_k}) C_{20}(z_{\ell:m_k})}{(\bar{F}^*(z_{\ell:m_k}))^2} \right) - \left(\frac{C_{12}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right) \right] \right\} \\ &\quad + \sum_{k=1}^K n(m_k - r_k) \left[- \left(\frac{C_{10}(z_{r_k:m_k}) C_{20}(z_{r_k:m_k})}{(\bar{F}^*(z_{r_k:m_k}))^2} \right) - \left(\frac{C_{12}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right) \right], \end{aligned} \quad (2.24)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left\{ - \left(\frac{P_{10}(z_{\ell:m_k}) P_{30}(z_{\ell:m_k})}{(f^*(z_{\ell:m_k}))^2} \right) + \left(\frac{P_{13}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right) \right. \\ &\quad \left. + (n-1) \left[- \left(\frac{C_{10}(z_{\ell:m_k}) C_{30}(z_{\ell:m_k})}{(\bar{F}^*(z_{\ell:m_k}))^2} \right) - \left(\frac{C_{13}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right) \right] \right\} \\ &\quad + \sum_{k=1}^K n(m_k - r_k) \left[- \left(\frac{C_{10}(z_{r_k:m_k}) C_{30}(z_{r_k:m_k})}{(\bar{F}^*(z_{r_k:m_k}))^2} \right) - \left(\frac{C_{13}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right) \right], \end{aligned} \quad (2.25)$$

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} &= \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left\{ - \left(\frac{P_{20}(z_{\ell:m_k}) P_{30}(z_{\ell:m_k})}{(f^*(z_{\ell:m_k}))^2} \right) + \left(\frac{P_{23}(z_{\ell:m_k})}{f^*(z_{\ell:m_k})} \right) \right. \\
&\quad \left. + (n-1) \left[- \left(\frac{C_{20}(z_{\ell:m_k}) C_{30}(z_{\ell:m_k})}{(\bar{F}^*(z_{\ell:m_k}))^2} \right) - \left(\frac{C_{23}(z_{\ell:m_k})}{\bar{F}^*(z_{\ell:m_k})} \right) \right] \right\} \\
&\quad + \sum_{k=1}^K n(m_k - r_k) \left[- \left(\frac{C_{20}(z_{r_k:m_k}) C_{30}(z_{r_k:m_k})}{(\bar{F}^*(z_{r_k:m_k}))^2} \right) - \left(\frac{C_{23}(z_{r_k:m_k})}{\bar{F}^*(z_{r_k:m_k})} \right) \right]. \quad (2.26)
\end{aligned}$$

Then, the Fisher information matrix and the asymptotic variance-covariance matrix in Eqs. (2.15) and (2.16) can be computed based on the second derivatives in Eqs. (2.21) – (2.26). In the following subsections, we provide the computational formulas when the components are distributed as lognormal and Weibull.

2.3.1. Lognormal distributed components

Consider the lifetimes of the components follow a two-parameter lognormal distribution with CDF and PDF

$$\begin{aligned}
F_{LN}(x; \mu, \sigma) &= \Phi_{nor} \left[\frac{\ln(x) - \mu}{\sigma} \right], x > 0, \\
f_{LN}(x; \mu, \sigma) &= \frac{1}{\sigma x} \phi_{nor} \left(\frac{\ln(x) - \mu}{\sigma} \right) = \frac{1}{\sqrt{2\pi}\sigma x} \exp \left[-\frac{1}{2} \left(\frac{\ln(x) - \mu}{\sigma} \right)^2 \right] x > 0,
\end{aligned}$$

respectively, where $\exp(\mu)$ is the scale parameter, $\sigma > 0$ is the shape parameter and $\Phi_{nor}(z)$ and $\phi_{nor}(z)$ are the CDF, SF and PDF for the standard normal distribution:

$$\begin{aligned}
\Phi_{nor}(z) &= \int_{-\infty}^z \phi_{nor}(w) dw, \quad \bar{\Phi}_{nor}(z) = 1 - \Phi_{nor}(z), \\
\phi_{nor}(z) &= \frac{1}{\sqrt{2\pi}} \exp \left(-\frac{z^2}{2} \right), \quad -\infty < z < \infty.
\end{aligned}$$

Then, the log-transformed component lifetimes follow a normal distribution with location parameter μ and scale parameter σ with CDF, SF and PDF

$$\begin{aligned} F_U(u; \mu, \sigma) &= \Phi_{nor} \left(\frac{u - \mu}{\sigma} \right), \\ \bar{F}_U(u; \mu, \sigma) &= 1 - \Phi_{nor} \left(\frac{u - \mu}{\sigma} \right) = \bar{\Phi}_{nor} \left(\frac{u - \mu}{\sigma} \right), \\ \text{and } f_U(u; \mu, \sigma) &= \frac{1}{\sigma} \phi_{nor} \left(\frac{u - \mu}{\sigma} \right), \quad -\infty < u < \infty, \end{aligned}$$

respectively. The first and second derivatives of the PDF and CDF of standard normal distribution are presented in Appendix B. Then, the second derivatives in Eqs. (2.21) – (2.26) can be obtained as

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0^2} = \frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [(n-1)B(z_{\ell:m_k}) - 1] + \sum_{k=1}^K n(m_k - r_k)B(z_{r_k:m_k}) \right\}, \quad (2.27)$$

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1^2} = \frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} y_k^2 [(n-1)B(z_{\ell:m_k}) - 1] + \sum_{k=1}^K n(m_k - r_k)y_k^2 B(z_{r_k:m_k}) \right\}, \quad (2.28)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} \left[(n-1)z_{\ell:m_k}^2 B(z_{\ell:m_k}) - 2z_{\ell:m_k}^2 - (n-1)z_{\ell:m_k} \frac{\phi_{nor}(z_{\ell:m_k})}{\bar{\Phi}_{nor}(z_{\ell:m_k})} \right] \right. \\ &\quad \left. + \sum_{k=1}^K n(m_k - r_k)z_{r_k:m_k} \left[z_{r_k:m_k} B(z_{r_k:m_k}) - \frac{\phi_{nor}(z_{r_k:m_k})}{\bar{\Phi}_{nor}(z_{r_k:m_k})} \right] \right\}, \quad (2.29) \end{aligned}$$

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} = \frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} y_k [(n-1)B(z_{\ell:m_k}) - 1] + \sum_{k=1}^K n y_k (m_k - r_k) B(z_{r_k:m_k}) \right\}, \quad (2.30)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} &= \frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} z_{\ell:m_k} [(n-1)B(z_{\ell:m_k}) - 1] \right. \\ &\quad \left. + \sum_{k=1}^K n z_{r_k:m_k} (m_k - r_k) B(z_{r_k:m_k}) \right\}, \quad (2.31) \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} &= \frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} y_k z_{\ell:m_k} [(n-1)B(z_{\ell:m_k}) - 1] \right. \\ &\quad \left. + \sum_{k=1}^K n(m_k - r_k) y_k z_{r_k:m_k} B(z_{r_k:m_k}) \right\}, \quad (2.32) \end{aligned}$$

where $B(z) = \phi_{nor}(z) [z\bar{\Phi}_{nor}(z) - \phi_{nor}(z)] / [\bar{\Phi}_{nor}(z)]^2$. In order to compute the expected Fisher information matrix, we need to compute the expectations $E(Z_{\ell:m_k}^2)$, $E(Z_{\ell:m_k} f^*(Z_{\ell:m_k}) / \bar{\Phi}_{nor}(Z_{\ell:m_k}))$, $E(B(Z_{\ell:m_k}))$, $E(Z_{\ell:m_k} B(Z_{\ell:m_k}))$, and $E(Z_{\ell:m_k}^2 B(Z_{\ell:m_k}))$, $\ell = 1, \dots, r_k$, $k = 1, \dots, K$.

Since these expectations cannot be obtained analytically, we consider computing these expectations by using numerical integration or Monte Carlo integration. For instance, since the PDF of the ℓ -th order statistic from a sample of size m_k , $z_{\ell:m_k}$, $\ell = 1, \dots, r_k$, $k = 1, \dots, K$ is given by

$$f_{\ell:m_k}(z) = \frac{m_k!}{(\ell-1)!(m_k-\ell)!} \frac{n}{\sigma} \phi_{nor}(z) [\Phi_{nor}(z)]^{n(\ell-1)} [\bar{\Phi}_{nor}(z)]^{m_k-\ell+n-1},$$

$$-\infty < z < \infty, \quad (2.33)$$

the expectation of a function of $Z_{\ell:m_k}$ (denoted as $g(Z_{\ell:m_k})$), $E[g(Z_{\ell:m_k})]$ can be approximated by Monte Carlo integration method as

$$E[g(Z_{\ell:m_k})] = \int_{-\infty}^{\infty} g(Z_{\ell:m_k}) f_{\ell:m_k}(z) dz \approx \frac{1}{S} \sum_{i=1}^S g(z_s), \quad (2.34)$$

where z_s is a random variate generated from the PDF in Eq. (2.33). By the law of large numbers, when $S \rightarrow \infty$, $\frac{1}{S} \sum_{i=1}^S g(z_s)$ converges almost surely to $E[g(Z_{\ell:m_k})]$.

2.3.2. Weibull distributed components

Suppose the lifetimes of the components follow a two-parameter Weibull distribution with CDF and PDF

$$F_{WE}(x; \eta, \beta) = 1 - \exp \left[- \left(\frac{x}{\eta} \right)^\beta \right], x > 0,$$

$$f_{WE}(x; \eta, \beta) = \frac{\beta}{\eta} \left(\frac{x}{\eta} \right)^{\beta-1} \exp \left[- \left(\frac{x}{\eta} \right)^\beta \right], x > 0,$$

respectively, where $\eta > 0$ is the scale parameter and $\beta > 0$ is the shape parameter. Then, the log-transformed component lifetimes follow a SEV distribution (also known as Gumbel Type I distribution) with location parameter μ and scale parameter σ , i.e.,

$$F_U(u; \mu, \sigma) = \Phi_{sev} \left(\frac{u - \mu}{\sigma} \right), -\infty < u < \infty,$$

$$f_U(u; \mu, \sigma) = \frac{1}{\sigma} \phi_{sev} \left(\frac{u - \mu}{\sigma} \right), -\infty < u < \infty,$$

where $\sigma = 1/\beta$, $\mu = \ln(\eta)$, and $\Phi_{sev}(z) = 1 - \exp[-\exp(z)]$ and $\phi_{sev}(z) = \exp[z - \exp(z)]$ are the CDF and PDF for the standard SEV distribution. The first and second derivatives of the PDF and CDF of standard SEV distribution are presented in Appendix C. Then, the second derivatives in Eqs. (2.21) – (2.26) can be obtained as

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0^2} = -\frac{n}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [\exp(z_{\ell:m_k})] + \sum_{k=1}^K (m_k - r_k) [\exp(z_{r_k:m_k})] \right\}, \quad (2.35)$$

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1^2} = -\frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [ny_\ell^2 \exp(z_{\ell:m_k})] + \sum_{k=1}^K ny_\ell^2 (m_k - r_k) [\exp(z_{r_k:m_k})] \right\}, \quad (2.36)$$

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= -\frac{1}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [n z_{\ell:m_k} \exp(z_{\ell:m_k})(z_{\ell:m_k} + 1) - z_{\ell:m_k}] \right. \\ &\quad \left. + \sum_{k=1}^K [n z_{r_k:m_k} \exp(z_{r_k:m_k})(m_k - r_k)(z_{r_k:m_k} + 1)] \right\}, \end{aligned} \quad (2.37)$$

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} = -\frac{n}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [y_{\ell} \exp(z_{\ell:m_k})] + \sum_{k=1}^K [y_k (m_k - r_k) \exp(z_{r_k:m_k})] \right\}, \quad (2.38)$$

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} = -\frac{n}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [z_{\ell:m_k} \exp(z_{\ell:m_k})] + \sum_{k=1}^K z_{r_k:m_k} (m_k - r_k) [\exp(z_{r_k:m_k})] \right\}, \quad (2.39)$$

$$\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} = -\frac{n}{\sigma^2} \left\{ \sum_{k=1}^K \sum_{\ell=1}^{r_k} [y_{\ell} z_{\ell:m_k} \exp(z_{\ell:m_k})] + \sum_{k=1}^K y_k z_{r_k:m_k} (m_k - r_k) [\exp(z_{r_k:m_k})] \right\}. \quad (2.40)$$

In order to compute the expected Fisher information matrix, we need to compute the expectations $E(\exp(Z_{\ell:m_k}))$ and $E(Z_{\ell:m_k}^d \exp(Z_{\ell:m_k}))$, $d = 0, 1, 2$. Consider the PDF of the ℓ -th order statistic of a sample of size m_k , $\ell = 1, \dots, r_k$, $k = 1, \dots, K$ of the minimum among n random variables from the standard SEV distribution is given by

$$\begin{aligned} f_{\ell:m_k}(z) &= \frac{m_k!}{(\ell-1)! (m_k - \ell)!} [\Phi_{sev}(z + \ln n)]^{\ell-1} [1 - \Phi_{sev}(z + \ln n)]^{m_k - \ell} \phi_{sev}(z + \ln n) \\ &= \frac{m_k!}{(\ell-1)! (m_k - \ell)!} [1 - e^{-ne^z}]^{\ell-1} [e^{-ne^z}]^{m_k - \ell} (ne^{z - ne^z}). \end{aligned}$$

Then, the expectations $E(\exp(Z_{\ell:m_k}))$ and $E(Z_{\ell:m_k}^d \exp(Z_{\ell:m_k}))$ can be expressed as

$$E(Z_{\ell:m_k}) = \frac{n(m_k!)}{(\ell-1)! (m_k - \ell)!} \sum_{p=0}^{m_k - \ell} (-1)^p \binom{m_k - \ell}{p} \int_{-\infty}^{\infty} z e^{z - n(p+\ell)e^z} dz$$

and

$$\begin{aligned} E[Z_{\ell:m_k}^d \exp(Z_{\ell:m_k})] &= \frac{n(m_k!)}{(\ell-1)! (m_k - \ell)!} \sum_{p=0}^{m_k - \ell} (-1)^p \binom{m_k - \ell}{p} \int_{-\infty}^{\infty} z^d e^{2z - n(p+\ell)e^z} dz, \end{aligned}$$

respectively, which can be computed by evaluating the integrals

$$h(c) = \int_{-\infty}^{\infty} z e^{z-ce^z} dz \text{ and } g_d(c) = \int_{-\infty}^{\infty} z^d e^{2z-ce^z} dz,$$

for $d = 0, 1, 2$ as

$$h(c) = -\frac{\gamma + \log c}{c}$$

and

$$\begin{aligned} g_0(c) &= \frac{1}{c^2}, \\ g_1(c) &= \frac{1 - \gamma - \log c}{c^2}, \\ g_2(c) &= \frac{\log c^2 - 2(1 - \gamma \log c + \gamma^2 - 2\gamma + \pi^2/6)}{c^2}, \end{aligned}$$

where $\gamma = -\Gamma'(1) = 0.57721566\dots$ is Euler's constant.

Note that the results for life testing experiment based on n -component series system with Weibull distributed components can be obtained from the results for life testing experiment based on individual components due to the fact that the first order statistic of n i.i.d. Weibull random variables is also Weibull distributed. Specifically, if the lifetimes of components in an n -component series system are Weibull distributed with scale parameter η and shape parameter β , then the lifetime of the n -component series system follows a Weibull distribution with scale parameter $n^{-1/\beta}\eta$ and shape parameter β . It is noteworthy that although the results for life testing experiment based on n -component series system with Weibull distributed components can be obtained from the results for life testing experiment based on individual components, comparing optimal allocations with series systems with different number of components is one of the main focuses in this paper.

2.4. Numerical Illustrations for Series Systems

In this section, we illustrate how the methodologies developed in Sections 2.2 and 2.3 can be used to plan a multi-level constant-stress experiment with Type-II censoring when series systems can be used in the experiment in addition to using individual components. We compare the experimental schemes based on series systems with different number of components by fixing the number of failed components in the experiment and demonstrate the possible advantages of using systems instead of individual components in a life testing experiment.

We consider that there are $N = 40$ and 60 components available for a multi-level constant-stress experiment with $K = 2$ or 4 stress levels. We can perform the experiment with individual components (i.e., $n = 1$) or with n -component series systems with $n \geq 2$. For an n -component series system, we set the possible values of n to be $1, 2,$ and 4 for $N = 40$ and n to be $1, 2,$ and 3 for $N = 60$. To provide a fair ground for comparison, we consider fixing the number of failed components R in obtaining the optimal experimental schemes. That is, for a fixed value of R , we obtain the optimal experimental schemes based on different optimality criteria with $n = 1, 2$ and 4 . On the other hand, in this study, for a fixed value of n , we can also compare the results with different R . For illustrative purposes, we consider the true values of the model parameters as $\beta_0 = 0, \beta_1 = 1$ and $\sigma = 1$.

2.4.1. Two-stress-level case

For the case of $K = 2$ stress levels, we set the stress levels to be $y = (-0.5, 0.5)$. Respectively, we assign (m_1, m_2) systems to the first and second stress levels, and plan to fail (r_1, r_2) systems of those (m_1, m_2) systems. In Tables 2.1 and 2.2, the optimal allocations for $N = 40$ with respect to the five optimality criteria described in Section 2.2.3 and under different settings [M1], [M2] and [M3] described in Section 2.2.4 when the components

are assumed to follow a lognormal and Weibull distributions, respectively. In addition to $N = 40$, we also explore the optimal allocations for a larger N ($N = 60$) with larger numbers of observed failures $R = 17(1)20$. In Table 2.3 and Table 2.4, we present the numerical results of optimal allocations for $N = 60$ with total number of failures $R = 17(1)20$ for $n = 1, 2$ and 3 for different optimality criteria under different settings [M1], [M2] and [M3]:

- [M1] We set $m_1 = m_2 = N/(2n)$ and $r_1 = r_2 = R/2$ and then obtain the optimal experimental plans under different optimality criteria.
- [M2] We set $m_1 = m_2 = N/(2n)$, and then determine the values of (r_1, r_2) for the optimal experimental plans under different optimality criteria.
- [M3] With no specific constraints on (m_1, m_2) and (r_1, r_2) , we determine the values of (m_1, m_2) and (r_1, r_2) for the optimal experimental plans under different optimality criteria.

Table 2.2: (Continue)

R	n	Setting	(m_1, m_2)	(r_1, r_2)	[C1]	[C2]	[C3]	[C4]	[C5]		
					$ \mathbf{I} $	$\text{tr}(\mathbf{I}^{-1})$	$\text{var}(\hat{\beta}_1)$	$E(TTE)$	$E(TTT)$		
7	1	[M1]	No optimal allocation can be obtained due to r_1 cannot be equal to r_2								
		[M2]	(20,20)	(4,3)	107.82	1.1266	0.5911	2.64	62.18		
			(20,20)	(3,4)	107.82	1.1266	0.5911	1.93	54.47		
			(20,20)	(2,5)	90.08	1.3629	0.7755	1.25	46.77		
			(20,20)	(1,6)	54.04	2.1907	1.4228	1.55	39.07		
		[M3]	(36,4)	(3,4)	125.70	1.6245	1.2979	9.34	54.47		
			(4,36)	(4,3)	125.70	1.6245	1.2979	25.38	62.18		
			(24,16)	(4,3)	107.72	1.1147	0.5860	2.17	62.18		
			(16,24)	(3,4)	107.72	1.1147	0.5860	2.44	54.47		
			(23,17)	(4,3)	107.72	1.1156	0.5836	2.27	62.18		
			(17,23)	(3,4)	107.72	1.1156	0.5836	2.29	54.47		
			(12,28)	(1,6)	53.19	1.9591	1.2144	1.06	39.07		
			(1,39)	(1,6)	52.64	2.1646	1.7083	12.18	39.07		
		2		[M1]	No optimal allocation can be obtained due to r_1 cannot be equal to r_2						
				[M2]	(10,10)	(4,3)	111.49	1.1018	0.5918	2.92	62.18
					(10,10)	(3,4)	111.49	1.1018	0.5918	2.05	54.47
					(10,10)	(2,5)	94.24	1.3370	0.7814	1.45	46.77
	(10,10)			(1,6)	57.91	2.1538	1.4339	1.89	39.07		
[M3]	(16,4)			(3,4)	126.42	1.311	0.9282	4.67	54.47		
	(4,16)			(4,3)	126.42	1.311	0.9282	12.69	62.18		
	(12,8)			(4,3)	111.24	1.0901	0.5860	2.35	62.18		
	(8,12)			(3,4)	111.24	1.0901	0.5860	2.65	54.47		
	(11,9)			(4,3)	111.27	1.0932	0.5838	2.6	62.18		
	(9,11)			(3,4)	111.27	1.0932	0.5838	2.31	54.47		
	(6,14)			(1,6)	55.49	1.9362	1.2206	1.20	39.07		
	(1,19)			(1,6)	54.21	1.8992	1.3903	6.09	39.07		
4		[M1]	No optimal allocation can be obtained due to r_1 cannot be equal to r_2								
		[M2]	(5,5)	(4,3)	122.63	1.0428	0.5942	3.91	62.18		
			(5,5)	(3,4)	122.63	1.0428	0.5942	2.39	54.47		
			(5,5)	(2,5)	111.41	1.2631	0.7993	2.56	46.77		
		[M3]	(6,4)	(3,4)	129.22	1.0706	0.6518	2.33	54.47		
			(4,6)	(4,3)	129.22	1.0706	0.6518	6.35	62.18		
			(6,4)	(4,3)	121.48	1.0322	0.5860	2.89	62.18		
			(4,6)	(3,4)	121.48	1.0322	0.5860	3.3	54.47		
			(2,8)	(1,6)	60.73	1.7926	1.1741	1.52	39.07		
			(3,7)	(1,6)	63.46	1.8747	1.2368	1.78	39.07		

2.4.2. Four-stress-level case

In the case of $K = 4$, we set the stress levels to be $y = (-1.0, -0.5, 0.5, 1.0)$. Similarly, we assign m_k systems to the k -th stress level y_k and fail r_k systems out of those m_k systems ($k = 1, 2, 3, 4$). The optimal experimental plans for $N = 40$ with respect to the five optimality criteria for lognormal and Weibull distributed components are presented in Table 2.5 and Table 2.6. The following settings are considered:

- [M1] We set $m_k = N/(4n)$ and $r_k = R/4$, $k = 1, 2, 3, 4$ and then obtain the optimal experimental plans under different optimality criteria.
- [M2] We set $m_k = N/(4n)$, $k = 1, 2, 3, 4$, and then to determine the values of (r_1, r_2, r_3, r_4) for the optimal experimental plans under different optimality criteria.
- [M3] With no specific constraints on m_k and r_k for $k = 1, 2, 3, 4$, we need to determine the values of (m_1, m_2, m_3, m_4) and (r_1, r_2, r_3, r_4) for the optimal experimental plans under different optimality criteria.

Table 2.5: Optimal allocations for n -component series systems with lognormal distributed components when $N = 40$, $K = 4$, $(y_1, y_2, y_3, y_4) = (-1.0, -0.5, 0.5, 1.0)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4

R	n	Setting	(m_1, m_2, m_3, m_4)	(r_1, r_2, r_3, r_4)	[C1]	[C2]	[C3]	[C4]	[C5]			
					II	$\text{tr}(\mathbf{I}^{-1})$	$\text{var}(\hat{\beta}_1)$	$E(TTE)$	$E(TTT)$			
10	1	[M1]	No optimal allocation can be obtained due to r_k cannot be equal, $k = 1, 2, 3, 4$									
		[M2]	(10, 10, 10, 10)	(4, 1, 1, 4)	6447.47	0.1983	0.0623	14.93	188.65			
			(10, 10, 10, 10)	(5, 0, 1, 4)	5434.85	0.1970	0.0635	19.17	183.39			
			(10, 10, 10, 10)	(0, 1, 3, 6)	1643.18	0.4519	0.2155	3.32	78.51			
			(10, 10, 10, 10)	(0, 0, 1, 9)	147.20	3.7772	2.0061	8.28	49.15			
		[M3]	(20, 0, 0, 20)	(5, 0, 0, 5)	8569.17	0.2018	0.0429	9.99	208.93			
		(20, 4, 0, 16)	(2, 4, 0, 4)	7557.39	0.1889	0.0593	44.45	204.87				
		(16, 0, 4, 20)	(4, 0, 4, 2)	7557.39	0.1889	0.0593	16.35	190.84				
		(0, 0, 7, 33)	(0, 0, 1, 9)	216.76	3.4099	1.6924	1.46	53.39				
		(25, 0, 2, 13)	(0, 0, 1, 9)	78.63	5.9117	3.0474	4.27	43.53				
	2	1	[M1]	No optimal allocation can be obtained due to r_k cannot be equal, $k = 1, 2, 3, 4$								
			[M2]	(5, 5, 5, 5)	(4, 1, 1, 4)	6373.78	0.1962	0.0651	19.18	188.99		
			(5, 5, 5, 5)	(5, 0, 1, 4)	5351.35	0.1954	0.0676	33.94	187.80			
			(5, 5, 5, 5)	(0, 1, 4, 5)	1659.10	0.4338	0.2180	4.59	81.12			
			(5, 5, 5, 5)	(0, 0, 5, 5)	268.90	1.8173	1.0805	7.57	56.99			
[M3]			(10, 0, 0, 10)	(5, 0, 0, 5)	8543.99	0.1965	0.0441	11.06	207.52			
		(7, 0, 8, 5)	(4, 0, 1, 5)	6985.74	0.1895	0.0601	12.46	175.84				
		(5, 8, 0, 7)	(5, 1, 0, 4)	6985.74	0.1895	0.0601	33.94	216.21				
		(0, 0, 3, 17)	(0, 0, 1, 9)	210.05	3.5750	1.7886	1.62	52.93				
		(9, 0, 1, 10)	(0, 0, 1, 9)	100.38	5.8106	2.9793	3.76	45.73				
4		[M1]	No optimal allocation can be obtained due to m_k cannot be equal, $k = 1, 2, 3, 4$									
		[M2]	No optimal allocation can be obtained due to m_k cannot be equal, $k = 1, 2, 3, 4$									
	[M3]	(5, 0, 0, 5)	(5, 0, 0, 5)	8539.63	0.1847	0.0475	17.32	205.70				
		(0, 0, 2, 8)	(0, 0, 2, 8)	341.63	2.2882	1.1885	2.76	55.40				
		(0, 0, 1, 9)	(0, 0, 1, 9)	192.20	4.1563	2.1127	2.81	52.22				

2.4.3. Discussion

The results presented in this section provide the necessary information to select an experimental plan for a fixed values of N and R when series systems are used in the experiment. For example, there are 40 components that assumed to follow a lognormal distribution available for the multi-level constant-stress experiment with Type-II censoring, and we can only afford to fail 10 of the 40 components in the experiment. Based on the numerical results presented in Table 2.1, for optimal criterion [C1] (D -optimality) that maximizes the determinant of the expected Fisher information matrix and for optimal criterion [C3] (V -optimality) that minimizes the asymptotic variance of the MLE $\hat{\beta}_1$, we would choose to perform the life testing experiment based on individual components by allocating $m_1 = m_2 = 20$ components to the two stress levels and terminate the experiment at each of the two stress levels when the 5-th failure occurs. The values of the optimal objective functions for [C1] and [C3] when $n = 1$, $n = 2$ and $n = 4$ are ($|I| = 2142.29$, $var(\hat{\beta}_1) = 0.1717$), ($|I| = 2136.00$, $var(\hat{\beta}_1) = 0.1763$) and ($|I| = 2134.91$, $var(\hat{\beta}_1) = 0.1902$), respectively.

If one consider the optimal criterion [C2] (A -optimality) that minimizes the sum of asymptotic variances of the MLEs, since the values of the optimal objective function (i.e., $tr(\mathbf{I}^{-1})$) for [C2] when $n = 1$, $n = 2$ and $n = 4$ are 0.3306, 0.3287 and 0.3273, respectively, we would perform the experiment by putting the 40 components into 10 series 4-component systems and then allocate these 10 systems equally to the two stress levels and observe the lifetimes of all these 10 systems. Note that the expected total time on test for the experiment based on 4-component series systems is the shortest compared to $n = 1$ and 2, while the expected total experimental time based on 4-component systems is the longest compared to $n = 1$ and 2.

In the above illustration, we can see that putting the components into 4-component series systems provides a slight decrease (about 1%) in the total estimation variances of the MLEs compared to using individual components or 2-component systems. However, in some cases,

using series systems can give a higher degree of advantage over using individual components, especially for A -optimality [C2]. For instance, in Table 2.4, when $K = 2$, $N = 60$, $R = 20$ and the component lifetimes follow a Weibull distribution, for D -optimality and A -optimality, the optimal experimental plan based on 3-component series systems give $|\mathbf{I}| = 3289.87$ and $\text{tr}(\mathbf{I}^{-1}) = 0.2943$, while the optimal experimental plan based on individual components give $|\mathbf{I}| = 2815.88$ and $\text{tr}(\mathbf{I}^{-1}) = 0.3316$. In other words, using 3-component series systems for the multi-level constant-stress experiment can give 16.83% and 11.25% improvements in terms of optimality criteria [C1] and [C2].

From the numerical results, we observe that the advantages and disadvantages of using systems in a multi-level constant-stress experiment does not show a specific pattern and it depends on the value of R , the number of stress levels K and the underlying component distributions. Therefore, it is important to evaluate the performance of the optimal experimental plans under different values of n in order to determine the optimal experimental planning for a specific situation, and the methodologies proposed in here are useful for this purpose. Although using systems in multi-level constant-stress experiment with Type-II censoring does not always give advantage over using individual components, when using systems is superior to using individual components, it always gains efficiency in estimation and gives shorter expected TTT.

2.5. Monte Carlo Simulation Study

Since the optimal experimental plans discussed in the previous sections are based on asymptotic properties of the MLEs and the accuracy of the asymptotic approximation depends on the sample sizes, we use a Monte Carlo simulation study to evaluate the validity of the numerical results based on expected Fisher information matrix and asymptotic variance-covariance matrix.

For each optimal experimental plans presented in Section 2.4, we simulate the failure times based on the multi-level constant-stress experiment with Type-II censoring and compute the corresponding MLEs of the model parameters $(\beta_0, \beta_1, \sigma)$ (denoted as $(\hat{\beta}_0, \hat{\beta}_1, \hat{\sigma})$) and the observed Fisher information matrix (denoted as \mathcal{I}) defined as

$$\mathcal{I}(\hat{\beta}_0, \hat{\beta}_1, \hat{\sigma}) = - \begin{bmatrix} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0^2} & \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} & \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} & \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1^2} & \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} & \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} & \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} \end{bmatrix}_{(\beta_0, \beta_1, \sigma) = (\hat{\beta}_0, \hat{\beta}_1, \hat{\sigma})}. \quad (2.41)$$

We also record the total time of the experiment (TTE) and total time on test (TTT) in each simulation. Based on 100,000 simulations, we compute the average of the 100,000 observed Fisher information matrices (denoted as $\bar{\mathcal{I}}$), the variances of the 100,000 MLEs $\hat{\beta}_0$, $\hat{\beta}_1$ and $\hat{\sigma}$ (denoted as V_{β_0} , V_{β_1} , V_{σ}), the average of the 100,000 TTE (denoted as \overline{TTE}), and the average of the 100,000 TTT (denoted as \overline{TTT}). We only present the simulation results for setting [M3] since it is the setting with the fewest restrictions. The simulated values of $\bar{\mathcal{I}}$, $V_{\beta_0} + V_{\beta_1} + V_{\sigma}$, V_{β_1} , \overline{TTE} and \overline{TTT} for the settings corresponding to Tables 2.1, 2.2, 2.5 and 2.6 are presented in Tables 2.7, 2.8, 2.9 and 2.10, respectively.

Table 2.7: Simulation results for the optimal allocations for n -component series systems with lognormal distributed components when $N = 40$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3] (referring to Table 2.1)

R	n	Setting	(m_1, m_2)	(r_1, r_2)	[C1]	[C2]	[C3]	[C4]	[C5]	
					$ \bar{Z} $	$V_{\beta_0} + V_{\beta_1} + V_{\sigma}$	V_{β_1}	\overline{TTE}	\overline{TTT}	
10	1	[M3]	(20, 20)	(5, 5)	1780.47	0.3279	0.1718	6.06	152.53	
			(12, 28)	(1, 9)	807.47	0.6432	0.4104	3.41	101.64	
			(2, 38)	(1, 9)	425.69	1.0158	0.7399	9.69	94.61	
	2	[M3]	(10, 10)	(5, 5)	1798.24	0.3267	0.1773	6.71	151.59	
			(5, 15)	(1, 9)	812.23	0.6468	0.4214	3.80	99.98	
			(1, 19)	(1, 9)	437.79	1.0212	0.7489	9.73	94.07	
	4	[M3]	(5, 5)	(5, 5)	1855.42	0.3275	0.1911	10.58	150.25	
			(1, 9)	(1, 9)	666.86	0.7747	0.5473	6.62	94.70	
	9	1	[M3]	(20, 20)	(5, 4)	1369.57	0.3658	0.1882	6.06	146.98
				(20, 20)	(4, 5)	1369.87	0.3642	0.1858	5.12	137.40
				(21, 19)	(5, 4)	1367.56	0.3643	0.1845	5.84	148.30
				(19, 21)	(4, 5)	1365.56	0.3622	0.1842	5.32	136.40
(13, 27)				(1, 8)	664.36	0.6567	0.4046	3.22	96.87	
(2, 38)				(1, 8)	350.11	1.0468	0.7550	9.67	89.09	
2		[M3]	(10, 10)	(5, 4)	1390.65	0.3628	0.1898	6.69	145.77	
			(10, 10)	(4, 5)	1388.74	0.3611	0.1888	5.48	136.50	
			(11, 9)	(5, 4)	1380.46	0.3618	0.1888	6.14	148.21	
			(9, 11)	(4, 5)	1383.33	0.3629	0.1900	5.95	134.14	
			(6, 14)	(1, 8)	688.35	0.6567	0.4124	3.50	95.81	
			(1, 19)	(1, 8)	359.70	1.0388	0.7518	9.71	88.58	
4		[M3]	(5, 5)	(5, 4)	1437.90	0.3586	0.2014	10.48	144.41	
			(5, 5)	(4, 5)	1437.91	0.3586	0.2010	6.93	134.89	
			(2, 8)	(1, 8)	694.47	0.6779	0.4489	5.13	92.60	
			(1, 9)	(1, 8)	533.72	0.7937	0.5487	5.91	88.87	
8		1	[M3]	(20, 20)	(4, 4)	1029.73	0.4005	0.1960	5.12	131.90
				(15, 25)	(1, 7)	533.90	0.6812	0.4067	3.02	92.38
	(2, 38)			(1, 7)	278.43	1.0659	0.7604	9.68	83.49	
	2	[M3]	(10, 10)	(4, 4)	1048.87	0.3997	0.1993	5.45	130.89	
			(7, 13)	(1, 7)	552.20	0.6753	0.4093	3.24	91.64	
			(1, 19)	(1, 7)	285.57	1.0616	0.7592	9.68	83.03	
	4	[M3]	(5, 5)	(4, 4)	1077.64	0.3958	0.2107	6.69	129.29	
			(2, 8)	(1, 7)	536.55	0.7035	0.4485	4.14	86.75	
			(1, 9)	(1, 7)	416.41	0.8106	0.5451	5.70	83.43	
	7	1	[M3]	(20, 20)	(4, 3)	718.24	0.4591	0.2170	5.11	125.95
				(20, 20)	(3, 4)	717.51	0.4625	0.2185	4.20	116.01
				(21, 19)	(4, 3)	715.96	0.4588	0.2163	4.94	127.07
(19, 21)				(3, 4)	718.43	0.4592	0.2169	4.33	114.88	
(17, 23)				(1, 6)	403.68	0.7185	0.4130	2.84	87.85	
(2, 38)				(1, 6)	212.89	1.1138	0.7841	9.66	77.76	
2		[M3]	(10, 10)	(3, 4)	729.73	0.4581	0.2209	4.37	115.30	
			(10, 10)	(4, 3)	730.00	0.4585	0.2216	5.45	125.19	
			(11, 9)	(4, 3)	724.32	0.4548	0.2181	5.06	127.57	
			(9, 11)	(3, 4)	729.36	0.4579	0.2198	4.68	113.27	
			(8, 12)	(1, 6)	422.49	0.7094	0.4115	3.00	87.14	
			(1, 19)	(1, 6)	217.94	1.0937	0.7685	9.71	77.50	
4		[M3]	(5, 5)	(3, 4)	758.82	0.4528	0.2281	4.85	114.01	
			(5, 5)	(4, 3)	758.67	0.4516	0.2285	6.67	123.63	
			(3, 7)	(1, 6)	443.77	0.6994	0.4144	3.52	84.12	
			(1, 9)	(1, 6)	313.72	0.8549	0.5585	5.62	78.02	

Table 2.8: Simulation results for the optimal allocations for n -component series systems with Weibull distributed components when $N = 40$, $K = 2$, $(y_1, y_2) = (-0.5, 0.5)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3] (referring to Table 2.2)

R	n	Setting	(m_1, m_2)	(r_1, r_2)	[C1]	[C2]	[C3]	[C4]	[C5]	
					$ \bar{I} $	$V_{\beta_0} + V_{\beta_1} + V_{\sigma}$	V_{β_1}	TTE	TTT	
10	1	[M3]	(35, 5)	(5, 5)	285.51	1.0062	0.7845	10.24	83.28	
			(5, 35)	(5, 5)	285.98	1.0113	0.7886	27.85	83.35	
			(20, 20)	(5, 5)	206.13	0.7704	0.4441	3.43	83.26	
			(9, 31)	(1, 9)	71.43	2.5819	1.8470	1.98	52.51	
			(3, 37)	(1, 9)	78.56	2.4193	1.7791	4.26	52.57	
	2	[M3]	(15, 5)	(5, 5)	279.61	0.8232	0.5719	5.27	83.37	
			(5, 15)	(5, 5)	279.27	0.8186	0.5679	13.91	83.29	
			(10, 10)	(5, 5)	230.81	0.7456	0.4440	3.97	83.30	
			(4, 16)	(1, 9)	81.25	2.5073	1.8172	2.28	52.51	
			(2, 18)	(1, 9)	84.43	2.3894	1.7525	3.39	52.56	
	4	[M3]	(5, 5)	(5, 5)	332.58	0.6865	0.4472	7.07	83.31	
			(1, 9)	(1, 9)	119.72	2.3710	1.7815	4.35	52.53	
9	1	[M3]	(35, 5)	(4, 5)	201.90	1.2131	0.9515	10.23	71.17	
			(5, 35)	(5, 4)	202.80	1.2169	0.9561	27.86	78.89	
			(23, 17)	(5, 4)	137.10	0.8818	0.5009	2.95	78.74	
			(17, 23)	(4, 5)	137.45	0.8932	0.5081	3.19	71.14	
			(22, 18)	(5, 4)	137.03	0.8872	0.5041	3.09	78.83	
			(18, 22)	(4, 5)	137.18	0.8931	0.5072	3.00	70.96	
			(9, 31)	(1, 8)	52.46	2.6202	1.8394	1.85	48.03	
			(4, 36)	(1, 8)	57.49	2.4936	1.7940	3.26	48.13	
	2	[M3]	(15, 5)	(4, 5)	194.83	0.9892	0.6913	5.18	71.14	
			(5, 15)	(5, 4)	195.63	0.9868	0.6900	13.93	78.81	
			(11, 9)	(5, 4)	153.39	0.8682	0.5057	3.51	78.90	
			(9, 11)	(4, 5)	152.50	0.8672	0.5083	3.38	71.12	
			(4, 16)	(1, 8)	59.69	2.5683	1.8279	2.10	48.03	
			(1, 19)	(1, 8)	66.74	2.4508	1.8334	6.19	48.03	
			(5, 5)	(5, 4)	211.48	0.8179	0.5196	6.97	78.85	
	4	[M3]	(5, 5)	(4, 5)	211.97	0.8199	0.5216	4.32	71.33	
			(4, 6)	(4, 5)	209.15	0.8060	0.5099	6.39	71.21	
			(6, 4)	(5, 4)	208.12	0.8098	0.5159	4.64	78.76	
			(3, 7)	(2, 7)	150.76	1.2181	0.8290	3.61	55.68	
			(1, 9)	(1, 8)	80.95	2.4334	1.8008	3.65	47.99	
			(5, 5)	(4, 4)	134.98	1.3666	1.0711	9.36	66.75	
			(4, 36)	(4, 4)	133.62	1.3733	1.0767	25.26	66.48	
	8	1	[M3]	(20, 20)	(4, 4)	88.12	1.0245	0.5682	2.68	66.62
				(11, 29)	(1, 7)	36.24	2.7423	1.8876	1.61	43.53
(6, 34)				(1, 7)	38.92	2.5938	1.8018	2.26	43.52	
(16, 4)				(4, 4)	127.41	1.1295	0.7876	4.74	66.66	
(4, 16)				(4, 4)	128.61	1.1323	0.7905	12.7	66.67	
2		[M3]	(10, 10)	(4, 4)	98.04	1.0051	0.5673	2.97	66.74	
			(5, 15)	(1, 7)	41.27	2.6815	1.8575	1.79	43.66	
			(2, 18)	(1, 7)	44.39	2.5193	1.7974	3.22	43.51	
			(6, 4)	(4, 4)	133.62	0.9566	0.5945	3.41	66.61	
4		[M3]	(4, 6)	(4, 4)	134.32	0.9552	0.5918	6.35	66.59	
			(5, 5)	(4, 4)	126.45	0.9562	0.5762	3.98	66.67	
			(2, 8)	(1, 7)	55.59	2.6241	1.8771	2.41	43.58	
	(1, 9)		(1, 7)	55.47	2.4936	1.8072	3.40	43.57		
7	1	[M3]	(36, 4)	(3, 4)	85.38	1.7376	1.3734	9.34	54.47	
			(4, 36)	(4, 3)	85.38	1.7366	1.3722	25.42	62.27	
			(24, 16)	(4, 3)	50.19	1.2325	0.6734	2.23	62.22	
			(16, 24)	(3, 4)	50.31	1.2366	0.6786	2.48	54.39	
			(23, 17)	(4, 3)	50.00	1.2374	0.6776	2.32	62.17	
			(17, 23)	(3, 4)	50.21	1.2485	0.6852	2.34	54.42	
			(12, 28)	(1, 6)	23.54	2.8628	1.9125	1.45	39.06	
			(1, 39)	(1, 6)	35.26	2.8192	2.1767	12.14	39.02	
	2	[M3]	(16, 4)	(3, 4)	79.62	1.4346	1.0133	4.70	54.44	
			(4, 16)	(4, 3)	79.14	1.4372	1.0154	12.65	62.01	
			(12, 8)	(4, 3)	55.46	1.2153	0.6770	2.42	62.39	
			(8, 12)	(3, 4)	55.17	1.2176	0.6800	2.68	54.39	
			(11, 9)	(4, 3)	55.44	1.2163	0.6741	2.63	62.21	
			(9, 11)	(3, 4)	54.99	1.2245	0.6834	2.38	54.48	
			(6, 14)	(1, 6)	26.03	2.8711	1.9466	1.54	39.05	
	4	[M3]	(1, 19)	(1, 6)	33.47	2.6725	1.9665	6.15	39.01	
			(6, 4)	(3, 4)	79.00	1.2110	0.7490	2.78	54.46	
			(4, 6)	(4, 3)	78.89	1.2145	0.7547	6.35	62.18	
			(6, 4)	(4, 3)	69.84	1.1725	0.6879	2.99	62.18	
			(4, 6)	(3, 4)	69.81	1.1709	0.6863	3.35	54.41	
			(2, 8)	(1, 6)	34.26	2.6998	1.8703	2.03	39.07	
			(3, 7)	(1, 6)	35.80	2.7980	1.9513	2.00	39.02	

Table 2.10: Simulation results for the optimal allocations for n -component series systems with Weibull distributed components when $N = 40$, $K = 4$, $(y_1, y_2, y_3, y_4) = (-1.0, -0.5, 0.5, 1.0)$ by fixing $R = 7, 8, 9$ and 10 with $n = 1, 2$ and 4 under setting [M3] (referring to Table 2.6)

R	n	Setting	(m_1, m_2, m_3, m_4)	(r_1, r_2, r_3, r_4)	[C1] \bar{Z}	[C2] $V_{\beta_0} + V_{\beta_1} + V_{\sigma}$	[C3] V_{β_1}	[C4] \overline{TTE}	[C5] \overline{TTT}
10	1	[M3]	(4,32,0,4)	(4,2,0,4)	2361.27	0.2940	0.1393	41.87	115.52
			(4,0,32,4)	(4,0,2,4)	2360.58	0.2941	0.1391	41.87	100.13
			(5,0,31,4)	(5,0,1,4)	2378.05	0.2807	0.1250	45.92	115.83
			(4,31,0,5)	(4,1,0,5)	2377.35	0.2810	0.1252	41.87	106.06
			(15,10,0,15)	(5,0,0,5)	910.09	0.3786	0.1112	7.82	114.03
			(15,9,1,15)	(5,0,0,5)	910.09	0.3786	0.1112	7.82	114.03
	2	[M3]	(0,0,6,34)	(0,0,1,9)	18.34	14.3116	7.1323	1.23	28.95
			(5,0,11,4)	(5,0,1,4)	1778.92	0.3060	0.1243	22.94	115.70
			(4,11,0,5)	(4,1,0,5)	1780.97	0.3054	0.1241	20.95	106.10
			(5,10,0,5)	(5,0,0,5)	1464.14	0.2921	0.1119	22.94	113.95
			(0,0,3,17)	(0,0,1,9)	20.55	14.2585	7.1234	1.30	28.95
			(5,0,0,5)	(5,0,0,5)	1330.32	0.3510	0.1118	11.47	113.96
9	1	[M3]	(0,0,2,8)	(0,0,2,8)	53.06	6.0225	3.1281	2.35	30.71
			(0,0,1,9)	(0,0,1,9)	166.71	4.3198	2.1891	3.19	52.20
			(4,32,0,4)	(4,1,0,4)	1795.06	0.3147	0.1413	41.88	103.40
			(4,0,32,4)	(4,0,1,4)	1809.15	0.3143	0.1406	42.00	96.02
			(5,31,0,4)	(5,0,0,4)	1147.36	0.3295	0.1285	45.86	111.36
			(5,30,1,4)	(5,0,0,4)	1143.91	0.3279	0.1289	45.83	111.22
	2	[M3]	(0,0,7,33)	(0,0,1,8)	13.50	14.4535	7.1779	1.16	26.25
			(4,12,0,4)	(4,1,0,4)	1328.27	0.3397	0.1391	20.94	103.42
			(4,0,12,4)	(4,0,1,4)	1336.11	0.3429	0.1408	20.95	95.84
			(5,11,0,4)	(5,0,0,4)	1038.27	0.3298	0.1272	22.91	111.07
			(5,10,1,4)	(5,0,0,4)	1034.93	0.3276	0.1266	22.96	111.46
			(0,0,3,17)	(0,0,1,8)	15.18	14.2266	7.1072	1.24	26.25
8	1	[M3]	(5,1,0,4)	(5,0,0,4)	923.57	0.3962	0.1281	11.47	111.36
			(5,0,1,4)	(5,0,0,4)	925.65	0.3956	0.1284	11.47	111.30
			(0,0,1,9)	(0,0,1,8)	20.37	14.1392	7.1510	1.69	26.23
			(4,0,33,3)	(4,0,1,3)	1284.79	0.3652	0.1673	41.88	93.01
			(3,33,0,4)	(3,1,0,4)	1286.80	0.3630	0.1661	36.97	83.45
			(20,0,0,20)	(4,0,0,4)	352.47	0.5970	0.1409	4.37	91.35
	2	[M3]	(0,0,7,33)	(0,0,1,7)	9.54	14.5605	7.2431	1.15	23.49
			(4,0,13,3)	(4,0,1,3)	944.89	0.3987	0.1651	21.00	93.14
			(3,13,0,4)	(3,1,0,4)	939.40	0.4001	0.1648	18.39	83.02
			(4,12,0,4)	(4,0,0,4)	726.19	0.3714	0.1436	20.91	91.13
			(0,0,3,17)	(0,0,1,7)	10.64	14.3125	7.1578	1.21	23.53
			(4,2,0,4)	(4,0,0,4)	635.37	0.4457	0.1434	10.45	91.10
7	1	[M3]	(4,1,1,4)	(4,0,0,4)	640.17	0.4473	0.1434	10.49	91.40
			(4,0,2,4)	(4,0,0,4)	639.17	0.4443	0.1434	10.48	91.40
			(0,0,3,7)	(0,0,2,6)	23.75	6.5525	3.3617	1.41	25.27
			(0,0,1,9)	(0,0,1,7)	13.79	14.1451	7.1799	1.53	23.49
			(3,34,0,3)	(3,1,0,3)	897.69	0.4223	0.1946	36.83	80.50
			(3,0,34,3)	(3,0,1,3)	905.95	0.4249	0.1961	36.96	72.99
	2	[M3]	(4,33,0,3)	(4,0,0,3)	529.51	0.4324	0.1708	41.81	88.38
			(0,0,8,32)	(0,0,1,6)	6.18	14.8476	7.3706	1.10	20.75
			(3,14,0,3)	(3,1,0,3)	654.99	0.4668	0.1927	18.42	80.60
			(3,0,14,3)	(3,0,1,3)	651.45	0.4663	0.1943	18.42	72.91
			(4,13,0,3)	(4,0,0,3)	465.88	0.4396	0.1719	20.87	88.26
			(0,0,4,16)	(0,0,1,6)	6.69	15.0237	7.4531	1.10	20.79
4	[M3]	(3,4,0,3)	(3,1,0,3)	419.63	0.5675	0.1922	9.23	80.68	
		(3,0,4,3)	(3,0,1,3)	419.95	0.5657	0.1918	9.21	72.77	
		(4,3,0,3)	(4,0,0,3)	396.19	0.5243	0.1716	10.48	88.61	
		(0,0,2,8)	(0,0,1,6)	8.57	14.9864	7.4590	1.16	20.79	
		(3,4,0,3)	(3,1,0,3)	419.63	0.5675	0.1922	9.23	80.68	
		(3,0,4,3)	(3,0,1,3)	419.95	0.5657	0.1918	9.21	72.77	

From the simulation results presented in Tables 2.7 – 2.10, we observe that the simulated values corresponding to the objective functions of optimality criteria [C2], [C3], [C4], [C5] are close to the corresponding values presented in Tables 2.1, 2.2, 2.5 and 2.6, which verify the validity of the numerical results obtained by the methodologies developed in Sections 2.2

and 2.3. Although the simulated values of the determinant of average observed Fisher information and the expected Fisher information are not close (say, within 10%), experimental schemes that give similar determinants of the expected Fisher information matrices also give similar determinants of average observed Fisher information matrices. For example, in Table 2.6, when $K = 4$, $R = 7$ and $n = 2$, the allocations $(m_1, m_2, m_3, m_4) = (3, 14, 0, 3)$ with $(r_1, r_2, r_3, r_4) = (3, 1, 0, 3)$ and $(m_1, m_2, m_3, m_4) = (3, 0, 14, 3)$ with $(r_1, r_2, r_3, r_4) = (3, 0, 1, 3)$ give $|\mathbf{I}| = 751.61$, while in Table 2.10, these two allocations give $|\bar{\mathcal{I}}| = 654.99$ and 651.45 , respectively. On the other hand, from this simulation study, we notice that Monte Carlo simulation is an effective tool to verify the optimal experimental schemes derived from the asymptotic theory of MLEs.

2.6. Illustrative Example

In this section, we use the motivating example of furniture joints testing presented in Klos et al. (2018) to illustrate the methodologies developed here for planning a future experiment. In Klos et al. (2018), different furniture joints have rupture force $P_{max} = 134$ Newton, 116 Newton, and 60 Newton. Therefore, for a future reliability test of furniture joints, we consider three stress levels at 60, 116, and 134 (Newton), which yields the standardized stress levels as $y_1 = -1.12$, $y_2 = 0.33$ and $y_3 = 0.79$. Suppose the total number of furniture joints available for the future reliability test is $N = 180$ and we consider putting the furniture joints into an n -component series system (i.e., n joints connected in series) with $n = 12, 10, 5$, and 3 (i.e., 15, 18, 36 and 60 systems, respectively). Based on assuming the lifetimes of the joints are Weibull distributed (Klos et al., 2018) and consider the optimality criteria and settings described in Section 1.2, we determine the optimal experimental plans for different optimality criteria under different settings. These optimal experimental plans are presented in Table 2.11.

Based on the results in Table 2.11, if optimality criteria [C1] and [C2] are considered and setting [M3] is used, the experimental plans based on $n = 3$ are preferred over $n = 12, 10$

and 5. For example, when $R = 15$, the optimal values of $\text{tr}(\mathbf{I}^{-1})$ based on setting [M3] for $n = 12, 10, 5$ and 3 are $0.3537, 0.3246, 0.2338$ and 0.1950 , respectively. In practice, one of the issues of considering settings [M3] or [M2] is that those optimal experimental schemes may assign none or very few items/systems in the non-extreme stress levels, which makes it hard, if not impossible, to check the validity of the link function μ_k in Eq. (2.1) based on the observed experimental data. Therefore, the setting [M1] (i.e., assigning equal number of systems to each stress levels and fixed number of censored systems) can be considered instead of setting [M3] or [M2] in case that the validation of the link function is needed in a practical situation. If setting [M1] is considered, based on the results presented in Table 2.11, then the optimal experimental plans based on $n = 12$ are preferred over $n = 10, 5$ and 3 .

Table 2.11: (Continue)

R	n	Setting	(m_1, m_2, m_3)	(r_1, r_2, r_3)	[C1]	[C2]	[C3]	[C4]	[C5]	
					I	$\text{tr}(I^{-1})$	$\text{var}(\hat{\beta}_1)$	$E(TTE)$	$E(TTT)$	
9	12	[M1]	(5,5,5)	(3,3,3)	690	0.9286	0.1677	3168	259074	
		[M2]	(5,5,5)	(5,0,4)	1033	0.6731	0.1253	5190	230066	
		[M3]	(5,5,5)	(4,0,5)	1033	0.6472	0.1253	9235	271412	
			(5,5,5)	(5,2,2)	825	0.9206	0.1802	1820	194276	
			(5,5,5)	(5,4,0)	595	0.8235	0.2174	3277	158486	
			(4,7,4)	(4,1,4)	1222	0.5922	0.1338	8426	253517	
			(5,6,4)	(5,0,4)	1080	0.5983	0.1234	8426	230066	
			(4,6,5)	(4,0,5)	1080	0.5897	0.1234	9235	271412	
		(11,4,0)	(8,1,0)	213	2.0787	0.5668	711	88132		
		10	[M1]	(6,6,6)	(3,3,3)	674	0.9550	0.1677	2993	259074
			[M2]	(6,6,6)	(4,1,4)	966	0.7794	0.1335	4611	253517
			[M3]	(6,6,6)	(5,0,4)	954	0.7306	0.1249	4611	230066
	(6,6,6)			(4,0,5)	954	0.7053	0.1249	7037	271412	
	(6,6,6)			(3,0,6)	923	0.6922	0.1514	11891	312759	
	(6,6,6)			(6,2,1)	685	1.0665	0.2452	1761	152930	
	(6,6,6)	(6,3,0)		532	1.0013	0.2627	1889	135035		
	(4,10,4)	(4,1,4)		1311	0.5370	0.1340	10111	253517		
	5	[M1]	(12,12,12)	(3,3,3)	643	1.0131	0.1677	2662	259074	
		[M2]	(12,12,12)	(4,1,4)	890	0.8571	0.1334	3740	253517	
		[M3]	(12,12,12)	(5,0,4)	848	0.8367	0.1246	3740	230066	
			(12,12,12)	(4,0,5)	848	0.8119	0.1246	4954	271412	
			(12,12,12)	(6,2,1)	583	1.2105	0.2383	1068	152930	
			(12,12,12)	(8,1,0)	208	2.2062	0.6747	1466	88132	
	(4,28,4)		(4,1,4)	1649	0.3905	0.1346	20222	253517		
(5,27,4)	(5,0,4)		1080	0.4062	0.1234	20222	230066			
3	[M1]	(4,27,5)	(4,0,5)	1080	0.3976	0.1234	22163	271412		
		(4,28,4)	(4,1,4)	1649	0.3905	0.1346	20222	253517		
		(25,11,0)	(8,1,0)	189	2.2724	0.5752	557	88132		
		(20,20,20)	(3,3,3)	633	1.0338	0.1677	2559	259074		
		(20,20,20)	(4,1,4)	868	0.8836	0.1334	3511	253517		
		(20,20,20)	(5,0,4)	820	0.8716	0.1245	3511	230066		
	[M2]	(20,20,20)	(4,0,5)	820	0.8469	0.1245	4522	271412		
		(20,20,20)	(7,1,1)	484	1.4215	0.3019	1000	129479		
		(20,20,20)	(8,1,0)	193	2.2889	0.6723	1185	88132		
		(4,53,3)	(4,2,3)	1937	0.3745	0.1533	29659	235622		
		(5,51,4)	(5,0,4)	1080	0.3419	0.1234	33703	230066		
		(4,51,5)	(4,0,5)	1080	0.3333	0.1234	36939	271412		
[M3]	(4,52,4)	(4,1,4)	1912	0.3290	0.1350	33703	253517			
	(40,20,0)	(8,1,0)	185	2.3499	0.5848	527	88132			
	(59,1,0)	(8,1,0)	182	1.6026	0.7731	10213	88132			

Since the expected Fisher information matrix depends on the underlying lifetime distribution of the components, consequently the optimal experimental scheme also depends on the unknown underlying lifetime distribution. For this reason, it is desired to have an experimental design that is not sensitive to the model specification. It would then assure the practitioners that misspecification of the assumed lifetime distribution would not result in unacceptable variation in the results of the experiment. For this reason, in Table 2.12, we presented the optimal experimental plans for different optimality criteria under different settings when lognormal distribution is assumed to be the lifetime distribution of the joints. To facilitate a sensitivity analysis on the model misspecification, we define the relative efficiency (RE) as follows. Suppose O_A is the value of the objective function corresponding to optimality criteria [C*] (where $*$ = 1, 2, 3, 4, 5) based on the optimal plan obtained under the assumed model, and O_T is the value of the objective function corresponding to optimal-

ity criteria [C*] based on the optimal plan obtained under the true model. The RE of the optimal experimental scheme under the assumed model relative to the optimal experimental scheme under the true model is

$$\text{RE}_{[C^*]}(Assumed, True) = \frac{O_A}{O_T}.$$

Under the optimal criterion [C1], the values of RE will be larger than or equal to 1. Under the optimality criteria [C2]–[C5], the values of RE will be smaller than or equal to 1. The REs when the assumed model is Weibull and the true model is lognormal under setting [M2] are presented in Table 2.13, which provide the information about the deviation in the values of the objective functions if we use the optimal experimental scheme obtained under the assumed Weibull distribution when the true underlying lifetime distribution of the joints is lognormal. From the results in Table 2.13, except for optimal criterion [C4], misspecifying the lifetime distribution as Weibull when the true underlying distribution is lognormal does not affect the efficiency of the optimal experimental plans. In fact, the optimal experimental plans under the Weibull and the lognormal distributions are the same in most of the settings considered here.

Table 2.12: Optimal allocations for n -component series systems with lognormal distributed components when $N = 180$, $K = 3$, $(y_1, y_2, y_3) = (-1.12, 0.33, 0.79)$ by fixing $R = 15, 12$, and 9 with $n = 12, 10, 5$ and 3

R	n	Setting	(m_1, m_2, m_3)	(r_1, r_2, r_3)	[C1]	[C2]	[C3]	[C4]	[C5]	
					[I]	$\text{tr}(I^{-1})$	$\text{var}(\hat{\beta}_1)$	$E(TTE)$	$E(TTT)$	
15	12	[M1-M2] [M3]	(5,5,5)	(5,5,5)	48088	0.1545	0.0298	18720	1181152	
			(7,1,7)	(7,1,7)	62901	0.1479	0.0228	20343	1150699	
			(8,0,7)	(8,0,7)	49947	0.1900	0.0208	20343	1111600	
			(7,0,8)	(7,0,8)	49947	0.1853	0.0208	20987	1369048	
			(12,3,0)	(12,3,0)	3594	0.9702	0.0633	10265	557811	
	10	[M1] [M2]	(6,6,6)	(5,5,5)	47345	0.1629	0.0290	15901	1196040	
			(6,6,6)	(6,3,6)	53441	0.1511	0.0273	22075	1175813	
		[M3]	(6,6,6)	(6,5,4)	48433	0.1613	0.0290	12515	1137450	
			(6,6,6)	(6,6,3)	47734	0.1570	0.0306	13936	1099837	
			(8,3,7)	(7,1,7)	61401	0.1477	0.0233	22946	1125703	
			(9,0,9)	(7,0,8)	27546	0.3347	0.0190	18352	1346640	
			(9,0,9)	(8,0,7)	27546	0.3380	0.0190	15176	1292532	
			(7,3,8)	(7,0,8)	57303	0.1412	0.0234	23702	1105259	
			(14,4,0)	(14,1,0)	2210	1.3146	0.1748	3981	469090	
			(14,1,3)	(14,1,0)	1375	1.0146	0.1641	7726	389384	
	5	[M1] [M2]	(12,12,12)	(5,5,5)	46391	0.1792	0.0276	13063	1226938	
			(12,12,12)	(7,1,7)	57153	0.1501	0.0242	17176	1143462	
		[M3]	(12,12,12)	(8,0,7)	46879	0.1518	0.0240	17176	953726	
(12,12,12)			(7,0,8)	46879	0.1499	0.0240	19661	1006638		
(12,12,12)			(5,1,9)	54887	0.1474	0.0261	22673	1246102		
(12,12,12)			(11,3,1)	35813	0.2039	0.0439	5941	809904		
(12,12,12)			(12,3,0)	21405	0.2294	0.0621	6613	503778		
(17,2,17)			(7,2,6)	61750	0.1667	0.0217	15936	1163835		
(19,3,14)			(1,0,14)	2758	3.1160	0.0159	46463	1571340		
(14,3,19)			(14,0,1)	2758	3.1102	0.0159	18503	1951930		
(7,21,8)			(7,0,8)	32077	0.1279	0.0315	39995	846371		
(21,15,0)			(14,1,0)	8827	0.5135	0.1184	3035	467656		
(14,1,21)			(14,1,0)	4624	0.5429	0.2183	11834	253310		
3			[M1] [M2]	(20,20,20)	(5,5,5)	46165	0.1847	0.0272	12440	1237644
				(20,20,20)	(7,1,7)	56827	0.1565	0.0236	15601	1155285
	[M3]	(20,20,20)	(7,0,8)	46486	0.1581	0.0234	17251	1020698		
		(20,20,20)	(8,0,7)	46486	0.1600	0.0234	15601	965880		
		(20,20,20)	(6,1,8)	56256	0.1544	0.0240	17251	1209718		
		(20,20,20)	(14,1,0)	9943	0.3964	0.1225	4478	385037		
		(28,4,28)	(6,4,5)	63933	0.1509	0.0236	31559	1164100		
		(22,9,29)	(13,1,1)	6593	1.4205	0.0162	18562	1924941		
		(7,45,8)	(7,0,8)	19887	0.1279	0.0402	63647	737328		
		(31,28,1)	(14,1,0)	8442	0.5320	0.1225	2904	471229		
		(14,1,45)	(14,1,0)	2866	0.6580	0.2788	17185	220678		

Table 2.13: Relative efficiency of the optimal experimental plans obtained when the assumed distribution is Weibull and the true distribution is lognormal for n -component series systems with $N = 180$, $K = 3$, $(y_1, y_2, y_3) = (-1.12, 0.33, 0.79)$ by fixing $R = 15, 12, 9$ and 42 with $n = 12, 10, 5$ and 3 under setting [M2] (referring to Table 2.11)

R	n	Optimal Criteria	Under the assumed model (Weibull)			Under the assumed model (Lognormal)			RE
			(m_1, m_2, m_3)	(r_1, r_2, r_3)	O_A	(m_1, m_2, m_3)	(r_1, r_2, r_3)	O_T	
15	12	C1	(5,5,5)	(5,5,5)	48088	(5,5,5)	(5,5,5)	48088	1.0000
		C2	(5,5,5)	(5,5,5)	0.1545	(5,5,5)	(5,5,5)	0.1545	1.0000
		C3	(5,5,5)	(5,5,5)	0.0298	(5,5,5)	(5,5,5)	0.0298	1.0000
		C4	(5,5,5)	(5,5,5)	18720	(5,5,5)	(5,5,5)	18720	1.0000
		C5	(5,5,5)	(5,5,5)	1181152	(5,5,5)	(5,5,5)	1181152	1.0000
	10	C1	(6,6,6)	(6,3,6)	53441	(6,6,6)	(6,3,6)	53441	1.0000
		C2	(6,6,6)	(6,3,6)	0.1511	(6,6,6)	(6,3,6)	0.1511	1.0000
		C3	(6,6,6)	(6,3,6)	0.0273	(6,6,6)	(6,3,6)	0.0273	1.0000
		C4	(6,6,6)	(6,5,4)	12515	(6,6,6)	(6,5,4)	12515	1.0000
		C5	(6,6,6)	(6,6,3)	1099837	(6,6,6)	(6,6,3)	1099837	1.0000
	5	C1	(12,12,12)	(7,1,7)	57153	(12,12,12)	(7,1,7)	57153	1.0000
		C2	(12,12,12)	(6,0,9)	0.1490	(12,12,12)	(5,1,9)	0.1474	1.0110
		C3	(12,12,12)	(7,0,8)	0.0240	(12,12,12)	(7,0,8)	0.0240	1.0000
		C4	(12,12,12)	(10,3,2)	7514	(12,12,12)	(11,3,1)	5941	1.2646
		C5	(12,12,12)	(12,3,0)	503778	(12,12,12)	(12,3,0)	503778	1.0000
	3	C1	(20,20,20)	(7,1,7)	56827	(20,20,20)	(7,1,7)	56827	1.0000
		C2	(20,20,20)	(7,0,8)	0.1581	(20,20,20)	(6,1,8)	0.1544	1.0239
		C3	(20,20,20)	(7,0,8)	0.0234	(20,20,20)	(7,0,8)	0.0234	1.0000
		C4	(20,20,20)	(10,3,2)	7452	(20,20,20)	(14,1,0)	4478	1.6640
		C5	(20,20,20)	(14,1,0)	385037	(20,20,20)	(14,1,0)	385037	1.0000
12	12	C1	(5,5,5)	(5,2,5)	33435	(5,5,5)	(5,2,5)	33435	1.0000
		C2	(5,5,5)	(5,2,5)	0.1923	(5,5,5)	(5,2,5)	0.1923	1.0000
		C3	(5,5,5)	(5,2,5)	0.0307	(5,5,5)	(5,2,5)	0.0307	1.0000
		C4	(5,5,5)	(5,4,3)	10244	(5,5,5)	(5,4,3)	10244	1.0000
		C5	(5,5,5)	(5,5,2)	953052	(5,5,5)	(5,5,2)	953052	1.0000
	10	C1	(6,6,6)	(5,1,6)	35053	(6,6,6)	(5,1,6)	35053	1.0000
		C2	(6,6,6)	(6,0,6)	0.1769	(6,6,6)	(6,0,6)	0.1769	1.0000
		C3	(6,6,6)	(6,0,6)	0.0291	(6,6,6)	(6,0,6)	0.0291	1.0000
		C4	(6,6,6)	(6,4,2)	7900	(6,6,6)	(6,4,2)	7900	1.0000
		C5	(6,6,6)	(6,6,0)	571983	(6,6,6)	(6,6,0)	571983	1.0000
	5	C1	(12,12,12)	(5,1,6)	34182	(12,12,12)	(5,1,6)	34182	1.0000
		C2	(12,12,12)	(5,0,7)	0.2014	(12,12,12)	(4,1,7)	0.2001	1.0066
		C3	(12,12,12)	(6,0,6)	0.0270	(12,12,12)	(6,0,6)	0.0270	1.0000
		C4	(12,12,12)	(8,3,1)	5941	(12,12,12)	(10,2,0)	4743	1.2526
		C5	(12,12,12)	(11,1,0)	356346	(12,12,12)	(11,1,0)	356346	1.0000
	3	C1	(20,20,20)	(5,1,6)	33988	(20,20,20)	(5,1,6)	33988	1.0000
		C2	(20,20,20)	(5,0,7)	0.2102	(20,20,20)	(4,1,7)	0.2072	1.0144
		C3	(20,20,20)	(6,0,6)	0.0265	(20,20,20)	(6,0,6)	0.0265	1.0000
		C4	(20,20,20)	(9,2,1)	5252	(20,20,20)	(11,1,0)	3380	1.5538
		C5	(20,20,20)	(11,1,0)	358944	(20,20,20)	(11,1,0)	358944	1.0000
9	12	C1	(5,5,5)	(5,0,4)	15283	(5,5,5)	(4,1,4)	17801	0.8585
		C2	(5,5,5)	(4,0,5)	0.2562	(5,5,5)	(4,0,5)	0.2562	1.0000
		C3	(5,5,5)	(4,0,5)	0.0346	(5,5,5)	(5,0,4)	0.0346	1.0000
		C4	(5,5,5)	(5,2,2)	7764	(5,5,5)	(5,3,1)	6467	1.2006
		C5	(5,5,5)	(5,4,0)	476560	(5,5,5)	(5,4,0)	476560	1.0000
	10	C1	(6,6,6)	(4,1,4)	17681	(6,6,6)	(4,1,4)	17681	1.0000
		C2	(6,6,6)	(3,0,6)	0.2628	(6,6,6)	(3,0,6)	0.2628	1.0000
		C3	(6,6,6)	(4,0,5)	0.0339	(6,6,6)	(4,0,5)	0.0339	1.0000
		C4	(6,6,6)	(6,2,1)	5252	(6,6,6)	(6,2,1)	5252	1.0000
		C5	(6,6,6)	(6,3,0)	441903	(6,6,6)	(6,3,0)	441903	1.0000
	5	C1	(12,12,12)	(4,1,4)	17472	(12,12,12)	(4,1,4)	17472	1.0000
		C2	(12,12,12)	(4,0,5)	0.2940	(12,12,12)	(2,6,1)	0.2914	1.0091
		C3	(12,12,12)	(5,0,4)	0.0326	(12,12,12)	(4,0,5)	0.0326	1.0000
		C4	(12,12,12)	(6,2,1)	5252	(12,12,12)	(8,1,0)	3316	1.5841
		C5	(12,12,12)	(8,1,0)	329957	(12,12,12)	(8,1,0)	329957	1.0000
	3	C1	(20,20,20)	(4,1,4)	17412	(20,20,20)	(4,1,4)	17412	1.0000
		C2	(20,20,20)	(4,0,5)	0.3026	(20,20,20)	(2,6,1)	0.2991	1.0115
		C3	(20,20,20)	(5,0,4)	0.0322	(20,20,20)	(4,0,5)	0.0322	1.0000
		C4	(20,20,20)	(7,1,1)	5252	(20,20,20)	(8,1,0)	3316	1.5841
		C5	(20,20,20)	(8,1,0)	331813	(20,20,20)	(8,1,0)	331813	1.0000

2.7. Concluding Remarks

In this article, we discuss the optimal experimental planning for multi-level stress experiments with Type-II censored when the experimental units can be put into coherent systems for the life testing experiments. The component lifetime distributions are assumed to be in the log-location-scale family of distributions, a general class of distributions that includes some commonly used lifetime distributions, such as the Weibull and the lognormal distributions. The formulations required for optimal experimental planning are presented in terms of system signatures for different optimality criteria. Motivated by the furniture joints experiment, the proposed methodologies are illustrated by the special case that the experimental units are put into series systems for the life testing experiment. The numerical results for two- and four-stress levels experimental planning are provided and these results are verified by a Monte Carlo simulation study.

We have shown that considering the use of systems formed by the test units in a multi-level stress experiment gives another level of flexibility in planning an experiment with Type-II censoring and gains in efficiency in some situations. To demonstrate the usefulness of the proposed methodologies, the proposed methods are applied to plan a reliability test of furniture joints, and a sensitivity analysis for misspecification of the underlying lifetime distribution is provided.

Overall, although using systems in multi-level constant-stress experiments with Type-II censoring does not always give advantages over using individual components when using systems is superior to using individual components, it always gains efficiency in estimation and gives shorter expected total time for all the components spent on the experiment. For future studies, considering some different optimality criteria that take into account the time of the experiment, efficiency in the estimation of the model parameters, and the cost of failing a component simultaneously, will be of interest. On the other hand, in addition to series systems, the formulations presented in Section 2.2 can be applied to experimental

planning for different kinds of coherent systems. It will be an interesting research direction to compare the performance of optimal experimental planning based on different coherent systems. We study these research topics and hope to report the results in a future paper.

CHAPTER 3

Optimal Experimental Planning for Progressively Type-II Censored Experiments based on Coherent Systems

3.1. Introduction

As mentioned in Chapter 1, the idea of optimal experimental planning of life testing procedures involving systems has been discussed in the literature. This chapter considers the progressively Type-II right-censored life testing experiment, which can be described as follows. Consider a life testing experiment in which m units are placed on the test simultaneously. At the time of the first failure, R_1 experimental units are randomly removed from the remaining $(m-1)$ surviving units. At the second failure, R_2 experimental units are randomly removed from the remaining $(m-R_1-1)$ surviving units. The life testing experiment continues similarly until the r -th failure, at which time, all remaining $(m-R_1-R_2-\dots-R_{r-1}-1)$ surviving units are removed. The progressive censoring scheme (R_1, R_2, \dots, R_r) are fixed prior to the study. For progressively Type-II censored life testing experiments, [Wu and Kus \(2009\)](#), [Hermanns and Cramer \(2017\)](#) and [Hermanns and Cramer \(2018\)](#) used the series systems, the parallel systems, and the l -out-of- n systems, respectively, for the censored life testing experiments and developed the related statistical inference. The problem of optimal progressive censoring has been studied in the literature after people realized that progressive Type-II censoring is a versatile censoring scheme in which there is flexibility in the choice of (R_1, R_2, \dots, R_r) . For example, [Balakrishnan and Aggarwala \(2000\)](#) defined the objective functions to find the optimal progressive censoring plans based on the variances and covariance of best linear unbiased estimators (BLUEs) of the parameters in location-scale distribution, and implemented analytical and computational methods to calculate these func-

tions for the location-scale family of distributions where moments of the usual order statistics are available. [Ng et al. \(2004\)](#) studied the optimal progressive censoring plans when the experimental units follow the Weibull distribution. [Burkschat et al. \(2006\)](#) determined the optimal progressive Type-II censoring schemes for exponential, uniform, and Pareto distributions. They used the variance of the BLUE for the one-parameter models. For the two-parameter models, two optimality criteria, minimizing the trace and the determinant of the variance-covariance matrix of the BLUEs, are utilized. [Burkschat et al. \(2007\)](#) obtained optimal censoring schemes by applying the p -criteria from experimental design to the variance-covariance matrix of the BLUEs. They also discussed the monotonicity properties of the trace and determinant of the variance-covariance matrix of the maximum likelihood estimators (MLEs) with respect to the sample size and the initial number of experimental units. [Dahmen et al. \(2012\)](#) established a representation of the Fisher information matrix of the MLEs in terms of the hazard rate of the baseline distribution and identified the A - and D -optimal progressively Type-II censoring plans when the experimental units follow various distributions. [Salemi et al. \(2019\)](#) explored the relationship between the missing information matrix and the Fisher information matrix, and presented a straightforward expression and method for determining the optimal progressive censoring plan from a specific class of one-step censoring plans under the A -optimality and D -optimality criteria for models with multiple parameters. In [Bhattacharya and Balakrishnan \(2023\)](#), the authors proposed a probabilistic approach to determine the optimal progressive censoring schemes by defining a probability structure on the set of feasible solutions, allowing for the computation of an updated solution. There have also been studies involving optimal censoring schemes based on non-parametric statistical inference. For instance, [Balakrishnan and Han \(2007\)](#) investigated the optimal censoring schemes for non-parametric confidence intervals of population quantiles in the context of progressive Type-II right censoring. The optimization process for optimal censoring schemes is independent of the observed sample values.

Although statistical inference for system-level progressively censored data and optimal progressive censoring schemes have been studied in the literature, a comprehensive study of the optimal experimental planning for progressively Type-II censored experiments based on coherent systems has not been done to our knowledge. Therefore, this chapter aims to develop the algorithm to obtain the optimal progressive Type-II censoring schemes when the components can be put into coherent systems for the life testing experiment.

In this chapter, we study the problem of optimal experimental planning for progressively Type-II censored experiments when coherent systems are used. We compute the expected Fisher information and the asymptotic variance-covariance matrix of the maximum likelihood estimates (MLEs) based on a progressively Type-II censored sample with coherent systems when the component lifetimes follow a statistical distribution in the log-location-scale family of distributions. Based on different optimality criteria, we use the expected Fisher information and the asymptotic variance-covariance matrix to determine the optimal progressive censoring plans. Optimal progressive censoring schemes based on different coherent systems are compared.

This chapter is organized as follows. In Section 3.2, we describe the model for progressively Type-II censored experiments with coherent systems and different optimality criteria. Specifically, we review the notation of the system signature and the location-scale family of distributions. Then, in Section 3.3, MLEs of the model parameters and the corresponding Fisher information matrix for the location-scale family of distributions are derived. Different optimality criteria, including some commonly used optimality criteria including the D -optimality, the A -optimality, the V -optimality, and a comprehensive criterion, and different settings for optimal experimental planning are discussed in Section 3.4. In Section 3.5, we consider multiple cases with various types of systems being used in the experiments with progressively censored samples. In Section 3.6, the computational formulas for lognormal and Weibull distributed components are used to illustrate the methodology developed in this

chapter. Numerical illustrations with n up to 4 or 5 are used to demonstrate the advantages and disadvantages. In Section 3.7, a practical example of insulating fluids testing is used to illustrate the methodologies for planning a future progressively Type-II censored experiment. Finally, some concluding remarks and discussions about future research directions are provided in Section 3.8.

3.2. Progressively Type-II Censored Experiments with Coherent Systems

Suppose we have $N = m \times n$ components available for a progressively Type-II censored experiment, and these components can be placed as m coherent n -component systems with system signature $\mathbf{s} = (s_1, s_2, \dots, s_n)$ for the life testing experiment, we plan to fail $r \leq m$ systems (i.e., r is the effective sample size and m is the total sample size in terms of systems) with progressive censoring scheme $\mathbf{R} = (R_1, R_2, \dots, R_r)$. Following the notations defined in Chapter 1, we use X_1, X_2, \dots, X_n to denote the independent and identically distributed (i.i.d.) component lifetimes, and T_1, T_2, \dots, T_m to denote the m system lifetimes. For the special case when $n = 1$, the life testing experiment is done at the component level in which $m = N$ components are placed on the life test, and the test is terminated as soon as the r -th component failure with progressive censoring scheme $\mathbf{R} = (R_1, R_2, \dots, R_r)$ is observed.

We further assume the component lifetimes follow a log-location-scale distribution; hence, the log-transformed component lifetimes follow a location-scale family distribution with location parameter $\mu \in (-\infty, \infty)$ and scale parameter $\sigma \in (0, \infty)$. Suppose $f_U(\cdot; \boldsymbol{\theta})$, $F_U(\cdot; \boldsymbol{\theta})$ and $\bar{F}_U(\cdot; \boldsymbol{\theta})$ are the probability density function (PDF), cumulative distribution function (CDF) and survival function (SF) of the log-lifetimes of components in the systems (i.e.,

$U = \ln X$) with parameter vector $\boldsymbol{\theta} = (\mu, \sigma)$, then we have

$$\begin{aligned} f_U(u; \mu, \sigma) &= \frac{1}{\sigma} f^* \left(\frac{u - \mu}{\sigma} \right), \\ F_U(u; \mu, \sigma) &= F^* \left(\frac{u - \mu}{\sigma} \right), \\ \bar{F}_U(u; \mu, \sigma) &= 1 - F^* \left(\frac{u - \mu}{\sigma} \right), \end{aligned}$$

where $-\infty < \mu < \infty$ is the location parameter and $\sigma > 0$ is the scale parameter, $f^*(\cdot)$ and $F^*(\cdot)$ are the PDF and CDF of the standardized distribution (i.e., $\mu = 0$ and $\sigma = 1$) of the corresponding distribution in the location-scale family. The PDF and SF of the log-transformed system lifetimes (i.e., $V = \ln T$) can be expressed in terms of the PDF, CDF, and SF of the log-transformed component lifetimes as

$$\begin{aligned} f_V(v; \boldsymbol{\theta}) &= \sum_{i=1}^n s_i \binom{n}{i} i f_U(v; \boldsymbol{\theta}) [F_U(v; \boldsymbol{\theta})]^{i-1} [\bar{F}_U(v; \boldsymbol{\theta})]^{n-i} \\ &= \frac{1}{\sigma} f^* \left(\frac{v - \mu}{\sigma} \right) \sum_{i=1}^n s_i \binom{n}{i} i \left[F^* \left(\frac{v - \mu}{\sigma} \right) \right]^{i-1} \left[\bar{F}^* \left(\frac{v - \mu}{\sigma} \right) \right]^{n-i} \\ &= \frac{1}{\sigma} f^*(z) \sum_{i=1}^n s_i \binom{n}{i} i [F^*(z)]^{i-1} [\bar{F}^*(z)]^{n-i}, \end{aligned} \quad (3.1)$$

and

$$\begin{aligned} \bar{F}_V(v; \boldsymbol{\theta}) &= \sum_{i=1}^n s_i \sum_{j=0}^{i-1} \binom{n}{j} [F_U(v; \boldsymbol{\theta})]^j [\bar{F}_U(v; \boldsymbol{\theta})]^{n-j} \\ &= \sum_{i=1}^n s_i \sum_{j=0}^{i-1} \binom{n}{j} \left[F^* \left(\frac{v - \mu}{\sigma} \right) \right]^j \left[\bar{F}^* \left(\frac{v - \mu}{\sigma} \right) \right]^{n-j} \\ &= \sum_{i=1}^n s_i \sum_{j=0}^{i-1} \binom{n}{j} [F^*(z)]^j [\bar{F}^*(z)]^{n-j}, \end{aligned} \quad (3.2)$$

where

$$z = \frac{v - \mu}{\sigma}.$$

3.3. Maximum Likelihood Estimation

3.3.1. Maximum likelihood estimation of model parameters

To obtain a progressively Type-II censored sample with the progressive censoring scheme $\mathbf{R} = (R_1, R_2, \dots, R_r)$, R_j operating systems are randomly removed from the life test when the j -th failure is observed, $\ell = 1, 2, \dots, r$. Thus, the pre-fixed censoring scheme (R_1, \dots, R_r) and the pre-fixed number of failures r satisfy the constraint $\sum_{\ell=1}^r R_\ell + r = m$, and the log-transformed observed progressively Type-II censored sample with coherent systems is denoted as $v_{1:r:m} < v_{2:r:m} < \dots < v_{r:r:m}$. The likelihood function and the log-likelihood function based on the observed system-level progressively Type-II censored sample can be expressed as

$$L(\boldsymbol{\theta}) = m(m - R_1 - 1) \dots (m - R_1 - R_2 - \dots - R_{r-1} - r + 1) \times \prod_{\ell=1}^r f_V(v_{\ell:r:m}; \boldsymbol{\theta}) [\bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})]^{R_\ell}, \quad v_{1:r:m} < v_{2:r:m} < \dots < v_{r:r:m}, \quad (3.3)$$

and

$$l(\boldsymbol{\theta}) = C + \sum_{\ell=1}^r \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) + \sum_{\ell=1}^r R_\ell \ln [\bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})], \quad v_{1:r:m} < v_{2:r:m} < \dots < v_{r:r:m}, \quad (3.4)$$

respectively, where $C = \ln[m(m - R_1 - 1) \dots (m - R_1 - R_2 - \dots - R_{r-1} - r + 1)]$ is a constant that does not depend on the parameter vector $\boldsymbol{\theta}$. We can obtain the likelihood equations by taking the first partial derivatives of the log-likelihood function and setting them to zero,

i.e.,

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \frac{1}{f_V(v_{\ell:r:m}; \boldsymbol{\theta})} \frac{\partial f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} \\ &+ \sum_{\ell=1}^r \frac{R_{\ell}}{\bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})} \frac{\partial \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} = 0, \end{aligned} \quad (3.5)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \frac{1}{f_V(v_{\ell:r:m}; \boldsymbol{\theta})} \frac{\partial f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} \\ &+ \sum_{\ell=1}^r \frac{R_{\ell}}{\bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})} \frac{\partial \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} = 0. \end{aligned} \quad (3.6)$$

The MLEs of the parameters μ and σ , denoted as $\hat{\mu}$ and $\hat{\sigma}$, respectively, can be obtained by solving Eqs. (3.5) and (3.6) simultaneously.

Following Eqs. (2.9)–(2.14), the first derivatives of the SF and the PDF of the log-transformed system lifetime with respect to the parameters μ and σ can be expressed in terms of the log-transformed component lifetime distributions as

$$\begin{aligned} \frac{\partial \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \left[-\frac{1}{\sigma} f^*(z_{\ell:r:m}) \right] \sum_{i=1}^n s_i \sum_j^{i-1} \binom{n}{j} \left[j [F^*(z_{\ell:r:m})]^{j-1} [\bar{F}^*(z_{\ell:r:m})]^{n-j} \right. \\ &\quad \left. - [F^*(z_{\ell:r:m})]^j (n-j) [\bar{F}^*(z_{\ell:r:m})]^{n-j-1} \right], \end{aligned} \quad (3.7)$$

$$\begin{aligned} \frac{\partial \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= \left[-\frac{z_{\ell:r:m}}{\sigma} f^*(z_{\ell:r:m}) \right] \sum_{i=1}^n s_i \sum_j^{i-1} \binom{n}{j} \left[j [F^*(z_{\ell:r:m})]^{j-1} [\bar{F}^*(z_{\ell:r:m})]^{n-j} \right. \\ &\quad \left. - [F^*(z_{\ell:r:m})]^j (n-j) [\bar{F}^*(z_{\ell:r:m})]^{n-j-1} \right], \end{aligned} \quad (3.8)$$

and

$$\begin{aligned}
\frac{\partial f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{1}{\sigma} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} \sum_{i=1}^n s_i \binom{n}{i} i [F^*(z_{\ell:r:m})]^{i-1} [\bar{F}^*(z_{\ell:r:m})]^{n-i} \\
&\quad - \frac{1}{\sigma^2} (f^*(z_{\ell:r:m}))^2 \sum_{i=1}^n s_i \binom{n}{i} i \left[(i-1) [F^*(z_{\ell:r:m})]^{i-2} [\bar{F}^*(z_{\ell:r:m})]^{n-i} \right. \\
&\quad \left. - [F^*(z_{\ell:r:m})]^{i-1} (n-i) [\bar{F}^*(z_{\ell:r:m})]^{n-i-1} \right], \tag{3.9}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= \left[-\frac{1}{\sigma^2} f^*(z_{\ell:r:m}) + \frac{1}{\sigma} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} \right] \\
&\quad \times \sum_{i=1}^k s_i \binom{n}{i} i [F^*(z_{\ell:r:m})]^{i-1} [\bar{F}^*(z_{\ell:r:m})]^{n-i} \\
&\quad - \frac{z_{\ell:r:m}}{\sigma^2} (f^*(z_{\ell:r:m}))^2 \sum_{i=1}^n s_i \binom{n}{i} i \left[(i-1) [F^*(z_{\ell:r:m})]^{i-2} [\bar{F}^*(z_{\ell:r:m})]^{n-i} \right. \\
&\quad \left. - [F^*(z_{\ell:r:m})]^{i-1} (n-i) [\bar{F}^*(z_{\ell:r:m})]^{n-i-1} \right]. \tag{3.10}
\end{aligned}$$

3.3.2. Fisher information and asymptotic variance-covariance matrices

The expected Fisher information matrix of the parameter vector $\boldsymbol{\theta} = (\mu, \sigma)$ can be expressed as

$$\mathbf{I}(\mu, \sigma) = - \begin{bmatrix} E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} \right) \\ E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma \partial \mu} \right) & E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} \right) \end{bmatrix}. \tag{3.11}$$

The second partial derivatives of the log-likelihood function involved in the Fisher information matrix in Eq. (3.11) can be expressed in terms of the PDF and CDF of the log-transformed component lifetimes as described in Section 3.3.1. Then, the asymptotic variance-covariance matrix of the MLEs of μ and σ can be obtained as the inverse of the

expected Fisher information matrix as

$$\mathbf{V}(\mu, \sigma) = \mathbf{I}^{-1}(\mu, \sigma) = \begin{bmatrix} \text{Var}(\hat{\mu}) & \text{Cov}(\hat{\mu}, \hat{\sigma}) \\ & \text{Var}(\hat{\sigma}) \end{bmatrix}. \quad (3.12)$$

For a particular standardized location-scale distribution, $f^*(\cdot)$, $F^*(\cdot)$, and $\bar{F}^*(\cdot)$ are specified and the normal equations in Eqs. (3.5) and (3.6), the expected Fisher information matrix in Eq. (3.11) and the asymptotic variance-covariance matrix in Eq. (3.12) can be obtained.

3.4. Experimental Planning and Optimality Criteria

3.4.1. Settings for optimal experimental planning

This subsection considers different settings and scenarios to plan the progressively Type-II censored experiments described in Section 3.1. Suppose there are N components available for a progressively Type-II censored experiment and assume that the components can be placed on a life test individually or systems formed by these components can be placed on a life test. We consider the case the system structures of the systems used in the progressively Type-II censored experiments are the same, i.e., the N components are put into $M = N/n$ n -component systems with system signature $\mathbf{s} = (s_1, \dots, s_n)$ and these M systems are placed on a life test with progressive censoring scheme $\mathbf{R} = (R_1, R_2, \dots, R_r)$ such that r failures are observed. In order to compare progressively Type-II censored experiments with different kinds of systems, the following two scenarios are considered:

Scenario I. Specifying the expected number of failed components in the failed systems: In this scenario, we consider fixing the expected number of failed components in the failed systems, denoted as

$$E(R) = \left[\sum_{i=1}^n i s_i \right] r.$$

For example, if we have $N = 20$ available for the experiment, we used ten 2-component parallel systems (i.e., $\mathbf{s} = (0, 1)$) for the progressively Type-II censored experiment with an effective sample size $r = 4$, then $E(R) = 2 \times 4 = 8$. Note that $E(R)$ is not the total number of failed components in the progressively censored experiment since the systems being censored can contain different numbers of failed components, except for the series systems. In the aforementioned example, with ten 2-component systems and $r = 4$, the six censored systems can contain 0 or 1 failed component.

Scenario II. Specifying the maximum number of failed components in both failed and censored systems: To take into account the component failures in the censored systems, we consider the maximum possible number of failed components in both failed and censored systems, denoted as R_{\max} . In the aforementioned example, with ten 2-component systems and $r = 4$, the four failed systems contain two failed components in each system, and the six censored systems can contain at most one failed component in each system. Therefore, the maximum possible number of failed components in both failed and censored systems is

$$R_{\max} = (2 \times 4) + (1 \times 6) = 14.$$

Note that this scenario considers the worst-case scenario.

When the values of $N = n \times m$ (i.e., the number of components available for the experiment) and $E(R)$ or R_{\max} are fixed in advance according to the availability of resources, we aim to determine the optimal experimental plan with progressive Type-II censoring. In other words, we aim to determine the number of components in each system n , the system signature $\mathbf{s} = (s_1, s_2, \dots, s_n)$, and the progressive censoring scheme $\mathbf{R} = (R_1, R_2, \dots, R_r)$.

To obtain the optimal progressive censoring schemes, we consider the following ways to settings when N and r ($E(R)$ in Scenario I or R_{\max} in Scenario II) are specified.

- [M1] Fix $R_\ell = m - r$, $R_{\ell'} = 0$, for $\ell, \ell' = 1, 2, \dots, r$ and $\ell' \neq \ell$, then we determine the optimal number of components in the system (denoted as $n^{(\ell)}$) and the system signature (denoted as $\mathbf{s}^{(\ell)}$) that optimize the specific objective function. The progressive censoring scheme that censored all $m - r$ systems at a certain observed failure is known as the progressive Type-II extremal censoring scheme (see, for example, [Ng et al., 2017](#)). In this setting, for each progressive Type-II extremal censoring scheme $(0, \dots, 0, R_\ell = m - r, 0, \dots, 0)$ for $\ell = 1, 2, \dots, r$, we search for the optimal values of n and \mathbf{s} .
- [M2] Fix $\sum_{\ell=1}^r R_\ell = m - r$, and then determine the values of R_ℓ (number of censored systems at each observed failure), the values of n (number of components in the system) and \mathbf{s} (system structure) that optimize the specific objective function. In this setting, we either fix the expected number of failed components in those failed systems (i.e., Scenario I) or the maximum possible number of failed components in the experiment (i.e., Scenario II). We do not put any restriction on the censoring scheme (R_1, R_2, \dots, R_r) .

3.4.2. Optimality criteria

Suppose we are interested in estimating the model parameters or function of the model parameters based on the settings presented in Section 3.4.1, or controlling the experimental time and cost, we plan the optimal progressively Type-II censored experiment by considering the following optimality criteria:

[C1] *D*-optimality: Maximizing the determinant of the expected Fisher information matrix, \mathbf{I} , i.e., maximizing the differential Shannon information contained in the MLEs and minimizing the volume of the Wald-type joint confidence region for the model parameter (μ, σ) . Specifically, we aim to maximize

$$\det[\mathbf{I}(\mu, \sigma)] = \left| E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} \right) E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} \right) - \left[E \left(\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} \right) \right]^2 \right|.$$

[C2] *A*-optimality: Minimizing the trace of the asymptotic variance-covariance matrix of the MLEs, $V(\mu, \sigma)$, i.e., minimizing the sum of the asymptotic variances of the MLEs of μ and σ . Specifically, we aim to minimize

$$Var(\hat{\mu}) + Var(\hat{\sigma}).$$

For notational convenience, we denote $V_\mu = Var(\hat{\mu})$ and $V_\sigma = Var(\hat{\sigma})$.

[C3] *V*-optimality: Minimizing the variance of the estimator of μ , $Var(\hat{\mu})$. This criterion minimizes the variance of the estimate of the slope parameter.

[C4] Minimization of the expected total time of the experiment, denoted as *TTE*, which is defined as

$$E(TTE) = E \{ [\exp(V_{r:r:m})] \}.$$

Using the relationship between $Z_{\ell:r:m}$ and $V_{\ell:r:m}$:

$$Z_{\ell:r:m} = \frac{V_{\ell:r:m} - \mu}{\sigma},$$

the TTE can be expressed in terms of $Z_{\ell:r:m}$, which is the ℓ -th ordered standardized log-transformed failure time, as

$$E(TTE) = \exp(\mu)E[\exp(\sigma Z_{r:r:m})]. \quad (3.13)$$

Based on the progressive Type-II censored experiments described in Section 3.2, the experiment terminates at the last observed failure. This criterion aims to minimize the termination time of the experiment.

[C5] Minimization of the expected maximum total time for all the components spending on the experiment, denoted as TTT , which is defined as

$$\begin{aligned} E(TTT) &= nE\left\{\sum_{\ell=1}^r (R_{\ell} + 1) \exp(V_{\ell:r:m})\right\} \\ &= n\sum_{\ell=1}^r (R_{\ell} + 1) \exp(\mu)E[\exp(\sigma Z_{\ell:r:m})]. \end{aligned}$$

Since the components that did not fail in the life testing experiment can be used in the future for other purposes, the shorter the time those components spent in the experiment, the longer they can be used for other purposes. Therefore, this criterion aims to minimize the maximum expected total time the components spent in the experiment.

[C6] Minimization of a cost function: For experimental planning purposes, we consider the optimal progressive censoring scheme by including the cost in the life testing experiment due to failures and time and the cost in the inaccuracy of parameter estimation. Specifically, for specific values of N , m , n , and system signature \mathbf{s} , we minimize the

objective function

$$\psi(\mathbf{R}) = c_1 E(R) + c_2 E(TTE) + c_3 (Var(\hat{\mu}) + Var(\hat{\sigma})), \quad (3.14)$$

where c_1, c_2 and c_3 are the cost per unit of failed components, the cost per unit of time for the duration of the experiment, and the cost of variance of the estimates of the unknown model parameters, respectively.

3.5. Specific Coherent Systems Being Considered

Many coherent systems can be considered for the progressively Type-II censored experiment involving systems, especially when N and n are large. In practice, it may be more feasible to use coherent systems with a small number of components since using systems with a large number of components reduce the flexibility of the progressively censored experiments. For example, with $N = 120$, if we consider using 3-component coherent systems (i.e., $n = 3$), we have 40 systems for the progressively Type-II censored experiment. However, if we consider using 10-component coherent systems (i.e., $n = 10$), we only have 12 systems for the progressively Type-II censored experiment. Therefore, to simplify the optimal experimental planning problem and for illustrative purposes, we restrict our discussion to $n \leq 3$. Note that the methodologies proposed in this chapter can be extended to $n > 3$.

For $n = 1$, the experiment reduces to a component-wise progressively Type-II censored experiment, in which the optimal experimental schemes have been discussed under different optimal criteria in the literature. For $n = 2$, two possible coherent systems can be considered: the series system with system signature $\mathbf{s} = (1, 0)$ and the parallel system with system signature $\mathbf{s} = (0, 1)$. For $n = 3$, five possible coherent systems can be considered, including the series system with system signature $\mathbf{s} = (1, 0, 0)$, parallel system, 2-out-of-3 system with system signature $\mathbf{s} = (0, 1, 0)$, parallel-series system with system signature $\mathbf{s} = (0, 2/3, 1/3)$, and series-parallel system with system signature $\mathbf{s} = (1/3, 2/3, 0)$. Among those different

types of systems, series systems and parallel systems are just special cases of l -out-of- n systems for $\ell = 1$ and $\ell = n$, respectively; hence, we consider l -out-of- n , parallel-series, and series-parallel systems for $n \leq 3$.

The following subsections provide the formulas required for obtaining the normal equations in Eqs. (3.5) and (3.6) for specific n -component coherent systems with $n \leq 3$.

3.5.1. l -out-of- n systems

For a l -out-of- n system, the system signature is $\mathbf{s} = (0, \dots, 0, R_\ell = 1, 0, \dots, 0)$. Thus, the SF and PDF of the log-transformed system lifetimes can be expressed as

$$\begin{aligned}\bar{F}_V(v; \boldsymbol{\theta}) &= \sum_{i=1}^n s_i \sum_{j=0}^{i-1} \binom{n}{j} [F^*(z)]^j [\bar{F}^*(z)]^{n-j} \\ &= \sum_{j=0}^{l-1} \binom{n}{j} [F^*(z)]^j [\bar{F}^*(z)]^{n-j}, \\ \text{and } f_V(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^*(z) \sum_{i=1}^n s_i \binom{n}{i} i [F^*(z)]^{i-1} [\bar{F}^*(z)]^{n-i} \\ &= \frac{1}{\sigma} f^*(z) \binom{n}{l} l [F^*(z)]^{l-1} [\bar{F}^*(z)]^{n-l}.\end{aligned}$$

The log-likelihood functions in Eq. (3.4) can be simplified as

$$l(\boldsymbol{\theta}) = C + \sum_{\ell=1}^r \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) + \sum_{\ell=1}^r R_\ell \ln [\bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})], \quad v_{1:r:m} < v_{2:r:m} < \dots < v_{r:r:m},$$

where

$$\begin{aligned}\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ \frac{1}{\sigma} f^*(z_{\ell:r:m}) \binom{n}{l} l [F^*(z_{\ell:r:m})]^{l-1} [\bar{F}^*(z_{\ell:r:m})]^{n-l} \right\} \\ \text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ \sum_{j=0}^{l-1} \binom{n}{j} [F^*(z_{\ell:r:m})]^j [\bar{F}^*(z_{\ell:r:m})]^{n-j} \right\}.\end{aligned}$$

Then, we can obtain the first partial derivatives of the log-likelihood function with respect to μ and σ . respectively, as

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} + R_{\ell} \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} \right] \\ \text{and } \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} + R_{\ell} \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} \right]. \end{aligned}$$

3.5.1.1. Series system: $l = 1$

For $l = 1$, we have the series system. Thus, the PDF and SF of the log-transformed system lifetimes can be further simplified as

$$\begin{aligned} f_V(v; \boldsymbol{\theta}) &= \frac{n}{\sigma} f^*(z) [\bar{F}^*(z)]^{n-1}, \\ \text{and } \bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^n, \quad n = 1, 2, 3. \end{aligned}$$

Then, we have

$$\begin{aligned} \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ \frac{n}{\sigma} f^*(z_{\ell:r:m}) [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\} \\ &= \ln n - \ln \sigma + \ln f^*(z_{\ell:r:m}) + (n-1) \ln \bar{F}^*(z_{\ell:r:m}) \\ \text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n \right\} = n \ln \bar{F}^*(z_{\ell:r:m}). \end{aligned}$$

Thus, we can obtain the first partial derivatives of the PDF and SF as

$$\begin{aligned} \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + (n-1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + (n-1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \sigma}, \end{aligned}$$

and

$$\begin{aligned}\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= n \left(\frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \right) \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= n \left(\frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \sigma} \right).\end{aligned}$$

Hence, the normal equations can be expressed as

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + (R_\ell n + n - 1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \right] \\ &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + (R_\ell n + n - 1) \frac{1}{\bar{F}^*(z_{\ell:r:m})} \frac{\partial \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \right] = 0 \quad (3.15)\end{aligned}$$

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + (R_\ell n + n - 1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \sigma} \right] \\ &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + (R_\ell n + n - 1) \frac{1}{\bar{F}^*(z_{\ell:r:m})} \frac{\partial \bar{F}^*(z_{\ell:r:m})}{\partial \sigma} \right] = 0.\end{aligned} \quad (3.16)$$

3.5.1.2. Parallel system: $l = n$

For $l = n$, we have the parallel system with system signature $\mathbf{s} = (0, 0, \dots, 1)$. The PDF and SF of the log-transformed system lifetimes can be expressed as

$$\begin{aligned}f_V(v; \boldsymbol{\theta}) &= \frac{n}{\sigma} f^*(z) [F^*(z)]^{n-1}, \\ \text{and } \bar{F}_V(v; \boldsymbol{\theta}) &= \sum_{j=0}^{n-1} \binom{n}{j} [\bar{F}^*(z)]^j [F^*(z)]^{n-j} \\ &= 1 - [F^*(z)]^n,\end{aligned}$$

respectively. Then, we have

$$\begin{aligned}\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ \frac{n}{\sigma} f^*(z) [F^*(z)]^{n-1} \right\} \\ &= \ln n - \ln \sigma + \ln f^*(z_{\ell:r:m}) + (n-1) \ln F^*(z_{\ell:r:m})\end{aligned}$$

$$\text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) = \ln \{1 - [F^*(z_{\ell:r:m})]^n\}.$$

Thus, we can obtain the first partial derivatives of the PDF and SF as

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + (n-1) \frac{\partial \ln F^*(z_{\ell:r:m})}{\partial \mu} \\ &= \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + \frac{n-1}{F^*(z_{\ell:r:m})} \frac{\partial F^*(z_{\ell:r:m})}{\partial \mu}\end{aligned}\quad (3.17)$$

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + (n-1) \frac{\partial \ln F^*(z_{\ell:r:m})}{\partial \sigma} \\ &= -\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{n-1}{F^*(z_{\ell:r:m})} \frac{\partial F^*(z_{\ell:r:m})}{\partial \sigma},\end{aligned}\quad (3.18)$$

and

$$\begin{aligned}\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= -\frac{n [F^*(z_{\ell:r:m})]^{n-1}}{1 - [F^*(z_{\ell:r:m})]^n} \frac{\partial F^*(z_{\ell:r:m})}{\partial \mu} \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{n [F^*(z_{\ell:r:m})]^{n-1}}{1 - [F^*(z_{\ell:r:m})]^n} \frac{\partial F^*(z_{\ell:r:m})}{\partial \sigma}.\end{aligned}$$

The normal equations can be obtained as

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} \right. \\ &\quad \left. + \frac{(n-1) - (R_\ell n + n-1) [F^*(z_{\ell:r:m})]^n}{F^*(z_{\ell:r:m}) (1 - [F^*(z_{\ell:r:m})]^n)} \frac{\partial F^*(z_{\ell:r:m})}{\partial \mu} \right] = 0 \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} \right. \\ &\quad \left. + \frac{(n-1) - (R_\ell n + n-1) [F^*(z_{\ell:r:m})]^n}{F^*(z_{\ell:r:m}) (1 - [F^*(z_{\ell:r:m})]^n)} \frac{\partial F^*(z_{\ell:r:m})}{\partial \sigma} \right] = 0.\end{aligned}$$

3.5.1.3. 2-out-of- n system

For 2-out-of- n ($n > 2$) system, the system signature is $\mathbf{s} = (0, 1, 0, \dots, 0)$, and the PDF and SF of the log-transformed system lifetimes are

$$f_V(v; \boldsymbol{\theta}) = \frac{1}{\sigma} f^*(z) \left\{ n(n-1) [F^*(z)] [\bar{F}^*(z)]^{n-2} \right\}$$

$$\text{and } \bar{F}_V(v; \boldsymbol{\theta}) = [\bar{F}^*(z)]^n + n[F^*(z)] [\bar{F}^*(z)]^{n-1}.$$

Then, we have

$$\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) = \ln n(n-1) - \ln \sigma + \ln f^*(z_{\ell:r:m}) + \ln \left\{ [F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-2} \right\}$$

$$\text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) = \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\}.$$

Thus, we can obtain the first partial derivatives of the PDF and SF with respect to μ and σ as

$$\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} = \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-2} \right\}}{\partial \mu}$$

$$\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} = -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-2} \right\}}{\partial \sigma}$$

and

$$\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} = \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\}}{\partial \mu}$$

$$\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} = \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\}}{\partial \sigma}.$$

The normal equations can be obtained as

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-2} \right\}}{\partial \mu} \right. \\ &\quad \left. + R_{\ell} \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\}}{\partial \mu} \right] = 0, \end{aligned} \quad (3.19)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-2} \right\}}{\partial \sigma} \right. \\ &\quad \left. + R_{\ell} \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\}}{\partial \sigma} \right] = 0. \end{aligned} \quad (3.20)$$

3.5.1.4. 3-out-of-n

For 3-out-of- n ($n > 3$) system, the system signature is $\mathbf{s} = (0, 0, 1, 0, \dots, 0)$, and the PDF and SF of the log-transformed system lifetimes are

$$\begin{aligned} f_V(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^*(z) \left\{ \frac{n(n-1)(n-2)}{2} [F^*(z)]^2 [\bar{F}^*(z)]^{n-3} \right\} \\ \text{and } \bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^n + n[F^*(z)] [\bar{F}^*(z)]^{n-1} + \frac{n(n-1)}{2} [F^*(z)]^2 [\bar{F}^*(z)]^{n-2}. \end{aligned}$$

Then, we have

$$\begin{aligned} &\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) \\ &= \ln \left[\frac{n(n-1)(n-2)}{2} \right] - \ln \sigma + \ln f^*(z_{\ell:r:m}) + \ln \left\{ [F^*(z_{\ell:r:m})]^2 [\bar{F}^*(z_{\ell:r:m})]^{n-3} \right\} \\ \text{and } &\ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) \\ &= \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} + \frac{n(n-1)}{2} [F^*(z_{\ell:r:m})]^2 [\bar{F}^*(z_{\ell:r:m})]^{n-2} \right\}. \end{aligned}$$

Thus, we can obtain the first partial derivatives of the PDF and SF with respect to μ and σ as

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^2 [\bar{F}^*(z_{\ell:r:m})]^{n-3} \right\}}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^2 [\bar{F}^*(z_{\ell:r:m})]^{n-3} \right\}}{\partial \sigma}\end{aligned}$$

and

$$\begin{aligned}& \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} \\ &= \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} + \frac{n(n-1)}{2} [F^*(z)]^2 [\bar{F}^*(z)]^{n-2} \right\}}{\partial \mu} \\ & \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} \\ &= \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} + \frac{n(n-1)}{2} [F^*(z)]^2 [\bar{F}^*(z)]^{n-2} \right\}}{\partial \sigma}.\end{aligned}$$

The normal equations can be obtained as

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^2 [\bar{F}^*(z_{\ell:r:m})]^{n-3} \right\}}{\partial \mu} \right. \\ & \quad \left. + \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} + \frac{n(n-1)}{2} [F^*(z)]^2 [\bar{F}^*(z)]^{n-2} \right\}}{\partial \mu} \right] \\ &= 0,\end{aligned}\tag{3.21}$$

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^2 [\bar{F}^*(z_{\ell:r:m})]^{n-3} \right\}}{\partial \sigma} \right. \\ & \quad \left. + \frac{\partial \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n + n[F^*(z_{\ell:r:m})] [\bar{F}^*(z_{\ell:r:m})]^{n-1} + \frac{n(n-1)}{2} [F^*(z)]^2 [\bar{F}^*(z)]^{n-2} \right\}}{\partial \sigma} \right] \\ &= 0.\end{aligned}\tag{3.22}$$

3.5.2. Series-parallel and parallel-series systems for $n = 3$

3.5.2.1. Series-parallel systems for $n = 3$

For $n = 3$, the system signature for series-parallel systems is $\mathbf{s} = (1/3, 2/3, 0)$, and the PDF and SF of the log-transformed system lifetimes are

$$\begin{aligned} f_V(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^*(z) \left\{ [\bar{F}^*(z)]^2 + 2[F^*(z)] [\bar{F}^*(z)] \right\} \\ &= \frac{1}{\sigma} f^*(z) \{1 - [F^*(z)]^2\} \\ \text{and } \bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^3 + 2[F^*(z)] [\bar{F}^*(z)]^2 \\ &= [F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1, \end{aligned}$$

respectively. Then, we have

$$\begin{aligned} \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= -\ln \sigma + \ln f^*(z_{\ell:r:m}) + \ln \{1 - [F^*(z_{\ell:r:m})]^2\} \\ \text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}. \end{aligned}$$

Thus, we can obtain the first partial derivatives of the PDF and SF with respect to μ and σ as

$$\begin{aligned} \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^2\}}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^2\}}{\partial \sigma} \end{aligned}$$

and

$$\begin{aligned} \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}}{\partial \mu} \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= \frac{\partial \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}}{\partial \sigma}. \end{aligned}$$

The normal equations can be obtained as

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^2\}}{\partial \mu} \right. \\ &\quad \left. + \frac{\partial \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}}{\partial \mu} \right] = 0, \end{aligned} \quad (3.23)$$

$$\begin{aligned} \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^2\}}{\partial \sigma} \right. \\ &\quad \left. + \frac{\partial \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}}{\partial \sigma} \right] = 0. \end{aligned} \quad (3.24)$$

3.5.2.2. Parallel-series systems for $n = 3$

For $n = 3$, the system signature for parallel-series systems is $\mathbf{s} = (0, 2/3, 1/3)$. Thus, the PDF and SF of the log-transformed system lifetimes are,

$$\begin{aligned} f_V(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^*(z) \left\{ 2[F^*(z)] [\bar{F}^*(z)] + \frac{1}{3}[F^*(z)]^2 \right\} \\ &= \frac{1}{\sigma} f^*(z) \left\{ 2[F^*(z)] - \frac{5}{3}[F^*(z)]^2 \right\} \\ \text{and } \bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^3 + 3[F^*(z)] [\bar{F}^*(z)]^2 + [F^*(z)]^2 [\bar{F}^*(z)], \\ &= [F^*(z)]^3 - 2[F^*(z)]^2 + 1, \end{aligned}$$

respectively. Thus, we have

$$\begin{aligned} \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= -\ln \sigma + \ln f^*(z_{\ell:r:m}) + \ln \left\{ 2[F^*(z)] - \frac{5}{3}[F^*(z)]^2 \right\} \\ \text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \{ [F^*(z)]^3 - 2[F^*(z)]^2 + 1 \}. \end{aligned}$$

Thus, we can obtain the first partial derivatives of the PDF and SF with respect to μ and σ as

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \left\{ 2 [F^*(z_{\ell:r:m})] - \frac{5}{3} [F^*(z_{\ell:r:m})]^2 \right\}}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \left\{ 2 [F^*(z_{\ell:r:m})] - \frac{5}{3} [F^*(z_{\ell:r:m})]^2 \right\}}{\partial \sigma},\end{aligned}$$

and

$$\begin{aligned}\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^3 - 2 [F^*(z_{\ell:r:m})]^2 + 1 \right\}}{\partial \mu} \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^3 - 2 [F^*(z_{\ell:r:m})]^2 + 1 \right\}}{\partial \sigma}.\end{aligned}$$

The normal equations can be obtained as

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \left\{ 2 [F^*(z_{\ell:r:m})] - \frac{5}{3} [F^*(z_{\ell:r:m})]^2 \right\}}{\partial \mu} \right. \\ &\quad \left. + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^3 - 2 [F^*(z_{\ell:r:m})]^2 + 1 \right\}}{\partial \mu} \right] = 0,\end{aligned}\tag{3.25}$$

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \left\{ 2 [F^*(z_{\ell:r:m})] - \frac{5}{3} [F^*(z_{\ell:r:m})]^2 \right\}}{\partial \sigma} \right. \\ &\quad \left. + \frac{\partial \ln \left\{ [F^*(z_{\ell:r:m})]^3 - 2 [F^*(z_{\ell:r:m})]^2 + 1 \right\}}{\partial \sigma} \right] = 0.\end{aligned}\tag{3.26}$$

3.6. Numerical Illustrations

3.6.1. Lognormal distributed components

Consider the lifetimes of the components follow a two-parameter lognormal distribution with CDF and PDF

$$F_{LN}(x; \mu, \sigma) = \Phi_{nor} \left[\frac{\ln(x) - \mu}{\sigma} \right], x > 0,$$

$$f_{LN}(x; \mu, \sigma) = \frac{1}{\sigma x} \phi_{nor} \left(\frac{\ln(x) - \mu}{\sigma} \right) = \frac{1}{\sqrt{2\pi}\sigma x} \exp \left[-\frac{1}{2} \left(\frac{\ln(x) - \mu}{\sigma} \right)^2 \right] x > 0,$$

respectively, where $\exp(\mu)$ is the scale parameter, $\sigma > 0$ is the shape parameter, and $\Phi_{nor}(z)$ and $\phi_{nor}(z)$ are the CDF and PDF for the standard normal distribution:

$$\Phi_{nor}(z) = \int_{-\infty}^z \phi_{nor}(w) dw, \quad \bar{\Phi}_{nor}(z) = 1 - \Phi_{nor}(z),$$

$$\phi_{nor}(z) = \frac{1}{\sqrt{2\pi}} \exp \left(-\frac{z^2}{2} \right), \quad -\infty < z < \infty.$$

Then, the log-transformed component lifetimes follow a normal distribution with location parameter μ and scale parameter σ with CDF, SF and PDF

$$F_U(u; \mu, \sigma) = \Phi_{nor} \left(\frac{u - \mu}{\sigma} \right),$$

$$\bar{F}_U(u; \mu, \sigma) = 1 - \Phi_{nor} \left(\frac{u - \mu}{\sigma} \right) = \bar{\Phi}_{nor} \left(\frac{u - \mu}{\sigma} \right),$$

and $f_U(u; \mu, \sigma) = \frac{1}{\sigma} \phi_{nor} \left(\frac{u - \mu}{\sigma} \right), \quad -\infty < u < \infty,$

respectively.

We consider the experimental planning for a fixed value of N and r when various types of coherent systems are used in progressively Type-II censored experiments. In Tables 3.1 and

3.2, we present the optimal progressive censoring schemes for n -component coherent systems with lognormal distributed components under settings [M1] and [M2]. In Table 3.3, we present the optimal progressive censoring schemes for n -component coherent systems with lognormal distributed components ($n = 1, 2$, and 3) by fixing $R_{\max} = 8$ under setting [M1] and [M2].

Table 3.1: Optimal progressive censoring schemes for n -component systems with lognormal distributed components when $N = 30$, by fixing $n = 1, 2$, and 3 under setting [M1] and [M2]

System Type	n	Setting	m	r	$E(R)$	R_{\max}	R	[C1]	[C2]	[C3]	[C4]	[C5]	[C6]	(1, 1, 1, 0)	(1, 1, 1, 0)	(0, 1, 1, 0)	(0, 1, 1, 0)	(0, 1, 2, 0)	(0, 1, 3, 0)		
Series	1	[M1]	30	6	6	6	(0.24,0.0,0.0)	194.48	0.1984	0.1420	27.91	92.08	7.98	33.91	29.90	28.91	31.88	33.87	33.87		
							(24.0,0.0,0.0)	172.23	0.1943	0.1419	30.56	89.61	8.94	31.56	32.50	31.53	34.45	36.39	34.58	36.39	34.45
	[M2]	30	6	6	6	(0.0,0.0,0.24)	143.63	0.2905	0.1818	3.13	87.90	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45	36.39	
						(24.0,0.0,0.0)	194.48	0.1984	0.1420	27.91	92.08	7.98	33.91	29.90	28.91	31.88	33.87	33.87	33.87	33.87	33.87
	2	1	[M1]	15	6	6	6	(0.24,0.0,0.0)	171.43	0.1985	0.1348	12.84	83.33	6.16	9.13	33.91	32.50	31.53	34.45	36.39	34.45
								(24.0,0.0,0.0)	146.57	0.2796	0.1752	3.36	87.25	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45
[M2]		15	6	6	6	(0.0,0.0,0.9)	183.59	0.2077	0.1404	12.13	86.15	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45		
						(9.0,0.0,0.0)	171.43	0.1985	0.1348	12.84	83.33	6.16	9.13	33.91	32.50	31.53	34.45	36.39	34.45	36.39	34.45
3		1	[M1]	10	6	6	6	(0.24,0.0,0.0)	167.13	0.2058	0.1357	8.17	82.30	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45
								(24.0,0.0,0.0)	142.29	0.2821	0.1583	4.03	82.37	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45
	[M2]	10	6	6	6	(0.0,0.0,0.5)	168.06	0.2113	0.1385	8.57	83.25	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45		
						(4.0,0.0,0.0)	149.97	0.2682	0.1684	3.70	86.61	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45	36.39	34.45
	Parallel	2	[M1]	15	3	6	18	(0.24,0.0,0.0)	174.29	0.2189	0.1343	8.28	85.23	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45
								(24.0,0.0,0.0)	168.06	0.2113	0.1385	8.57	83.25	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45
[M2]		15	3	6	18	(0.0,0.0,0.4)	149.97	0.2682	0.1684	3.70	86.61	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45		
						(4.0,0.0,0.0)	174.29	0.2189	0.1343	8.28	85.23	6.04	9.13	33.91	32.50	31.53	34.45	36.39	34.45	36.39	34.45
2-out-of- n		3	[M1]	10	2	6	22	(0.24,0.0,0.0)	70.43	0.2595	0.1078	20.73	177.68	29.33	23.33	22.03	25.92	25.92	25.92	25.92	25.92
								(24.0,0.0,0.0)	69.79	0.2465	0.1261	28.01	169.73	36.47	8.47	34.01	30.47	29.24	32.94	35.40	35.40
	[M2]	10	2	6	18	(0.0,0.1,2)	61.01	0.3010	0.0992	6.23	178.90	15.24	9.01	12.23	9.24	7.73	12.25	15.26	15.26		
						(12.0,0.0)	70.43	0.2595	0.1078	20.73	177.68	29.33	8.60	26.73	23.33	22.03	25.92	25.92	25.92		
	Series-parallel	3	[M1]	10	4	6	2/3	(0.0,0.0)	71.88	0.2573	0.1181	7.24	131.18	15.99	8.75	13.24	9.99	8.62	12.75	15.99	15.99
								(0.0,0.0)	70.86	0.2471	0.1457	4.48	118.08	22.46	9.24	10.96	8.25	9.60	11.51	14.78	14.78
[M2]		10	4	6	2/3	(0.0,0.6)	65.04	0.3143	0.1515	4.48	118.08	22.46	9.24	10.96	8.25	9.60	11.51	14.78	14.78		
						(6.0,0.0)	79.86	0.2573	0.1358	11.33	115.16	21.17	9.24	10.96	8.25	9.60	11.51	14.78	14.78		
Parallel-series		3	[M1]	10	3	7	23	(0.24,0.0,0.0)	63.56	0.2836	0.1226	16.37	172.26	26.21	9.84	23.37	19.21	17.79	22.04	24.88	24.88
								(24.0,0.0)	62.22	0.2706	0.1364	21.42	169.30	31.13	9.71	28.42	24.13	22.77	26.83	29.54	29.54
	[M2]	10	3	7	23	(0.0,0.0)	63.56	0.2836	0.1226	16.37	172.26	26.21	9.84	23.37	19.21	17.79	22.04	24.88	24.88		
						(7.0,0.0)	62.22	0.2706	0.1364	21.42	169.30	31.13	9.71	28.42	24.13	22.77	26.83	29.54	29.54		
	[M2]	10	3	7	23	(0.0,0.7)	58.26	0.3128	0.1146	6.04	169.05	16.17	10.13	13.04	9.17	7.60	12.30	15.42	15.42		
						(5.0,2)	61.72	0.2779	0.1197	9.46	162.73	19.24	9.78	16.46	12.24	10.85	15.02	17.80	17.80		

For criterion [C6], the objective function is $\psi(\mathbf{R}) = c_1 E(R) + c_2 E(TTE) + c_3 (Var(\hat{\mu}) + Var(\hat{\sigma}))$.

Table 3.2: Optimal progressive censoring schemes for n -component systems with lognormal distributed components when $N = 24$, by fixing $n = 1, 2, 3$, and 4 under setting [M1] and [M2]

System Type	n	Setting	m	r	$E(R)$	R_{\max}	R	[C1]	[C2]	[C3]	[C4]	[C5]	[C6]	(0, 1, 20)	(0, 1, 5)	(0, 1, 10)	(0, 1, 10)	(1, 0, 10)	(1, 1, 10)	(1, 1, 10)	(1, 1, 0)	(1, 1, 0)	(0, 1, 20)	(0, 1, 30)			
Series	1	[M1]	24	4	4	4	(0, 20, 0, 0)	94.62	$V_1 + V_2$	0.224	19.61	64.56	26.77	23.61	21.19	25.93	29.10	29.65	30.65	31.62	32.61	33.61	34.61	35.61	36.61		
		[M2]	24	4	4	4	(0, 0, 0, 20)	88.84	0.2904	0.2128	23.75	62.94	62.94	6.90	26.65	25.20	29.56	29.65	30.65	31.62	32.61	33.61	34.61	35.61	36.61		
2	[M1]	12	4	4	4	(0, 20, 0, 0)	94.62	0.3162	0.2241	19.61	64.56	26.77	23.61	21.19	25.93	29.10	29.65	30.65	31.62	32.61	33.61	34.61	35.61	36.61	37.61		
							88.84	0.2904	0.2128	23.75	62.94	62.94	6.90	26.65	25.20	29.56	29.65	30.65	31.62	32.61	33.61	34.61	35.61	36.61	37.61	38.61	39.61
3	[M1]	8	4	4	4	(0, 4, 0, 0)	84.55	0.3469	0.2331	6.59	58.86	14.40	7.20	11.20	10.40	8.80	13.60	16.80	16.80	17.00	17.20	17.40	17.60	17.80	18.00	18.20	
							83.54	0.3200	0.2154	7.20	58.86	14.40	7.20	11.20	10.40	8.80	13.60	16.80	16.80	17.00	17.20	17.40	17.60	17.80	18.00	18.20	18.40
4	[M1]	6	4	4	4	(0, 2, 0, 0)	81.00	0.3587	0.2389	5.40	60.69	7.20	3.88	60.21	12.99	7.60	9.40	8.99	7.20	12.59	16.19	16.19	16.19	16.19	16.19	16.19	16.19
							81.25	0.3400	0.2255	5.70	59.33	13.10	7.40	60.69	13.10	7.40	9.10	8.99	7.20	12.59	16.19	16.19	16.19	16.19	16.19	16.19	16.19
Parallel	2	[M1]	12	2	4	(10, 0)	84.81	0.3682	0.2465	3.97	60.36	12.24	7.64	23.86	23.49	21.67	27.13	30.76	30.76	30.76	30.76	30.76	30.76	30.76	30.76	30.76	
							84.55	0.3469	0.2331	6.59	60.83	14.06	7.47	23.86	23.49	21.67	27.13	30.76	30.76	30.76	30.76	30.76	30.76	30.76	30.76	30.76	30.76
3	[M1]	8	2	6	18	(6, 0)	34.54	0.3530	0.1151	25.35	217.32	19.68	9.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68		
							32.18	0.3396	0.1118	25.35	217.32	19.68	9.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68	11.68
4	[M1]	6	2	8	20	(4, 0)	33.70	0.3671	0.1283	30.33	214.70	21.93	11.93	13.93	13.93	13.93	13.93	13.93	13.93	13.93	13.93	13.93	13.93	13.93	13.93		
							33.36	0.4477	0.1684	13.93	316.65	26.40	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48	12.48
2-out-of- n	3	[M1]	8	2	6	(6, 0)	39.83	0.3859	0.1855	10.13	95.15	17.99	7.86	14.13	13.99	12.06	17.85	21.71	21.71	21.71	21.71	21.71	21.71	21.71	21.71	21.71	
							39.83	0.3859	0.1855	10.13	95.15	17.99	7.86	14.13	13.99	12.06	17.85	21.71	21.71	21.71	21.71	21.71	21.71	21.71	21.71	21.71	21.71
Series-parallel	3	[M1]	8	4	6 2/3	(6, 0)	25.54	0.5022	0.3085	8.34	36.74	16.69	8.34	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88		
							25.54	0.5022	0.3085	8.34	36.74	16.69	8.34	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88	10.88
Parallel-series	3	[M1]	10	3	7	(6, 0)	31.18	0.4026	0.1923	15.35	121.77	24.04	8.69	20.02	19.38	17.36	23.43	27.43	27.43	27.43	27.43	27.43	27.43	27.43	27.43		
							31.18	0.4026	0.1923	15.35	121.77	24.04	8.69	20.02	19.38	17.36	23.43	27.43	27.43	27.43	27.43	27.43	27.43	27.43	27.43	27.43	27.43

For criterion [C6], the objective function is $\psi(\mathbf{R}) = c_1 E(R) + c_2 E(TTE) + c_3 (Var(\hat{\mu}) + Var(\hat{\sigma}))$.

Table 3.3: Optimal progressive censoring schemes for n -component systems with lognormal distributed components when $N = 18$, by fixing $n = 1, 2$, and 3 , $R_{\max} = 8$ under setting [M1] and [M2]

System Type	n	Setting	m	r	$E(R)$	R_{\max}	R	[C1]	$V_{\mu} + V_{\sigma}$	[C2]	$V_{\mu} + V_{\sigma}$	[C3]	$\frac{[C4]}{\sqrt{[C5]}}$	[C5]	$\frac{[C6]}{\sqrt{[C5]}}$	(1, 1, 1, 0)	(1, 0, 1, 0)	(1, 1, 0)	(0, 1, 1, 0)	(0, 1, 1, 5)	(0, 1, 1, 20)	(0, 1, 30)			
Series	1	[M1]	18	8	8	8	(0,0,10,0,0,0,0,0)	217.5	0.1552	0.1029	0.1029	32.06	103.27	34.51	33.72	42.51	9.55	42.81	36.36	34.51	35.59	36.06	37.62		
							(0,1,0,0,0,0,0,0)	182.19	0.1551	0.0965	6.27	92.55	105.17	44.36	16.00	9.73	14.27	14.27	14.27	14.27	14.27	14.27	14.27	14.27	14.27
	[M2]	18	8	8	8	8	(0,0,10,0,0,0,0,0)	217.5	0.1552	0.1029	0.1029	32.06	103.27	34.51	33.72	42.51	9.55	42.81	36.36	34.51	35.59	36.06	37.62	11.45	
							(0,8,2,0,0,0,0,0)	215.11	0.1551	0.1038	34.06	104.67	104.67	43.61	16.00	9.55	42.06	35.61	34.84	37.16	12.62	11.45			
	2-out-of-3	2	[M1] and [M2]	9	8	8	8	(0,0,0,0,0,0,0,0)	182.19	0.1725	0.0965	6.27	92.55	105.17	44.36	16.00	9.73	14.27	14.27	14.27	14.27	14.27	14.27	14.27	14.27
								(0,9,0,1,0,0,0,0)	204.48	0.1535	0.1097	33.78	105.34	105.34	43.33	16.00	9.73	14.27	14.27	14.27	14.27	14.27	14.27	14.27	14.27
[M1]		6	2	4	8	8	(0,0,0,0,0,0,0,0)	192.95	0.1633	0.0963	9.71	93.42	95.11	24.44	16.44	15.65	16.44	15.65	16.44	15.65	16.44	15.65	16.44	15.65	16.44
							(0,0,0,0,0,0,0,1)	192.95	0.1633	0.0963	9.71	93.42	95.11	24.44	16.44	15.65	16.44	15.65	16.44	15.65	16.44	15.65	16.44	15.65	16.44
[M2]		6	2	4	8	8	(4,0)	33.82	0.3933	0.1814	10.40	83.06	87.15	22.33	11.93	18.40	14.33	12.36	18.26	14.33	12.36	18.26	14.33	12.36	18.26
							(0,4)	30.33	0.4657	0.1812	5.12	87.15	87.15	17.78	12.66	13.12	13.12	13.12	13.12	13.12	13.12	13.12	13.12	13.12	13.12
Series-parallel	3	[M1]	6	2	3	1/3	(4,0)	32.80	0.4171	0.1767	7.09	84.05	84.05	19.26	12.17	15.09	11.26	9.17	15.43	19.60	19.60	19.60	19.60	19.60	
							(1,3)	30.82	0.4627	0.1788	5.49	85.28	85.28	17.98	12.52	13.46	9.98	7.72	14.40	19.02	19.02	19.02	19.02	19.02	19.02
	[M2]	6	2	3	1/3	8	(4,0)	21.76	0.5036	0.2939	8.61	60.01	60.01	21.65	13.04	16.42	11.73	11.73	11.73	11.73	11.73	11.73	11.73	11.73	
							(0,4)	18.47	0.6191	0.3185	3.73	62.86	62.86	17.93	14.19	11.73	9.93	6.83	16.12	22.31	22.31	22.31	22.31	22.31	22.31
	(2,2)	6	2	3	1/3	8	(3,1)	20.37	0.5376	0.2927	5.53	60.52	60.52	18.90	13.38	13.53	10.90	8.22	16.28	21.66	21.66	21.66	21.66	21.66	21.66
							(2,2)	19.47	0.5697	0.3004	4.54	61.38	61.38	18.24	13.70	12.54	10.24	7.39	15.93	21.63	21.63	21.63	21.63	21.63	21.63
(0,4)	18.47	0.6191	0.3185	3.73	62.86	62.86	17.93	14.19	11.73	9.93	6.83	16.12	22.31	22.31	22.31	22.31	22.31	22.31	22.31	22.31	22.31	22.31			

For criterion [C6], the objective function is $\psi(\mathbf{R}) = c_1 R_{\max} + c_2 E(TTE) + c_3 (Var(\mu) + Var(\hat{\sigma}))$.

3.6.2. Weibull distributed components

Suppose the lifetimes of the components follow a two-parameter Weibull distribution with CDF and PDF

$$F_{WE}(x; \eta, \beta) = 1 - \exp \left[- \left(\frac{x}{\eta} \right)^\beta \right], \quad x > 0,$$

$$f_{WE}(x; \eta, \beta) = \frac{\beta}{\eta} \left(\frac{x}{\eta} \right)^{\beta-1} \exp \left[- \left(\frac{x}{\eta} \right)^\beta \right], \quad x > 0,$$

respectively, where $\eta > 0$ is the scale parameter and $\beta > 0$ is the shape parameter. Then, the log-transformed component lifetimes follow a SEV distribution (also known as Gumbel Type I distribution) with location parameter μ and scale parameter σ , i.e.,

$$F_U(u; \mu, \sigma) = \Phi_{sev} \left(\frac{u - \mu}{\sigma} \right), \quad -\infty < u < \infty,$$

$$f_U(u; \mu, \sigma) = \frac{1}{\sigma} \phi_{sev} \left(\frac{u - \mu}{\sigma} \right), \quad -\infty < u < \infty,$$

where $\sigma = 1/\beta$, $\mu = \ln(\eta)$, and $\Phi_{sev}(z) = 1 - \exp[-\exp(z)]$ and $\phi_{sev}(z) = \exp[z - \exp(z)]$ are the CDF and PDF for the standard SEV distribution.

We consider the experimental planning for a fixed value of N and r when various types of coherent systems are used in the progressively Type-II censored experiments when the component lifetimes follow a Weibull distribution. In Tables 3.4 and 3.5, we present the optimal progressive censoring schemes for n -component coherent systems with Weibull distributed components under settings [M1] and [M2]. In Table 3.6, we present the optimal progressive censoring schemes for n -component coherent systems with Weibull distributed components ($n = 1, 2$, and 3) by fixing $R_{\max} = 8$ under setting [M1] and [M2].

Table 3.4: Optimal progressive censoring schemes for n -component systems with Weibull distributed components when $N = 30$, by fixing $n = 1, 2$, and 3 under setting [M1] and [M2]

System Type	n	Setting	m	r	$E(R)$	R_{\max}	R	[C1] $ J $	[C2] $V_0 + V_r$	[C3] V_0	[C4] $\frac{E(R)}{TTE}$	[C5] $\frac{E(R)}{TTE}$	(1, 1, 1, 10)	(1, 0, 1, 10)	(1, 1, 1, 10)	(0, 1, 1, 5)	(0, 1, 2, 0)	(0, 1, 3, 0)		
Series	2	[M1]	30	6	6	6	(0.24,0.0,0.0)	118.21	0.2257	0.1749	15.89	44.33	24.15	8.26	18.15	17.02	20.40	22.66		
							(24.0,0.0,0.0)	108.74	0.2220	0.1668	17.12	44.33	25.34	8.22	23.12	18.23	23.78			
							(0.0,0.0,0.24)	43.19	0.6115	0.4726	1.62	44.33	13.73	12.12	7.62	7.73	4.68	13.85	19.97	
		[M2]	30	6	6	6	6	(0.24,0.0,0.0)	118.21	0.2257	0.1749	15.89	44.33	24.15	8.26	18.15	17.02	20.40	22.66	
								(24.0,0.0,0.0)	108.74	0.2220	0.1668	17.12	44.33	25.34	8.22	23.12	18.23	23.78		
								(0.0,0.0,0.24)	43.19	0.6115	0.4726	1.62	44.33	13.73	12.12	7.62	7.73	4.68	13.85	19.97
	3	[M1]	15	6	6	6	(6.0,0.0,0.18)	54.69	0.4157	0.3060	2.73	44.33	12.89	10.16	8.73	6.89	4.81	11.04	15.20	
							(6.0,0.0,0.12)	47.67	0.5168	0.3909	2.01	44.33	13.18	11.17	8.01	7.18	4.59	12.35	17.51	
							(18.0,0.0,0.8)	67.60	0.3124	0.2433	4.06	44.33	13.58	10.46	9.33	6.02	10.76			
		[M2]	15	6	6	6	6	(0.9,0.0,0.0)	87.96	0.2759	0.2077	8.21	44.33	16.97	8.76	14.21	10.97	9.59	13.73	16.39
								(9.0,0.0,0.9)	84.47	0.2600	0.1890	8.68	44.33	17.28	8.60	14.68	11.28	9.98	13.88	16.48
								(9.0,0.0,0.0)	87.96	0.2759	0.2077	8.21	44.33	16.97	8.76	14.21	10.97	9.59	13.73	16.39
Parallel	2	[M1]	15	3	6	18	(12.0,0.0)	60.87	0.2615	0.1557	15.95	97.65	24.57	8.62	21.95	18.57	17.26	21.18	23.80	
							(0.12,0)	54.21	0.2891	0.1552	12.4	110.03	14.42	11.3	9.12	8.42	5.77	13.72	19.02	
							(0.0,12)	33.42	0.4327	0.1940	4.15	118.10	14.48	10.33	10.15	8.48	6.31	12.80	17.13	
	[M2]	15	3	6	18	18	(12.0,0)	60.87	0.2615	0.1557	15.95	97.65	24.57	8.62	21.95	18.57	17.26	21.18	23.80	
							(0.12,0)	54.21	0.2891	0.1552	12.4	110.03	14.42	11.3	9.12	8.42	5.77	13.72	19.02	
							(0.0,12)	33.42	0.4327	0.1940	4.15	118.10	14.48	10.33	10.15	8.48	6.31	12.80	17.13	
2-out-of-n	3	[M1]	10	2	6	22	(8,0)	39.77	0.3194	0.1420	4.60	153.70	23.79	9.19	20.60	17.79	16.20	20.99	24.18	
							(0.8)	26.33	0.4489	0.1245	6.02	174.83	16.51	10.49	12.02	10.51	8.26	15.00	19.49	
							(8,0)	39.77	0.3194	0.1420	4.60	153.70	23.79	9.19	20.60	17.79	16.20	20.99	24.18	
	[M2]	10	2	6	22	22	(2,6)	27.34	0.4313	0.1238	6.45	172.03	16.76	10.31	12.45	10.76	8.61	15.08	19.39	
							(0.8)	26.33	0.4489	0.1245	6.02	174.83	16.51	10.49	12.02	10.51	8.26	15.00	19.49	
							(3,5)	28.0495	0.4203	0.124	6.74	170.21	16.94	10.20	12.74	10.94	8.84	15.15	19.35	
Series-parallel	3	[M1]	10	3	6	13	(7,0,0)	53.54	0.3004	0.1786	8.95	73.94	17.95	9	14.95	11.95	10.45	14.96	17.96	
							(0,7)	52.7	0.353	0.2971	8.12	85.94	14.42	11.3	9.12	8.42	5.77	13.72	19.02	
							(0,0,7)	54.74	0.3044	0.1973	9.5	74.94	14.92	11.3	9.12	8.42	5.77	13.72	19.02	
	[M2]	10	3	6	13	13	(2,5)	34.86	0.4804	0.2664	3.53	83.75	14.33	10.80	9.53	8.33	5.93	13.14	17.94	
							(5,0,2)	41.45	0.3835	0.2124	4.93	79.22	14.77	9.84	10.93	8.77	6.85	12.60	16.44	
							(6,0,0,0)	43.58	0.3166	0.1964	8.98	62.30	18.81	9.83	15.65	12.15	10.56	15.31	18.48	
Parallel-series	3	[M1]	10	3	7	23	(6,0,0,0)	43.01	0.3381	0.2152	8.06	64.96	18.11	10.05	14.73	11.44	9.75	14.82	18.2	
							(0,0,6)	24.7	0.5605	0.3377	2.73	69.08	15	12.27	9.4	8.34	5.53	13.94	19.55	
							(0,0,0,6)	43.58	0.3166	0.1964	8.98	62.30	18.81	9.83	15.65	12.15	10.56	15.31	18.48	
For criterion [C6], the objective function is $\psi(\mathbf{R}) = c_1 E(R) + c_2 E(TTE) + c_3 (Var(E(R)) + Var(TTE) + Var(\hat{\sigma}))$.	[M1]	10	3	7	23	(6,0,1)	41.50	0.3987	0.1798	8.28	100.83	18.57	10.29	15.28	11.57	9.92	14.85	18.14		
						(0,7)	30.62	0.4589	0.2274	4.00	107.06	15.59	11.59	11.00	8.59	6.29	13.18	17.77		
						(2,0,5)	32.57	0.4217	0.2096	4.56	107.58	15.78	11.22	11.56	8.78	6.67	12.99	17.21		
	[M2]	10	3	7	23	23	(4,0,0,2)	32.68	0.3967	0.2201	4.6	65.68	15.23	10.63	11.27	8.57	6.58	12.53	16.50	
							(0,7)	47.19	0.3037	0.1824	12.89	109.98	22.93	10.04	11.89	14.41	18.96	22.00		
							(6,0,1)	41.50	0.3987	0.1798	8.28	100.83	18.57	10.29	15.28	11.57	9.92	14.85	18.14	

Table 3.6: Optimal allocations for n -component systems with Weibull distributed components when $N = 18$, by fixing $R_{\max} = 8$ with $n = 1$ and 2 under setting [M1] and [M2]

System Type	n	Setting	m	r	$E(R)$	R_{\max}	R	[C1] I	[C2] $V_{\mu} + V_{\sigma}$	[C3] V_{μ}	[C4] $\frac{[C4]}{\bar{T}TT}$	[C5] $\frac{[C5]}{\bar{T}TT}$	(1, 1, 1, 0)	(1, 0, 1, 0)	[C6] (1, 1, 0)	(0, 1, 1, 0)	(0, 1, 1, 5)	(0, 1, 2, 0)	(0, 1, 3, 0)
Series	1	[M1]	18	8	8	8	(0,1,0,0,0,0,0,0)	150.52	0.1783	0.1255	18.35	59.11	18.72	10.66	38.39	20.72	5.24	23.51	13.32
		[M2]	18	8	8	8	(0,0,0,0,0,0,0,0)	70.52	0.2683	0.1638	4.18	59.11	14.85	12.18	6.82	9.51	12.17	23.30	
	2	[M1]/[M2]	9	8	8	8	(4,4,1,0,1,0,0,0)	150.55	0.1783	0.1251	18.95	59.11	28.73	9.78	26.95	19.07	21.79	23.60	12.17
		[M1]/[M2]	9	8	8	8	(0,0,0,0,0,0,0,0)	141.87	0.1814	0.1250	18.16	59.11	27.97	9.81	26.16	19.97	21.79	23.60	12.17
2-out-of- n	3	[M1]	6	2	4	8	(0,1,0,0,0,0,0,0)	110.90	0.2050	0.1329	9.92	59.11	19.97	10.05	17.92	11.97	10.95	14.02	16.07
		[M2]	6	2	4	8	(1,0,0,0,0,0,0,0)	110.03	0.2045	0.1318	9.99	59.11	20.03	10.04	17.99	11.01	14.08	16.12	
	3	[M1]	6	2	4	8	(0,0,0,0,0,0,0,1)	95.99	0.2261	0.1427	6.76	59.11	17.02	10.26	14.76	7.89	11.28	13.54	
		[M2]	6	2	4	8	(4,0)	21.87	0.4807	0.2766	7.01	49.67	19.82	12.81	15.01	9.42	16.63	21.43	
Series-parallel	3	[M1]	6	2	3 1/3	8	(0,4)	15.14	0.7112	0.3857	3.25	34.42	18.36	11.25	10.36	6.80	17.47	24.58	24.58
		[M2]	6	2	3 1/3	8	(0,4)	21.57	0.6712	0.3497	3.25	49.71	18.32	15.11	11.25	6.80	17.47	24.58	
	3	[M1]	6	2	3 1/3	8	(2,2)	16.60	0.6294	0.3407	3.95	52.77	18.25	11.95	10.25	7.10	16.54	22.84	
		[M2]	6	2	3 1/3	8	(3,1)	18.24	0.5671	0.3105	4.77	51.56	18.44	13.67	12.77	7.61	16.11	21.78	
3	[M1]	6	2	3 1/3	8	(4,0)	11.31	0.6708	0.4379	5.70	32.60	20.41	14.71	13.70	12.41	9.06	19.12	25.83	
	[M2]	6	2	3 1/3	8	(4,0)	11.31	0.6708	0.4379	5.70	32.60	20.41	14.71	13.70	12.41	9.06	19.12	25.83	
Series-parallel	3	[M1]	6	2	3 1/3	8	(0,4)	6.94	1.1000	0.7067	2.13	35.03	21.13	19.00	10.13	13.13	7.63	24.13	35.13
		[M2]	6	2	3 1/3	8	(0,4)	6.94	1.1000	0.7067	2.13	35.03	21.13	19.00	10.13	13.13	7.63	24.13	35.13
	3	[M1]	6	2	3 1/3	8	(3,1)	8.99	0.8145	0.5141	3.55	33.70	19.70	16.15	11.55	11.70	7.62	19.84	27.99
		[M2]	6	2	3 1/3	8	(2,2)	7.91	0.9328	0.5890	2.78	34.31	20.11	17.33	10.78	7.44	21.44	30.76	

For criterion [C6], the objective function is $\psi(\mathbf{R}) = c_1 R_{\max} + c_2 E(TTE) + c_3 (Var(\mu) + Var(\hat{\sigma}))$.

3.6.3. Discussions

Based on the numerical results presented in Table 3.1, for optimality criteria [C1] (D -optimality), [C2] (A -optimality) and [C4] (\overline{TTE}), we would choose to perform the life testing experiment using individual components (i.e., $n = 1$) over other types of systems. Specifically, for optimal criterion [C1] (D -optimality) that maximizes the determinant of the expected Fisher information matrix, when $N = 30$ and $r = 6$, we would censor all 24 components at the second observed failure. In addition, for optimal criterion [C2] (A -optimality) that minimizes the sum of the asymptotic variance of the MLEs, we would choose to perform a progressively Type-II censored experiment by censoring $R_1 = 23$ and $R_6 = 1$ components at the first and last observed failures, respectively. For optimal criterion [C4] (\overline{TTE}) that minimizes the expected total time on test, the optimal scheme would censor all of the 24 components at the last observed failure, which is the conventional Type-II censoring scheme. This result agrees with our intuition as the conventional Type-II censoring scheme gives the shortest experimental time among all the progressive censoring schemes.

When we consider $E(R) = 6$ and experimental schemes that give $E(R)$ close to 6, the optimal values of the objective functions for [C1], [C2], and [C4] when using series, parallel, 2-out-of- n , series-parallel, and parallel-series systems are ($|I| = 194.48$, $V_\mu + V_\sigma = 0.1933$, $\overline{TTE} = 3.13$), ($|I| = 70.43$, $V_\mu + V_\sigma = 0.2465$, $\overline{TTE} = 6.23$), ($|I| = 80.81$, $V_\mu + V_\sigma = 0.2513$, $\overline{TTE} = 4.96$), ($|I| = 79.86$, $V_\mu + V_\sigma = 0.2471$, $\overline{TTE} = 4.48$) and ($|I| = 63.56$, $V_\mu + V_\sigma = 0.2706$, $\overline{TTE} = 6.04$), respectively. If one considers the optimal criterion [C6] that minimizes a combined cost function involving the costs due to failures and time and inaccuracy of parameter estimation, based on the choices of c_1 , c_2 , and c_3 , which are the cost per unit if failed components, the cost per unit of time for the duration of the experiment, and the cost of variance of the estimates of the unknown model parameters, respectively, putting individual components in the experiments still produce best performance compared to other settings.

Note that for series-parallel and parallel-series systems, the values of $E(R)$ are slightly larger than those for other systems, which might bring some disadvantages in comparison.

Suppose one considers the optimal criterion **[C3]** (V -optimality) that minimizes the asymptotic variance of the MLE, the optimal values of the objective function (i.e., V_μ) for **[C3]** based on series, parallel, 2-out-of- n , series-parallel, and parallel-series systems are 0.1330, 0.0980, 0.1181, 0.1381, and 0.1144, respectively. From these results, we suggest performing the progressively Type-II censored experiment by putting the 30 components into ten 3-component parallel systems and censoring eight systems at the second failure. However, the trade-off of using 3-component parallel systems for the progressively Type-II censored experiment is that the expected total time on test and the expected total experimental time based on 3-component parallel systems are the longest compared to the other systems considered here.

From Tables 3.4 and 3.5, we observe a similar pattern when the underlying component lifetimes follow Weibull distribution. For example, suppose there are 24 components available for the experiment, and we plan to fail four components. From Table 3.5, when $N = 24$, $E(R) = 4$ and the component lifetimes follow a Weibull distribution, for optimal criterion **[C3]**, the optimal experimental plan based on 3-component and 2-component parallel systems give the optimal values 0.1246 and 0.2292, respectively, while the optimal experimental plan based on individual components gives 0.2553. In other words, using 3-component and 2-component parallel systems for the progressively Type-II censored experiment provides 51.19% and 10.22% improvements, respectively, in terms of the criterion **[C3]** compared to using individual components for the experiment. However, the value of $E(R)$ based on 3-component parallel systems is 6, which is larger than the target value of $E(R) = 4$.

Instead of fixing the value of $E(R)$, in Tables 3.3 and 3.6, we compare the optimal progressive censoring schemes based on different coherent systems by fixing the value of R_{\max} . From Tables 3.3 and 3.6, we observe that for a fixed value of R_{\max} , although using

2-out-of-3 or series-parallel systems in a progressively Type-II censored experiment do not always give an advantage over using series systems; they always give shorter expected TTE and TTT for both lognormal and Weibull distributed components.

The numerical results show the advantages and disadvantages of using systems in an experiment with progressively Type-II censored samples that do not show a specific pattern. The performance depends on the type of systems, the value of $E(R)$ (or R_{\max}), and the underlying component distributions. Therefore, it is crucial to evaluate the performance of the optimal experimental plans under different types of systems and different values of n to determine the optimal experimental planning for a specific situation, and the methodologies proposed here are helpful for this purpose.

3.7. Practical Example

In this section, we use a practical example of insulating fluids testing presented in [Viveros and Balakrishnan \(1994\)](#) and [Ng et al. \(2004\)](#) to illustrate the methodologies developed in this chapter for planning a future progressively Type-II censored experiment. [Ng et al. \(2004\)](#) compared the efficiency of different progressively Type-II censoring plans with $N = 19$ components effective sample size $r = 8$ (i.e., the number of observed failures). For a future test, suppose the total number of insulating fluids available is $N = 19$, and we consider putting the insulating fluids into a n -component series system with $n = 1$ (i.e., component-wise experiment), and $n = 2$ (i.e., nine series systems).

Assuming the lifetimes of the insulating fluids follow Weibull distribution and lognormal distribution and considering the optimality criteria and settings described in [Section 3.4](#), we determine the optimal experimental plans for different optimality criteria under different settings. The optimal progressive censoring schemes for different criteria under the assumption that the component lifetimes follow Weibull and lognormal distributions are presented in [Tables 3.7 and 3.8](#), respectively.

From the results in Table 3.7, the progressively Type-II censored experimental plans based on $n = 1$ are preferred over $n = 2$ for different optimality criteria. For example, for optimality criterion [C2], the optimal value of $Var(\hat{\mu}) + Var(\hat{\sigma})$ based on setting [M2] for $n = 1$ and $n = 2$ are 0.1770 and 0.2045, respectively. For various combinations of costs c_1 , c_2 , and c_3 , the performance of optimal experimental plans for $n = 1$ still outperforms those for $n = 2$. In practice, engineers might need to do all censoring at one time in certain circumstances. Therefore, the setting [M1] (i.e., censoring all of the $m - r$ systems or components at a certain failure) can be considered instead of setting [M2] in a practical situation. If setting [M1] is considered, based on the results presented in Table 3.7, the optimal experimental plans based on $n = 1$ are still preferred over $n = 2$.

We have similar observations in Table 3.8. If we consider setting [M2], the progressively Type-II censored experimental plans with a single component ($n = 1$) consistently outperform the plans with two components ($n = 2$) across multiple criteria. For instance, for optimality criterion [C3], the optimal value of $Var(\hat{\mu})$ based on setting [M2] for $n = 1$ and $n = 2$ are 0.0958 and 0.0963, respectively. For setting [M1], if we use criteria [C3] and [C5], then using two-component systems in progressively Type-II censored experiments would yield better performance than those of using components.

Table 3.7: Optimal progressive censoring schemes for n -component series systems with Weibull distributed components when $N = 19$, by fixing $r = 8$ with $n = 1$ and 2 under settings [M1] and [M2]

n	Setting	m	r	$E(R)$	R_{\max}	R	[C1] $ I $	[C2] $Var(\hat{\mu}) + Var(\hat{\sigma})$	[C3] $Var(\hat{\mu})$	[C4] $\frac{T}{T\bar{E}}$	[C5] $\frac{T}{T\bar{T}}$	(1, 1, 10)	(1, 0, 10)	(1, 1, 10)	(1, 0, 10)	[C6] with (c_1, c_2, c_3)	(0, 1, 20)	(0, 1, 30)
1	[M1]	19	8	8	8	(11,0,0,0,0,0,0,0)	144.42	0.1826	0.1272	19.55	59.11	29.37	9.83	27.55	21.37	30.46	23.2	25.02
						(0,11,0,0,0,0,0,0)	154.11	0.1770	0.1250	18.90	59.11	28.67	9.77	26.90	20.67	19.79	22.44	24.21
	[M2]	19	8	8	8	(0,0,0,0,0,0,0,11)	78.98	0.2756	0.1743	3.90	59.11	14.66	10.76	11.9	6.66	5.28	9.41	12.17
						(0,11,0,0,0,0,0,0)	154.11	0.1770	0.1250	18.90	59.11	28.67	9.77	26.90	20.67	19.79	22.44	24.21
2	[M1]	9	8	8	8	(8,0,1,1,0,0,0,0)	140.40	0.1820	0.1250	18.03	59.11	27.85	9.82	26.03	19.85	18.94	21.67	23.49
						(0,0,0,0,0,0,11)	78.98	0.2756	0.1743	3.90	59.11	14.66	10.76	11.90	6.66	5.28	9.41	12.17
	and [M2]	9	8	8	8	(1,0,0,0,0,0,10)	81.24	0.2656	0.1671	4.16	59.11	14.82	10.66	12.16	6.82	5.49	9.47	12.13
						(0,1,0,0,0,0,0,0)	110.90	0.2050	0.1329	9.92	59.11	19.97	10.05	17.92	11.97	10.95	14.02	16.07
						(1,0,0,0,0,0,0,0)	110.03	0.2045	0.1318	9.99	59.11	20.03	10.04	17.99	12.03	11.01	14.08	16.12
						(0,0,0,0,0,0,0,1)	95.99	0.2261	0.1427	6.76	59.11	17.02	10.26	14.76	9.02	7.89	11.28	13.54

Table 3.8: Optimal progressive censoring schemes for n -component series systems with lognormal distributed components when $N = 19$, by fixing $r = 8$ with $n = 1$ and 2 under settings [M1] and [M2]

n	Setting	m	r	$E(R)$	R_{\max}	R	[C1] $ I $	[C2] $Var(\hat{\mu}) + Var(\hat{\sigma})$	[C3] $Var(\hat{\mu})$	[C4] $\frac{[C4]}{\bar{T}T\bar{E}}$	[C5] $\frac{[C5]}{\bar{T}T\bar{E}}$	(1, 1, 1, 10)	(1, 0, 10)	(1, 1, 0)	[C6] with (c_1, c_2, c_3) (0, 1, 10)	(0, 1, 5)	(0, 1, 20)	(0, 1, 30)	
1	[M1]	19	8	8	8	(0,0,11,0,0,0,0,0)	225.27	0.1543	0.1020	32.82	105.26	42.36	9.54	40.82	34.36	33.59	35.91	37.45	
						(0,11,0,0,0,0,0,0)	221.84	0.1540	0.1047	34.70	105.99	44.24	9.54	42.70	36.24	35.47	37.78	39.32	
	[M2]	19	8	8	8	(0,0,0,0,0,0,11)	186.53	0.1741	0.0975	5.92	93.61	15.66	9.74	13.92	7.66	6.79	9.40	11.14	
						(0,0,11,0,0,0,0,0)	225.27	0.1543	0.1020	32.82	105.26	42.36	9.54	40.82	34.36	33.59	35.91	37.45	
2	[M1]	9	8	8	8	(0,10,1,0,0,0,0,0)	222.06	0.1540	0.1041	34.28	105.72	43.82	9.54	42.28	35.82	35.05	37.36	38.90	
						(4,0,0,0,0,0,0,7)	191.72	0.1639	0.0958	7.64	93.02	17.28	9.64	15.64	9.28	8.46	10.92	12.56	
	and [M2]	9	8	8	8	(0,0,0,0,0,0,11)	186.53	0.1741	0.0975	5.92	93.61	15.66	9.74	13.92	7.66	6.79	9.40	11.14	
						(0,1,0,0,0,0,0,0)	200.68	0.1590	0.0976	14.76	95.39	24.35	9.59	22.76	16.35	15.56	17.94	19.33	
					(1,0,0,0,0,0,0,0)	198.19	0.1589	0.0976	14.85	95.11	24.44	9.59	22.85	16.44	15.65	18.03	19.62		
					(0,0,0,0,0,0,1,1)	192.95	0.1633	0.0963	9.71	93.42	19.34	9.63	17.71	11.34	10.52	12.97	14.61		

3.8. Concluding Remarks

In this chapter, we discuss the optimal experimental planning for progressively Type-II censored experiments when the experimental units can be put into coherent systems for the life testing experiments. The component lifetime distributions are assumed to follow a distribution in the log-location-scale family of distributions, a general class of distributions that includes some commonly used lifetime distributions, such as the Weibull and the lognormal distributions. The formulations required to obtain the optimal experimental planning are presented in terms of system signatures for different optimality criteria. Motivated by the insulating fluids testing presented in [Balakrishnan and Aggarwala \(2000\)](#) and [Ng et al. \(2004\)](#), the proposed methodologies are illustrated by the special case that the experimental units are put into series systems for the life testing experiment. The optimal progressive Type-II censoring schemes for different types of systems and different numbers of components available for the experiment are provided. We have shown that considering the use of systems formed by the test units in a progressively Type-II censored experiment provides extra flexibility in planning an experiment and gains efficiency in some situations.

In summary, the performance of utilizing systems/components in progressively Type-II censored experiments depends on the types of systems and criteria. Using systems for the experiment does not always confer advantages over using individual components, but it enhances estimation efficiency and reduces the expected total time spent on the experiment when it does prove superior. Comparing the performance of optimal experimental plans based on different coherent systems with the number of components $n > 3$ would be an intriguing avenue for further research.

CHAPTER 4

Concluding Remarks and Future Research Directions

4.1. Summaries and Concluding Remarks

In this thesis, we investigate the planning of life-testing experiments when the experimental units can be put into coherent systems. Different experimental schemes, including the multi-level constant-stress accelerated life testing scheme and the progressive Type-II censoring scheme, are considered. The advantages and disadvantages of the experimental plans based on components and systems are discussed, and practical recommendations are made based on the results obtained in this thesis. The major contributions of Chapters 2 and 3 are summarized here.

4.1.1. Major contributions of Chapter 2

In Chapter 2, we discuss the optimal experimental planning for multi-level stress experiments with Type-II censoring, where experimental units can be put into coherent systems for the life testing experiment. We assume that the component lifetime distributions belong to a log-location-scale family distribution, encompassing commonly used distributions such as Weibull and lognormal. We present formulations for obtaining optimal experimental planning for different optimality criteria. A reliability test for furniture joints is used to illustrate the proposed methodologies with series systems and a sensitivity analysis for misspecification of the underlying lifetime distribution is also provided. While using systems in multi-level constant-stress experiments with Type-II censoring does not always provide advantages, we demonstrate that it always adds flexibility, improves efficiency, and reduces

the expected total time spent on the experiment for all components in certain situations compared to using individual components.

4.1.2. Major contributions of Chapter 3

In Chapter 3, we discuss the optimal experimental planning for progressive Type-II censoring. Similar to the setting in Chapter 2, we assume the component lifetimes follow a log-location-scale family of distribution. We provide formulas for obtaining optimal experimental planning by using different types of systems with $n \leq 4$ components for various optimality criteria. We demonstrate the proposed methodologies with a reliability test with insulating fluids. While the performance of the optimal experimental plans for different types of systems under different optimality criteria are evaluated, we show that the advantages and disadvantages of using systems in progressively Type-II censored experiments vary based on the structure of the system $E(R)$ (or the maximum possible number of component failures R_{\max}), and the underlying component lifetime distribution. Based on the results obtained in this thesis, it is recommended to consider optimal progressive censoring schemes with both component-level and system-level experiments and to determine the best experimental planning strategy for a specific situation and optimal criterion.

4.2. Future Research Directions

In this thesis, we study the optimal experimental planning for multi-level and single-level stress constant-stress accelerated life test with Type-II censoring and progressive Type-II censoring in Chapters 2 and 3. The following research directions can be explored for future research on this topic.

4.2.1. Extensions to other experimental schemes

Following the study in this thesis, one potential direction is to study the optimal experimental planning for the step-stress accelerated life test (SSALT) described in Section 1.6.3. The primary interest in the optimal experimental planning for an SSALT is to determine the optimal time points for changing the stress level of the experiment when all the experimental units or the systems formed by those experimental units are placed on the life tests with the same start-up stress level.

4.2.1.1. Step-stress ALT with Type-II censoring

Consider a step-stress ALT with K stress levels, $y_1 < y_2 < \dots < y_K$, in the test with $m \times n$ experimental units and a pre-fixed stress change points $\tau_1 < \tau_2 < \dots < \tau_{K-1}$. Suppose the experimental units are put into m n -component coherent systems in which the system signature (s_1, s_2, \dots, s_n) and the minimal signature (a_1, a_2, \dots, a_n) defined in Section 1.2.2 are known. Initially, all the m coherent n -component systems are placed on the life testing experiment starting with the first stress level y_1 . At time τ_1 , the stress level is changed from y_1 to y_2 , and we denote the number of systems that failed in period $[0, \tau_1)$ as m_1 . Then, the life test continues with the remaining $m - m_1$ systems. At time τ_2 , the stress level is changed to y_3 . We denote the number of systems failed in $[\tau_1, \tau_2)$ as m_2 . The experiment continues in this manner until we reach stress level y_K , and the experiment will be terminated when the r -th system failure is observed, where r is pre-fixed (i.e., Type-II censoring). Here, we denote the total number of failures from the first k stress levels as $r_k = \sum_{q=1}^k m_q$. Since there is a positive probability that the r -th system failure (i.e., the termination time of the experiment) occurs before reaching the K -th stress level, we denote the stress level that the experiment is terminated at as k^* -th stress level, i.e.,

$$k^* = \left(\max_{k \in \{1, 2, \dots, K-1\}} \{k : r_k < r\} \right) + 1.$$

We further denote the system failure times at the k -th stress level as $T_{k1}, T_{k2}, \dots, T_{km_k}$ for $k = 1, 2, \dots, K$. Thus, the observed data are

$$\begin{aligned} & t_{11}, t_{12}, \dots, t_{1m_1}, \\ & t_{21}, t_{22}, \dots, t_{2m_2}, \dots, \dots, \\ & t_{(k^*-1)1}, t_{(k^*-1)2}, \dots, t_{(k^*-1)m_{(k^*-1)}}, \\ & t_{k^*1}, t_{k^*2}, \dots, t_{k^*(r-r_{k^*-1})}. \end{aligned}$$

4.2.1.2. Cumulative exposure model

A cumulative exposure model is commonly used to model data obtained from step-stress ALTs. This model connects the distribution of the lifetime on the current stress level with the distribution on the preceding level, assuming no effect from other stress levels. Assume the lifetimes of the experimental units (components) follow a log-location-scale distribution and hence, the log-transformed lifetimes of the experimental units working under stress level k (i.e., y_k) follow a location-scale distribution with location parameter μ_k and scale parameter σ (see, Section 1.4). We also assume the location parameter μ_k of the log-transformed component lifetimes is related to the stress levels with a linear relationship with parameters β_0 and β_1 , that is,

$$\mu_k = \beta_0 + \beta_1 y_k,$$

$k = 1, 2, \dots, K$.

We denote the PDF and SF of the log-transformed component lifetimes on the k -th stress level respectively by $f_{U_k}(\cdot; \mu_k, \sigma)$ and $\bar{F}_{U_k}(\cdot; \mu_k, \sigma)$ with location parameters μ_k and a common scale parameter σ , for $k = 1, 2, \dots, K$. For the i -th order statistics among the n

log-transformed component lifetimes in a system tested at the k -th stress level, we denote the PDF and SF of the i -th ordered component log-lifetime as $f_{i:n}^{U_k}(\cdot; \mu_k, \sigma)$ and $\bar{F}_{i:n}^{U_k}(\cdot; \mu_k, \sigma)$, respectively. Then, the PDF and SF of the log-transformed system lifetimes at the k -th stress level, denoted as $f_{V_k}(\cdot; \mu_k, \sigma)$ and $\bar{F}_{V_k}(\cdot; \mu_k, \sigma)$, respectively, for $k = 1, 2, \dots, K$, can be expressed as

$$f_{V_k}(v; \mu_k, \sigma) = \sum_{i=1}^n a_i f_{1:i}^{U_k}(v; \mu_k, \sigma) = \sum_{i=1}^n a_i i f_{U_k}(v; \mu_k, \sigma) [\bar{F}_{U_k}(v; \mu_k, \sigma)]^{i-1},$$

$$\bar{F}_{V_k}(v; \mu_k, \sigma) = \sum_{i=1}^n a_i \bar{F}_{1:i}^{U_k}(v; \mu_k, \sigma) = \sum_{i=1}^n a_i [\bar{F}_{U_k}(v; \mu_k, \sigma)]^i,$$

as presented in Section 1.4.

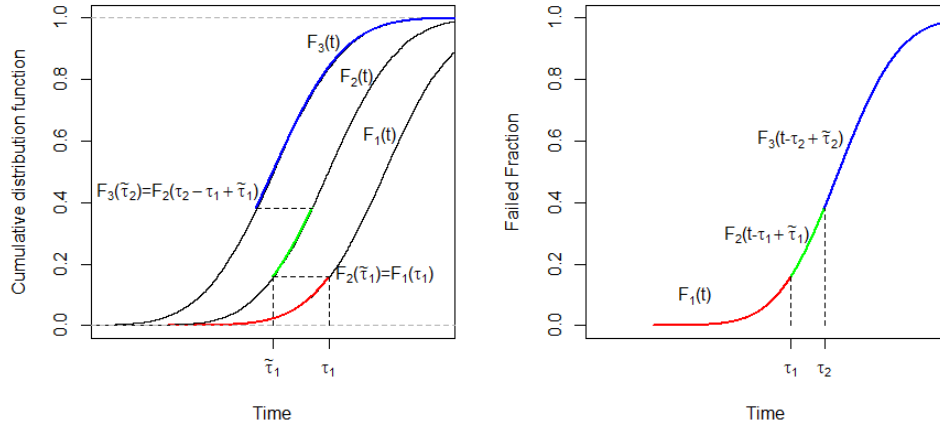


Figure 4.1: Illustration of the CDF of lifetime distribution under step-stress testing with three stress levels based on cumulative exposure model

In the step-stress ALT with Type-II censoring described in Section 4.2.1.1, we start the life test with all m coherent n -component systems at stress level y_1 , where the CDF of the log-transformed component lifetime is $F_{U_1}(u; \mu_1, \sigma)$. At time τ_1 (corresponding to log-transformed time $\ln \tau_1$), the stress level changes from y_1 to y_2 , at which the surviving systems (and the surviving components in those systems) keep running with the CDF $F_{U_2}(u; \mu_2, \sigma)$. Under the cumulative exposure model, we consider the failed fraction of those

remaining components. We assume at time $\tilde{\tau}_1$ ($0 < \tilde{\tau}_1 < \tau_1$), the component consumes the same fraction of log-lifetime with CDF $F_{U_2}(u; \mu_2, \sigma)$ as that at time $\ln \tau_1$ with CDF $F_{U_1}(u; \mu_1, \sigma)$, that is, $F_{U_1}(\ln \tau_1; \mu_1, \sigma) = F_{U_2}(\ln \tilde{\tau}_1; \mu_2, \sigma)$. Then, for any components failing at stress level y_2 , the cumulative fraction of the log-lifetime is $F_{U_2}(\ln(\exp(u) - \tau_1 + \tilde{\tau}_1); \mu_2, \sigma)$, where $F_{U_1}(\ln \tau_1; \mu_1, \sigma) = F_{U_2}(\ln \tilde{\tau}_1; \mu_2, \sigma)$.

For the first two stress levels, under the assumption that the log-lifetime distributions of the components at different stress levels are in the location-scale family of distributions with different location parameters and the same scale parameter, we have

$$\frac{\ln \tau_1 - \mu_1}{\sigma} = \frac{\ln \tilde{\tau}_1 - \mu_2}{\sigma} \implies \ln \tilde{\tau}_1 = \ln \tau_1 - \mu_1 + \mu_2 \implies \tilde{\tau}_1 = \tau_1 \exp(\mu_2 - \mu_1).$$

Similarly, at time τ_2 , the stress level changes from y_2 to y_3 . If we assume at time $\tilde{\tau}_2$ ($\tau_1 < \tilde{\tau}_2 < \tau_2$), the component consume the same fraction of log-lifetime with CDF $F_{U_3}(u; \mu_3, \sigma)$ as that at time τ_2 with CDF $F_{U_2}(u; \mu_2, \sigma)$, i.e., $F_{U_2}(\ln(\exp(u) - \tau_2 + \tilde{\tau}_2); \mu_2, \sigma)$, where $F_{U_2}(\ln(\tau_2 - \tau_1 + \tilde{\tau}_1); \mu_2, \sigma) = F_{U_3}(\ln \tilde{\tau}_2; \mu_3, \sigma)$. Then, we have $((\ln(\tau_2 - \tau_1 + \tilde{\tau}_1) - \mu_2)/\sigma = (\ln \tilde{\tau}_2 - \mu_3)/\sigma$, which leads to

$$\ln \tilde{\tau}_2 = (\ln(\tau_2 - \tau_1 + \tilde{\tau}_1) - \mu_2 + \mu_3) \implies \tilde{\tau}_2 = (\tau_2 - \tau_1 + \tilde{\tau}_1) \exp(\mu_3 - \mu_2).$$

Following the same argument, in general, we have

$$\tilde{\tau}_k = (\tau_k - \tau_{k-1} + \tilde{\tau}_{k-1}) \exp(\mu_{k+1} - \mu_k),$$

for $k = 1, 2, \dots, K - 1$. We also set $\tau_0 = 0$, $\tilde{\tau}_0 = 0$, and $\tau_K = \infty$. If we use d_k to denote the difference between τ_k and τ_{k-1} , i.e., $\tau_k - \tau_{k-1} \triangleq d_k$, we obtain

$$\begin{aligned}\tilde{\tau}_1 &= d_1 \exp(\mu_2 - \mu_1) = \tau_1 \exp(\mu_2 - \mu_1) \\ \tilde{\tau}_2 &= (d_2 + \tilde{\tau}_1) \exp(\mu_3 - \mu_2) = d_2 \exp(\mu_3 - \mu_2) + d_1 \exp(\mu_3 - \mu_1) \\ \tilde{\tau}_3 &= (d_3 + \tilde{\tau}_2) \exp(\mu_4 - \mu_3) = d_3 \exp(\mu_4 - \mu_3) + d_2 \exp(\mu_4 - \mu_2) + d_1 \exp(\mu_4 - \mu_1)\end{aligned}$$

Therefore, in general, we have

$$\tilde{\tau}_k = \sum_{p=1}^k d_p \exp(\mu_{k+1} - \mu_p) = \sum_{p=1}^k d_p \exp[\beta_1(y_{k+1} - y_p)],$$

where $k = 1, 2, \dots, K - 1$, $\tau_K = \infty$, $d_1 = \tau_1$.

After we obtain the Type-II censored system lifetime data and formulate the cumulative exposure model for step-stress ALTs, a similar concept of examining all the permutations of censored system lifetimes, as described in Chapter 2 and Chapter 3, can be applied. However, considering required permutations for step-stress ALTs with Type-II censoring is more complex than constant-stress ALTs. Special attention and caution are necessary to effectively handle the complexities of analyzing Type-II censoring data for step-stress ALTs.

4.2.2. Consider systems with a larger number of components

In this thesis, our primary objective is to determine the optimal experimental planning for a few components and a limited range of system types. This limitation is primarily due to the limited number of systems that can be used in the experiment when the number of components available for the experiment is small. For example, if we have 20 components available for the experiment, we will only have 10, 5, 4, and 2 systems if we consider 2-, 4-, 5-, and 10-component systems. It would be valuable to expand our study for future research to

study experimental planning with a larger number of components, such as hundreds or even thousands, and explore a broader range of system types. By broadening our investigation, we can obtain a more comprehensive understanding of optimal experimental planning across a greater diversity of scenarios.

4.2.3. Consider non-location-scale family of distributions

In this thesis, our focus has been on investigating optimal experimental planning based on location-scale family distributions. This choice is motivated by the flexibility of these distributions in fitting experimental data. However, for future research endeavors, we can consider exploring certain distributions from the scale-shape family, such as the gamma and Pareto distributions. It is important to note that working with scale family distributions poses challenges due to the lack of a standardized form of the distribution. Therefore, to obtain meaningful and reliable results, conducting such investigations requires careful execution due to the increased intricacies involved.

APPENDIX A

Appendix A: Terms Involved in Second Partial Derivatives of the Log-likelihood Function

$$\begin{aligned}
& \frac{\partial^2 \bar{F}_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0^2} \\
= & \left(-\frac{1}{\sigma} \frac{\partial \phi_{sev}(z_{\ell:m_k})}{\partial \beta_0} \right) \\
& \times \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(-\frac{1}{\sigma} f^*(z_{\ell:m_k}) \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_0} \right) \left[(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \right. \\
& - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \left. \right] \\
& - (n_k - j) \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_0} \right) \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2} \right] \right\} \\
= & \left(-\frac{1}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \\
& \left. - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(\frac{1}{\sigma^2} [f^*(z_{\ell:m_k})]^2 \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j \left[(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \right. \\
& \left. - (n_k - j) \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2} \right] \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 \bar{F}_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} \\
= & \left(-\frac{1}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(\frac{y_k}{\sigma^2} [f^*(z_{\ell:m_k})]^2 \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j [(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1}] \right. \\
& \left. - (n_k - j) [j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2}] \right\} \\
& \frac{\partial^2 \bar{F}_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} \\
= & \left(-\frac{1}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} + \frac{1}{\sigma^2} f^*(z_{\ell:m_k}) \right) \\
& \times \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(\frac{z_{\ell:m_k}}{\sigma^2} [f^*(z_{\ell:m_k})]^2 \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j [(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1}] \right. \\
& \left. - (n_k - j) [j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2}] \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 \bar{F}_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_1^2} \\
= & \left(-\frac{y_k}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} \right) \\
& \times \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(\frac{y_k^2}{\sigma^2} [f^*(z_{\ell:m_k})]^2 \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j [(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1}] \right. \\
& \left. - (n_k - j) [j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2}] \right\} \\
& \frac{\partial^2 \bar{F}_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} \\
= & \left(-\frac{y_k}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} + \frac{y_k}{\sigma^2} f^*(z_{\ell:m_k}) \right) \\
& \times \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(\frac{y_k z_{\ell:m_k}}{\sigma^2} [f^*(z_{\ell:m_k})]^2 \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j [(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1}] \right. \\
& \left. - (n_k - j) [j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2}] \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 \bar{F}_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \sigma^2} \\
= & \left(-\frac{z_{\ell:m_k}}{\sigma} \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} + \frac{2z_{\ell:m_k}}{\sigma^2} f^*(z_{\ell:m_k}) \right) \\
& \times \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} - [F^*(z_{\ell:m_k})]^j (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \\
& + \left(\frac{z_{\ell:m_k}^2}{\sigma^2} [f^*(z_{\ell:m_k})]^2 \right) \sum_{i=1}^{n_k} s_{ki} \sum_j^{i-1} \binom{n_k}{j} \\
& \left\{ j \left[(j-1) [F^*(z_{\ell:m_k})]^{j-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j} \right. \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^{j-1} (n_k - j) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right] \right. \\
& \left. - (n_k - j) \left[j [F^*(z_{\ell:m_k})]^{j-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-1} \right. \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^j (n_k - j - 1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-j-2} \right] \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0^2} \\
= & \frac{1}{\sigma} \left\{ \frac{\partial^2 f^*(z_{\ell:m_k})}{\partial \beta_0^2} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& + \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_0} \right) \\
& \times \left. \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right\} \\
& - \frac{1}{\sigma^2} \left\{ 2f^*(z_{\ell:m_k}) \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right. \\
& + (f^*(z_{\ell:m_k}))^2 \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_0} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \\
& \left[[(i-1)(i-2) [F^*(z_{\ell:m_k})]^{i-3} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& \left. - (i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \\
& \left. - [(i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right. \\
& \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i)(n_k-i-1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-2} \right] \left. \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} \\
= & \frac{1}{\sigma} \left\{ \frac{\partial^2 f^*(z_{\ell:m_k})}{\partial \beta_0 \partial \beta_1} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& + \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_1} \right) \\
& \times \left. \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right\} \\
& - \frac{1}{\sigma^2} \left\{ 2f^*(z_{\ell:m_k}) \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right. \\
& + (f^*(z_{\ell:m_k}))^2 \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_1} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \\
& \left[[(i-1)(i-2) [F^*(z_{\ell:m_k})]^{i-3} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& \left. - (i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \\
& \left. - [(i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right. \\
& \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i)(n_k-i-1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-2} \right] \left. \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} \\
= & \frac{1}{\sigma^2} \left\{ \left[\frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} + \sigma \frac{\partial^2 f^*(z_{\ell:m_k})}{\partial \beta_0 \partial \sigma} \right] \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& + \sigma \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \sigma} \right) \\
& \times \left. \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right\} \\
& - \frac{1}{\sigma^2} \left\{ 2f^*(z_{\ell:m_k}) \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \right. \\
& - \left. \left. [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right. \\
& + (f^*(z_{\ell:m_k}))^2 \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \sigma} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \\
& \left[[(i-1)(i-2) [F^*(z_{\ell:m_k})]^{i-3} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& - (i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \\
& - [(i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \\
& \left. \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i)(n_k-i-1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-2} \right] \right\} \\
& + \left(-\frac{2}{\sigma} \right) \frac{\partial f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_0}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_1^2} \\
= & \frac{1}{\sigma} \left\{ \frac{\partial^2 f^*(z_{\ell:m_k})}{\partial \beta_1^2} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& + \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_1} \right) \\
& \times \left. \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right\} \\
& - \frac{y_k}{\sigma^2} \left\{ 2f^*(z_{\ell:m_k}) \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_0} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right. \\
& + (f^*(z_{\ell:m_k}))^2 \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \beta_1} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \\
& \left[[(i-1)(i-2) [F^*(z_{\ell:m_k})]^{i-3} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& \left. - (i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \\
& \left. - [(i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right. \\
& \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i)(n_k-i-1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-2} \right] \left. \right\}
\end{aligned}$$

$$\begin{aligned}
& \frac{\partial^2 f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} \\
= & \frac{1}{\sigma^2} \left\{ \left[\frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} + \sigma \frac{\partial^2 f^*(z_{\ell:m_k})}{\partial \beta_1 \partial \sigma} \right] \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& + \sigma \frac{\partial f^*(z_{\ell:m_k})}{\partial \beta_1} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \sigma} \right) \\
& \times \left. \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right\} \\
& - \frac{y_k}{\sigma^2} \left\{ 2f^*(z_{\ell:m_k}) \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1) [F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \right. \\
& \left. \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right. \\
& + (f^*(z_{\ell:m_k}))^2 \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \sigma} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \\
& \left[[(i-1)(i-2) [F^*(z_{\ell:m_k})]^{i-3} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
& \left. - (i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \\
& \left. - [(i-1) [F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right. \\
& \left. - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i)(n_k-i-1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-2} \right] \left. \right\} \\
& + \left(-\frac{2}{\sigma} \right) \frac{\partial f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \beta_1}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 f_{V_k}(v_{\ell:m_k}; \boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma^2} \left\{ \left[\sigma \frac{\partial^2 f^*(z_{\ell:m_k})}{\partial \sigma^2} \right] \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i [F^*(z_{\ell:m_k})]^{i-1} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
&+ \left[\sigma \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} - f^*(z_{\ell:m_k}) \right] \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \sigma} \right) \\
&\times \left. \left[(i-1)[F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} - [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \right\} \\
&- \frac{1}{\sigma^2} \left\{ \left[-\frac{z_{\ell:m_k}}{\sigma} (f^*(z_{\ell:m_k}))^2 + z_{\ell:m_k} 2f^*(z_{\ell:m_k}) \frac{\partial f^*(z_{\ell:m_k})}{\partial \sigma} \right] \right. \\
&\times \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \left[(i-1)[F^*(z_{\ell:m_k})]^{i-2} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
&- \left. [F^*(z_{\ell:m_k})]^{i-1} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \right] \\
&+ z_{\ell:m_k} (f^*(z_{\ell:m_k}))^2 \left(\frac{\partial F^*(z_{\ell:m_k})}{\partial \sigma} \right) \sum_{i=1}^{n_k} s_{ki} \binom{n_k}{i} i \\
&\left[[(i-1)(i-2)[F^*(z_{\ell:m_k})]^{i-3} [\bar{F}^*(z_{\ell:m_k})]^{n_k-i} \right. \\
&- (i-1)[F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \\
&- [(i-1)[F^*(z_{\ell:m_k})]^{i-2} (n_k-i) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-1} \\
&- \left. \left. [F^*(z_{\ell:m_k})]^{i-1} (n_k-i)(n_k-i-1) [\bar{F}^*(z_{\ell:m_k})]^{n_k-i-2} \right] \right] \left. \right\} \\
&+ \left(-\frac{2}{\sigma} \right) \frac{\partial f_{T_k}(t_{k\ell}; \boldsymbol{\theta})}{\partial \sigma}
\end{aligned}$$

APPENDIX B

Appendix B: First and second derivatives of the PDF and CDF of standard normal distribution

$$\begin{aligned}
 C_{10}(z) &= \frac{\partial \Phi_{nor}(z)}{\partial \beta_0} = -\frac{1}{\sigma} \phi_{nor}(z) & P_{10}(z) &= \frac{\partial \phi_{nor}(z)}{\partial \beta_0} = \frac{z}{\sigma} \phi_{nor}(z) \\
 C_{20}(z) &= \frac{\partial \Phi_{nor}(z)}{\partial \beta_1} = -\frac{y}{\sigma} \phi_{nor}(z) & P_{20}(z) &= \frac{\partial \phi_{nor}(z)}{\partial \beta_1} = \frac{zy}{\sigma} \phi_{nor}(z) \\
 C_{30}(z) &= \frac{\partial \Phi_{nor}(z)}{\partial \sigma} = -\frac{z}{\sigma} \phi_{nor}(z) & P_{30}(z) &= \frac{\partial \phi_{nor}(z)}{\partial \sigma} = \frac{z^2}{\sigma} \phi_{nor}(z) \\
 C_{11}(z) &= \frac{\partial^2 \Phi_{nor}(z)}{\partial \beta_0^2} = -\frac{z}{\sigma^2} \phi_{nor}(z) & P_{11}(z) &= \frac{\partial^2 \phi_{nor}(z)}{\partial \beta_0^2} = \frac{z^2 - 1}{\sigma^2} \phi_{nor}(z) \\
 C_{12}(z) &= \frac{\partial^2 \Phi_{nor}(z)}{\partial \beta_0 \partial \beta_1} = -\frac{zy}{\sigma^2} \phi_{nor}(z) & P_{12}(z) &= \frac{\partial^2 \phi_{nor}(z)}{\partial \beta_0 \partial \beta_1} = \frac{(z^2 - 1)y}{\sigma^2} \phi_{nor}(z) \\
 C_{13}(z) &= \frac{\partial^2 \Phi_{nor}(z)}{\partial \beta_0 \partial \sigma} = -\frac{z^2 - 1}{\sigma^2} \phi_{nor}(z) & P_{13}(z) &= \frac{\partial^2 \phi_{nor}(z)}{\partial \beta_0 \partial \sigma} = \frac{z^3 - 2z}{\sigma^2} \phi_{nor}(z) \\
 C_{22}(z) &= \frac{\partial^2 \Phi_{nor}(z)}{\partial \beta_1^2} = -\frac{zy^2}{\sigma^2} \phi_{nor}(z) & P_{22}(z) &= \frac{\partial^2 \phi_{nor}(z)}{\partial \beta_1^2} = \frac{(z^2 - 1)y^2}{\sigma^2} \phi_{nor}(z) \\
 C_{23}(z) &= \frac{\partial^2 \Phi_{nor}(z)}{\partial \beta_1 \partial \sigma} = -\frac{z^2 y - y}{\sigma^2} \phi_{nor}(z) & P_{23}(z) &= \frac{\partial^2 \phi_{nor}(z)}{\partial \beta_1 \partial \sigma} = \frac{zy(z^2 - 2)}{\sigma^2} \phi_{nor}(z) \\
 C_{33}(z) &= \frac{\partial^2 \Phi_{nor}(z)}{\partial \sigma^2} = -\frac{z^3 - 2z}{\sigma^2} \phi_{nor}(z) & P_{33}(z) &= \frac{\partial^2 \phi_{nor}(z)}{\partial \sigma^2} = \frac{z^4 - 3z^2}{\sigma^2} \phi_{nor}(z)
 \end{aligned}$$

APPENDIX C

Appendix C: First and second derivatives of the PDF and CDF of standard SEV
distribution

$$\begin{aligned}
 C_{10}(z) &= \frac{\partial \Phi_{sev}(z)}{\partial \beta_0} = -\frac{1}{\sigma} \phi_{sev}(z) \\
 C_{20}(z) &= \frac{\partial \Phi_{sev}(z)}{\partial \beta_1} = -\frac{y}{\sigma} \phi_{sev}(z) \\
 C_{30}(z) &= \frac{\partial \Phi_{sev}(z)}{\partial \sigma} = -\frac{z}{\sigma} \phi_{sev}(z) \\
 C_{11}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \beta_0^2} = -\frac{(e^z - 1)}{\sigma^2} \phi_{sev}(z) \\
 C_{12}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \beta_0 \partial \beta_1} = -\frac{(e^z - 1)y}{\sigma^2} \phi_{sev}(z) \\
 C_{13}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \beta_0 \partial \sigma} = -\frac{ze^z - z - 1}{\sigma^2} \phi_{sev}(z) \\
 C_{22}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \beta_1^2} = -\frac{(e^z - 1)y^2}{\sigma^2} \phi_{sev}(z) \\
 C_{23}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \beta_1 \partial \sigma} = -\frac{(ze^z - z - 1)y}{\sigma^2} \phi_{sev}(z) \\
 C_{33}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \sigma^2} = -\frac{z(ze^z - z - 2)}{\sigma^2} \phi_{sev}(z) \\
 P_{10}(z) &= \frac{\partial \phi_{sev}(z)}{\partial \beta_0} = \frac{(e^z - 1)}{\sigma} \phi_{sev}(z) \\
 P_{20}(z) &= \frac{\partial \phi_{sev}(z)}{\partial \beta_1} = \frac{(e^z - 1)y}{\sigma} \phi_{sev}(z) \\
 P_{30}(z) &= \frac{\partial \phi_{sev}(z)}{\partial \sigma} = \frac{(e^z - 1)z}{\sigma} \phi_{sev}(z) \\
 P_{11}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \beta_0^2} = \frac{(e^{2z} - 3e^z + 1)}{\sigma^2} \phi_{sev}(z) \\
 P_{12}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \beta_0 \partial \beta_1} = \frac{((e^{2z} - 3e^z + 1)y)}{\sigma^2} \phi_{sev}(z) \\
 P_{13}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \beta_0 \partial \sigma} = \frac{(ze^{2z} - 3ze^z - 2e^z + z + 1)}{\sigma^2} \phi_{sev}(z) \\
 P_{22}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \beta_1^2} = \frac{(e^{2z} - 3e^z + 1)y^2}{\sigma^2} \phi_{sev}(z) \\
 P_{23}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \beta_1 \partial \sigma} = \frac{y(ze^{2z} - 3ze^z - 2e^z + z + 1)}{\sigma^2} \phi_{sev}(z) \\
 P_{33}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \sigma^2} = \frac{z(ze^{2z} - 3ze^z - 2e^z + z + 2)}{\sigma^2} \phi_{sev}(z)
 \end{aligned}$$

APPENDIX D

Appendix D: Fisher Information Matrix for Series Systems

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0^2} &= n \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-A^{-2}(z_{\ell:m_k}) A_1^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{11}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. - r \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_1^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{11}(z_{\ell:m_k}) \right] \right\} \\
&\quad + \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-B^{-2}(z_{\ell:m_k}) B_1^2(z_{\ell:m_k}) + B^{-1}(z_{\ell:m_k}) B_{11}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. + A^{-2}(z_{\ell:m_k}) A_1^2(z_{\ell:m_k}) - A^{-1}(z_{\ell:m_k}) A_{11}(z_{\ell:m_k}) \right] \\
&\quad \left. + \frac{N}{2} \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_1^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{11}(z_{\ell:m_k}) \right] \right\} \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1^2} &= n \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-A^{-2}(z_{\ell:m_k}) A_2^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{22}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. - r \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_2^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{22}(z_{\ell:m_k}) \right] \right\} \\
&\quad + \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-B^{-2}(z_{\ell:m_k}) B_2^2(z_{\ell:m_k}) + B^{-1}(z_{\ell:m_k}) B_{22}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. + A^{-2}(z_{\ell:m_k}) A_2^2(z_{\ell:m_k}) - A^{-1}(z_{\ell:m_k}) A_{22}(z_{\ell:m_k}) \right] \\
&\quad \left. + \frac{N}{2} \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_2^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{22}(z_{\ell:m_k}) \right] \right\}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= n \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-A^{-2}(z_{\ell:m_k}) A_3^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{33}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. - r \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_3^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{33}(z_{\ell:m_k}) \right] \right\} \\
&\quad + \left\{ \frac{1}{\sigma^2} + \sum_{k=1}^K \sum_{\ell=1}^r \left[-B^{-2}(z_{\ell:m_k}) B_3^2(z_{\ell:m_k}) + B^{-1}(z_{\ell:m_k}) B_{33}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. + A^{-2}(z_{\ell:m_k}) A_3^2(z_{\ell:m_k}) - A^{-1}(z_{\ell:m_k}) A_{33}(z_{\ell:m_k}) \right] \\
&\quad \left. + \frac{N}{2} \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_3^2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{33}(z_{\ell:m_k}) \right] \right\}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} &= n \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{12}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. - r \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{12}(z_{\ell:m_k}) \right] \right\} \\
&\quad + \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-B^{-2}(z_{\ell:m_k}) B_1(z_{\ell:m_k}) B_2(z_{\ell:m_k}) + B^{-1}(z_{\ell:m_k}) B_{12}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. + -A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{12}(z_{\ell:m_k}) \right] \\
&\quad \left. + \frac{N}{2} \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_2(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{12}(z_{\ell:m_k}) \right] \right\}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_0 \partial \sigma} &= n \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{13}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. - r \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{13}(z_{\ell:m_k}) \right] \right\} \\
&\quad + \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-B^{-2}(z_{\ell:m_k}) B_1(z_{\ell:m_k}) B_3(z_{\ell:m_k}) + B^{-1}(z_{\ell:m_k}) B_{13}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. + -A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{13}(z_{\ell:m_k}) \right] \\
&\quad \left. + \frac{N}{2} \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_1(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{13}(z_{\ell:m_k}) \right] \right\}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \beta_1 \partial \sigma} &= n \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-A^{-2}(z_{\ell:m_k}) A_2(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{23}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. - r \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_2(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{23}(z_{\ell:m_k}) \right] \right\} \\
&\quad + \left\{ \sum_{k=1}^K \sum_{\ell=1}^r \left[-B^{-2}(z_{\ell:m_k}) B_2(z_{\ell:m_k}) B_3(z_{\ell:m_k}) + B^{-1}(z_{\ell:m_k}) B_{23}(z_{\ell:m_k}) \right] \right. \\
&\quad \left. + -A^{-2}(z_{\ell:m_k}) A_2(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{23}(z_{\ell:m_k}) \right] \\
&\quad \left. + \frac{N}{2} \sum_{k=1}^K \left[-A^{-2}(z_{\ell:m_k}) A_2(z_{\ell:m_k}) A_3(z_{\ell:m_k}) + A^{-1}(z_{\ell:m_k}) A_{23}(z_{\ell:m_k}) \right] \right\}
\end{aligned}$$

APPENDIX E

Appendix E: First and second derivatives of the PDF and CDF of standard Normal distribution

$$CC_{10}(z) = \frac{\partial \Phi_{nor}(z)}{\partial \mu} = -\frac{1}{\sigma} \phi_{nor}(z)$$

$$CC_{20}(z) = \frac{\partial \Phi_{nor}(z)}{\partial \sigma} = -\frac{z}{\sigma} \phi_{nor}(z)$$

$$CC_{11}(z) = \frac{\partial^2 \Phi_{nor}(z)}{\partial \mu^2} = -\frac{z}{\sigma^2} \phi_{nor}(z)$$

$$CC_{12}(z) = \frac{\partial^2 \Phi_{nor}(z)}{\partial \mu \partial \sigma} = -\frac{z^2 - 1}{\sigma^2} \phi_{nor}(z)$$

$$CC_{22}(z) = \frac{\partial^2 \Phi_{nor}(z)}{\partial \sigma^2} = -\frac{z^3 - 2z}{\sigma^2} \phi_{nor}(z)$$

$$PP_{10}(z) = \frac{\partial \phi_{nor}(z)}{\partial \mu} = \frac{z}{\sigma} \phi_{nor}(z)$$

$$PP_{20}(z) = \frac{\partial \phi_{nor}(z)}{\partial \sigma} = \frac{z^2}{\sigma} \phi_{nor}(z)$$

$$PP_{11}(z) = \frac{\partial^2 \phi_{nor}(z)}{\partial \mu^2} = \frac{z^2 - 1}{\sigma^2} \phi_{nor}(z)$$

$$PP_{12}(z) = \frac{\partial^2 \phi_{nor}(z)}{\partial \mu \partial \sigma} = \frac{z^3 - 2z}{\sigma^2} \phi_{nor}(z)$$

$$PP_{22}(z) = \frac{\partial^2 \phi_{nor}(z)}{\partial \sigma^2} = \frac{z^4 - 3z^2}{\sigma^2} \phi_{nor}(z)$$

APPENDIX F

Appendix F: First and second derivatives of the PDF and CDF of standard SEV
distribution

$$\begin{aligned}
 CC_{10}(z) &= \frac{\partial \Phi_{sev}(z)}{\partial \mu} = -\frac{1}{\sigma} \phi_{sev}(z) \\
 CC_{20}(z) &= \frac{\partial \Phi_{sev}(z)}{\partial \sigma} = -\frac{z}{\sigma} \phi_{sev}(z) \\
 CC_{11}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \mu^2} = -\frac{(e^z - 1)}{\sigma^2} \phi_{sev}(z) \\
 CC_{12}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \mu \partial \sigma} = -\frac{ze^z - z - 1}{\sigma^2} \phi_{sev}(z) \\
 CC_{22}(z) &= \frac{\partial^2 \Phi_{sev}(z)}{\partial \sigma^2} = -\frac{z(ze^z - z - 2)}{\sigma^2} \phi_{sev}(z) \\
 PP_{10}(z) &= \frac{\partial \phi_{sev}(z)}{\partial \mu} = \frac{(e^z - 1)}{\sigma} \phi_{sev}(z) \\
 PP_{20}(z) &= \frac{\partial \phi_{sev}(z)}{\partial \sigma} = \frac{(e^z - 1)z}{\sigma} \phi_{sev}(z) \\
 PP_{11}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \mu^2} = \frac{(e^{2z} - 3e^z + 1)}{\sigma^2} \phi_{sev}(z) \\
 PP_{12}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \mu \partial \sigma} = \frac{(ze^{2z} - 3ze^z - 2e^z + z + 1)}{\sigma^2} \phi_{sev}(z) \\
 PP_{22}(z) &= \frac{\partial^2 \phi_{sev}(z)}{\partial \sigma^2} = \frac{z(ze^{2z} - 3ze^z - 2e^z + z + 2)}{\sigma^2} \phi_{sev}(z)
 \end{aligned}$$

APPENDIX G

Appendix G: Detailed Formula for LogNormal Distribution with Various Types of Systems

G.1. $l = 1$

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}}{\sigma} + \frac{R_{\ell}n + n - 1}{\sigma} \frac{\phi_{nor}(z_{\ell:r:m})}{\bar{\Phi}_{nor}(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{z_{\ell:r:m}^2}{\sigma} + \frac{z_{\ell:r:m}(R_{\ell}n + n - 1)}{\sigma} \frac{\phi_{nor}(z_{\ell:r:m})}{\bar{\Phi}_{nor}(z_{\ell:r:m})} \right].\end{aligned}$$

So the likelihood equations for μ and σ are, respectively,

$$\begin{aligned}\sum_{\ell=1}^r z_{\ell:r:m} + \sum_{\ell=1}^r (R_{\ell}n + n - 1) \frac{\phi_{nor}(z_{\ell:r:m})}{\bar{\Phi}_{nor}(z_{\ell:r:m})} &= 0; \\ -r + \sum_{\ell=1}^r z_{\ell:r:m}^2 + \sum_{\ell=1}^r (R_{\ell}n + n - 1) z_{\ell:r:m} \frac{\phi_{nor}(z_{\ell:r:m})}{\bar{\Phi}_{nor}(z_{\ell:r:m})} &= 0.\end{aligned}$$

From the log-likelihood function, the second derivatives forming the observed Fisher Information are

$$\begin{aligned}\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= -\frac{r}{\sigma^2} + \frac{1}{\sigma^2} \sum_{\ell=1}^r (R_{\ell}n + n - 1) \frac{z_{\ell:r:m} \phi_{nor}(z_{\ell:r:m}) \bar{\Phi}_{nor}(z_{\ell:r:m}) - \phi_{nor}^2(z_{\ell:r:m})}{\bar{\Phi}_{nor}^2(z_{\ell:r:m})} \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= -\frac{2}{\sigma^2} \sum_{\ell=1}^r z_{\ell:r:m} - \frac{1}{\sigma^2} \sum_{\ell=1}^r (R_{\ell}n + n - 1) \frac{\phi_{nor}(z_{\ell:r:m})}{\bar{\Phi}_{nor}(z_{\ell:r:m})} \\ &\quad + \frac{1}{\sigma^2} \sum_{\ell=1}^r (R_{\ell}n + n - 1) z_{\ell:r:m} \frac{z_{\ell:r:m} \phi_{nor}(z_{\ell:r:m}) \bar{\Phi}_{nor}(z_{\ell:r:m}) - \phi_{nor}^2(z_{\ell:r:m})}{\bar{\Phi}_{nor}^2(z_{\ell:r:m})} \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{r}{\sigma^2} - \frac{3}{\sigma^2} \sum_{\ell=1}^r z_{\ell:r:m}^2 - \frac{2}{\sigma^2} \sum_{\ell=1}^r (R_{\ell}n + n - 1) z_{\ell:r:m} \frac{\phi_{nor}(z_{\ell:r:m})}{\bar{\Phi}_{nor}(z_{\ell:r:m})} \\ &\quad + \frac{1}{\sigma^2} \sum_{\ell=1}^r (R_{\ell}n + n - 1) z_{\ell:r:m}^2 \frac{z_{\ell:r:m} \phi_{nor}(z_{\ell:r:m}) \bar{\Phi}_{nor}(z_{\ell:r:m}) - \phi_{nor}^2(z_{\ell:r:m})}{\bar{\Phi}_{nor}^2(z_{\ell:r:m})}.\end{aligned}$$

We can obtain optimal planning with two methods. The first method uses approximation with Taylor series expansion. The approximated first and second partial derivatives of the log-likelihood function involved in the MLEs and Fisher information matrix are described and presented in Appendix F. The second method uses the Monte Carlo integration, similar to what we do in Chapter 2.

G.2. $l = n$

The likelihood equations for μ and σ are, respectively,

$$\sum_{\ell=1}^r \left[z_{\ell:r:m} + \frac{(R_{\ell}n + n - 1) [\Phi_{nor}(z_{\ell:r:m})]^n - (n - 1) \phi_{nor}(z_{\ell:r:m})}{1 - [\Phi_{nor}(z_{\ell:r:m})]^n} \frac{\phi_{nor}(z_{\ell:r:m})}{\Phi_{nor}(z_{\ell:r:m})} \right] = 0;$$

$$\sum_{\ell=1}^r \left[-1 + z_{\ell:r:m}^2 + \frac{z_{\ell:r:m} [(R_{\ell}n + n - 1) [\Phi_{nor}(z_{\ell:r:m})]^n - (n - 1)] \phi_{nor}(z_{\ell:r:m})}{1 - [\Phi_{nor}(z_{\ell:r:m})]^n} \frac{\phi_{nor}(z_{\ell:r:m})}{\Phi_{nor}(z_{\ell:r:m})} \right] = 0.$$

Let

$$p_1 \triangleq R_{\ell}n + n - 1$$

$$p_2 \triangleq n - 1,$$

then we have

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} = \frac{1}{\sigma} \sum_{\ell=1}^r \left[z_{\ell:r:m} + \frac{p_1 [\Phi_{nor}(z_{\ell:r:m})]^n - p_2 \phi_{nor}(z_{\ell:r:m})}{1 - [\Phi_{nor}(z_{\ell:r:m})]^n} \frac{\phi_{nor}(z_{\ell:r:m})}{\Phi_{nor}(z_{\ell:r:m})} \right]$$

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} = \frac{1}{\sigma} \sum_{\ell=1}^r \left[-1 + z_{\ell:r:m}^2 + z_{\ell:r:m} \frac{p_1 [\Phi_{nor}(z_{\ell:r:m})]^n - p_2 \phi_{nor}(z_{\ell:r:m})}{1 - [\Phi_{nor}(z_{\ell:r:m})]^n} \frac{\phi_{nor}(z_{\ell:r:m})}{\Phi_{nor}(z_{\ell:r:m})} \right].$$

Suppose

$$g(z) = \frac{p_1 [\Phi_{nor}(z)]^n - p_2 \phi_{nor}(z)}{1 - [\Phi_{nor}(z)]^n} \frac{\phi_{nor}(z)}{\Phi_{nor}(z)} = \frac{p_1 \phi_{nor}(z) [\Phi_{nor}(z)]^n - p_2 \phi_{nor}(z)}{\Phi_{nor}(z) - [\Phi_{nor}(z)]^{n+1}},$$

then we have

$$\begin{aligned}\frac{\partial g(z)}{\partial \mu} &= \frac{1}{\sigma} \left[z g(z) + [\phi_{nor}(z)]^2 \frac{p_2(2 - Rn) [\Phi_{nor}(z)]^n - p_1 [\Phi_{nor}(z)]^{2n} - p_2}{[\Phi_{nor}(z) - [\Phi_{nor}(z)]^{n+1}]^2} \right] \\ \frac{\partial g(z)}{\partial \sigma} &= \frac{z}{\sigma} \left[z g(z) + [\phi_{nor}(z)]^2 \frac{p_2(2 - Rn) [\Phi_{nor}(z)]^n - p_1 [\Phi_{nor}(z)]^{2n} - p_2}{[\Phi_{nor}(z) - [\Phi_{nor}(z)]^{n+1}]^2} \right].\end{aligned}$$

We can also obtain

$$\begin{aligned}\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{\partial g(z_{\ell:r:m})}{\partial \mu} \right] \\ &= \frac{1}{\sigma^2} \sum_{\ell=1}^r \left[z_{\ell:r:m} g(z_{\ell:r:m}) + [\phi_{nor}(z_{\ell:r:m})]^2 \frac{p_2(2 - Rn) [\Phi_{nor}(z_{\ell:r:m})]^n - p_1 [\Phi_{nor}(z_{\ell:r:m})]^{2n} - p_2}{[\Phi_{nor}(z_{\ell:r:m}) - [\Phi_{nor}(z_{\ell:r:m})]^{n+1}]^2} - 1 \right] \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[-\frac{2z_{\ell:r:m}}{\sigma} + z_{\ell:r:m} \frac{\partial g(z_{\ell:r:m})}{\partial \mu} - \frac{g(z_{\ell:r:m})}{\sigma} \right] \\ &= \frac{1}{\sigma^2} \sum_{\ell=1}^r \left[(z_{\ell:r:m}^2 - 1) g(z_{\ell:r:m}) + z_{\ell:r:m} [\phi_{nor}(z_{\ell:r:m})]^2 \frac{p_2(2 - Rn) [\Phi_{nor}(z_{\ell:r:m})]^n - p_1 [\Phi_{nor}(z_{\ell:r:m})]^{2n} - p_2}{[\Phi_{nor}(z_{\ell:r:m}) - [\Phi_{nor}(z_{\ell:r:m})]^{n+1}]^2} \right. \\ &\quad \left. - 2z_{\ell:r:m} \right] \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[-2z_{\ell:r:m} \frac{z_{\ell:r:m}}{\sigma} + z_{\ell:r:m} \frac{\partial g(z_{\ell:r:m})}{\partial \sigma} + \left(-\frac{z_{\ell:r:m}}{\sigma}\right) g(z_{\ell:r:m}) \right] \\ &\quad - \frac{1}{\sigma^2} \sum_{\ell=1}^r [-1 + z_{\ell:r:m}^2 + z_{\ell:r:m} g(z_{\ell:r:m})] \\ &= \frac{1}{\sigma^2} \sum_{\ell=1}^r \left[z_{\ell:r:m}^3 g(z_{\ell:r:m}) + z_{\ell:r:m}^2 [\phi_{nor}(z_{\ell:r:m})]^2 \frac{p_2(2 - Rn) [\Phi_{nor}(z_{\ell:r:m})]^n - p_1 [\Phi_{nor}(z_{\ell:r:m})]^{2n} - p_2}{[\Phi_{nor}(z_{\ell:r:m}) - [\Phi_{nor}(z_{\ell:r:m})]^{n+1}]^2} \right. \\ &\quad \left. - 2z_{\ell:r:m} g(z_{\ell:r:m}) - 3z_{\ell:r:m}^2 + 1 \right].\end{aligned}$$

G.3. 2-out-of- n

With lognormal distributed components, if we use the following

$$g_1(z_{\ell:r:m}) = \Phi_{nor}(z_{\ell:r:m}) [1 - \Phi_{nor}(z_{\ell:r:m})]^{n-2}$$

$$\text{and } g_2(z_{\ell:r:m}) = [1 - \Phi_{nor}(z_{\ell:r:m})]^n + n [\Phi_{nor}(z_{\ell:r:m})] [1 - \Phi_{nor}(z_{\ell:r:m})]^{n-1},$$

we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}^2 - 1}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{(n-2)\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1-\Phi_{nor}(z_{\ell:r:m})]^{n-3}}{\sigma} \\ &\quad - \frac{\phi_{nor}(z_{\ell:r:m})[1-\Phi_{nor}(z_{\ell:r:m})]^{n-2}}{\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{(n-2)z_{\ell:r:m}\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1-\Phi_{nor}(z_{\ell:r:m})]^{n-3}}{\sigma} \\ &\quad - \frac{z_{\ell:r:m}\phi_{nor}(z_{\ell:r:m})[1-\Phi_{nor}(z_{\ell:r:m})]^{n-2}}{\sigma}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{n(n-1)\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1-\Phi_{nor}(z_{\ell:r:m})]^{n-2}}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{n(n-1)z_{\ell:r:m}\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1-\Phi_{nor}(z_{\ell:r:m})]^{n-2}}{\sigma}.\end{aligned}$$

Then, we have

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{2z_{\ell:r:m}}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - 3z_{\ell:r:m}^2}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right].
\end{aligned}$$

When $n = 3$, the explicit formula are given by

$$\begin{aligned}
\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) - \phi_{nor}(z_{\ell:r:m})}{\sigma} \\
\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{z_{\ell:r:m} [2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) - \phi_{nor}(z_{\ell:r:m})]}{\sigma}, \\
\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{6\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) [1 - \Phi_{nor}(z_{\ell:r:m})]}{\sigma} \\
\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{z_{\ell:r:m} 6\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) [1 - \Phi_{nor}(z_{\ell:r:m})]}{\sigma},
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[2\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m} - 2\phi_{nor}^2(z_{\ell:r:m})}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})[2\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}^2 - 2\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m})[2\Phi_{nor}(z_{\ell:r:m}) - 1]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[2\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}^3 - 2\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m})[2\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}}{\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{6\phi_{nor}(z_{\ell:r:m})(-[\Phi_{nor}(z_{\ell:r:m})]^2 + [\Phi_{nor}(z_{\ell:r:m})])z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{6\phi_{nor}^2(z_{\ell:r:m})(2\Phi_{nor}(z_{\ell:r:m}) - 1)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{6\phi_{nor}(z_{\ell:r:m})(-[\Phi_{nor}(z_{\ell:r:m})]^2 + [\Phi_{nor}(z_{\ell:r:m})])z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{6\phi_{nor}^2(z_{\ell:r:m})(2\Phi_{nor}(z_{\ell:r:m}) - 1)z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{6\phi_{nor}(z_{\ell:r:m})(-[\Phi_{nor}(z_{\ell:r:m})]^2 + [\Phi_{nor}(z_{\ell:r:m})])}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{6\phi_{nor}(z_{\ell:r:m})(-[\Phi_{nor}(z_{\ell:r:m})]^2 + [\Phi_{nor}(z_{\ell:r:m})])z_{\ell:r:m}^3}{\sigma^2} \\
&\quad + \frac{6\phi_{nor}^2(z_{\ell:r:m})(2\Phi_{nor}(z_{\ell:r:m}) - 1)z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{12\phi_{nor}(z_{\ell:r:m})(-[\Phi_{nor}(z_{\ell:r:m})]^2 + [\Phi_{nor}(z_{\ell:r:m})])z_{\ell:r:m}}{\sigma^2}
\end{aligned}$$

When $n = 4$, the explicit formula are given by

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]}{\sigma} \\ &\quad - \frac{\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2}{\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]}{\sigma} \\ &\quad - \frac{\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2}{\sigma}(z_{\ell:r:m}),\end{aligned}$$

and

$$\begin{aligned}\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{12\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{12\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2}{\sigma}(z_{\ell:r:m}).\end{aligned}$$

Then, we have

$$\begin{aligned}\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})][3\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}}{\sigma^2} \\ &\quad - \frac{\phi_{nor}^2(z_{\ell:r:m})[6\Phi_{nor}(z_{\ell:r:m}) - 4]}{\sigma^2} \\ \frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})][3\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}^2}{\sigma^2} \\ &\quad - \frac{\phi_{nor}^2(z_{\ell:r:m})[6\Phi_{nor}(z_{\ell:r:m}) - 4]z_{\ell:r:m}}{\sigma^2} \\ &\quad - \frac{\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})][3\Phi_{nor}(z_{\ell:r:m}) - 1]}{\sigma^2} \\ \frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})][3\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}^3}{\sigma^2} \\ &\quad - \frac{\phi_{nor}^2(z_{\ell:r:m})[6\Phi_{nor}(z_{\ell:r:m}) - 4]z_{\ell:r:m}^2}{\sigma^2} \\ &\quad - \frac{2\phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})][3\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}}{\sigma^2}\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{12\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2 z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{12\phi_{nor}^2(z_{\ell:r:m})(4\Phi_{nor}^2(z_{\ell:r:m}) - 3\Phi_{nor}(z_{\ell:r:m}) - 1)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{12\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2 z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{12\phi_{nor}^2(z_{\ell:r:m})(4\Phi_{nor}^2(z_{\ell:r:m}) - 3\Phi_{nor}(z_{\ell:r:m}) - 1) z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{12\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{12\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2 z_{\ell:r:m}^3}{\sigma^2} \\
&\quad + \frac{12\phi_{nor}^2(z_{\ell:r:m})(4\Phi_{nor}^2(z_{\ell:r:m}) - 3\Phi_{nor}(z_{\ell:r:m}) - 1) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{24\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^2 z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

G.4. 3-out-of- n for $n = 4$

If we use the following

$$\begin{aligned}
g_1(z_{\ell:r:m}) &= \Phi_{nor}^2(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^{n-3} \\
&= \Phi_{nor}^2(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})] \\
\text{and } g_2(z_{\ell:r:m}) &= [1 - \Phi_{nor}(z_{\ell:r:m})]^n + n\Phi_{nor}(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^{n-1} \\
&\quad + \frac{n(n-1)}{2}\Phi_{nor}^2(z_{\ell:r:m})[1 - \Phi_{nor}(z_{\ell:r:m})]^{n-2} \\
&= [3\Phi_{nor}^2(z_{\ell:r:m}) + 2\Phi_{nor}(z_{\ell:r:m}) + 1][1 - \Phi_{nor}(z_{\ell:r:m})]^2 \\
&= 3\Phi_{nor}^4(z_{\ell:r:m}) - 4\Phi_{nor}^3(z_{\ell:r:m}) + 1,
\end{aligned}$$

we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}^2 - 1}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{3\phi_{nor}(z_{\ell:r:m})\Phi_{nor}^2(z_{\ell:r:m}) - 2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{3\phi_{nor}(z_{\ell:r:m})\Phi_{nor}^2(z_{\ell:r:m}) - 2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{\sigma}(z_{\ell:r:m})\end{aligned}$$

and

$$\begin{aligned}\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{12\phi_{nor}(z_{\ell:r:m})(\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m}))}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{12\phi_{nor}(z_{\ell:r:m})(\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m}))}{\sigma}(z_{\ell:r:m}).\end{aligned}$$

Then,

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{2z_{\ell:r:m}}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - 3z_{\ell:r:m}^2}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right],
\end{aligned}$$

where

$$\begin{aligned}
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[3\Phi_{nor}^2(z_{\ell:r:m})]}{\sigma^2} \\
&\quad - \frac{2\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m} - 2\phi_{nor}^2(z_{\ell:r:m})[3\Phi_{nor}(z_{\ell:r:m}) - 1]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})[3\Phi_{nor}^2(z_{\ell:r:m}) - 2\Phi_{nor}(z_{\ell:r:m})]z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}^2(z_{\ell:r:m})[3\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m})[3\Phi_{nor}^2(z_{\ell:r:m}) - 2\Phi_{nor}(z_{\ell:r:m})]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[3\Phi_{nor}^2(z_{\ell:r:m})]}{\sigma^2} \\
&\quad - \frac{2\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m}^3 - 2\phi_{nor}^2(z_{\ell:r:m})[3\Phi_{nor}(z_{\ell:r:m}) - 1]z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m})[3\Phi_{nor}^2(z_{\ell:r:m}) - 2\Phi_{nor}(z_{\ell:r:m})]z_{\ell:r:m}}{\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{12\phi_{nor}(z_{\ell:r:m}) [\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m})] z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{12\phi_{nor}^2(z_{\ell:r:m}) [3\Phi_{nor}^2(z_{\ell:r:m}) - 2\Phi_{nor}(z_{\ell:r:m})]}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{12\phi_{nor}(z_{\ell:r:m}) [\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m})] z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{12\phi_{nor}^2(z_{\ell:r:m}) [3\Phi_{nor}^2(z_{\ell:r:m}) - 2\Phi_{nor}(z_{\ell:r:m}) z_{\ell:r:m}]}{\sigma^2} \\
&\quad - \frac{12\phi_{nor}(z_{\ell:r:m}) [\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m})]}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{12\phi_{nor}(z_{\ell:r:m}) [\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m})] z_{\ell:r:m}^3}{\sigma^2} \\
&\quad + \frac{12\phi_{nor}^2(z_{\ell:r:m}) [3\Phi_{nor}^2(z_{\ell:r:m}) - 2\Phi_{nor}(z_{\ell:r:m}) z_{\ell:r:m}^2]}{\sigma^2} \\
&\quad - \frac{24\phi_{nor}(z_{\ell:r:m}) [\Phi_{nor}^2(z_{\ell:r:m}) - \Phi_{nor}^3(z_{\ell:r:m})] z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

G.5. Series-parallel systems

With lognormal distributed components, we have

$$\begin{aligned}
\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[z_{\ell:r:m} + \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{1 - [\Phi_{nor}(z_{\ell:r:m})]^2} \right. \\
&\quad \left. + R_{\ell} \frac{\phi_{nor}(z_{\ell:r:m}) (-3[\Phi_{nor}(z_{\ell:r:m})]^2 + 2[\Phi_{nor}(z_{\ell:r:m})] + 1)}{[\Phi_{nor}(z_{\ell:r:m})]^3 - [\Phi_{nor}(z_{\ell:r:m})]^2 - \Phi_{nor}(z_{\ell:r:m}) + 1} \right] \\
\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[-1 + z_{\ell:r:m}^2 + \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{1 - [\Phi_{nor}(z_{\ell:r:m})]^2} z_{\ell:r:m} \right. \\
&\quad \left. + R_{\ell} \frac{\phi_{nor}(z_{\ell:r:m}) (-3[\Phi_{nor}(z_{\ell:r:m})]^2 + 2[\Phi_{nor}(z_{\ell:r:m})] + 1)}{[\Phi_{nor}(z_{\ell:r:m})]^3 - [\Phi_{nor}(z_{\ell:r:m})]^2 - \Phi_{nor}(z_{\ell:r:m}) + 1} z_{\ell:r:m} \right].
\end{aligned}$$

To find the maximum likelihood estimates of the parameters, we could set the above equations to 0 and solve them simultaneously.

Similarly, if we use the following

$$g_1(z_{\ell:r:m}) = 1 - [\Phi_{nor}(z_{\ell:r:m})]^2$$

$$\text{and } g_2(z_{\ell:r:m}) = [\Phi_{nor}(z_{\ell:r:m})]^3 - [\Phi_{nor}(z_{\ell:r:m})]^2 - \Phi_{nor}(z_{\ell:r:m}) + 1,$$

we can obtain

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} = \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right]$$

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} = \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}^2 - 1}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],$$

where

$$\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} = \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{\sigma}$$

$$\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} = \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{\sigma}(z_{\ell:r:m})$$

and

$$\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} = \frac{\phi_{nor}(z_{\ell:r:m}) (-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1)}{\sigma}$$

$$\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} = \frac{\phi_{nor}(z_{\ell:r:m}) (-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1)}{\sigma}(z_{\ell:r:m}).$$

Then,

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{2z_{\ell:r:m}}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - 3z_{\ell:r:m}^2}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right],
\end{aligned}$$

where

$$\begin{aligned}
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m} - 2\phi_{nor}^2(z_{\ell:r:m})}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m}^2 - 2\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m}^3 - 2\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m}}{\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 2)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 2) z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) z_{\ell:r:m}^3}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 2) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

G.6. Parallel-series systems

If we use the following

$$\begin{aligned}
g_1(z_{\ell:r:m}) &= 2\Phi_{nor}(z_{\ell:r:m}) - \frac{5}{3} [\Phi_{nor}(z_{\ell:r:m})]^2 \\
\text{and } g_2(z_{\ell:r:m}) &= [\Phi_{nor}(z_{\ell:r:m})]^3 - 2 [\Phi_{nor}(z_{\ell:r:m})]^2 + 1,
\end{aligned}$$

we have

$$\begin{aligned}
\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}^2 - 1}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],
\end{aligned}$$

where

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{10\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) - 6\phi_{nor}(z_{\ell:r:m})}{3\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{10\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) - 6\phi_{nor}(z_{\ell:r:m})}{3\sigma}(z_{\ell:r:m})\end{aligned}$$

and

$$\begin{aligned}\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{\phi_{nor}(z_{\ell:r:m})(-3[\Phi_{nor}(z_{\ell:r:m})]^2 + 4[\Phi_{nor}(z_{\ell:r:m})])}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})(-3[\Phi_{nor}(z_{\ell:r:m})]^2 + 4[\Phi_{nor}(z_{\ell:r:m})])}{\sigma}(z_{\ell:r:m}).\end{aligned}$$

Then,

$$\begin{aligned}\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\ &\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{2z_{\ell:r:m}}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\ &\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - 3z_{\ell:r:m}^2}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\ &\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]z_{\ell:r:m} - 10\phi_{nor}^2(z_{\ell:r:m})}{3\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]z_{\ell:r:m}^2 - 10\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}}{3\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]}{3\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]z_{\ell:r:m}^3 - 10\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}^2}{3\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]z_{\ell:r:m}}{3\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 4)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 4) z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) z_{\ell:r:m}^3}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 4) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

APPENDIX H

Appendix H: Detailed Formula for Weibull Distribution with Various Types of Systems

H.1. $l = 1$

With $l = 1$, we are using series systems. Thus, the SF and PDF of the log-transformed system failure times can be simplified as

$$\begin{aligned}\bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^n, \\ \text{and } f_V(v; \boldsymbol{\theta}) &= \frac{n}{\sigma} f^*(z) [\bar{F}^*(z)]^{n-1}, \quad n = 1, 2, 3.\end{aligned}$$

Thus, we have

$$\begin{aligned}\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ \frac{n}{\sigma} f^*(z_{\ell:r:m}) [\bar{F}^*(z_{\ell:r:m})]^{n-1} \right\} \\ &= \ln n - \ln \sigma + \ln f^*(z_{\ell:r:m}) + (n-1) \ln \bar{F}^*(z_{\ell:r:m}) \\ \text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ [\bar{F}^*(z_{\ell:r:m})]^n \right\} = n \ln \bar{F}^*(z_{\ell:r:m}).\end{aligned}$$

Hence, we have the first derivatives as

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + (n-1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + (n-1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \sigma}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= n \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= n \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \sigma}.\end{aligned}$$

Therefore, we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + (R_\ell n + n - 1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \right] \\ &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} + (R_\ell n + n - 1) \frac{1}{\bar{F}^*(z_{\ell:r:m})} \frac{\partial \bar{F}^*(z_{\ell:r:m})}{\partial \mu} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + (R_\ell n + n - 1) \frac{\partial \ln \bar{F}^*(z_{\ell:r:m})}{\partial \sigma} \right] \\ &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} + (R_\ell n + n - 1) \frac{1}{\bar{F}^*(z_{\ell:r:m})} \frac{\partial \bar{F}^*(z_{\ell:r:m})}{\partial \sigma} \right].\end{aligned}$$

With Weibull distributed components, we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{e^{z_{\ell:r:m}} - 1}{\sigma} + \frac{R_\ell n + n - 1}{\sigma} \frac{\phi_{sev}(z_{\ell:r:m})}{\bar{\Phi}_{sev}(z_{\ell:r:m})} \right] \\ &= \sum_{\ell=1}^r \left[\frac{e^{z_{\ell:r:m}} - 1}{\sigma} + \frac{R_\ell n + n - 1}{\sigma} e^{z_{\ell:r:m}} \right] \\ &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{R_\ell n + n}{\sigma} e^{z_{\ell:r:m}} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{\sigma} + \frac{z_{\ell:r:m}(R_\ell n + n - 1)}{\sigma} \frac{\phi_{sev}(z_{\ell:r:m})}{\bar{\Phi}_{sev}(z_{\ell:r:m})} \right] \\ &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{\sigma} + \frac{z_{\ell:r:m}(R_\ell n + n - 1)}{\sigma} e^{z_{\ell:r:m}} \right] \\ &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} - \frac{z_{\ell:r:m}}{\sigma} + \frac{z_{\ell:r:m}(R_\ell n + n)}{\sigma} e^{z_{\ell:r:m}} \right].\end{aligned}$$

Hence, the likelihood equations for μ and σ are, respectively,

$$\begin{aligned} -r + \sum_{\ell=1}^r (R_\ell n + n) e^{z_{\ell:r:m}} &= 0; \\ -r - \sum_{\ell=1}^r z_{\ell:r:m} + \sum_{\ell=1}^r (R_\ell n + n) z_{\ell:r:m} e^{z_{\ell:r:m}} &= 0. \end{aligned}$$

From the log-likelihood function, the second derivatives forming the observed Fisher Information are

$$\begin{aligned} \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= -\frac{1}{\sigma^2} \sum_{\ell=1}^r (R_\ell n + n) e^{z_{\ell:r:m}} \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \frac{r}{\sigma^2} - \frac{1}{\sigma^2} \sum_{\ell=1}^r (R_\ell n + n) (z_{\ell:r:m} e^{z_{\ell:r:m}} + e^{z_{\ell:r:m}}) \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{r}{\sigma^2} + \frac{2}{\sigma^2} \sum_{\ell=1}^r z_{\ell:r:m} - \frac{1}{\sigma^2} \sum_{\ell=1}^r (R_\ell n + n) (z_{\ell:r:m}^2 e^{z_{\ell:r:m}} + 2z_{\ell:r:m} e^{z_{\ell:r:m}}). \end{aligned}$$

In order to compute the expected Fisher information matrix, we need to compute the expectations $E(Z_{\ell:r:m})$ and $E(Z_{\ell:r:m}^d \exp(Z_{\ell:r:m}))$, $d = 0, 1, 2$. Consider the PDF of the ℓ -th order statistic of a sample of size m , $\ell = 1, \dots, r$ of the minimum among n random variables from the standard SEV distribution is given by

$$\begin{aligned} f_{\ell:r:m}(z_\ell) &= c' \sum_{i=0}^{\ell-1} c_{i,\ell-1} (R_1 + 1, \dots, R_{\ell-1} + 1) f_v(z_\ell) [\bar{F}_v(z_\ell)]^{R_i'' - 1}, \\ &= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1} (R_1 + 1, \dots, R_{\ell-1} + 1) f^*(z_\ell) [\bar{F}^*(z_\ell)]^{nR_i'' - 1} \\ &= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1} (R_1 + 1, \dots, R_{\ell-1} + 1) e^{z_\ell - nR_i'' e^{z_\ell}}, \quad -\infty < z_\ell < \infty, \end{aligned}$$

where

$$\begin{aligned}
R_i'' &= R_\ell^* + \sum_{j=\ell-i}^{\ell-1} (R_j + 1) \\
R_\ell^* &= m - \ell - R_1 - \dots - R_{\ell-1} + 1 \\
c' &= m(m - R_1 - 1) \dots (m - \ell - R_1 - \dots - R_{\ell-1} + 1),
\end{aligned}$$

and

$$c_{i,q}(a_1, \dots, a_r) = \frac{(-1)^i}{\left\{ \prod_{j=1}^i \left(\sum_{k=q-i+1}^{q-i+j} a_k \right) \right\} \left\{ \prod_{j=1}^{q-i} \left(\sum_{k=j}^{q-i} a_k \right) \right\}},$$

where the conventions are that $\prod_{j=1}^0 a_j = 1$. Then, the expectations $E(\exp(Z_{\ell:m_k}))$ and $E(Z_{\ell:m_k}^d \exp(Z_{\ell:m_k}))$ can be expressed as

$$E(Z_{\ell:m_k}) = nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1}(R_1 + 1, \dots, R_{\ell-1} + 1) \int_{-\infty}^{\infty} z e^{z - nR_i'' e^z} dz$$

and

$$\begin{aligned}
&E[Z_{\ell:m_k}^d \exp(Z_{\ell:m_k})] \\
&= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1}(R_1 + 1, \dots, R_{\ell-1} + 1) \int_{-\infty}^{\infty} z^d e^{2z - nR_i'' e^z} dz,
\end{aligned}$$

respectively, which can be computed by evaluating the integrals

$$h(c) = \int_{-\infty}^{\infty} z e^{z - ce^z} dz \text{ and } g_d(c) = \int_{-\infty}^{\infty} z^d e^{2z - ce^z} dz,$$

for $d = 0, 1, 2$ as

$$h(c) = -\frac{\gamma + \log c}{c}$$

and

$$\begin{aligned}
g_0(c) &= \frac{1}{c^2}, \\
g_1(c) &= \frac{1 - \gamma - \log c}{c^2}, \\
g_2(c) &= \frac{\log^2 c - 2(1 - \gamma)\log c + \gamma^2 - 2\gamma + \pi^2/6}{c^2},
\end{aligned}$$

where $\gamma = -\Gamma'(1) = 0.57721566\dots$ is Euler's constant.

Hence, we find the expected values as

$$\begin{aligned}
E(\exp(Z_{\ell:m_k})) &= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1}(R_1 + 1, \dots, R_{\ell-1} + 1) \frac{-\gamma - \log(nR_i'')}{nR_i''} \\
E(\exp(Z_{\ell:m_k})) &= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1}(R_1 + 1, \dots, R_{\ell-1} + 1) \frac{1}{(nR_i'')^2} \\
E(Z_{\ell:m_k} \exp(Z_{\ell:m_k})) &= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1}(R_1 + 1, \dots, R_{\ell-1} + 1) \frac{1 - \gamma - \log(nR_i'')}{(nR_i'')^2} \\
E(Z_{\ell:m_k}^2 \exp(Z_{\ell:m_k})) &= nc' \sum_{i=0}^{\ell-1} c_{i,\ell-1}(R_1 + 1, \dots, R_{\ell-1} + 1) \\
&\quad \times \frac{(\log nR_i'')^2 - 2(1 - \gamma)\log(nR_i'') + \gamma^2 - 2\gamma + \pi^2/6}{(nR_i'')^2}.
\end{aligned}$$

H.2. $l = n$

With $l = n$, we have parallel systems with system structure being $\mathbf{s} = (0, 0, \dots, 0, 1)$.

The SF and PDF of the log-transformed system failure times are

$$\begin{aligned}
\bar{F}_V(v; \boldsymbol{\theta}) &= \sum_{j=0}^{n-1} \binom{n}{j} [\bar{F}^*(z)]^j [\bar{F}^*(z)]^{n-j} \\
&= 1 - [F^*(z)]^n, \\
\text{and } f_V(v; \boldsymbol{\theta}) &= \frac{n}{\sigma} f^*(z) [F^*(z)]^{n-1}.
\end{aligned}$$

Thus, we have

$$\begin{aligned}\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ \frac{n}{\sigma} f^*(z) [F^*(z)]^{n-1} \right\} \\ &= \ln n - \ln \sigma + \ln f^*(z_{\ell:r:m}) + (n-1) \ln F^*(z_{\ell:r:m})\end{aligned}$$

$$\begin{aligned}\text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \{1 - [F^*(z_{\ell:r:m})]^n\} \\ &= \ln \{1 - [F^*(z_{\ell:r:m})]^n\}.\end{aligned}$$

Hence, we have the first derivatives as

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + (n-1) \frac{\partial \ln F^*(z_{\ell:r:m})}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + (n-1) \frac{\partial \ln F^*(z_{\ell:r:m})}{\partial \sigma}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^n\}}{\partial \mu} \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^n\}}{\partial \sigma}.\end{aligned}$$

Therefore, we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \mu} \right. \\ &\quad \left. + \frac{(n-1) - (R_\ell n + n-1) [F^*(z_{\ell:r:m})]^n}{F^*(z_{\ell:r:m}) (1 - [F^*(z_{\ell:r:m})]^n)} \frac{\partial F^*(z_{\ell:r:m})}{\partial \mu} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{1}{f^*(z_{\ell:r:m})} \frac{\partial f^*(z_{\ell:r:m})}{\partial \sigma} \right. \\ &\quad \left. + \frac{(n-1) - (R_\ell n + n-1) [F^*(z_{\ell:r:m})]^n}{F^*(z_{\ell:r:m}) (1 - [F^*(z_{\ell:r:m})]^n)} \frac{\partial F^*(z_{\ell:r:m})}{\partial \sigma} \right].\end{aligned}$$

With Weibull distributed components, we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[(e^{z_{\ell:r:m}} - 1) + \frac{(R_{\ell}n + n - 1) [\Phi_{sev}(z_{\ell:r:m})]^n - (n - 1) \phi_{sev}(z_{\ell:r:m})}{1 - [\Phi_{sev}(z_{\ell:r:m})]^n} \frac{\phi_{sev}(z_{\ell:r:m})}{\Phi_{sev}(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[-1 + (e^{z_{\ell:r:m}} - 1) z_{\ell:r:m} \right. \\ &\quad \left. + \frac{z_{\ell:r:m} [(R_{\ell}n + n - 1) [\Phi_{sev}(z_{\ell:r:m})]^n - (n - 1)] \phi_{sev}(z_{\ell:r:m})}{1 - [\Phi_{sev}(z_{\ell:r:m})]^n} \frac{\phi_{sev}(z_{\ell:r:m})}{\Phi_{sev}(z_{\ell:r:m})} \right].\end{aligned}$$

Hence, the likelihood equations for μ and σ are, respectively,

$$\begin{aligned}\sum_{\ell=1}^r \left[(e^{z_{\ell:r:m}} - 1) + \frac{(R_{\ell}n + n - 1) [\Phi_{sev}(z_{\ell:r:m})]^n - (n - 1) \phi_{sev}(z_{\ell:r:m})}{1 - [\Phi_{sev}(z_{\ell:r:m})]^n} \frac{\phi_{sev}(z_{\ell:r:m})}{\Phi_{sev}(z_{\ell:r:m})} \right] &= 0; \\ \sum_{\ell=1}^r \left[-1 + (e^{z_{\ell:r:m}} - 1) z_{\ell:r:m} + \frac{z_{\ell:r:m} [(R_{\ell}n + n - 1) [\Phi_{sev}(z_{\ell:r:m})]^n - (n - 1)] \phi_{sev}(z_{\ell:r:m})}{1 - [\Phi_{sev}(z_{\ell:r:m})]^n} \frac{\phi_{sev}(z_{\ell:r:m})}{\Phi_{sev}(z_{\ell:r:m})} \right] &= 0.\end{aligned}$$

If we use the following

$$\begin{aligned}g_1(z_{\ell:r:m}) &= \Phi_{sev}(z_{\ell:r:m}) \\ \text{and } g_2(z_{\ell:r:m}) &= 1 - [\Phi_{sev}(z_{\ell:r:m})]^n,\end{aligned}$$

we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{(e^{z_{\ell:r:m}} - 1)}{\sigma} + (n - 1) \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{(e^{z_{\ell:r:m}} - 1) z_{\ell:r:m}}{\sigma} + (n - 1) \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= -\frac{\phi_{sev}(z_{\ell:r:m})}{\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= -\frac{\phi_{sev}(z_{\ell:r:m})}{\sigma} z_{\ell:r:m}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= n \frac{\phi_{sev}(z_{\ell:r:m}) [\Phi_{sev}(z_{\ell:r:m})]^{n-1}}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= n \frac{\phi_{sev}(z_{\ell:r:m}) [\Phi_{sev}(z_{\ell:r:m})]^{n-1}}{\sigma} z_{\ell:r:m}.\end{aligned}$$

Then,

$$\begin{aligned}\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{e^{z_{\ell:r:m}}}{\sigma^2} + (n-1) \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\ &\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{z_{\ell:r:m} e^{z_{\ell:r:m}} + e^{z_{\ell:r:m}} - 1}{\sigma^2} \right. \\ &\quad \left. + (n-1) \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\ &\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - z_{\ell:r:m}^2 e^{z_{\ell:r:m}} - 2z_{\ell:r:m} e^{z_{\ell:r:m}} + 2z_{\ell:r:m}}{\sigma^2} \right. \\ &\quad \left. + (n-1) \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\ &\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}\frac{\partial^2 g_1(z_{l:r:m})}{\partial \mu^2} &= -\frac{(e^{z_{l:r:m}} - 1)\phi_{sev}(z_{l:r:m})}{\sigma^2} \\ \frac{\partial^2 g_1(z_{l:r:m})}{\partial \mu \partial \sigma} &= -\frac{-(e^{z_{l:r:m}} - 1)\phi_{sev}(z_{l:r:m})z_{l:r:m} + \phi_{sev}(z_{l:r:m})}{\sigma^2} \\ \frac{\partial^2 g_1(z_{l:r:m})}{\partial \sigma^2} &= -\frac{-(e^{z_{l:r:m}} - 1)\phi_{sev}(z_{l:r:m})z_{l:r:m}^2 + 2\phi_{sev}(z_{l:r:m})z_{l:r:m}}{\sigma^2}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial^2 g_2(z_{l:r:m})}{\partial \mu^2} &= n \left\{ \frac{(e^{z_{l:r:m}} - 1)\phi_{sev}(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-1}}{\sigma^2} \right. \\ &\quad \left. - \frac{(n-1)\phi_{sev}^2(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-2}}{\sigma^2} \right\} \\ \frac{\partial^2 g_2(z_{l:r:m})}{\partial \mu \partial \sigma} &= n \left\{ \frac{[(e^{z_{l:r:m}} - 1)\phi_{sev}(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-1}]}{\sigma^2} \right. \\ &\quad \left. - \frac{(n-1)\phi_{sev}^2(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-2}}{\sigma^2} z_{l:r:m} \right. \\ &\quad \left. - \frac{\phi_{sev}(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-1}}{\sigma^2} \right\} \\ \frac{\partial^2 g_2(z_{l:r:m})}{\partial \sigma^2} &= n \left\{ \frac{[(e^{z_{l:r:m}} - 1)\phi_{sev}(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-1}]}{\sigma^2} \right. \\ &\quad \left. - \frac{(n-1)\phi_{sev}^2(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-2}}{\sigma^2} z_{l:r:m}^2 \right. \\ &\quad \left. - \frac{2\phi_{sev}(z_{l:r:m}) [\Phi_{sev}(z_{l:r:m})]^{n-1} z_{l:r:m}}{\sigma^2} \right\}.\end{aligned}$$

H.3. 2-out-of- n

With Weibull distributed components, when $n = 3$, we have If we use the following

$$g_1(z_{\ell:r:m}) = \Phi_{sev}(z_{\ell:r:m}) - \Phi_{sev}^2(z_{\ell:r:m})$$

$$\text{and } g_2(z_{\ell:r:m}) = 2\Phi_{sev}^3(z_{\ell:r:m}) - 3\Phi_{sev}^2(z_{\ell:r:m}) + 1,$$

we have

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} = \sum_{\ell=1}^r \left[\frac{(e^{z_{\ell:r:m}} - 1)}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right]$$

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} = \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],$$

where

$$\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} = \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m}) - \phi_{sev}(z_{\ell:r:m})}{\sigma}$$

$$\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} = \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m}) - \phi_{sev}(z_{\ell:r:m})}{\sigma}(z_{\ell:r:m})$$

and

$$\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} = \frac{6\phi_{sev}(z_{\ell:r:m})(-\Phi_{sev}^2(z_{\ell:r:m}) + \Phi_{sev}(z_{\ell:r:m}))}{\sigma}$$

$$\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} = \frac{6\phi_{sev}(z_{\ell:r:m})(-\Phi_{sev}^2(z_{\ell:r:m}) + \Phi_{sev}(z_{\ell:r:m}))}{\sigma}(z_{\ell:r:m}).$$

Then,

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{e^{z_{\ell:r:m}}}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_{\ell} \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{z_{\ell:r:m} e^{z_{\ell:r:m}} + e^{z_{\ell:r:m}} - 1}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_{\ell} \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - 3z_{\ell:r:m}^2}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_{\ell} \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right],
\end{aligned}$$

where

$$\begin{aligned}
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{sev}(z_{\ell:r:m}) [2\Phi_{sev}(z_{\ell:r:m}) - 1] [e^{z_{\ell:r:m}} - 1] - 2\phi_{sev}^2(z_{\ell:r:m})}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{sev}(z_{\ell:r:m}) [2\Phi_{sev}(z_{\ell:r:m}) - 1] [e^{z_{\ell:r:m}} - 1] z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}^2(z_{\ell:r:m}) z_{\ell:r:m} - \phi_{sev}(z_{\ell:r:m}) [2\Phi_{sev}(z_{\ell:r:m}) - 1]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{sev}(z_{\ell:r:m}) [2\Phi_{sev}(z_{\ell:r:m}) - 1] [e^{z_{\ell:r:m}} - 1] z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}^2(z_{\ell:r:m}) z_{\ell:r:m}^2 - 2\phi_{sev}(z_{\ell:r:m}) [2\Phi_{sev}(z_{\ell:r:m}) - 1] z_{\ell:r:m}}{\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{6\phi_{sev}(z_{\ell:r:m}) \left(-[\Phi_{sev}(z_{\ell:r:m})]^2 + [\Phi_{sev}(z_{\ell:r:m})] \right) [e^{z_{\ell:r:m}} - 1]}{\sigma^2} \\
&\quad + \frac{6\phi_{sev}^2(z_{\ell:r:m}) (2\Phi_{sev}(z_{\ell:r:m}) - 1)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{6\phi_{sev}(z_{\ell:r:m}) \left(-[\Phi_{sev}(z_{\ell:r:m})]^2 + [\Phi_{sev}(z_{\ell:r:m})] \right) [e^{z_{\ell:r:m}} - 1] z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{6\phi_{sev}^2(z_{\ell:r:m}) (2\Phi_{sev}(z_{\ell:r:m}) - 1) z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{6\phi_{sev}(z_{\ell:r:m}) \left(-[\Phi_{sev}(z_{\ell:r:m})]^2 + [\Phi_{sev}(z_{\ell:r:m})] \right)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{6\phi_{sev}(z_{\ell:r:m}) \left(-[\Phi_{sev}(z_{\ell:r:m})]^2 + [\Phi_{sev}(z_{\ell:r:m})] \right) [e^{z_{\ell:r:m}} - 1] z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{6\phi_{sev}^2(z_{\ell:r:m}) (2\Phi_{sev}(z_{\ell:r:m}) - 1) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{12\phi_{sev}(z_{\ell:r:m}) \left(-[\Phi_{sev}(z_{\ell:r:m})]^2 + [\Phi_{sev}(z_{\ell:r:m})] \right) z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

When $n = 4$, the explicit formulas are given by

$$\begin{aligned}
\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})] - \phi_{sev}(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})]^2}{\sigma} \\
\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{2z_{\ell:r:m}\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})] - z_{\ell:r:m}\phi_{sev}(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})]^2}{\sigma},
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{12\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})]^2}{\sigma} \\
\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{12z_{\ell:r:m}\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})]^2}{\sigma}.
\end{aligned}$$

Then, we have

$$\begin{aligned}
\frac{\partial^2 g_1(z_{l:r:m})}{\partial \mu^2} &= \frac{\phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})] [3\Phi_{sev}(z_{l:r:m}) - 1] [e^{z_{l:r:m}} - 1]}{\sigma^2} \\
&\quad - \frac{\phi_{sev}^2(z_{l:r:m}) [6\Phi_{sev}(z_{l:r:m}) - 4]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{l:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})] [3\Phi_{sev}(z_{l:r:m}) - 1] [e^{z_{l:r:m}} - 1] z_{l:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{sev}^2(z_{l:r:m}) [6\Phi_{sev}(z_{l:r:m}) - 4] z_{l:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})] [3\Phi_{sev}(z_{l:r:m}) - 1]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{l:r:m})}{\partial \sigma^2} &= \frac{\phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})] [3\Phi_{sev}(z_{l:r:m}) - 1] [e^{z_{l:r:m}} - 1] z_{l:r:m}^2}{\sigma^2} \\
&\quad - \frac{\phi_{sev}^2(z_{l:r:m}) [6\Phi_{sev}(z_{l:r:m}) - 4] z_{l:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})] [3\Phi_{sev}(z_{l:r:m}) - 1] z_{l:r:m}}{\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{l:r:m})}{\partial \mu^2} &= \frac{12\phi_{sev}(z_{l:r:m})\Phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})]^2 [e^{z_{l:r:m}} - 1]}{\sigma^2} \\
&\quad + \frac{12\phi_{sev}^2(z_{l:r:m}) (4\Phi_{sev}^2(z_{l:r:m}) - 3\Phi_{sev}(z_{l:r:m}) - 1)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{l:r:m})}{\partial \mu \partial \sigma} &= \frac{12\phi_{sev}(z_{l:r:m})\Phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})]^2 [e^{z_{l:r:m}} - 1] z_{l:r:m}}{\sigma^2} \\
&\quad + \frac{12\phi_{sev}^2(z_{l:r:m}) (4\Phi_{sev}^2(z_{l:r:m}) - 3\Phi_{sev}(z_{l:r:m}) - 1) z_{l:r:m}}{\sigma^2} \\
&\quad - \frac{12\phi_{sev}(z_{l:r:m})\Phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})]^2}{\sigma^2} \\
\frac{\partial^2 g_2(z_{l:r:m})}{\partial \sigma^2} &= \frac{12\phi_{sev}(z_{l:r:m})\Phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})]^2 [e^{z_{l:r:m}} - 1] z_{l:r:m}^2}{\sigma^2} \\
&\quad + \frac{12\phi_{sev}^2(z_{l:r:m}) (4\Phi_{sev}^2(z_{l:r:m}) - 3\Phi_{sev}(z_{l:r:m}) - 1) z_{l:r:m}^2}{\sigma^2} \\
&\quad - \frac{24\phi_{sev}(z_{l:r:m})\Phi_{sev}(z_{l:r:m}) [1 - \Phi_{sev}(z_{l:r:m})]^2 z_{l:r:m}}{\sigma^2}.
\end{aligned}$$

H.4. 3-out-of- n for $n = 4$

For Weibull distributed components, from the following equations

$$g_1(z_{\ell:r:m}) = \Phi_{sev}^2(z_{\ell:r:m}) [1 - \Phi_{sev}(z_{\ell:r:m})]$$

$$\text{and } g_2(z_{\ell:r:m}) = 3\Phi_{sev}^4(z_{\ell:r:m}) - 4\Phi_{sev}^3(z_{\ell:r:m}) + 1$$

we have

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} = \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right]$$

$$\frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} = \sum_{\ell=1}^r \left[\frac{z_{\ell:r:m}^2 - 1}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],$$

where

$$\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} = \frac{3\phi_{sev}(z_{\ell:r:m})\Phi_{sev}^2(z_{\ell:r:m}) - 2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})}{\sigma}$$

$$\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} = \frac{3\phi_{sev}(z_{\ell:r:m})\Phi_{sev}^2(z_{\ell:r:m}) - 2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})}{\sigma}(z_{\ell:r:m})$$

and

$$\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} = \frac{12\phi_{sev}(z_{\ell:r:m})(\Phi_{sev}^2(z_{\ell:r:m}) - \Phi_{sev}^3(z_{\ell:r:m}))}{\sigma}$$

$$\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} = \frac{12\phi_{sev}(z_{\ell:r:m})(\Phi_{sev}^2(z_{\ell:r:m}) - \Phi_{sev}^3(z_{\ell:r:m}))}{\sigma}(z_{\ell:r:m}).$$

Then,

$$\begin{aligned}
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu^2} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} \right]^2}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \mu \partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{2z_{\ell:r:m}}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_1(z_{\ell:r:m}) - \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma \partial \mu} g_2(z_{\ell:r:m}) - \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\
\frac{\partial^2 l(\boldsymbol{\theta})}{\partial \sigma^2} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[\frac{1 - 3z_{\ell:r:m}^2}{\sigma^2} + \frac{\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} g_1(z_{\ell:r:m}) - \left[\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_1(z_{\ell:r:m})^2} \right. \\
&\quad \left. + R_\ell \frac{\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} g_2(z_{\ell:r:m}) - \left[\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} \right]^2}{g_2(z_{\ell:r:m})} \right],
\end{aligned}$$

where

$$\begin{aligned}
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{sev}(z_{\ell:r:m})[3\Phi_{sev}^2(z_{\ell:r:m}) - 2\Phi_{sev}(z_{\ell:r:m})](e^{z_{\ell:r:m}} - 1)}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}^2(z_{\ell:r:m})[3\Phi_{sev}(z_{\ell:r:m}) - 1]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{sev}(z_{\ell:r:m})[3\Phi_{sev}^2(z_{\ell:r:m}) - 2\Phi_{sev}(z_{\ell:r:m})](e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}^2(z_{\ell:r:m})[3\Phi_{sev}(z_{\ell:r:m}) - 1]z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{sev}(z_{\ell:r:m})[3\Phi_{sev}^2(z_{\ell:r:m}) - 2\Phi_{sev}(z_{\ell:r:m})]}{\sigma^2} \\
\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{sev}(z_{\ell:r:m})[3\Phi_{sev}^2(z_{\ell:r:m}) - 2\Phi_{sev}(z_{\ell:r:m})](e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}^2(z_{\ell:r:m})[3\Phi_{sev}(z_{\ell:r:m}) - 1]z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{sev}(z_{\ell:r:m})[3\Phi_{sev}^2(z_{\ell:r:m}) - 2\Phi_{sev}(z_{\ell:r:m})]z_{\ell:r:m}}{\sigma^2}
\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{l:r:m})}{\partial \mu^2} &= \frac{12\phi_{sev}(z_{l:r:m}) [\Phi_{sev}^2(z_{l:r:m}) - \Phi_{sev}^3(z_{l:r:m})] (e^{z_{l:r:m}} - 1)}{\sigma^2} \\
&\quad + \frac{12\phi_{sev}^2(z_{l:r:m}) [3\Phi_{sev}^2(z_{l:r:m}) - 2\Phi_{sev}(z_{l:r:m})]}{\sigma^2} \\
\frac{\partial^2 g_2(z_{l:r:m})}{\partial \mu \partial \sigma} &= \frac{12\phi_{sev}(z_{l:r:m}) [\Phi_{sev}^2(z_{l:r:m}) - \Phi_{sev}^3(z_{l:r:m})] (e^{z_{l:r:m}} - 1) z_{l:r:m}}{\sigma^2} \\
&\quad + \frac{12\phi_{sev}^2(z_{l:r:m}) [3\Phi_{sev}^2(z_{l:r:m}) - 2\Phi_{sev}(z_{l:r:m}) z_{l:r:m}]}{\sigma^2} \\
&\quad - \frac{12\phi_{sev}(z_{l:r:m}) [\Phi_{sev}^2(z_{l:r:m}) - \Phi_{sev}^3(z_{l:r:m})]}{\sigma^2} \\
\frac{\partial^2 g_2(z_{l:r:m})}{\partial \sigma^2} &= \frac{12\phi_{sev}(z_{l:r:m}) [\Phi_{sev}^2(z_{l:r:m}) - \Phi_{sev}^3(z_{l:r:m})] (e^{z_{l:r:m}} - 1) z_{l:r:m}^2}{\sigma^2} \\
&\quad + \frac{12\phi_{sev}^2(z_{l:r:m}) [3\Phi_{sev}^2(z_{l:r:m}) - 2\Phi_{sev}(z_{l:r:m}) z_{l:r:m}^2]}{\sigma^2} \\
&\quad - \frac{24\phi_{sev}(z_{l:r:m}) [\Phi_{sev}^2(z_{l:r:m}) - \Phi_{sev}^3(z_{l:r:m})] z_{l:r:m}}{\sigma^2}.
\end{aligned}$$

H.5. Series-Parallel Systems

For $n = 3$, the system structure for series-parallel systems is $\mathbf{s} = (1/3, 2/3, 0)$, and now the SF and PDF of the log-transformed system failure times are

$$\begin{aligned}
\bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^3 + 2[F^*(z)] [\bar{F}^*(z)]^2 \\
&= [F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1, \\
\text{and } f_V(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^*(z) \left\{ [\bar{F}^*(z)]^2 + 2[F^*(z)] [\bar{F}^*(z)] \right\} \\
&= \frac{1}{\sigma} f^*(z) \left\{ 1 - [F^*(z)]^2 \right\}.
\end{aligned}$$

Thus, we have

$$\begin{aligned}
\ln f_V(v_{l:r:m}; \boldsymbol{\theta}) &= -\ln \sigma + \ln f^*(z_{l:r:m}) + \ln \left\{ 1 - [F^*(z_{l:r:m})]^2 \right\} \\
\text{and } \ln \bar{F}_V(v_{l:r:m}; \boldsymbol{\theta}) &= \ln \left\{ [F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1 \right\}.
\end{aligned}$$

Hence, we have the first derivatives as

$$\begin{aligned}\frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \mu} + \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^2\}}{\partial \mu} \\ \frac{\partial \ln f_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= -\frac{1}{\sigma} + \frac{\partial \ln f^*(z_{\ell:r:m})}{\partial \sigma} + \frac{\partial \ln \{1 - [F^*(z_{\ell:r:m})]^2\}}{\partial \sigma}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \mu} &= \frac{\partial \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}}{\partial \mu} \\ \frac{\partial \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta})}{\partial \sigma} &= \frac{\partial \ln \{[F^*(z)]^3 - [F^*(z)]^2 - F^*(z) + 1\}}{\partial \sigma}.\end{aligned}$$

With Weibull distributed components, we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[(e^{z_{\ell:r:m}} - 1) + \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})}{1 - [\Phi_{sev}(z_{\ell:r:m})]^2} \right. \\ &\quad \left. + R_{\ell} \frac{\phi_{sev}(z_{\ell:r:m}) (-3[\Phi_{sev}(z_{\ell:r:m})]^2 + 2[\Phi_{sev}(z_{\ell:r:m})] + 1)}{[\Phi_{sev}(z_{\ell:r:m})]^3 - [\Phi_{sev}(z_{\ell:r:m})]^2 - \Phi_{sev}(z_{\ell:r:m}) + 1} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \frac{1}{\sigma} \sum_{\ell=1}^r \left[-1 + (e^{z_{\ell:r:m}} - 1)z_{\ell:r:m} + \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})}{1 - [\Phi_{sev}(z_{\ell:r:m})]^2} z_{\ell:r:m} \right. \\ &\quad \left. + R_{\ell} \frac{\phi_{sev}(z_{\ell:r:m}) (-3[\Phi_{sev}(z_{\ell:r:m})]^2 + 2[\Phi_{sev}(z_{\ell:r:m})] + 1)}{[\Phi_{sev}(z_{\ell:r:m})]^3 - [\Phi_{sev}(z_{\ell:r:m})]^2 - \Phi_{sev}(z_{\ell:r:m}) + 1} z_{\ell:r:m} \right].\end{aligned}$$

To find the maximum likelihood estimates of the parameters, we could set the above equations to 0 and solve them simultaneously.

Similarly, from the following equations

$$\begin{aligned}g_1(z_{\ell:r:m}) &= 1 - [\Phi_{sev}(z_{\ell:r:m})]^2 \\ \text{and } g_2(z_{\ell:r:m}) &= [\Phi_{sev}(z_{\ell:r:m})]^3 - [\Phi_{sev}(z_{\ell:r:m})]^2 - \Phi_{sev}(z_{\ell:r:m}) + 1,\end{aligned}$$

we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{(e^{z_{\ell:r:m}} - 1)}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})}{\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{2z_{\ell:r:m}\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{\phi_{sev}(z_{\ell:r:m}) \left(-3 [\Phi_{sev}(z_{\ell:r:m})]^2 + 2 [\Phi_{sev}(z_{\ell:r:m})] + 1 \right)}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{z_{\ell:r:m}\phi_{sev}(z_{\ell:r:m}) \left(-3 [\Phi_{sev}(z_{\ell:r:m})]^2 + 2 [\Phi_{sev}(z_{\ell:r:m})] + 1 \right)}{\sigma}\end{aligned}$$

and

$$\begin{aligned}\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})(e^{z_{\ell:r:m}} - 1) - 2\phi_{sev}^2(z_{\ell:r:m})}{\sigma^2} \\ \frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{sev}(z_{\ell:r:m})(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m} - 2\phi_{sev}^2(z_{\ell:r:m})z_{\ell:r:m}}{\sigma^2} \\ &\quad - \frac{2\phi_{sev}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})}{\sigma^2} \\ \frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}^2 - 2\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}^2}{\sigma^2} \\ &\quad - \frac{2\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m})z_{\ell:r:m}}{\sigma^2}\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) (e^{z_{\ell:r:m}} - 1)}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 2)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) (e^{z_{\ell:r:m}} - 1) z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 2) z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) (e^{z_{\ell:r:m}} - 1) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 2) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 2 [\Phi_{nor}(z_{\ell:r:m})] + 1 \right) z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

H.6. Parallel-Series Systems

For $n = 3$, the system structure for parallel-series systems is $\mathbf{s} = (0, 2/3, 1/3)$. Thus, the SF and PDF of the log-transformed system failure times are, respectively,

$$\begin{aligned}\bar{F}_V(v; \boldsymbol{\theta}) &= [\bar{F}^*(z)]^3 + 3[F^*(z)] [\bar{F}^*(z)]^2 + [F^*(z)]^2 [\bar{F}^*(z)], \\ &= [F^*(z)]^3 - 2[F^*(z)]^2 + 1, \\ \text{and } f_V(v; \boldsymbol{\theta}) &= \frac{1}{\sigma} f^*(z) \left\{ 2[F^*(z)] [\bar{F}^*(z)] + \frac{1}{3}[F^*(z)]^2 \right\} \\ &= \frac{1}{\sigma} f^*(z) \left\{ 2[F^*(z)] - \frac{5}{3}[F^*(z)]^2 \right\}.\end{aligned}$$

Thus, we have

$$\begin{aligned}\ln f_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= -\ln \sigma + \ln f^*(z_{\ell:r:m}) + \ln \left\{ 2[F^*(z)] - \frac{5}{3}[F^*(z)]^2 \right\} \\ \text{and } \ln \bar{F}_V(v_{\ell:r:m}; \boldsymbol{\theta}) &= \ln \left\{ [F^*(z)]^3 - 2[F^*(z)]^2 + 1 \right\}.\end{aligned}$$

If we use the following

$$\begin{aligned}g_1(z_{\ell:r:m}) &= 2\Phi_{nor}(z_{\ell:r:m}) - \frac{5}{3} [\Phi_{nor}(z_{\ell:r:m})]^2 \\ \text{and } g_2(z_{\ell:r:m}) &= [\Phi_{nor}(z_{\ell:r:m})]^3 - 2[\Phi_{nor}(z_{\ell:r:m})]^2 + 1,\end{aligned}$$

we have

$$\begin{aligned}\frac{\partial l(\boldsymbol{\theta})}{\partial \mu} &= \sum_{\ell=1}^r \left[\frac{e^{z_{\ell:r:m}} - 1}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu}}{g_2(z_{\ell:r:m})} \right] \\ \frac{\partial l(\boldsymbol{\theta})}{\partial \sigma} &= \sum_{\ell=1}^r \left[-\frac{1}{\sigma} + \frac{(e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{\sigma} + \frac{\frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma}}{g_1(z_{\ell:r:m})} + R_{\ell} \frac{\frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma}}{g_2(z_{\ell:r:m})} \right],\end{aligned}$$

where

$$\begin{aligned}\frac{\partial g_1(z_{\ell:r:m})}{\partial \mu} &= \frac{10\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) - 6\phi_{nor}(z_{\ell:r:m})}{3\sigma} \\ \frac{\partial g_1(z_{\ell:r:m})}{\partial \sigma} &= \frac{10\phi_{nor}(z_{\ell:r:m})\Phi_{nor}(z_{\ell:r:m}) - 6\phi_{nor}(z_{\ell:r:m})}{3\sigma}(z_{\ell:r:m})\end{aligned}$$

and

$$\begin{aligned}\frac{\partial g_2(z_{\ell:r:m})}{\partial \mu} &= \frac{\phi_{nor}(z_{\ell:r:m})(-3[\Phi_{nor}(z_{\ell:r:m})]^2 + 4[\Phi_{nor}(z_{\ell:r:m})])}{\sigma} \\ \frac{\partial g_2(z_{\ell:r:m})}{\partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})(-3[\Phi_{nor}(z_{\ell:r:m})]^2 + 4[\Phi_{nor}(z_{\ell:r:m})])}{\sigma}(z_{\ell:r:m})\end{aligned}$$

The second derivatives of g_1 and g_2 can be obtained as

$$\begin{aligned}\frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6](e^{z_{\ell:r:m}} - 1) - 10\phi_{nor}^2(z_{\ell:r:m})}{3\sigma^2} \\ \frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6](e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}}{3\sigma^2} \\ &\quad - \frac{10\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m} - \phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]}{3\sigma^2} \\ \frac{\partial^2 g_1(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6](e^{z_{\ell:r:m}} - 1)z_{\ell:r:m}^2}{3\sigma^2} \\ &\quad - \frac{10\phi_{nor}^2(z_{\ell:r:m})z_{\ell:r:m}^2 - 2\phi_{nor}(z_{\ell:r:m})[10\Phi_{nor}(z_{\ell:r:m}) - 6]z_{\ell:r:m}}{3\sigma^2}\end{aligned}$$

and

$$\begin{aligned}
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) (e^{z_{\ell:r:m}} - 1)}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 4)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \mu \partial \sigma} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) (e^{z_{\ell:r:m}} - 1) z_{\ell:r:m}}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 4) z_{\ell:r:m}}{\sigma^2} \\
&\quad - \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right)}{\sigma^2} \\
\frac{\partial^2 g_2(z_{\ell:r:m})}{\partial \sigma^2} &= \frac{\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) (e^{z_{\ell:r:m}} - 1) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad + \frac{\phi_{nor}^2(z_{\ell:r:m}) (6\Phi_{nor}(z_{\ell:r:m}) - 4) z_{\ell:r:m}^2}{\sigma^2} \\
&\quad - \frac{2\phi_{nor}(z_{\ell:r:m}) \left(-3 [\Phi_{nor}(z_{\ell:r:m})]^2 + 4 [\Phi_{nor}(z_{\ell:r:m})] \right) z_{\ell:r:m}}{\sigma^2}.
\end{aligned}$$

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