#### 1

# Disk Encryption: Do We Need to Preserve Length?

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Abstract—In the last one-and-a-half decade there has been a lot of activity towards development of cryptographic techniques for disk encryption. It has been almost canonised that an encryption scheme suitable for the application of disk encryption must be length preserving, i.e., it rules out the use of schemes like authenticated encryption where an authentication tag is also produced as a part of the ciphertext resulting in ciphertexts being longer than the corresponding plaintexts. The notion of a tweakable enciphering scheme (TES) has been formalised as the appropriate primitive for disk encryption and it has been argued that they provide the maximum security possible for a tag-less scheme. On the other hand, TESs are less efficient than some existing authenticated encryption schemes. Also TES cannot provide true authentication as they do not have authentication tags. In this paper, we analyze the possibility of the use of encryption schemes where length expansion is produced for the purpose of disk encryption. On the negative side, we argue that nonce based authenticated encryption schemes are not appropriate for this application. On the positive side, we demonstrate that deterministic authenticated encryption (DAE) schemes may have more advantages than disadvantages compared to a TES when used for disk encryption. Finally, we propose a new deterministic authenticated encryption scheme called BCTR which is suitable for this purpose. We provide the full specification of BCTR, prove its security and also report an efficient implementation in reconfigurable hardware. Our experiments suggests that BCTR performs significantly better than existing TESs and existing DAE schemes.

Index Terms	—Disk encryption,	Tweakable	Enciphering	Schemes,	Deterministic	Authenticated	Encryption

#### 1 Introduction

Security of data stored in bulk storage devices such as hard disks of laptop and desktop computers, USB sticks and SD cards has received a fair bit of attention from the cryptographic community. It has been argued that the best solution to this problem is an encryption scheme where the encryption and decryption algorithms reside in the disk controller. The algorithms would have access to the disk sectors but would have no knowledge about the high-level logical partitions of the disk, such as files and directories, which are maintained by the operating system and/or database management systems. Under this scenario, the disk controller encrypts the data before it writes a sector, and similarly, after reading a sector, the disk controller decrypts it before sending it to the operating system. This type of encryption has been termed in the literature as low-level disk encryption or inplace disk encryption.

A symmetric key cryptosystem with certain specific properties can serve as a solution to the low-level disk encryption problem. From the usability angle, one particularly important property that has been emphasized is length-preservation, i.e., the string that should be stored on a disk sector must have the same length as

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 Palash Sarkar is with the Applied Statistics Unit, Indian Statistical Institute, 203 B.T Road, Kolkata 700108, India. Email: palash@isical.ac.in that of the plaintext. This requirement rules out the schemes which produces authentication tags or uses other kinds of parameters such as nonces, initialization vectors etcetera. From the security angle, the schemes to be used must be secure against adaptive-chosen plaintext and ciphertext attacks. Informally this implies that no efficient adversary should be able to distinguish ciphertexts from random strings; and should not be able to modify a ciphertext so that it gets decrypted to something meaningful.

The cryptographic primitive called tweakable enciphering scheme (TES) was introduced in [18] as an appropriate candidate for low level disk encryption. The paper also provided the first TES scheme as a mode of operation of a block cipher. In the last few years, a number of proposals for TES have been proposed (see for example [18], [19], [37], [32]) and there have been studies regarding efficient hardware implementations of the proposed schemes [25].

In this paper, we revisit the requirement of length preservation for disk encryption. We argue that the length preserving property may not be crucial for this application as disk manufacturers can suitably format hard disks to accommodate a possible expansion in the ciphertext. A disk sector in any case has to store more information (such as error correction information) than the user data, so, the suggestion for storing a little extra information arising from encryption requirement may not be a big issue. Our analysis shows that space overhead for storing a longer ciphertext is as little as 0.4%.

Removing the restriction of length preservation brings

up the question of whether there are schemes which offer the same (or more) security guarantee as a TES, but at the same time are more efficient. To this end, we consider two kinds of authenticated encryption, namely (nonce based) authenticated encryption (AE) and deterministic authenticated encryption (DAE).

Using a (nonce based) AE for disk encryption is very attractive. However, we argue that there are significant security and practicability concerns which nullify this option. The other natural candidate is DAE with associated data. We argue that a DAE scheme satisfies the security requirement expected of a disk encryption scheme. Further, it also provides true message authentication unlike that of a TES<sup>1</sup>. The main gain in using a DAE scheme instead of a TES is in terms of efficiency.

To the best of our knowledge, the possibility of using DAE for disk encryption has not been explored earlier. One possible reason for this may be the fact that the notion of TES and its suitability for disk encryption predates the notion of DAE. The other possible reason is that DAE itself was introduced for a different application which is to solve the so-called key-wrap problem [30]. So, we are suggesting that a later introduced primitive (DAE) is more suitable for solving an earlier introduced problem (disk encryption) than the earlier introduced solution (TES).

We present a new DAE scheme called BCTR which is designed to specifically serve as a low-level disk encryption primitive. The design is based on a combination of XOR universal hash function and a block cipher. The hash function uses a very fast polynomial based hashing technique due to Bernstein [4]. The overall design strategy is to hash the contents of the sector and the sector address to produce a tag. This tag is used as an initialization vector (IV) in a counter type mode of a block cipher to perform the actual encryption of the contents of the sector. The ciphertext consists of the encrypted sector and the tag. This approach to the design of DAE follows the conceptual framework outlined in [30]. The idea of combining a XOR universal hash and a block cipher to design a DAE scheme has also been suggested in [20], [21]. Our details, however, are different and results in a faster overall scheme. We note that even though the main target of the new DAE scheme is disk encryption, the scheme itself (actually a slightly generalised version) can also be used for other more typical DAE applications.

The structure of BCTR bears some similarity with a construction named DCM-BRW proposed in [9]. In [9] a variant of the counter mode and a special polynomial hash were used to construct a double ciphertext mode (DCM). A DCM is a special mode which produces two ciphertexts for a single message, its functionality and security are different from that of a DAE. BCTR, though

shares the same components of DCM-BRW, its details are quite different from DCM-BRW.

**Previous and related works:** The primitives TES and DAE are well studied and below we briefly mention the relevant previous works.

The notion of TES as a distinct cryptographic primitive and its application to disk encryption was proposed in [18]. Since then, there has been a long line of research in designing secure and efficient TESs [19], [16], [26], [37], [11], [12], [17], [32]. These have mostly been block cipher modes of operations. Application of stream ciphers to TES design have been proposed in [33], [8]. Comparative implementation of different TES on reconfigurable hardware has been carried out in [25], [10], [8].

Some schemes for disk encryption have been standardised by different agencies. Notable among these are EME2 [16] and XCB [27], which have been standardized in IEEE-std 1619.2-2010 [2]. In a recent work, several flaws about XCB have been reported in [7]. A mode of operation called XTS has also been standardised for disk encryption in IEEE-std 1619-2007 [1]. It is well known that XTS is not a TES and there are easy block-level mixand-match attacks on XTS. This is noted in the standard document itself which consciously overlooks this due to the higher efficiency of XTS compared to known TES designs. More discussions regarding the disk encryption standards can be found in Appendix A.

The notion of DAE was formalised in [30] which also proposed a concrete DAE scheme. At a top level, the basic construction idea for DAE outlined in [30] has been followed in later works [20], [21]. As mentioned above, the works [20], [21] follow the strategy of combining a XOR universal hash function with a block cipher to obtain a DAE scheme. A DAE scheme realised as a mode of operation of a stream cipher has been proposed in [34].

#### 2 BACKGROUND

#### 2.1 Notation

We denote the set of all binary strings by  $\{0,1\}^*$ , and the set of all n-bit strings by  $\{0,1\}^n$ . For  $X,Y \in \{0,1\}^*$ , X||Y will denote the concatenation of the strings X and Y, and |X| denotes the length of X in bits. For a nonnegative integer  $i < 2^n$ ,  $\text{bin}_n(i)$  will denote the n-bit binary representation of i. By  $X \overset{\$}{\leftarrow} \mathcal{S}$ , we will denote the event of choosing X uniformly at random from the finite set  $\mathcal{S}$ .

An irreducible polynomial of degree n over GF(2) provides a representation of the finite field  $GF(2^n)$ . The elements of  $GF(2^n)$  can be considered to be polynomials over GF(2) of degrees less than n. We shall sometimes view n-bit strings as polynomials of degree less than n with coefficients in GF(2) and as such consider n-bit strings to be elements of  $GF(2^n)$ . If X and Y are n-bit strings, then  $X \oplus Y$  will denote the addition in the field, which is a bitwise XOR of the strings; and XY will denote multiplication in  $GF(2^n)$  which can be

<sup>1.</sup> TESs do provide implicit authentication in the sense that if a single bit of a valid ciphertext is changed then it gets decrypted to a random plaintext which can be detected by a high level application which would use the plaintext.

realized by ordinary polynomial multiplication modulo the irreducible polynomial representing the field.

An adversary  $\mathcal{A}$  is an algorithm which has access to one or more oracles and which outputs either 0 or 1. Oracles are written as superscripts. The notation  $\mathcal{A}^{\mathcal{O}_1,\mathcal{O}_2}$  denotes an adversary  $\mathcal{A}$  which has access to the oracles  $\mathcal{O}_1$  and  $\mathcal{O}_2$  and the notation  $\mathcal{A}^{\mathcal{O}_1,\mathcal{O}_2} \Rightarrow 1$  denotes the event that the adversary  $\mathcal{A}$  outputs the bit 1.

An n-bit block cipher is a function  $E: \mathcal{K} \times \{0,1\}^n \to \{0,1\}^n$ , where  $\mathcal{K} \neq \emptyset$  is the key space and for any  $K \in \mathcal{K}$ , E(K,.) is a permutation. We write  $E_K(.)$  instead of E(K,.). Let  $\operatorname{Perm}(n)$  denote the set of all permutations on  $\{0,1\}^n$ . Our security analysis will be in the information theoretic setting where a block cipher is modelled as a uniform random permutation, i.e., in the analysis a concrete block cipher will be replaced by  $\pi$  which is chosen uniformly at random from  $\operatorname{Perm}(n)$ .

#### 2.2 Tweakable Enciphering Schemes

A tweakable enciphering scheme is a tuple  $(\mathbf{K}, \mathbf{E}, \mathbf{D})$  where  $\mathbf{K}$  is the key generation algorithm (which is randomised) and  $\mathbf{E}$  and  $\mathbf{D}$  are deterministic algorithms and can be seen as functions  $\mathbf{E}, \mathbf{D} : \mathcal{K} \times \mathcal{T} \times \mathcal{X} \to \mathcal{X}$ . Here  $\mathcal{K} \neq \emptyset$  and  $\mathcal{T} \neq \emptyset$  are the key space and the tweak space respectively. The message and the cipher spaces are  $\mathcal{X}$ . We shall write  $\mathbf{E}_K^T(.)$  and  $\mathbf{D}_K^T(.)$  instead of  $\mathbf{E}(K,T,.)$  and  $\mathbf{D}(K,T,.)$  respectively. The functions  $\mathbf{E}$  and  $\mathbf{D}$  are inverses in the following sense:  $X = \mathbf{D}_K^T(Y)$  if and only if  $\mathbf{E}_K^T(X) = Y$ .

Let  $\Pi^{\mathcal{T}}(\mathcal{X})$  denote the set of all functions  $\pi: \mathcal{T} \times \mathcal{X} \to \mathcal{X}$  where  $\pi(\mathcal{T},.)$  is a length preserving permutation. Such a  $\pi \in \Pi^{\mathcal{T}}$  is called a tweak indexed permutation. For a tweakable enciphering scheme  $\mathbf{E}: \mathcal{K} \times \mathcal{T} \times \mathcal{X} \to \mathcal{X}$ , we define the advantage an adversary  $\mathcal{A}$  has in distinguishing  $\mathbf{E}$  and its inverse from a random tweak indexed permutation and its inverse in the following manner.

$$\mathbf{Adv}_{\mathbf{E}}^{\pm \widetilde{\mathrm{prp}}}(\mathcal{A}) = \left| \Pr \left[ K \overset{\$}{\leftarrow} \mathcal{K} : \mathcal{A}^{\mathbf{E}_{K}, \mathbf{E}_{K}^{-1}} \Rightarrow 1 \right] - \Pr \left[ \boldsymbol{\pi} \overset{\$}{\leftarrow} \boldsymbol{\Pi}^{\mathcal{T}}(\mathcal{M}) : A^{\boldsymbol{\pi}, \boldsymbol{\pi}^{-1}} \Rightarrow 1 \right] \right| . (1)$$

 ${\mathcal A}$  has the following restrictions while querying its oracles: Let T, P and C represent tweak, plaintext and ciphertext respectively. We assume that an adversary never repeats a query, i.e., it does not ask the encryption oracle with a particular value of (T,P) or the decryption oracle with a particular value of (T,C) more than once. Furthermore, an adversary never queries its decryption oracle with (T,C) if it got C in response to an encrypt query (T,P) for some P. Similarly, the adversary never queries its encryption oracle with (T,P) if it got P as a response to a decryption query of (T,C) for some C. These queries are called *pointless* as the adversary knows what it would get as responses for such queries.

The resource bounded advantage  $\mathbf{Adv_E^{\pm prp}}(q, \sigma)$  is defined to be the maximum advantage over all adversaries  $\mathcal{A}$ , when  $\mathcal{A}$  is allowed to make a total of at most q

queries with query complexity  $\sigma$ . The number of queries includes both encryption and decryption queries and the query complexity counts the total number of bits in both encryption and decryption queries.

#### 2.3 Deterministic Authenticated Encryption

Deterministic authenticated encryption (DAE) schemes are encryption schemes which provide security both in terms of privacy and authentication. These schemes were first proposed by Rogaway and Shrimpton [30], where the authors described the syntax of the DAE along with the security definition and a generic construction which they called as the Synthetic Initialization Vector (SIV) mode.

A DAE is a tuple  $\Psi = (\mathbf{K}, \mathbf{E}, \mathbf{D})$ , where  $\mathbf{K}$  is the key generation algorithm (which is randomised);  $\mathbf{E}$  and  $\mathbf{D}$  are deterministic algorithms called as encryption and decryption algorithms respectively.

With a DAE  $\Psi$  are associated non-empty sets  $\mathcal{K}$ ,  $\mathcal{X}$ ,  $\mathcal{Y}$  and  $\mathcal{H}$  which are respectively the key, message, cipher and header spaces. The encryption algorithm  $\mathbf{E}$  takes as input an element from  $\mathcal{K} \times \mathcal{H} \times \mathcal{X}$  and returns an element in  $\mathcal{Y}$ ; the decryption algorithm takes as input an element from  $\mathcal{K} \times \mathcal{H} \times \mathcal{Y}$  and returns either an element in  $\mathcal{X}$  or a special symbol  $\bot$ . We shall write  $\mathbf{E}_K^H(X)$  or  $\mathbf{E}_K(H,X)$  to denote  $\mathbf{E}(K,H,X)$ . Similarly, we shall write  $\mathbf{D}_K^H(Y)$  or  $\mathbf{D}_K(H,Y)$  to denote  $\mathbf{D}(K,H,Y)$ .

The message space and the cipher space are nonempty sets containing binary strings, i.e.,  $\mathcal{X}, \mathcal{Y} \subseteq \{0,1\}^*$ , and the header space  $\mathcal{H}$  contains vectors whose components are binary strings. It is required that  $\mathbf{D}_K^H(Y) = X$ if  $\mathbf{E}_K^H(X) = Y$  and  $\mathbf{D}_K^H(Y) = \bot$  if no such  $H \in \mathcal{H}$  and  $X \in \mathcal{X}$  exist such that  $\mathbf{E}_K^H(X) = Y$ .

It is assumed that for any  $K \in \mathcal{K}$ ,  $X \in \mathcal{X}$  and  $H \in \mathcal{H}$ ,  $|\mathbf{E}_K^H(X)| = |X| + e(X,H)$ , where  $e: \mathcal{X} \times \mathcal{H} \to \mathbb{N}$  is called the expansion function of the DAE scheme. The value  $\lambda = \min_{X \in \mathcal{X}, H \in \mathcal{H}} \{e(X,H)\}$  is called the stretch of the DAE scheme. In most (possibly all) constructions the amount of expansion is independent of the length of the message.

Let  $\Psi = (\mathbf{K}, \mathbf{E}, \mathbf{D})$  be a DAE scheme. Let  $\mathcal{A}$  be an adversary attacking  $\Psi$ . The adversary has access to the oracle  $\mathcal{O}$ .  $\mathcal{O}$  can either be  $\mathbf{E}_K(.,.)$ , where K is generated uniformly at random from the key space  $\mathcal{K}$  or it can be \$(.,.) which returns random strings of length equal to the length of the ciphertext. The adversary can query the oracle with a query of the form (H,M), where H, M denotes the header and message respectively and and thus get back the responses from the oracle.  $\mathcal{A}$  has the restriction that it cannot repeat a query. The privacy advantage of adversary  $\mathcal{A}$  is defined as

$$\mathbf{Adv}_{\Psi}^{\text{dae-priv}}(\mathcal{A}) = \left| \Pr \left[ K \stackrel{\$}{\leftarrow} \mathcal{K} : \mathcal{A}^{\mathbf{E}_{K}} \Rightarrow 1 \right] - \Pr \left[ \mathcal{A}^{\$} \Rightarrow 1 \right] \right|. \tag{2}$$

To define the authentication advantage we consider that A is given access to the encryption oracle  $\mathbf{E}_K(.,.)$  and

queries it with plaintexts of his choice and obtains the corresponding ciphertexts. Finally,  $\mathcal A$  outputs a forgery, which consists of a header and a ciphertext  $(T,\mathcal C)$ .  $\mathcal A$  is said to be successful if  $\mathbf D_K(T,\mathcal C) \neq \bot$ . For querying the encryption oracle  $\mathcal A$  follows the same restriction that the adversary does not repeat a query additionally  $\mathcal A$  cannot output  $(T,\mathcal C)$  as a forgery if he obtained  $\mathcal C$  as a response for his query (T,X) to the encryption oracle. The last restriction is to rule out trivial win. The authentication advantage of the adversary  $\mathcal A$  is defined as the probability that  $\mathcal A$  does a successful forgery, in other words

$$\mathbf{Adv}_{\Psi}^{\text{dae-auth}}(\mathcal{A}) = \Pr[\mathcal{A}^{\mathbf{E}_K(.,.,.)} \text{ forges }].$$
 (3)

The resource bounded advantages  $\mathbf{Adv}_{\Psi}^{\mathrm{dae-priv}}(q,\sigma)$  and  $\mathbf{Adv}_{\Psi}^{\mathrm{dae-auth}}(q,\sigma)$  are defined in the same way as that for  $\mathbf{Adv}_{\mathbf{E}}^{\pm \widetilde{\mathrm{prp}}}(q,\sigma)$ . In [30] the two notions of privacy and authentication as depicted in equations (2) and (3) were combined to give a unified security definition. In [30] it was shown that the unified definition of security is equivalent to the separate notions of privacy and authenticity. In the present case we use the separate definitions of privacy and authenticity, as that makes it easier to understand the proofs.

#### 2.4 (Nonce Based) Authenticated Encryption

The notion of nonce-based AE predates the formalisation of DAE. As evident, nonce based AE schemes receives as input a nonce in addition to the plaintext and the header. The nonce is supposed to be unique for each message, and no security is guaranteed if the same nonce is ever used to encrypt two messages. The use of a nonce allows more efficient constructions of AE compared to DAE. There are very efficient constructions of nonce based AEs already available in the literature, for example the OCB mode of operation and its variants [29], [28], [22]. The CAESER competition [6] is currently considering more than 50 different AE constructions. All these candidates are not necessarily nonce based AEs.

The security of AE schemes was first formalized in [3]. The currently accepted security definition for nonce based AEs is similar to that of a DAE, i.e., an AE is considered to be secure if it is secure both in terms of privacy and authentication as mentioned in equations (2) and (3). The important difference is that an adversary is allowed to choose the nonce along with the message and headers in its encryption queries and is not allowed to repeat a nonce in its encryption queries.

#### 3 To Tag or not to Tag?

Suppose that for disk encryption, we wish to use a length increasing encryption primitive where ciphertexts are longer than plaintexts due to the generation of a tag. We will assume that the length of the ciphertext for a message of length  $\ell$  is  $\ell+\lambda$  bits, where  $\lambda$  is a constant, i.e.,

it does not depend on  $\ell$  and is fixed for the scheme. Most (possibly all) practical schemes providing authentication satisfy this condition.

The first question one has to consider is how would such a primitive fit into the existing architecture. There are two options that one may consider. For the ensuing discussion, suppose that disk sectors are *s* bits long.

**Application-oblivious strategy:** In a typical architecture, software applications such as operating systems and databases read and write data from the disk in chunks of s-bit blocks. The same continues to be true even with the use of a tag-based disk encryption scheme. To enable this, the disk would have to be organised so that  $\lambda$  additional bits are made available per sector to store the tag. With this option, the applications do not require any change and continue to read and write data as before.

**Application-aware strategy:** In this option, the organisation of the disk is not changed. Instead, the  $\lambda$ -bit tag is stored within the s bits of each sector. As a result, applications will be required to read and write data in chunks of  $s-\lambda$  bits.

Both the strategies require storing the tag and will result in the loss of some amount of available disk space. There are, however, several important differences between the two strategies.

For the application-aware strategy there are several objections. For one thing, it will require basic changes in the input/output routines of a large number of applications such as operating systems and database management systems. This makes the option unattractive from an application point of view. From a more abstract level, this strategy violates the principle of low-level disk encryption.

The deployment of a disk encryption scheme should be invisible to top level applications which should work the same way for both encrypted and unencrypted disks. Modifying the disk read/write modules of applications to enable these to communicate with encrypted disks will make them unsuitable for communicating with unencrypted disks. Since it is not envisaged that all disks will be encrypted, applications will be required to have two sets of disk read/write modules, one for accessing encrypted disks and another for accessing unencrypted disks. This is clearly a problematic scenario and will result in the whole idea being a non-starter. Having said this, we do remark that there could be some specific niche applications where this approach would be suitable. The particular tag-based disk encryption scheme that we propose can be suitably modified to handle such situations.

Let us now consider the application-oblivious strategy. From the point of top-level applications which interact with disks, this strategy does not require any change in the read/write modules. Both encrypted and unencrypted disks will be accessed in exactly the same manner and data will be read in s-bit chunks. It will be the responsibility of the disk controller to ensure that encryption and decryption are done in a manner which

is transparent to the applications.

The application-oblivious strategy requires disk manufactures to incorporate certain changes in the way disks are organised. Currently disk sectors are 4096 bytes, which means that each sector can store 4096 bytes of user data. This, however, does not mean that only 4096 bytes are alloted for a sector. The following additional overhead have to be incurred per sector.

Error correction coding: The user data is not stored in the format provided by an application to the disk. An important transformation that the user data undergoes is error correction coding and this obviously creates an expansion in length of the original data. So the 4096 bytes of data which an application sends to the disk controller for writing occupies more than 4096 bytes in the physical disk as it is appropriately coded for error correction by the disk controller.

**Preamble:** These bits are used to synchronize read/write head movements. Formatting a disk is writing all preambles on it.

**Inter-sector gap:** A certain amount of physical gap is kept between two sectors on a disk.

The sum-total of the above constitutes the data sector level overhead. Additionally, there is another overhead which is at the servo sector level. Some idea about the overheads can be found in [36]. A letter by Fujitsu Corporation in 2003 declared that the then format overhead of their commercial hard disks were approximately 15% of the sector size, and in the letter it was predicted that maintaining hard disks which store 512 bytes (the sector size in 2003) of user data per sector would make the format overhead to grow to 30% within 2006 [14](Page 15). Current disks store 4096 bytes of user data per sector.

The essence of the above discussion is that physically a disk sector is larger than the amount of user data it can store. It is in this context that we put forward the suggestion that disk manufacturers can organise sectors to accommodate an additional  $\lambda$  bits to store a tag. In the application oblivious strategy, these  $\lambda$  bits will not be visible to the applications which access the disks which will continue to read/write data in the same manner as it does for unencrypted disks. If  $\lambda = 128$  (i.e., 128-bit tags are used for authentication), then the storage overhead incurred due to the storage of the tags is 0.4%. Using smaller values of  $\lambda$  reduces the overhead further. Compared to the overhead for error correction coding this is negligible.

It is to be noted that TES based disk encryption schemes do not have any ciphertext expansion. As a result, using a TES for disk encryption does not require any reorganisation of the physical sector layout of a disk. Arguably, it is for this reason that TESs have been proposed as the ideal solution for disk encryption.

Implementing any disk encryption scheme as part of the disk controller entails a performance penalty. It is desirable to minimise this penalty to the extent possible. In this context, the question arises as to whether it is possible to design a disk encryption scheme which is faster than a TES and provides the same (or better) security guarantee? In the rest of the work we answer this question in the affirmative, but with the trade-off that the physical sector organisation should be capable of storing an additional tag and so incurring a small overhead.

# 4 TAG-BASED ENCRYPTION SCHEMES: WHICH ONE TO USE?

The literature describes two types of symmetric encryption schemes which lead to ciphertexts being longer than plaintext due to the generation of a tag. These are authenticated encryption with associated data and deterministic authenticated encryption also with associated data

As already discussed in Section 2.4, AE schemes provide security both in terms of privacy and authentication. The ciphertext produced by these schemes includes an authentication tag, and this authentication tag can be used to verify the authenticity of the ciphertext. There have been many proposals for AE scheme. Among them, some (such as the famous OCB mode of operation [29], [28], [22]) are very efficient and require little computation other than a block-cipher call per block of message.

AE schemes are nonce based, i.e., they require a quantity called nonce, which is non-repeating. In other words, to ensure security, each plaintext needs to be encrypted with a different value of the nonce. If the same value of the nonce is used for two encryptions then the scheme loses security. It is in the generation and management of nonces that problems arise. We next discuss the problems of using a nonce based scheme for disk encryption.

#### 4.1 Problems with Nonces

AE requires nonces for both encryption and decryption. Thus, in a ciphertext produced by an AE scheme, the nonce has to be stored along with the ciphertext. This results in further increasing the sector level overhead beyond what would be required for storing only the tag. If a scheme uses a  $\mu$ -bit nonce and a  $\lambda$ -bit tag, the expansion would be  $\mu + \lambda$  bits beyond the user data. It is possible to consider several strategies for generation and storage of nonces. We list these possibilities and analyse them:

Sector level counter: In this strategy, we assume that a counter is maintained for each sector, and a nonce is generated by concatenating the sector address with the current counter value. For this, it would be sufficient to use a 40-bit counter to generate the nonces. This 40-bit counter value for each sector is stored within the sector. When a write to the sector is required the current counter value is read from the sector, it is incremented, and this value is used to generate the nonce by concatenating the counter with the sector address and finally encrypt. The incremented value is written back to the sector along with the ciphertext. This will ensure that each plaintext

gets encrypted with a unique nonce. Also, storing the 40-bit counter would be sufficient as the sector addresses are implicitly known by the disk controller.

A serious security concern with this strategy is that a malicious adversary may be able to tamper the value of the counter stored in a sector and force the encryption of two different messages with the same nonce. This is possible in the following scenario. The adversary sends a plaintext to be stored in a sector and the disk controller generates the ciphertext and stores the current counter value and the ciphertext on the disk. The adversary reads off the ciphertext and tampers the data stored on the sector by decrementing the value of the counter. It then sends another plaintext to be stored in the same sector. In response, the disk controller reads the current counter value stored in the sector, increments it and encrypts the provided plaintext with the counter value and again stores on the sector. By reading off the new ciphertext, the adversary is able to obtain the ciphertexts corresponding to two different plaintexts encrypted under the same nonce. This violates the security requirement of nonce-based encryption schemes and can lead to concrete attacks.

Apart from the security issue, storing the counter along on the sector creates another inefficiency. Suppose a write to the sector is required. To determine the present value of the counter, the disk controller must first read the entire sector before it can encrypt the given data and write back. So, each write request necessarily generates a read request.

A solution would be to not store the counter value in the sector but, to maintain a separate counter for each sector in additional tamper resistant storage, which may be a part of the disk controller. Given the huge number of sectors that are present in modern day disks, such a solution is infeasible from an engineering point of view. **Global counter:** In this approach, a single global counter is maintained in a tamper resistant storage for the whole disk and any sector write uses the current value of the counter and increments it. To enable decryption, the value of the counter under which encryption is done has to be stored in the sector along with the ciphertext. One major difficulty with this solution is the following. Suppose several sectors are required to be written simultaneously. With a single global counter this will not be possible. Since unique counter values will be required, the writes will necessarily have to be done in a sequential manner. This will result in significant performance degradation.

An intermediate solution can be to use several global counters. While this is an engineering compromise between a single global counter and sector level counter, it still has the problem that the global counters have to be stored in tamper resistant memory. To avoid repetition, the nonces for a particular sector must be from a single counter. So, the sectors in a disk would have to be partitioned and each counter is to be used for servicing one set of sectors. As a result, the problem of simultane-

ous writing of sectors in one particular partition is not resolved.

**Random Nonce:** Nonces are required to be distinct, but if relatively long nonces are used, then one may work with a random nonce. For example, if 128-bit nonces are used, then using a random nonce will with high probability ensure that the first  $2^{64}$  nonces are distinct. Such nonces would have to stored in the sector along with the ciphertext. The major problem with this approach is the proper generation of random nonces for each sector write. It is this problem which makes this solution infeasible.

In summary, the issue of secure generation, handling, and storage of nonces is a non-trivial engineering task and effectively rules out the use of nonce based AE schemes for disk encryption.

# 5 Use of DAE Schemes for Disk Encryption

DAE schemes are similar to AE schemes but they do not require nonces. They provide almost the same security as that of AE schemes. The only difference is that DAE schemes being deterministic produce the same ciphertext if the same plaintext is encrypted multiple times.

We propose the use of DAE schemes with support for authenticating associated data as a solution to the disk encryption problem. The proposed usage is as follows.

Plaintexts are of fixed lengths which is the length of the user data that is stored on individual sectors. For encryption, the sector address is used as the associated data. The ciphertext consists of two strings, one of which is of the same length as the plaintext and the other string is a short fixed length tag. The first string is written on the portion of the sector which stores user data. The tag is written in an additional space in the sector. As argued above, this is the application oblivious strategy and the physical disk structure has to be organised to provide space for storing such a tag.

In the following subsections we discuss several issues regarding the suitability of DAE when used in the above manner.

### 5.1 Is Security of DAE Adequate for Disk Encryption?

Both DAE and TES being deterministic schemes, they share a common feature. If the same plaintext is encrypted with the same tweak (associated data) twice then the ciphertexts are also the same. We would like to suggest the replacement of TES with DAE. For this we need to argue that the security guarantee of a DAE scheme is not at a lower level than the security guarantee of a TES.

As explained earlier, the security model of a TES is the following. The adversary is given access to two oracles which it can query in an adaptive manner (without making pointless queries). At the end, it has to decide whether the oracles are real (i.e., the oracles are the

encryption and decryption algorithms of the TES instantiated with a uniform random key) or random (i.e., the oracles are two independent random oracles).

Security of DAE can also be viewed in a similar manner. The adversary is given access to two oracles (say left and right) which it can query in an adaptive manner. At the end, it has to determine whether the oracles are real or random. For the real case, the left and the right oracles are respectively the encryption and the decryption algorithms of the DAE scheme instantiated with a uniform random key; while for the random case, the left oracle is a random oracle which returns independent and uniform random strings of appropriate length and the right oracle is one which always returns  $\bot$ .

The security of DAE defined earlier implies security against the above adversarial model. This can be easily seen by considering a sequence of three games. In the first game, the oracles provided to the adversary are real. In the second game, the decryption (i.e., the right) oracle is replaced by an oracle which always returns ⊥. The advantage of an adversary to distinguish between these two games can be upper bounded by the advantage of an adversary in defeating the authenticity of the DAE scheme. In the third game, the encryption (i.e., the left) oracle is replaced by a random oracle which returns independent uniform random strings of appropriate lengths. The advantage of an adversary to distinguish between the second and the third game is upper bounded by the advantage of an adversary in defeating the privacy of the DAE scheme.

The first game is the real game and the third game is the random game. For a secure DAE scheme, the difference in an adversary's advantage in the two games are bounded above by the sum of the advantages of defeating either privacy or authenticity of the DAE scheme. This informal argument shows that a DAE scheme secure in the model defined in Section 2.3 implies security in the two-oracle model. For a more formal treatment of this approach see [30].

Two-oracle security models for TES and DAE are similar. Both essentially capture the intuition that access to these oracles do not provide sufficient information to the adversary to distinguish real from random. So, from a security point of view, replacing TES with DAE does not entail any loss.

**True Authentication:** DAE are authenticated encryption schemes and ciphertexts produced by such schemes have authentication tags. Using these tags the authenticity of the ciphertext can be explicitly verified and invalid ciphertexts can be explicitly rejected.

On the other hand, TESs are length preserving and so they cannot provide true authentication. The only guarantee that such schemes can provide is that an adversarially modified ciphertext will get decrypted to a random plaintext. This can be detected by a high level application which uses the data, but the decryption algorithm itself cannot detect this. In some (though rare)

cases, this may cause some difficulty if the plaintext were to be truly random since then there would be no way to detect tampering in the ciphertext. Thus, a TES is unable to provide true authentication. The type of authentication that they provide has been termed as "poor man's authentication" in [15].

**Limitations:** It is to be noted that sector-level mix-andmatch apply to disk encryption schemes irrespective of whether a TES or a DAE scheme is used. This can be seen as follows. Suppose there are two sectors having addresses add<sub>1</sub> and add<sub>2</sub>. An adversary makes two plaintext queries: the first query is to encrypt a string  $w_1$  to the first sector and a string  $w_2$  to the second sector; the second query is to encrypt  $x_1$  and  $x_2$  to the first and the second sectors respectively. This creates ciphertexts  $u_1$  for  $(\mathsf{add}_1, w_1)$ ;  $u_2$  for  $(\mathsf{add}_2, w_2)$ ;  $y_1$  for  $(\mathsf{add}_1, x_1)$ ; and  $y_2$  for  $(add_2, y_2)$ . Possessing  $(u_1, u_2)$  and  $(y_1, y_2)$ , the adversary can now create the ciphertexts  $u_1$  for the first sector and  $y_2$  for the second sector. Decryption of this ciphertext results in the data  $w_1$  for the first sector and  $x_2$ for the second sector. Since this data was never written to the disk, this defeats the security of the scheme.

Thus, both TES and DAE based disk encryption schemes ensures security only at the granularity level of a sector. Viewed across multiple sectors, neither schemes provide proper security. Having said this, we would like to point out an important difference in the way an adversary would have to carry out the above attack depending on whether TES or DAE is employed. With a TES, the adversary can simply swap the user data portions of the two sectors as mentioned above leading to a successful attack. When a DAE is applied, the tags are written to a portion of the disk which is separate from the user data portion. So, to mount a successful mix-and-match attack, the adversary would be required to access both the user data portions along with the control portions of a sector. To some extent, this makes the attack a little more difficult to mount.

#### 5.2 Gains and Loses

**Loss of space:** As argued above, it is technically feasible for disk manufacturing companies to modify the physical organisation of a disk to create space for storing the tag produced by a DAE scheme. Needless to say, the extra information stored in form of a tag will mean loss of space for storing user data. A DAE scheme produces a tag of fixed length for each plaintext encrypted. Thus if one fixes the tag length to  $\lambda$  bits then for each plaintext of  $\ell$  bits the ciphertext will be  $(\ell + \lambda)$  bits long. So, greater the length of the plaintext the less would be the percentage loss of space.

In case of disk encryption, the length of the plaintext is also fixed and equals the length of the user data to be stored in a sector. The hard disks available in the market have 4096-byte sectors [14] which is an increase over the previously used 512-byte sectors. This increase in the sector size makes the use of DAE as a disk encryption

TABLE 1 Extra format overhead

Sector size	Tag	size (in bits)		
(in bytes)	64	96	128	
512	1.56%	2.34%	3.13%	
4096	0.19%	0.29%	0.39%	
8192	0.09%	0.14%	0.19 %	

algorithm more appealing, as due to the greater sector size the total loss incurred in space for storing the tags is lesser. In Table 1 we show the amount of loss in space that would take place taking into account various disk sizes and tag lengths.

Table 1 shows that the extra format overhead for using a DAE with tag length 128 bits would be a negligible 0.4% for 4096-byte sectors. The security promise of a 128-bit tag may not be required. It is quite likely that a 64-bit tag will suffice if the number of times a sector is encrypted or decrypted between two key changes is not too high. For 64-bit tags, the overhead would be 0.2% for 4096-byte sectors.

Gain in efficiency: The current constructions of tweakable enciphering schemes fall into three basic categories: Encrypt-Mask-Encrypt type, Hash-ECB-Hash type, and Hash-Counter-Hash type. CMC [18], EME [19], and EME\*[16] fall under the Encrypt-Mask-Encrypt group. PEP [11], TET [17], and HEH [31] fall under the Hash-ECB-Hash type; and XCB [26], HCTR [37], HCH [12], HMCH [32] fall under the Hash-Counter-Hash type.

These constructions use a block cipher as the basic primitive, and in addition, some schemes utilize a universal hash function which is a Wegman-Carter type polynomial hash or a more efficient variant known as Bernstein-Rabin-Winograd hash [32]. The constructions of the Hash-Counter-Hash and Hash-Encrypt-Hash type invoke two polynomial hash functions with a layer of encryption in-between. The Encrypt-Mask-Encrypt structure consists of two layers of encryption with a light weight masking layer in-between.

So, the main computational overhead of the Encrypt-Mask-Encrypt architecture is given by the block cipher calls, whereas for the other two classes of constructions, both block cipher calls and finite field multiplications account for a significant portion of the total computational cost.

Known DAE constructions require less computational overhead. This is due to the fact that it is possible to realize a DAE with a single layer of polynomial hashing along with a layer of encryption. In comparison, hashbased TES constructions require two layers of hashing and a layer of encryption. The operation counts of the existing TES and DAE constructions are provided in Tables 2 and 3 respectively.

**Usability issues:** As mentioned earlier, the best way to go for low level disk encryption is to implement the encryption and decryption algorithms to be a part of the disk controller. Additionally, a mechanism for directly

injecting a key into the disk controller would be required. The resulting architecture would ensure that the disk encryption is transparent to the higher level applications which access the disk. Note that a mechanism for direct key injection is required irrespective of whether a TES or a DAE is used for disk encryption.

The direct key injection into the disk controller can be achieved by having a port in the disk to directly read the key from a small portable device. Such a device can be a small USB drive or an RF device. Design of the key transfer mechanism, however, will require careful security engineering so that the key is not revealed during the transfer. While important, these details are outside the present scope of the work and so we do not consider them any further here.

#### 6 BCTR: A New DAE Scheme

BCTR uses a special class of polynomial proposed in [4]. These polynomials were later named as Bernstein-Rabin-Winograd (BRW) polynomials in [32]. Let  $X_1, X_2, \ldots, X_m \in GF(2^n)$ , and  $h \in GF(2^n)$  then a BRW polynomial over  $GF(2^n)$  is defined as follows

- BRW<sub>h</sub>() = 0
- BRW<sub>h</sub>( $X_1$ ) =  $X_1$
- BRW<sub>h</sub> $(X_1, X_2) = X_1 h \oplus X_2$
- BRW<sub>h</sub> $(X_1, X_2, X_3) = (h \oplus X_1)(h^2 \oplus X_2) \oplus X_3$
- $\mathsf{BRW}_h(X_1, X_2, \dots, X_m) = \mathsf{BRW}_h(X_1, \dots, X_{t-1})(h^t \oplus X_t) \oplus \mathsf{BRW}_h(X_{t+1}, \dots, X_m)$ , if  $t \in \{4, 8, 16, 32, \dots\}$  and  $t \leq m < 2t$ .

For  $m \geq 2$ ,  $\mathsf{BRW}_h(X_1, \dots, X_m)$  can be computed using  $\lfloor m/2 \rfloor$  multiplications and  $\lg m$  squarings [4], [32]. Thus, it requires half the number of multiplications compared to a normal polynomial.

#### 6.1 The Construction

BCTR is designed to be suitable for low level disk encryption. In particular, the message space of BCTR is  $\{0,1\}^{nm}$  where n is the block length of the underlying block cipher. Hence a message for BCTR is of fixed length containing m blocks of n-bits. The tweak space is  $\{0,1\}^n$  and the cipher space is  $\{0,1\}^{mn+\lambda}$  where  $\lambda$  is the desired tag length. Thus, the construction inherently has restrictions on the message length and the tweak length. But these restrictions are not of any significance for the disk encryption application as the messages are always of fixed length which is the data size of the sector and which in turn is 4096 bytes for the currently available disks. The sector address is treated as the tweak, thus the restriction in the tweak length is also of no consequence.

The encryption and decryption algorithms using BCTR are shown in Figure 1. The construction requires a key h for the BRW polynomial and a key K for the block-cipher. Other than the two keys the encryption algorithm takes in the plaintext and the tweak and returns a ciphertext and the decryption algorithm takes in the ciphertext and tweak and returns the plaintext.

The details of the working of the algorithm are self explanatory as depicted in Figure 1. It essentially consists of a BRW hashing in combination with a modified counter mode which was proposed in [37]. In comparison to previous works, the main efficiency improvement comes from the application of BRW hashing.

To encrypt a message of m blocks, BCTR requires (m+1) block cipher calls. In addition to this it requires  $\lfloor \frac{m+1}{2} \rfloor + 1$  finite field multiplications and computation of  $\lg(m+1)$  squares. Note that, computing squares in binary fields is much more efficient than multiplication. Thus, the (m+1) block cipher calls and the  $\lfloor \frac{m+1}{2} \rfloor + 1$  multiplications constitute the main computational overhead of BCTR. Same number of operations are required for decryption.

The construction requires two keys, h the key for the BRW polynomial and K the block-cipher key. Using known techniques, it is possible to generate the key h using the block-cipher key and still obtain a secure construction, but this would mean one more block-cipher call or a storage of key related material which is (almost) the same as storage of an extra key. So, we decided to keep two independent keys.

As is the case with all DAE schemes, the encryption algorithm requires two passes over the data, one for computing the tag  $\tau$  and other for generating the ciphertext. The ciphertext is generated using a counter type mode of operation which is fully parallelizable. For decryption, in practice, two passes are not required. As the counter mode and the computation of  $\tau$  can be done in parallel. Thus the construction offers ample flexibility for an efficient parallel implementation. Also, in an optimized hardware implementation the decryption speed would be significantly better than the encryption speed. For the application of disk encryption, this property can be very useful; as in normal usage, a sector which has been written once is expected to be read multiple times. Handling length variability: Our definition of BCTR assumes that messages are all of the same length which is a multiple of the block length. For the purposes of disk encryption, this is sufficient. More generally, however, there can be applications which require to encrypt variable length messages which are not necessarily a multiple of the block length. There are standard ways to handle such situations and we briefly mention the required modifications.

The main change would be in the application of the BRW map. This would now be applied to a string which is a concatenation of the following three strings: the message, zero padded to the next multiple of n; a single n-bit block encoding the binary representation of the length of the message; and the tweak. Hashing such pre-processed messages will ensure low differential probability in the more general case of variable length messages. The other modification will be to run the counter mode to generate sufficiently many bits required to encrypt the message. **Comparison to existing TESs:** It has been already discussed in Section 5.2 that the existing TES can be classi-

fied into three basic categories according to the way they are constructed. They are hash-ECB-hash, hash-counter-hash and encrypt-mask-encrypt types. For the first two types (for example TET, HCTR, HCH, XCB etcetera) one uses two layers of polynomial hashes with a layer of ECB or a counter mode in-between. For the last type (example CMC, EME) there are two encryption layers.

To encrypt/decrypt a message/cipher of m blocks the first two types roughly require m block-cipher calls along with 2m multiplications. In [32] some new constructions of hash ECB hash type and hash counter hash type were proposed which uses a BRW polynomial to compute the hash and for these constructions about m multiplications are required. The encrypt-mask-encrypt type algorithms like EME [19] and CMC [18] require about 2m block cipher calls and no multiplication.

In Table 2 we compare the number of operations required for tweakable enciphering schemes for fixed length messages which uses n-bit tweaks with the number of operations required for BCTR. From this table, we can see that encrypting with BCTR will be more efficient than encrypting by the existing tweakable enciphering schemes which uses polynomial hashing. A direct comparison to CMC/EME is not possible, since this depends on the relative efficiencies of a block cipher call and a multiplication. Later we provide implementation results which indicate that BCTR performs better than encrypt-mix-encrypt type TESs.

Comparison to existing DAE schemes: Table 3 shows the operation counts of BCTR compared to some of the other known DAE schemes. From this it is clear that BCTR is better than both HBS and BTM. The comparison to SIV is based on the comparative performance of a block cipher call versus that of a multiplication. Our implementation results suggest that multiplication is faster than a block cipher call. For SIV, however, the disadvantage is that the sequential CMAC algorithm is used to perform authentication. As such, there is no good pipelined implementation of SIV and for this reason we later do not report implementation results for SIV.

#### 6.2 Security of BCTR

The following result states the security property of BCTR.

Theorem 1: Let BCTR[ $\Pi$ ] denote BCTR as in Figure 2 where the block cipher  $E_K()$  is replaced by a permutation  $\pi \stackrel{\$}{\leftarrow} \operatorname{Perm}(n)$ . Let  $\mathcal A$  be an arbitrary adversary attacking BCTR[ $\Pi$ ] who asks a total of q queries, then

$$\mathbf{Adv}_{\mathrm{BCTR}[\Pi]}^{\mathrm{dae-priv}}(\mathcal{A}) \leq \frac{9m^2q^2}{2^n},$$
 (4)

$$\mathbf{Adv}_{\mathrm{BCTR}[\Pi]}^{\mathrm{dae-auth}}(\mathcal{A}) \leq \frac{1}{2^n} + \frac{9m^2q^2}{2^n}. \tag{5}$$

Note, that for the authentication bound in equation (5), q includes the final forgery query of A.

The above Theorem states the information theoretic security bounds for BCTR, i.e., it guarantees security

```
Algorithm BCTR.\mathbf{E}_{h,K}^T(P_1,\ldots,P_m)
                                                                        Algorithm BCTR.\mathbf{D}_{h,K}^T(C_1,\ldots,C_m,\tau)
    \gamma \leftarrow h \cdot \mathsf{BRW}_h(P_1||P_2||\dots||P_m||T)
                                                                  1. for j = 1 to m,
     \tau \leftarrow E_K(\gamma)
                                                                              R_j \leftarrow E_K(\tau \oplus \mathsf{bin}_n(j));
                                                                  2.
                                                                              P_i \leftarrow C_j \oplus R_j
      for j = 1 to m
                                                                  3.
                                                                   4.
4.
            R_j \leftarrow E_K(\tau \oplus \mathsf{bin}_n(j))
                                                                         \gamma \leftarrow h \cdot \mathsf{BRW}_h(P_1||P_2||\dots||P_m||T);
5.
           C_i \leftarrow R_i \oplus P_i
                                                                  5.
6.
      endfor
                                                                       \tau' \leftarrow E_K(\gamma)
      return (C_1||C_2||\ldots||C_m||\tau)
                                                                   7. if \tau' = \tau return (P_1, \ldots, P_m) else return \perp;
```

Fig. 1. Encryption and decryption using BCTR.

#### TABLE 2

Comparison of BCTR with tweakable enciphering schemes for fixed length messages which uses n-bit tweak. [BC]: Number of block-cipher calls; [M]: Number of multiplications, [BCK]: Number of blockcipher keys, [OK]: Other keys, including hash keys.

Mode	[BC]	[M]	[BCK]	[OK]
CMC [18]	2m + 1	_	1	_
EME [19]	2m + 2	_	1	
XCB [26]	m+1	2(m+3)	3	2
HCTR [37]	m	(2m+1)	1	1
HCHfp [12]	m+2	2(m-1)	1	1
TET [17]	m+1	2m	2	3
Constructions				
in [32] using	m+1	2(m-1)	1	1
normal polynomials				
Constructions				
in [32] using	m+1	$2+2\lfloor (m-1)/2\rfloor$	1	
BRW polynomials				
BCTR	m+1	$1 + \lfloor (m+1)/2 \rfloor$	1	1

#### TABLE 3

Comparison between BCTR and DAE schemes for encrypting m blocks of messages. In the DAE schemes the operation counts are based on only one block of tweak. [BC]: Number of block-cipher calls; [M]: Number of multiplications, [BCK]: Number of blockcipher keys, [OK]: Other keys, including hash keys.

Mode	[BC]	[M]	[BCK]	[OK]
SIV [30]	2m+3	_	2	_
HBS [21]	m+2	m+3	1	_
BTM [20]	m+3	m	1	_
BCTR	m+1	$1 + \lfloor (m+1)/2 \rfloor$	1	1

of BCTR when the blockcipher is considered to be a uniform random permutation. The corresponding complexity theoretic bounds can be easily derived from the above theorem. We prove Theorem 1 using the standard game playing technique as used in [12], [18], [19], [21]. The complete proof is provided in Appendix B.

#### 7 HARDWARE IMPLEMENTATION OF BCTR

In this section we present an optimized hardware architecture of BCTR and provide experimental performance data of the architecture. We also provide performance comparison of BCTR with other feasible architectures for disk encryption.

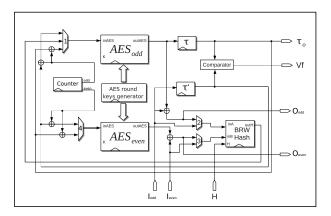


Fig. 2. Architecture of BCTR-2

#### 7.1 Basic Design Decisions

We develop our architecture keeping in mind high end FPGAs, in particular our target device is Virtex 5 xc5vlx330-2ff1760. The primary goal of the design is to achieve high speed, but we also try to keep the area metric reasonable. We optimize the architecture for message lengths of 4096 bytes. The block cipher is fixed to be the AES with 128-bit key and so the two keys that BCTR receives as input are both 128 bits long.

The two main building blocks of BCTR are the BRW hash and AES, we present details of these modules next. The BRW hash: In [10] a detailed study of some interesting structural properties of BRW polynomials are presented. It also reports an optimized hardware architecture for computation of BRW polynomials. We use the same ideas in [10] to develop the hash module of BCTR. The architecture reported in [10] is for computing BRW polynomials on 31 blocks (each block of 128 bits) of input. In our case, the BRW polynomial is to be computed on 257 blocks, and the final result of the hash is to be multiplied by the hash key h. The hash

computation requires computing powers of the hash key h, these are computed on the fly.

The multiplier used to implement the hash is a four-staged pipelined Karatsuba multiplier. The registers were placed after a meticulous re-timing process to create almost balanced pipeline stages. The number of stages were selected to match the frequency of the AES, which is the other significant hardware component of the architecture. It is to be noted that in [10], a three staged pipelined multiplier was used. The BRW hash in [10] was used for the design of the disk encryption modes HMCH and HEH [32]. Both these schemes requires an inverse call to the block cipher for decryption, hence the architectures of these modes include a decryption core of the AES. The specific implementation of the decryption core used there had a much higher critical path compared to the encryption core, and the critical path of the circuit was given by the AES decryption core. Hence in [10], a 3-stage pipelined multiplier was used to match the frequency of the decryption core. In case of BCTR the AES decryption core is not required, hence the main aim was to match the critical path of the hash module with the AES encryption core. This allowed us to use a four staged multiplier.

The AES: The AES is used in BCTR in the counter mode. This allows a pipelined AES implementation. The structure of AES (with 128-bit key) allows a natural 10-stage pipelined implementation, where each round occupies a stage. Our AES design closely follows the techniques used in [5]. In [5], the S-boxes were implemented as 256×8 multiplexers. This was possible due to special six input lookup tables (LUT) available in Virtex 5 devices. One S-box fits into 32 six-input LUTs available in Virtex 5 FPGAs. The design presented in [5] is sequential, we adapt the ideas in [5] to a 10 staged pipelined AES encryption core. Some of our designs involves multiple AES cores, for these designs all AES cores share the same key generation module.

#### 7.2 Proposed Architecture of BCTR

Two architectures were developed, one using two AES cores which we call as BCTR-2 and another using a single AES core which we call as BCTR-1. We will only describe in detail the architecture of BCTR-2, but we will present the results of both architectures in Section 7.3.

A simplified architecture of BCTR-2 using two AES cores is shown in Figure 2. The main components of the architecture are as follows:

- Two pipelined AES cores labeled AES<sub>even</sub> and AES<sub>odd</sub>, both cores have one input port labeled inAES and one output port labeled outAES. The round keys for both the cores are received from a single round key generator, which is also shown in the figure.
- 2) The block for computing the BRW polynomial labeled **BRW Hash**. This component receives the hash key through the input port *H*, through *inA*

- and *inB* it receives the data to be hashed. For the specific architecture that is used to compute the BRW polynomial, two data blocks are required simultaneously to perform the multiplications, hence it receives data through two input ports. The output port outH outputs the BRW hash. For details of the architecture of this block see [10].
- 3) A counter labeled **Counter** which has two output ports labelled *odd* and *even* trough which it outputs odd and even values. We will further denote the outputs of these two ports as **Counter**<sub>odd</sub> and **Counter**<sub>even</sub> respectively.
- 4) The multiplexer labeled **1** selects the input of  $\mathbf{AES_{odd}}$  between output of  $\mathbf{BRW}$  Hash,  $\tau \oplus \mathbf{Counter}_{odd}$  and  $\tau' \oplus \mathbf{Counter}_{odd}$ . Here  $\tau$  is the verification tag generated by encryption and  $\tau'$  is the tag to verify the output of decryption which is fed to the architecture as a part of the ciphertext.
- 5) Multiplexers labeled **2** and **3** are used to select the correct inputs for **BRW Hash** for encryption and decryption. For encryption, the multiplexers feed the **BRW Hash** directly from the data input ports  $I_{odd}$  and  $I_{even}$ . For decryption it feeds the xor of the input ports and the outputs of the AES cores, i.e., for decryption it feeds the **BRW Hash** with the same values as in the output ports  $O_{odd}$  and  $O_{even}$ .
- 6) Multiplexer 4 serves the same purpose as of multiplexer 1 but it selects inputs for AES<sub>even</sub>.
- 7) The comparator labeled **Comparator** is used for the tag verification during decryption. It receives as inputs  $\tau$  and  $\tau'$ , and checks if they are equal.

The data flow is controlled by a control unit constructed using a finite state machine, which is not shown in the figure. We explain the basic data flow in the architecture separately for encryption and decryption.

For encryption, first the BRW hash is computed using plaintext blocks fed in ports  $I_{odd}$  and  $I_{even}$  to get  $\gamma$ . Further,  $\gamma$  is processed by  $\mathbf{AES_{odd}}$  to produce  $\tau$ . The value in register  $\tau$  is presented in port  $\tau_o$  as authentication tag and also is used as an initialization vector in the counter mode.  $\mathbf{AES_{odd}}$  and  $\mathbf{AES_{even}}$  both compute  $R_j$  using  $\tau \oplus \mathbf{Counter}_{odd}$  and  $\tau \oplus \mathbf{Counter}_{even}$  as inputs respectively. The plaintext is fed again in ports  $I_{odd}$  and  $I_{even}$  and they are xored with  $R_j$ 's getting the respective ciphertexts in ports  $O_{odd}$  and  $O_{even}$ .

For decryption, first the architecture receives the tag to verify in  $I_{odd}$  and it is stored in register  $\tau'$  to be used as IV in the counter mode.  $\mathbf{AES_{odd}}$  and  $\mathbf{AES_{even}}$  compute  $R_j$  using  $\tau' \oplus \mathbf{Counter}_{odd}$  and  $\tau' \oplus \mathbf{Counter}_{even}$  as inputs respectively. Now the ciphertext in ports  $I_{odd}$  and  $I_{even}$  are xored with the  $R_j$  to get the plaintexts in ports  $O_{odd}$  and  $O_{even}$  which are also used as inputs for  $\mathbf{BRW}$  Hash. It is important to note that during decryption, the counter mode and  $\mathbf{BRW}$  hash can be run in parallel, this makes decryption faster than encryption. When the computation of the  $\mathbf{BRW}$ -hash is finished,  $\tau$  is computed and is compared with  $\tau'$  to verify whether the cipher text was valid.

**Timing Analysis of BCTR-2:** Now we analyze the behavior of the circuit of BCTR-2 in time. In Figure 3(a) a time diagram for the encryption process is shown, which clearly shows the possible parallelization. For computing the value  $\gamma$  a BRW polynomial on 257 blocks is computed which takes 135 cycles, further this result has to be multiplied by h which takes an additional 4 cycles (as we use a four staged pipelined multiplier), hence the total number of clocks required for producing  $\gamma$  is 140 (this includes an additional cycle for synchronization). We use a pipelined AES whose latency is 11 cycles. When  $\gamma$  is ready it is fed to AES, after 11 clock cycles  $\tau$  is produced which is stored in the register  $\tau$  which is connected to the output  $\tau_o$ . After  $\tau$  has been generated then the generation of the stream  $R_i$  is started by the two AES cores simultaneously. The first two blocks of the stream  $R_1$  is ready after 11 cycles. After this, in each cycle two cipher blocks are produced. The first valid block of ciphertext appear in the output after a latency of 164 clock cycles. All the ciphertext blocks are produced after 128 clock cycles and hence the complete encryption of a 4096 bytes is achieved after 292 clock cycles.

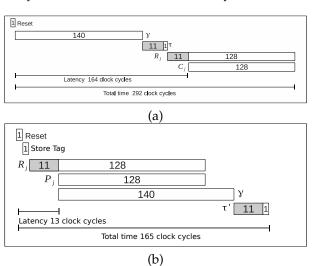


Fig. 3. Timing diagram for BCTR-2: (a) encryption (b) decryption.

In the encryption process the computation of  $\gamma$  cannot be parallelized with the encryption with AES, but this is not the case for decryption. This makes the decryption and verification process very different from the encryption process. The time diagram for decryption process is shown in Figure 3(b). As shown in the diagram, the circuit starts with the computation of the plaintext just after the tag is stored in the register. As soon as two plaintext blocks are available the computation of  $\tau$  can be started. The first valid block of plaintext is produced after 13 clock cycles. The total process, i.e, decryption and verification is done using only 165 clock cycles which is much less than the encryption process.

**Architectures for EME2 and XCB:** We compare the performance of our architecture with the architectures of EME2 and XCB, as they are the current standards for

TABLE 4
Summary of the main hardware resources in the architectures of BCTR-1, BCTR-2, EME2 and XCB

Scheme	Pipelined AES	Pipelined AES	Sequential AES	Pipelined
	encryption core	decryption core	decryption core	multiplier
BCTR-1	1	0	0	1
EME2-1	1	1	0	0
XCB-1	1	0	1	1
BCTR-2	2	0	0	1
EME2-2	2	2	0	0
XCB-2	2	0	1	2

disk encryption. For a fair comparison, we developed two architectures for both EME2 and XCB, we call them EME2-1, EME2-2, XCB-1 and XCB-2. The design goal of these architectures were such that EME2-1 and XCB-1 matches the speed of BCTR-1 and EME2-2 and XCB-2 matches the speed of BCTR-2. To achieve this, the architectures require different hardware resources. A summary of the number of main blocks utilized in each architecture is presented in Table 4. We describe in Appendix C some important aspects of the architectures EME2-2 and XCB-2.

#### 7.3 Results

We implemented BCTR-1, BCTR-2, EME2-1, EME2-2, XCB-1 and XCB-2 in Virtex 5 xc5vlx330-2ff1760. The results reported in Table 5 were obtained after place and route simulation using Xilinx ISE 13.4. In Table 5 we compare performance of BCTR with the implementations of EME2 and XCB. The performance is measured in terms of slices, frequency, throughput and throughput per area (TPA). For BCTR-1 and BCTR-2 there are two values specified for throughput, cycles and TPA, these values are for encryption/decryption. For EME2 and XCB the times required for encryption and decryption are the same.

In the first part of the Table 5 we present the results for the basic primitives, i.e., the AES cores and the multiplier, followed by the results of the single-core and double-core architectures of the modes. It is important to note that the results regarding the AES cores in the table include the key generation. When these cores were used to implement the modes, then regardless of the number and type of AES cores all of them share the same key generation module.

We summarize the performance metrics of the architectures using two AES cores, i.e., BCTR-2, EME2-2 and XCB-2 next.

 EME2-2 occupies the largest area, as it requires both an AES encryption core and an AES decryption core. In addition to the slices shown in the Table, EME2 requires four block RAMs to store the intermediate values. No other architecture requires Performance of BCTR, EME2 and XCB on Virtex-5 device. AES-PEC: AES pipelined encryption core, AES-PDC: AES pipelined decryption core, AES-SDC: AES sequential decryption core. For BCTR-1 and BCTR-2 the encryption and decryption times are different thus in the columns Throughput, Clock cycles and TPA the two numbers represents encryption/decryption. For EME2 and XCB the encryption and decryption times are the same.

Mode	Implementation	Slices	Frequency	Throughput	Clock	TPA
	Details		(MHz)	(Gbits/Sec)	cycles	(Mbits/Sec)/Slice
AES-PEC		2859	300.56	38.47	1	
AES-PDC		3110	239.34	30.72	1	
AES-SDC		1800	292.48	3.40	11	
128-bit Karatsuba		1650	298.43	38.20	1	
Multiplier						
BCTR-1	1 AES-PEC	5147	292.67	17.13/31.44	560/305	3.33/6.11
EME2-1	1 AES-PEC, 1 AES-PDC	6500	233.58	13.64	561	2.09
XCB-1	1 AES-PEC,1 AES-SDC	6070	272.75	15.70	569	2.58
BCTR-2	2 AES-PEC	7048	291.52	32.71/57.89	292/165	4.64/8.21
EME2-2	2 AES-PEC,2 AES-PDC	10970	230.56	24.77	305	2.25
XCB-2	2 AES-PEC, 1 AES-SDC	9752	270.52	28.05	316	2.87

block RAMs. XCB-2 is smaller than EME2-2, but is still occupies much more area compared to BCTR-2. Note XCB-2 requires an additional multiplier and an AES decryption core compared to BCTR-2.

- 2) The amount of parallelism that can be exploited is the best in BCTR-2, this is shown by the least number of clock cycles required for encryption of a sector using BCTR-2. XCB-2 requires more cycles than EME2-2. For decryption, BCTR-2 requires far less number of cycles compared to XCB-2 and EME2-2.
- 3) BCTR-2 also enjoys the highest frequency compared to EME2-2 and XCB-2. The frequency attained by BCTR-2 is almost the same as that of the pipelined AES encryption core. EME2-2 runs at the lowest frequency, as its critical path is given by the pipelined AES decryption core.
- 4) In terms of throughput, BCTR-2 is far better than XCB-2 and EME2-2. For decryption, BCTR-2 attains an impressive performance of about 58 Gbits/sec. The TPA metric is also best for BCTR-2, which proves that the BCTR-2 architecture attains a very good tradeoff in terms of speed and the amount of hardware resources used.

As expected, the single core architectures occupy much less area than their double core counterparts. The comparative performance of the single core architectures is almost the same as that of the double-core architectures, in particular BCTR-1 is superior to XCB-1 and EME2-1 considering all the important metrics. The TPA metric for the single core architectures is slightly lesser than the double core ones.

Thus the results clearly suggests that in terms of performance BCTR is much superior to IEEE disk encryption standards EME2 and XCB. In Appendix D we provide some possible architectures for the existing DAE

schemes and compare them with BCTR. There also we conclude that architectures of the existing DAE schemes would not attain the performance of BCTR given the same hardware resources.

#### 8 CONCLUSION

In this paper, we reconsidered the requirement of length preservation for disk encryption schemes. In existing disks, physical sectors are already larger than the actual amount of user data stored in a sector. We argued that it is feasible for disk manufacturers to change the physical layout to incur an additional overhead (which is at most 0.4% for 4096-byte sectors) for storing a tag. This opens up the possibility of using schemes for disk encryption where the ciphertexts are longer than the plaintexts. The benefit is that encryption and decryption can be faster.

Consideration of such schemes leads us to discard the possibility of using nonce-based AE schemes since the nonce management will become an extremely problematic engineering issue. We further propose that DAE schemes are well suited for disk encryption applications. They provide security at least at the level of a TES and in fact, can also explicitly reject mal-formed ciphertexts which a TES cannot.

Continuing along this direction, we presented a new DAE scheme. This is based on hashing using BRW polynomials and a counter-type mode of operation of a block cipher. This DAE scheme is more efficient that previous schemes appearing in the literature and is faster than known TES schemes. A concrete implementation of the new DAE scheme in reconfigurable hardware is reported. Comparison with implementations of TES schemes for disk encryption shows the clear superiority of the new scheme.

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### **APPENDIX A**

### **DISK ENCRYPTION STANDARDS**

There are two IEEE standards which specifies cryptographic algorithms for disk encryption.

**IEEE 1619 2007:** This standard specifies an algorithm called XTS. XTS is derived from a previous construction of Rogaway [28] which was called XEX. XEX is a tweakable block cipher (a notion introduced in [24]) and in [28] it was shown how such a tweakable blockcipher can be used to construct authenticated encryption schemes and message authentication codes. XTS is different from XEX by the fact that it uses two keys and later it was pointed out in [23] that use of two keys were unnecessary. XTS can be seen as a electronic code book mode of tweakable block-ciphers where each block uses a different tweak, hence the name "narrow block mode".

As a mode of operation, XTS is efficient, fully parallelizable, and possibly does not have any patent claims. On the other hand, it is questionable whether XTS provides adequate security for the purpose of disk encryption. For one thing, there is no scope of authentication using XTS. As a result, trivial mix-and-match attacks are applicable to XTS. These weaknesses are acknowledged in the standard document itself. The document proves security for XTS (the validity of the proof has also been contested in [23], where a better proof has been provided), but the proof only shows that XTS is a secure tweakable block-cipher. This security guarantee is insufficient for assuring secure encryption of multi-block disk sectors. The concern is well known and has been voiced in other public comments such as [35].

**IEEE 1619.2-2010:** This standard specifies two *wide block* modes. A wide block mode of operation behaves like a (tweakable) block-cipher with a block length equal to the data length of a sector. This notion is achieved by tweakable enciphering schemes and the security guarantees provided by TES seems adequate for the disk encryption scheme. The ciphertext produced by a TES can be shown to be indistinguishable from random strings and are also non-malleable [18]. So, in terms of security, for the application of disk encryption, wide blocks modes are much more suitable compared to narrow block modes such as XTS.

The two modes specified in IEEE Std 1612.2-2010 [2] are EME2 (a variant of EME [19]), and XCB. Among the many available TESs the reasons for choosing EME2 and XCB were not made clear. The studies in [25] show XCB to be the least efficient mode<sup>2</sup>. Moreover, security weaknesses in the specification of XCB in the standard were pointed out in [7]. Finally, both XCB and EME are covered by patent claims.

## APPENDIX B PROOF OF THEOREM 1

First we state some useful properties of BRW polynomials without proof. For the proofs, the interested reader is referred to [4], [32].

Property 1: If  $m \ge 3$  and  $t \le m < 2t - 1$  then  $\mathsf{BRW}_h(X_1, \dots, X_m)$  is a monic polynomial of degree 2t - 1.

Property 2: Let  $X=(X_1,X_2,\ldots,X_m), X'=(X_1',X_2',\ldots,X_m')\in [GF(2^n)]^m$  such that  $X\neq X'$ . Let  $Y=\mathsf{BRW}_h(X_1,X_2,\ldots,X_m)$  and  $Y'=\mathsf{BRW}_h(X_1',X_2',\ldots,X_m')$ . Then for every fixed  $a\in GF(2^n)$ 

$$\Pr[Y \oplus Y' = a] = \frac{(2m-1)}{2^n}$$

The probability is taken over the random choice of h.

For proving Theorem 1 we also use the following lemma.

*Lemma 1:* Let  $X = (X_1, X_2, \dots, X_m), X' = (X'_1, X'_2, \dots, X'_m) \in [GF(2^n)]^m$  such that  $X \neq X'$ . Let  $Y = h\mathsf{BRW}_h(X_1, X_2, \dots, X_m)$  and  $Y' = h\mathsf{BRW}_h(X'_1, X'_2, \dots, X'_m)$ . Then for every fixed  $\delta \in GF(2^n)$ 

$$\Pr[Y \oplus Y' = \delta] \le \frac{2m}{2^n},$$

The probability is taken over the random choice of h.

The proof easily follows from Property 2 of the BRW polynomials [32].

**Proof of Theorem 1:** To prove the security of BCTR[ $\Pi$ ] we replace the the block cipher E in the construction of Figure 1 by a permutation  $\pi$  chosen uniformly at random from  $\Pi = \text{Perm}(n)$ . We call the encryption function of BCTR[ $\Pi$ ] as  $\mathbf{E}_{h,\pi}$ , where  $h \stackrel{\$}{\leftarrow} \{0,1\}^n$  is the key for the BRW polynomial. We prove the privacy bound first. We consider the game playing technique. We briefly discuss the games below:

- 1) Game G0: In G0 (shown in Figure 4) the block-cipher is replaced by the random permutation  $\pi$ . The permutation  $\pi$  is constructed on the fly keeping record of the domain and range sets as done in the subroutine Ch- $\pi$  in Figure 4. Thus, G0 provide the proper encryption oracle to  $\mathcal{A}$ . Thus we have:
- 2. Our experiments presented in Section 7.3 shows EME2 to be worse than XCB. The study in [25] does not include EME2, also the XCB architecture presented in this paper is better in several respects compared to the one in [25].

$$\Pr\left[\mathcal{A}^{\mathbf{E}_{h,\pi}(\cdot,\cdot)} \Rightarrow 1\right] = \Pr[\mathcal{A}^{G0} \Rightarrow 1]. \tag{6}$$

2) Game G1: Figure 4 with the boxed entries removed represents the game G1. In G1 it is not guaranteed that Ch- $\pi$  behaves like a permutation, but the games G0 and G1 are identical until the bad flag is set. Thus we have

$$\Pr[\mathcal{A}^{G0} \Rightarrow 1] - \Pr[\mathcal{A}^{G1} \Rightarrow 1] \le \Pr[\mathcal{A}^{G1} \text{ sets bad}]. \tag{7}$$

Note that in G1 the adversary gets random strings as output irrespective of his queries. Hence,

$$\Pr[\mathcal{A}^{G1} \Rightarrow 1] = \Pr[\mathcal{A}^{\$(.,.)} \Rightarrow 1]. \tag{8}$$

3) Game G2: In Game G2 (shown in Figure 5) we do not use the subroutine  $Ch-\pi$  any more but return random strings immediately after the  $\mathcal{A}$  asks a query. Later we keep track of the elements that would have got in the domain and range sets of the permutation  $\pi$  in multi-sets  $\mathcal{S}$  and  $\mathcal{R}$ . We set the bad flag when there is a collision in either  $\mathcal{S}$  or  $\mathcal{R}$ . For the adversary the games G1 and G2 are identical. So,

$$\Pr[\mathcal{A}^{G1} \Rightarrow 1] = \Pr[\mathcal{A}^{G2} \Rightarrow 1],\tag{9}$$

and

$$\Pr[\mathcal{A}^{G1} \text{ sets bad}] = \Pr[\mathcal{A}^{G2} \text{ sets bad}]. \tag{10}$$

```
Subroutine Ch-\pi(X)
           Y \xleftarrow{\$} \{0,1\}^n; \text{ if } Y \in Range_\pi \text{ then bad} \leftarrow \text{true; } \middle| Y \xleftarrow{\$} \overline{Range_\pi} \middle|; \text{ endif;}
01.
           if X \in Domain_{\pi} then bad \leftarrow true; Y \leftarrow \pi(X); endif
           \pi(X) \leftarrow Y; Domain_{\pi} \leftarrow Domain_{\pi} \cup \{X\}; Range_{\pi} \leftarrow Range_{\pi} \cup \{Y\}; return(Y);
      Initialization:
           for all X \in \{0,1\}^n \pi(X) = undefined endfor
11.
            Domain_{\pi} \leftarrow \emptyset; Range_{\pi} \leftarrow \emptyset;
12.
Respond to the s^{th} encryption query (T^s; P_1^s, P_2^s, \dots, P_m^s) as follows:
101. \gamma^s \leftarrow h \cdot BRW(P_1^s||P_2^s||\dots||P_m^s||T^s);
102. \tau^s \leftarrow \text{Ch-}\pi(\gamma^s);
103. for i = 1 to m,
104. R_i^s \leftarrow \text{Ch-}\pi(\tau^s \oplus \text{bin}_n(i));
105. C_i^s \leftarrow R_i^s \oplus P_i^s;
106. end for
107. Return (C_1^s||C_2^s||\dots||C_{m^s}^s||\tau^s)
```

Fig. 4. Games G0 and G1

Hence, using Eqs. (6), (7), (8), (9) and (10), we have

$$\Pr\left[\mathcal{A}^{\mathbf{E}_{h,\pi}(.,.)} \Rightarrow 1\right] - \Pr[\mathcal{A}^{\$(.,.)} \Rightarrow 1] \le \Pr[\mathcal{A}^{G2} \text{ sets bad}].$$

According to the definition of the privacy advantage of A, we have

$$\mathbf{Adv}_{\mathrm{BCTR}[\Pi]}^{\mathrm{dae-priv}}(\mathcal{A}) \leq \Pr[\mathcal{A}^{\mathrm{G2}} \text{ sets bad}] \tag{11}$$

Now we need to bound  $\Pr[\mathcal{A}^{G2} \text{ sets bad}]$ . Assuming that  $\mathcal{A}$  makes a total of q queries, the elements in the multi-sets  $\mathcal{S}$  and  $\mathcal{R}$  after the interaction of  $\mathcal{A}$  with G2 terminates would be

$$S = \{\gamma^s : 1 \le s \le q\} \cup \{\tau^s \oplus \mathsf{bin}_n(i) : 1 \le i \le m, 1 \le s \le q\}$$

$$\tag{12}$$

$$\mathcal{R} = \{ \tau^s : 1 \le s \le q \} \cup \{ C_i^s \oplus P_i^s : 1 \le i \le m, 1 \le s \le q \}, \tag{13}$$

Let COLLD be the event that there is a collision in  $\mathcal{S}$  and COLLR be the event that there is a collision in  $\mathcal{R}$ . Using the facts that  $\gamma^s = h\mathsf{BRW}_h(P_1^s||P_2^s||\dots||P_m^s||T^s)$  and  $\tau^s, C_i^s$  are uniform random elements of  $\{0,1\}^n$ , we have the following:

- 1) For  $1 \le s, s' \le q$  and  $s \ne s'$ ,  $\Pr[\gamma^s = \gamma^{s'}] \le 2(m+1)/2^n$  (see Lemma 1).
- 2) For  $1 \le s, s' \le q$ ,  $1 \le i, i' \le m$ , and  $s \ne s'$ ,  $\Pr[\tau^s \oplus \mathsf{bin}_n(i) = \tau^{s'} \oplus \mathsf{bin}_n(i')] \le 1/2^n$ , as  $\tau^s, \tau^{s'}$  are uniform random elements in  $\{0,1\}^n$ .
- 3) For  $1 \le s \le q$ ,  $1 \le i, i' \le m$ , and  $i \ne i'$ ,  $\Pr[\tau^s \oplus \mathsf{bin}_n(i) = \tau^s \oplus \mathsf{bin}_n(i')] = 0$ .
- 4) For  $1 \le s \le q$ ,  $1 \le i \le m$ ,  $\Pr[\gamma^s = \tau^s \oplus \mathsf{bin}_n(i)] = 2(m+1)/2^n$ . To see this, note that  $\gamma^s \oplus \tau^s \oplus \mathsf{bin}_n(i)$  is a non-zero polynomial on h of degree at most 2(m+1) [32].
- 5) For  $1 \le s, s' \le q$  and  $s \ne s'$ ,  $\Pr[\tau^s = \tau^{s'}] = 1/2^n$ .
- 6) For  $1 \le s \le q$ ,  $1 \le i, i' \le m$ , and  $i \ne i'$ ,  $\Pr[C_i^s \oplus P_i^s = C_{i'}^s \oplus P_{i'}^s] = 1/2^n$ .
- 7) For  $1 \le s \le q$ ,  $1 \le i \le m$ ,  $\Pr[\tau^s = C_i^s \oplus P_i^s] = 1/2^n$ , as  $\tau^s$  and  $C_i^s$  are uniform random elements in  $\{0,1\}^n$ .

Using the above observations, and the union bound we conclude,

$$\Pr[\mathsf{COLLD}] \leq \binom{q}{2} \frac{(2m+2)}{2^n} + \binom{mq}{2} \frac{1}{2^n} + \frac{2mq^2(m+1)}{2^n} \\
\leq \frac{7m^2q^2}{2^n}, \tag{14}$$

and

$$\Pr[\mathsf{COLLR}] = \binom{(mq+q)}{2} \frac{1}{2^n} \\ \leq \frac{2m^2q^2}{2^n}. \tag{15}$$

Thus we have

$$\Pr[\mathcal{A}^{G2} \text{ sets bad}] = \Pr[\mathsf{COLLD}] + \Pr[\mathsf{COLLR}]$$

$$\leq \frac{9m^2q^2}{2^n} \tag{16}$$

This completes the proof of the privacy bound.

Fig. 5. Game G2: S and R are multisets.

**Proving the authentication bound:** To prove the authenticity bound, we assume that  $\mathcal{A}$  makes a total of q queries including the forgery. The first q-1 queries are  $(T^1; P^1), (T^2; P^2), \ldots, (T^{q-1}; P^{q-1})$ . Finally  $\mathcal{A}$  attempts a forgery  $(T^q; C^q || \tau^q)$ .

We describe how the the queries of A are responded. As in the previous proof we assume the BCTR construction to be instantiated with  $\pi$  selected randomly from  $\operatorname{Perm}(n)$ . We start with two empty multisets Dom and Ran. In response to the  $s^{th}$  query  $(T^s, P^s)(1 \le s \le q-1)$  the following steps are executed:

- 1) A uniform random string  $C^s||\tau^s|$  of (m+1)n bits is returned to A.
- 2)  $\gamma^s = h BRW_h(P^s 1, P_2^s, \dots, P_m^s, T_m^s)$  is inserted in Dom and  $\tau^s$  is inserted in Ran.
- 3) For  $1 \le i \le m$ ,  $\tau^s \oplus \text{bin}_n(i)$  is inserted in Dom and  $(P_i^s \oplus C_i^s)$  is inserted into Ran.

Note that this simulation is perfect if there is no collision in the multisets Dom and Rng.

For the final forgery query  $C^q || \tau^q$ , let  $C^q = C^q_1 || C^q_2 || \cdots || C^q_m$ , and  $P^q_i = C^q_i \oplus \pi(\tau^q \oplus \mathsf{bin}_n(i))$ , for  $1 \le i \le m$ . Let  $\gamma^q = h\mathsf{BRW}_h(P^q_1, P^q_2, \dots, P^q_m)$ . The adversary is successful in its forgery if  $\pi(\gamma^q) = \tau^q$ . If  $\gamma^q$  is distinct from all the elements in Dom and  $\tau^q$  is also distinct from all elements in Rng, then  $\Pr[\pi(\gamma^q) = \tau^q] = 1/2^n$ . If  $\gamma^q$  is distinct from all elements in Dom and  $\tau^q$  is in Rng then  $\Pr[\pi(\gamma^q) = \tau^q] = 0$ .

Let COLL be the event that there is a collision in the set  $\mathsf{Dom} \cup \{\gamma^q\}$  or  $\mathsf{Rng}$ , then we have

$$\begin{split} \mathbf{Adv}_{\mathrm{BCTR}[\Pi]}^{\text{dae-auth}}(\mathcal{A}) &= & \Pr[\tau^q = \pi(\gamma^q)] \\ &= & \Pr[\tau^q = \pi(\gamma^q) | \mathsf{COLL}] \Pr[\mathsf{COLL}] + \Pr[\tau^q = \pi(\gamma^q) | \overline{\mathsf{COLL}}] \Pr[\overline{\mathsf{COLL}}] \\ &\leq & \Pr[\tau^q = \pi(\gamma^q) | \overline{\mathsf{COLL}}] + \Pr[\mathsf{COLL}] \\ &\leq & \frac{1}{2^n} + \Pr[\mathsf{COLL}]. \end{split}$$

It is easy to verify that Pr[COLLD] + Pr[COLLR], where COLLD and COLLR are defined in the proof for privacy. Thus, using Eqs. (14), (15), we have

$$\mathbf{Adv}_{\mathtt{BCTR}[\Pi]}^{\mathsf{dae-auth}}(\mathcal{A}) \leq \frac{1}{2^n} + \frac{9m^2q^2}{2^n},$$

as desired.□

#### **APPENDIX C**

#### SOME DETAILS ABOUT THE ARCHITECTURES OF EME2 AND XCB

The mode EME2 has two ECB layers with an intermediate masking. The ECB layers can be implemented with pipelined AES cores. For decryption, ECB in decryption mode is required, hence for efficient decryption functionality pipelined AES decryption cores are required to be used. For fair comparison with BCTR-2 we implemented EME2-2 with two encryption and two decryption cores. The second layer of ECB in EME2 can only be computed once the first layer has been completed, thus the intermediate results of the first layer of ECB encryption are required to be stored. We use block RAMs for this purpose.

XCB is a hash-counter-hash type mode which involves a counter mode of operation sandwiched between two polynomial hash layers. The main encryption/decryption in XCB takes place through the counter mode, hence AES decryption core is not required. But, other than the counter mode, one inverse call of the AES is required in XCB for both encryption and decryption. For this a sequential AES decryption core is utilized. Thus, XCB-2 uses two pipelined AES encryption cores which does the bulk encryption and in addition a sequential AES decryption core.

The polynomial hash layers in XCB are normal polynomials computed using the Horner's rule. For a fair comparison with BCTR-2 we used the same pipelined 128-bit Karatsuba multiplier which we used for the BRW hash of BCTR. For efficiently computing a polynomial with a pipelined multiplier we used the strategy described in [10] (see Section 4.4). The second hash function computation in XCB can be computed in parallel with the counter mode. As the counter mode in XCB-2 is implemented using two AES cores hence in each clock cycle we obtain two blocks of outputs. As the hash is computed using the Horner's rule hence only one block can be utilized for computing the hash in one cycle. This leads to significant loss of cycles. Hence to match the speed of BCTR-2 we decided to use two multipliers. This allows us to compute the counter mode and one of the hash in parallel.

#### **APPENDIX D**

### COMPARISON WITH OTHER EXISTING DAE SCHEMES.

The basic paradigm of constructing DAE schemes proposed in [30] is to combine a secure pseudorandom function with an IV based privacy only encryption scheme. We discuss the possible architectures for some existing DAE schemes and compare them with BCTR. We do not have real experimental data on the DAE schemes, thus the comparison that we provide below is based on feasible estimates and our analysis show that the architectures for existing DAE schemes would not attain the performance of BCTR-2.

The SIV mode was proposed in [30], it uses a CMAC on the plaintext to create a tag, and the tag is used as an initialization vector for a counter mode of operation. Thus an AES encryption is the main component required

for SIV. The use of CMAC (which is based on the CBC MAC) restricts the mode in terms of usable parallelism, and a pipelined AES core cannot be used suitably here. Thus, any feasible architecture for SIV would require much more clock cycles compared to the architectures in Table 5. The CBC-MAC can be replaced by other block-cipher based parallel MACs like the PMAC. A construction of such a kind can be found in [13]. SIV with PMAC (instead of a CMAC) can be implemented using two pipelined AES encryption cores, this architecture is expected to have the same throughput for encryption as BCTR-2, and have an smaller than BCTR-2. But, for getting the decryption throughput same as BCTR-2 two additional pipelined AES cores would be required, as the extra speedup in the decryption is obtained by running the MAC and the counter mode in parallel. These additional cores would make this architecture much more larger than BCTR-2.

Both BTM and HBS use a polynomial hash along with a counter mode. But the hash is the usual polynomial hash and so the number of multiplications required is roughly twice that of BCTR (see Table 3). To obtain equivalent speedups as in BCTR-2 an architecture implementing HBS or BTM would require two pipelined AES cores along with two pipelined multipliers. Thus such an architecture would have an area more than BCTR-2 but less than XCB-2. The encryption throughput of such an architecture is expected to be the same as that of XCB-2, but the decryption throughput would be more than the encryption.