



Spatio-Temporal High-Resolution Subsoil Compaction Risk Assessment for a 5-Years Crop Rotation at Regional Scale

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Soil compaction results whenever applied soil stress by machinery exceed the soil strength. Both, soil strength and stress, are spatially and temporally highly variable, depending on the weather situation, the current crop type, and the machinery used. Thus, soil compaction risk is very dynamic, changes from day to day and from field to field. The objective of this study was to analyze the spatio-temporal dynamics of soil compaction risk and to identify hot-spot areas of high soil compaction risk at regional scale. Therefore, we selected a study area (~2,000 km²) with intensive arable farming in Northern Germany, having a high share of cereals, maize and sugar beets. Sentinel-2 images were used to derive the crop types for a 5-years crop rotation (2016-2020). We calculated the soil compaction risk using an updated version of the SaSCiA-model (Spatially explicit Soil Compaction risk Assessment) for each single day of the period, with a spatial resolution of 20 m. The results showed the dynamic changes of soil compaction risk within a year and throughout the entire crop rotation. The relatively dry years 2016 and 2018–2020 reduced the soil compaction risk even at high wheel loads applied to soil during maize and sugar beet harvest. Contrary, high precipitation in 2017 increased the soil compaction risk considerably. Focusing on the complete 5-year period, 2.7% of the cropland area was identified as hot-spots of soil compaction risk, where the highest soil compaction risk class ("extremely high") occurred every year. Additionally, 39.8% of the cropland was affected by "extremely high" soil compaction at least in one of the 5 years. Although the soil compaction risk analysis does not provide information on the actual extent of the compacted area, the identification of risk areas within a period may contribute to understand the dynamics of soil compaction risk in crop rotation at regional scale and provide advice to mitigate further soil compaction in areas classified as high risk.

Keywords: soil degradation, sustainable management, modelling, field traffic, SaSCiA-model

INTRODUCTION

Soil compaction is one of the main soil degradation processes on agricultural land worldwide (FAO, 2015). This degradation process is expected to continue in the coming centuries due to intensive field traffic activities with heavy machinery (Keller et al., 2017; Keller et al., 2019; Techen et al., 2020). Continued soil compaction, however, contradicts the sustainable development goal 15 (SDG15),

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TABLE 1 Common spatial models and spatial approaches in soil compaction research (according to Kuhwald (2019).

Reference	Aim/focus/product	Used method
Horn et al. (2002)	- Maps for Germany: precompression stress, changes in air capacity and air conductivity by applied stress	- Application of Lebert and Horn (1991), DVWK 234 (1995)
Jones et al. (2003)	- Map of subsoil susceptibility for soil compaction for Europe	- Application of Jones et al. (2003)
van den Akker (2004)	- Wheel load bearing capacity map of the Netherlands	- Used SOCOMO van den Akker (2004)
Horn et al. (2005)	- Precompression stress, contact area stress (and their relationship) and	- Application of Lebert and Horn (1991), DVWK 234 (1995), Horn and
	change in air conductivity	Fleige (2003)
	- Soil maps for Europe, Germany and for a farm	
Horn and Fleige (2009)	- Maps of precompression, change in air capacity	- Application of Lebert and Horn (1991), DVWK 234 (1995), Horn and
	- Subsoil stress of 60 and 90 kPa (40 cm)	Fleige (2003)
Kroulík et al. (2009)	- Mapping spatial pattern of traffic intensity	- GPS tracking and tire measurements (tire width)
	- Wheel track area and wheel passages for entire cropping season	
Lebert (2010)	- Maps of susceptibility to soil compaction for varying field capacities for	- Application of Lebert and Horn (1991), DVWK 234 (1995), Horn and
	entire Germany	Fleige (2003), DIN V 19688 (2011)
	- Assumption of the same field capacities for entire Germany	
van den Akker and	- Calculating the soil vulnerability and susceptibility to soil compaction in	- Application of Jones et al. (2003) and van den Akker (2004)
Hoogland (2011)	the Netherlands	
	- Calculating the soil strength and the allowable wheel load for the	
	Netherlands	
Duttmann et al. (2013)	- Modelling and mapping of wheel passages, wheel load, mean ground	- Application of Diserens (2002), Diserens (2009)
	contact pressure for maize harvest	- Recorded GPS-data and time stamps
Duttmann et al. (2014)	- Modelling and mapping of wheel passages, wheel load, mean ground	- Application of Diserens (2002), Diserens (2009), Horn and Fleige
	contact pressure, soil strength, soil stress (2D and 3D) for maize harvest	(2003)
		 Recorded GPS-data and time stamps
D'Or and Destain (2014)	- Calculation of precompression stress maps and soil compaction risk	- Application of Horn and Fleige (2003), Keller (2005), Schjønning et al.
	maps for Belgium	(2008)
Schjønning et al. (2015a)	 Mapping wheel load carrying capacity for Europe 	- Application of Terranimo (Stettler et al., 2014) algorithm
	- For a tire with a diameter of 800 mm, soil depth of 25 cm and traffic at a	
	matric potential of - 300hPa	
Lamandé et al. (2018)	- Mapping wheel load carrying capacity for Europe (for rubber tracks	- Application of Frida (Schjønning et al., 2008; Schjønning et al., 2015a)
	and wheels)	and Schjønning and Lamandé (2018) for soil strength calculation
	- Tire: 1050/50R32, at a depth of 35 cm	
	- Matric potential of -50 hPa	
Kuhwald et al. (2018)	- Mapping daily soil compaction risk at regional scale with high spatial	- SaSCiA-model, incorporates Horn and Fleige (2003), DIN V 19688
	resolution (20 m*20 m)	(2011), Nendel et al. (2011), Rücknagel et al. (2012, 2013, 2015)
Ledermüller et al. (2018)	- Mapping soil compaction risk for a feral state (Lower Saxony) in	- Application of Lorenz et al. (2016)
	Germany	
Augustin et al. (2020)	- Modelling spatial pattern of traffic intensity for an entire crop rotation for	- Application of FiTraM (Augustin et al., 2019), which incorporates
	one field	Koolen et al. (1992)
	- Maps of wheel passages, maximum wheel load, maximum mean	
	ground contact pressure for maize harvest	
Duttmann et al. (2021)	- modelling of soil compaction risk beneath the wheel tracks of a	- Application of FiTraM and SaSCiA (Kuhwald et al., 2018; Augustin
	complete maize season	et al., 2019)

which aims to achieve land degradation neutrality by sustainable land use management. Reducing soil compaction is therefore necessary to achieve the SDG 15 and to enable a sustainable soil use.

Soil compaction is defined as an increase of bulk density while pore volume decreases (Horn et al., 1995). Compared to an uncompacted soil, compacted soils have a lower air capacity, reduced water infiltration, lower air permeability, lower biological activity, reduced root and plant growth (e.g., Horn et al., 1995; Weisskopf et al., 2010; Destain et al., 2016; Szatanik-Kloc et al., 2018). Therefore, compacted soils are more susceptible to surface water runoff and soil erosion (Alaoui et al., 2018; Keller et al., 2019). In addition, soil compaction results often in lower yields (Arvidsson and Håkansson, 2014; Daigh et al., 2020). As soil compaction is persistent (Keller et al., 2017; Seehusen et al., 2021), especially in the subsoil, the environmental effects are present in the long term. As exemplarily shown by Graves et al. (2015) for England and Wales, the total economic costs of soil degradation caused by soil compaction can be three times that of soil erosion. Thus, quantifying and localizing already compacted soils is as important as identifying areas where the risk of soil compaction is increased to prevent further soil degradation.

Calculating area percentages is challenging as soil compaction on arable land is a spatio-temporal highly dynamic process (Schjønning et al., 2015b), because crop type, soil, weather and used machinery interact (Kuhwald et al., 2018). Comparing soil strength against soil stress is the most common approach to evaluate whether soil compaction may occur during wheeling (Horn and Fleige, 2003; Horn et al., 2005). Soil strength results from soil texture, carbon content, soil structure and soil moisture (Horn et al., 1995; Horn and Fleige, 2003; Rücknagel et al., 2012; Gut et al., 2015). Soil stress depends on the wheel load, tire inflation pressure, contact area and amount of wheel passes (Horn, 2003; Horn et al., 2003; Arvidsson and Keller, 2007; Botta et al., 2009; Schjønning et al., 2012). Several studies exist that analyzed the various effects of wheeling on stress propagation and distribution inside the soil as on physical soil properties as well (e.g., Gebhardt et al., 2009; Lamandé and Schjønning, 2011; Hartmann et al., 2012; Keller et al., 2012; Berisso et al., 2013; Seehusen et al., 2019).

From field and laboratory experiments, numerous functions were derived to calculate e.g. the contact area, the soil strength at a certain soil moisture state or the stress distribution while wheeling (Keller et al., 2007; Schjønning et al., 2008; Diserens, 2009; Rücknagel et al., 2012). These functions, incorporated into more complex assessment models, allow to estimate soil compaction behavior at different spatial scales. **Table 1** lists common spatial approaches and models in soil compaction research.

The growing availability of high resolute data from global navigation satellite systems (GNSS) received and recorded by modern farm vehicles enables to precisely predict traffic intensity (e.g., Kroulík et al., 2009; Duttmann et al., 2013) and traffic related compaction effects at field scale (e.g., Duttmann et al., 2014; Augustin et al., 2020; Duttmann et al., 2021).

From field to larger scales, the pre-compression (or preconsolidation stress)-concept (e.g., Lebert and Horn, 1991) has been applied in various studies (e.g., Horn et al., 2002; Horn et al., 2005; Horn and Fleige, 2009; Lebert, 2010; Destain et al., 2016). The results are maps showing the susceptibility to soil compaction (Jones et al., 2003; Lebert, 2010), the soil compaction risk (D'Or and Destain, 2014) or, by using further equations, changes in air conductivity and air capacity (Horn et al., 2002; Horn et al., 2005; Horn and Fleige, 2009). Furthermore, the wheel load carrying capacity can be derived by calculating the soil strength and setting threshold values for soil stress. Examples are given by van den Akker (2004) for the Netherlands and by Schjønning et al. (2015b) and Lamandé et al. (2018) for Europe.

One limitation of all these large scale predictions is the assumption of static conditions, either for the soil or for the used machinery data or for both. Dynamic changes of soil stress and soil strength in space and time were rarely considered.

Newer approaches try to consider the dynamics of soil stress and soil strength in soil compaction risk modelling at regional scale (Kuhwald et al., 2018; Ledermüller et al., 2018). The approach of Ledermüller et al. (2018) uses available soil moisture information at a spatial resolution of 1*1 km² provided by the German weather service (DWD) and land use data from the Integrated Administration and Control System (IACS) to calculate soil compaction risk according to Lorenz et al. (2016). This method aims at a long-term assessment of topsoil compaction risk, which can support famers in decision making.

Kuhwald et al. (2018) developed a different approach to calculate soil compaction risk, called "SaSCiA" (Spatially explicit Soil Compaction risk Assessment). The raster-based model incorporates spatial information of the soil and current crop types and calculates the daily soil strength depending on actual soil moisture. For the calculation of soil stress, the current crop type, the actual soil moisture, crop-dependent used machinery and field traffic days are considered. The modelling results are daily maps of soil compaction risk at a spatial resolution of 20 m. As shown in a first study by Kuhwald et al. (2018), the SaSCiA-model was successfully used to simulate the daily changes of soil compaction risk, separated by different soil depths (20, 35 and 50 cm), within 1 year for two study areas. Among other aspects, the high variability of soil compaction risk within a year was evident, confirming the significant influence of the actual weather conditions in a respective region. However, Kuhwald et al. (2018) analyzed only 1 year for each study area could not accounted for.

Thus, the following research questions arise for this study: (i) whether and to what extend does soil compaction risk vary between individual years, and (ii) does a continuous calculation of soil compaction risk over a longer period enable the detection of areas within the region that are more often affected by high soil compaction risk than other areas? To answer both questions, we analyzed the soil compaction risk for a 5-year period for an intensively cropped region using an updated version of the SaSCiA-model. The objectives of this study are (i) to model and analyze the variation of soil compaction risk within the individual years and within the 5-years period (2016-2020), and (ii) to identify areas with recurring patterns of high soil compaction risk within this period. We hypothesize that (i) the variation in soil compaction risk between the single years will be strong depending on actual weather conditions, but that (ii) classes of higher soil compaction risk can be observed for the same areas in each year, which enables to delineate "hot-spot" areas of increased soil compaction risk.

This study focusses on a perennial analysis of soil compaction risk dynamics at regional scale to understand the spatio-temporal characteristics of soil compaction. Furthermore, identifying areas of different soil compaction risk during a crop rotation enables selective and specific intervention through soil management to mitigate potential soil compaction. In this way, this study may support to a more sustainable soil use as envisaged by the SDG 15.

MATERIALS AND METHODS

Study Area

A 2,000 km² region in Lower Saxony (Germany) near the city of Hildesheim was selected as study area (**Figure 1**). Intensive agricultural use characterizes this region. Most important crop types are winter wheat (*Triticum aestivum*), sugar beets (*Beta vulgaris*), silage maize (*Zea mays*) and rapeseed (*Brassica napus*). The study area is part of the Lower Saxony Loess Hill Country. The geology of the region is complex, resulting in diversely distributed soil parent material. Deeply weathered loess predominates along the hill slopes, while loamy deposits occur in the valleys. Shallow layers of sandy and clayey weathered materials are mostly found at the hilltops. Typical soil types at the hill slopes and valleys are Luvisols (often stagnic) and Cambisols, while Leptosols and Regosols (FAO, 2014) occur at the hilltops. Forests cover the hilly areas and the areas





with shallow soil development. The climate is humid with a mean annual precipitation of 649 mm and mean annual temperature of 10.0° C (weather station Liebenburg-Othfresen; DWD, 2021). The weather conditions for the investigated period are exemplarily shown for the weather station "Liebenburg-Othfresen," which is centrally located in the study area (**Figure 2**).

Modelling, Model Structure and Input Data The SaSCiA-model (Spatially explicit Soil Compaction risk Assessment) was used for the 5-years analysis. The freely available study by Kuhwald et al. (2018) describes the model and its components in detail. Here, we briefly explain the model and highlight the changes in the model and the used input data.



The SaSCiA-model incorporates crop type data, weather information, soil data, machinery information, the crop model "MONICA" and various pedotransfer functions (e.g., Horn and Fleige, 2003; Nendel et al., 2011; Rücknagel et al., 2012; Rücknagel et al., 2013; Rücknagel et al., 2015). Based on these components, it calculates the daily soil compaction risk for each raster cell within a selected area (**Figure 3**). In this study, we modelled and analyzed the subsoil compaction risk at a soil depth of 40 cm. Since this depth will not be reached by regular primary tillage and related loosening effects, soil compaction persists (Keller et al., 2017; Keller et al., 2021) and may not recover in short-term.

Crop Types and Crop Rotations

The crop types and crop rotations for the period (2016–2020) were derived by land use mapping and land use classification. During each summer (July–September) of the investigation period, we mapped crop types in the study area for ground control. Field mapping data encompassed the following target classes: cereals (e.g., winter wheat, rye, barley), maize, winter

rapeseed, sugar beets and grassland. Google Earth imagery supported the identification of less changing land cover classes such as water bodies, evergreen/deciduous forest and sealed areas. The mapped data formed the basis for a remote sensing approach to obtain spatially continuous maps of cultivated crop types at 20 m spatial resolution.

To this end, we selected 20 cloud-free or almost cloud-free Sentinel-2 scenes, which were acquired during the vegetation periods 2016-2020 (Supplementary Table S1). Since its launch in 2015, Sentinel-2 data are widely used and established for crop type mapping (e.g., Immitzer et al., 2016). To ensure data comparability, we downloaded atmospherically corrected (Sen2Cor (Müller-Wilm, 2016); Level-2A products from the Copernicus Open Access Hub (https://scihub.copernicus.eu/). Crop types were classified by using a random forest classification algorithm implemented as QGIS plugin (dzetsaka classification; Karasiak, 2016). The random forest algorithm is a supervised ensemble classifier and well known for crop type classification. To learn the spectral signatures of the target classes (training), the classifier requires georeferenced data on known crop types (Belgiu and Drăguț, 2016). For this purpose, we used the crop types mapped annually in the study area. The Sentinel-2 bands 2-7, 8A, 11 and 12 (20 m spatial resolution) of all selected scenes from a year served as spectral input, whereas we excluded cloudy pixels based on the standard cloud mask of the Level-2A products.

Speckle in the crop type maps was reduced by using a 3×3 pixel median filter. Here, speckle means natural classification noise. At field borders, for instance, different land cover are represented within one 20 m \times 20 m large pixel (e.g., the crop type, field path and hedgerow or crop type of adjacent field). The result are single, erroneously classified pixels and a grainy appearing land cover map. Filtering is a common postclassification tool to refine and smoothen the map. Furthermore, we applied the IRSeL tool (Rathjens et al., 2014). IRSeL is a post-classification tool for refining remote sensing based land cover maps (e.g., interpolation of no data gaps, reduction of misclassifications between crop types and less dynamic classes; Kandziora et al., 2014; Rathjens et al., 2014). Accuracy assessment followed the suggestions by Foody (2002) using independent field mapping data, which were not used for classifier training (Supplementary Table S2).

Subsequently, the received crop types were used to calculate soil moisture, to select the machinery employed for crop-specific field traffic activities and to define time periods for these activities.

Weather Data

The weather data is used to calculate the soil moisture within the crop model MONICA. Required weather information are temperature (minimum, maximum, average), precipitation, relative humidity, Sun duration and wind speed. In the original SaSCiA-version, only one weather station was used for deriving weather information for an entire region. As weather is highly variable in space, one station may not adequately represent the weather conditions within a region of 2,000 km². For this reason, we newly incorporated regionalized weather data in the model. In a first step, all available weather stations within the

federal state "Lower Saxony" were identified and the available data automatically downloaded using the R-package "papros" (Hamer, 2019). Afterwards the data were processed in R (version 4.1.0; R Core Team, 2020) to generate regionalized weather information for each day for each of the required weather variable. From these grids, the weather input-files for each crop-soil grid cell were automatically generated. As a result, the spatial variation of weather can be considered in the calculation of soil compaction risk.

Soil Data

Soil data was extracted from the digital soil map BK 50 (scale 1: 50,000) provided by the federal state agency of Lower Saxony (LBEG, 2020). The BK 50 contains information of e.g., soil type, soil horizons, soil depths, soil texture class, carbon content, gravel content and dry bulk density class, which were used for modelling. Further information about air capacity, field capacity, available field capacity and wilting point were derived according to Wessolek et al. (2009). In total, 1,800 different soil profiles were located within the study area and used for further soil compaction analysis.

Machinery Data

The study area represents a region with highly mechanized agriculture, i.e., nearly all field processes are conducted with heavy machinery. The SaSCiA-model considers the used machinery based on the present crop type. For each crop type, a machinery with fixed wheel load and tire inflation pressure is defined and the periods for potential field traffic (**Supplementary Table S3**; cf. Kuhwald et al., 2018). For instance, it is assumed that the winter wheat is harvested between the first and 15th of August each year using a 220 kw combine harvester (max wheel load: 8,200 Mg, tire inflation pressure: 2.0 bar). We used the same machinery setups and field traffic days as selected by Kuhwald et al. (2018).

Soil Moisture Modelling

Soil moisture is calculated from the present crop type, weather information and soil data for each day for each grid cell using the MONICA-model (Nendel et al., 2011). Among others, the model provides the soil moisture in 10 cm intervals for the depth between 0 and 200 cm (cf. Kuhwald et al., 2018).

Calculation of Soil Strength, Soil Stress and Soil Compaction Risk

The soil strength is calculated by the static soil properties (e.g., soil texture, gravel content) in combination with the modelled soil moisture by the MONICA-model using the pedotransfer functions of Horn and Fleige (2003), DIN V 19688 (2011), Rücknagel et al. (2012), Rücknagel et al. (2013) and Rücknagel et al. (2015). The result is a dynamic change of soil strength on a daily basis, depending on present crop type, weather situation and soil properties.

The soil strength is compared against the soil stress caused by the used machinery. The latter depends on the present crop type and time of year. The soil stress is calculated by the pedotransfer function from Koolen et al. (1992) and Rücknagel et al. (2015).



Input data is the wheel load, the tire inflation pressure and the desired depth of risk analyses.

The comparison of soil strength and soil stress results in the soil compaction index (Rücknagel et al., 2015). The index is divided into five classes ranging from "no risk" (value <0) to "extremely high" (value >0.4) soil compaction risk. Though, the final result is a soil compaction risk class for each grid cell for each day within a year.

Spatio-Temporal Analysis and Hot-Spots Detection

The temporal analysis of soil compaction risk within a year was performed by stringing together the daily results for the investigated period.

For the analyses of recurring patterns, all grid cells of 1 year with the class "extremely high" soil compaction risk were summed up. The results were summed raster for each year showing the areas of the highest soil compaction risk class. By summarizing and counting these five grids, we can identify the hot-spots of extremely high soil compaction risk and areas, that were never affected by such a high soil compaction risk class.

RESULTS

Spatial Characterization of the Study Area

The total size of the study area is $2,000 \text{ km}^2$. The cover by arable land had a share of 50.2%, followed by forest (27.2%), grassland (16.0%), sealed area (5.4%) and water bodies (1.2%; **Supplementary Table S2**).

Organic soils cannot be processed by the SaSCiA-model since the incorporated functions (Horn and Fleige, 2003; Rücknagel et al., 2015) are invalid for soil with organic matter content >30%. Therefore, 1,562 of the originally 1,800 soil profiles could be used for soil compaction risk analysis, representing 116,309 ha under arable use.

At the desired depth of 40 cm, a wide range of soil texture classes occurred (**Figure 4**). Soil texture classes having high clay (Tt, Tl, Ts) and silt content (Uu, Ut2) were absent, as were those with low silt but high sand content (St2, St3, Ls4, Ts4, Ts3; according to the German classification scheme; Ad-Hoc-AG Boden, 2005).

Within the 116,309 ha area, cereals share ranged from 54 to 68% and was the predominating crop type in all years, while rapeseed always had the lowest share (4-12%; Table 2).

Spatial Distribution of Soil Compaction Risk

Figure 5 exemplarily shows the spatial distribution of soil compaction risk on 07 August 2017 for the depth of 40 cm. On this date, all soil compaction risk classes ("no risk" to "extremely high risk") occurred in the study area, each with varying percentages of area (**Table 3**). In total, one quarter of the cropland area was not affected by field traffic, while another quarter revealed no soil compaction risk. The remaining area was distributed among the classes "low" to "extremely high" soil compaction risk, with the "extremely high" class having the highest share at 19.3%.

No field traffic occurred for maize and rapeseed as no field traffic was assumed for these crop types on this date. The plant height of maize prevents any field traffic without damaging the plants; rapeseed has already been harvested and the sowing of a subsequent crop is too early in the year. For sugar beet, the class "no risk" dominated (19.1%), while 2.9% of the sugar beet area had a "low" soil compaction risk. Thus, the risk classes "medium" to "extremely high" referred to the crop type cereals on this date.

Temporal Variation of Soil Compaction Risk

Summarizing all daily soil compaction risk maps of a year and calculating the area shares of each soil compaction risk class, results in a temporal overview of soil compaction risk (**Figures 6A–E**). Focusing on all years, there were periods without soil compaction risk, e.g., December and January. Here, no field traffic was assumed, thus no soil compaction could occur. During the rest of the year, the percentage of arable land, which was potentially affected by soil compaction, varies from 10 to 100%. Autumn was the period with most field traffic activities. The risk class "no risk" predominates in all years. The highest risk class "extremely high" mainly occurred in spring. From February to mid of June, all soil compaction risk classes occurred in all years, which was not the case in summer and autumn.

Comparing the years with each other, 2017 showed a distinctly different distribution of soil compaction risk. In particular from mid of July to November, the soil compaction risk was much higher than in all other years. For instance, the classes "high" to "extremely high" accounted for 43.6% of the arable land in mid of August. At the same time the year before and the years after, this

Crop type	2016		2017		2018		2019		2020	
	ha	%								
Cereals	77,155	66.3	62,880	54.1	76,065	65.4	62,594	53.8	78,722	67.7
Maize	14,312	12.3	16,805	14.4	12,308	10.6	17,754	15.3	9,843	8.5
Sugar beets	15,042	12.9	25,590	22.0	19,022	16.4	22,430	19.3	22,866	19.7
Rapeseed	9,800	8.4	11,034	9.5	8,914	7.7	13,530	11.6	4,878	4.2

TABLE 2 | Absolute and percentage area of the classified crop types for the single years between 2016 and 2020.



percentage ranged between 0.0 and 10.0%; the "extremely high risk" class was absent in August in any other year than 2017.

Hot-Spots of Soil Compaction Risk Within the Region

Focusing on the class "extremely high" soil compaction risk enables the detection of areas that are mostly at risk for soil compaction within the region. In a first step, all daily soil compaction risk maps with the class "extremely high" risk were summarized for each year (**Supplementary Figures S1–S5**). This yielded in the amount of days, on which a certain area/raster cell falls into the highest compaction risk class within 1 year. In 2016 and 2018–2020, the highest soil compaction risk class is absent in more than 90% of the cropland area. In 2017, however, only 60.3% of the area were

Risk class	Cereals		Maize		Sugar beet		Rapeseed		Total	
	ha	%	ha	%	ha	%	ha	%	ha	%
No field traffic	0	0.0	16,805	14.4	0	0	11,034	9.5	27,839	23.9
No risk	6,435	5.5	0	0	22,197	19.1	0	0	28,632	24.6
Low	1,322	1.1	0	0	3,392	2.9	0	0	4,714	4.1
Medium	4,080	3.5	0	0	0	0	0	0	4,080	3.5
High	21,388	18.4	0	0	0	0	0	0	21,388	18.4
Very high	7,190	6.2	0	0	0	0	0	0	7,190	6.2
Extremely high	22,466	19.3	0	0	0	0	0	0	22,466	19.3

TABLE 3 Absolute and percentage area of soil compaction risk classes for the four crop types on 07 August 2017 at a depth of 40 cm.

not at "extremely high" risk (**Table 4**). Additionally, the number of days with "extremely high" soil compaction risk is increased in 2017 compared to the four other years, e.g., 21,985 ha with 11–20 days of "extremely high" soil compaction risk **Table 4**.

In a second step, all soil compaction risk maps of the 5 years (= 1,827 days) with the class "extremely high" were summarized to identify the area of highest soil compaction risk (**Figure 7**). It showed that 39.8% of the cropland was exposed to "extremely high" soil compaction risk at least once during the entire study period (**Table 5**). Overall, 2.7% of the area revealed an "extremely high" soil compaction risk in each year. The areas, which were never or only once affected by "extremely high" soil compaction risk, were heterogeneously distributed across the study area. The north-western part of the study area showed a remarkable cluster with increased soil compaction risk.

Analyzing the 2.7% area exposed to "extremely high" soil compaction risk in all 5 years in more detail revealed that a high percentage of this area (40.3–86%) corresponds to the crop type cereals (**Table 6**), followed by maize with a share ranging between 12.0 and 28.7%. An exception was 2017, where cereals (40.3%) and sugar beets (39.1%) reached similar area percentages.

Focusing on the soil characteristics of the 2.7% area showed that the soil texture class "Ut4" (German classification scheme; clay content: 17–25%, silt content: 65–83%) predominated this area with 3,055 ha. Further affected soil texture classes were Sl2, Lt2 and Lu. However, almost all soil texture classes (Ls2, Lt2, Lt3, Lts, Lu, Sl2, Ss, Su3, Su4, Tu2, Tu3, Tu4, Uls, Us, Ut3, Ut4) occurred at the areas exposed to "extremely high" soil compaction risk in at least 1 year.

DISCUSSION

Spatio-Temporal Variation of Soil Compaction Risk

Our study showed the high spatio-temporal variation of soil compaction risk within a region. This applies to the annual changes in the same way as to the changes between the individual years.

These variations result from the interaction of actual soil strength and soil stress, which was calculated from the present crop type, soil data, weather data, machinery characteristics and field traffic days. The combination and interaction of these factors resulted in a heterogenous distribution of soil compaction risk across the region (exemplarily shown in **Figure 5**). Cereals harvest with wheel loads of 8.2 Mg (**Supplementary Table S3**) and relatively wet soil conditions in 2017 (discussion below) resulted in an increased share of high" to "extremely high" soil compaction risk at that date. The areas with sugar beets were less affected, as only spraying operation with wheel loads of 1.1/2.4 Mg were assumed, causing only "low" soil compaction risk (**Table 3**). The selected wheel loads represent typical ones for the study area. However, as wheel loads continuously increase in intensive agriculture (Keller et al., 2019; Kuhwald, 2019), higher wheel loads will frequently occur in the study area as well, resulting in higher soil stress and thus in higher soil compaction risk.

Weather is one highly variable and strongly influencing factor affecting variation of soil compaction risk, which exerts a large influence both within a year and between years. Within a year, spring is the period with the highest soil compaction risk in all years. The reason is a decreased evapotranspiration during winter, while precipitation is at a high level (Figure 2). Both factors increase soil moisture until spring. Generally, an increase in soil moisture leads to a decrease in soil strength (Rücknagel et al., 2012; Gut et al., 2015; Edwards et al., 2016). Thus, the soil strength is decreased to a minimum when field traffic activities occur in spring, usually in March and at the beginning of April. Consequently, it can be assumed that a high share of field traffic activities occurring at this time are associated with an increased soil compaction risk. Many field studies investigated the negative effects of field traffic in spring under wet soil conditions on soil functions (e.g., Schjønning et al., 2016; Pulido-Moncada et al., 2019; Ren et al., 2019).

During summer, evapotranspiration increases. The soils may become drier, which generally results in higher soil strength and lower soil compaction risk in general, as seen for the years 2016 and 2018–2020. In contrast, precipitation was higher in 2017. The mean annual precipitation was 750 mm this year, while it ranged between 454 and 641 mm in the other 4 years (DWD, 2021). Especially in July and August, the precipitation was significantly higher amounting to 278 mm in 2017 compared to 50–117 mm as registered for 2016 and 2018–2020 (**Figure 2**; **Supplementary Table S4**). The high amount of precipitation in summer increased the soil moisture even in the subsoil. Thus, the soil strength was reduced and the soil compaction risk noticeably increased in 2017 during cereal harvest. The effects of increased soil moisture were



also evident in autumn for 2017, where the soil compaction risk remained at a high level during maize and sugar beet harvest. The harvest of maize and sugar beets are accompanied with high wheel loads, resulting in high soil stress and increased soil compaction risk (e.g., Peth et al., 2006; Barik et al., 2014; Duttmann et al., 2014; Destain et al., 2016; Götze et al., 2016). Thus, an increased susceptibility to soil compaction can generally be expected for maize and sugar beet.

Nevertheless, modelled soil compaction risk was relatively low during autumn in 2016 and 2018–2020. These years were extremely dry (e.g., Zscheischler and Fischer, 2020; Kowalski et al., 2022), especially in the summer months. The dryness increased soil strength and resulted in a reduced soil compaction risk even for the heavy machineries used for maize and sugar beet harvest. Thus, an increased soil compaction risk in autumn can be expected for "normal" years, during which the precipitation is around the long-term average.

Overall, analyses of the spatio-temporal dynamics revealed that 1 year with increased precipitation can considerably affect the soil compaction risk. This is particularly problematic as soil compaction, especially subsoil compaction, can be persistent for many years (Etana et al., 2013; Keller et al., 2017; Keller et al., 2021; Seehusen et al., 2021). Thus, 1 year of increased soil compaction risk accompanied by unsuited field traffic activities can be sufficient to affect soil functions and soil health in the long term.

Hot-Spots of Soil Compaction Risk

The hot-spot analysis revealed an area share of 2.7% that was exposed to the highest soil compaction risk class ("extremely high") in each year of the 5-years period. From the perspective of sustainable soil use and soil protection, these areas are suggested to be the most endangered ones. In order to prevent harmful soil changes, they have to be managed carefully.

The soil texture class "Ut4" dominated the 2.7% area. Generally, silty clay soils are highly susceptible to soil compaction compared to other soil texture classes (Lorenz et al., 2016). In the study area, 260 soil profiles are characterized by the soil texture class "Ut4" at the investigated depth, representing an area of 39,574 ha. Out of these, only 54 soil profiles were part of the 2.7% hot-spot area. Thus, soil texture of "Ut4" is not necessarily associated with the highest soil compaction risk.

Focusing on the area that is affected at least in 1 year by the highest soil compaction risk class revealed an area share of 39.8%. The majority of these area is affected in 1 year (**Table 5**). As described above, soil compaction, especially subsoil compaction, is persistent and hardly to recover. Thus, even a one-time increased soil compaction risk can result in soil compaction that persists for many years if field traffic is conducted with machinery unsuitable for the current situation. In practice, this will not be the case for the entire 39.8% area; however, the analysis showed the high area share that is potentially affected.

As described above, the 5-years period was characterized by mainly dry years. The mean annual precipitation between 2016 and 2020 was 582 mm, while it was 680 mm between the years 2005 and 2015 (**Supplementary Table S4**). Lower precipitation and soil desiccation during the investigated period compared to previous years resulted in a potentially

Days	201	2016		2017		2018		2019		2020	
	ha	%	ha	%	ha	%	ha	%	ha	%	
0	105,207	90.5	70,047	60.3	106,291	91.4	106,088	91.2	106,915	91.9	
1–10	402	0.3	5,891	5.1	6,953	6.0	7,068	6.1	104	0.1	
11–20	2,633	2.3	22,060	18.9	2,969	2.6	1,459	1.3	9,127	7.8	
21–30	7,641	6.6	16,247	14.0	56	0.0	1,691	1.5	145	0.1	
31–40	35	0.0	1,457	1.3	36	0.0	3	0.0	17	0.0	
>40	391	0.3	607	0.5	4	0.0	0	0.0	0	0.0	

TABLE 4 | Absolute and percentage area of days with the class "extremely high" soil compaction risk summarized for each year (2016-2020).



underestimated hot-spot area. Thus, we assume that the area percentage of the highest risk class would have been larger when the weather and soil moisture conditions of a longer period would have been considered. However, it remains to be seen whether drier conditions will be the new "normal" in the study area. The potential area exposed to high soil compaction risk will further increase when changing the definition of "hot-spot". The presented hot-spot analysis was conducted for the "extremely high" soil compaction risk class. When considering the two highest classes ("very high" and "extremely high"), the hot-spot area increased considerably TABLE 5 | Absolute and percentage area of hot-spots (containing only the class "extremely high" soil compaction risk) of soil compaction risk, grouped by number of years of their occurrence.

	Occurrence of class "extremely high" soil compaction risk in										
	0 years	1 year	2 years	3 years	4 years	5 years					
Area share (in %)	60.2	26.8	2.1	2.5	5.7	2.7					
Total area (in ha)	69,977	31,220	2,475	2,854	6,649	3,134					

TABLE 6 | Absolute and percentage crop type area of the areas with every year soil compaction risk class "extremely high".

	2016		2017		2018		2019		2020	
	ha	%								
Cereals	2,487	79.4	1,263	40.3	2,199	70.2	1,906	60.8	2,696	86.0
Maize	50	16.2	503	16.0	844	26.9	899	28.7	376	12.0
Sugar beet	6	0.2	1,224	39.1	2	0.1	97	3.1	9	0.3
Rapeseed	134	4.3	143	4.6	88	2.8	231	7.4	52	1.7

TABLE 7 | Absolute and percentage area of hot-spots (containing the classes "very high" and "extremely high" soil compaction risk) of soil compaction risk, grouped by number of years of their occurrence.

	Occurrence of classess "very high" and "extremely high" soil compaction risk in										
	0 years	1 year	2 years	3 years	4 years	5 years					
Area share (in %)	40.1	42.4	2.7	1.8	1.8	11.1					
Total area (in ha)	46,678	49,369	3,185	2,076	2,145	12,854					

(**Table** 7). The area share affected at least one time every year by "very high" and/or "extremely high" soil compaction risk was at 11.1%. Only 40% of the study area were never affected by "very high" and/or "extremely high" soil compaction risk.

The definition of the term "hot-spot" is therefore very important to provide information on the spatial extent of critical soil compaction risk. This also raises the question of how to assess the respective risk classes. The used approach classifies the soil compaction risk in five classes (Rücknagel et al., 2015; Götze et al., 2016). Terranimo, for instance, uses only three classes (Stettler et al., 2014), while Jones et al. (2003) uses four classes. It remains unclear, however, how these classes are to be evaluated. Is a "medium" soil compaction risk tolerable, or will it result in severe soil compaction? Thus, an evaluation of the calculated soil compaction risk is necessary, as exemplarily shown by Götze et al. (2016), in order to derive the critical risk classes.

Advances and Limitations of the Soil Compaction Risk Analysis

Generally, it must be kept in mind that the used SaSCiAmodel calculates the risk of soil compaction. Thus, the model does not predict the real occurrence and distribution of soil compaction, but indicates where soil compaction is likely to occur. Furthermore, the SaSCiA-model has some limitations, which are discussed in detail by Kuhwald et al. (2018). An important limitation is that the wheel pass frequency is not considered in the SaSCiA-model, although the amount of wheel passes has an impact on soil compaction (e.g., Botta et al., 2009; Pulido-Moncada et al., 2019). Another limitation is associated with the raster approach, which leads to the fact that the entire raster cell is always affected by field traffic. This results in an overestimation of the risk area, since almost never all parts of a field are wheeled during one field traffic activity (except for sugar beet harvest with a self-propelled harvester; Augustin et al., 2020).

However, two limitations of the original SaSCiA-version were addressed in the present study. The first one was the use of all available weather stations (a total of 55 stations) within the federal state to regionalize the weather information; in the original approach, only one weather station was used (cf. Kuhwald et al., 2018). Thus, spatial variations, e.g., in precipitation, could be accounted for in the 5-years analysis. The second one was the use of a soil map at a scale of 1:50.000 instead of a soil map of 1:200.000 (Kuhwald et al., 2018), which increased the accuracy of the spatial representation of soil characteristics. However, even a soil map of at a scale of 1:50.000 shows a relatively coarse spatial resolution compared to a Sentinel 2-pixel size of 20 m. Therefore, a higher spatial resolution soil map is needed to increase the reliability of the soil compaction risk assessment, but is not yet available for the region.

Independent on model limitations, the model approach and model results may be useful to support sustainable soil use and soil protection.

CONCLUSION

This study modelled the spatio-temporal soil compaction risk on a daily basis for 5 years for a region. Thus, for the first time, it was feasible to analyze and show how the dynamic characteristic of soil compaction risk vary in space and time over such a long period of time with high spatial (20 m) and temporal (daily) resolution.

One main result of this analysis is that 1 year of increased precipitation can contribute to a tremendous increase in soil compaction risk, which was the case in this study in 2017. Another important finding was that 2.7% of the area exhibited the highest soil compaction risk class ("extremely high") in each year of the study period. Looking at the areas that were affected by "extremely high" soil compaction risk at least once, this percentage increased to 39.8%.

As discussed above, soil compaction is persistence and many years are required to reach the pre-soil compaction state, if it is achievable at all. Assuming a share of nearly 40% of compacted soil in the study area would therefore have strong environmental effects and will reduce the yield substantially. However, the modelled results show the risk of soil compaction, not the actual state. But by identifying the risk, the extent of possible soil degradation becomes apparent.

Thus, this study may contribute to increased awareness of soil compaction risk dynamics in order to mitigate further soil degradation. In this sense, a next step must be the integration of weather forecast to enable the prediction of soil compaction risk for the following days. This prediction will enable to decide on which day a field might by trafficked by identifying the day with the lowest soil compaction risk.

DATA AVAILABILITY STATEMENT

The data analyzed in this study is subject to the following licenses/restrictions: - The soil map used (BK 50) must be paied for use. - The weather data used is free available (https:// opendata.dwd.de/climate_environment/CDC/)—The satellite

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AUTHOR CONTRIBUTIONS

MK designed the study, conducted the modelling, analyzed the data and wrote the majority of the text. KK prepared the satellite data, conducted the crop type classification and contributed to the text. RD contributed in reviewing and finalizing the manuscript.

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SUPPLEMENTARY MATERIAL

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