Modal and non-modal stabilities of flow around a stack of plates

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Abstract

Modal and non-modal stabilities of flow around a stack of flat plates are investigated by means of asymptotic stability and transient growth analyses respectively. It is observed that over the parameters considered, both the base flow and the stabilities vary as a function of $ReW^2/(W-1)^2$, i.e. the product of the Reynolds number and the square of the expansion ratio of the stack. The most unstable modes are found to be located downstream of the recirculation bubble while the global optimal initial perturbations (resulting in maximum energy growth over the entire domain) and the weighted optimal initial perturbations (resulting in maximum energy growth in the close downstream region of the stack) concentrate around the stack end owing to the Orr mechanism. In direct numerical simulations (DNS) of the base flow initially perturbed by the modes, it is noticed that the weighted optimal initial perturbation induces periodic vortex shedding downstream of the stack much faster than the most unstable mode. This observation suggests that the widely reported vortex shedding in flow around a stack of plates, e.g. in thermoacoustic devices, is associated with perturbations around the stack end.

Keywords: laminar wake, flat plates, stability

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1. Introduction

Flow around a stack of plates has been widely encountered, e.g. in thermoacoustic devices applied in electricity generators, refrigeration or heat recovery systems for conversion between thermal and acoustic energies. From the fluid dynamical point of view, the fluid flow past a stack of parallel flat plates exhibits many interesting flow features. Some of these have been studied experimentally in the past, revealing interesting patterns of both symmetric and asymmetric vortex shedding and loss of stability of elongated shear layers [2, 3, 4, 5, 6].

Parameter dependence of the vortex shedding in flow past a stack of parallel plates has been extensively studied, e.g. effects of stack positioning, blockage ratio, plate aspect ratio and Reynolds number [7, 8, 9, 10]. To reduce the number of independent parameters, the flow past a stack can be simplified as flow past one flat plate confined by periodic (upper and lower) boundaries, as shown in fig. 1. Effects of confinement on flow stabilities have been well investigated, e.g.

¹⁵ in confined planar wake flow [11] and flow around arrays of rectangular cylinders [12] or circular cylinders [10], where the critical Reynolds number above which instabilities or vortex shedding occur was calculated. For flow at Reynolds number well above the critical value, three-dimensional stability of the wake flow around a thin plate has been studied [13].

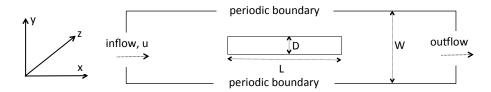


Figure 1: Simplified model of flow past a stack of plates adopted in this work.

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The literature about flow around a stack of plates (or more general bluff bodies) has focused on either the flow instabilities, which can be interpreted as the onset of vortex shedding, or the fully developed vortex shedding state. The gap between the two states, i.e. the route from initial infinitesimal perturbations to periodic vortex shedding, is still an open question. The current study will target this gap and focus on identifying the origin of vortex shedding and how the infinitesimal perturbation to a steady base flow develops into vortex shedding

In the rest of this work, the methodology to calculate perturbations relevant to vortex shedding, e.g. modal stability (asymptotic stability) theory to calculate the modal modes (most unstable modes) and nonmodal stability (non-normality, transient growth) theory to calculate the nonmodal modes (optimal initial perturbations) are presented, followed by the numerical setup, and then the modal and nonmodal modes as well as their nonlinear developments to vortex shedding are discussed.

35 2. Methodology

in flow past a periodic plate array.

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Both modal and nonmodal studies performed in this work involve the linearisation of the incompressible Navier-Stokes (NS) equations:

$$\partial_t \boldsymbol{u} = -(\boldsymbol{u} \cdot \boldsymbol{\nabla})\boldsymbol{u} - \boldsymbol{\nabla} \boldsymbol{p} + Re^{-1}\boldsymbol{\nabla}^2 \boldsymbol{u},$$

with $\boldsymbol{\nabla} \cdot \boldsymbol{u} = 0,$ (1)

where \boldsymbol{u} is the velocity vector, p is the modified pressure and Re is the Reynolds number. The flow field can be decomposed into the summation of a steady base flow and a perturbation flow as

$$(u, p) = (U, P) + (u', p').$$
 (2)

Substituting eq. (2) into eq. (1) and linearizing the convective term, the linearized NS equations are obtained:

$$\partial_t \boldsymbol{u}' = -(\boldsymbol{U} \cdot \boldsymbol{\nabla}) \boldsymbol{u}' - (\boldsymbol{u}' \cdot \boldsymbol{\nabla}) \boldsymbol{U} - \boldsymbol{\nabla} \boldsymbol{p}' + R e^{-1} \boldsymbol{\nabla}^2 \boldsymbol{u}',$$

with $\boldsymbol{\nabla} \cdot \boldsymbol{u}' = 0.$ (3)

In the Cartesian coordinates with x, y and z denoting the streamwise, vertical and spanwise directions respectively as illustrated in fig. 1, the base flow around a stack of plates is assumed to be homogenous in the spanwise direction z. Therefore any perturbation at time t = T can be further decomposed as the sum of modal modes

$$\boldsymbol{u}'(x,y,z,T) = \sum \left(\sum \hat{\boldsymbol{u}}_{ij}(x,y) \mathrm{e}^{\sigma_i T}\right) \mathrm{e}^{\beta_j z}$$

where $\hat{\boldsymbol{u}}_{ij}$ denotes the modal mode with spanwise wavenumber β_j , growth rate $\operatorname{Re}(\sigma_i)$ and frequency $\operatorname{Im}(\sigma_i)$. At each given spanwise wavenumber, the most unstable mode can be calculated as the modal mode with the largest growth rate. Clearly if all the growth rates are negative, all the modal modes decay in time and the flow is stable to perturbations, while if at least one growth rate is positive, the flow is asymptotically unstable.

To calculate the most unstable mode and its growth rate at a given β , define an operator \mathcal{A} , which evolves a perturbation from t = 0 to t = T by integrating the linearized NS equations:

$$\boldsymbol{u}'(T) = \mathcal{A}(T)\boldsymbol{u}'(0).$$

The growth rate of the most unstable mode can be obtained as $\sigma_{\text{max}} = T^{-1} \ln \lambda$, where λ is the eigenvalue of \mathcal{A} . This (dominant) eigenvalue can be calculated by implementing an Arnoldi method to a Krylov sequence built by iterative calls of the linearized NS equations [14]. In a convergence test, it is observed that as expected the growth rate is independent on the value of T. However for larger values of T, the growth rate converges over less iterative calls of the governing equations but each iteration costs more CPU hours. In this work T = 5 is adopted.

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While the modal stability analyses focus on asymptotic growth of perturbations over infinite time horizons, dynamics of perturbations over finite time, or transient energy growth, can be investigated by nonmodal analyses. Transient growth is defined with respect to the energy growth of the perturbation over a given time interval [15] and can be quantitatively measured as the maximum ratio of the final perturbation energy and the initial energy across all possible initial perturbations [14]:

$$G = \max_{\boldsymbol{u}'(0)} \frac{(\boldsymbol{u}'(\tau), \boldsymbol{u}'(\tau))}{(\boldsymbol{u}'(0), \boldsymbol{u}'(0))}$$

where τ is a final time and the scale product is defined as $(\boldsymbol{u}', \boldsymbol{u}') \equiv \int_{\Omega} \boldsymbol{u}' \cdot \boldsymbol{u}' dv$, ⁵⁵ with Ω denoting the computational domain.

Defining $\mathcal{A}^*(\tau)$ as the adjoint operator of $\mathcal{A}(\tau)$, there is $(\boldsymbol{u}'(\tau), \boldsymbol{u}'(\tau)) = (\mathcal{A}\boldsymbol{u}'(0), \mathcal{A}\boldsymbol{u}'(0)) = (\mathcal{A}^*(\tau)\mathcal{A}(\tau)\boldsymbol{u}'(0), \boldsymbol{u}'(0))$. Therefore the most significant transient energy growth G and the corresponding optimal initial perturbation are the largest eigenvalue and the corresponding eigenvector of the joint operator $\mathcal{A}^*(\tau)\mathcal{A}(\tau)\mathcal{A}(\tau)\mathcal{A}(\tau)$.

 $\mathcal{A}^*(\tau)\mathcal{A}(\tau)$. This eigenvalue can be calculated similarly as in the modal stability analyses through iterative calls of operator $\mathcal{A}(\tau)$ and $\mathcal{A}^*(\tau)$ to build a Krylov sequence. The action of the adjoint operator corresponds to the integration of the adjoint equations

$$\partial_t \boldsymbol{u}^* = -(\boldsymbol{U} \cdot \boldsymbol{\nabla}) \boldsymbol{u}^* + (\boldsymbol{\nabla} \cdot \boldsymbol{U})^T \boldsymbol{u}^* - \boldsymbol{\nabla} p^* + Re^{-1} \boldsymbol{\nabla}^2 \boldsymbol{u}^*$$

 $\boldsymbol{\nabla} \cdot \boldsymbol{u}^* = 0$

backwards from $t = \tau$ to t = 0 [14].

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To evaluate the energy growth in a particular area of the computational domain, e.g., the region around the exit of the stack where the perturbation has significant impacts on the efficiency of the thermoacoustic system, a weighted energy growth is defined:

$$G_F = \max_{\boldsymbol{u}'(0)} \frac{(F\boldsymbol{u}'(\tau), F\boldsymbol{u}'(\tau))}{(\boldsymbol{u}'(0), \boldsymbol{u}'(0))}$$
(4)

where F is a non-negative spatial weight function to filter the energy growth ⁷⁰ in the "uninterested region", e.g. region far downstream of the stack. This weighted maximum transient growth and the corresponding optimal initial perturbation are the largest eigenvalue and the corresponding eigenvector of the operator $\mathcal{A}^*(\tau)F^2\mathcal{A}(\tau)$. In the numerical calculation, F can be considered as a diagonal matrix with entries between 0 and 1. In the following G and G_F will

\mathcal{P}	$\operatorname{Real}(\sigma)_{\max}$
2	9.7562e-02
3	9.7604 e- 02
4	9.7616e-02
5	9.7620e-02
6	9.7622 e- 02
7	9.7622 e-02

Table 1: Convergence of the growth rate of the most unstable mode with respect to the polynomial order \mathcal{P} at (Re, W) = (150, 2.8).

3. Numerical setup

In this work, the stack is isolated and a constant inflow condition is implemented on the inflow boundary (see fig. 1). The inflow velocity and the width of the plate are used to define the Reynolds number and therefore the nondimensionalized plate width is D = 1. The length of the plate is fixed at L = 10to generate a thin plate and the domain width W is a free parameter. Therefore the flow expands with a ratio W/(W - 1) when exiting the channel.

In the numerical setup, the centre of the plate is located at the origin, the inflow and outflow boundaries are located at x = -30 and x = 150, respectively. The domain is decomposed into 4522 spectral elements as shown in fig. 2 and in each element Gauss-Lobatto polynomial expansions are employed. The convergence of the growth rate of the most unstable mode with respect to the polynomial order used in the elemental expansion, denoted as \mathcal{P} , is presented in table 1. It is seen that at $\mathcal{P} = 6$ the growth rate has converged to five significant figures and this polynomial order will be used in all the following work.

In direct numerical simulations (DNS) to calculate the base flow or the nonlinear development of perturbations, the inflow boundary velocity condition is set to $\boldsymbol{U} = (1,0)$, the outflow velocity condition is $\partial_x \boldsymbol{U} = (0,0)$ combined with a zero pressure condition, periodic conditions are imposed on the lower and upper ⁹⁵ boundaries, and no-slip boundary conditions are implemented on the surface of the plate. For modal stability studies, the inflow velocity condition is modified to be zero and for nonmodal stability studies, both the inflow and outflow velocity conditions are set to Dirichlet zero [14]. When the velocity condition is of Dirichlet type, a computed Neumann pressure condition is adopted [16].

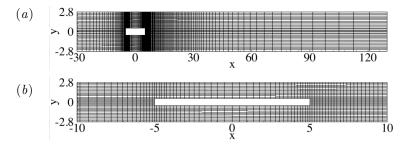


Figure 2: (a) Whole mesh; (b) mesh around the plate.

100 4. Results

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In this section, the steady base flow is firstly calculated and then the modal and nonmodal studies are carried out to calculate the most unstable modes and optimal initial perturbations. Finally, the nonlinear developments of the modes are studied to identify their role in activating vortex shedding through DNS of the base flow initially perturbed by the modes.

4.1. Base Flow

In stability studies, a steady base flow is required to solve the linearized NS equations and the adjoint equations. To obtain a steady solution of the base flow, DNS is conducted in combination with a frequency selective damping scheme, which suppresses the development of unsteadiness [17]. The simulation is run for a sufficiently long time interval until the solution converges.

Fig. 3 shows the steady base flow at various Reynolds numbers and domain width. It is seen that the wake features a recirculation bubble and a pair of elongated shear layers. This type of wake flow has been previously observed in

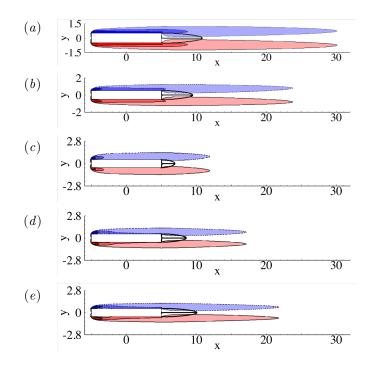


Figure 3: Contours of spanwise vorticity of the steady base flow at (Re, W) = (100, 3), (100, 4), (50, 5.6), (100, 5.6) and (150, 5.6) for (a), (b), (c), (d) and (e), respectively. The contour levels are [-4, -2.4, -0.8, 0.8, 2.4, 4]. Thick solid lines are border streamlines of the recirculation bubble, while dashed and solid contour lines represent negative and positive contour levels respectively, as will be used in following contour plots.

¹¹⁵ flow around a stack of plates in thermoacoustic devices [18], as well as in other bluff body flows, e.g. flow around a cylinder cascade [19] and flow past square cylinders [20]. As the Reynolds number or the expansion ratio W/(W-1)increases, both the bubble and the shear layers extend downstream, while the vertical extension of the bubble is almost constant, owing to the confinement effect of neighbouring plates. These observations suggest that the increases of Re and W/(W-1) have similar effects on the base flow over the parameters

studied.

Considering that the boundary layer thickness inside the channel is a square root function of the Reynolds number and the boundary expands as a ratio

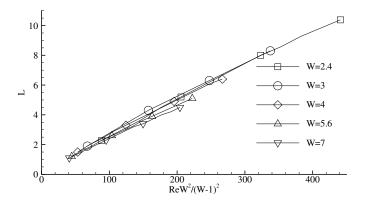


Figure 4: Bubble length L as a function of $ReW^2/(W-1)^2$.

W/(W-1) when exiting the channel, it can be expected that base flow downstream of the stack varies as a function of $ReW^2/(W-1)^2$. To verify this hypothesis, the length of the recirculation bubble, which is critical to the stability of the flow as will be presented later, is illustrated in fig. 4. It is observed that at a fixed W (or expansion ratio), the bubble length L increases linearly with the Reynolds number. Furthermore, as W varies, all the curves overlap, indicating that L is a linear function of $ReW^2/(W-1)^2$. Therefore the Reynolds number has similar effects on the bubble length as the square of the expansion

ratio, e.g. L doubles when either Re or $W^2/(W-1)^2$ doubles.

4.2. Modal Stability Analyses

The geometry with W = 5.6 matches the experimental setup used in [2] and is therefore adopted as an example to illustrate the instabilities at various spanwise wavenumber and Reynolds number, as presented in fig. 5. It is observed that the boundary of instability, featured by the contour line $\text{Re}(\sigma_{\text{max}}) = 0$ expands to higher values of spanwise wavenumber as the Reynolds number increases. It is also noted that the two-dimensional mode ($\beta = 0$) is always the most unstable one for a given Reynolds number and therefore the following studies focus on two-dimensional instabilities.

For two-dimensional instabilities, various values of the domain width, i.e.

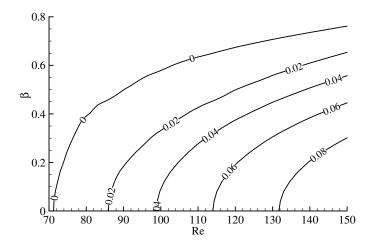


Figure 5: Contours of the growth rate of three-dimensional most unstable modes, i.e. ${\rm Re}(\sigma_{\rm max})$, at W=5.6.

W=2.4, 3, 4, 5.6, 7 and Reynolds number, i.e. $Re \leq 150$, are studied, considering

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the geometry and flow conditions in thermoacoustic devices [2, 6, 18]. From the growth rate of the most unstable mode presented in fig. 6(a), it is seen that the flow becomes more unstable at larger Reynolds number or larger expansion ratios (smaller W) over the parameters considered. This observation suggests that over the cases studied, the confinement of the channel and the subsequent flow expansion destabilises the wake flow and the increase of expansion ratio has a similar effect as increasing the Reynolds number.

To quantitatively evaluate effects of Reynolds number and the expansion ratio, the critical Reynolds number, above which the flow becomes unstable, is plotted in fig. 6(b). It is observed that the critical Reynolds number increases linearly with $(W-1)^2/W^2$ and $Re_C W^2/(W-1)^2 \approx 0.00907$ over the parameters considered.

Distributions of the most unstable modes at Re = 100 and various domain width are shown in fig. 7. It is seen that all the modes are located far downstream of the plate trailing edge and are associated with the shear flow downstream of the bubble. These modes are roughly periodic in the streamwise direction, manifesting the local instabilities of the parallel shear layers down-

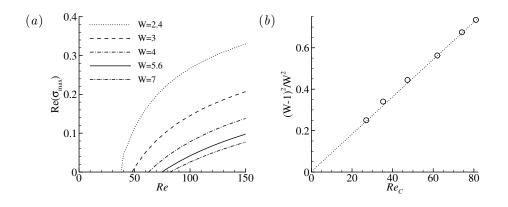


Figure 6: (a) Growth rate of the two-dimensional most unstable modes; (b) the critical Reynolds number Re_C as a function of $(W-1)^2/W^2$, denoted by circles, and a straight (dotted) line with slope 0.00907.

stream of the bubble. For increasing W, the shear layers in the base flow are less compressed and correspondingly the modes expand in the vertical direction. These most unstable modes exhibit in-phase oscillatory around the upper and lower boundaries and align with the odd-odd modes observed in flow past a cylinder cascade at low blockage ratios [10].

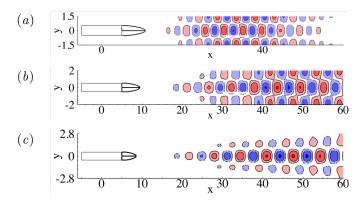


Figure 7: Contours of spanwise vorticity of the most unstable modes at Re = 100 and (a) W = 3, (b) W = 4 and (c) W = 5.6, respectively. Contour levels are chosen to highlight the structures.

4.3. Nonmodal Stability Analyses

The distributions of all the calculated unstable modes are concentrated far downstream of the stack, and would require a large time interval to reach the stack and activate vortex shedding. To reveal the most effective route from initial perturbations to vortex shedding, nonmodal stability analyses (or transient energy growth), which concentrate on the short time dynamics of perturbations, become an ideal tool. Nonmodal stabilities have been well investigated for asymptotically stable or weakly unstable flows, while in this case it will be shown that even for an asymptotically unstable flow, the nonmodal modes can be much more effective than the modal modes in perturbing the flow.

The perturbations near the stack end have the most impact on the efficiency of the thermoacoustic system. As a result, perturbation energy growth around the stack end deserves particular attention. To further concentrate on the energy growth around the stack end over short time intervals, the weighted transient growth is calculated by using a weight function (see eq. 4) to filter energy growth downstream of the bubble:

$$F = \begin{cases} 1 & \text{if} \quad 5 \le x \le 10; \\ \exp^{-(x-5)^2} & \text{if} \quad x < 5; \\ \exp^{-(x-10)^2} & \text{if} \quad x > 10. \end{cases}$$

The global transient energy growth G as well as the weighted transient growth G_F at W = 5.6 is shown in fig. 8. It is noticed that there is significant transient growth even in the asymptotically stable condition (Re < 74.1as shown in fig. 6). For the weakly unstable cases, e.g. Re = 100, the transient growth is dominant over the time interval considered. For example, at $\tau = 50$, the energy growth of the most unstable mode is below 60 while the transient growth is over 1.8×10^7 . However the weighted transient growth G_F is significantly different with G, suggesting that the strong global transient growth relies on the noise amplification downstream of the bubble. Nevertheless, the growth over the bubble region, evaluated by G_F , is still much higher than the energy growth of the most unstable mode, manifesting a strong noise amplification over

the bubble region.

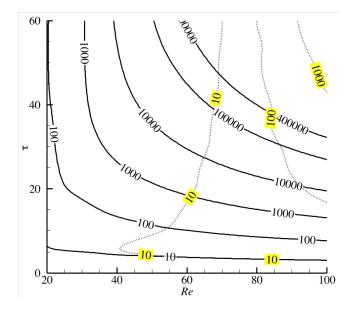


Figure 8: Contours of global (solid lines) and weighted (dotted lines and highlighted contour levels) transient energy growth at W = 5.6.

Structures of the global and weighted optimal initial perturbations that re-¹⁹⁰ sult in the maximum transient energy growth are illustrated in fig. 9. Comparing with the most unstable modes, which are far downstream of the stack as shown in fig. 7, the weighted optimal initial perturbations are located around the stack end, and therefore can be convected downstream and activate vortex shedding around the stack faster than the unstable modes. Physically these perturba-¹⁹⁵ tions could stem from wall roughness around the stack end. As τ increases, the perturbation moves upstream slightly so as to keep the bubble region disturbed over the range $0 \le t \le \tau$. Compared with the weighted optimal initial perturbation, the global optimal initial perturbation is located more downstream and therefore relies less on the amplification in the bubble region.

It is worth noting that the structures of the optimal initial perturbations tilt backwards so as to take advantage of the Orr mechanism when they are convected downstream and compressed by the base flow at t = 5, as shown in

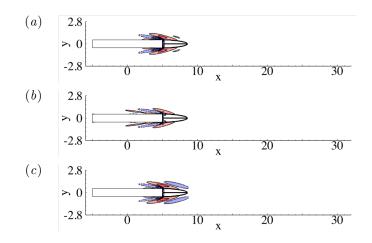


Figure 9: Contours of the spanwise vorticity of (a) weighted optimal initial perturbation at $\tau = 5$, (b) weighted optimal initial perturbation at $\tau = 50$ and (c) global optimal initial perturbation at $\tau = 50$. The Reynolds number and domain width are fixed at Re = 100 and W = 5.6, respectively.

fig. 10(a) and observed in several other nonmodal stability analyses [21, 14]. For further developments of the perturbation until t = 50 (see fig. 10(b)), the amplification effect of the shear layer downstream of the bubble becomes dominant and the perturbation is amplified to resemble the periodic structure of the most unstable mode (see fig. 7(c)). Therefore the transient growth is related to two mechanisms: the Orr mechanism around the bubble region and the shear-layer amplification far downstream of the stack. To concentrate on the perturbation growth over short time in the region around the stack end, the weighted optimal initial perturbation at $\tau = 5$ will be adopted in the following studies.

4.4. Nonlinear Development of the Modes

Both the modal and nonmodal stability analyses performed above are based on linear assumptions and are only valid on the condition that the perturbation is small enough. Clearly, the vortex shedding is a dramatic change of the steady state and corresponds to large-scale perturbations. Therefore nonlinear developments of perturbations are critical in studying the route from initial

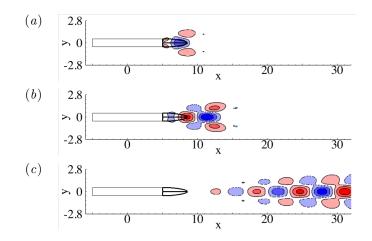


Figure 10: Contours of the spanwise vorticity in the development of the weighted optimal initial perturbation at W = 5.6, Re = 100, $\tau = 5$ and (a) t = 5, (b) t = 10 and (c) t = 50. Contour levels are chosen to highlight the structures.

perturbations to vortex shedding. In this subsection, the steady base flow is initially perturbed by either the most unstable modes or weighted optimal initial perturbations at $\tau = 5$ and evolved in DNS over time long enough to identify the role of initial perturbations in vortex shedding [22].

Since the vortex shedding state features periodic velocity oscillations, the vertical velocities at three points along the axis, i.e. (x, y) = (6, 0), (20, 0) and (40, 0) are chosen to monitor the development of vortex shedding, as shown in fig. 11. Since the perturbation modes are obtained based on the linear assumption, the initial perturbation has to be small enough to get the linearly predicted amplification. In this work, the relative energy of the initial perturbation with respect to the base flow is fixed at 10^{-6} . At this relative energy level, the perturbations are negligible compared with the base flow.

For all the three points considered, it is seen that the optimal initial perturbation leads to periodic oscillations of the vertical velocity much faster than the most unstable mode. As the most unstable mode travels upstream, it perturbs the region downstream of the bubble first (fig. 11b, c) and takes over 100 time units to reach the trailing edge region of the stack (fig. 11a). In contrast, the

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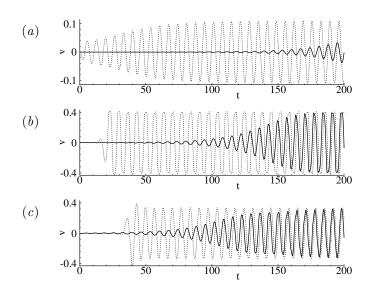


Figure 11: Development of the vertical velocity v in DNS of the steady base flow initially perturbed by the most unstable mode (solid lines) and weighted optimal initial perturbation at $\tau = 5$ (dotted lines) with relative energy (with respect to the base flow) 10^{-6} at Re = 100, W = 5.6 and (a) (x, y) = (6, 0), (b) (x, y) = (20, 0) and (c) (x, y) = (40, 0).

optimal initial perturbation is convected downstream by the base flow from the trailing edge of the stack and perturbs all the three points to oscillatory states before t = 50, which is the largest time for perturbations to develop in a thermoacoustic device as studied in [2, 6, 18]. These observations indicate that even when the flow is asymptotically unstable, the most unstable modes located far downstream of the body can be far less effective in perturbing the flow from a steady state to a periodic vortex shedding state than noise around the stack end.

5. Conclusion

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A simplified model is established to investigate the stability of flow around a stack of flat plates. The steady base flow around an isolated plate with periodic boundary conditions on upper and lower boundaries is calculated through DNS. It is observed that the base flow varies as a function of $ReW^2/(W-1)^2$, which

is the product of the Reynolds number and the square of the expansion ratio of the stack flow, over the parameters considered.

Then the steady base flow is used in modal and nonmodal stability analyses to reveal the asymptotic and transient energy growth of perturbations, respectively. In modal stability studies, the growth rate of the most unstable mode is found to increase at increasing Reynolds number or the stack expansion ratio, indicating a destabilisation effect of the flow expansion or confinement. The critical Reynolds number Re_C is observed to be a linear function of $(W-1)^2/W^2$ and satisfies $Re_C W^2/(W-1)^2 \approx 0.00907$. Therefore the two free parameters, i.e. the Reynolds number and expansion ratio, can be merged into one param-

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- eter, i.e. $ReW^2/(W-1)^2$, in studies of both base flow and instabilities. The unstable modes, in the form of odd-odd modes as discussed in [10], are located in the region far downstream of the plates and are associated with the shear layers downstream of the recirculation bubble.
- In nonmodal stability analyses, it is seen that both the global optimal initial perturbations (resulting in maximum energy growth across all the domain) and the weighted optimal initial perturbation (resulting in maximum energy growth around the stack trailing edge) are located around the stack end. The transient energy growth relies on both the Orr mechanism around the stack end and the amplification effects of the parallel shear layers downstream of the recirculation bubble.

The route from initial perturbations to vortex shedding is investigated through DNS of the base flow initially perturbed by the modes calculated in stability analyses. It is observed that the weighted optimal initial perturbations are convected downstream and trigger vortex shedding much faster than the most unstable modes, which travel upstream to activate vortex shedding. Overall the

275 linear and nonlinear dynamics of the perturbations investigated in this work indicate that even when the steady flow is asymptotically unstable, the most unstable modes are ineffective in activating the bifurcation to vortex shedding since the upstream noise can be much faster in perturbing the flow.

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