DOI: http://dx.doi.org/10.21123/bsj.2019.16.2.0389

On Skew Left n-Derivations with Lie Ideal Structure

Anwar Khaleel Faraj*

Ruqaya Saadi Hashim

Received 15/7/2018, Accepted 9/12/2018, Published 2/6/2019

This work is licensed under a <u>Creative Commons Attribution 4.0 International License</u>.

Abstract

In this paper the centralizing and commuting concerning skew left n-derivations and skew left n-derivations associated with antiautomorphism on prime and semiprime rings were studied and the commutativity of Lie ideal under certain conditions were proved.

Key words: Centralizing mapping, Commuting mapping, Prime ring, Skew left *n*-derivation.

Introduction:

represents an Throughout this paper \mathcal{R} associative ring with center $\mathcal{Z}(\mathcal{R})$ and α^* an antiautomorphism of \mathcal{R} . A ring \mathcal{R} is said to be ntorsion free if na=0 with $a \in \mathcal{R}$ then a=0, where nis nonzero integer (1). For any $v, \gamma \in \mathcal{R}$, the commutator $v\gamma - \gamma v$ is denoted by $[v, \gamma]$ (2). Recall that a ring \mathcal{R} is said to be prime if $a\mathcal{R}b=0$ implies that either a=0 or b=0 for all $a, b \in \mathbb{R}$ (3) and it is semiprime if $a\mathcal{R}a=0$ implies that a=0 for all $a \in \mathcal{R}$ (1). An additive mapping $\xi: \mathcal{R} \to \mathcal{R}$ is called a derivation if $\xi(v\gamma) = \xi(v)\gamma + v\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ (4), and it is called a skew derivation (α^* derivation) of ${\mathcal R}$ associated with the antiautomorphism α^* if $\xi(\upsilon\gamma) = \xi(\upsilon)\alpha^*(\gamma) + \upsilon\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ (5). An additive mapping $\xi: \mathcal{R} \to \mathcal{R}$ is called a left derivation if $\xi(v\gamma) = \gamma \xi(v) + v \xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ (6), and it is called a skew left derivation antiautomorphism α^* of ${\mathcal R}$ associated with if $\xi(v\gamma) = \alpha^*(\gamma)\xi(v) + v\xi(\gamma)$ for all $v, \gamma \in \mathcal{R}$ (7), it is clear that the concepts of derivation and left derivation are identical whenever \mathcal{R} is commutative. A map $\mathcal{F}: \mathcal{R} \rightarrow \mathcal{R}$ is said to be commuting (resp. centralizing) on \mathcal{R} if $[\mathcal{F}(v), v] = 0$ (resp. $[\mathcal{F}(v), v] \in \mathcal{Z}(\mathcal{R})$) for all $v \in \mathcal{R}$ (2). An additive subgroup \mathcal{U} of \mathcal{R} is called Lie ideal if whenever $u \in \mathcal{U}$, $r \in \mathcal{R}$ then $[\mathcal{U}, r] \in \mathcal{U}$ (1). A Lie ideal \mathcal{U} of \mathcal{R} is called a square closed Lie ideal of \mathcal{R} if $u^2 \in \mathcal{U}$, for all $u \in \mathcal{U}$ (6). A square closed Lie ideal \mathcal{U} of \mathcal{R} such that $\mathcal{U} \not\subseteq \mathcal{Z}(\mathcal{R})$ is called an admissible Lie ideal of \mathcal{R} (4). In 2009, Park introduced the concept of symmetric *n*-derivation and he studied the concept as centralizing and commuting (2). The history of centralizing and commuting mapping is due to Divinsky in 1955 (8).

Department of Applied Science, University of Technology, Baghdad, Iraq.

*Corresponding author: <u>anwar_78_2004@yahoo.com</u>

Several authors have studied the concept as commuting and centralizing derivations like J. Vukman who investigated symmetric bi-derivations on prime and semiprime rings (9). We obtain the similar results of Jung and Park ones for permuting 3-derivations on prime and semiprime rings (10) and more results in (11, 12, 13, 14, 15). In the present paper, we have introduced the notion of skew left *n*-derivation and skew left *n*-derivationn associated with the antiautomorphism α^* and studied the commuting and centralizing of this notion and commutativity of Lie ideal under certain conditions.

Throughout this paper n is considered as a fixed positive integer.

Preliminaries

Definition (2.1) (2)

A map $\xi: \mathcal{R}^n \to \mathcal{R}$ is called permuting (or symmetric) if the equation $\xi(v_1, v_2, ..., v_n)$ = $\xi(v_{\pi(1)}, v_{\pi(2)}, ..., v_{\pi(n)})$ holds, for all $v_i \in \mathcal{R}$ and for every permutation { $\pi(1), \pi(2), ..., \pi(n)$ }.

Definition (2.2) (2)

An n-additive mapping $\xi: \mathcal{R}^n \to \mathcal{R}$ is said to be a symmetric *n*-derivation if the following equations are identical:

$$\begin{split} \xi(v_1\gamma, v_2, \dots, v_n) = & \xi(v_1, v_2, \dots, v_n)\gamma + v_1\xi \\ (\gamma, v_2, \dots, v_n) \\ \xi(v_1, v_2\gamma, \dots, v_n) = & \xi(v_1, v_2, \dots, v_n)\gamma + \\ & v_2\xi(v_1, \gamma, \dots, v_n) \\ & \cdot \\ \xi(v_1, v_2, \dots, v_n\gamma) = & \xi(v_1, v_2, \dots, v_n)\gamma + \end{split}$$

 $v_n \xi(v_1, v_2, \dots, \gamma)$ For all $v_1, \gamma, v_2, \dots, v_n \in \mathcal{R}$.

Definition (2.3) (2)

A map $\delta: \mathcal{R} \to \mathcal{R}$ is defined as $\delta(v) = \Omega(v, v, ..., v)$ for all $v \in \mathcal{R}$, where $\Omega: \mathcal{R}^n \to \mathcal{R}$ is called the trace of the symmetric mapping Ω .

It is clear that the trace function δ is an odd function if n is an odd number and is an even function if nis an even number.

Note (2.4) (2)

Let δ be a trace of an *n*-additive symmetric map $\mathcal{D}: \mathcal{R}^n \to \mathcal{R}$, then δ satisfies the relation $\delta(\upsilon+\gamma) = \delta(\upsilon) + \delta(\gamma) + \sum_{k=1}^{n-1} \binom{n}{\nu} h_k(\upsilon,\gamma)$ for all $v, \gamma \in \mathcal{R}$ such that $h_k(v, \gamma) = \Omega(v, v, \dots, v, \gamma, \gamma, \dots, \gamma)$ where v appears (n - k)-times and γ appear ktimes and $\binom{n}{k} = \frac{n!}{k!(n-k)!}$.

Now, we introduce new concept which is called skew left *n*-derivation is defined as follows.

Definition (2.5):

An *n*-additive symmetric mapping $\xi: \mathcal{R}^n \to \mathcal{R}$ is said to be a skew left n-derivation if

$$\xi(v_{1}\gamma, v_{2}, ..., v_{n}) = \gamma \xi(v_{1}, v_{2}, ..., v_{n}) + v_{1}\xi$$

$$(\gamma, v_{2}, ..., v_{n})$$

$$\xi(v_{1}, v_{2}\gamma, ..., v_{n}) = \gamma \xi(v_{1}, v_{2}, ..., v_{n}) + v_{2}\xi$$

$$(v_{1}, \gamma, ..., v_{n})$$

$$\vdots$$

$$\xi(v_{1}, v_{2}, ..., v_{n}\gamma) = \gamma \xi(v_{1}, v_{2}, ..., v_{n}) + v_{n}\xi$$

$$(v_{1}, v_{2}, ..., \gamma)$$

For all $v_1 \gamma, v_2, \dots, v_n \in \mathcal{R}$, it is clear that the concepts of derivation and left derivation are identical whenever \mathcal{R} is commutative

Example (2.6):

Let $\mathcal{R} = \left\{ \begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix} \mid a \in \mathbb{Z} \right\}$ be a ring, and \mathbb{Z} be a ring of integer numbers. A map $\xi: \mathcal{R}^n \to \mathcal{R}$ is defined by $\begin{pmatrix} 0 & a \end{pmatrix} \begin{pmatrix} 0 & a \end{pmatrix}$

$$\xi \begin{pmatrix} \begin{pmatrix} 0 & a_1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & a_2 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & a_n \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & a_1 a_2 \dots a_n \\ 0 & 0 \end{pmatrix}, \text{ for all } \begin{pmatrix} 0 & a_1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & a_2 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 & a_n \\ 0 & 0 \end{pmatrix} \in \mathcal{R}.$$
Then, it easy to check that ξ is skew by

to check that ξ is skew left *n*-Then it easy derivation.

Example (2.7): Let $\mathcal{R} = \left\{ \begin{pmatrix} a & b \\ 0 & 0 \end{pmatrix} \mid a, b \in \mathbb{R} \right\}$, where \mathbb{R} a ring of real numbers and \mathcal{R} is a non-commutative ring under addition and multiplication of matrices. A map $\xi: \mathcal{R}^n \to \mathcal{R}$ defined by $\begin{aligned} & \xi \bigg(\begin{pmatrix} a_1 & b_1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} a_2 & b_2 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} a_n & b_n \\ 0 & 0 \end{pmatrix} \bigg) = \\ & \begin{pmatrix} 0 & b_1 b_2 \dots b_n \\ 0 & 0 \end{pmatrix}, \text{ for all} \end{aligned}$

$$\begin{pmatrix} a_1 & b_1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} a_2 & b_2 \\ 0 & 0 \end{pmatrix}, \dots, \begin{pmatrix} a_n & b_n \\ 0 & 0 \end{pmatrix} \in \mathcal{R}.$$

Then ξ is an *n*-derivation but it's not a left *n*derivation.

Example (2.8):

Let \mathcal{R} be a non-commutative ring. Define a map $\xi: \mathcal{R}^n \to \mathcal{R}$ by $\xi(v_1, v_2, \dots, v_n) = \xi(v_1) \xi(v_2) \dots \xi(v_n)$, for all $v_1, v_2, ..., v_n \in \mathcal{R}$. Then ξ is a skew left *n*derivation but it's not *n*-derivation.

Lemma (2.9) (4): Let \mathcal{R} be a prime ring and $\xi: \mathcal{R} \to \mathcal{R}$ be a derivation such that $a \in \mathcal{R}$. If $a\xi(v) = 0$ holds for all $v \in \mathbb{R}$, then either a=0 or $\xi=0$.

Lemma (2.10) (3): Let \mathcal{R} be a *n*!-torsion free ring and $\lambda \gamma_1 + \lambda^2 \gamma_2 + \ldots + \lambda^n \gamma_n = 0$ where $\gamma_1, \gamma_2, \ldots, \gamma_n \in \mathcal{R}$ with $\lambda = 1, 2, \dots, n$. Then $\gamma_i = 0$, for all $i = 1, 2, \dots, n$.

Lemma (2.11) (2): Let \mathcal{R} be a *n*!-torsion free ring and $\lambda \gamma_1 + \lambda^2 \gamma_2 + \ldots + \lambda^n \gamma_n \in \mathbb{Z}(\mathcal{R})$ where $\gamma_1, \gamma_2, \ldots, \gamma_n \in \mathbb{Z}(\mathcal{R})$ \mathcal{R} with $\lambda = 1, 2, \dots, n$. Then $\gamma_i \in \mathbb{Z}$, for all i=1,2,...,n.

The Main Results

In 2009, K.H. Park (2) studied the concept of symmetric *n*-derivation as centralizing and commuting, we have studied the concept of skew left *n*-derivations in rings and introduced the term of skew left n-derivation associated with an antiautomorphism α^* .

In the following results, U is considered as a noncentral Lie ideal of n!-torsion free prime ring \mathcal{R} .

Theorem3.1: Let $\Omega: \mathcal{U}^n \to \mathcal{R}$ be a skew left *n*derivation such that the trace δ of Ω is commuting on \mathcal{U} . Then $\Omega=0$.

Proof:

 $[\delta(v), v] = 0, \forall v \in \mathcal{U}.$... (1) Substituting $v=v+\mu\gamma$ in equation (1) and using it and let $\mu(1 \le \mu \le n)$ be any integer, then $0 = [\delta(\upsilon + \mu \gamma), \upsilon + \mu \gamma]$ = $[\delta(v)+\delta(\mu\gamma)+\sum_{k=1}^{n-1}C_kh_k(v,\mu\gamma), v+\mu\gamma]$ $=\mu\{[\delta(v),\gamma]+$ $[c_1h_1(v,\gamma),v]$ + $\mu^2\{[c_2h_2(v,\gamma),v]$ + $[c_1h_1(v,\gamma),\gamma]$ + ...+ $\mu^{n}\{[\delta(\gamma), v] + [c_{n-1}h_{n-1}(v, \gamma), \gamma]$... (2) From lemma (2.10) and equation (2), to have $[\delta(v), \gamma] + n[h_1(v, \gamma), v] = 0$... (3) Replacing $\gamma = 2\nu\gamma$ in equation (3) and using it, then $0=[\delta(v), 2v\gamma]+n[h_1(v, 2v\gamma), v]$ $=2\{v\{[\delta(v), \gamma] + n[h_1(v, \gamma), v]\} + n[\gamma, v]\delta(v)\}$ $=2n[\gamma, \nu]\delta(\nu)$, and by using *n*!-torsion to have $[\gamma, \upsilon]\delta(\upsilon)=0.$... (4) From equation (4) and Lemma (2.9), to get A map $\gamma \rightarrow [\gamma, \upsilon]$ is a derivation on \mathcal{U} . Then $\delta(\upsilon)=0$... (5)

Baghdad Science Journal

k=1,2,...,nFor each let $p_k(v) = \Omega(v, ..., v, v_{k+1}, v_{k+2}, ..., v_n)$ where v appears k-times and $v, v_i \in \mathcal{U}, i = k+1, k+2, ..., n$ Let τ ($1 \le \tau \le n - 1$) be any integer. By equation (5) the relation $0=\delta(\tau v+v_n)=p_n(\tau v+v_n)$ $=\tau^n \delta(v) + \delta(v_n) + \sum_{k=1}^{n-1} \tau^k c_k p_k(v)$ $=\sum_{k=1}^{n-1}\tau^k c_k p_k(v)$... (6) By lemma (2.10) and equation (6), to have $c_{n-1}p_{n-1}(v)=p_{n-1}(v)=0$... (7) Let $\zeta (1 \leq \zeta \leq n - 2)$ be any integer. By equation (7) the relation $p_{n-1}(\zeta v + v_{n-1}) = 0, \forall v, v_{n-1} \in \mathcal{U}$ $\zeta^{n-1}p_{n-1}(v) + p_{n-1}(v_{n-1}) + \sum_{k=1}^{n-2} \zeta^k c_k p_k(v) = 0$ $\sum_{k=1}^{n-2} \zeta^k c_k p_k(v) = 0$... (8) Using lemma (2.10) and equation (8) to get $c_{n-2}p_{n-2}(v)=p_{n-2}(v)=0$, hence $c_1p_1(v)=0$ and then $p_1(v)=0$, which means $\Omega(v_1, v_2, \dots, v_n) = 0, \forall v_i \in \mathcal{U}, \text{ where } i = 1, 2, \dots, n.$

Theorem3.2: Let $\Omega: \mathcal{U}^n \to \mathcal{R}$ be a skew left *n*-derivation such that the trace δ of Ω is centralizing on \mathcal{U} . Then δ is commuting on non-zero ideal I of \mathcal{U} .

Proof:

 $[\delta(v), v] \in \mathcal{Z}(\mathcal{R}), \forall v \in \mathcal{U}.$... (1) Substituting $v=v+\mu\gamma$ in equation (1) and using it and let $\mu(1 \le \mu \le n)$ be any integer, to obtain $\mathcal{Z}(\mathcal{R}) \ni [\delta(\upsilon + \mu \gamma), \upsilon + \mu \gamma]$ =[$\delta(v)$ + $\delta(\mu\gamma)$ + $\sum_{r=1}^{n-1} C_r h_r(v,\mu\gamma), v + \mu\gamma$] $=\mu\{[\delta(v),\gamma]+$ $[c_1h_1(v,\gamma),v]$ + $\mu^2\{[c_2h_2(v,\gamma),v]$ + $[c_1h_1(v,\gamma),\gamma]$ + … + $\mu^{n}\{[\delta(\gamma), v] + [c_{n-1}h_{n-1}(v, \gamma), \gamma]\}$... (2) From lemma (2.11) and equation (2), to have $[\delta(v), \gamma] + n[h_1(v, \gamma), v] \in \mathcal{Z}(\mathcal{R}),$ $\forall v, v \in \mathcal{U}$... (3) Taking $\gamma = 2v^2$ in equation (3) and using it, to get $\mathcal{Z}(\mathcal{R}) \ni [\delta(v), 2v^2] + n[h_1(v, 2v^2), v]$ $=(2n+2)[\delta(v),v]v$... (4) Commuting equation (4) with $\delta(v)$ gives $0=(2n+2)[\delta(v),v]^2$... (5) Substituting $\gamma = 2v\gamma$ in equation (3) to have $\mathcal{Z}(\mathcal{R}) \ni [\delta(v), 2y] + n[h_1(v, 2vy), v]$ $= (n+1)[\delta(v), v]\gamma + v\{[\delta(v), \gamma] + n[h_1(v, \gamma), v]\} +$ $n[v,v]\delta(v)$ Commuting the last equation with v, and using equation (3) then

 $[(n+1)[\delta(v),v]\gamma+n[\gamma,v]\delta(v),v]+[v\{[\delta(v),\gamma]+$ $n[h_1(v,\gamma),v],v]=0$... (6) It follows equation (6) that $0 = (n + 1) [[\delta(v), v], v] \gamma + (n + 1) [[\delta(v), v] \gamma + (n +$ 1) $[\delta(v), v][\gamma, v] + n[[\gamma, v], v]\delta(v) + n[\gamma, v][\delta(v), v]$ $= (2n+1)[\delta(v), v][\gamma, v] + n[[\gamma, v], v]\delta(v)$... (7) Since \mathcal{U} is a non-central Lie ideal then there exists a non-zero ideal I of \mathcal{U} . Replacing $\gamma = \delta(v)\gamma$ in equation (7) for all $v \in \mathcal{U}$, $\gamma \in I$ and by using equation (1), to have: $0 = (2n + 1)^{-1}$ 1) $[\delta(v), v][\delta(v)\gamma, v] + n[[\delta(v)\gamma, v], v]\delta(v)$ = $(2n +)[\delta(v), v]^2\gamma + \delta(v) \{(2n+1)[\delta(v), v][\gamma, v] + n[[\gamma$ $[v],v]\delta(v)\} + 2n[\delta(v),v][\gamma,v]\delta(v)$ According to equation (7), to get $(2n+1)[\delta(v),v]^2\gamma+2n[\delta(v),v][\gamma,v]\delta(v)=0$... (8) Taking $\gamma = [\delta(z), z]$ and v = z in equation (8) where $z \in I$, to have $0 = (2n + 1)^{n}$ 1) $\left[\delta(z), z\right]^3 + 2n \left[\delta(z), z\right] \left[\delta(z), z\right], z \left[\delta(z), z\right]$ $=(2n+1)[\delta(z),z]^3=0, \forall z \in I$ and so we have $(2n + 1)[\delta(z), z]^2 U(2n + 1)[\delta(z), z]^2 = 0$. By the semiprimeness of \mathcal{R} , to get $(2n+1)[\delta(z),z]^2=0$... (9) Combining equation (9) with (5) then $[\delta(z), z]^2 = 0, \forall z \in I.$ As the center of a semiprime ring contains no non-

As the center of a semiprime ring contains no nonzero nilpotent elements, then we conclude that $[\delta(z), z], \forall z \in I$.

Theorem 3.3: Let $\Omega: \mathcal{U}^n \to \mathcal{R}$ be a non-zero skew left *n*-derivation such that the trace δ of Ω is centralizing \mathcal{U} . Then \mathcal{U} is commutative.

Proof:

Suppose that \mathcal{U} is a non-commutative prime ring. Then from theorem (3.2) we have δ which is commuting on \mathcal{U} . And from theorem (3.1) we have $\Omega=0$, which is contradiction hence, \mathcal{U} must be commutative prime ring.

Now, the pervious results can be generalized by introducing the concept of skew left n-derivation associated with antiautomorphism as follows:

Definition 3.4:

An *n*-additive mapping $\xi: \mathcal{R}^n \to \mathcal{R}$ is called a skew left *n*-derivation associated with an antiautomorphism α^* if

$$\begin{split} &\xi(v_1\gamma, v_2, ..., v_n) = \alpha^*(\gamma)\xi(v_1, v_2, ..., v_n) + \\ &v_1\xi(\gamma, v_2, ..., v_n) \\ &\xi(v_1, v_2\gamma, ..., v_n) = \alpha^*(\gamma)\xi(v_1, v_2, ..., v_n) + \\ &v_2\xi(v_1, \gamma, ..., v_n) \end{split}$$

 $\xi(v_1, v_2, \dots, v_n \gamma) = \alpha^*(\gamma)\xi(v_1, v_2, \dots, v_n) + v_n \xi$ (v_1, v_2, \dots, γ), for all $v_1, \gamma, v_2, \dots, v_n \in \mathcal{R}$.

Examples 3.5:

(1) Let \mathcal{F} be a field and let α^* be an antiautomorphism of \mathcal{F} . Assume that

 $\mathcal{R} = \left\{ \begin{pmatrix} a & 0 \\ b & 0 \end{pmatrix} \mid a, b \in \mathcal{F} \right\}, \text{ where } \mathcal{R} \text{ is a non-commutative ring under addition and multiplication of matrices. Define a map } \alpha^* : \mathcal{R} \to \mathcal{R} \text{ as } \begin{pmatrix} a & 0 \\ b & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & \alpha^*(a) \end{pmatrix} \text{ for all } a, b \in \mathcal{F}. \text{ Now let us define a map } \xi: \mathcal{R}^n \to \mathcal{R} \text{ as }$

$$\xi \left(\begin{pmatrix} a_1 & 0 \\ b_1 & 0 \end{pmatrix}, \begin{pmatrix} a_2 & 0 \\ b_2 & 0 \end{pmatrix}, \dots, \begin{pmatrix} a_n & 0 \\ b_n & 0 \end{pmatrix} \right) = \\ \begin{pmatrix} 0 & 0 \\ \alpha^*(a_1)\alpha^*(a_2) \dots \alpha^*(a_n) & 0 \end{pmatrix}$$
for all $\begin{pmatrix} a_1 & 0 \\ b_1 & 0 \end{pmatrix}, \begin{pmatrix} a_2 & 0 \\ b_2 & 0 \end{pmatrix}, \dots, \begin{pmatrix} a_n & 0 \\ b_n & 0 \end{pmatrix} \in \mathcal{R}.$

This means that ξ is a skew left *n*-derivation associated with antiautomorphism α^* , but it is not *n*-derivation.

(2) Let \mathbb{C} be a complex field and let α^* be an antiautomorphism of \mathbb{C} . Assume

that $\mathcal{R} = \left\{ \begin{pmatrix} a & 0 \\ b & 0 \end{pmatrix} \mid a, b \in \mathbb{C} \right\}$, where \mathcal{R} is a noncommutative ring under addition and multiplication of matrices. Define a map $\alpha^* \colon \mathcal{R} \to \mathcal{R}$ as $\begin{pmatrix} a & 0 \\ b & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & \alpha^*(a) \end{pmatrix}$ for all $a, b \in \mathbb{C}$. Now let us define a map $\xi \colon \mathcal{R}^n \to \mathcal{R}$ as $\xi \left(\begin{pmatrix} a_1 & 0 \\ b_1 & 0 \end{pmatrix}, \begin{pmatrix} a_2 & 0 \\ b_2 & 0 \end{pmatrix}, \dots, \begin{pmatrix} a_n & 0 \\ b_n & 0 \end{pmatrix} \right) =$ $\begin{pmatrix} 0 & 0 \\ 0 & \alpha^*(a_1)\alpha^*(a_2) \dots \alpha^*(a_n) \\ b_1 & 0 \end{pmatrix}, \begin{pmatrix} a_2 & 0 \\ b_2 & 0 \end{pmatrix}, \dots, \begin{pmatrix} a_n & 0 \\ b_n & 0 \end{pmatrix} \in \mathcal{R}.$ This means that ξ is a skew left *n*-derivation

associated with antiautomorphism α^* .

In the following results, \mathcal{U} is assumed as an admissible Lie ideal of n!-torsion free ring \mathcal{R} with $n \geq 2$.

Theorem 3.6: Let \mathcal{R} be a prime ring and $\Omega: \mathcal{U}^n \to \mathcal{R}$ be a skew left *n*-derivation associated with an antiautomorphism α^* . If the trace δ of Ω satisfies $[\delta(v), \alpha^*(v)]=0$, for all $v \in \mathcal{U}$ then $\Omega(v_1, v_2, \dots, v_n)=0$, for all $v_i \in \mathcal{U}$ where $i=1,2,\dots,n$.

Proof:

 $\begin{bmatrix} \delta(v), \alpha^*(v) \end{bmatrix} = 0, \forall v \in \mathcal{U} \\ \dots (1)$

Substituting $v=v+\mu\gamma$ in equation (1) and using it and let $\mu(1 \le \mu \le n)$ be any integer, to obtain

 $0 = [\delta(\upsilon + \mu\gamma), \alpha^*(\upsilon + \mu\gamma)] = [\delta(\upsilon) + \delta(\mu\gamma) + \delta(\mu\gamma)] = [\delta(\upsilon) + \delta(\mu\gamma)] = [\delta(\upsilon)] = [\delta(\upsilon) + \delta(\mu\gamma)] = [\delta(\upsilon)] = [\delta(\upsilon) + \delta(\mu\gamma)] = [\delta(\upsilon)] = [\delta(\upsilon)$ $\sum_{s=1}^{n-1} C_s f_s(v, \mu \gamma), \ \alpha^*(v) + \mu \alpha^*(\gamma)]$ $=\mu\{[\delta(v), \alpha^*(\gamma)] +$ $[c_1f_1(v,\gamma), \alpha^*(v)] + \mu^2 \{ [c_2f_2(v,\gamma), \alpha^*(v)] +$ $[c_1 f_1(v, \gamma), \alpha^*(\gamma)] + ... + \mu^n \{ [\delta(\gamma), \alpha^*(v)] +$ $[c_{n-1}f_{n-1}(v,\gamma), \alpha^{*}(\gamma)]\} \dots (2)$ Applying lemma (2.10) to equation (2) $[\delta(v), \alpha^{*}(\gamma)] + [c_{1}f_{1}(v, \gamma), \alpha^{*}(v)] = 0$... (3) Replacing $\gamma = 2\gamma v$ in equation (3), to get $0 = [\delta(v), \alpha^{*}(2\gamma v)] + [c_{1}f_{1}(v, 2\gamma v), \alpha^{*}(v)]$ $=2[\delta(v),\alpha^*(v)]\alpha^*(\gamma)+2\alpha^*(v)[\delta(v),\alpha^*(\gamma)]+$ $2c_1[\alpha^*(v)f_1(v,\gamma),\alpha^*(v)] + 2c_1[\gamma\delta(v),\alpha^*(v)]$ $=2\alpha^{*}(v)\{[\delta(v), \alpha^{*}(\gamma)]+c_{1}[f_{1}(v, \gamma), \alpha^{*}(v)]\}+2$ $c_1[\gamma, \alpha^*(\upsilon)]\delta(\upsilon)$ By using equation (3), the above equation becomes $2c_1[\gamma, \alpha^*(\nu)]\delta(\nu)=0$, using *n*!-torsion free, to have $[\gamma, \alpha^*(v)]\delta(v)=0,$ $\forall v. v \in \mathcal{U}$... (4) Replacing $\gamma = 2\gamma w$ in equation (4), for all $w \in \mathcal{U}$ to have $0=[2\gamma w, \alpha^*(v)]\delta(v)$ $=2[\gamma, \alpha^*(\upsilon)]w\delta(\upsilon)+2\gamma[w, \alpha^*(\upsilon)]\delta(\upsilon)$ By using equation (4) the above equation becomes $[\gamma, \alpha^*(\upsilon)]w\delta(\upsilon)=0$... (5) By using lemma (2.9), $\gamma \rightarrow [\gamma, \alpha^*(v)]$ is a derivation on \mathcal{U} . Then $\delta(v)=0$... (6) Now, for each value $l=1,2,\ldots,n$, let us denote $T_l(v) = \Omega(v, v, \dots, v_{l+1}, v_{l+2}, \dots, v_n), \text{ where } v, v_i \in$ $U, i=l+1, l+2, ..., n. T_n(v)=\delta(v)=0 ... (7)$ Let $\eta(1 \le \eta \le n)$ be any positive integer. From equation (7) to have $0=T_n(\eta v+v_n)=T_n(v_n)+T_n(\eta v)+$ $\sum_{l=1}^{n-1} \eta^l c_l T_l(v) = \delta(v_n) + \eta^n \delta(v) +$ $\sum_{l=1}^{n-1} \eta^l c_l T_l(v) = \sum_{l=1}^{n-1} \eta^l c_l T_l(v) = \eta^1 c_1 T_1(v) +$ $\eta^2 c_2 T_2(v) + \dots + \eta^{n-1} c_{n-1} T_{n-1}(v)$... (8) Applying lemma (2.10) to equation (8) then If $c_1T_1(v)=0$ then $T_1(v)=0$ which implies that $\Omega(v, v_2, v_3, \dots, v_n) = 0$ If $c_2T_2(v)=0$ then $T_2(v)=0$ which implies that $\Omega(v, v, v_3, \dots, v_n) = 0$ If $c_{n-1}T_{n-1}(v)=0$ then $T_{n-1}(v)=0$ which implies that $\Omega(v, v, v, \dots, v_n)=0$ from above, $T_{n-1}(v) = 0$ Hence have we ... (9) Again let $\tau(1 \le \tau \le n - 1)$ be any positive integer. Then from equation (9) to get $0 = T_{n-1}(\tau v + v_{n-1}) = T_{n-1}(\tau v) + T_{n-1}(v_{n-1}) + T_{n \sum_{t=1}^{n-2} \tau^t C_t T_t(v)$ $=\tau^{1}c_{1}T_{1}(v)+\tau^{2}c_{2}T_{2}(v)+\cdots+\tau^{n-2}c_{n-2}T_{n-2}(v)$... (10) Again applying lemma (2.10) to equation (10) then $\Omega(v, v, \dots, v, v_{n-1}, v_n) = T_{n-2}(v) = 0.$... (11)

Continuing the above process, finally we obtain $T_1(v)=0$, then $\Omega(v_1, v_2, v_3, \dots, v_{n-1}, v_n) = 0$... (12) Replacing $v_1 = 2v_1p_1$, where $p_1 \in \mathcal{U}$ in equation (12) to get $0=\Omega(2v_1p_1, v_2, v_3, \dots, v_{n-1}, v_n)=$ $\alpha(p_1) \Omega(v_1, v_2, v_3, \dots, v_{n-1}, v_n) +$ $v_1 \Omega(p_1, v_2, v_3, \dots, v_{n-1}, v_n) =$ $v_1 \Omega(p_1, v_2, v_3, \dots, v_{n-1}, v_n)$... (13) Applying lemma (2.9) to equation (13) to have $\Omega(p_1, v_2, v_3, \dots, v_{n-1}, v_n) = 0, \forall p_1, v_i \in \mathcal{U}.$ Replacing $v_2 = v_2 p_2$, $p_2 \in \mathcal{U}$ in equation (13) to obtain $0=\Omega(p_1, v_2p_2, v_3, \dots, v_{n-1}, v_n)=$ $\alpha(p_2) \Omega(p_1, v_2, v_3, \dots, v_{n-1}, v_n) +$ $v_2\Omega(p_1, p_2, \dots, v_{n-1}, v_n) = v_2\Omega(p_1, p_2, \dots, v_{n-1}, v_n) =$ $\Omega(p_1, p_2, \dots, v_{n-1}, v_n), \forall p_1, p_2, v_i \in \mathcal{U}$ Repeating the above process we finally obtain $\Omega(p_1, p_2, \dots, p_{n-1}, p_n) = 0, \forall p_i \in \mathcal{U}.$ **Theorem 3.7:** Let \mathcal{R} be a semiprime ring and $\Omega: \mathcal{U}^n \to \mathcal{R}$ be a skew left *n*-derivation associated with an antiautomorphism α^* . If the trace δ of $\Omega \delta$ is commuting on \mathcal{U} and $[\delta(v), \alpha^*(v)] \in \mathcal{Z}(\mathcal{R})$, then $[\delta(v), \alpha^*(v)] = 0$ for all $v \in \mathcal{U}$. **Proof:** $[\delta(v), \alpha^*(v)] \in \mathcal{Z}(\mathcal{R}), \forall v \in \mathcal{U}.$... (1) Substituting $v=v+\mu\gamma$ in equation (1) and using it $\mu(1 \le \mu \le n)$ be any integer, then and let $\mathcal{Z}(\mathcal{R}) \ni [\delta(\upsilon + \mu \gamma), \alpha^*(\upsilon + \mu \gamma)]$ = $[\delta(v)+\delta(\mu\gamma)+\sum_{s=1}^{n-1}C_sf_s(v,\mu\gamma), \alpha^*(v)+$ $\mu \alpha^*(\gamma)$] = $[\delta(v), \alpha^*(v)] + \mu\{[\delta(v), \alpha^*(\gamma)] +$ $[c_1 f_1(v, \gamma), \alpha^*(v)] + \mu^2 \{ [c_2 f_2(v, \gamma), \alpha^*(v)] +$ $[c_1f_1(v,\gamma),\alpha^*(\gamma)]\}+...+\mu^n\{[\delta(\gamma),\alpha^*(v)]+$ $[c_{n-1}f_{n-1}(v,\gamma), \alpha^{*}(\gamma)] + \mu^{n+1}[\delta(\gamma), \alpha^{*}(\gamma)] \dots (2)$ Commuting equation (2) with $\delta(v)$, to have $[[\delta(v), \alpha^*(v)], \delta(v)] + \mu\{[[\delta(v), \alpha^*(\gamma)] +$ $[c_1 f_1(v, \gamma), \alpha^*(v)], \delta(v)] +$ $\mu^{2}\{[c_{2}f_{2}(v,\gamma),\alpha^{*}(v)] +$ $[c_1 f_1(v, \gamma), \alpha^*(\gamma)], \delta(v)]$ + … + $\mu^n\{[\delta(\gamma), \alpha^*(v)] +$ $[c_{n-1}f_{n-1}(v,\gamma),\alpha^*(\gamma)],\delta(v)]\}$ $+\mu^{n+1}[[\delta(\gamma), \alpha^*(\gamma)], \delta(v)]=0$... (3) Applying lemma (2.10) to equation (3), then $0 = [[\delta(v), \alpha^{*}(\gamma)], \delta(v)] + [[c_{1}f_{1}(v, \gamma), \alpha^{*}(v)], \delta(v)]$... (4) Replacing $\gamma = 2v^2$ in equation (4), to obtain $0 = [[\delta(v), \alpha^*(2v^2)], \delta(v)]$ + $[[c_1 f_1(v, 2v^2), \alpha^*(v)], \delta(v)]$ =[[$\delta(v), \alpha^*(v)$], $\delta(v)$] $\alpha^*(v)$ + $[\delta(v), \alpha^*(v)][\alpha^*(v), \delta(v)] +$ $[\alpha^*(v), \delta(v)][\delta(v), \alpha^*(v)] +$ $\alpha^*(v)[[\delta(v),\alpha^*(v)],\delta(v)]+$ $c_1[\alpha^*(v),\delta(v)][\delta(v),\alpha^*(v)]+$

 $c_1 \alpha^*(v) [[\delta(v), \alpha^*(v)], \delta(v)] +$ $c_1[[v, \alpha^*(v)], \delta(v)]\delta(v) + c_1[v, \alpha^*(v)][\delta(v), \delta(v)] +$ $c_1[v, \delta(v)][\delta(v), \alpha^*(v)] + c_1v[[\delta(v), \alpha^*(v)], \delta(v)]$ $-(c_1+2)[\delta(v), \alpha^*(v)]^2 + c_1[[v, \alpha^*(v)], \delta(v)] \delta(v)$ $=-(c_1+2)[\delta(v),\alpha^*(v)]^2+c_1[\{v\alpha^*(v) \alpha^*(v)v$, $\delta(v)$] $\delta(v)$ $= -(c_1 + 2)[\delta(v), \alpha^*(v)]^2 + c_1[v, [\alpha^*(v), \delta(v)]]\delta(v)$ $=(c_1+2)[\delta(v),\alpha^*(v)]^2$... (5) Commuting equation (2) with $\alpha^*(v)$ and by using lemma (2.10), then 0 = $[[\delta(v), \alpha^{*}(\gamma)], \alpha^{*}(v)] + [c_{1}f_{1}(v, \gamma), \alpha^{*}(v)], \alpha^{*}(v)]$... (6) Replacing $\gamma = 2\gamma v$ in equation (6), to obtain $0 = [[\delta(v), \alpha^*(2\gamma v)] + [c_1 f_1(v, 2\gamma v), \alpha^*(v)], \alpha^*(v)]$ = $[\delta(v), \alpha^*(v)], \alpha^*(v)]\alpha^*(\gamma)+$ $[\delta(v), \alpha^*(v)][\alpha^*(\gamma), \alpha^*(v)]+$ $[\alpha^*(v), \alpha^*(v)] [\delta(v), \alpha^*(\gamma)] +$ $\alpha^*(v) \left[\left[\delta(v), \alpha^*(\gamma) \right], \alpha^*(v) \right] +$ $c_1[\alpha^*(v), \alpha^*(v)][f_1(v, \gamma), \alpha^*(v)] +$ $c_1 \alpha^*(v) [[f_1(v, \gamma), \alpha^*(v)], \alpha^*(v)] +$ $c_1[[\gamma, \alpha^*(\upsilon)], \alpha^*(\upsilon)]\delta(\upsilon) +$ $c_1[\gamma, \alpha^*(v)][\delta(v), \alpha^*(v)]+$ $c_1[\gamma, \alpha^*(\upsilon)][\delta(\upsilon), \alpha^*(\upsilon)] +$ $c_1 \gamma [[\delta(v), \alpha^*(v)], \alpha^*(v)]$ =[$\delta(v), \alpha^*(v)$][$\alpha^*(\gamma), \alpha^*(v)$]+ $\alpha^*(\upsilon)\{[\delta(\upsilon), \alpha^*(\gamma)], \alpha^*(\upsilon)] +$ $c_1[[f_1(v,\gamma),\alpha^*(v)],\alpha^*(v)]+$ $c_1[[\gamma, \alpha^*(v)], \alpha^*(v)]\delta(v) +$ $2c_1[\gamma, \alpha^*(v)][\delta(v), \alpha^*(v)]$ By using equation (6), the last equation becomes $[\delta(v), \alpha^*(v)][\alpha^*(\gamma), \alpha^*(v)]+$ $c_1[[\gamma, \alpha^*(\upsilon)], \alpha^*(\upsilon)]\delta(\upsilon) +$ $2c_1[\gamma, \alpha^*(v)][\delta(v), \alpha^*(v)]=0...(7)$ Replacing $\gamma = \delta(v)[\delta(v), \alpha^*(v)]$ in equation (7), to get $0 = [\delta(v), \alpha^*(v)][\alpha^*(\delta(v)[\delta(v), \alpha^*(v)]), \alpha^*(v)] +$ $c_1[[\delta(v)][\delta(v), \alpha^*(v)], \alpha^*(v)], \alpha^*(v)]\delta(v) +$ $2c_1[\delta(v)[\delta(v),\alpha^*(v)],\alpha^*(v)][\delta(v),\alpha^*(v)]$ $= [\delta(v), \alpha^*(v)][\alpha^*[\delta(v), \alpha^*(v)]\alpha^*(\delta(v)), \alpha^*(v)] +$ $c_1[[\delta(v), \alpha^*(v)]^2 +$ $\delta(v)[[\delta(v), \alpha^*(v)], \alpha^*(v)], \alpha^*(v)]\delta(v) +$ $2c_1[\delta(v), \alpha^*(v)]^3 +$ $2c_1\delta(v)[[\delta(v),\alpha^*(v)],\alpha^*(v)][\delta(v),\alpha^*(v)]$ $= [\delta(v), \alpha^*(v)] \alpha^* [[\delta(v), \alpha^*(v)], v] \alpha^*(\delta(v)) +$ $[\delta(v), \alpha^*(v)]\alpha^*[\delta(v), \alpha^*(v)] + \alpha^*[\delta(v), v] +$ $2c_{1}[\delta(v), \alpha^{*}(v)]^{3}$ $=2c_1[\delta(v), \alpha^*(v)]^3$... (8) Then $2c_1[\delta(v), \alpha^*(v)]^2 \mathcal{U} 2c_1[\delta(v), \alpha^*(v)]^2 = 0$ Since \mathcal{R} is a semiprime, then $2c_1[\delta(v), \alpha^*(v)]^2=0$, for all $v \in U$... (9) Combining equation (5) and (9), we have

 $[\delta(v), \alpha^*(v)]^2 = 0$, for all $v \in \mathcal{U}$

As the center of the semiprime ring contains no non-zero nilpotent elements, then we have $[\delta(v), \alpha^*(v)]=0, \forall v \in \mathcal{U}.$

Theorem 3.8: Let \mathcal{R} be a prime ring and $\Omega: \mathcal{U}^n \to \mathcal{R}$ be a non-zero skew left *n*-derivation associated with an antiautomorphism α^* . If the trace δ of Ω is commuting on \mathcal{U} and $[\delta(v), \alpha^*(v)] \in \mathcal{Z}(\mathcal{R})$ for all $v \in \mathcal{U}$, then \mathcal{U} must be commutative.

Proof:

Suppose that \mathcal{U} is anon commutative prime ring. From theorem (3.7), we have $[\delta(v), \alpha^*(v)]=0$ for all $v \in \mathcal{U}$. And from theorem (3.6) we have $\Omega=0$ which is contradiction hence, \mathcal{U} is commutative prime ring.

Conflicts of Interest: None.

References:

- 1. Herstein IN. Topics in Ring Theory. The University of Chicago Press. Chicago. 1969.
- 2. Park KH. On prime and semiprime rings with symmetric n-derivations. J.Chungcheong Math.Soc. 2009 Sep; 22 (3): 451-458.
- Yadav VK, Sharma RK. Skew n-derivations on prime and semi prime rings. Ann.Univ.Ferrara. 2016 Sep. 1-12.
- 4. Posner EC. Derivations in Prime Rings. Proc. Amer. Math.Soc. 1957 Dec; 8(6): 1093-1100.

- Xiaowei X, Yang L, Wei Z. Skew n-derivations on semiprime rings. Bull. Korean Math. Soc. 2013.50 (6): 1863–1871.
- Bresar M, Vukman J. On left derivations and related mappings. Proc. Amer. Math. So. 1990. 110 (1): 7-16.
- 7. Chuijia W, Xiaowei X, Xiaofei Y. Generalized skew left derivations characterized by acting on zero products. Int. J. Algebra. 2012. 6 (18): 881-884.
- Divinsky N. On commuting automorphisms on rings. Trans. Roy. Soc. Canada, Sec.III, 1955. 49: 19–22.
- Vukman J. Symmetric bi-derivations on prime and semiprime rings. Aequationes Math. 1989 June; 38 (2-3): 245-254.
- Jung YS, Park KH. On prime and semiprime rings with permuting 3-derivation. Bull. Korean. Math. Soc. 2007. 44 (4): 789-794.
- Faraj AK, Shareef SJ. Generalized permuting 3derivations of prime rings. Iraqi J. Sci., 2016.57 (3C): 2312-2317.
- 12. Faraj AK, Shareef SJ. Jordan permuting 3-derivations of prime rings. Iraqi J. Sci., 2017.58 (2A): 687-693.
- Faraj AK. Shareef SJ. On generalized permuting left 3-derivations of prime rings. Eng. and Tech. Journal. 2017. 35 Part B (1).
- 14. Reddy CJ, Kumar SV, Rao SM. Symmetric skew 4derivations on prime rings. Global Jr. of pure and appl. Math. 2016. 12 (1): 1013-1018.
- 15. Fosner A. Prime and semiprime rings with symmetric skew 3-derivations. Aequat. Math. 2014. 87: 191-200.

حول مشتقات الالتواء اليسارية من النمط n مع تركيبة مثالى لى

رقية سعدى هاشم

انوار خليل فرج

*قسم العلوم التطبيقية، الجامعة التكنولوجية، بغداد، العراق

الخلاصة:

n في هذا البحث درست التمركزات و التباديل لمشتقات الالتواء اليسارية من النمط n و كذلك مشتقات الالتواء اليسارية من النمط n المرتبطة مع ضد التشاكلات التقابلية للحلقات الاولية وتم بر هنة ابدالية مثالي لي تحت شروط معينة.

الكلمات المفتاحية: دالة التمركز، دالة التباديل، حلقة اولية، مشتقة الالتواء اليسرى من المعيار n.