# Using Bernoulli Equation to Solve Burger's Equation 

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#### Abstract

: In this paper we find the exact solution of Burger's equation after reducing it to Bernoulli equation. We compare this solution with that given by Kaya where he used Adomian decomposition method, the solution given by chakrone where he used the Variation iteration method (VIM)and the solution given by Eq(5)in the paper of M . Javidi. We notice that our solution is better than their solutions.


Key words: Burger's equation, kdv equation, PDF.

## 1. Introduction:

We consider the following Burger's equation

$$
u_{t}+u u_{x}-\lambda u_{x x}=0
$$

Where $\boldsymbol{\lambda}$ is positive parameter
This equation arises in various areas of science. Equation (1.1) has been used in the study of the propagation through liquid-filled elastic tube[1].and description for shallow water waves on a viscous fluid [2].Equation(1.1)is used as a model for traffic flow [3].Many Researchers had proposed various kinds of exact and numerical solution [4,5,6,7,8,9,10] where they used Adomian decomposition method, variation iteration method, Galerkin method.

## 2. Derivation of Burger's equation.[9]

We recall the differential form of the nonlinear conservation equation
$\frac{\partial \mathrm{p}}{\partial \mathrm{t}}+\frac{\partial \mathrm{q}}{\partial \mathrm{x}}=0$
To investigate the nature of the discontinuous solution or shock waves, we assume a function relation
$q=Q(p)$ and allow a jump discontinuity for p and q .
In many physical problems of interest it would be a better approximadtioh to assume that q is a function of the density gradient $p_{x}$ as well as p.A simple model is to take
$\mathrm{q}=\mathrm{Q}(\mathrm{p})-v \mathrm{p}_{\mathrm{x}}$
Where $v$ is a positive constant .Substituting (2.2) into (2.1), we obtain the nonlinear diffusion equation

$$
p_{t}+c(p) p_{x}=v p_{x x}
$$

Where,
$\mathrm{c}(\mathrm{p})=\mathrm{Q}^{\prime}(\mathrm{p})$
We multiply (2.3) by $\mathrm{c}^{\prime}(\mathrm{p})$ to obtain

$$
c^{\prime}(p) p_{t}+c(p) c^{\prime}(p) p_{x}=v c^{\prime}(p) p_{x x}
$$

Hence:
$c_{t}+c_{x}=v c^{\prime}(p) p_{x x}$

And therefore:
$\left.c_{t}+c_{z}=v_{c}^{\prime}(p)\right)_{x_{z K}}=c_{x_{X X}}-c^{\prime \prime}(p) p_{x}^{2}$
If $Q(p)$ is a quadratic (2.1) function in $p$,then $c(p)$ is linear in $p$, ande $^{\prime \prime}(\mathrm{p})=0$.
Consequently (2.4) becomes

[^0]$c_{t}+c_{x}=v c_{x x}$
As a simple model of turbulence, $c$ is replaced by the fluid velocity field $\mathrm{u}(\mathrm{x}, \mathrm{t})$ to obtain the well-known Burgers equation as
$\mathrm{u}_{\mathrm{t}}+\mathrm{uu} \mathrm{u}_{\mathrm{x}}=\mathrm{vu}_{\mathrm{xx}}$

Where $v$ is the kinematic viscosity.Thus,the Burgers equation is a balance between time evaluation, nonlinearity and diffusion.

## 3. Solution of Burger's

## equation.

To solve Burger's equation (1.1), we can assume the solution $u(x, t)=v(z)$
Where
$z=x-\lambda t$
$-v$ is called the travelling wave solution-Substituting (3.1) into (1.1) becomes
$v_{z z}=\left(\frac{v}{\lambda}-1\right) v_{z}$
Rewrite (3.2) as a system of first order O.D.E's

Let
$r_{1}=v$
$r_{2}=v_{z}$
Where $r_{1}, r_{2}$ represent the velocity and a acceleration respectively.
Then
$r_{1}^{\prime}=v=r_{2}$
$r_{2}^{\prime}=v_{z z}=\left(\frac{r_{1}}{\lambda}-1\right) r_{2}$
This system has an infinite number of equilibrium points which is
$\mathrm{r}_{1}$-axis
To solve (3.4) divide the two equations to get
$\frac{\mathrm{dr}_{2}}{\mathrm{dr}_{1}}=\frac{\mathrm{r}_{1}}{\lambda}-1$
i.e.

$$
\mathrm{dr}_{2}=\left(\frac{r_{1}}{\lambda}-1\right) \mathrm{d} r_{1}
$$

$r_{2}=\frac{r_{1}^{2}}{2 \lambda}-r_{1}+c$
Where c is an arbitrary constant.
Hence, from (3.3) we get
$v_{z}+v=\frac{v^{2}}{2 \lambda}+c$
Now, let
$\mathrm{w}=\mathrm{v}+\mathrm{k}$
[In order to eliminate c from equation (3.5)] substituting (3.6) into (3.5)
becomes
$w_{z}+w-k=\frac{(w-k)^{2}}{2 \lambda}+c$
i.e.
$w_{z}+\left(1+\frac{k}{\lambda}\right) w=\frac{w^{2}}{2 \lambda}+\frac{k^{2}}{2 \lambda}+k+c$

Let $\frac{k^{2}}{2 \lambda}+k+c=0$ to get
$\mathrm{k}=-\lambda \mp \sqrt{\lambda^{2}-2 \lambda c}$
Then (3.7) becomes
$w_{z}+\left(1-\frac{k}{\lambda}\right) w=\frac{w^{2}}{2 \lambda}$

Notice that equation (3.9) represents
Bernoulli equation. To solve it Suppose
$\eta=w^{-1} \rightarrow \eta_{z}=-w^{-2} w_{z}$
Substituting (3.10) int 63 34. 9 )
$\mathrm{w}^{-2} \mathrm{w}_{\mathrm{z}}+\left(1+\frac{\mathrm{k}}{\lambda}\right) \mathrm{w}^{-1}=\frac{1}{2 \lambda}$
We get
$\eta_{z}-\left(1+\frac{k}{\lambda}\right) \eta=\frac{-1}{2 \lambda}$

This equation is first-order linear differential equation, its integrating factor is
$I(z)=e^{-\left(1+\frac{k}{\lambda}\right)} z$
And its solution is gives by
$\eta I=\frac{1}{2(\lambda+\kappa)} e^{-\left(\frac{k}{\lambda}+1\right) z}+\alpha$
Where $\alpha$ is an arbitrary constant so,
$\eta=\left(\frac{1}{2(\lambda+k)}+\alpha e^{\left(1+\frac{k}{\lambda}\right) z}\right.$

From (3.10), we get the solution of Bernoulli equation (3.9)
$w(z)=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha e^{\left(1+\frac{k}{\lambda}\right) z}}$
By using (3.6) and (3.11)
Now, from (3.6) $v=w-k$ so the traveling wave solution (3.1) becomes
$\mathrm{u}(\mathrm{x}, \mathrm{t})=\mathrm{v}(\mathrm{z})=\mathrm{w}(\mathrm{z})-\mathrm{k}$
$u(x, t)=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha e^{\left(1+\frac{k}{\lambda}\right)(x-\lambda t)}}-k$
Where k is given in (3.8) and $\alpha$ is an arbitrary constant where
$\mathrm{k}=-\lambda \mp \sqrt{\lambda^{2}-2 \lambda \mathrm{c}}$ And
$\alpha, c$ are arbitrary constants.

## 4. The solution of Burger's

## equation with Dirichlet

## conditions.

From (3.12) the solution of Burger's equation is
$u(x, t)=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha e^{\left(1+\frac{k}{\lambda}\right)(x-\lambda t)}}-k$
Dirichlet conditions are
$\mathrm{BC} 1: \mathrm{u}(0, \mathrm{t})=\mathrm{g}(\mathrm{t})$
$0 \leq t \leq t_{1}$
$\mathrm{BC} 2: \mathrm{u}(1, \mathrm{t})=\mathrm{h}(\mathrm{t})$
Clearly u (0, 0) =0 (stationary case)
$\mathrm{BC} 1 \rightarrow$
$u(x, t)=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha e^{-\left(1+\frac{k}{\lambda}\right) t}}-k=g(t)$
BC2 $\rightarrow$
$\mathrm{u}(\mathrm{x}, \mathrm{t})=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha \mathrm{e}^{\left(1+\frac{k}{\lambda}\right)(1-\lambda \mathrm{t})}}-\mathrm{k}=\mathrm{h}(\mathrm{t})$
$u(0,0)=0 \rightarrow$
$\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha}-k=0$
Therefore,
$\alpha=\frac{1}{\mathrm{k}}-\frac{1}{2(\lambda+\mathrm{k})}=\frac{2 \lambda+\mathrm{k}}{2(\lambda+\mathrm{k}) \mathrm{k}}$
Remember that from (3.8)
$\mathrm{k}=-\lambda \mp \sqrt{\lambda^{2}-\lambda c}$
And from (4.2)
$h(0)=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha e^{\left(1+\frac{k}{\lambda}\right)}}-k$

From which we get
$\alpha=\left[\frac{1}{h(0)+k}-\frac{1}{2(\lambda+k)}\right] e^{\frac{-(\lambda+k)}{\lambda}}$

From(4.3) and (4.4)we
determine $\alpha$ and $c$
After determining these constants we
find the solution of Burger's equation with Dirichlet conditions.
As a special case let $\lambda=2$ and $c=0.75$ then from (3.8) we get
$\mathrm{k}=-3$ or -1
And from (4.3) we get
$\alpha=\frac{1}{6}$ if $\mathrm{k}=-3$
Or
$\alpha=\frac{-3}{2}$ if $k=-1$

## Case

$\underline{\underline{1}}: \lambda=2, c=0.75, k=-3, \alpha=\frac{1}{6}$

$$
\mathrm{u}(\mathrm{x}, \mathrm{t})=\frac{1}{\frac{-1}{2}+\frac{1}{6} \mathrm{e}^{-0.5(\mathrm{x}-2 \mathrm{t})}}+3
$$

## Case2:

$\overline{\lambda=2, c}=0.75, k=-1, \alpha=\frac{-3}{2}$
$\mathrm{u}(\mathrm{x}, \mathrm{t})=\frac{1}{\frac{1}{2}-\frac{3}{2} \mathrm{e}^{0.5(\mathrm{x}-2 \mathrm{t})}}+1$
The graphs of (4.5),(4.6) are in figures (1) and(2) respectively.
The two shapes have the same qualitative behavior but quantitavely different.

## 5.Comparison.

- The solution of this equation obtained by Kaya
$u(x, t)=\frac{\left(\alpha+\beta+(\beta-\alpha) e^{(\phi)}\right)}{\left(1+e^{(t)}\right)}$
Where $\zeta=\frac{a}{v}(x-\beta t-\eta)$ where is not easier than our solution.
- The solution obtained by Omar is approximated
solution, while our solution is exact solution.
- The solution obtained by Javidi

$$
u(x, t)=\frac{\left(0.1 e^{-A}+0.5 e^{-B}+e^{-C}\right)}{\left(e^{-A}+e^{-B}+e^{-C}\right)}
$$

Where,
$\mathrm{A}=\frac{0.05}{\mu}(x-0.5+4.95 t)$,
$B=\frac{0.05}{\mu}(x-0.5+0.75 t)$ and
$\mathrm{C}=\frac{0.05}{\mu}(\mathrm{x}-0.5+0.375 \mathrm{t})$
Clearly our solution is easier than his solution.
when

$$
\begin{array}{lll} 
& \alpha=-1.72, & \lambda=0.1 \\
, \mathrm{k}=0.2, \mathrm{c}=0 & (4.5) &
\end{array}
$$

in the solution function
$u(x, t)=\frac{1}{\frac{1}{2(\lambda+\kappa)}+\alpha e^{\left(1+\frac{k}{\lambda}\right)(x-\lambda, t)}}-k$
where $t=[0: 0.1: 0.4], x=[-10: 5: 10]$
This figure classifies the wave at the beginning of the earth quake.


Case 1: $\lambda=2, c=0.75, k=-3, \alpha=\frac{1}{6}$


Fig.-1-

Case2: $\lambda=2, c=0.75, k=-1, \alpha=\frac{-3}{2}$


Fig.-2-

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حصلنا من بحثنا هذا على الحل المضبوط (Exact) لمعادلة بيركر بعد تحويلها إلى معادلة برنو لي وتمت مقارنة هذا الحل مع حل "Kaya"الذي استخدم طريقة تجزئة ادومين وحل "Chakrone" الذي أستخدم طريقة التغاير المتكرر وحل "Javidi" المعطى بالعلاقة (5)وتبين ان حلنا هذا افضل من حلولهم للبساطه الصيغة


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