

## Scalable parallel rank order filters

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## Scalable Parallel Rank Order Filters

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February 26, 2007

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## Chapter 1

## Introduction

Rank order filters are non-linear filters used in a wide range of applications. The median filter is perhaps the most common of the rank order filters. It can be used to remove noise from a signal while preserving edge information (see Figure 1.1), which is something that linear filters cannot do. This makes the median filter a popular filter in speech and image processing applications.



Figure 1.1: Median filtering

Rank order filters work by sorting a window of inputs and selecting the input with a certain rank as the output. In the case of the median filter the element with the middle rank is selected, hence the name (although it is called a speckle filter in some applications, after the type of noise it removes). Other common rank order filters are the minimum and maximum filter, selecting respectively the input with the lowest and highest rank from the window. In image processing applications these minimum and maximum filters are sometimes also called dilation and erosion filters, because they make dark regions in an image respectively larger or smaller, as shown in Figure 1.2.

Rank order filters take a lot of processing power to implement, a lot more than the well-known linear filters. This is why rank order filters are rarely used in real-time signal processing applications. However, just like linear filters, rank order filters can benefit from parallelism. If enough parallelism is available any



(a) Logo after a  $7 \times 7$  dilation/minimum filter

(c) Logo after a 7 sion/maximum filter

Figure 1.2: Minimum and maximum filtering

desirable throughput can be achieved.

In this report we take a look at rank order filters and implement them in an efficient, parallel fashion such that the throughput of the implementation scales linearly with the amount of parallelism. What constitutes as "the amount of parallelism" depends on the implementation method used. When implementing the filter in hardware, as a VLSI circuit, the amount of parallelism would be the number of components used. When implementing the filter in software on a SIMD processor, the amount of parallelism is determined by the number of processing elements of the SIMD processor.

Implementing the filters in such a manner that the throughput scales linearly with the amount of parallelism is quite trivial. The calculations for the outputs of the filter have constant complexity and are independent of each other, therefore unlimited parallelism can be achieved. However, more efficient implementations are possible; the calculations of successive outputs have enough in common to allow the reuse of sub-calculations, thereby increasing efficiency. By exploiting this reuse we are be able to find the most efficient implementations to date.

The implementation of rank order filters clearly requires some form of sorting. To make practical implementation possible we resort to so-called oblivious sorting algorithms. Oblivious sorting algorithms always perform the same number of operations in the same order, regardless of the data that has to be sorted. The well-known quick-sort algorithm, for example, is not an oblivious algorithm, whereas another well-known sorting algorithm, namely merge sort, is oblivious. We choose oblivious sorting algorithms because they are especially suited both for implementation on SIMD processors, since there is no data-dependency in the execution path, and for hardware implementation, since there is no overhead in the form of control logic.

In the literature there are already a number of parallel designs available for both hardware [2, 3, 9] and SIMD [8] implementations, but we improve upon all of them. The most important contributions described in this report, however, are the optimizations that can be applied to existing filters and the mathematical framework in which the design problem, and its solutions, can be described. We introduce these contributions the following manner. First we formally define the problem of designing the implementation of a rank order filter in Chapter 2. In Chapter 3 we introduce the so-called calculation graph as an abstract representation of the calculations performed by a rank order filter based on oblivious sorting networks. Since a filter calculates (theoretically) infinitely many outputs, the associated calculation graph is also infinite. However, a calculation graph has regularities and in Chapter 4 we introduce generator graphs which are finite, yet still describe an entire calculation graph. The design of the filter implementation can be read from such a generator graph, but a suitable generator graph has to be found first, which is the subject of Chapter 5. In Chapter 6 we compare our designs with those found in the literature. The practical issues that arise when a design is turned into an actual implementation are discussed in Chapter 7. And finally, there is the conclusion in Chapter 8.

## Chapter 2

## **Problem Description**

The problem we address in this report is that of constructing efficient, scalable parallel implementations of rank order filters. We will not limit ourselves to filters that determine a single rank, but allow filters that produce a range of ranks as output.

For implementing rank order filters we use oblivious sorting methods, since the absence of data dependencies facilitates the implementation on SIMD machines and in VLSI circuits.

The outline of this chapter is as follows. The next section introduces a rigorous mathematical formulation of the problem and Section 2.2 gives the complexity measure by which we can judge the various algorithms used to solve the problem.

#### 2.1 Mathematical Definition

A common property of filter applications is that the data to be filtered is organized in some underlying structure. For each location of this structure a filtered value has to be determined based on the original data item at that location and on the values of data items in some finite neighborhood. The precise way in which such a filter operates is given by its kernel, which describes both the structure of the neighborhood and the contribution of the individual values in that neighborhood to the resulting value.

In this report we restrict ourselves to very simple underlying structures, viz. to grid topologies. So, for D > 0, let  $\mathbb{Z}^D$  be a *D*-dimensional grid with integral coordinates. The notion of a neighborhood is captured by a tile which is nothing but a finite set of grid locations. The size of a tile  $\mathbf{T} \in \mathbb{P}(\mathbb{Z}^D)$  is the number of grid locations in  $\mathbf{T}$  and is denoted by  $|\mathbf{T}|$ . We say that two tiles  $\mathbf{S}$  and  $\mathbf{T}$  have an equivalent shape when there exists a translation vector  $\mathbf{t} \in \mathbb{Z}^D$  such that  $\mathbf{T} = \mathbf{S} + \mathbf{t}$  with tile  $\mathbf{S} + \mathbf{t}$  defined as  $\{\mathbf{s}+\mathbf{t} \mid \mathbf{s} \in \mathbf{S}\}$ . Note that tiles that differ by a rotation are *not* considered equivalently shaped. In the sequel we will be interested in sets of tiles with equivalent shapes, laid out in repetitive patterns. So we define the function  $\mathtt{tile} : (\mathbb{P}(\mathbb{Z}^D) \times \mathbb{Z}^D \times \mathbb{Z}^D) \to \mathbb{P}(\mathbb{P}(\mathbb{Z}^D))$  given by:

$$tile(\mathbf{S}, \mathbf{f}, \mathbf{p}) = \{\mathbf{S} + \mathbf{f} + \mathbf{g} \cdot \mathbf{p} \mid \mathbf{g} \in \mathbb{Z}^D\}$$
(2.1)

In this definition the dot-operator "." stands for coordinate-wise vector multi-



Figure 2.1: The tiles generated by  $tile(\{(0,0), (1,0), (0,1)\}, (1,2), (4,3))$ 

plication. Function tile produces an infinite number of copies of tile **S** that are spread over the entire grid in a periodic fashion, as illustrated in Figure 2.1. We call **S** the *shape*, **f** the *phase*, and **p** the *period* of the resulting tile set. When a tile set  $\mathcal{T}$  can be described by the function tile, we use the triple  $(\mathbf{S}_{\mathcal{T}}, \mathbf{f}_{\mathcal{T}}, \mathbf{p}_{\mathcal{T}})$ to describe it (i.e.  $\mathcal{T} = \texttt{tile}(\mathbf{S}_{\mathcal{T}}, \mathbf{f}_{\mathcal{T}}, \mathbf{p}_{\mathcal{T}})$ ). Note that this triple is not unique, since  $\texttt{tile}(\mathbf{S}_{\mathcal{T}} + k\mathbf{f}_{\mathcal{T}}, (1-k)\mathbf{f}_{\mathcal{T}}, \mathbf{p}_{\mathcal{T}})$  generates the same tile set for every  $k \in \mathbb{Z}$ .

We also introduce the two basic vectors  $\mathbf{0}_D$  and  $\mathbf{1}_D$ . These two vectors are of length D and contain only zeroes or ones respectively. Using these vectors we can construct such functions as:

$$hypercube(k, D) = \{ \mathbf{g} \mid \mathbf{g} \in \mathbb{Z}^D \land -k\mathbf{1}_D \le \mathbf{g} \le k\mathbf{1}_D \}$$
(2.2)

In this definition the relationship " $\leq$ " stands for coordinate-wise comparison, and the relationship " $\leq$ " only holds for the entire vector when it holds for all of it elements. The function hypercube therefore produces a tile centered on the origin, with a volume of  $(2k + 1)^D$ , i.e. a hypercube in D dimensions.

Let  $\mathbb{D}$  be a domain of data values. The precise nature of the elements of  $\mathbb{D}$  is irrelevant apart from the fact that they can be ordered according to some linear order  $\preceq$ . Furthermore, let data :  $\mathbb{Z}^{D} \to \mathbb{D}$  be a function that associates a data value with each grid location, i.e. data(g) is the value at grid location  $\mathbf{g} \in \mathbb{Z}^{D}$ . Denoting the sorted list of data elements of  $\mathbf{T}$  by  $\overline{\mathbf{T}}$  we can indicate the data element of rank i of  $\mathbf{T}$  by  $\overline{\mathbf{T}}(i)$  and the sorted sublist of elements with ranks ranging from l up to and including u with  $\overline{\mathbf{T}}[l..u]$ .

With these preliminaries done, we can define what we consider to be a rankorder filter.

**Definition 2.1.1** (Rank order filter (ROF)). A rank order filter is an algorithm parameterized by

- a number  $D \in \mathbb{N}^+$  that specifies the dimension of the grid,
- a set of similar shaped tiles, called windows  $\mathcal{W} = \mathsf{tile}(\mathbf{S}_{\mathcal{W}}, \mathbf{f}_{\mathcal{W}}, \mathbf{p}_{\mathcal{W}})$ ,
- two numbers l and u such that  $0 \le l \le u < |\mathbf{S}_{\mathcal{W}}|$ .

Given an arbitrary function data :  $\mathbb{Z}^D \longrightarrow \mathbb{D}$ , the rank order filter determines for each  $\mathbf{W} \in \mathcal{W}$  the sorted list  $\overline{\mathbf{W}}[l..u]$ , that is the elements of  $\mathbf{W}$  with ranks ranging from l up to and including u.  $\Box$ 

Note that most rank order filters are designed for a specific value or range of values for the parameters D, W, l and u. An image processing application, for example, only needs 2-dimensional rank order filters (D = 2). Also, in most cases we have l = u, i.e. rank order filters that select one specific rank. However, the definition above also includes so-called window sorters (l = 0 and  $u = |\mathbf{S}_W|$ ) and other intermediate problems which will be useful in designing rank order filters.

Some special cases of rank order filters are:

The 1-D median filter with window size 2K + 1:

- The number of dimensions is D = 1
- The input signal is represented by the data function
- The shape of the windows is  $\mathbf{S}_{\mathcal{W}} = \text{hypercube}(K, D)$
- The windows themselves are given by  $\mathcal{W} = \mathtt{tile}(\mathbf{S}_{\mathcal{W}}, 1, 0)$
- We are interested in the item with rank K, hence l = u = K

The 2-D median filter with kernel size  $(2K + 1) \times (2K + 1)$ :

- The number of dimensions is D = 2
- The input image is represented by the data function
- The shape of the windows is  $\mathbf{S}_{\mathcal{W}} = \text{hypercube}(K, D)$
- The windows themselves are given by  $\mathcal{W} = \texttt{tile}(\mathbf{S}_{\mathcal{W}}, (1, 1), (0, 0))$
- We are interested in the item with rank  $2K^2 + 2K$ , hence  $l = u = 2K^2 + K$

Note that the function tile produces an infinite set. In practice the set of windows for a rank order filter is finite. However, for now we will assume the set of windows to be infinite, and save this aspect of practical implementation for Section 7.3.

Using the definition of a rank-order filter we can define what we consider to be a rank-order filter design problem.

**Definition 2.1.2** (Rank order filter design problem (ROFDP)). Assume that we are given

- a number  $D \in \mathbb{N}^+$  that specifies the dimension of the filter,
- a set of similar shaped tiles, called windows  $\mathcal{W} = \mathsf{tile}(\mathbf{S}_{\mathcal{W}}, \mathbf{f}_{\mathcal{W}}, \mathbf{p}_{\mathcal{W}}),$
- two numbers l and u such that  $0 \le l \le u < |\mathbf{S}_{\mathcal{W}}|$ .

Design a rank order filter for these parameters.  $\Box$ 

To solve this problem and to find an algorithm that calculates the rank [l..u] elements of every window in an oblivious manner, we will need some form of sorting network. However, the optimum networks for sorting lists of arbitrary size are unknown. We only know good instances when it comes to minimum-comparison sorting networks [7]. Therefore we are content to resort to heuristic methods to find the implementations of rank order filters.

#### 2.2 Complexity measure

The elementary operation of oblivious sorting is a so-called compare and swap (C&S) operation. This operation effectively sorts a list of two inputs by comparing them and swapping them if necessary. The same result can be obtained by using a minimum and a maximum operator (the so-called extrema operations). Sorting is then accomplished by making the first element of the resulting list the minimum of the two inputs and the last element of the resulting list the maximum of the two inputs.

In this report we will use the number of extrema operations to measure the complexity of a ROF. We do so because the extrema count allows for a more fine-grained determination of the cost. If, for example, we only need one of the outputs of a C&S operation, we still need a single C&S operation. However, whenever two extrema operations are used to implement the C&S operation we can eliminate the one that produces the unneeded output.

Since there is no consensus in literature whether to use extrema or C&S operation counts, one has to be careful when comparing implementations. Even when the difference is taken into account there is no quick translation of costs. An C&S operation consists of two extrema operations, but it is possible that the design discussed in the literature can be optimized by converting all the C&S operations into extrema operations and subsequently removing the unnecessary operations.

However, whether C&S or extrema operations are used to implement a rank order filter, it is beneficial to minimize the operation count. We could have used an other complexity measure like the throughput (i.e. the number of results produced per unit of time). This measure, however, is implementation specific. Moreover, the operation count signifies the amount of work that needs to be done, therefore minimizing the amount of work will speed up any implementation, regardless what particular method of implementation is used.

Therefore the problem we investigate in this report is: What is the minimum number of extrema operations needed for a rank-order filter?

# Chapter 3 Problem Approach

In this chapter we analyze the problem, derive some properties and introduce an abstract representation for our solutions, which we call the calculation graph. This graph captures the structure of the calculation performed by a rank order filter. To find this structure we first examine the basic operation of an oblivious sorting algorithm (namely the merge operation) in Section 3.1. In Section 3.2 we show that the problem of calculating the filter result provides the opportunity to reuse intermediate results. This leads to the introduction of the calculation graph in Section 3.3, which specifies which merge operations have to take place, provides a (partial) order for them and specifies where the operation results are (re)used. A cost function is needed to calculate the cost (in extrema operations) of an algorithm represented by a calculation graph. One such cost function, based on pruned Batcher's merging networks, is introduced in Section 3.4. In Section 3.5 we show how a simple optimization leads to better merging networks and thus a different cost function.

#### 3.1 Divide and Conquer

A familiar and efficient way of solving problems is the divide and conquer strategy. When this strategy is applied to a sorting problem the result is the merge sort algorithm. The basic operation of a merge sort algorithm is the merging of two sorted lists into a (larger) sorted list denoted by the function:

$$\overline{\mathbf{T}} = \texttt{merge}(\overline{\mathbf{T}_1}, \overline{\mathbf{T}_2}) \tag{3.1}$$

where  $\{\mathbf{T_1}, \mathbf{T_2}\}$  is a partition of  $\mathbf{T}$ , i.e.  $\mathbf{T}_1 \cup \mathbf{T}_2 = \mathbf{T}$  and  $\mathbf{T}_1 \cap \mathbf{T}_2 = \emptyset$ .

As a first step in designing a rank order filter we look at the possibility of dividing the problem of calculating a single window into smaller subproblems in a similar manner. As proper generalization of (3.1) we introduce

$$\overline{\mathbf{T}}[l_0..u_0] = \texttt{merge}(\overline{\mathbf{T}}_1[l_1..u_1], \overline{\mathbf{T}}_2[l_2..u_2])[l_3..u_3]$$
(3.2)

However, this equality only holds if the parameters of the **merge** function adhere to the following properties:

1. (a) 
$$0 \le l_i \le ((l_0 - |\mathbf{T}| + |\mathbf{T}_i|) \uparrow 0)$$
 for  $i = 1, 2$   
(b)  $(u_0 \downarrow (|\mathbf{T}_i| - 1)) \le u_i < |\mathbf{T}_i|$  for  $i = 1, 2$ 

2. (a) 
$$l_3 = l_0 - (l_1 + l_2)$$
  
(b)  $u_3 = u_0 - (l_1 + l_2)$ 

A merge operation that adheres to these properties is called a valid merge operation. An example of such an operation is depicted in Figure 3.1.



Figure 3.1: A merge operation according to (3.2)

To explain property 1 we introduce the function "rnk" to denote the rank of data(g) in  $\overline{T}$ . More formally:

$$\operatorname{rnk}(\mathbf{g}, \mathbf{T}) = (\downarrow i : 0 \le i < |\mathbf{T}| \land \overline{\mathbf{T}}(i) = \operatorname{data}(\mathbf{g}) : i)$$

$$(3.3)$$

Observe that for any element  $\mathbf{g} \in \mathbf{T}_i$  (for i = 1, 2) it holds that  $\operatorname{rnk}(\mathbf{g}, \mathbf{T}) \geq \operatorname{rnk}(\mathbf{g}, \mathbf{T}_i)$ . In other words, adding elements to a set can only increase the rank of an element already in the set, but it cannot decrease it.

Because **T** contains  $|\mathbf{T}| - |\mathbf{T}_i|$  elements more than  $\mathbf{T}_i$ , we therefore know that  $\operatorname{rnk}(\mathbf{g}, \mathbf{T}_i) \leq \operatorname{rnk}(\mathbf{g}, \mathbf{T}) \leq \operatorname{rnk}(\mathbf{g}, \mathbf{T}_i) + (|\mathbf{T}| - |\mathbf{T}_i|)$ . So the interval  $[l_i..u_i]$  must be such that it contains (at least) all elements  $\mathbf{g} \in \mathbf{T}_i$  with  $\operatorname{rnk}(\mathbf{g}, \mathbf{T}_i) \leq u_0$  and  $\operatorname{rnk}(\mathbf{g}, \mathbf{T}_i) + (|\mathbf{T}| - |\mathbf{T}_i|) \geq l_0$  (i.e. at least all the elements  $\mathbf{g}$  of  $\mathbf{T}_i$  for which  $l_0 \leq \operatorname{rnk}(\mathbf{g}, \mathbf{T}) \leq u_0$  might hold). This is exactly what property 1 expresses.

Property 2 can be derived by noting that the merge operation results in a list that is a sublist of  $\overline{\mathbf{T}}$ . The missing elements are elements that, as a consequence of property 1, have a rank in  $\mathbf{T}$  that is not within the interval  $[l_0..u_0]$ . Of the removed elements there are  $l_1 + l_2$  elements with a rank lower than l. The removal of these elements means that an index r in the merged list corresponds to a rank  $r + l_1 + l_2$  in the set  $\mathbf{T}$  for  $l_0 \leq r + l_1 + l_2 \leq u_0$ .

From these properties we can draw some interesting conclusions. First of all, let us return to our original problem of calculating for a single window  $\mathbf{W} \in \mathcal{W}$ a range of ranks  $\overline{\mathbf{W}}[l..u]$ . When we write such a calculation as a series of nested merge operations on tiles  $\mathbf{T}_j$  for some j, we can use property 1 to calculate the ranges for the lower and upper bounds for each of the tiles  $\mathbf{T}_j$ . It turns out that these bounds depend only on  $|\mathbf{T}_j|$  and  $|\mathbf{S}_{\mathcal{W}}|$ . So introduce functions that calculate the highest valid lower bound, and the lowest valid upper bound:

$$low(\mathbf{T}) = (l - |\mathbf{S}_{\mathcal{W}}| + |\mathbf{T}|) \uparrow 0$$
  
up(\mathbf{T}) = u \downarrow (|\mathbf{T}| - 1) (3.4)



Figure 3.2: An example of reuse

Using these functions guarantees validity of the merge operation, w.r.t. property 1, and at the same time minimizes the size of the interval [low(T)..up(T)]. A small interval means little information to calculate and keep track of, which benefits performance. So, once  $T_1$  and  $T_2$  have been chosen, the best choice for  $l_1, u_1, l_2$  and  $u_2$  is given by (3.4). Therefore we will be using these bounds throughout this report, and we introduce a special notation for it:

$$[\mathbf{T}] = \overline{\mathbf{T}}[\mathsf{low}(\mathbf{T})..\mathsf{up}(\mathbf{T})]$$
(3.5)

Also, since property 2 uniquely determines  $l_3$  and  $u_3$ , we can omit them in our notation of any valid merge operation. Therefore we introduce the operator  $\bowtie$ , so that we can write (3.2) as:

$$[\mathbf{T}] = [\mathbf{T}_1] \bowtie [\mathbf{T}_2] \tag{3.6}$$

Note that the operator we introduce is associative and commutative, as can be expected from a generalization of the standard merge operation and therefore it is functionally correct to write:

$$([\mathbf{T}_1] \bowtie [\mathbf{T}_2]) \bowtie [\mathbf{T}_3] = ([\mathbf{T}_2] \bowtie [\mathbf{T}_3]) \bowtie [\mathbf{T}_1]$$

$$(3.7)$$

However, the costs of implementing the left and right hand side of this expression may differ. Consider the following example:  $l = 0, u = |\mathbf{S}_{\mathcal{W}}| - 1, |\mathbf{S}_{\mathcal{W}}| >$  $4, |\mathbf{T}_1| = 1, |\mathbf{T}_2| = 1$  and  $|\mathbf{T}_3| = 2$ . In this example the size of the tiles is the same as the size of the interval of ranks required from them. So, the left hand side of equation (3.7) tells us to merge two tiles of size 1 and the resulting tile (of size 2) with a tile of size 2. The right hand side, on the other hand, tells us to merge a tile of size 1 and size 2 and subsequently merge the resulting tile (of size 3) with a tile of size 1. These are all quite different merging operations and it is not surprising that they differ in cost.

#### 3.2 Divide, Re-use and Conquer

Divide and conquer suffices when we have to "rank-filter" a single window, but our problem statement is concerned with multiple windows that overlap. This overlapping means that there could be common subexpressions that can be reused. This is illustrated in Figure 3.2. The figure shows that we can calculate the two windows  $\mathbf{W}_i$  and  $\mathbf{W}_{i+1}$  as  $[\mathbf{W}_i] = [\{i-3\}] \bowtie [\mathbf{T}_i]$  and  $[\mathbf{W}_{i+1}] = [\mathbf{T}_i] \bowtie [\{i+4\}]$ . This allows us to use  $[\mathbf{T}_i]$  twice, and thus the cost for calculating the intermediate result  $[\mathbf{T}_i]$  is amortized over two window calculations.

Dynamic programming is a standard technique for dealing with such situations, but it can only be applied if a problem exhibits two properties: optimal substructures and overlapping subproblems ([4] Chapter 15). We have already shown that the problem has overlapping subproblems, so we only have to show that it exhibits optimal substructures. Unfortunately this is not possible, since the subproblems are not independent; they share resources. Each subproblem chooses the tiles used in the construction of its windows, these tiles represent the resources and the cost for these resources is shared between the subproblems if reuse takes place. A good, every-day, analogy is car-pooling; perhaps the cheapest way to travel for each individual is by public transport, but travel by car becomes cheaper if you travel in a group and the costs can be amortized.

So, applying dynamic programming to our design problem is not possible. However, the variant of dynamic programming known as "memoization" can still be used in the implementation of the filter ([4] Chapter 15). Using memoization amounts to an implementation that stores all tiles in a table and uses a tablelookup whenever possible. This minimizes the number of extrema operations, at the cost of table lookup operations, and makes sure all previously calculated results are reused whenever possible. In Chapter 7 we show that the regularity of our designs can be used to implemented this table and the lookup operations efficiently with a small number of buffers.

#### 3.3 Calculation Graph

In this section we introduce the notion of a calculation graph G = (V, E) to capture the computation performed by a ROF. The nodes of this graph, given by set  $V \subseteq \mathbb{P}(\mathbb{Z}^D)$ , represent all the (intermediate) results produced during the calculation, i.e. the tiles that will be put in the look-up table. The set of nodes must contain at least:

- all the windows  $\mathcal{W} \subseteq V$ , and
- all the necessary elements  $(\forall \mathbf{W}, \mathbf{i} : \mathbf{W} \in \mathcal{W} \land \mathbf{i} \in \mathbf{W} : {\mathbf{i}} \in V)$

The set of edges  $E \subseteq V \times V$  denotes how the tiles are used to construct other tiles. An edge from  $\mathbf{T}_1$  to  $\mathbf{T}$  means that tile  $\mathbf{T}_1$  is used to construct tile  $\mathbf{T}$  with a merge operation. The following constraints must hold for this set:

- 1.  $(\forall \mathbf{T} : \mathbf{T} \in V \land |\mathbf{T}| > 1 : [\mathbf{T}] = (\bowtie \mathbf{T}_1 : (\mathbf{T}_1, \mathbf{T}) \in E : [\mathbf{T}_1]))$
- 2.  $(\forall \mathbf{T} : \mathbf{T} \in V \land |\mathbf{T}| > 1 : |\{(\mathbf{T}_1, \mathbf{T}) | (\mathbf{T}_1, \mathbf{T}) \in E\}| = 2)$

Property 1 expresses that each tile that does not consist of a single data element is formed by merging the tiles specified by the set E. Note that this implies that the constraints for a valid merge operation, as derived in Section 3.1, must also hold: i.e. together all the tiles used in the construction of a tile **T** must form a partition of that tile **T**. This immediately implies that the graph must be acyclic, since merging tiles can only result in larger tiles. Furthermore, it implies that for each window there must exist paths that start in the tiles representing the window's components and end in the tile representing the window. The calculation graph effectively describes the calculation of the windows during the implementation. Each node in the graph represents the result of a calculation and the node's incoming edges represent the recursive calculations needed to for the sub-tiles. However, we need another property besides 1 to define the calculation done by the implementation unambiguously.

Property 2 enforces that each merge operation merges only two tiles. This removes any ambiguity that arises when more than two tiles are merged. As mentioned in Section 3.1 the costs may differ depending on the order in which tiles are merged. By limiting the calculation graph to an in-degree of 2, we enforce the specification of the evaluation order of the merge operations, and thus remove the ambiguity.

In summary, any solution for a ROFDP can be described as a calculation graph G. The nodes of this graph (V) are called tiles and represent the (intermediate) results of the calculation. The edges (E) of the graph represent the way in which tiles are combined, using merging operations, to form larger tiles.

The cost of the solution can be expressed as C(G):

$$C(G) = \lim_{k \to \infty} \left( \sum \mathbf{T}, \mathbf{T}_1, \mathbf{T}_2 : \mathbf{T} \in (V \cap \text{hypercube}(k, D)) \land \\ (\mathbf{T}_1, \mathbf{T}) \in E \land (\mathbf{T}_2, \mathbf{T}) \in E : \frac{\text{MC}(\mathbf{T}_1, \mathbf{T}_2, \mathbf{T})}{|\mathcal{W} \cap \text{hypercube}(k, D)|} \right)$$
(3.8)

where  $MC(\mathbf{T}_1, \mathbf{T}_2, \mathbf{T})$  is the cost function that determines the cost, in extrema operations, for a merge operation  $[\mathbf{T}] = [\mathbf{T}_1] \bowtie [\mathbf{T}_2]$ . Note that we have to take the limit here because  $\mathcal{W}, V$  and E are infinite sets. So C(G) effectively gives us the cost in extrema operations per window. From this point on we abbreviate this unit of cost as "epw".

The Rank Order Filter Design Problem can now be restated as follows: given a specification find the calculation graph G that adheres to the properties above and minimizes C(G) for a certain cost function MC. Before we solve this problem we first examine the cost function.

#### **3.4** Cost of Merging Networks

In principle the calculation graph is indifferent to the implementation of the merge function. In order to associate a cost with a calculation graph we have to choose a particular implementation. In this report we choose to implement each merging operation using an instance of Batcher's merging network, because Batcher's merging network is the most efficient, known, network for merging two sorted lists. Also, there is a simple formula to calculate the number of extrema operations used in such a network. Note that this approach differs from most of the literature, where a combination of the optimum sorting networks and Batcher's merging networks is used. However, in Chapter 6 we show that we improve upon the results existing in the literature, despite the fact that we do not use the optimum sorting networks.

The formula for the number of compare and swap operations in the network can be found in [7]. However, recall that we measure the cost of our calculation in extrema operations. The cost function in [7] measures cost in C&S operations, so we had to adapt our cost function to produce its result in extrema operations. Also, since each tile  $\mathbf{T}$  represents only an interval  $[low(\mathbf{T})..up(\mathbf{T})]$  of the resulting list, we do not need the entire merging network. We only need that part of the network that has an effect on the desired outputs, and we can prune the network to get rid of the rest of the extrema operations.

Pruning is a relatively simple optimization that can be done automatically. In the case of a software implementation it is called "dead-code elimination" and in circuit design it is called "unused logic elimination", which is performed automatically by the compiler or synthesizer respectively. So it is by no means a new optimization, but in this section we introduce (to the best of our knowledge) the first cost function for such networks.

The function  $\mathsf{PB}(s_1, s_2, l_0, u_0)$  for  $0 \le l_0 \le u_0 < s_1 + s_2$  returns the number of extrema operations required by a pruned version of Batcher's merging network which takes sorted lists, say  $\overline{\mathbf{T}_1}$  and  $\overline{\mathbf{T}_2}$ , of size  $s_1 = |\mathbf{T}_1|$  and  $s_2 = |\mathbf{T}_2|$  respectively and produces the interval  $[l_0..u_0]$  of the sorted list  $\overline{\mathbf{T}_1 \cup \mathbf{T}_2}$ . This function PB satisfies the following recurrence relation:

$$\begin{split} \mathsf{PB}(s_1, s_2, l_0, u_0) &= \\ \begin{cases} 0 & (s_1 = 0) \lor (s_2 = 0) \lor \\ & (u_0 = -1) \lor (l_0 = s_1 + s_2) \\ (u_0 \downarrow 1) - (l_0 \uparrow 0) + 1 & (s_1 = s_2 = 1) \land \\ & (u_0 \neq -1) \land (l_0 \neq s_1 + s_2) \end{cases} \\ \mathsf{PB}(\left\lceil \frac{s_1}{2} \right\rceil, \left\lceil \frac{s_2}{2} \right\rceil, \left\lceil \frac{l_0}{2} \right\rceil, \left\lceil \frac{u_0}{2} \right\rceil) + \\ \mathsf{PB}(\left\lfloor \frac{s_1}{2} \right\rfloor, \left\lfloor \frac{s_2}{2} \right\rfloor, \left\lceil \frac{l_0}{2} \right\rceil - 1, \left\lceil \frac{u_0}{2} \right\rceil - 1) + \\ & (u_0 \downarrow (2 \lfloor \frac{s_1 + s_2 - 1}{2} \rfloor)) - (l_0 \uparrow 1) + 1 \end{split}$$
(3.9)

Note that this recurrence relation has a larger domain than  $0 \leq l_0 \leq u_0 < s_1 + s_2$ . We expanded the domain to  $l_0 \leq u_0 \wedge -1 \leq u_0 \wedge l_0 \leq s_1 + s_2$  to simplify the relation's notation. The extra range of values introduced for  $l_0$  and  $u_0$  does not really affect the outcome of the function, since we have that  $\mathsf{PB}(s_1, s_2, l_0, u_0) = \mathsf{PB}(s_1, s_2, l_0 \uparrow 0, u_0 \downarrow (s_1 + s_2 - 1))$ .

The recurrence relation is a modification of the cost function for Batcher's merging networks without pruning given in [7]. The first case of (3.9) are simple; first of all if  $s_1 = 0$ ,  $s_2 = 0$ ,  $u_0 = -1$  or  $l_0 = s_1 + s_2$ , then there is no merging necessary, since either one of the lists is empty, or we need an empty interval from the resulting list.

The second case occurs when two lists of length 1 are merged. In this case the cost can also be easily calculated. If only one member of the resulting list is needed  $(l_0 = u_0)$  then we need 1 extrema operation to determine it. If both members of the resulting list are needed  $(l_0 < u_0)$  then we need 2 extrema operations.

The third case is the most complicated, but the example in Figure 3.3 might help in understanding. In this figure a merging network is depicted by a box. The numbers in the upper left  $(s_1)$  and upper right corner  $(s_2)$  denote the size of the lists to be merged. The box contains a merging network that accomplishes that operation. This merging network consists of three parts, the first two are recursively merging the even and odd sequences, which have length  $\left\lceil \frac{s_1}{2} \right\rceil + \left\lceil \frac{s_2}{2} \right\rceil$ and  $\left\lfloor \frac{s_1}{2} \right\rfloor + \left\lfloor \frac{s_2}{2} \right\rfloor$  respectively. In the figure we see this recursion as the nesting of two boxes in the main box, in equation (3.9) we see this as the two recursive calls.



Figure 3.3: Batcher's merging network for a 4-5 merge

The third part of the merging network consist of a network that merges the results of the other two (odd and even) parts. In the figure this part has been marked by a dashed box. Its structure is relatively simple; it pairwise compares and swaps elements from the even and the odd list, starting from element 1 from the even list and element 0 from the odd list. This is illustrated in the picture by the small grey numbers, which indicate the indices of the elements in the sorted lists.

This pair-merging network allows us to derive the lower and upper bounds of the ranks for the recursive calls; from the even sequence we need  $\lceil \frac{l_0}{2} \rceil$  and  $\lceil \frac{u_0}{2} \rceil$  as lower and upper bound respectively. This, and the structure of the pair-merging network implies that we need  $\lceil \frac{l_0}{2} \rceil - 1$  through  $\lceil \frac{u_0}{2} \rceil - 1$  from the odd sequence.

The cost of the pair-merging network is expressed by the last term of the third case of (3.9). This term looks daunting, but we can understand it by noting that every element passing through the pair-merging network takes part in one extrema operation, except for the element with index 0 and possibly the element with the highest index. So, we simply count the number of elements that pass through the pair-merging network to get the number of extrema operations.

The first element that passes through the pair-merging network and participates in an extrema operation is  $l_0 \uparrow 1$ . The last element that participates is  $u_0$  when  $u_0 < s_1 + s + 2$ . Otherwise the last element is  $s_1 + s_2$  if  $s_1 + s_2$  is odd, or  $s_1 + s_2 - 1$  if  $s_1 + s_2$  is even. Hence when pruning takes place the last element that participates in an extrema operation is the element with index  $u_0 \downarrow 2 \lfloor \frac{s_1 + s_2 - 1}{2} \rfloor$ .

#### 3.5 Mirroring

Since Batcher's merging networks are the best merging networks known, we might expect that their pruned versions are also the best. This is, however, not the case.

This is caused by the fact that when the range of desired ranks is not symmetric around the center of the window the amount of pruning depends on the order in which the extrema operators are arranged in the network. As an example let  $\overline{\mathbf{T}}_1$  be a list of size  $|\mathbf{T}_1| = 1$  and let  $\overline{\mathbf{T}}_2$  be a list of size  $|\mathbf{T}_2| = 2$  and let  $\overline{\mathbf{T}} = \overline{\mathbf{T}_1 \cup \mathbf{T}_2}$  be a list of size 3. When  $\overline{\mathbf{T}}[0..2]$ , i.e. all ranks, is required Batcher's merging network requires 4 extrema operations (see Figure 3.4(a)). When  $\overline{\mathbf{T}}[1]$ , i.e. the median, is required a pruned version of the network containing 2 extrema operations suffices (see Figure 3.4(b)). When  $\overline{\mathbf{T}}[2]$ , i.e. the minimum, is required a pruned version of the network also containing 2 extrema operations suffices (see Figure 3.4(c)). However, when  $\overline{\mathbf{T}}[0]$ , i.e. the minimum, is required a pruned version of the network containing only 1 extrema operations suffices (see Figure 3.4(d)).



Figure 3.4: Batcher's merging network for a 1-2 merge

This example suggest that in case of pruning we can come up with another automatic optimization which involves varying the layout of the network by varying the sorting order. We either sort in the standard ascending order, or we switch to a descending order if that is less costly. Changing the sorting order amounts to taking the mirror image of a sorting network. Hence we obtain the following cost function:

$$\begin{split} \text{MPB}(s_1, s_2, l_0, u_0) &= \\ \text{MPB}'(s_1, s_2, l_0, u_0) \downarrow \text{MPB}'(s_1, s_2, s_1 + s_2 - 1 - u_0, s_1 + s_2 - 1 - l_0) \\ \text{MPB}'(s_1, s_2, l_0, u_0) &= \\ \begin{cases} 0 & (s_1 = 0) \lor (s_2 = 0) \lor \\ (u_0 = -1) \lor (l_0 = s_1 + s_2) \\ (u_0 \downarrow 1) - (l_0 \uparrow 0) + 1 & (u_0 \neq -1) \land (l_0 \neq s_1 + s_2) \\ (u_0 \neq -1) \land (l_0 \neq s_1 + s_2) \end{cases} \\ \text{MPB}(\left\lceil \frac{s_1}{2} \right\rceil, \left\lceil \frac{s_2}{2} \right\rceil, \left\lceil \frac{l_0}{2} \right\rceil, \left\lceil \frac{u_0}{2} \right\rceil) + \\ \text{MPB}(\left\lfloor \frac{s_1}{2} \right\rfloor, \left\lfloor \frac{s_2}{2} \right\rfloor, \left\lceil \frac{l_0}{2} \right\rceil - 1, \left\lceil \frac{u_0}{2} \right\rceil - 1) + \\ (u_0 \downarrow (2 \lfloor \frac{s_1 + s_2 - 1}{2} \rfloor)) - (l_0 \uparrow 1) + 1 \end{split}$$
(3.10)

This function is almost identical to (3.9), but at each point in the recursion we now consider whether the pruned version of the original, or the pruned version of the mirror network, minimizes the cost.

This new optimization method can also be applied to networks other than pruned versions of Batcher's merging networks. Optimal sorting networks that are pruned can also be mirrored prior to the pruning operation to see if this leads to a decrease in cost. In at least one case (namely in the solution presented in [8]) this is the case.

We are now in a position to define the cost function MC from (3.8). Using function MPB (3.10) and functions low and up as defined in (3.4) we define MC as:

$$\begin{split} \mathsf{MC}(\mathbf{T}_1, \mathbf{T}_2, \mathbf{T}) &= \mathsf{MPB}(\\ & \mathsf{up}(\mathbf{T}_1) - \mathsf{low}(\mathbf{T}_1) + 1, \\ & \mathsf{up}(\mathbf{T}_2) - \mathsf{low}(\mathbf{T}_2) + 1, \\ & \mathsf{low}(\mathbf{T}) - \mathsf{low}(\mathbf{T}_1) - \mathsf{low}(\mathbf{T}_2), \\ & \mathsf{up}(\mathbf{T}) - \mathsf{low}(\mathbf{T}_1) - \mathsf{low}(\mathbf{T}_2)) \end{split} \tag{3.11}$$

## Chapter 4

## **Generator Graphs**

A calculation graph is an infinite graph that represents the infinite calculation performed by a filter. The filter itself, however, being an algorithm implemented either in hardware or software, is a finite object. The gap between infinite calculation graphs and finite filter implementations is bridged by so-called *generator graphs*. A generator graph is a finite representation of a filter that exploits the regularities present in the calculations performed by such a filter. On the one hand the generator graph, as its name suggests, can be used to generate a calculation graph. On the other hand, a generator graph can serve as the starting point for a concrete filter implementation.

In this chapter generator graphs are defined and it is shown how calculation graphs can be generated from them. Finding a generator graph for a specific filter is the subject of Chapter 5. However, various heuristics presented in that chapter share a common approach, which we explain in this chapter as well. Deriving parallel implementations from generator graphs is the subject of Chapter 7.

#### 4.1 Preliminaries

Although a calculation graph contains infinitely many tiles there are only a finite number of ways in which a tile of a certain shape is constructed. This suggests that one can condense the calculation graph such that only the different construction methods are retained. Consider all tiles of a specific shape in the calculation graph. We group these tiles according to their construction method and represent this group by a single node in the generator graph.

Recall that we have already introduced the function tile (2.1) as a way of generating regular sets of tiles. The argument of this function is a triple consisting of a shape, a phase and a period:

$$\mathsf{T} = (\mathbf{S}_\mathsf{T}, \mathbf{f}_\mathsf{T}, \mathbf{p}_\mathsf{T})$$

We will use these triples as the nodes of our generator graph  $G_g = (V_g, E_g)$ . Hence it follows that a node represents a tile-set  $\mathcal{T} = \text{tile}(\mathbf{S}_{\mathsf{T}}, \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{\mathsf{T}}) = \text{tile}(\mathsf{T})$ . Note that the phase and periods can be used to identify the various construction methods for tiles of the same shape. So, the node set of a generator graph  $V_g$  is a subset of  $(\mathbb{P}(\mathbb{Z}^D) \times \mathbb{Z}^D \times \mathbb{Z}^D)$ , with each node representing a tile-set. Since distinct triples can describe the same tile set we introduce the function norm(T) that rewrites these triples to a unique canonical form that satisfies:

$$\texttt{tile}(\texttt{norm}(\mathsf{T})) = \texttt{tile}(\mathsf{T}) \tag{4.1}$$

$$\mathbf{0}_D \le \mathbf{f}_{\texttt{norm}(\mathsf{T})} \le \mathbf{p}_{\texttt{norm}(\mathsf{T})} \tag{4.2}$$

$$(\forall \mathbf{g} : \mathbf{g} \in \mathbf{S}_{\texttt{norm}(\mathsf{T})} : \mathbf{g} \ge \mathbf{0}_D) \tag{4.3}$$

$$(\forall \mathbf{t} : \mathbf{t} \in \mathbb{N}^D \land \mathbf{t} \neq \mathbf{0}_D : (\exists \mathbf{g} : \mathbf{g} \in (\mathbf{S}_{\texttt{norm}(\mathsf{T})} - \mathbf{t}) : \mathbf{g} < \mathbf{0}_D))$$
(4.4)

The canonical form describes the same tile set (4.1), but its phase lies between zero and the period (4.2). Also, the set of grid locations forming its shape are positioned in the positive hyper-quadrant (4.3) in such a way that there is no tile with the same shape in the positive hyper-quadrant that lies closer to the origin (4.4). All the nodes in the generator graph adhere to this canonical form.

The nodes are used to group tiles that have the same construction method and the edges of the generator graph are used to capture these construction methods. To this end the edges of the generator graph mimic those of the calculation graph. Since a tile containing more than one grid location is constructed from two other tiles the generator graph also has this property:

$$(\forall \mathsf{T} : \mathsf{T} \in V_q \land |\mathbf{S}_{\mathsf{T}}| > 1 : |\{(\mathsf{U},\mathsf{T})|(\mathsf{U},\mathsf{T}) \in E_q\}| = 2)$$

However, the tiles  $\mathbf{T}_1$  and  $\mathbf{T}_2$ , used in the construction of a tile  $\mathbf{T}$ , may be contained in the same tile-set and thus the same node of the generator graph. This means that the generator graph is a multi-graph and thus the set of edges is a multi-set. From our definition of the nodes of the generator graph it then follows:

$$(\forall \mathsf{T}, \mathsf{T}_1, \mathsf{T}_2 : (\mathsf{T}_1, \mathsf{T}) \in E_g \land (\mathsf{T}_2, \mathsf{T}) \in E_g \land \mathsf{T}_1 \neq \mathsf{T}_2 : \\ \texttt{tile}(\mathsf{T}) \subseteq \{ [\mathbf{T}_1] \bowtie [\mathbf{T}_2] \mid \mathsf{T}_1 \in \texttt{tile}(\mathsf{T}_1) \land \mathsf{T}_2 \in \texttt{tile}(\mathsf{T}_2) \} )$$

$$(4.5)$$

$$(\forall \mathsf{T}, \mathsf{T}_1 : (\mathsf{T}_1, \mathsf{T}) \in E_g \land (\forall \mathsf{T}_2 : (\mathsf{T}_2, \mathsf{T}) \in E_g : \mathsf{T}_1 = \mathsf{T}_2) : \\ \texttt{tile}(\mathsf{T}) \subseteq \{ [\mathsf{T}_1] \bowtie [\mathsf{T}_2] \mid \mathsf{T}_1, \mathsf{T}_2 \in \texttt{tile}(\mathsf{T}_1) \land \mathsf{T}_1 \neq \mathsf{T}_2 \} )$$

$$(4.6)$$

These restrictions express that for every pair of edges describing the construction of a tile set  $\mathcal{T}$ , there are two other tile-sets  $\mathcal{T}_1$  and  $\mathcal{T}_2$  in which the necessary tiles can be found. Equation (4.5) expresses this for cases where the composing tiles come from distinct tile-sets and (4.6) expresses it for cases where the composing tiles come from the same tile-set.

Consider the example generator graph in Figure 4.1. For ease of reading we have chosen to denote shapes in a graphical manner. Each shape is a set of grid locations, and in the one dimensional case we can represent this set as a linear sequence of squares. When a square is black ( $\blacksquare$ ) this means that that specific grid location is in the set, when the square is blank ( $\square$ ) that specific grid location is not in the set. We start the numbering of grid locations at 0 because of the normalization requirements. So sequence " $\blacksquare\blacksquare\blacksquare\blacksquare$ " denotes the set  $\{0, 1, 2, 3\}$ , and " $\blacksquare\square\square\blacksquare$ " denotes the set  $\{0, 3\}$ .

Figure 4.1 shows us an example of why the generator graph is a directed *multi-graph*, whereas the calculation graph is not a multi-graph. A tile **T** from the tile-set tile(**DEDE**, 1, 2) is formed by taking two tiles  $\mathbf{T}_1$  and  $\mathbf{T}_2$  from the



Figure 4.1: Example generator graph  $G_g$  for  $\mathcal{W} = \texttt{tile}(\texttt{mmmm}, 0, 1)$ 

same tile-set  $tile(\blacksquare, 1, 2)$ . In the generator graph nodes represent tile-sets and we might need two tiles from the same tile-set to generate a tile, hence we need the generator graph to be a multi-graph. In the calculation graph each tile is represented by a single node and hence we only need at most one edge between nodes.

#### 4.2 Canonical generator graphs

Using the preliminaries from the previous section we can now define the relationship between the nodes of the calculation graph (V) and the generator graph  $(V_g)$  more formally:

$$V = (\cup \mathsf{T} : \mathsf{T} \in V_q : \mathtt{tile}(\mathbf{S}_\mathsf{T}, \mathbf{f}_\mathsf{T}, \mathbf{p}_\mathsf{T}))$$

The set of edges of the calculation graph describe the construction method for the tiles/nodes of the calculation graph. These edges can also be derived from the generator graph. Using restriction (4.5) and (4.6) we specify:

$$(\forall \mathbf{T}, \mathsf{T}, \mathsf{T}_1 : \mathbf{T} \in \mathtt{tile}(\mathsf{T}) \land (\mathsf{T}_1, \mathsf{T}) \in E_g : (\exists \mathbf{T}_1 : \mathbf{T}_1 \in \mathtt{tile}(\mathsf{T}_1) : (\mathbf{T}_1, \mathbf{T}) \in E))$$

Note that since  $E_g$  is a multi-set, a duplicate edge in  $E_g$  means that there are two (distinct) edges in E.

This, however, does not describe exactly which tiles  $\mathbf{T}_1 \in \mathcal{T}_1$  and  $\mathbf{T}_2 \in \mathcal{T}_2$ should be used in the construction of a tile  $\mathbf{T} \in \mathcal{T}$ , only that a construction method exists for some  $\mathbf{T}_1$  and  $\mathbf{T}_2$ . However, there are at most two combinations of tiles  $\mathbf{T}_1$  and  $\mathbf{T}_2$  that partition the tile  $\mathbf{T}$ . This can be explained as follows: take a grid location  $\mathbf{g} \in \mathbf{T}$ . We now have either  $\mathbf{g} \in \mathbf{T}_1$  or  $\mathbf{g} \in \mathbf{T}_2$ , i.e. the tile containing  $\mathbf{g}$  comes either from tile-set  $\mathcal{T}_1$  or  $\mathcal{T}_2$ , hence there are two options. One might argue that there could be multiple tiles  $\mathbf{T}_1 \in \mathcal{T}_1$  such that  $\mathbf{g} \in \mathbf{T}_1$ , however there is only one  $\mathbf{T}_1$  capable of forming  $\mathbf{T}$  with one other tile  $\mathbf{T}_2$  from the other tile-set because the shape of the tiles is fixed for  $\mathcal{T}_1, \mathcal{T}_2$  and  $\mathcal{T}$ . The same reasoning can, of course, be used to show that there is only one suitable  $\mathbf{T}_2 \in \mathcal{T}_2$ .

When multiple options exist a choice must be made. This choice does not influence the cost of the resulting calculation graph. The cost of merging, after all, depends only on the size of the tiles, which is not influenced by the choice. The choice, however, must be made in a consistent manner. This ensures that always the same calculation graph is generated from a generator graph. This, in turn, ensures that the implementation based on the generator graph will correspond to the calculation graph.

To make such a consistent choice we introduce an ordering on the grid locations and the tile-sets. The grid locations are ordered by sorting them in ascending order on their first coordinate, then on their second coordinate, etc. The tile-sets are ordered first on the size of the shape then on their phase and subsequently on their period. Whenever a choice has to be made we make it such that the tile containing the grid location with the lowest rank of the resulting tile ( $\mathbf{g} \in \mathbf{T}$ ) comes from the tile-set with the lowest rank. In most cases it is possible to make a consistent choice, but the example of Section 4.1 shows a case where this is not possible: tile( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 0, 1). Consider the lowest coordinates of the tiles from tile( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 0, 1) if this coordinate is even the tile can only be formed by taking a tile containing the grid normal by taking a tile containing the condinate from tile( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 1, 2).

To solve this problem we introduce a canonical form such that all choices during the generation of a calculation graph from generator graphs in canonical form can be made in a consistent manner. The canonical form entails nothing more than that all the nodes in the generator graph should have the same period and that this period should be as small as possible. We call this period the metaperiod of the graph and it can be calculated by taking the least common multiple of the periods of all the nodes of a generator graph (that has minimum periods for all its tile-sets). This meta-period also plays an important role in actually implementing the design in Chapter 7.

Note that it is always possible to get the canonical form of a generator graph since nodes that do not have the required period can simply be duplicated a number of times. We have done this for the generator graph from Figure 4.1 and the result is shown in Figure 4.2.

A major benefit of this canonical form is that the the choices in generating the calculation graph can now be made consistently. For example the tiles from node ( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 0, 2) in Figure 4.2 are always constructed by a tile from ( $\blacksquare$ , 0, 2) followed by a tile from ( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 1, 2). Conversely the tiles from node ( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 1, 2) are always constructed by a tile from ( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 1, 2) followed by a tile from ( $\blacksquare\blacksquare\blacksquare\blacksquare$ , 1, 2). In contrast the tiles from the original graph in Figure 4.1 had to alternate between these construction methods and thus did not allow a consistent choice.



Figure 4.2: Figure 4.1 in canonical form

### 4.3 Cost calculation

We can calculate the cost of a calculation graph generated by a generator graph without actually generating the calculation graph itself. Take Figure 4.2 for example; the fact that node ( $\blacksquare$ , 1, 2) has incoming edges from ( $\blacksquare$ , 0, 2) and ( $\blacksquare$ , 1, 2) means that it represents the merging of two tiles of size 1 and that this merging occurs with a period of 2. To calculate the cost of merging two tiles of size 1 we need to know the range of ranks needed from the resulting tile. This range of ranks can be calculated using (3.4) and, for the sake of simplicity, we look at the window sorting problem here, where all ranks are needed. Then the merging of two tiles of size 1 requires 2 extrema operations. Because the period of the windows is 1 and the period of these mergings is 2 we know that this cost of the merging operation can be amortized over 2 windows. Hence the contribution of this merging operation to the total is 1 epw. In a similar manner we can calculate the contribution of all the nodes in the generator graph to the total cost. For Figure 4.2 this has been done in Table 4.1.

Note that, besides not having to actually generate the calculation graph to calculate the cost, the generator graph has another advantage; we are able to avoid taking limits as required by definition (3.8).

Node	Cost per operation	Contribution
(■■■■■,0,2)	10	5
( <b>EEEEE</b> , 1, 2)	10	5
(■■■■■,0,2)	8	4
(■■■■■, 1, 2)	8	4
(■■■■,1,2)	6	3
(■■,1,2)	2	1
(■,0,2)	0	0
$(\blacksquare, 1, 2)$	0	0
Total cost: (in epw)		22

Table 4.1: Cost of the generator graph in Figure 4.2

#### 4.4 Constructing generator graphs

Chapter 5 describes, in detail, several heuristic algorithms for constructing generator graphs. In this section we discuss the framework used by some of the algorithms from that chapter and indicate how other heuristic algorithms can be designed.

The algorithms for constructing a generator graph start with an empty generator graph  $(\emptyset, \emptyset)$  and add nodes and edges until a generator graph is formed such that the calculation graph derived from it is valid.

To add a node and edges to the generator graph the **add** function is used, which returns the updated graph:

$$add(G_q, \mathsf{T}, \mathsf{T}_1, \mathsf{T}_2) = (V_q \cup \{\mathsf{T}\}, E_q \cup \{(\mathsf{T}_1, \mathsf{T}), (\mathsf{T}_2, \mathsf{T})\})$$
(4.7)

This adds the node  $\mathsf{T}$  to the set of nodes and adds incoming edges (from  $\mathsf{T}_1$  and  $\mathsf{T}_2$ ) to the graph. Note that for the resulting graph to be valid the construction of the tiles in  $\mathcal{T}$  from the tiles in  $\mathcal{T}_1$  and  $\mathcal{T}_2$  must be possible, that  $\mathsf{T}_1$  and  $\mathsf{T}_2$  must be in the set of nodes, and that all the triples have to be in canonical form. Moreover, recall that  $E_q$  is a multi-set, so in case  $\mathsf{T}_1 = \mathsf{T}_2$  two edges are added.

Some algorithms create a generator graph in a top down fashion. These algorithms start by defining the construction of the windows (specified by the ROFDP) and then recursively define the construction method of the window's components.

The top down approach is based on two functions. The first one is a function that specifies how tiles from an existing tile-set should be split into two sub-tiles from (possibly different) tile-sets and which (possibly other) function specifies the construction method of these new tile-sets. This function forms the core of the heuristic algorithm and we therefore call it the heuristic function. The second function used by this approach is the function that recursively calls the heuristic function and adds the results to the generator graph.

The method of construction of a tile set is defined by the heuristic function, say f. The function differs for each algorithm, but all functions return the same kind of tuple:  $f(T) = ((T_1, f_1), (T_2, f_2))$ , where  $T_1 = norm(T_1)$  and  $T_2 = norm(T_2)$ . The function effectively specifies that the tiles in tile set tile(T) should be constructed from tiles in tile( $T_1$ ) and tile( $T_2$ ). It also specifies that the tile-sets tile( $T_1$ ) and tile( $T_2$ ) should be constructed in the manner defined by the heuristic functions  $f_1$  and  $f_2$  respectively. For basic algorithms we have  $f = f_1 = f_2$ , but more sophisticated algorithms switch heuristics at a certain point.

Although this first function differs per algorithm, there are enough similarities between algorithms to introduce the so-called **split** function. This function is used to split a tile at a specific point into two sub-tiles:

$$split(\mathsf{T}, \mathbf{c}, \mathbf{p}_1, \mathbf{f}_1, \mathbf{p}_2, \mathbf{f}_2) = ((cut(\mathsf{T}, \mathbf{c}, \mathbf{p}_1), \mathbf{f}_1), (rem(\mathsf{T}, \mathbf{c}, \mathbf{p}_2), \mathbf{f}_2))(4.8)$$

The result returned by the **split** function adheres to the format for the heuristic function and is often used as a basis for such a function.

To split a tile into two sub-tiles the **split** function uses the **cut** and **rem** functions which respectively return the part of a tile closest to the origin and the remainder of the tile. More formally:

$$\operatorname{cut}(\mathsf{T}, \mathbf{c}, \mathbf{p}_{new}) = \operatorname{norm}((\mathbf{S}_{\mathsf{T}} \cap \operatorname{hyperbar}(\mathbf{c}), \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{new}))$$
 (4.9)

$$\operatorname{rem}(\mathsf{T}, \mathbf{c}, \mathbf{p}_{new}) = \operatorname{norm}((\mathbf{S}_{\mathsf{T}} \setminus \operatorname{hyperbar}(\mathbf{c}), \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{new}))$$
(4.10)

(4.11)

The functions  $\operatorname{cut}(\mathsf{T}, \mathbf{c}, \mathbf{p}_{new})$  and  $\operatorname{rem}(\mathsf{T}, \mathbf{c}, \mathbf{p}_{new})$  therefore return normalized triples based on  $\mathsf{T}$ . The difference between the two functions is in the shape of the returned triple. The shape of the original triple is effectively cut in two pieces based on the cut-off point described by vector  $\mathbf{c}$ . The function  $\operatorname{cut}$  returns the part closest to the origin, while the function  $\operatorname{rem}$  returns the remainder. The triples returned by these functions have a period indicated by the vector  $\mathbf{p}_{new}$ .

The hyperbar function is used by the cut and rem functions to partition a tile. As it name implies the function does nothing more than returning a tile in the shape of a hyper-bar with dimensions indicated by vector s:

$$hyperbar(s) = \{g | \mathbf{0}_D \le g < s\}$$
(4.12)

(4.13)

Let us examine  $split((\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 0, 1), 2, 1, f_1, 2, f_2)$  as an example. This formula specifies that the tiles from  $(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 0, 2)$  have to be formed from tiles of size 2 and 4, with periods 1 and 2 respectively:

Note that the **split** function does nothing to ensure correctness. We could also have used the example:

 $split((\blacksquare\blacksquare\blacksquare\blacksquare, 0, 1), 2, 3, f_1, 2, f_2) = (((\blacksquare\blacksquare, 0, 3), f_1), ((\blacksquare\blacksquare\blacksquare, 2, 2), f_2)),$ which would result in a generator graph that is in violation of (4.5). So split is only a notational shorthand for our algorithms. That an algorithms provides us with a correct generator graph has to be shown for each algorithm individually.

The other major part of the frame work for top-down algorithms is the function that recursively calls the heuristic function until the construction method of every tile has been specified. This function is called TD:

$$\begin{aligned} \mathsf{TD}(G_g,\mathsf{T},\mathsf{f}) &= \\ \begin{cases} G_g & \mathsf{T} \in V_g \\ (V_g \cup \{\mathsf{T}\}, E_g) & \mathsf{T} \notin V_g \land |\mathbf{S}_\mathsf{T}| = 1 \\ \mathsf{TD}(\mathsf{TD}(\mathsf{add}(G_g,\mathsf{T},\mathsf{T}_1,\mathsf{T}_2),\mathsf{T}_1,\mathsf{f}_1),\mathsf{T}_2,\mathsf{f}_2) & \text{otherwise} \\ \end{aligned}$$
where  $((\mathsf{T}_1,\mathsf{f}_1),(\mathsf{T}_2,\mathsf{f}_2)) = \mathsf{f}(\mathsf{T}) \end{aligned}$ 

$$(4.14)$$

This function returns an updated generator graph by taking a generator graph  $G_g$  by adding the triple T to it (we assume that T = norm(T)). This explains the first two cases in (4.14); in the first case the triple T is already part of the generator graph and thus nothing has to be done. In the second case the triple T is not yet part of the generator graph, so it has to be added, and since it is of size 1 it requires no incoming edges to describe its construction. The last case is more complicated, not only must the triple T be added as a node, also two edges need to be added that describe how the tiles in the tile set (T) must be constructed. The particular manner in which this construction takes place is described by the heuristic function f, which (for most algorithms) is based on the split function described earlier.

## Chapter 5

## Heuristic Algorithms

In the previous chapter the problem of designing an efficient ROF has been reduced to the problem of finding a generator graph with low cost. In this chapter we introduce several heuristic algorithms capable of finding such lowcost generator graphs. Finding optimal ROFs of small size can be done by a brute force algorithm, just as optimal sorting networks have been found for small sorting problems [7], but for larger problems the number of possible generator graphs explodes. Therefore we resort to heuristic algorithms.

In the next few sections we develop several heuristic algorithms for (mainly one dimensional) ROFDPs using the method sketched in Chapter 4. This means that we introduce various ways of splitting tile-sets. We also show how an algorithm designed for a one dimensional ROFDP can be generalized to multiple dimensions.

#### 5.1 Preliminaries

$$pow2(a) = (\exists i : i \in \mathbb{N} : 2^i = a)$$

$$(5.1)$$

$$msb_1(a) = (\uparrow i : 2^i < a : 2^i)$$
 (5.2)

$$lsb_1(a) = (\uparrow i : 2^i \mid a : 2^i)$$

$$(5.3)$$

These functions respectively return: a boolean value that indicates whether a is a power of two and the power of two represented by the most-significant 1-bit of a and the least-significant 1-bit of a.

An operation which is used often by the algorithms is selecting the triple describing tiles with the largest or smallest shape from a set. To indicate these we use the following notation:

$$\downarrow Q \quad \text{for an element of } Q \text{ such that } |\mathbf{S}_{(\downarrow Q)}| = (\downarrow q : q \in Q : |\mathbf{S}_q|)$$
  
$$\uparrow Q \quad \text{for an element of } Q \text{ such that } |\mathbf{S}_{(\uparrow Q)}| = (\uparrow q : q \in Q : |\mathbf{S}_q|)$$
(5.4)

### 5.2 Divide and Conquer

This algorithm is based on the observation that, when using Batcher's merging networks, the cheapest way to obtain a sorted list of size s is by merging sorted lists of size:  $\lceil \frac{s}{2} \rceil$  and  $\lfloor \frac{s}{2} \rfloor$ . This is a simple divide and conquer approach leading to the construction:

$$G_q = \mathsf{TD}((\emptyset, \emptyset), \mathsf{norm}(\mathsf{W}), \mathsf{dac})$$

where the heuristic function dac is specified by:

$$\begin{array}{lll} G_g & = & \texttt{TD}((\emptyset, \emptyset), \texttt{norm}(\mathsf{W}), \texttt{dac}) \\ \texttt{dac}(\mathsf{T}) & = & \texttt{split}(\mathsf{T}, \lceil \frac{|\mathbf{S}_\mathsf{T}|}{2} \rceil, \mathbf{p}_\mathsf{T}, \texttt{dac}, \mathbf{p}_\mathsf{T}, \texttt{dac}) \end{array}$$



Figure 5.1: Generator graphs produced by the dac-heuristic

The generator graphs produced by this algorithm for our running examples are shown in Figure 5.1. The resulting rank order filters require 18 epw (extrema operations per window) and 28 epw for sorting windows of size of 6 and 7 respectively. Since each tile-set has a period equal to the period of the windows the **dac**-heuristic does not reuse any tiles.



(a) largest possible overlap



(b) intermediate overlap

Figure 5.2: Example of overlapping for  $\mathsf{T} = (\blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare, 0, 1)$ 

#### 5.3 Recursive Tiling

The divide and conquer algorithm from the previous section provides generator graphs in which no reuse takes place. Before we introduce an algorithm that generates generator graphs with reuse, let us examine a possible way in which reuse can take place.

A solid tile  $\mathbf{T} \in \mathcal{T}$  can be formed by combining two tiles  $\mathbf{T}_1$  and  $\mathbf{T}_2$  with  $(\forall \mathbf{g}_1, \mathbf{g}_2 : \mathbf{g}_1 \in \mathbf{T}_1 \land \mathbf{g}_2 \in \mathbf{T}_2 : \mathbf{g}_1 < \mathbf{g}_2)$ . When  $|\mathbf{T}_1|$  is a multiple of  $\mathbf{p}_{\mathcal{T}}$  then  $\mathbf{T}_2$  can be reused in the construction of  $\mathbf{T} + |\mathbf{T}_1|$  like so:  $[\mathbf{T} + |\mathbf{T}_1|] = [\mathbf{T}_2] \bowtie [\mathbf{T}_1 + |\mathbf{T}|]$ . Two examples of this are shown in Figure 5.2.

Note that the part that could be reused in the divide and conquer algorithm is relatively small; for any **T** the reusable part would have size  $\lfloor \frac{|\mathbf{T}|}{2} \rfloor$ . So, instead of adopting the divide and conquer algorithm so that it exhibits reuse, we immediately turn to an algorithm that maximizes the size of the reused parts.

This algorithm simply splits a tile in a remainder and in an overlapping part. In the first step the remainder will be of size one and the overlapping part of size  $|\mathbf{S}_{\mathcal{W}}| - 1$ . This overlapping part then has a period of 2, so this remainder is split into a part of size 2 and a part of size  $|\mathbf{S}_{\mathcal{W}}| - 3$ . More formally this algorithm is described by the heuristic function rts:

$$\begin{split} \mathtt{rts}(c,m)(\mathsf{T}) &= \begin{cases} \mathtt{split}(\mathsf{T},c,\mathbf{p}_\mathsf{T},\mathtt{dac},(2\mathbf{p}_\mathsf{T})\downarrow m,\mathtt{rts}(2c,m)) & c < |\mathbf{S}_\mathsf{T}| \\ \mathtt{dac}(\mathsf{T}) & c = |\mathbf{S}_\mathsf{T}| \\ \mathtt{rtm}(\mathsf{T}) & c > |\mathbf{S}_\mathsf{T}| \\ \end{split} \\ \mathtt{rtm}(\mathsf{T}) &= \mathtt{split}(\mathsf{T},\mathtt{msb}_1(|\mathbf{S}_\mathsf{T}|),\mathbf{p}_\mathsf{T},\mathtt{dac},\mathbf{p}_\mathsf{T},\mathtt{rtm}) \end{split}$$

The **rts** function has two parameters: c and m. The parameter c equals the size of the tile that is split of. The algorithm starts with c = 1 and, since c can

only be doubled, this means that c is always a power of two. Conceptually the period of the overlapping part will double in each recursive step. However, to make sure that the generator graph produced by the algorithm is valid we need to limit the period at a certain value. This limit is indicated by the parameter m. Since a higher period allows for more reuse this parameter will be set as high as possible, but low enough to ensure that a valid generator graph is produced. This leads to  $m = 21 \text{sb}_1(|\mathbf{S}_W| + 1)$ .

The **rts** function recursively calls itself to split the tiles, but at a certain stage c will be larger or equal to the size of the tile that is under construction. In these cases we have to switch heuristics. The **dac** heuristic is a possible choice, but while using the **rts** heuristic a lot of tiles with sizes that are a power of two have been generated. We can reuse these tiles by switching to the correct heuristic. When c, which is a power of two, equals the tile size the **dac** heuristic will reuse them automatically since all the tiles it generates will be powers of two. In the case where c is larger than the tile size we switch to the **rtm** heuristic to make sure that we construct the tile from tiles whose size are a power of two.

This heuristic performs well for odd window sizes, however for even window sizes we have  $m = 21 \text{sb}_1(|\mathbf{S}_{\mathcal{W}}|+1) = 2$ , which severely limits reuse. We therefore take a special step in the case of even window sizes, defined by the rtf heuristic:

$$\mathsf{rtf}(\mathsf{T}) = \begin{cases} \mathsf{split}(\mathsf{T}, 1, \mathbf{p}_{\mathsf{T}, -}, \mathbf{p}_{\mathsf{T}}, \mathsf{rts}(1, 2\mathsf{lsb}_1(|\mathbf{S}_{\mathsf{T}}|))) & |\mathbf{S}_{\mathsf{T}}| \mod 2 = 0\\ \mathsf{rts}(1, 2\mathsf{lsb}_1(|\mathbf{S}_{\mathsf{T}}| + 1))(\mathsf{T}) & |\mathbf{S}_{\mathsf{T}}| \mod 2 = 1 \end{cases}$$

The generator graph produced by the recursive tiling algorithm for one dimensional problems is therefore defined by:

$$G_q = \mathsf{TD}((\emptyset, \emptyset), (\texttt{norm}(\mathsf{W}), \texttt{rtf}))$$

The result of this algorithm for our running examples can be seen in figures 4.2 and 5.3. The cost for both solutions is respectively 22 and 20.5 epw for window sizes 6 and 7. So for windows of size 7 this algorithm is better than the divide an conquer algorithm. In fact, for most problems this algorithm performs better than the divide and conquer algorithm. The reason for this is the reuse; for the problem with window size 7 the tiles of size 2, 4 and 6 can be reused, with the tile of size 4 even being used for 4 different windows. It is this amount of reuse that allows the recursive tiling algorithm to improve upon the divide and conquer algorithm. Unfortunately, only the tiles of size 2 and 4 can be reused for the problem with window size 6 and this reuse is not enough to improve upon the divide and conquer algorithm.

#### 5.4 Bit-pattern Tiling

Our experiments with the heuristic from the previous section shows that power of two tiles (i.e. tiles with a size that is a power of two) can be created efficiently using the **dac**-heuristic. In this section we therefore present an algorithm that produces windows based on such power of two tiles. Since the type of power of two tiles depends on the pattern of bits representing the window size, we have named this heuristic "Bit-pattern tiling".

This algorithm comes in two variants; one that splits off the least significant power of two from an existing tile, and one that splits of the most significant



Figure 5.3:  $G_g$  for the Recursive Tiling algorithm for window size 7 (20.5 epw)

power of two. In effect we either iterate through the bit-pattern from left to right or from right to lift.

The first variant of the algorithm is called "Least Significant Bit Tiling" or "LSB Tiling" and is defined as follows:

$$G_q = \mathsf{TD}((\emptyset, \emptyset), \mathsf{norm}(\mathsf{W}), \mathsf{lsbt})$$

where the heuristic function lsbt is specified by:

$$\begin{split} \texttt{lsbt}(\mathsf{T}) = & \\ \begin{cases} \texttt{dac}(\mathsf{T}) & \texttt{pow2}(|\mathbf{S}_\mathsf{T}|) \\ \texttt{split}(\mathsf{T},\texttt{lsb}_1(|\mathbf{S}_\mathsf{T}|), \mathbf{p}_\mathsf{T},\texttt{lsbt}, 2\mathbf{p}_\mathsf{T},\texttt{lsbt}) & \neg \texttt{pow2}(|\mathbf{S}_\mathsf{T}|) \land \mathbf{p}_\mathsf{T} = \texttt{lsb}_1(|\mathbf{S}_\mathsf{T}|) \\ \texttt{split}(\mathsf{T},\texttt{lsb}_1(|\mathbf{S}_\mathsf{T}|), \mathbf{p}_\mathsf{T},\texttt{lsbt}, \mathbf{p}_\mathsf{T},\texttt{lsbt}) & \text{otherwise} \end{cases} \end{split}$$

The second variant is called "Most Significant Bit Tiling" or "MSB Tiling":

$$G_q = \mathsf{TD}((\emptyset, \emptyset), \mathsf{norm}(\mathsf{W}), \mathsf{msbt})$$

where the heuristic function msbt is specified by:

$$\begin{split} G_g &= \texttt{TD}((\emptyset, \emptyset), (\texttt{norm}(\mathsf{W}), \texttt{msbt})) \\ \texttt{msbt}(\mathsf{T}) &= \\ \begin{cases} \texttt{dac}(\mathsf{T}) & \texttt{pow2}(|\mathbf{S}_\mathsf{T}|) \\ \texttt{split}(\mathsf{T}, \texttt{msb}_1(|\mathbf{S}_\mathsf{T}|), \mathbf{p}_\mathsf{T}, \texttt{msbt}, 2\mathbf{p}_\mathsf{T}, \texttt{msbt}) & \neg \texttt{pow2}(|\mathbf{S}_\mathsf{T}|) \land \mathbf{p}_\mathsf{T} = \texttt{msb}_1(|\mathbf{S}_\mathsf{T}|) \\ \texttt{split}(\mathsf{T}, \texttt{msb}_1(|\mathbf{S}_\mathsf{T}|), \mathbf{p}_\mathsf{T}, \texttt{msbt}, \mathbf{p}_\mathsf{T}, \texttt{msbt}) & \text{otherwise} \end{cases} \end{split}$$

Both algorithms consists of three cases. The first case applies only to tiles that have a size that is a power of two. Those tiles are constructed using the dac-heuristic. The other two cases are quite similar; a piece of the tile is split off and the size of this piece is the least- and most-significant bit of the tile's size for lsbt and msbt respectively. The only difference between the two cases is the period of the part that is split off. If possible, i.e. if we still end up with a valid construction, this period is double the period of the original tile since it can be reused in that case.



Figure 5.4:  $G_g$  for the Bit-Pattern Tiling 1 and 2 algorithms for window size 6 (20 epw)

Both algorithms produce the same generator graph for our running example with window size 6 (see Figure 5.4), which costs 20 epw. However, there is very little reuse in this solution, so although the new algorithms improve upon the recursive tiling algorithm, they do not improve upon the divide and conquer algorithm. The LSB tiling algorithm produces, for windows of size 7, the same graph as the recursive tiling algorithm (shown in Figure 5.3) and thus has the same cost (20.5 epw). The MSB tiling algorithm also produces an already familiar graph for windows of size 7, namely the same one produced by the divide an conquer algorithm (Figure 5.1(b)) which has a cost of 28 epw.

#### 5.5 Split Tiling

The fact that power of two tiles can be formed relatively cheaply is exploited in the heuristic from the previous section, but not to its full extent. In this section we propose a heuristic that will form each window from a set of power of two tiles, just like the Bit-pattern tiling heuristic from the previous section, but there will be more (possible) orders in which these power of two tiles are combined. Most notably we make use of the fact that the merge operation is commutative (see Section 3.1), which allows us to construct tiles which are split by "holes". Hence we call this heuristic "Split Tiling".

This heuristic assumes that the period of the windows is one  $(\mathbf{p}_W = 1)$  and that the shape of the tile is solid to begin with, i.e.  $\mathbf{S}_W = \{0, \dots, |\mathbf{S}_W| - 1\}$ .

The algorithm works by first creating all tiles with a size that is a power of two and that have a period equal to their size. This can be done at a very low cost.

$$G = \text{TD}((\emptyset, \emptyset), ((\{0, \dots, msb(|\mathbf{S}_{\mathcal{W}}|) - 1\}, 0, \text{msb}_1(|\mathbf{S}_{\mathcal{W}}|)), \text{sth}))$$
  
sth(T) = split(T, |S\_T|/2, p\_T/2, sth, p\_T/2, sth)

This only generates part of the final generator graph. The second step is to use the tiles in this partial generator graph to form the window. Since the metaperiod of the graph created so far is  $\mathtt{msb}_1(|\mathbf{S}_{W}|)$ , there are  $\mathtt{msb}_1(|\mathbf{S}_{W}|)$  different combinations of tiles that form a window; one combination for each phase in the period  $\mathtt{msb}_1(|\mathbf{S}_{W}|)$ . The combination of tiles that form the window at phase *i* is expressed by  $\mathtt{comb}(i)$ :

$$\begin{array}{lll} \operatorname{comb}(f) &=& \operatorname{cr}(|\mathbf{S}_{\mathcal{W}}|, f) \\ \operatorname{cr}(s, f) &=& \operatorname{ct}(\operatorname{gt}(\operatorname{msb}_1(s), f)) \cup \operatorname{cr}(s - \operatorname{gt}(\operatorname{msb}_1(s), f), f + \operatorname{gt}(\operatorname{msb}_1(s), f)) \\ \operatorname{ct}(s, f) &=& \{(\{0, \dots, s - 1\}, f, s)\} \\ \operatorname{gt}(s, f) &=& \begin{cases} s & f \mod s = 0 \\ \operatorname{gt}(s/2, f) & f \mod s \neq 0 \end{cases} \end{array}$$

The function gt returns the size of the largest tile smaller than or equal to s that starts at phase f. This function is then used by the recursive function cr to find the set of triples describing the tiles that will form the window. The function cr returns the set of tiles that form a tile of size s at phase f. The function ct is used to construct the actual triple, based on its size. Note that this triple is not normalized. This is done to make sure that the set returned by cr contains one triple for each tile used in the construction of the window. For example: constructing the tiles from tile( $\blacksquare\blacksquare\blacksquare$ , 1, 4) requires tiles from tile( $\blacksquare$ , 1, 1), tile( $\blacksquare\blacksquare$ , 2, 2) and tile( $\blacksquare\blacksquare$ , 4, 2). If we would normalize the triples we would end up with only two distinct triples, and the implicit information in the phase would be destroyed too.

Now, the order in which those tiles are combined can be varied, therefore we have made three variants of this heuristic. These variants are named "Split Tiling 1", "Split Tiling 2" and "Split Tiling 3" respectively. Each of the split tiling algorithm variants generates a partial generator graph  $G_i$  based on comb(i)for  $0 \le i < \text{msb}_1(|\mathbf{S}_W|)$ . We then combine all the partial generator graphs to create the final generator graph like so:

$$G_g = G_b \cup (\cup i: 0 \le i < \mathsf{msb}_1(|\mathbf{S}_{\mathcal{W}}|): G_i)$$

To generate the partial graphs  $G_i$  all the variants of this heuristic have to merge the tiles in comb(i) until the entire window is formed. This bottom up

approach can be expressed as follows:

The ST function generates the partial generator graph  $G_i$  by repeatedly taking two tiles from the set S, merging them and adding them to  $G_i$ . This will eventually lead to a single tile in the set S (the window at phase i), which indicates that the partial graph is finished. If the recursion is not yet finished the ST function uses the function ma to merge two tiles and add the new tile and its construction method to  $G_i$ . It does this by using mt which merges the tile, which in turn uses ms to merge the shape of the tiles. The function sup is used to update the set of tiles that still have to be merged.

The selection of the tiles from the set S is determined by the selection function f, which differs per variant of the split tiling algorithm. The function  $f(S) = (T_1, T_2, f_1)$  returns a triple with  $T_1 \in S$  and  $T_2 \in S$  indicating the tiles to be merged and  $f_1$  indicating a (possibly) new selection function for the next step in the algorithm.

So, in contrast to the algorithms discussed so far the "Split Tiling" approach is bottom-up; given some tiles it constructs the windows. Whereas the other algorithms are top-down approaches; given the window they decide in which way it should be split.

The differences between the variants of the "Split Tiling" algorithm lie in the selection function and for "Split Tiling 1" we have  $G_i = ST((\emptyset, \emptyset), comb(i), st1)$ :

$$st1(S) = (\downarrow S, \downarrow (S \setminus \{\downarrow S\}), st1)$$

So "Split Tiling 1" simply keeps on merging the smallest tiles in the set, until the entire window has been constructed.

For "Split Tiling 2" we have  $G_i = ST((\emptyset, \emptyset), comb(i), st2(i))$ :

$$\begin{array}{lll} \mathtt{st2}(i)(S) &= \begin{cases} \mathtt{st2a}(i)(S) & (\exists \mathsf{T}_1,\mathsf{T}_2:\mathsf{T}_1,\mathsf{T}_2\in (S\cap\mathtt{comb}(i))\wedge \\ & \mathsf{T}_1\neq\mathsf{T}_2:|\mathtt{S}_{\mathsf{T}_1}|=|\mathtt{S}_{\mathsf{T}_2}| \\ & \mathtt{st1}(S) & \mathtt{otherwise} \end{cases} \\ \mathtt{st2a}(i)(S) &= & (\mathsf{T}_1,\mathsf{T}_2,\mathtt{st2}) \ \mathtt{such that:} \\ & |\mathtt{S}_{\mathsf{T}_1}| &= & |\mathtt{S}_{\mathsf{T}_2}| \\ & \mathsf{T}_1,\mathsf{T}_2 &\in & (S\cap\mathtt{comb}(i)) \\ & \mathsf{T}_1 &\neq & \mathsf{T}_2 \\ & |\mathtt{S}_{\mathsf{T}_1}| &= & (\downarrow \mathsf{T}_3,\mathsf{T}_4:\mathsf{T}_3,\mathsf{T}_4\in (S\cap\mathtt{comb}(i))\wedge \\ & & \mathsf{T}_3\neq\mathsf{T}_4\wedge|\mathtt{S}_{\mathsf{T}_3}|=|\mathtt{S}_{\mathsf{T}_4}|:|\mathtt{S}_{\mathsf{T}_3}|) \end{cases} \end{array}$$

This variant first merges all the initial tiles of the same size, and only after that it starts merging the smallest tiles until the entire window is formed. The idea
is that Batcher's merging networks are more efficient when lists of the same size are merged.

For "Split Tiling 3" we have  $G_i = ST((\emptyset, \emptyset), comb(i), st3)$ :

$$\begin{array}{lll} {\rm st3}(S) & = & \begin{cases} {\rm st3a}(S) & (\exists \mathsf{T}_1,\mathsf{T}_2:\mathsf{T}_1,\mathsf{T}_2\in S\wedge\mathsf{T}_1\neq\mathsf{T}_2:|\mathbf{S}_{\mathsf{T}_1}|=|\mathbf{S}_{\mathsf{T}_2}|) \\ {\rm st3b}(S) & \text{otherwise} \end{cases} \\ {\rm st3a}(S) & = & (\mathsf{T}_1,\mathsf{T}_2,\mathsf{st3}) \text{ such that} \\ & |\mathbf{S}_{\mathsf{T}_1}| & = & |\mathbf{S}_{\mathsf{T}_2}|\wedge\mathsf{T}_1,\mathsf{T}_2\in S\wedge\mathsf{T}_1\neq\mathsf{T}_2 \\ & |\mathbf{S}_{\mathsf{T}_1}| & = & (\downarrow\mathsf{T}_3,\mathsf{T}_4:\mathsf{T}_3,\mathsf{T}_4\in S\wedge\mathsf{T}_3\neq\mathsf{T}_4\wedge|\mathbf{S}_{\mathsf{T}_3}|=|\mathbf{S}_{\mathsf{T}_4}|:|\mathbf{S}_{\mathsf{T}_3}|) \\ {\rm st3b}(S) & = & ((\uparrow S,\uparrow(S\setminus\{\uparrow S\})),\mathsf{st3b}) \end{cases} \end{array}$$

This variant first merges all the tiles of the same size in S. If all the tiles have different sizes it simply starts merging the largest two tiles.



Figure 5.5:  $G_g$  for the Split Tiling 1,2 and 3 algorithms for window size 6 (17 epw)

For windows of size 6 all three variants of the algorithm produce the same generator graph (depicted in Figure 5.5), with a cost of 17 epw. This is an improvement over all the algorithms we have seen so far. This is not surprising since this is the first design for this problem in which tiles of size 4 are reused. For windows of size 7 the first variant produces the generator graph in Figure 5.6 with a cost of 22.5 epw and the other two variants produce the same graph as the recursive tiling algorithm (Figure 5.3) with a cost of 20.5 extrema operations.

### 5.6 Overlap Recursive Mirroring

So far our algorithms have attempted to maximize reuse by following some algorithm based on the shape of the windows. However, the cost of the generator



Figure 5.6:  $G_q$  for the Split Tiling 1 algorithm for window size 7 (22.5 epw)

graph also depends on l and u and we can obtain better results by taking a look at the possible ways of reuse and selecting the best one based on the cost function. This is what the "Overlap Recursive Mirroring" algorithm does.

For every tile it has to construct the heuristic checks whether that tile is a hyper-bar and whether it overlaps with the next (periodic) version of itself. If this is the case the overlapping part is a good candidate for an intermediate tile. Of course, a tile may overlap with multiple versions of itself. The overlapping part of multiple versions is smaller than the overlapping part of two single versions, but the former can be reused multiple times. This is a difficult tradeoff and the "ORM" algorithm makes this trade-off by simply trying a number of possibilities and selecting the one with the lowest cost.

To keep the calculation time under control we introduce the parameter R which indicates the maximum number of times an overlap is re-used. So, for R = 0 the algorithm only considers constructing the tile without making use of any overlap. For R = 1 it also considers constructing a tile by re-using the overlap between two consecutive occurrences of a tile. For R = 2 it considers all the possibilities of R = 1 and the possibility of re-using the overlap between three consecutive occurrences of a tile. And so forth for larger values of R.

The function ovl(T) returns the set of possible manners in which tiles from tile(T) can be overlapped with periodic versions of itself, given that the tile is a hyper-bar.

$$\operatorname{ovl}(R,\mathsf{T}) = \{ \mathbf{g} | \mathbf{g} \in \operatorname{hyperbar}(R \ \mathbf{1}_D) \land (\mathbf{S}_{\mathsf{T}} \cap (\mathbf{g} \cdot \mathbf{p}_{\mathsf{T}} + \mathbf{S}_{\mathsf{T}})) \neq \emptyset \}$$

So each element of the returned set is a vector. This vector no longer represents a coordinate on the grid, but a way in which the tiles overlap with other tiles from the same tile-set. So (0,0) means no overlapping, (1,0) means that a tile overlaps with the next tile in the first dimension, but that there is no overlapping in the second dimension. This function is used to generate the set of overlaps considered by the algorithm. Note that the parameter R is used here to keep the number of possibilities in check.

Note that we only apply the ovl function when  $S_T$  is a hyper bar. We do this because this makes it possible to implement the ovl function in a fast manner in practice. Whenever the tile is not a hyper-bar we only consider the overlaps represented by the set  $\{0_D\}$ .

Other functions that deal with the overlapping part are:

$$\begin{array}{lll} \mathsf{os}(\mathsf{T},\mathbf{o}) &=& (\cap \mathbf{g}:\mathbf{g}\in \mathtt{hyperbar}(\mathbf{o}+\mathbf{1}_D):\mathbf{S}_\mathsf{T}+\mathbf{g}\cdot\mathbf{p}_\mathsf{T}) \\ \mathsf{op}(\mathsf{T},\mathbf{o}) &=& (\mathbf{o}+\mathbf{1}_D)\cdot\mathbf{p}_\mathsf{T} \\ \mathsf{ot}(\mathsf{T},\mathbf{o}) &=& \mathtt{norm}(\mathsf{os}(\mathsf{T},\mathbf{o}),\mathbf{f}_\mathsf{T},\mathsf{op}(\mathsf{T},\mathbf{o})) \end{array}$$

In these functions the parameter **o** is an element of the set produced by the ovl function that indicates the manner of overlap under consideration. The function os returns the shape of the overlapping part of the tiles, op the period and ot returns the normalized triple representing the tile-set of overlapping parts.

The generator graph created by the function orm heuristic:

$$\begin{array}{lll} G_g & = & \operatorname{orm}(R, (\emptyset, \emptyset), \operatorname{norm}(\mathsf{W})) \\ \operatorname{orm}(R, G_g, \mathsf{T}) & \in & \{\operatorname{ov}(G_g, \mathsf{T}, \mathbf{o}) | \mathbf{o} \in \operatorname{ovl}(R, \mathsf{T})\} \\ & \text{such that} & & \operatorname{C}(\operatorname{orm}(R, G_g, \mathsf{T})) = (\downarrow \mathbf{o} : \mathbf{o} \in \operatorname{ovl}(R, \mathsf{T}) : \operatorname{C}(\operatorname{ov}(G_g, \mathsf{T}, \mathbf{o}))) \end{array}$$

Note that we abuse the notation here slightly; the cost function C should receive a calculation graph instead of a generator graph as its parameter. We allow this, however, since the cost can be calculated from the generator graph directly (see Section 4.3).

The function orm simply selects the best generator graph generated by the ov function. This ov function generates a generator graph by using the given overlapping pattern o for the tile T.

$$\mathsf{ov}(G_g,\mathsf{T},\mathbf{o}) = \begin{cases} \mathsf{nov}(G_g,\mathsf{T}) & \mathbf{o} = \mathbf{0}_D\\ \mathsf{ovt}(G_g,\mathsf{T},\mathbf{o}) & \text{otherwise} \end{cases}$$

The generator graph in which no overlap for tiles in T is used is generated by nov and the generator graph in which overlap is used is generated by ovt.

An example: The tiles defined by the triple  $T = (\blacksquare\blacksquare\blacksquare, 0, 1)$  overlap each other. For R = 0 the algorithm constructs the tile without exploiting any overlap in the tiles. This method is explained later on in this section. For R = 1 the algorithm also considers constructing  $(\blacksquare\blacksquare\blacksquare, 1, 2)$  as an intermediate result, since these tiles are the overlapping part of two consecutive tiles from T. For R = 2 the algorithm considers all the previous possibilities and also the construction of  $(\blacksquare\blacksquare, 2, 3)$ , since those tiles are the overlapping part of three consecutive tiles from T.

So, that is where the "Overlap" part of the algorithm's name comes from. The "Recursive" part is because this algorithm is applied recursively to the resulting intermediate tiles. And the "Mirroring" part is because the shape of tiles that have to be constructed to form the original tiles in combination with the overlap are mirror symmetric. In the last case from our example we construct ( $\blacksquare \blacksquare, 2, 3$ ) as the overlap and we would need ( $\blacksquare \blacksquare, 0, 3$ ), ( $\blacksquare \square \square \blacksquare, 1, 3$ ) and ( $\blacksquare \blacksquare, 4, 3$ ) to be able to construct T.

This is all done by the ovt function:

$$\begin{array}{lll} \texttt{ovt}(G_g,\mathsf{T},\mathbf{o}) &=& \texttt{pq}_1(G_g,\mathsf{T},\texttt{ot}(\mathsf{T},\mathbf{o}),\texttt{enq}(\mathsf{T},\mathbf{o}),\{\texttt{ot}(\mathsf{T},\mathbf{o})\})\\ \texttt{rt}(\mathsf{T},\mathbf{o},\mathbf{g}) &=& \texttt{norm}((\mathbf{S}_\mathsf{T}+\mathbf{g}\cdot\mathbf{p}_\mathsf{T})\setminus\texttt{os}(\mathsf{T},\mathbf{o}),\mathbf{f}_\mathsf{T}+\mathbf{g}\cdot\mathbf{p}_\mathsf{T},\texttt{op}(\mathsf{T},\mathbf{o}))\\ \texttt{enq}(\mathsf{T},\mathbf{o}) &=& \{\texttt{rt}(\mathsf{T},\mathbf{o},\mathbf{g})|\mathbf{g}\in\texttt{hyperbar}(\mathbf{o}+\mathbf{1}_D)\} \end{array}$$

The function rt calculates the triple representing the tile-sets describing the remaining (non-overlapping) parts at phase g for an overlapping pattern o. The function enq uses this function in turn to create a set the remaining parts for each phase. This set, or queue, is then processed by the following function to add the construction method (overlapping part and the remaining part) for the tiles of T to the generator graph for each of the phases:

$$pq_1(G_g, \mathsf{T}, \mathsf{O}, Q_1, Q_2) = \begin{cases} pq_2(G_g, Q_2) & Q_1 = \emptyset \\ pq_1(\mathsf{add}(G_g, (\mathbf{S}_\mathsf{T}, \mathbf{p}_\mathsf{Q}, \mathbf{f}_\mathsf{Q}), \mathsf{T}, \mathsf{O}, \mathsf{Q}), \mathsf{O}, \\ Q_1 \setminus \{\mathsf{Q}\}, Q_2 \cup \{\mathsf{Q}\}) \text{ with } \mathsf{Q} \in Q_1 \quad \text{otherwise} \end{cases}$$

The  $pq_2$  function is then used to make sure that the tiles used in the construction are actually constructed themselves using the **orm** heuristic:

$$\mathtt{pq}_2(G_g,Q) \quad = \quad \begin{cases} G_g & Q = \emptyset \\ \mathtt{pq2}(\mathtt{orm}(G_g, \mathop{\downarrow} Q), Q \setminus \{\mathop{\downarrow} Q\}) & \text{otherwise} \end{cases}$$

This is how the ovt function is used to construct tiles with overlap. The nov is used when the algorithm decides to consider the possibility of constructing a tile without overlap (either as one of the possibilities, or because the tile simply does not overlap). The function searches in the tiles generated so far for any tile that overlaps with the tile that is to be constructed. At the very least it finds  $(\blacksquare, 0, 1)$ , but perhaps it can find something bigger. If the tile it finds is of "reasonable" size, it is used in the construction. Otherwise the tile to be constructed is simply created by splitting it into two parts. This splitting is done in one of two ways: if the tile is not a hyper-bar (i.e. it contains gaps) then the largest possible hyper-bar is found and split from the tile. If the tile is a hyper-bar we take the dimension in which it is largest (say size x) and split the tile along that dimension in a tile of size  $lsb_1(x)$  and  $x - lsb_1(x)$ .

The algorithm decides what a "reasonable" size is by estimating the amount of work that still has to be done after the available tile has been reused. It does this by taking the size of the tile and subtracting the size of the available tile. It then estimates the amount of work that has to be done if the tile is split. It does this by taking the size of the largest of the two components in which the tile should be split. The idea here is that the smaller of the two parts is reused in the larger part, so that no extra costs are incurred for the smaller part. These two estimates are compared and the one that is estimated to lead to the lowest cost is used.

So, the construction of tiles without reusing the overlap is done as follows:

$$\begin{split} \mathsf{nov}(G_g,\mathsf{T}) &= & \mathsf{orm}(\mathsf{arm}(\mathsf{add}(G_g,\mathsf{T},\mathsf{T}_1,\mathsf{T}_2),\mathsf{T}_1),\mathsf{T}_2) \\ & & \text{where } (\mathsf{T}_1,\mathsf{T}_2) = \mathsf{ch}(V_g,\mathsf{T}) \end{split}$$

The function **nov** adds the construction method specified by the function **ch** to the generator graph and calls **orm** to add the composing tile sets to the generator graph. The function **ch** makes the choice between either by reusing available tiles, or by splitting the tile without reuse:

$$\begin{aligned} \mathsf{ch}(V_g,\mathsf{T}) &= \begin{cases} \mathsf{reu}(V_g,\mathsf{T}) & (|\mathbf{S}_\mathsf{T}| - |\mathbf{S}_{\mathsf{T}_2}|) \leq (|\mathbf{S}_{\mathsf{T}_3}| \uparrow |\mathbf{S}_{\mathsf{T}_4}|) \\ \mathsf{spl}(\mathsf{T}) & \text{otherwise} \\ & \text{where } (\mathsf{T}_1,\mathsf{T}_2) = \mathsf{reu}(V_g,\mathsf{T}) \land (\mathsf{T}_3,\mathsf{T}_4) = \mathsf{spl}(\mathsf{T}) \end{aligned}$$

Splitting depends on whether the shape is a hyper-bar or not:

$$spl(T) = \begin{cases} spl_1(T) & S_T \text{ is a hyberbar} \\ spl_2(T) & \text{otherwise} \end{cases}$$

If the shape happens to be a hyper-bar we split it along the largest dimension:

$$\begin{aligned} & \operatorname{spl}_1(\mathsf{T}) &= (\operatorname{norm}(\mathbf{S}_{\mathsf{T}_1}, \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{\mathsf{T}}), \operatorname{norm}(\mathbf{S}_{\mathsf{T}_2}, \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{\mathsf{T}})) \text{ such that} \\ & \mathbf{S}_{\mathsf{T}} &= \operatorname{hyperbar}(\mathbf{q}) \\ & \mathbf{S}_{\mathsf{T}_1} &= \operatorname{hyperbar}(\mathbf{r}) \\ & \mathbf{S}_{\mathsf{T}_2} &= \mathbf{S}_{\mathsf{T}} \setminus \mathbf{S}_{\mathsf{T}_1} \\ & \mathbf{r}(e) &= \mathbf{1} \operatorname{sb}_1(\mathbf{q}(e)) \\ & (\forall d: 0 \le d < D \land d \ne e: \mathbf{r}(d) = \mathbf{q}(d)) \\ & (\forall d: 0 \le d < D: \mathbf{q}(d) \le \mathbf{q}(e)) \end{aligned}$$

Otherwise we just extract the largest hyper-bar from the shape:

$$\begin{split} & \mathtt{spl}_2(\mathsf{T}) &= (\mathtt{norm}(\mathbf{S}_{\mathsf{T}_1}, \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{\mathsf{T}}), \mathtt{norm}(\mathbf{S}_{\mathsf{T}_2}, \mathbf{f}_{\mathsf{T}}, \mathbf{p}_{\mathsf{T}})) \text{ such that } \\ & \mathbf{S}_{\mathsf{T}_2} &= \mathbf{S}_{\mathsf{T}} \setminus \mathbf{S}_{\mathsf{T}_1} \\ & \mathbf{S}_{\mathsf{T}_1} &= \text{ the largest hyper-bar in } \mathbf{S}_{\mathsf{T}} \end{split}$$

The **reu** function returns, given an original tile, a triple containing an already existing tile that can be reused and the rest of the original tile.

$$\begin{aligned} \mathbf{reu}(V_g,\mathsf{T}) &= (\mathsf{T}_1, \mathtt{norm}((\mathbf{S}_{\mathsf{T}} + \mathbf{f}_{\mathsf{T}}) \setminus (\mathbf{S}_{\mathsf{T}_1} + \mathbf{g} \cdot \mathbf{p}_{\mathsf{T}_1} + \mathbf{f}_{\mathsf{T}_1}), 0, \mathbf{p}_{\mathsf{T}})) \text{ such that} \\ \mathbf{g} &\in \mathbb{Z}^D \\ \mathsf{T}_1 &= \uparrow \{\mathsf{T}_2 | \mathsf{T}_2 \in V_g \land (\mathbf{p}_{\mathsf{T}} \bmod \mathbf{p}_{\mathsf{T}_2} = 0) \land \\ & (\mathbf{S}_{\mathsf{T}_2} + \mathbf{g} \cdot \mathbf{p}_{\mathsf{T}_2} + \mathbf{f}_{\mathsf{T}_2}) \subseteq (\mathbf{S}_{\mathsf{T}} + \mathbf{f}_{\mathsf{T}})) \} \end{aligned}$$

Where the set from which  $T_1$  is selected is the set containing all the triples describing tile set of which all the tiles are a subset of a tile described by T.

Furthermore, this set is constructed in such a way that the tiles occur at a regular position in T, which is expressed by the variable g.

Note that an increase in R generally results in lower cost generator graphs, since the algorithm considers more generator graphs. However, it does not necessarily mean that it considers a superset. Therefore it is not guaranteed that an increase in R leads to a reduction in cost. The two dimensional median filtering is a good example of this (see Appendix A.2.2). Consider the following example; the function orm selects the best generator graphs generated by the ov function. For R = 1 the best graph it encounters is  $G_1$ . For R = 2 it also encounters  $G_1$ , but also the slightly better  $G_2$ . So the R = 1 algorithm selects  $G_1$  and the R = 2 algorithm selects  $G_2$ . However, if this happens to be an intermediate step in the generation of the final graph, then there are still some tiles that have to be added to the selected graph. The cost of adding tiles depends on the chosen graph, since tiles already in the chosen graph might be reused. It is possible that some of the tiles which are to be added can be constructed with more reuse in  $G_1$  than in  $G_2$ . The net effect of this is that the final calculation graph produced by the R = 1 algorithm can be less costly than the R = 2 algorithm, because the R = 1 algorithm based its solution on the (at first sight slightly more costly)  $G_1$  graph.



Figure 5.7:  $G_g$  for the ORM 1 algorithm for window size 6 (17.5 epw)

The generator graph produced by this algorithm for our running example with window sizes 6 for R = 1 is shown in Figure 5.7. This generator graph has a cost of 17.5 epw, which is slightly more expensive than our best solution so far. But when the parameter R is increased to 2 we get the generator graph



Figure 5.8: A generator graph  $G_q(V_q, E_q)$  for  $\mathcal{W} = \texttt{tile}(\texttt{EFEEE}, 0, 1)$  (16 epw)

from Figure 5.8. The reuse of the tile of size 4 gives this solution its efficiency and results in a cost of 16 epw, which is the lowest cost found by our algorithms. For the running example with window sizes 7 the ORM algorithm produces the same calculation graphs as the recursive tiling algorithm (depicted in Figure 5.3), with a cost of 20.5 extrema operations, which is also the lowest cost found by our algorithms.

### 5.7 Multiple Dimensions

Most of our algorithms (except for Overlap Recursive Mirroring) are designed for one dimensional problems. However, they can be generalized to algorithms for multi-dimensional problems using the method described in this section.

This method is only applicable for a certain class of problems, namely the class of problems whose windows have the shape of a hyper-bar.

$$(\exists s : s \in \mathbb{Z}^{\mathcal{D}} : \mathbf{S}_{\mathcal{W}} = \texttt{hyperbar}(s)) \tag{5.5}$$

The generalized algorithm then functions as follows: We first use the onedimensional algorithm to produce a solution for windows of size  $\mathbf{s}(0)$ . This solution shows us how we can construct those windows from tiles of size 1. We then take this solution and extend all the generated tiles into another dimension. All the tiles get a size of  $\mathbf{s}(1)$  in this dimension. The construction methods we have for all the tiles are still valid, except for the tiles of size  $1 \times \mathbf{s}(1)$ . We never generated a construction method for them because they used to be of size 1 in the one-dimensional problem.

So now we execute the algorithm again, but take the tiles with size  $1 \times s(1)$  as the new windows and generate a way to constructing these tiles. Since these tiles only have a size larger than one in the second dimension, they can be considered one dimensional in practice and the algorithm can be executed normally on them.

We repeat this process as often as necessary to get a solution in all the dimensions.

#### 5.8 Maximum reuse

Upon reviewing this report prior to publication we were able to devise a new heuristic which we call the "Maximum Reuse" heuristic. This heuristic is for one dimensional windows, but can be generalized for multi dimensional windows as described in the previous section.

The algorithm works like the ORM 1 algorithm, but instead of choosing between no overlap and reusing the overlap between two successive windows it always chooses for the reuse. Hence the name of this heuristic, since this method results in that the largest possible tile being reused. But only the overlapping tile is fed back into the maximum reuse heuristic, all other tiles, and tiles with no overlap are created using the msbt heuristic.

This new heuristic provides solutions that are close (in cost) to those of the ORM 1 algorithm. Since it is not an improvement upon the ORM algorithm we have not updated the tables and graphs in this report. However, the new heuristic deserves to be mentioned here because its running time is much lower than that of any of the ORM algorithms.

### Chapter 6

# Results

In the previous chapters we have presented several heuristic algorithms that find generator graphs for specific ROFs. Although we have not yet discussed how an abstract representation in the format of a generator graph can be turned into a concrete implementation, we can already determine the performance of such an abstract filter in terms of extrema operations per window. In this chapter we use this performance measure for two purposes. First we compare the heuristic algorithms from Chapter 5. Second we compare our best abstract designs to designs found in the literature.

#### 6.1 Filter classes

In this section we define the three filter classes that we use to evaluate the heuristic algorithms. These three classes are chosen such that they are representative for filters commonly found in literature and provide sufficient variety to illustrate the differences between the heuristic algorithms.

Although our implementations could easily generate calculation graphs for ROFDPs with an arbitrary number of dimensions, we restrict our attention to one- and two-dimensional cases, where in the latter case we only consider square windows. Although for each window size there are many rank order filters that select a single rank and many more that select an interval of ranks, we restricted our attention to the following three classes:

- Window sorters Since in a window sorter all the ranks are obtained, this class gives us an upper-bound for any filter which has to select one or more ranks.
- Median filters This rank order filter is interesting because the median is the most costly single rank that we could wish to obtain.
- Minimum filters This rank order filter is interesting because the minimum is the least costly single rank that we could wish to obtain. Note that the minimum filter, on grounds of symmetry, cost the same as the maximum filter.

#### 6.2 Heuristic algorithm evaluation

In this section we compare the heuristic algorithms from Chapter 5 by studying their performance on the various filter classes defined in the previous section.

The results of the heuristic algorithms for the classes are plotted in Figures 6.1, 6.2, 6.3, 6.4, 6.5 and 6.6. In all figures the vertical axis shows the cost of the resulting calculation graph in extrema operations per window. The horizontal axis contains the window size. The results of the different heuristic algorithms have been plotted using distinct symbols and colors.

The graphs (sub-figures (a)) show us that the same algorithm can exhibit a quite different trend when it is applied to a different class of filters. All algorithms, for example, display roughly the same, approximately linear, trend when applied to window sorting (except for LSB tiling). However, when those same algorithms are applied to the median filtering algorithm they show different trends; the divide and conquer algorithm shows a linear trend, while the ORM algorithms seem to indicate a logarithmic curve. This difference also holds for the minimum filtering problem, where the divide and conquer algorithm appears to be logarithmic, but the ORM algorithms seem to have an almost constant upper-bound.

Despite the difference in trends the ORM algorithm produces the best filter in each of the three classes. Specifically it is the ORM 4 algorithm (displayed by the small dots) that provides the design with the lowest cost, compared to the other algorithms.

Since we are mainly interested in these best designs, we limit our examination of the trends to the trend of the ORM algorithm. To this end the figures also contain a graph (sub-figures (b)) that contains the results of the ORM algorithms for a specific R, with a curve fitted to the data points. For the 1dimensional cases these graphs contain the results for R = 4. However, for the 2dimensional cases the original graphs contain too few data points to examine the trend effectively. This was solved by taking larger window sizes and generating additional designs. However, the running time of the ORM algorithm for larger window sizes is impractical for larger R and therefore we opted to use ORM 1 algorithm instead.

The curve fitting for both the window sorting and median filtering for 1dimensional problems is quite satisfactory. The window sorting seems to follow a linear curve, while the median filtering problem exhibits a logarithmic curve. The 2-dimensional variants are fitted with the same curve as the 1dimensional variants. Even though the curve fits well the predictive quality of the 2-dimensional curves is questionable.

It is possible that the curves would fit better if we had fitted them to the results of the ORM algorithm with a larger parameter R. After all, we see that the ORM algorithms produce approximately the same results for smaller window sizes, but for larger windows the ORM algorithms with a higher R produce better results.

The minimum filtering problem seems to be in another category entirely. Fitting a curve to it proves difficult and we have not been able to find an appropriate one. It seems that the one dimensional variant requires between three and four extrema operations for all the window sizes we examined. The 2dimensional variant seems to require between four and eight extrema operations.

The cost of the minimum filter increases with the size of the window, but this



(a) All algorithms





Figure 6.1: 1-Dimensional Window Sorting









• • • .

Figure 6.2: 2-Dimensional Window Sorting



(a) All algorithms





Figure 6.3: 1-Dimensional Median Filter



(a) All algorithms



(c) Legend

• • .

Figure 6.4: 2-Dimensional Median Filter



(a) All algorithms







Figure 6.5: 1-Dimensional Minimum Filter



(a) All algorithms







Figure 6.6: 2-Dimensional Minimum Filter

increase is extremely small. So it is safe to say that implementing a minimum (or maximum) filter requires very few extrema operations, regardless of the number of dimensions and the window size. This is interesting since the best solutions for minimum filter are actually the best solutions for any problem where the cost function always returns a cost of 1 operation. This is discussed in more detail in Chapter 8.

#### 6.3 Comparison with known filters

In the previous section we compared the heuristic algorithms. In this section we compare the results found by our best algorithm with filters taken from the literature. Whenever a publication contains multiple filters for the same ROFDP we have compared our solution with the best one in the publication. These comparisons are based on the cost of the filter in epw. Note that for some publications this measure requires the conversion of the cost in C&S operations (as presented in the publication) to the cost in extrema operations. We do this using the rule that 1 C&S operation costs 2 extrema operations. This conversion is not entirely fair; it might be possible to prune some of those extrema operations, but this can only be done when the design is known. However, most publications only mention their design method and the cost of the resulting filters, but not the filters themselves. Therefore we mark all the costs that have been converted with "\*", to indicate that the cost might be lower if extrema operations are pruned.

#### 6.3.1 Window sorters

In this section we survey the first class of problems: the window sorters. We first examine the one-dimensional cases, followed by the two-dimensional cases.

Window	ORM 4	Lucke&Parhi[9]
3	5.00	$5.00^{*}$
5	12.00	$12.00^{*}$
6	16.00	$15.00^{*}$
7	20.50	$20.88^{*}$
9	29.00	$29.00^{*}$

Table 6.1: Cost of known solutions for 1-dimensional window sorting

Table 6.1 contains the costs of one-dimensional window sorters. Lucke and Parhi examine such window sorters, which they call merge sorters (because of the merging used), in the first part of their paper [9]. Their method is quite similar to our ORM algorithm, in that it exploits overlap between successive windows. However, instead of working with infinite input streams they optimize for a fixed number of overlapping windows, which they call the block size. For all block sizes considered the results shown in Table 6.1 are the best results reported by them.

In one specific instance in Table 6.1, indeed in anything we found in the literature, there is a better solution than the one found by the ORM algorithm. The 1-dimensional window sorter for  $|\mathbf{S}_{W}| = 6$  by Lucke and Parhi [9] requires

only 15 epw, compared to the 16 required by the solution of the ORM algorithm. Unfortunately we cannot explain this anomaly since we have been unable to reconstruct the design of Lucke and Parhi using the algorithm described in their article.

Window	ORM 4	Kolte et al.[8]	Lucke&Parhi[9]
$3 \times 3$	35.00	50.00	37.50*
$4 \times 4$	76.00	128.00	
$5 \times 5$	152.00	288.00	$180.44^{*}$
$6 \times 6$	254.50	520.00	
$7 \times 7$	379.00	820.00	
$8 \times 8$	526.67	1,232.00	
$9 \times 9$	711.00	$1,\!804.00$	
$10 \times 10$	940.71	2,522.00	
$11 \times 11$	1,169.13	$3,\!346.00$	
$12 \times 12$	1,379.83	4,400.00	
$13 \times 13$	1,688.85	$5,\!572.00$	
$14 \times 14$	2,017.88	$7,\!050.00$	
$15 \times 15$	2,339.65	$8,\!494.00$	
$16 \times 16$	2,627.45	$10,\!348.00$	

Table 6.2: Known solutions for 2-dimensional window sorting

Lucke and Parhi also examined 2-dimensional window sorters [9] and so did Kolte, Smith and Su in their paper [8]. The results from these papers are shown in Table 6.2 and compared to our ORM 4 algorithm. Again the ORM 4 algorithm performs best, but the results of Lucke and Parhi come very close. Although the focus of Kolte et al. lies on finding implementations that are easy to implement on a SIMD processor, they nevertheless manage to get good results.

#### 6.3.2 Median filter

In this section we survey the second class of problems: the median filters. We first examine the one-dimensional cases, followed by the two-dimensional cases.

Window	ORM 4	Chakrabarti[2]	Lucke&Parhi[9]
3	3.00	5.00*	
5	5.00	11.20*	$31.00^{*}$
7	8.50	$19.66^{*}$	
9	10.00	$32.00^{*}$	

Table 6.3: Known solutions for 1-dimensional median filtering

In the article [9] Lucke and Parhi also make an excursion to the median filter. Their approach is to specify the median filter as a stack filter in a maxmin structure and then applying their method for implementing stack filters. However, as shown in Table 6.3 the resulting solution is not very efficient. In fact, it is less costly to implement a window sorter according to their own method (see Table 6.1) than it is to implement a median filter (for  $|\mathbf{S}_{W}| = 5$ ).

Chakrabarti focusses entirely on 1-dimensional median filters in his paper [2] and achieves better results. In a later publication with Wang [3] he also considers 2-dimensional median filtering and again obtains good results (see Table 6.4). Still, the ORM 4 algorithm produces even better results.

Window	ORM 4	Chakrabarti &	Kolte et al.[8]
		Wang [3]	
$3 \times 3$	16.00	26.00*	17.00
$5 \times 5$	53.00	61.00*	107.00
$7 \times 7$	105.75		317.00
$9 \times 9$	171.00		685.00
$11 \times 11$	232.75		1254.00
$13 \times 13$	321.25		2036.00
$15 \times 15$	404.38		3018.00

Table 6.4: Known solutions for 2-dimensional median filtering

#### 6.3.3 Minimum filter

In this section we examine the third and final class of filters, namely the minimum filters. There has been little attention for the minimum filter in the literature, but Harrington [5] has examined the problem and has patented a novel method for both 1 and 2-dimensional minimum filters. The 1-dimensional method proposed by Harrington requires just under 3 epw for any window size  $|\mathbf{S}_{\mathcal{W}}|$ . In most cases this is better than the solutions found by our algorithms. Our algorithms only obtain solutions with such a similar low cost for  $|\mathbf{S}_{\mathcal{W}}| = 2^i - 1$  for  $i \in \mathbb{Z}$ .

The two dimensional approach specified in [5], however, is less efficient. The proposed method for 2-dimensional rectangular windows requires just under 11 epw, which is more expensive than the solutions found by our algorithms. Furthermore, unlike our approach and the 1-dimensional approach from [5], the two dimensional approach in [5] is not suited for every associative operation. The method presented in the patent relies on combining overlapping tiles and thus it is only suited for idempotent operators like minimum and maximum.

#### 6.4 Summary

In the previous chapter we presented several heuristic algorithms that generate a generator graph and thus a design for a ROF. The so-called "Overlap Recursive Mirroring" or ORM algorithm is the best algorithm we designed. The only method we found in the literature that is capable of obtaining better results than our ORM algorithm is by Harrington [5], but only for 1-dimensional minimum filtering. The approach by Lucke and Parhi [9] is capable of obtaining similar results, but only for the window sorting problem. For the median filtering problem our ORM algorithm is the best so far.

The ORM algorithm has a parameter R that gives an indication of the search space covered by the algorithm. As R increases more and more possible designs are considered, and better designs are found. For R = 4 the ORM algorithm finds the better solutions than for R = 3, however in the majority of cases up to  $|\mathbf{S}_{\mathcal{W}}| \leq 250$  the ORM algorithm with R = 3 already provides the best solution. The solutions provided by R = 4 are only better in a handful of cases.

An overview of the costs of the designs generated by our algorithms can be found in Appendix A. Furthermore the detailed designs of several of the smaller solutions for window sorting and median filtering can be found in Appendix B.

### Chapter 7

# Parallel ROF Implementations

In this chapter we present two kinds of parallel ROF implementations, viz. implementations in the form of VLSI-circuits and implementations in the form of parallel programs suited for SIMD machines like the  $EVP_{16}$ . We discuss the scalability of the resulting implementations and for some specific 2-dimensional filters we provide the number of clock cycles per output required by the  $EVP_{16}$  solution. As an intermediate step towards a parallel implementation we first show how to obtain a sequential program and in passing we also show how to handle finite input streams.

### 7.1 Sequential Implementation

So far we have used calculation graphs as abstract representations of ROFs. Recall that a calculation graph is an acyclic graph whose nodes represent merging operations and whose edges represent the dependencies those operations. By sorting the nodes topologically we obtain an order in which to perform the merge operations and thereby a sequential program.

Unfortunately, because the calculation graph is an infinite graph the program is infinite as well. We can overcome this problem by introducing loops that capture the repetitive nature of the calculation graph.

This repetitive behavior is captured by the generator graph. Note that any two tiles (or windows) from the same tile-set in the generator graph are calculated in the same way and that these tiles are separated by a meta-period. Therefore we can obtain a loop in our program that handles one meta-period per iteration.

The number of windows in a single meta-period is  $I = \frac{meta-period}{\mathbf{p}_{\mathcal{W}}}$ , and this is therefore the number of windows which are calculated in a single iteration of the sequential program. This differs from common filtering programs which usually calculate only one result per iteration of the loop.

Because a single iteration of our program calculates I new windows it follows that all tiles needed for the calculation of those windows also need to be "obtained". We use the word *obtain* and not *calculate*, since there are two ways



Figure 7.1: A solution for  $\mathcal{W} = \texttt{tile}(\blacksquare\blacksquare, 0, 1)$ 

in which the tile can be obtained. On the one hand it can, of course, be calculated by merging the tiles on which it depends. These tiles, in turn, have to be obtained and the recursion ends in the tiles of size one, which form the actual inputs. On the other hand the memoization technique discussed in Section 3.3 can be used. Whenever a tile has been computed that is needed in a future iteration that tile is stored in memory, so that in future iterations the tile only needs to be retrieved, not calculated.

Note that tiles need not be stored indefinitely; by examining the calculation graph we can determine when tiles are no longer needed and remove them from memory. In fact the regularity of the calculation graph allows us to simply introduce a fixed number of buffers which are read and written in a regular pattern.

Whereas the number of windows per iteration is fixed at I, the phasing of the windows within the meta-period can be selected freely. This phase determines which of the actual windows are calculated in a single iteration. Therefore this choice affects the implementation, since it determines which tiles need to be buffered and therefore the size of the buffer.

As an illustration consider the ROFDP with  $\mathcal{W} = (\blacksquare\blacksquare\blacksquare, 0, 1)$  for which a solution is given in Figure 7.1. This figure shows the generator graph with metaperiod 2 and some tiles of the three tile sets tile( $\blacksquare\blacksquare\blacksquare, 0, 1$ ), tile( $\blacksquare\blacksquare, 1, 2$ ) and tile( $\blacksquare, 0, 1$ ). The construction of these individual tiles can be derived from the generator graph:

$$\begin{array}{rclcrcl} {\bf B}_{2i+1} & = & {\bf A}_{2i+1} \Join {\bf A}_{2i+2} \\ {\bf W}_{2i} & = & {\bf A}_{2i} \Join {\bf B}_{2i+1} \\ {\bf W}_{2i+1} & = & {\bf B}_{2i+1} \Join {\bf A}_{2i+3} \end{array}$$

If we choose phase 0, then  $\mathbf{W}_{2i}$  and  $\mathbf{W}_{2i+1}$  (for  $i \in \mathbb{Z}$ ) would fall into the same meta-period. So the iteration that calculates  $\mathbf{W}_0$  and  $\mathbf{W}_1$  needs to obtain tiles  $\mathbf{A}_0$ ,  $\mathbf{B}_1$ ,  $\mathbf{A}_3$  and, recursively,  $\mathbf{A}_1$  and  $\mathbf{A}_2$ . Of these tiles  $\mathbf{A}_0$  and  $\mathbf{A}_1$  can be read from memory, because they were also needed in the previous iteration, and

tiles  $\mathbf{A}_2$  and  $\mathbf{A}_3$  need to be stored in memory because they will be needed in the next iteration. Choosing phase of 0 therefore requires the buffering of two tiles of size 1 between each iteration.

Next, choose the phase to be 1, then  $\mathbf{W}_{2i+1}$  and  $\mathbf{W}_{2i+2}$  would fall into the same meta-period. So the iteration that calculates  $\mathbf{W}_1$  and  $\mathbf{W}_2$  needs to obtain tiles  $\mathbf{B}_1$ ,  $\mathbf{A}_3$ ,  $\mathbf{A}_2$ ,  $\mathbf{B}_3$  and, recursively,  $\mathbf{A}_1$ ,  $\mathbf{A}_2$ ,  $\mathbf{A}_3$  and  $\mathbf{A}_4$ . Note that the tiles  $\mathbf{A}_2$  and  $\mathbf{A}_3$  have to be obtained twice in this iteration. Of the tiles to be obtained the tiles  $\mathbf{B}_1$  and  $\mathbf{A}_2$  can be read from memory, because they were needed in the previous iteration, and tiles  $\mathbf{B}_3$  and  $\mathbf{A}_4$  need to be stored in memory because they will be needed in the next iteration (the one that calculates  $\mathbf{W}_3$  and  $\mathbf{W}_4$ ). Choosing a phasing of 1 therefore requires the buffering of one tile of size 1 and one tile of size 2 between each iteration.

It seems that a phase of 1, for our example, requires the largest amount of buffering. However, keep in mind that the size of a tile and the size of the interval of ranks required from a tile are not necessarily the same (see Section 3.1). If Figure 7.1 is a solution for a minimum or maximum filter, for example, then we only need one item from the tile of size 2. So the buffer cost for both phases would be 2 data items, in that case, therefore, the phase would not matter.

Finding the best phase can be done with a simple exhaustive search, since the meta-period for a dimension is an upper bound for the number of phases in that dimension. Note that choosing the correct phase can diminish the amount of buffering, but that it does not adversely affect the number of extrema operations that have to be performed.

```
do true \rightarrow
      \{buf0 = A_{2i}\} \{buf1 = A_{2i+1}\}
    a2 := read (A_{2i+2});
      \{a2 = A_{2i+2}\}
    b := buf1 \bowtie a2;
      \{\mathbf{b} = \mathbf{B}_{2i+1} = \mathbf{A}_{2i+1} \bowtie \mathbf{A}_{2i+2}\}
    \mathbf{W}_{2i} := \text{buf0} \bowtie \text{b};
      \{\mathbf{W}_{2i} = \mathbf{A}_{2i} \bowtie \mathbf{B}_{2i+1}\}\
    buf 0 := a2;
      \{buf0 = A_{2i+2}\}
    a3 := read (A_{2i+3});
      \{a3 = A_{2i+3}\}
    \mathbf{W}_{2i+1} := \mathbf{b} \bowtie \mathbf{a3};
      \{\mathbf{W}_{2i+1} = \mathbf{B}_{2i+1} \bowtie \mathbf{A}_{2i+3}\}\
    buf1 := a3;
      \{\operatorname{bufl} = \mathbf{A}_{2i+3}\}
    i := i + 1;
\mathbf{od}
```

Figure 7.2: Pseudo-code for the example in Figure 7.1

Once the phase has been chosen the sequential program can be written. The program executes an infinite loop that calculates I windows per iteration and

between each iteration the program buffers several data items, in accordance with the explanation above. Effectively, we have chosen a part of the calculation graph and implemented it as a number of statements. Because the calculation graph can be formed by replication of the chosen part we can implement the filter by repeating those statements in a loop.

A phase of zero for our example leads to the pseudo-code in Figure 7.2. Note that the pseudo-code resembles the generator graph. The number of merge operations equals the number of tile-sets with tiles larger than one and the number of read operations equals the number of tile-sets with tiles of size one in the generator graph. It is, in fact, possible to generate the program code for a rank order filter automatically from the generator graph.

In Section 7.3 we will show how to deal with an input stream that is finite in one or more dimensions. This will effectively limit the number of iterations for the loops that are related to those finite dimensions. Using this we can generalize our approach to multi-dimensional problems where the program will consist of several nested loops, one loop for each dimension. The approach will work as long as there is at most one dimension in which the inputs are infinite; the loop related to that dimension will become the outermost loop.

### 7.2 Parallel Implementation

The parallel implementations in this section are based on one iteration of the sequential program. The VLSI implementation, for example, will be based on components that implement one such iteration. Furthermore, although there are data dependencies between consecutive iterations, it is also possible to implement each iteration on a processing element of a SIMD machine since these dependencies can be resolved.

#### 7.2.1 VLSI Circuit

Implementing the rank order filter in parallel in a VLSI circuit is quite straightforward.

First we create a component that performs the same operation as a single iteration of the sequential program. This component has two sets of inputs and two sets of outputs. One set of inputs is for the tiles of size one, the actual inputs of the filter. The other set of inputs is for the tiles the component needs to read from a buffer from a previous iteration. Similarly the outputs are divided into two sets; those for the complete windows and those for the tiles that need to be buffered for a next iteration.

This component is depicted in Figure 7.3. Note that we used boxes with the symbol " $\Join$ " to denote the merging networks. One such component can be used to get an implementation that calculates I outputs in parallel. To do this we simply connect the components buffer outputs to a buffer and connect the buffer to the components buffer inputs, as is depicted in Figure 7.4(a).

To obtain a circuit that calculates L = IP windows in parallel we simply use P components and connect them in a similar manner. For P = 4 this has been done in Figure 7.4(b). In this way any number of components may be connected to increase the number of results calculated by the circuit.



Figure 7.3: Basic component for VLSI implementation



Figure 7.4: Parallel rank order filtering circuit

The actual cycle time of the circuit is independent of P. There is a dependency between components since tiles that are calculated in one component may be needed (also) in the others, but it is the depth of the calculation graph (from tiles of size 1 to the windows) and the calculation time of the merging networks that determine the cycle time. Neither of these depend on P, therefore the cycle time is independent of the amount of parallelism, and an arbitrary throughput can be obtained. This throughput is  $\mathcal{O}(L)$  and therefore it scales linearly with the size of the circuit.

The circuit may even be pipelined to obtain a smaller cycle time, since it is essentially a feed forward network. The calculation graph is an directed acyclic graph and this is reflected in the circuit; smaller tiles are fed into the rest of the circuit to calculate larger tiles. Although there appears to be a cycle in the circuit (see Figure 7.4) a detailed examination of the circuit will show that there are no cycles, only some feed forward paths that contain one or (possibly) more buffers.

A note on optimization: a component that performs a compare and swap operation is cheaper (in terms of the number of gates) than two components that perform an extrema operation. Therefore a good optimization step when implementing the merging networks is to replace all the pairs of extrema components that actually perform a C&S operation by a C&S component.

#### 7.2.2 SIMD Processor

In an SIMD processor with P processing elements (PEs) there are more restrictions to implementing an algorithm than in hardware. However we can calculate P iterations of the sequential program in one iteration of the SIMD program. We can also look at it from a different angle and consider one iteration of the SIMD program as the simulation of one cycle of the VLSI implementation (with P components).

The problem in vectorizing the sequential program is that there is a data dependency between the iterations; the tiles stored in the buffers. The reading from and writing to these buffers needs to be synchronized such that a read from a buffer is immediately followed by a write to that buffer. In this way the communication of the tile stored in the buffer can be implemented by a shift operation. During the shift operation each of the PEs receives a tile from its neighbor that is working on the preceding iteration (the read from the buffer) and sends a tile to its neighbor that is working on the next iteration (the write to the buffer).

The calculation of a tile that has to be written to a buffer will never depend on the contents of that same buffer (tiles can only depend on smaller tiles), it is therefore always possible to rearrange the statements in such a way that the read from and write to a buffer follow each other immediately.

Note that during a shift operation the tile received by PE 0 has to come from a buffer and the element send by PE P-1 has to be placed in that buffer, and that the contents of this buffer need to be kept for the next iteration of the SIMD program. Most SIMD processor have some sort of functionality to handle the data items at the edge of the PE array during a shift operation, so this is not a problem.

There is one last problem that we have to tackle before we have our SIMD implementation. This concerns the reading of the inputs and the writing of the outputs. Since all the tile-set in the generator graph have a period equal to the meta-period the implementation requires the inputs and produces the outputs with that same period. Consider our running example; the sequential program calculates first the next even and then the next odd window in an iteration. The SIMD program, however, first calculates the next P even windows and than the next P odd windows. The same reasoning holds for the reading of the inputs.

This is no problem if the inputs and outputs happen to be in memory in that particular order. However in most cases the inputs are in memory in consecutive order and the outputs are also desired in a consecutive order. Therefore we can use so-called strided memory access to implement our algorithm, as shown in Figure 7.5.

```
do true \rightarrow
```

 $\{buf0 = \mathbf{A}_{2i}\}$  $\{buf1 = A_{2i+1}\}$  $a2\_vec := strided\_read(\mathbf{A}_{2i+2}, 2);$  $\{\operatorname{a2\_vec}[j] = \mathbf{A}_{2(i+j)+2} \text{ for } 0 \leq j < P\}$  $a3\_vec := strided\_read(\mathbf{A}_{2i+3}, 2);$  $\{a3\_vec[j] = \mathbf{A}_{2(i+j)+3} \text{ for } 0 \le j < P\}$  $t1\_vec$ ,  $buf1 := shift(buf1, a3\_vec);$  $\{t1\_vec[j] = \mathbf{A}_{2(i+j)+1} \text{ for } 0 \le j < P \land buf1 = \mathbf{A}_{2(i+P)+1}\}$  $b_vec := t1_vec \bowtie a2_vec;$  $\{ \mathbf{b}_{-} \operatorname{vec}[j] = \mathbf{B}_{2(i+j)+1} = \mathbf{A}_{2(i+j)+1} \bowtie \mathbf{A}_{2(i+j)+2} \text{ for } 0 \le j < P \}$  $t0\_vec$ ,  $buf0 := shift(buf0, a2\_vec);$  $\{ t 0 \_ v e c [j] = \mathbf{A}_{2(i+j)} \text{ for } 0 \le j < P \land b u f 0 = \mathbf{A}_{2(i+P)} \}$  $\mathbf{W}_{2i} := t0\_vec \bowtie b\_vec;$  $\{\mathbf{W}_{2(i+j)} = \mathbf{A}_{2(i+j)} \bowtie \mathbf{B}_{2(i+j)+1} \text{ for } 0 \le j < P\}$  $\mathbf{W}_{2i+1} := b_{-} \operatorname{vec} \bowtie a_{3_{-}} \operatorname{vec};$  $\{\mathbf{W}_{2(i+j)+1} = \mathbf{B}_{2(i+j)+1} \bowtie \mathbf{A}_{2(i+j)+3} \text{ for } 0 \le j < P\}$ i := i + P;



Figure 7.5: SIMD pseudo-code for the example in Figure 7.1

Not many SIMD processors support strided memory access, but another solution to this problem is possible if the processor is capable of shuffling the vectors. A shuffle operation is used to reorder the elements of a vector. So, after the inputs have been read in consecutive order we use several (masked) shuffling operations to distribute them to the correct PEs. This process is depicted in Figure 7.6 for an SIMD processor with 4 PEs. On the top the figure shows the inputs as they read from memory, at the bottom it shows how two vectors have been created, both containing the inputs with a period of two, but the left-most vector with a phase of 0, and the right-most vector with a phase of 1. The numbers at the arrows indicate the number of the shuffle operation in which the movement of the input to the destination vector is accomplished. The figure shows that 4 shuffle operations are needed, assuming that each shuffle operation can have only one source and one destination vector. A similar shuffling pattern can be used to get the outputs back into a consecutive order.



Figure 7.6: Shuffling consecutive inputs for P = 4 and a meta-period of 2

Note that the number of shuffling operations depends only on the metaperiod, not on the number of processing elements (P). Therefore the running time of an iteration of the SIMD program is still independent of P and we end up with an SIMD implementation of which the throughput  $(\mathcal{O}(L) = \mathcal{O}(IP))$ scales linearly with the number of processing elements.

A note on optimization: a SIMD processor is usually capable of the required extrema operations. However should it be capable of the C&S operation then using that instruction wherever possible in the implementation would be a good idea. A C&S (or extrema) operation can even be simulated by comparing two values and using the result as a mask to some assignment operations, as shown by the pseudo-code in Table 7.1.

Option 1:	Option 2:
t := a; a := min(a,b); b := max(t,b);	<pre>mask := compare_gte(a,b); t := a; a := masked_move(b, mask); b := masked_move(t, mask);</pre>

Table 7.1: Two options for implementing a C&S operation

Clearly option 1 requires less instructions, and by using dead code elimination it can be automatically removed from the program if necessary. However, option 2 might be faster than simple extrema operations if the processor also provides VLIW parallelism. Although option 2 clearly requires more operations, in a VLIW processor there might be multiple functional units capable of a move operation (addition of zero, shifting over a distance of zero, etc.), while there is usually only one functional unit capable of extrema operations. So option 2 implementation might require less clock cycles for some processors. For an example of such a processor, see Section 7.4.

#### 7.3 Finite input streams

So far we have considered input streams that are infinite. In practice, however, this is not the case. How do our implementations cope with this?

The answer is relatively simple: the finite input streams are extended to contain a number of elements that is a multiple of L. In that way all of our

implementations can simply make an integer number of iterations. Extending the input stream with dummy inputs is something that happens routinely in image processing to prevent artifacts at the edge of a picture.

The only problem with this solution is that the implementation now has some overhead compared to the theoretical solution found by the calculation graph. However, this overhead is  $\mathcal{O}(L)$  for the entire input stream, so it becomes less and less important for the larger input streams.

This solution can be extended to multiple-dimensions. If there are  $d \leq D$  dimensions in which the input stream is finite then this introduces an overhead of  $\mathcal{O}(L^d)$ . Again this overhead becomes less and less important as the size of the input stream increases.

#### 7.4 Philips $EVP_{16}$

The Philips  $\text{EVP}_{16}$  is an SIMD processor with P = 16 processing elements [1]. The  $\text{EVP}_{16}$  is a processor that supports extrema operations and shuffle operations. So, although it does not support C&S operations or strided memory access, it possible to implement our solution. We wrote a program that, given a generator graph, automatically produces the program code for the  $\text{EVP}_{16}$ .

The EVP<sub>16</sub> also supports VLIW parallelism and masked operations. The extrema operations and compare operations are only supported on one unit<sup>1</sup>, while assignment or move operations are supported on 4 units<sup>2</sup>. This means that the alternative implementation of the C&S operation, i.e. option 2 from Table 7.1, is possible and might even be an improvement.

Option 2 would also take two clock cycles (one for the compare and move operation and the other for the two remaining masked move operations). So there seems to be no gain. However, with this implementation we can start a new C&S operation in each clock cycle. Assuming, of course, that the second of the subsequent C&S operations does not require the outputs of the first as input. This is something to take into account.

Another thing we must take into account is that the compiler also needs to schedule some other operations, like the memory accesses and the shuffling of vectors. These operations can only be performed on the same units that are used by option 2. So producing the most efficient program code is an entirely new optimization problem.

We have not examined this problem extensively, because with (for example) N C&S operations in a program, and two options for implementing each C&S operation, there would be  $2^N$  configurations of the program in total. Needless to say, it is impractical to examine all these possibilities and select the best one.

To find a good program we use two steps. The first step is to find all the C&S operations of which one of the extrema operations can be pruned. For these C&S operations the best implementation is option 1, since that implementation reduces to a single extrema operation and thus requires only one clock cycle on the ALU unit.

After this first step there may still be C&S operations left for which we can choose between the two alternative implementations. So in the second step we use a simple heuristic algorithm to find good choices for these remaining C&S

 $<sup>^{1}</sup>$ VALU

<sup>&</sup>lt;sup>2</sup>VLSU, VMAC, VALU and VSHU

operations. The choices for these operations can be represented as a bit vector. We start by using the bit vector representing that all C&S operations are implemented as option 2. We then examine the neighborhood of the current configuration for a new configuration that is better. The neighborhood of a configuration consists of all configurations with a Hamming distance of one to the current configuration, i.e. all the configurations that have a different option for a single one of the C&S operations. The best configuration in this neighborhood is taken and we apply the same algorithm again and again, until there is no more improvement. The performance of the resulting implementations after such an optimization can be found in Table 7.2. However, solving this optimization problem with a more sophisticated algorithm may improve these results.

Window:	$3 \times$	3	$5 \times 5$		
Clock cycles per:	iteration	output	iteration	output	
Using only option 1	84	1.31	295	4.61	
Using only option 2	77	1.20	345	5.39	
After optimization	71	1.11	241	3.77	

Table 7.2: Clock cycles for median filtering on the  $EVP_{16}$ 

Table 7.2 presents the information on two 2-dimensional median filters implemented on the EVP<sub>16</sub>. The implementations produce L = IP outputs per iteration. The number of windows per iteration happens to be I = 4 for both problems and the processor has P = 16 PEs, therefore the number of clock cycles per output is simply the number of clock cycles per iteration divided by L = 64. The rows of the table indicate the number of clock cycles for different implementation strategies. The row marked "Using only option 1" and "Using only option 2" shows the results when step 2 of our optimization is skipped and all remaining C&S operations are implemented using option 1 or option 2 respectively. The row marked "After optimization" shows the results when the neighborhood search algorithm is used to optimize the implementation.

Note that the  $3 \times 3$  and  $5 \times 5$  median filters require 1.15 and 6.6 clock cycles per output respectively on the AltiVec, according to [8]. Our implementation on the EVP<sub>16</sub> with 1.11 and 3.77 clock cycles respectively is an improvement on those numbers, especially for the latter filter.

Table 7.2 also shows that median filters can be implemented very efficiently. No sequential algorithm is capable of producing outputs at the rate shown in the table. There are sequential algorithms that have a better complexity than our solutions, but the oblivious approach allows for easy parallelism. For practical window sizes this parallelism compensates small differences in complexity and provides better overall performance.

# Chapter 8

# Conclusion

In this report we have presented a mathematical framework for representing both the rank-order filter design problem (ROFDP) and the solutions to that problem, i.e. the rank-order filters (ROF) themselves. We have also introduced several heuristic algorithms for solving the ROFDP and have compared the filters found by those algorithms to filters found in the literature. Furthermore, we have shown how our designs can be used to obtain scalable, parallel implementations of ROFs as VLSI circuits or as programs on a SIMD machine like the EVP<sub>16</sub>.

A novelty of our designs is the mirroring of merging and/or sorting networks prior to the pruning (or "dead-code elimination"). We have not encountered this optimization in the literature so far, but it improves results significantly. Furthermore we present a cost function for pruned merging networks, both for the standard versions and for the versions with the mirroring optimization applied.

The major result of our research, however, we consider the mathematical framework that uses concepts like tiling, the calculation graph and the generator graph. This framework enables us to formalize the reuse that takes place in a ROF. In addition it allows us to make a clear distinction between the calculation to be performed by the ROF and the (parallel) implementation itself. This separation of concerns allows us to design the solution first and choose the implementation method and the amount of parallelism at a later stage. In all cases considered this approach has resulted in designs that require less extrema operations per window than the ones reported in the literature so far, except for 1-dimensional minimum filtering [5] and a 1-dimensional window sorter for windows of size 6[9].

Since we have not been unable to provide an upper bound for the cost for arbitrary large window sizes. The asymptotic complexity of our designs is unknown, just like the designs presented in [2, 3, 8, 9]. Although the cost of our ROF designs is very low, we know that the complexity is not as low some of the best algorithms found in the literature [6, 10], due to the fact that we resort to oblivious sorting methods. Because our designs rely on oblivious sorting methods they have two major advantages over these algorithms. First of all they allow for scalable parallelism; the throughput of the filter scales linearly with the amount of parallelism. Secondly, the constant factor for our designs is very low, which means that our designs perform better for practical (i.e. relatively small) window sizes.

The methods presented in this report are widely applicable. Any problem consisting of a sliding window and an aggregation operator that is both associative and commutative can benefit from our approach. The cost of an implementation using an aggregation function with a cost of one (like the addition, multiplication, minimum and maximum operators) is equal to the cost of the minimum filter. The only difference is that in the first two cases the cost is measured in addition operations per window and multiplications operations per window respectively, instead of extrema operations per window.

Other problems for which our methods can be adapted are weighted rank order filters. In these filters the set of coordinates forming the windows become multi-sets, and the weight of a coordinate is represented by the number of times it is in the multi-set.

Although the generator graphs found by our algorithms are already quite good there is still room for improvement. The largest improvement, however, can be achieved by improving on the implementation of our designs on SIMD processors. Generating efficient code that can be readily optimized by the compiler for such machines is a hard problem that we have not examined fully yet. All these improvements, however, are possible topics for future research.

In summary, our research has shown that the computational gap between linear filters and rank order filters is not as large as was previously believed. The improvements made in this report are sufficient to make the use of rank order filters in real-time systems attractive.

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# Appendix A Algorithm Results

The next sections of this appendix present tables containing the results of the different algorithms described in Chapter 5. Each row of such a table corresponds to a specific window size W, and each column to a specific algorithm. For the sake of brevity, we have adopted the following numbering scheme to identify the algorithms:

- 0. Divide and Conquer (Section 5.2)
- 1. Recursive Tiling (Section 5.3)
- 2. LSB Tiling (Section 5.4)
- 3. MSB Tiling (Section 5.4)
- 4. Split Tiling 1 (Section 5.5)
- 5. Split Tiling 2 (Section 5.5)
- 6. Split Tiling 3 (Section 5.5)
- 7. Overlap Recursive Mirroring 1 (Section 5.6 with R = 1)
- 8. Overlap Recursive Mirroring 2 (Section 5.6 with R = 2)
- 9. Overlap Recursive Mirroring 3 (Section 5.6 with R = 3)
- 10. Overlap Recursive Mirroring 4 (Section 5.6 with R = 4)

The last column of these tables indicates which of the algorithms provided a solution with the minimum cost.

### A.1 One Dimensional Problems

In this section we present the results of our algorithms for one-dimensional ROFDPs.

- D = 1
- W = tile(hyperbar(W), 1, 0)

The following subsections consider various choices for l and u.

### A.1.1 Window Sorting

This section considers the problem of sorting the entire window. Hence l = 0 and  $u = \mathbb{W}-1$ .

W	0)	1)	2)	3)	4)	5)	6)	7)	8)	9)	10)	Best strategies
1	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10
2	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10
4	8.00	11.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	0, 2, 3, 4, 5, 6, 7, 8, 9, 10
5	16.00	12.00	12.00	16.00	13.50	12.00	12.00	12.00	12.00	12.00	12.00	1, 2, 5, 6, 7, 8, 9, 10
6	18.00	22.00	20.00	20.00	17.00	17.00	17.00	17.50	16.00	16.00	16.00	8, 9, 10
7	28.00	20.50	20.50	28.00	22.50	20.50	20.50	20.50	20.50	20.50	20.50	1, 2, 5, 6, 7, 8, 9, 10
8	26.00	34.50	26.00	42.00	26.00	29.00	26.00	26.00	25.33	25.33	25.33	8, 9, 10 2 5 6 7 8 9 10
10	42.00	48.50	50.00	50.00	41.25	38.00	38.00	36.75	36.67	36.67	36.67	8, 9, 10
11	60.00	39.00	39.00	60.00	47.75	39.00	39.00	39.00	39.00	39.00	39.00	1, 2, 5, 6, 7, 8, 9, 10
12	52.00	61.00	60.00	60.00	46.50	53.50	46.50	47.00	45.33	45.33	45.33	8, 9, 10
13	80.00	51.50	54.00	74.00	58.00	49.50	49.50	50.75	48.00	48.00	48.00	8, 9, 10
14	94 00	59 25	96.00 59.25	94 00	72 75	62.50 59.25	62.50 59.25	59.00	59.07	59.07	59.07	0, 9, 10 1 2 5 6 7 8 9 10
16	76.00	89.25	76.00	76.00	76.00	82.00	76.00	68.00	67.33	67.33	67.33	8, 9, 10
17	122.00	77.00	70.00	108.00	91.63	74.00	70.00	70.00	68.67	68.67	68.67	8, 9, 10
18	106.00	111.00	124.00	124.00	100.88	91.00	87.00	79.38	77.17	77.17	77.17	8, 9, 10
19	140.00	81.50	79.50	138.00	110.38	106 00	79.50	79.50	79.50	79.50	79.50	2, 5, 6, 7, 8, 9, 10
20	164.00	103.00	111.00	158.00	123.88	94.00	94.00	94.13	91.83	91.83	91.60	10
22	140.00	145.00	202.00	168.00	131.63	115.00	115.00	101.25	100.00	99.50	99.50	9, 10
23	182.00	101.50	101.50	182.00	138.88	101.50	101.50	101.50	101.50	101.50	101.50	1, 2, 5, 6, 7, 8, 9, 10
24	142.00	147.50	166.00	166.00	122.25	138.25	122.25	112.00	109.17	109.17	109.17	8, 9, 10
25	180.00	179.00	238.00	204.00	151.50	122.25	137.25	123.75	119.56	119.56	111.55	8, 9, 10
27	230.00	126.75	130.00	220.00	164.00	123.75	123.75	125.75	121.67	121.67	121.67	8, 9, 10
28	180.00	180.75	264.00	224.00	166.75	162.25	139.25	135.25	132.75	132.00	132.00	9, 10
29	254.00	160.00	188.00	244.00	184.25	142.25	142.25	139.63	134.17	134.17	134.17	8, 9, 10
30	214.00	218.00	348.00	256.00	195.75	1/1.25	171.25	147.00	142.89	142.75	142.75	9, 10
32	206.00	207.63	206.00	206.00	205.00	199.50	206.00	156.63	154.33	153.00	153.00	9, 10
33	312.00	193.50	167.00	270.00	228.94	175.50	167.00	161.38	157.42	155.38	155.38	9, 10
34	264.00	259.50	302.00	302.00	243.56	208.50	200.00	169.13	165.33	164.75	164.75	9, 10
35	334.00	178.00	168.00	324.00	257.94	173.00	168.00	168.00	165.67	165.67	165.67	8, 9, 10
30	364 00	248.00	240.00	336.00	261.25	223.50	187.50	180.88	175.22	175.22	175.22	8, 9, 10
38	306.00	301.50	444.00	370.00	288.94	232.50	227.50	192.38	185.89	185.89	185.89	8, 9, 10
39	386.00	192.25	189.75	388.00	298.44	189.75	189.75	189.75	189.17	186.00	186.00	9, 10
40	290.00	270.25	376.00	376.00	282.50	254.50	218.50	203.63	198.33	197.50	197.50	9, 10
41	422.00	259.50	268.00	402.00	303.06	222.50	200.50	208.06	198.00	198.00	198.00	8, 9, 10
42	444.00	229.25	238.50	416.00	329.06	263.50	241.50	215.50	209.44	209.00	209.00	10
44	342.00	315.25	538.00	442.00	331.25	278.50	239.50	227.00	221.00	219.63	219.63	9, 10
45	474.00	295.50	357.00	464.00	349.19	242.50	242.50	231.19	223.83	222.75	222.75	9, 10
46	396.00	385.50	670.00	478.00	359.81	287.50	287.50	238.38	232.00	230.00	230.00	9, 10
47	496.00 368.00	235.75	235.75	496.00	366.94	235.75	235.75	235.75	232.75	230.00	230.00	9,10
49	538.00	322.50	312.00	474.00	335.75	279.63	255.13	253.81	242.20	242.00	242.00	9, 10
50	450.00	420.50	576.00	498.00	353.00	328.63	304.13	261.56	253.61	251.25	251.25	9, 10
51	560.00	280.25	280.50	520.00	370.50	269.13	256.13	263.81	255.25	254.42	254.42	9, 10
52	430.00	382.25	626.00	530.00	376.63	343.63	283.63	273.63	264.94	262.33	262.33	9, 10
54	492.00	469.50	782.00	570.00	411.75	352.63	339.63	285.44	203.78	272.75	272.75	9. 10
55	612.00	285.88	290.00	590.00	425.00	281.88	281.88	284.63	278.50	271.42	271.42	9, 10
56	454.00	395.88	682.00	578.00	412.38	374.63	318.63	296.50	286.67	284.17	284.17	9, 10
57	648.00	401.50	453.00	610.00	438.13	326.63	292.63	301.31	290.00	286.75	286.75	9, 10
58	540.00 670.00	515.50 337 50	371 00	652 00	455.63	383.63	349.63	309.19	297.83	295.58	296.58	9, 10 8 9 10
60	512.00	455.50	908.00	660.00	480.88	398.63	343.63	321.06	308.00	307.83	307.83	9, 10
61	700.00	442.50	574.00	686.00	504.38	346.63	346.63	325.38	310.00	310.00	310.00	8, 9, 10
62	582.00	564.50	1088.00	702.00	519.88	407.63	407.63	332.69	318.67	318.33	318.33	9, 10
63 64	722.00 528.00	327.81 453.81	327.81 528.00	722.00 528.00	527.94	327.81	327.81 528.00	327.81	324.61	318.06	318.06	9, 10
65	776.00	483.00	392.00	656.00	559.53	389.75	392.00	346.44	333.17	331.13	331.13	9, 10
66	648.00	613.00	720.00	720.00	580.97	454.75	457.00	354.44	342.83	339.96	339.96	9, 10
67	802.00	398.50	360.50	758.00	601.84	371.25	360.50	356.88	346.83	343.13	343.13	9, 10
68	614.00	532.50	786.00	786.00	610.00	469.75	396.00	366.75	354.72	350.33	350.33	9, 10
70	698.00	668.00	529.00 990.00	836.00	648.16	409.75	468.00	378.75	366.94	360.38	360.38	9, 10
71	864.00	387.00	374.00	862.00	661.97	380.00	374.00	374.00	364.61	359.17	359.17	9, 10
72	638.00	529.00	858.00	858.00	648.63	500.75	418.75	390.38	374.44	370.92	370.92	9, 10
73	908.00	571.00	573.00	888.00	674.59	436.75	384.75	395.19	376.94	373.29	373.29	9, 10
74 75	755.00 934 00	/1/.00	1074.00	908.00	690.78 707 59	509.75 414 25	457.75	403.06	386.33	382.92	382.92	9,10
76	712.00	608.75	1148.00	940.00	711.50	524.75	447.75	414.75	397.44	394.58	394.58	9, 10
77	970.00	614.00	726.00	966.00	732.66	456.75	450.75	418.91	396.89	396.89	396.89	8, 9, 10
78	806.00	768.00	1376.00	984.00	744.84	533.75	527.75	426.06	408.67	405.33	405.33	9, 10
79 80	996.00 724.00	422.88	419.88 946.00	1006.00	753.47	419.88 563 7F	419.88 522 2F	419.88	412.50	404.17	404.17	9,10
81	1046.00	648.00	633.00	990.00	725.97	491.75	435.25	442.09	424.61	418.38	418.38	9, 10
82	870.00	810.00	1186.00	1016.00	745.28	572.75	516.25	449.88	433.22	427.88	427.88	9, 10
83	1072.00	516.75	521.00	1040.00	764.66	465.25	436.25	452.09	434.83	431.08	431.08	9, 10
84	816.00	682.75	1268.00	1052.00	771.13	587.75	479.75	462.03	444.06	439.13	439.13	9, 10
86	920.00	866.00	1520.00	1096.00	807.84	596.75	±02.75	473.72	455.89	449.50	449.50	9, 10
87	1134.00	487.63	498.25	1118.00	821.03	470.00	470.00	472.88	460.64	450.63	448.65	10
88	832.00	661.63	1356.00	1108.00	807.00	618.75	522.75	484.94	467.61	460.83	460.83	9, 10
89	1178.00	740.00	854.00	1142.00	833.66	538.75	480.75	489.59	465.61	463.28	463.07	10
30	310.00	310.00	1020.00	1104.00	000.72	021.15	009.15	491.34	411.22	412.31	412.31	5, 10

91	1204.00	580.00	651.50	1188.00	868.66	508.25	508.25	499.38	480.47	475.69	475.69	9,	10
92	914.00	762.00	1710.00	1198.00	873.63	642.75	555.75	508.97	488.31	483.06	483.06	9,	10
93	1240.00	786.00	1039.00	1226.00	896.34	558.75	558.75	513.13	491.22	486.25	486.25	9,	10
94	1028.00	972.00	1986.00	1244.00	909.91	651.75	651.75	520.28	499.42	493.47	493.47	9,	10
95	1266.00	513.88	513.88	1266.00	915.97	513.88	513.88	513.88	500.50	491.88	491.88	9,	10
96	914.00	703.88	1074.00	1074.00	762.06	693.81	762.06	530.59	510.39	503.50	503.50	9,	10
97	1322.00	801.00	729.00	1150.00	797.00	605.81	578.06	535.53	512.67	505.71	505.71	9,	10
98	1098.00	995.00	1362.00	1192.00	821.63	702.81	675.06	543.47	522.28	515.13	515.13	9,	10
99	1348.00	631.75	609.00	1224.00	846.00	571.31	538.56	545.88	526.75	518.38	518.38	9,	10
100	1024.00	829.75	1460.00	1244.00	857.31	717.81	590.06	555.84	533.64	526.42	526.42	9,	10
101	1384.00	857.00	930.00	1274.00	884.88	625.81	593.06	560.19	535.19	529.63	529.63	9,	10
102	1148.00	1059.00	1760.00	1296.00	903.00	726.81	694.06	567.81	544.92	536.79	536.79	9,	10
103	1410.00	587.63	586.25	1322.00	920.50	572.06	556.06	567.28	548.86	535.38	535.38	9.	10
104	1032.00	793.63	1564.00	1316.00	910.56	748.81	616.81	579.78	556.75	548.09	548.09	9.	10
105	1454.00	906.00	990.00	1352.00	941.13	652.81	566.81	584.38	560.17	550.41	550.41	9.	10
106	1206.00	1116.00	1876.00	1376.00	961.75	757.81	671.81	592.13	568.14	560.00	560.00	9.	10
107	1480 00	700 00	759 50	1402 00	983 13	614 31	598 31	594 03	564 22	563 31	563 31	٥, ٩	10
108	1122.00	914.00	1982.00	1414.00	991.31	772.81	653.81	604.28	575.78	571.44	571.44	9.	10
109	1516 00	956 00	1207 00	1444 00	1017 25	672 81	656 81	608 44	577 70	574 75	574 75	٥, ٩	10
110	1256 00	1174 00	2306 00	1464 00	1033 88	781 81	765 81	615 81	587 26	582 03	582 03	٥, ۵	10
111	1542 00	612 04	618 00	1488 00	1047 00	607 94	607 94	611 44	501.20	581 41	581 41	۵, ۵	10
110	1112.00	012.04	1694 00	1400.00	00/ 10	011 01	720 21	606 00	E09 70	E00 70	E00 70	<i>°</i> ,	10
112	1502.00	007.00	1066 00	1420.00	1000 01	707 91	610 21	621 00	E00 22	E04 07	504 07	<i>°</i> ,	10
110	1220.00	1002 00	2020.00	1510.00	1025.01	000.01	720 21	620 25	600.00	604 05	604.05	<i>°</i> ,	10
114	1610.00	765 00	2020.00	1512.00	1000.00	020.01	600 21	039.20	009.09	004.20	004.20	э,	10
110	1010.00	005.00	0124 00	1542.00	1000.00	005.31	670.01	041.00	013.35	C1F 1C	C1F 1C	э,	10
110	1220.00	1050.00	2134.00	1556.00	11092.69	707 01	6/9.01	001.00	621.96	615.10	615.10	9,	10
110	1054.00	1052.00	1299.00	1610.00	1122.00	044 01	700 01	662.01	620.11	616.19	616.19	9,	10
110	1370.00	1200.00	2462.00	1012.00	1141.01	044.01	/99.01	003.91	033.00	020.31	020.31	9,	10
119	1680.00	695.25	734.50	1638.00	1161.06	662.06	662.06	663.19	636.26	625.42	625.42	9,	10
120	1226.00	933.25	2254.00	1630.00	1152.44	866.81	/30.81	675.41	644.41	636.72	636.72	9,	10
121	1724.00	1102.00	1367.00	1670.00	1186.19	754.81	672.81	680.16	646.59	639.13	639.13	9,	10
122	1428.00	1344.00	2614.00	1696.00	1209.69	875.81	793.81	688.00	655.85	648.25	648.25	9,	10
123	1750.00	834.25	988.00	1724.00	1234.19	708.31	708.31	690.06	660.30	651.72	651.72	9,	10
124	1324.00	1080.25	2736.00	1736.00	1244.94	890.81	//1.81	699.75	067.15	659.16	059.16	9,	10
125	1786.00	1153.00	1616.00	1768.00	1274.44	774.81	774.81	703.97	662.67	662.41	662.07	10	
126	14/8.00	1403.00	3108.00	1/88.00	1293.94	899.81	899.81	/11.19	6//.78	669.72	669.72	9,	10
127	1812.00	701.91	701.91	1812.00	1300.97	701.91	701.91	701.91	681.70	666.84	666.84	9,	10
128	1298.00	955.91	1298.00	1298.00	1298.00	948.88	1298.00	718.81	690.04	678.94	678.94	9,	10
129	1882.00	1193.50	905.00	1554.00	1339.30	828.88	905.00	723.91	693.56	681.41	681.41	9,	10
130	1562.00	1451.50	1682.00	1682.00	1368.83	957.88	1034.00	732.00	701.81	691.16	691.16	9,	10
131	1912.00	904.00	777.00	1752.00	1397.61	778.38	777.00	734.53	703.15	694.72	694.72	9,	10
132	1450.00	1166.00	1812.00	1812.00	1412.06	972.88	844.50	744.56	713.89	703.06	703.06	9,	10
133	1954.00	1261.50	1170.00	1856.00	1443.58	848.88	847.50	749.13	716.15	706.66	706.66	9,	10
134	1620.00	1527.50	2208.00	1894.00	1463.98	981.88	980.50	756.69	725.89	714.09	714.09	9,	10
135	1984.00	807.75	758.25	1936.00	1483.86	771.13	758.25	756.44	730.54	710.53	710.53	9,	10
136	1448.00	1077.75	1948.00	1948.00	1474.81	1003.88	835.00	768.75	737.39	723.72	723.72	9,	10
137	2036.00	1316.50	1246.00	1986.00	1508.27	875.88	769.00	773.59	738.35	726.13	726.13	9,	10
138	1688.00	1590.50	2356.00	2014.00	1530.05	1012.88	906.00	781.53	747.91	735.88	735.88	9,	10
139	2066.00	978.25	967.50	2044.00	1552.42	821.38	808.50	783.69	751.39	739.25	739.25	9,	10
140	1564.00	1256.25	2494.00	2062.00	1560.06	1027.88	880.00	793.47	758.98	747.53	747.53	9,	10
141	2108.00	1370.50	1527.00	2096.00	1586.73	895.88	883.00	797.78	761.93	750.91	750.91	9.	10
142	1746.00	1652.50	2914.00	2122.00	1602.64	1036.88	1024.00	805.09	770.17	758.31	758.31	9.	10
143	2138.00	812.00	796.00	2152.00	1614.98	803.00	796.00	796.00	765.92	755.92	755.92	9.	10
144	1536.00	1098.00	2100.00	2100.00	1560.13	1066.88	954.38	816.41	778.93	769.06	769.06	9.	10
145	2198 00	1414 50	1338 00	2148 00	1596 08	930 88	803 38	821 44	781 06	771 41	771 41	٥, ٩	10
146	1822 00	1704 50	2532 00	2178 00	1620 17	1075 88	9/8 38	829 //	790 61	780 78	780 78	٥, ۵	10
147	2228 00	1046 25	1033 50	2206 00	1644 23	872 38	804 38	831 81	795 26	784 03	784 03	٥, ٩	10
1/18	1686 00	1340 25	2678 00	22222 00	1653 63	1000 88	879 88	842 03	801 96	701 84	701 84	٥, ۵	10
140	2270 00	1471 50	1625 00	2222.00	1601 05	050.00	000.00	042.00	001.00	70/ 0/	704 04	<i>°</i> ,	10
149	1990 00	1760 50	2100.00	2232.00	1607 64	1000 00	1021 00	040.31	011.40	900 16	900 16	, ,	10
150	1000.00	010 20	020 50	2214.00	1712 55	1055.00	1031.00	003.94	012.00	002.10	002.10	э,	10
151	2300.00	1000 20	930.50	2300.00	1700 50	1101 00	004.13	003.22	010.17	001.75	012 70	9,	10
152	1674.00	1220.30	2030.00	2294.00	1700.56	1121.00	930.00	005.44	024.20	013.72	013.72	9,	10
153	2352.00	1523.50	1/19.00	2332.00	1731.42	9//.88	864.88	870.08	827.20	816.11	816.11	9,	10
154	1948.00	1829.50	3286.00	2358.00	1751.02	1130.88	1017.88	877.80	835.31	825.19	825.19	9,	10
100	2382.00	1117.50	1244.00	2386.00	1777 0-	915.38	908.38	019.78	038.11	028.45	028.45	э,	10
156	1800.00	1427.50	3440.00	2400.00	1///.25	1145.88	987.88	889.35	845.93	835.85	835.85	9,	10
157	2424.00	15/6.50	2032.00	2432.00	1802.33	997.88	990.88	893.47	847.96	838.98	838.98	9,	10
120	2006.00	1890.20	3908.00	2454.00	1816.67	1154.88	114/.88	900.58	051.20	040.17	040.17	э,	10
159	2454.00	893.44	889.94	2480.00	1823.48	889.94	889.94	889.94	861.94	840.88	840.88	9,	10
101	1/50.00	1211.44	2292.00	2292.00	1700.01	1193.88	1234.13	911.70	008.72	051.00	000.60	10	
101	2520.00	1001 22	1400.00	2310.00	1725 05	1041.88	954.13	910.61	003.93	059.40	058.63	10	
162	2088.00	1921.50	2112.00	2414.00	1762	1202.88	1115.13	924.53	011.72	009.10	001.98	10	
163	2550.00	1177.25	1137.50	2448.00	1763.14	975.38	898.63	926.91	881.48	872.60	871.13	10	
104	1928.00	1503.25	2934.00	2410.00	1/15.75	1217.88	982.13	936.91	089.63	080.90	019.05	10	
165	2592.00	1664.50	1795.00	2502.00	1805.92	1061.88	985.13	941.23	893.00	884.42	882.28	10	
166	2146.00	1994.50	3426.00	2526.00	1825.14	1226.88	1150.13	948.78	901.17	891.77	889.28	10	
167	2622.00	1026.38	1026.50	2554.00	1843.64	960.13	924.13	948.23	902.24	888.00	883.83	10	
168	1906.00	1360.38	3102.00	2550.00	1833.25	1248.88	1016.88	960.86	912.54	901.02	900.05	10	
169	2674.00	1721.50	1887.00	2588.00	1865.98	1088.88	934.88	965.47	914.67	903.36	902.60	10	
170	2214.00	2059.50	3606.00	2614.00	1887.33	1257.88	1103.88	973.25	924.19	912.91	912.38	10	
171	2704.00	1253.50	1368.00	2642.00	1909.33	1018.38	982.38	975.11	928.59	916.19	915.95	10	
172	2042.00	1595.50	3776.00	2656.00	1916.75	1272.88	1069.88	985.22	935.26	924.22	924.20	10	
173	2746.00	1778.50	2232.00	2688.00	1943.14	1108.88	1072.88	989.33	936.33	927.47	927.47	9,	10
174	2272.00	2124.50	4292.00	2710.00	1958.86	1281.88	1245.88	996.66	946.00	934.67	934.67	9,	10
175	2776.00	1010.06	1022.13	2736.00	1971.02	988.00	988.00	992.25	949.61	934.14	934.14	9,	10
176	1986.00	1360.06	3286.00	2678.00	1915.94	1311.88	1174.38	1007.45	957.46	945.55	945.55	9,	10
177	2836.00	1826.50	1995.00	2732.00	1952.92	1143.88	991.38	1012.33	960.56	947.64	947.64	9,	10
178	2348.00	2180.50	3814.00	2766.00	1978.20	1320.88	1168.38	1020.25	968.89	956.81	956.81	9,	10
179	2866.00	1325.50	1442.00	2798.00	2003.64	1069.38	992.38	1022.55	966.00	959.89	959.89	9	10
180	2164.00	1683.50	3992.00	2816.00	2014.44	1335.88	1083.88	1032.70	978.69	967.48	967.48	9,	10
181	2908.00	1888.50	2356.00	2850.00	2043.58	1163.88	1086.88	1036.89	980.98	970.41	970.41	9,	10
182	2406.00	2250.50	4532.00	2874.00	2061.86	1344.88	1267.88	1044.48	990.52	977.41	977.41	9	10
183	2938.00	1141.00	1222.75	2902.00	2079.58	1050.13	1050.13	1043.69	995.30	978.78	978.78	9.	10
184	2132.00	1507.00	4176.00	2896.00	2068.25	1366.88	1150.88	1055.92	1002.07	988.83	988.83	9.	10
185	2990.00	1944.50	2456.00	2938.00	2101.45	1190.88	1060.88	1060.55	1001.74	991.09	991.09	9.	10
186	2474.00	2314.50	4728.00	2966.00	2123.23	1375.88	1245.88	1068.28	1013.91	1000.09	1000.09	9.	10
187	3020.00	1400.75	1692.50	2996.00	2145.95	1112.38	1112.38	1070.25	1017.37	1003.45	1003.45	9.	10
188	2278 00	1774 75	4914 00	3010 00	2153 81	1390 88	1207 88	1079 84	1025 69	1010 73	1010 73	9	10
189	3062 00	2000 50	2833 00	3044 00	2181 40	1210 89	1210 89	1083 05	1028 87	1013 84	1013 86	ģ,	10
	2002.00	0	2000.00	2014.00				1000.00	-020.07	1010.00		ς,	÷.,
190	2532.00	2378.50	5478.00	3066.00	2197.95	1399.88	1399.88	1091.06	1037.41	1021.02	1021.02 9,	10	
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191	3092.00	1079.94	1079.94	3092.00	2201.98	1079.94	1079.94	1079.94	1040.02	1016.88	1016.88 9,	10	
192	2196.00	1461.94	2580.00	2580.00	1822.03	1452.91	1822.03	1100.84	1048.48	1030.27	1030.27 9.	10	
193	3164.00	1968.50	1674.00	2722.00	1867.56	1268.91	1301.03	1105.86	1050.72	1032.60	1032.60 9.	10	
194	2620.00	2354.50	3156.00	2798.00	1901.00	1461.91	1494.03	1113.88	1060.33	1042.23	1042.23 9.	10	
195	3194.00	1438.25	1321.50	2848.00	1933.88	1186.41	1141.03	1116.36	1065.07	1045.69	1045.69 9.	10	
196	2412 00	1828 25	3350 00	2886 00	1952 03	1476 91	1240 53	1126 39	1072 20	1053 90	1053 90 9	10	
197	3236 00	2047 50	2067 00	2926 00	1987 75	1288 91	1243 53	1130 84	1070 43	1057 38	1057 38 9	10	
108	2678 00	2441 50	3938 00	2958 00	2012 10	1485 01	1440 53	1138 //	1082 /6	1064 67	1064 67 9	10	
100	2010.00	10/1 20	1206 50	2000.00	2012.10	1162 16	1100.00	1120 06	1002.40	1061 00	1061 00 0	10	
200	2270 00	1620 20	2550.00	2004.00	2000.00	1507 01	1021 02	1150.00	1000.20	1074 50	1074 52 0	10	
200	2310.00	1039.30	0175 00	2990.00	2030.00	1215 01	1122 02	1100.01	1007 70	1074.02	1074.52 9,	10	
201	0746 00	2112.00	2175.00	2070.00	2000.03	1516.91	1224 02	1100.01	11057.70	1000.19	1000.19 9,	10	
202	2740.00	2514.50	4150.00	3070.00	2094.01	1000 41	1100 52	1105.10	1105.76	1000.44	1000.44 9,	10	
203	3346.00	1022.00	1592.00	3102.00	2121.03	1229.41	1000.03	1105.19	1100.52	1007.00	1007.00.0	10	
204	2526.00	1926.50	4352.00	3120.00	2133.53	1551.91	1292.03	11/0.22	1110.41	1097.00	1097.08 9,	10	
205	3390.00	2175.50	2584.00	3155.00	2164.69	1335.91	1295.03	11/9.44	1118.46	1101.17	1101.17 9,	10	
206	2804.00	2585.50	4964.00	3182.00	2184.88	1540.91	1500.03	1186.77	1128.22	1108.42	1108.42 9,	10	
207	3420.00	1207.06	1204.13	3212.00	2201.50	1187.03	1168.03	1182.77	1132.87	1107.46	1107.35 10		
208	2442.00	1621.06	3766.00	3158.00	2150.66	1570.91	1382.41	1198.58	1139.74	1119.65	1119.65 9,	10	
209	3480.00	2228.50	2299.00	3214.00	2192.00	1370.91	1167.41	1203.41	1141.15	1121.81	1121.81 9,	10	
210	2880.00	2646.50	4390.00	3250.00	2221.31	1579.91	1376.41	1211.31	1150.81	1131.21	1131.21 9,	10	
211	3510.00	1599.50	1674.00	3284.00	2250.69	1280.41	1168.41	1213.52	1154.52	1134.27	1134.27 9,	10	
212	2648.00	2021.50	4600.00	3304.00	2265.16	1594.91	1275.91	1223.66	1162.46	1142.04	1142.04 9,	10	
213	3552.00	2294.50	2724.00	3340.00	2298.06	1390.91	1278.91	1227.84	1165.78	1145.04	1145.04 9,	10	
214	2938.00	2720.50	5236.00	3366.00	2319.88	1603.91	1491.91	1235.39	1174.07	1152.17	1152.17 9,	10	
215	3582.00	1361.00	1426.75	3396.00	2341.06	1253.16	1234.16	1234.45	1166.28	1153.03	1153.03 9,	10	
216	2596.00	1791.00	4816.00	3392.00	2333.03	1625.91	1350.91	1247.52	1178.41	1163.38	1163.38 9,	10	
217	3634.00	2354.50	2840.00	3436.00	2369.69	1417.91	1244.91	1252.16	1180.48	1165.60	1165.60 9,	10	
218	3006.00	2788.50	5464.00	3466.00	2394.75	1634.91	1461.91	1259.92	1189.91	1174.75	1174.75 9,	10	
219	3664.00	1678.75	1964.50	3498.00	2420.69	1323.41	1304.41	1261.84	1194.54	1178.02	1178.02 9,	10	
220	2762.00	2116.75	5682.00	3514.00	2431.66	1649.91	1415.91	1271.69	1201.17	1185.50	1185.50 9,	10	
221	3706.00	2414.50	3281.00	3550.00	2462.38	1437.91	1418.91	1275.81	1200.69	1188.65	1188.65 9,	10	
222	3064.00	2856.50	6342.00	3574.00	2481.94	1658.91	1639.91	1283.02	1212.61	1195.90	1195.90 9,	10	
223	3736.00	1275.97	1282.00	3602.00	2494.00	1269.97	1269.97	1274.22	1216.33	1188.90	1188.90 9,	10	
224	2650.00	1721.97	4022.00	3414.00	2344.09	1697.91	1710.16	1292.67	1224.69	1206.73	1206.73 9,	10	
225	3802.00	2445.50	2459.00	3502.00	2391.03	1481.91	1334.16	1297.73	1227.93	1209.23	1209.23 9,	10	
226	3146.00	2895.50	4694.00	3554.00	2425.66	1706.91	1559.16	1305.81	1236.50	1219.08	1219.08 9,	10	
227	3832.00	1746.50	1794.00	3596.00	2460.03	1383.41	1262.66	1308.31	1239.46	1222.67	1222.67 9,	10	
228	2890.00	2200.50	4920.00	3624.00	2479.34	1721.91	1378.16	1318.48	1247.89	1231.10	1231.10 9,	10	
229	3874.00	2519.50	2916.00	3664.00	2516.91	1501.91	1381.16	1322.92	1250.24	1234.71	1234.71 9,	10	
230	3204.00	2977.50	5604.00	3694.00	2543.03	1730.91	1610.16	1330.59	1259.65	1241.98	1241.98 9,	10	
231	3904.00	1477.00	1530.75	3728.00	2568.53	1352.16	1296.16	1330.14	1264.28	1238.46	1238.46 9,	10	
232	2828.00	1939.00	5152.00	3728.00	2564.59	1752.91	1420.91	1343.02	1271.20	1252.44	1252.44 9,	10	
233	3956.00	2584.50	3040.00	3774.00	2605.16	1528.91	1306.91	1347.70	1266.89	1254.66	1254.66 9.	10	
234	3272.00	3050.50	5848.00	3806.00	2633.78	1761.91	1539.91	1355.58	1281.61	1264.33	1264.33 9.	10	
235	3986.00	1830.75	2104.50	3840.00	2663.16	1426.41	1370.41	1357.52	1287.94	1267.60	1267.60 9.	10	
236	3004.00	2300.75	6082.00	3858.00	2677.34	1776.91	1489.91	1367.75	1293.17	1275.63	1275.63 9.	10	
237	4028.00	2648.50	3513.00	3896.00	2711.28	1548.91	1492.91	1371.95	1296.33	1278.92	1278.92 9.	10	
238	3330 00	3122 50	6790 00	3922 00	2733 91	1785 91	1729 91	1379 38	1304 56	1286 18	1286 18 9	10	
239	4058 00	1413 13	1458 25	3952 00	2753 03	1372 03	1372 03	1375 03	1305 76	1285 26	1282 05 10	10	
240	2892 00	1801 13	5400.00	3896 00	2704 22	1815 01	1614 41	1300 30	1316 78	1207 53	1202.00 10		
240	1110 00	2702 50	2100.00	2050.00	2704.22	1502 01	1267 /1	1205 2/	1210.02	1200 57	1200.10 10		
241	2406 00	2105.50	6120.00	2009 00	2743.04	1003.91	1609 /1	1402 21	1200.00	1209.00	1298.30 10		
242	4148 00	1000 75	2104 50	4036 00	2816 59	1477 41	1368 41	1405.51	1333 81	1311 07	1311 08 10		
243	3126 00	1305.75	£154.00	4058 00	2834 70	1830 01	1/01 01	1415 29	1340 20	1310 74	1310 13 10		
244	4100.00	2330.10	3660 00	4000.00	2004.12	1602 01	1404 01	1400.00	1241 04	1200 74	1200 E0 10		
240	3464 00	2060 50	7004 00	4106 00	2012.09	10/0 01	1720 01	1407 67	1251 01	1220 50	1222.00 10	10	
240	4000.00	1509 62	1775 00	4159 00	2031.04	1440.31	1440 10	1406 01	1255 50	1220 72	1204 20 40	10	
241	*220.00	1090.03	1115.00	4154.00	2323.09	1970 01	1574 01	1420.91	1262 70	1240 80	1240 20 10		
240	4070 00	2092.03	20010.00	4104.00	2310.4/	1620 01	1452 01	1439.20	1267 11	1242.00	1240.20 10		
249	+212.00	2004.00	7254 00	4024 00	2300.22	1030.91	1701 01	1443.08	1075 56	1343.04	1342.45 10		
200	0002.00	0002.00	1354.00	4234.00	2303.(2	1019.91	TIOT.91	1401.00	1313.00	1302.21	1001.90 10		

## A.1.2 Median Filtering

This section considers the problem of selecting the median of a window. Hence  $l = u = \lfloor \frac{W}{2} \rfloor$ .

W	0)	1)	2)	3)	4)	5)	6)	7)	8)	9)	10)	Best strategies	
1	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0, 1, 2, 3, 4, 5, 6, 7, 8, 9,	10
2	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	0, 1, 2, 3, 4, 5, 6, 7, 8, 9,	10
3	4.00	3.00	3.00	4.00	3.00	3.00	3.00	3.00	3.00	3.00	3.00	1, 2, 4, 5, 6, 7, 8, 9, 10	
4	5.00	6.00	5.00	5.00	5.00	5.00	5.00	4.50	4.50	4.50	4.50	7, 8, 9, 10	
5	10.00	5.00	5.00	8.00	7.00	5.00	5.00	5.00	5.00	5.00	5.00	1, 2, 5, 6, 7, 8, 9, 10	
6	11.00	9.50	11.00	11.00	8.50	8.50	8.50	7.00	7.00	7.00	7.00	7, 8, 9, 10	
7	18.00	8.50	8.50	18.00	12.50	8.50	8.50	8.50	8.50	8.50	8.50	1, 2, 5, 6, 7, 8, 9, 10	
8	15.00	13.00	15.00	15.00	15.00	15.00	15.00	10.75	10.33	10.33	10.33	8, 9, 10	
9	30.00	11.00	10.00	18.00	19.00	10.00	10.00	10.00	10.00	10.00	10.00	2, 5, 6, 7, 8, 9, 10	
10	25.00	16.25	23.00	23.00	19.75	14.50	14.50	12.50	12.50	12.50	12.50	7, 8, 9, 10	
11	38.00	12.00	12.00	32.00	22.25	12.00	12.00	12.00	12.00	12.00	12.00	1, 2, 5, 6, 7, 8, 9, 10	
12	29.00	17.25	31.00	31.00	19.75	19.75	19.75	14.25	14.25	14.25	14.25	7, 8, 9, 10	
13	52.00	15.00	20.00	42.00	27.50	16.00	16.00	14.25	14.25	14.25	14.25	7, 8, 9, 10	
14	41.00	21.25	45.00	49.00	33.25	21.25	21.25	17.25	16.50	16.50	16.50	8, 9, 10	
15	60.00	16.25	16.25	60.00	38.75	16.25	16.25	16.25	16.25	16.25	16.25	1, 2, 5, 6, 7, 8, 9, 10	
16	41.00	21.50	41.00	41.00	41.00	28.00	41.00	19.38	19.17	19.17	19.17	8, 9, 10	
17	80.00	24.00	23.00	44.00	49.00	23.50	23.00	19.50	17.33	17.33	17.33	8, 9, 10	
18	63.00	29.75	51.00	51.00	51.00	29.50	28.50	21.25	19.50	19.50	19.50	8, 9, 10	
19	90.00	20.00	19.50	62.00	53.88	19.50	19.50	19.50	19.50	19.50	19.50	2, 5, 6, 7, 8, 9, 10	
20	61.00	25.63	61.00	61.00	49.00	27.25	27.25	22.38	20.83	20.83	20.83	8, 9, 10	
21	106.00	29.00	35.00	72.00	54.75	23.50	23.50	21.88	21.88	21.88	21.88	7, 8, 9, 10	
22	81.00	35.75	79.00	83.00	57.50	29.75	29.75	23.88	23.88	23.88	23.88	7, 8, 9, 10	
23	116.00	21.00	21.00	98.00	61.13	21.00	21.00	21.00	21.00	21.00	21.00	1, 2, 5, 6, 7, 8, 9, 10	
24	75.00	26.63	81.00	81.00	46.88	33.38	46.88	24.63	23.92	23.92	23.92	8, 9, 10	
25	138.00	33.00	45.00	100.00	58.75	30.50	30.00	24.13	23.83	23.83	23.83	8, 9, 10	
26	105.00	40.75	97.00	113.00	66.63	36.88	35.38	25.88	25.42	25.42	25.42	8, 9, 10	

27	148.00	26.25	32.00	128.00	75.50	26.25	26.25	25.25	24.33	24.33	24.33	8, 9, 10
28	97.00	31.88	115.00	131.00	76.38	34.88	34.88	27.63	27.63	27.63	27.63	7, 8, 9, 10
29	164.00	43.00	65.00	148.00	90.00	32.50	32.50	27.88	25.67	25.67	25.67	8, 9, 10
30	123.00	50.75	141.00	159.00	99.63	39.13	39.13	30.38	28.42	28.42	28.42	8, 9, 10
31	174.00	26.13	26.13	174.00	105.88	26.13	26.13	26.13	26.13	26.13	26.13	1, 2, 5, 6, 7, 8, 9, 10
32	107.00	31.75	107.00	107.00	107.00	43.50	107.00	29.75	28.92	28.92	28.92	8, 9, 10
33	204.00	56.00	56.00	110.00	120.75	40.25	56.00	30.50	29.75	29.75	29.75	8. 9. 10
34	155.00	62.25	119.00	119.00	126.06	47.25	62.50	32.31	31.17	31.17	31.17	8. 9. 10
35	216 00	37 00	37 00	132 00	131 56	37 00	37 00	30 63	27 00	27 00	27 00	8 9 10
26	141 00	10 00	121 00	121 00	107 20	45 25	44 75	22 //	20.50	20.59	20 50	8 9 10
30	141.00	42.00	131.00	131.00	127.30	40.20	44.75	00.44	30.38	30.38	30.38	8, 9, 10
37	236.00	64.00	70.00	142.00	134.50	42.25	41.00	33.06	30.17	30.17	30.17	8, 9, 10
38	177.00	71.25	151.00	155.00	136.44	49.50	47.75	34.69	31.50	31.50	31.50	8, 9, 10
39	248.00	31.00	30.25	172.00	139.31	30.25	30.25	30.25	30.25	30.25	30.25	2, 5, 6, 7, 8, 9, 10
40	151.00	36.81	155.00	155.00	118.50	42.63	56.13	33.88	33.88	33.88	33.88	7, 8, 9, 10
41	274.00	69.00	82.00	174.00	128.00	39.75	39.25	34.44	31.08	31.08	31.08	8, 9, 10
42	205.00	77.25	175.00	191.00	132.06	46.63	45.13	35.88	33.92	33.92	33.92	8, 9, 10
43	286.00	44.25	52.50	210.00	138.44	36.50	36.50	34.25	34.25	34.25	34.25	7, 8, 9, 10
44	183.00	50.13	197.00	213.00	135.63	45.13	45.13	36.69	35.00	35.00	35.00	8, 9, 10
45	306.00	79.00	106.00	230.00	146.75	42.75	42.75	36.31	36.31	36.31	36.31	7, 8, 9, 10
46	227.00	87.25	229.00	247.00	152.94	50.13	50.13	38.06	38.06	38.06	38.06	7.8.9.10
47	318 00	32 00	32 00	268 00	156 81	32 00	32 00	32 00	31 75	31 75	31 75	8 9 10
48	189 00	37 81	203 00	203.00	113 0/	19 69	113 0/	35 81	35 81	35 81	35 81	7 8 9 10
40	250.00	79 00	106 00	200.00	121 62	47 05	64 00	27 10	25 75	25 75	25 75	8 0 10
-1J E0	261 00	07 05	221 00	261 00	1/2 10	EA 06	60.21	20 62	26.06	26.06	26.06	8 9 10
50	261.00	67.25	221.00	261.00	145.19	54.00	69.31	30.03	30.90	36.96	30.90	8, 9, 10
51	362.00	50.25	63.50	282.00	155.00	44.13	43.63	37.55	35.75	35.75	35.75	8, 9, 10
52	231.00	56.13	241.00	289.00	157.19	53.19	52.19	39.56	39.56	39.56	39.56	7, 8, 9, 10
53	382.00	89.00	128.00	308.00	172.63	51.50	49.75	38.88	36.44	36.44	36.44	8, 9, 10
54	283.00	100.25	271.00	325.00	182.69	59.06	56.56	41.38	39.79	39.79	39.79	8, 9, 10
55	394.00	38.63	46.00	346.00	192.25	38.63	38.63	37.38	36.17	36.17	36.17	8, 9, 10
56	235.00	44.44	285.00	333.00	177.69	51.44	64.94	41.19	40.21	40.21	40.21	8, 9, 10
57	420.00	100.00	150.00	360.00	197.50	49.25	48.75	40.94	40.94	40.94	40.94	7, 8, 9, 10
58	311.00	111.25	313.00	379.00	211.19	56.19	54.69	42.88	42.29	42.29	42.29	8, 9, 10
59	432.00	62.50	88.00	400.00	225.88	46.38	46.38	42.13	37.33	37.33	37.33	8, 9, 10
60	273.00	68.38	345.00	407.00	230.69	55.69	55.69	44.38	41.88	41.88	41.88	8, 9, 10
61	452.00	117.00	184.00	430.00	250.25	54.25	54.25	44.25	41.33	41.33	41.33	8, 9, 10
62	333.00	126.25	387.00	445.00	263.81	61.81	61.81	46.25	42.22	42.22	42.22	8. 9. 10
63	464 00	38.06	38.06	464 00	269 94	38.06	38.06	38.06	38.06	38.06	38.06	1 2 5 6 7 8 9 10
64	269.00	43.88	269 00	269 00	269 00	61 75	269 00	41 88	41 88	41 88	41 88	7 8 9 10
65	E06 00	122 00	127 00	200.00	200.00	EQ 12	127 00	44.95	41.00	41.00	41 12	8 0 10
66	377.00	102.00	137.00	212.00	290.00	09.10	144 50	44.20	41.13	41.13	41.13	8, 9, 10
00	577.00	130.75	263.00	265.00	300.44	50.30	144.50	45.91	43.79	43.79	43.79	8, 9, 10
67	520.00	77.00	78.50	298.00	310.59	56.75	78.50	44.00	43.63	43.63	43.63	8, 9, 10
68	331.00	83.13	297.00	297.00	309.25	65.63	86.25	46.91	43.92	43.92	43.92	8, 9, 10
69	544.00	146.00	153.00	308.00	320.31	63.63	82.50	46.44	44.92	44.92	44.92	8, 9, 10
70	403.00	153.75	319.00	323.00	324.06	71.50	89.75	48.03	46.33	46.33	46.33	8, 9, 10
71	558.00	52.00	51.50	342.00	328.78	51.25	51.50	43.81	38.33	38.33	38.33	8, 9, 10
72	331.00	57.94	325.00	325.00	308.00	63.88	77.38	47.72	44.04	44.04	44.04	8, 9, 10
73	590.00	154.00	167.00	344.00	319.88	61.38	60.50	47.88	44.00	44.00	44.00	8, 9, 10
74	437.00	162.75	347.00	363.00	324.19	68.75	66.63	49.47	44.88	44.88	44.88	8, 9, 10
75	604.00	87.25	96.00	384.00	330.84	59.25	58.25	47.56	44.04	44.04	44.04	8, 9, 10
76	381.00	93.38	371.00	387.00	326.50	68.25	66.88	50.09	47.38	47.38	47.38	8, 9, 10
77	628 00	166 00	193 00	404 00	337 44	66.38	64 50	49 47	44 29	44 29	44 29	8 9 10
78	463.00	174 75	405 00	423 00	341 56	74 38	72 13	50 91	47 50	47 50	47 50	8 9 10
70	642.00	44 00	12 12	446 00	242 66	/2 12	/2.10	42 12	42 12	12 12	42 12	0, 0, 10
90	360.00	44.00	201 00	201 00	000 12	40.10	105 06	40.10	45.15	45.15	45.15	7 9 0 10
00	369.00	49.91	105 00	416.00	202.13	50.01	125.00	40.94	40.94	40.94	40.94	7, 8, 9, 10
81	680.00	166.00	195.00	416.00	297.00	58.38	75.13	50.03	48.88	48.88	48.88	8, 9, 10
82	503.00	1/5./5	403.00	443.00	304.19	65.44	80.69	51.28	50.04	50.04	50.04	8, 9, 10
83	694.00	94.25	110.00	468.00	313.03	55.75	55.25	49.47	44.42	44.42	44.42	8, 9, 10
84	437.00	100.38	427.00	475.00	311.00	64.81	63.81	51.88	48.58	48.58	48.58	8, 9, 10
85	718.00	177.00	221.00	494.00	323.56	63.13	61.38	50.97	48.08	48.08	48.08	8, 9, 10
86	529.00	188.75	461.00	515.00	329.31	70.94	68.44	52.81	49.63	49.63	49.63	8, 9, 10
87	732.00	60.63	70.25	540.00	335.84	50.75	50.75	48.25	48.25	48.25	48.25	7, 8, 9, 10
88	429.00	66.56	479.00	527.00	317.13	63.56	77.06	52.16	52.16	52.16	52.16	7, 8, 9, 10
89	764.00	188.00	247.00	554.00	334.00	61.38	60.88	51.91	48.44	48.44	48.44	8, 9, 10
90	563.00	199.75	513.00	579.00	343.56	68.69	67.19	53.44	51.63	51.63	51.63	8, 9, 10
91	778.00	106.50	139.50	606.00	355.28	59.25	59.25	51.75	51.75	51.75	51.75	7, 8, 9, 10
92	487.00	112.63	551.00	613.00	356.00	68.56	68.56	54.13	52.17	52.17	52.17	8, 9, 10
93	802.00	205.00	287.00	636.00	372.56	67.13	67.13	53.56	53.42	53.42	53.42	8, 9, 10
94	589.00	214.75	601.00	659.00	382.19	75.19	75.19	55.06	54.83	54.83	54.83	8, 9, 10
95	816.00	45.00	45.00	686.00	385.41	45.00	45.00	45.00	44.04	44.04	44.04	8, 9, 10
96	463.00	50.91	493.00	493.00	276.97	68.84	276.97	48.91	48.91	48.91	48.91	7, 8, 9, 10
97	860.00	185.00	251.00	560.00	301.94	66.63	146.00	53.22	50.54	50.54	50.54	8, 9, 10
98	635.00	195.75	513.00	601.00	318.78	73.59	151.22	54.50	51.48	51.48	51.48	8, 9, 10
99	874.00	106.25	137.00	632.00	335.38	63.94	84.94	53.00	50.17	50.17	50.17	8, 9, 10
100	549.00	112.38	535.00	647.00	340.72	73.22	93.47	55.06	53.90	53.90	53.90	8, 9, 10
101	898.00	200.00	275.00	670.00	360.31	71,88	91.00	54,25	50,83	50,83	50,83	8, 9, 10
102	661 00	214 75	567 00	693 00	372 66	79.72	97.72	56.28	53.77	53.77	53.77	8. 9. 10
103	912 00	67 63	83 25	720 00	384 39	59 69	59 11	52 16	49 88	49.88	49 88	8 9 10
10/	532.00	73 56	583 00	711 00	370 47	70 70	85 70	56 06	54 00	54 00	54 00	8 9 10
105	944 00	212 00	200.00	740.00	303 00	70 00	69 50	55.00	55 04	55 04	55 04	8 9 10
100	544.00 605 00	212.00	255.00	765 00	407 04	70.00	75 47	50.44 EC 04	55.04 E6 02	55.04 E6 02	55.04 E6 02	0, <del>3</del> , 10 0 0 10
107	050.00	101 50	164 50	700.00	402 50	60.22	67 10	50.04	40.23	40.23	40.23	0, <del>3</del> , 10 0 0 10
100	906.00	107.00	104.50	192.00	423.50	00.94	01.19	00.00	49.0/	49.0/	49.0/	0, 9, 10
108	599.00	127.63	651.00	801.00	427.72	78.59	76.47	58.06	55.56	55.56	55.56	8, 9, 10
109	982.00	233.00	337.00	826.00	447.69	//.63	75.00	57.63	55.13	55.13	55.13	8, 9, 10
110	721.00	245.75	699.00	849.00	460.53	85.84	82.72	59.47	55.90	55.90	55.90	8, 9, 10
111	996.00	53.06	62.00	876.00	469.88	53.06	53.06	51.56	50.08	50.08	50.08	8, 9, 10
112	565.00	58.97	687.00	815.00	415.09	70.97	135.22	55.47	54.10	54.10	54.10	8, 9, 10
113	1034.00	240.00	351.00	860.00	442.75	68.88	85.63	57.78	54.94	54.94	54.94	8, 9, 10
114	761.00	252.75	717.00	891.00	462.16	75.91	91.16	59.09	57.65	57.65	57.65	8, 9, 10
115	1048.00	134.50	189.50	920.00	481.81	66.31	65.81	58.03	57.19	57.19	57.19	8, 9, 10
116	655.00	140.63	751.00	933.00	489.97	75.72	74.72	60.03	57.03	57.03	57.03	8, 9, 10
117	1072.00	256.00	387.00	960.00	513.38	74.50	72.75	59.34	58.33	58.33	58.33	8, 9, 10
118	787.00	272.75	797.00	983.00	529.28	82.41	79.91	61.69	59.52	59.52	59.52	8, 9, 10
119	1086.00	82,25	113.00	1010.00	544.69	62,44	62.44	57,56	50,67	50,67	50,67	8, 9, 10
120	631 00	88.19	827 00	1001 00	534 09	75.59	89.09	61.47	56.52	56.52	56.52	8. 9. 10
121	1118 00	275 00	425 00	1036 00	561 88	73.88	73.38	61.09	57.63	57.63	57.63	8, 9, 10
122	821 00	289 75	871 00	1061 00	581 47	81 22	79 70	62 78	58 31	58 31	58 31	8 9 10
102	1120 00	152 75	330 00	1089 00	602.00	71 04	71 04	61 44	57 99	57 02	57 02	8 9 10
123	1132.00	150.00	230.00	1000.00	610 04	01 70	11.94	01.44	D1.23	51.23	D1.23	0, 9, 10
124	/05.00	158.88	921.00	1099.00	010.84	81.72	81.72	03.72	60.52	60.52	60.52	0, 9, 10
105	1166 00	244 00	411 00	1128.00	636 38	80.88	80 88	63.28	b6 25	b6 25	b6 25	8 9 10

126	847.00	309.75	983.00	1147.00	653.91	89.03	89.03	64.91	60.40	60.40	60.40	8, 9,	10					
127	1170.00	52.03	52.03	1170.00	658.97	52.03	52.03	52.03	52.03	52.03	52.03	1, 2,	5,	6,	7, 1	в, я	э, :	10
128	655.00	57.94	655.00	655.00	655.00	82.88	655.00	55.94	55.94	55.94	55.94	7, 8,	9,	10				
129	1226.00	308.00	330.00	658.00	684.56	80.56	330.00	60.94	60.94	60.94	60.94	7.8.	9.	10				
130	905 00	315 25	671 00	671 00	701 67	87 81	338 50	62 42	62 17	62 17	62 17	8 9	10	10				
130	1040.00	160.00	176.00	600.00	710.00	70.20	176.00	02.42	02.17	02.17 FF 00	55.00	0, 9,	10					
131	1242.00	169.00	176.00	688.00	/18.20	78.38	176.00	60.34	55.92	55.92	55.92	8, 9,	10					
132	779.00	175.38	687.00	687.00	721.53	87.56	183.75	63.20	60.71	60.71	60.71	8, 9,	10					
133	1270.00	334.00	348.00	698.00	738.63	86.06	180.00	62.59	59.92	59.92	59.92	8, 9,	10					
134	935.00	342.25	711.00	715.00	746.39	94.13	187.75	64.02	60.81	60.81	60.81	8, 9,	10					
135	1286.00	100.00	100.75	736.00	755.20	74.25	100.75	59.63	59.58	59.58	59.58	8, 9,	10					
136	749.00	106.06	719.00	719.00	736.69	87.19	126.63	63.58	62.96	62.96	62.96	8.9.	10					
137	1324 00	348 00	364 00	738 00	753 75	85 19	109 75	63 81	59 27	50 27	59 27	8 Q	10					
120	1324.00	340.00	742.00	750.00	761 17	00.15	116 12	03.01	09.21	09.21	09.21	0, 9,	10					
138	975.00	357.25	743.00	759.00	/61.1/	92.75	116.13	65.30	62.10	62.10	62.10	8, 9,	10					
139	1340.00	185.25	195.50	782.00	770.95	83.63	108.00	63.13	61.98	61.98	61.85	10						
140	837.00	191.63	769.00	785.00	767.84	93.13	116.63	65.83	62.13	62.13	62.13	8, 9,	10					
141	1368.00	364.00	392.00	802.00	781.69	91.94	114.25	65.19	63.17	63.17	63.17	8, 9,	10					
142	1005.00	373.25	805.00	823.00	786.77	100.31	122.13	66.58	64.29	64.29	64.29	8.9.	10					
143	1384.00	69.00	68.25	848.00	789.95	67.63	68.25	59.03	51.67	51.67	51.67	8. 9.	10					
144	781 00	7/ 97	783 00	783 00	727 75	85 44	150 19	62.98	57 52	57 52	57 52	s 0	10					
144	1420.00	267 00	206.00	010.00	745 04	00.44	100.15	02.90	61.02	01.02	61.02	0, 9,	10					
145	1430.00	367.00	396.00	010.00	745.94	03.19	100.25	65.66	61.08	61.08	61.08	0, 9,	10					
146	1053.00	377.25	807.00	847.00	754.42	90.50	105.94	67.02	61.65	61.65	61.65	8, 9,	10					
147	1446.00	195.25	211.50	874.00	764.64	81.13	80.63	65.00	60.67	60.67	60.67	8, 9,	10					
148	903.00	201.63	833.00	881.00	762.16	90.38	89.19	67.83	63.63	63.63	63.63	8, 9,	10					
149	1474.00	380.00	424.00	900.00	775.75	88.94	86.75	66.97	60.35	60.35	60.35	8.9.	10					
150	1083 00	392 25	869 00	923 00	780 64	97.06	93 94	68 61	63 56	63 56	63 56	8 9	10					
150	1400.00	111 62	101 50	050.00	706 50	77 05	76 20	62 01	E0 60	E0 60	E0 60	0, 5,	10					
151	1490.00	111.03	121.50	930.00	780.52	11.25	10.38	03.91	39.09	39.09	09.09	0, 9,	10					
152	863.00	117.69	889.00	937.00	765.44	90.25	102.69	67.86	63.44	63.44	63.44	8, 9,	10					
153	1528.00	393.00	452.00	964.00	782.63	88.31	86.50	67.73	64.38	64.38	64.38	8, 9,	10					
154	1123.00	405.25	925.00	991.00	790.67	95.94	92.94	69.09	65.48	65.48	65.48	8, 9,	10					
155	1544.00	209.50	243.00	1020.00	801.14	86.88	85.13	66.97	59.69	59.69	59.69	8, 9,	10					
156	961.00	215.88	965.00	1027.00	798.97	96.44	94.44	69.44	65.10	65.10	65.10	8.9.	10					
157	1572 00	412 00	494 00	1050 00	814 06	95 31	93 00	68 69	64 31	64 31	64 31	s 0	10					
157	1072.00	412.00	494.00	1030.00	814.00	30.31	93.00	00.03	04.31	04.31	04.31	0, 9,	10					
158	1153.00	422.25	1017.00	1075.00	820.52	103.75	101.19	69.97	65.06	65.06	65.06	8, 9,	10					
159	1588.00	59.00	58.06	1104.00	820.95	58.06	58.06	58.06	58.06	58.06	58.06	2, 5,	6,	7,	8, 9	9, 3	10	
160	883.00	64.95	911.00	911.00	661.81	81.91	290.03	61.97	61.97	61.97	61.97	7, 8,	9,	10				
161	1640.00	393.00	460.00	978.00	683.50	79.69	159.06	68.58	62.33	62.33	62.33	8, 9,	10					
162	1207.00	404.25	935.00	1023.00	695.48	86.78	164.41	69.73	66.98	66.98	66.98	8, 9,	10					
163	1656.00	210.25	243.50	1058.00	708.67	77.25	98.25	67.72	66.75	66.75	66.75	8.9.	10					
164	1033 00	216 63	961 00	1073 00	709 28	86 53	106 78	70.08	66 69	66 69	66 69	s 0	10					
104	1000.00	400.00	400.00	1006.00	705.20	00.00	100.70	60.14	67.71	67.71	67.71	0, 5,	10					
165	1684.00	408.00	488.00	1096.00	725.56	85.19	104.31	69.14	67.71	67.71	67.71	8, 9,	10					
166	1237.00	423.25	997.00	1123.00	733.08	93.16	111.16	70.70	69.10	69.10	69.10	8, 9,	10					
167	1700.00	119.63	137.50	1154.00	741.36	73.25	73.00	66.17	58.96	58.96	58.96	8, 9,	10					
168	983.00	125.69	1017.00	1145.00	722.75	86.28	99.28	70.13	64.81	64.81	64.81	8, 9,	10					
169	1738.00	420.00	516.00	1174.00	742.00	84.44	83.06	69.88	65.58	65.58	65.58	8, 9,	10					
170	1277.00	437.25	1053.00	1203.00	752.05	91.91	89.16	71.17	66.33	66.33	66.33	8.9.	10					
171	1754 00	225 50	275 00	1234 00	764 17	82 75	81 00	69 17	66 02	66 02	66 02	s 0	10					
170	1001.00	021 00	1002 00	12042.00	762.70	02.10	01.00	71 00	60.02	60.02	60.02	0, 5,	10					
172	1091.00	231.00	1093.00	1243.00	763.72	92.41	90.28	/1.80	00.00	00.00	00.00	0, 9,	10					
173	1782.00	441.00	558.00	1268.00	780.31	91.44	88.81	71.05	65.90	65.90	65.90	8, 9,	10					
174	1307.00	454.25	1145.00	1295.00	788.39	99.78	96.66	72.55	69.35	69.35	69.35	8, 9,	10					
175	1798.00	79.06	90.13	1326.00	794.23	67.13	67.13	64.31	64.31	64.31	64.31	7, 8,	9,	10				
176	1007.00	85.03	1137.00	1265.00	734.81	85.03	149.28	68.27	68.27	68.27	68.27	7.8.	9.	10				
177	1844 00	448 00	576 00	1310 00	759 06	82 94	99 69	70 86	70 31	70 31	70 31	8 9	10					
170	1255 00	461 95	1172 00	1247 00	772 90	00.16	105 41	70.05	71 01	71 01	71 01	0, 0,	10					
170	1960.00	401.20	205.00	1347.00	700.00	90.10	105.41	72.03	62.56	62 56	62 56	0, 9,	10					
179	1860.00	230.50	305.00	1362.00	769.96	80.75	80.25	70.23	03.50	63.56	03.50	0, 9,	10					
180	1157.00	244.88	1213.00	1395.00	793.53	90.16	89.16	72.66	69.92	69.92	69.92	8, 9,	10					
181	1888.00	464.00	618.00	1422.00	813.50	88.94	87.19	71.73	69.29	69.29	69.29	8, 9,	10					
182	1385.00	481.25	1265.00	1451.00	824.77	97.03	94.53	73.50	70.38	70.38	70.38	8, 9,	10					
183	1904.00	134.25	172.25	1484.00	836.67	77.25	77.25	68.88	68.88	68.88	68.88	7, 8,	9,	10				
184	1097.00	140.31	1301.00	1475.00	821.50	90.41	103.91	72.83	72.75	72.75	72.75	8. 9.	10					
195	1042.00	102 00	662.00	1510.00	0/E 01	00.11	99 10	70 50	60.04	60.04	60.04	0, 0,	10					
100	1942.00	403.00	002.00	1510.00	040.01	00.09	00.19	72.52	09.04	09.04	70.00	0, 9,	10					
186	1425.00	498.25	1353.00	1543.00	860.86	96.28	94.78	73.92	72.02	72.02	72.02	8, 9,	10					
187	1958.00	256.75	352.50	1578.00	877.98	87.25	87.25	71.94	71.94	71.94	71.94	7, 8,	9,	10				
188	1215.00	263.13	1411.00	1589.00	882.22	97.03	97.03	74.33	69.74	69.74	69.74	8, 9,	10					
189	1986.00	507.00	722.00	1618.00	904.25	96.19	96.19	73.61	73.23	73.23	73.23	8, 9,	10					
190	1455.00	518.25	1483.00	1647.00	917.33	104.66	104.66	74.92	74.35	74.35	74.35	8.9.	10					
191	2002 00	60.00	60.00	1680 00	918.95	60.00	60.00	60.00	58.35	58.35	58.35	8.9	10					
100	1105.00	CF OF	1167 00	1167.00	662.00	00.00	662.00	62.05	63.05	62.05	62.05	7 0	-	10				
192	1105.00	400.00	1107.00	1107.00	003.50	90.92	003.98	03.95	03.95	03.95	03.90	1, 0,	5,	10				
192	2000.00	±32.00	000.00	1290.00	091.03	00.01	340.00	12.20	00.31	00.31	00.31	o, 9,	10					
194	1515.00	444.25	1189.00	1373.00	721.11	95.83	345.14	73.39	69.05	69.05	69.05	8, 9,	10					
195	2076.00	234.25	306.50	1422.00	744.13	86.28	182.28	71.55	67.65	67.65	67.65	8, 9,	10					
196	1293.00	240.63	1213.00	1453.00	754.30	95.67	190.80	73.75	71.20	71.20	71.20	8, 9,	10					
197	2104.00	457.00	614.00	1484.00	780.03	94.50	188.31	72.88	68.00	68.00	68.00	8, 9,	10					
198	1545.00	475.25	1247.00	1517.00	796.61	102.45	194.95	74.55	70.89	70.89	70.89	8.9.	10					
199	2120 00	133 63	168 50	1554 00	812 56	82.59	108 34	70.25	66 83	66 83	66 83	8 9	10					
100	1002.00	120.00	100.00	1554.00	012.00	02.00	100.04	74.00	70.04	70.04	70.04	0, 5,	10					
200	1223.00	139.09	1200.00	1003.00	001.23	30.13	134.01	14.20	10.64	10.64	10.64	o, 9,	10					
201	2158.00	473.00	640.00	1586.00	829.22	94.06	118.38	73.59	71.77	71.77	71.77	8, 9,	10					
202	1585.00	495.25	1299.00	1617.00	847.55	101.52	124.27	74.89	72.82	72.82	72.82	8, 9,	10					
203	2174.00	255.50	336.00	1650.00	866.50	92.41	115.91	73.38	66.92	66.92	66.92	8, 9,	10					
204	1351.00	261.88	1337.00	1663.00	872.42	102.23	125.17	75.61	72.26	72.26	72.26	8, 9.	10					
205	2202.00	500.00	680.00	1692 00	895.59	101.50	123.69	75.03	71.60	71.60	71.60	8.9	10					
206	161E 00	516 25	1387 00	1721 00	000.00	100 00	131 22	76 50	72 00	72 00	72 00	2, 2, 8 0	10					
200	1010.00	010.20	105 10	1754 00	000.02	103.03	131.33	10.09	12.22	12.22	12.22	0, 9,	10					
207	2218.00	01.06	105.13	1/54.00	920.69	11.34	11.41	08.83	00.10	00.10	00.10	σ, 9,	10					
208	1239.00	93.03	1377.00	1697.00	865.86	95.36	159.61	72.78	70.20	70.20	70.20	8, 9,	10					
209	2264.00	508.00	696.00	1744.00	897.22	93.44	110.00	75.56	71.02	71.02	71.02	8, 9,	10					
210	1663.00	526.25	1411.00	1781.00	918.67	100.64	115.52	76.55	73.86	73.86	73.86	8, 9.	10					
211	2280.00	271.50	364.00	1816.00	940.19	91.28	90.16	75.08	73.31	73.31	73.31	8, 9.	10					
212	1417 00	277.88	1449 00	1831 00	948.67	100.86	99.05	76.80	73.76	73.76	73.76	8.9	10					
212	7411.00	520 00	736 00	1860 00	073 E0	200.00	97 06	75 21	74 67	74 67	74 67	3, <del>3</del> , 8 0	10					
213	2300.00	020.00	130.00	1000.00	313.59	39.00	J1.00	10.01	14.0/	(4.0/	14.0/	o, 9,	10					
214	1693.00	548.25	1499.00	1889.00	989.55	108.02	104.20	(1.84	15.74	15.74	75.74	8, 9,	10					
215	2324.00	151.25	201.25	1922.00	1004.88	88.34	86.72	73.39	64.56	64.56	64.56	8, 9,	10					
216	1337.00	157.31	1533.00	1915.00	992.86	101.67	113.36	77.34	71.29	71.29	71.29	8, 9,	10					
217	2362.00	543.00	778.00	1952.00	1021.53	100.19	97.63	77.25	73.75	73.75	73.75	8, 9.	10					
218	1733.00	567.25	1583.00	1985.00	1040.73	107.83	104.02	78.75	74.36	74.36	74.36	8, 9.	10					
219	2378 00	291.75	409 50	2020 00	1060 81	98.91	96.28	77.16	73.25	73.25	73.25	8.9	10					
220	147E 00	202.10	1630 00	2020.00	1067 90	108 00	106 05	70 /0	76 F1	76 F1	76 F1	3, <del>3</del> , 8 0	10					
220	1410.00	290.13	1039.00	2033.00	1000	100.92	100.05	19.48	10.01	10.51	10.01	o, 9, o -	10					
221	2406.00	575.00	836.00	2064.00	1092.53	108.38	105.19	/8.84	/3.21	/3.21	/3.21	8,9,	10					
222	1763.00	589.25	1709.00	2093.00	1108.23	116.95	113.45	80.31	76.34	76.34	76.34	8, 9,	10					
223	2422.00	69.53	80.00	2126.00	1116.44	69.53	69.53	67.78	66.04	66.04	66.04	8, 9,	10					
224	1335.00	75.48	1617.00	1937.00	964.55	93.48	301.61	71.73	70.05	70.05	70.05	8, 9,	10					

225	2474.00 564.00	816.00 2016.00	1001.50 91.44	170.81	77.52	77.25	77.25	77.25	8, 9, 10
226	1817.00 578.25	1649.00 2067.00	1028.23 98.48	176.11	78.73	78.28	78.28	78.28	8, 9, 10
227	2490.00 299.50	423.00 2108.00	1054.72 88.97	109.97	77.13	71.94	71.94	71.94	8, 9, 10
228	1547.00 305.88	1685.00 2131.00	1068.05 98.42	118.67	79.19	77.05	77.05	77.05	8, 9, 10
229	2518.00 582.00	854.00 2164.00	0 1097.63 97.31	116.44	78.27	76.23	76.23	76.23	8, 9, 10
230	1847.00 606.25	1733.00 2195.00	1117.86 105.30	123.30	80.23	76.91	76.91	76.91	8, 9, 10
231	2534.00 166.25	230.25 2230.00	) 1137.47 85.47	85.22	76.08	75.52	75.52	75.52	8, 9, 10
232	1457.00 172.31	1765.00 2227.00	1129.55 98.67	111.67	80.03	78.85	78.85	78.85	8, 9, 10
233	2572.00 600.00	894.00 2266.00	1162.13 97.06	95.69	79.42	73.57	73.57	73.57	8, 9, 10
234	1887.00 628.25	1813.00 2299.00	1184.86 104.55	101.80	80.84	77.93	77.93	77.93	8, 9, 10
235	2588.00 322.75	466.50 2334.00	1208.34 95.47	93.72	79.58	77.51	77.51	77.51	8, 9, 10
236	1605.00 329.13	1867.00 2349.00	1218.55 105.36	103.23	81.86	77.69	77.69	77.69	8, 9, 10
237	2616.00 634.00	950.00 2382.00	1246.50 104.69	102.06	81.36	78.60	78.60	78.60	8, 9, 10
238	1917.00 652.25	1935.00 2411.00	1265.23 113.11	109.98	83.11	79.57	79.57	79.57	8, 9, 10
239	2632.00 104.13	140.00 2444.00	1280.47 80.59	80.59	75.09	66.00	66.00	66.00	8, 9, 10
240	1465.00 110.09	1941.00 2387.00	1229.67 98.67	162.92	79.05	71.93	71.93	71.93	8, 9, 10
241	2678.00 650.00	982.00 2442.00	1267.31 96.81	113.56	81.69	77.19	77.19	77.19	8, 9, 10
242	1965.00 666.25	1987.00 2481.00	1294.64 104.02	119.27	82.83	77.16	77.16	77.16	8, 9, 10
243	2694.00 342.75	509.50 2518.00	1322.22 94.66	94.16	81.33	76.44	76.44	76.44	8, 9, 10
244	1671.00 349.13	2039.00 2537.00	1336.36 104.30	103.30	83.48	79.44	79.44	79.44	8, 9, 10
245	2722.00 671.00	1036.00 2572.00	1367.75 103.38	101.63	82.63	76.07	76.07	76.07	8, 9, 10
246	1995.00 693.25	2105.00 2601.00	1389.58 111.52	109.02	84.53	79.15	79.15	79.15	8, 9, 10
247	2738.00 187.88	278.00 2634.00	) 1410.91 91.84	91.84	80.09	75.07	75.07	75.07	8, 9, 10
248	1571.00 193.94	2155.00 2629.00	1404.30 105.23	118.73	84.05	78.84	78.84	78.84	8, 9, 10
249	2776.00 698.00	1094.00 2672.00	1440.06 103.81	103.31	83.66	79.71	79.71	79.71	8, 9, 10
250	2035.00 716.25	2219.00 2703.00	1465.61 111.42	109.92	85.14	80.69	80.69	80.69	8, 9, 10

#### A.1.3 Minimum Filtering

This section considers the problem of selecting the minimum of a window. Hence l = u = 0.

W	0)	1)	2)	3)	4)	5)	6)	7)	8)	9)	10)	Best strategies
1	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10
2	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10
3	2.0	1.5	1.5	2.0	1.5	1.5	1.5	1.5	1.5	1.5	1.5	1, 2, 4, 5, 6, 7, 8, 9, 10
4	2.0	2.5	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	2.0	0, 2, 3, 4, 5, 6, 7, 8, 9, 10
5	3.0	2.0	2.0	3.0	2.25	2.0	2.0	2.0	2.0	2.0	2.0	1, 2, 5, 6, 7, 8, 9, 10
6	3.0	3.0	3.0	3.0	2.5	2.5	2.5	2.5	2.33	2.33	2.33	8, 9, 10
7	4.0	2.25	2.25	4.0	2.75	2.25	2.25	2.25	2.25	2.25	2.25	1, 2, 5, 6, 7, 8, 9, 10
8	3.0	3.25	3.0	3.0	3.0	3.0	3.0	2.75	2.67	2.67	2.67	8, 9, 10
9	5.0	2.5	2.5	4.0	3.13	2.5	2.5	2.5	2.5	2.5	2.5	1, 2, 5, 6, 7, 8, 9, 10
10	4.0	3.5	4.0	4.0	3.25	3.0	3.0	3.0	3.0	3.0	3.0	5, 6, 7, 8, 9, 10
11	5.0	2.5	2.5	5.0	3.38	2.5	2.5	2.5	2.5	2.5	2.5	1, 2, 5, 6, 7, 8, 9, 10
12	4.0	3.5	4.0	4.0	3.25	3.25	3.25	3.0	2.83	2.83	2.83	8, 9, 10
13	6.0	2.75	3.0	5.0	3.5	2.75	2.75	2.75	2.67	2.67	2.67	8, 9, 10
14	5.0	3.75	5.0	5.0	3.75	3.25	3.25	3.25	3.0	3.0	3.0	8, 9, 10
15	6.0	2.63	2.63	6.0	3.88	2.63	2.63	2.63	2.63	2.63	2.63	1, 2, 5, 6, 7, 8, 9, 10
16	4.0	3.63	4.0	4.0	4.0	3.5	4.0	3.13	3.13	3.13	3.13	7, 8, 9, 10
17	7.0	3.0	3.0	5.0	4.06	3.0	3.0	2.88	2.83	2.83	2.83	8, 9, 10
18	6.0	4.0	5.0	5.0	4.13	3.5	3.5	3.38	3.08	3.08	3.08	8, 9, 10
19	7.0	2.75	2.75	6.0	4.19	2.75	2.75	2.75	2.75	2.75	2.75	1, 2, 5, 6, 7, 8, 9, 10
20	5.0	3.75	5.0	5.0	4.0	3.5	3.5	3.25	3.17	3.17	3.17	8, 9, 10
21	7.0	3.25	3.5	6.0	4.19	3.0	3.0	3.0	3.0	3.0	3.0	5, 6, 7, 8, 9, 10
22	6.0	4.25	6.0	6.0	4.38	3.5	3.5	3.5	3.5	3.5	3.5	5, 6, 7, 8, 9, 10
23	7.0	2.75	2.75	7.0	4.44	2.75	2.75	2.75	2.75	2.75	2.75	1, 2, 5, 6, 7, 8, 9, 10
24	5.0	3.75	5.0	5.0	4.13	3.63	4.13	3.25	3.17	3.17	3.17	8, 9, 10
25	8.0	3.25	3.5	6.0	4.25	3.13	3.13	3.06	2.92	2.92	2.92	8, 9, 10
26	7.0	4.25	6.0	6.0	4.38	3.63	3.63	3.56	3.25	3.25	3.25	8, 9, 10
27	8.0	2.88	3.0	7.0	4.5	2.88	2.88	2.88	2.83	2.83	2.83	8, 9, 10
28	6.0	3.88	6.0	6.0	4.38	3.63	3.63	3.38	3.33	3.33	3.33	8, 9, 10
29	8.0	3.5	4.0	7.0	4.63	3.13	3.13	3.13	3.0	3.0	3.0	8, 9, 10
30	7.0	4.5	7.0	7.0	4.88	3.63	3.63	3.63	3.29	3.29	3.29	8, 9, 10
31	8.0	2.81	2.81	8.0	4.94	2.81	2.81	2.81	2.81	2.81	2.81	1, 2, 5, 6, 7, 8, 9, 10
32	5.0	3.81	5.0	5.0	5.0	3.75	5.0	3.31	3.31	3.31	3.31	7, 8, 9, 10
33	9.0	3.5	3.5	6.0	5.03	3.25	3.5	3.13	3.13	3.06	3.06	9, 10
34	8.0	4.5	6.0	6.0	5.06	3.75	4.0	3.63	3.63	3.56	3.56	9, 10
35	9.0	3.0	3.0	7.0	5.09	3.0	3.0	2.94	2.92	2.92	2.92	8, 9, 10
30	7.0	4.0	6.0	5.0	4.88	3.75	3.75	3.44	3.33	3.33	3.33	8, 9, 10
20	9.0	3.75	4.0	7.0	5.03	3.25	3.20	3.19	3.04	3.04	3.04	8, 9, 10
20	0.0	4.75	7.0	0 0	5.19	3.75	3.15	3.09	3.30	3.30	3.30	0, 9, 10 1 0 5 6 7 9 0 10
39	9.0	2.00	2.00	6.0	0.22	2.00	2.00	2.00	2.00	2.00	2.00	7 9 0 10
40	0.0	2 75	4.0	7.0	4.00	2.75	2.25	2.00	2.00	2.00	2.00	7, 0, 5, 10 9 0 10
41	8.0	4 75	7.0	7.0	5.06	3.25	3.25	3.22	3.00	3 38	3.00	8 9 10
42	9.0	3 13	3 25	8.0	5 16	3.0	3.0	3.0	3.0	3.0	3.0	5 6 7 8 9 10
44	7 0	4 13	7 0	7 0	5.0	3 75	3 75	3.5	3 42	3 42	3 42	8 9 10
45	9.0	4 0	4.5	8.0	5 22	3 25	3 25	3 25	3 25	3 25	3 25	5 6 7 8 9 10
46	8.0	5.0	8.0	8.0	5.44	3.75	3.75	3.75	3.75	3.75	3.75	5, 6, 7, 8, 9, 10
47	9.0	2.88	2.88	9.0	5.47	2.88	2.88	2.88	2.88	2.88	2.88	1. 2. 5. 6. 7. 8. 9. 10
48	6.0	3.88	6.0	6.0	5.06	3.81	5.06	3.38	3.38	3.38	3.38	7, 8, 9, 10
49	10.0	3.75	4.0	7.0	5.13	3.31	3.56	3.25	3.08	3.08	3.08	8, 9, 10
50	9.0	4.75	7.0	7.0	5.19	3.81	4.06	3.75	3.42	3.42	3.42	8, 9, 10
51	10.0	3.13	3.25	8.0	5.25	3.06	3.06	3.03	2.96	2.96	2.96	8, 9, 10
52	8.0	4.13	7.0	7.0	5.06	3.81	3.81	3.53	3.46	3.46	3.46	8, 9, 10
53	10.0	4.0	4.5	8.0	5.25	3.31	3.31	3.28	3.13	3.13	3.13	8, 9, 10
54	9.0	5.0	8.0	8.0	5.44	3.81	3.81	3.78	3.42	3.42	3.42	8, 9, 10
55	10.0	2.94	3.0	9.0	5.5	2.94	2.94	2.94	2.92	2.92	2.92	8, 9, 10
56	7.0	3.94	7.0	7.0	5.19	3.81	4.31	3.44	3.42	3.42	3.42	8, 9, 10
57	10.0	4.0	4.5	8.0	5.31	3.31	3.31	3.28	3.28	3.19	3.19	9, 10
58	9.0	5.0	8.0	8.0	5.44	3.81	3.81	3.78	3.78	3.69	3.69	9, 10
59	10.0	3.25	3.5	9.0	5.56	3.06	3.06	3.06	3.0	3.0	3.0	8, 9, 10
60	8.0	4.25	8.0	8.0	5.44	3.81	3.81	3.56	3.46	3.46	3.46	8, 9, 10
61	10.0	4.25	5.0	9.0	5.69	3.31	3.31	3.31	3.15	3.15	3.15	8, 9, 10

62	9.0	5.25	9.0	9.0	5.94	3.81	3.81	3.81	3.48	3.48	3.48	8, 9, 10
63 64	10.0	2.91	2.91	10.0	5.97	2.91	2.91	2.91	2.91	2.91	2.91	1, 2, 5, 6, 7, 8, 9, 10 7, 8, 9, 10
65	11.0	4.0	4.0	7.0	6.02	3.38	4.0	3.28	3.17	3.17	3.17	8, 9, 10
66 67	10.0	5.0 3.25	7.0 3.25	7.0 8.0	6.03	3.88	4.5 3.25	3.78	3.48	3.48	3.48	9, 10 9, 10
68 69	9.0	4.25	7.0	7.0	5.81	3.88	4.0	3.56	3.5	3.5	3.5	8, 9, 10 7 8 9 10
70	10.0	5.25	8.0	8.0	6.09	3.88	4.0	3.81	3.81	3.81	3.62	10
71 72	11.0 8.0	3.0 4.0	3.0 7.0	9.0 7.0	6.11 5.75	3.0 3.88	3.0 4.38	2.97 3.47	2.96 3.46	2.96 3.46	2.96 3.46	8, 9, 10 9, 10
73	11.0	4.25	4.5	8.0	5.83	3.38	3.38	3.31	3.17	3.17	3.17	8, 9, 10
74 75	10.0	3.38	8.0 3.5	9.0	5.91	3.88	3.88	3.81	3.5	3.5	3.5	8, 9, 10 8, 9, 10
76 77	9.0	4.38 4.5	8.0	8.0 9.0	5.81 6.02	3.88	3.88	3.59	3.52	3.52	3.52	8, 9, 10 8, 9, 10
78	10.0	5.5	9.0	9.0	6.22	3.88	3.88	3.84	3.5	3.5	3.5	9, 10
79 80	11.0 7.0	2.94 3.94	2.94 7.0	10.0 7.0	6.23 5.81	2.94 3.88	2.94 5.13	2.94 3.44	2.94 3.44	2.94 3.44	2.94 3.44	1, 2, 5, 6, 7, 8, 9, 10 7, 8, 9, 10
81 82	11.0	4.25	4.5	8.0	5.86	3.38	3.63	3.34	3.34	3.23	3.23	9, 10
83	11.0	3.38	3.5	9.0	5.95	3.13	3.13	3.11	3.04	3.04	3.04	8, 9, 10
84 85	9.0 11.0	4.38 4.5	8.0 5.0	8.0 9.0	5.75 5.92	3.88 3.38	3.88 3.38	3.61 3.36	3.5 3.19	3.5 3.19	3.5 3.19	8, 9, 10 8, 9, 10
86	10.0	5.5	9.0	9.0	6.09	3.88	3.88	3.86	3.52	3.52	3.52	8, 9, 10
87 88	8.0	4.06	3.13 8.0	8.0	6.14 5.81	3.0	3.0 4.38	3.0	3.0	3.0	3.0	10
89 90	11.0	4.5	5.0	9.0	5.92	3.38	3.38	3.36	3.21	3.21	3.21	8, 9, 10
91	11.0	3.5	3.75	10.0	6.14	3.13	3.13	3.13	3.13	3.13	3.13	5, 6, 7, 8, 9, 10
92 93	9.0 11.0	4.5 4.75	9.0 5.5	9.0 10.0	6.0 6.23	3.88	3.88	3.63	3.54 3.38	3.54 3.38	3.54	8, 9, 10 5, 6, 7, 8, 9, 10
94	10.0	5.75	10.0	10.0	6.47	3.88	3.88	3.88	3.88	3.88	3.88	5, 6, 7, 8, 9, 10
95 96	11.0 7.0	2.94 3.94	2.94 7.0	11.0 7.0	6.48 6.03	2.94 3.91	2.94 6.03	2.94 3.44	2.94 3.44	2.94 3.44	2.94 3.44	1, 2, 5, 6, 7, 8, 9, 10 7, 8, 9, 10
97 98	12.0	4.25	4.5	8.0	6.06	3.41	4.03	3.34	3.19	3.19	3.19	8, 9, 10
99	12.0	3.38	3.5	9.0	6.13	3.16	3.28	3.13	3.04	3.04	3.04	8, 9, 10
100 101	10.0 12.0	4.38 4.5	8.0 5.0	8.0 9.0	5.91 6.06	3.91 3.41	4.03	3.63	3.54 3.21	3.54 3.21	3.54 3.21	8, 9, 10 8, 9, 10
102	11.0	5.5	9.0	9.0	6.22	3.91	4.03	3.88	3.52	3.52	3.52	8, 9, 10
103 104	12.0 9.0	3.06 4.06	3.13 8.0	10.0 8.0	6.25 5.91	3.03 3.91	3.03 4.41	3.02 3.52	2.98 3.48	2.98 3.48	2.98 3.48	8, 9, 10 8, 9, 10
105	12.0	4.5	5.0	9.0	6.0	3.41	3.41	3.38	3.37	3.27	3.27	9, 10
108	12.0	3.5	9.0 3.75	10.0	6.19	3.16	3.16	3.00	3.06	3.06	3.06	9, 10 8, 9, 10
108 109	10.0	4.5 4.75	9.0	9.0	6.03	3.91 3.41	3.91 3.41	3.64	3.52	3.52	3.52	8, 9, 10 8, 9, 10
110	11.0	5.75	10.0	10.0	6.47	3.91	3.91	3.91	3.54	3.54	3.54	8, 9, 10
111 112	12.0 8.0	2.97 3.97	3.0 8.0	11.0 8.0	6.5 6.09	2.97 3.91	2.97 5.16	2.97 3.47	2.96 3.46	2.96 3.46	2.96 3.46	8, 9, 10 8, 9, 10
113	12.0	4.5	5.0	9.0	6.16	3.41	3.66	3.38	3.23	3.23	3.23	8, 9, 10
114 115	11.0	3.5	9.0 3.75	9.0 10.0	6.22	3.91	4.16	3.88	3.54	3.54	3.54	8, 9, 10 9, 10
116 117	10.0 12.0	4.5 4.75	9.0 5.5	9.0 10.0	6.09 6.28	3.91 3.41	3.91 3.41	3.64 3.39	3.56	3.56	3.56 3.39	8, 9, 10 7, 8, 9, 10
118	11.0	5.75	10.0	10.0	6.47	3.91	3.91	3.89	3.89	3.89	3.89	7, 8, 9, 10
119 120	12.0 9.0	3.13 4.13	3.25 9.0	11.0 9.0	6.53 6.22	3.03 3.91	3.03 4.41	3.03 3.53	3.0 3.5	3.0 3.5	3.0 3.5	8, 9, 10 8, 9, 10
121	12.0	4.75	5.5	10.0	6.34	3.41	3.41	3.39	3.23	3.23	3.23	8, 9, 10
122	12.0	3.63	4.0	11.0	6.59	3.16	3.16	3.16	3.07	3.07	3.07	8, 9, 10
124 125	10.0 12.0	4.63 5.0	10.0 6.0	10.0 11.0	6.47 6.72	3.91 3.41	3.91 3.41	3.66 3.41	3.57 3.24	3.57 3.24	3.57 3.24	8, 9, 10 8, 9, 10
126	11.0	6.0	11.0	11.0	6.97	3.91	3.91	3.91	3.57	3.57	3.57	8, 9, 10
127 128	12.0 7.0	2.95	2.95	12.0 7.0	6.98 7.0	2.95 3.94	2.95	2.95	2.95 3.45	2.95	2.95	1, 2, 5, 6, 7, 8, 9, 10 7, 8, 9, 10
129	13.0	4.5	4.5	8.0	7.01	3.44	4.5	3.38	3.38	3.27	3.27	9, 10
131	13.0	3.5	3.5	9.0	7.02	3.19	3.5	3.14	3.08	3.08	3.08	8, 9, 10
132 133	11.0 13.0	4.5 4.75	8.0 5.0	8.0 9.0	6.78 6.91	3.94 3.44	4.25 3.75	3.64 3.39	3.56 3.24	3.54 3.24	3.54 3.24	9, 10 8, 9, 10
134	12.0	5.75	9.0	9.0	7.05	3.94	4.25	3.89	3.57	3.57	3.57	8, 9, 10
135	10.0	4.13	8.0	8.0	6.69	3.94	4.5	3.53	3.53	3.52	3.52	9, 10
137	13.0	4.75	5.0	9.0	6.76	3.44	3.5	3.39	3.25	3.25	3.25	8, 9, 10 8, 9, 10
139	13.0	3.63	3.75	10.0	6.9	3.19	3.25	3.16	3.16	3.16	3.16	7, 8, 9, 10
140 141	11.0 13.0	4.63 5.0	9.0 5.5	9.0 10.0	6.72 6.91	3.94 3.44	4.0 3.5	3.66 3.41	3.58 3.41	3.58 3.41	3.58 3.31	8, 9, 10 10
142	12.0	6.0	10.0	10.0	7.11	3.94	4.0	3.91	3.91	3.91	3.81	10
143 144	13.0 9.0	3.0 4.0	3.0 8.0	11.0 8.0	7.12 6.69	3.0 3.94	3.0 5.19	2.98	2.98 3.48	2.98 3.48	2.98 3.48	8, 9, 10 8, 9, 10
145 146	13.0	4.75	5.0	9.0	6.73	3.44	3.69 4 10	3.39	3.23	3.23	3.23	8, 9, 10 8 9 10
147	13.0	3.63	3.75	10.0	6.8	3.19	3.19	3.16	3.08	3.08	3.08	8, 9, 10
148 149	11.0 13.0	4.63 5.0	9.0 5.5	9.0 10.0	6.59 6.76	3.94 3.44	3.94 3.44	3.66 3.41	3.58 3.25	3.58 3.25	3.58 3.25	8, 9, 10 8, 9, 10
150	12.0	6.0	10.0	10.0	6.92	3.94	3.94	3.91	3.56	3.56	3.56	8, 9, 10 8 9 10
152	10.0	4.19	9.0	9.0	6.63	3.94	4.44	3.55	3.51	3.51	3.51	8, 9, 10
153 154	13.0 12.0	5.0 6.0	5.5 10.0	10.0 10.0	6.73 6.83	3.44 3.94	3.44 3.94	3.41 3.91	3.41 3.91	3.3 3.8	3.3 3.8	9, 10 9, 10
155	13.0	3.75	4.0	11.0	6.93	3.19	3.19	3.17	3.09	3.09	3.09	8, 9, 10
156 157	11.0 13.0	4.75 5.25	10.0 6.0	10.0 11.0	6.78 7.01	3.94 3.44	3.94 3.44	3.67 3.42	3.56 3.25	3.54 3.25	3.54 3.25	9, 10 8, 9, 10
158	12.0	6.25	11.0	11.0	7.23	3.94	3.94	3.92	3.58	3.58	3.58	8, 9, 10
160	8.0	2.97	2.97	8.0	6.78	2.97	6.06	3.47	3.47	3.47	3.47	7, 8, 9, 10

161	13.0	4.75	5.0	9.0	6.8	3.44	4.06	3.41	3.26	3.26	3.26	8, 9, 10
100	10.0	E 75	0.0	0.0	6.02	2.04	4 50	2.01	2 50	2 50	2 50	0, 0, 10
102	12.0	5.75	9.0	9.0	0.00	5.94	4.50	3.91	3.50	3.50	3.50	8, 9, 10
163	13.0	3.63	3.75	10.0	6.85	3.19	3.31	3.17	3.17	3.12	3.12	9, 10
164	11.0	4 63	9.0	9.0	6 63	3 9/	4 06	3 67	3.6	3.6	3.6	8 9 10
104	11.0	4.03	5.0	5.0	0.03	3.94	4.00	3.07	3.0	3.0	3.0	8, 9, 10
165	13.0	5.0	5.5	10.0	6.77	3.44	3.56	3.42	3.42	3.42	3.42	7, 8, 9, 10
166	12 0	6.0	10 0	10 0	6 92	3 94	4 06	3 92	3 92	3 92	3 92	7 8 9 10
100	10.0	0.0	2010	10.0	0.02	0.01	1.00	0.02	0.02	0.02	0.02	1, 0, 0, 10
167	13.0	3.19	3.25	11.0	6.95	3.06	3.06	3.05	3.02	3.02	3.02	8, 9, 10
168	10.0	4.19	9.0	9.0	6.59	3.94	4.44	3.55	3.52	3.52	3.52	8, 9, 10
100	12.0	F 0		10.0	C CO	2 44	2 44	2 42	2 05	2 05	2 05	8 0 10
109	13.0	5.0	5.5	10.0	0.00	5.44	5.44	3.43	3.20	3.25	3.25	8, 9, 10
170	12.0	6.0	10.0	10.0	6.77	3.94	3.94	3.93	3.58	3.58	3.58	8, 9, 10
171	13.0	3 75	4 0	11 0	6 85	3 10	3 10	3 18	3 09	3 09	3 09	8 9 10
111	10.0	5.75	4.0	11.0	0.00	0.15	5.15	0.10	0.00	0.05	5.05	0, 0, 10
172	11.0	4.75	10.0	10.0	6.69	3.94	3.94	3.68	3.59	3.59	3.59	8, 9, 10
173	13.0	5 25	6.0	11 0	6 9	3 44	3 44	3 45	3 26	3 26	3 26	8 9 10
115	10.0	0.20	0.0	11.0	0.5	5.11	0.11	0.40	0.20	0.20	0.20	0, 0, 10
174	12.0	6.25	11.0	11.0	7.11	3.94	3.94	3.95	3.6	3.6	3.6	8, 9, 10
175	13.0	3.03	3.06	12.0	7.13	3.0	3.0	3.0	3.0	3.0	3.0	5. 6. 7. 8. 9. 10
470		4.00	0.0		0.70	0.04	5 40					7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7, 7
1/6	9.0	4.05	9.0	9.0	0.72	5.94	5.19	3.5	3.5	3.5	3.5	7, 8, 9, 10
177	13.0	5.0	5.5	10.0	6.77	3.44	3.69	3.42	3.42	3.3	3.3	9, 10
178	12 0	6.0	10.0	10.0	6 83	3 9/	1 10	3 92	3 02	3.8	38	9 10
110	12.0	0.0	1010	10.0	0.00	0.01	1110	0.02	0.02	0.0	0.0	5, 20
179	13.0	3.75	4.0	11.0	6.88	3.19	3.19	3.18	3.1	3.1	3.1	8, 9, 10
180	11.0	4.75	10.0	10.0	6.69	3.94	3.94	3.68	3.58	3.58	3.58	8, 9, 10
101	12.0	F 0F	6.0	11.0	C 07	2 44	2 44	2 42	2.00	2.00	2.00	8 0 10
101	13.0	5.25	0.0	11.0	0.0/	5.44	5.44	3.43	3.20	3.20	3.20	8, 9, 10
182	12.0	6.25	11.0	11.0	7.05	3.94	3.94	3.93	3.59	3.59	3.59	8, 9, 10
183	13.0	3 25	3 38	12 0	7 1	3 06	3 06	3 06	3 06	3 06	3 06	5 6 7 8 9 10
100	10.0	0.20	5.50	12.0	1.1	0.00	5.00	0.00	5.00	5.00	5.00	5, 5, 7, 5, 5, 10
184	10.0	4.25	10.0	10.0	6.78	3.94	4.44	3.56	3.56	3.56	3.56	7, 8, 9, 10
185	13.0	5.25	6.0	11.0	6.9	3.44	3.44	3.43	3.27	3.27	3.27	8, 9, 10
100	40.0	0.05			7 00	0.04	0.04	0.00	0.50	0.50	0.50	-, -,
186	12.0	6.25	11.0	11.0	7.02	3.94	3.94	3.93	3.59	3.59	3.59	8, 9, 10
187	13.0	3.88	4.25	12.0	7.13	3.19	3.19	3.19	3.19	3.19	3.19	5, 6, 7, 8, 9, 10
182	11.0	1 00	11 0	11 0	7 0	3 04	3 04	3 60	3 6	36	36	8 9 10
100	11.0	4.00	11.0	11.0	1.0	3.94	3.94	3.09	3.0	3.0	3.0	8, 9, 10
189	13.0	5.5	6.5	12.0	7.24	3.44	3.44	3.44	3.44	3.44	3.44	ь, 6, 7, 8, 9, 10
190	12 0	6.5	12 0	12 0	7.48	3.94	3.94	3.94	3.94	3.94	3.72	10
101	12.0	0.07	0.07	10.0	7 40	0.07	0.07	0.07	0.07	0.07	0.07	1 0 5 6 7 0 0 1
191	13.0	2.97	2.97	13.0	7.49	2.97	2.97	2.97	2.97	2.97	2.97	1, 2, 5, 6, 7, 8, 9, 10
192	8.0	3.97	8.0	8.0	7.02	3.95	7.02	3.47	3.47	3.47	3.47	7.8.9.10
102	14.0	4 75	E 0	0.0	7 02	2 45	4 50	2 / 1	2 05	2 05	2 05	8 0 10
192	14.0	4.75	5.0	9.0	7.05	3.45	4.52	3.41	3.20	3.25	3.25	8, 9, 10
194	13.0	5.75	9.0	9.0	7.05	3.95	5.02	3.91	3.58	3.58	3.58	8, 9, 10
105	14.0	3 63	3 75	10.0	7 06	3.2	3 52	3 17	3 09	3 09	3 09	8 9 10
155	14.0	5.00	5.10	10.0	7.00	0.2	0.02	0.17	5.05	5.05	5.05	0, 0, 10
196	12.0	4.63	9.0	9.0	6.83	3.95	4.27	3.67	3.59	3.59	3.59	8, 9, 10
197	14.0	5.0	5.5	10.0	6.97	3.45	3.77	3.42	3.26	3.26	3.26	8, 9, 10
109	12.0	6 0	10.0	10.0	7 11	2 05	4 97	2 0 2	2 50	2 50	2 50	9 0 10
190	13.0	0.0	10.0	10.0	1.11	3.90	4.21	3.92	3.00	3.00	3.00	8, 9, 10
199	14.0	3.19	3.25	11.0	7.13	3.08	3.14	3.06	3.02	3.02	3.02	8, 9, 10
200	11.0	4.19	9.0	9.0	6.77	3.95	4.52	3.56	3.52	3.52	3.52	8, 9, 10
001	14.0	F 0		10.0	6.04	2.45	2 50	2.40	2 40	2.21	2 21	0, 10
201	14.0	5.0	5.5	10.0	0.04	3.45	3.52	3.42	3.42	3.31	3.31	9, 10
202	13.0	6.0	10.0	10.0	6.92	3.95	4.02	3.92	3.92	3.81	3.81	9, 10
203	14 0	3 75	4 0	11 0	7 0	3 2	3 27	3 19	3.1	3 1	3 1	8 9 10
200	10.0	4.75	100	10.0	0.00	0.2	4.00	0.10	0.1	0.1	0.1	0, 0, 10
204	12.0	4.75	10.0	10.0	6.83	3.95	4.02	3.69	3.58	3.58	3.58	8, 9, 10
205	14.0	5.25	6.0	11.0	7.03	3.45	3.52	3.44	3.26	3.26	3.26	8, 9, 10
206	12.0	6 25	11 0	11 0	7 02	2 05	4 02	2 0/	2 50	2 50	2 50	9 0 10
200	13.0	0.20	11.0	11.0	1.23	3.90	4.02	3.94	3.05	3.09	3.05	8, 9, 10
207	14.0	3.03	3.06	12.0	7.25	3.02	3.02	3.01	2.99	2.99	2.99	8, 9, 10
208	10 0	4 03	9.0	9.0	6 83	3 95	5 2	3 51	3 49	3 49	3 49	8 9 10
		5.0		40.0	0.00	0.45	0.7	0.40	0.07	0.07	0.07	-, -,
209	14.0	5.0	5.5	10.0	6.88	3.45	3.7	3.42	3.27	3.27	3.27	8, 9, 10
210	13.0	6.0	10.0	10.0	6.92	3.95	4.2	3.92	3.59	3.59	3.59	8, 9, 10
211	14 0	3 75	4 0	11 0	6 97	3 2	3 2	3 10	3 10	3 13	3 13	9 10
	1110			11.0	0.01	0.2	0.2	0.10	0.10	0.10	0.10	5, 20
212	12.0	4.75	10.0	10.0	6.77	3.95	3.95	3.69	3.6	3.6	3.6	8, 9, 10
213	14.0	5.25	6.0	11.0	6.94	3.45	3.45	3.44	3.44	3.44	3.44	7.8.9.10
214	12 0	6 25	11.0	11 0	7 11	2 05	2 05	2 0/	2 0/	2 0/	2 0/	7 9 0 10
214	13.0	0.20	11.0	11.0	1.11	3.90	3.90	3.94	3.94	3.94	3.94	7, 8, 9, 10
215	14.0	3.25	3.38	12.0	7.16	3.08	3.08	3.07	3.03	3.03	3.03	8, 9, 10
216	11 0	4 25	10 0	10 0	6 83	3 95	4 45	3 57	3 53	3 53	3 53	8 9 10
210		1.20	1010	10.0	0.00	0.00	1.10	0.01	0.00	0.00	0.00	0, 0, 10
217	14.0	5.25	6.0	11.0	6.94	3.45	3.45	3.44	3.26	3.26	3.26	8, 9, 10
218	13.0	6.25	11.0	11.0	7.05	3.95	3.95	3.94	3.59	3.59	3.59	8, 9, 10
210	14 0	2 00	4 95	12.0	7 16	2 0	2.0	2.0	2 1	2 1	2 1	9 0 10
219	14.0	3.00	4.20	12.0	1.10	3.2	3.2	3.2	3.1	3.1	3.1	8, 9, 10
220	12.0	4.88	11.0	11.0	7.02	3.95	3.95	3.7	3.6	3.6	3.6	8, 9, 10
221	14 0	5 5	6 5	12 0	7 25	3 45	3 45	3 45	3 27	3 27	3 27	8 9 10
000	12.0	6.5	10.0	10.0	7 40	2.10	2.10	2.10	2.21	2.21	2.21	., -,
222	13.0	0.5	12.0	12.0	1.48	3.95	3.95	3.95	3.0	3.0	3.0	0, 9, 10
223	14.0	2.98	3.0	13.0	7.5	2.98	2.98	2.98	2.98	2.98	2.98	8, 9, 10
224	9.0	3 98	9.0	9.0	7 05	3 95	6 08	3 48	3 48	3 48	3 48	8 9 10
444	3.0	0.90	5.0	5.0	1.00	0.00	0.00	0.40	0.40	0.40	0.40	
225	14.0	5.0	5.5	10.0	7.08	3.45	4.08	3.43	3.43	3.31	3.31	э, 10
226	13.0	6.0	10.0	10.0	7,11	3,95	4,58	3,93	3,93	3,81	3,81	9, 10
007	44.0	0.75	4.0	44.0		0.0	0.00	0.40				-,
221	14.0	3.15	4.0	11.0	1.14	3.2	3.33	3.19	3.11	3.11	3.11	0, 5, 10
228	12.0	4.75	10.0	10.0	6.92	3.95	4.08	3.69	3.59	3.59	3.59	8, 9, 10
229	14 0	5 25	6.0	11 0	7 08	3 45	3 58	3 44	3 27	3 27	3 27	8 9 10
220	11.0	0.20	0.0	11.0	7.00	0.40	0.00	0.11	0.21	0.21	0.21	0, 0, 10
230	13.0	6.25	11.0	11.0	7.23	3.95	4.08	3.94	3.6	3.6	3.6	8, 9, 10
231	14.0	3.25	3.38	12.0	7.27	3.08	3.08	3.07	3.07	3.05	3.05	9, 10
232	11 0	4 25	10 0	10.0	6 92	3 95	4 45	3 57	3 57	3 55	3 55	9 10
202	11.0	4.20	10.0	10.0	0.92	0.90	-1.40	5.57	0.01	0.00	0.00	·, ··
233	14.0	5.25	6.0	11.0	7.02	3.45	3.45	3.45	3.28	3.28	3.28	8, 9, 10
234	13.0	6,25	11.0	11.0	7,11	3,95	3,95	3,95	3.6	3.6	3.6	8, 9, 10
005	14.0	2.00	4.05	10.0	7.0	2.00	2.00	2.00	2.0	2.0	2.0	7 9 9 10
235	14.0	3.88	4.25	12.0	1.2	3.2	3.2	3.2	3.2	3.2	3.2	1, 8, 9, 10
236	12.0	4.88	11.0	11.0	7.05	3.95	3.95	3.7	3.61	3.61	3.61	8, 9, 10
237	14 0	5.5	6 5	12 0	7 97	3 45	3 45	3 46	3 46	3 45	3 45	5 6 9 10
201	14.0	0.0	0.0	12.0	1.21	3.40	0.40	0.40	3.40	0.40	3.40	5, 0, 5, 10
238	13.0	6.5	12.0	12.0	7.48	3.95	3.95	3.96	3.96	3.95	3.95	5, 6, 9, 10
239	14.0	3,06	3,13	13.0	7,52	3,02	3,02	3,02	3.0	3.0	3.0	8, 9, 10
040	10.0	4 00	10.10	10.0	7	0.02	E 0	0.02	2.0	2.0	2.0	-, -, -,
240	10.0	4.06	10.0	10.0	7.11	3.95	ь.2	3.52	3.5	3.5	3.5	δ, 9, 10
241	14.0	5.25	6.0	11.0	7.17	3.45	3.7	3.44	3.28	3.28	3.28	8, 9, 10
240	13.0	6 05	11 0	11 0	7 02	3 05	4.9	3 0/	3 61	3 61	3 61	8 9 10
242	10.0	0.20	11.0	11.0	1.23	3.90	4.2	3.94	3.01	3.01	3.01	0, 9, 10
243	14.0	3.88	4.25	12.0	7.3	3.2	3.2	3.2	3.11	3.11	3.11	8, 9, 10
244	12.0	4,88	11.0	11.0	7,11	3,95	3,95	3.7	3,61	3,61	3,61	8, 9, 10
045	14.0	F F	6 5	10.0	7 2	2.45	2.45	2.45	2.00	2.00	2.00	-, -, -0
240	14.0	0.5	0.5	12.0	1.3	3.45	3.45	3.45	3.28	3.28	3.28	0, 9, 10
246	13.0	6.5	12.0	12.0	7.48	3.95	3.95	3.95	3.61	3.61	3.61	8, 9, 10
247	14.0	3,31	3.5	13.0	7,55	3.08	3,08	3,08	3.04	3,04	3,04	8, 9, 10
249	11 0	4 24	11 0	11 0	7 00	2.00	1 45	2 50	2 54	2 54	2 54	8 0 10
248	11.0	4.31	11.0	11.0	7.23	3.95	4.45	3.58	3.54	3.54	3.54	δ, 9, 10
249	14.0	5.5	6.5	12.0	7.36	3.45	3.45	3.45	3.45	3.33	3.33	9, 10
250	13 0	6.5	12 0	12 0	7.48	3,95	3,95	3,95	3,95	3,83	3.74	10
200	10.0	0.0				0.00	0.00	0.00	0.00	0.00	0	

## A.2 Two Dimensional Problems

In this section we present the results of our algorithms for two-dimensional ROFDPs with squares windows.

- *D* = 2
- $\mathcal{W} = \texttt{tile}(\texttt{hyperbar}((\texttt{W},\texttt{W})), \mathbf{0}_D, \mathbf{1}_D)$

The following subsections consider various choices for l and u.

#### A.2.1 Window Sorting

This section considers the problem of sorting the entire window. Hence l = 0 and  $u = \mathbb{W} \times \mathbb{W}$ .

W	0)	1)	2)	3)	4)	5)	6)	7)	8)	9)	10)	Bes	st s	stra	ateg	gies	5					
1	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	Ο,	1,	2,	з,	4,	5,	6,	7,	8,	9,	10
2	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	8.00	Ο,	1,	2,	з,	4,	5,	6,	7,	8,	9,	10
3	42.00	35.00	35.00	42.00	35.00	35.00	35.00	35.00	35.00	35.00	35.00	1,	2,	4,	5,	6,	7,	8,	9,	10		
4	76.00	104.00	76.00	76.00	76.00	76.00	76.00	76.00	76.00	76.00	76.00	Ο,	2,	З,	4,	5,	6,	7,	8,	9,	10	
5	192.00	152.00	152.00	204.00	165.00	152.00	152.00	152.00	152.00	152.00	152.00	1,	2,	5,	6,	7,	8,	9,	10			
6	270.00	342.00	306.00	306.00	258.00	258.00	258.00	255.25	254.50	254.50	254.50	8,	9,	10								
7	500.00	379.00	379.00	500.00	391.00	379.00	379.00	379.00	379.00	379.00	379.00	1,	2,	5,	6,	7,	8,	9,	10			
8	528.00	777.50	528.00	528.00	528.00	579.00	528.00	528.00	526.67	526.67	526.67	8,	9,	10								
9	1048.00	744.00	711.00	1020.00	808.00	711.00	711.00	711.00	711.00	711.00	711.00	2,	5,	6,	7,	8,	9,	10				
10	1062.00	1476.50	1294.00	1294.00	1032.75	976.00	976.00	944.63	944.83	940.71	940.71	9,	10									
11	1648.00	1182.00	1182.00	1720.00	1308.50	1182.00	1182.00	1176.75	1176.75	1169.13	1169.13	9,	10									
12	1580.00	2285.00	1852.00	1852.00	1429.00	1632.00	1429.00	1460.28	1438.56	1379.83	1379.83	9,	10									
13	2694.00	1861.00	1951.00	2492.00	1889.00	1796.00	1796.00	1752.13	1734.75	1688.85	1688.85	9,	10									
14	2544.00	3566.50	3486.00	2952.00	2305.00	2265.00	2265.00	2106.66	2099.21	2017.88	2017.88	9,	10									
15	3646.00	2618.75	2529.50	3646.00	2716.50	2529.50	2529.50	2422.31	2386.64	2345.21	2339.65	10										
16	3092.00	4914.25	3092.00	3092.00	3092.00	3337.00	3092.00	2866.41	2831.44	2627.45	2627.45	9,	10									
17	5336.00	3738.00	3394.00	5064.00	3910.75	3544.00	3394.00	3231.00	3185.26	3047.08	3047.08	9,	10									
18	4920.00	7015.00	5822.00	5822.00	4504.63	4268.00	4106.00	3768.94	3515.65	3513.47	3513.47	9,	10									
19	6784.00	4813.50	4401.00	6812.00	5129.25	4401.00	4401.00	4147.88	4102.56	3947.67	3947.67	9,	10									

#### A.2.2 Median Filtering

This section considers the problem of selecting the median of a window. Hence  $l=u=\lfloor\frac{\mathbb{W}\times\mathbb{W}}{2}\rfloor.$ 

W	0)	1)	2)	3)	4)	5)	6)	7)	8)	9)	10)	Bes	st	stra	ate	gies	3					
1	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	Ο,	1,	2,	з,	4,	5,	6,	7,	8,	9,	10
2	5.00	5.00	5.00	5.00	5.00	5.00	5.00	5.00	5.00	5.00	5.00	Ο,	1,	2,	з,	4,	5,	6,	7,	8,	9,	10
3	22.00	16.00	16.00	22.00	16.00	16.00	16.00	16.00	16.00	16.00	16.00	1,	2,	4,	5,	6,	7,	8,	9,	10		
4	41.00	51.00	41.00	41.00	41.00	41.00	41.00	32.50	32.50	32.50	32.50	7,	8,	9,	10							
5	106.00	53.00	53.00	88.00	72.50	53.00	53.00	53.00	53.00	53.00	53.00	1,	2,	5,	6,	7,	8,	9,	10			
6	151.00	120.50	145.00	145.00	108.50	108.50	108.50	76.50	75.75	75.75	75.75	8,	9,	10								
7	290.00	113.50	113.50	290.00	188.50	113.50	113.50	105.75	105.75	105.75	105.75	7,	8,	9,	10							
8	269.00	260.00	269.00	269.00	269.00	255.00	269.00	141.63	141.29	141.29	141.29	8,	9,	10								
9	644.00	203.50	214.00	394.00	380.75	214.00	214.00	171.00	171.00	171.00	171.00	7,	8,	9,	10							
10	587.00	464.00	533.00	533.00	451.50	334.50	334.50	209.63	209.21	209.21	209.21	8,	9,	10								
11	990.00	270.50	270.50	826.00	553.25	270.50	270.50	232.75	232.75	232.75	232.75	7,	8,	9,	10							
12	825.00	601.50	839.00	839.00	550.25	513.25	550.25	279.84	281.96	281.96	281.96	7										
13	1682.00	445.50	573.00	1344.00	844.50	452.50	452.50	320.69	321.25	321.25	321.25	7										
14	1425.00	988.00	1395.00	1683.00	1098.25	651.25	651.25	362.94	370.79	370.79	370.79	7										
15	2242.00	577.75	492.75	2242.00	1342.25	492.75	492.75	404.38	404.38	404.38	404.38	7,	8,	9,	10							
16	1553.00	1323.75	1553.00	1553.00	1553.00	997.00	1553.00	454.28	461.49	461.49	461.49	7										
17	3422.00	908.00	967.00	1868.00	1932.63	914.50	967.00	499.94	507.23	507.23	507.23	7										
18	2837.00	2025.50	2197.00	2197.00	2128.00	1208.00	1236.50	549.91	558.04	558.04	558.04	7										
19	4278.00	1068.50	825.50	2824.00	2337.13	825.50	825.50	576.72	576.72	576.72	576.72	7,	8,	9,	10							
20	2943.00	2366.00	2883.00	2883.00	2242.25	1285.25	1355.25	642.53	645.32	645.32	645.32	7										

#### A.2.3 Minimum Filtering

This section considers the problem of selecting the minimum of a window. Hence l = u = 0.

W	0)	1)	2)	3)	4)	5)	6)	7)	8)	9)	10)	Best	t s	tra	teg	ies	3					
1	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0, 3	1,	2,	з,	4,	5,	6,	7,	8,	9,	10
2	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	0, 3	1,	2,	з,	4,	5,	6,	7,	8,	9,	10
3	4.00	3.00	3.00	4.00	3.00	3.00	3.00	3.00	3.00	3.00	3.00	1, 3	2,	1,	5,	6,	7,	8,	9,	10		
4	4.00	5.00	4.00	4.00	4.00	4.00	4.00	4.00	4.00	4.00	4.00	0, 3	2,	З,	4,	5,	6,	7,	8,	9,	10	
5	6.00	4.00	4.00	6.00	4.50	4.00	4.00	4.00	4.00	4.00	4.00	1, 3	2,	5,	6,	7,	8,	9,	10			
6	6.00	6.00	6.00	6.00	5.00	5.00	5.00	5.00	4.83	4.83	4.83	8, 9	Э,	10								
7	8.00	4.50	4.50	8.00	5.50	4.50	4.50	4.50	4.50	4.50	4.50	1, 1	2,	5,	6,	7,	8,	9,	10			
8	6.00	6.75	6.00	6.00	6.00	6.00	6.00	5.50	5.42	5.42	5.42	8, 9	Э,	10								
9	10.00	5.00	5.00	8.00	6.25	5.00	5.00	5.00	5.00	5.00	5.00	1, 2	2,	5,	6,	7,	8,	9,	10			

10	8.00	7.50	8.00	8.00	6.50	6.00	6.00	6.00	6.00	6.00	6.00	5,	6,	7,	8,	9,	10		
11	10.00	5.00	5.00	10.00	6.75	5.00	5.00	5.00	5.00	5.00	5.00	1,	2,	5,	6,	7,	8,	9,	10
12	8.00	7.50	8.00	8.00	6.50	6.50	6.50	6.00	5.83	5.83	5.83	8,	9,	10					
13	12.00	5.50	6.00	10.00	7.00	5.50	5.50	5.50	5.33	5.33	5.33	8,	9,	10					
14	10.00	8.25	10.00	10.00	7.50	6.50	6.50	6.50	6.17	6.17	6.17	8,	9,	10					
15	12.00	5.38	5.25	12.00	7.75	5.25	5.25	5.25	5.25	5.25	5.25	2,	5,	6,	7,	8,	9,	10	
16	8.00	8.13	8.00	8.00	8.00	7.00	8.00	6.25	6.25	6.25	6.25	7,	8,	9,	10				
17	14.00	6.00	6.00	10.00	8.13	6.00	6.00	5.75	5.67	5.67	5.67	8,	9,	10					
18	12.00	9.00	10.00	10.00	8.25	7.00	7.00	6.75	6.42	6.42	6.42	8,	9,	10					
19	14.00	5.75	5.50	12.00	8.38	5.50	5.50	5.50	5.50	5.50	5.50	2,	5,	6,	7,	8,	9,	10	
20	10.00	8.75	10.00	10.00	8.00	7.00	7.00	6.50	6.42	6.42	6.42	8,	9,	10					

## Appendix B

# Sample solutions

In this appendix we present the details of some of the smaller ROF we found.

#### **B.1** Representation of the ROFs

The ROFs in the rest of this appendix are presented in a table with a specific format.

The first two rows of such a table describe the windows and the desired interval of ranks from those windows that have to be calculated by the filter algorithm. The filter itself is described by the generator graph. The next two rows give the meta-period of this graph and the number of extrema operations per window.

The remaining rows of the table are used to describe the generator graph itself. Each row describes a single node of the graph. The first column contains the triple associated with the node. The next two columns contain the nodes that have edges leading towards the node in question. The final column contains the contribution of this node to the final cost of the entire filter.

### **B.2** One Dimensional Problems

This section contains some solutions for one dimensional problems.

#### B.2.1 Window Sorting

Window:	(■■■,0,1)		
Desired Interval:	[02]		
Meta-period:	2		
Total Cost:	5.00		
$V_g$	Incoming edges Cost		
(■,0,2)			0.00
(■, 1, 2)			0.00
(■■, 1, 2)	(■, 1, 2)	(■,0,2)	1.00
(■■■,0,2)	(■■, 1, 2)	(■,0,2)	2.00
(■■■,1,2)	$(\blacksquare \blacksquare, 1, 2)$	$(\blacksquare, 1, 2)$	2.00

The first problem is that of sorting the entire window.

#### APPENDIX B. SAMPLE SOLUTIONS

Window:	(∎∎∎∎,0,1	1)		
Desired Interval:	[03]			
Meta-period:	1			
Total Cost:	8.00			
$V_g$	Incoming edges Cost			
(■,0,1)			0.00	
(■■,0,1)	(■,0,1)	(■,0,1)	2.00	
(■■■■,0,1)	$(\blacksquare \blacksquare, 0, 1)$	(∎∎,0,1)	6.00	

Window:	(■■■■■,0,1)		
Desired Interval:	[04]		
Meta-period:	2		
Total Cost:	12.00		
$V_g$	Incoming	edges	Cost
$(\blacksquare, 0, 2)$			0.00
$(\blacksquare, 1, 2)$			0.00
$(\blacksquare \blacksquare, 1, 2)$	(■, 1, 2)	(■, 0, 2)	1.00
(∎∎∎∎, 1, 2)	(■■,1,2)	(∎∎, 1, 2)	3.00
(■■■■■, 0, 2)	(■■■■, 1, 2)	(■, 0, 2)	4.00
(■■■■■, 1, 2)	(∎∎∎∎, 1, 2)	$(\blacksquare, 1, 2)$	4.00

Window:	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,0,1)$		
Desired Interval:	[05]		
Meta-period:	3		
Total Cost:	16.00		
$V_g$	Incoming	edges	Cost
(■, 0, 3)			0.00
$(\blacksquare, 1, 3)$			0.00
(■, 2, 3)			0.00
(■■, 0, 3)	$(\blacksquare, 0, 3)$	$(\blacksquare, 1, 3)$	0.67
$(\blacksquare \Box \Box \Box \Box \Box \blacksquare, 1, 3)$	$(\blacksquare, 1, 3)$	$(\blacksquare, 0, 3)$	0.67
$(\blacksquare \Box \Box \blacksquare, 2, 3)$	$(\blacksquare, 2, 3)$	$(\blacksquare, 2, 3)$	0.67
(∎∎∎∎, 2, 3)	$(\blacksquare\Box\Box\blacksquare,2,3)$	(∎∎, 0, 3)	2.00
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,0,3)$	$(\blacksquare\blacksquare\blacksquare\blacksquare,2,3)$	(∎∎, 0, 3)	4.00
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,1,3)$	$(\blacksquare \Box \Box \Box \Box \Box \blacksquare, 1, 3)$	$(\blacksquare\blacksquare\blacksquare\blacksquare,2,3)$	4.00
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,2,3)$	$(\blacksquare\blacksquare\blacksquare\blacksquare, 2, 3)$	(■■, 0, 3)	4.00

Window:	(■■■■■■■,0,1)			
Desired Interval:	[06]			
Meta-period:	4			
Total Cost:	20.50			
$V_g$	Incoming e	edges	Cost	
$(\blacksquare, 0, 4)$			0.00	
$(\blacksquare, 1, 4)$			0.00	
(■, 2, 4)			0.00	
$(\blacksquare, 3, 4)$			0.00	
$(\blacksquare \blacksquare, 1, 4)$	$(\blacksquare, 1, 4)$	$(\blacksquare, 2, 4)$	0.50	
$(\blacksquare \blacksquare, 3, 4)$	$(\blacksquare, 3, 4)$	$(\blacksquare, 0, 4)$	0.50	
$(\blacksquare \blacksquare \blacksquare \blacksquare, 3, 4)$	$(\blacksquare \blacksquare, 1, 4)$	$(\blacksquare \blacksquare, 3, 4)$	1.50	
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	(∎∎∎∎, 3, 4)	$(\blacksquare \blacksquare, 1, 4)$	3.00	
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 3, 4)$	(■■■■, 3, 4)	(∎∎, 3, 4)	3.00	
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,0,4)$	(■■■■■■,1,4)	$(\blacksquare, 0, 4)$	3.00	
(■■■■■■■, 2, 4)	(■■■■■■,3,4)	$(\blacksquare, 2, 4)$	3.00	
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	(∎∎∎∎∎∎,1,4)	(■, 3, 4)	3.00	
(∎∎∎∎∎∎∎, 3, 4)	(∎∎∎∎∎∎,3,4)	$(\blacksquare, 1, 4)$	3.00	

Window:	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,0,1)$
Desired Interval:	[07]
Meta-period:	6
Total Cost:	25.33

$V_g$	Incoming	edges	Cost
(■,0,6)			0.00
(■,1,6)			0.00
(■, 2, 6)			0.00
(■, 3, 6)			0.00
$(\blacksquare, 4, 6)$			0.00
$(\blacksquare, 5, 6)$			0.00
(■■,0,6)	(■,0,6)	$(\blacksquare, 1, 6)$	0.33
(■■, 3, 6)	$(\blacksquare,3,6)$	$(\blacksquare, 4, 6)$	0.33
(■■, 2, 6)	$(\blacksquare, 2, 6)$	$(\blacksquare, 3, 6)$	0.33
(■■, 5, 6)	(■, 5, 6)	$(\blacksquare, 0, 6)$	0.33
$(\blacksquare \Box \Box \Box \Box \Box \Box \Box \blacksquare, 1, 6)$	$(\blacksquare, 1, 6)$	$(\blacksquare, 2, 6)$	0.33
$(\blacksquare \square \square \square \square \square \blacksquare, 4, 6)$	$(\blacksquare, 4, 6)$	$(\blacksquare, 5, 6)$	0.33
$(\blacksquare\blacksquare\blacksquare, 2, 6)$	(■■, 3, 6)	$(\blacksquare, 2, 6)$	0.67
$(\blacksquare\blacksquare\blacksquare, 5, 6)$	(■■,0,6)	$(\blacksquare, 5, 6)$	0.67
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,2,6)$	(■■■, 2, 6)	$(\blacksquare\blacksquare\blacksquare, 5, 6)$	2.00
(■■■■■■, 5, 6)	(■■■, 2, 6)	$(\blacksquare\blacksquare\blacksquare, 5, 6)$	2.00
	(■■■■■■,2,6)	(■■,0,6)	3.00
	(■■■■■■,5,6)	(■■, 3, 6)	3.00
	(∎□□□□□□■,1,6)	(■■■■■■,2,6)	3.00
	(∎□□□□□□■,4,6)	(■■■■■■,5,6)	3.00
( <b>EEEEEE</b> , 2, 6)	(■■■■■■,2,6)	(■■, 2, 6)	3.00
(■■■■■■■■, 5, 6)	(■■■■■■,5,6)	$(\blacksquare \blacksquare, 5, 6)$	3.00

Window:			
Desired Interval:	[08]		
Meta-period:	2		
Total Cost:	29.00		
$V_g$	Incoming e	edges	Cost
(■,0,2)			0.00
(■, 1, 2)			0.00
(■■, 1, 2)	$(\blacksquare, 1, 2)$	(■,0,2)	1.00
(■■■■, 1, 2)	(■■,1,2)	$(\blacksquare \blacksquare, 1, 2)$	3.00
( <b>HEHEHEH</b> , 1, 2)	$(\blacksquare\blacksquare\blacksquare\blacksquare, 1, 2)$	(■■■■, 1, 2)	9.00
( <b>EEEEEEE</b> , 0, 2)	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 2)$	(■,0,2)	8.00
(	(	$(\blacksquare, 1, 2)$	8.00

## B.2.2 Median Filtering

This is the median filtering problem.

Window:	$(\blacksquare\blacksquare\blacksquare, 0, 1)$		
Desired Interval:	[11]		
Meta-period:	2		
Total Cost:	3.00		
$V_g$	Incomin	g edges	Cost
$(\blacksquare, 0, 2)$			0.00
$(\blacksquare, 1, 2)$			0.00
$(\blacksquare \blacksquare, 1, 2)$	$(\blacksquare, 1, 2)$	$(\blacksquare, 0, 2)$	1.00
$(\blacksquare \blacksquare \blacksquare, 0, 2)$	$(\blacksquare \blacksquare, 1, 2)$	(■,0,2)	1.00
$(\blacksquare\blacksquare\blacksquare, 1, 2)$	$(\blacksquare \blacksquare, 1, 2)$	$(\blacksquare, 1, 2)$	1.00

Window:	(■■■■■,0,1)		
Desired Interval:	[22]		
Meta-period:	2		
Total Cost:	5.00		
$V_g$	Incoming	edges	Cost
(■, 0, 2)			0.00
$(\blacksquare, 1, 2)$			0.00
$(\blacksquare \blacksquare, 1, 2)$	(■, 1, 2)	$(\blacksquare, 0, 2)$	1.00
(∎∎∎∎, 1, 2)	(■■,1,2)	(■■, 1, 2)	2.00
(■■■■■, 0, 2)	(■■■■, 1, 2)	(■, 0, 2)	1.00
( <b>IIIII</b> , 1, 2)	(∎∎∎∎, 1, 2)	$(\blacksquare, 1, 2)$	1.00

Window:	( <b>EEEEEE</b> , 0, 1)		
Desired Interval:	[33]		
Meta-period:	4		
Total Cost:	8.50		
$V_g$	Incoming e	edges	Cost
(■,0,4)			0.00
(■, 1, 4)			0.00
$(\blacksquare, 2, 4)$			0.00
(■, 3, 4)			0.00
(■■,1,4)	$(\blacksquare, 1, 4)$	$(\blacksquare, 2, 4)$	0.50
(■■, 3, 4)	$(\blacksquare, 3, 4)$	(■,0,4)	0.50
(■■■■, 3, 4)	(■■,1,4)	(∎∎, 3, 4)	1.50
(∎∎∎∎∎∎,1,4)	(∎∎∎∎, 3, 4)	(∎∎,1,4)	2.00
(■■■■■■,3,4)	(■■■■, 3, 4)	(∎∎, 3, 4)	2.00
(■■■■■■■,0,4)	(∎∎∎∎∎∎,1,4)	(■,0,4)	0.50
(■■■■■■■, 2, 4)	(■■■■■■,3,4)	$(\blacksquare, 2, 4)$	0.50
( <b>EEEEEE</b> , 1, 4)	(■■■■■■,1,4)	(■, 3, 4)	0.50
(■■■■■■■, 3, 4)	(■■■■■■,3,4)	$(\blacksquare, 1, 4)$	0.50

Window:			
Desired Interval:	[44]		
Meta-period:	2		
Total Cost:	10.00		
$V_g$	Incoming e	edges	Cost
(■,0,2)			0.00
(■,1,2)			0.00
(■■, 1, 2)	$(\blacksquare, 1, 2)$	(■,0,2)	1.00
(■■■■, 1, 2)	(■■,1,2)	$(\blacksquare \blacksquare, 1, 2)$	3.00
( <b>IIIIIII</b> , 1, 2)	(■■■■, 1, 2)	$(\blacksquare \blacksquare \blacksquare \blacksquare, 1, 2)$	4.00
(	(	(■,0,2)	1.00
(	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 2)$	$(\blacksquare, 1, 2)$	1.00

## B.2.3 Minimum Filtering

This is the minimum filtering problem.

Window:	(■■■,0,1)		
Desired Interval:	[00]		
Meta-period:	2		
Total Cost:	1.50		
$V_g$	Incomin	g edges	Cost
(■, 0, 2)			0.00
$(\blacksquare, 1, 2)$			0.00
$(\blacksquare \blacksquare \blacksquare, 0, 2)$	(■■, 1, 2)	$(\blacksquare, 0, 2)$	0.50
$(\blacksquare\blacksquare\blacksquare, 1, 2)$	$(\blacksquare \blacksquare, 1, 2)$	$(\blacksquare, 1, 2)$	0.50
$(\blacksquare \blacksquare, 1, 2)$	$(\blacksquare, 1, 2)$	$(\blacksquare, 0, 2)$	0.50

Window:	(∎∎∎∎,0,1	1)	
Desired Interval:	[00]		
Meta-period:	1		
Total Cost:	2.00		
$V_g$	Incoming edges Cost		
(■,0,1)			0.00
(■■■■,0,1)	(■■,0,1)	(■■,0,1)	1.00
(■■,0,1)	$(\blacksquare, 0, 1)$	$(\blacksquare, 0, 1)$	1.00

Window:	(■■■■,0,1)
Desired Interval:	[00]
Meta-period:	2
Total Cost:	2.00

$V_g$	Incoming edges		Cost
(■, 0, 2)			0.00
(■, 1, 2)			0.00
(∎∎∎∎∎,0,2)	(∎∎∎∎, 1, 2)	$(\blacksquare, 0, 2)$	0.50
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 2)$	(■■■■, 1, 2)	$(\blacksquare, 1, 2)$	0.50
$(\blacksquare\blacksquare\blacksquare\blacksquare, 1, 2)$	$(\blacksquare \blacksquare, 1, 2)$	$(\blacksquare \blacksquare, 1, 2)$	0.50
$(\blacksquare\blacksquare,1,2)$	$(\blacksquare, 1, 2)$	$(\blacksquare, 0, 2)$	0.50

Window:	(■■■■■■,0,1)		
Desired Interval:	[00]		
Meta-period:	2		
Total Cost:	2.50		
$V_g$	Incoming	edges	Cost
(■,0,2)			0.00
(■, 1, 2)			0.00
(■■■■■■,0,2)	(■■■■■,1,2)	(■, 0, 2)	0.50
(■■■■■■, 1, 2)	(■■■■■, 1, 2)	(■, 0, 2)	0.50
(■■■■■,1,2)	(■■■■,0,2)	$(\blacksquare, 1, 2)$	0.50
(■■■■,0,2)	(■■, 0, 2)	(■■, 0, 2)	0.50
(■■,0,2)	$(\blacksquare, 0, 2)$	$(\blacksquare, 1, 2)$	0.50

****	( (		
Window:	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 0, 1)$		
Desired Interval:	[00]		
Meta-period:	4		
Total Cost:	2.25		
$V_g$	Incoming e	edges	Cost
$(\blacksquare, 0, 4)$			0.00
$(\blacksquare, 1, 4)$			0.00
$(\blacksquare, 2, 4)$			0.00
$(\blacksquare, 3, 4)$			0.00
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,0,4)$	(■■■■■■,1,4)	$(\blacksquare, 0, 4)$	0.25
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,2,4)$	(■■■■■■,3,4)	$(\blacksquare, 2, 4)$	0.25
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	(■, 3, 4)	0.25
(∎∎∎∎∎∎∎, 3, 4)	(■■■■■■,3,4)	$(\blacksquare, 1, 4)$	0.25
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	$(\blacksquare\blacksquare\blacksquare\blacksquare, 3, 4)$	$(\blacksquare \blacksquare, 1, 4)$	0.25
$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare=,3,4)$	(∎∎∎∎, 3, 4)	(∎∎, 3, 4)	0.25
$(\blacksquare \blacksquare, 1, 4)$	$(\blacksquare, 1, 4)$	$(\blacksquare, 2, 4)$	0.25
$(\blacksquare \blacksquare, 3, 4)$	$(\blacksquare, 3, 4)$	(■,0,4)	0.25
(∎∎∎∎, 3, 4)	(■■, 1, 4)	(∎∎, 3, 4)	0.25

Window:	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,0,1)$		
Desired Interval:	[00]		
Meta-period:	4		
Total Cost:	2.75		
$V_g$	Incoming ee	lges	Cost
$(\blacksquare, 0, 4)$			0.00
(■,1,4)			0.00
(■, 2, 4)			0.00
(■, 3, 4)			0.00
( <b>EEEEEE</b> , 0, 4)	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	$(\blacksquare, 0, 4)$	0.25
(	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,3,4)$	$(\blacksquare, 2, 4)$	0.25
( <b>HEHEHEH</b> , 1, 4)	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 1, 4)$	(■,0,4)	0.25
( <b>EEEEEE</b> , 3, 4)	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare,3,4)$	$(\blacksquare, 2, 4)$	0.25
( <b>HEHEHEH</b> , 1, 4)	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 2, 4)$	$(\blacksquare, 1, 4)$	0.25
(■■■■■■■,3,4)	$(\blacksquare\blacksquare\blacksquare\blacksquare\blacksquare, 0, 4)$	$(\blacksquare, 3, 4)$	0.25
(■■■■■■,0,4)	$(\blacksquare\blacksquare\blacksquare\blacksquare, 2, 4)$	$(\blacksquare \blacksquare, 0, 4)$	0.25
(■■■■■■, 2, 4)	$(\blacksquare\blacksquare\blacksquare\blacksquare, 2, 4)$	(■■, 2, 4)	0.25
(■■, 0, 4)	$(\blacksquare, 0, 4)$	$(\blacksquare, 1, 4)$	0.25
$(\blacksquare \blacksquare, 2, 4)$	$(\blacksquare, 2, 4)$	$(\blacksquare, 3, 4)$	0.25
(■■■■, 2, 4)	(■■, 0, 4)	(■■, 2, 4)	0.25

Window:			
Desired Interval:	[00]		
Meta-period:	2		
Total Cost:	2.50		
$V_g$	Incoming e	edges	Cost
(■,0,2)			0.00
(■,1,2)			0.00
(	(■■■■■■■■, 1, 2)	(■,0,2)	0.50
(	(	$(\blacksquare, 1, 2)$	0.50
( <b>HEHEHEH</b> , 1, 2)	(■■■■, 1, 2)	(∎∎∎∎, 1, 2)	0.50
(■■■■, 1, 2)	(■■,1,2)	(■■, 1, 2)	0.50
(■■, 1, 2)	(■,1,2)	$(\blacksquare, 0, 2)$	0.50

## **B.3** Two Dimensional Problems

In this section we present some solutions for two dimensional problems.

We extend our notation for a set of coordinates to two dimensions by drawing matrices of squares. The upper left square of such a matrix corresponds to the coordinate (0,0) the square to the right corresponds to (1,0), etc.

#### B.3.1 Window Sorting

The first problem is that of sorting the entire window.

Window:	(0,0),(1,1)		
Desired Interval:	[08]		
Meta-period:	(2,2)		
Total Cost:	35.00		
$V_g$	Incoming	g edges	Cost
$(\blacksquare, (0, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$			0.00
$(\blacksquare, (1, 0), (2, 2))$			0.00
$(\blacksquare, (1, 1), (2, 2))$			0.00
([0,1),(2,2))	$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 0), (2, 2))$	0.50
$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 0), (2, 2))$	0.50
$\left( {\color{red}\bullet}, (0,0), (2,2) \right)$	$(\blacksquare, (0, 0), (2, 2))$	$\left(\blacksquare, (0, 1), (2, 2)\right)$	1.00
$\left( {\color{red}\bullet}, (0,1), (2,2) \right)$	$(\blacksquare, (0, 1), (2, 2))$	$\left(\blacksquare,(0,1),(2,2)\right)$	1.00
$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (1,0), (2,2) \right] \right)$	$(\blacksquare, (1, 0), (2, 2))$	$\left(\blacksquare,(1,1),(2,2)\right)$	1.00
$\left( \left[ , (1,1), (2,2) \right] \right)$	$(\blacksquare, (1, 1), (2, 2))$	$\left(\blacksquare,(1,1),(2,2)\right)$	1.00
(1,0),(2,2)	([1,0),(2,2))	$(\mathbf{I}, (0, 0), (2, 2))$	3.00
(1,1),(2,2)	([1,1),(2,2))	$(\mathbf{I}, (0, 1), (2, 2))$	3.00
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \\ \bullet \bullet \bullet \end{array}, (0,0), (2,2) \right) \right)$	(1,0),(2,2)	$\left( \left[ 0, (0, 0), (2, 2) \right] \right)$	6.00
(0,1),(2,2)	(1,1),(2,2)	$\left( \left[ \bullet, (0,1), (2,2) \right) \right)$	6.00
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \\ \bullet \bullet \bullet \end{array}, (1,0), (2,2) \right) \right)$	(1,0),(2,2)	$(\blacksquare, (1, 0), (2, 2))$	6.00
(1,1),(2,2)	(1,1),(2,2)	$(\mathbf{I}, (1, 1), (2, 2))$	6.00

Window:	(		
Desired Interval:	[024]		
Meta-period:	(2,2)		
Total Cost:	152.00		
	Incoming	; edges	Cost
$(\blacksquare, (0, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$			0.00
$(\blacksquare, (1, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 0), (2, 2))$	0.50
$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 0), (2, 2))$	0.50
(, (0, 1), (2, 2))	$(\blacksquare, (0, 1), (2, 2))$	$\left(\blacksquare, (0, 1), (2, 2)\right)$	1.50
$\left( \begin{bmatrix} 1 \\ $	$(\blacksquare, (1, 1), (2, 2))$	$\left(\blacksquare,(1,1),(2,2)\right)$	1.50
(0,0),(2,2)	$(\blacksquare, (0, 0), (2, 2))$	$\left( \begin{bmatrix} \bullet \\ \bullet \\ \bullet \end{bmatrix}, (0,1), (2,2) \right)$	2.00
$\left( \left( \bullet, (0,1), (2,2) \right) \right)$	$(\blacksquare, (0, 1), (2, 2))$	$\left( \begin{bmatrix} \bullet \\ \bullet \end{bmatrix}, (0,1), (2,2) \right)$	2.00
$\left( \left[ , (1,0), (2,2) \right] \right)$	$(\blacksquare, (1, 0), (2, 2))$	$\left( \begin{bmatrix} \bullet \\ \bullet$	2.00
$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (1,1), (2,2) \right] \right)$	$(\blacksquare, (1, 1), (2, 2))$	$\left( \begin{bmatrix} \bullet \\ \bullet \end{bmatrix}, (1,1), (2,2) \right)$	2.00
$\left( \bigoplus_{i=1}^{n}, (1,0), (2,2) \right)$	(, $(1, 0), (2, 2)$ $)$	$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (0,0), (2,2) \right] \right)$	6.50
$\left( \underbrace{\bullet}_{\bullet}, (1,1), (2,2) \right)$	(, (1, 1), (2, 2))	$\left( \left( \bullet, (0,1), (2,2) \right) \right)$	6.50
$\left( \underbrace{\bullet \bullet \bullet \bullet}_{\bullet \bullet \bullet \bullet}, (1,0), (2,2) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,0), (2,2) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,0), (2,2) \right)$	17.50
$\left( \left( \begin{array}{c} \\ \end{array} \right), (1,1), (2,2) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,1), (2,2) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,1), (2,2) \right)$	17.50
$\left( \left( \begin{array}{c} \bullet \bullet$	$\left( \underbrace{\bullet} \bullet \bullet \bullet \bullet , (1,0), (2,2) \right)$	$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (0,0), (2,2) \right] \right)$	23.00
$\left( \begin{array}{c} \bullet \bullet$	$\left( \underbrace{\bullet}, (1,1), (2,2) \right)$	$\left( \left[ , (0,1), (2,2) \right] \right)$	23.00
$\left( \bullet \bullet$	(, $(1,0), (2,2)$ $)$	$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (1,0), (2,2) \right] \right)$	23.00
(	(, $(1,1), (2,2)$ )	(, $(1, 1), (2, 2)$ )	23.00

## B.3.2 Median Filtering

This is the median filtering problem.

Window:	( 1, 1)		
Desired Interval:	[44]		
Meta-period:	(2,2)		
Total Cost:	16.00		
$V_g$	Incomin	g edges	Cost
$(\blacksquare, (0, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$			0.00
$(\blacksquare, (1, 0), (2, 2))$			0.00
$(\blacksquare, (1, 1), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 0), (2, 2))$	0.50
$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 0), (2, 2))$	0.50
$\left( {\color{red} \bullet}, (0,0), (2,2) \right)$	$(\blacksquare, (0, 0), (2, 2))$	$\left(\blacksquare,(0,1),(2,2)\right)$	1.00
$\left( {\color{red} \bullet}, (0,1), (2,2) \right)$	$(\blacksquare, (0, 1), (2, 2))$	$\left(\blacksquare,(0,1),(2,2)\right)$	1.00
$\left( {\color{red}\bullet},(1,0),(2,2) \right)$	$(\blacksquare, (1, 0), (2, 2))$	$\left(\blacksquare,(1,1),(2,2)\right)$	1.00
$\left( \left( \bullet, (1,1), (2,2) \right) \right)$	$(\blacksquare, (1, 1), (2, 2))$	$\left(\blacksquare,(1,1),(2,2)\right)$	1.00
$\left( \bigoplus_{i=1}^{n}, (1,0), (2,2) \right)$	$\left( {\color{red}\bullet},(1,0),(2,2) \right)$	$\left( \blacksquare, (0,0), (2,2) \right)$	2.50
$\left( \bigoplus, (1,1), (2,2) \right)$	$\left( {\color{red} \bullet}, (1,1), (2,2) \right)$	$\left( \blacksquare, (0,1), (2,2) \right)$	2.50
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \\ \bullet \bullet \bullet \end{array}, (0,0), (2,2) \right) \right)$	(1,0),(2,2)	$\left( \left[ 0, (0, 0), (2, 2) \right] \right)$	1.50
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \end{array}, (0,1), (2,2) \right) \right)$	(1,1),(2,2)	$\left( \left[ 0, 1, (2, 2) \right] \right)$	1.50
(1,0),(2,2)	(1,0),(2,2)	$(\mathbf{I}, (1,0), (2,2))$	1.50
(1,1),(2,2)	(1,1),(2,2)	$(\mathbf{I}, (1, 1), (2, 2))$	1.50

Window:	$\left( \left( \begin{array}{c} \bullet \bullet$		
Desired Interval:	[1212]		
Meta-period:	(2,2)		
Total Cost:	53.00		
$V_g$	Incoming	edges	Cost
$(\blacksquare, (0, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$			0.00
$(\blacksquare, (1, 0), (2, 2))$			0.00
$(\blacksquare, (1, 1), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 0), (2, 2))$	0.50
$\left( \blacksquare, (1,1), (2,2) \right)$	$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 0), (2, 2))$	0.50
$\left( \begin{bmatrix} \bullet \\ \bullet \\ \bullet \end{bmatrix}, (0,1), (2,2) \right)$	$\left( \blacksquare, (0,1), (2,2) \right)$	$\left( \blacksquare, (0,1), (2,2) \right)$	1.50
$\left( \left[ , (1,1), (2,2) \right] \right)$	$\left(\blacksquare,(1,1),(2,2)\right)$	$\left(\blacksquare,(1,1),(2,2)\right)$	1.50
$\left( \left( \begin{array}{c} \bullet \\ \bullet \\ \bullet \end{array}, (0,0), (2,2) \right) \right)$	$(\blacksquare, (0, 0), (2, 2))$	$\left( \begin{array}{c} \bullet \\ \bullet \end{array}, (0,1), (2,2) \right)$	2.00
$\left(\left(\begin{smallmatrix} \bullet \\ \bullet $	$(\blacksquare, (0, 1), (2, 2))$	(, $(0, 1), (2, 2))$	2.00

$\left( \left( \begin{array}{c} \bullet \\ \bullet \end{array}, (1,0), (2,2) \right) \right)$	$(\blacksquare, (1, 0), (2, 2))$	$\left( {\rule{0.5ex}{.5ex}},(1,1),(2,2) \right)$	2.00
$\left( \left( \begin{array}{c} \bullet \\ \bullet \end{array}, (1,1), (2,2) \right) \right)$	$(\blacksquare, (1, 1), (2, 2))$	$\left( {\rule{0.5ex}{.5ex}},(1,1),(2,2) \right)$	2.00
$\left( \bigoplus_{i=1}^{n}, (1,0), (2,2) \right)$	(, (1, 0), (2, 2) $)$	$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (0,0), (2,2) \right] \right)$	6.50
$\left( \bigoplus_{i=1}^{n}, (1,1), (2,2) \right)$	(, (1, 1), (2, 2) $)$	$\left( \left( \bullet, (0,1), (2,2) \right) \right)$	6.50
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \end{array}, (1,0), (2,2) \right) \right)$	$\left( \underbrace{\bullet \bullet}_{\bullet}, (1,0), (2,2) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,0), (2,2) \right)$	9.00
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \end{array}, (1,1), (2,2) \right) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,1), (2,2) \right)$	$\left( \underbrace{\bullet}_{\bullet}, (1,1), (2,2) \right)$	9.00
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \bullet \end{array} \right), (0,0), (2,2) \right)$	(, $(1,0), (2,2)$ $)$	$\left( \left[ , (0,0), (2,2) \right] \right)$	2.50
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \bullet \end{array} \right), (0,1), (2,2) \right)$	(, $(1, 1), (2, 2))$	(, $(0, 1), (2, 2)$ $)$	2.50
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \bullet \end{array} \right), (1,0), (2,2) \right)$	(, $(1,0), (2,2)$ $)$	$\left( \left[ , (1,0), (2,2) \right] \right)$	2.50
$\left( \left( \begin{array}{c} \bullet \bullet$	(, $(1, 1), (2, 2)$ )	$\left( \left[ , (1,1), (2,2) \right] \right)$	2.50

## B.3.3 Minimum Filtering

This is the minimum filtering problem.

Window:	(0,0),(1,1)		
Desired Interval:	[00]		
Meta-period:	(2,2)		
Total Cost:	3.00		
$V_g$	Incoming edges		Cost
$(\blacksquare, (0, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$			0.00
$(\blacksquare, (1, 0), (2, 2))$			0.00
$(\blacksquare, (1, 1), (2, 2))$			0.00
$\left( \textcircled{\bullet}, (0,0), (2,2) \right)$	$\left( \blacksquare, (1,0), (2,2) \right)$	$\left( \blacksquare, (0,0), (2,2) \right)$	0.25
$\left( \textcircled{\bullet \bullet \bullet}, (0,1), (2,2) \right)$	$\left( \blacksquare, (1,1), (2,2) \right)$	$\left( \blacksquare, (0,1), (2,2) \right)$	0.25
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \end{array}, (1,0), (2,2) \right) \right)$	$\left( \blacksquare, (1,0), (2,2) \right)$	$\left( \blacksquare, (1,0), (2,2) \right)$	0.25
$\left( \textcircled{\bullet \bullet \bullet}, (1,1), (2,2) \right)$	$\left( \blacksquare, (1,1), (2,2) \right)$	$\left( \blacksquare, (1,1), (2,2) \right)$	0.25
$\left( {\color{red} \bullet}, (0,0), (2,2) \right)$	$(\blacksquare, (0, 0), (2, 2))$	$\left(\blacksquare,(0,1),(2,2)\right)$	0.25
$\left( {\color{red}\bullet}, (0,1), (2,2) \right)$	$(\blacksquare, (0, 1), (2, 2))$	$\left(\blacksquare,(0,1),(2,2)\right)$	0.25
(1,0),(2,2)	$(\blacksquare, (1, 0), (2, 2))$	$\left(\blacksquare, (1, 1), (2, 2)\right)$	0.25

$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (1,1), (2,2) \right) \right)$	$(\blacksquare, (1, 1), (2, 2))$	$\left(\blacksquare,(1,1),(2,2)\right)$	0.25
$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 0), (2, 2))$	0.25
$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 1), (2, 2))$	$(\blacksquare, (1, 0), (2, 2))$	0.25
(1,0),(2,2)	$(\mathbf{I}, (1,0), (2,2))$	$\left( \blacksquare, (0,0), (2,2) \right)$	0.25
$\left( \blacksquare , (1,1), (2,2) \right)$	$(\mathbf{I}, (1, 1), (2, 2))$	$\left( \blacksquare, (0,1), (2,2) \right)$	0.25

Window:	(, $(0,0), (1,1)$		
Desired Interval:	[00]		
Meta-period:	(2,2)		
Total Cost:	4.00		
$V_q$	Incoming	; edges	Cost
$(\blacksquare, (0, 0), (2, 2))$			0.00
$(\blacksquare, (0, 1), (2, 2))$			0.00
$(\blacksquare, (1, 0), (2, 2))$			0.00
$(\blacksquare, (1, 1), (2, 2))$			0.00
(0,0),(2,2)	(, $(1, 0), (2, 2)$ )	$\left( \left[ , (0,0), (2,2) \right] \right)$	0.25
(, $(0, 1), (2, 2))$	$\left( \underbrace{\bullet \bullet \bullet \bullet}_{\bullet}, (1,1), (2,2) \right)$	$\left( \begin{bmatrix} \bullet \\ \bullet \\ \bullet \end{bmatrix}, (0,1), (2,2) \right)$	0.25
(, $(1, 0), (2, 2)$ )	$\left( \underbrace{\bullet \bullet \bullet \bullet}_{\bullet \bullet \bullet \bullet}, (1,0), (2,2) \right)$	$\left( \begin{bmatrix} \bullet \\ \bullet \\ \bullet \end{bmatrix}, (1,0), (2,2) \right)$	0.25
$\left( \underbrace{\bullet \bullet \bullet \bullet \bullet}_{\bullet \bullet \bullet \bullet \bullet}, (1,1), (2,2) \right)$	$\left( \underbrace{\bullet \bullet \bullet \bullet}_{\bullet \bullet \bullet \bullet}, (1,1), (2,2) \right)$	$\left( \left[ \begin{array}{c} \bullet \\ \bullet \end{array}, (1,1), (2,2) \right] \right)$	0.25
$\left( \left( \bullet, (0,0), (2,2) \right) \right)$	$(\blacksquare, (0, 0), (2, 2))$	$\left( \begin{bmatrix} \bullet \\ \bullet \\ \bullet \end{bmatrix}, (0,1), (2,2) \right)$	0.25
(, $(0, 1), (2, 2))$	$(\blacksquare, (0, 1), (2, 2))$	(0,1),(2,2)	0.25
(, $(1,0), (2,2)$ )	$(\blacksquare, (1, 0), (2, 2))$	$\left( \begin{bmatrix} \bullet \\ \bullet \\ \bullet \end{bmatrix}, (1,1), (2,2) \right)$	0.25
(, $(1, 1), (2, 2)$ )	$(\blacksquare, (1, 1), (2, 2))$	(, $(1, 1), (2, 2))$	0.25
(, $(0, 1), (2, 2))$	$\left(\blacksquare,(0,1),(2,2)\right)$	$\left(\blacksquare, (0, 1), (2, 2)\right)$	0.25
$\left( \left[ , (1,1), (2,2) \right] \right)$	$\left(\blacksquare,(1,1),(2,2)\right)$	$\left(\blacksquare,(1,1),(2,2)\right)$	0.25
$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 1), (2, 2))$	$(\blacksquare, (0, 0), (2, 2))$	0.25
$(\blacksquare (1, 1), (2, 2))$	(■ (1 1) (2 2))	$(\blacksquare (1, 0) (2, 2))$	0.25
	(=, (1, 1), (2, 2))	(=,(1,0),(2,2))	0.20
$\left( \left( \begin{array}{c} \bullet \bullet \bullet \bullet \\ \bullet \bullet \bullet \bullet \end{array}, (1,0), (2,2) \right) \right)$	$\left( \blacksquare, (1,0), (2,2) \right)$	$\left( \left( \begin{array}{c} \bullet \\ \bullet \end{array}, (1,0), (2,2) \right) \right)$	0.25
(, $(1, 1), (2, 2))$	$\left( \begin{array}{c} \bullet \\ \bullet \\ \bullet \end{array}, (1,1), (2,2) \right)$	$\left( \left( \begin{array}{c} \bullet \\ \bullet \end{array}, (1,1), (2,2) \right) \right)$	0.25

#### APPENDIX B. SAMPLE SOLUTIONS

$\left( \left( \begin{array}{c} \bullet \\ \bullet \end{array}, (1,0), (2,2) \right) \right)$	(, $(1,0), (2,2)$ $)$	$\left( \left( , (0,0), (2,2) \right) \right)$	0.25
$\left( \left( \bullet , (1,1), (2,2) \right) \right)$	(, $(1, 1), (2, 2)$ )	(0,1),(2,2)	0.25