# Decomposition of a Positive Definite Matrix Function that is Continuously Differentiable 

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# Decomposition of a Positive Definite Matrix Function that is Continuously Differentiable 

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## I. Introduction

When studying nonlinear problems in a quadratic form, it can be of interest to decompose a continuously differentiable, positive definite matrix function $A$, which maps from $\mathcal{X} \subseteq \mathbb{R}^{n}$ to $\mathbb{R}^{n \times n}$ into a constant matrix that is pre- and and post multiplied with another matrix function that maps from $\mathcal{X} \subseteq \mathbb{R}^{n}$ to $\mathbb{R}^{n \times n}$, i.e., for all $x \in \mathcal{X}$ we have $A(x)=B(x)^{\top} Q B(x)$. In this document, we show that this can be accomplished under certain assumptions.

## II. Problem definition

Consider the matrix function $A: \mathcal{X} \mapsto \mathbb{R}^{n \times n}$, where $\mathcal{X} \subseteq \mathbb{R}^{n}$, $n \in \mathbb{N}$, and assume that $A$ admits the following properties

- $\forall x \in \mathcal{X}$, we have that $A(x)$ is real, symmetric and bounded.
- $A(x)$ is a $\mathcal{C}_{1}$ function, i.e., $A(x)$ and $\frac{\partial A(x)}{\partial x}$ are continuous functions.
- There exist two constants $0<c_{1} \leq c_{2}$ such that $\forall x \in \mathcal{X}$, $c_{1} I \preccurlyeq A(x) \preccurlyeq c_{2} I$.
Note that the last property ensures that $A(x)$ is positive definite for all $x \in \mathcal{X}$. The problem is to show that $A(x)$ can always be decomposed as

$$
A(x)=B(x)^{\top} Q B(x)
$$

where the matrix $Q$ is positive definite, i.e., $0 \prec Q \in \mathbb{R}^{n \times n}$, and the matrix function $B: \mathcal{X} \mapsto \mathbb{R}^{n \times n}$ is a $\mathcal{C}_{1}$ function which is non-singular for all $x \in \mathcal{X}$, i.e., $\forall x \in \mathcal{X}, \operatorname{det}(B(x)) \neq 0$.

## III. Result

We now show that this decomposition is possible under the assumptions in Section $\Pi$ First, denote the set of all real, symmetric matrices by $\mathcal{S}$ and the set of all positive definite matrices by $\mathcal{P}$. Note that $\mathcal{P}$ is open in the $\frac{n(n+1)}{2}$-dimensional real vector space $\mathcal{S}$. The positive definite square-root function $g(A)=A^{\frac{1}{2}}$ is well-defined on $\mathcal{P}$ [1]. In fact, given $A$, its positive definite square-root is uniquely determined by the Lagrange interpolation polynomial that maps each distinct eigenvalue $\lambda$ of $A$ to $\sqrt{\lambda}$.
Now, let $A_{0}$ be any positive definite matrix and let $B_{0}=A_{0}^{\frac{1}{2}}$. Note that $B_{0}$ is positive definite. Define $f(B)=B^{2}$ on $\mathcal{S}$. Then $f$ is $\mathcal{C}_{1}$ and its Fréchet derivative $\mathrm{D} f: X \mapsto B X+X B$ is non-singular at $B_{0}$. Note that $X$ is the argument of $\mathrm{D} f$ here, and serves as a dummy variable. As the Fréchet derivative of $f$ is non-singular at $B_{0}$, by the inverse function theorem, $f$ has a $\mathcal{C}_{1}$ local inverse defined on some neighbourhood $\mathcal{W}$ containing $A_{0}$. Since $\mathcal{P}$ is open, we may assume that $\mathcal{W} \subseteq \mathcal{P}$. As this
local inverse of $f$ gives a positive definite square-root function on $\mathcal{W}$, it must agree with $g$. Hence, $g$ is $\mathcal{C}_{1}$ on $\mathcal{W}$. It follows that $g$ is $\mathcal{C}_{1}$ on $\mathcal{P}$ because $A_{0}$ is arbitrary.
Finally, when $A$ is a $\mathcal{C}_{1}$ function of $x$, its square root $A(x)^{\frac{1}{2}}=g(A(x))$ is also $\mathcal{C}^{1}$, by the chain rule. Therefore, the matrix function $A(x)$ can always be decomposed as $A(x)=B(x)^{\top} Q B(x)$ by taking $B(x):=A(x)^{\frac{1}{2}}$ and $Q=I$.

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## REFERENCES

[1] M. Koeber and U. Schäfer, "The unique square root of a positive semidefinite matrix," International Journal of Mathematical Education in Science and Technology, vol. 37, no. 8, pp. 990-992, 2006.

