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# Periodic homogenization of a pseudo-parabolic equation via a spatial-temporal decomposition

Arthur. J. Vromans and Fons van de Ven and Adrian Muntean

**Abstract** Pseudo-parabolic equations have been used to model unsaturated fluid flow in porous media. In this paper it is shown how a pseudo-parabolic equation can be upscaled when using a spatio-temporal decomposition employed in the Peszyńska-Showalter-Yi paper [8]. The spatial-temporal decomposition transforms the pseudo-parabolic equation into a system containing an elliptic partial differential equation and a temporal ordinary differential equation. To strengthen our argument, the pseudo-parabolic equation has been given advection/convection/drift terms. The upscaling is done with the technique of periodic homogenization via two-scale convergence. The well-posedness of the extended pseudo-parabolic equation is shown as well. Moreover, we argue that under certain conditions, a non-local-in-time term arises from the elimination of an unknown.

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## 1 Introduction

Groundwater recharge and pollution prediction for aquifers need models for describing unsaturated fluid flow in porous media. Pseudo-parabolic equations were found to be adequate models, see eqn. 25 in [3]. In [8] a spatial-temporal decomposition

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of a pseudo-parabolic system was introduced. It was shown that this decomposition made upscaling of this system rather straightforward in several classical situations such as vanishing time-delay and double-porosity systems. In [8] a toy pseudo-parabolic model was derived from a balance equation describing flow through a partially saturated porous medium. In our framework, a convective term that was dropped in [8], is retained in order to show that this term yields no additional problems for upscaling with the spatial-temporal decomposition. We want to convey the message that this decomposition can be applied not only to the physical system in [8] but also to other physical systems with pseudo-parabolic equations, such as the concrete corrosion reaction model introduced in [9]. Both these pseudo-parabolic systems are physical systems on a spatial micro scale with an intrinsic microscopic periodicity of size  $\varepsilon \ll 1$ . Similar intrinsic microscopic periodic behaviors are found in highly active research fields using composite structures or nano-structures.

In this paper, we use this spatial-temporal decomposition to upscale our pseudo-parabolic equation by using the concept of periodic homogenization via two-scale convergence, which leads to a homogenized system that retains the spatial-temporal decomposition. We start in Section 2 with formulating our pseudo-parabolic system  $(\mathbf{Q}^\varepsilon)$ , the decomposition system  $(\mathbf{P}^\varepsilon)$  and stating our assumptions. In Section 3, an existence and uniqueness result for weak solutions to our problem  $(\mathbf{P}^\varepsilon)$  is derived. In Section 4, we apply the idea of two-scale convergence to a weak version of problem  $(\mathbf{P}^\varepsilon)$ , denoted  $(\mathbf{P}_w^\varepsilon)$ , that contains the microscopic information at the  $\varepsilon$ -level. Furthermore in this section, an upscaled system  $(\mathbf{P}_w^0)$  of the weak system  $(\mathbf{P}_w^\varepsilon)$  is derived in the limit  $\varepsilon \downarrow 0$ , and, under certain conditions, an upscaled strong system  $(\mathbf{P}_s^0)$  is obtained after eliminating several variables. This upscaled strong system contains a non-local-in-time term, but the system has lost the partial differential equation framework as a consequence. Contrary, the upscaled weak system  $(\mathbf{P}_w^0)$  keeps the partial differential equation framework due to the spatial-temporal decomposition.

## 2 Basic system and assumptions

Our pseudo-parabolic system  $(\mathbf{Q}^\varepsilon)$  consists of a family of  $N$  partial differential equations for the variable vector  $\mathbf{U}^\varepsilon(t, \mathbf{x}, \mathbf{x}/\varepsilon) = (U_1^\varepsilon, \dots, U_\alpha^\varepsilon, \dots, U_N^\varepsilon)$  with  $t > 0$  and  $\mathbf{x} = (x_1, \dots, x_i, \dots, x_d) \in \Omega \subset \mathbf{R}^d$ . For  $\varepsilon \in (0, \varepsilon_0)$  with  $\varepsilon_0 > 0$ , system  $(\mathbf{Q}^\varepsilon)$  is formulated as

$$(\mathbf{Q}^\varepsilon) \quad \begin{cases} M^\varepsilon G^{-1} \partial_t \mathbf{U}^\varepsilon - \nabla \cdot ((E^\varepsilon \cdot \nabla + D^\varepsilon) G^{-1} (\partial_t \mathbf{U}^\varepsilon + \mathbf{L} \mathbf{U}^\varepsilon)) \\ \quad = \mathbf{H}^\varepsilon + (K^\varepsilon - M^\varepsilon G^{-1} \mathbf{L}) \mathbf{U}^\varepsilon + \mathbf{J}^\varepsilon \cdot \nabla \mathbf{U}^\varepsilon & \text{on } \mathbf{R}_+ \times \Omega, \\ \mathbf{U}^\varepsilon = \mathbf{U}_* & \text{on } \{0\} \times \Omega, \\ \partial_t \mathbf{U}^\varepsilon + \mathbf{L} \mathbf{U}^\varepsilon = \mathbf{0} & \text{on } \mathbf{R}_+ \times \partial \Omega. \end{cases}$$

The vectors  $\mathbf{V}^\varepsilon$  and  $\mathbf{U}^\varepsilon$  are both functions of the time coordinate  $t$ , the global or macro position coordinate  $\mathbf{x}$ , and also periodic functions of the micro (or nano) coordinate  $\mathbf{y} \in Y$ , where  $\mathbf{y} = \mathbf{x}/\varepsilon$ , where the size of the micro domain  $Y$  is  $\mathcal{O}(\varepsilon)$  of the size of the macro domain  $\Omega$ .

Our dimensionless decomposition system  $(\mathbf{P}^\varepsilon)$  consists of a family of  $N$  partial differential equations (PDEs) and a family of  $N$  ordinary differential equations (ODEs) for the two variable vectors  $\mathbf{V}^\varepsilon(t, \mathbf{x}, \mathbf{x}/\varepsilon) = (V_1^\varepsilon, \dots, V_\alpha^\varepsilon, \dots, V_N^\varepsilon)$  and  $\mathbf{U}^\varepsilon(t, \mathbf{x}, \mathbf{x}/\varepsilon)$ . For  $\varepsilon \in (0, \varepsilon_0)$  with  $\varepsilon_0 > 0$ , it is formulated as

$$(\mathbf{P}^\varepsilon) \quad \begin{cases} \mathbf{M}^\varepsilon \mathbf{V}^\varepsilon - \nabla \cdot (\mathbf{E}^\varepsilon \cdot \nabla \mathbf{V}^\varepsilon + \mathbf{D}^\varepsilon \mathbf{V}^\varepsilon) = \mathbf{H}^\varepsilon + \mathbf{K}^\varepsilon \mathbf{U}^\varepsilon + \mathbf{J}^\varepsilon \cdot \nabla \mathbf{U}^\varepsilon & \text{on } \mathbf{R}_+ \times \Omega, \\ \partial_t \mathbf{U}^\varepsilon + \mathbf{L} \mathbf{U}^\varepsilon = \mathbf{G} \mathbf{V}^\varepsilon & \text{on } \mathbf{R}_+ \times \Omega, \\ \mathbf{U}^\varepsilon = \mathbf{U}_* & \text{on } \{0\} \times \Omega, \\ \mathbf{V}^\varepsilon = \mathbf{0} & \text{on } \mathbf{R}_+ \times \partial \Omega. \end{cases}$$

Above, the  $\varepsilon$ -dependent notation  $c^\varepsilon(t, \mathbf{x}) = c(t, \mathbf{x}, \mathbf{x}/\varepsilon)$  is used for the  $\varepsilon$ -independent 1-, 2- and 3-tensors of assumption (A1).

(A1) For all  $\alpha, \beta \in \{1, \dots, N\}$  and for all  $i, j \in \{1, \dots, d\}$ , we have

$$\begin{aligned} \mathbf{M}_{\alpha\beta}, \mathbf{E}_{ij}, \mathbf{D}_{i\alpha\beta}, \mathbf{H}_\alpha, \mathbf{K}_{\alpha\beta}, \mathbf{J}_{i\alpha\beta} &\in L^\infty(\mathbf{R}_+ \times \Omega; C_\#(Y)), \\ \mathbf{L}_{\alpha\beta}, \mathbf{G}_{\alpha\beta} &\in L^\infty(\mathbf{R}_+; W^{1,\infty}(\Omega)), \\ \mathbf{U}_* &\in C^1(\Omega)^N, \end{aligned}$$

with  $\mathbf{G}$  invertible.

(A2) Let the tensors  $\mathbf{M}^\varepsilon$  and  $\mathbf{E}^\varepsilon$  be in diagonal form<sup>1</sup> with elements  $m_\alpha^\varepsilon > 0$  and  $e_i^\varepsilon > 0$ , respectively, satisfying  $1/m_\alpha^\varepsilon, 1/e_i^\varepsilon \in L^\infty(\mathbf{R}_+ \times \Omega; C_\#(Y))$ .

(A3) The inequality

$$\|D_{i\beta\alpha}^\varepsilon\|_{L^\infty(\mathbf{R}_+ \times \Omega^\varepsilon; C_\#(Y))}^2 < \frac{4}{dN^2 \|1/m_\alpha^\varepsilon\|_{L^\infty(\mathbf{R}_+ \times \Omega^\varepsilon; C_\#(Y))} \|1/e_i^\varepsilon\|_{L^\infty(\mathbf{R}_+ \times \Omega^\varepsilon; C_\#(Y))}}$$

holds for all  $\alpha, \beta \in \{1, \dots, N\}$ , for all  $i \in \{1, \dots, n\}$ , and for all  $\varepsilon \in (0, \varepsilon_0)$ .

Remark, inequality (2) implies that automatically (2) holds for the  $Y$ -averaged functions  $\overline{D}_{i\beta\alpha}^\varepsilon$ ,  $\overline{M}_{\beta\alpha}^\varepsilon$ , and  $\overline{E}_{ij}^\varepsilon$  in  $L^\infty(\mathbf{R}_+ \times \Omega)$ , using  $|Y|\overline{f}(t, \mathbf{x}) = \int_Y f(t, \mathbf{x}, \mathbf{y}) d\mathbf{y}$ .

### 3 Existence and uniqueness of weak solutions to $(\mathbf{P}_w^\varepsilon)$

In this section, we show the existence and uniqueness of a weak solution  $(\mathbf{U}, \mathbf{V})$  to  $(\mathbf{P}^\varepsilon)$ . We define a weak solution to  $(\mathbf{P}^\varepsilon)$  for  $\varepsilon \in (0, \varepsilon_0)$  and  $T \in \mathbf{R}_+$  as a pair of

<sup>1</sup> Due to the Theorem of Jacobi about quadratic forms (cf. [4]) in combination with the coercivity of both  $\mathbf{M}^\varepsilon$  and  $\mathbf{E}^\varepsilon$ , we are allowed to assume diagonal forms of  $\mathbf{M}^\varepsilon$  and  $\mathbf{E}^\varepsilon$  as the orthogonal transformations, necessary to put their quadratic forms in diagonal form, modify the domain  $\Omega^\varepsilon$  and the coefficients of  $\mathbf{D}^\varepsilon$ ,  $\mathbf{H}^\varepsilon$ ,  $\mathbf{K}^\varepsilon$  and  $\mathbf{J}^\varepsilon$  without changing their regularity.

sequences  $(\mathbf{U}^\varepsilon, \mathbf{V}^\varepsilon) \in H^1((0, T) \times \Omega)^N \times L^\infty((0, T), H_0^1(\Omega))^N$  satisfying

$$(\mathbf{P}_w^\varepsilon) \begin{cases} \int_{\Omega} \phi^\top [\mathbf{M}^\varepsilon \mathbf{V}^\varepsilon - \mathbf{H}^\varepsilon - \mathbf{K}^\varepsilon \mathbf{U}^\varepsilon - \mathbf{J}^\varepsilon \cdot \nabla \mathbf{U}^\varepsilon] + (\nabla \phi)^\top \cdot (\mathbf{E}^\varepsilon \cdot \nabla \mathbf{V}^\varepsilon + \mathbf{D}^\varepsilon \mathbf{V}^\varepsilon) \, dx = 0, \\ \int_{\Omega} \psi^\top [\partial_t \mathbf{U}^\varepsilon + \mathbf{L}^\varepsilon \mathbf{U}^\varepsilon - \mathbf{G}^\varepsilon \mathbf{V}^\varepsilon] \, dx = 0, \\ \mathbf{U}^\varepsilon(0, \mathbf{x}) = \mathbf{U}_*(\mathbf{x}) \text{ for all } \mathbf{x} \in \Omega, \end{cases}$$

for a.e.  $t \in (0, T)$ , for all test-functions  $\phi \in H_0^1(\Omega)^N$  and  $\psi \in L^2(\Omega)^N$ .

The existence and uniqueness can only hold when the first equation of  $(\mathbf{P}_w^\varepsilon)$  satisfies all the conditions of Lax-Milgram. The next lemma provides the coercivity condition, while the continuity condition is trivially satisfied.

**Lemma 1.** *Assume assumptions (A1) - (A3) hold, then there exist positive constants  $\tilde{m}_\alpha$ ,  $\tilde{e}_i$ ,  $\tilde{H}$ ,  $\tilde{K}_\alpha$ ,  $\tilde{J}_{i\alpha}$  for  $\alpha \in \{1, \dots, N\}$  and  $i \in \{1, \dots, d\}$  such that the following a-priori estimate holds for a.e.  $t \in (0, T)$ .*

$$\begin{aligned} \sum_{\alpha=1}^N \tilde{m}_\alpha \|\mathbf{V}_\alpha^\varepsilon\|_{L^2(\Omega)}^2 + \sum_{i=1}^d \sum_{\alpha=1}^N \tilde{e}_i \|\partial_{x_i} \mathbf{V}_\alpha^\varepsilon\|_{L^2(\Omega)}^2 \\ \leq \tilde{H} + \sum_{\alpha=1}^N \tilde{K}_\alpha \|\mathbf{U}_\alpha^\varepsilon\|_{L^2(\Omega)}^2 + \sum_{i=1}^d \sum_{\alpha=1}^N \tilde{J}_{i\alpha} \|\partial_{x_i} \mathbf{U}_\alpha^\varepsilon\|_{L^2(\Omega)}^2 \quad (1) \end{aligned}$$

*Proof.* See pages 92, 93 in [9] for proof and relation with parameters of  $(\mathbf{P}_w^\varepsilon)$ .  $\square$

**Theorem 1.** *Assume assumptions (A1) - (A3) hold, then there exists a unique pair  $(\mathbf{U}^\varepsilon, \mathbf{V}^\varepsilon) \in H^1((0, T) \times \Omega)^N \times L^\infty((0, T), H_0^1(\Omega))^N$  such that  $(\mathbf{U}^\varepsilon, \mathbf{V}^\varepsilon)$  is a weak solution to  $(\mathbf{P}_w^\varepsilon)$ .*

*Proof.* Use  $\phi = \mathbf{V}^\varepsilon$  and apply Lemma 1. Then use  $\psi \in \{\mathbf{U}^\varepsilon, \partial_t \mathbf{U}^\varepsilon\}$ . Moreover, apply a gradient to the second equation of  $(\mathbf{P}^\varepsilon)$  and test that equation with  $\nabla \mathbf{U}^\varepsilon$  and  $\partial_t \nabla \mathbf{U}^\varepsilon$ . Application of Young's inequality, use of (1) and application of Gronwall's inequality, see [2, Thm. 1], yields the existence for  $\mathbf{U}^\varepsilon$ . Then Lax-Milgram yields the existence for  $\mathbf{V}^\varepsilon$ . Uniqueness follows from the bilinearity of  $(\mathbf{P}_w^\varepsilon)$ . For more details, see pages 93 and 94 in [9].  $\square$

## 4 Upscaling the system $(\mathbf{P}_w^\varepsilon)$ via two-scale convergence

Based on two-scale convergence, see [1], [5], [7] for details, we obtain the following Lemma ensuring that the weak solution to problem  $(\mathbf{P}_w^\varepsilon)$  has two-scale limits in the limit  $\varepsilon \downarrow 0$ .

**Lemma 2.** *Assume assumptions (A0), (A1), (A2) to hold. For each  $\varepsilon \in (0, \varepsilon_0)$ , let the pair of sequences  $(\mathbf{U}^\varepsilon, \mathbf{V}^\varepsilon) \in H^1((0, T) \times \Omega) \times L^\infty((0, T); H_0^1(\Omega))$  be the unique weak solution to  $(\mathbf{P}_w^\varepsilon)$ . Then this sequence of weak solutions satisfies the estimate*

$\|\mathbf{U}^\varepsilon\|_{H^1((0,T)\times\Omega)^N} + \|\mathbf{V}^\varepsilon\|_{L^\infty((0,T),H_0^1(\Omega))^N} \leq C$ , for all  $\varepsilon \in (0, \varepsilon_0)$  and there exist vector functions

$$\begin{aligned} \mathbf{u} & \text{ in } H^1((0,T)\times\Omega)^N, & \mathcal{U} & \text{ in } H^1((0,T);L^2(\Omega;H_\#^1(Y)/\mathbf{R}))^N, \\ \mathbf{v} & \text{ in } L^\infty((0,T);H_0^1(\Omega))^N, & \mathcal{V} & \text{ in } L^\infty((0,T)\times\Omega;H_\#^1(Y)/\mathbf{R})^N, \end{aligned}$$

and a subsequence  $\varepsilon' \subset \varepsilon$ , for which the following two-scale convergences

$$\begin{aligned} \mathbf{U}^{\varepsilon'} & \xrightarrow{2} \mathbf{u}(t, \mathbf{x}), & \nabla \mathbf{U}^{\varepsilon'} & \xrightarrow{2} \nabla \mathbf{u}(t, \mathbf{x}) + \nabla_{\mathbf{y}} \mathcal{U}(t, \mathbf{x}, \mathbf{y}), \\ \partial_t \mathbf{U}^{\varepsilon'} & \xrightarrow{2} \partial_t \mathbf{u}(t, \mathbf{x}), & \partial_t \nabla \mathbf{U}^{\varepsilon'} & \xrightarrow{2} \partial_t \nabla \mathbf{u}(t, \mathbf{x}) + \partial_t \nabla_{\mathbf{y}} \mathcal{U}(t, \mathbf{x}, \mathbf{y}), \\ \mathbf{V}^{\varepsilon'} & \xrightarrow{2} \mathbf{v}(t, \mathbf{x}), & \nabla \mathbf{V}^{\varepsilon'} & \xrightarrow{2} \nabla \mathbf{v}(t, \mathbf{x}) + \nabla_{\mathbf{y}} \mathcal{V}(t, \mathbf{x}, \mathbf{y}) \end{aligned}$$

hold for a.e.  $t \in (0, T)$ .

*Proof.* See pages 95 and 96 of [9].  $\square$

Using Lemma 2, we upscale  $(\mathbf{P}_w^\varepsilon)$  to  $(\mathbf{P}_w^0)$  via two-scale convergence.

**Theorem 2.** Assume the conditions of Lemma 2 are met. Then the two-scale limits  $\mathbf{u} \in H^1((0, T) \times \Omega)^N$ ,  $\mathcal{U} \in H^1((0, T); L^2(\Omega; H_\#^1(Y)/\mathbf{R}))^N$  and  $\mathbf{v} \in L^\infty((0, T); H_0^1(\Omega))^N$  introduced in Lemma 2 form the weak solution triple to

$$(\mathbf{P}_w^0) \quad \begin{cases} \int_{\Omega} \phi^\top \left[ \overline{\mathbf{M}}\mathbf{v} - \overline{\mathbf{H}} - \overline{\mathbf{K}}\mathbf{u} - \overline{\mathbf{J}} \cdot \nabla \mathbf{u} - \frac{1}{|Y|} \int_Y \mathbf{J} \cdot \nabla_{\mathbf{y}} \mathcal{U} \, d\mathbf{y} \right] \\ \quad + (\nabla \phi)^\top \cdot (\mathbf{E}^* \cdot \nabla \mathbf{v} + \mathbf{D}^* \mathbf{v}) \, d\mathbf{x} = 0, \\ \int_{\Omega} \psi^\top [\partial_t \mathbf{u} + \mathbf{L}\mathbf{u} - \mathbf{G}\mathbf{v}] \, d\mathbf{x} = 0, \\ \int_Y \xi^\top \cdot \nabla_{\mathbf{y}} [\partial_t \mathcal{U} + \mathbf{L}\mathcal{U} - \tilde{\delta}\mathbf{v} - \tilde{\omega} \cdot \nabla \mathbf{v}] \, d\mathbf{y} = 0, \\ \mathbf{u}(0, \mathbf{x}) = \mathbf{U}_*(\mathbf{x}) \quad \text{on } \Omega, \\ \nabla_{\mathbf{y}} \mathcal{U}(0, \mathbf{x}, \mathbf{y}) = \mathbf{0} \quad \text{on } \Omega \times Y, \end{cases}$$

for a.e.  $t \in (0, T)$ , for all test-functions  $\phi \in H_0^1(\Omega)^N$ ,  $\psi \in L^2(\Omega)^N$ , and  $\xi \in H_\#^1(Y)^{d \times N}$ , where the effective coefficients  $\mathbf{E}^*$  and  $\mathbf{D}^*$  are given by

$$\begin{aligned} \mathbf{E}^* &= \frac{1}{|Y|} \int_Y \mathbf{E} \cdot (1 + \nabla_{\mathbf{y}} \mathbf{W}) \, d\mathbf{y}, & \mathbf{D}^* &= \frac{1}{|Y|} \int_Y \mathbf{D} + \mathbf{E} \cdot \nabla_{\mathbf{y}} \delta \, d\mathbf{y}, \\ & \tilde{\delta} = \nabla_{\mathbf{y}} (\mathbf{G}\delta), & \tilde{\omega} &= \nabla_{\mathbf{y}} \mathbf{W} \otimes \mathbf{G}, \end{aligned}$$

and the tensor  $\delta_{\alpha\beta} \in L^\infty((0, T) \times \Omega; H_\#^1(Y)/\mathbf{R})$  and vector  $\mathbf{W}_i \in L^\infty((0, T) \times \Omega; H_\#^1(Y)/\mathbf{R})$  satisfy the cell problems

$$0 = \int_Y \Phi^\top \cdot (\nabla_{\mathbf{y}} \cdot [\mathbf{E} \cdot (1 + \nabla_{\mathbf{y}} \mathbf{W})]) \, d\mathbf{y}, \quad 0 = \int_Y \Psi^\top \cdot (\nabla_{\mathbf{y}} \cdot [\mathbf{D} + \mathbf{E} \cdot \nabla_{\mathbf{y}} \delta]) \, d\mathbf{y}$$

for all  $\Phi \in C_\#(Y)^d$ ,  $\Psi \in C_\#(Y)^{N \times N}$ .

*Proof.* In  $(\mathbf{P}_w^\varepsilon)$ , we choose  $\phi = \phi^\varepsilon = \Phi(t, \mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$  and  $\psi = \psi^\varepsilon = \Psi(t, \mathbf{x}) + \varepsilon\varphi(t, \mathbf{x}, \frac{\mathbf{x}}{\varepsilon})$  for the test-functions  $\Phi \in L^2((0, T); \mathcal{D}(\Omega; C_\#^\infty(Y)))^N$ ,  $\Psi \in L^2((0, T); C_0^\infty(\Omega))^N$  and for  $\varphi \in L^2((0, T); \mathcal{D}(\Omega; C_\#^\infty(Y)))^N$ . Two-scale convergence limits, see [1], [5], [7], and cell-function arguments, see [6], give  $(\mathbf{P}_w^0)$ . Details in pages 97,98 of [9].  $\square$

We have shown that upscaling system  $(\mathbf{P}_w^\varepsilon)$  yields system  $(\mathbf{P}_w^0)$ . This system contains only PDEs with respect to  $(t, \mathbf{x})$ . However, an extra variable  $\nabla_{\mathbf{y}} \mathcal{U}$  was needed. Removing  $\nabla_{\mathbf{y}} \mathcal{U}$  needs the use of continuous semi-group theory, see papers 10 and 14 of [10], for solving the third equation of system  $(\mathbf{P}_w^0)$ . This leads to a non-local-in-time term as a consequence of removing  $\nabla_{\mathbf{y}} \mathcal{U}$ .

## 5 Conclusion

Our main goal of this paper is to show that the spatial-temporal decomposition, as employed in [8], allows for the straightforward upscaling of pseudo-parabolic equations, in specific for system  $(\mathbf{Q}^\varepsilon)$ . The upscaling procedure is here performed using the concept of two-scale convergence as reported in Section 4. Moreover, the decomposition is retained in the upscaled limit. A non-local-in-time term arose when an extra variable was eliminated. The spatial-temporal decoupling showed why this non-local term is non-local in time.

In future research we intend to investigate the applicability of the spatial-temporal decomposition of our pseudo-parabolic system to perforated periodic domains, corrector estimates (convergence speed estimate) and high-contrast situations.

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