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Citation for published version (APA):

Helvoirt, van, J. (2006). *Calculating the hydraulic inductance of a compressor duct*. (DCT rapporten; Vol. 2006.010). Technische Universiteit Eindhoven.

Document status and date:

Published: 01/01/2006

Document Version:

Publisher's PDF, also known as Version of Record (includes final page, issue and volume numbers)

Please check the document version of this publication:

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Calculating the Hydraulic Inductance of a Compressor Duct

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DCT 2006.10

DCT Internal report

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Eindhoven, January, 2006

Abstract

The Greitzer model is a well-known nonlinear model that describes the transient behavior of compression systems. The model is particularly useful for describing the limit cycle oscillations associated with a compressor instability called surge.

One of the important parameters in the model is the so-called hydraulic inductance. With an appropriate choice of this parameter, all the kinetic energy of the flow through the compressor is lumped onto a duct of a certain length and with a constant cross-sectional area. The actual value for the hydraulic inductance is usually determined by tuning the Greitzer model to obtain a good match between measured and simulated surge oscillations.

In this report we propose a different way to determine the hydraulic inductance for a compressor duct. After various geometric simplifications, the governing integral of the cross-sectional duct area along the entire flow path, is calculated directly.

The values for the hydraulic inductance of two compressor test rigs are determined. When comparing the result for one rig with a tuned inductance value, a large difference can be observed. This difference might indicate that not all the relevant dynamic effects are captured by the lumped Greitzer model.

I Introduction

The operating range of turbo compressors is limited towards low mass flows by the occurrence of surge and rotating stall. Surge is an unstable operating mode of a compression system, characterized by large oscillations in compressor flow and pressure rise. Surge reduces compressor performance and the resulting thermal and mechanical loads can cause structural damage.

One of the first nonlinear models of transient compressor behavior was proposed in [1]. This model is capable of describing the limit cycle oscillations in compressor flow and pressure rise that are associated with surge. Although developed for axial compressors, the authors of [2] showed that this nonlinear model was also applicable to centrifugal compressors. To this day, it is the most widely used dynamic model in the field.

The main idea of the approach used in [1] is to associate the kinetic and potential energy of the compressor transients with different components of the compression system. Therefore, in the derivation of the Greitzer model the fluid dynamics in the compressor and the connecting ducts are accounted for by a constant area pipe of a certain length. The pressure rise due to the compressor is represented by an actuator disk. Similarly, the duct in which the throttle resides is modeled by a second constant area pipe and actuator disk.

In the Greitzer model the parameter L/A appears in the momentum equation for both the compressor and throttle ducts. This parameter is usually referred to as the hydraulic inductance. In practice the momentum equation for the throttle duct can usually be neglected, see for example [3, 4]. In contrast, the hydraulic inductance of the compressor duct L_c/A_c plays an important role in describing the dynamic behavior of the compression system.

However, we point out that the parameter L_c/A_c is already a simplification for the actual term in the momentum equation, namely

$$\int_{\text{actual ducting}} \frac{ds}{A(s)} = \left(\frac{L_c}{A_c} \right)_{\text{model}} \quad (1)$$

This relation implies that the actual duct is replaced by a constant area pipe of a certain length to obtain a simple expression for the hydraulic inductance L_c/A_c . However, in practice the area of the compressor duct is not constant, so the corresponding duct length L_c must be determined iteratively.

In order to avoid tuning of the duct length L_c , we propose to calculate the integral of the duct area $A(s)$ along the flow path s directly. Due to the complex three-dimensional geometry of the internals of a centrifugal compressors, we divide the total duct into several sections and apply appropriate assumptions to solve the integral for each of those sections. The method will be evaluated on two different compressor configurations and after a short discussion of the results we finish with some concluding remarks.

2 Calculating the hydraulic inductance

In Figure 1 the cross section is shown for a typical configuration of a centrifugal compressor. From this figure we observe a distinct reduction of the cross-sectional area along the direction of flow. These area changes define the start and end point of the compressor duct. Following the geometry of the compressor internals, a partitioning of the total duct into various elements is suggested, according to Figure 2. We point out that the impeller is subdivided into a curved duct and a radial duct. We will now present analytical approximations of the integral in (1) for each of the simplified geometries and the assumptions that were made during the derivations.

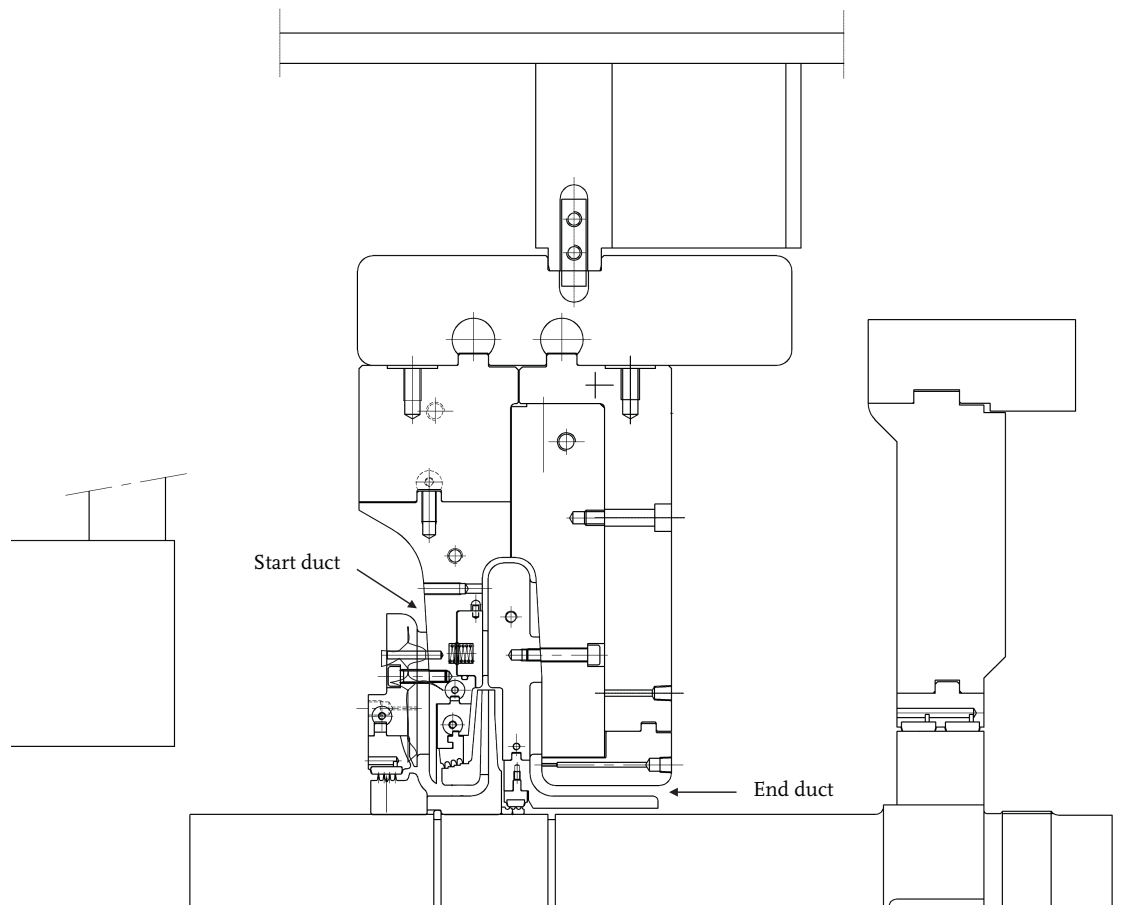


Figure 1: Cross sectional view of a typical configuration for a centrifugal compressor.

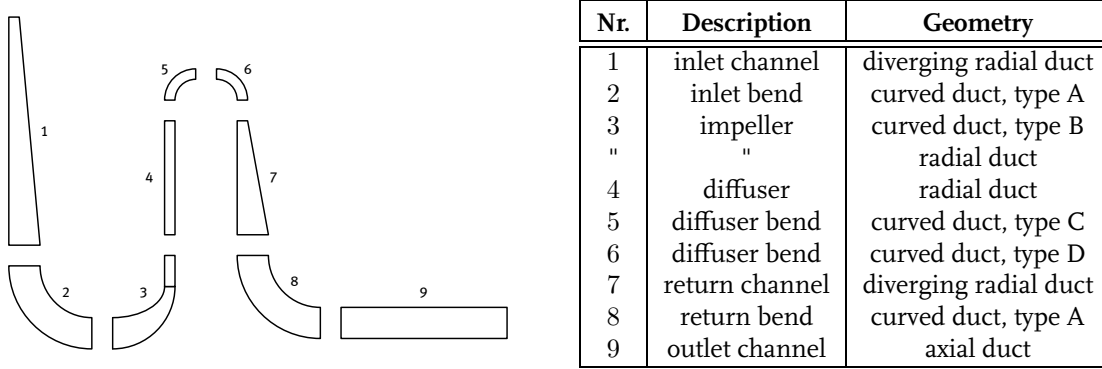


Figure 2: Division of compressor ducting into elements with simple geometry.

2.1 Straight radial ducts

Following the geometry from Figure 3 the following expression for the hydraulic inductance is obtained

$$\int_S \frac{ds}{A(s)} = \int_{y_1}^{y_2} \frac{dy}{2\pi wy} = \begin{cases} \frac{1}{2\pi w} \ln\left(\frac{y_2}{y_1}\right) & \text{for } y_2 > y_1 > 0 \\ -\frac{1}{2\pi w} \ln\left(\frac{y_2}{y_1}\right) & \text{for } y_1 > y_2 > 0 \end{cases} \quad (2)$$

where we assume that $ds = dy$, requiring that the flow through the duct is strictly radial and uniform.

2.2 Diverging radial ducts

Following the geometry from Figure 4 the following expression for the hydraulic inductance is obtained

$$\int_S \frac{ds}{A(s)} = \int_{y_1}^{y_2} \frac{dy}{2\pi w(y)y} = \begin{cases} \frac{1}{2\pi b} \ln\left(\frac{y_2(ay_1+b)}{y_1(ay_2+b)}\right) & \text{for } y_2 w(y_1) > y_1 w(y_2) > 0 \\ -\frac{1}{2\pi b} \ln\left(\frac{y_2(ay_1+b)}{y_1(ay_2+b)}\right) & \text{for } y_1 w(y_2) > y_2 w(y_1) > 0 \end{cases} \quad (3)$$

where we assume that $ds = dy$, requiring that the flow through the duct is strictly radial and uniform. Furthermore, we assume a linearly increasing or decreasing width of the duct, yielding the following expression for $w(y)$

$$w(y) = ay + b = \underbrace{\frac{w_2 - w_1}{y_2 - y_1}}_a y + \underbrace{w_1 - \frac{w_2 - w_1}{y_2 - y_1} y_1}_b \quad (4)$$

2.3 Straight axial ducts

Following the geometry from Figure 5 the following expression for the hydraulic inductance is obtained

$$\int_S \frac{ds}{A(s)} = \int_{x_1}^{x_2} \frac{dx}{\pi(y_1 + y_2)w} = \frac{|x_2 - x_1|}{\pi(y_1 + y_2)w} \quad (5)$$

where we assume that $ds = dx$, requiring that the flow through the duct is strictly axial and uniform.

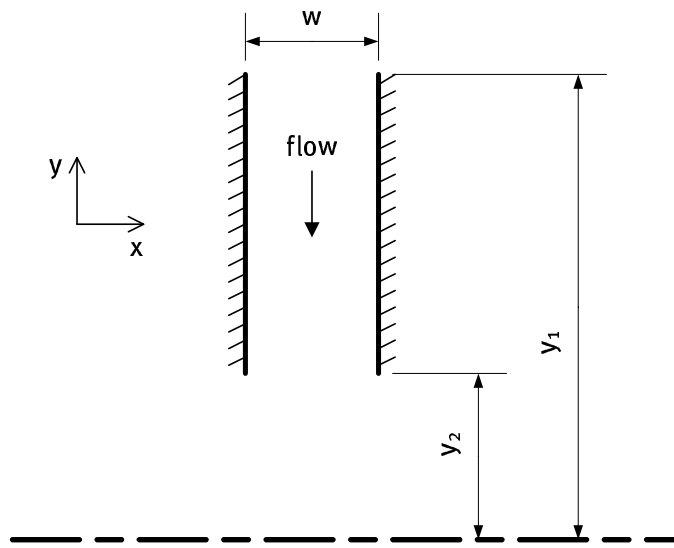


Figure 3: Radial duct geometry.

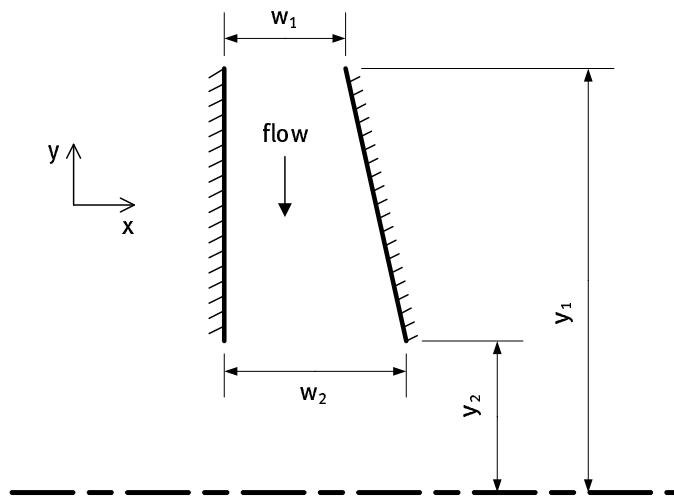


Figure 4: Diverging radial duct geometry.

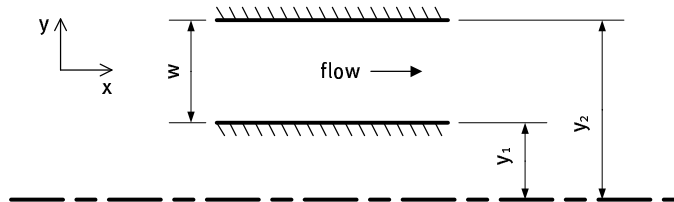


Figure 5: Axial duct geometry.

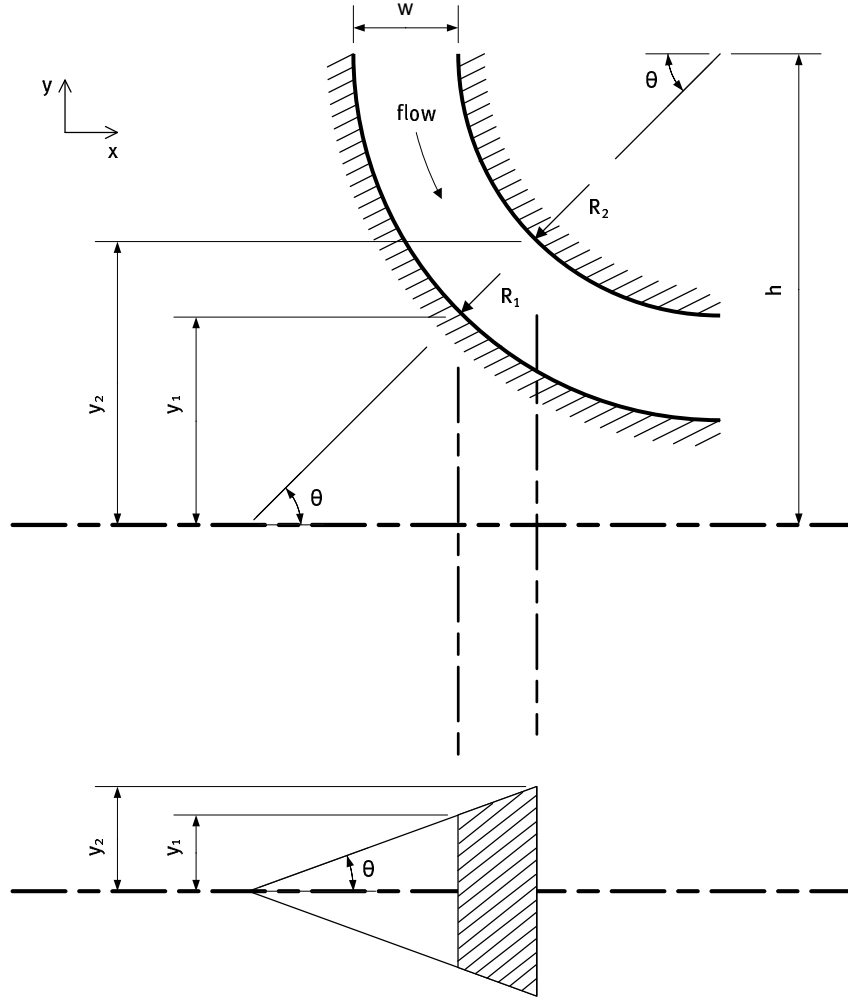


Figure 6: Curved duct geometry, type A.

2.4 Curved ducts

For the various bends in the compressor duct we make use of an auxiliary geometry as shown in Figure 6. From this figure we see that the cross sectional area of the duct at an angle θ is given by the lateral area of the frustum $A(\theta) = \pi w(y_1(\theta) + y_2(\theta))$ with $y_i = h - R_i \sin \theta$, $i = 1, 2$.

Following the geometry from Figure 5 the following expression for the hydraulic inductance is obtained

$$\int_S \frac{ds}{A(s)} = \int_0^\phi \frac{\frac{1}{2}(R_1 + R_2)}{A(\theta)} d\theta = \frac{R_1 + R_2}{\pi w \sqrt{4h^2 - (R_1 + R_2)^2}} \tan^{-1} \left(\frac{-R_1 - R_2 + 2h \tan(\frac{\theta}{2})}{\sqrt{4h^2 - (R_1 + R_2)^2}} \right) \quad (6)$$

where we assume that $ds = \frac{1}{2}(R_1 + R_2)d\theta$, requiring that the flow is uniform and that it follows the centerline of the curved duct from Figure 6. Note that ϕ denotes the angle in rad at the end of the curved duct.

Analogous to this approach, expressions for the curved ducts of type B, C, and D can be obtained. However, note that the resulting expressions are different due to the start and end position of the ducts relative to the flow.

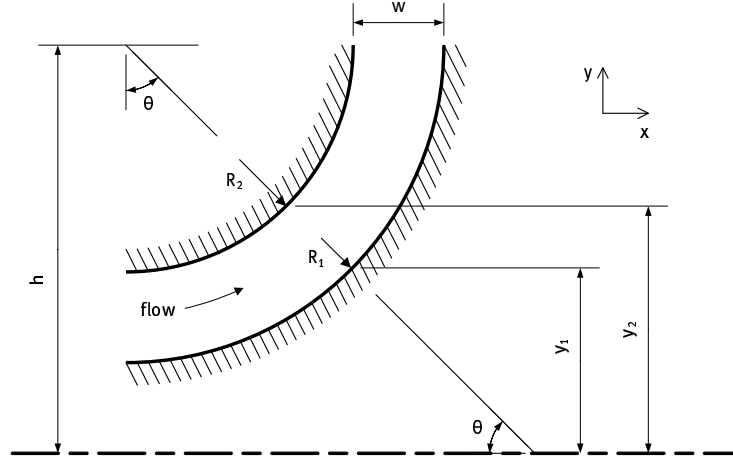


Figure 7: Curved duct geometry, type B.

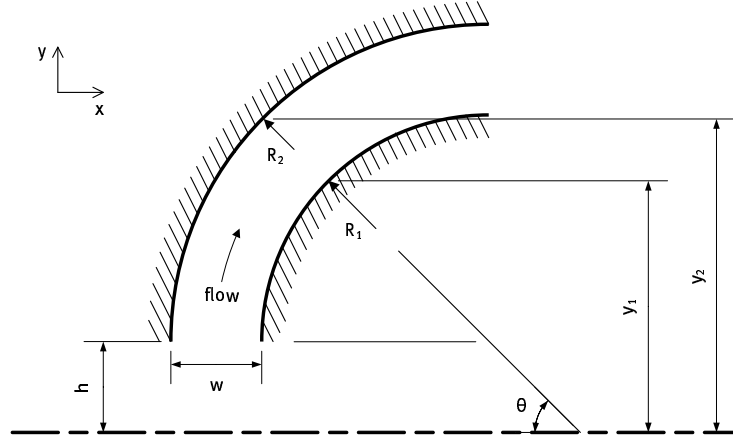


Figure 8: Curved duct geometry, type C.

Following the geometry from Figure 7 the following expression for the hydraulic inductance for a curved duct of type B is obtained

$$\int_S \frac{ds}{A(s)} = \frac{R_1 + R_2}{\pi w \sqrt{(R_1 + R_2)^2 - 4h^2}} \tanh^{-1} \left(\frac{(R_1 + R_2 + 2h) \tan(\frac{\theta}{2})}{\sqrt{(R_1 + R_2)^2 - 4h^2}} \right) \quad (7)$$

using $y_i = h - R_i \cos \theta$, while the hydraulic inductance for a curved duct of type C (see Figure 8) is given by

$$\int_S \frac{ds}{A(s)} = \frac{R_1 + R_2}{\pi w \sqrt{4h^2 - (R_1 + R_2)^2}} \tanh^{-1} \left(\frac{R_1 + R_2 + 2h \tan(\frac{\theta}{2})}{\sqrt{4h^2 - (R_1 + R_2)^2}} \right) \quad (8)$$

using $y_i = h + R_i \sin \theta$. Finally, the hydraulic inductance for a curved duct of type D (see Figure 9) is given by

$$\int_S \frac{ds}{A(s)} = \frac{R_1 + R_2}{\pi w \sqrt{(R_1 + R_2)^2 - 4h^2}} \tanh^{-1} \left(\frac{(R_1 + R_2 - 2h) \tan(\frac{\theta}{2})}{\sqrt{(R_1 + R_2)^2 - 4h^2}} \right) \quad (9)$$

using $y_i = h + R_i \cos \theta$.

Table 1: Hydraulic inductance calculation for both test rigs.

Number	Duct type	L_c/A_c	
		50EB1	65EA1
1	inlet channel	5.62	3.55
2	inlet bend	2.61	2.11
3	impeller bend	2.61	2.11
"	impeller duct	3.37	1.10
4	diffuser	6.44	5.37
5	diffuser bend	1.00	1.38
6	diffuser bend	0.986	1.38
7	return channel	7.68	4.29
8	return bend	2.98	1.86
9	outlet channel	1.99	7.69
sum	total channel	35.3	30.8

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