

# Local recognition of non-incident point-hyperplane graphs

Citation for published version (APA): Cohen, A. M., Cuypers, F. G. M. T., & Gramlich, R. (2002). Local recognition of non-incident point-hyperplane graphs. Technische Universität Darmstadt.

## Document status and date:

Published: 01/01/2002

### Document Version:

Publisher's PDF, also known as Version of Record (includes final page, issue and volume numbers)

## Please check the document version of this publication:

- A submitted manuscript is the version of the article upon submission and before peer-review. There can be important differences between the submitted version and the official published version of record. People interested in the research are advised to contact the author for the final version of the publication, or visit the DOI to the publisher's website.
- The final author version and the galley proof are versions of the publication after peer review.
- The final published version features the final layout of the paper including the volume, issue and page numbers.

Link to publication

### General rights

Copyright and moral rights for the publications made accessible in the public portal are retained by the authors and/or other copyright owners and it is a condition of accessing publications that users recognise and abide by the legal requirements associated with these rights.

- · Users may download and print one copy of any publication from the public portal for the purpose of private study or research.
- You may not further distribute the material or use it for any profit-making activity or commercial gain
  You may freely distribute the URL identifying the publication in the public portal.

If the publication is distributed under the terms of Article 25fa of the Dutch Copyright Act, indicated by the "Taverne" license above, please follow below link for the End User Agreement:

www.tue.nl/taverne

### Take down policy

If you believe that this document breaches copyright please contact us at:

openaccess@tue.nl

providing details and we will investigate your claim.

Download date: 16. Nov. 2023

# TECHNISCHE UNIVERSITÄT DARMSTADT

# Local recognition of non-incident point-hyperplane graphs

Arjeh, M. Cohen, Hans Cuypers, Ralf Gramlich

Preprint Nr. 2248

Oktober 2002

FACHBEREICH MATHEMATIK

# LOCAL RECOGNITION OF NON-INCIDENT POINT-HYPERPLANE GRAPHS

ARJEH M. COHEN, HANS CUYPERS, RALF GRAMLICH

ABSTRACT. Let  $\mathbb P$  be a projective space. By  $\mathbf H(\mathbb P)$  we denote the graph whose vertices are the non-incident point-hyperplane pairs of  $\mathbb P$ , two vertices (p,H) and (q,I) being adjacent if and only if  $p\in I$  and  $q\in H$ . In this paper we give a characterization of the graph  $\mathbf H(\mathbb P)$  (as well as of some related graphs) by its local structure. We apply this result by two characterizations of groups G with  $\mathrm{PSL}_n(\mathbb F) \leq G \leq \mathrm{PGL}_n(\mathbb F)$ , by properties of centralizers of some (generalized) reflections. Here  $\mathbb F$  is the (skew) field of coordinates of  $\mathbb P$ .

## 1. INTRODUCTION

Local recognition of graphs is a problem described, for example, in [2]. The general idea is the following. Choose your favorite graph  $\Delta$  and try to find all connected graphs  $\Gamma$  that are locally  $\Delta$ , i.e., graphs whose induced subgraph on the set of all neighbors of an arbitrary vertex of  $\Gamma$  is isomorphic to  $\Delta$ . One restricts the search to connected graphs, because a graph is locally  $\Delta$  if and only if all of its connected components are locally  $\Delta$ . There has already been done a lot of work in this direction, see, e.g., [1, 6, 7, 8, 10, 11].

Suppose  $\mathbb P$  is a projective space of (projective) dimension n (possibly infinite). Then by  $\mathbf H(\mathbb P)$  we denote the graph with as vertices the non-incident point-hyperplane pairs and with two vertices (p,H) and (q,I), with p,q points and H,I hyperplanes such that  $p \notin H$  and  $q \notin I$ , being adjacent if and only if  $p \in I$  and  $q \in H$ .

For each vertex of the graph  $\mathbf{H}(\mathbb{P})$ , the induced subgraph on the neighbors of this vertex is isomorphic to  $\mathbf{H}(\mathbb{P}_0)$ , where  $\mathbb{P}_0$  is a hyperplane of  $\mathbb{P}$ . In this paper we give a characterization of the graphs  $\mathbf{H}(\mathbb{P})$  by their local structure.

In fact, we consider a slightly larger class of graphs. Let  $\mathbb{H}$  be a subspace of the dual  $\mathbb{P}^{\text{dual}}$  of  $\mathbb{P}$  with the property that the intersection of all the hyperplanes  $H \in \mathbb{H}$  is trivial (we say  $\mathbb{H}$  has a trivial annihilator in  $\mathbb{P}$ ). If  $\mathbb{P}$  is finite-dimensional, then  $\mathbb{H}$  equals  $\mathbb{P}^{\text{dual}}$ , but for infinite dimensional  $\mathbb{P}$  the space  $\mathbb{H}$  can be a proper subspace of  $\mathbb{P}^{\text{dual}}$ . The subgraph  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  of  $\mathbf{H}(\mathbb{P})$  induced on the vertices (p, H) with  $H \in \mathbb{H}$ , has the property that for each vertex v the induced subgraph on the neighbors of v is isomorphic to  $\mathbf{H}(\mathbb{P}_0, \mathbb{H}_0)$  for some hyperplanes  $\mathbb{P}_0$  of  $\mathbb{P}$  and  $\mathbb{H}_0$  of  $\mathbb{H}$ . Indeed, if v = (x, X), then with  $\mathbb{P}_0$  the projective space induced on X and  $\mathbb{H}_0$  the set of hyperplanes K of  $\mathbb{P}_0$  such that the subspace of  $\mathbb{P}$  generated by x and K belongs to  $\mathbb{H}$ , we find the induced subgraph on the neighbors of v to be isomorphic to  $\mathbf{H}(\mathbb{P}_0, \mathbb{H}_0)$ . Moreover, as  $\bigcap_{H \in \mathbb{H}, x \in H} H = \{x\}$ , we have  $\bigcap_{H \in \mathbb{H}_0} H = \emptyset$ . Our main result reads as follows.

<sup>1991</sup> Mathematics Subject Classification. 05C25, 20D06, 20E42, 51E25. Key words and phrases. Graphs, local recognition, groups, reflections.

Theorem 1.1. Let  $\mathbb{P}_0$  be a projective space of dimension at least 3 and  $\mathbb{H}_0$  a subspace of  $\mathbb{P}_0^{\text{dual}}$  with trivial annihilator in  $\mathbb{P}_0$ . Suppose  $\Gamma$  is a connected graph which is locally  $\mathbf{H}(\mathbb{P}_0,\mathbb{H}_0)$ . Then  $\Gamma$  is isomorphic to  $\mathbf{H}(\mathbb{P},\mathbb{H})$  for some projective space  $\mathbb{P}$ and some subspace H of P<sup>dual</sup> with trivial annihilator in P.

The condition  $\dim(\mathbb{P}_0) \geq 3$  in our local recognition result is sharp as is shown by an example in Section 5 of a connected, locally  $\mathbf{H}(\mathbb{P}(\mathbb{F}_2^6))$  graph that is not isomorphic to  $\mathbf{H}(\mathbb{P}(\mathbb{F}_2^4))$ .

Our proof of Theorem 1.1 is partly motivated by the methods developed in [4], where local recognition results are obtained for subgraphs of  $\mathbf{H}(\mathbb{P})$  fixed under

polarities of P.

If  $\mathbb{P}$  is the projective space  $\mathbb{P}(V)$  of some vector space V defined over a field  $\mathbb{F}$  of order at least 3, then the graphs  $\mathbf{H}(\mathbb{P},\mathbb{H})$  can be described as graphs on the reflection tori in subgroups of GL(V). Let V be a left vector space over a (possibly commutative) skew field  $\mathbb{F}$ . For  $g \in \mathrm{GL}(V)$ , we set

$$[V,g]=\{vg-v\mid v\in V\} \quad ext{and} \quad C_V(g)=\{v\in V\mid vg-v=0\},$$

and call these subspaces the center and axis of g. A transformation  $g \in \mathrm{GL}(V)$ satisfying dim([V,g]) = 1 is called a reflection if  $[V,g] \not\subseteq C_V(g)$ . Observe that  $C_V(g)$ 

is a hyperplane if g is a reflection.

If we specify a hyperplane H and a one-dimensional subspace, that is, a projective point, p of V, then by  $T_{p,H}$  we denote the subgroup of GL(V) generated by all  $g \in \mathrm{GL}(V)$  with p = [V, g] and  $H = C_V(g)$ . If  $p \notin H$ , the subgroup  $T_{p,H}$  consists of the identity and all reflections with center p and axis H. The group is isomorphic with  $\mathbb{F}^*$  and is called a reflection torus. All reflection tori in  $\mathrm{GL}(V)$  generate the full finitary general group FGL(V) of V, i.e., the subgroup of GL(V) consisting of all elements  $g \in \mathrm{GL}(V)$  with [V,g] finite dimensional. Below we will describe more examples of groups generated by reflection tori, closely related to the graphs appearing in Theorem 1.1.

Let  $\Phi$  be a subspace of  $V^*$ . By  $R(V,\Phi)$  we denote the subgroup G of  $\mathrm{GL}(V)$ generated by the reflections with center in V and axis in  $\Phi$ . If  $\Phi = V^*$ , then G is equal to the full finitary general linear group FGL(V). If  $\Phi \neq V^*$  but  $\{v \in V \mid$  $v\phi = 0$  for all  $\phi \in \Phi$  = 0 (i.e., the annihilator of  $\Phi$  in V is trivial), then  $R(V,\Phi)$ 

still acts irreducibly on V, see [3].

If  $T_{(p,H)}$  and  $T_{(q,I)}$  are two distinct reflection tori in  $\mathrm{GL}(V)$ , then  $T_{(p,H)}$  and  $T_{(q,I)}$  commute if and only if  $p \in I$  and  $q \in H$ . Hence, if G is one of the groups  $R(V,\Phi)$ , where the annihilator of  $\Phi$  in V is trivial, then the graph with as vertex set the reflection tori in G, two tori being adjacent if and only if they commute, is isomorphic to the graph  $\mathbf{H}(\mathbb{P}(V), \mathbb{P}(\Phi))$ .

If  $\mathcal{C}$  is a conjugacy class of reflections in  $\mathrm{GL}_{n+1}(\mathbb{F})$ , then each reflection torus of  $\mathrm{GL}_{n+1}(\mathbb{F})$  meets  $\mathcal C$  in a unique element. So, the commuting graph on  $\mathcal C$ , i.e., the graph with vertex set C and in which two distinct vertices are adjacent if and only

if they commute, is isomorphic to  $\mathbf{H}_n(\mathbb{F})$ .

In view of these observations we can use Theorem 1.1 in order to locally recognize linear groups. We state two such results. I

**Theorem 1.2.** Let  $n \geq 3$  be finite, and let  $\mathbb{F}$  be a skew field of order  $\geq 3$ . Let Gbe a group with distinct elements x, y and subgroups X, Y such that

- (i)  $C_G(x) = X \times K$  with  $K \cong GL_{n+1}(\mathbb{F})$ ;
- (ii)  $C_G(y) = Y \times J \text{ with } J \cong GL_{n+1}(\mathbb{F});$

(iii) there exists an element in  $J \cap K$  that is a reflection of both J and K conjugate to x in J and y in K, respectively.

If  $G = \langle J, K \rangle$ , then (up to isomorphism)  $PSL_{n+2}(\mathbb{F}) \leq G/Z(G) \leq PGL_{n+2}(\mathbb{F})$ .

Our second applications deals with finite groups. Let n be finite and  $\mathbb{F}$  a field. An element r of  $\mathrm{SL}_{n+1}(\mathbb{F})$  is called a generalized reflection if, up to a scalar factor, r is a reflection in  $\mathrm{GL}_{n+1}(\mathbb{F})$ , i.e., if there exists a reflection in  $rZ(\mathrm{GL}_{n+1}(\mathbb{F}))$ . The axis and center of a generalized reflection are, by definition, its eigenspaces of dimension n and 1, respectively, in the natural module. They are the axis and center of the unique reflection in  $rZ(\mathrm{GL}_{n+1}(\mathbb{F}))$ . The group generated by all generalized reflections with a given axis and center is called a generalized reflection torus and is isomorphic to  $\mathbb{F}^*/\langle \lambda \in \mathbb{F}^* \mid \lambda^{n+1} = 1 \rangle$ .

With this notion we have the following result for finite groups.

**Theorem 1.3.** Let  $n \geq 3$  be finite, and let  $\mathbb{F}$  be a finite field of order  $q \geq 3$ . Let p be a prime dividing q-1. Let G be a group with distinct elements x, y of order p such that

- (i)  $C_G(x)$  contains a characteristic subgroup K with  $K \cong \mathrm{SL}_{n+1}(\mathbb{F})$ ;
- (ii)  $C_G(y)$  contains a characteristic subgroup J with  $J \cong \operatorname{SL}_{n+1}(\mathbb{F})$ ;
- (iii) there exists an element z in  $J \cap K$  conjugate to x in J and y in K, respectively. Moreover, z is a generalized reflection of both K and J.

If  $G = \langle J, K \rangle$ , then  $G/Z(G) \cong PSL_{n+2}(\mathbb{F})$ .

The latter theorem is the kind of result that is useful in the classification of finite simple groups in that a quasi-simple group is recognized from a component in the centralizer of an element about which some fusion information is given.

The remainder of this paper is organized as follows. In the next two sections we derive various properties of the graphs  $\mathbf{H}(\mathbb{P},\mathbb{H})$ . In particular, we show that both  $\mathbb{P}$  and  $\mathbb{H}$  can be recovered from the graph  $\mathbf{H}(\mathbb{P},\mathbb{H})$ . As a consequence we are able to determine the full automorphism group of  $\mathbf{H}(\mathbb{P},\mathbb{H})$ . Then in Section 4 we prove Theorem 1.1. As mentioned before, in Section 5 a family of graphs which are locally  $\mathbf{H}(\mathbb{P}(\mathbb{F}_2^6))$  is discussed and finally in Section 6 the two group-theoretical applications, Theorem 1.2 and 1.3, of Theorem 1.1 are discussed.

Acknowledgment. The authors want to thank Andries Brouwer, Richard Lyons, Sergey Shpectorov and Ronald Solomon for various helpful remarks concerning the topics of this paper. An earlier version of this paper forms part of the PhD thesis of the last author, see [5].

### 2. The point-hyperplane graph

**Definition 2.1.** Consider a projective space  $\mathbb{P}$  and a subspace  $\mathbb{H}$  of the dual  $\mathbb{P}^{\text{dual}}$  of  $\mathbb{P}$  with  $\bigcap_{H \in \mathbb{H}} H = \emptyset$ . The *point-hyperplane graph*  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  is the graph whose vertices are the non-incident point-hyperplane pairs of  $\mathbb{P}$  with the hyperplanes in  $\mathbb{H}$ , in which a vertex (a, A) is adjacent to another vertex (b, B) (in symbols,  $(a, A) \perp (b, B)$ ) if and only if  $a \in B$  and  $b \in A$ .

By definition, we have  $\mathbf{x} \not\perp \mathbf{x}$ , so the perp  $\mathbf{x}^{\perp}$  of  $\mathbf{x}$  of all vertices of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  in  $\perp$  relation to  $\mathbf{x}$  is the set of vertices in  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  at distance one from  $\mathbf{x}$ . Moreover, for a set X of vertices, we define the perp of X as  $X^{\perp} := \bigcap_{\mathbf{x} \in X} \mathbf{x}^{\perp}$  with the understanding that  $\emptyset^{\perp} = \mathbf{H}(\mathbb{P}, \mathbb{H})$ . The double perp of X is  $X^{\perp \perp} := (X^{\perp})^{\perp}$ .

The graph  $\mathbf{H}(\mathbb{P}, \mathbb{P}^{\text{dual}})$  is also denoted by  $\mathbf{H}(\mathbb{P})$ . Moreover, if  $\mathbb{P} = \mathbb{P}(V)$  for some (n+1)-dimensional vector space V over a (skew) field  $\mathbb{F}$ , then we also write  $\mathbf{H}_n(\mathbb{F})$  for  $\mathbf{H}(\mathbb{P})$ . If the field  $\mathbb{F}$  is finite of order q, then we write  $\mathbf{H}_n(q)$ . Finally, if the field  $\mathbb{F}$  is irrelevant, then we also write  $\mathbf{H}_n$  instead of  $\mathbf{H}_n(\mathbb{F})$ .

Let P be a projective space and H a subspace of the dual of P such that the intersection over all hyperplanes in  $\mathbb H$  is empty. A point p of the projective space  $\mathbb{P}=(\mathcal{P},\mathcal{L})$  determines the set of vertices  $v_p=\{(x,X)\in \mathbf{H}(\mathbb{P},\mathbb{H})\mid x=p\}$  of the graph  $\mathbf{H}(\mathbb{P},\mathbb{H})$ . A line l of  $\mathbb{P}$  determines the union  $v_l$  of all sets  $v_p$  of vertices for  $p \in l$ . Clearly the map  $v: \mathcal{P} \cup \mathcal{L} \to 2^{\mathbf{H}(\mathbb{P}, \mathbb{H})}: x \mapsto v_x$  is injective, and  $p \in l$  if and only if  $v_p \subset v_l$ , so we can identify the projective space with its image under vin the collection of all subsets of the vertex set of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . We shall refer to this image in  $2^{\mathbf{H}(\mathbb{P},\mathbb{H})}$  as the exterior projective space on  $\mathbf{H}(\mathbb{P},\mathbb{H})$ . Similarly, one can map points  $\Pi$  and lines  $\Lambda$  of  $\mathbb H$  onto subsets of vertices of  $\mathbf H(\mathbb P,\mathbb H)$  of the form  $w_\Pi=$  $\{(x,X)\in \mathbf{H}(\mathbb{P},\mathbb{H})\mid X=\Pi\}$  and  $w_{\Lambda}=igcup_{\Pi\supset\Lambda}w_{\Pi}$  for  $\Pi$  running over all points of  $\mathbb{P}^{\text{dual}}$  containing  $\Lambda$ . This gives rise to the dual exterior projective space on  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . The subsets  $v_p$ ,  $v_l$ ,  $w_{\Lambda}$  and  $w_{\Pi}$  so obtained are called exterior points, exterior lines, exterior hyperlines, and exterior hyperplanes of  $\mathbf{H}(\mathbb{P},\mathbb{H})$ , respectively. Note that, if the projective space  $\mathbb P$  is isomorphic to  $\mathbb H$ , there is an automorphism of  $\mathbf H(\mathbb P,\mathbb H)$ mapping the image under v onto the image under w. (If  $\pi$  is an isomorphism from  $\mathbb{P}$  to  $\mathbb{H}$ , then  $(x,X)\mapsto (\pi(X),\pi(x))$  is an automorphism of  $\mathbf{H}(\mathbb{P},\mathbb{H})$  as required.) Also, if P is a subspace of Hdual with trivial annihilator in H (in particular, if  $\mathbb P$  and  $\mathbb H$  have the same finite dimension), then  $\mathbf H(\mathbb P,\mathbb H))\cong \mathbf H(\mathbb H,\mathbb P)$  by the map  $(x,X)\mapsto (X,x)$ . So, in general it will not be possible to distinguish exterior points from exterior hyperplanes if one tries to reconstruct the projective space from the graph. Another useful observation is that the exterior points partition the vertex set of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . In other words, each vertex of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  belongs to a unique exterior point. The same holds for exterior hyperplanes.

One of our goals is to characterize the graph  $\mathbf{H}(\mathbb{P},\mathbb{H})$  by its local structure. In this light the following two observations are important.

**Proposition 2.2.** Let  $\mathbb{P}$  have dimension at least one. The graph  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  is locally  $\mathbf{H}(\mathbb{P}_0, \mathbb{H}_0)$  for some hyperplanes  $\mathbb{P}_0$  of  $\mathbb{P}$  and  $\mathbb{H}_0$  of  $\mathbb{H}$ .

*Proof.* Let  $\mathbf{x} = (x, X)$  be a vertex of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . Identify X with  $\mathbb{P}_0$ . For any vertex  $\mathbf{y} = (y, Y)$  adjacent to  $\mathbf{x}$ , we have  $x \in Y$ ,  $y \in X \setminus Y$ , and  $X \cap Y$  a hyperplane in both X and Y, so  $(y, X \cap Y)$  belongs to  $\mathbf{H}(X)$ . We can identify the space of all hyperplanes of the form  $X \cap Y$  of X where  $x \in Y \in \mathbb{H}$  with a hyperplane  $\mathbb{H}_0$  of  $\mathbb{H}$ . Hence,  $(y, X \cap Y)$  belongs to  $\mathbf{H}(\mathbb{P}_0, \mathbb{H}_0)$ .

Conversely, for any vertex of  $\mathbf{H}(\mathbb{P}_0, \mathbb{H}_0)$ , i.e., for any non-incident pair (z, Z) consisting of a point z and a hyperline Z of  $\mathbb{P}$  with  $z \in X$ ,  $Z \subseteq X$ , the pair

 $(z,\langle Z,x\rangle)$  is a vertex of  $\mathbf{x}^{\perp}$ . (Indeed,  $z\not\in\langle Z,x\rangle$ , since  $x\not\in X$ .)

Clearly, the maps  $(y,Y)\mapsto (y,X\cap Y)$  and  $(z,Z)\mapsto (z,\langle Z,x\rangle)$  are each other's inverses. Moreover, the maps preserve adjacency and the proposition follows.

**Proposition 2.3.**  $\mathbf{H}_0$  consists of precisely one point;  $\mathbf{H}_1$  is the disjoint union of cliques of size two; the diameter of  $\mathbf{H}_2$  equals three; the diameter of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ , where  $\dim(\mathbb{P}) \geq 3$ , equals two. In particular,  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  is connected for  $\dim(\mathbb{P}) \geq 2$ .

*Proof.* The statements about  $\mathbf{H}_0$  and  $\mathbf{H}_1$  are obvious. Let  $\mathbf{x}=(x,X), \mathbf{y}=(y,Y)$  be two non-adjacent vertices of  $\mathbf{H}_2$ . The intersection  $X \cap Y$  is a point or a line, and

xy is a point or a line. The vertices x and y have a common neighbor, i.e., they are at distance two, if and only if  $X \cap Y \not\subseteq xy$ . If  $X \cap Y \subseteq xy$ , however, it is easily seen, that they are at distance three. Indeed, choose  $a \in X \setminus \{y\}$  and  $b \in Y \setminus \{x\}$  with  $ay \not\ni b$  and  $bx \not\ni a$ . Then (x, X), (a, bx), (b, ay), (y, Y) establishes a path of length three.

Now let  $\mathbf{x} = (x, X)$ ,  $\mathbf{y} = (y, Y)$  be two non-adjacent vertices of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ , where  $\dim(\mathbb{P}) \geq 3$ . The intersection  $X \cap Y$  contains a line. Since  $x \notin X$  and  $y \notin Y$ , we find a point  $z \in X \cap Y$  and a hyperplane  $Z \supseteq xy$  with  $z \notin Z$  and, thus, a vertex (z, Z) adjacent to both  $\mathbf{x}$  and  $\mathbf{y}$ .

Our first main result will be a reconstruction theorem of the projective space from graphs isomorphic to the point-hyperplane graph  $\mathbf{H} = \mathbf{H}(\mathbb{P}, \mathbb{H})$  without making use of the coordinates, see the next section. This goal will be achieved by the study of double perps of two vertices, i.e., subsets of  $\mathbf{H} = \mathbf{H}(\mathbb{P}, \mathbb{H})$  of the form  $\{\mathbf{x}, \mathbf{y}\}^{\perp \perp}$ . By n we denote the dimension of  $\mathbb{P}$ .

Lemma 2.4. Let  $\mathbf{x} = (x, X)$ ,  $\mathbf{y} = (y, Y)$  be distinct vertices of  $\mathbf{H}$  with  $\{\mathbf{x}, \mathbf{y}\}^{\perp} \neq \emptyset$ . Then the double perp  $\{\mathbf{x}, \mathbf{y}\}^{\perp \perp}$  equals the set of vertices  $\mathbf{z} = (z, Z)$  of  $\mathbf{H}$  with  $z \in xy$  and  $Z \supseteq X \cap Y$ .

Proof. Distinct vertices with non-empty perp only exist for  $n \geq 2$ . The vertices of  $\{\mathbf{x}, \mathbf{y}\}^{\perp}$  are precisely the non-incident point-hyperplane pairs (p, H) with  $p \in X \cap Y$  and  $H \supset xy$ . Let  $\{(p_i, H_i) \in \{\mathbf{x}, \mathbf{y}\}^{\perp} \mid i \in I\}$  be the set of all these vertices, indexed by some set I. Now  $\{\mathbf{x}, \mathbf{y}\}^{\perp \perp} = (\{\mathbf{x}, \mathbf{y}\}^{\perp})^{\perp}$  consists of precisely those vertices  $(z, Z) \in \mathbf{H}$  with  $z \in \bigcap_{i \in I} H_i$  and  $Z \supset \langle (p_i)_{i \in I} \rangle$ . But since  $\{\mathbf{x}, \mathbf{y}\}^{\perp} \neq \emptyset$ , we have  $\bigcap_{i \in I} H_i = xy$  and  $\langle (p_i)_{i \in I} \rangle = X \cap Y$ , thus proving the claim.

In order to recover the projective spaces  $\mathbb{P}$  and  $\mathbb{H}$  from the information contained in a graph  $\Gamma \stackrel{\phi}{\cong} \mathbf{H}$ , we have to recognize vertices  $\mathbf{x}$ ,  $\mathbf{y}$  of  $\Gamma$  with x=y or, dually, X=Y, if  $\phi(\mathbf{x})=(x,X)$ ,  $\phi(\mathbf{y})=(y,Y)$ . Clearly, x=y and X=Y if and only if the vertices  $\mathbf{x}$ ,  $\mathbf{y}$  are equal. To recognize the other cases, we make use of the following definition and lemma.

Recall that the *(projective)* codimension of a subspace X of a projective space  $\mathbb{P}$  is the number of elements in a maximal chain of proper inclusions of subspaces properly containing X and properly contained in  $\mathbb{P}$ . For example, the codimension of a hyperplane of  $\mathbb{P}$  equals 0.

**Definition 2.5.** Let  $n \geq 2$ . Vertices  $\mathbf{x} = (x, X)$ ,  $\mathbf{y} = (y, Y)$  of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  are in relative position (i, j) if

$$i = \dim \langle x, y \rangle$$
 and  $j = \operatorname{codim}(X \cap Y)$ 

where dim denotes the projective dimension and codim the projective codimension. Note that  $i, j \in \{0, 1\}$ .

Lemma 2.6. Let  $n \geq 2$ , and let  $x, y \in H$ . Then the following assertions hold.

- (i) The vertices x and y are in relative position (0,0) if and only if they are equal.
- (ii) The vertices x and y are in relative position (0,1) or (1,0) if and only if they are distinct and the double perp  $\{x,y\}^{\perp\perp}$  is minimal with respect to containment, i.e., it does not contain two vertices with a non-empty strictly smaller double perp.

(iii) The vertices  $\mathbf{x}$  and  $\mathbf{y}$  are in relative position (1,1) if and only if they are distinct and the double perp  $\{\mathbf{x},\mathbf{y}\}^{\perp\perp}$  is not minimal.

Proof. Statement (i) is obvious. Suppose x and y are in relative position (0,1). Then  $\{x,y\}^{\perp} \neq \emptyset$  (since  $n \geq 2$ ), and we can apply Lemma 2.4. We obtain  $\{x,y\}^{\perp\perp} = \{(z,Z) \in \mathbf{H} \mid z = x = y, Z \supseteq X \cap Y\}$ , whence any pair of distinct vertices contained in  $\{x,y\}^{\perp\perp}$  is in relative position (0,1) and gives rise to the same double perp. Symmetry handles the case (1,0). If x and y are in relative position (1,1) and  $\{x,y\}^{\perp} = \emptyset$ , then  $\{x,y\}^{\perp\perp} = \mathbf{H}$ , which is clearly not minimal. So let us assume  $\{x,y\}^{\perp} \neq \emptyset$ . Again by Lemma 2.4, we have  $\{x,y\}^{\perp\perp} = \{(z,Z) \in \mathbf{H} \mid z \in xy, Z \supseteq X \cap Y\}$ . This double perp contains a vertex that is at relative position (0,1) to x, and we obtain a double perp strictly contained in  $\{x,y\}^{\perp\perp}$ . Statements (ii) and (iii) now follow from the fact that distinct vertices  $\mathbf{x} = (x,X)$  and  $\mathbf{y} = (y,Y)$  are in relative position (0,1), (1,0), or (1,1).

We conclude this section with a lemma that will be needed later.

**Lemma 2.7.** Let  $\mathbf{x} = (x, X)$  and  $\mathbf{y} = (y, Y)$  be two adjacent vertices in  $\mathbf{H}$ . If  $\mathbf{x}$  is adjacent to a vertex  $(z, Z_1)$  and  $\mathbf{y}$  adjacent to a vertex  $(z, Z_2)$ , then there exists a vertex  $(z, Z_3)$  adjacent to both  $\mathbf{x}$  and  $\mathbf{y}$ .

*Proof.* The statement of the lemma is empty for n < 2, and we can assume  $n \ge 2$ . We have  $z \in X \cap Y$ . Since x and y are adjacent,  $x \in Y$  and  $y \in X$  are distinct and the line xy does not contain z. Hence the choice of a hyperplane  $Z_3$  that contains xy and does not contain z is possible, and we have found a vertex  $(z, Z_3)$  adjacent to both x and y.

## 3. RECONSTRUCTION OF THE PROJECTIVE SPACE

This section will concentrate on the reconstruction of the projective spaces  $\mathbb P$  and  $\mathbb H$  from a graph  $\Gamma$  isomorphic to  $\mathbf H(\mathbb P,\mathbb H)$ . Abusing notation to some extent, we will sometimes speak of relative positions on  $\Gamma$ , but only if we have fixed a particular isomorphism  $\Gamma \cong \mathbf H(\mathbb P,\mathbb H)$ . Throughout the whole section, let  $n=\dim(\mathbb P)\geq 2$ . Furthermore, let  $\mathbb F$  be a division ring and  $\Gamma \cong \mathbf H=\mathbf H(\mathbb P,\mathbb H)$ .

**Definition 3.1.** Let  $\mathbf{x}$ ,  $\mathbf{y}$  be vertices of  $\Gamma$ . Write  $\mathbf{x} \approx \mathbf{y}$  to denote that  $\mathbf{x}$ ,  $\mathbf{y}$  are equal or the double perp  $\{\mathbf{x},\mathbf{y}\}^{\perp\perp}$  is minimal with respect to inclusion (in the class of double perps  $\{\mathbf{u},\mathbf{v}\}^{\perp\perp}$  for vertices  $\mathbf{u}$ ,  $\mathbf{v}$  with  $\mathbf{u} \neq \mathbf{v}$ ).

For a fixed isomorphism  $\Gamma\cong H$  the relation  $\approx$  coincides with the relation 'being equal or in relative position (1,0) or (0,1)' by Lemma 2.6(ii). What remains is the problem of distinguishing the dual cases (0,1) and (1,0).

**Lemma 3.2.** On the vertex set of  $\Gamma$ , there are unique equivalence relations  $\approx^p$  and  $\approx^h$  such that  $\approx$  equals  $\approx^p \cup \approx^h$  and  $\approx^p \cap \approx^h$  is the identity relation. Moreover, for a fixed isomorphism  $\Gamma \cong \mathbf{H}_n$ , we either have

•  $\approx^p$  is the relation being equal or in relative position (0,1), and  $\approx^h$  is the relation being equal or in relative position (1,0), or

•  $\approx^p$  is the relation 'being equal or in relative position (1,0)', and  $\approx^h$  is the relation 'being equal or in relative position (0,1)'.

In other words, for a fixed isomorphism  $\Gamma \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$  and up to interchanging  $\approx^p$  and  $\approx^h$ , we may assume that  $\approx^p$  stands for being equal or in relative position (0,1) and  $\approx^h$  stands for being equal or in relative position (1,0).

Proof. As we have noticed after Definition 3.1, vertices  $\mathbf{x}$ ,  $\mathbf{y}$  of  $\Gamma$  are in relation  $\approx$  if and only if their images (x,X) and (y,Y) in  $\mathbf{H}$  are equal or in relative positions (0,1) or (1,0). Let us consider equivalence relations that are subrelations of  $\approx$ . Obviously, the identity relation is an equivalence relation. Moreover, the relation 'equal or in relative position (0,1)' and the relation 'equal or in relative position (1,0)' are equivalence relations. Now let us assume we have vertices  $\mathbf{x}=(x,X)$ ,  $\mathbf{y}=(y,Y)$ ,  $\mathbf{z}=(z,Z)$  of  $\Gamma\cong\mathbf{H}$  such that  $\mathbf{x}$ ,  $\mathbf{y}$  are in relative position (0,1) and  $\mathbf{x}$ ,  $\mathbf{z}$  are in relative position (1,0). Then  $y\neq z$  and  $y\neq Z$  and y, z cannot be in relative position (0,1) or (1,0). Consequently, if we want to find two subequivalence relations  $\approx^p$  and  $\approx^h$  of  $\approx$  whose union equals  $\approx$ , then either of  $\approx^p$  and  $\approx^h$  has to be a subrelation of the relation 'equal or in relative position (0,1)' or of the relation 'equal or in relative position (0,1)'. The lemma is proved.

Convention 3.3. From now on, we will always assume that, as soon as we fix an isomorphism  $\Gamma \cong \mathbf{H}$ , the relation  $\approx^p$  corresponds to 'equal or in relative position (0,1)'.

**Definition 3.4.** Let x be a vertex of  $\Gamma$ . With  $\approx^p$  and  $\approx^h$  as in Lemma 3.2, we shall write  $[\mathbf{x}]^p$  to denote the equivalence class of  $\approx^p$  containing x, and similarly we shall write  $[\mathbf{x}]^h$  to denote the equivalence class of  $\approx^h$  containing x. We shall refer to  $[\mathbf{x}]^p$  as the *interior point* on x and to  $[\mathbf{x}]^h$  as the *interior hyperplane* on x.

**Lemma 3.5.** For a fixed isomorphism  $\Gamma \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$ , an interior point of  $\Gamma$  is the image of an exterior point of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  under this isomorphism, and vice versa. The same correspondence exists between interior hyperplanes of  $\Gamma$  and exterior hyperplanes of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ .

Proof. This is direct from the above.

Note that an exterior point and an exterior hyperplane of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  are disjoint if and only if the corresponding point and hyperplane of  $\mathbb{P}_n(\mathbb{F})$  are incident. The above lemma motivates us to call a pair (p, H) of an interior point and an interior hyperplane of  $\Gamma$  incident if and only if  $p \cap H = \emptyset$ . This enables us to define interior lines.

**Definition 3.6.** Let p and q be distinct interior points of  $\Gamma$ . The *interior line l* of  $\Gamma$  spanned by p and q is the union of all interior points disjoint from every interior hyperplane disjoint from both p and q. In other words, the interior line pq consists of exactly those interior points which are incident with every interior hyperplane incident with both p and q.

Dually, one can define the *interior hyperline* spanned by distinct interior hyperplanes H and I as the union of all interior hyperplanes disjoint from every interior point disjoint from both H and I.

**Lemma 3.7.** For a fixed isomorphism  $\Gamma \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$ , each interior line of  $\Gamma$  is the image of an exterior line of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  under this isomorphism, and vice versa. The analogue holds for interior hyperlines.

Proof. The proof is straightforward.

The geometry  $(\mathcal{P}, \mathcal{L}, \subset)$  on  $\Gamma$  where  $\mathcal{P}$  is the set of interior points of  $\Gamma$  and  $\mathcal{L}$  is the set of interior lines of  $\Gamma$  is called the *interior projective space on*  $\Gamma$ . By Lemma 3.5 and Lemma 3.7, this interior projective space is isomorphic to the exterior projective space on  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . Proceeding with  $\approx^h$  as we did for  $\approx^p$ , the same holds for the dual of the interior projective space on  $\Gamma$ . We summarize the findings in the following proposition.

**Proposition 3.8.** Let  $n \geq 2$ . Up to interchanging  $\approx^p$  and  $\approx^h$  every isomorphism  $\Gamma \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$  induces an isomorphism between the interior projective space on  $\Gamma$  and the exterior projective space on  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . The analogue holds for the dual interior projective space on  $\Gamma$ .

Corollary 3.9. Let  $n \geq 2$ , and let  $\Gamma$  be isomorphic to  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . Then the interior projective space on  $\Gamma$  is isomorphic to  $\mathbb{P}$  or  $\mathbb{H}$ .

Corollary 3.10. Let  $n \geq 2$ , and let  $\Gamma$  be isomorphic to  $\mathbf{H}(\mathbb{P})$ . If  $\mathbb{P}$  and  $\mathbb{P}^{\text{dual}}$  are isomorphic, then the automorphism group of  $\Gamma$  is of the form  $\text{Aut}(\mathbb{P})$ .2. Otherwise, it is isomorphic to  $\text{Aut}(\mathbb{P})$ .

*Proof.* Indeed, every automorphism of  $\mathbb P$  induces an automorphism of  $\Gamma$ . Conversely, every automorphism of  $\Gamma$  that preserves the interior projective space gives rise to a unique automorphism of  $\mathbb P$ , by the theorem. Moreover, every automorphism of  $\Gamma$  either preserves the interior projective space or maps it onto the dual interior projective space, again by the theorem. Finally, an outer automorphism is induced on  $\Gamma$  by the map  $(p, H) \mapsto (\delta(H), \delta(p))$  for a duality  $\delta$  of the projective space, and the map  $(p, H) \mapsto (\delta^2(p), \delta^2(H))$  preserves the interior projective space on  $\Gamma$ .  $\square$ 

Remark 3.11. Now might be an appropriate moment to address the problem of duality. Although, by Convention 3.3, as soon as we fix an isomorphism  $\Gamma \cong \mathbf{H}$ , we also choose the equivalence relation  $\approx^p$  to correspond to the relation 'equal or in relative position (0,1)' of  $\mathbf{H}$ , there is a subtle problem—mainly of notation—coming with this: Suppose  $\Gamma \cong \mathbf{H}_n(\mathbb{F})$  with  $\mathbb{F} \not\cong \mathbb{F}^{\text{opp}}$ . Then, by the convention, the interior projective space on  $\Gamma$  will always be isomorphic to  $\mathbb{P}_n(\mathbb{F})$ . If one wants the interior projective space to be isomorphic to  $\mathbb{P}_n(\mathbb{F})^{\text{dual}}$ , then one will have to fix an isomorphism  $\Gamma \cong \mathbf{H}_n(\mathbb{F}^{\text{opp}})$ , although  $\mathbf{H}_n(\mathbb{F}) \cong \mathbf{H}_n(\mathbb{F}^{\text{opp}})$  by means of the map  $(p,H) \mapsto (H,p)$ . The reason for this is that we have defined the graph  $\mathbf{H}_n(\mathbb{F})$  as the point-hyperplane graph of the space  $\mathbb{P}_n(\mathbb{F})$ , which by Convention 3.3 determines the isomorphism class of the interior projective space on  $\Gamma$ .

The remainder of this section serves as a collection of results to be used later on. First comes a useful result on subspaces of the interior projective space of  $\Gamma$ .

**Lemma 3.12.** Let U be a finite dimensional subspace of the interior projective space on  $\Gamma$ . For any projective basis of U there exists a clique of vertices in  $\Gamma$  such that the interior points containing these vertices are the basis elements.

*Proof.* Fix an isomorphism  $\phi: \Gamma \to \mathbf{H}(\mathbb{P}, \mathbb{H})$ . By Proposition 3.8, we can as well argue with exterior points of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . Let  $x_i$ , for i = 1, ..., m, be exterior points forming a (projective) basis for  $\phi(U)$ . Let K be a complement to  $\phi(U)$  in  $\mathbb{P}$ , which is the intersection of hyperplanes in  $\mathbb{H}$ . Notice that such subspace K exists as  $\bigcap_{H \in \mathbb{H}} H$  is empty. Moreover, as K has finite codimension in V, all

hyperplanes of V containing K are in  $\mathbb{H}$ . If for each  $i \in \{1, ..., m\}$  we have  $x_i = \{(p_i, H) \in \mathbf{H}(\mathbb{P}, \mathbb{H}) \mid H \in \mathbb{H}\}$ , then the vertices  $(p_i, \langle K, \{p_j \mid j \in \{1, ..., m\} \setminus \{i\}\})) \in x_i$ , with i = 1, ..., m, form the clique we are looking for.

Notation 3.13. Let  $n \geq 3$ . For a vertex x of  $\Gamma \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$ , we write  $\approx_{\mathbf{x}}$  for the relation  $\approx$  defined on  $\mathbf{x}^{\perp}$  (bear in mind that the latter is isomorphic to  $\mathbf{H}(\mathbb{P}_0, \mathbb{H}_0)$  by Proposition 2.2, where  $\mathbb{P}_0$  and  $\mathbb{H}_0$  are hyperplanes of  $\mathbb{P}$  and  $\mathbb{H}$ , respectively).

**Lemma 3.14.** Let  $n \geq 3$ . Let x be a vertex of  $\Gamma$ . Then  $\approx_x$  is the restriction of  $\approx$  to  $x^{\perp}$ .

In particular, if p is an interior point of  $\Gamma$  with  $p \cap \mathbf{x}^{\perp} \neq \emptyset$ , then  $p \cap \mathbf{x}^{\perp}$  is an interior point or an interior hyperplane of  $\mathbf{x}^{\perp}$ , and conversely, if q is an interior point of  $\mathbf{x}^{\perp}$ , then there exists an interior point or hyperplane q' of  $\Gamma$  with  $q' \cap \mathbf{x}^{\perp} = q$ .

*Proof.* Fix an isomorphism  $\phi: \Gamma \to \mathbf{H}$ . As above, we argue in  $\mathbf{H}$  rather than in  $\Gamma$ . Let  $\phi(\mathbf{x}) = (x, X)$ . Now the statement follows from the fact that, for  $\mathbf{a}, \mathbf{b} \in \mathbf{x}^{\perp}$ , with  $\mathbf{a} \approx_{\mathbf{x}} \mathbf{b}$  and  $\phi(\mathbf{a}) = (a, A)$ ,  $\phi(\mathbf{b}) = (b, B)$ , the statements  $A \cap X = B \cap X$  and A = B are equivalent.

Notation 3.15. In view of the lemma, we can choose the equivalence relation  $\approx_{\mathbf{x}}^{p}$  on  $\mathbf{x}^{\perp}$  in such a way that  $(\approx_{\mathbf{x}})^{p} = (\approx^{p})_{\mathbf{x}}$ . In that case, there is no harm in writing  $\approx_{\mathbf{x}}^{p}$  to denote this relation. In particular, there is a one-to-one map from the set of interior points of  $\mathbf{x}^{\perp}$  into the set of interior points of  $\Gamma$ .

**Lemma 3.16.** Let  $n \geq 3$  and let x be a vertex of  $\Gamma$ . Then the interior projective space on  $x^{\perp}$  is a hyperplane of the interior projective space on  $\Gamma$ .

Proof. Fix an isomorphism  $\Gamma \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$ . By Proposition 3.8 this isomorphism of graphs induces an isomorphism between the interior projective space on  $\Gamma$  and the exterior projective space on  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ . The vertex  $\mathbf{x} \in \Gamma$  is mapped onto a non-incident point-hyperplane pair of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ , say (x, X). The neighbors of  $\mathbf{x}$  are mapped onto point-hyperplane pairs (y, Y) with  $y \in X$ , inducing a map of the set of interior points of  $\Gamma$  that meet  $\mathbf{x}^{\perp}$  non-trivially onto the set of exterior points of  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  that intersect  $(x, X)^{\perp}$  non-trivially. But that set of exterior points form a hyperplane of the exterior projective space on  $\mathbf{H}(\mathbb{P}, \mathbb{H})$ , and the lemma is proved.

### 4. LOCALLY POINT-HYPERPLANE GRAPHS

Throughout the whole section, we take  $n \geq 3$ , and  $\Gamma$  a connected, locally  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  graph for some projective space  $\mathbb{P}$  of dimension n (possibly infinite) and subspace  $\mathbb{H}$  of  $\mathbb{P}^{\text{dual}}$  with trivial annihilator in  $\mathbb{P}$ . Thus, the fact that  $\Gamma$  is locally  $\mathbf{H}(\mathbb{P}, \mathbb{H})$  means that, for each vertex  $\mathbf{x}$  of  $\Gamma$ , there is an isomorphism  $\mathbf{x}^{\perp} \to \mathbf{H}(\mathbb{P}, \mathbb{H})$ . Consequently, by Corollary 3.9, the interior projective space on  $\mathbf{x}^{\perp}$  is isomorphic to  $\mathbb{P}$  or  $\mathbb{H}$ . The goal of this section is, by use of these isomorphisms, to show that  $\Gamma$  is isomorphic to the non-incident point-hyperplane graph  $\mathbf{H}(\mathbb{P}_1, \mathbb{H}_1)$  for some projective space  $\mathbb{P}_1$  and subspace  $\mathbb{H}_1$  of  $\mathbb{P}_1^{\text{dual}}$ . This will establish Theorem 1.1.

Notice that the definitions of interior points and lines are only local and may differ on different perps. It is one task of this section to show that there is a well-defined notion of *global points* and *global lines* on the whole graph. To avoid

confusion, we will index each interior point p and each interior line l by the vertex x whose perp it belongs to, so we write  $p_x$  and  $l_x$  instead of p and l. These interior points and lines are called *local points* and *local lines*, respectively. We do the same for the relations  $\approx$ ,  $\approx^p$ ,  $\approx^h$  obtaining the local relations  $\approx_x$ ,  $\approx^p_x$ ,  $\approx^h_x$ .

**Lemma 4.1.** Let x and y be two adjacent vertices of  $\Gamma$ . Then there is a choice of local equivalence relations  $\approx_x^p$  and  $\approx_y^p$  such that the restrictions of  $\approx_x^p$  and  $\approx_y^p$  to  $x^{\perp} \cap y^{\perp}$  coincide.

*Proof.* This follows immediately from a repeated application of Lemma 3.14 to  $\mathbf{x}^{\perp} \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$  and  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp}$  and to  $\mathbf{y}^{\perp} \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$  and  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp}$ .

The preceding lemma allows us to transfer points from  $\mathbf{x}^{\perp}$  to  $\mathbf{y}^{\perp}$ . Indeed, if there is a local point  $p_{\mathbf{x}}$  in  $\mathbf{x}^{\perp}$  that lies in the hyperplane  $Y_{\mathbf{x}}$  induced by the vertex  $\mathbf{y}$  on  $\mathbf{x}^{\perp}$ , the point  $p_{\mathbf{x}}$  corresponds to a point  $p_{\mathbf{y}}$  of  $\mathbf{y}^{\perp}$ . That point  $p_{\mathbf{y}}$  is simply the  $\approx_{\mathbf{y}}^{p}$  equivalence class that contains the set  $p_{\mathbf{x}} \cap \mathbf{y}^{\perp}$ .

In the next two lemmas we prove some technical statements enabling us to prove simple connectedness of  $\Gamma$ . (A graph is simply connected if it is connected and

every cycle in can be triangulated.)

Lemma 4.2. Let  $\mathbf{w} \perp \mathbf{x} \perp \mathbf{y} \perp \mathbf{z}$  be a path of vertices in  $\Gamma$ . Then for  $\mathbf{x} = (x_{\mathbf{y}}, X_{\mathbf{y}})$  and  $\mathbf{z} = (z_{\mathbf{y}}, Z_{\mathbf{y}})$  inside  $\mathbf{y}^{\perp}$ , if  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap x_{\mathbf{y}}z_{\mathbf{y}} = \emptyset$  or if  $X_{\mathbf{y}} = Z_{\mathbf{y}}$ , there is a path of vertices in  $\mathbf{x}^{\perp} \cap \mathbf{z}^{\perp}$  from  $\mathbf{y}$  to a vertex in  $\{\mathbf{w}, \mathbf{x}, \mathbf{z}\}^{\perp}$ .

Notice that, for example, we have  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle = \emptyset$ , in case  $x_{\mathbf{y}} = z_{\mathbf{y}}$ .

Proof. Choose local equivalence relations  $\approx_{\mathbf{w}}^p$ ,  $\approx_{\mathbf{x}}^p$ ,  $\approx_{\mathbf{y}}^p$ , and  $\approx_{\mathbf{z}}^p$  such that  $\approx_{\mathbf{w}}^p$  and  $\approx_{\mathbf{x}}^p$  coincide on  $\mathbf{w}^{\perp} \cap \mathbf{x}^{\perp}$ , such that  $\approx_{\mathbf{x}}^p$  and  $\approx_{\mathbf{z}}^p$  coincide on  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp}$ , and such that  $\approx_{\mathbf{y}}^p$  and  $\approx_{\mathbf{z}}^p$  coincide on  $\mathbf{y}^{\perp} \cap \mathbf{z}^{\perp}$  as indicated in Lemma 4.1. Application of Lemma 3.16 to the interior projective space of  $\mathbf{y}^{\perp} \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$  shows that the interior projective spaces of  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp}$  and of  $\mathbf{y}^{\perp} \cap \mathbf{z}^{\perp}$  correspond to hyperplanes of  $\mathbf{y}^{\perp} \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$ . We have to investigate  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp} \cap \mathbf{z}^{\perp}$ . We have  $\mathbf{x} = (x_{\mathbf{y}}, X_{\mathbf{y}})$  and  $\mathbf{z} = (z_{\mathbf{y}}, Z_{\mathbf{y}})$  inside  $\mathbf{y}^{\perp}$ . Then the graph  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp} \cap \mathbf{z}^{\perp}$  (considered inside  $\mathbf{y}^{\perp}$ ) consists of the non-incident point-hyperplane pairs whose points are contained in

 $X_{\mathbf{y}} \cap Z_{\mathbf{y}}$  and whose hyperplanes contain the subspace  $\langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle$ . First, let us assume  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle = \emptyset$ . Also assume that  $x_{\mathbf{y}} \neq z_{\mathbf{y}}$  and denote the intersection  $x_{\mathbf{y}}z_{\mathbf{y}} \cap X_{\mathbf{y}}$  by  $a_{\mathbf{y}}$ . Inside  $\mathbf{x}^{\perp}$  denote  $\mathbf{w}$  by  $(w_{\mathbf{x}}, W_{\mathbf{x}})$  and  $\mathbf{y}$ by  $(y_x, Y_x)$ . Consider  $x^{\perp}$ , in which the point  $a_y \in X_y$  arises as  $a_x$  inside  $Y_x$ . Inside  $\mathbf{y}^{\perp}$ , the intersection  $X_{\mathbf{y}} \cap Z_{\mathbf{y}}$  contains a line  $l_{\mathbf{y}}$ . This line  $l_{\mathbf{y}}$  arises as a subspace  $l_{\mathbf{x}}$  of  $\mathbf{x}^{\perp}$  that is contained in  $Y_{\mathbf{x}}$ . As there exists a  $\mathbf{y}'$  in  $\{\mathbf{x}, \dot{\mathbf{y}}, \mathbf{z}\}^{\perp}$ , we can assume, up to a change of y into y', that  $w_x$  is also contained in  $Y_x$ . (Indeed, choose a hyperplane  $H_x$  that contains  $a_x$ ,  $w_x$ , and  $y_x$  but not  $l_x$ , and choose a point  $p_x$ on  $l_x$  off  $H_x$ . The vertex  $(p_x, H_x)$  gives rise to a vertex y' that is adjacent to x and y. Local analysis of  $y^{\perp}$  shows that the hyperplane of the vertex y' contains the point  $x_y$  and the point  $a_y$ , whence also the point  $z_y$ . Moreover, the point of y' is contained in  $l_y$ , whence also in  $Z_y$ , and y' is a neighbor of z.) Inside  $x^{\perp}$ we have now the following setting. The hyperplane  $Y_{\mathbf{x}}$  contains the points  $w_{\mathbf{x}}$  and  $a_{\mathbf{x}}$  as well as the line  $l_{\mathbf{x}}$ . Note that  $l_{\mathbf{x}}$  has to intersect the hyperplane  $W_{\mathbf{x}}$ . If  $\langle a_{\mathbf{x}}, w_{\mathbf{x}} \rangle$  does not intersect  $l_{\mathbf{x}} \cap W_{\mathbf{x}}$ , then we can choose a point inside  $l_{\mathbf{x}} \cap W_{\mathbf{x}}$ and a non-incident hyperplane that contains  $(a_x, w_x, y_x)$ , yielding a vertex that is adjacent to  $\mathbf{w}$ ,  $\mathbf{x}$ ,  $\mathbf{y}$ , and—after local analysis of  $\mathbf{y}^{\perp}$ —also to  $\mathbf{z}$ . Therefore assume that  $\langle a_{\mathbf{x}}, w_{\mathbf{x}} \rangle$  does intersect  $l_{\mathbf{x}} \cap W_{\mathbf{x}}$ . Then fix the point  $u_{\mathbf{x}} := \langle a_{\mathbf{x}}, w_{\mathbf{x}} \rangle \cap l_{\mathbf{x}} \cap W_{\mathbf{x}}$  and choose a hyperplane  $U_{\mathbf{x}}$  that contains  $a_{\mathbf{x}}$  and  $y_{\mathbf{x}}$  but not  $u_{\mathbf{x}}$ . The pair  $(u_{\mathbf{x}}, U_{\mathbf{x}})$  describes another vertex,  $\mathbf{u}$  say, that is adjacent to  $\mathbf{x}$ ,  $\mathbf{y}$ , and  $\mathbf{z}$ . Inside  $\mathbf{u}^{\perp}$  we have a hyperplane  $X_{\mathbf{u}}$  of  $\mathbf{x}$ , a line  $k_{\mathbf{u}}$  in  $X_{\mathbf{u}}$  that arises from a line  $k_{\mathbf{x}}$  contained in the intersection  $U_{\mathbf{x}} \cap W_{\mathbf{x}}$  of the hyperplanes of the vertices  $\mathbf{u}$  and  $\mathbf{w}$  inside  $\mathbf{x}^{\perp}$ , and the hyperplane  $Z_{\mathbf{u}}$  of  $\mathbf{z}$ . Choose a point  $v_{\mathbf{u}}$  in  $k_{\mathbf{u}} \cap Z_{\mathbf{u}}$  and a hyperplane  $V_{\mathbf{u}}$  on  $x_{\mathbf{u}}z_{\mathbf{u}}$  that does not contain  $v_{\mathbf{u}}$ . Obviously, this vertex  $\mathbf{v} = (v_{\mathbf{u}}, V_{\mathbf{u}})$  is adjacent to  $\mathbf{x}$ ,  $\mathbf{u}$  and  $\mathbf{z}$ . In  $\mathbf{x}^{\perp}$ , however, we see  $\mathbf{v}$  as  $(v_{\mathbf{x}}, V_{\mathbf{x}})$  whose hyperplane  $V_{\mathbf{x}}$  contains the points  $a_{\mathbf{x}}$  and  $u_{\mathbf{x}}$ , therefore also  $w_{\mathbf{x}}$ . Moreover,  $v_{\mathbf{x}}$  is contained in  $k_{\mathbf{x}}$ , whence also in  $W_{\mathbf{x}}$ , and  $\mathbf{v}$  is the required vertex.

If  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle = \emptyset$  and  $x_{\mathbf{y}} = z_{\mathbf{y}}$ , then similar arguments yield a proof. Also the case that  $X_{\mathbf{y}} = Z_{\mathbf{y}}$  runs along the same lines and is, in fact, easier to prove.

Lemma 4.3. For every path  $\mathbf{w} \perp \mathbf{x} \perp \mathbf{y} \perp \mathbf{z}$  in  $\Gamma$  there is a vertex  $\mathbf{x_0} \in \{\mathbf{x}\} \cup \{\mathbf{w}, \mathbf{x}, \mathbf{y}\}^{\perp}$  such that, with  $\mathbf{x_0} = (x_{\mathbf{y}}^0, X_{\mathbf{y}}^0)$  and  $\mathbf{z} = (z_{\mathbf{y}}, Z_{\mathbf{y}})$  inside  $\mathbf{y}^{\perp}$ , we have  $\langle x_{\mathbf{y}}^0, z_{\mathbf{y}} \rangle \cap X_{\mathbf{y}}^0 \cap Z_{\mathbf{y}} = \emptyset$ .

*Proof.* Choose a path  $\mathbf{w} \perp \mathbf{z} \perp \mathbf{y} \perp \mathbf{z}$  of vertices in  $\Gamma$ , and fix local equivalence relations  $\approx_{\mathbf{w}}^p$ ,  $\approx_{\mathbf{x}}^p$ ,  $\approx_{\mathbf{y}}^p$ , and  $\approx_{\mathbf{z}}^p$  as in the proof of the preceding lemma. Inside  $\mathbf{y}^{\perp}$ , let  $\mathbf{x}$  correspond to  $(x_{\mathbf{y}}, X_{\mathbf{y}})$  and  $\mathbf{z}$  correspond to  $(z_{\mathbf{y}}, Z_{\mathbf{y}})$ . Suppose that  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle \neq \emptyset$ . Then  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle$  is a point;  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \setminus x_{\mathbf{y}} z_{\mathbf{y}}$  contains (the point set of) an affine line, for n=3, and (the point set of) a dual affine plane, for  $n \geq 4$ ; it may be even bigger if  $X_y = Z_y$ . The set of common neighbors of x and  ${f z}$  in  ${f y}^\perp$  corresponds to the set of all non-incident point-hyperplane pairs  $(p_{f y}, H_{f y})$ with  $p_{\mathbf{y}} \in X_{\mathbf{y}} \cap Z_{\mathbf{y}}$  and  $H_{\mathbf{y}} \supset x_{\mathbf{y}}z_{\mathbf{y}}$  inside  $\mathbf{y}^{\perp}$ . This implies that for any point  $p_{\mathbf{y}} \in X_{\mathbf{y}} \cap Z_{\mathbf{y}} \setminus x_{\mathbf{y}} z_{\mathbf{y}}$  we can find a vertex  $(p_{\mathbf{y}}, H_{\mathbf{y}})$  in  $\mathbf{y}^{\perp}$  adjacent to both  $\mathbf{x}$  and  $\mathbf{z}$ . Now consider  $\mathbf{x}^{\perp}$ . Let  $\mathbf{w} = (w_{\mathbf{x}}, W_{\mathbf{x}})$  and  $\mathbf{y} = (y_{\mathbf{x}}, Y_{\mathbf{x}})$ . Any vertex  $\mathbf{x}_0 = (x_{\mathbf{x}}^0, X_{\mathbf{x}}^0)$ adjacent to w, x, y consists of a point  $x_x^0 \in W_x \cap Y_x$  and a non-incident hyperplane  $X_{\mathbf{x}}^{0}\supset w_{\mathbf{x}}y_{\mathbf{x}}$ . Hence, as above in  $\mathbf{y}^{\perp}$ , we can choose  $x_{\mathbf{x}}^{0}$  freely on an affine line for n=3 or a dual affine plane for  $n\geq 4$ . This translates to  $\mathbf{y}^{\perp}$  as follows. The line  $w_{\mathbf{x}}y_{\mathbf{x}}$  intersects  $Y_{\mathbf{x}}$  in a point,  $a_{\mathbf{x}}$  say, which gives rise to a point  $a_{\mathbf{y}} \in X_{\mathbf{y}}$  of  $\mathbf{y}^{\perp}$ . So all these hyperplanes  $X^0_{\mathbf{x}}$  arise as hyperplanes  $X^0_{\mathbf{y}}$  in  $\mathbf{y}^{\perp}$  that contain the line  $x_{\mathbf{y}}a_{\mathbf{y}}$ . Notice that this line  $x_{\mathbf{y}}a_{\mathbf{y}}$  is the largest subspace of  $\mathbf{y}^{\perp}$  that is contained in all these hyperplanes  $X^0_y$ . If for some fixed choice of  $x^0_y$ , there exists a hyperplane  $X^0_y$  of  $\mathbf{y}^{\perp}$  such that  $X_{\mathbf{y}}^{0} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}^{0}, z_{\mathbf{y}} \rangle = \emptyset$ , we are done. Hence, for a fixed  $x_{\mathbf{y}}^{0}$ , suppose all choices for  $X^0_{\mathbf{y}}$  contain the point  $\langle x^0_{\mathbf{y}}, z_{\mathbf{y}} \rangle \cap Z_{\mathbf{y}}$ . But in this case, we can choose another  $x^1_{\mathbf{y}}$  instead of  $x^0_{\mathbf{y}}$  and find an  $X^0_{\mathbf{y}}$  with  $X^0_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x^1_{\mathbf{y}}, z_{\mathbf{y}} \rangle = \emptyset$ . For, suppose for a choice  $x^1_{\mathbf{y}}$  distinct from  $x^0_{\mathbf{y}}$  still  $X^0_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x^1_{\mathbf{y}}, z_{\mathbf{y}} \rangle \neq \emptyset$  for all possible  $X^0_{\mathbf{y}}$  inside  $\mathbf{y}^{\perp}$ . Then the points  $u_{\mathbf{y}} := \langle x_{\mathbf{y}}^0, z_{\mathbf{y}} \rangle \cap Z_{\mathbf{y}}$  and  $v_{\mathbf{y}} := \langle x_{\mathbf{y}}^1, z_{\mathbf{y}} \rangle \cap Z_{\mathbf{y}}$  span a line as  $z_{\mathbf{y}} \not\in Z_{\mathbf{y}}$ . But this line  $u_{\mathbf{y}}v_{\mathbf{y}}$  has to coincide with the line  $x_{\mathbf{y}}a_{\mathbf{y}}$ . In particular,  $x_{\mathbf{y}}$  is contained in  $Z_{\mathbf{y}}$ . But this contradicts our assumption that  $X_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x_{\mathbf{y}}, z_{\mathbf{y}} \rangle \neq \emptyset$ . Hence we can find an  $x^1_{\mathbf{y}} \not\in X^0_{\mathbf{y}}$  with  $X^0_{\mathbf{y}} \cap Z_{\mathbf{y}} \cap \langle x^1_{\mathbf{y}}, z_{\mathbf{y}} \rangle = \emptyset$ , and so the vertex  $(x^1_{\mathbf{v}}, X^0_{\mathbf{v}})$  is as required.

We owe the following proposition to Andries Brouwer, who observed that the combination of the two preceding lemmas yields simple connectedness.

**Proposition 4.4.** The graph  $\Gamma$ , considered as a two-dimensional simplicial complex whose two-simplices are its triangles, is simply connected. Moreover, the diameter of  $\Gamma$  equals two.

Proof. Lemma 4.3 shows that for every path of distinct vertices  $\mathbf{w}$ ,  $\mathbf{x}$ ,  $\mathbf{y}$ ,  $\mathbf{z}$  in  $\Gamma$  there exists a vertex  $\mathbf{x}_0 \in \{\mathbf{w}, \mathbf{x}, \mathbf{y}\}^{\perp}$  with  $\mathbf{x}_0 = (x_{\mathbf{y}}^0, X_{\mathbf{y}}^0)$  in  $\mathbf{y}^{\perp}$  such that  $\langle x_{\mathbf{y}}^0, z_{\mathbf{y}} \rangle \cap X_{\mathbf{y}}^0 \cap Z_{\mathbf{y}} = \emptyset$ . Lemma 4.2, on the other hand, implies that there exists a path of vertices inside  $\mathbf{x}_0^{\perp} \cap \mathbf{z}^{\perp}$  from  $\mathbf{y}$  to a vertex  $\mathbf{v}$  that is adjacent to  $\mathbf{w}$ ,  $\mathbf{x}_0$ , and  $\mathbf{z}$ . Simple connectedness of  $\Gamma$  follows.

As for the second statement; suppose  $\mathbf{w} \perp \mathbf{x} \perp \mathbf{y} \perp \mathbf{z}$  is a path in  $\Gamma$ , then by by the above arguments there is a vertex  $\mathbf{v}$  in  $\mathbf{w}^{\perp} \cap \mathbf{z}^{\perp}$ . Hence  $\mathbf{z}$  is at distance at most two from  $\mathbf{w}$ . This implies that the diameter of  $\Gamma$  is at most two and settles the proof of the proposition.

**Lemma 4.5.** There is a choice of local equivalence relations  $\approx_{\mathbf{x}}^{p}$  for all  $\mathbf{x} \in \Gamma$  such that, for any two adjacent vertices  $\mathbf{x}$  and  $\mathbf{y}$ , the restrictions of  $\approx_{\mathbf{x}}^{p}$  and  $\approx_{\mathbf{y}}^{p}$  to  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp}$  coincide.

Proof. Suppose that  $\mathbf{x}$ ,  $\mathbf{y}$ ,  $\mathbf{z}$  is a triangle. In view of Lemma 4.1, we may assume that  $\approx^p_{\mathbf{x}}$  and  $\approx^p_{\mathbf{y}}$  have the same restriction to  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp}$  and that  $\approx^p_{\mathbf{x}}$  and  $\approx^p_{\mathbf{z}}$  have the same restriction to  $\mathbf{x}^{\perp} \cap \mathbf{z}^{\perp}$ . Let  $p_{\mathbf{x}}$  be an interior point of  $\mathbf{x}^{\perp}$  such that  $p_{\mathbf{x}} \cap \mathbf{y}^{\perp} \cap \mathbf{z}^{\perp} \neq \emptyset$ . By analysis of  $\mathbf{x}^{\perp}$ , we can find two vertices, say  $\mathbf{u}$  and  $\mathbf{v}$ , in  $p_{\mathbf{x}} \cap \mathbf{y}^{\perp} \cap \mathbf{z}^{\perp}$ . Now the above choices of local equivalence relations imply that  $(\mathbf{u}, \mathbf{v})$  belongs to  $\approx^p_{\mathbf{y}} \cap \approx^p_{\mathbf{z}}$  (indeed,  $(\mathbf{u}, \mathbf{v})$  belongs to both  $\approx^p_{\mathbf{x}} \cap \approx^p_{\mathbf{y}}$  and  $\approx^p_{\mathbf{z}} \cap \approx^p_{\mathbf{z}}$ ). By Lemma 3.2 this forces that  $\approx^p_{\mathbf{y}}$  and  $\approx^p_{\mathbf{z}}$  have the same restriction to  $\mathbf{y}^{\perp} \cap \mathbf{z}^{\perp}$ . Since  $\Gamma$  is simply connected (by Proposition 4.4), the lemma follows immediately from the triangle analysis.

Notation 4.6. Fix a choice of  $\approx_{\mathbf{x}}^p$ , for all vertices  $\mathbf{x}$  of  $\Gamma$ , as in Lemma 4.5 and set  $\approx^p = \bigcup_{\mathbf{x} \in \Gamma} \approx_{\mathbf{x}}^p$ .

**Lemma 4.7.** Let x and y be vertices of  $\Gamma$  such that  $x \approx_u^p y$  for some vertex u in  $\{x,y\}^{\perp}$ . Then  $x \approx_v^p y$  for every vertex v in  $\{x,y\}^{\perp}$ .

*Proof.* Let  $\mathbf{u}$ ,  $\mathbf{x}$ ,  $\mathbf{y}$  be as in the hypothesis and let  $\mathbf{v} \in \{\mathbf{x}, \mathbf{y}\}^{\perp}$  be an additional vertex. If  $\mathbf{u} \perp \mathbf{v}$ , then the claim is true by Lemma 4.5.

Thus, it is sufficient to show that the induced subgraph  $\{\mathbf{x},\mathbf{y}\}^{\perp}$  of  $\Gamma$  is connected. In  $\mathbf{x}^{\perp}$  we have  $\mathbf{u}=(u_{\mathbf{x}},U_{\mathbf{x}})$  and  $\mathbf{v}=(v_{\mathbf{x}},V_{\mathbf{x}})$ . Moreover, the intersection  $X_{\mathbf{u}}\cap Y_{\mathbf{u}}$  from  $\mathbf{u}^{\perp}$  arises as a hyperplane  $W_{\mathbf{x}}$  of  $U_{\mathbf{x}}$  in  $\mathbf{x}^{\perp}$ . Therefore the intersection  $W_{\mathbf{x}}\cap V_{\mathbf{x}}$  contains a point  $p_{\mathbf{x}}$ . If in  $\mathbf{x}^{\perp}$  the line  $u_{\mathbf{x}}v_{\mathbf{x}}$  does not contain  $p_{\mathbf{x}}$ , we can find a hyperplane  $H_{\mathbf{x}} \supset u_{\mathbf{x}}v_{\mathbf{x}}$  that does not contain  $p_{\mathbf{x}}$ , and  $(p_{\mathbf{x}},H_{\mathbf{x}})$  is a vertex of  $\mathbf{x}^{\perp}$  which is adjacent to both  $\mathbf{u}$  and  $\mathbf{v}$ . But inside  $\mathbf{u}^{\perp}$  this vertex also corresponds to some point-hyperplane pair, whose point is contained in  $Y_{\mathbf{u}}$  and whose hyperplane contains  $y_{\mathbf{u}} = x_{\mathbf{u}}$ . In particular, this vertex is also adjacent to  $\mathbf{y}$ , and we are done.

So assume we have  $p_{\mathbf{x}} \in u_{\mathbf{x}}v_{\mathbf{x}}$  in  $\mathbf{x}^{\perp}$ . Then choose any hyperplane  $H_{\mathbf{x}}$  that contains  $u_{\mathbf{x}}$  but not  $p_{\mathbf{x}}$ . Then the vertex  $\mathbf{t} := (p_{\mathbf{x}}, H_{\mathbf{x}})$  is adjacent to  $\mathbf{x}$ ,  $\mathbf{u}$ , and  $\mathbf{y}$ , but not  $\mathbf{v}$ . Inside  $\mathbf{t}^{\perp}$  we have hyperplanes  $X_{\mathbf{t}}$  and  $Y_{\mathbf{t}}$  coming from  $\mathbf{x}$  and  $\mathbf{y}$ . The intersection  $X_{\mathbf{t}} \cap Y_{\mathbf{t}}$  corresponds to a subspace  $S_{\mathbf{x}}$  of  $H_{\mathbf{x}}$  (the hyperplane of the vertex  $\mathbf{t}$ ) in  $\mathbf{x}^{\perp}$ . The intersection  $S_{\mathbf{x}} \cap V_{\mathbf{x}}$  in  $\mathbf{x}^{\perp}$  contains some point  $q_{\mathbf{x}}$ . If  $q_{\mathbf{x}}$  lies on the line  $p_{\mathbf{x}}v_{\mathbf{x}}$ , then  $q_{\mathbf{x}} = p_{\mathbf{x}}v_{\mathbf{x}} \cap H_{\mathbf{x}} = p_{\mathbf{x}}u_{\mathbf{x}} \cap H_{\mathbf{x}} = u_{\mathbf{x}}$ , and we have  $u_{\mathbf{x}} \in V_{\mathbf{x}}$ . But this contradicts  $p_{\mathbf{x}} \in u_{\mathbf{x}}v_{\mathbf{x}}$ , as  $p_{\mathbf{x}} \in V_{\mathbf{x}} \cap U_{\mathbf{x}}$ ,  $v_{\mathbf{x}} \notin V_{\mathbf{x}}$  and  $u_{\mathbf{x}} \in V_{\mathbf{x}} \setminus U_{\mathbf{x}}$ . Therefore

we have  $q_x \notin p_x v_x$  and we are in the situation of the preceding paragraph with the vertex t instead of  $\mathbf{u}$ .

We are now ready to show that there exists a well-defined notion of *global points* on  $\Gamma$ , which will then allow us to study a geometry on  $\Gamma$ .

Lemma 4.8. The relation  $\approx^p$  on the vertices of  $\Gamma$  is an equivalence relation.

*Proof.* Reflexivity and symmetry follow from reflexivity and symmetry of each  $\approx_{\bullet}^{p}$ . To prove transitivity, assume that  $\mathbf{x} \approx^p \mathbf{y}$  and  $\mathbf{y} \approx^p \mathbf{z}$ . Then there exist vertices  $\mathbf{u}$ ,  $\mathbf{v}$  with  $\mathbf{x} \approx_{\mathbf{u}}^{p} \mathbf{y}$  and  $\mathbf{y} \approx_{\mathbf{v}}^{p} \mathbf{z}$ . By Proposition 4.4, there also exists a vertex  $\mathbf{a} \in \{\mathbf{x}, \mathbf{z}\}^{\perp}$ . We will prove that  $\mathbf{x} \approx_{\mathbf{a}}^{p} \mathbf{z}$ . In view of the Lemma 4.2 (applied to the the chains  $\mathbf{a} \perp \mathbf{x} \perp \mathbf{u} \perp \mathbf{y}$  and  $\mathbf{a} \perp \mathbf{z} \perp \mathbf{v} \perp \mathbf{y}$ ) there are vertices  $\mathbf{b} \in \{\mathbf{a}, \mathbf{x}, \mathbf{y}\}^{\perp}$ and  $c \in \{a, z, y\}^{\perp}$ . Lemma 4.7 implies  $x \approx_b^p y$  and  $y \approx_c^p z$ . Set  $b = (b_a, B_a)$ ,  $\mathbf{c} = (c_{\mathbf{a}}, C_{\mathbf{a}}), \mathbf{x} = (x_{\mathbf{a}}, X_{\mathbf{a}}), \text{ and } \mathbf{z} = (z_{\mathbf{a}}, Z_{\mathbf{a}}) \text{ in } \mathbf{a}^{\perp}.$  Notice that  $z_{\mathbf{a}} \in C_{\mathbf{a}}$ . We can additionally assume that  $x_a \in C_a$  and  $c_a \notin b_a x_a$ . (Indeed, set  $a = (a_c, A_c)$ ,  $\mathbf{y} = (y_{\mathbf{c}}, Y_{\mathbf{c}}), \ \mathbf{z} = (z_{\mathbf{c}}, Z_{\mathbf{c}}) \text{ in } \mathbf{c}^{\perp}.$  The intersection  $A_{\mathbf{c}} \cap Y_{\mathbf{c}}$  contains a line  $l_{\mathbf{c}}$ . Moreover,  $y_c = z_c$ , as  $y \approx_c^p z$ . Locally in  $a^{\perp}$  the line  $l_c$  arises as a line  $l_a \subset C_a$ . Fix a hyperplane  $H_{\bf a}$  that contains  $\langle c_{\bf a}, x_{\bf a}, z_{\bf a} \rangle$  and fix a point  $p_{\bf a}$  on  $l_{\bf a}$  off  $\langle c_{\bf a}, x_{\bf a}, z_{\bf a} \rangle$ and  $(b_a, x_a)$ ; such a choice is always possible as  $x_a \notin l_a$  and  $c_a \notin C_a$  and  $l_a$  contains at least three points. This gives a new vertex  $c' = (p_a, H_a)$  that is adjacent to a, c, and y. Local analysis of  $c^{\perp}$  shows that we can find a vertex z' in  $\approx_c^p$  relation to z that is adjacent to c' and a.) But now, we can find a vertex  $\mathbf{d} = (x_a, D_a)$ in  $\mathbf{a}^{\perp}$  that is adjacent to  $\mathbf{b} = (b_{\mathbf{a}}, B_{\mathbf{a}})$  and  $\mathbf{c} = (c_{\mathbf{a}}, C_{\mathbf{a}})$  (notice that by the above we can assume  $c_{\mathbf{a}} \notin b_{\mathbf{a}}x_{\mathbf{a}}$ , whence  $x_{\mathbf{a}} \notin b_{\mathbf{a}}c_{\mathbf{a}}$ ). By construction we have  $\mathbf{d} \approx_{\mathbf{b}}^{p} \mathbf{x}$ , so  $\mathbf{d} \approx_{\mathbf{b}}^{p} \mathbf{x}$  by Lemma 4.7, and as  $\mathbf{x} \approx_{\mathbf{b}}^{p} \mathbf{y}$  we also have  $\mathbf{d} \approx_{\mathbf{b}}^{p} \mathbf{y}$ . Now Lemma 4.7 implies  $\mathbf{d} \approx_{\mathbf{c}}^{p} \mathbf{y}$ . But also  $\mathbf{y} \approx_{\mathbf{c}}^{p} \mathbf{z}$ . Transitivity of  $\approx_{\mathbf{c}}^{p}$  implies  $\mathbf{d} \approx_{\mathbf{c}}^{p} \mathbf{z}$  and, again Lemma 4.7 yields  $\mathbf{d} \approx_{\mathbf{a}}^{p} \mathbf{z}$ . Finally, transitivity of  $\approx_{\mathbf{a}}^{p}$  gives  $\mathbf{x} \approx_{\mathbf{a}}^{p} \mathbf{z}$ , yielding  $\mathbf{x} \approx^{p} \mathbf{z}$ . Hence  $\approx^p$  is transitive.

All statements and results about the local relations  $\approx_{\mathbf{x}}^{p}$  are also true for the local relations  $\approx_{\mathbf{x}}^{h}$ , and we can define a global relation  $\approx^{h} = \bigcup_{\mathbf{x} \in \Gamma} \approx_{\mathbf{x}}^{h}$  with the same nice properties on the local intersections.

**Definition 4.9.** A global point of  $\Gamma$  is defined as an equivalence class of  $\approx^p$ . Dually, define a global hyperplane as an equivalence class of  $\approx^h$ .

We already have a local notion of incidence as defined before Definition 3.6. A global notion also exists.

**Lemma 4.10.** A global point p and a global hyperplane H are incident if and only if  $p \cap H = \emptyset$ .

Proof. One implication is trivial. To prove the other, suppose there exists a vertex  $\mathbf{y} \in p \cap H$ . Then, any vertex  $\mathbf{x}$  for which  $p_{\mathbf{x}}$  and  $H_{\mathbf{x}}$  exist is at distance at most two to  $\mathbf{y}$ , by Proposition 4.4, and there exists a vertex  $\mathbf{z}$  adjacent to both  $\mathbf{y}$  and  $\mathbf{x}$ . The local elements  $p_{\mathbf{z}}$  and  $H_{\mathbf{z}}$  exist, as  $\mathbf{y}$  is a representative of both. But then  $p_{\mathbf{x}} \cap z^{\perp} \neq \emptyset$  as well as  $H_{\mathbf{x}} \cap z^{\perp} \neq \emptyset$ . Now inside  $\mathbf{x}^{\perp} \cap \mathbf{z}^{\perp}$  we see that  $p_{\mathbf{x}}$  and  $H_{\mathbf{x}}$  have a non-empty intersection.

**Definition 4.11.** Let p and q be distinct global points and let x be a vertex such that  $p_x$  and  $q_x$  exist. Then the global line of  $\Gamma$  spanned by p and q is the set of those global points a such that  $a_x$  exists and is contained in the local line  $p_xq_x$ .

Let  $\mathbb{P}_{\Gamma}=(\mathcal{P}_{\Gamma},\mathcal{L}_{\Gamma},\subset)$  be the point-line geometry consisting of the point set  $\mathcal{P}_{\Gamma}$  of global points of  $\Gamma$  and the line set  $\mathcal{L}_{\Gamma}$  of global lines of  $\Gamma$ .

Lemma 4.12. The notion of a global line is well-defined.

*Proof.* Let p and q be global points and suppose x and y are distinct vertices such that  $p_x$ ,  $q_x$ ,  $p_y$ , and  $q_y$  exist. We prove that for any global point r for which  $r_x$ exists and is contained in the local line on  $p_x$  and  $q_x$ , the local point  $r_y$  also exists and is on the local line on  $p_y$ , and  $q_y$ .

If  $\mathbf{x} \perp \mathbf{y}$ , then  $p_{\mathbf{x}} \cap p_{\mathbf{y}} \neq \emptyset$  and  $q_{\mathbf{x}} \cap q_{\mathbf{y}} \neq \emptyset$ , and the claim follows from Lemma

3.16 applied to  $\mathbf{x}^{\perp}$ .

Choose vertices  $\mathbf{a} \in p_{\mathbf{x}}, \ \mathbf{b} \in q_{\mathbf{x}}, \ \mathbf{c} \in q_{\mathbf{y}}, \ \mathrm{and} \ \mathbf{d} \in p_{\mathbf{y}}$ . By Lemma 3.12 we can assume that  ${\bf c}$  and  ${\bf d}$  are adjacent. By Proposition 4.4 there exists a vertex  ${\bf z}_1$ adjacent to both x and c. By Lemma 4.2 (applied to the path a, x,  $z_1$ , c) we can find a vertex  $z_2$  adjacent to a, x, and c (indeed, inside  $z_1^\perp$  the point  $c_{z_1}$  of c has to lie in the hyperplane  $X_{\mathbf{z}_1}$  of  $\mathbf{x}$ . So, the condition of the lemma is satisfied and we can apply that lemma). Local analysis of c yields a vertex  $z_3$  that is adjacent to  $\mathbf{z}_2$ ,  $\mathbf{c}$ , and  $\mathbf{d}$ . The induced subgraph  $\{\mathbf{c},\mathbf{d}\}^{\perp}$  of  $\Gamma$  is isomorphic to  $\mathbf{H}(\mathbb{P}_0,\mathbb{H}_0)$  for some hyperplane  $\mathbb{P}_0$  of  $\mathbb{P}$ . According to Proposition 2.3, it is connected. Therefore, we can find a path from y to  $z_3$  inside  $\{c,d\}^{\perp}$ . This establishes the lemma.

**Proposition 4.13.** The space  $\mathbb{P}_{\Gamma}$  is a linear space with thick lines.

Proof. This is an immediate consequence of Lemma 4.12.

As customary in linear spaces, for distinct global points p and q we denote by pq the unique global line on p and q.

Proposition 4.14. The space  $\mathbb{P}_{\Gamma}$  is a projective space.

Proof. In view of Proposition 4.13 we only have to verify Pasch's Axiom. Let a, b, c, d be four global points such that ab intersects cd in the global point e. Then ab = ae and cd = ce. By Proposition 4.4 and Lemma 3.12, there are vertices a in a and e in e such that a  $\perp$  e. Choose a vertex c in c. Now, by Proposition 4.4, there is a vertex y adjacent to e and c. After suitable replacements of e in e and c in c, we can assume that inside  $y^{\perp}$  we have  $c = (c_y, C_y)$  and  $e = (e_y, E_y)$  with  $C_{\mathbf{y}} \cap E_{\mathbf{y}} \cap \langle c_{\mathbf{y}}, e_{\mathbf{y}} \rangle = \emptyset$ . Lemma 4.2 implies the existence of  $\mathbf{x} \in \{\mathbf{a}, \mathbf{c}, \mathbf{e}\}^{\perp}$ . The global lines ae and ce meet x1 in interior lines. In particular, by Pasch's Axiom applied to the interior projective space of  $\mathbf{x}^{\perp}$ , there is an interior point  $w_{\mathbf{x}}$  on both the interior lines  $(ac)_{\mathbf{x}}$  and  $(bd)_{\mathbf{x}}$  of  $\mathbf{x}^{\perp}$ . Consequently, the global lines ac and bdmeet in a global point, whence Pasch's Axiom holds.

Notation 4.15. Denote by  $\langle x^{\perp} \rangle$  the set of global points intersecting  $x^{\perp}$ . Notice that this set is a subspace of  $\mathbb{P}_{\Gamma}$ .

Lemma 4.16. Let  $\mathbf{x}, \mathbf{y} \in \Gamma$  with  $\mathbf{x} \approx^h \mathbf{y}$ . Then  $\langle \mathbf{x}^{\perp} \rangle = \langle \mathbf{y}^{\perp} \rangle$ .

*Proof.* By symmetry of  $\approx^h$  it suffices to show  $\langle \mathbf{x}^{\perp} \rangle \subseteq \langle \mathbf{y}^{\perp} \rangle$ . To this end, let  $p \in \langle \mathbf{x}^{\perp} \rangle$ , so that there exists a vertex  $\mathbf{p} \in p$  with  $\mathbf{p} \perp \mathbf{x}$ . By Proposition 4.4, we can find a vertex z with  $x \perp z \perp y$ . If  $x = (x_z, X_z)$ ,  $y = (y_z, Y_z)$  inside  $z^{\perp}$ , we have  $X_z = Y_z$ , as  $\mathbf{x} \approx^h \mathbf{y}$ . Applying Lemma 4.2, we obtain a vertex  $\mathbf{a} \in \{\mathbf{p}, \mathbf{x}, \mathbf{y}\}^{\perp}$ . Writing  $\mathbf{p} = (p_{\mathbf{a}}, H_{\mathbf{a}})$  in  $\mathbf{a}^{\perp}$ , we see  $p_{\mathbf{a}} \in X_{\mathbf{a}}$ , whence  $p_{\mathbf{a}} \in Y_{\mathbf{a}}$  by  $\mathbf{x} \approx_{\mathbf{a}}^{h} \mathbf{y}$ . But now we can find a vertex  $\mathbf{p}_1 = (p_{\mathbf{a}}, H_{\mathbf{a}}^1)$  with  $y_{\mathbf{a}} \in H_{\mathbf{a}}^1$  and consequently  $p \in \langle \mathbf{y}^{\perp} \rangle$ .

We are ready to give a nice description of the hyperplanes of the projective space  $\mathbb{P}_{\Gamma}$  appearing in vertices of  $\Gamma$ . To this end, denote by  $\langle \mathbf{x}^{\perp} \rangle$  the set of global points that meet  $\mathbf{x}^{\perp}$ ; it will turn out to be a hyperplane.

Lemma 4.17. The set  $\langle \mathbf{x}^{\perp} \rangle$  does not contain the global point that contains  $\mathbf{x}$ .

*Proof.* Otherwise  $\mathbf{x}^{\perp}$  contains a vertex  $\mathbf{y}$  that belongs to the same global point. But then there exists a third vertex  $\mathbf{z}$  adjacent to both  $\mathbf{x}$  and  $\mathbf{y}$ , so  $\mathbf{x}$  and  $\mathbf{y}$  are two adjacent vertices belonging to the same interior point in  $\mathbf{z}^{\perp}$ , a contradiction.

Lemma 4.18. Let x be a vertex of  $\Gamma$ . Then  $\langle x^{\perp} \rangle$  is a hyperplane of  $\mathbb{P}_{\Gamma}$ .

Proof. Suppose l is a global line of  $\Gamma$ . We have to show that it intersects  $\langle \mathbf{x}^{\perp} \rangle$ . Let  $a \neq b$  be two global points on l and choose vertices  $\mathbf{a} \in a$ ,  $\mathbf{b} \in b$ . By Lemma 3.12 we may assume  $\mathbf{a} \perp \mathbf{b}$ . By Proposition 4.4, there exists a vertex  $\mathbf{y}$  with  $\mathbf{b} \perp \mathbf{y} \perp \mathbf{x}$ . Changing  $\mathbf{b}$  inside  $b \cap \mathbf{a}^{\perp} \cap \mathbf{y}^{\perp}$  and  $\mathbf{x}$  inside  $\mathbf{y}^{\perp}$  while leaving  $\langle \mathbf{x}^{\perp} \rangle$  invariant, we can assume  $B_{\mathbf{y}} \cap X_{\mathbf{y}} \cap \langle b_{\mathbf{y}}, x_{\mathbf{y}} \rangle = \emptyset$  (for  $\mathbf{b} = (b_{\mathbf{y}}, B_{\mathbf{y}})$ ,  $\mathbf{x} = (x_{\mathbf{y}}, X_{\mathbf{y}})$ , inside  $\mathbf{y}^{\perp}$ ); notice that, by Lemma 4.16, changing  $\mathbf{x}$  as indicated basically means changing the point  $x_{\mathbf{y}}$ . Consequently, by Lemma 4.2, there exists a vertex  $\mathbf{c} \in \{\mathbf{a}, \mathbf{b}, \mathbf{x}\}^{\perp}$ . Now local analysis of  $\mathbf{c}^{\perp}$  shows that l has to intersect  $\langle \mathbf{x}^{\perp} \rangle$ . Lemma 4.17 shows that  $\langle \mathbf{x}^{\perp} \rangle$  is not the whole space, and  $\langle \mathbf{x}^{\perp} \rangle$  is a hyperplane.

By  $\mathbb{H}_{\Gamma}$  we denote the set of all subsets  $\langle \mathbf{x}^{\perp} \rangle$ , where  $\mathbf{x}$  runs through the vertex set of  $\Gamma$ .

**Lemma 4.19.** The set  $\mathbb{H}_{\Gamma}$  is a subspace of  $\mathbb{P}_{\Gamma}^{\text{dual}}$  such that  $\mathbb{H}_{\Gamma}$  has trivial annihilator in  $\mathbb{P}_{\Gamma}$ .

Proof. Let  $\mathbf{x}$  and  $\mathbf{y}$  be two points of  $\Gamma$  with  $\langle \mathbf{x}^{\perp} \rangle \neq \langle \mathbf{y}^{\perp} \rangle$ . Denote by x and y the global points and by X and Y the global hyperplanes containing  $\mathbf{x}$  and  $\mathbf{y}$ , respectively. By Proposition 4.4 there exists a third vertex adjacent to  $\mathbf{x}$  and  $\mathbf{y}$ . Then, by Lemma 3.12, there exist adjacent vertices  $\mathbf{x}_1 \in X$  and  $\mathbf{y}_1 \in Y$  with  $\langle \mathbf{x}^{\perp} \rangle = \langle \mathbf{x}_1^{\perp} \rangle$  and  $\langle \mathbf{y}^{\perp} \rangle = \langle \mathbf{y}_1^{\perp} \rangle$ . We will show that the hyperpline on  $\langle \mathbf{x}^{\perp} \rangle$  and  $\langle \mathbf{y}^{\perp} \rangle$  is contained in  $\mathbb{H}_{\Gamma}$ . By the above we can assume that  $\mathbf{x}$  and  $\mathbf{y}$  are adjacent. We show that for every global point u, there is a point  $\mathbf{z}$  such that  $\langle \mathbf{x}^{\perp} \rangle \cap \langle \mathbf{y}^{\perp} \rangle \subseteq$ 

 $\langle \mathbf{z}^{\perp} \rangle$  and  $u \in \langle \mathbf{z}^{\perp} \rangle$ . Let  $\Pi$  be the hyperplane of  $\mathbb{P}_{\Gamma}$  containing  $\langle \mathbf{x}^{\perp} \rangle \cap \langle \mathbf{y}^{\perp} \rangle$  and u. The global line on x and y meets  $\Pi$  in a point outside  $\langle \mathbf{x}^{\perp} \rangle \cap \langle \mathbf{y}^{\perp} \rangle$ . So, without loss we may assume this intersection point to be u.

Let  $\mathbf{w}$  be adjacent to both  $\mathbf{x}$  and  $\mathbf{y}$ . Then both  $\mathbf{x}$  and  $\mathbf{y}$  are global points in  $\langle \mathbf{w}^{\perp} \rangle$  and hence so is  $\mathbf{u}$ . So, inside  $\mathbf{w}^{\perp} \cong \mathbf{H}(\mathbb{P}, \mathbb{H})$  we find a point  $\mathbf{z}$  such that  $\mathbf{z}^{\perp}$  meets all global points meeting  $\mathbf{x}^{\perp} \cap \mathbf{y}^{\perp} \cap \mathbf{w}^{\perp}$  and  $\mathbf{u}$ . Indeed, inside  $\mathbf{w}^{\perp}$  the hyperplane  $\langle \mathbf{z}^{\perp} \rangle$  of  $\mathbb{P}_{\Gamma}$  is the hyperplane containing  $\langle \mathbf{x}^{\perp} \rangle \cap \langle \mathbf{y}^{\perp} \rangle \cap \langle \mathbf{w}^{\perp} \rangle$  and  $\mathbf{u}$ . But then  $\langle \mathbf{z}^{\perp} \rangle$  contains  $\langle \mathbf{x}^{\perp} \rangle \cap \langle \mathbf{y}^{\perp} \rangle \cap \langle \mathbf{w}^{\perp} \rangle$  and  $\mathbf{w}$ , the global point on  $\mathbf{w}$ , and hence  $\langle \mathbf{x}^{\perp} \rangle \cap \langle \mathbf{y}^{\perp} \rangle$ . Moreover, as  $\mathbf{z}^{\perp}$  meets  $\mathbf{u}$ , it contains  $\Pi$  and hence coincides with  $\Pi$ .

It remains to show that the intersection of all elements in  $\mathbb{H}_{\Gamma}$  is empty. However, that easily follows from Lemma 4.17.

**Lemma 4.20.** Suppose x is a global point in  $\mathbb{P}_{\Gamma}$  and  $H \in \mathbb{H}_{\Gamma}$  is a hyperplane not containing x. Then there is a vertex  $\mathbf{x} \in x$  with  $\langle \mathbf{x}^{\perp} \rangle = H$ .

*Proof.* Suppose  $\mathbf{x} \in x$  and  $\mathbf{y}$  is a vertex of  $\Gamma$  with  $\langle \mathbf{y}^{\perp} \rangle = H$ . Then in  $\mathbf{z}^{\perp}$ , for some common neighbor  $\mathbf{z}$  of  $\mathbf{x}$  and  $\mathbf{y}$ , we find a vertex  $\mathbf{x}' \in x \cap Y$ , where Y is the global hyperplane on  $\mathbf{y}$ . But then, by Lemma 4.16,  $\langle \mathbf{x}'^{\perp} \rangle = H$ .

**Proposition 4.21.** Let  $\Gamma$  be a connected, locally  $H(\mathbb{P},\mathbb{H})$  graph. Then  $\Gamma$  is isomorphic to  $H(\mathbb{P}_{\Gamma},\mathbb{H}_{\Gamma})$ .

Proof. Consider the map  $\Gamma \to \mathbf{H}(\mathbb{P}_{\Gamma}, \mathbb{H}_{\Gamma}) : \mathbf{x} \mapsto (x, \langle \mathbf{x}^{\perp} \rangle)$  where x is the global point of  $\Gamma$  containing  $\mathbf{x}$ . We want to show that this is an isomorphism of graphs. Surjectivity follows from Lemma 4.18 and Lemma 4.20, since any point x of  $\mathbb{P}_{\Gamma}$  is a global point of  $\Gamma$  and any hyperplane in  $\mathbb{H}_{\Gamma}$  not containing it is of the form  $\langle \mathbf{x}^{\perp} \rangle$  for a vertex  $\mathbf{x} \in x$ . Injectivity is obtained as follows. Suppose the global point x contains two vertices  $\mathbf{x}_1$ ,  $\mathbf{x}_2$  with  $\langle \mathbf{x}_1^{\perp} \rangle = \langle \mathbf{x}_2^{\perp} \rangle$ . By Proposition 4.4 there exists a vertex  $\mathbf{y}$  adjacent to both  $\mathbf{x}_1$  and  $\mathbf{x}_2$ . Since  $\langle \mathbf{x}_1^{\perp} \rangle = \langle \mathbf{x}_2^{\perp} \rangle$ , both vertices describe the same hyperplane in  $\mathbf{y}^{\perp}$ . But they also describe the same point and hence have to be equal. Finally, if  $\mathbf{x} \perp \mathbf{y}$ , then, letting x and y be the global points of  $\Gamma$  containing  $\mathbf{x}$  and  $\mathbf{y}$ , respectively, we find  $x \in \langle \mathbf{y}^{\perp} \rangle$  and  $y \in \langle \mathbf{x}^{\perp} \rangle$ , so  $(\mathbf{x}, \langle \mathbf{x}^{\perp} \rangle) \perp (\mathbf{y}, \langle \mathbf{y}^{\perp} \rangle)$ .  $\square$ 

Theorem 1.1 is an immediate consequence of the above proposition and the Lemmas 4.19 and 4.20.

## 5. SMALL DIMENSIONS

In view of Proposition 2.3, any connected, locally  $\mathbf{H}_0$  graph is isomorphic to a clique of size two. Furthermore, it is easily seen that any connected, locally  $\mathbf{H}_1$  graph admits an infinite universal cover and we obtain infinitely many counterexamples to local recognition of  $\mathbf{H}_2$ . The case of a locally  $\mathbf{H}_2$  graph proves to be a bit more complicated. We can only offer a counterexample for  $\mathbb{F} = \mathbb{F}_2$ . The proof of its existence is based on a computation with the computer algebra package GAP [9].

**Proposition 5.1.** There exists a connected graph on 128·120 vertices that is locally  $\mathbf{H}_2(2)$ .

*Proof.* We determine the stabilizers of a vertex, an edge, and a 3-clique of the graph  $\mathbf{H}_3(2)$  inside the canonical group (P)SL<sub>4</sub>(2) and let GAP determine the order of the universal completion of the amalgam of these groups and their intersections. This universal completion is the group G with a presentation by the generators w, u, b, a and the relations

$$w^{2} = u^{2} = b^{2} = a^{2} = 1,$$
  
 $(wu)^{3} = (ab)^{3} = 1,$   
 $(bw)^{3} = (bu)^{4} = 1,$   
 $(wub)^{7} = (wa)^{2} = (ua)^{2} = 1.$ 

The stabilizers of a vertex, an edge, and a 3-clique of  $\mathbf{H}_3(2)$ , respectively, are of the form

$$\langle w, u, b \rangle \cong \operatorname{SL}_3(2),$$
  
 $\langle w, u, a \rangle \cong \operatorname{SL}_2(2) \times 2,$   
 $\langle a, b \rangle \cong \operatorname{Sym}_3,$ 

with the intersections

$$\langle w, u, b \rangle \cap \langle w, u, a \rangle = \langle w, u \rangle \cong \operatorname{SL}_2(2),$$
  
 $\langle w, u, a \rangle \cap \langle a, b \rangle = \langle a \rangle \cong 2,$   
 $\langle a, b \rangle \cap \langle w, u, b \rangle = \langle b \rangle \cong 2.$ 

A coset enumeration in GAP shows that the order of G is  $128 \cdot |SL_4(2)|$ , and that there exists a normal subgroup  $N \cong 2^{1+6}$  of G. Hence  $H_3(2)$  admits a 128-fold cover  $\Gamma$  with the same local structure.

This proposition shows that the bound on n in Theorem 1.1 is sharp. Besides the above universal cover of the canonical graph  $\mathbf{H}_3(2)$  nothing is known to us about locally  $\mathbf{H}_2(\mathbb{F})$  graphs. The methods that we have presented for  $n \geq 3$  do not apply in this case.

## 6. GROUP-THEORETIC CONSEQUENCES

In this section we study group-theoretic consequences of our local recognition Theorem 1.1 of the point-hyperplane graphs  $\mathbf{H}_n(\mathbb{F})$ , where  $n \geq 3$  is a finite integer and  $\mathbb{F}$  a skew field. In particular, we prove Theorem 1.2 and Theorem 1.3.

Proposition 6.1. Let G be a group as in the hypothesis of Theorem 1.2. Then  $\operatorname{PSL}_{n+2}(\mathbb{F}) \leq G/Z(G) \leq \operatorname{PGL}_{n+2}(\mathbb{F})$ .

Proof. We use the notation of Theorem 1.2. By (iii) of Theorem 1.2, we can choose an element  $z \in J \cap K$  that is a reflection in the groups J and K conjugate to x and y, respectively. Hence x is a reflection in J and y is a reflection in K. Note that z commutes with x and y. As, by (i),  $K \cong \mathrm{GL}_{n+1}(\mathbb{F})$ , we find the elements y and z to be conjugate in K by an involution. Similarly, by (ii), x and z are conjugate in J by an involution. Therefore the conjugation action of the group G induces an action as the group  $\operatorname{Sym}_3$  on the set  $\{x,y,z\}$  and as the group  $\operatorname{Sym}_2$  on the set  $\{x,y\}$ . Consider the graph  $\Gamma$  on all conjugates of x in G. A pair a,b of vertices of  $\Gamma$ is adjacent if there exists an element  $g \in G$  such that  $(gxg^{-1}, gyg^{-1}) = (a, b)$ . Since G induces the action of  $\text{Sym}_3$  on  $\{x,y,z\}$ , this definition of adjacency is completely symmetric, and we have defined an undirected graph. The elements x, y, z form a 3-clique of  $\Gamma$ . Define  $U_1$  to be the stabilizer in G of the vertex x, and define  $U_2$  to be the stabilizer in G of the edge  $\{x,y\}$ . The stabilizer of  $\{x,y\}$  permutes x and y and therefore interchanges  $C_G(x) \geq K$  and  $C_G(y) \geq J$ , see (i) and (ii). Hence the stabilizer of x together with the stabilizer of  $\{x,y\}$  generates G, as  $G = \langle J, K \rangle \leq \langle U_1, U_2 \rangle$ . Consequently, the graph  $\Gamma$  is connected. Also,  $\Gamma$  is locally  $\mathbf{H}_n(\mathbb{F})$  by construction. To prove this, it is enough to show that any triangle in  $\Gamma$  is a conjugate of (x,y,z). Let (a,b,c) be a triangle. Let  $g\in G$  with  $(gxg^{-1},gyg^{-1})=$ (a, b). Notice that  $b, d = gzg^{-1} \in gKg^{-1}$  are commuting reflections of  $gKg^{-1}$ . The edges (a,b) and (a,c) are conjugate in  $C_G(a) = gXg^{-1} \times gKg^{-1}$  (use (i) of Theorem 1.2). Choose  $h \in C_G(a)$  such that  $(hah^{-1}, hbh^{-1}) = (a, c)$ . Then  $h = h_X h_K$  with  $h_X \in gXg^{-1}$ ,  $h_K \in gKg^{-1}$ . The element  $h_X$  centralizes b and d, since  $b, d \in gKg^{-1}$ . Therefore  $c = hbh^{-1} = h_K bh_K^{-1} \in gKg^{-1}$  is a reflection of  $gKg^{-1}$ . Hence (a, b, d) and (a, b, c) are conjugate in  $gKg^{-1} \cong GL_n(\mathbb{F})$ . Therefore (a,b,c) and (x,y,z) are conjugate in G.

Thus, by Theorem 1.1, the graph  $\Gamma$  is isomorphic to  $\mathbf{H}_{n+1}(\mathbb{F})$ . Moreover, there is a kernel N of the action of G on  $\Gamma$ , such that G/N can be embedded in  $\mathrm{Aut}(\Gamma)$ , which has been determined in Corollary 3.10. Since G/N is transitive on  $\Gamma$  and the

stabilizer in G/N of the vertex x induces  $\operatorname{PGL}_{n+1}(\mathbb{F})$  on the neighbors of x, we find that  $\mathrm{PSL}_{n+2}(\mathbb{F}) \leq G/N$ . Furthermore, as G is generated by  $C_G(x)$  and  $C_G(y)$ , we

find that G/N embeds in  $PGL_{n+2}(\mathbb{F})$ .

. Let  $g \in N$ . Then g acts trivially on  $\Gamma$ , in particular it centralizes x and y, so we have  $g \in X \times K$  and  $g \in Y \times J$ . Let  $g_X \in X$  and  $g_K \in K$  be such that  $g = g_X g_K$ . The element  $g_X$  commutes with K, and therefore also centralizes all neighbors of x. Consequently, also  $g_K = g_X^{-1}g$  centralizes all neighbors of x, and hence lies in the center of K. We have proved that g commutes with K. Similarly, g commutes with J. This implies that g commutes with  $G = \langle J, K \rangle$ , and, thus,  $g \in Z(G)$ . Certainly, Z(G) acts trivially on  $\Gamma$ , whence N = Z(G).

The above proves Theorem 1.2. It only remains to prove Theorem 1.3. This will be done in the next proposition. Its proof proceeds along the lines of the proof of Theorem 1.2.

Proposition 6.2. Let G be a group as in the hypothesis of Theorem 1.3.  $G/Z(G) \cong \mathrm{PGL}_{n+2}(\mathbb{F}).$ 

*Proof.* With the notation as in the hypothesis of Theorem 1.3 we have the following. The element z is conjugate to both x and y, so, also x and y are conjugate. Moreover, x and y are generalized reflections in J and K, respectively. Note that z commutes with x and y. As  $K \cong \mathrm{SL}_{n+1}(\mathbb{F})$ , we find the elements y and z to be conjugate in K by an involution. Similarly, x and z are conjugate in J by an involution. Therefore the conjugation action of the group G induces an action as the group  $\operatorname{Sym}_3$  on the set  $\{x,y,z\}$  and as the group  $\operatorname{Sym}_2$  on the set  $\{x,y\}$ . Consider the graph  $\Gamma$  on all conjugates of  $\langle x \rangle$  in G. A pair a, b of vertices of  $\Gamma$  is adjacent if there exists an element  $g \in G$  such that  $(g\langle x \rangle g^{-1}, g\langle y \rangle g^{-1}) = (a, b)$ . As in the proof of Proposition 6.1, the graph  $\Gamma$  is connected.

Let (a,b,c) be a triangle of  $\Gamma$ . We will show that (a,b,c) is also conjugate to  $(\langle x \rangle, \langle y \rangle, \langle z \rangle)$ . Without loss of generality, we can assume that  $a = \langle x \rangle$  and  $b = \langle y \rangle$ . The edges (a,b) and (a,c) are conjugate in  $N_G(a)$ . Choose  $h \in N_G(a)$  such that  $(hah^{-1}, hbh^{-1}) = (a, c)$ . Since  $C_G(a)$  is normal in  $N_G(a)$ , and K is characteristic in  $C_G(x)$ , we find that h normalizes K. Therefore  $c = hbh^{-1}$  is a group of order p generated by a generalized reflection of K. But then  $(b,\langle z\rangle)$  and (b,c) are conjugate inside  $K \cong \mathrm{SL}_{n+1}(\mathbb{F})$ . As  $K \leq C_G(a)$  we find the triangles (a,b,c) and  $(\langle x \rangle, \langle y \rangle, \langle z \rangle)$ to be conjugate in G.

As each generalized reflection torus is cyclic and thus contains a unique subgroup of order p, we find  $\Gamma$  to be locally  $\mathbf{H}_n(\mathbb{F})$ . But that implies, by Theorem 1.1, that

the graph  $\Gamma$  is isomorphic to  $\mathbf{H}_{n+1}(\mathbb{F})$ .

Let N be the kernel of the action of G on  $\Gamma$ . Then, as in the proof of Theorem 1.2, we see that  $G/N \leq \operatorname{PGL}_{n+2}(\mathbb{F})$ . In particular,  $K \cap N = 1$  and, since G is generated by J and K, we even have  $G/N = \mathrm{PSL}_{n+2}(\mathbb{F})$ . Moreover, as  $N \leq N_G(\langle x \rangle)$  and K is normal in  $N_G(\langle x \rangle)$ , we find  $[N,K] \leq K \cap N = 1$ . Similarly, [N,J] = 1 and hence  $N \leq Z(\langle K, J \rangle) = Z(G)$ , which completes the proof of the proposition, as Z(G) is in the kernel of the action by construction of  $\Gamma$ .

## REFERENCES

<sup>[1]</sup> Francis Buckenhout and Xayier Hubaut, Locally polar spaces and related rank 3 groups, J. Algebra, 45 (1977), 391-434.

- [2] Arjeh M. Cohen, Local recognition of graphs, buildings, and related geometries, in William M. Kantor, Robert A. Liebler, Stanley E. Payne, and Ernest E. Shult, editors, Finite Geometries, Buildings, and related Topics, pages 85-94, Oxford Sci. Publ., New York, 1990.
- [3] Arjeh M. Cohen, Hans Cuypers, and Hans Sterk, Linear groups generated by reflection tori, Canad. J. Math. 51 (1999), 1149-1174.
- [4] Hans Cuypers, Nonsingular points of polarities, Technische Universiteit Eindhoven, 1999.
- [5] Ralf Gramlich, On Graphs, Geometries and Groups of Lie Type, PhD thesis, Technische Universiteit Eindhoven, 2002.
- [6] Jonathan I. Hall, Locally Petersen graphs, J. Graph Theory 4 (1980), 173-187.
- [7] Jonathan I. Hall, A local characterization of the Johnson scheme, Combinatorica 7 (1987), 77-85.
- [8] Mark A. Ronan, On the second homotopy group of certain simplicial complexes and some combinatorial applications, Quart. J. Math. Oxford Ser. (2) 32 (1981), 225-233.
- [9] Martin Schönert et al., GAP Groups, Algorithms, and Programming, Rheinisch Westfälische Technische Hochschule, Aachen, 1995.
- [10] Graham M. Weetman, A construction of locally homogeneous graphs, J. London Math. Soc. (2) 50 (1994), 68-86.
- [11] Graham M. Weetman, Diameter bounds for graph extensions, J. London Math. Soc. (2) 50 (1994), 209-221.

DEPARTMENT OF MATHEMATICS AND COMPUTER SCIENCE, TECHNISCHE UNIVERSITY EINDHOVEN, P.O. Box 513, 5600 MB EINDHOVEN, THE NETHERLANDS

E-mail address: {amc,hansc,squid}@win.tue.nl