

# Optimum path and discrete 3D forming

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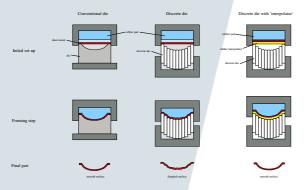
**TU/e** technische universiteit eindhoven Optimum path and discrete 3D forming

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## Introduction

Discrete die forming is a useful concept in a small-lot production environment because different products can be made with the same reconfigurable die and many resources are saved. From a scientific point of view: a discrete die allows a changing strain path during forming; products with an optimized internal strain distribution can be produced, e.g. the lifetime of parts carrying cyclic (thermal) loading can be enhanced considerably.



**Figure 1** *Rubber pad forming with conventional die, reconfigurable die and interpolator.* 

### Objective

A numerical tool to calculate, using non-proportional forming-limit diagrams, time-varying boundary conditions of a deformation process, yielding different internal strain distributions in geometrically identical products. Validation will be done by using an experimental set-up. The numerical tool controls the internal strain distribution by means of nonproportional forming-limit diagrams.



**Figure 2** *Prototype of discrete die, surface dimensions: 20x30 mm, forming pressures up to 5 ton.* 

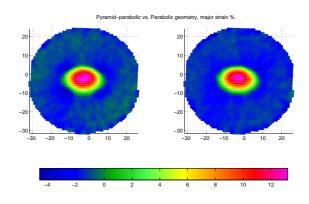
## Methods

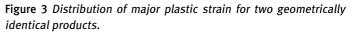
- Experimental deformation process with discrete die prototype in which the strain path is variable.
- Determination of strain distribution and product geometry with photogrammetry technique.
- Numerical algorithm, providing boundary conditions for an optimal deformation process.

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## Results

Using the discrete die and photogrammetry technique, two geometrically equal products are produced with different strain distributions.





Using the reconfigurable die, a product without defects is produced with an intermediate forming step.

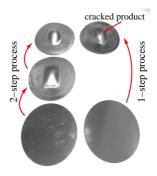


Figure 4 Multi-step forming experiment with discrete die.

#### Discussion

- Non-proportional loading tests must be done for model input.
- □ Implement numerical tool within FEM framework.
- □ Criterion must be formulated to determine optimal strain distribution.
- □ Automated control of discrete die is preferable.

#### References

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