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## Real-time control of tearing modes and current density profile in TCV

#### **Federico Felici**

O. Sauter, T.P. Goodman, S. Coda, B.P. Duval, J-M. Moret, J.X. Rossel, J.I. Paley and the TCV team

CRPP-EPFL, Association Euratom-Suisse, CH-1015 Lausanne Switzerland

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http://crpp.epfl.ch federico.felici@epfl.ch

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## **Outline and summary**

- Part I: Studies of effects of ECRH/ECCD on tearing mode creation and stabilization using real-time control
  - Tearing modes created on TCV by global *q* profile evolution via deltaprime effects.
  - Experiments using real-time control were performed to study the effect of localized ECCD on the island.
  - Results point towards dominant effect of heating with some specific effects due to current drive.
- Part II: Real-time simulation and control of current density profile
  - Implemented on TCV with closed loop experiments performed.

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- Part I: Studies of effects of ECRH/ECCD on tearing mode creation and stabilization using real-time control
  - Objective of these experiments: separate direct ECH/ECCD effects on island through  $\Delta'_{CD}$  and q profile effects through  $\Delta'_0$
  - Results of recent experiments, enabled by real-time control system, are presented here. Modeling will be focus of future work.

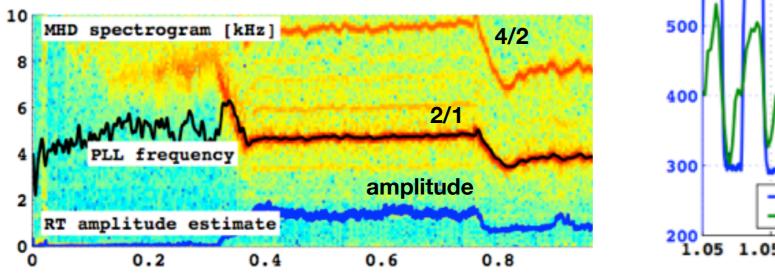
$$\frac{dw}{dt} \sim \Delta'_0 + \Delta'_{BS} + \Delta'_{CD} + \Delta'_H$$
 affected by ECCD

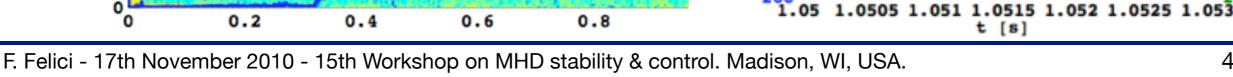
### **Recently expanded capabilities for NTM experiments on TCV** thanks to new digital real-time control system

- 6 independently real-time steerable EC launchers (500kW each) 0
- Gyrotron power supply modulation possible, 40-100% duty cycle. 0
  - 0%-100% for <600ms</li>

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- New digital real-time control system is operational 0
  - **Real-time NTM detection**
  - Phased Lock Loop (PLL) for in-phase firing
  - Simultaneous control of
    - Mirror position
    - ECCD power
    - Modulation phase
    - Modulation depth
  - Flexible, rapid inter-shot reprogramming using Simulink





Detail of time traces (3)

Forward ECH power [kW]

Bpol signal [au]

600

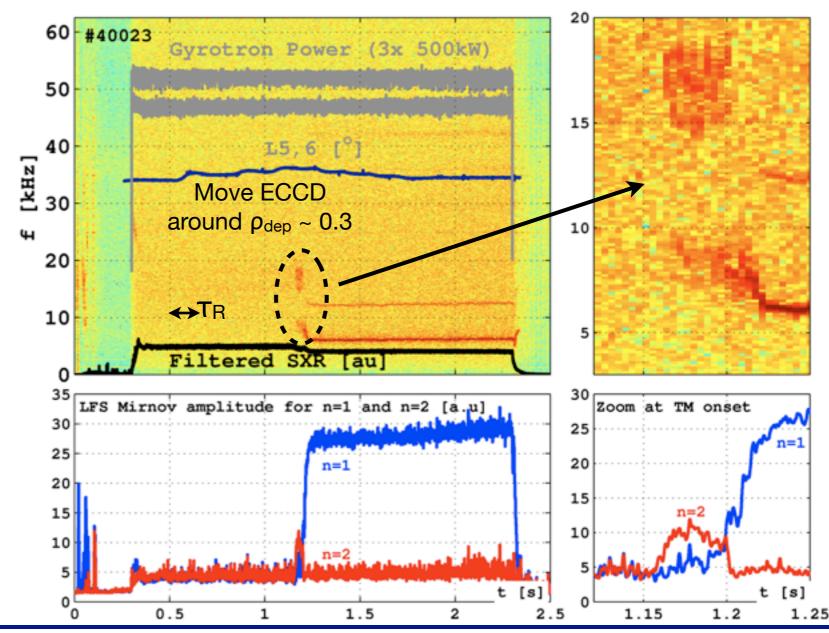
# **Δ'**<sup>0</sup> destabilized modes created on TCV by global *q* profile changes using near on-axis ECCD

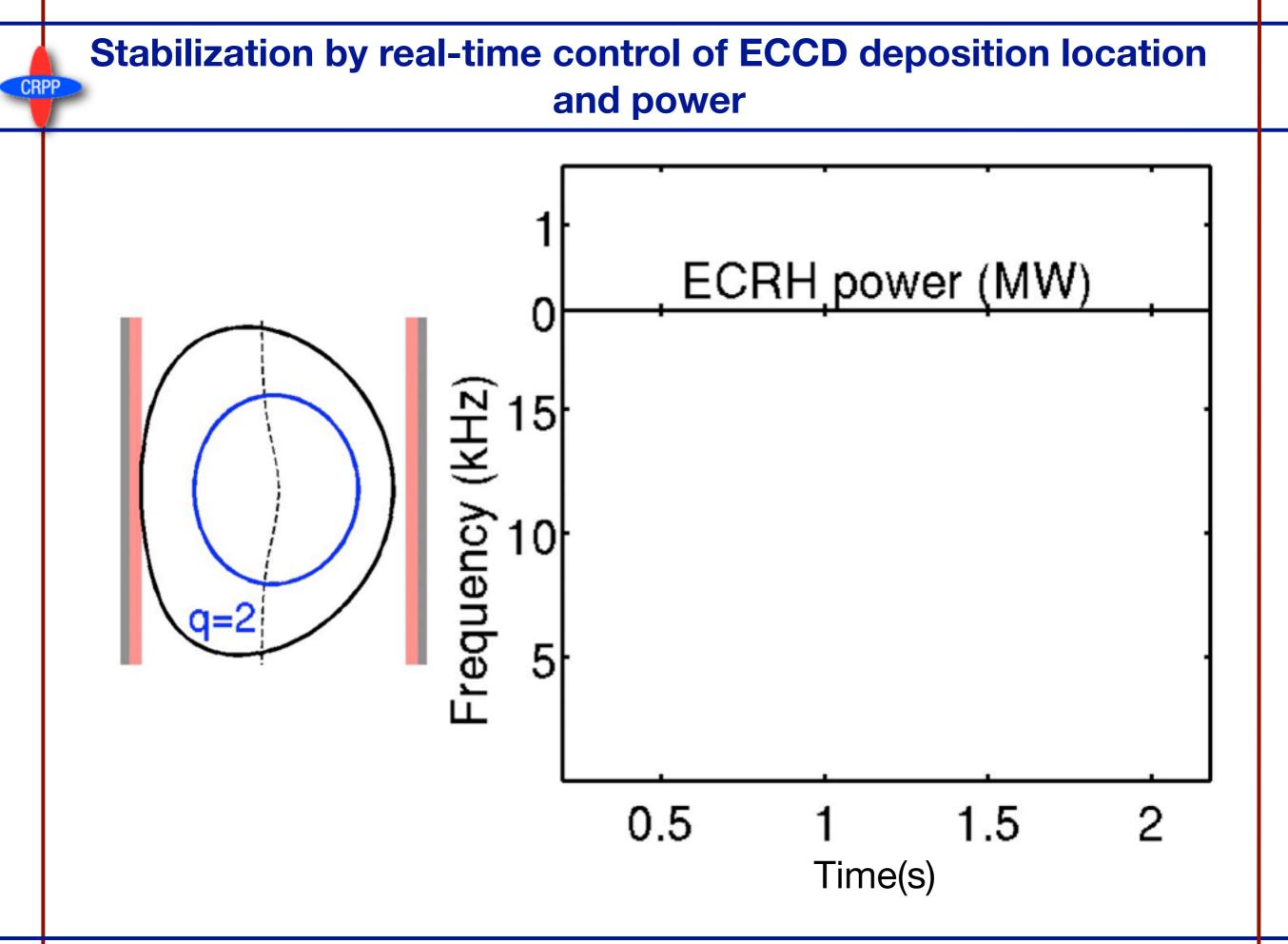
 No clear trigger from sawteeth in these cases

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- Sawtooth triggered NTMs have been seen on TCV with long, large, stabilized sawteeth (not these shots)
- 3/2 mode precursor observed
  - Suppressed by 2/1 growth
- Use these modes as target for stabilization experiments

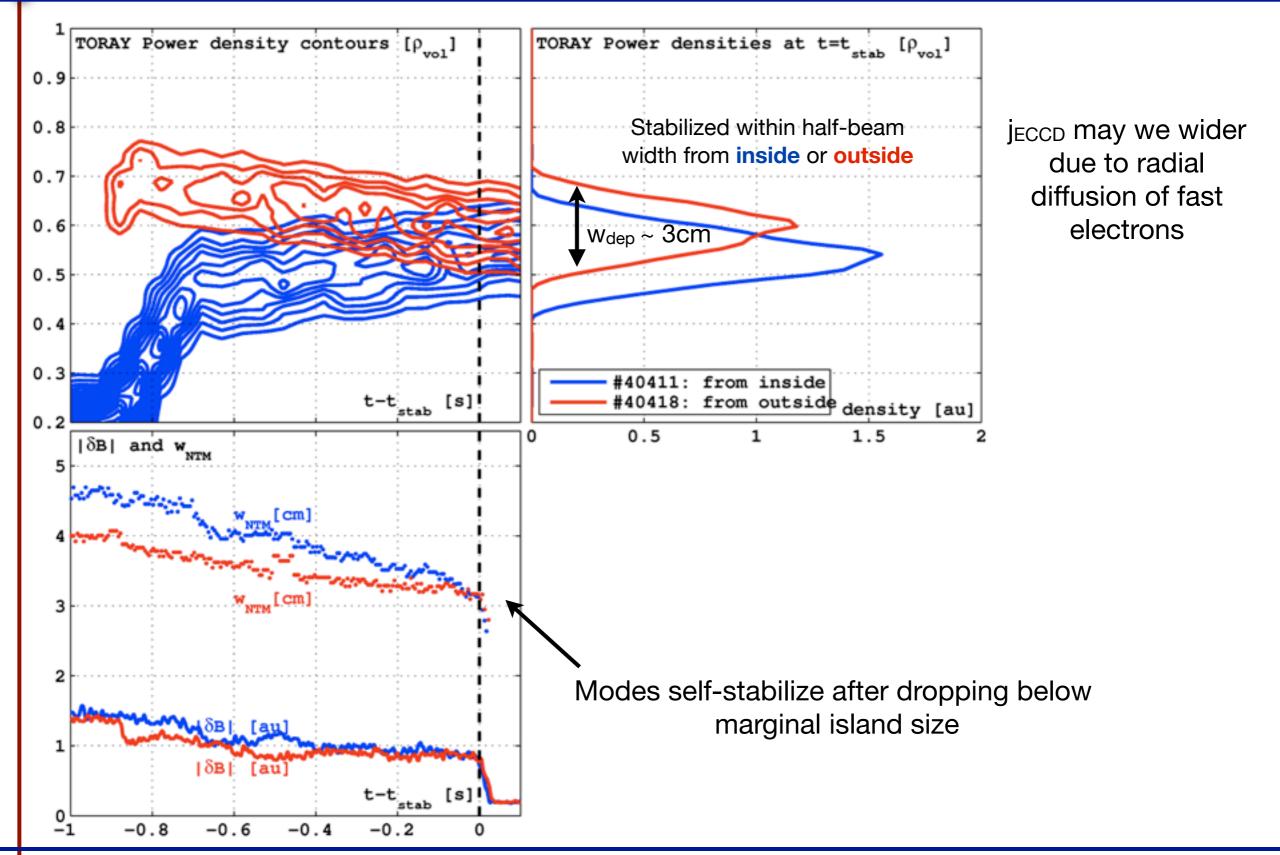
Typical parameters for these discharges:  $I_p=150kA B_T=1.45T q_{95}\sim 6$   $T_{e0} = 3keV n_{e0} = 1.5x10^{19} m^{-3}$   $\beta_{pol}\sim 0.7, \beta_{tor}\sim 0.3\%, \beta_{N}\sim 0.8$ L-mode plasmas



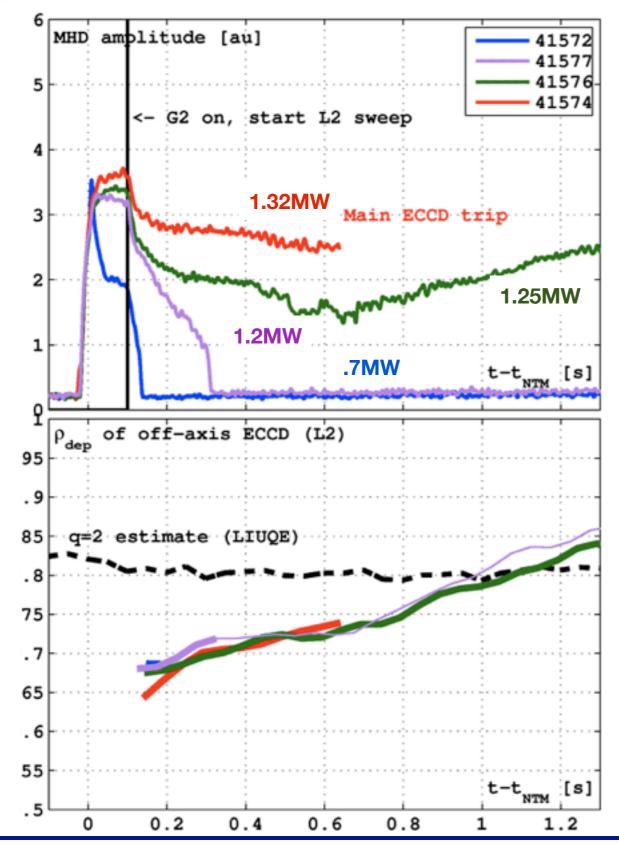


## Mode stabilized both from inside and outside q=2 once mode shrunk to marginal island width

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# Create modes of varying strength by varying central EC power after TM is triggered



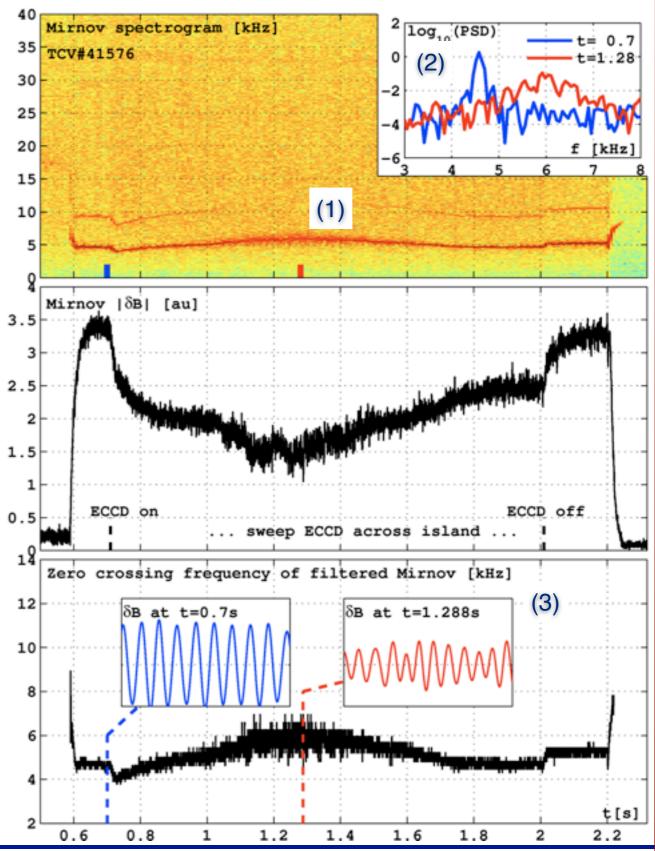
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- Can create modes of varying strength by varying central ECCD
- Angle scan across mode -> different response to ECCD close q=2
  - Stabilized immediately upon off-axis EC power on (blue)
  - Stabilized only after longer time (violet)
  - Almost stabilized but not fully, even upon sweep across island (green)
- Marginal case used for subsequent studies

### Mode near marginal island size shows increased variance in Mirnov probe oscillation frequency

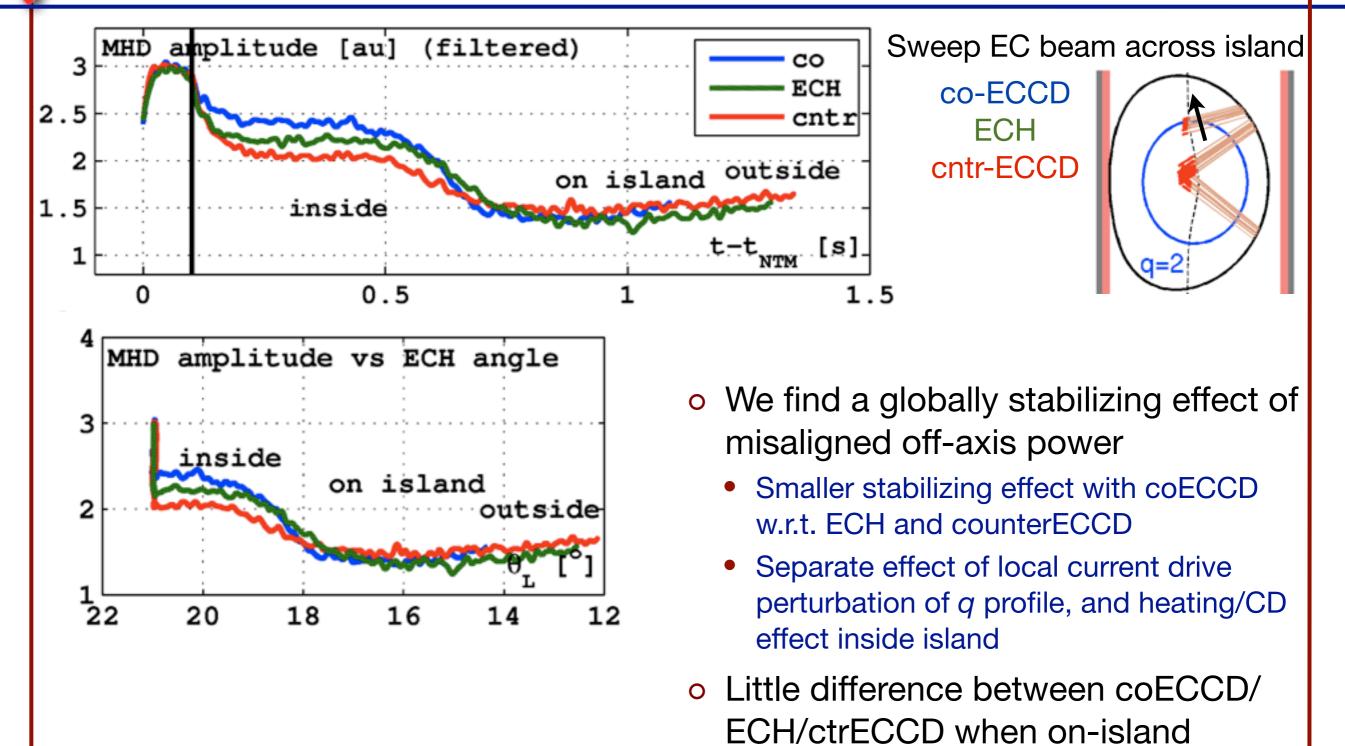
- "Fuzzy" NTMs near marginal island limit
- Variance of oscill. freq is visible as:
  - (1) "Fuzziness" in spectrogram
  - (2) Broader power spectral density
  - (3) Less regular oscillations in Mirnov
- Also appears in last phases of mode before full stabilization
- Possible consequences for in-phase ECCD modulation
  - Windowing methods not adequate? (FFT)
  - Should use time-based methods? (PLL)
- o Seen in other machines?
- o Physics origin?

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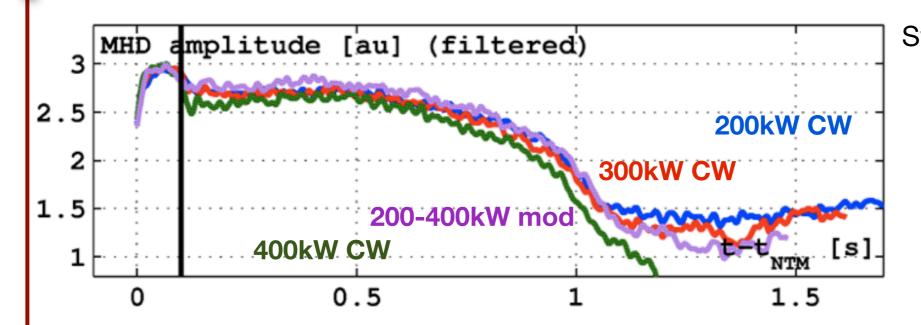
#### Misaligned ECCD deposited to the inside of the island is expected to be destabilizing [Westerhof1990]

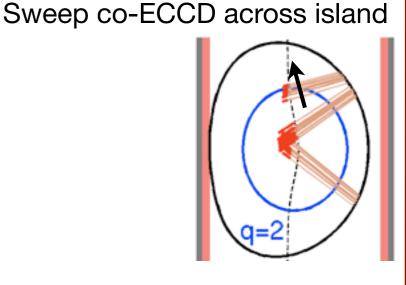
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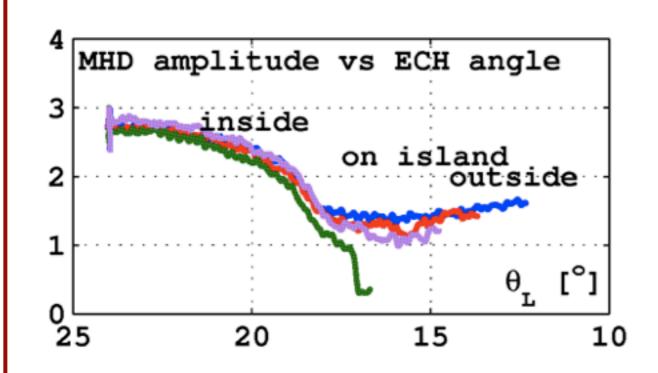


• May be dominated by heating effects

# Using all available CW power is more effective than partial power modulation in this case







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- Scan of CW powers and modulation
  - chose phase giving best stabilization.
- Full available CW power stabilizes mode.
- Modulated power is slightly more effective than mean power (but only when on-island)
  - Small effects, should become clearer by increasing current drive contribution

## **Conclusions and outlook for tearing mode studies**

#### Experimental results of detailed NTM studies

- NTMs classically destabilized by q profile evolution
- Metastable limit can be approached and studied, found "Fuzzy" NTMs, small island effects
- Observed Westerhof effect of local current drive just inside of island
- Modulation effects not very strong in this configuration.
- Modeling based on MRE is planned

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- Further experiments including full power modulation
- Ideas are welcome for cross-machine benchmarking and comparisons.



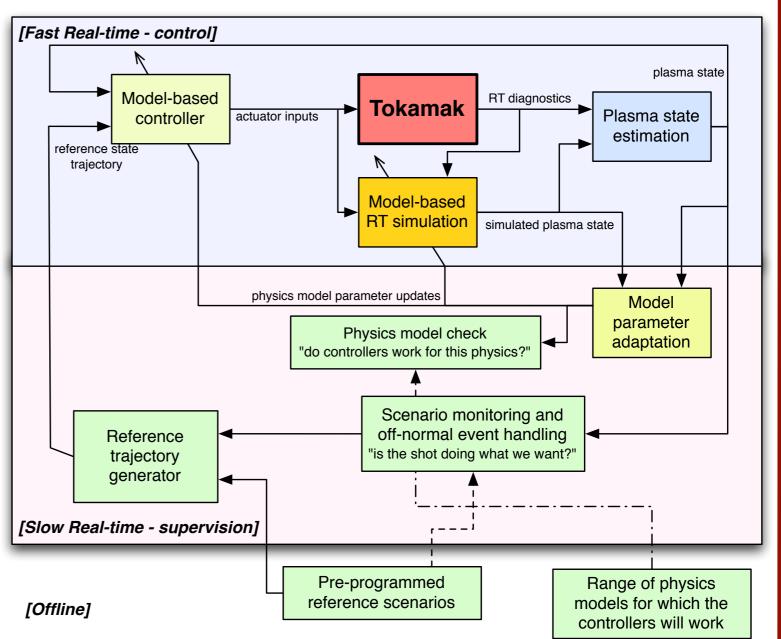
### • Part II: Real-time simulation and control of current density profile

### Real-time simulations: at the heart of future advanced Tokamak operation & control

- Today: run interpretative transport simulations post-shot
  - Combine diagnostic data to get kinetic profiles, simulate current profile, update equilibrium
- Tomorrow: routinely run interpretative simulations in real-time
  - Numerically evolve the plasma in a computer, while evolving in physically in the Tokamak
- Possible uses

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- Plasma state estimation
- Physics parameter estimates
- Adaptive model-based control
- Scenario monitoring & safety
- Predictive control

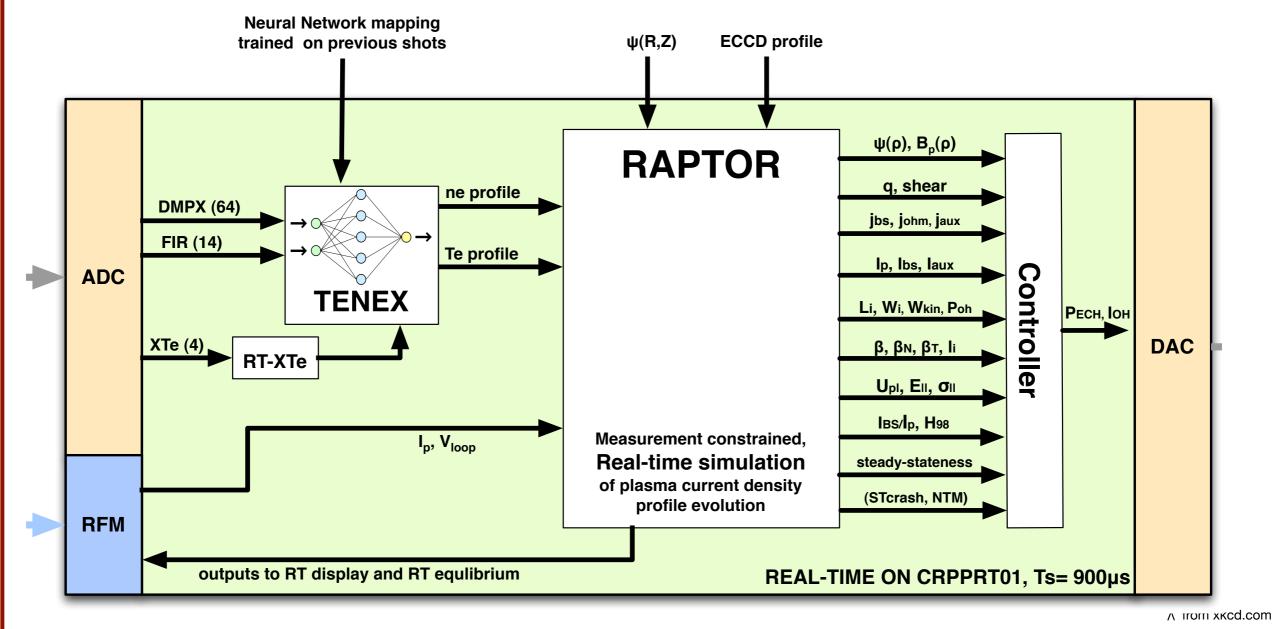


#### Implementation of fast real-time transport code "RAPTOR" in TCV digital control system

- RApid Plasma Transport Simulator 1D  $\psi(\rho)$  transport, finite elements
- o Te( $\rho$ ), ne( $\rho$ ) profile estimates by combining Xray and interferometer data
  - One time step per 0.9ms (τ<sub>R</sub>~150ms, shot time ~2s)

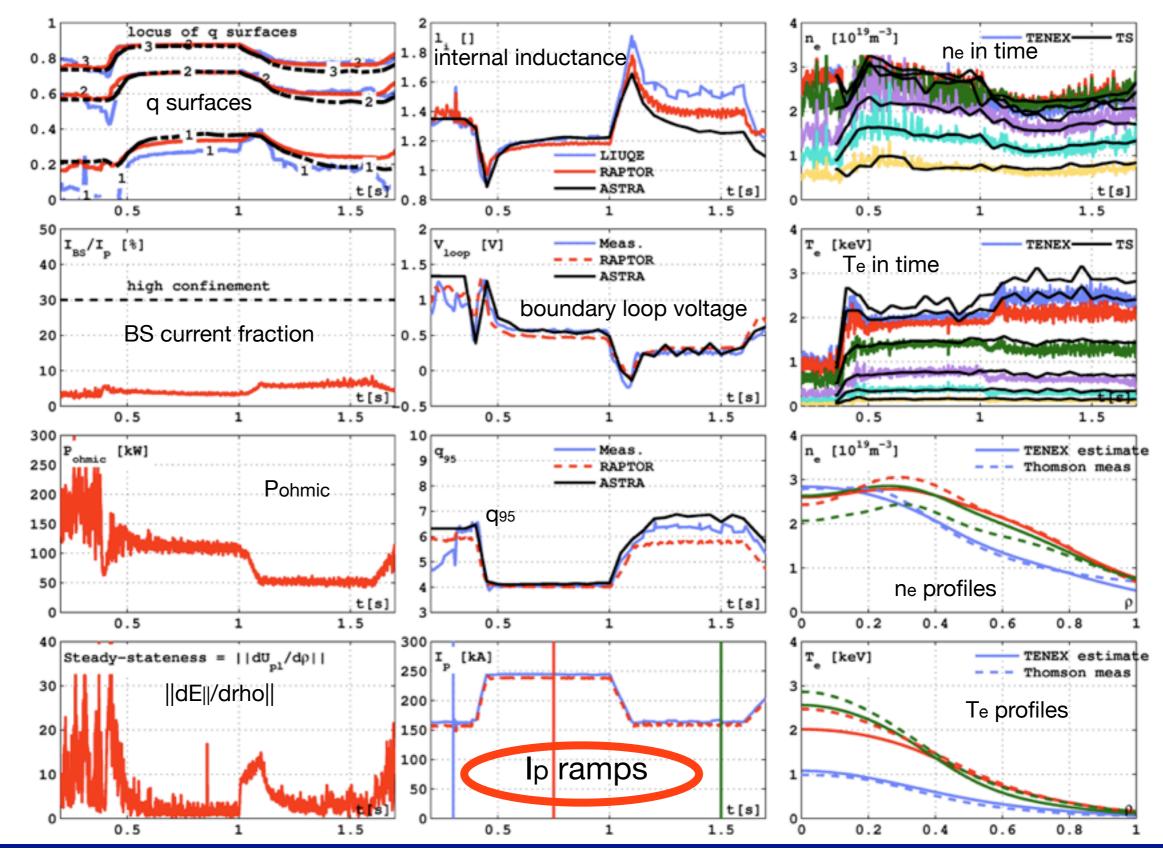
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o Outputs are available which often difficult or impossible to measure



#### Experiments confirm that RT-RAPTOR gives good results compared to off-line transport modeling

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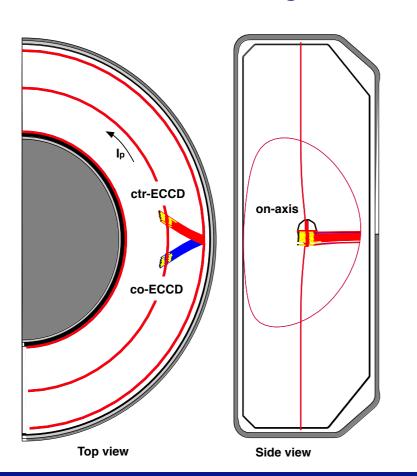


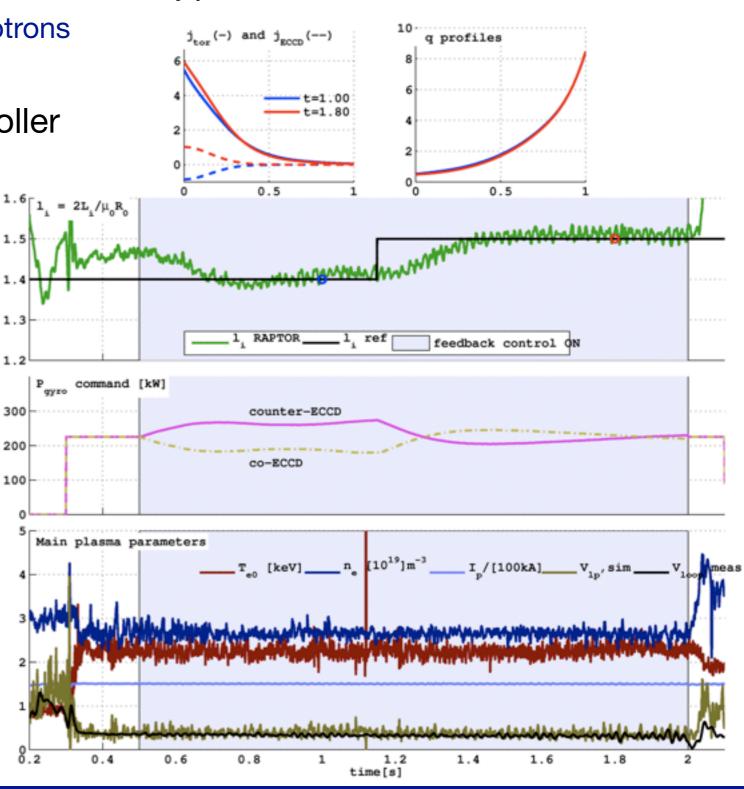
### First closed-loop experiments: feedback control of internal inductance using co/counter on-axis ECCD

- On-axis co-counter ECCD, peak or flatten j profile
  - Control ratio of powers in two gyrotrons
  - Effect on li

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- Use proportional-integral controller
  - Tracks reference step change in li
- Comparison to off-line data
  - Vertical position drift cause reality and simulation to diverge





## Thank you

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