## Few-distance sets

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## FEW-DISTANCE SETS


A. BLOKHUIS

FEW-DISTANCESETS

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PROEFSCHRIFT

TER VERKRIJGING VAN DE GRAAD VAN DOCTOR IN DE TECHNISCHE WETENSCHAPPEN AAN DE TECHNISCHE HOGESCHOOL EINDHOVEN, OP GEZAG VAN DE RECTOR MAGNIFICUS, PROF. DR. S.T.M. ACKERMANS, VOOR EEN COMMISSIE AANGEWEZEN DOOR HET COLLEGE VAN DEKANEN IN HET OPENBAAR TE VERDEDIGEN OP VRIJDAG 30 SEPTEMBER 1983 TE 16.00 UUR

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## INTRODUCTION

The vertices of a regular ( $2 s+1$ )-gon in the plane form a set of points on the circle with the property that the distance between different points assumes only $s$ different values. It is easy to see that $2 \mathrm{~s}+1$ is the maximal cardinality of such a set since, starting with any point on the circle, there are at most two points at a prescribed distance away from it. If we denote by $f(s, d)$ the maximal number of points on the unit sphere in d-dimensional space $R^{d}$, constituting an $s$-distance set, then exactly the same reasoning yields an exponential bound in $d$ by the inequality $f(s, d) \leq 1+s f(s, d-1)$. If $s$ is dmall compared to $d$, all known examples indicate that the proper bound should be polynomial in $d$, of degree s. Using ingredients from the theory of harmonic analysis, especially the addition theorem for Gegenbauer polynomials, Delsarte, Goethals and Seidel [DGS] showed that this is the case. Koornwinder [K] gave a simpler argument, yielding the same absolute bound and avoiding harmonics. His method is to associate with an s-distance set $X$ on the unit sphere in $R^{d}$, an independent set of $|X|$ polynomials of degree $s$ in $d$ varíables. Hence the cardinality of $X$ is bounded by dim Pol (s, d ) , i.e., the dimension of the space of polynomials of degree at most $s$, in d variables.

Koornwinder's method is applicable in many cases, however if we consider sets of vectors with few inner products in an arbitrary inner product space, this method does not depend on the signature of the inner product. With the harmonic method we can do better in case of an indefinite inner product, i.e., the vector space $R^{p, q}$ provided with the inner product $(x, y)=x_{1} y_{1}+x_{2} y_{2}+\ldots+x_{p} y_{p}-x_{p+1} y_{p+1}-\ldots-x_{p+q} y_{p+q}$, of signature ( $p, q$ ). This is done in chapter 2, which is joint work with Bannai, De1sarte and Seidel [BBDS]. First we prove a generalized version of the addition formula, which is of independent interest. Then we apply it to few-distance sets in indefinite inner product spaces. For example theorem 2.8.1. reads as follows: Let $X$ be a set of unit vectors in $R^{d-1,1}$, such that the inner product between different
elements of $X$ assumes only $s$ different values (all different from 1 ). Then $\operatorname{card}(X) \leq\binom{ d+s-1}{s}$.
We conclude this chapter with examples, e.g.: The maximal number of vectors in $R^{9,1}$ having inner products $\left\{0, \pm \frac{1}{2}\right\}$ is exactly 165 .

Another way to obtain better bounds is to start with Koornwinder's method, but to show that one can actually construct a larger independent set of polynomials. In chapter 3 this approach yields an essentially sharp bound on the number of equiangular lines in $\mathbb{R}^{d, 1}$ viz. theorem 3.2.1. : Let $X$ be a set of equiangular lines in $R^{d, l}$ at angle $\arccos (\alpha)$. Then
(i) if $(d+1) a^{2}<1, \quad \operatorname{card}(X) \leq d\left(1-\alpha^{2}\right) /\left(1-d a^{2}\right)$;
(ii) if $(d+1) \alpha^{2} \geq 1, \quad \operatorname{card}(x) \leq \frac{1}{2} d(d+1)$.

The first case is proved using the eigenvalue method and is called the special bound.

In chapter 4 , we apply the same idea to improve the bounds for s-distance sets in Euclidean d-space, $E^{d}$, and hyperbolic d-space, $H^{\text {d }}$. In these cases we get the following result: Let $X$ be an s-distance set in $E^{d}$ or $H^{d}$, then $\operatorname{card}(X) \leqslant\left(\begin{array}{c}d+s\end{array}\right)$.
The bound for $H^{d}$ can also be derived from the results in chapter 2. It is still an open question whether an harmonic analysis approach could give the bound for $\mathrm{E}^{\mathrm{d}}$ as well.

An interesting idea, due to Frankl and Wilson [FW], is to consider sets of points with few distances modulo a prime. In chapter 5 a useful number theoretic lemma is combined with Koornwinder's argument to give a.o. the following result (theorem 5.3.1.): Let $X$ be a set of vectors in $R^{d}$ such that there are integers $a_{1}, \ldots, a_{s}$ with
(i) $(x, x) \neq a_{i}(\bmod p),(x, x) \in Z$ for all $x \in X, 1 \leq i \leq$.
(ii) $(x, y) \equiv a_{i}(\bmod p)$ for some $i, 1 \leq i \leq s$, if $x \neq y \in X$.

Then $\operatorname{card}(X) \leq\binom{ d+s}{s}$.
In chapter 6 , the same leman is applied to the more natural question of few-distance sets modulo a prime in Delsarte spaces, a notion
due to Neumaier [N1] and Delsarte. Since the basic text is not generally available, we repeat the basic theory of Delsarte spaces and association schemes in this chapter. As a corollary of the mod $p$ bound for Delsarte spaces we obtain the result of Frankl and Wilson and also the following theorem: Let $X$ be a collection of subsets from an n-set, such that for any $x \not y \in X:|x \Delta y| \in T$, where $T$ is the union of $t$ non-zero residue classes mod $p$. Then card $(X) \leq\binom{ n}{t}$. This chapter finishes with a series of examples meeting this bound. Part of the work in this chapter is joint work with Singhi.

In chapter 7 a relation between two-distance sets and a problem of Erdös is demonstrated. Isosceles sets are sets of points, such that each triple among them determines an isosceles triangle. We show that an isosceles set in $E^{d}$ can be decomposed in a collection of "mutually orthogonal" two-distance sets. As a result the following bound is obtained (theorem 7.2.5.): Let $X$ be an isosceles set in $E^{d}$, then card $(X) \leq \frac{1}{2}(d+1)(d+2)$. Equality implies that $X$ is a two-distance set or a spherical two-distance set together with its center. Crucial in the proof of the decomposition theorem is the following graph-theoretical proposition: Let the edges of the complete graph on $n$ vertices be colored by $k$ colors, such that
(i) each triangle has at most two colors ;
(ii) the induced graph on each color is connected.

Then there are at most two colors.
In chapter 8 , which contains joint work with Wilbrink and Kloks, the same proposition plays a key rôle in the study of the structure of graphs satisfying the following two regularity conditions:
(i) There is a constant $K$, such that every maximal clique has size $K$.
(ii) There is a constant $e$, such that for every maximal clique $C$ and every vertex $p$ not in $C$, there are exactly $e$ vertices in $C$, adjacent to $p$.

These graphs were introduced by Zara [Z] in an attempt to characterize polar spaces (in the sense of Veldkamp and Tits). The main result in
this chapter is theorem 8.5.11 : Let $G$ be a coconnected Zara-graph of rank $r$, then the reduced graph of $G$, say $G^{\prime}$, is again a coconnected Zara-graph and the partially ordered set of closed cliques in $G$ ' is an $\mathrm{M}_{\mathrm{r}}$-space in the sense of Neumaier [ N ].

## CHAPTER 2

THE ADDITION FORMULA FOR $R^{p, q}$

## §2.1 Introduction

In [DGS], the authors investigate few-distance sets on the sphere in Euclidean d-space, $\mathrm{R}^{\mathrm{d}}$. If a two-distance set is considered, then a "lifting" process results in a set of equiangular lines, either in $\mathrm{R}^{\mathrm{d}+1}$ cf. [vLS], or in $R^{d, 1}$. In this way the 5 points of the regular pentagon correspond to the 6 diagonals of the icosahedron. This is one of the reasons to study the problem of few-distance sets and sets of lines with few angles in the more general setting of an arbitrary inner product space.

If we want to apply the same techniques as in [DGS] we need a generalization of the addition formula for Gegenbauer polynomials. The addition formula reads as follows:

$$
\gamma_{k} G_{k}^{(d-2) / 2}((x, y))=\sum_{i=1}^{\mu_{k}} f_{k, i}(x) f_{k, i}(y)
$$

Here $C_{k}^{(d-2) / 2}$ is a Gegenbauer polynomial, with a scaling factor $\gamma_{k}$, while $x$ and $y$ are unit vectors in $R^{d}$, provided with the standard inner product $(x, y)$. The $\left\{f_{k, i}\right\}$ form an orthonormal basis of the space of the homogeneous harmonic polynomials of degree $k$, with respect to the inner product

$$
\langle f, g\rangle=\frac{1}{|\Omega|} \int_{\Omega} f(x) g(x) d \omega(x)
$$

Here $\Omega$ stands for the unit sphere in $\mathrm{R}^{\mathrm{d}}$.

From this representation of the inner product the difficulty in deriving a generalized addition formula becomes apparent: In the case of an indefinite space we no longer have a compact unit sphere, so we have to define the inner product on the space harm( $k$ ) of homogeneous harmonic polynomials of degree $k$ in $d$ variables in a different way. To do this we introduce differential operators and the algebra of symmetric tensors ,cf. [BBDS] . It turns out that the new inner product gives back the "old" addition formula in the Euclidean case, while in the indefinite case we still get Gegenbauer polynomials, the only difference being that the inner product on the space harm(k) is no longer positive definite. This fact enables us to improve the bounds for few-distance sets in indefinite space. In the most interesting case of hyperbolic space, $R^{d, 1}$, we obtain equality in a number of examples.

The main objective in this chapter is to give the setting for the more general inner product. The application to few-distance sets is essentially the same as in [DGS].

## §2.2. Polynomials and tensors

Let $V$ denote a real d-dimensional vector space and let $\left(v^{1}, v^{2}, \ldots, v^{d}\right)$ be any basis of $v$. Let $s^{\star}$ denote the algebra of polynomial functions on $V$; thus $S^{\star}$ consists of the functions f : $V \rightarrow R$ that are represented by polynomials in the coordinates with respect to the basis $\left(v^{1}, \ldots, v^{d}\right)$. Next let $S$ denote the symmetric algebra on $V$, consisting of the symmetric tensors

$$
s=\sum_{a} s_{a_{1} a_{2} \ldots a_{d}}{ }^{a_{1}} v^{1} \ldots \&^{a_{d_{v}}}
$$

with $s_{a} \in R$ and $a=\left(a_{1}, a_{2}, \ldots, a_{d}\right)$, only a finite number of the $s_{a}$ being non-zero.

Let Aut $V$ denote the automorphism group of $V$. The action of an element $\sigma \in$ Aut $V$ will be written in the form $x \in V \rightarrow x^{\sigma} \in V$. The group Aut $V$ acts as an algebra automorphism group on both $S^{\star}$ and $S$ according to the following rules. The image $f^{\sigma}$ of a polynomial $f \in S^{*}$ is defined by $f^{\sigma}(x)=f\left(x^{\sigma^{-1}}\right)$. The image of a symmetric tensor $s \in S$
is defined by

$$
s^{\sigma}=\sum_{a} s_{a^{\infty}}{ }^{a}\left(v^{1}\right)^{\sigma} \ldots \otimes^{a} d_{\left(v^{d}\right)^{\sigma}}
$$

## §2.3. Differential operators.

To any vector $w \in V$ corresponds the directional derivative $\partial_{w}$, which is the linear operator on $S^{*}$ defined by

$$
\begin{equation*}
\left(\partial_{w} f\right)(x)=\lim _{h \rightarrow 0} h^{-1}[f(x+h w)-f(x)], \tag{1}
\end{equation*}
$$

for $x \in V$ and $f \in S^{*}$. We extend this definition to the whole algebra $S$ by associating the differential operator $\partial_{s}=\Sigma s_{a} \partial_{1}{ }^{a_{1}} \ldots \partial_{d}{ }^{a_{d}}$, where $\partial_{i}=\partial_{v}$, to the symmetric tensor

$$
s=\sum_{a} s_{a}^{a} I_{v} 1_{\theta^{a_{2}} v^{2}}^{\ldots}{ }^{a_{d} d}
$$

Note the property $\partial_{s \otimes t}=\partial_{s} \partial_{t}$ for $a l l$ and $t$ in $S$. A nonsingular linear pairing $<\mid>$ between $S$ and $S^{*}$ is defined by

$$
\begin{equation*}
\langle s \mid f\rangle=\left(\partial_{s} f\right)(0) \quad, \quad s \in S \quad, \quad f \in S^{*} . \tag{2}
\end{equation*}
$$

Since $\partial_{s \otimes t}=\partial_{s} \partial_{t}$ we have $\langle s \otimes t \mid f\rangle=\left\langle s \mid \partial_{t} f\right\rangle$.
Let homs $(d, k)$ denote the space of the homogeneous polynomials of degree $k$ in $d$ variables. For later use we prove the following lemmas.

LEMMA 2.3.1. For all $x \in V$, and $f \in \operatorname{hom}(d, k)$ we have

$$
\left\langle\otimes^{k} x \mid f\right\rangle=k!f(x)
$$

PROOF. For $k=1$ the statement follows from the definition of ${ }_{x} f$. Indeed $\langle x \mid f\rangle=\partial_{x} f(0)=f(x)$ since $f$ is linear. For $k>1$ we have

$$
\left\langle\theta^{k} x \mid f\right\rangle=\left\langle\theta^{k-1} x \mid \partial_{x} f\right\rangle=(k-1):\left(\partial_{x} f\right)(x)
$$

Now if $f$ is homogeneous of degree $k$ then $\left(\partial_{x} f\right)(x)=k f(x)$ since

$$
\left(\partial_{x} f\right)(x)=\lim _{h^{-1}}[f((1+h) x)-f(x)]=\operatorname{lim~}^{-1}\left((1+h)^{k}-1\right) f(x)
$$

This finishes the proof.

LEMMA 2.3.2. Fon $a Z Z \quad \sigma \in$ Aut $V, S \in S$ and $f \in S^{*}$ we have

$$
\left\langle s s^{\sigma} \mid f^{\sigma}\right\rangle=\langle s \mid f\rangle
$$

PROOF. First note that for $x \in V$ we have $\partial_{x}{ }_{\mathrm{o}} f^{\sigma}=\left(\partial_{x} f\right)^{\sigma}$. By induction on the degree of $s$ we then can prove $\partial_{s} f^{\sigma}=\left(\partial_{s} f\right)^{\sigma}$, and this implies $\left\langle s^{\sigma} \mid f^{\sigma}\right\rangle=\langle s \mid f\rangle$.
52.4. Bilinear form spaces.

Let $B(.,$.$) denote any nondegenerate symmetric bilinear form on V$. Then $B$ induces a vector space isomorphism $B: V \rightarrow V^{\star}$ (the dual of $V$ ), given by $\quad x \rightarrow B(x,$.$) for all x \in V$. This vector space isomorphism naturally extends to the algebra isomorphism $B ; S \rightarrow S^{*}$ given by

$$
\sum_{a} s^{a^{1}} v^{1} \ldots \theta^{a_{d} d} \rightarrow \sum_{a} s_{a}^{B\left(v^{1}, . .\right)^{a} 1} \ldots B\left(v^{d},\right)^{a_{d}}
$$

It is clear from the definition that we have, for all $x, y$ in $V$ :

$$
\langle x \mid B y\rangle=B(x, y)=\langle y \mid B x\rangle
$$

More generally we have

LEMMA 2.4.1. $\langle s \mid B t\rangle=\langle t \mid B s\rangle$ for $s, t \in S$.

PROOF. Let $v^{1}, v^{2}, \ldots, v^{d}$ be an orthogonal basis of $v$, with $B\left(v^{i}, v^{i}\right)=\phi_{i}$, and let

$$
s=\otimes^{a} 1_{v} 1 \ldots \otimes^{a_{d} d}, t=\otimes^{b} 1_{v} 1 \ldots{ }^{b} d_{v} d .
$$

Then $\langle s \mid B t\rangle=0$ if there is an index $i$ with $a_{i} \not{ }^{*} b_{i}$, while if $s=t$ we have, with $\phi=\Pi \phi_{i}$ :

Since tensors of the form $\otimes^{a} v^{1} \ldots \otimes^{a} d^{d}$ constitute a basis for $s$ the proof is finished.

The isomorphism $B$ allows one to interpret the pairing in (2) between $S$ and $S^{*}$ as an inner product on the space $S^{\star}$; the definition of this inner product is as follows:

$$
\begin{equation*}
\langle f, g\rangle=\left\langle B^{-1} f \mid g\right\rangle ; \text { for } f, g \in S^{\star} \text {. } \tag{5}
\end{equation*}
$$

From (3) it follows that this inner product is symmetric, i.e., $\langle f . g\rangle=\langle g, f\rangle$. To any polynomial $g \in S^{*}$ let us now associate the differential operator $\partial_{g}$ defined by $\partial_{g}=\partial_{B_{g}^{-1}}$. Then multiplication and differentiation with respect to a given polynomial are adjoint operations with respect to the inner product defined in (5), in the sense that

$$
\begin{equation*}
\langle\mathrm{gh}, \mathrm{f}\rangle=\left\langle\mathrm{h}, \mathrm{\partial}_{\mathrm{g}} \mathrm{f}\right\rangle \text {, for } \mathrm{f}, \mathrm{~g}, \mathrm{~h} \in \mathrm{~S}^{\star} . \tag{6}
\end{equation*}
$$

Let Aut B denote the automorphism group of the bilinear form B, i.e., the subgroup of Aut $V$ containing all $\sigma$ such that $B\left(x^{\sigma}, y^{\sigma}\right)=B(x, y)$ for all $x, y \in . V$. Using $\left\langle s{ }^{\sigma} \mid f^{\sigma}\right\rangle=\langle s \mid f\rangle$ together with the property $B\left(s^{\sigma}\right)=(B s)^{\sigma}$ for all $\sigma \in A u t B$, one can show that the inner product defined in (5) is invariant under Aut B, i.e.,

THEOREM 2.4.2. $\left\langle\mathrm{f}^{\sigma}, \mathrm{g}^{\sigma}\right\rangle=\langle\mathrm{f}, \mathrm{g}\rangle$ for all $\sigma \in \mathrm{Aut} \mathrm{B}$ and $\mathrm{f}, \mathrm{g} \in \mathrm{S}^{\text {* } . \square}$

### 52.5. Harmonic polynomials.

We now fix a bilinear form $B$ of inertia ( $p, q$ ), with $p+q=d$, so that $B$ is nondegenerate. Thus for a suitable basis $v^{1}, \ldots, v^{d}$ of $V$ we may write

$$
B(x, y)=x_{1} y_{1}+\ldots+x_{p} y_{p}-\ldots-x_{p+q} y_{p+q}
$$

Let $s={ }^{a} 1_{v}{ }^{1} \ldots{ }^{a} d_{v} d^{\text {. Then }}$ the polynomial corresponding to $s$. is:

$$
f=B s=(-1)^{a_{p+1}+\ldots+a_{d}}{ }_{x_{1}}^{a_{1}}{ }_{x_{2}}{ }^{a_{2}} \ldots x_{d}{ }^{a_{d}}
$$

Hence, given a polynomial $g$, we may write the associated differential operator as follows:

$$
\partial_{g}=a_{B}^{-1}=g(\partial) \quad, \text { with } \partial=\left(\partial_{1}, \ldots, \partial_{p},-\partial_{p+1}, \ldots,-\partial_{d}\right)
$$

Here $a_{i}$ stands for $a_{i}$. The inner product (5) takes the following form:

$$
\langle f, g\rangle=(f(\partial) g)(0)
$$

Let us mention in particular the differential operator associated to the quadratic form $B$ itself; $B(x):=B(x, x)$ :

$$
\partial_{B}=\partial_{1}^{2}+\ldots+\partial_{p}^{2}-\partial_{p+1}^{2}-\ldots-\partial_{d}^{2} .
$$

$\partial_{\beta}$ is called the Laplacian (associated to the bilinear form B).
Define the space harm $_{B}(k)$ to consist of the polynomials $f \in S^{\star}$ which are homogeneous of degree $k$ and satisfy the Laplace equation $\partial_{\beta} f=0$; thus

$$
\operatorname{harm}_{B}(k)=\operatorname{Ker} \partial_{\beta} \cap \operatorname{hom}(d, k)
$$

Let us mention the following important decomposition (cf. [V] page 446) of hom(d,k) into the kernel and the image of the operator $\beta \partial_{\beta}$ :

$$
\begin{equation*}
\operatorname{hom}(d, k)=\operatorname{harm}_{B}(k) \perp B(,) \operatorname{hom}(d, k-2) \tag{7}
\end{equation*}
$$

The orthogonality of the sumands on the right hand side of (7) is an immediate consequence of (6) . When no confusion is possible we shall write hom(k) instead of hom(d,k).

$$
\text { The monomials } x^{a}=x_{1}{ }^{a_{1}} x_{2}^{a_{2}} \ldots x_{d}{ }^{a_{d}} \text { with } \sum_{i=1}^{d} a_{i}=k \text {, form an }
$$

orthogonal basis for the space hom $(k)$; furthermore we have

$$
\left\langle x^{a}, x^{a}\right\rangle=(-1)^{a^{a}+1+\ldots+a_{d}}{\underset{i=1}{d} a_{i}!}_{p}
$$

as a direct consequence of (4). This leads us to the following decomposition of hom(k)

$$
\operatorname{hom}(k)=\operatorname{hom}^{+}(k) \perp \operatorname{hom}^{-}(k)
$$

Here $\operatorname{hom}^{+}(k)=\left\langle x^{a} \mid \sum_{i=p+1}^{d} a_{i}=0(\bmod 2)\right\rangle ;$
and $\operatorname{hom}^{-}(k)=\left\langle x^{a} \mid \sum_{i=p^{+1}}^{d} a_{i} \equiv 1(\bmod 2)\right\rangle$.

Clearly the restriction of the innerproduct to hom ${ }^{+}(k)$ is positive definite, while the restriction to hom ${ }^{-}(k)$ is negative definite. We will show that $\operatorname{harm}_{B}(k)$ splits in a similar way into subspaces harm $_{B}^{+}(k)$ and $\operatorname{harm}_{B}^{-}(k)$, and we shall compute the dimensions of these subspaces.

Let $H$ denote the projection $H: \operatorname{hom}(k) \rightarrow \operatorname{harm}_{B}(k)$, with respect to the decomposition

$$
\operatorname{hom}(k)=\operatorname{harm}_{B}(k) \oplus \beta(.) \operatorname{hom}(k-2)
$$

LEMMA 2.5.1. If $\mathrm{f} \in \operatorname{hom}^{+}(\mathrm{k})$ then also $\mathrm{Hf} \in \operatorname{hom}^{+}(\mathrm{k})$ and $f \in \operatorname{hom}^{-}(k)$ implies Hf $\in \operatorname{hom}^{-}(k)$.

PROOF. Analogous to [V], page 445 (13), one can prove that Hf may be written in the following form:

$$
\begin{equation*}
H f=\sum_{i=0}^{\lfloor k / 2\rfloor} c_{i} \beta^{i}\left(\partial_{\beta}\right)^{i_{f}}, \tag{8}
\end{equation*}
$$

for some constants $c_{0}, \ldots, c_{[k / 2]}$. It therefore suffices to show that $B \partial_{B} f$ is in hom $^{+}(k)$, resp. hom (k), if $f$ is. This however follows from the fact that $x_{i}^{2} \partial_{j}^{2} f$ is in $\operatorname{hom}^{+}(k)$, resp. $\operatorname{hom}^{-}(k)$, if $f$ is, for all $i, j$.

The lemma gives us the following decomposition:

$$
\operatorname{harm}_{B}(k)=\operatorname{harm}_{B}^{+}(k) \perp \operatorname{harm}_{B}^{-}(k),
$$

where $\operatorname{harm}_{B}^{E}(k):=\operatorname{hom}^{\varepsilon}(k) \cap \operatorname{harm}_{B}(k)$ for $E=+/-$.
Finally we shall use this information to determine the dimensions of $\operatorname{harm}_{B}^{+}(k)$ and $\operatorname{harm}_{B}^{-}(k)$, and hence the inertia of the inner product.

THEOREM 2.5.2. The dimensions of the spaces considered in this section are as follows:
(i) $\quad \operatorname{dim} \operatorname{hom}(\mathrm{d}, \mathrm{k})=\binom{\mathrm{d}+\mathrm{k}-1}{\mathrm{k}}$
(ii) $\quad \operatorname{dim} \operatorname{harm}_{B}(k)=\binom{d+k-1}{k}-\binom{d+k-3}{k-2}$;
(iii) $\operatorname{dim} \operatorname{hom}^{+}(\mathrm{d}, \mathrm{k})=\underset{\mathbf{j}=0}{\mathbf{k} / 2}\binom{\mathrm{p}+\mathbf{k}-2 \mathbf{j}-1}{\mathbf{k}-2 \mathbf{j}}\binom{\mathrm{q}+2 \mathbf{j}-1}{\mathbf{2 j}}$;
(iv) $\operatorname{dim} \operatorname{hom}^{-}(k)=\sum_{i j=0}^{(k-1) / 2}\binom{p+k-2 j-2}{k-2 j-1}\binom{q+2 j}{2 j+1}$;
(v) $\quad \operatorname{dim} \operatorname{harm}_{\mathrm{B}}^{+}(\mathrm{k})=\operatorname{dim} \operatorname{hom}^{+}(\mathrm{d}, \mathrm{k})-\operatorname{dim} \operatorname{hom}^{+}(\mathrm{d}, \mathrm{k}-2)=$

$$
=\sum_{j=0}^{k / 2}\binom{p+k-2 j-1}{k-2 j}\binom{q+2 j-1}{2 j}-\underset{j=0}{(k-2) / 2}\binom{p+k-2 j-3}{k-2 j-2}\binom{q+2 j-1}{2 j} ;
$$

(vi) $\quad \operatorname{dim}^{-1} \operatorname{harm}_{\mathrm{B}}^{-}(\mathrm{k})=\operatorname{dim} \operatorname{hom}^{-}(\mathrm{d}, \mathrm{k})-\operatorname{dim} \operatorname{hom}^{-}(\mathrm{d}, \mathrm{k}-2)=$

$$
=\sum_{j=0}^{(k-1) / 2}\binom{p+k-2 j-2}{k-2 j-1}\binom{q+2 j}{2 j+1}-\sum_{j=0}^{(k-3) / 2}\binom{p+k-2 j-4}{k-2 j-3}\binom{q+2 j}{2 j+1}
$$

PROOF. ( $i$ ) is well-known ; ( $i i$ ) follows from the decomposition $\operatorname{hom}(\mathrm{d}, \mathrm{k})=\operatorname{harg}_{\mathrm{B}}(\mathrm{k}) \perp \mathrm{B}(.) \operatorname{hom}(\mathrm{d}, \mathrm{k}-2)$. To see ( $(i i i)$ we construct an explicit basis of hom ${ }^{+}(k)$ : Write $a=\left(a_{+} ; a_{-}\right)$where $a=\left(a_{1}, \ldots, a_{p+q}\right)$, $a_{+}=\left(a_{1}, \ldots, a_{p}\right)$ and $a_{-}=\left(a_{p+1}, \ldots, a_{p+q}\right)$. Then $x^{a}=x^{a_{+}} \cdot x^{a_{-}}$and $\mathbf{x}^{\mathbf{a}} \in \operatorname{hom}^{+}(k)$ iff $\sum_{i=1}^{d} \mathbf{a}_{\mathbf{i}}=k$ and $\sum_{i=p+1}^{d} a_{i} \equiv 0(\bmod 2)$. Hence

$$
\operatorname{dim} \operatorname{hom}^{+}(k)=\sum_{j=0}^{k / 2} \operatorname{dim} \operatorname{hom}(p, k-2 j) \cdot \operatorname{dim} \operatorname{hom}(q, 2 j) .
$$

The proof of ( $i v$ ) is entirely similar. Statements ( $v$ ) and ( $v i$ ) follow from the following decomposition:

$$
\operatorname{hom}^{\varepsilon}(d, k) \simeq \operatorname{har}_{B}^{\varepsilon}(k) \oplus \operatorname{hom}^{\varepsilon}(d, k-2) \quad ; \varepsilon=+/-
$$

### 82.6. The addition formula.

Let $B$ be a bilinear form of inertia ( $p, q$ ). For any vector $x \in V$ the map $f \rightarrow f(x)$ defines a linear functional on the space harm ${ }_{B}(k)$; Hence there exists a unique polynomial $\tilde{x} \in$ harm $_{B}(k)$ with the following "reproducing" property :

$$
\begin{equation*}
\langle\tilde{x}, f\rangle=f(x) \quad \text { for all } f \in \operatorname{har}_{B}(k) \tag{9}
\end{equation*}
$$

Note that for all $\sigma \in \operatorname{Aut} B$ we have $\tilde{x}^{\sigma}=\tilde{x}^{\sigma}$, since for all $f \in \operatorname{harm}_{B}(k)$

$$
\left.\left.\tilde{\left\langle x^{\sigma}\right.}, f\right\rangle=f\left(x^{\sigma}\right)=f^{\sigma^{-1}}(x)=\left\langle\tilde{x}, f^{\sigma^{-1}}\right\rangle=\tilde{x}^{\sigma}, f\right\rangle
$$

Next write $q(x, y)=\tilde{x}(y)$. Since $\tilde{x}^{\sigma}=\tilde{x}^{\sigma}$ we have

$$
q\left(x^{\sigma}, y^{\sigma}\right)=q(x, y) \quad \text { for } x, y \in V \text { and } \quad \sigma \in A u t B \text {. }
$$

Consider an "orthonormal" basis $\left\{f_{k, i} ; g_{k, j} \mid i=1, \ldots, \mu_{k} ; j=1, \ldots, v_{k}\right\}$, i.e., a basis of harm $\mathrm{m}_{\mathrm{B}}(\mathrm{k})$ such that

$$
\begin{aligned}
& \left\langle f_{k, i}, f_{k, u}>=\delta_{i u} ;\left\langle g_{k, j}, g_{k, v}\right\rangle=-\delta_{j v} ;\right. \\
& \left\langle f_{k, i}, g_{k, j}>=0 \quad \text { for all } i, j, u, v .\right.
\end{aligned}
$$

The harmonic polynomial $\tilde{\mathbf{x}}$ has the following expansion in this basis :

$$
\begin{equation*}
\tilde{x}=\sum_{i=1}^{u_{k}}<\tilde{x}, f_{k, i}>f_{k, i}-\sum_{j=1}^{v_{k}}<\tilde{x}, g_{k, j}>g_{k, j} . \tag{10}
\end{equation*}
$$

Combining this with (9) yields :

$$
q(x, y)=\sum_{i=1}^{\mu_{k}} f_{k, i}(x) f_{k, j}(y)-\sum_{j=1}^{v_{k}} g_{k, j}(x) g_{k, j}(y)
$$

Next we show that we may identify the function $q(x, y)$ in terms of the Gegenbauer polynomial of order ( $d-2$ )/2 and degree $k$ in the variable $[x, y]:=B(x, y)$. By lemma 2.3.1. we have $\left\langle\otimes_{x, f\rangle}^{k}=k!f(x)\right.$ for $x \in V$ and $f \in \operatorname{hom}(k)$. The polynomial corresponding to ${ }^{k}$ is

$$
[\mathrm{x}, .]^{\mathrm{k}} \in \operatorname{hom}(\mathrm{k}),
$$

hence

$$
\left.<[x, .]^{k}, f\right\rangle=k!f(x)
$$

As before, let $H$ denote the projection $H: \operatorname{hom}(k)+h a r m i l_{B}(k)$, according to decomposition (7). From the uniqueness of the harmonic polynomial $\tilde{\mathbf{x}}$ and the orthogonality of decomposition (7) we then have :

$$
\begin{equation*}
\tilde{x}=\frac{1}{k!} \mathrm{H}[\mathrm{x}, .]^{\mathrm{k}} . \tag{11}
\end{equation*}
$$

For the explicit determination of $\tilde{\boldsymbol{x}}$ we need the following identity for $f \in \operatorname{hom}(k)$, which is easy to verify (cf. [v] page 446):

$$
\begin{equation*}
\partial_{\beta}\left(\beta^{i} \partial_{\beta} f\right)=\beta \partial_{\beta} \mathbf{i}_{\beta}^{i+1} f+2 i(d+2 k-2 i-2) \beta^{i-1} \partial_{\beta} \mathbf{i}_{f} . \tag{12}
\end{equation*}
$$

In view of (8) we may write

$$
H[x, .]^{k}=\sum_{i=0}^{m} a_{i} \beta^{i_{\partial}} i_{B}[x, .]^{k},
$$

with $a_{0}=1$ and $m=\lfloor k / 2\rfloor$.
To determine the other coefficients $a_{i}$, apply $\partial_{B}$ to both sides and use (12). From this one can derive the following recurrence relation:

$$
a_{i}+(2 i+2)(d+2 k-2 i-4) a_{i+1}=0
$$

Together with the following observation

$$
\partial_{\beta} i^{i}[x, .]^{k}=\frac{k!}{(k-2 i)!}[x, .]^{k-2 i_{\beta} i(x)},
$$

we obtain along the lines of [v] page 458 :

$$
\begin{equation*}
H[x, .]^{k}=k!\gamma_{k} \beta(x)^{k / 2} \beta(.)^{k / 2} G_{k}^{(d-2) / 2}\left([x, .] / \beta(x)^{\frac{1}{2}} \beta(.)^{\frac{1}{2}}\right), \tag{13}
\end{equation*}
$$

where $\gamma_{k}=[(d-2)(d) \ldots(d+2 k-4)]^{-1}$, and $c_{k}^{(d-2) / 2}$ is a Gegenbauer polynomial. The Gegenbauer polynomial $C_{m}^{p}$ is defined as follows :

$$
C_{m}^{p}(t)=\frac{2 m(p+m)}{m!(p)}\left[t^{m}-\frac{m(m-1)}{2^{2}(p+m-1)}+\frac{m(m-1)(m-2)(m-3)}{2^{4} \cdot 1 \cdot 2 \cdot(p+m-1)(p+m-2)} \pm \cdots\right]
$$

(cf. [v] page 458). An alternative definition is the following ([v] p. 492)

$$
\left(1-2 t h+h^{2}\right)^{-p}=\sum_{m=0}^{\infty} c_{m}^{p}(t) h^{m}
$$

We now may combine (10), (11) and (13) to obtain the generalized addition formula.

THEOREM 2.6.1. $\gamma_{k} \beta(x)^{k / 2} \beta(y)^{k / 2} C_{k}^{(d-2) / 2}\left(B(x, y) / \beta(x)^{\left.\frac{1}{2} \beta(y)^{\frac{1}{2}}\right)=}=\right.$

$$
=\sum_{i=1}^{\sum_{k}} f_{k, i}(x) f_{k, i}(y)-\sum_{j=1}^{\sum_{k}} g_{k, j}(x) g_{k, j}(y) .
$$

Here $\mu_{k}=\operatorname{dim} \operatorname{harm}_{B}^{+}(k), v_{k}=\operatorname{dim} \operatorname{harm}_{B}^{-}(k)$ (cf. theorem 2.5.2), while $\gamma_{k}=\left[\begin{array}{lll}(d-2) d & \ldots & (d+2 k-4)\end{array}\right]^{-1}$.
§2.7. Applications to few-distance sets in $R^{p, q}$.

In this section we shall use the generalized addition formula and the knowledge of the inertia of the inner product on harm ${ }_{B}(k)$ to obtain
bounds on the size of s-distance sets of mit vectors in $R^{p, q}$, and in particular $R^{p, 1}$ and $R^{1, q}$.

LEMMA 2.7.1. Let $A$ be avxm matrix, $\mathrm{I}_{\mathrm{s}, \mathrm{t}}=\operatorname{diag}\left(1^{\mathrm{s}},-1^{\mathrm{t}}\right)$, where $\mathrm{s}+\mathrm{t}=\mathrm{m}$, and suppose $\mathrm{AI}_{\mathrm{s}, \mathrm{t}} \mathrm{A}^{\mathrm{t}}=\mathrm{I}_{\mathrm{v}}$. Then $\mathrm{v} \leq \mathrm{s}$.

PROOF. Suppose that $v>s$, then certainly $\operatorname{rank}(A)>s$, and there exists an $x \in R^{V}$ with the property that $\left(x^{t} A\right) I_{s, t}\left(A^{t} x\right)<0$. Since $\mathrm{AI}_{s, t} \mathrm{~A}^{\mathrm{t}}=\mathrm{I}_{\mathrm{v}}$ this implies that $\mathrm{x}^{\mathrm{t}} \mathrm{x}<0$, contradiction.

Let $X$ be a set of points an the "unit sphere" of $V=R^{p, q}$ :

$$
S_{p, q}:=\left\{x \in R^{p, q} \mid B(x, x)=1\right\},
$$

with $\operatorname{card}(x)=v$. Again we shall write $[x, y]$ for $B(x, y)$.
Let $A:=\{[x, y] \mid x, y \in X, x \neq y\}$ and suppose that $1 \& A$. Also put $A^{\prime}:=A \cup\{1\}$. We define the following matrices :

$$
\begin{aligned}
& F_{k}=F_{k}(x, i)=\left[f_{k, i}(x)\right] x \in X ; i=1, \ldots, \mu_{k} ; \\
& G_{k}=G_{k}(y, j)=\left[g_{k, j}(y)\right] \quad y \in X ; j=1, \ldots, v_{k} ; \\
& D_{\alpha}=\left[d_{\alpha}(x, y)\right]_{x \in X ; y \in X ;} \quad \begin{aligned}
d_{\alpha}(x, y)=1 & \text { if }[x, y]=\alpha, \\
d_{\alpha}(x, y)=0 & \text { otherwise. }
\end{aligned}
\end{aligned}
$$

As a direct consequence of the addition formula the following holds :

$$
F_{k} F_{k}^{t}-G_{k} G_{k}^{\mathbf{t}}=\sum_{\alpha \in A^{+}} Q_{k}^{(\alpha) D_{\alpha}}
$$

Here $Q_{k}=\gamma_{k} C_{k}^{(d-2) / 2}$. Define the "annihilator polynomial" $\phi$ of $X:$

$$
\phi(t)=\pi \frac{t-\alpha}{\alpha \in \mathbb{A}}
$$

and expand $\phi$ in the "normalized" Gegenbauer polynomials $Q_{k}$

$$
\phi=\sum_{k=0}^{s} \phi_{k} Q_{k} \quad, \quad \text { where } \quad s=\operatorname{card}(A)
$$

Then

$$
\sum_{k=0}^{\mathbf{s}} \phi_{k}\left\{F_{k} F_{k}^{t}-G_{k} G_{k}^{t}\right\}=\sum_{\alpha \in A^{\prime}} \phi(\alpha) D_{\alpha}=I_{v},
$$

i.e.,

$$
H \cdot \stackrel{\oplus}{\mathbf{m}=0} \phi_{k} I_{\mu_{k}, v_{k}} \cdot H^{t}=I_{v}
$$

Here $H=\left[F_{0} ; F_{i} ; G_{0} ; G_{1} ; \ldots ; F_{d} ; G_{d}\right]$, and $I_{\mu_{k}, \nu_{k}}=\operatorname{diag}\left(1^{\mu_{k}},(-1)^{\nu}{ }^{\nu}\right)$.

The following theorem is now an imnediate consequence of lemma 2.7.1.:

THEOREM 2.7.2. Let X be a set of unit vectors in $\mathrm{R}^{\mathrm{P}, \mathrm{q}}$, such that, for $\mathbf{x}, \mathrm{y} \in \mathrm{X},[\mathrm{x}, \mathrm{y}]$ assumes only s different values, all different from 1 . Let $\phi=\Sigma \phi_{\mathbf{k}} \mathrm{O}_{\mathbf{k}}$ be the expansion of the amihilator polynomial in the normalized Gegenbouer polynomials. Then

$$
\begin{aligned}
\operatorname{card}(x) \leq \sum_{k=0}^{s} \sigma_{k} \quad, \text { where } \sigma_{k} & =\mu_{k} \text { if } \phi>0, \\
\sigma_{k} & =\nu_{k} \text { if } \phi<0, \\
\sigma & =0 \text { if } \phi=0 .
\end{aligned}
$$

Here $\mu_{k}=\operatorname{dim} \operatorname{harm}_{B}^{+}(k), \nu_{k}=\operatorname{dim}$ harm $_{B}^{-}(k)$ (cf. theorem 2.5.2).
52.8. Examples.

In this section we shall compute the bounds explicitly for the case $p=d-1, q=1$. According to theorem 2.5.2., $\mu_{k}$ and $v_{k}$ have the following values:

$$
u_{k}=\operatorname{dimharm}_{B}^{+}(k)=\binom{d+k-2}{k-1} ; \quad v_{k}=\binom{d+k-3}{k-1} .
$$

Hence we get the following absolute bound:

THEOREM 2.8.1. Let $X$ be a set of unit vectors in $\mathrm{R}^{\mathrm{d}-1,1}$ such that the inner product between different elements of $\mathbf{x}$ assumes only s different values, all different from 1, then

$$
\operatorname{card}(X) \leq\binom{ d+s-1}{s}
$$

PROOF. $\quad \operatorname{Card}(X) \leq \sum_{k=0}^{s} \mu_{k}=\sum_{k=0}^{s}\binom{d+k-2}{k}=\binom{d+s-1}{s}$, since $v_{k} \leq \mu_{k}$.

In certain cases we can improve the bound, using the expansion of the annihilator polynomial in Gegenbauer polynomials explicitly. We give the first Gegenbauer polynomials:

$$
\begin{aligned}
& Q_{0}(t)=1 ; \quad Q_{1}(t)=d x \\
& Q_{2}(t)=\frac{1}{2} d(d+2)\left(x^{2}-\frac{1}{d}\right) ; \\
& Q_{3}(t)=\frac{1}{6} d(d+2)(d+4)\left(x^{3}-\frac{3}{d+2} x\right) ; \\
& Q_{4}(t)=\frac{1}{24} d(d+2)(d+4)(d+6)\left(x^{4}-\frac{6}{d+4} x^{2}+\frac{3}{(d+2)(d+4)}\right) ; \\
& Q_{5}(t)=\frac{1}{120} d \ldots(d+8)\left(x^{5}-\frac{10}{d+6} x^{3}+\frac{15}{(d+4)(d+6)} x\right) ;
\end{aligned}
$$

EXAMPLE 2.8.2. Let $X$ be a set of unit vectors in $\mathbf{R}^{9,1}$ with inner products $\left\{0,-\frac{1}{2},+\frac{1}{2}\right\}$. The annihilator polynomial in this case is

$$
\phi(t)=\frac{4}{3} t\left(t+\frac{1}{2}\right)\left(t-\frac{1}{2}\right) .
$$

Sinde $d=10$ the annihilator polynomial is an exact multiple of $Q_{3}$. Hence the bound of theorem 2.7.2. yields $\operatorname{card}(X) \leq \operatorname{dim}^{\text {harm }}{ }_{9,1}^{+}(3)=165$. Equality is realized by the following set of vectors in $R^{10,1}$, in the orthoplement of the vector $\left(3 ; 1^{10}\right)$ :

$$
\left(0 ; 1,-1,0^{8}\right) \quad \text { and } \quad\left(1 ; 1^{3}, 0^{7}\right)
$$

There are 90 vectors of the first type, which fall in 45 antipodal pairs, and 120 of the second type. This system can be regarded as an extension of the rootsystem $E_{8}$ in the following representation :

$$
\pm\left(0 ; 1,-1,0^{7}\right) \quad \text { and } \quad \pm\left(1 ; 1^{3}, 0^{6}\right)
$$

in the orthoplement of the isotropic vector $\left(3 ; 1^{9}\right)$ in $R^{9,1}$.

EXAMPLE 2.8.3. Let $X$ be a set of vectors with inner products $\{+1 / 3,-1 / 3\}$ in $R^{9,1}$. The annihilator polynomial $\left(9 t^{2}-1\right) / 8$ is a multiple of $Q_{2}$. We get card $(X) \leq \operatorname{dim}_{\text {harm }}^{8,1}+(2)=36$. Equality is realized by the following vectors in $R^{9,1}$ in the orthoplement of $\left(2 \sqrt{2} ; 1^{9}\right)$ :

$$
\left(\frac{1}{2} \sqrt{ } 2 ; 1^{2}, 0^{7}\right)
$$

This system can be seen as a subsystem of the previous example in the following way: Fix a vector and consider all vectors with inner product $+\frac{1}{2}$ with this vector. Now project this system on the orthoplement of the fixed vector.

NON-EXAMPLE 2.8.4. Let $X$ be a set of vectors in $R^{3,1}$, with inner products $\left\{0, \pm \frac{1}{2}, \pm \frac{1}{2} \sqrt{3}\right\}$. Then $\phi(t)=t\left(4 t^{2}-1\right)\left(4 t^{2}-3\right) / 3$ is an exact multiple of $Q_{5}$. From this we get that $\operatorname{card}(X) \leq 21$. However this bound cannot be achieved, as was established by Bussemaker using a computer search.

EXAMPLE 2.8.5. Let $x$ be a set of vectors in $R^{25,1}$, with inner products $\left\{0, \pm \frac{1}{2},+\frac{1}{}\right\}$. Then $\phi(t)$ is a multiple of $Q_{5}$ and we get $\operatorname{card}(X) \leq\binom{ 29}{5}$. This example is analogous to example 2.8.2. in the following sense. Example 2.8.2. is a system of vectors that is an extension of a (1,1)- dimensional lower extremal system. In this case the extremal system in $R^{24}$ indeed exists, consisting of the $\binom{28}{5}$ antipodal pairs of vectors closest to the origin in the Leech lattice. Whether this system can be extended in a certain sense to $\binom{29}{5}$ vectors in $R^{25,1}$ is unknown.

EXAMPLE 2.8.6. Let $X$ be a set of vectors in $R^{24,1}$, with inner products $\{0, \pm i / 3\}$. The annihilator polynomial is a multiple of $Q_{3}$, and the bound yields $2600=\binom{26}{3}$. There do exist 2300 vectors with the prescribed inner products in $\mathrm{R}^{23}$. So far the best we can realize in $\mathrm{R}^{24,1}$ is 2324, viz. the following set of vectors: ( $8 ; 4^{2}, 0^{22}$ ), giving $\binom{24}{2}$ vectors, and the vectors $\left(0 ;( \pm 1)^{24}\right)$ where the +1 positions correspond to a word in the extended binary Golay code, 2048 pairs.

## CHAPTER 3

## EQUIANGULAR LINES IN $\mathbf{R}^{\mathbf{d}, 1}$

### 53.1. Introduction.

Let $R^{d, 1}$ be the ( $d+1$-dimensional vector space over the reals, provided with the following inner product:

$$
(x, y)=-x_{0} y_{0}+x_{1} y_{1}+\ldots x_{d} y_{d}
$$

If two lines through the origin span a plane on which the inherited inner product is positive definite, we can define their angle to be arccos $|(x, y)|$ where $x$ and $y$ are unit vectors along the lines. A set of equiangular lines is a set of lines, such that for each pair the angle is defined and equal to the same value, arccos $\alpha$ say, Using an argument based on an idea of Koornwinder [ $K$ ], and on eigenvalue techniques of van Lint and Seidel
[vLS] we obtain sharp bounds on the cardinality of sets of equiangular lines in $\mathrm{R}^{\mathrm{d}, 1}$.

### 53.2. The theorem

THEOREM 3.2.1. Let $X$ be a set of equiangular lines in $\mathrm{R}^{\mathrm{d}, 1}$ at angle arccos ( $\alpha$ ), then
(i) if $(d+1) \alpha^{2} \leq 1$, then $\operatorname{card}(X) \leq d\left(1-a^{2}\right) /\left(1-d \alpha^{2}\right)$;
(ii) if $(d+1) \alpha^{2}>1$, then $\operatorname{card}(X) \leq \frac{1}{1} d(d+1)$,
and equality in (i) can only be realized if the set is in a positive definite subspace of dimension $\mathbf{d}$. Also, an infinite semies of sets realizing equality in (ii) exists.

PROOF. Let $U$ be a set of unit vectors, one along each line of $X$. The Gram matrix $G$ of the set $U$ has at most $d$ positive eigenvalues. Hence $C=\alpha^{-1}(G-I)$ has $v$-d eigenvalues less than or equal to $-\alpha^{-1}$, with $v=\operatorname{card}(X)$. Call the other eigenvalues $\lambda_{i}, \lambda_{2}, \ldots, \lambda_{d}$.

Since the matrix $C$ has zeros on the diagonal and $\pm 1$ elsewhere

$$
\begin{aligned}
& 0=\operatorname{trc} \leq \lambda_{1}+\lambda_{2}+\ldots+\lambda_{d}-\frac{v-d}{a} \\
& v(v-1)=\operatorname{trc} c^{2} \geq \lambda_{1}^{2}+\ldots+\lambda_{d}^{2}+\frac{v-d}{a^{2}}
\end{aligned}
$$

As a consequence the following inequalities hold:

$$
\frac{(v-d)^{2}}{a^{2}} \leq\left(\lambda_{1}+\ldots+\lambda_{d}\right)^{2} \leq d\left(\lambda_{1}^{2}+\ldots+\lambda_{d}^{2}\right) \leq d\left(v(v-1)-\frac{v-d}{a^{2}}\right)
$$

In case $d<1 / \alpha^{2}$ this is equivalent to

$$
v \leq d\left(1-\alpha^{2}\right) /\left(1-d \alpha^{2}\right)
$$

Note that equality can only occur if $\lambda_{d+1}, \cdots, \lambda_{v}$ are all equal to $-1 / a$ and this implies that the subspace $\langle\mathbb{U}\rangle$ is actually positive definite.

To prove the second part we proceed as follows. For each $u \in U$ define $F_{u}: R^{d, 1} \rightarrow R$ by

$$
F_{u}(x)=(u, x)^{2}-\alpha^{2}(x, x)
$$

and define $d+1$ additional functions

$$
f_{0}(x)=(x, x) \quad ; \quad f_{i}(x)=x_{0} x_{i} \quad, \text { for } i=1,2, \ldots, d
$$

We will show that the set $F=\left\{F_{u}, f_{0}, f_{i} \mid i=1, \ldots, d, u \in U\right\}$ is independent. This implies our claim, since all these functions are homogeneous of degree 2 and therefore $\operatorname{card}(F) \leq \frac{1}{2}(d+1)(d+2)$.

Suppose there is a dependency relation for the functions in $F$ :

$$
\begin{equation*}
\sum_{u \in U} a_{u} F_{u}(x)+\sum_{i=1}^{d} a_{i} f_{i}(x)+a_{0} f_{0}(x) \equiv 0 \tag{1}
\end{equation*}
$$

For $u, v \in U$ always $F_{u}(v)=\left(1-\alpha^{2}\right) \delta_{u v}$, hence when we insert $u \in U$ in this relation the following results:

$$
\begin{equation*}
a_{u}\left(1-a^{2}\right)+\sum_{i=1}^{d} a_{i} u_{0} u_{i}+a_{0}=0 \tag{2}
\end{equation*}
$$

Comparing coefficients of $x_{0}{ }^{2}, x_{i}{ }^{2}$, and $x_{0} x_{i}$ in (1) yields :

$$
\begin{align*}
& \sum_{u \in U} \quad a_{u}\left(u_{0}^{2}+\alpha^{2}\right)-a_{0}=0  \tag{3}\\
& \sum_{u \in U} a_{u}\left(u_{i}^{2}-a^{2}\right)+a_{0}=0 ;  \tag{4}\\
& -2 \sum_{u \in U} a_{u} u_{0} u_{i}+a_{i}=0 \tag{5}
\end{align*}
$$

Now add (3) and (4) :

$$
\underset{u \in U}{\sum} a_{u} u_{0}^{2}=-\sum_{u \in U} a_{u} u_{i}^{2}
$$

Sumation of both sides of this equation, and putting ( $u, u$ ) $=1$ yields:

$$
d \sum_{u \in U} a_{u} u_{0}^{2}=-\sum_{u \in U} a_{u}\left(1+u_{0}^{2}\right)
$$

From (3) one obtains

$$
\begin{equation*}
a_{0}=\left(\alpha^{2}-\frac{1}{d+1}\right) \sum_{u \in U} a_{u} \tag{6}
\end{equation*}
$$

Now if $(d+1) a^{2}=1$ this implies $a_{0}=0$. Otherwise we can multiply (1) by $a_{u}$ and sum over $u$ (using (5) and (6)) to obtain

$$
\sum_{u \in U} a_{u}^{2}\left(1-\alpha^{2}\right)+\frac{1}{2} \sum_{i=1}^{d} a_{i}^{2}+\frac{d+1}{(d+1) a^{2}-1} a_{0}^{2}=0
$$

This is a sum of squares since $(d+1) \alpha^{2}-1 \geqslant 0$, hence all $a_{i}$ are 0 . If $(d+1) \alpha^{2}=1$ we get the same relation except for the terminvolving $a_{0}$ and we are done as well. So $\operatorname{card}(\mathrm{U})=\operatorname{card}(\mathrm{F})-(\mathrm{d}+1) \leq \frac{1}{2} \mathrm{~d}(\mathrm{~d}+1)$.

An infinite series of sets realizing the bound is provided by:

In $R^{d+1,1}$ the vector $w=\left(2 \sqrt{2} ; 1^{d+1}\right)$ satisfies $(w, w)=d-7$. Therefore we may identify $w^{\perp}$ with $R^{d, 1}$ for $d>7$. The set of $\frac{1}{2} d(d+l)$ vectors of the form

$$
\left(\frac{1}{2} \sqrt{2} ; 1^{2}, 0^{d-1}\right)
$$

is in $w^{\perp}$ and spans a set of equiangular lines at $\arccos (1 / 3)$. For $d=7$, $w^{\perp} /<w>$ is isomorphic to $R^{7}$ and the construction yields 28 equiangular lines. More on this system can be found in [LS] and [vLS]. This representation is due to Seidel (unpublished). For $\alpha=1 / 5, d=23$, there exists a set of 276 lines (cf. [LS]). With the help of the Steiner system 4-(23, 7,1 ) they can be nicely described as a set of lines in $\mathrm{R}^{23,1}$ as follows: (For details about Steiner systems see [CvL])

$$
\begin{aligned}
& 23 \text { vectors : }\left(32 ;-1^{1}, 1^{22}\right), \\
& 253 \text { vectors : }\left(2 ; 1^{7}, 0^{16}\right),
\end{aligned}
$$

where the positions of the seven ones in the last type corresponds to the blocks of the Steiner system $4-(23,7,1)$.
Related to this example are sets of lines at arccos(1/5) in $\mathrm{R}^{22}$ and $R^{21}$ realizing the bound in part (i) of the theorem. For $\alpha<1 / 5$ no case of equality is known.

REMARK 3.2.2. In the case $(d+2)^{-1}<\alpha^{2}<(d+1)^{-1}$ we have

$$
d\left(1-\alpha^{2}\right) /\left(1-d \alpha^{2}\right)<\frac{1}{2} d(d+1)
$$

This set of values for $a$ is excluded however by the following theorem.
THEOREM 3.2.3. If $\mathrm{v}<2 \mathrm{~d}+2$ then $\mathrm{a}^{-1}$ is an integer.

PROOF. This is essentially theorem 3.4. from [LS], due to Neumann. Let $A=\alpha^{-1}(G-I)$ where $G$ is the Gram matrix of $U$. Then $A$ is an integral matrix, and has eigenvalue $-\alpha^{-1}$ with multiplicity mev-d-1. Therefore, $-\alpha^{-1}$ is an algebraic integer, and every algebraic conjugate is an eigenvalue with the same multiplicity m. Since $2 m=2 v-(2 d+2)>v$, there is at most one eigenvalue of multiplicity $m$, which implies that
$-\alpha^{-1}$ is rational, and hence an integer. (In fact one can prove that $\alpha^{-1}$ is an odd integer.)

## CHAPTER 4

## FEW-DISTANCE SETS IN E ${ }^{\text {d }}$ AND $H^{\text {d }}$

### 54.1. Introduction.

Using Koornwinders argument one obtains the same bounds for s-distance sets in $E^{d}$, d-dimensional Euclidean space, and $H^{d}$, d-dimensional hyperbolic space, viz.

$$
\binom{d+s}{s}+\binom{d+s-1}{s-1}
$$

In both cases it is possible to reduce the bounds using the trick of finding an additional set of independent functions. As a consequence we get the following

THEOREM 4.1.1. Let X be an s-distance set in $\mathrm{E}^{\mathrm{d}}$ or $\mathrm{H}^{\mathrm{d}}$, then

```
card(X)}\leq(\frac{d+s}{g})
```


## §4.2. Preliminaries and notation.

The vector space $R^{d}$ together with the usual metric, coming from the inner product $\quad(x, y)=x_{1} y_{1}+\ldots+x_{d} y_{d}$, will be called $E^{d}$, i.e., d-dimensional Euclidean space. By $H^{d^{d}}$ we denote d-dimensional hyperbolic space. $H^{\text {d }}$ can be realized as follows : Let $R^{\text {l, }}$ d be a ( $\mathrm{d}+\mathrm{l}$ )-dimensional vector space over $R$ provided with the inner product

$$
\langle x, y\rangle=x_{0} y_{0}-x_{1} y_{1}-\ldots-x_{d} y_{d}
$$

The points of $H^{d}$ are the l-dimensional subspaces $\langle x\rangle$, with $<x, x \gg 0$. Distance is defined by

$$
d(\alpha x\rangle,\langle y\rangle)=\operatorname{arcosh}\left|\frac{\alpha, y\rangle}{\langle x, x\rangle^{\frac{1}{2}}\langle y, y\rangle^{\frac{1}{2}}}\right|
$$

If we take for $x$ and $y$ unit vectors with positive first coordinate, this becomes $d(x, y)=\operatorname{arcosh}(-\langle x, y\rangle)$. Vectors in $R^{d}$ or $R^{1, d}$ will be denoted by $u, v, x, y, z$, where $x=\left(x_{1}, x_{2}, \ldots, x_{d}\right)$ or $x=\left(x_{0}, x_{1}, \ldots, x_{d}\right)$. By $b, c, \ldots, g$ we denote vectors of length $d$ or $d+1$ with nonnegative integral entries.
The monomial $\quad x_{0}{ }_{0}{ }_{x_{1}}{ }^{e_{1}} \ldots x_{d}{ }^{e} d$ is denoted by the symbor $x^{e}$. An appropriate greek letter will denote the sum of the entries of an integral vector ( $\beta=b_{0}+b_{1}+\ldots+b_{d}$ etc.) . Also

$$
\binom{\beta}{b}=\frac{\beta!}{b_{0}!b_{1}!\cdot \cdot b_{d}!}
$$

Let $\sigma(j)$ be the elementary symmetric function in the variables $\alpha_{1}, \ldots, \alpha_{s}$, of degree j. So

$$
\prod_{i=1}^{s}\left(t+\alpha_{i}\right)=\sum_{j=0}^{s} \sigma(j) t^{s-j}
$$

Denote by $\sigma_{u}(j)$ the elementary symmetric function of degree $j$ in the variables $(u, u)-a_{i} ; i=1, \ldots, s$. So

$$
\prod_{i=1}^{s}\left(t+(u, u)-\alpha_{i}\right)=\sum_{j=0}^{s} \sigma_{u}(j) t^{s-j}
$$

Note that $\sigma_{u}(j)=\sum_{i=0}^{j}\binom{s-i}{j-i}(-1)^{i}(u, u)^{j-i} \sigma(i)$.

Finally if $V$ is a vector space with basis $A$, we write $p=\Sigma[p, a] a$ for $p \in V$, so $[p, a]$ are the coordinates of $p$ relative to the basis $A$.

### 54.3. The bound in Euclidean space.

THEOREM 4.3.1. Let $X$ be an s-distance set in $\mathrm{E}^{\mathrm{d}}$, then

$$
\operatorname{card}(X) \leq\binom{\mathrm{d}^{+} \mathrm{s}}{s}
$$

PROOF. Let $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{s}$ be the squares of the distances that occur in $X$. For each $u \in X$ define the polynomial

$$
F_{u}(x)=\prod_{i=1}^{s}\left\{(x-u, x-u)-\alpha_{i}\right\}=\prod_{i=1}^{s}\left\{(x, x)-2(x, u)+(u, u)-\alpha_{i}\right\} .
$$

For $u, v \in X$ we have $F_{u}(v)=0$ iff $u \neq v$. This implies that the polynomials $F_{u}(x)$ are independent. We may expand $F_{u}$ as follows:

$$
\begin{align*}
& F_{u}(x)=\sum_{j=0}^{s} \sigma_{u}(s-j)[(x, x)-2(x, u)]^{j}= \\
& \left.=\underset{\substack{E ; g \\
E+\gamma \leq s}}{\sum} \sigma_{u}(s-E-\gamma)(\underset{\gamma}{\varepsilon+\gamma})(-2)^{\gamma} \underset{g}{\gamma}\right) u^{g} x^{g}(x, x)^{\varepsilon} . \tag{1}
\end{align*}
$$

The summation in (1) is over all nonnegative integral $d$-vectors $g$ and nonnegative integers $\varepsilon$, such that $E+g_{1}+g_{2}++g_{d} \leq s$.

The $F_{u}$ are linear combinations of the functions in the set

$$
\left\{(x, x)^{\delta} x^{b} \mid \delta+\beta=s \text { or } \delta=0 \text { and } B<a\right\} .
$$

The following bound is a direct consequence of this:

$$
\operatorname{card}(X) \leq\binom{ d+s}{s}+\binom{d+s-1}{s-1}
$$

We now proceed to show that in fact the set

$$
\left\{F_{u}(x), x^{b} \mid u \in X, B<s\right\}
$$

is independent. This yields the desired result :

$$
\operatorname{card}(X)+\binom{d+s-1}{s-1} \leq\binom{ d+s}{s}+\binom{d+s-1}{s-1} .
$$

Suppose then, there is a dependency relation:

$$
\begin{equation*}
\sum_{u \in X}^{\sum} a_{u} F_{u}(x)+\underset{b: B<s}{\Sigma} a_{b} x^{b}=0 \tag{2}
\end{equation*}
$$

LEMMA 4.3.2. Relation (2) implies :

$$
\forall b \text { with } \beta<s: \sum_{u \in \mathbb{X}} a_{u} u^{b}=0 \text {. }
$$

PROOF. We shall use induction. First consider the part of (2) that is homogeneous of maximal degree 2 s in x . From the explicit expansion (1) of $F_{u}$ we see that this only happens for $\varepsilon=s, \delta=0$, and we obtain $\underset{\mathbf{u} \in \mathrm{X}}{\Sigma} \mathbf{a}_{\mathbf{u}}=0$. So the lemma is true for $B=0$. Now suppose

$$
\underset{u \in X}{\Sigma} \mathbf{a}_{\mathbf{u}} \mathbf{u}^{\mathbf{b}}=0 \text {, for all } \mathbf{b} \text { with } 0 \leq \beta<t<s \text {. }
$$

Consider the part of (2) that is homogeneous of degree $2 \mathrm{~s}-\mathrm{t}$ in x . This yields

$$
\underset{u \in X}{\Sigma} a_{u}\left[\underset{\substack{\varepsilon ; g \\ 2 \varepsilon+\gamma=2 s-t}}{\sigma_{u}(s-\varepsilon-\gamma)}(\underset{\gamma}{\gamma+\varepsilon})\left({ }_{g}^{\gamma}\right)(-2)^{\gamma} u^{g}(x, x)^{\varepsilon} x^{g}\right]=0 .
$$

Since

$$
\sigma_{u}(s-\varepsilon-\gamma)=\binom{s}{s-\varepsilon-\gamma}(u, u)^{s-\varepsilon-\gamma}-\binom{s-1}{s-\varepsilon-\gamma-1}(u, u)^{s-\varepsilon-\gamma-1} \pm \ldots,
$$

we may, after changing the order of summation, use the induction hypothesis:

$$
\sum_{u \in X} a_{u}(u, u)^{s-\varepsilon-\gamma-i} u^{g}=0, \quad \text { for } \quad \text { all } i>0
$$

## Hence

Finally, substituting $x=v$, multiplying by $a_{v}(v, v)^{s-t}$ and summing over all $v \in X$ yields:

$$
\underset{\substack{\varepsilon ; g \\ 2 \varepsilon+\gamma=2 s-t}}{\left.\sum_{\gamma}^{\gamma+\varepsilon}\right)\binom{\gamma}{g}(-2)^{\gamma}(\underset{\gamma+\varepsilon}{s})\left[\sum_{u \in X} a_{u}(u, u)^{s-\varepsilon-\gamma_{u} d}\right]^{2}=0 .}
$$

This is a sum of squares, with all coefficients of same sign, therefore

$$
\sum_{u \in X} a_{u}(u, u)^{s-\varepsilon-\gamma_{u} g}=0 \quad, \quad \text { if } \quad 2 \varepsilon+\gamma=2 s-t
$$

and in particular

$$
\begin{equation*}
\sum_{u \in X} a_{u} u^{d}=0 \quad \text { if } \quad \gamma=t \tag{ㅁ}
\end{equation*}
$$

We now proceed with the proof of the theorem. From (2) it follows in particular, with $\pi=\prod_{i=1}\left(-\alpha_{i}\right)$ :

$$
a_{u} \pi+\sum_{b: \beta<s}^{\sum} a_{b} u^{b}=0 .
$$

The second term of the left hand side is 0 , by lemma 4.3.2., so finally we arrive at $a_{u}=0$ for all $u \in X$. This finishes the proof of theorem 4.3.1.

### 4.4. The bound in hyperbolic space.

THEOREM 4.4.1. Let X be an s-distance set in $\mathrm{H}^{\mathrm{d}}$, then

$$
\operatorname{card}(X) \leq\binom{\mathrm{d}+\mathrm{s}}{\mathrm{~s}} .
$$

PROOF. We use the representation of $H^{d}$ described in 4.2., each point will be identified with a unit vector in $R^{1, d}$ with positive first coordinate. Let $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{s}$ denote the different values of $\langle u, v\rangle$ for distinct $u, v \in X$. For each $u \in X$ define

$$
F_{u}(x)=\prod_{i=1}^{s}\left(\langle u, x\rangle-\alpha_{i}\right)
$$

and consider these polynomials as elements of the ring

$$
R\left[x_{0}, x_{1}, \ldots, x_{d}\right] /(\langle x, x\rangle-1)
$$

Since $x_{0}^{2}=1+x_{1}^{2}+\ldots+x_{d}^{2}$ in this ring, a basis is formed by the set $\left\{x^{e} \mid e_{0} \in\{0,1\}\right\}$. The $F_{u}$ are independent and they are linear combinations of the basis elements $x^{e}$ with $\varepsilon \leq s$. From this it follows that

$$
\operatorname{card}(X) \leq\binom{ d+s}{s}+\binom{d+s-1}{s=1}
$$

In this case we will show that in fact the following set is independent:

$$
\left\{F_{u}(x), x^{e} \mid u \in X, E \leq s, e_{0}=1\right\}
$$

From this we get $\operatorname{card}(X) \leq\binom{ d+s}{s}$. We shall write

$$
E_{i}=\left\{e \mid \varepsilon \leq s, e_{0}=i\right\} \quad, i=0,1 ; E=E_{0} \cup E_{1}
$$

Also, $\left[x^{f}, x^{e}\right]$ will be abbreviated by $[f, e]$ (see 4.2. last line).

Suppose then we have the following dependence relation:

$$
\begin{equation*}
\sum_{u \in X} a_{u} F_{\mathbf{u}}(x)+\sum_{e \in E_{1}} a_{e^{x^{e}}}=0 \tag{3}
\end{equation*}
$$

d
Then, with $\pi=\prod_{i=1}\left(1-\alpha_{i}\right)$, we have in particular

$$
\begin{equation*}
a_{u} \pi+\Sigma_{e \in E_{1}} a_{e} u^{e}=0, \quad \text { for } a l l \quad u \in X \tag{4}
\end{equation*}
$$

The $F_{u}(x)$ may be represented relative to the basis $\{x \mid e \epsilon E\}$ as follows:

$$
\begin{aligned}
& F_{u}(x)=\sum_{f: \phi \leq s}^{\sum}\binom{\phi}{f}(s-\phi)(-1)^{s-\phi_{u}} f_{x}^{f}(-1)^{\phi-f_{0}}= \\
& \left.=\underset{f: \phi \leq s}{\Sigma}(-1)^{s-f_{0}}(s-\phi)\left({ }_{f}^{\phi}\right) u^{f} \underset{e \in E}{\sum}[f, e] x^{e}\right] .
\end{aligned}
$$

Note that $[f, e]=0$ either for all $e \in E_{0}$ or for all e $\epsilon E_{1}$ depending on whether $f_{0}$ is odd or even. So, comparing coefficients of the respective basis elements we get:

$$
\begin{equation*}
(-1)^{s-1} \sum_{\mathbf{L} \in \mathbf{X}} \mathbf{a}_{\mathbf{u}} \underset{f: \phi \leq s}{\Sigma}\binom{\phi}{f}[f, e] \mathbf{u}^{f_{\alpha}}(s-\phi)+a_{e}=0 \quad \forall e \in E_{1} \tag{5}
\end{equation*}
$$

and

Multiplication of (5) by $v^{e}$ and of (6) by $(-1)^{s-1} v^{e}$ and summation over e $\in E$ yields:

Since $\sum_{e \in E}[f, e] v^{e}=v^{f}$, this together with (4) implies

Finally, after multiplication by $a_{v}$, and summation over all $v \in X$ :

$$
(-1)^{s-1} \underset{f: \phi \leq s}{\sum}\left(_{f}^{\phi}\right) \sigma(s-\phi)\left[\underset{u \in X}{\Sigma} a_{u} u^{f^{f}}\right]^{2}-\pi \underset{u \in X}{\sum} a_{u}^{2}=0
$$

Now $(-1)^{s} \pi>0$ since $a_{i}>1$ for all $i$. Therefore we have again a sum of squares, and $a_{u}=0$ for all $u \in X$. This finishes the proof of theorem 4.4.1. .

## FEW-DISTANCE SETS MOD $p$

5.1. Introduction.

In [FW] the authors proved the following theorem:

THEOREM 5.1.1. Let $F=\left\{F_{i} \mid i \in I\right\}$ be a colleotion of subsets of an $n-s e t$, and tet $\mu_{0}, \mu_{1}, \ldots, \mu_{s}$ be distinct residues moduto a prime $p$, such that $\left|F_{i}\right|=k$, with $k \equiv \mu_{0}(\bmod p)$, and $\left|F_{i} \cap F_{j}\right| \equiv \mu_{h}(\bmod p)$ for some $h, 1 \leq h \leq s$. Then $|F| \leq\left(\frac{n}{s}\right)$.

In this chapter we shall generalize this theorem to arbitrary bilinear form spaces in two ways. Central to the proof is the following lemma, where $Z M$ denotes the set of all $Z$-linear combinations of elements from the set $M$.

LEMMA 5.1.2. Let $M$ be a nonempty finite set of real numbers. If $\mathrm{M} \subset \mathrm{pZM}$ for some prime p , then $\mathrm{M}=\{0\}$.

PROOF. $Q M$ is a finite dimensional vector space over $Q$, the field of rational numbers. Write the elements of $M$ as vectors expressed in some fixed basis of this vector space. For $m \in Q M$ let $v_{p}(m)$ be the minimal exponent of $p$ in all coordinates of $m$ relative to this basis, where the exponent of $p$ in 0 is to be taken $+\infty$. Since $v_{p}(\mathbb{m}+n) \geq \min \left(v_{p}(\mathbb{m}), v_{p}(n)\right)$, we have the following :

$$
\min _{m \in Z M} v_{p}(m)=\min _{m \in M} v_{p}(m)=\min _{m \in p M} v_{p}(m)=1+\min _{m \in M} v_{p}(m) .
$$

Hence $M=\{0\}$.
5.2. The mod $p$-bound , first version.

Let $V=R^{d}$ be equipped with a bilinear form $B$, say

$$
B(x, y)=x_{1} y_{1}+\ldots+x_{q} y_{q}-x_{q+1} y_{q+1}-\ldots-x_{d} y_{d} .
$$

THEOREM 5.2.1. Let X be a set of vectors in V such that there are $a_{0}, a_{1}, \ldots, a_{s} \in Z$ all distinct $\bmod p$ with
(i) $\mathrm{B}(\mathrm{x}, \mathrm{x})=\mathrm{a}_{0}$ for all $\mathrm{x} \in \mathrm{X}$;
(ii) $B(x, y) \equiv a_{i}(\bmod p)$ for some $i, 1 \leq i \leq s i f x \notin y \in X ;$ then $\operatorname{card}(\mathrm{X}) \leq\binom{\mathrm{d}+\mathrm{s}-1}{\mathrm{~d}-1}+\binom{\mathrm{d}+\mathrm{s}-2}{\mathrm{~d}-\mathrm{j}}$.

PROOF. Let Pol (s,d) denote the set of all polynomials of degree at most $s$ in $d$ variables restricted to the "sphere" $B(x, x)=a_{0}$. Then $\operatorname{dim} \operatorname{Pol}(s, d)=\binom{d+s-1}{d-1}+\binom{d+s-2}{d-1}$ (unless $q=0$ or $d$, and $a_{0} \geq 0$ resp. $\left.a_{0} \leq 0\right)$. Again we associate to $x \in X$ the polynomial $f_{x}(y)=\prod_{i=1}^{s}\left((x, y)-a_{i}\right)$ where $(x, y)=B(x, y)$. We then have :

$$
\begin{array}{ll}
f_{x}(x) \neq 0(\bmod p) & \text { for all } x \in X ; \\
f_{x}(y) \equiv 0(\bmod p) & \text { for } x \neq y \in X
\end{array}
$$

Assume there is a relation $\underset{\mathbf{x} \in \mathbb{X}}{\Sigma}{\underset{X}{x}} f_{x}=0$. Inserting $\mathbf{x} \in \mathbb{X}$ in this relation
yields:

$$
m_{x} f_{x}(x)=-\underset{y \neq x}{\Sigma} m_{y} f_{y}(x) \in p Z M,
$$

where $M=\left\{m_{\mathbf{x}} \mid \mathbf{x} \in \mathrm{X}\right\}$. Since $\mathrm{f}_{\mathbf{x}}(\mathbf{x}) \neq 0(\bmod \mathrm{p})$ this implies that $m_{x} \in p Z M$ for all $x$, hence $M \in p Z M$. Lemma 5.1.2. now yields that $M=\{0\}$, i.e., the polymomials are independent. This finishes the proof.

### 5.3. The mod $p$-bound second version.

THEOREM 5.3.1. Let X be a set of vectors in V such that there are $a_{1}, \ldots, a_{s} \in Z$ with
(i) $\mathrm{B}(\mathrm{x}, \mathrm{x}) \in \mathrm{Z}$ and $\mathrm{B}(\mathrm{x}, \mathrm{x}) \not \mathrm{a}_{\mathrm{i}}(\bmod \mathrm{p})$ for all $\mathrm{x} \in \mathrm{X}$ and $\mathrm{l} \leq \mathrm{i} \leq \mathrm{s}$;
(ii) $\mathrm{B}(\mathrm{x}, \mathrm{y}) \equiv \mathrm{a}_{\mathrm{i}}(\bmod \mathrm{p})$ for some $\mathrm{i}, 1 \leq \mathrm{i} \leq \mathrm{s}$ and $\mathrm{x} \neq \mathrm{y} \in \mathrm{X}$; then $\operatorname{card}(\mathrm{X}) \leq\binom{\mathrm{d}+\mathrm{s}}{\mathrm{d}}$.

PROOF. The proof is entirely similar to the previous one. The only difference is that one takes instead of Pol(s,d) the space of all polynomials of degree at most $s$, i.e., no longer restricted to the "sphere".

EXAMPLE 5.3.2. Let $X$ be a set of vectors in $R^{d}$ all with norm $\sqrt{ } 7$. Assume the inner products that are allowed are $0,2,3,5,6$. The bound in theorem 5.2.1. with $p=3$ yields $\operatorname{card}(x) \leq \frac{1}{2} d(d+3)$. So far the best bound was $\binom{d+9}{10}+\binom{d+8}{9}$.

For more significant and realistic examples we refer to the end of the next chapter.

## CHAPTER 6

association schemes, delsarte spaces and the mod p-bound
56.1 Introduction.

The theorem of Frankl and Wilson of the previous chapter deals with collections of k-subsets of an n-set, i.e., sets of points in the Johnson scheme $J(n, k)$. This scheme as well as the Hamming scheme are examples of $Q$-polynomial association schemes. These schemes have central properties in common with finite dimensional projective spaces over the real or the complex numbers. Neumaier [N1] proposed a common generalization which he calls Delsarte spaces. It is our aim in this chapter to present the basic facts concerning association schemes and Delsarte spaces, to prove the generalization of Frankl and Wilson's theorem for Delsarte spaces and to give examples meeting the bound, in particular for the Hamming scheme.
96.2. Association schemes.

Let $X$ be a finite set with cardinality $n$. An s-class assocíation scheme on $X$ is a partition of $X X X$ into $s+1$ symmetric relations $\Gamma_{0}, \Gamma_{1}, \ldots, \Gamma_{s}$ having the following properties :
(i) $\Gamma_{0}$ is the identity : $\Gamma_{0}=\{(x, x) \mid x \in X\}$.
(ii) There are constants $v_{k}, k=0,1, \ldots, s$ such that for all $x \in X$ :

$$
\left|\left\{y \in X \mid(x, y) \in \Gamma_{k}\right\}\right|=v_{k}
$$

(iii) There are constants $\mathbf{a}_{\mathbf{i j}}^{k}, i, j, k=0,1, \ldots, s$ with $\forall(x, y) \in \Gamma_{k}$ :

$$
\left|\left\{z \in X \mid(x, z) \in \Gamma_{i} \wedge(z, y) \in \Gamma_{j}\right\}\right|=a_{i j}^{k}
$$

The $a_{i j}^{k}$ are called the intersection numbers of the scheme, the $v_{k}$ the valencies. Note that (iii) implies (ii) since $v_{k}=a_{k k}^{0}$.

Another way to characterize the defining properties of an association scheme is by means of the adjacency matrices $A_{0}, \ldots, A_{s}$ defined by

$$
\begin{gathered}
A_{i}(x, y)=1 \quad \text { if }(x, y) \in \Gamma_{i}, \\
0 \text { otherwise }
\end{gathered}
$$

Since $\Gamma_{0}$ is the identity $A_{0}=I$. The $\Gamma_{i}$ partition $X \times X$, hence

$$
A_{0}+A_{1}+\ldots+A_{s}=J .
$$

Property (ii) implies $A_{k} J=v_{k} J$ and (iii): $A_{i} A_{j}=\underset{k=0}{s} a_{i j}^{k} A_{k}$. Since the relations $\Gamma_{k}$ are symmetric, so are the matrices $A_{k}$. The vector space $\left\langle A_{0}, A_{1}, \ldots, A_{s}\right\rangle_{R}$ is therefore a commutative algebra called the Bose-Mesner algebra of the association scheme.

EXAMPLES 6.2.2. Let $x$ be the collection of all $k$-subsets of an n-set. Put $(x, y) \in \Gamma_{i}$ if $|x \Delta y|=2 i$, for $i=0,1, \ldots, k$, where $k \leq \frac{1}{2} n$. This defines am association scheme called the Johnson scheme $J(n, k)$. This scheme has the following intersection numbers :

$$
a_{i j}^{h}=\sum_{t=0}^{h}(\underset{k-i-t}{h})(\underset{t}{k-h})(\underset{k-j-t}{h})\binom{n-k-h}{t+j-k}
$$

Next let $X$ be the collection of all subsets of an $n$-set, and put $(x, y) \in \Gamma_{i}$ if $|x \Delta y|=i$; for $i=0,1, \ldots, n$. This association scheme is called the Hamming scheme $H(n, 2)$ and has the following intersection numbers:

$$
\begin{aligned}
& a_{i j}^{h}=\left(\underset{\frac{1}{2}(i-j+h)}{h}\right)\left(\frac{1}{\frac{n}{2}(i+j-h)}\right) \quad \text { if } i+j+h \quad i s \text { even }, \\
& 0 \text { otherwise . }
\end{aligned}
$$

§6.3. The Bose-Mesner algebra.

An important rôle in the theory is played by the basis of orthogonal minimal idempotents (cf [D],[BM]). They are precisely the projectors on
the common eigenspaces of the matrices $A_{0}, A_{1}, \ldots, A_{s}$, and are denoted by $E_{0}, E_{1}, \ldots, E_{s}$ with $E_{0}=\frac{1}{n} \mathrm{~J}$. The Bose-Mesner algebra is also closed under Schur (or Hadamard) multiplication, defined by $A o B(x, y)=A(x, y) . B(x, y)$. This implies the existence of constants $b_{i j}^{k}$ such that $E_{i}{ }^{\circ} E_{j}=\frac{1}{n} \sum_{k=0}^{s} b_{i j}^{k} E_{k}$. Moreover $b_{i j}^{k} \geq 0$ for all $i, j, k$ since $E_{i} o E_{j}$ is a principal minor of $E_{i} \otimes E_{j}$ which is positive semidefinite. The $b_{i j}^{k}$ are called the Krein parameters. Summarizing :
(i)

$$
\begin{array}{ll}
E_{i} E_{j}=\delta_{i j} E_{i} & ; E_{i} o E_{j}=\frac{1}{n} \sum_{k=0}^{s} b_{i j}^{k} E_{k} ; \\
A_{i} O A_{j}=\delta_{i j} A_{i} & ; A_{i} A_{j}=\sum_{k=0}^{s} a_{i j}^{k} A_{k} \tag{ii}
\end{array}
$$

The matrices $P=\left(p_{i k}\right)$ and $Q=\left(q_{i k}\right), i, k=0,1, \ldots, s$ are defined by the following relations :

$$
A_{k}=\sum_{i=0}^{s} p_{i k} E_{i} \quad ; \quad E_{i}=\frac{1}{n} \sum_{k=0}^{s} q_{k i} A_{k}
$$

Note that $p_{i k}$ is an eigenvalue of $A_{k}$ with multiplicity $H_{i}=r k E_{i}=$
$=\operatorname{tr} E_{i}=q_{0 i}$. The $u_{i}$ are called the multiplicities of the scheme. Let $\quad \Delta_{\mu}=\operatorname{diag}\left(\mu_{i}\right) \underset{i=0}{s}$ and $\Delta_{v}=\operatorname{diag}\left(v_{k}\right) \underset{k=0}{s}$. The multiplicities and the valencies are related as follows :

THEOREM 6.3.1. $\quad \Delta_{\mu} P=Q^{t} \Delta_{v}$.
PROOF. $\quad u_{i} p_{i k}=p_{i k} \operatorname{trE}_{i}=\operatorname{tr} A_{k} E_{i}=\underset{e l t s}{\sum E_{i} O A_{k}=-\frac{q_{k i}}{n} \underset{\text { elts }}{\sum A_{k}}=q_{k i} v_{k} .}$

Define a graph on $x$ by $x \sim y$ if $(x, y) \in \Gamma_{1}$. If $(x, y) \in \Gamma_{i}$ iff $d(x, y)=i$ in this graph the scheme is called metric. The Johnson scheme and the Hamming scheme are examples of metric schemes. In a metric scheme $a_{i j}^{k}=0$ if $i+j<k$ because of the triangle inequality (similarly $a_{k j}^{i}=0$ if $i+j<k$, etc.). As a consequence there are polynomials $f_{0}, f_{1}, \ldots, f_{s}$, with $f_{k}$ of degree $k$, such that $A_{k}=f_{k}\left(A_{1}\right)$ and therefore $p_{z k}=f_{k}\left(p_{z 1}\right)$.

Thus the elements of the $k$-th colum of $P$ are polynomials of degree $k$ in the elements of the "first" column. Therefore metric schemes are also called $P$-polynomial. Of more importance to us is the notion $Q$-polynomial. An association scheme is called Q-polynomial, if there exist polynomials $g_{0}, g_{j}, \ldots, g_{s}$, with $g_{k}$ of degree $k$, satisfying $q_{z k}=g_{k}\left(q_{z l}\right)$. Q-polynomial schemes are sometimes also called cometric. As a consequence of theorem 6.3.1., which can also be written in the form $P^{t_{\Delta_{\mu}}} P=n \Delta_{v}$, or $n_{\mu}=Q^{t_{\Delta}} Q_{v}$ we get

$$
\sum_{z=0}^{s} \mu_{z} p_{z k} p_{z t 0}=n v_{k} \delta_{k, m}
$$

and

$$
\sum_{z=0}^{s} v_{z} q_{z k} q_{z m}=n \mu_{k} \delta_{k, m}
$$

That means, that in case the scheme is P -polynomial the $\mathrm{f}_{\mathrm{k}}$ are orthogonal polymomials with respect to the weight $\mu_{z}$. And similar in case of a Q-polynomial scheme.

Let $A$ be a matrix and $f$ a polynomial. Then $f$ o $A$ is the matrix defined by for $A(x, y)=f(A(x, y))$. The following is an alternative definition of $Q$-polynomiality: There exist polynomials $g_{0}, g_{1}, \ldots, g_{s}$, with $g_{k}$ of degree $k$, such that $E_{k}=g_{k} \circ E_{j}$.

### 56.4. Delsarte spaces.

In this section we present the theory of Delsarte spaces from Neumaier [NI]. A finite Delsarte space is the same as a Q-polynomial association scheme,

Let ( $\mathrm{X}, \mathrm{d}$ ) be a metric space with finite diameter $\sqrt{ } \delta$, together with a finite measure $\omega$. We put $w(x)=w$. Write $c_{x y}=d^{2}(x, y)$ for $x, y \in X$, then $0 \leq c_{x y} \leq \delta$. There is an induced measure $\hat{\omega}$ on $X x X$. We define the measure $\mu$ on $[0, \delta]$ by

$$
\mu(A)=w^{-1} \hat{Q}\left(\left\{\{x, y\} \mid c_{x y} \in A\right\}\right), A \subset[0, \delta] .
$$

For every polynomial $f$ the following holds:

$$
\int_{[0, \delta]} f(\alpha) d \mu(\alpha)=w^{-1} \int_{X} \int_{X} f\left(c_{x y}\right) d \omega(x) d \omega(y)
$$

If $X$ is finite, $\omega$ and $\mu$ are taken to be multiples of counting measures, and all integrals are finite sums. Suppose $X$ has $s$ non-zero distances, i.e., $s+1$ is the smallest cardinal of a set $T$ satisfying $\mu([0, \delta] T)=0$. We call $s$ the degree of $x$.

THEOREM 6.4.1. There exists a family $\left\{\mathbf{q}_{\mathbf{i}}\right\}, \mathrm{i}=0,1, \ldots, \mathrm{~s}$, if $\mathrm{s}<\infty$, resp. $i=0,1, \ldots$ if $s$ is infinite, of orthogonal polynomials, with $\operatorname{deg}\left(q_{i}\right)=\mathbf{i}$,i.e., the $q_{i}$ satisfy

$$
\int_{[0, \delta]} q_{i}(\alpha) q_{j}(\alpha) d \mu(\alpha)=\delta_{i j}
$$

PROOF. ( $f, g$ ) $=\int f(\alpha) g(\alpha) d \mu(\alpha)$ is a positive definite inner product on the space of all polynomials of degree at most $s$, since ( $f, f$ ) $=0$ implies $f(\alpha)=0$ a.e.. Using Gram-Schmidt on the basis $\left\{1, x, \ldots, x^{s}\right\}$ (if $s$ is finite) yields the family $\left\{q_{i}\right\}$.

The following definition is the analogue for metric spaces of the notion of Q-polynomiality.

DEFINITION 6.4.2. ( $\mathrm{X}, \mathrm{d}, \omega$ ) is a Delsarte space if for each pair of nonnegative integers $i, j$, there exists a polynomial $f_{i j}$ of degree at most min\{i,j\} such that for all $a, b \in X$ :

$$
\int_{x} c_{a x}^{i} c_{b x}^{j} d \omega(x)=f_{i j}\left(c_{a b}\right)
$$

THEOREM 6.4.3. Let x be a Delsarte space with degree s . Then for alt $i, j \in\{0,1, \ldots, s\}$ and $a, b \in \mathrm{x}$ :

$$
\begin{equation*}
\int_{x} q_{i}\left(c_{a x}\right) q_{j}\left(c_{b x}\right) d \omega(x)=q_{i}(0)^{-1} q_{i}\left(c_{a b}\right) \delta_{i j} \tag{1}
\end{equation*}
$$

PROOF. By induction: assume ( 1 ) is true for all $\mathbf{i} \leq \mathbf{i}_{0}, j \leq j_{0}$, but $(i, j) \neq\left(i_{0}, j_{0}\right)$. The definition of Delsarte space implies the existence of constants $\mathbf{u}_{i_{0} j_{0}}^{k}$ such that

$$
\begin{equation*}
\int_{x} q_{i_{0}}\left(c_{a x}\right) q_{j_{0}}\left(c_{b x}\right) d \omega(x)=\sum_{k=0}^{m} u_{i_{0}}^{k} j_{0} q_{k}\left(c_{a b}\right) \tag{2}
\end{equation*}
$$

Here $m=\min \left(i_{0}, j_{0}\right)$. Take $i_{0} \leq j_{0}$ without loss of generality. For h<io, multiplication of (2) by $q_{h}\left(c_{b y}\right)$ followed by integration over $b$ yields (using the induction hypothesis and changing the order of integration):

$$
\begin{aligned}
& \left.0=\int_{x} q_{i_{0}}\left(c_{a x}\right) d \int_{x} q_{j_{0}}\left(c_{b x}\right) q_{h}\left(c_{b y}\right) d \omega(b)\right\} d \omega(x)= \\
& =\sum_{k=0}^{i_{0}} u_{i_{0} j_{0}}^{k} \int q_{k}\left(c_{a b}\right) q_{h}\left(c_{b y}\right) d \omega(b)=u_{i_{0} j_{0}}^{h} q_{h}(0)^{-1} q_{h}\left(c_{a y}\right),
\end{aligned}
$$

whence $\mathbf{u}_{\mathbf{i}_{0} j_{0}}^{h}=0$ for all $h<i$. Therefore

$$
\int_{X} q_{i_{0}}\left(c_{a b}\right) q_{j_{0}}\left(c_{b x}\right) d \omega(x)=u_{i_{0}}^{\mathbf{i}_{0}} q_{i_{0}}\left(c_{a b}\right)
$$

Finally let $a=b$ and integrate over $a$ :

$$
\begin{aligned}
& \delta_{i j} w=w \int q_{i}(\alpha) q_{j}(\alpha) d \mu=\iint q_{i}\left(c_{a x}\right) q_{j}\left(c_{a x}\right) d \omega(a) d \omega(x)= \\
& =\int u_{i_{0}} j_{0} q_{i}(0) d \omega(a)={i_{0}}_{0} j_{0} q_{i}(0) w .
\end{aligned}
$$

Hence $q_{i}(0) \neq 0$ and $\mathbf{u}_{i_{0} j_{0}}=q_{i_{0}}{ }^{-1} \delta_{i_{0}} j_{0}$, proving (1). Let $H(t)$ denote the space of all functions on $X$, that can be written as linear combinations of functions in the set $\left\{c_{a x}^{i} \mid a \in X\right\}$ and $0 \leq i \leq t$. Then $H(t)$ is a positive definite inner product space when we define $(f, g)=\int_{X} f(x) g(x) d w(x)$.

The subspace of $H(t)$ generated by the functions $x \rightarrow \mathcal{T}_{i}\left(c_{a x}\right), a \in X$, is called harm(i) . From theorem 6.4.3. we have the following decomposition:

$$
H(t)=\operatorname{harm}(0) \perp \text { harm }(1) \perp \ldots \perp \operatorname{harm}(t)
$$

THEOREM 6.4.4. $\operatorname{Dim} \operatorname{harm}(\mathrm{i})=\mathrm{q}_{\mathrm{i}}(0)^{2} \mathbf{w} \geqslant 0$ for $0 \leq \mathrm{i} \leq \mathrm{s}$.

PROOF. Consider an orthonormal basis $\left\{s_{h} \mid h \in L\right\}$. For certain functions $P_{h}$, and a finite set $A_{h} \subset X$ :

$$
\begin{equation*}
s_{h}(x)=\underset{b \in A_{h}}{\sum} p_{h}(b) q_{i}\left(c_{b x}\right) \tag{3}
\end{equation*}
$$

Also for certain functions $\quad r_{h}$ :

$$
\begin{equation*}
q_{i}\left(c_{a x}\right)=\sum_{h \in L} r_{h}(a) s_{h}(x), \tag{4}
\end{equation*}
$$

where for each $a \in X$ only finitely many $r_{h}(a) \neq 0$. Using (3), (4) and theorem 6.4.2. one obtains

$$
\begin{aligned}
& r_{h}(a)=\left\langle q_{i}\left(c_{a x}\right), s_{h}(x)\right\rangle=\int q_{i}\left(c_{a x}\right) s_{h}(x) d \omega(x)= \\
& =\int_{x} \sum_{b \in A_{h}} P_{h}(b) q_{i}\left(c_{a x}\right) q_{i}\left(c_{b x}\right) d \omega(x)= \\
& =\sum_{b \in A_{h}}^{\sum} P_{h}(b) q_{i}(0)^{-1} q_{i}\left(c_{a b}\right)=q_{i}(0)^{-1} s_{h}(a) .
\end{aligned}
$$

Hence $s_{h}(a)=q_{i}(0) q_{i}\left(c_{a x}\right)$ and by (4):

$$
\begin{equation*}
\sum_{h \in L} s_{h}(a) s_{h}(x)=q_{i}(0) q_{i}\left(c_{a x}\right), \tag{5}
\end{equation*}
$$

where for each $a \in X$ only finitely many $s_{h}(a) \neq 0$. Hence for all $X \in X$

$$
\underset{h \in L}{\sum} s_{h}(x)^{2}=q_{i}(0)^{2},
$$

and

$$
\begin{aligned}
& \operatorname{card}(L)=\sum_{h \in L}\left(s_{h}, s_{h}\right)=\sum_{h \in L} \int_{X} s_{h}(x)^{2} d \omega(x)= \\
& =\int \sum_{h \in L} s_{h}(x)^{2} d \omega(x)=\int_{X} q_{i}(0)^{2} d \omega(x)=q_{i}(0)^{2} w .
\end{aligned}
$$

association schemes is provided by

THEOREM 6.4.5. A finite metric space with distance matrix $C$ is a Delsarte space (with respect to the discrete measure) iff its distribution scheme is a Q-polynomial association scheme.

PROOF. The distance matrix of a finite metric space $X$ is defined by $C(x, y)=d^{2}(x, y)$ for $x, y \in X$. The associated distribution scheme has as relations the distances that occur in $X$. We will show that the minimal idempotents can be labeled in such a way that $E_{k}=g_{k} \circ C$, for the following polynomials $g_{k}$ of degree $k: g_{k}(x)=q_{k}(0) q_{k}(x)$.

By theorem 6.4.3. :

$$
\int_{x} q_{k}\left(c_{a x}\right) q_{j}\left(c_{b x}\right) d \omega(x)=q_{k}(0)^{-1} q_{k}\left(c_{a b}\right) \delta_{i j}
$$

Multiplying this equation by $\mathbf{q}_{\mathbf{k}}{ }^{(0)} \mathfrak{q}_{\mathbf{j}}(0)$ yields

$$
\sum_{x \in X} g_{k}\left(c_{a x}\right) g_{j}\left(c_{b x}\right)=g_{k}\left(c_{a b}\right) \delta_{k j}
$$

so

$$
\left(g_{k} \circ C\right)\left(g_{j} \circ C\right)=\left(g_{k} \circ C\right)_{k j} \quad: E_{k} E_{j}=\delta_{k j} E_{k}
$$

Therefore $E_{0}, E_{1}, \ldots, E_{s}$ are $s+1$ mutually orthogonal idempotents forming a basis. For the if part, and the implicitly used fact that the distibution scheme is an association scheme we refer to [ Nl ].

A Delsarte space is a metric space. This seems to suggest that only Q-polynomial schemes that are metric, i.e., P-polynomial, are Delsarte spaces. However the two "metrics" are different:

REMARK 6.4.6. Every finite scheme can be realized as the distribution scheme of a spherical metric space.

For the proof we refer again to [N1].

In case of a Q-polynomial scheme, dim harm(i) is equal to $\mu_{i}=r k E_{i}$. For a number of infinite Delsarte spaces dim harm(i) has been computed by Hoggar [H].
56.5. The mod p-bound in Delsarte spaces.

THEOREM 6.5.1. Let X be a Delsarte space and B a set of points in X . Suppose there is a prime p , and integers $\mathrm{a}_{1}, \ldots, a_{t} \neq 0(\bmod \mathrm{p})$ such that for $a l l a \neq b$ in $B: c_{a b}=a_{i}(\bmod p)$ for some $i: k i \leq t$. Then

$$
\operatorname{card}(B) \leq \sum_{i=0}^{t} \operatorname{dim} \operatorname{harm}(i) .
$$

PROOF. $H(t)$ has finite dimension $\sum_{i=0}^{t}$ dim harm(i), and the inner product ((1) in theorem 6.4.2.) is nondegenerate. Hence for all $x \in X$, there is an $\tilde{x} \in H(t)$ satisfying $\langle\tilde{x}, f\rangle=f(x)$. We will show, using lemma 5.1.2. that $\widetilde{B}:=\{\tilde{\mathrm{b}} \mid \mathrm{b} \in \mathrm{B}\}$ is an independent subset of $\mathrm{H}(\mathrm{t})$. Suppose

$$
\begin{equation*}
\underset{b \in B}{\Sigma} m_{b} \tilde{b}=0, \tag{6}
\end{equation*}
$$

for certain coefficients $m_{b}$. For each $a \in B$ define $f_{a}(x)=F\left(c_{a x}\right)$, where $F(u):=\prod_{i=1}^{t}\left(a_{i}-u\right)$. Since $F$ is a polynomial of degree $t$, $f_{a}$ is in $H(t)$. Taking the inner product of $f_{a}$ with (6) yields

$$
\underset{b \in B}{\sum} m_{b}<\tilde{b}, f_{a}>\sum_{b \in B}^{\Sigma} m_{b} f_{a}(b)=0 .
$$

Now $f_{a}(b) \equiv 0(\bmod p) \quad$ if $b \neq a \quad$ and $f_{a}(a)=\prod_{i=1}^{t} \quad a_{i} \neq 0(\bmod p)$. Let $M=\left\{m_{b} \mid b \in B\right\}$, then $m_{a} \in p Z M$ with a arbitrary. Therefore $M$ cpZM and we may apply leman 5.1.2., so $M=\{0\}$.

### 56.6. Examples.

The Johnson scheme $J(n, k)$ is a Delsarte space if we define $c_{x y}=\frac{1}{2}|x \Delta y|$. In this case $\operatorname{dim}$ harm $(i)=\binom{n}{i}-\binom{n}{i-1}$. Hence we get the following bound for a $t$-distance set $\bmod p: \sum_{i=0}^{t}\left[\binom{n}{i}-\binom{n}{i-1}\right]=\binom{n}{t}$. This is exactly

Frankl and Wilsons result (cf. theorem 5.1.1.).
The Hamming scheme $H(n, 2)$ is a Delsarte space for $c_{x y}=|x \Delta y|$. Dim harm(i) $=\binom{n}{i}$ and the bound for a $t$-distance set mod $p$ becomes

$$
\sum_{i=0}^{t}\binom{n}{i} .
$$

There seem to be many examples realizing this bound :

EXAMPLE 6.6.1. Let $p$ be any prime. $B$ is the collection of subsets with even cardinality of a $(2 \mathrm{p}-1)$-set. No distance in B is $0(\bmod \mathrm{p})$

EXAMPLE 6.6.2. Let $n \equiv 3(\bmod p)$. $B$ is the collection of subsets of an $n$-set with cardinality 0 or $n-1$. All distances are $2(\bmod p)$.

EXAMPLE 6.6.3. Let $n \equiv 2$ (mod 3). $B$ consists of the empty set, all 2 -sets and all ( $n-1$ )-sets. Distance $0(\bmod 3)$ does not occur.

EXAMPLE 6.6.5. Let $n \equiv 2(\bmod 5)$. B consists of all singletons, 3 -sets, ( $\mathrm{n}-2$ )-sets and the complete set. Distances are 1,2 and $4(\bmod 5)$.

EXAMPLE 6.6.5. Let $n=m^{2}+m+1$ be the order of a projective plane, $\mathrm{pl}(\mathrm{m}-2)$, and p odd. The set of all lines, together with the complete set realizes the bound. All distances are $4(\bmod p)$.

EXAMPLE 6.6.6. Let $P$ be a projective plane of order $n$. We can define a Q-polynomial association scheme as follows : $X$ consists of the points and lines of the projective plane; relation 1 consists of all incident point line pairs; relation 2 of all point point and all line line pairs; relation 3 is the rest. For $a, b$ in $X$ the following, normalized, non-zero values occur : $\{n \sqrt{n}, n \sqrt{n}+n+\sqrt{n}, n \sqrt{n}+\sqrt{n}+n+1\}$. Unfortunately, these never reduce to less nonzero numbers modulo a prime. Hence we do not obtain new criteria for the existence of projective planes.

In a similar way one cam see that no now existence conditions for strongly regular graphs are obtained.

ISOSCELES POINT SETS

## §7.1. Introduction and notation.

In this chapter we will solve a problem, due to Paul Erdös, related to two-distance sets in Euclidean space. An isosceles set is a set of points such that among any three of them at most two distances occur, i.e., every triangle is isosceles. Two-distance sets are isosceles sets. We will show that essentially the converse is also true. More precisely we prove that isosceles sets can be de composed in a collection of mutually "orthogonal" two-distance sets. This gives the bound $\frac{1}{2}(\mathrm{~d}+1)(\mathrm{d}+2)$ for an isosceles set in Euclidean d-space. It also shows that maximal two-distance sets yield maximal isosceles sets. Throughout this chapter $X$ will denote an isosceles set in $R^{d}, X=\left\{x_{1}, x_{2}, \ldots, x_{v}\right\}$, and we assume

$$
\operatorname{aff}(\mathrm{X}):=\left\{\sum_{i=1}^{v} a_{i} x_{i} \mid \sum a_{i}=1\right\}=R^{d}
$$

For any subset $X_{1} \subset X, \operatorname{dim}\left(X_{1}\right)$ will denote the dimension of aff $\left(X_{1}\right)$. The set $X$ is called decomposable if there is a partition $X=X_{1} \cup X_{2}$, with card $\left(X_{2}\right)>1$ and $X_{1} \neq \emptyset$, such that any point of $X_{1}$ is equidistant to all points of $X_{2}$ (this distance may vary for different points of $X_{1}$ ).
§7.2. The structure of isosceles sets.

LEMMA 7.2.1. If $\left(\mathrm{X}_{1}, \mathrm{X}_{2}\right)$ is a decomposition for X , then

$$
\operatorname{dim}\left(X_{1}\right)+\operatorname{dim}\left(X_{2}\right) \leq \operatorname{dim}(X)
$$

PROOF. Let $P$ be the orthogonal projection on aff $\left(X_{2}\right)$. Then for any $x_{1} \in X_{1}, P x_{1}$ is the center of a sphere in aff $\left(X_{2}\right)$ containing $X_{2}$. Since $X_{2}$ spans aff $\left(X_{2}\right), P$ maps $X_{1}$ onto a single point. Therefore the flats aff $\left(X_{1}\right)$ and $\operatorname{aff}\left(X_{2}\right)$ are orthogonal.

THEOREM 7.2.2. Let X be an isosceles set. If X is indecomposable then it is a two-distance set.

PROOF. Consider the complete graph on the points of $X$, with the following edge coloring: to each Euclidean distance between different points $x, y$ of $X$ we associate a unique color $c(x, y)$. The set of colors thus obtained will be called $C$. For each $c \in C$, $X_{c}$ denotes the induced graph on the color $c$, that is, the graph with point set $X$ and edges the pairs $\{x, y\}$ with $c(x, y)=c$. The following two lemmas together provide the proof of theorem 7.2.2.:

LEMMA 7.2.3. If X is an indecomposable isosceles set, then for each $\mathrm{c} \in \mathrm{C}$ the graph $\mathrm{X}_{\mathrm{c}}$ is connected.

PROOF. Let $c$ be a color for which $X_{c}$ is disconnected and let $X_{2}$ be a connected component of $X_{c}$ having more than one point. From the isosceles property it now follows that each point not in $X_{2}$ is joined to the points of $X_{2}$ with edges of the same color. Indeed, if $y z$ is a $c$-colored edge in $X_{2}$ and $x \in X X_{2}$ then $c(x, y)$ and $c(x, z)$ are different from $c$ since $X_{2}$ is a component of $X_{c}$. Hence they are equal. This implies that $\left(X \backslash X_{2}, X_{2}\right)$ is a decomposition of $X$, contradicting the assumption that $X$ is indecomposable.

LEMMA 7.2.4. Let the edges of the conqlete groph $x$ be colored with $\mathbf{k}$ colors, such that
(i) for each $c \in C, X_{c}$ is connected;
(ii) in each triangle at most two colons occur.

Then $\mathrm{k} \leq 2$.

PROOF. We distinguish two cases. First we assume that there is a color $c \in C$ for which the diameter of $X_{c}$ exceeds 2 . Secondly we treat the case that $\operatorname{diam}\left(X_{c}\right) \leq 2$ for all $c \in C$.

CASE 1. Let $c \in C$ and suppose $u$ and $\nabla$ have distance 3 in the graph $X_{c}$. Put $c(u, v)=a$. Let $U$ be the set of points in $X$ that are closer to $u$ than to $v$ in the graph $X_{c}$ and put $V=X \backslash U$.

For any $z \in U$ there is ( $u, z$ )-path entirely in $U$, so by the isosceles property (ii), $c(v, z)=a$. Similarly $c(u, w)=a \quad$ for all $w \in V$. Now take $z_{1} \in U$ and $z_{2} \in V$ and let $P_{1}$ be a shortest $\left(z_{1}, u\right)$ path and $P_{2}$ a shortest $\left(z_{2}, v\right)-p a t h$. We will show that $c\left(z_{1}, z_{2}\right) \in\{a, c\}$. If $z_{1} \sim z_{2}$ in $X_{c}$ then $c\left(z_{1}, z_{2}\right)=c$. If $z_{1}$ is not adjacent to any point on $P_{2}$ then $c\left(z_{1}, z_{2}\right)=a$ by the isosceles property (ii). The same is true if $z_{2}$ is not adjacent to any point of $P_{1}$. Finally let $z_{1}$ have a neighbor $z_{1}^{\prime}$ on $P_{2}$ and $z_{2} \sim z_{2}^{\prime}$ on $P_{1}$. Then

$$
d_{c}\left(v, z_{1}\right) \leq d_{c}\left(v, z_{2}^{\prime}\right)+1=d_{c}\left(v, z_{2}\right) \leq d_{c}\left(v, z_{1}^{\prime}\right)+1=d_{c}\left(u, z_{1}\right)
$$

This contradicts the fact that $z_{1} \in U \quad\left(d_{c}\right.$ denotes the distance in the graph $X_{c}$ ). So indeed for $a 11 z_{1} \in U$ and $z_{2} \in V, c\left(z_{1}, z_{2}\right) \in\{a, c\}$. But now for any further color $b$, the graph $X_{b}$ cannot be connected, since no edge of color $b$ joins $U$ with $V$. Hence $k \leq 2$.

CASE 2. We now assume that $X_{c}$ is connected and has diameter at most 2 for each $c \in C$. Let $a, b, c$ be three different colors in $C$. We shall construct an infinite subset of $X$, thus obtaining a contradiction. Let $z$ be an arbitrary point in $X$, and $a_{1}$ a point with $c\left(a_{1}, z\right)=a$. Since diam $\left(X_{b}\right) \leq 2$, there is a point $b_{1}$ having $c\left(b_{1}, z\right)=c\left(b_{1}, a_{1}\right)=b$. Similarly there is a point $c_{1}$ with $c\left(c_{1}, z\right)=c\left(c_{1}, b_{1}\right)=c$. Since $c_{1} a_{1}$ is both in triangle $c_{1} a_{1} b_{1}$ and $c_{1} a_{1} z, c\left(c_{1}, a_{1}\right)=c$ also. Next let $a_{2}$ be a point satisfying $c\left(a_{2}, c_{1}\right)=c\left(a_{2}, z\right)=a$ and define $b_{2}, c_{2}, a_{3}, \ldots$ analogously. We will show that at each stage the new constructed point has edges of the same color to all previous points. Suppose the new point is $a_{k}$, and assume that our induction hypothesis holds for $a_{1}, b_{1}, \ldots, c_{k-1}$. By definition $c\left(a_{k}, z\right)=c\left(a_{k}, c_{k-1}\right)=a$. Comparing $z a_{k} b_{j}$ and $c_{k-1} a_{k} b_{j}$ we see that $c\left(a_{k} b_{j}\right)=a$. By comparison of $z a_{k} c_{j}$ and $b_{j+1} a_{k} c_{j}$ (where $j+1 \leq k$ ) we conclude that $c\left(a_{k}, a_{j}\right)=a$. For $b_{k}$ and $c_{k}$ a similar proof holds. Since all points are new this procedure produces an infinite subset, contradiction. Hence $k$ is at most 2 .
The lemmas 7.2.3. and 7.2.4. together yield the proof of theorem 7.2.2.
THEOREM 7.2.5. Let X be an isosceles set in $\mathrm{R}^{\mathrm{d}}$, then $\operatorname{card}(\mathrm{X}) \leq \frac{1}{2}(\mathrm{~d}+1)(\mathrm{d}+2)$. Equality implies that X is a two-distance set, or a spherical two-distonce set together with its center.

PROOF. The proof is by induction on $d$. If $d=1$ then $|X| \leq 3$. For $d=2$, Kelly proved [K] that the maximum is 6, realized only by the centered regular pentagon. Now let $d>2$. If $X$ is a two-distance set, then we have the required inequality from theorem 4.1.1. If $X$ has more distances, then by theorem 7.2.2. $X$ is decomposable. Let ( $X_{1}, X_{2}$ ) be a decomposition.

Case 1. $\operatorname{Dim}\left(X_{1}\right) \neq 0$. It follows from lemma 7.2.1. , with $\operatorname{dim}(X)=d$ that $0<\operatorname{dim}\left(X_{1}\right)<d$, since $\left|X_{2}\right|>1$. Let $\operatorname{dim}\left(X_{i}\right)=d_{i}$, then by induction it follows that

$$
|x|=\left|x_{1}\right|+\left|x_{2}\right| \leq \sum_{i=1}^{2} \frac{1}{2}\left(d_{i}+1\right)\left(d_{i}+2\right)<\frac{1}{2}(d+1)(d+2) .
$$

Case 2. $\operatorname{Dim}\left(X_{1}\right)=0$. In this case $X_{1}$ is a singleton and $X_{2}$ lies on a sphere. If $X_{2}$ is not a two-distance set it is again decomposable and we are in case 1 again. Otherwise

$$
|x|=1+\left|x_{2}\right| \leq 1+\frac{1}{2} d(d+3)=\frac{1}{2}(d+1)(d+2)
$$

Equality therefore implies that $X$ is a centered maximal two-distance set.

## CHAPTER

## graphs related to polar spaces

### 58.1. Introduction.

Let $P$ be a finite projective geometry, that is, the collection of all subspaces of a finite projective space. A polarity $\pi$ on $P$ is a permutation of $P$ of order 2 , reversing inclusion:

$$
\forall S, T \in P:(S \subset T) \Rightarrow\left(T^{\pi} \subset S^{\pi}\right) \quad \text { and } \quad \pi^{2}=1 .
$$

A subspace $S \in P$ is called totally isotropic if $S \in S^{\pi}$. The set $S(\pi)$ of all (totally) isotropic points of $\pi$ is provided with three essentially equivalent structures, namely (cf. [BS]) :
(i) A graph structure: $p \sim q$ if $p \in q^{\pi}$, for $p, q \in S(\pi)$.
(ii) The structure of the totally isotropic lines.
(iii) The structure of the totally isotropic subspaces, partially ordered by inclusion.

The set $S(\pi)$ provided with any of the structures (i), (ii) and (iii) is called the polar space relative to $\pi$. All maximal totally isotropic subspaces have the same dimension $d$ and $d+1$ is called the rank of $S(\pi)$. Also given a maximal t.i. subspace $L$ and a point $p \in S(\pi) \backslash L$ there is a unique maximal t.i. subspace $M$ such that $p \in M$ and $M \cap L$ has dimension $d-1 \quad(M=\langle p \pi \cap L, p\rangle)$. Hence the graph (i) defined on $S(\pi)$ has the following two properties:
(i) $\exists \mathrm{K}: ~ e v e r y ~ m a x i m a l ~ c l i ́ q u e ~ h a s ~ s i z e ~ K . ~$
(ii) ヨe: given a maximal clique $C$ and a point $p \& C$, there are precisely $e$ points in $C$ adjacent to $p$.

In this chapter we shall investigate graphs satisfying these two conditions. A finite graph satisfying (i) and (ii) will be called a Zara-graph, after
F. Zara who introduced the concept in [z].
58.2. Preliminaries and notation.

Following Higman [Hi] we use the following graph theoretical notation. Let $G=(V, E)$ be a simple graph. We write $x \sim y$ or $x \perp y$ if $\{x, y\} \in E$ and $x^{\perp}=\{y \in V(G) \| x=y$ or $x \sim y\}$. A graph $G$ is called connected if for all $x, y \in V(G)$ there is a sequence $x=x_{0}, x_{1}, \ldots, x_{n}=y$, such that $x_{i} \sim x_{i+1}$ for $i=0, \ldots, n-1$. $G$ is called coconnected if the complement of $G$ is connected. If $G_{1}$ is a Zara-graph with parameters $\left(K_{1}, e_{1}\right)$ and $G_{2}$ is a Zara-graph with parameters $\left(K_{2}, e_{2}\right)$, then the graph obtained by joining all points of $G_{1}$ to all points of $G_{2}$ is a Zara graph whenever $K_{1}+e_{2}=K_{2}+e_{1}$. Every Zara-graph can be built from coconnected Zara-graphs in this way. Our main concern will therefore be the structure of coconinected or cc-Zara-graphs.

Note that if $G$ is a Zara-graph with parameters ( $K, e$ ), then the induced subgraph on $x \backslash\{x\}$ is a Zara-graph with parameters (K-1,e-1). This graph is called the residue of $x$, or $\operatorname{Res}(x)$. For arbitrary $S \subset V$, we define $S^{\perp}=\cap x^{\perp}$. If $S$ is a clique, Res $(S)$ is defined analogous$x \in S$
$1 y$, i.e., Res (S) is the induced subgraph on $S \backslash S$. Again Res (S) is a Zara-graph with parameters ( $K-|S|, e-|S|$ ). An equivalence relation $\approx$ is defined on $V$ by $x \Leftrightarrow y \Leftrightarrow x^{\perp}: y^{\perp}$. The equivalence classes [x] are cliques and if $x$ and $y$ are adjacent then all points in [ $x$ ] are adjacent to all points in [y]. The graph $G / a$ is defined on $V / s s$ by $[x] \sim[y]$ whenever $x \sim y$ and $[x] \neq[y]$. This graph is called the reduced graph of $G$. In general a graph $H$ is called reduced if $[x]=x \quad$ for each point $x \in V(H)$. In 58.6. we will show that the reduced graph of a ce-Zara-graph is a (reduced) ce-Zara-graph.

Let $S$ be a clique in a graph $H$. Then $S^{\perp \perp}$ is again a clique since $S \in S^{\perp \perp} \in S^{\perp}$. Note that $S^{\perp \perp}=\left(S^{\perp \perp}\right)^{\perp \perp}$. We call $S^{\perp \perp}$ the closure of $S$, in particular $x^{\perp \perp}=[x]$. An equivalent way of defining reduced is to say that each point is closed. The key theorem, whinh allows us to use induction in the proofs that follow, is the fact that for each $x$ in a ce-Zara-graph the residue of the closure of $x$, Res ([ $x]$ ), is again a cc-Zara-graph (theorem 8.5.3.). Using this we can prove that all equivalence classes under $\approx$ have the same size. It follows that if $G$ is a cc-Zara-graph with parameters ( $K, e$ ), then $G / a$ is again a
cc-Zara-graph with parameters ( $K /[[x] \mid, e /[x]]$ ). Closures of cliques are called singular subsets or closed cliques: The closure of the empty set is called the radical of $G, \operatorname{rad}(G)$. The intersection of two singular subsets is again a singular subset. For $x, y \in X$ we define:

$$
\begin{aligned}
& d(x)=\left|x^{\perp}\right|-1 ; d(x) \text { is called the degree of } x ; \\
& \lambda(x, y)=\left|x^{\perp} \cap y^{\perp}\right|-2, \\
& \mu(x, y)=\left|x^{\perp} \cap y^{\perp}\right| \quad, \quad \text { if } x \sim y ;
\end{aligned}
$$

If $d, \lambda$ and $\mu$ are constant the graph is called strongly regular. We will show that a reduced ce-Zara-graph is strongly regular. The collection of singular subsets forms a partially ordered set under inclusion. In a polar space this is exactly the structure of all totally isotropic subspaces. This poset will be investigated in. $£ \$ 8.5$ and 6 . Following Neumaier [N1] we define the notion of an $M_{r}$-space: (cf. also [N3])

Let $P$ be a set of points and $X_{1}, X_{2}, \ldots, X_{r}$ sets of subsets of $P$. Write $X=X_{1} \cup \ldots U X_{r}$. Elements of $X_{i}$ are called i-varieties, r-varieties are also called blocks. $X$ is an $M_{r}$-space if it satisfies:
(i) $\quad X_{1}$ is the set of all singletons $\{a\}, a \in P$.
(ii) There are constants $1=K_{1}<\ldots<K_{r}$, such that an i-variety contains exactly $K_{i}$ points.
(iii) There are constants $R_{1}>\ldots>R_{r}=1$, such that an i-variety is contained in exactly $R_{i}$ blocks.
(iv) The intersection of two varieties is a variety or empty.
(v) If $x$ is an i-variety, $z$ a block containing $x$ and $p$ a point in $z$ but not in $x$, then there is an (i+1)-variety $y \subset z$ containing $x$ and $p$.

The main result in this chapter is that a reduced co-Zara-graph is an $M_{r}$-space for some $r$, called the rank of the Zara-graph.
§8.3. Examples of Zara-graphs.

In [Z] Zara gives the following examples of (cc-) Zara-graphs.

1. Polar spaces. Let $W$ be an m-dimensional vector space, $m$ finite, over a finite field $F$, together with a field automorphism $\beta$ satisfying $\beta^{2}=1$. Let $F_{0}$ denote the subfield fixed by $\beta$. Put $\left|F_{0}\right|=q$, then $|F|=q$ or $|F|=q^{2}$.
Let $\phi: W x W \rightarrow F$ be a $\beta$-sesquilinear form, nondegenerate and reflexive. $Q: W+F$ is a quadratic form with an associated bilinear nondegenerate form $\phi_{1}: W \times W \rightarrow F$. The following graphs are Zara-graphs. In each case $V$ is the set $\{\langle a\rangle \mid a \in V \backslash\{0\}\}$, <a> isotropic, resp. singular\}, and $\langle a\rangle \sim<b\rangle$ if $\phi(a, b)=0$, resp. $\phi_{1}(a, b)=0$ and $\langle a\rangle \neq\langle b\rangle$. The following cases occur :
(Sp). $\phi$ alternating, $m=2 m_{1}, \quad \beta=1 ;$

$$
(|V|, K, e)=\left(\left(q^{m}-1\right) /(q-1), \quad\left(q^{m_{1}}-1\right) /(q-1), \quad\left(q^{m_{1}}-1\right) /(q-1)\right)
$$

(Q). $Q$ quadratic , $\beta=1$;
(i) $\quad m=2 m_{1}+1 ;\left(\left(q^{m-1}-1\right) /(q-1),\left(q^{m_{1}}-1\right) /(q-1),\left(q^{m_{1}^{-1}}-1\right) /\left(q^{-1}\right)\right)$.
(ii) $m=2 m_{1}$, maximal Witt index ;

$$
\left(\left(q^{m_{1}}-1\right)\left(q^{m_{1}^{-1}}-1\right) /(q-1),\left(q^{m_{1}}-1\right) /(q-1),\left(q^{m_{1}^{-1}}-1\right) /(q-1)\right)
$$

(iii) $m=2 m$, non-maximal Witt index ;

$$
\left(\left(q^{m_{1}}+1\right)\left(q^{m_{1}^{-1}}-1\right) /(q-1), \quad\left(q^{m_{1}^{-1}}-1\right) /(q-1), \quad\left(q^{m_{1}^{-2}}-1\right) /(q-1)\right.
$$

(U) . $\phi$ a non-degenerate $\beta$-hermitean form, $|F|=q^{2}$;
(i) $\quad m=2 m_{1} \geq 4$

$$
\left(\left(q^{\mathrm{m}}-1\right)\left(q^{\mathrm{m}-1}+1\right) /\left(q^{2}-1\right),\left(q^{\mathrm{m}}-1\right) /\left(q^{2}-1\right),\left(q^{m-2}-1\right) /\left(q^{2}-1\right)\right)
$$

(ii) $m=2 m_{1}+1 \geq 3$

$$
\left.\left.\left(\left(q^{m}+1\right)\left(q^{m-1}-1\right) / q^{2}-1\right),\left(q^{m-1}-1\right) /\left(q^{2}-1\right), q^{m-3}-1\right) /\left(q^{2}-1\right)\right)
$$

(GO). Rank 2 polar spaces, or generalized quadrangles $C Q(s, t)$. For definition and examples of generalized quadrangles see [Th].

$$
(|v|, \mathrm{K}, \mathrm{e})=((\mathrm{s}+1)(\mathrm{st+1}), \mathrm{s}+1,1)
$$

2. Let $W$ be a 2 m-dimensional vector space over $G F(2)$, together with a quadratic form $Q$ of maximal Witt index, for which the associated alternating bilinear form is non-degenerate, $V=\{x \mid x \in W, Q(x)=1\}$, and $x \sim y$ if $x \neq y$ and $\phi_{1}(x, y)=0$.

$$
(|v|, K, e)=\left(2^{\mathbb{W}-1}\left(2^{\mathrm{m}}-1\right), 2^{\mathbb{T}-1}, 2^{\mathrm{W}-2}\right)
$$

3. V consists of all triples from a 7-set.

$$
\begin{aligned}
& \text { (i) } x \sim y \quad \text { if } \quad|x \cap y|=1 ;(35,7,3) \text {; } \\
& \text { (ii) } x \sim y \quad \text { if }|x \cap y| \neq 1 ;(35,5,2),
\end{aligned}
$$

Note that case (i) is the same as $Q$ (ii) with $\mathbb{I}=6, q=2$.
4. Let $W$ be a 6-dimensional vector space over GF(3) together with a non-degenerate symmetric bilinear form $\phi$, such that $W$ admits an orthonormal basis. $V=\{\langle a\rangle \mid a \in W, \phi(a, a)=1\}$ and $\langle a\rangle \sim\langle b\rangle$ if $\langle a\rangle \neq\langle b\rangle$ and $\phi(a, b)=0 ; \quad(126,6,2)$.
5. The strongly regular graph of McLaughlin (cf. [GS]); (275, 5, 2).
6. Let $W$ be a 2 m-dimensional vector space over $G F(q)$, together with a quadratic form $Q$ of maximal Witt inder. $V=W$, and $x \sim y$ if $Q(x-y)=0$ and $y \neq x ; \quad\left(q^{2 m}, q^{m}, q^{m-1}\right)$.
7. $\overline{L_{2}(n)}$. Points are all ordered pairs from an $n$-set, and $(a, b) \sim(c, d)$ if $a \neq c$ and $b \neq d$; $\left(n^{2}, n, n-2\right)$.
8. $\overline{T(2 n)} . \quad V=a l l$ pairs from a $2 n-s e t, x \sim y$ if $x \cap y=\emptyset$; ( $n(2 n-1), n, n-2)$.
58.4. Regularity properties of Zara-graphs.

All examples given in the previous section are strongly regular graphs. As a consequence of the results in the present section we will see that a reduced cc-Zara-graph, i.e., $\{x\}=[x]$ for each point, is strongly regular. In the following $G$ will always denote a Zara-graph.

LEMMA 8.4.1. Let C be a maximal clique in G and $\mathrm{P} \nmid \mathrm{C}$. There is a wique maximal clique containing $\mathbf{p}$ and e points of C .

PROOF. The statement is equivalent to : two distinct maximal cliques intersect in at most $e$ points; this is a direct consequence of property (ii), defining $e$.

LEMMA 8.4.2. Let $C, C_{1}$ and $C_{2}$ be different maximal cliques in G such that $\mathrm{C}_{1}$ and $\mathrm{C}_{2}$ intersect C in e points. Then $\mathrm{C}_{1} \cap \mathrm{C}_{2} \subset \mathrm{C}$.

PROOF. If $\mathrm{C}_{1} \cap \mathrm{C}_{2} \notin \mathrm{C}$, then $\left|\left(\mathrm{C}_{1} \mathrm{uC}_{2}\right) \cap \mathrm{C}\right|>e$ and there is a point $x \in C_{1} \mathrm{nC}_{2} \backslash \mathrm{C}$. This point is joined to more then e points of C , contradiction.

As a consequence of lemmas 8.4.1 and 2 we can start with any maximal clique $C$, take for each point outside $C$ the unique clique through this point and $e$ points of $C$. This way we obtain a collection of cliques $\mathrm{C}_{1}, \ldots, \mathrm{c}_{\mathrm{s}}$ inducing a partition of ViAC. This collection is called the c-decomposition.

THEOREM 8.4.3. Let $\mathrm{x}, \mathrm{y} \in \mathrm{V}(\mathrm{G})$. If $\mathrm{x} \neq \mathrm{y}$ then $\mathrm{d}(\mathrm{x})=\mathrm{d}(\mathrm{y})$.

PROOF. Let $C$ be a maximal clique containing $x$. Then $y \not C C$. Consider the C -decomposition $\left\{\mathrm{C}_{1}, \ldots, \mathrm{C}_{\mathrm{s}}\right\}$ with $\mathrm{y} \in \mathrm{C}_{1}$ and put $C \backslash C_{1}=\left\{x=x_{1}, x_{2}, \ldots, x_{k-e}\right\}$. For each $z \in C_{1} \backslash C$ we have

$$
d(z)=\sum_{i=2}^{s}\left(e-\left|C_{1} n C_{i}\right|\right)+K-1
$$

Inded, the number of points in $C_{i} \backslash C_{1}$ adjacent to $z$ is $e-\left|C_{1} \cap C_{i}\right|$,
and since $C_{1} n C_{i} \subset C$, all these points are outside $C$, hence no points are counted twice. Rewriting this yields

$$
d(z)=\sum_{i=2}^{s}\left\{\sum_{\operatorname{mix} x_{m} \in C_{i}} 1\right\}+K-1
$$

since $\underset{\min x_{m} \in C_{i}}{ } 1=e-\left|C_{1} n C_{i}\right|$. Changing the order of summation yields:

$$
\left.d(z)=\sum_{m=1}^{K-e}\left(d\left(x_{m}\right)-(K-1)\right) /(K-e)\right\}+K-1=\frac{1}{K-e} \sum_{m=1}^{K-e} d\left(x_{m}\right) .
$$

Hence $d\left(z_{i}\right)=d\left(z_{j}\right)$ for all $z_{i}, z_{j} \in C_{1} \backslash C$, and by symmetry $d\left(x_{i}\right)=d\left(x_{j}\right)$ for all $x_{i}, x_{j} \in C \backslash C_{j}$. This implies $d(y)=d(x)$.

COROLLARY 8.4.4. A ce-Zara-graph is regular.

THEOREM 8.4.5. Let $G$ be a co-Zara-groph. There axists a constant $\mu$, such that $\mu(x, y)=\mu$ for all $x, y \in V(G), \quad x \neq y$.

PROOF. We will show that $\mu\left(x, y_{1}\right)=\mu\left(x, y_{2}\right)$ for each triple $x, y_{1}, y_{2}$ with $x \neq y_{1}$ and $x \neq y_{2}$. First assume $y_{1} \sim y_{2}$. Take a clique $C_{1}$ containing $y_{1}$ and $y_{2}$ and a clique $C$ with $x \in C$ and $\left|C \cap C_{1}\right|=e$. Consider the $C$-decomposition $\left\{C_{1}, C_{2}, \ldots, C_{s}\right\}$. For $i=1,2$ :

$$
\mu\left(x, y_{i}\right)=\sum_{k: x \in C_{k}}\left(e-\left|C_{1} \cap C_{k}\right|\right)+e,
$$

independent of $i$. Hence $\mu\left(x, y_{1}\right)=\mu\left(x, y_{2}\right)$.
Next let $y_{1} \neq y_{2}$. Claim: there either exists a point $z$ with $z \neq x$, and $z \sim y_{1}, y_{2}$ or for all $z \sim x$, we have $y_{1} \sim z<i \sim y_{2} \sim z$. To see this suppose $z \sim x, z \sim y_{1}$ and $z \neq y_{2}$ and let $C$ be a clique containing $y_{1}$ and $z$. Then $x^{\perp} \cap C$ and $y_{2}^{\perp} n C$ are different sets of the same cardinality e. Hence there is a point $z^{\prime} \in y_{2}^{\perp} n C$ not adjacent to $x$. This proves the claim. In the first case $\mu\left(x, y_{1}\right)=\mu(x, z)=\mu\left(x, y_{2}\right)$. In the second case $x^{\perp} n y_{1}^{\perp}=x^{\perp} n y_{2}^{\perp}$, hence also $\mu\left(x, y_{1}\right)=\mu\left(x, y_{2}\right)$. Since $G$ is coconnected,
is constant for the whole graph.

THEOREM 8.4.6. Let $G$ be a ce-2ara-graph. There exists a constant $\lambda$ such that $\lambda(x, y)=\lambda$ for $x, y \in V(G), x \sim y$ and $x \neq y$.

PROOF. First recall lemma 7.2.4.: let the edges of the complete graph $X=K_{n}$ be colored with $k$ colors such that (i) for each color $c$, the induced graph on this color, $X_{c}$, is connected; (ii) in each triangle at most two colors are used. Then $k$ is at most 2.
Now let $\mathbf{H}=\mathrm{G} / \approx$ be the reduced graph of G . Note that H is also coconnected. We are going to color the edges and non-edges of $H$. All non-edges get the same color $\infty$, while if $[x] \sim[y]$ the edge ( $[x],[y]$ ) gets the color $\lambda(x, y)$, i.e., the number of common neighbors of $x$ and $y$ in . This coloring satisfies the hypotheses (ii) and (i) of lemm 7.2.4.: (ii) : Triangles with less than two edges satisfy the requirements automatically. Next consider $[y] \sim[x] \sim[z],[y] \notin[z]$ in $H$. In $G$ we have $\mathrm{y} \sim \mathrm{x} \sim \mathrm{z}, \mathrm{y} \nmid \mathrm{z}$. Since $\operatorname{Res}(\mathrm{x})$ is a Zara-graph, theorem 8.4.3. tells us that $d_{\operatorname{Res}(x)}(y)=d_{\operatorname{Res}(x)}(z)$. This just means $\lambda(x, y)=\lambda(x, z)$. Hence triangles with two edges also satisfy (ii). Finally let $[x] \sim[y] \sim[z] \sim[x]$ in $H$, or $x, y, z$ mutually adjacent and non-equivalent in $G$. If there is a point $u$ in $G$ adjacent to precisely one of $x, y, z$, say to $x$, then by the previous reasoning $\lambda(u, x)=\lambda(y, x)$ and $\lambda(u, x)=\lambda(z, x)$ and we are done. If not, then, writing $\lambda(x, y, z)$ for the number of common neighbors of $x, y$ and $z$ in $G$ :

$$
\begin{aligned}
& d(x)=\lambda(x, y)+\lambda(x, z)-\lambda(x, y, z) ; \\
& d(y)=\lambda(y, z)+\lambda(y, x)-\lambda(x, y, z) ; \\
& d(z)=\lambda(z, x)+\lambda(z, y)-\lambda(x, y, z) .
\end{aligned}
$$

Since $G$ is coconnected it is regular and therefore $\lambda(x, y)=\lambda(y, z)=\lambda(z, x)$ in this case. This shows that for each triangle (ii) holds.
(i): Let $H_{c}$ be a connected component for the color $\left.c,\left|H_{c}\right|\right\rangle 1$, and suppose $H_{c}$ has not all of the vertices of $H$. A point outside $H_{c}$ is joined to all points of $H_{c}$ with edges (or non-edges) of the same color, by the isosceles property and the fact that $H_{c}$ is connected and a component. In particular a point outside $H_{c}$ is either adjacent to all
points of $H_{c}$, or to no point of $H_{c}$. Let $A$ be the set of points that are adjacent to all points of $H_{c}$ and $N$ the set of points adjacent to none. Note that $N$ is certainly non-empty, since $H$ is coconnected. In case $A$ is empty $H$ is not connected and also $G$ is not connected, i.e., $e=0$. In this case $x \sim y$ implies $x \approx y$ and the theorem is void. So let $A \neq \emptyset$. Now $H_{c}$ is not a clique, since in that case $[x]$ and [ $y$ ] in $H_{c}$ would have the same neighbors, i.e., $x \approx y$. Take $[h] \epsilon H_{c}$, $[a] \in A$ and construct a maximal clique $C$ in $G$ containing [a] and [h]. Let $A^{\prime}$ be the "preimage" of $A$ in $G$, similarly define $H_{c}^{\prime}$ and N'. Any point $n \in \mathbb{N}^{\prime}$ has $e$ neighbors in $A^{\prime} n C$, hence $\left|A^{\prime} n C\right| \geq e$. There is a point $h^{\prime} \in H^{\prime} \backslash C$ having a neighbor in $H_{c}^{\prime} C C$, since $H_{c}^{\prime}$ is connected and not a clique. But this point is also adjacent to all points of $A^{\prime}$, therefore it has more than $e$ neighbors in $C$, contradiction. So $H_{c}=H$, i.e., the induced graph on $c$ is connected. This shows (i) and the theorem is proved, because since there are at most two colors, one of them $\infty$, the other one must be the constant $\lambda$.

COROLLARY 8.4.7. Let $G$ be a reduced ce-Zara-graph, i.e., $G=G / \approx$. Then $G$ is strongly regular.
58.5. The poset of singular subsets.

In this section we study the partially ordered set of closed cliques. Crucial steps in the investigation that allow us to study the structure by induction are:
(i) If $G$ is a cc-Zara-graph and $x \in V(G)$ then $\operatorname{Res}([x])$ is again a ce-Zara-graph.
(ii) All equivalence classes of points have the same size.

We start off with two simple lemmas. Throughout this section $G$ will be a Zara-graph.

LEMMA 8.5.1. If $\mathbf{u}$ and $\mathbf{v}$ are connected by a path in $\overline{\mathbf{G}}$, then the distance of $u$ and $v$ in $\bar{G}, d_{\bar{G}}^{(u, v)}$ is at most 2 .

PROOF. The points $u$ and $v$ are in the same coconnected component
of G . But coconnected components of a Zara-graph are cc-Zara-graphs.

LEMMA 8.5.2. Let $\mathrm{x}, \mathrm{y}, \mathrm{z} \in \mathrm{V}(\mathrm{G})$, where G is a cc-Zara-graph. Suppose Res([x]) is not coconnected, and $\mathbf{y , z}$ are in different cc-components of Res ([x]). Then Res([y]) is not coconnected, and $x, z$ are in different ce-components of Res ([y]).

PROOF. We show that the following statements are equivalent:
(i) $\operatorname{Res}([x])$ is not coconnected and $y, z$ are in different cc-components.
(ii) There is no point $u$ adjacent to $x$ and not to $y, z$.
(iii) There is no point $v$ adjacent to $y$ and not to $x, z$.
(iv) Res([y]) is not coconnected and $x, z$ are in different cc-components.
(i) $=>$ (ii) : By definition. (ii) $=>$ (i): Lemma 8.5.1..
(ii)<=>(iii): $x, y$ and $z$ are mutually adjacent and non-equivalent. Let $\lambda_{1}(x)$ be the number of points adjacent to $x$ and not to $y, z$. Then

$$
\begin{aligned}
& d(x)=\lambda_{1}(x)+\lambda(x, y)+\lambda(x, z)-\lambda(x, y, z)= \\
& =\lambda_{1}(x)+2 \lambda-\lambda(x, y, z) . \\
& d(y)=\lambda_{1}(y)+2 \lambda-\lambda(x, y, z),
\end{aligned}
$$

where again $(x, y, z)$ is the number of common neighbors of $x, y$ and $z$. This shows that $\lambda_{1}(x)=\lambda_{1}(y)$.
(iii) $\Leftrightarrow$ (iv): This is the same as (i) $\Leftrightarrow>(i i)$.

Triples $x, y, z$ as in the lemma will be called trios. Note that the lemma says that the order of $x, y, z$ is irrelevant.

THEOREM 8.5.3. If $G$ is a cc-Zara-graph, $\mathbf{x} \in \mathrm{V}(\mathrm{G})$, then Res ([x]) is a cc-Zara-graph.

PROOF. It is enough to show that trios do not exist. Let $\{x, y, z\}$ be a trio, then no point of $G$ is adjacent to exactly one point of $\{x, y, z\}$. Let $A_{x}=\{u \in V(G) \mid u \notin x, u \sim y, u \sim z\}, A_{y}$ and $A_{z}$ similar; $C=\{u \mid u \sim x, y, z\} ; N=\{u \mid u \nmid x, y, z\}$. Picture:


Observe: (i) $N \neq \emptyset$ (lemma 8.5.1.) .
(ii) There are no edges between $N$ and $A_{x}, A_{y}$ and $A_{z}$. This is shown as follows: If $x^{\prime} \in A_{x}$, then $x^{\prime}, y, z \quad$ is again a trio, for $x^{\prime}$ and $x$ are in the same cc-component of $\operatorname{Res}([y])$ and therefore $x^{\top}$ and $z$ in different co-components. Since the points of $N$ are not adjacent to $y$ and $z$, they are also not adjacent to $x^{\prime}$. The proof is finished by deriving a contradiction. Let $x^{\prime} \in A_{x}$. Since $x^{\prime}$ and $x$ have $\mu$ common neighbors, $x^{\prime}$ has less than $\mu$ neighbors in $C$ (at most $\mu-2$ ). On the other hand $n \in N$ and $x^{\prime}$ must have $\mu$ common neighbors in $C$. This is a contradiction, hence trios do not exist and the proof is finished.

In order to investigate the pose of closed cliques we need the following characterization of singular subsets. Here $C$ denotes the set of all maximal cliques in $G$.

LEMMA 8.5.4. Let S be a clique in G , then

$$
s^{1 \perp}=n\{C \in C \mid S \in C\}
$$

PROOF. $\quad S^{\perp \perp}=n\left\{y^{\perp} \mid S \subset y^{\perp}\right\}=\prod_{\substack{C \in C \\ S \in y^{\perp}}}\left\{y^{\perp} \mid y \in C\right\}=$

$$
=n\left\{C^{\perp} \mid S \in C \in C\right\}=n\{C \in C \mid S \subset C\},
$$

since $C^{\perp}=C$ for all $C \in \mathcal{C}$.

Notation: $(S, c)$ is the poses of singular subsets, for $C \in C$ define

$$
S(C)=\{S \in S \mid S \in C\}
$$

Let $X, Y$ be different elements from a lattice ( $L, C$ ). If $X \subset Y \subset Z$ implies $X=Z$ or $Y=Z$ we say that $Y$ covers $X$ and write $X<Y$. $A$ lattice is semi-modular if for all $X, Y:(X>X \wedge Y) \Leftrightarrow(X \vee Y>Y)$. The following two lemmes enable us to show that $(S(C), C)$ is a semimodular lattice for all $C \in \mathcal{C}$.

LEMMA 8.5.5. The groph defined on $C$ by $C \sim D$ if $|C \cap D|=e$ is connected.

PROOF. Ne show that two maximal cliques $C$ and $D$ are joined by a path using induction on $|\mathrm{C} \cap \mathrm{D}|$.
(i) If $|C \cap D|=e$ then $C \sim D$ and there is nothing to prove.
(ii) If $|C \cap D|<e$ take $x \in C \backslash D$ and a clique $E$ containing $x$ and $e$ points of $D$, then $|E \cap D|=e$ and $|C \cap E|>|C \cap D|$, hence $C$ and $E$ are joined by a path. Since $E \sim D$ we are done.

LEMMA 8.5.6. Let $S \in S, C \in C, S \in C$. Then there exists $a$ $D \in C$ such that $S=C \cap D$.

PROOF. By induction on the size of $S$.
(i) $|S|=e$. This case is trivial.
(ii) $|S|<e$ Choose closed cliques $S_{1}$ and $S_{2}$ minimal with respect to $S \subset S_{i} \subset C$. This is possible since $S=0\{T \in S \mid T \supset S\}$. Since $S_{1}$ and $S_{2}$ are minimal, $S_{1} \cap S_{2}=S$ and there are maximal cliques $D_{1}$ and $D_{2}$ such that $S_{i}=C \cap D_{i}, i=1,2$. Choose $x \in D_{2} \backslash\left(C \cup D_{1}\right)$ such that $x$ is not adjacent to all of $S_{1} \backslash S$ (and hence to none of $\left.S_{1} \backslash S\right)$. Let $D_{3}$ be the closure of $\left(x^{\perp} \cap C_{1}\right) u\{x\}$. Then $D_{3} \cap C=S$. To see this, suppose $y \in\left(D_{3} n C\right) \backslash S$. Then either $y \in S_{1}$, which implies $y \sim x$, or $y<S_{1}$, but then $\left|y^{1}{ }_{n D_{1}}\right|>e$, contradiction.

We define the binary operations $\wedge$ and $\vee$ on $S$ as follows:

$$
S \wedge T=S \cap T ; S \dot{V} T=\cap\{U \in S \mid U \supset S U T\}
$$

$S \cap T$ is again a singular subset since $(S \cap T)^{\perp \perp}=S^{\perp \perp} \cap T^{\perp \perp}$ (cf 8.6).

THEOREM 8.5.7. Let G be a ce-Zara-graph, and C a maximal clique in G . Then ( $\mathrm{S}(\mathrm{C}), \mathrm{c}$ ) is a semi-modular Lattice.
 Then $Z_{n} X=Y_{n} X$, for otherwise $\underset{\neq}{X_{n} Y} \underset{\neq}{c} X_{n} Z \underset{\neq}{c} X$. Take a point $z \in Z \backslash Y$ and $x \in X \backslash Y$. Apparently $X^{\perp} \subset z^{\perp}$ in the Zara-graph Res (Y). To see this let $u$ be adjacent to $X$ and $Y$. Since $X$ covers $X \cap Y$, $u$ is joined to all of $X$, and if is $u$ is joined to $X$ and $Y$ it is joined to all of $X V Y$, including $z$. By repeated application of theorem 8.5.3. Res (Y) is a cc-Zara-graph, hence $\mathrm{x}^{\perp}=\mathrm{z}^{\perp}$ in Res (Y). This is a contradiction since $z \in Z$ while $x \notin Z$.

The semi-modularity of the lattice $S(C)$ allows us to introduce a rank fuction on $S(C)$ satisfying $r k(S)=r k(T)+1$ whenever $S<T$, and $\mathrm{rk}(\boldsymbol{\eta})=0$, cf. [Bi] . By lenma 8.5.5. this rank function can be extended to the poset $S$. Indeed, for a given set $E$ of cardinality $e$ in $S$, the rank in $S(C)$ is the same for all $C \supset E$. All maximal cliques have the same rank $r$. This $r$ is called the rank of the Zaragraph.
58.6. Zara-graphs and $M_{r}$-spaces,

In this section the main structure theorem for ce-Zara-graphs is proved. We show that the poset of singular subsets of the reduced graph of a rank $r$ Zara-graph is an $M_{r}$-space (for the definition see 58.2 .). Write $S=S_{0} \cup S_{1} \cup \ldots \cup S_{r}$. Recall that $S_{i}$ is the collection of singular subsets of rank $i$. We shall prove the following properties:
(i) There are constants $R_{0}, \ldots, R_{r}$ such that each rank $i$ singular subset is in $R_{i}$ maximal cliques.
(ii) There are constants $K_{0}, \ldots, K_{r}$ such that each rank $i$ singular subset has $K_{i}$ points.
(iii) The intersection of two singular subsets is again a singular subset.
(iv) If $x$ is a rank $i$ singular subset, and $C$ : a maximal clique containing $x$ and $p \in C \backslash x$, then there is a $r k(i+1)$ singular subset $y$,
containing $x$ and $p$, and contained in $C$.
Note that it follows from (ii) that all equivalence classes have the same size $K_{0}$, and that (i),..., (iv) imply that $G / \approx$ is an $M_{r}$-space.

Property (iv) is a consequence of the semi-modularity of the lattice $S(C)$ for each $C \in \mathcal{C}$. Property (iii) follows from the observation that $(S \cap T)^{\perp \perp}=S^{\perp \perp} \cap T^{\perp \perp}$, if $S$ and $T$ are singular subsets. Indeed, for arbitary sets $A$ and $B$ we have $(A \subset B) \Rightarrow B^{\perp} \subset A^{\perp}$, and if $A$ is a clique then $A \subset A^{\perp \perp}$. Hence $\left(S \cap T \in(S \cap T)^{\perp \perp}\right.$ and $(S \cap T)^{\perp \perp} \subset S^{\perp \perp} \cap T^{\perp \perp}$. The following theorems establish (i) and (ii).

THBOREM 8.6.1. Let $G$ be a ac-Zara-graph. There are constants $R_{0}, \ldots R_{r}$, such that each $S \in S_{i}$ is contained in precisely $R_{i}$ maximal cliques.

PROOF. By induction in $i$. For $i=0$ there is nothing to prove. Rank 1 sets are the equivalence classes of points. Let $[x]$ and $[y] \in S_{1}$, $x \neq y$. For each maximal clique $C$ containing $x$, and hence [ $x$ ], there is a unique clique containing $y$ and intersecting $C$ in $e$ points. This establishes a one to one correspondence between the cliques containing [x] and those containing $[y]$. Since $G$ is coconnected we are done. Finally let $i>1, S, T \in S_{i}$. If $S \cap T \neq \emptyset$ then we may use the induction hypothesis since Res (SnT) is again a cc-Zara-graph. Hence in this case $S$ and $T$ are in the same number of maximal cliques. However, the graph defined on $S_{i}$ by $S \sim T$ if $S \cap T \neq \emptyset$ is connected if $i>1$, since every edge of $G$ is in a rank $i$ set, and $G$ is connected if the rank of $G$ as a Zara-graph is greater than 1. So for all $S, T \in S_{i}$ the number of maximal cliques containing them is constant,

THEOREM 8.6.2. Let $G$ be a co-Zara-graph of rank $\mathbf{r}$. There are constants $K_{0}, \ldots, K_{r}, ~ s u c h ~ t h a t ~ e a c h ~ S \in S_{i}$ has $K_{i}$ points.

In order to prove this we need the following lemma.

LEMMA 8.6.3. Let $G$ be a ca-Zara-graph of rank $r$, and suppose $|\mathrm{s}|=\mathrm{K}_{\mathbf{i}}$ for all $\mathrm{s} \in \mathrm{S}_{\mathbf{i}}, \mathbf{i}=0, \ldots, \mathbf{r}$. Then the number of rank $\mathbf{i}$ sets in a given maximal citique C equals


PROOF of the lemma. We use induction on $r$, the case $r=1$ being trivial, using the convention that the empty product equals 1 . Now let $r>1$, and $C$ a maximal clique containing $c_{i}$ rank $i$ sets. Since $C$ is partitioned into rank 1 sets $c_{1}=K_{r} / K_{1}$. Next let $i>1$. Counting in two ways the pairs $S, T \subset C, S \in S_{1}, T \in S_{i}$ satisfying $S \subset T$ and using the induction hypothesis yields

$$
\frac{K_{r}}{K_{1}} \prod_{j=1}^{i-1} \frac{\left(K_{r}-K_{1}\right)-\left(K_{j}-K_{1}\right)}{\left(K_{i}-K_{1}\right)-\left(K_{j}-K_{1}\right)}=c_{i} \frac{K_{i}}{K_{1}}
$$

This proves lemma 8.6.3. .

PROOF of the theorem. Again we use induction on $r$. If $r=1$ or 2 the statement is true by definition. Let $r>2$, and take $S \in S_{1}$ with $|S|=s$. By induction $\operatorname{Res}(S)$ has parameters $K_{r-1}^{1}, \ldots, R_{0}^{1}=0$. So each rank $i$ set containing $S$ has cardinality $K_{i-1}^{1}+s$. We allready noticed that the graph defined on $S_{i}$ by $S \sim T$ if $S \cap T \neq \emptyset$ is connected. Hence there allready exist constants $K_{2}, K_{3}, \ldots, K_{r}$. Count the number of points inside and outside a given maximal clique $C$, observing that $G$ is regular, say of degree $k$. Hence, using the lemma:

$$
k-s+1=|\operatorname{Res}(S)|=K_{r-1}^{1}+\prod_{j=0}^{r-3} \frac{K_{r-1}^{1}-K_{j}^{1}}{K_{r-2}^{1}-K_{j}^{1}}\left(R_{r-1}^{-1}\right)\left(K_{r-1}^{1}-K_{r-2}^{1}\right)
$$

To explain this note that each point in $\operatorname{Res}(S)$ outside $C$ determines a unique clique intersecting $C$ in $e$ points, while each e-set in $S_{r-1}$ is in $R_{\left.r^{-}\right]}$maximal cliques. For $i>1$ we may put $k_{i-1}^{l}=K_{i}-s$, whence

$$
k-s+1=K_{r}-s+\frac{K_{r}-s}{K_{r-1}^{-s}} \prod_{j=1}^{r-3} \frac{K_{r}-K_{j+1}}{K_{r-1}-K_{j+1}}\left(R_{r-1}-1\right)\left(K_{r}-K_{r-1}\right)
$$

Considered as an equation in $s$ we see that there is only one solution. Indeed, rewrite the equation to get

$$
k+1-K_{r}=\left(1+\frac{K_{r}-K_{r-1}}{K_{r-1}}\right){\underset{j=1}{r-3}}_{M_{r=1}}^{K_{r-1}-K_{j+1}} K_{j+1} \quad\left(R_{r-1}-1\right)\left(K_{r}-K_{r-1}\right),
$$

and notice that $\left(\mathrm{K}_{\mathrm{r}}-\mathrm{K}_{\mathrm{r}-1}\right) /\left(\mathrm{K}_{\mathrm{r}-1}-\mathrm{s}\right)$ is monotonic. Hence s is constant i.e., $K_{1}=s$. This finishes the proof of the theorem.

MAIN THEOREM 8.6.4. Let $G$ be a co-Zara-graph of rank $r$, then $\mathrm{G}^{\prime}$, the reduced graph of G is also a cc-2ara-graph, and the poset of closed cliques of $\mathrm{G}^{\prime}$ is an $M_{r}$-space.

## §8.7. Final remarks.

In the previous section it was proved that the reduced graph of a cc-Zara-graph is strongly regular. The parameters of this strongly regular graph can be computed in terms of K , e , and the smallest eigenvalue (cf. [N4]). The integrality of the multiplicity of the eigenvalues puts further restrictions on the feasibility of parameter sets. Another related subject is the classification of completely regular two-graphs (cf. [N5]). To each completely regular two-graph there is related at least one Zaragraph. More about these aspects will appear in a forthcoming article by Wilbrink, Kloks and the author. The list in 58.3. contains all examples known to the authors of reduced cc-Zara-graphs. More about $M_{r}$-spaces can be found in $[\mathrm{N} 1,3]$. Neumaier gives a.o. the following examples:
(i) All $\leq r$ subsets of an $n$-set.
(ii) All $\leq r$ dimensional subspaces of a projective space $\operatorname{PG}(n, q)$.
(iii) All subspaces of a polar space over GF(q).

The graph associated with these structures is the complete graph in (i) and (ii). Only in case (iii) we have a "proper" Zara-graph. The structure of all varieties in a fixed block of an $M_{r}$-space, or the lattice (S (C), c) in case of a Zara-graph is a perfect matroid design [We]. Our closure operator ${ }^{11}$ coincides with the usual closure operator for matroids. The singular subsets are called subspaces or flats in this terminology.

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## LIST OF SYMBOLS

| $\mathrm{A}_{\mathrm{k}}$ | 37 | I | 37 | S | 6 | ${ }^{\mu}{ }_{i}$ | 38 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $a_{i j}^{k}$ | 36 | $\mathrm{I}_{\mathbf{s}, \mathrm{t}}$ | 17 | S | 6 |  | 16 |
|  |  | J | 37 | S | 40 | $\mu(x, y)$ | 52 |
| aff (X) | 46 | $J(\mathrm{l}, \mathrm{k})$ | 37 |  | 17 |  | 16 |
| Aut (V) | 6 | $J(n, k)$ | 37 | P,q |  | k |  |
| B( , ) | 8 | $\mathrm{K}_{\mathrm{i}} \quad 52$ |  | $\overline{T(2 n)}$ | 54 | $\sigma(\mathrm{j})$ | 27 |
| B(, ) |  |  |  | V | 6 | $\sigma_{u}(\mathrm{j})$ | 27 |
| $b_{i j}^{k}$ | 38 | (K,e) | 51 | v | 8 | $\phi(t)$ | 17 |
| d(x) | 52 | $\overline{L_{2}(\mathrm{n})}$ | 54 | $\mathrm{v}_{\mathrm{k}}$ | 36 | $\omega$ | 39 |
| $d($, | 26 | $\mathrm{Mr}_{\mathrm{r}}$-space | 52 | $v$ (m) | 33 |  |  |
| dim( X$)$ | 46 |  |  |  |  | 4-(23,7 |  |
|  |  | P | 38 | [x] | 51 |  | 24 |
| $\mathrm{E}_{8}$ | 19 | [p,a] | 27 |  |  | $\sim$ | 51 |
| $\mathrm{E}_{\mathbf{k}}$ | 38 | $\operatorname{Pol}(\mathrm{s}, \mathrm{d})$ | 1 | ZM | 33 | 1 | 51 |
| $E^{\text {d }}$ | 26 | Q | 38 | B | 10 | 11 | 51 |
|  |  | $\mathrm{q}_{1}$ | 40 |  |  | v | 61 |
| H | 12 |  | 17 | b | 27 | $\wedge$ | 61 |
| $\mathrm{H}^{\text {d }}$ | 26 | ${ }_{k}$ |  |  | 10 | <1> | 7 |
| $\mathrm{H}(\mathrm{n}, 2)$ | 37 | QM | 33 | $\partial_{s}$ | :7 | < > | 9 |
| H(t) | 41 | $\mathrm{R}^{\mathrm{p}, \mathrm{q}}$ | 1 | $\partial$ | 7 | $s$ | 62 |
| harm(i) | 41 | $\mathrm{R}_{\mathbf{i}} \quad 52$ |  | $\partial_{\beta}$ | 11 | $S_{k}$ | 62 |
| harm(k) | 6 | $\operatorname{Rad}(\mathrm{G})$ | 52 | $\lambda(x, y)$ | 52 | $S$ (C) | 62 |
| $\mathrm{harm}_{B}(\mathrm{k})$ | 11 | $\operatorname{Res}(\mathrm{x})$ | 51 | $\lambda(x, y$, |  |  |  |
| hom( $\mathrm{d}, \mathrm{k}$ ) | 7 | Res (S) | 51 |  | 39 |  |  |

## SAMENVATTING

Het voornaamste onderwerp van dit proefschrift is het bepalen van grenzen voor de cardinaliteit van puntverzamelingen met weinig afstanden. Voor puntverzamelingen op de eenheidsbol in de Euclidische ruimte ${ }^{\mathbf{d}}$, werden reeds scherpe grenzen afgeleid in [DGS]. Koornwinder gaf later een simpeler bewijs voor een apart geval hiervan, namelijk verzamelingen van gelijkhoekige rechten in $E^{d}$.

In hoofdstuk 2 wordt de theorie ontwikkeld, die het mogelijk maakt om de methoden uit [DGS] toe te passen op puntverzamelingen op de "eenheidsbol" in inprodukt ruimten met een willekeurige signatuur. Vooral het geval van de hyperbolische ruimte $\mathbb{R}^{\text {d,l }}$, levert scherpe grenzen op.

Een verscherping van de methode van Koornwinder stelt ons in staat de grenzen voor s-afstands-verzamelingen in $E^{d}$ en $H^{d}$, d-dimensionale hyperbolische ruimte, te verbeteren. Ook worden op die manier scherpe grenzen voor verzamelingen van gelijkhoekige rechten in $\mathrm{R}^{\mathrm{d}, 1}$ verkregen.

Nemen de afstanden alleen mar bepaalde gehele waarden modulo een priemgetal aan, dan kunnen opnieuw scherpere grenzen worden bereikt. De metrische ruimten warin dit het meest tot zijn recht komt zijn de zogenaamde Delsarte ruimten. Als corollarium treedt een stelling van Franki en Wilson op.

Hierna wordt een probleem van Erdös opgelost, nauw verwant met 2-afstands-verzamelingen, namelijk: wat is het maximaal aantal punten in $E^{d}$, zodanig dat elke driehoek, die door drie punten uit de verzameling wordt bepaald, gelijkbenig is. Een essentieel lemma uit dit hoofdstuk vormt de verbinding met het laatste onderwerp. Welke grafen voldoen aan de volgende eigenschappen: 1. Er is een $K$ zodanig dat elke maximale kliek omvang $K$ heeft; 2. Er is een $e$ zodanig dat voor elke maximale kliek $C$ en punt $p$ niet in $C$, het punt $p$ precies $e$ buren in heeft. Deze grafen werden geintroduceerd door Zara [Z] in een poging polaire ruimten te karakteriseren. We laten zien dat Zara-grafen die aan enkele noodzakelijke eigenschappen voldoen sterk regulier zijn en verdere regelmatigheidseigenschappen hebben.

## CURRICULUM VITAE

De schrijuer van dit proefschrift werd geboren op 6 juli 1956 in Alkmaar. Hij beëindigde de gymasium $\beta$ opleiding aan het Johannes College in Den Helder in 1974. Daarna studeerde hij wiskunde met bijvak Econometrie aan de Vrije Universiteit in Amsterdam, waar hij in 1979 het doctoraal examen aflegde. Tijdens zijn studie was hij gedurende een half jaar student assistent.

Van oktober 1979 tot oktober 1983 was hij wetenschappelijk assistent bij de onderafdeling der wiskunde en informatica van de Technische Hogeschool Eindhoven.

## STELLINGEN

1. Er bestaat geen Zara-graaf met 95 punten, $K=5$ en $e=2$. Er bestaan geen Zara-grafen met $K / 2<e<K-2$. De enige cc-Zaragrafen met $K=e+2 \operatorname{zijn} \overline{L(n)}$ en $\overline{T(2 n)}$, met $n \geq 3$.
A. Blokhuis, T. Kloks, H. Wilbrink; A class of graphs containing the polar spaces, to appear'.
2. Er bestaan geen niet-triviale compleet reguliere "two-graphs" op 96 of op 640 punten.
3. Zij $\sigma(n, k)$ het antal formulieren dat ingevuld moet worden bij een toto met $n$ wedstrijden en $k$ mogelijke uitslagen per wedstrijd, on zeker een prijs te winnen voor alle of op één na alle goede uitslagen. Dan geldt, met $q$ is priem en $k=1+t\left(q^{r-1}-1\right) /(q-1)$ :
(i) $\sigma(k, q) \leq(q-t+1) q^{k-r}$;
(ii) $\sigma(n, m t) \leq \sigma(n, m) t^{m-1}$;
(iii) $\sigma(q+1, q t)=q^{q-1} t^{q} \quad$;
(iv) $\sigma\left(n p^{+1}, p\right) \leq \sigma(n, p) p^{n p-n}$;
(v) $\sigma(7,3) \leq 216, \sigma(10,3) \leq 5.3^{6}, \sigma(16,5) \leq 13.5^{12}$.
A. Blokhuis, C. Lam; More coverings by rook domains. To appear in the J. of Comb. Theory A.
4. Het is niet mogelijk een eindig aantal even lange lucifers zodanig neer te leggen in het vlak dat twee lucifers nooit over elkaar heen liggen en in elk eindpunt vijf lucifers bij elkaar komen.
5. De volgende formule van $N$ : Bebiano voor de permanent:

$$
\exp (\underline{x}, A y) t=\sum_{k=0} t^{k} \underset{|\underline{k}|=|\underline{1}|=k}{\sum} \frac{\underline{x}-\underline{y}^{k}}{\underline{k}: \underline{1}:} \text { per } A(\underline{1}, \underline{k})
$$

is eenvoudig met multilineaire algebra te bewijzen. Hier zijn $x, y \in R^{d}$, $\underline{k}=\left(k_{1}, \ldots, k_{d}\right), \underline{k}!=k_{1}: k_{2}!\ldots k_{d}!, \underline{x^{k}}=x_{1}{ }^{k_{1}} \ldots x_{d} k_{d}$. Tenslotte is
$A(\underline{1}, \underline{k})$ de matrix die uit $A$ ontstaat door de $i$-de rij $l_{i}$ keer en de j -de kolom $\mathrm{k}_{\mathrm{j}}$ keer te herhalen. Natália Bebiano; On. the evaluation of permanents, Pacific J. Math. vol. 101 no. 1, 1982.
6. Zij $C$ een kleuring van de kanten van de volledige graaf op $n$ punten ( $n$ eindig), zodanig dat voor elke vijfhoek in $K_{n}$ geldt dat er twee opeenvolgende zijden zijn met gelijke kleur, terwijl de geĭnduceerde graaf op elke afzonderlijke kleur samenhangend is. Dan zijn er hooguit twee kleuren.
7. Als men $n$ koorden trekt in een cirkel, zodanig dat er geen drie door éēn punt binnen de cirkel gaan, en als deze koorden m snijpunten binnen de cirkel bepalen, dan wordt de cirkel in $n+m+1$ gebieden verdeeld. Met deze observatie kan men probleem 8.1 uit L. Comtet; Advanced aombinatorics, p. 74, zeer eenvoudig oplossen.
8. In tegenstelling tot de indruk die bij het middelbaar onderwijs gewekt wordt, houdt een wiskundige zich bezig met onopgeloste problemen.
9. De maximaal toegelaten rugwind bij het lopen of springen van een wereldrecord dient minder te zijn op grote hoogte dan op zeeniveau, in verband met het verschil in luchtweerstand.

