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Formality theorem and bialgebra deformations

VLADIMIR HINICH⁽¹⁾, DAN LEMBERG⁽²⁾

RÉSUMÉ. – On vérifie la formalité de l'algèbre exterieure de $V \oplus V^*$ munie du grand crochet considérée comme une algèbre de Poisson graduée. On discute la pertinence de ce resultat pour les déformations de bigèbres d'une algèbre symétrique de V considérée comme une bigèbre.

Abstract. – In this paper we prove formality of the exterior algebra on $V \oplus V^*$ endowed with the *big bracket* considered as a graded Poisson algebra. We also discuss connection of this result to bialgebra deformations of the symmetric algebra of V considered as bialgebra.

1. Introduction

1.1. In this paper k will always denote a ground field of characteristic zero. Fix a finite dimensional vector space V over k. This paper deals with the graded vector space $H = \oplus H^n$ where

$$H^{n} = \bigoplus_{p+q=n} \wedge^{p} V \otimes \wedge^{q} V^{*}, \quad n \ge 0.$$
 (1.1)

This vector space has a graded Poisson structure defined as follows. This is a (graded) commutative algebra with unit as H = S(W) where

$$W = (V \oplus V^*)[-1].$$

Here we use the standard convention for graded versions of commutative algebras, based on symmetric monoidal structure on the category of graded

 $^{^1\}mathrm{Department}$ of Mathematics, University of Haifa, Mount Carmel, Haifa 31905, Israel vhinich@gmail.com

 $^{^2\}mathrm{Department}$ of Mathematics, University of Haifa, Mount Carmel, Haifa 31905, Israel lembergdan@gmail.com

vector spaces defined by the commutativity constraint given by the standard formula

$$\sigma: X \otimes Y \longrightarrow Y \otimes X, \quad \sigma(x \otimes y) = (-1)^{|x||y|} y \otimes x.$$
 (1.2)

The commutative algebra H has a degree -2 Lie bracket (called big bracket by Y. Kosmann-Schwarzbach in [9]) satisfying Leibniz rule with respect to the multiplication, and given on the generators by the formula

$$[x, x'] = 0, [y, y'] = 0, [x, y] = [y, x] = \langle y, x \rangle$$
 (1.3)

for $x, x' \in V$, $y, y' \in V^*$.

Throughout this paper we will be using the language of operads to describe various algebraic structures. Graded Poisson algebras are algebras over a certain operad denoted P_n . Algebras over P_n have a degree zero commutative multiplication and degree 1-n Lie bracket satisfying Leibniz rule. Thus, our algebra H is a P_3 -algebra.

The operad P_n is Koszul [4], so it has a particularly nice cofibrant resolution and a particularly nice notion of homotopy P_n -algebra.

In this paper we prove that H is intrinsically formal as P-algebra. This means that any homotopy P_3 -algebra X such that H(X) = H as P-algebras, is equivalent to X.

The proof follows ideas of Tamarkin [21] and makes use of the criterion of intrinsic formality described in [6], 4.1.3.

- 1.2. The graded vector space H appears in two interconnected instances in deformation theory. The first one is connected to Lie bialgebras, and the second to associative bialgebras.
- 1.2.1. Lie bialgebras. Recall that, according to Y. Kosmann-Schwarzbach [9] a proto-Lie bialgebra structure on a vector space V is just a degree 3 element h of H satisfying the condition [h,h]=0. Let $\lambda\in V\otimes \wedge^2V^*$, $\delta\in \wedge^2V\otimes V^*$, $\alpha\in \wedge^3V$ and $\beta\in \wedge^3V^*$ be the components of h. One can easily check that if $\alpha=0,\ \beta=0$, the tensors λ and δ determine a Lie bialgebra structure on V. The case $\beta=0$ describes Lie quasi-bialgebras, whereas $\alpha=0$ corresponds to the dual notion.

Lie bialgebras and their "quasi-" versions describe quasiclassical limits of quantized enveloping algebras as defined by Drinfeld [3]. The notion of Lie proto-bialgebra naturally generalizes both Lie quasi-bialgebra and coquasi-bialgebras. We are unaware of the existence of the notion of associative proto-bialgebra quantizing Lie proto-bialgebras.

Let $h \in H^3$ satisfy [h, h] = 0, so that (V, h) is a Lie proto-bialgebra. The operator $d_h = \mathrm{ad}_h$ is a derivation of both commutative and Lie algebra structure on H, so that (H, d_h) becomes a dg P_3 -algebra. The dg Lie algebra $(H[2], d_h)$ governs formal deformations of the Lie proto-bialgebra (V, h). In particular, H[2] governs deformations of the commutative Lie bialgebra (in the class of Lie proto-bialgebras).

Our result on formality should be much more relevant to another deformation problem, that of associative bialgebras¹, see 1.2.3.

1.2.2. Associative algebras. Before we start talking about bialgebra deformations, it is worthwhile to remind what is going on with already classical problem of deformations of associative algebras.

Let A be an associative algebra. The Hochschild cohomology $HH^*(A)$ has a structure of Gerstenhaber algebra (this is the same as P_2 -algebra in our notation). Moreover, P_2 is the homology of the small squares operad E_2 (F. Cohen, [1]), and the Hochschild cochain complex $CC^*(A)$ has a (homotopy) structure of algebra over E_2 (Deligne conjecture). In case A is a polynomial algebra its Hochschild cohomology, the algebra of polyvector fields $\wedge T$, is intrinsically formal as P_2 -algebra, and this result implies the famous Kontsevich formality theorem for the polynomial ring, see Kontsevich [8], Tamarkin [21]. Note that the algebra $\wedge T$, similarly to our algebra H, can also be interpreted as the algebra responsible for deformations of the (trivial) Poisson bracket in the polynomial ring.

Note that there are two different deformation problems connected to an associative algebra A. Deformations of A are governed by the (shifted and) truncated Hochschild cochain complex Def_A concentrated in nonnegative degrees, so that

$$\operatorname{Def}_{A}^{n} = \operatorname{Hom}(A^{\otimes n+1}, A), \ n \geq 0.$$

However, this dg Lie algebra is not formal even in case A is a polynomial ring. The Kontsevich formality theorem states that the full (shifted) Hochschild cochain complex concentrated in degrees $n \geq -1$ is formal. The deformation problem described by the full Hochschild complex is that of the category of A-modules. This deformation problem is not easy to formally define; the difference between two deformation problems can be seen if one studies deformation of a sheaf of associative algebras: as a result of deformation one can get an algebroid stack instead of the deformed sheaf of associative algebras.

¹Or associative proto-bialgebras if one could imagine what they are.

1.2.3. Associative bialgebras. Deformation theory for associative bialgebras was pioneered by Gerstenhaber and Schack in [5] where a deformation complex $C_{GS}(A)$ of a bialgebra A was defined by the ad hoc formulas

$$C_{GS}^{n}(A) = \bigoplus_{p+q=n} \operatorname{Hom}(A^{\otimes p}, A^{\otimes q}), \tag{1.4}$$

with the differential given for $\phi: A^{\otimes p} \to A^{\otimes q}$ by the formula

$$d(\phi) = d_1(\phi) + d_2(\phi), \tag{1.5}$$

where

$$d_1(\phi)(a_0 \otimes \ldots \otimes a_p) = \Delta^{q-1}(a_0)\phi(a_1 \otimes \ldots \otimes a_p) +$$

$$+ \sum_{i=0}^{p-1} (-1)^{i+1}\phi(a_0 \otimes \ldots \otimes (a_i a_{i+1}) \otimes \ldots \otimes a_p) +$$

$$+ (-1)^{p-1}\phi(a_0 \otimes \ldots \otimes a_{p-1})\Delta^{q-1}(a_p)$$

$$(1.6)$$

and

$$d_2(a_1 \otimes \ldots \otimes a_p) = (\mu_{p-1} \otimes \phi) \Delta^{\otimes p}(a_1 \otimes \ldots \otimes a_p) + (1.7)$$

$$\sum_{i=1}^q \Delta_i(\phi(a_1 \otimes \ldots \otimes a_p)) + (-1)^{p-1}(phi \otimes \mu_{p-1}) \Delta^{\otimes p}(a_1 \otimes \ldots \otimes a_p).$$

Here in formula (1.6) Δ^{q-1} denotes the multiple comultiplication $A \longrightarrow A^{\otimes p}$, $\Delta^{\otimes p}$ in formula (1.7) denotes the comultiplication induced on $A^{\otimes p}$, that is, a map $A^{\otimes p} \longrightarrow A^{\otimes p} \otimes A^{\otimes p}$, μ_{p-1} denotes the (multiple) product $A^{\otimes p} \longrightarrow A$, and $\Delta_i = 1 \otimes \ldots \otimes \Delta \otimes \ldots \otimes 1$. Gerstenhaber-Schack cohomology is defined by the formula

$$H_{GS}^*(A) = H^*(C_{GS}(A)).$$

For the bialgebra A = S(V) with standard multiplication and coproduct, a well-known calculation (reproduced below, following Shoikhet [18], see 3.2.1) shows $H_{GS}(A) = H$ as a graded vector space. According to a version of Deligne conjecture proven by B. Shoikhet [19], the chain complex C_{GS} admits a structure of E_3 -algebra. Once more, in characteristic zero the operad E_3 is equivalent to P_3 , see [10], so Gerstanhaber-Schack cochains admit a canonical homotopy P_3 -algebra structure.

Therefore, in order to have a complete analog of Kontsevich formality theorem for bialgebras, one needs to solve two problems.

1. Verify that the P_3 -algebra structure on H defined in 1.1 comes from the E_3 -algebra structure on the cochains $C_{GS}(S(V))$.

2. Understand in what sense E_3 -algebra $C_{GS}(A)$ governs deformations of the bialgebra A.

We will now describe what we can say about the above problems.

1.2.4. First of all, Gerstenhaber-Schack cohomology is known to be described as $\operatorname{Ext}(A,A)$ calculated in the abelian category of A-tetramodules, see Taillefer [20] and Section 3 below. The commutative algebra structure on $H_{GS}(A)$ comes from Yoneda product in Ext's, and it is not difficult to verify that for A = S(V) this yields the commutative multiplication in H coming from the symmetric algebra structure.

Furthermore, Leibniz rule together with degree considerations imply that the Lie bracket on the cohomology induced from the E_3 structure on the cochains, is determined by its restriction to W, that is by a symmetric bilinear form on $V \oplus V^*$.

One can easily deduce from this that the bracket on H defined by E_3 structure is proportional to the one given by the formula (1.3). Unfortunately, this does not imply that the bracket is nonzero. This remains a problem. We were unable to make an explicit computation of the bracket using Shoikhet's description of E_3 structure on the chain complex. We believe that a correct way of doing so would be using deformation theory; at the moment we are only able to deduce this fact from Conjecture 1, see Section 4.

1.2.5. Gerstenhaber and Shack used their cohomology to describe obstruction theory: third cohomology of a certain subcomplex of $C_{GS}(A)$ describes infinitesimal deformations, with obstructions dwelling in the fourth cohomology. They conjectured the existence of Lie algebra bracket on cohomology so that the obstruction of infinitesimal deformation given by $u \in H^3_{GS}(A)$ is $[u, u] \in H^4_{GS}(A)$.

Merkulov and Vallette [16] proved existence of such bracket on a certain subcomplex of $C_{GS}(A)$; unfortunately, we see no way of comparing this bracket with the one coming from E_3 -structure.

One should also have in mind that, similarly to the case of associative algebras, one cannot expect the full Gerstenhaber complex to govern deformations of bialgebras; the full complex should rather govern deformations of a certain "linear" object attached to a bialgebra A.

A sensible candidate would be the two-category of categories, left-tensored over the monoidal category of left A-modules.

We hope to be able to make sense of this claim in a later publication.

2. Intrinsic formality of H

The rational homology P_n of the topological operad E_n was calculated by Fred Cohen in 1973. This is a graded operad over \mathbb{Q} generated by two operations: commutative associative multiplication μ in degree zero, and a Lie bracket λ in degree 1-n, subject to the graded version of Leibniz rule.

Furthermore, the operad $C_{\bullet}(E_n, \mathbb{Q})$ on rational chains is known to be formal: it is quasiisomorphic to P_n as an operad of complexes, see [10].

In this section we prove the intrinsic formality of the P_3 -algebra $H = S(V[-1] \oplus V^*[-1])$ in the sense of [6], 4.1.2.

We will follow the Tamarkin's idea [21, 6].

Recall that $\mathcal{P} = P_3$ is Koszul operad and the free \mathcal{P} -algebra spanned by a complex X has the following form.

$$\mathbb{F}_{\mathcal{P}}(X) = \mathbb{F}_{\texttt{Com}} \circ \mathbb{F}_{\texttt{Lie}\{2\}}(X) \tag{2.1}$$

where $\mathbb{F}_{\mathtt{Com}}$ is the free commutative (=symmetric) algebra, $\mathtt{Lie}\{2\}$ is the operad defined by the property that $\mathtt{Lie}\{2\}$ -algebra structure on X is the same as \mathtt{Lie} -algebra structure on X[2].

Also $\mathcal{P}^{\perp} = \mathcal{P}\{-3\}^*$, so that the cofree \mathcal{P}^{\perp} -coalgebra spanned by H has form

$$\mathbb{F}_{\mathcal{P}^{\perp}}^{*}(H) = \mathbb{F}_{\mathsf{Com}}^{*}(\mathbb{F}_{\mathsf{Lie}}^{*}(H[1])[2])[-3]. \tag{2.2}$$

We will use the following criterion of intrinsic formality.

2.1. THEOREM. (see [6], 4.1.3). — Let \mathfrak{g} be the dg Lie algebra of coderivations of $(\mathbb{F}_{\mathcal{P}^{\perp}}^*(H), Q)$, where the differential Q is defined by the \mathcal{E} -algebra structure on H. Denote

$$\mathfrak{g}_{\geq 1} = \operatorname{Hom}(\bigoplus_{i \geq 2} \mathbb{F}_{\mathcal{P}^{\perp}}^{*i}(H), H) \subset \operatorname{Hom}(\bigoplus_{i \geq 1} \mathbb{F}_{\mathcal{P}^{\perp}}^{*i}(H), H) = \mathfrak{g}.$$
 (2.3)

Then , if the map $H^1(\mathfrak{g}_{\geq 1}) \longrightarrow H^1(\mathfrak{g})$ is zero, the P-algebra H is intrinsically formal.

The dg Lie algebra g is obtained from a bicomplex,

$$\mathfrak{g} = \bigoplus_{p,q \ge 0} \mathfrak{g}^{p,q}, \quad \mathfrak{g}_{\ge 1} = \bigoplus_{(p,q) \ne (0,0)} \mathfrak{g}^{p,q},$$
 (2.4)

where

$$\mathfrak{g}^{p\bullet} = \text{Hom}(\mathbb{F}_{\text{com}}^{*(p+1)}(\mathbb{F}_{\text{Lie}}^{*}(H[1])[2]), H[3]),$$
 (2.5)

and q+1 is the total Lie-degree. The horizontal and the vertical components Q_l and Q_m of the differential are defined by the Lie bracket and commutative multiplication on H respectively. In order to calculate the cohomology of

 ${\mathfrak g}$ we can use the spectral sequence of the above bicomplex. Look at the complexes

$$(\mathfrak{g}^{p\bullet}, Q_m) = \operatorname{Hom}_H(S_H^{p+1}(\mathbb{F}_{Lie}^*(H[1]) \otimes H[2]), H[3]). \tag{2.6}$$

The complex $Z := \mathbb{F}^*_{\mathtt{Lie}}(H[1]) \otimes H$ is the homological Harrison complex of the commutative algebra H. Therefore,

$$(\mathfrak{g}^{p\bullet}, Q_m) = \text{Hom}_H(S_H^{p+1}(Z[2]), H[3]).$$
 (2.7)

Now recall that H = S(W) where $W = V[-1] \oplus V^*[-1]$, so Z is quasiisomorphic to the shifted module of differentials, $Z = H \otimes W[1]$.

Therefore, the homology of the complex $\mathfrak{g}^{p\bullet}$ with respect to the vertical differential Q_m is

$$E_1^{p,q} = \begin{cases} \text{Hom}(S^{p+1}(W[3]), S(W)[3]) & \text{if } q = 0\\ 0 & \text{otherwise.} \end{cases}$$
 (2.8)

The spaces $E_1^{p,0}$ are quotients of $\mathfrak{g}^{p,0} = \operatorname{Hom}(\mathbb{F}^{*p+1}_{\mathtt{Com}}(H[3]), H[3])$, so the differential Q_l on $E_0^{p,0}$ is induced by the Chevalley-Eilenberg differential

$$(df)(a_1 \cdots a_{p+1}) = -\sum_{i=1}^{p+1} (-1)^{i+|a_i|(|a_1|+\dots+|a_{i-1}|)} [a_i, f(a_1 \dots \widehat{a_i} \dots a_{p+1})]$$
(2.9)

The spectral sequence degenerates at term 2 $(E_2^{p,q}=E_\infty^{p,q}), E_2^{p,q}=0$ for q>0 and $E_2^{p,0}$ is the p-th cohomology of the complex $(E_1^{p,0},Q_l)$.

We can now verify the condition of Theorem 2.1. One-cochain in $E_1^{p,0}$ has form $\sum_p f_p$ with

$$f_p \in \text{Hom}(S^{p+1}(W[3]), S^{4-2(p+1)}(W)).$$

This immediately implies that $f_p = 0$ for p > 1. Such cochain is in the image of $\mathfrak{g}_{\geq 1}$ iff $f_0 = 0$. Thus, any one-cochain coming from $\mathfrak{g}_{\geq 1}$ is presented by a map $f_1: S^2(W) \longrightarrow k$. We will show it is always a boundary. More precisely, we claim there exists $g \in E_1^{0,0}$ of total degree zero such that $f_1 = Q_l(g)$. The elements of total degree zero in $E_1^{0,0}$ are maps $g: W \longrightarrow W$. The formula (2.9) shows that for such g its differential is calculated as

$$Q_l(g)(a,b) = [a,g(b)] + [b,g(a)].$$

Since the bracket restricted to W is a nondegenerate symmetric bilinear form, existence of g is a basic fact of linear algebra. This proves the theorem.

3. Gerstenhaber-Schack cohomology of Ug

According to Taillefer [20], Gerstenhaber-Schack cohomology of a bialgebra A is just $\operatorname{Ext}(A,A)$ in a certain abelian category Tetra_A , the category of A-tetramodules. According to Shoikhet [19], the braided monoidal structure on the category of tetramodules induces E_3 -algebra structure on GS cochains. This induces a P_3 -algebra structure on the cohomology. The graded space H studied in the previous section is the GS cohomology of the bialgebra A = S(V). We would like to identify the P_3 -structure on H defined by the formulas (1.1)–(1.3) with the one induced on H as the GS cohomology. We have not completely succeeded in this.

We check that the commutative multiplication in H induced from the P_3 structure comes from the presentation H = S(W); furthermore, we prove that the bracket is proportional to the one given by formula (1.3). Thus, if the bracket on H is nonzero, the formality calculation of Section 2 is applicable. Unfortunately, we were unable to prove nonvanishing of the bracket on H induced from the E_3 -structure on GS cochains.

We believe that the Lie bracket on H is in fact given by the formula (1.3). We support this belief in Section 4 with some speculations and conjectures.

In this section we present the calculation of $\mathbf{R}\mathrm{Hom}_{\mathtt{Tetra}_A}(A,A)$ for $A=U\mathfrak{g}$ the enveloping algebra. We present it by a dg algebra which induces Yoneda product on the cohomology.

In the special case $\mathfrak{g} = V$ is a commutative Lie algebra, this allows one to identify the Yoneda product on H with the multiplication in the symmetric algebra. Then we deduce that the bracket is proportional to (1.3).

The category Tetra_A of A-tetramodules has enough injectives; but it is more convenient to make calculations using formalism of (P,Q) pairs described in [18]. In the following subsection we recall the relevant definitions.

3.1. Tetramodules. Let A be a bialgebra.

Recall that a tetramodule structure on a vector space M is a bialgebra structure on the direct sum $A \oplus M$ sich that the natural projection $p:A \oplus M \longrightarrow A$ is a bialgebra morphism and p is an abelian group object in the category of bialgebra morphisms $B \longrightarrow A$ with target A. The latter means that the maps $M \otimes M \to M$ and $M \to M \otimes M$ defined by restriction of the multiplication and the comultiplication on M, vanish.

Thus, a tetramodule has both a bimodule and a bicomodule structure, satisfying certain compatibilities.

The category of A-tetramodules is denoted Tetra_A . This is an abelian category with enough injectives, see [20]. In case A is a Hopf algebra, it is equivalent to the category of Yetter-Drinfeld modules and is Drinfeld double of the monoidal category of left A-modules, see [17].

3.1.1. Induced and coinduced tetramodules. We have two pairs of adjoint functors

$$\operatorname{Bicomod}_A \xrightarrow{\operatorname{Ind}} \operatorname{Tetra}_A \xrightarrow{G} \operatorname{Bimod}_A$$
 (3.1)

where G denotes the forgetful functors, Ind is the induction and Coind the coinduction functor defined as in Shoikhet [18].

Any tetramodule embeds into a coinduced tetramodule and is an image of induced tetramodule. Therefore, any tetramodule X admits an induced resolution

$$\longrightarrow P_n \longrightarrow \dots \longrightarrow P_0 \longrightarrow X \longrightarrow 0$$

and a coinduced resolution

$$0 \longrightarrow X \longrightarrow Q^0 \longrightarrow \dots \longrightarrow Q^n \longrightarrow ...$$

One has

THEOREM. — (see [18]) One can calculate \mathbf{R} Hom_{Tetra_A}(X,Y) using induced resolution for X and coinduced resolutions for Y.

3.2. The case $A = U\mathfrak{g}$. Let $A = U\mathfrak{g}$ be the enveloping algebra of a finite dimensional Lie algebra \mathfrak{g} considered as a bialgebra.

We will calculate $\mathbf{R}\mathrm{Hom}_{\mathtt{Tetra}_A}(A,A)$ using an induced and a coinduced resolutions for the tetramodule A. We define $P_n = \mathrm{Ind}(\wedge^n \mathfrak{g})$ and $Q^n = \mathrm{Coind}(\wedge^n \mathfrak{g})$, where in the first formula $\wedge^n \mathfrak{g}$ has the trivial bicomodule structure, whereas in the second formula it has the trivial bimodule structure.

We will use the following notation. For a subset $I \subset N = \{1, ..., n\}$ and a collection of elements $x_i \in \mathfrak{g}$, $i \in N$, we denote as x_I the product $x_{i_1} \wedge ... \wedge x_{i_{|I|}}$.

The induced tetramodules P_n form a complex P_{\bullet} with $H^0(P_{\bullet}) = A$, with the differentials $\partial_n : P_n \longrightarrow P_{n-1}$ defined by the formula

$$\partial_n(a \otimes x_N \otimes b) = \sum_{i=1}^n (-1)^{i-1} a x_i \otimes x_{N-\{i\}} \otimes b - a \otimes x_{N-\{i\}} \otimes x_i b + (3.2)$$
$$+ \sum_{i < j \in N} (-1)^{i+j} a \otimes [x_i, x_j] \wedge x_{N-\{i,j\}} \otimes b.$$

The formulas for a differential in the coinduced resolution Q^{\bullet} of A are similar: ² the differential $d_n: Q^n \longrightarrow Q^{n+1}$ is given by the formula

$$d_n(a \otimes x_N \otimes b) = \Delta_r^1(a) \otimes \Delta_r^2(a) \wedge x_N \otimes b - a \otimes x_N \wedge \Delta_l^1(b) \otimes \Delta_l^2(b), (3.3)$$

where $\Delta_r^1(a) \otimes \Delta_r^2(a)$ (resp., $\Delta_l^1(a) \otimes \Delta_l^2(a)$) denotes the projection of $\Delta(a)$ to $U\mathfrak{g} \otimes \mathfrak{g}$ (resp., to $\mathfrak{g} \otimes U\mathfrak{g}$).

Now Gerstenhaber-Schack cohomology of $A = U\mathfrak{g}$ can be expressed as

$$H_{GS}(A) = \mathcal{H}om_{\mathsf{Tetra}_A}(P_{\bullet}, Q^{\bullet}), \tag{3.4}$$

where $\mathcal{H}om$ denotes the complex of morphisms in Tetra_A

The right-hand side of the equation can be easily calculated. This is $H = \wedge \mathfrak{g} \otimes \wedge \mathfrak{g}^*$ as a graded commutative algebra, with the differential $d = \operatorname{ad}_{\lambda}$ where $\lambda \in H^3$ is the tensor defining Lie bracket on \mathfrak{g} , and $\operatorname{ad}_{\lambda}$ makes use of the Lie bracket defined by the pairing $\mathfrak{g}^* \otimes \mathfrak{g} \longrightarrow k$.

In particular, if $\mathfrak{g} = V$ is a commutative Lie algebra, one has

$$H_{GS}(A) = \text{Hom}(\land V, \land V) = H.$$
 (3.5)

We will now describe the Yoneda multiplication in $H_{GS}(U\mathfrak{g})$.

Since tetramodules form a monoidal (even braided monoidal) category, Yoneda product can be expressed via the monoidal stucture as follows.

If α and β are cycles in $\mathcal{H}om(P_{\bullet}, Q^{\bullet})$ of degrees m and n, one has a cycle

$$\alpha \otimes \beta \in \mathcal{H}om(P_{\bullet} \otimes P_{\bullet}, Q^{\bullet} \otimes Q^{\bullet})$$

of degree m+n which yields an element in $H_{GS}^{m+n}(A)$ as $P_{\bullet}\otimes P_{\bullet}$ and $Q^{\bullet}\otimes Q^{\bullet}$ are also resolutions of A. One can further simplify the formulas using the coalgebra structure on P_{\bullet} and the algebra structure on Q^{\bullet} described as follows.

The forgetful functors $\mathsf{Tetra}_A \longrightarrow \mathsf{Bicomod}_A$ and $\mathsf{Tetra}_A \longrightarrow \mathsf{Bimod}_A$ are monoidal. Thus, Ind is colax monoidal functor, that is one has a natural morphism

$$\operatorname{Ind}(X \otimes Y) \longrightarrow \operatorname{Ind}(X) \otimes \operatorname{Ind}(Y).$$

Similarly, Coind is lax monoidal, that is one has a canonical morphism

$$Coind(X) \otimes Coind(Y) \longrightarrow Coind(X \otimes Y).$$

Taking this into account, we can define a quasiisomorphism $P_{\bullet} \longrightarrow P_{\bullet} \otimes P_{\bullet}$ of complexes of tetramodules as follows. For n = p + q one has a map

²But simpler as there is no term coming from (co)bracket.

 $\wedge^n V \to \wedge^p V \otimes \wedge^q V$ (of trivial bicomodules over SV) which add up to the commutative comultiplication in the algebra $\wedge V$. This yields the map

$$P_n \longrightarrow \operatorname{Ind}(\wedge^p V \otimes \wedge^q V) \longrightarrow P_p \otimes P_q.$$

The comultiplication on P_{\bullet} defined by these maps commutes with the differentials $P_n \longrightarrow P_{n-1}$ defined by the formula (3.2). Dually, one has a multiplication $Q^{\bullet} \otimes Q^{\bullet} \longrightarrow Q^{\bullet}$ (co)induced by the multiplication in $\wedge V$.

The complex $\mathcal{H}om_{\mathsf{Tetra}_A}(P_{\bullet}, Q^{\bullet})$ has, therefore, a dg commutative algebra structure which induces the Yoneda product in cohomology.

3.2.1. $\mathfrak{g} = V$ is commutative. In this case the complex $\mathcal{H}om_{\mathtt{Tetra}_A}(P_{\bullet}, Q^{\bullet}) = \mathrm{Hom}(\wedge V, \wedge V)$ has zero differential and is isomorphic to H. An easy calculation shows that the Yoneda product in this case is simply given by the commutative product in the presentation

$$H = \wedge V^* \otimes \wedge V$$
.

3.3. The Lie bracket. Here we assume A = S(V). Since Lie bracket on H should satisfy Leibniz rule, it is uniquely defined by its value on algebra generators, that is on $W = (V \oplus V^*)[-1]$. Since the bracket has to have degree -2 and $H_0 = k$, it has to be given by a symmetric bilinear form on $V \oplus V^*$.

Let us show that the bracket has to be proportional to the one defined by the formulas (1.3). In fact, the group GL(V) acts by automorphisms on the bialgebra A=S(V). Any automorphism $g\in GL(V)$ gives rise to a braided autoequivalence of the category Tetra_A . Therefore, the (homotopy) E_3 -algebra structure on H has to be GL(V)-equivariant. But the formula (1.3) is the only, up to scalar, GL(V)-invariant symmetric bilinear form on $V\oplus V^*$ as

$$S^{2}(V \oplus V^{*}) = S^{2}(V) \oplus S^{2}(V^{*}) \oplus V \otimes V^{*},$$

 $S^2(V)$ and $S^2(V^*)$ have no invariants and $V \otimes V^*$ has one-dimensional invariant subspace.

This proves our claim.

4. Speculations

The calculation of Gerstenhaber-Schack cohomology of $U\mathfrak{g}$ presented in the previous section yields, in particular, a canonical map

$$\mathbf{R}\mathrm{Hom}_{U\mathfrak{g}}(k,\mathfrak{g}) \longrightarrow \mathbf{R}\mathrm{Hom}_{\mathtt{Tetra}_{U\mathfrak{g}}}(U\mathfrak{g},U\mathfrak{g})[1] \tag{4.1}$$

(compare to [14], Theorem 2').

We want to look at this map as a categorification of an embedding

$$T \longrightarrow \wedge T$$
 (4.2)

from the Lie algebra of vector fields on a smooth affine variety to the algebra of polyvector fields endowed with the Schouten bracket.

Our reasoning is as follows. The left-hand side of the formula, cut and shifted by one, is the dg Lie algebra governing deformations of Lie algebra \mathfrak{g} . The whole shifted left-hand side $\mathbf{R}\mathrm{Hom}_{U\mathfrak{g}}(k,\mathfrak{g})[1]$ has a dg Lie algebra structure since it identifies with the dg Lie algebra of coderivations of the standard Chevalley-Eilenberg chain complex of \mathfrak{g} . This is the dg Lie algebra governing deformations of the category of \mathfrak{g} -modules considered as symmetric monoidal category.

The shifted right-hand side of (4.1), $\mathbf{R}\operatorname{Hom}_{\mathtt{Tetra}_{U\mathfrak{g}}}(U\mathfrak{g},U\mathfrak{g})[2]$, is expected to govern deformations of the same category of \mathfrak{g} -modules considered as monoidal category.

Thus, the map (4.1) corresponds to the embedding of symmetric monoidal deformations of if the monoidal category $Mod_{\mathfrak{g}}$ into its monoidal deformations.

There is no doubt the following claim should be true.

Conjecture 1.— The map (4.1) preserves Lie bracket in cohomology, where Lie bracket in the left-hand side comes from its interpretation as the complex of coderivations, whereas the Lie bracket in the right-hand side is induced from the E_3 -algebra structure on the GS cochains.

This conjecture immediately implies that the Lie bracket in $H = H_{GS}(S(V))$ is in fact given by the formula (1.3).

Actually, we believe a much stronger conjecture is true.

Recall the version of Kontsevich formality for smooth commutative dg algebras proven in [7]:

THEOREM. — Let A be a smooth commutative dg algebra over a field of characteristic zero. Then the Hochschild cochain complex of A is equivalent to the dg algebra of polyvector fields as (homotopy) Gerstenhaber algebras.

We believe that a categorified version of the above result should be valid.

³This is not precise. It should be rather responsible for deformations of 2-category of categories, left-tensored over Mod_n.

The complex $L = \mathbf{R}\mathrm{Hom}_{U\mathfrak{g}}(k,\mathfrak{g})[1]$ is a Lie algebroid over the commutative dg algebra $A = C^*(\mathfrak{g}, k)$. This implies that, similarly to the algebra of polyvector fields acquiring a Gerstenhaber algebra structure, the shifted symmetric algebra $S_A(L[-2]) = S_A(\mathbf{R}\mathrm{Hom}_{U\mathfrak{g}}(k,\mathfrak{g})[-1])$ acquires a structure of P_3 -algebra.

Recall that the operads P_3 and E_3 are equivalent in characteristic zero.

Keeping in mind this equivalence, we believe the following to be true.

Conjecture 2. — The E_3 -algebra \mathbf{R} Hom $_{\mathtt{Tetra}_{U\mathfrak{g}}}(U\mathfrak{g}, U\mathfrak{g})$ is equivalent to the algebra $S_A(L[-2])$ where L is the dg Lie algebroid \mathbf{R} Hom $_{U\mathfrak{g}}(k,\mathfrak{g})[1]$ over $C^*(\mathfrak{g},k)$.

Our formality result of Section 2 shows that in case $\mathfrak g$ is commutative, Conjecture 1 implies Conjecture 2.

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