

ESSAYS ON BUSINESS ANALYTICS AND GAME THEORY

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To my families, teachers, and friends.

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Abstract

This collection of essays explores several research topics in business analytics and game theory. The first essay, Chapter 2, applies text mining and machine learning to quantify the impact of natural disaster risk on firm performance. The second essay, Chapter 3, uses machine learning and the Merton model to predict corporate financial distress in a transition economy. The third essay, Chapter 4, investigates optimal investment strategies in finite and mean field games, considering the presence of risk-seeking agents and using a hyperbolic absolute risk aversion (HARA) utility function. Each chapter focuses on a specific type of shock, including climate shocks (Chapter 2), economic shocks (Chapter 3), and stochastic shocks (Chapter 4).

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Chapter 1

Introduction

This dissertation comprises three essays, each of which explores a research topic in business analytics or game theory with focusing on a specific type of shock.

1.1 Motivations

Shocks can exist in many forms. Each chapter in this dissertation explores a type of shock.

Climate shocks. Chapter 2 investigates natural disasters such as climate shocks and their effects on U.S. public firm performance. In this chapter, climate shocks are proxy for environmental shocks or environmental uncertainty. There are many studies in the literature examining (objective) environmental uncertainty/shocks ([Downey et al. 1975](#); [Swamidass and Newell 1987](#); [Faucheux and Froger 1995](#); [Kreiser and Marino 2002](#); [López-Gamero et al. 2011](#); [Yu et al. 2018](#)) and perceived environmental uncertainty/shocks ([Duncan 1972](#); [Lewis and Harvey 2001](#); [Freel 2005](#); [Yu et al. 2018](#)). This chapter contributes to the understanding of both objective and perceived environmental uncertainty in terms of climate shocks and its effects on the US firm performance. In this chapter, perceived natural disaster risk is a proxy for perceived environmental uncertainty.

Economic shocks. Chapter 3 predicts corporate financial distress of firms in a transition economy, Vietnam, under economic shocks (e.g. 2008-9 financial crisis, macroeconomic fluctuations, and the COVID-19 pandemic). There exist very few studies about financial distress prediction under shocks in Vietnam up to this point. [Vo et al. \(2019\)](#) predict financial distress prediction at the industry level during the global financial crisis 2007-2009 and the post-global financial crisis between 2010 and 2017. In contrast, we will focus on the firm-level data in this chapter.

Stochastic shocks. Brownian motions are considered as stochastic shocks. Chapter 4 will examine Brownian motions as stochastic shocks (or stochastic uncertainty) in the framework of a n -agent games and mean field games on the financial markets. The key new aspects in our setting are that there are presence of risk-seeking agents and relative performance

motivation in the stochastic environment. Brownian motions are used extensively in the literature of optimal investment and portfolio selection to model the dynamics of wealth (Merton 1969; Liu 2000; Espinosa and Touzi 2015; Lacker and Zariphopoulou 2019).

1.2 General research question

The general research question of this dissertation is: *How do shocks affect the performance and behavior of economic agents (e.g. firms and individual investors)?*

1.3 Dissertation contributions

This dissertation contributes to the understanding of how shocks affect the performance and behavior of economic agents, including firms and individual investors. The three essays in this dissertation present empirical and theoretical findings on the relationships between climate shocks and firm performance (Chapter 2), economic shocks and corporate financial distress (Chapter 3), and stochastic shocks and investment behavior (Chapter 4).

Chapter 2 contributes to the empirical understanding of the relationship between climate shocks and firm performance. It also contributes to the understanding of the comparison among models performance using different machine learning techniques in predicting firm performance. Particularly, we propose a new way to measure the perceived natural disaster risk by using text mining. We also propose a new dictionary of words related to natural disasters and natural hazards. To the best of my knowledge, this chapter is the first study that measures the perceived natural disaster risk using Form 10-Ks. Moreover, this chapter contributes to the further understanding of the relationships between perceived natural disaster risk, government-reported damages of natural disasters and hazards, and firm performance. Furthermore, this chapter contributes to the understanding of the relative performance among several machine learning models (classification and regression trees or CART, neural works, and linear regression) in predicting firm performance under natural disaster risks.

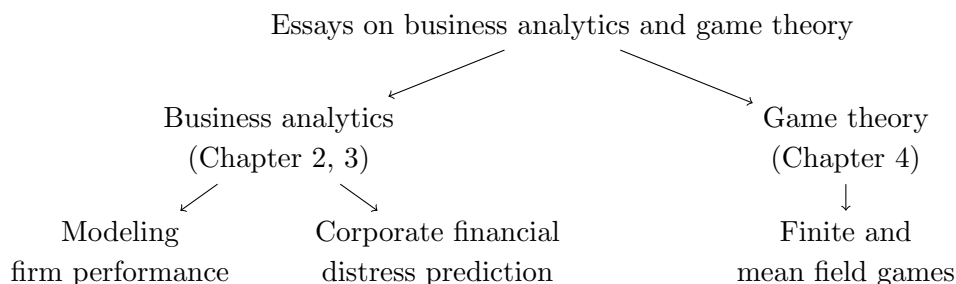
Chapter 3 makes significant contributions to the limited literature on predicting corporate financial distress in a transition economy, Vietnam, during economic shocks. Specifically, this study provides empirical insights into predicting financial distress in a transition economy like Vietnam, where market conditions and data may not be as available or reliable as in many developed economies. It is the first study to employ three methods, including accounting-based, market-based, and machine-learning models, to investigate financial distress among public firms in Vietnam. Additionally, this study is the first to use the synthetic minority oversampling technique (SMOTE) to address biased results caused by imbalanced financial distress data in Vietnam. Another contribution is the provision of new and explicit data for the Merton model, which can be valuable for future research.

Chapter 4 contributes to the theoretical understanding of the behavior of risk-averse and risk-seeking agents on the financial markets. For the case of strictly concave utility function, We prove that there exists the Nash equilibrium for the n -agent games and the mean-field equilibrium for the mean-field games (MFG) in both exponential and power utility functions. Under some mild conditions, the equilibrium is unique. For the case of strictly convex utility function, we prove that there exists a unique corner solution in both n -agent games and MFG for both exponential and power cases. We also quantify the qualitative effects of personal and market parameters on the optimal investment strategies in both n -agent and mean field games.

1.4 The outline of the dissertation

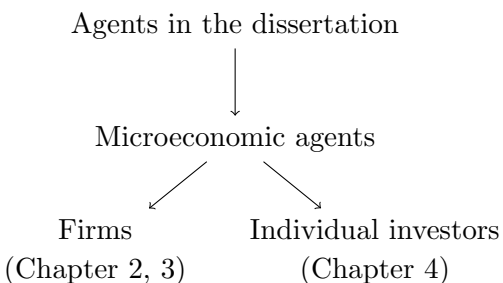
The organization of this dissertation, aside from the introduction (Chapter 1) and conclusion (Chapter 5), consists of two main blocks: business analytics and game theory. The relationship between these two blocks and their related chapters is illustrated in a tree in the following figure.

Figure 1.1: The organizational diagram of two blocks of the dissertation



This dissertation examines the performance and behavior of various economic agents, including both firms and individual investors.

Figure 1.2: The organizational diagram of agents in the dissertation



Chapter 2

Natural disaster risk and firm performance: Text mining and machine learning approach

Abstract

We develop a perceived measure of firms' disaster exposure and/or preparedness equal to the number of words related to natural disaster events in the firms' Form 10-Ks. We then link this measure to contemporary and future firm decision-making and performance. We find that this perceived natural disaster risk and the government-reported damages of natural hazards this year are negatively associated with firm profitability next year. However, the perceived natural disaster risk is not associated with sales growth and Tobin's Q ratio. Specifically, the perceived natural disaster risk negatively affects firm profitability in the services sector but not in the manufacturing sector. The firm profitability in the services sector is also negatively affected by the billion-dollar natural disasters in the same year. Finally, we find that advanced machine learning models robustly outperform linear regression in predicting firm performance under natural disaster risks. The main implication from this study is that we can employ textual data in financial reports to measure the perceived natural disaster risk and predict its effects on firm performance.

Keywords: Natural disaster risk, firm performance, Form 10-Ks, text mining, machine learning.

JEL Codes: C45, C53, L25, M21, Q51, Q54.

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2.1 Introduction

Natural disasters and natural hazards are common phenomena that all public authorities, firms, and academics are concerned about. Academics might measure the effects (direction and magnitude) of the natural disasters and natural hazards on many outcomes such as damages, economic growth, or employment. Public authorities might try to find good strategies and guidance to help vulnerable communities and economic sectors to adapt and respond to natural disasters and hazards. Firms might want to identify factors and mechanisms how natural disasters and natural hazards affect their performance so that they can survive and thrive especially during and after each major weather and climate event. Therefore, a study on environmental uncertainty (natural disasters and natural hazards) is necessary for public authorities, firms, and academics.

This study aims to address several research gaps in the literature. The first research gap is that despite the increasing of number of the billion-dollar natural disaster events as well as its damages as seen in Figure 2.1 and Figure 2.2 respectively and the growing of number studies of the effects of natural disasters on supply chain (Ye and Abe 2012; Abe and Ye 2013), the literature of the relationship between natural disasters and firm performance is relatively limited and fragmented. Many studies just focus on one specific aspect of firms' activities such as firm investment (Hosono et al. 2016) or operating performance (Hsu et al. 2018). At the moment since the evidence of the relationship between natural hazards and disasters and firm performance is relatively limited, this study aims at providing further understanding about this relationship.

The second research gap is that even though the perception of natural hazards and disasters has long been studied in the literature, for example Burton and Kates (1963), the way to measure it mostly bases on the Likert-type scale questions. This type of scale might be subjective and might not be comparable.

Another research gap in the literature of firm performance is that most current empirical studies rely heavily on the linear regression method. This method, however, is not always the best tool for predicting firm performance. This study aims at going beyond linear regression by investigating systematically several common machine learning techniques to predict firm performance. Specifically, this paper will model firm performance under environmental uncertainty by using linear regression (baseline model) and several other advanced machine learning techniques (classification and regression trees or CART, neural networks, and linear regression). The reason to use CART and neural networks is that they are promising tools to capture the nonlinear interactions between natural disasters and firm performance and among other variables in this study. It is necessary to examine more machine learning

techniques to have a comparative perspective of the performances among these techniques, which might help to select the suitable models in predicting firm performance.

This study aims to address these above gaps by answering the following three questions: (i) How to construct an alternative measure for the perceived natural disaster risk? (ii) How do this perceived risk of natural disasters and the government-reported of natural hazards and disasters affect firm performance? (iii) How are differences in performance among several machine learning models (linear regression, CART, and neural networks) in predicting firm performance under natural disaster risks?

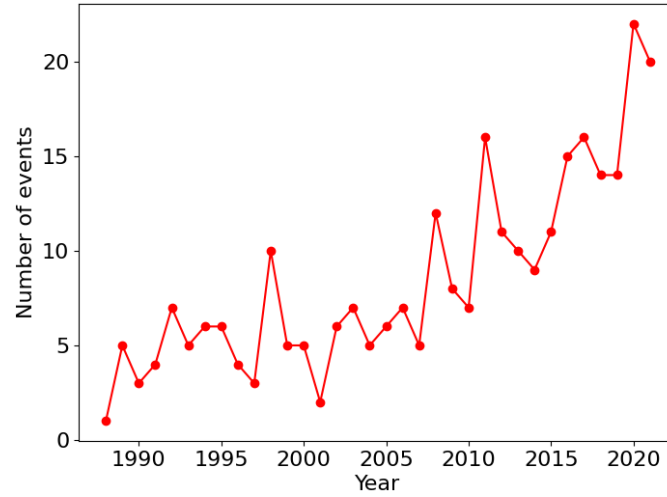
Contributions. This study makes the following primary contributions to the existing literature on natural disasters and firm performance. First, we propose a new way to measure the perceived risk of natural hazards and disasters (or perceived natural disaster risk for short) by using text mining. Second, in order to create a measure of perceived risk of natural disasters, we propose a new dictionary of words related to natural disasters disasters and hazards (see Table 2.11). Third, to the best of my knowledge, this is the first study measures the perceived natural disaster risk using Form 10-Ks. Four, this study contributes to the further understanding of the relationships between perceived natural disaster risk, government-reported damages of natural disasters and hazards, and firm performance. Five, this study contributes to the understanding of the relative performance among several machine learning models (CART, neural works, and linear regression) in predicting firm performance under natural disaster risks.

2.1.1 Motivations

An increase in number of billion-dollar natural disasters

The number of billion-dollar weather and climate disaster events in the U.S. between 1988 and 2021 is shown in Figure 2.1. In general, there is an upward trend of the number of billion-dollar natural disasters in the given period with the trough being in 1988 (1 disaster) and the peak is in 2020 (22 disasters). The average number of billion-dollar natural disasters is approximately 8.44 per year. Note that this upward trend is not affected by inflation since the damages are already adjusted to CPI in 2021. In this study, natural disasters are a proxy for environmental uncertainty. In the sense of frequency, we can consider the billion-dollar disasters as black swan events since they are rare and it is hard to predict when a disaster happening in a particular area.

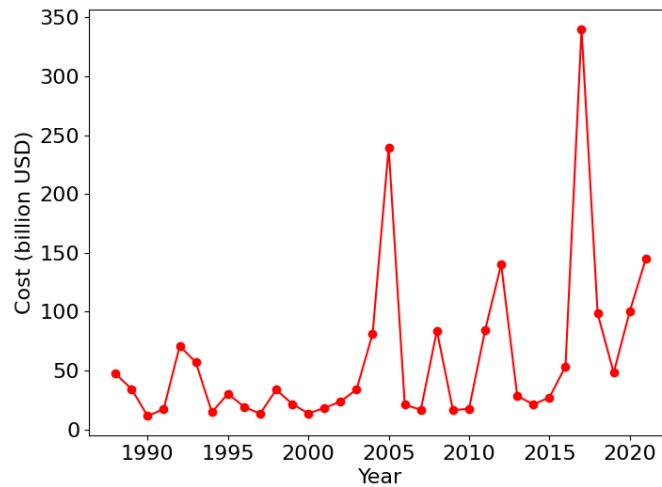
Figure 2.1: Number of billion-dollar natural disasters in the U.S. between 1988 and 2021



Source: The National Oceanic and Atmospheric Administration (NOAA)

Figure 2.2 illustrates the damages of the billion-dollar natural disasters adjusted to CPI in 2021 in the U.S. in the 1988-2021 period. We can observe that the second highest peak and the highest peak are in 2005 with the record-breaking hurricane Katrina¹ and in 2017 with hurricane Harvey, Maria, Irma, and the largest wildfire season ever in California. On average, the damage of billion-dollar disasters is \$59.43 billion per year in the U.S. over the 1988-2021 period.

Figure 2.2: Damages of billion-dollar natural disasters in the U.S. between 1988 and 2021

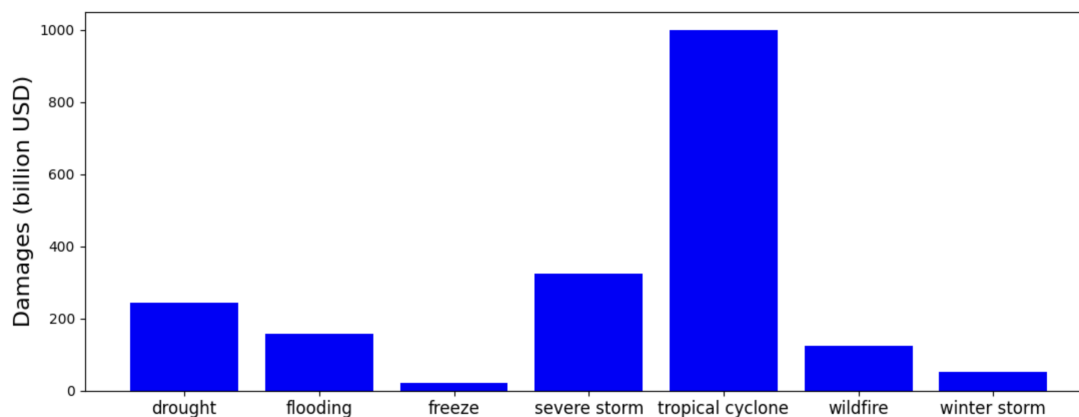


Source: NOAA

¹Hurricane Katrina caused 1,833 deaths and \$178.8 billion in damages. For more details, please see <https://www.ncdc.noaa.gov/billions/events>.

Note that natural disasters in this study include seven types of natural disasters which are tropical cyclones, severe storm, drought, flooding, wildfire, winter storm, and freeze. It can be seen that tropical cyclones are the main billion-dollar natural disasters in the United States.

Figure 2.3: The damages of seven types of natural disasters in the U.S between 1988-2021



Source: NOAA

Table 2.3 shows the damages of the U.S. natural hazards and U.S. billion-dollar natural disasters between 1988 and 2021. The differences between these damages are discussed more details in Section 2.3.1. Note that these damages are already adjusted to CPI in 2021. It can be seen that Texas, Louisiana, Florida, and California are the four most affected states by the damages of both natural hazards and billion-dollar natural disasters in this period.

Table 2.1: Damages of the U.S. natural hazards and billion-dollar natural disasters by state between 1996 and 2021 (unit: \$ billion)

State	Damage (hazards)	Damage (disasters)	State	Damage (hazards)	Damage (disasters)
AK	0.5306	1.7800	MT	0.4548	9.0050
AL	14.7559	43.1300	NC	19.4234	79.3075
AR	6.7640	13.7600	ND	8.9996	13.4275
AZ	5.3592	5.6500	NE	7.8058	20.0050
CA	42.0547	110.0250	NH	0.4074	1.4925
CO	9.8094	30.6775	NJ	32.8633	66.1300
CT	0.3078	6.6125	NM	3.4049	5.5775
DE	0.2454	2.1675	NV	1.5264	2.4725
FL	77.1236	172.8375	NY	6.7471	63.1825
GA	10.8816	30.5525	OH	8.9132	22.7075
HI	0.3525	0.0000	OK	11.6543	33.4800
IA	15.1654	39.1650	OR	5.5070	11.4050
ID	1.2038	4.9775	PA	5.6403	23.3850
IL	7.3788	34.8275	RI	0.1615	1.5200
IN	3.9683	19.0575	SC	2.2795	18.4800
KS	4.9935	23.9325	SD	2.1579	13.3050
KY	5.0951	15.7875	TN	9.8923	29.9775
LA	119.7575	258.3025	TX	147.8666	342.3525
MA	1.1323	5.0600	UT	1.2495	1.8175
MD	1.9651	13.2100	VA	4.0211	15.6600
ME	0.8270	1.5100	VT	1.9174	1.7625
MI	6.9556	8.2100	WA	4.0305	6.1600
MN	7.3728	19.9275	WI	5.8471	14.1550
MO	10.9232	33.2300	WV	1.7502	3.0300
MS	44.3708	51.9075	WY	0.2957	3.2925

Notes: For the U.S. billion-dollar natural disasters (disasters for short), NOAA only provides the estimation of the interval of damages for each state every year. I take the average damages of each interval in each year, then summarize all of these averages to get the total damages for each state in this table. For the U.S. natural hazards, the damages are not adjusted to CPI. Therefore, they are adjusted to CPI in 2021 to be consistent with that of the U.S. billion-dollar natural disasters.

The revolution of textual data

At the firm level, textual data is increasingly widely used. Recently, there are many studies using textual data to examine many aspects of business such as corporate disclosures (Li 2011), firm performance prediction (Qiu et al. 2014), bankruptcy prediction (Mai et al. 2019), corporate innovation (Bellstam et al. 2021), product sales (Li et al. 2019), and corporate culture (Li et al. 2021).

The textual data obtained from Form 10-Ks seems a good channel which reflects firm performance. Cohen et al. (2020) find that “changes to the language and construction of financial reports have strong implications for firms’ future returns and operations”.

¹See more details at <https://www.businessinsider.com/world-cup-favorites-2014-4>

Specifically, they show that the changes to Form 10-Ks predict the firm’s future earnings and profitability. One of the first textual-data studies using Form 10-Ks is the seminar paper (Loughran and McDonald 2011). Specifically, they develop a word list that reflects the tone in financial text and link it to 10-Ks filings. There are several other studies using Form 10-Ks such as (Kang et al. 2018; Ladas 2021).

There are a number of previous studies using the qualitative Management Discussion and Analysis (MD&A) section, which is one of the richest information sections in Form 10-Ks, to explore bankruptcy prediction (Mai et al. 2019), company’s earnings (Feldman et al. 2010; Bochkay and Levin 2019), firm investment (Cho and Muslu 2021), and corporate credit rating prediction (Choi et al. 2020). Our study take into account the MD&A Section as well as other sections in the Form 10-Ks.

2.1.2 Related literature

Objective and perceived environmental uncertainty

Environmental uncertainty is an object of many fields including economics of disasters, environmental economics, environmental management, strategic management, organization theory, microeconomics, and business economics. We will review two different kinds of environmental uncertainty which are actual environmental uncertainty and perceived environmental uncertainty.

Objective environmental uncertainty (OEU), in the context of organizational environment, has long been examined in the management literature (e.g. Downey et al. 1975; Swamidass and Newell 1987; Faucheux and Froger 1995; Kreiser and Marino 2002; López-Gamero et al. 2011; Yu et al. 2018). However, the literature of environmental uncertainty in the context of the natural environment is fairly limited. Many previous studies do not have explicit ways to measure environmental uncertainty either in organizational or environmental context. This study empirically uses the government-reported damages of natural disasters as the proxy of objective environmental uncertainty.

Regarding perceived environmental uncertainty (PEU), there are two types of PEU. The first type of PEU is in the sense of the *organizational* (or *business*) environment and it has long been studied in the fields of strategic management and organization theory (e.g. Duncan 1972; Downey et al. 1975; Miles et al. 1978; Miller 1993; Freel 2005). Meanwhile, the second type of PEU is in the sense of the *natural* environment, which is studied much less and much later compared to the first type of PEU. Indeed, the first research investigating PEU in the natural environment is Lewis and Harvey (2001), which is thirty-four years later compared to the first research about PEU in the organizational environment by Lawrence and Lorsch (1967). This study, therefore, focuses on the second type of PEU to fulfill the gap. Let’s call the second type of PEU *perceived natural environmental uncertainty* (or PNEU). Note that in contrast to many previous studies in the organization theory

literature about PEU using self-report questionnaire (e.g. [Lawrence and Lorsch 1967](#); [Tosi et al. 1973](#); [Tung 1979](#); [Miller 1993](#); [Lewis and Harvey 2001](#)), this study employs the text mining technique.

There are several studies examining both OEU and PEU in the context of organizational environment (e.g. [Downey et al. 1975](#); [Milliken 1987](#); [Yu et al. 2018](#)). It seems that most studies explore both OEU and PEU in the context of organizational environment. This study, however, focuses on objective and perceived environmental uncertainty in the context of *natural* environment. In this paper, the government-reported damages of natural hazards and disasters are proxy for the objective natural environmental uncertainty (ONEU) and the perceived natural hazard risk is proxy for the perceived natural environmental uncertainty (PNEU).

The effects of natural disasters on economy and firms

There are two ways that natural disasters affect the economy through two channels: observed damages and perceived measure. For the first channel, the literature shows limited and mixed results about the effects of observed damages of natural disasters on the economy at the macro and micro level. It seems that the effects of natural disasters on both the economy (at the macro level) and firms (at the micro level) are insignificant.

At the macro level, the neoclassical growth model anticipates that the growth effect is negative in the very short run and the growth is temporarily higher than the balanced growth after that ([Felbermayr and Gröschl 2014](#)). The previous macroeconomic empirical studies seem to support this result. Indeed, natural disasters generally have negative effects on the direct costs such as lost lives or physical destruction and an insignificant impact on the indirect costs (consequences physical destruction) ([Botzen et al. 2019](#); [Lazzaroni and Bergeijk 2014](#)). Also, since the proportion of indirect costs increases in larger disasters and might constitute a larger fraction of total costs in large disasters than in small disasters ([National Research Council 1999](#)), the total impact of natural disasters might be insignificant. For example, [Noy and Vu \(2010\)](#) find evidence in a developing country, Vietnam, that more deadly disasters result in lower output growth, destroy more property and capital but these negative effects appear in turn to boost the economy in the short-run. They argue that these outcomes can be supported by the so-called ‘investment-producing destruction’ hypothesis.

At the firm level, natural disasters might have negative effects (e.g. [Hsu et al. 2018](#); [Huang et al. 2018](#); [Pankratz et al. 2023](#)), positive effects (e.g. [Noth and Rehbein 2019](#)) or mixed effects on firms (e.g. [Zhou and Botzen 2021](#); [Leiter et al. 2009](#)). On the one hand, [Hsu et al. \(2018\)](#) find that firms with factories located in states highly affected by natural disasters are much less profitable than states less affected. Also, firms located in countries with more severe weather are likelier to hold more cash and less likely to distribute cash dividends

(Huang et al. 2018). Moreover, Pankratz et al. (2023) find that increasing exposure to extremely high temperatures reduces firms’ revenues and operating income. On the other hand, Noth and Rehbein (2019) examine firms’ outcomes after a major flood in Germany in 2013 and find that firms located in the disaster areas have significantly higher turnover, lower leverage, and higher cash in the period after 2013. Furthermore, Zhou and Botzen (2021) investigate the effects of natural disasters on the firm level in Vietnam. They find that flooding increases labor and capital growth but reduces sales growth notably up to three years after flooding. Also, Leiter et al. (2009) find that, in the short run, floods lead to an increase in total assets and employment growth of firms in regions affected by flooding more than firms in regions unaffected by flooding. However, the productivity of the former firms is negatively affected by flooding. One explanation is that the increase in investments in assets and employment offset the damaged production capabilities. This research will provide further evidence on whether natural disasters have a significant effect on firm performance or not and whether the direction of effect is positive or negative.

Regarding the second channel, perceived measure, the natural disasters might affect the behavior and decisions of the firm’s executives and managers and firm’s related agents (e.g investors). Several previous studies examine the reactions of executives, managers, and investors to natural disasters (McKnight and Linnenluecke 2017; Alok et al. 2020; Huynh and Xia 2022; Huang et al. 2022).

2.1.3 Comparison among machine learning techniques

One of the main goals of this study is to compare the modeling performances under uncertainty using different machine learning methods. Some comparisons in the literature are as follows.

Linear regression vs. CART. There are relatively few papers comparing the performances of linear regression and CART models in comparison to other techniques like ANN with linear regression. In health science, Razi and Athappilly (2005) use linear regression, neural networks (NNs), and CART to forecast the number of days in bed due to illness. They find that NNs and CART provide better prediction accuracy than linear regression model². In finance, Zhu et al. (2011) propose a combination of CART and logistic regression for stock ranking. The work of Barth et al. (2023) implies that CART models are a good tool to investigate the annual relations between share price and accounting amounts (amount of accounting information).

Linear regression vs. Neural networks. As opposed to the class of linear regressions, neural networks can be classified as the multivariate nonlinear nonparametric models (White 1989; Zhang et al. 1998). Neural networks have some advantages compared to traditional

²Even though the authors mentioned that the regression model in their paper is nonlinear. They are in fact linear in parameters.

econometric methods. One of the advantages of neural networks over model-based methods like linear regression is that neural networks are data-driven methods which need very few assumptions about the model itself³. Since neural networks are not restricted by many assumptions they are more flexible than the model-based methods like linear regression. As a result, in many complicated problems in which we do not have good models, neural networks are feasible and promising ways for modeling as long as we have enough reliable data. Another advantage is that neural networks (and also many other machine learning techniques) have strong power of prediction. This is because, with a neural networks model, one usually splits data into two parts: train data and test data⁴. One uses train data to build the training machine learning models (e.g. neural networks, CART, and linear regression), then validating this model with unseen test data. By the nature that neural networks always work with unseen data, they are attractive and promising for forecasting tasks (Sharda and Patil 1992; Swanson and White 1995; Adya and Collopy 1998; Huang et al. 2007) and management science (Sharda 1994). Further, neural networks perform well with high noise data (Marquez et al. 1991).

The prediction ability of neural networks has improved recently relative to traditional methods like linear regression. Early forecasting studies observe that traditional methods including linear regression or vector autoregressions perform better (lower mean squared errors) than neural networks (e.g. Swanson and White 1995, 1997) or equivalent to and sometimes better than neural networks (e.g. Hill et al. 1994). Moreover, these studies also argue that neural networks appear to be promising models for forecasting even though further refinement of neural networks is needed. However, more recent studies in the literature find that neural networks outperform linear regression models in prediction (e.g. Hill et al. 1996; Desai and Bharati 1998; Fadlalla and Lin 2001; Anyaeche and Ighravwe 2013; Pombeiro et al. 2017). Li and Ma (2010) discover that neural networks are valuable tools for forecasting in financial economics due to the learning, generalization, and nonlinear behavior properties. Anyaeche and Ighravwe (2013), in a study of profitability forecasting, find that neural networks have MSE lower than multiple-linear regression model. Further, Pombeiro et al. (2017) find that neural networks models (together with fuzzy model) outperform linear regression in predicting electricity consumption. For a systematic review of neural networks in business in the last two decades, please read Tkac and Verner (2016).

A noticeable point of neural networks is that simply increasing the number of hidden layers may not improve the performance of the neural networks much when working with the high-frequency financial data (Chen et al. 2017).

³One typical assumption of neural networks is that the neural networks are *fully* connected. Of course, one can relax this assumption if necessary.

⁴In many cases, one splits data into three parts: train data, validation data, and test data. Also note that in the old days, economists did not call train data and test data. Rather, they call it in-sample and out-of-sample data (e.g. Swanson and White 1995, 1997; Altay and Satman 2005).

CART vs. Neural networks. Yildiz et al. (2017) employ several machine learning models including support vector regression (SVR), regression trees (RT or CART), artificial neural networks (ANNs), nonlinear autoregressive network with exogenous inputs (NARX), and Multivariate regression model (MLR) for commercial building electricity load forecasting. They find that ANNs and NARX relatively perform better than other techniques.

2.1.4 Lagged dependent variables in machine learning models

Lagged dependent variables have long been studied extensively in econometrics of regression in the forms of autocorrelation or serial correlation (e.g. Taylor and Wilson 1964; Durbin 1970; Godfrey 1978; Inder 1984; Arellano and Bond 1991). They play important roles in regression in economics and other social sciences. For example, Wilkins (2018) argues that including the additional lagged dependent variables leads to more accurate parameter estimates in regression. Moreover, Keele and Kelly (2006) find that adding lagged dependent variables remains an appropriate model used to estimate dynamic phenomena. In the case of adding different orders of lagged variables into regression models we need to pay attention to the multicollinearity issues among lagged variables.

Lagged dependent variables are not only examined in regression but also in the CART models. Gocheva-Ilieva et al. (2019) employ both lagged dependent and independent variables in the CART models. They find that the first-order of lagged dependent variables are the most relatively important variables in two towns in Bulgaria. Ou et al. (2017) use many lagged features in CART as well as other techniques to forecast traffic flow in urban roads in Kunshan City, China.

Lagged dependent (and independent) variables are also studied widely in many neural network models. Doganis et al. (2006) find that ANN models with lagged variables of sales are better than traditional methods in forecasting such as linear regression or moving average model. Swanson and White (1995) use both lagged dependent and lagged independent variables in linear regression as well as ANN to predict future spot rates. Tsoumakas (2019) surveys a number of previous studies in many machine learning models (moving average, radial basis function network, ensemble approach, long short-term memory, and deep neural networks) for food sales prediction in which lagged variables play very important roles.

2.1.5 Firm performance indicators

This study investigates four common measures of firm performance in the business literature which are return on assets (ROA), earnings before interest and taxes on assets (EBITAT)⁵, Tobin’s Q ratio, and sales growth. Here, ROA and EBITAT represent firm

⁵Note that in this study I use EBITAT for in-text sentences. The corresponding lower word, *ebitat*, is used as a variable. Similarly for ROA and *roa*.

profitability, Tobin's Q represents the investment opportunity, and sales growth is an indicator representing the efficiency of firm operations.

Return on assets (ROA). ROA is a measure that represents the profitability (or efficiency) of a firm in relation to its total assets. Specifically, return on assets is calculated by dividing a firm's net income by its total assets as follows

$$\text{ROA} = \frac{\text{Net income}}{\text{Total assets}}, \quad (2.1)$$

where

$$\text{Net income} = \text{Total revenue} - \text{Total expenses}.$$

Therefore, we can say that ROA measures the profitability or efficiency of a firm. The higher ROA, the more efficient assets are and vice versa. Note that net income and total assets are normally measured in the same period of time.

Earnings before interest and taxes on assets (EBITAT). EBITAT is another indicator of a firm's profitability. It is the ratio of earnings before interest and taxes on assets (EBIT) to total assets⁶. To make it comparable with ROA, EBIT is divided by total assets to obtain the earnings before interest and taxes on total assets.

$$\text{EBITAT} = \frac{\text{Earnings before interest and taxes}}{\text{Total assets}}. \quad (2.2)$$

Similarly to (2.1), in (2.2) EBIT and total assets are measured in the same period of time.

Tobin's Q . Tobin's Q (or just Q for short) is an indicator as a proxy for investment opportunities. It was first studied by two macroeconomists: Nicholas Kaldor and James Tobin. Kaldor (1966) introduces the evaluation ratio v (or Kaldor's v) of the stock market in the following formula

$$\text{Kaldor's } v = \frac{\text{Firm's market value}}{\text{Replacement cost}},$$

where the replacement cost means the capital employed by the firms, which is normally approximately by the book value of total assets. It is named after the q theory of investment in Tobin (1969).

More recently, Lindenberg and Ross (1981) develop a procedure for calculating q ratio in which the numerator is not the market value of shares like in the Kaldor's v formula. Rather, the numerator should be the firm's total market value including the market value of

⁶The ratio of EBIT/total assets is a common measure of profitability in many previous studies (e.g. Margaritis and Psillaki 2010; Cornett et al. 2008; Yu et al. 2009).

a firm's debt, the market value of common stock, and the market value of preferred stock. The denominator, which measures the replacement cost, is more complicated to measure. Loosely speaking, the denominator can be approximated by the book value of the firm's total assets. Therefore, Tobin's Q is defined as the ratio of the market value of a firm's equity and liabilities to its corresponding book values, i.e.

$$\begin{aligned}\text{Tobin's } Q &= \frac{\text{Equity market value} + \text{Liabilities market value}}{\text{Equity book value} + \text{Liabilities book value}} \\ &= \frac{\text{Equity market value} + \text{Liabilities market value}}{\text{Total assets}},\end{aligned}$$

where $\text{Total assets} = \text{Shareholders' equity} + \text{Liabilities} = \text{Equity market value} + \text{Liabilities book value}$ in which the first equality is the basic relation in accounting.

In this study, I denote Q as Tobin's Q and estimate it by the similar formula as that in [Smirlock et al. \(1984\)](#) given by

$$Q = \frac{\text{Equity market value} + \text{Total preferred stock} + \text{Total long-term debt} + \text{Total debt in current liabilities}}{\text{Total assets}}. \quad (2.3)$$

Sales growth. Sales growth (or revenue growth) is one of the most common measures of firm performance. There are many previous studies that use revenue growth (i.e. sale growth) as an indicator of firm performance (e.g. [Thornhill 2006](#); [Mithas et al. 2012](#); [Mironov 2013](#)).

$$\text{Sales growth}(t) = \frac{\text{Sales}(t+1) - \text{Sales}(t)}{\text{Sales}(t)}. \quad (2.4)$$

The remainder of this chapter is organized as follows. Section [2.2](#) presents the methods that we use in this chapter. Section [2.3](#) describes the data and variables. The results of different models are presented in Section [2.4](#). We discuss several noticeable points in Section [2.5](#) before concluding chapter in Section [2.6](#).

2.2 The methods

As famous statistician Leo Breiman suggested in his 2001 paper that “we need to move away from exclusive dependence on data models and adopt a more diverse set of tools” ([Breiman 2001](#)), this study employ three different types of machine learning techniques representing for three different statistical methods including classical parametric method (linear regression), non-parametric method (CART), and flexible nonlinear models (neural networks).

2.2.1 Linear regression

The specification of the first linear regression model is given by

$$y_{ijkt} = \beta_0 + \beta_l \mathbf{X}_{lit} + \beta_e \mathbf{X}_{eit} + \beta_m \mathbf{X}_t + \beta_1 \text{disaster}_{jt} + \beta_2 \text{disaster}_{j,t+1} + \beta_3 \text{disaster10K}_{it} + \nu_j + \varphi_k + \xi_t + \epsilon_{ijkt},$$

where

- y_{ijkt} is a specific firm performance indicator for firm i in state j in industry k in year t ,
- \mathbf{X}_{lit} is the list of m state controls of firm i at year t , where $2 \leq l \leq m$,
- \mathbf{X}_{eit} is the list of $n - m$ action controls of firm i at year t , where $m + 1 \leq e \leq n$,
- \mathbf{X}_t are the Herfindahl-Hirschman index and macroeconomic controls in year t ,
- disaster_{jt} and $\text{disaster}_{j,t+1}$ are the damages of natural disasters/hazards in state j at year t and year $t + 1$,
- disaster10K_{it} is the firm i 's reporting natural disasters in Form 10K in year t ,
- ν_j is the state fixed effects, where $j = 1, \dots, 49$ represents for forty nine states,
- φ_k is the industry fixed effects, where $k = 1, 2, \dots, 61$ (historical SIC classification),
- ξ_t is the year fixed effects, where $t = 1994, \dots, 2021$,
- ϵ_{ijt} is the error term.

Note that the above year fixed effects ξ_t excluded one base year (year_2003) to avoid the perfect multicollinearity issue. Similarly, the industry fixed effects φ_k and state fixed effects ν_j already excluded one industry (sich2d_59) and one state (WY) to avoid perfect multicollinearity problem. Note also that the year fixed effects, industry fixed effects, and state fixed effects allow to eliminate bias from unobservables that change over states and industries but constant over time, bias from unobservables that change over time and state but constant over industries, and bias from unobservables that change over time and industries but constant over states.

The second linear regression specification is given by

$$y_{ijkt} = \beta_0 + \beta_l \mathbf{X}_{lit} + \beta_e \mathbf{X}_{eit} + \beta_m \mathbf{X}_t + \beta_1 \text{damage}_{jt} + \beta_2 \text{damage}_{j,t+1} + \beta_3 \text{disaster10K}_{it} + \nu_j + \varphi_k + \xi_t + \epsilon_{ijkt},$$

where ξ_t is the year fixed effects, where $t = 1997, \dots, 2021$. Note that for natural hazards we only have data from 1996 to 2021 instead of from 1993 to 2021 as that of the billion-dollar natural disasters.

2.2.2 Classification and regression trees

Classification and regression trees (also known as decision trees or CART) are a non-parametric supervised machine learning method for classification and regression tasks. It was first introduced by [Breiman et al. \(1984\)](#). Since the predicted outcomes in this study are continuous, we will focus on regression trees. Potential applications of CART in economics are discussed intensively in [Athey and Imbens \(2019\)](#).

It is necessary to give a quick overview of the empirical CART models⁷. Given a sample of training data $(X_{i1}^t, \dots, X_{iK}^t, Y_i)$, for $i = 1, \dots, N$ and $t = 1, \dots, T$, where K is the number of features and t denotes time at the period t . Here, at one time, only one predicted outcome Y_i is considered. The idea of regression trees is to split sequentially the sample of training data into subsamples, then using regression method to estimate the average predicted outcome in each subsample. Each split is only based on a threshold criterion of one feature.

Before the split, the empirical sum of squared errors of the training data is given by

$$Q = \sum_{i=1}^N (Y_i^t - \bar{Y}^t)^2, \quad \text{where} \quad \bar{Y}^t = \frac{1}{N} \sum_{i=1}^N Y_i^t.$$

Starting with the full training data sample, at each internal node, split the sample into two subsamples based on one single feature X_{ik} and a threshold criterion c_j , where $j = 1, \dots, J$. The goal of the split is to minimize the empirical sum of squared errors of two training subsamples after splitting

$$\min \quad Q(k, c_j) = \sum_{i: X_{ik}^t \leq c_j} (Y_i^t - \bar{Y}_{k, c_j, l}^t)^2 + \sum_{i: X_{ik}^t > c_j} (Y_i^t - \bar{Y}_{k, c_j, r}^t)^2$$

where

$$\bar{Y}_{k, c_j, l}^t = \frac{\sum_{i: X_{ik}^t \leq c_j} Y_i^t}{\sum_{i: X_{ik}^t \leq c_j} 1} \quad \text{and} \quad \bar{Y}_{k, c_j, r}^t = \frac{\sum_{i: X_{ik}^t > c_j} Y_i^t}{\sum_{i: X_{ik}^t > c_j} 1}$$

are the average predicted outcomes in the two subsamples and l and r denote left and right, respectively. Note that the split point is the internal node such that the above sum of squared is minimum among all possible sums of squared errors. Repeat until the stopping criterion is reached. The common stopping criterion is the minimum number of training

⁷A similar framework can be found in [Athey and Imbens \(2019\)](#).

observations (or *sample* as a common word used in the machine learning language) at each leaf node.

The key feature importance metric for CART is the weighted impurity reduction (or mean decrease in impurity or variance reduction). Note that in the tree, a node will be split if this split induces a decrease of impurity greater than or equal to this impurity value. The weighted impurity decrease (or variance decrease) formula is given as follows

$$\text{weighted impurity decrease} = \frac{N_t}{N}(\text{impurity} - \frac{N_{tR}}{N_t} * \text{right_impurity} - \frac{N_{tL}}{N_t} * \text{left_impurity}),$$

where N is the total number of samples, N_t is the number of samples at the current node, N_{tL} and N_{tR} are the number of samples in the left and right child, respectively⁸. Note that the CART model in this study contains *only one* decision tree. This is in contrast to other several ensemble learning methods like XGBoost (Extreme Gradient Boosting), AdaBoost (Adaptive Boosting), or Random Forest which use several different trees.

2.2.3 Neural networks

This study employs neural networks with a single hidden layer called artificial neural network (ANN) and neural networks with two or more hidden layers called deep neural networks (DNN)⁹. Specifically, an ANN is a network with one input layer, one hidden layer, and one output layer¹⁰. As we will see, the only difference between ANN and DNNs is the number of hidden layers. In this study, the word “deep” in deep neural networks stands for many (at least two) hidden layers.

Deep neural networks (DNNs) are a class of neural networks that compose two or more hidden layers. Inspired by the notations used in [Amasyali and El-Gohary \(2021\)](#), in this study, DNN[2], DNN[3], and DNN[4] are defined as the DNN model with two, three, and four hidden layers, respectively. Assume that all DNN models are fully connected neural networks. In all DNN models, Rectified Linear Unit (ReLU) is used as the activation function. Note that by the Universal Approximation Theorem, any complex continuous functions can be approximated by neural networks.

The goal of learning in DNNs is to adjust the set of weights so that the performances of the networks are as good as possible (e.g. as small mean squared error as possible). In order to do that we need to adjust a list of parameters such as number of hidden layers,

⁸For more details, please see <https://scikit-learn.org/stable/modules/generated/sklearn.ensemble.RandomForestRegressor.html>.

⁹Note that this classification is just with the naming purpose. In reality, ANN and DNN might be used interchangeably.

¹⁰This definition is similar to that in [Amasyali and El-Gohary \(2021\)](#). Meanwhile, other studies might define that ANNs are neural networks with one or two hidden layers and DNNs are neural networks with more than two hidden layers (e.g. [Merkel et al. 2018](#)).

number of neurons in each layer, optimizer, batch size, number of epochs, initialization (using random seed), and dropout rate. They are normally called hyperparameters, which are the parameters of weights (or coefficients).

Note that in contrast with the linear regression models, CART and neural networks are nonlinear models. This implies that CART and neural networks can capture the nonlinear relationships and heterogeneous effects among features which are usually ignored in the linear models. However, some costs of using neural networks are computational intensity, losing the level of interpretability, curse of dimensionality, and overfitting problems.

2.2.4 Comparison among models

Meanwhile there are many studies that compare linear regression, CART, and neural networks in other fields ([Razi and Athappilly 2005](#); [Kim 2008](#); [Wang et al. 2016](#)), there are much less studies comparing models using these techniques in the literature of business, management, and finance. In the business, management, and finance literature, [Bensic et al. \(2005\)](#) studies small business credit scoring using neural networks, decision trees, and logistic regression rather than linear regression. Also, [Schumacher et al. \(2010\)](#) predict success of actuarial students using neural networks, classification trees, and logistic regression rather than regression trees and linear regression. It seems there are no studies in the literature of business, management, and finance using linear regression, CART (decision trees), and neural networks at the same time. Further, even though there might exist some studies using these three comparative techniques, it is unlikely that these studies focus on firm performance prediction. This is a big gap in the literature of business, management, accounting, and finance and this study aims to partially fulfill this gap.

2.3 The data and variables

2.3.1 Data sources

The datasets and corresponding sources used in this research are shown in Table [2.2](#). All data are annual and they are collected from 1993 and 2021 except for the U.S. natural hazard data that is collected between 1996 and 2021. The firm’s characteristics are collected from the Compustat-Capital IQ (or just Compustat for short) database from the Wharton Research Data Services (WRDS). Macroeconomic variables are collected from the World Bank’s website. The costs of natural disasters are collected from the National Oceanic and Atmospheric Administration (NOAA)’s billion-dollar weather and climate disasters database. Form-10Ks are collected from the Electronic Data Gathering, Analysis, and Retrieval system (EDGAR) from the U.S. Securities and Exchange Commission (SEC).

Table 2.2: The data and corresponding sources

Data	Frequency	Period	Source
Firm’s characteristics	Annually	1993-2021	Compustat
Macroeconomic variables	Annually	1993-2021	The World Bank
Natural hazards	Annually	1996-2021	NOAA
Billion-dollar natural disasters	Annually	1993-2021	NOAA
Form 10-Ks (reporting)	Annually	1993-2021	EDGAR filings

Regarding the U.S. billion-dollar natural disasters, there are 287 billion-dollar natural disaster events (e.g. floods, tropical cyclones, droughts) that occurred between 1993 and 2021 in the United States. This is equivalent to, on average, 8.44 billion-dollar natural disaster events per year. The number of events at the state level is clearly less than 8.44 since not all events occur in all states, which makes billion-dollar disasters as rare events in the U.S. at the state level.

U.S. natural hazards vs. U.S. billion-dollar natural disasters. The U.S natural hazards data (officially the U.S. Natural Hazard Statistics¹¹) provides the statistical information on damages caused by weather related hazards. There are some important differences between the U.S. natural hazards data and the U.S. billion-dollar natural disasters. First, the natural hazard data include all hazardous weather events either big or small weather phenomena. In contrast, the U.S. billion-dollar natural disasters only covers the major weather and climate disasters in the U.S. Second, the U.S. natural hazardous damages are the *real* values obtained or estimated from each event while the U.S. billion-dollar disasters are the *interval* estimates. Those interval estimates are averaged to get a unique value of damage of each natural disaster. Third, it seems that the damages of the U.S. natural hazardous events are the estimated *direct* damages while that of the U.S. billion-dollar natural disasters are the *total* (direct and relevant indirect) damages of natural disasters. Moreover, the average damages of the U.S. natural hazard is approximately \$1.008 billion per year while that of the U.S. billion-dollar natural disasters is around \$2.8538 billion per year. Table 2.3 summarizes the comparison between the U.S. natural hazards and the U.S. billion-dollar natural disasters.

¹¹See <https://www.weather.gov/hazstat/>

Table 2.3: Comparison between U.S. natural hazards and billion-dollar natural disasters

	Natural hazards	Natural disasters
Size of disasters	Small & big	Big (billion-dollar events)
Types of costs	Direct	Direct & Indirect
Values of estimates	Unique real number	Interval
CPI adjustment to 2021	Yes	Yes
Average damages per year	\$1.008 billion	\$2.8538 billion

This study takes inflation (i.e Consumer Price Index or CPI) into account. The U.S. billion-dollar natural disasters are adjusted to CPI in 2021. However, the damages of the U.S. natural hazards are measured every year. To make sure these two damages are comparable, we adjust the damages of the U.S. natural hazards to CPI in 2021. That is, both damages of the U.S. natural hazards and billion-dollar natural disasters are adjusted to CPI in 2021. By taking CPI into account, we reduce the possibility of the endogeneity issue regarding the changes of the values of damages of natural hazards and disasters over time.

2.3.2 The variables

Dependent variables

The dependent variables and the corresponding definitions are shown in Table 2.4. Note that in this table t stands for the current year and $t + 1$ stands for the next year.

Table 2.4: The list of dependent variables

Variable	Definition
roa	Net income($t+1$)/Total assets($t+1$)
ebitat	Income before interest and taxes($t+1$)/Total assets($t+1$)
Q	(Equity market value($t+1$) + Total preferred stock($t+1$) + Total long-term debt($t+1$) + Total debt in current liabilities ($t+1$))/Total assets($t+1$)
salegrowth	(Sales($t+1$) - Sales(t)) / Sales(t)

Since all of the firm-level state independent variables are at time t and all dependent variables are at time $t + 1$, this is a prediction problem. Specifically, this is a short-term prediction problem since data this year is used to predict the next year firm performance.

Independent variables

In order to investigate the relationships between uncertainty variables and firm performance, various control variables, including firm-wide state and action variables, industry-wide variable, and macroeconomic variables, are utilized. These controls are generated based on

the literature on bankruptcy, firm performance, and accounting, specifically many variables are borrowed from [Mai et al. \(2019\)](#). When predicting firm performance, it is natural to consider variables at the firm-wide, industry-wide, and the economy-wide variables. The firm-level variables are split into two groups: firm-wide state independent variables and firm-wide action independent variables. Here the word “action” implies that firms can adjust these variables to obtain the desired firm performance indicators next year based on the current performance and the effects of natural disasters this year. The definitions of these controls are described in detail in the following tables.

Firm-wide state independent variables. Table 2.5 shows the list of firm-wide state independent variables (features). Most of variables in this list are the ratio variables with the denominator is total assets or sales. One important advantage of the ratio variables with total assets as denominator is that it helps to deal with the so-called *asset inflation*. As a result, the ratio variables might help dealing with the *endogeneity* problem because of the increase of the values of (total) assets over time. The similar argument might make sense when the denominator is sales.

Table 2.5: The list of firm-wide state independent variables

Variable	Definition
roalag1	Prior year ROA
ebitatlag1	Prior year EBITAT
qlag1	Prior year Q
salegrowthlag1	Prior year sales growth
lctat	Current liabilities(t)/Total assets(t)
chlct	Cash(t)/Current liabilities(t)
lctlct	Current liabilities(t)/Total liabilities(t)
relct	Retained earnings(t)/Current liabilities(t)
atemp	Total assets(t)/Employees(t)
logat	Ln(Total assets(t))
cheat	Cash and short-term investment(t)/Total assets(t-1)
saleat	Sales(t)/Total assets(t-1)
reat	Return earnings(t)/Total assets(t-1)
dtat	Total debt including current(t)/Total assets(t-1)
seqat	Total stockholders' equity(t)/Total asset(t-1)
invtsale	Inventories(t)/Sales(t-1)
xintsale	Total interest and related expense(t)/Sales(t-1)
invtgrowth	(Inventories(t) – Inventories(t-1))/Inventories(t-1)

Notes: This table includes four blocks of variables: lagged, ratio, and normalized variables. First block contains four lagged dependent variables. Second block contains the next five ratio variables. Third block only contains the logarithm of total assets. The last block contains nine state variables, which are normalized either by last year total assets or last year sales. Normalization by last year total assets or sales is necessary to avoid the endogeneity problem.

Firm-wide action independent variables. A list of firm-wide action independent variables used in this study is shown in Table 2.6.

Table 2.6: The list of firm-wide action independent variables

Variable	Definition
xintgrowth	$(\text{Total Interest and Related Expense}(t+1) - \text{Total Interest and Related Expense}(t)) / \text{Total Interest and Related Expense}(t)$
capxgrowth	$(\text{Capital expense}(t+1) - \text{Capital expense}(t)) / \text{Capital expense}(t)$
empgrowth	$(\text{Employees}(t+1) - \text{Employees}(t)) / \text{Employees}(t)$
dvcib	Dividends common, ordinary($t+1$)/Income before extraordinary items($t+1$)

Note: These variables are called *action* variables since firms can observe the effects of natural disasters on their performance to adjust these actions (or controls) to achieve their goals.

Herfindahl-Hirschman Index and macroeconomic variables. The Herfindahl-Hirschman Index (or Herfindahl index or industrial concentration index) is considered as a measure for industrial concentration. This index is calculated by the sum of square of market shares of all firms within a particular 3-digit SIC industry in a particular year¹². Macroeconomic variables, including GDP growth, inflation, and real interest rate, can be found from the World Bank’s database¹³ and the Bureau of Economic Analysis (BEA) database¹⁴, and the Federal Reserve Economic Data (FRED) database¹⁵. The Herfindahl index and three macroeconomic variables used in this study are shown in Table 2.7.

Table 2.7: The list of exogenous variables

Variable	Definition	Source
hhi	Industrial concentration(t)	Calculated by author
gdpgrowth	GDP growth, annual %(t)	World Bank, BEA
inflation	Inflation, annual %(t)	World Bank
interestrate	Real interest rate, annual %(t)	World Bank, FRED

Notes: The Herfindahl index is calculated based on the data of sales and 3-digit historical Standard Industrial Classification (or SIC) from the Compustat database with four steps. Step 1: Calculate the “total sales” of all firms within a 3-digit SIC industry in every year; Step 2: Calculate the market share for each firm within this 3-digit SIC industry in every year; Step 3: Square every market share; Step 4: Sum of all of the squares by 3-digit SIC industry in every year to obtain the Herfindahl index. Moreover, at the time we accessed, 06/06/2022, the World Bank database, the U.S. GDP growth in 2021 is not available. Therefore, we used data of U.S GDP growth in 2021 from the Bureau of Economic Analysis. Similarly, since U.S. real interest rate in 2021 is not available on 06/06/2022 in the World Bank database, we used the average of all monthly U.S. real interest rates from the Federal Reserve Economic Data (FRED) database as the U.S. real interest rate in 2021.

¹²For more details about 3-digit SIC industry classification, see <https://siccode.com/>.

¹³See <https://data.worldbank.org/country/united-states?view=chart>

¹⁴See <https://www.bea.gov/news/2022/gross-domestic-product-fourth-quarter-and-year-2021-advance-estimate>

¹⁵See <https://fred.stlouisfed.org/series/REAINTRATREARAT1YE>

Variables of interest and sources. Table 2.8 shows the list of all variables of interest, the data type, definition, and the data sources. Note that in this table, the damages of natural disasters in the last year (or year t) are denoted as **disaster** and the damages of natural disasters in the current year (or year $t + 1$) are denoted as **disaster0**. Similarly for **damage** and **damage0** for the case of natural hazards. There is only one perceived natural disaster risk for both natural hazards and natural disasters, which is denoted as **disaster10K**.

Table 2.8: The list of variables of interest

Variable	Type	Definition	Source
disaster	Government-reported	Damages of natural disasters(t)	NOAA database
disaster0	Government-reported	Damages of natural disasters($t+1$)	NOAA database
damage	Government-reported	Damages of natural hazards (t)	NOAA database
damage0	Government-reported	Damages of natural hazards($t+1$)	NOAA database
disaster10K	Firms' self-reported	Reporting disaster(t)	Form 10-Ks

Notes: Note that there are two variables related to the damages of natural billion-dollar disasters and two corresponding for natural hazards. However, for each linear regression specification, we only consider these two kinds of damages in two separate cases. For more details, see Subsection 2.2.1.

2.3.3 Data collection procedure

Table 2.9 describes the steps to collect data (the number of firms and firm-year observations). At the beginning (Step 1), there are 29,908 firms and 315,051 firm-year observations. Note that at Step 1 not all observations are firm-based observations. The reason is that many stock ticker symbols are bonds or exchange-traded funds (ETFs). The following steps will remove these non-firm stocks.

The raw data from Step 1 contains so many rows with missing values in most of the columns. These rows should be deleted. Step 2 removes all rows with missing values in more than 75% of the columns. Many of them might be bonds and ETFs since they are not firm-based stocks, then there are not common financial statement variables such as number of employees, sales, total assets, and so on. After Step 2, there are 23,950 firms and 247,477 firm-year observations. At Step 3, the data getting from Step 2 is merged with the actual damages of natural disasters and reporting disasters data.

Step 4 and Step 5-8 help to exclude the non-firm stocks. In total, our final sample size includes 10,575 firms and 97,761 firm-year observations with no missing values. Table 2.9 shows the procedure to get the final sample size as well as all number of firms and firm-year observations at each step. Note that the sample size excludes the firms in the utility, finance, insurance, and real estate sector (Step 5) since these firms typically have the capital structures and other characteristics different compared to manufacturing and other sectors.

Table 2.9: The data collection procedure

Step	Observations	Number of firms
1. Total U.S. firms from Compustat database	315,051	29,908
2. Firms with data in at least 75% columns	247,477	23,950
3. U.S. firms with state and disasters data	141,229	16,601
4. U.S. firms with SIC, CUSIP, and GVKEY number	139,968	16,452
5. Exclude U.S. utilities, financial, insurance, real estate firms	113,009	13,689
6. U.S. firms with total assets at least \$0.1 million	111,361	13,569
7. U.S. firms with positive sales	107,019	13,074
8. U.S. firms with at least 1 employee	103,401	12,776
9. Sample after handling missing values	97,761	10,575
Final sample size	97,761	10,575

The approximate number of firms by sector and the corresponding proportions are shown in Table 2.10. It is apparent that most of the firms in our sample are manufacturing (45.72%) and services (27.02%). These proportions seem representative for all public firms. Note that the number of firms in Table 2.10 and that in Table 2.9 are close to each other with 11,373 and 97,761, respectively, but not the same. The reason is because a number of firms belong to two or more sectors. For example, some firms are classified to the whole trade sector but they are also classified to the retail trade sector because they do both wholesale and retail trading.

Table 2.10: Number of firms and proportions by sector

Sector	Number of firms	Proportion (%)
Agriculture, Forestry, Fishing	21	0.18
Mining	586	5.15
Construction	172	1.51
Manufacturing	5,200	45.72
Transportation	951	8.36
Wholesale Trade	545	4.79
Retail Trade	827	7.27
Services	3,071	27.02
Total	11,373	100

2.3.4 Constructing a natural disaster dictionary

In order to capture the intensity of the natural disasters to accurately reflect the perceived natural disaster risk we need the following assumption.

Assumption 2.3.1. *People (i.e. firms) are likely to discuss the big natural disasters more often than the relatively smaller ones in their Form 10-Ks.*

This assumption is necessary to examine the different intensities of different natural disasters. Without this assumption, the perceived natural disaster risk might be biased. For example, a Form 10-K of a company mentions both Hurricane Katrina in 2005 (one of the most powerful hurricane in the U.S. in the history) and Hurricane Iniki (the most powerful hurricanes striking Hawaii in recorded history) in 1992. Obviously, these two hurricanes have different intensities. Separately, one word related to Hurricane Katrina is not equivalent to one word related to Hurricane Iniki (in the sense that these hurricanes were damaged differently). By Assumption 2.3.1, on average, firms tend to talk about Hurricane Katrina more than Hurricane Iniki. This obviously makes sense in the real world. Note that this assumption can be applied to not only the same types of natural disasters but also the different ones (e.g hurricanes in Louisiana vs. wildfires in California).

Table 2.11 shows the natural disaster dictionary including 133 words or phrases related to natural disasters in alphabetical order. This dictionary is generated based on the words related to natural disasters from the National Oceanic and Atmospheric Administration (NOAA) website¹⁶, the Emergency Events Database (EM-DAT) glossary on natural disasters¹⁷, Oxford's English dictionaries from Oxford Languages¹⁸, and the well-known Merriam-Webster dictionary¹⁹.

¹⁶<https://www.ncei.noaa.gov/access/billions/events>

¹⁷<https://www.emdat.be/Glossary>

¹⁸<https://languages.oup.com/google-dictionary-en/>

¹⁹<https://www.merriam-webster.com/>

Table 2.11: The natural disaster dictionary

adaptive capacity	droughts	heat wave	seiches
air burst	earthquake	heat waves	severe winter condition
airburst	earthquakes	heavy rainfall	severe winter conditions
airbursts	El Nino	heavy snow	snow
apocalypse	extreme heat	high wind	snowstorm
apocalypses	extreme rain	high winds	snowstorms
ash fall	extreme rainfall	hurricane	storm
ashfall	extreme rains	hurricanes	storms
avalanche	extreme temperature	hydrological hazard	thunderstorm
avalanches	extreme temperatures	hydrological hazards	thunderstorms
blizzard	extreme weather	La Nina	tornado
blizzards	firestorm	landfall	tornadoes
calamity	firestorms	landfalls	tremor
camillities	flood	landslide	tsunami
cataclysm	flooded	landslides	tsunamis
cataclysms	flooding	lava flow	twister
climate change	floodings	lava flows	typhoon
climate warms	floods	microburst	typhoons
coastal erosion	fog	microbursts	volcanic
cold wave	fogs	mudslide	volcano
cold waves	forest fire	mudslides	volcanos
coping capacity	forest fires	natural hazard	whirlpool
cyclone	freeze	natural hazards	whirlpools
cyclones	freezes	rainfall	wildfire
debacle	freezing	rainfalls	wildfires
debacles	gale	rainstorm	wind
derecho	gales	rainstorms	winds
derechos	geophysical hazard	rock fall	windstorm
disaster	geophysical hazards	rock-fall	windstorms
disaster risk	global warming	rockfall	winterstorm
disaster risk management	hail	rockfalls	winterstorms
disaster risks	hailstorm	rogue wave	
disasters	hailstorms	rogue waves	
drought	hazard mitigation	seiche	

Notes: The words list related to natural disasters in this dictionary bases on several reliable sources including NOAA, EM-DAT glossary, Oxford Languages (Oxford's English dictionaries), and Merriam-Webster dictionary.

2.3.5 Using the natural disaster dictionary to explore Form 10-Ks

The natural disaster dictionary in Table 2.11 is used to count the number of words related to natural disasters in Form 10-Ks from 1993 to 2021. Note that our raw data includes 195,229 firm-year Form 10-Ks and 35,640 unique firms. That is, on average, each firm has approximately 5.48 Form 10-Ks.

Table 2.12 shows the most frequent words, number of firms mentioned that word, and number of word count. Two most frequent words related to natural disasters between 1993

and 2021 are *flood* (from 1996 to 2004) and *disasters* (in 2007 and from 2012 to 2021). The word *hurricanes* is the most frequent in 2005 and 2006, which might be caused by Hurricane Katrina in late August 2005. The word *earthquake* and *wind* are the most frequent words related natural disasters in several years.

Table 2.12: The most frequent words related to natural disasters in Form 10-Ks

Year	Most frequent word	Number of firms mentioned	Word count
1993	earthquake	114	373
1994	earthquake	110	359
1995	earthquake	262	798
1996	flood	620	1,432
1997	flood	688	1,796
1998	flood	689	1,623
1999	flood	650	1,436
2000	flood	695	1,560
2001	flood	636	1,465
2002	flood	931	2,220
2003	flood	967	2,144
2004	flood	1,177	2,390
2005	hurricanes	1,290	4,677
2006	hurricanes	1,341	4,470
2007	disasters	2,411	4,479
2008	wind	905	5,494
2009	wind	1,036	7,713
2010	wind	1,093	8,947
2011	wind	1,067	7,283
2012	disasters	3,208	7,298
2013	disasters	3,357	7,680
2014	disasters	3,481	8,178
2015	disasters	3,522	8,363
2016	disasters	3,523	8,484
2017	disasters	3,592	9,113
2018	disasters	3,677	9,533
2019	disasters	3,893	10,804
2020	disasters	4,193	12,209
2021	disasters	808	2,427

Table 2.13 describes the top ten topics related to natural disasters in Form 10-Ks. We can observe that the words or phrases belong to the topic of *natural disasters*, *wind*, and *flooding* are the most common in Form 10-Ks with the corresponding number of word count are 204,007 terms, 116,670 terms, and 112,338 terms. For the full list of the frequencies of all words/phrases related natural disasters in Forms 10-Ks, please see Appendix 5.

Table 2.13: Top 10 topics related to natural disasters in Form 10-Ks

Topic	Word/Phrase	Word count
natural disasters	disaster, disasters, natural hazard, natural hazards	204,007
wind	wind, winds, windstorm, windstorms, high wind, high winds	116,670
flooding	flood, floods, flooding, floodings, heavy rainfall, rainfalls, extreme rains, extreme rainfall, rainstorm, rainstorms	112,338
earthquake	earthquake, earthquakes	93,743
hurricanes	hurricane, hurricanes	81,314
storm	storm, storms, winterstorm	73,710
climate change	climate change, global warming, climate warms	67,725
freeze	freeze, freezes, freezing, snow, heavy snow, snowstorm, snowstorms	51,873
drought	drought, droughts	19,194
tornado	tornado, tornadoes	16,365

2.3.6 Data processing

In order to obtain reliable input data, it is necessary to do the following steps. First of all, all variable (except fixed effects) are winsorized at the 1st and 99th percentiles²⁰. Next, the correlation matrix of all independent variables is generated. Thus, one of the two variables in pairs with correlations greater than 0.8 will be dropped. This step is repeated until obtaining all correlations less than 0.8. For the models with the billion-dollar natural disasters, the following table shows the top 20 correlations of the independent variables²¹.

²⁰These percentiles are common to handle outliers, e.g [Dessaint and Matray \(2017\)](#), [Mai et al. \(2019\)](#).

²¹The top 20 correlations of the models corresponding with the damages of the natural *hazards* are exactly the same that of natural *disasters* so we do not show it here.

Table 2.14: Top 20 absolute correlations of Model 1 and Model 2

Model 1 (ROA)			Model 2 (EBITAT)		
Variable 1	Variable 2	Correlation	Variable 1	Variable 2	Correlation
logoil	interestrate	0.732368	logoil	interestrate	0.732368
lctat	reat	0.687432	lctat	reat	0.687432
lctat	seqat	0.635743	reat	ebitatlag1	0.642279
reat	roalag1	0.621879	lctat	seqat	0.635743
lctat	roalag1	0.542714	cheat	chlct	0.541779
cheat	chlct	0.541779	reat	relct	0.534726
reat	relct	0.534726	lctat	ebitatlag1	0.529939
lctlct	logat	0.515386	lctlct	logat	0.515386
dtat	seqat	0.467097	logat	ebitatlag1	0.490036
reat	seqat	0.463247	dtat	seqat	0.467097
logat	roalag1	0.456176	reat	seqat	0.463247
logat	reat	0.427153	relct	ebitatlag1	0.428460
seqat	roalag1	0.414960	logat	reat	0.427153
gdpgrowth	inflation	0.395303	gdpgrowth	inflation	0.395303
logoil	gdpgrowth	0.393173	logoil	gdpgrowth	0.393173
lctlct	dtat	0.389953	lctlct	dtat	0.389953
xintsale	roalag1	0.388670	xintsale	ebitatlag1	0.385681
relct	roalag1	0.383257	seqat	ebitatlag1	0.384161
reat	xintsale	0.381331	reat	xintsale	0.381331
logat	relct	0.377250	logat	relct	0.377250

Table 2.15: Top 20 absolute correlations of Model 3 and Model 4

Model 3 (Tobin's Q)			Model 4 (Sales growth)		
Variable 1	Variable 2	Correlation	Variable 1	Variable 2	Correlation
logoil	interestrate	0.732368	logoil	interestrate	0.732368
lctat	reat	0.687432	lctat	reat	0.687432
lctat	seqat	0.635743	lctat	seqat	0.635743
cheat	chlct	0.541779	cheat	chlct	0.541779
reat	relct	0.534726	reat	relct	0.534726
lctl	logat	0.515386	lctl	logat	0.515386
dtat	seqat	0.467097	dtat	seqat	0.467097
reat	seqat	0.463247	reat	seqat	0.463247
logat	reat	0.427153	logat	reat	0.427153
reat	Qlag1	0.425811	gdpgrowth	inflation	0.395303
gdpgrowth	inflation	0.395303	logoil	gdpgrowth	0.393173
logoil	gdpgrowth	0.393173	lctl	dtat	0.389953
lctl	dtat	0.389953	reat	xintsale	0.381331
reat	xintsale	0.381331	logat	relct	0.377250
logat	relct	0.377250	lctat	saleat	0.377027
lctat	saleat	0.377027	xintsale	salegrowthlag1	0.376152
cheat	relct	0.370620	cheat	relct	0.370620
lctat	logat	0.368511	lctat	logat	0.368511
lctat	xintsale	0.349713	lctat	xintsale	0.349713
gdpgrowth	interestrate	0.340178	gdpgrowth	interestrate	0.340178

VIF test. To eliminate severe multicollinearity problem, besides using correlation coefficient matrix, we do the Variance Inflation Factor (VIF) test by calculating $VIF_j = \frac{1}{1-R_j^2}$, where R_j^2 is the goodness of fit value obtained by regressing the j th variable on the remaining independent variables. Empirically, variables with VIF's values less than 8 are kept as shown in Table 2.51²².

²²The top VIF's values of the linear regression for the case of natural hazards are shown in Appendix 4.

Table 2.16: Top 20 VIF's values for linear regression models

Model 1	VIF	Model 2	VIF	Model 3	VIF	Model 4	VIF
inflation	7.017203	inflation	7.013184	lctlt	7.334174	inflation	6.998687
lctlt	6.916450	lctlt	6.922942	inflation	7.009825	lctlt	6.955896
logat	6.449909	logat	6.549338	logat	6.347809	logat	6.380665
lctat	6.235576	lctat	6.233981	lctat	6.120241	lctat	6.187584
interestrate	4.376896	interestrate	4.373795	seqat	4.406900	interestrate	4.379291
seqat	4.281882	seqat	4.277134	interestrate	4.374459	seqat	4.300491
reat	3.871019	reat	3.900545	gdpgrowth	3.834821	gdpgrowth	3.832852
gdpgrowth	3.833718	gdpgrowth	3.832756	reat	3.829549	reat	3.760325
saleat	3.639975	saleat	3.697453	saleat	3.607631	saleat	3.655896
cheat	3.240497	cheat	3.250151	cheat	3.242551	cheat	3.248636
hhi	2.661929	hhi	2.663623	hhi	2.661298	hhi	2.661279
relct	2.282047	relct	2.295641	dtat	2.258163	dtat	2.258033
dtat	2.257078	dtat	2.256507	relct	2.243393	relct	2.241613
chlct	2.186465	ebitatlag1	2.239404	chlct	2.197794	chlct	2.178986
roalag1	2.136983	chlct	2.187009	Qlag1	2.112606	disaster10K	1.685062
disaster10K	1.688482	disaster10K	1.691070	disaster10K	1.686413	invtsale	1.627244
invtsale	1.582029	invtsale	1.585414	invtsale	1.579723	atemp	1.560506
atemp	1.558577	atemp	1.558415	atemp	1.558741	xintsale	1.553171
xintsale	1.424234	xintsale	1.418182	xintsale	1.407173	salegrowthlag1	1.403611
capxgrowth	1.228371	capxgrowth	1.228950	capxgrowth	1.224616	capxgrowth	1.224616

2.3.7 Data transformation

Note that in this study we use two datasets: original data and transformed data. For the comparison between linear regression and CART, we use the original data. For comparison among linear regression, CART, and neural networks, we use the transformed data.

To compare among all models (linear regression, CART, and neural networks), the entire data (both train and test data) is scaled by min-max scaler. Consider a feature or target x with values $x_i, i = 1, 2, \dots, n$. The original values of x will be transformed as follows

$$x_{\text{scaled}} = \frac{x - x_{\min}}{x_{\max} - x_{\min}}, \quad (2.5)$$

where x_{\min} and x_{\max} is the minimum and the maximum of feature (or variable) x , respectively.

By using min-max scaler, all targets and features of both train and test data will be transformed into the range $[0, 1]$. This means that the minimum and maximum value of a feature or target is 0 and 1, respectively. In Python, one can use the `MinMaxScaler()` built-in function.

2.3.8 Exploratory data analysis

Exploratory data analysis (EDA) is a crucial step of performing initial investigations on data. Three common tools for EDA are summary statistics, histogram, and heat map.

Table 2.17 illustrates the summary statistics of all dependent and lagged dependent variables. Note that even though the mean ROA and EBITAT are negative, the median ROA and EBITAT are about 1.9% and 5.1%, respectively, which seem rational.

Table 2.17: Summary statistics of the dependent and lagged dependent variables

	roa	ebitat	Q	salegrowth	roalag1	ebitatlag1	Qlag1	salegrowthlag1
count	97761	97761	97761	97761	97761	97761	97761	97761
mean	-0.1597	-0.0885	2.3457	0.0487	-0.1664	-0.0927	2.2709	0.0494
std	0.6107	0.4922	3.3787	0.7767	0.6381	0.5093	3.2011	0.7812
min	-4.2418	-3.2768	0.3079	-0.8855	-4.4444	-3.4259	0.2866	-0.8855
25%	-0.1127	-0.0677	0.8721	-0.1840	-0.1153	-0.0694	0.8552	-0.1838
50%	0.0186	0.0515	1.3185	-0.0637	0.0193	0.0509	1.2901	-0.0637
75%	0.0652	0.1061	2.3400	0.0505	0.0666	0.1063	2.2770	0.0505
max	0.3100	0.3346	25.0567	5.8950	0.3232	0.3411	23.4122	5.9450

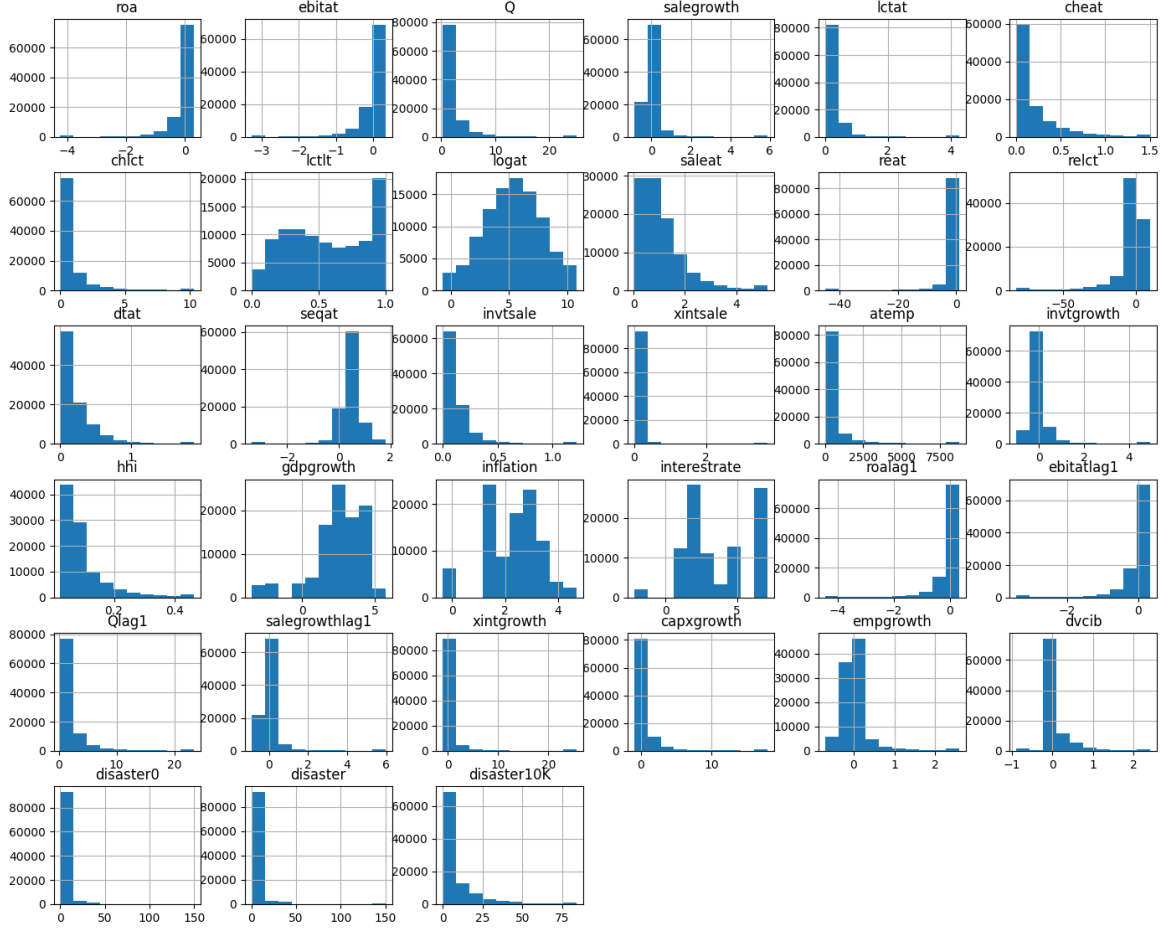
Table 2.18 shows the summary statistics of action independent variables and variables of interest (natural disasters).

Table 2.18: Summary statistics of action independent variables and variables of interest

	xintgrowth	capxgrowth	empgrowth	dvcib	disaster0	disaster	disaster10K
count	97761	97761	97761	97761	97761	97761	97761
mean	0.6231	0.6050	0.0257	0.1154	2.8538	2.7275	8.9035
std	3.1686	2.4821	0.4038	0.3731	11.1612	10.7287	14.5812
min	-1.0000	-0.9939	-0.7000	-0.8834	0.0000	0.0000	0.0000
25%	-0.2339	-0.3252	-0.1214	0.0000	0.0525	0.0525	0.0000
50%	0.0000	-0.0142	-0.0207	0.0000	0.3750	0.3750	3.0000
75%	0.2782	0.4742	0.0654	0.0177	1.5000	1.5000	11.0000
max	25.6000	17.9381	2.5854	2.4079	150.0000	150.0000	84.0000

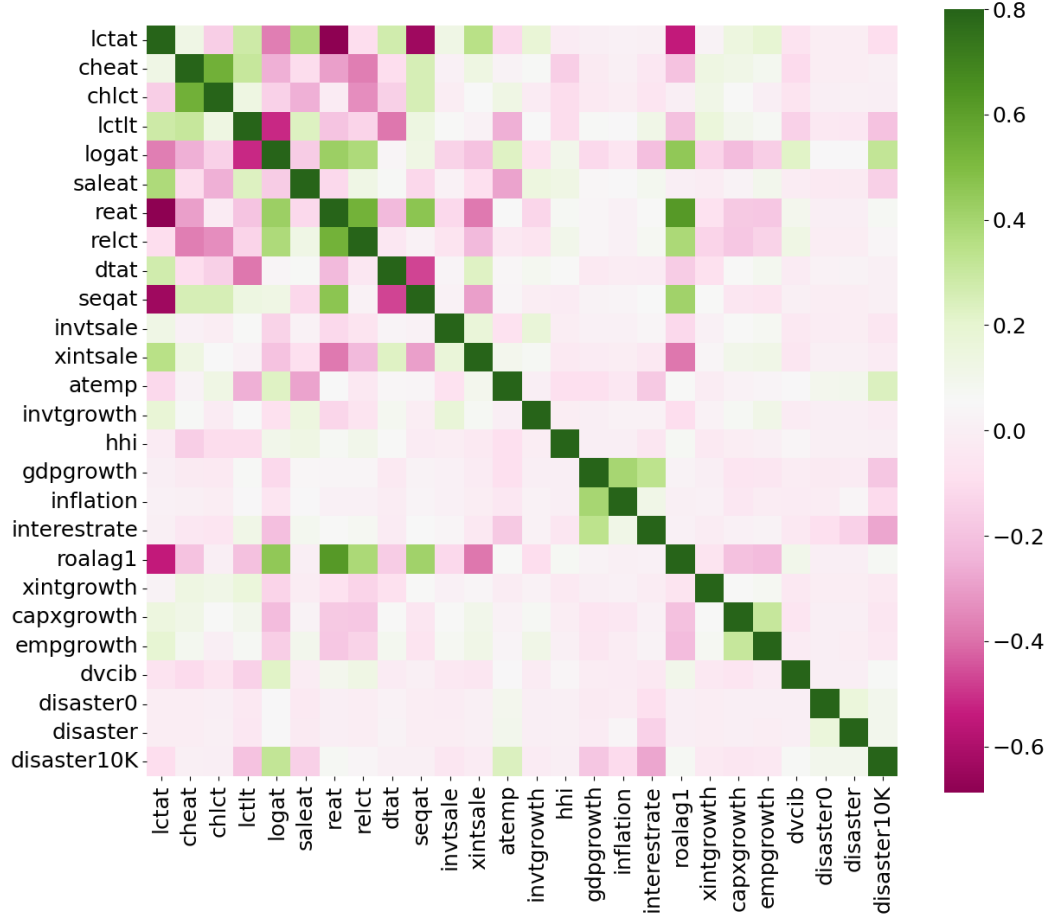
The histograms of all variables of the original data are shown in Figure 2.4.

Figure 2.4: The histograms of the original data



Heat map of original features. The heat map of all of the original features of the entire data (both train and test data) are shown in Figure 2.5. Heat map gives us a general image of the relationships among variables in terms of direction and magnitude. The green implies the positive relationship while the pink implies the negative relationship between a pair of two variables. Note that the bolder green cells represent the more positive correlation and the bolder pink cells imply the more negative correlation.

Figure 2.5: Heat map of the original features of Model 1 (ROA)



Notes: The figure shows that the correlation coefficient between any pair of variables is less than 0.8. This implies that there are no severe correlations among independent variables in Model 1. Note that, for the illustration purpose, only the heat map of Model 1 is shown in Figure 2.5. Other heat maps are shown in Appendix 3.

2.3.9 Train and test data

Data is split into train data (or in-sample data) and test data (or out-of-sample data). Train data is used to build and train models and unseen test data will be used to validate the models.

In order to quantify the effects of natural disasters on firm performance in the linear regression and CART model for the original data, we use the 50/50 split ratio in this study for two reasons. The reason is because, on average, the billion-dollar disasters are rare events at the state level and also at the firm level. Therefore, for the linear regression and CART models, we randomly split data into 50% of training data and 50% of test data to avoid the bias of splitting due to the nature of rare events (billion-dollar natural disasters).

In order to compare the performances among neural networks, CART, and the benchmark linear regression models using the scaled data, we use the most common split ratios in machine learning including 80/20, 90/10, and 50/50²³. Note that the 80/20 split ratio means that the entire data is split into 80% train data and 20% test data (hold-out sample), and similarly for other split ratios. In turn, the train data is split into 80% of training data and 20% of validation data for the 80/20 split, which yields 64% ($0.8 * 80\%$) training data, 16% ($0.2 * 80\%$) validation data, and 20% unseen test data. Similarly for other splits. Table 2.19 shows the proportions of training data, validation data, and test data for neural networks models.

Table 2.19: Training, validation, and test data for different splits

Split ratio	Training data	Validation data	Test data
80/20	64%	16%	20%
90/10	81%	9%	10%
50/50	25%	25%	50%

2.4 Results

The results in this paper are obtained from running data using Python version 3.7, Numpy version 1.19.5, and Tensorflow version 2.7.0.

2.4.1 The linear regression results

The effects of natural hazards and disasters on firm performance. We can observe from Table 2.20 that the observed damages of natural disasters are not associated with any firm performance criteria. However, the perceived natural disaster risk (i.e. `disaster10K`) are negatively associated with the firm’s profitability (ROA and EBITAT) at the 99% and 90% confidence level, respectively. Moreover, perceived natural disaster risk is not associated with Tobin’s Q and sales growth.

Let’s dive deeper into the meaning of the coefficients of the variables of interest. The coefficient of `disaster10K` for ROA equals to -0.0004 , which means that if Form 10-Ks include one more additional word related to natural disasters then ROA tends to decrease by 0.0004%. Linearly, we can say that if Form 10-Ks include 10 more additional words (which approximately equals the mean of `disaster10K`) related to natural disasters then ROA is likely to decrease by 0.004%. Also, if Form 10-Ks include 15 more additional words (which is approximately 1 standard deviation) related to natural disasters then ROA is likely to decrease by 0.006%. These results imply that the effects of perceived natural disasters on

²³Some previous studies also utilize these three split ratios of 50/50, 80/20, and 90/10, for example [Wilson and Sharda \(1994\)](#).

ROA is insignificant. Moreover, the effects of perceived natural disasters on EBITAT is two times smaller than that on ROA.

Table 2.20: Linear regression results

	roa	ebitat	Q	salegrowth
const	-0.2226***	-0.1496***	0.7068***	0.0278
lctat	-0.0929***	-0.0555***	0.4708***	0.1444***
cheat	-0.0533***	-0.0738***	0.7328***	0.0485***
chlct	-0.0024	-0.0028***	0.0295***	0.0129***
lctlt	-0.0198**	-0.0087	0.0124	-0.0133
saleat	0.0537***	0.0373***	-0.1842***	-0.0732***
logat	0.0307***	0.0233***	-0.0765***	-0.0111***
reat	0.0097***	0.0048***	-0.0234***	0.0066***
relct	0.0036***	0.0028***	-0.0016	-0.0047***
dtat	0.0121	0.0244***	0.0156	-0.0131
seqat	0.0805***	0.0596***	0.0140	0.0136
invtsale	-0.0116	-0.0108	0.1272*	0.1112***
xintsale	-0.0917***	-0.0600***	0.1430***	0.1845***
atemp	0.0000	-0.0000*	0.0000**	0.0000
invtgrowth	0.0065**	0.0032	-0.0298**	0.0033
hhi	0.0233	0.0205	-0.2553	0.0892
gdpgrowth	-0.0030	-0.0013	0.0051	-0.0059*
inflation	-0.0089	-0.0111	0.1078*	-0.0168
interestrate	0.0005	0.0004	0.0065	0.0038*
roalag1	0.4251***			
ebitatlag1		0.5423***		
Qlag1			0.6879***	
salegrowthlag1				0.0794***
xintgrowth	-0.0021***	0.0006	-0.0017	0.0131***
capxgrowth	-0.0100***	-0.0062***	-0.0355***	0.0176***
empgrowth	0.0478***	0.0452***	-0.5972***	0.6607***
dvcib	0.0147***	0.0108***	0.0512*	0.0110
disaster	-0.0002	-0.0002	-0.0015	-0.0003
disaster0	-0.0002	-0.0002	0.0007	-0.0002
disaster10K	-0.0004***	-0.0002*	-0.0003	0.0002
Year FE	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes
N	48881	48881	48881	48881
R ²	0.5587	0.6438	0.5716	0.2386

Notes: In this table, each column shows the coefficients and its levels of significance in the corresponding model. Here, *, **, and *** stand for p -value are less than 0.1, 0.05, and 0.01, respectively.

Natural hazards vs. Natural disasters. Table 2.21 compares the effects of the U.S. natural hazards and U.S. (billion-dollar) natural disasters together with the perceived natural disaster risk on firm performance. It can be seen that the effects of perceived natural disaster risk on firm profitability are the same in both cases. However, the effects

of government-reported damages of natural hazards on firm profitability are different with that of the billion-dollar natural disasters. Specifically, the damages of natural hazards are negatively associated with firm profitability while that of the billion-dollar natural disasters have no effects on firm profitability. Regarding Tobin's Q and sales growth, both the damages of natural hazards and that of the billion-dollar natural disasters have no effects on these criteria of firm performance.

Table 2.21: The effects of natural hazards vs. natural disasters on firm performance

	Natural hazards				Billion-dollar natural disasters			
	roa	ebitat	Q	salegrowth	roa	ebitat	Q	salegrowth
Controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
damage	-0.0012***	-0.0009***	0.0004	-0.0006				
damage0	-0.0001	-0.0004	-0.0023	0.0004				
disaster					-0.0002	-0.0002	-0.0015	-0.0003
disaster0					-0.0002	-0.0002	0.0007	-0.0002
disaster10K	-0.0004**	-0.0002*	-0.0007	0.0002	-0.0004***	-0.0002*	-0.0003	0.0002
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
N	46376	46376	46376	46376	48881	48881	48881	48881
R ²	0.5792	0.6567	0.5839	0.2347	0.5587	0.6438	0.5716	0.2386

Natural disasters vs. Perceived risk of natural disasters. We now run the models with only natural disasters and only perceived risk of natural disasters to examine the sensitivity of the coefficients of variables of interest. Table 2.22 compares the results of the variables of interest in the case of billion-dollar natural disasters only and perceived risk of natural disasters only. Comparing the coefficients of variables of interest in the model of natural disasters only, perceived risk of natural disasters only, and both, we observe that the signs, magnitudes, and levels of statistical significance of the coefficients in the first two models are exactly the same as that in the third model. This implies that the regression coefficients are robust either we take into account natural disaster and perceived risk of natural disasters separately or at the same time.

Table 2.22: The effects of the natural disasters vs. perceived risk of natural disasters

	Natural disasters				Perceived risk of natural disasters				Both			
	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg
Controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
disaster	-0.0003	-0.0002	-0.0015	-0.0003					-0.0002	-0.0002	-0.0015	-0.0003
disaster0	-0.0002	-0.0002	0.0007	-0.0002					-0.0002	-0.0002	0.0007	-0.0002
disaster10K					-0.0004***	-0.0002*	-0.0003	0.0002	-0.0004***	-0.0002*	-0.0003	0.0002
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
N	48881	48881	48881	48881	48881	48881	48881	48881	48881	48881	48881	48881
R ²	0.5586	0.6438	0.5716	0.2386	0.5587	0.6438	0.5715	0.2386	0.5587	0.6438	0.5716	0.2386

Note: saleg stands for sales growth and * $p < .1$, ** $p < .05$, *** $p < .01$.

The results and implications in the case of natural hazards are similar compared to that of natural disasters. Note that the perceived risk of natural disasters are the same in both Table 2.22 and Table 2.23.

Table 2.23: Natural hazards vs. perceived risk of natural disasters

	Natural hazards				Perceived risk of natural disasters				Both			
	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg
Controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
damage	-0.0012***	-0.0009***	0.0004	-0.0006					-0.0012***	-0.0009***	0.0004	-0.0006
damage0	-0.0001	-0.0005	-0.0023	0.0004					-0.0001	-0.0004	-0.0023	0.0004
disaster10K					-0.0004***	-0.0002*	-0.0007	0.0002	-0.0004**	-0.0002*	-0.0007	0.0002
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
N	46376	46376	46376	46376	46376	46376	46376	46376	46376	46376	46376	46376
R ²	0.5792	0.6567	0.5839	0.2347	0.5791	0.6566	0.5839	0.2346	0.5792	0.6567	0.5839	0.2347

Note: saleg stands for sales growth and * $p < .1$, ** $p < .05$, *** $p < .01$.

Manufacturing vs. Services sector. Since manufacturing and services are two dominant sectors in the U.S. economy (see Table 2.10), it is worth to examine the effects of natural disasters on these sectors separately. Specifically, the effects of natural disasters and natural hazards on firm performance of manufacturing sector, services sector, and the whole economy are shown in Table 2.24 and Table 2.25, respectively. We can observe in both tables that, for the manufacturing sector, perceived natural uncertainty is negatively associated with Tobin's Q. Meanwhile, for the services sector actual damages in year t+1 and perceived environmental uncertainty in year t are negatively associated with firm profitability in year t+1.

Table 2.24: The effects of natural disasters on the manufacturing vs. services sector

	Manufacturing sector				Services sector				Whole economy			
	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg
controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
disaster	-0.0002	-0.0002	-0.0007	-0.0002	-0.0001	-0.0003	-0.0002	-0.0007	-0.0002	-0.0002	-0.0015	-0.0003
disaster0	0.0001	-0.0001	-0.0016	0.0002	-0.0014**	-0.0009**	0.0052	-0.0010	-0.0002	-0.0002	0.0007	-0.0002
disaster10K	0.0003	0.0002	-0.0032***	0.0006	-0.0011*	-0.0009**	0.0056	-0.0004	-0.0004***	-0.0002*	-0.0003	0.0002
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
N	24269	24269	24269	24269	10713	10713	10713	10713	48881	48881	48881	48881
R ²	0.6209	0.7058	0.6029	0.1917	0.5459	0.6143	0.5475	0.2996	0.5587	0.6438	0.5716	0.2386

Note: saleg stands for sales growth and * $p < .1$, ** $p < .05$, *** $p < .01$.

Table 2.25: The effects of natural hazards on the manufacturing vs. services sector

	Manufacturing sector				Services sector				Whole economy			
	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg
controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
damage	-0.0005	-0.0003	0.0004	0.0021	-0.0023	-0.0015	0.0079	-0.0016	-0.0012***	-0.0009***	0.0004	-0.0006
damage0	0.0003	-0.0001	0.0033	-0.0003	-0.0020	-0.0022**	0.0029	-0.0013	-0.0002	-0.0002	0.0007	-0.0002
disaster10K	-0.0001	0.0000	-0.0023*	0.0012***	-0.0014**	-0.0010**	0.0021	-0.0005	-0.0004***	-0.0002*	-0.0003	0.0002
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
N	22909	22909	22909	22909	10377	10377	10377	10377	48881	48881	48881	48881
R ²	0.6083	0.6894	0.6022	0.1913	0.5372	0.6171	0.5556	0.3195	0.5587	0.6438	0.5716	0.2386

Note: saleg stands for sales growth and * $p < .1$, ** $p < .05$, *** $p < .01$.

Small vs. Large firms. We check the regression results according to the firm's size by splitting the data into two groups: Small firms and big firms. Small firms are those have

total assets less than the median of total assets of all firms (237.119 million USD) while big firms are those have total assets greater than or equal the median of total assets of all firms. The regression results of small and big firms corresponding to the billion-dollar natural disasters and natural hazards are shown in Table 2.26 and Table 2.27, respectively. The effects of natural disasters on firm profitability is consistently negatively in all three cases (small, large, or all firms).

Table 2.26: The effects of natural disasters on small vs. large firms

	Small firms				Large firms				All firms			
	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg
controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
disaster	0.0001	-0.0003	-0.0007	-0.0021	-0.0002***	-0.0002***	-0.0001	-0.0003***	-0.0002	-0.0002	-0.0015	-0.0003
disaster0	-0.0009	-0.0015***	0.0061*	0.0005	0.0000	-0.0000	-0.0003	-0.0000	-0.0002	-0.0002	0.0007	-0.0002
disaster10K	-0.0002	-0.0001	-0.0059*	0.0001	-0.0001***	-0.0001**	0.0002	0.0002***	-0.0004***	-0.0002*	-0.0003	0.0002
N	24679	24679	24679	24679	23766	23766	23766	23766	48881	48881	48881	48881
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
R ²	0.5230	0.5955	0.5313	0.1815	0.4469	0.6612	0.7321	0.3873	0.5587	0.6438	0.5716	0.2386

Note: saleg stands for sales growth and * $p < .1$, ** $p < .05$, *** $p < .01$.

Table 2.27 shows a clear and consistent results that natural hazards are consistently negatively associated with firm profitability. Moreover, for large firms, natural hazards in year t are negatively associated with sales growth in year $t + 1$.

Table 2.27: The effects of natural hazards on small vs. large firms

	Small firms				Large firms				All firms			
	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg	roa	ebitat	Q	saleg
controls	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
damage	0.0003	0.0000	-0.0094	0.0032	-0.0003***	-0.0002**	0.0010	-0.0005**	-0.0002	-0.0002	-0.0015	-0.0003
damage0	-0.0007	-0.0025***	0.0062	-0.0018	0.0001	-0.0001	-0.0004	-0.0002	-0.0002	-0.0002	0.0007	-0.0002
disaster10K	-0.0013**	-0.0010**	-0.0052	0.0014	-0.0000	0.0000	0.0004	0.0001	-0.0004***	-0.0002*	-0.0003	0.0002
Year FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Industry FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
State FE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
N	23430	23430	23430	23430	22529	22529	22529	22529	48881	48881	48881	48881
R ²	0.5188	0.5814	0.5106	0.1807	0.4429	0.6669	0.7302	0.4076	0.5587	0.6438	0.5716	0.2386

Note: saleg stands for sales growth and * $p < .1$, ** $p < .05$, *** $p < .01$.

2.4.2 Goodness of fit

Recall that the goodness of fit (or R^2) is a measure that explains the variation of the dependent (or target) variable due to the variation of the independent variables (or features). Formally, the goodness of fit metric is defined as follows

$$R^2 = 1 - \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2},$$

where n is the size of the test data, y_i , \hat{y}_i , and \bar{y} are the ground truth, estimated, and mean of y_i values, respectively.

Note that even though some previous studies criticize R^2 and prefer error measures (e.g. Razi and Athappilly 2005), R^2 still brings some useful insights about the models and used as a criterion for evaluating forecasting models (e.g. Swanson and White 1995). In order

to avoid the bias in evaluating the models, we decided to use both R^2 and error measures to compare the performances among these models, including linear regression, CART, and DNNs. However, we need to keep in mind that error measures seem more reliable criteria to evaluate the models in relation to R^2 . In this subsection, we focus on evaluation models using R^2 .

The architecture of the CART models. In order to find a good architecture we use two steps: trial and error method, and grid search. we first use the trial and error method to derive the lists of hyperparameters in Table 2.28. The trial and error step is very important since by doing this we have an insight of what are the suitable ranges of hyperparameters that we should choose for hyperparameter optimization.

Table 2.28: The list of hyperparameters for the CART models

Hyperparameter	Range
<code>list_max_depth</code>	[None, 5, 6, 7, 8, 9, 10, 11, 12]
<code>list_max_features</code>	[None, 0.65, 0.70, 0.75, 0.80, 0.85, 0.90, 0.95, 1.00]
<code>list_min_samples_split</code>	[2, 3]
<code>list_min_samples_leaf</code>	[10, 20, 30, 40, 50, 60, 70, 80, 90, 100]

Notes: For the CART models, here we only consider four important and common hyperparameters including `max_depth`, `max_features`, `min_samples_split`, and `min_samples_leaf`. However, the CART models indeed have several more hyperparameters such as `max_leaf_nodes`, `min_weight_fraction_leaf`, `max_leaf_nodes`, `min_impurity_decrease`, and `ccp_alpha`.

We then use grid search (multiple for loops) based on the lists of hyperparameters from the trial and error method to tune the hyperparameters to derive the optimal hyperparameters for each target variable.

Table 2.29: Two methods using for hyperparameter optimization

Step	Method	Output
Step 1	Trial and error	“Best” of lists of hyperparameters
Step 2	Grid search	Optimal combination of hyperparameters

Notes: Step 1 is necessary because without this step, Step 2 (grid search) would take too much time to be implemented. If the ranges of hyperparameters are not restricted at Step 1, it might take many days to run just a model at the Step 2 stage. For Step 1 itself, to obtain the “best” lists of hyperparameters, hundreds of lists have been run to select the best ones. That is why Step 1 is called *trial and error method*.

The optimal hyperparameters for the models for predicting ROA, EBITAT, Tobin’s Q, and sales growth are shown respectively in Table 2.30. Note that, for simplicity, in this table we use a dependent variable to represent for each corresponding model.

Table 2.30: Hyperparameters optimization

	roa	ebitat	Q	salegrowth
max_depth	9	12	10	11
max_features	0.85	0.7	0.65	0.9
min_samples_split	2	2	2	2
min_samples_leaf	90	60	100	80

The comparison of goodness of fit R^2 for the original data between linear regression and CART is shown in Table 2.31²⁴. It can be seen that the R^2 of CART and that of the linear regression are not much different. The goodness of fit of CART is slightly higher than that of linear regression model for the models of ROA and sales growth while R^2 of the linear regression models are slightly higher than that of CART for the models of EBITAT and Tobin's Q²⁵.

Table 2.31: Comparison goodness of fit among models with test data

	Linear regression	CART
roa	0.5587	0.5618
ebitat	0.6438	0.6399
Q	0.5716	0.5668
salegrowth	0.2386	0.2496

Notes: This table shows that the goodness of fit (R^2) of the linear regression and CART models are not much different in all models. This implies R^2 might not be the best predictive metrics to evaluate the models. In the next subsections, we will investigate two important metrics that are feature importance and prediction errors.

2.4.3 Feature importance

Feature importance is a scoring metric used to measure the relative importance of each input feature in relation to other features of a predictive model. Specifically, feature importance

²⁴Not that since R^2 is not a common criterion of neural networks, we only measure R^2 of CART and linear regression model.

²⁵Note that the list of variables in this study is restricted by some restrictions of the linear regression model. For example, in order to avoid the severe multicollinearity problem and highly correlated between variables, we removed several independent variables out of the initial list. Since multicollinearity problem is an issue for linear regression, but not for the CART model, adding some more variables (which we cannot add to the linear regression model due to the multicollinearity issue) to the CART model might help increase R^2 of this model.

is a technique help to select the most important variables in the sense that how much each of these variables help to reduce the level of predicted error (i.e. impurity or uncertainty) of the target variables²⁶. In the CART model, impurity can be understood as the level of uncertainty present at every node. The goal of the CART model is to minimize impurity (or minimize uncertainty) of the target variables at each of the leaf neurons.

There are two main roles of the feature importance metric. Firstly, the feature importance metric provides insights for the feature selection process. A natural way is to keep those features that help reduce the level of impurity the most and remove the variables that contribute nothing or very little to decrease the level of impurity. Note that even if we do not want to remove any features, we still know which variables contribute to the most and which variables contribute the least. Secondly, as a consequence of the first role, by removing some irrelevant (non-informative) or redundant features, the feature importance metric is a good tool for the dimensionality reduction purpose and decreasing the computational cost of processing data and training models. Thirdly, reducing the number of inputs by removing irrelevant or redundant features might help to improve the performances of our models in terms of error measures.

We can observe one noticeable result from Table 2.32 that the uncertainty variables (`disaster0`, `disaster`, and `disaster10K`) are much relatively less important, in the sense of helping to decrease the impurity level, compared to lagged dependent variables (e.g. `roalag1`, `ebitatlag1`, `qlag1`, `salegrowthlag1`) and financial statement state variables (e.g. `empgrowth`, `reat`, `logat`, `saleat`, `seqat`).

²⁶A good reference for data-driven feature selection in the CART model is [Gocheva-Ilieva et al. \(2019\)](#).

Table 2.32: Feature importance of the CART models

Model 1 (ROA)		Model 2 (EBITAT)		Model 3 (Tobin's Q)		Model 4 (sales growth)	
variable	impurity decrease	variable	impurity decrease	variable	impurity decrease	variable	impurity decrease
roalag1	0.731264	ebitatlag1	0.894507	Qlag1	0.910080	empgrowth	0.554372
reat	0.142301	logat	0.024963	logat	0.024171	saleat	0.215514
logat	0.046613	seqat	0.021086	empgrowth	0.012403	salegrowthlag1	0.110306
seqat	0.023266	reat	0.018697	capxgrowth	0.008595	reat	0.037373
saleat	0.014844	saleat	0.009083	reat	0.007689	xintgrowth	0.028039
xintsale	0.013228	xintsale	0.008432	relct	0.005536	capxgrowth	0.020958
lctat	0.007838	relct	0.007126	inflation	0.005440	logat	0.005717
relct	0.004745	empgrowth	0.005834	gdpgrowth	0.005412	lctat	0.005061
capxgrowth	0.003734	lctat	0.002278	cheat	0.004037	disaster10K	0.004982
empgrowth	0.003187	interestrate	0.001717	seqat	0.003520	invtsale	0.004648
interestrate	0.002582	capxgrowth	0.001518	interestrate	0.002652	cheat	0.003900
cheat	0.002469	chlct	0.001170	lctlct	0.002152	inflation	0.002572
dvcib	0.001411	lctlct	0.001019	xintsale	0.001980	gdpgrowth	0.001174
invtsale	0.001158	dtat	0.000797	xintgrowth	0.001278	chlct	0.001124
invtgrowth	0.000432	dvcib	0.000701	disaster10K	0.001219	seqat	0.000819
xintgrowth	0.000313	xintgrowth	0.000417	chlct	0.000827	hhi	0.000779
inflation	0.000281	atemp	0.000171	saleat	0.000756	interestrate	0.000751
gdpgrowth	0.000130	cheat	0.000147	atemp	0.000637	lctlct	0.000727
chlct	0.000074	invtgrowth	0.000145	invtgrowth	0.000503	atemp	0.000639
dtat	0.000044	invtsale	0.000073	lctat	0.000433	invtgrowth	0.000395
disaster10K	0.000039	gdpgrowth	0.000045	invtsale	0.000372	relct	0.000151
lctlct	0.000037	inflation	0.000032	hhi	0.000200	dtat	0.000000
atemp	0.000008	disaster10K	0.000025	dtat	0.000070	xintsale	0.000000
disaster0	0.000001	hhi	0.000016	disaster0	0.000038	dvcib	0.000000
hhi	0.000000	disaster0	0.000000	dvcib	0.000000	disaster0	0.000000
disaster0	0.000000	disaster	0.000000	disaster	0.000000	disaster	0.000000

A node will be split if this split induces a decrease of the impurity (mean square error) greater than or equal to this current value²⁷. For example, we illustrate the trees with `max_depth=2`. Intuitively, the trees with mean squared error (`squared_error`), number of samples (`samples`), and the average predicted value of ROA, EBITAT, Tobin's Q, and sales growth are respectively shown in Figure 2.6, Figure 2.7, Figure 2.8, and Figure 2.9.

²⁷<https://scikit-learn.org/stable/modules/generated/sklearn.tree.DecisionTreeRegressor.html>

Figure 2.6: Decision tree of the CART model for predicting ROA

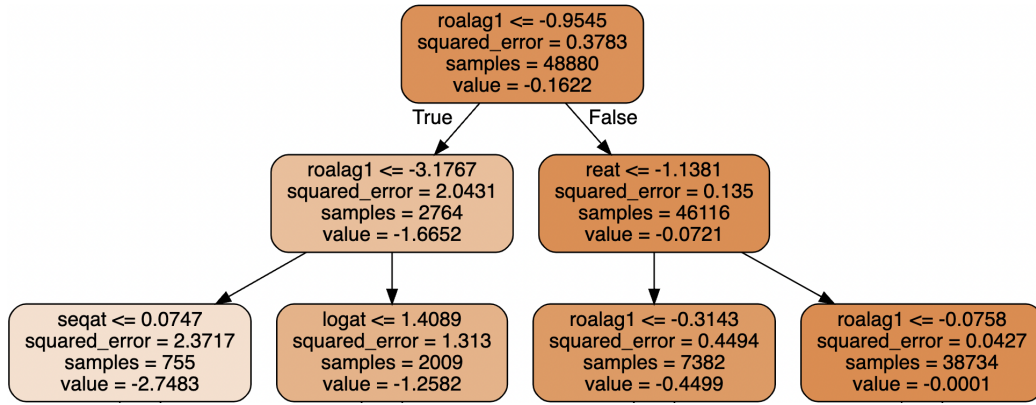


Figure 2.7: Decision tree of the CART model for predicting EBITAT

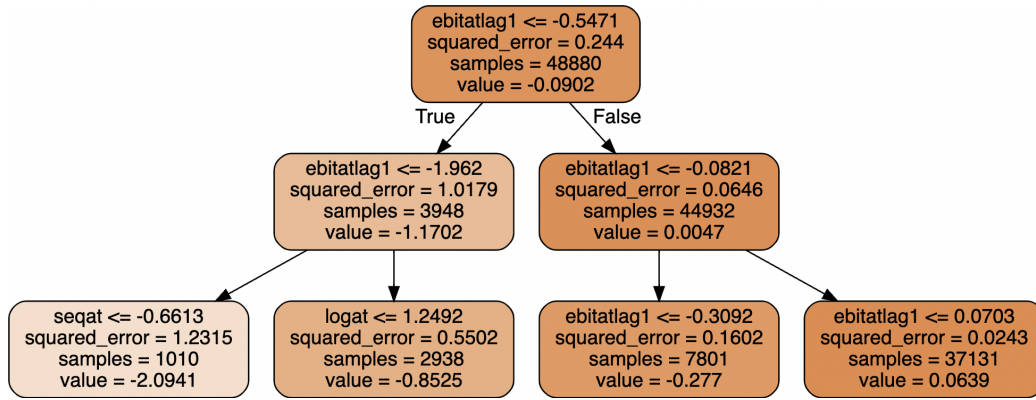


Figure 2.8: Decision tree of the CART model for predicting Tobin's Q

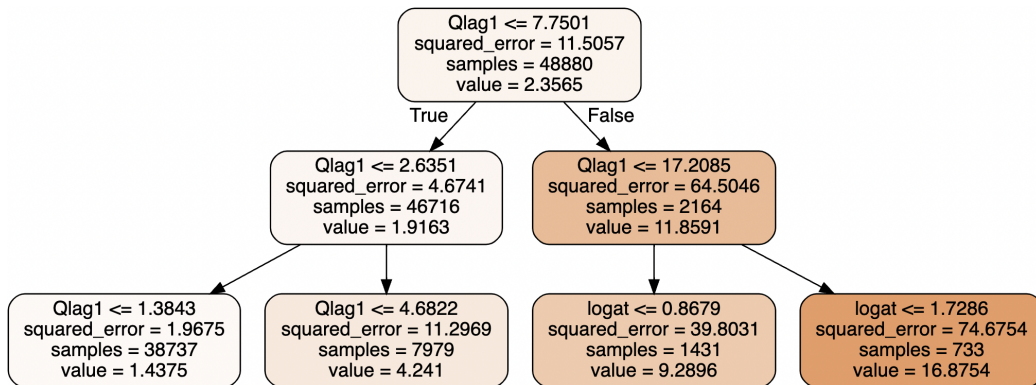
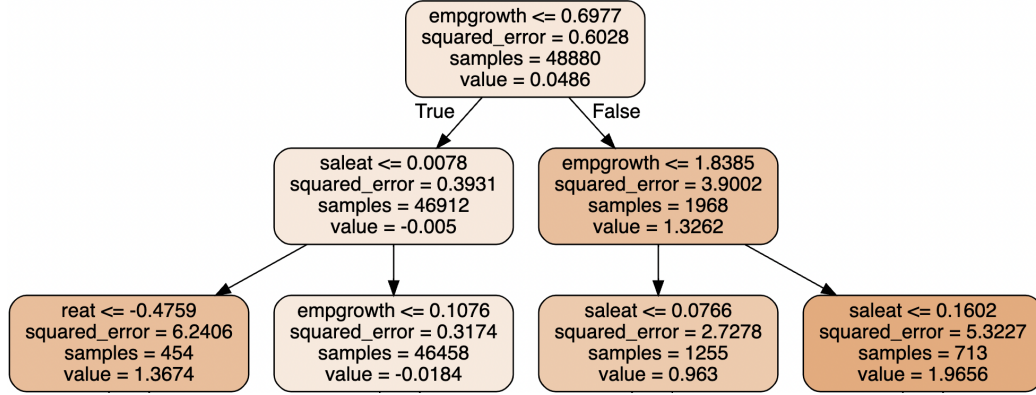


Figure 2.9: Decision tree of the CART model for predicting sales growth



2.4.4 Prediction errors analysis

Since we are working on the prediction problems, a natural way to measure the quality of our predictive models is how close from predicted values to the actual ground truth values. That is, how large the error measures are. Error measures are popular indicators used to compare the performances between linear regression model and DNNs (e.g. [Doganis et al. 2006](#); [Anyaeche and Ighravwe 2013](#); [Pombeiro et al. 2017](#)). Formally, the mean squared error (MSE), root mean squared error (RMSE), and mean absolute error (MAE) are defined as follows.

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2,$$

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2},$$

$$\text{MAE} = \frac{1}{n} \sum_{i=1}^n |y_i - \hat{y}_i|,$$

where n is the size of the test set, y_i and \hat{y}_i are the actual and predicted values, respectively.

Note that there is no absolute criterion for a “good” value of MSE, RMSE, or MAE. The best way we can do this is to compare these criteria among models. The smaller error measures the better. Since the definition and the behavior of each dependent variable is different compared to the others, we are going to investigate four different models corresponding to four different firm performance criteria including ROA, EBITAT, Tobin’s Q, and sales growth.

Model 1: Predicting ROA

Neural networks. Neural networks with one hidden layer, two hidden layers, three hidden layers, and four hidden layers are denoted as ANN, DNN[2], DNN[3], and DNN[4], respectively. Google Colab with the Numpy version 1.19.5 and the Tensorflow version 2.7.0 are used to run the neural network models. Choosing the optimal number of neurons is the first important step to build the architecture of neural networks.

Hyperparameter tuning the number of neurons. Finding the optimal architectures for neural networks depends critically on determining a good set of hyperparameters. Since there are many hyperparameters, there are many ways that we can tune the hyperparameters. First, we need to find the optimal number of neurons (or units) in each layer. In order to tune hyperparameters we use the Keras tuner library. This library contains four types of algorithms, including Hyperband, random search, sklearn, and Bayesian optimization. We choose Hyperband for tuning the number of inputs for the input and hidden layers²⁸. Note that, in our architecture of neural networks, the number of neurons in the input layer equals the number of independent variables (features), which is 27, and the number of output is only one (e.g ROA). The following table shows the optimal number of neurons for the hidden layer with `epochs=500`.

Table 2.33: The optimal number of neurons of neural networks for predicting ROA

	min_value	max_value	Step	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	27	27	-	27	27	27	27
Hidden layer [1]	8	512	4	464	272	456	360
Hidden layer [2]	8	512	4	-	488	288	368
Hidden layer [3]	8	512	4	-	-	272	288
Hidden layer [4]	8	512	4	-	-	-	212
Output layer	1	1	-	1	1	1	1

Now, we are going to identify the types of activation function for each layer. For the output layer, since our problem is a prediction problem with continuous target variables it is classified as *regression* problem. In practice, the common activation function for regression problems is linear. For the input and hidden layer, in practice, there are three common activation functions for input and hidden layers including Rectified Linear Unit (ReLU), logistic (sigmoid), and hyperbolic tangent (tanh). In modern neural networks, the default recommendation is to use the ReLU activation function (Goodfellow et al. 2016). Therefore,

²⁸For more details about the Hyperband algorithm, see Li et al. (2018) or the republished version at ?. Li et al. (2018) compare the Hyperband algorithm and the popular Bayesian optimization methods and find that the Hyperband algorithm “can provide over an order-of-magnitude speedup over our competitor set on a variety of deep-learning and kernel-based learning problems”.

we use the ReLU activation function in this model. Recall that a ReLU activation function has the form $g(z) = \max\{0, z\}$.

The architectures of all neural networks models are shown in Table 2.34. From the number of inputs in Table 2.33, we obtain the number of parameters in Table 2.34. The number of parameters is calculated as follows. Suppose n is the number of neurons in the previous layer and m is the number of neurons in the current layer. By adding the bias to the previous layer, we have $n + 1$ neurons. The number of parameters between the previous layer and the current layer is equal to $(n + 1)m$. Specifically, the number of trainable parameters of neural networks for predicting ROA is shown as follows²⁹.

Table 2.34: The number of trainable parameters of neural networks for predicting ROA

	Activation function	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	ReLU	-	-	-	-
Hidden layer [1]	ReLU	12992	7616	12768	10080
Hidden layer [2]	ReLU	-	133224	131616	132848
Hidden layer [3]	ReLU	-	-	78608	106272
Hidden layer [4]	ReLU	-	-	-	61268
Output layer	linear	465	489	273	213
Total parameters	-	13,457	141,329	223,265	310,681

Hyperparameter tuning number of epochs. In order to find the optimal number of epochs, we first run the Keras sequential `model.fit()` function for ROA with `epochs=500`, `batch_size=32`, `validation_split=0.5`³⁰. For example, for the 80/20 split data, we run the `index(min(val_mse_per_epoch))` function and get the optimal number of epochs for ANN, DNN[2], DNN[3], and DNN[4], which are 282, 157, 157, and 103, respectively. We then rerun the `model.fit()` function with these optimal epochs, i.e. `epochs=282` for ANN, `epochs=157` for DNN[2], `epochs=157` for DNN[3], and `epochs=103` for DNN[4]. Finally, we evaluate the model on the test data by using the `model.evaluate()` function to obtain the error measures for unseen test data.

²⁹For example, for the ANN model, the number of parameters between the input layer and the hidden layer equals to $(27 + 1) \times 464 = 12,992$. Also, the number of parameters between the hidden layer and the output layer equals $(464 + 1) \times 1 = 465$. Therefore, the total parameters equals $12,992 + 465 = 13,457$. The numbers of parameters in other neural network models are calculated in a similar manner.

³⁰Note that the `validation_split` parameter shows the fraction of training data to be used as validation data. Since about 66.66% of our data is training set, the `validation_split=0.5` implies that the fraction of validation data is approximately 33.33% of the entire data. So the fraction of each train set, validation set, and test set is equally one third of the data or approximately 33.33%.

Table 2.35: Optimal epochs of neural networks for predicting ROA

Model	ANN	DNN[2]	DNN[3]	DNN[4]
Epochs range	[1, 500]	[1, 500]	[1, 500]	[1, 500]
Optimal epoch (80/20 split)	282	157	157	112
Optimal epoch (90/10 split)	405	197	158	119
Optimal epoch (50/50 split)	384	204	160	132

Visualization of MSE and MAE of training and validation data. The variations of the mean squared error (MSE) and mean absolute error (MAE) of training and validation data with the 80/20 split ratio of the ANN, DNN[2], DNN[3], and DNN[4] model are shown in Figure 2.10-2.13. We can observe that both MSE and MAE drop dramatically at the very few initial epochs then decrease very slowly after that before going up eventually.

Figure 2.10: The MSE and MAE loss function of the ANN model for predicting ROA

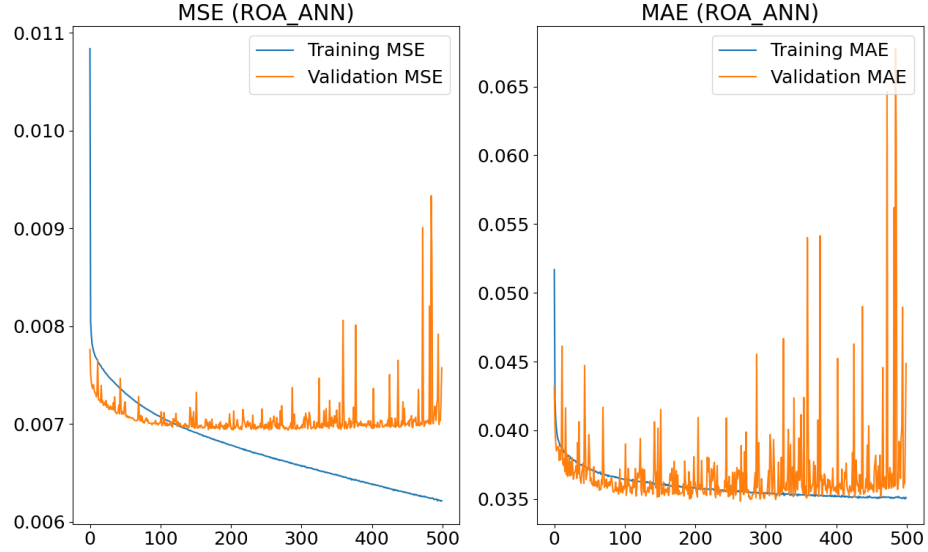


Figure 2.11: The MSE and MAE loss function of the DNN[2] model for predicting ROA

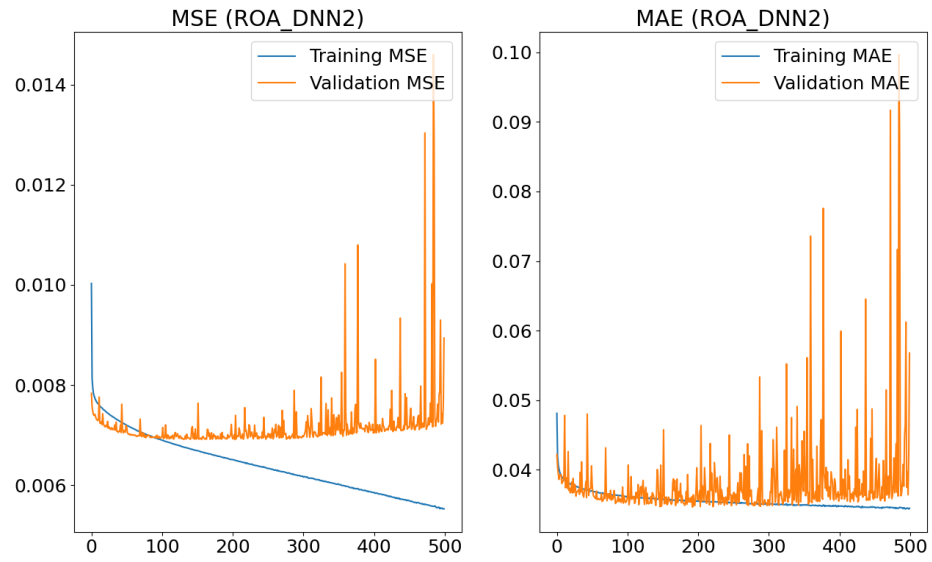


Figure 2.12: The MSE and MAE loss function of the DNN[3] model for predicting ROA

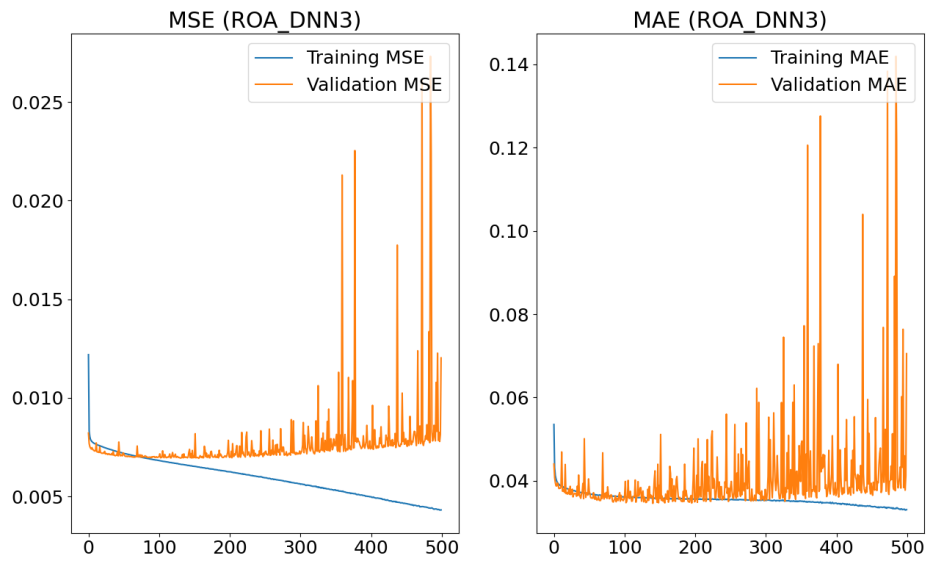
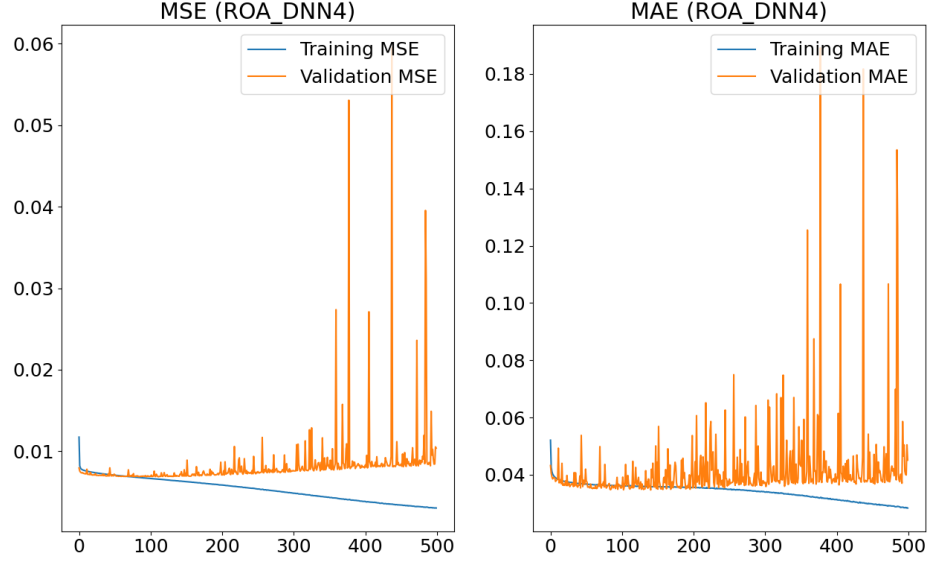


Figure 2.13: The MSE and MAE loss function of the DNN[4] model for predicting ROA



CART model. For the CART model, first the trial and error method is used to derive a good list of values for each hyperparameter. Four common hyperparameters and their lists of values are shown in Table 2.28. Then, four *for loops* are used to examine all combinations of the lists of given values of four hyperparameters. The optimal combinations of the hyperparameters for the CART models for testing data is shown in Table 2.30.

Performance comparison. Table 2.36 compares the performances on the test data (or holdout sample) between CART, several neural network models, and the benchmark linear regression model with different split ratios (80/20, 90/10, and 50/50 train and test set respectively) and in terms of MSE, RMSE, and MAE. It can be seen that CART and neural network models outperform linear regression in all given criteria and with any given split ratios in predicting ROA. Comparing CART and neural networks, it is clear that CART is better than NNs if the split ratio is 50/50, and if the split ratio is 80/20 and in terms of MAE. Meanwhile, neural networks are better than CART if the split ratio is 90/10, and if the split ratio is 80/20 and in terms of MSE or RMSE. Notice that simply increasing the number of hidden layers does not consistently improve the accuracy of predictions. This finding is similar to the result in Chen et al. (2017).

Table 2.36: Comparison of models performance on the test data for predicting ROA

	80/20 split			90/10 split			50/50 split		
	MSE	RMSE	MAE	MSE	RMSE	MAE	MSE	RMSE	MAE
Regression	0.0078	0.0882	0.0393	0.0075	0.0868	0.0391	0.0079	0.0888	0.0393
CART	0.0073	0.0854	0.0349	0.0072	0.0851	0.0353	0.0071	0.0845	0.0344
<i>Change</i>	-6.41%	-3.17%	-11.19%	4.00%	1.96%	-9.72%	-10.13%	-4.84%	-12.47%
ANN	0.0072	0.0849	0.0355	0.0069	0.0831	0.0351	0.0074	0.0860	0.0362
<i>Change</i>	-7.69%	-3.74%	-9.67%	-8.00%	-4.26%	-10.23%	-6.33%	-3.15%	-7.89%
DNN[2]	0.0072	0.0849	0.0357	0.0069	0.0831	0.0360	0.0074	0.0860	0.0363
<i>Change</i>	-7.69%	-3.74%	-9.16%	-8.00%	-4.26%	-7.93%	-6.33%	-3.15%	-7.63%
DNN[3]	0.0072	0.0849	0.0353	0.0069	0.0831	0.0352	0.0074	0.0860	0.0366
<i>Change</i>	-7.69%	-3.74%	-10.18%	-8.00%	-4.26%	-9.97%	-6.33%	-3.15%	-6.87%
DNN[4]	0.0072	0.0849	0.0360	0.0070	0.837	0.0348	0.0074	0.0860	0.0359
<i>Change</i>	-7.69%	-3.74%	-8.39%	-6.67%	-3.57%	-10.99%	-6.33%	-3.15%	-8.65%

Model 2: Predicting EBITAT

Hyperparameter tuning number of neurons. Similarly for models for predicting ROA, the Hyperband method is used to tune the number of neurons in each layer in the neural network models for predicting EBITAT. The following table shows the optimal number of neurons for the input and hidden layers with epochs=500.

Table 2.37: The optimal number of neurons of neural networks for predicting EBITAT

	min_value	max_value	Step	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	27	27	-	27	27	27	27
Hidden layer [1]	8	512	4	276	128	476	424
Hidden layer [2]	8	512	4	-	504	448	464
Hidden layer [3]	8	512	4	-	-	472	252
Hidden layer [4]	8	512	4	-	-	-	44
Output layer	1	1	-	1	1	1	1

The architectures of the neural network models for EBITAT are shown in Table 2.38.

Table 2.38: The number of trainable parameters of neural networks for predicting EBITAT

	Activation function	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	ReLU	-	-	-	-
Hidden layer [1]	ReLU	7728	3584	13328	11872
Hidden layer [2]	ReLU	-	65016	213696	197200
Hidden layer [3]	ReLU	-	-	211928	117180
Hidden layer [4]	ReLU	-	-	-	11132
Output layer	linear	277	505	473	45
Total parameters	-	8,005	69,105	439,425	337,429

Hyperparameter tuning number of epochs. For each model, the range from 1 to 500 epochs is run to obtain the optimal epoch. Holding other things constant, the “optimal” epoch for each model is the one that leads to the minimum value of the MSE of that model.

Table 2.39: Optimal epochs of neural networks for predicting EBITAT

Model	ANN	DNN[2]	DNN[3]	DNN[4]
Epochs range	[1, 500]	[1, 500]	[1, 500]	[1, 500]
Optimal epoch (80/20 split)	276	169	157	132
Optimal epoch (90/10 split)	358	185	210	122
Optimal epoch (50/50 split)	310	188	172	149

Visualization of MSE and MAE of training and validation data. The variations of MSE and MAE of training and validation data with the 80/20 split ratio of the ANN, DNN[2], DNN[3], and DNN[4] model for predicting EBITAT are shown in Figure 2.14-2.17.

Figure 2.14: The MSE and MAE loss function of the ANN model for predicting EBITAT

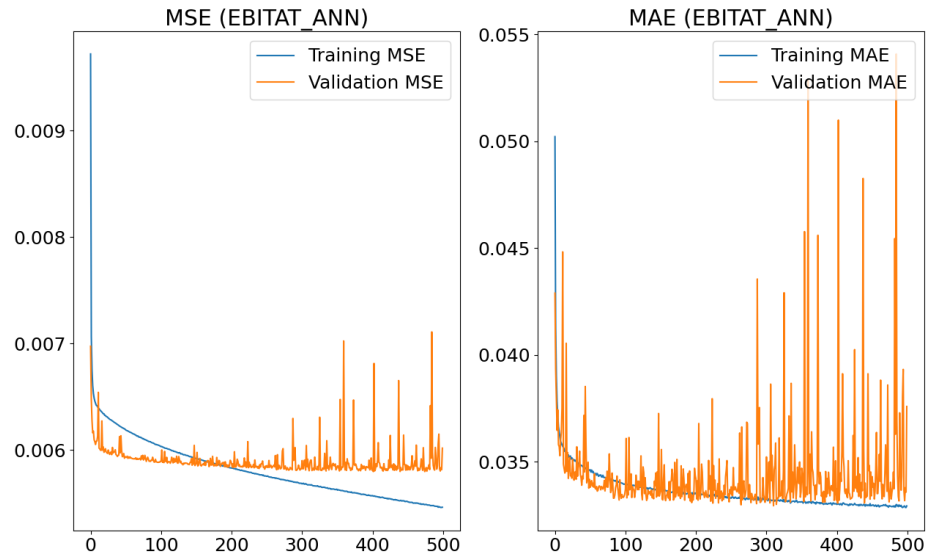


Figure 2.15: The MSE and MAE loss function of the DNN[2] model for predicting EBITAT

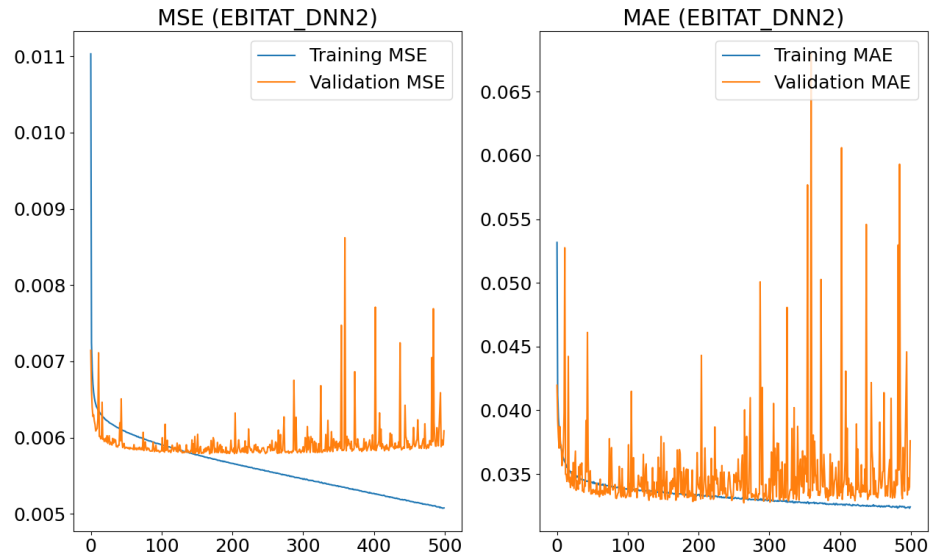


Figure 2.16: The MSE and MAE loss function of the DNN[3] model for predicting EBITAT

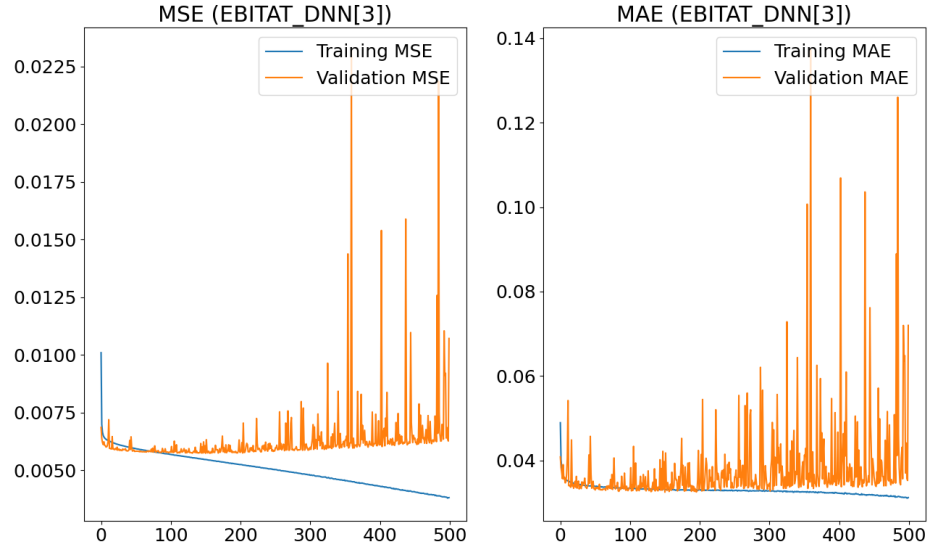
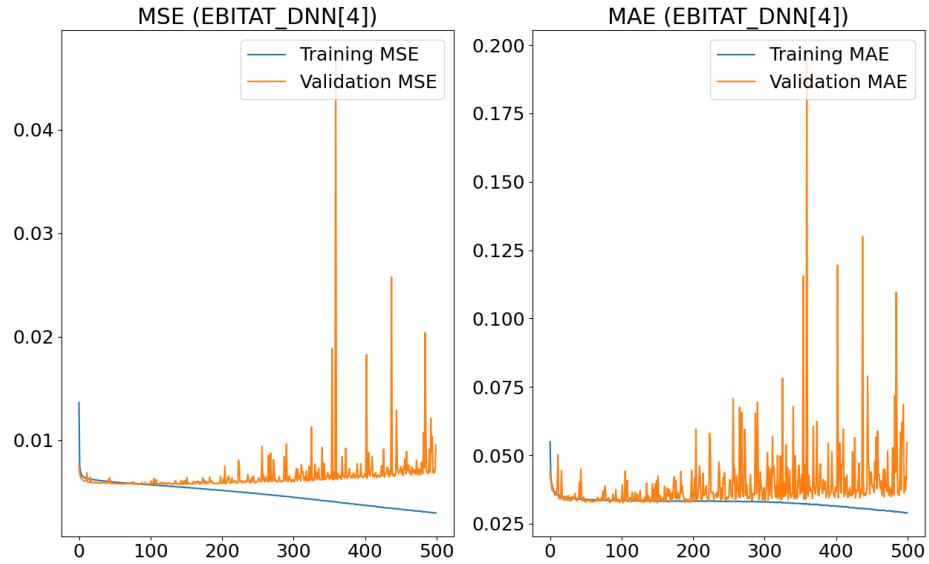


Figure 2.17: The MSE and MAE loss function of the DNN[4] model for predicting EBITAT



Performance comparison. Table 2.40 compares the performances on the test data among linear regression, CART, and neural networks, it is obvious that CART and neural networks are better than linear regression models in predicting EBITAT with any given split ratios and in terms of any given error measures. Moreover, in general, neural networks are better than CART if the split ratio is 80/20 or 90/10 meanwhile CART is better than neural networks if the split ratio is 50/50.

Table 2.40: Comparison of models performance on the test data for predicting EBITAT

	80/20 split			90/10 split			50/50 split		
	MSE	RMSE	MAE	MSE	RMSE	MAE	MSE	RMSE	MAE
Regression	0.0066	0.0813	0.0358	0.0063	0.0791	0.0353	0.0066	0.0813	0.0357
CART	0.0063	0.0792	0.0329	0.0060	0.0775	0.0329	0.0061	0.0778	0.0323
<i>Change</i>	-4.55%	-2.58%	-8.10%	-4.76%	-2.02%	-6.79%	-7.58%	-4.31%	-9.52%
ANN	0.0062	0.0787	0.0333	0.0057	0.0755	0.0322	0.0062	0.0787	0.0337
<i>Change</i>	-6.06%	-3.19%	-6.98%	-9.52%	-4.55%	-8.78%	-6.06%	-3.19%	-5.60%
DNN [2]	0.0062	0.0787	0.0330	0.0057	0.0755	0.0325	0.0062	0.0787	0.0338
<i>Change</i>	-6.06%	-3.19%	-7.82%	-9.52%	-4.55%	-7.93%	-6.06%	-3.19%	-5.32%
DNN [3]	0.0061	0.0781	0.0330	0.0058	0.0761	0.0324	0.0063	0.0794	0.0338
<i>Change</i>	-7.58%	-3.94%	-7.82%	-7.94%	-3.79%	-8.21%	-4.55%	-2.34%	-5.32%
DNN [4]	0.0061	0.0781	0.0333	0.0057	0.0755	0.0324	0.0062	0.0787	0.0336
<i>Change</i>	-7.58%	-3.94%	-6.98%	-9.52%	-4.55%	-8.21%	-6.06%	-3.19%	-5.88%

Model 3: Predicting Tobin's Q

Hyperparameter tuning number of neurons. Similarly to Model 1 and Model 2, the Hyperband method is used for tuning the number of neurons in Model 3. Table 2.43 shows the optimal number of neurons for the input and hidden layers of different neural networks with epochs=500.

Table 2.41: The optimal number of neurons of neural networks for predicting Tobin's Q

	min_value	max_value	Step	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	27	27	-	27	27	27	27
Hidden layer [1]	8	512	4	432	312	240	216
Hidden layer [2]	8	512	4	-	480	424	428
Hidden layer [3]	8	512	4	-	-	416	416
Hidden layer [4]	8	512	4	-	-	-	120
Output layer	1	1	-	1	1	1	1

The architectures of the neural network models for Tobin's Q are shown in the following table.

Table 2.42: The number of parameters of neural networks for predicting Tobin's Q

	Activation function	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	ReLU	-	-	-	-
Hidden layer [1]	ReLU	12096	8736	6720	6048
Hidden layer [2]	ReLU	-	150240	102184	92876
Hidden layer [3]	ReLU	-	-	176800	178464
Hidden layer [4]	ReLU	-	-	-	50040
Output layer	linear	433	481	417	121
Total parameters	-	12,529	159,457	286,121	327,549

Hyperparameter tuning number of epochs. The range from 1 to 500 epochs is run to obtain the optimal epoch for each model.

Table 2.43: Optimal epochs of neural networks for predicting Tobin's Q

Model	ANN	DNN[2]	DNN[3]	DNN[4]
Epochs range	[1, 500]	[1, 500]	[1, 500]	[1, 500]
Optimal epochs (80/20 split)	294	256	139	143
Optimal epochs (90/10 split)	323	216	149	141
Optimal epochs (80/20 split)	291	253	148	148

Visualization of MSE and MAE of training and validation data. The variations of MSE and MAE of training and validation data with the 80/20 split ratio of the ANN, DNN[2], DNN[3], and DNN[4] model for predicting Tobin's Q are shown in Figure 2.18-2.21.

Figure 2.18: The MSE and MAE loss function of the ANN model for predicting Tobin's Q

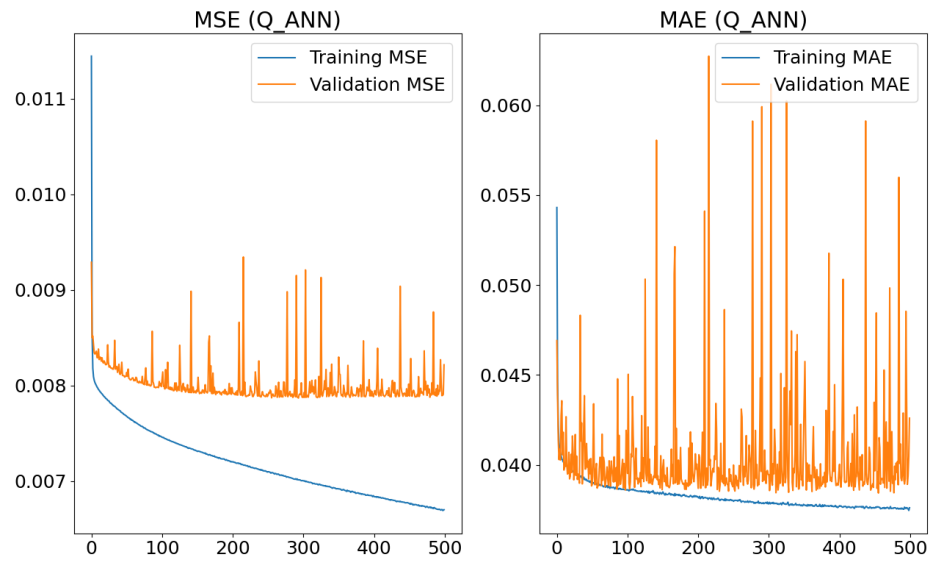


Figure 2.19: The MSE and MAE loss function of the DNN[2] for predicting Tobin's Q

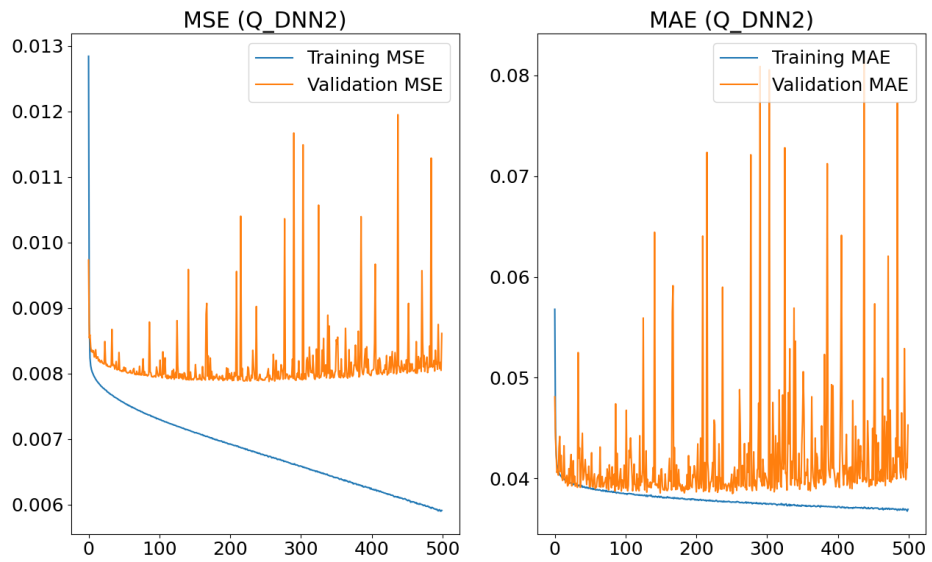


Figure 2.20: The MSE and MAE loss function of the DNN[3] for predicting Tobin's Q

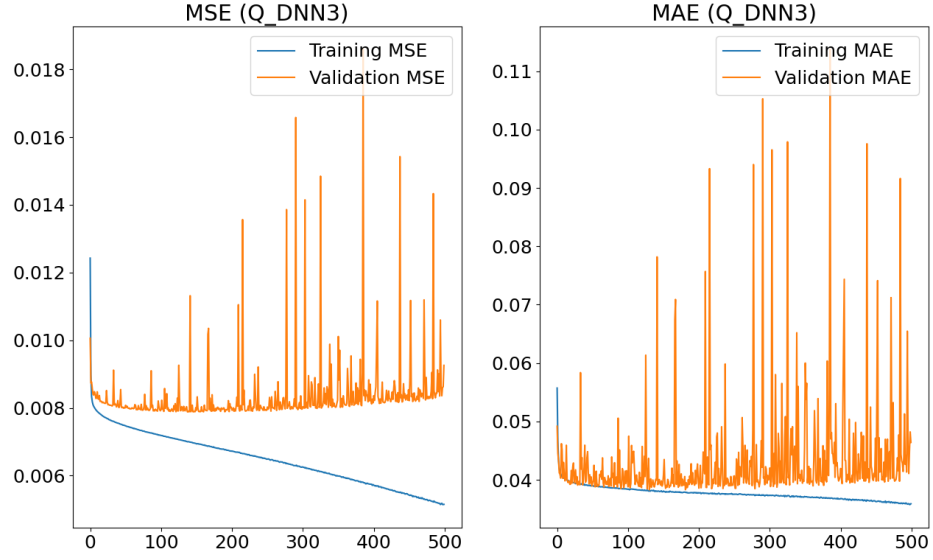
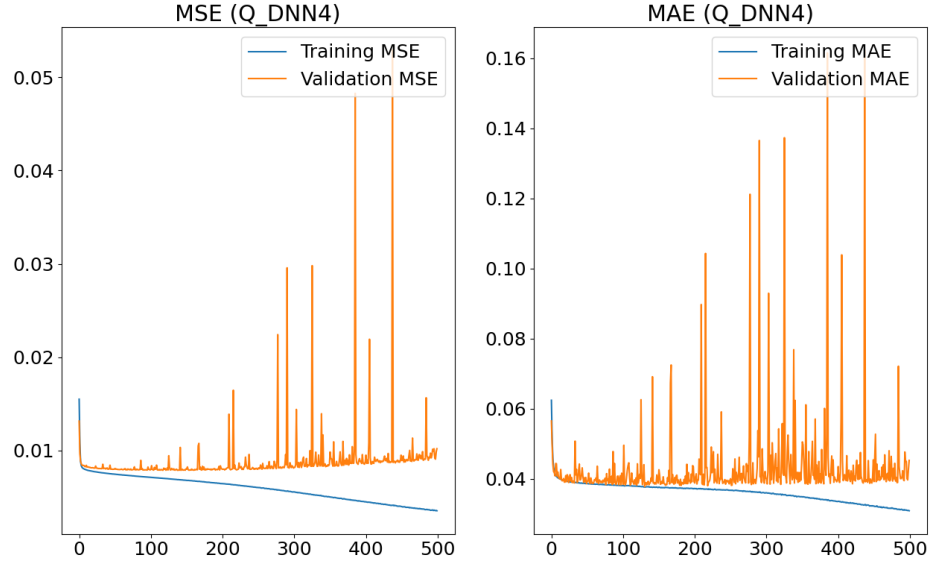


Figure 2.21: The MSE and MAE loss function of the DNN[4] for predicting Tobin's Q



Performance comparison. Table 2.44 compares the performances of the linear regression, CART, and neural network models on the test data in terms of MSE, RMSE, and MAE with the 80/20, 90/10, and 50/50 split ratios. Overall, CART and neural networks outperform linear regression models in predicting Tobin's Q with any given split ratios and in terms of any given error measures. Comparison between neural networks and CART, in general, neural networks are better predictive models when the split ratio is 80/20 and 90/10. Meanwhile, CART models are better than neural networks when the split ratio is 50/50.

Table 2.44: Comparison of models performance on the test data for predicting Tobin's Q

	80/20 split			90/10 split			50/50 split		
	MSE	RMSE	MAE	MSE	RMSE	MAE	MSE	RMSE	MAE
Regression	0.0081	0.0898	0.0399	0.0078	0.0883	0.0397	0.0081	0.0901	0.0399
CART	0.0076	0.0869	0.0374	0.0076	0.0875	0.0376	0.0074	0.0859	0.0369
<i>Change</i>	-6.17%	-3.23%	-6.27%	-2.56%	-0.91%	-5.29%	-8.64%	-4.66%	-7.52%
ANN	0.0076	0.0869	0.0382	0.0072	0.0849	0.0376	0.0078	0.0883	0.0393
<i>Change</i>	-6.17%	-3.23%	-4.26%	-7.69%	-3.85%	-5.29%	-3.70%	-1.99%	-1.50%
DNN [2]	0.0076	0.0869	0.0382	0.0072	0.0849	0.0373	0.0078	0.0883	0.0387
<i>Change</i>	-6.17%	-3.23%	-4.26%	-7.69%	-3.85%	-6.05%	-3.70%	-1.99%	-3.01%
DNN [3]	0.0075	0.0866	0.0384	0.0071	0.0843	0.0375	0.0078	0.0883	0.0391
<i>Change</i>	-7.41%	-3.56%	-3.76%	-8.97%	-4.53%	-5.54%	-3.70%	-1.99%	-2.01%
DNN [4]	0.0075	0.0866	0.0375	0.0072	0.0849	0.0384	0.0078	0.0883	0.0389
<i>Change</i>	-7.41%	-3.56%	-6.02%	-7.69%	-3.85%	-3.27%	-3.70%	-1.99%	-2.51%

Model 4: Predicting sales growth

Hyperparameter tuning number of neurons. Similarly to previous models, the Hyperband method is used for tuning the number of neurons in Model 4. The following table shows the optimal number of neurons for the input and hidden layers of several neural network models with epochs=500.

Table 2.45: The optimal number of neurons of neural networks for predicting sales growth

	min_value	max_value	Step	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	27	27	-	27	27	27	27
Hidden layer [1]	8	512	4	404	256	328	496
Hidden layer [2]	8	512	4	-	376	212	196
Hidden layer [3]	8	512	4	-	-	440	332
Hidden layer [4]	8	512	4	-	-	-	412
Output layer	1	1	-	1	1	1	1

The architectures of the neural network models for sales growth are shown in Table 2.46.

Table 2.46: The number of parameters of neural networks for predicting sales growth

	Activation function	ANN	DNN[2]	DNN[3]	DNN[4]
Input layer	ReLU	-	-	-	-
Hidden layer [1]	ReLU	11312	7168	9184	13888
Hidden layer [2]	ReLU	-	96632	69748	97412
Hidden layer [3]	ReLU	-	-	93720	65404
Hidden layer [4]	ReLU	-	-	-	137196
Output layer	linear	405	377	441	413
Total parameters	-	11,717	104,177	173,093	314,313

Hyperparameter tuning number of epochs. The range from 1 to 500 epochs is run to obtain the optimal epoch (i.e. smallest MSE) for each model.

Table 2.47: Optimal epochs of neural networks for predicting sales growth

Model	ANN	DNN[2]	DNN[3]	DNN[4]
Epochs range	[1, 500]	[1, 500]	[1, 500]	[1, 500]
Optimal epochs (80/20 split)	458	288	166	128
Optimal epochs (90/10 split)	479	207	207	204
Optimal epochs (50/50 split)	199	149	165	82

Visualization of MSE and MAE of training and validation data. The MSE and MAE loss functions of training and validation data with the 80/20 split ratio of the neural networks for predicting sales growth are shown in Figure 2.22-2.25.

Figure 2.22: The MSE and MAE loss function of the ANN model for predicting sales growth

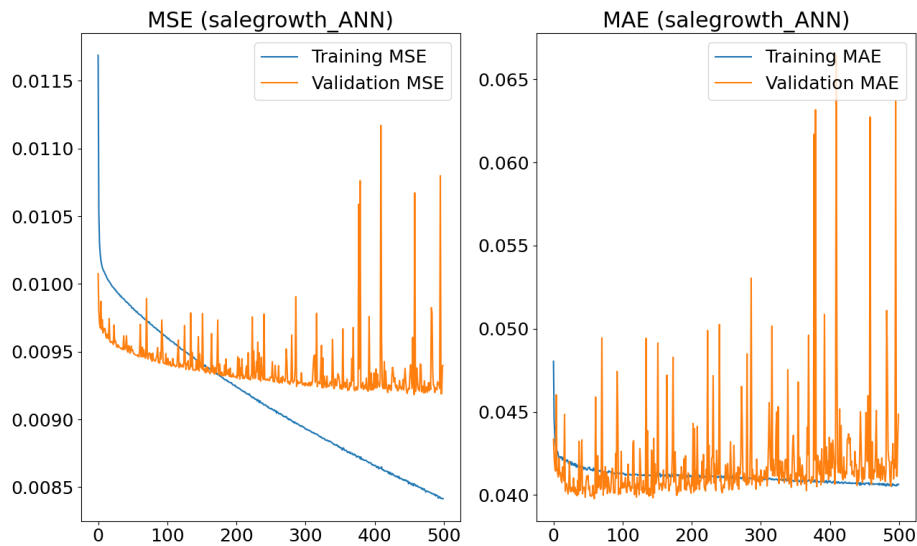


Figure 2.23: The MSE and MAE loss function of the DNN[2] for predicting sales growth

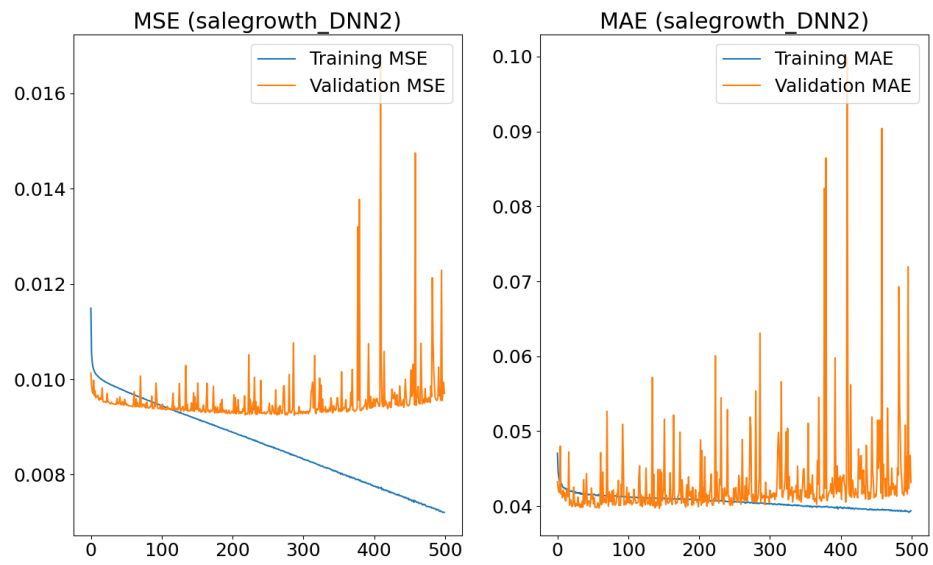


Figure 2.24: The MSE and MAE loss function of the DNN[3] for predicting sales growth

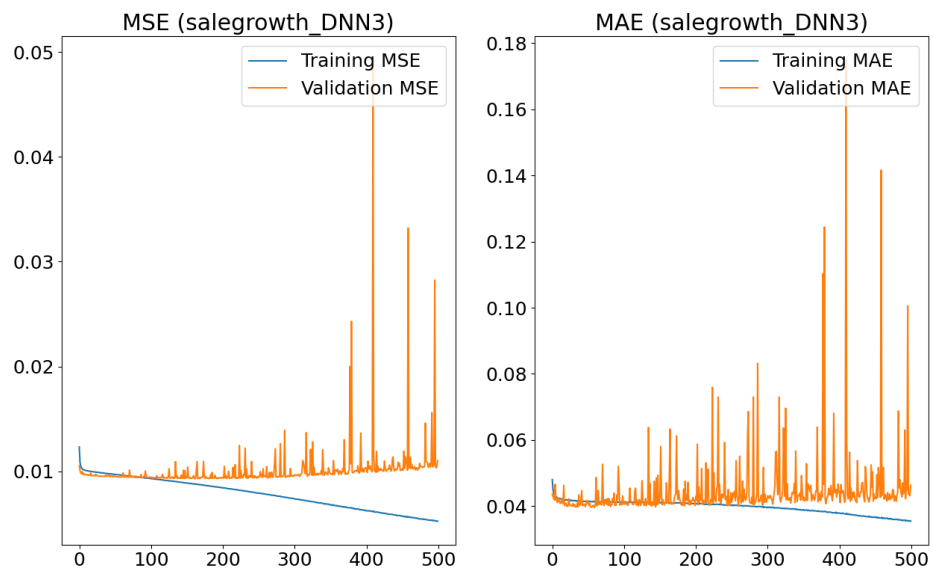
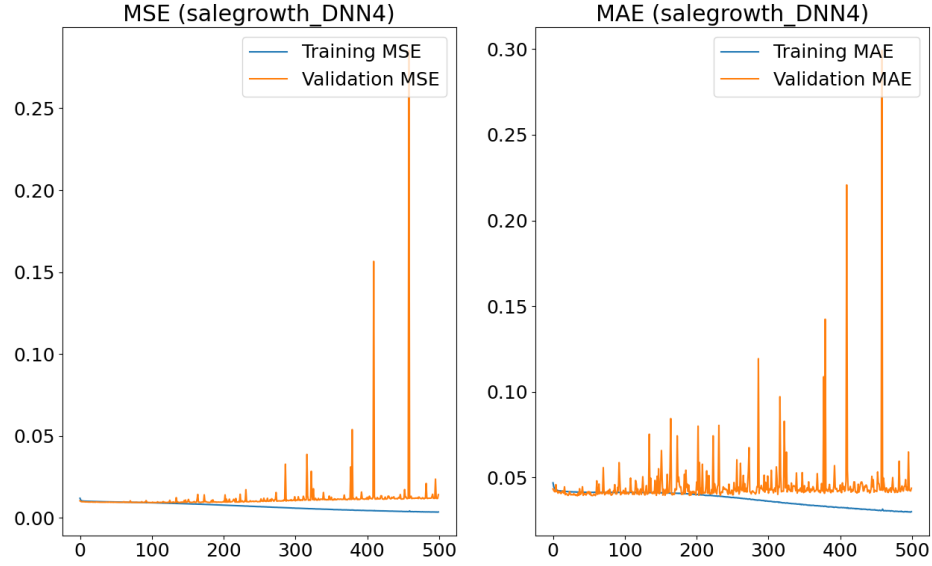


Figure 2.25: The MSE and MAE loss function of the DNN[4] for predicting sales growth



Performance comparison. The MSE, RMSE, MAE of linear regression, neural networks, and CART models for predicting sales growth are shown in Table 2.48. It is obvious that CART and neural networks outperform linear regression models in predicting sales growth with any given split ratios and in terms of any given error measures. Comparison between CART and neural networks, it seems that CART have the best predictive models for 80/20 and 50/50 split ratios, and for 90/10 split ratio in terms of MAE. Meanwhile, neural networks are only better than CART for 90/10 split ratio in terms of MSE or RMSE. In general, CART seem to be the best predictive models in predicting sales growth in comparison to linear regression and neural networks.

Table 2.48: Comparison of models performance on the test data for predicting sales growth

	80/20 split			90/10 split			50/50 split		
	MSE	RMSE	MAE	MSE	RMSE	MAE	MSE	RMSE	MAE
Regression	0.0103	0.1016	0.0420	0.0104	0.1019	0.0420	0.0102	0.1008	0.0421
CART	0.0098	0.0991	0.0407	0.0102	0.1010	0.0417	0.0094	0.0967	0.0400
<i>Change</i>	-4.85%	-2.46%	-3.09%	-1.92%	-0.88%	-0.71%	-7.84%	-4.07%	-4.99%
ANN	0.0100	0.1000	0.0414	0.0103	0.1015	0.0417	0.0099	0.0995	0.0409
<i>Change</i>	-2.91%	-1.57%	-1.43%	-0.96%	-0.39%	-0.71%	-2.94%	-1.29%	-2.85%
DNN[2]	0.0100	0.1000	0.0417	0.0103	0.1015	0.0415	0.0099	0.0995	0.0412
<i>Change</i>	-2.91%	-1.57%	-0.71%	-0.96%	-0.39%	-1.19%	-2.94%	-1.29%	-2.14%
DNN[3]	0.0100	0.1000	0.0412	0.0103	0.1015	0.0416	0.0100	0.1000	0.0416
<i>Change</i>	-2.91%	-1.57%	-1.90%	-0.96%	-0.39%	-0.95%	-1.96%	-0.79%	-1.19%
DNN[4]	0.0100	0.1000	0.0412	0.0104	0.1019	0.0407	0.0100	0.1000	0.0410
<i>Change</i>	-2.91%	-1.57%	-1.90%	0.00%	0.00%	-3.09%	-1.96%	-0.79%	-2.61%

In summary, comparing Table 2.36, Table 2.40, Table 2.44, and Table 2.48 yields three noticeable results. First, it is obvious and robust that neural networks and CART models outperform linear regression models in predicting any given firm performance criteria with any given split ratios and in terms of any given error measures. This finding is consistent with many previous studies (Hill et al. 1996; Desai and Bharati 1998; Fadlalla and Lin 2001; Weatherford et al. 2003; Razi and Athappilly 2005; Anyaeche and Ighravwe 2013; Pombeiro et al. 2017). Second, in general, neural networks are better than CART when the split ratio is 80/20 or 90/10 in predicting ROA, EBITAT, and Tobin’s Q while CART are better than neural networks in predicting ROA, EBITAT, and Tobin’s Q when the split ratio is 50/50. Third, for predicting sales growth, it seems that CART are better than neural networks when the split ratio is 80/20 or 50/50. Meanwhile neural networks seem to be better predictive models when the split ratio is 90/10.

2.5 Discussion

2.5.1 The effects of natural disasters on firm performance revisited

In the introduction section, we know that, at the firm level, the effect of natural disasters on firm performance is mixed or insignificant but these findings might be misleading. One of the reasons is that many previous studies only examine one particular type of disaster or one specific area or in a short period of time; therefore the findings might not be general enough. For example, Noth and Rehbein (2019) only study a major flood in Germany in only one year in 2013. Therefore, their results might not be general enough for the whole picture of general natural disasters. Similarly, Zhou and Botzen (2021) and Leiter et al. (2009) only focus on flooding, but not other types of disasters. Our study, however, considers disasters in its general sense which include all main types of natural disasters such as drought, flooding, freeze, severe storm, tropical cyclone, wildfire, and winter storm.

It is necessary to address that even though the relationships between disasters and firm performance are in the sense of correlations, they indeed have a cause and effect relationship. It is impossible that firms’ ROA causes natural disasters since natural disasters are exogenous shocks. Firm profitability cannot cause disasters. Hence, the conclusion is that both actual and reporting disasters negatively impact the firm’s ROA in the next year.

2.5.2 Objective versus perceived natural environmental uncertainty revisited

The results in this study shows the importance of both *numerical* and *textual* data in accessing the effects of the natural environmental uncertainty on firm performance. Most of previous studies only examine either numerical or textual data in predicting firm performance. The implication is that we should pay more attention on textual data, specifically Form 10-Ks and their roles in firm performance analysis as shown, for example,

in [Feldman et al. \(2010\)](#), [Loughran and McDonald \(2011\)](#), [Bochkay and Levin \(2019\)](#), [Choi et al. \(2020\)](#), [Cohen et al. \(2020\)](#), and [Cho and Muslu \(2021\)](#).

More importantly, this is probably the first study investigating the *jointly* effects of the actual *and* perceived natural environmental uncertainty. This implies there is a big gap in the literature since, to the best of my knowledge, there are no previous studies in the literature that consider these two natural environmental uncertainties at the same time. This study partially helps to fill this gap. Our results actually indicate that both of the natural environmental uncertainties simultaneously impact on firm performance.

2.5.3 CART and neural networks vs. linear regression

Generally, in most models, CART and neural network models outperform linear regression in predicting any given firm performance criteria. This finding is consistent with the current literature on comparison between neural networks and linear regression (e.g. ([Hill et al. 1996](#); [Fadlalla and Lin 2001](#); [Doganis et al. 2006](#); [Anyaeche and Ighravwe 2013](#); [Pombeiro et al. 2017](#))). It also shows that neural networks are suitable tools for forecasting in finance and economics as discussed by [Li and Ma \(2010\)](#).

2.5.4 The importance of the holistic approach

One of the essential contributions of this study is employing the holistic approach for firm performance modeling under actual and perceived environmental uncertainty. In this study, we examine four different criteria of firm performance including ROA, EBITAT, Tobin's Q, and sales growth. The first two criteria (ROA and EBITAT) represent the *profitability* of a firm. Tobin's Q represents the *investment opportunity* of a firm. Meanwhile, sales growth reflects the *operational efficiency* of a firm. These all criteria are essential to evaluate how well a firm performs. If only one in these four criteria is used to evaluate the performance of a firm, the comparison among models might be biased or not general enough.

Another aspect of the holistic approach in this research is that employing different models, including linear regression, CART, and neural networks, allows us to choose the suitable model(s) for each firm performance criterion. Particularly, as shown in the results section, sales growth performs best with the CART model while Tobin's Q performs best with NNs. Moreover, ROA and EBITAT are predicted best by either neural networks or CART depending on the error measure metrics. Using multiple models together with multiple criteria in evaluating firm performance prediction provides the robust and unbiased (or probably less biased) results.

2.6 Conclusion

This study proposes a new dictionary of words related to natural hazards and disasters. Thus, the text mining technique is used to count the number of words in Form 10-Ks which also appear in the dictionary. The constructed indicator is called the perceived risk of natural disasters. This textual measure of perceived risk of natural disasters is combined with the government-reported damages of natural hazards and disasters, and a number of control variables to predict the effects of natural hazards and disasters on the U.S firm performance in the 1993-2021 period.

We find that this self-reported perceived risk of natural hazards and disasters and government-reported of the damages of natural hazards in the current year are negatively associated with firm profitability next year. However, the perceived risk indicator is not associated with sales growth and Tobin’s Q ratio. In particular, the perceived risk of natural hazards and disasters negatively affect firm profitability in the services sector but not in the manufacturing sector. The firm profitability in the services sector is also negatively affected by the billion-dollar natural disasters in the same year but not in the previous year. This implies that there is a lag effect of perceived risk of natural disasters on firm profitability in the services sector while there is no lag effect of the government-reported damages of the billion-dollar natural disasters on firm profitability in this sector. Finally, we find that CART and neural networks robustly outperform linear regression in predicting firm performance under natural disaster risks. The main suggestion from this study is that we can use textual data in financial reports (e.g Form 10-K filings) to measure the perceived risk of natural disasters and predict its effects on general firm performance and firm profitability specifically.

As would be expected, this study contains several limitations that pave several ways for potential future works. Future works might use the factory-level data set rather than the firm-level one to capture the situation that a firm has the headquarter in one location but have factories in several locations. One also explores the causal relationship between natural hazards and disasters and firm performance by using several techniques like instrumental variables or causal machine learning.

Appendices

Appendix 1.1 An illustration of Form 10-K (Alphabet Inc. and Google Inc.)

**UNITED STATES
SECURITIES AND EXCHANGE COMMISSION**
Washington, D.C. 20549

FORM 10-K

ANNUAL REPORT PURSUANT TO SECTION 13 OR 15(d) OF THE SECURITIES EXCHANGE ACT OF 1934

For the fiscal year ended December 31, 2021

OR

TRANSITION REPORT PURSUANT TO SECTION 13 OR 15(d) OF THE SECURITIES EXCHANGE ACT OF 1934

For the transition period from _____ to _____.

Commission file number: **001-37580**

Alphabet Inc.

(Exact name of registrant as specified in its charter)

Delaware

(State or other jurisdiction of incorporation or organization)

61-1767919

(I.R.S. Employer Identification No.)

1600 Amphitheatre Parkway

Mountain View, CA 94043

(Address of principal executive offices, including zip code)

(650) 253-0000

(Registrant's telephone number, including area code)

Securities registered pursuant to Section 12(b) of the Act:

Source: SEC

Appendix 1.2 An illustration of the content in a Form 10-K.

Figure 2.26: The content of a Form 10-K

Alphabet Inc.	
Form 10-K	
For the Fiscal Year Ended December 31, 2021	
TABLE OF CONTENTS	
<u>Note About Forward-Looking Statements</u>	
PART I	
Item 1.	<u>Business</u>
Item 1A.	<u>Risk Factors</u>
Item 1B.	<u>Unresolved Staff Comments</u>
Item 2.	<u>Properties</u>
Item 3.	<u>Legal Proceedings</u>
Item 4.	<u>Mine Safety Disclosures</u>
PART II	
Item 5.	<u>Market for Registrant's Common Equity, Related Stockholder Matters and Issuer Purchases of Equity Securities</u>
Item 6.	<u>[Reserved]</u>
Item 7.	<u>Management's Discussion and Analysis of Financial Condition and Results of Operations</u>
Item 7A.	<u>Quantitative and Qualitative Disclosures About Market Risk</u>
Item 8.	<u>Financial Statements and Supplementary Data</u>
Item 9.	<u>Changes in and Disagreements With Accountants on Accounting and Financial Disclosure</u>
Item 9A.	<u>Controls and Procedures</u>
Item 9B.	<u>Other Information</u>
Item 9C.	<u>Disclosure Regarding Foreign Jurisdictions that Prevent Inspections</u>
PART III	
Item 10.	<u>Directors, Executive Officers and Corporate Governance</u>
Item 11.	<u>Executive Compensation</u>
Item 12.	<u>Security Ownership of Certain Beneficial Owners and Management and Related Stockholder Matters</u>
Item 13.	<u>Certain Relationships and Related Transactions, and Director Independence</u>
Item 14.	<u>Principal Accountant Fees and Services</u>
PART IV	
Item 15.	<u>Exhibits, Financial Statement Schedules</u>
Item 16.	<u>Form 10-K Summary</u>

Source: SEC

Appendix 2. Two-digit SIC codes³¹

Table 2.49: Two-digit SIC codes and corresponding industries

Two-digit SIC code	Industry
01	Agricultural Production - Crops
02	Agricultural Production - Livestock
07	Agricultural Services
08	Forestry
09	Fishing, Hunting and Trapping
10	Metal Mining
12	Bituminous Coal and Lignite Mining
13	Oil and Gas Extraction
14	Mining and Quarrying of Nonmetallic Minerals, except Fuels
15	Building Construction General Contractors and Operative Builders
16	Heavy Construction other than Building Construction Contractors
17	Construction Special Trade Contractors
20	Food and Kindred Products
21	Tobacco Products
22	Textile Mill Products
23	Apparel and other Finished Products Made from Fabrics and Similar Materials
24	Lumber and Wood Products, except Furniture
25	Furniture and Fixtures
26	Paper and Allied Products
27	Printing, Publishing, and Allied Industries
28	Chemicals and Allied Products
29	Petroleum Refining and Related Industries
30	Rubber and Miscellaneous Plastics Products
31	Leather and Leather Products
32	Stone, Clay, Glass, and Concrete Products
33	Primary Metal Industries
34	Fabricated Metal Products, except Machinery and Transportation Equipment
35	Industrial and Commercial Machinery and Computer Equipment
36	Electronic and other Electrical Equipment and Components, except Computer Equipment
37	Transportation Equipment
38	Measuring, Analyzing, and Controlling Instruments; Photographic, Medical and Optical Goods; Watches and Clocks
39	Miscellaneous Manufacturing Industries
40	Railroad Transportation
41	Local and Suburban Transit and Interurban Highway Passenger Transportation
42	Motor Freight Transportation and Warehousing

³¹See <https://siccode.com/>

Appendix 2. Two-digit SIC codes (cont.)

Table 2.50: Two-digit SIC codes and corresponding industries (cont.)

Two-digit SIC code	Industry
43	United States Postal Service
44	Water Transportation
45	Transportation by Air
46	Pipelines, except Natural Gas
47	Transportation Services
48	Communications
49	Electric, Gas and Sanitary Services
50	Wholesale Trade-Durable Goods
51	Wholesale Trade-Nondurable Goods
52	Building Materials, Hardware, Garden Supply, and Mobile Home Dealers
53	General Merchandise Stores
54	Food Stores
55	Automotive Dealers and Gasoline Service Stations
56	Apparel and Accessory Stores
57	Home Furniture, Furnishings, and Equipment Stores
58	Eating and Drinking Places
59	Miscellaneous Retail
70	Hotels, Rooming Houses, Camps, and other Lodging Places
72	Personal Services
73	Business Services
75	Automotive Repair, Services, and Parking
76	Miscellaneous Repair Services
78	Motion Pictures
79	Amusement and Recreation Services
80	Health Services
81	Legal Services
82	Educational Services
83	Social Services
84	Museums, Art Galleries, and Botanical and Zoological Gardens
86	Membership Organizations
87	Engineering, Accounting, Research, Management, and Related Services
88	Private Households
89	Miscellaneous Services

Notes: These SIC codes exclude the Finance, Insurance, Real Estate sector (two-digit SIC code from 60 to 67) and Public Administration sector (two-digit SIC code from 91 to 99). The reason is that companies in the Finance, Insurance, Real Estate sector usually have dissimilar patterns of capital structures compared to companies from other sectors. For the companies in the Public Administration sector, their goals might be not profit or not only profit (profit might be less important than other goals for example social welfare).

Appendix 3. Histograms of independent variables of Model 2-4

Figure 2.27: Heat map of the original features of Model 2 (EBITAT)

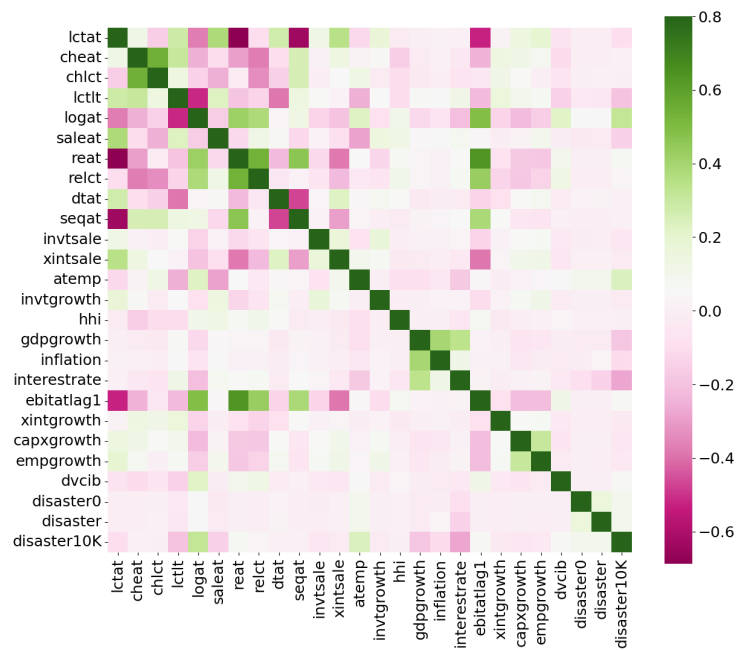


Figure 2.28: Heat map of the original features of Model 3 (Tobin's Q)

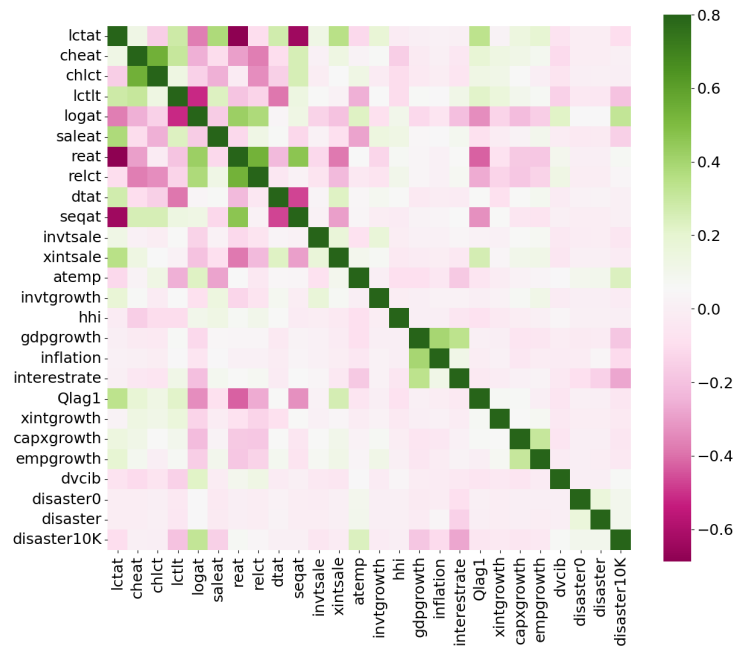
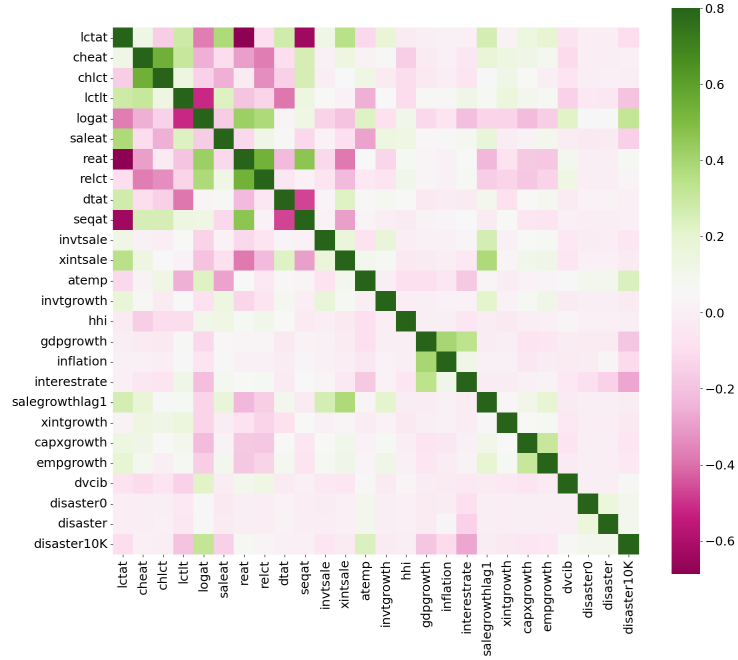


Figure 2.29: Heat map of the original features of Model 4 (sales growth)



Appendix 4: Top 20 VIFs for the case of damages of natural hazards.

Table 2.51: Top 20 VIF's values for linear regression models for the case of natural hazards

Model 5	VIF	Model 6	VIF	Model 7	VIF	Model 8	VIF
lctl	6.881487	lctl	6.890518	lctl	7.278854	lctl	6.910421
inflation	6.691684	inflation	6.688276	inflation	6.682604	inflation	6.670935
logat	6.391205	logat	6.488870	logat	6.287555	logat	6.320445
lctat	6.205631	lctat	6.203778	lctat	6.097546	lctat	6.164566
seqat	4.287896	seqat	4.283971	seqat	4.410722	seqat	4.305235
interestrate	4.169784	interestrate	4.166773	interestrate	4.165903	interestrate	4.170176
reat	3.866809	reat	3.895254	reat	3.823880	reat	3.755915
gdpgrowth	3.699480	gdpgrowth	3.698220	gdpgrowth	3.699915	gdpgrowth	3.698156
saleat	3.579374	saleat	3.636816	saleat	3.548044	saleat	3.594935
cheat	3.229502	cheat	3.239009	cheat	3.231313	cheat	3.238179
hhi	2.683497	hhi	2.685514	hhi	2.682847	hhi	2.682481
dtat	2.319157	dtat	2.318606	dtat	2.320167	dtat	2.319864
relct	2.268091	relct	2.282542	relct	2.232440	relct	2.230530
chlct	2.176366	ebitatlag1	2.239430	chlct	2.186312	chlct	2.168748
roalag1	2.133635	chlct	2.177203	Qlag1	2.084342	disaster10K	1.695737
disaster10K	1.699093	disaster10K	1.701731	disaster10K	1.697062	invtsale	1.609227
invtsale	1.566088	invtsale	1.569528	invtsale	1.563703	atemp	1.551872
atemp	1.549942	atemp	1.549855	atemp	1.550098	xintsale	1.543207
xintsale	1.416533	xintsale	1.410274	xintsale	1.399127	salegrowthlag1	1.397037
capxgrowth	1.227708	capxgrowth	1.228246	capxgrowth	1.224133	capxgrowth	1.224133

Appendix 5: The frequency of natural disaster words/phrases

Word/Phrase	Word count	Word/Phrase	Word count	Word/Phrase	Word count
disasters	126,207	extreme temperatures	1228	rainfalls	96
wind	100,011	landfall	1,193	lava flow	86
disaster	76,652	high winds	1,105	avalanches	80
climate change	61,559	thunderstorms	1,102	gale	78
hurricanes	56,363	blizzards	1,053	debacle	64
flood	55,596	tremor	1,008	rainstorm	57
earthquake	47,391	cyclone	988	disaster risk	55
earthquakes	46,352	typhoon	946	extreme rain	47
storm	45,501	whirlpool	922	gales	47
floods	37,389	natural hazards	878	landfalls	47
storms	28,197	fog	761	firestorms	46
hurricane	24,951	mudslides	761	hazard mitigation	46
freeze	20,829	forest fires	640	rock fall	32
flooding	18,280	cyclones	616	twister	31
snow	17,748	snowstorms	577	microbursts	26
drought	13,426	extreme heat	548	La Nina	25
tornadoes	11,609	heavy rainfall	544	ash fall	21
extreme weather	11,159	heavy snow	523	cold waves	18
freezing	8,739	volcano	457	extreme rainfall	16
volcanic	7,724	avalanche	405	fogs	16
windstorm	7,046	derechos	401	winterstorm	12
rainfall	6,835	extreme temperature	395	air burst	9
wildfires	6,645	landslide	389	airburst	9
hail	6,582	heat waves	364	floodings	9
global warming	6,159	forest fire	348	adaptive capacity	8
droughts	5,768	rainstorms	346	apocalypse	8
windstorms	4,882	snowstorm	343	volcanos	8
tornado	4,756	hailstorm	330	climate warms	7
tsunamis	3,420	El Nino	310	cold wave	6
winds	3,412	natural hazard	270	extreme rains	5
tsunami	3,184	whirlpools	241	firestorm	5
freezes	3,114	mudslide	226	cataclysms	3
typhoons	3,062	high wind	214	debacles	3
wildfire	2,537	blizzard	213	cataclysm	2
derecho	2,225	thunderstorm	204	seiche	2
landslides	2,055	lava flows	172	ashfall	1
calamity	2,008	disaster risks	155	microburst	1
hailstorms	1,477	coastal erosion	146	rockfall	1
flooded	1,309	heat wave	144	rockfalls	1
				rogue waves	1

Table 2.52: The frequency of words/phrases related to natural disasters in Form 10-Ks

Chapter 3

Corporate financial distress prediction in a transition economy

Abstract

Forecasting the financial distress of corporations is a difficult task in economies undergoing transition, as data is scarce and highly imbalanced. This research tackles these difficulties by gathering reliable financial distress data in the context of a transition economy and employing the synthetic minority oversampling technique (SMOTE). The study employs five different models, including linear discriminant analysis (LDA), logistic regression, support vector machines (SVM), neural networks, and the Merton model, to predict financial distress of public firms in Vietnam between 2011 and 2021. The first four models use accounting-based variables, while the Merton model utilizes market-based variables. The findings indicate that while all models perform fairly well in predicting results for non-delisted firms, they perform somewhat poorly in predicting results for delisted firms in terms of various accuracy measures such as balanced accuracy, precision, recall, and F_1 score. The study shows that the models that incorporate both the Altman's and Ohlson's variables consistently outperform those that only use the Altman's or Ohlson's variables in terms of balanced accuracy. Additionally, the study finds that neural networks are consistently the most effective models in terms of both balanced accuracy and Matthews correlation coefficient (MCC). The most important variable in Altman's variables as well as the combination of the Altman's and Ohlson's variables is **reat** (retained earnings over total assets), whereas **ltat** (total liabilities over total assets) and **wcapat** (working capital over total assets) are the most important variables in Ohlson's variables. The study also reveals that in most cases, the models perform better in predicting results for big firms than for small firms, and for good years than for bad years in terms of MCC.

Keywords: financial distress, transition economy, Altman's variables, Ohlson's variables, Merton model, machine learning.

JEL Codes: C45, C53, G33, M21.

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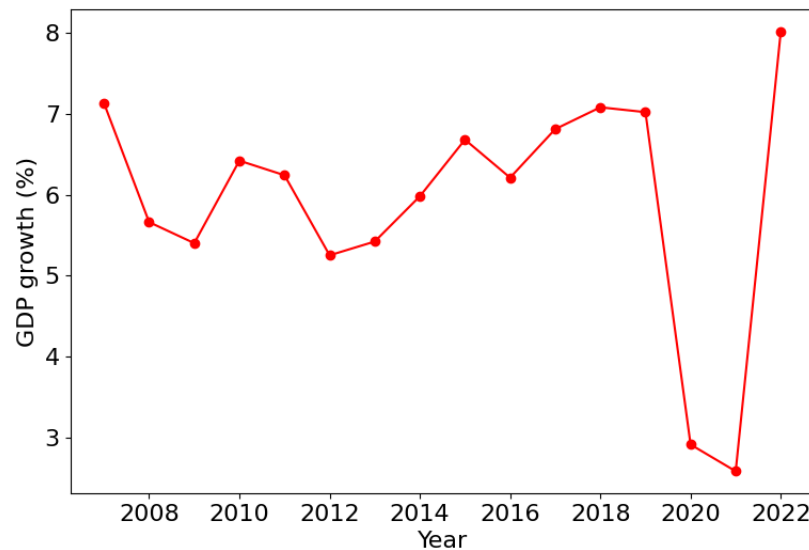
3.1 Introduction

3.1.1 Motivations

Corporate financial distress prediction is very critical in corporate risk management. It is even more critical in transition economies where data is limited and might not be reliable¹. This task is more challenging in the economic distress periods.

In the last fifteen years, Vietnam experienced some economic distress periods including the 2008-2009 financial crisis, macroeconomic economic fluctuation in 2012-2014, and the COVID-19 pandemic in 2020-2021. Table 3.1 shows the GDP growth of Vietnam's economy in the 2007-2022 period. This dynamic market is also a challenge for all entities in that market. The need to predict the stable performance of companies is essential in many activities such as when making investment decisions, financing decisions, and lending decisions. The main goal of this study is to explore models to predict the corporate financial distress of the public firms in Vietnam during the period with several economic distress. Since firms tend to face financial distress situations during economic distress periods, this study is necessary to understand the financial health status when the economic conditions are not good. Our study focuses on Vietnam as an example of a transition economy in which the legal regulations, economic conditions, and availability of data are very different compared to that in many advanced economies.

Figure 3.1: GDP growth of Vietnam's economy between 2007 and 2022



Source: The World Bank

¹ A transition economy is an economy that is transforming from a centrally planned economy to a market economy. In East and South-East Asia, there are four transition economies including Cambodia, China, Laos, and Vietnam. There are other 25 transition economies in other areas on over the world. For more details, see <https://www.imf.org/external/np/exr/ib/2000/110300.htm>.

Since the bankruptcy data in many developing and transition economies like Vietnam is usually either not available or not reliable as in many developed economies like the United States, this study focuses on the corporate financial distress probability rather than the corporate bankruptcy probability. We consider firms delisted on the stock markets due to financial reasons as financial distress firms and firms not delisted on the stock markets due to financial reasons as non-financial distress firms.

3.1.2 Related literature

Financial distress vs. bankruptcy prediction

Although existing research efforts with solid data have been put on financial distress in advanced economies (e.g. [Opler and Titman 1994](#); [Altman et al. 2019](#)), little reliable notice has been paid to financial distress in transition economies and developing countries, where normally there is a lack of reliable data and unstable bankruptcy law, especially under economic shocks. To the best of our knowledge, this study is the first of its kind in Vietnam. It is noticeable that the bankruptcy procedure of Vietnam's Law on Bankruptcy in 2014 is clear, but it has rarely been implemented in reality. Therefore, it is infeasible to collect the data of bankruptcy cases in Vietnam. That is why this study focuses on corporate financial distress rather than corporate bankruptcy. Since financial distress is more realistic and practical in transition economies like Vietnam than bankruptcy, it is more meaningful to find suitable models to predict financial distress rather than bankruptcy. Moreover, financial distress normally is the status before bankruptcy, therefore financial distress prediction is also meaningful in the context that firms can be aware of it as the early warning signal to avoid going bankrupt. Note that since prolonged corporate financial distress might eventually lead to corporate bankruptcy this research is based on the framework of default risk or default probability.

Accounting-based models

There are two main approaches in studying corporate bankruptcy prediction which uses accounting-based variables (e.g. [Altman 1968](#); [Ohlson 1980](#)) and market-based variables (e.g. [Merton 1974](#))². Each method has its own strengths and weaknesses. Indeed, choosing which to build the prediction model is not an easy task.

[Altman \(1968\)](#) pioneers in studying the prediction of corporate bankruptcy and financial distress by using the method of multivariate discriminant analysis (MDA). This statistical technique categorizes variables into groups (or indicators) which reduces the dimensionality

²Note that we consider the machine learning models that base on the accounting-based variables as the accounting-based models. That is, in this study, the accounting-based models include both accounting models like [Altman \(1968\)](#) and [Ohlson \(1980\)](#), and also the machine learning models using accounting-based variables.

of high-dimension datasets³. In this study, Altman discriminates firms into three zones including “non-bankrupt”, “zone of ignorance”, and “grey area” (Altman 1968). He argues that the financial health of a company is reflected by five financial indicators, four of which can only be constructed from one-year financial statements and one needed equity market values. The subsequent studies expand Altman (1968) in many various ways. Systematically, one can see the evolution of the Altman Z-score family in Chapter 10 in Altman et al. (2019).

There are many accounting-based studies about financial distress and bankruptcy prediction after Altman (1968) such as Ohlson (1980), Zmijewski (1984), Altman et al. (2017), and many others. Among these studies, Ohlson (1980) is the most typical accounting-based work after Altman (1968). In this study, Ohlson uses the logistic regression rather than the multivariate discriminant analysis method as that in Altman (1968).

Market-based models

The Black-Scholes-Merton (BSM) model is a structural credit risk model and is a continuous market model. In a seminal work, Black and Scholes (1973) derives a theoretical valuation formula for options called the Black-Scholes option pricing equation. But it can also be applied to corporate liabilities such as common stock, corporate bonds, and warrants. Inspired by this Black and Scholes’s pioneer work, Merton (1974) builds a structural model to estimate the continuous probability of default which is derived from the distance-to-default calculation. Note that in this study the BSM model and Merton model are interchangeable. But the Merton model is mostly used. One of the underlying assumptions of the Merton model is that the total value of a firm follows a geometric Brownian motion of the form

$$dV = \mu_V V dt + \sigma_V V dW,$$

where V is the total value of a firm, μ_V and σ_V are the expected return and the volatility, and dW is the standard Wiener process. Many recent studies about the distance to default admit this standard assumption, for example, Bharath and Shumway (2008) and Vassalou and Xing (2004). Our study also bases on this fundamental assumption.

Based on the BSM model, the KMV-Merton model⁴ focuses on the default probability of corporate liabilities (e.g. debt) in the canonical Merton model, the KMV-Merton model investigates the probability of default of an individual company as a whole (Kealhofer 2003).

³Indeed, in the modern economy, it is complicated to categorize millions of firms into millions of financial health levels. In this case, categorizing all firms into a few groups is a common and useful statistical technique to analyze high-dimensional datasets that consist of many variables. This technique enables one to investigate whether there are significant differences among groups.

⁴The term KMV stands for Kealhofer, McQuown and Vasicek, who are the founders of the KMV corporation. KMV Corporation was acquired by Moody’s Corporation in 2002.

In this model, the value of the company’s stock equity and debt are modeled as a long call option and a short put option on the firm’s assets, respectively.

When the expected value (unobservable) of the firm is less than the firm’s debt, shareholders would choose not to repay (not exercise their call option) while when the firm’s value is greater than the firm’s debt, they would choose to repay (exercise their call option). That is, ultimately the shareholders’ gain equals $\max\{\text{Value}(T) - \text{Debt}(T), 0\}$, where $\text{Value}(T)$ and $\text{Debt}(T)$ are the expected value of the firm and the firm’s debt at time T , respectively.

The KMV-Merton model is probably the most famous application of the Merton model in the financial sector. Our study will explore the KMV-Merton model and apply it in a transition economy. The KMV-Merton model is used widely in practice and is used broadly by the Big-Three credit rating agencies including Standard & Poor’s, Fitch, and Moody’s. Some recent studies related to the KMV-Merton model are [Kealhofer \(2003\)](#), [Tudela and Young \(2005\)](#), [Benos and Papanastasopoulos \(2007\)](#), [Bharath and Shumway \(2008\)](#), [Lee \(2011\)](#), and [Yeh et al. \(2012\)](#).

Accounting-based vs. Market-based models

The accounting-based models (e.g [Altman 1968](#)) and market-based models (e.g KMV-Merton model) are different in many aspects. Table 3.1 shows some differences between these two types of models.

Table 3.1: Comparison the accounting-based and market-based models

	Accounting-based model	Market-based model
Firm’s equity	Book value	Market value
Firm’s debt	Book values	(Estimated) market values
Volatility of firm’s assets	No	Yes
Frequency of data	Quarterly, yearly	Daily

Regarding the ability to estimate the default probability, some studies find that the Merton-type model outperforms the Altman-type model ([Hillegeist et al. 2004](#); [Tanthanongsakkun et al. 2011](#)). Specifically, [Hillegeist et al. \(2004\)](#) discover that the BSM option-pricing model provides significantly more information than Altman’s (1968) Z-Score and Ohlson’s (1980) O-Score. Also, [Tanthanongsakkun et al. \(2011\)](#) detects that the Merton model is the most informative model in explaining corporate bankruptcy compared to other models, which include the Altman model. However, some studies find that the Altman-type model outperforms the Merton model. For example, [Reisz and Perlich \(2007\)](#) estimate probabilities of bankruptcy for 5,784 industrial firms in the period 1988–2002. They find that Altman Z -and Z'' -scores outperform structural models in 1-year-ahead bankruptcy predictions compared to BSM models.

Some studies show that the hybrid model (combine accounting-based and market-based models) outperforms either separate accounting-based or market-based models. For example, [Shumway \(2001\)](#) shows that combining accounting and market variables results in the most accurate model.

Financial distress prediction in Vietnam

While financial distress prediction studies, especially those studies using machine learning methods, are popular in many other transition economies in decades ([Gruszczyński 2004](#); [Chen et al. 2006](#); [Wang and Li 2007](#); [Zheng and Yanhui 2007](#); [Li and Sun 2008](#); [Xie et al. 2011](#); [Sun et al. 2011](#)), there are relatively few and late studies in Vietnam.

For Vietnam’s stock market, the previous studies about financial distress or default probability can be classified into four groups. The first group uses the Altman model approach (e.g. Z-score or Z”-score model), the second group utilizes the Ohlson-type approach (i.e. logistic regression or logit), the third group employs the KMV-Merton model approach, and the fourth group examines other models (e.g. mixed models and machine learning models). Despite some effort has been made, there is a scarcity of reliable empirical results in many studies in all four groups.

All studies in the first group that we found use the given coefficients and thresholds from Altman’s and related studies, especially [Altman \(1968\)](#) ([Lieu 2014](#); [Vo and Nguyen 2014](#); [Nguyen 2015](#); [Hoang 2020](#)). This is clearly a big limitation since, for example, the coefficients of variables and the Z-score thresholds derived from 66 firms in one sector (manufacturing) in the 1960s in a developed country like the United States [Altman \(1968\)](#) are not necessarily the same as those derived from firms at the moment and for the whole stock market in a transition economy like Vietnam. It is vital to note that the Z-score model ([Altman 1968](#)) is a data-dependent formula, which is definitely not like a universal formula in mathematics. Therefore, that formula works in a particular market or country in a specific period does not necessarily mean it works in another (or even the same) market or country in another period. Using coefficients and thresholds of [Altman \(1968\)](#) or of any other studies to apply to other datasets might lead to misleading and unreliable conclusions.

For the second approach, there are relatively few studies compared to the first approach. Some studies using logistic regression include [Vo \(2015\)](#) and [Vo et al. \(2019\)](#). Both work on highly imbalanced data. [Vo \(2015\)](#) works on the data including 946 non-distress observations and 36 distress observations and [Vo et al. \(2019\)](#) work on the data including 1,572 non-distress observations and 3,718 distress observations. Unfortunately, the authors in both studies do not do anything to take imbalanced data into account. Their results, therefore, tend to be biased toward the majority group (non-distress firms). This implies that their results, especially accuracy in [Vo et al. \(2019\)](#), seem unreliable to evaluate the predictive performances of their models.

There are a number of studies investigating the probability of default using KMV-Merton model in Vietnam (Lam and Phan 2009; Le and Le 2012; Nguyen and Pham 2014; Nguyen and Nguyen 2017; Vu et al. 2019). Unfortunately, the results in these studies lack reliability and/or verification. To the best of our knowledge, Lam and Phan (2009) is the first study considering the KMV-Merton model in Vietnam but this paper actually discusses very little about the KMV-Merton model. Le and Le (2012) claim that they combine CVaR and KMV-Merton model to examine the corporate default probability. However, the paper clearly did not derive any results related to the KMV-Merton model. Also, the authors claim that CVaR is better VaR to estimate the default probability under shock. This is an overclaim since they did not compare CVaR and VaR explicitly in their study. Nguyen and Pham (2014) analyze 6,398 listed and unlisted firms as corporate customers of a bank named Vietcombank in Vietnam and find that the probability of default of the whole portfolio is 2.6%. This study, however, does not verify the results or show the accuracy of the prediction.

Regarding the other approaches, Ninh et al. (2018) uses a combination of accounting, market, and macroeconomic variables to examine the corporate financial distress of 800 listed firms on Vietnam’s stock market from 2003 to 2016. Unfortunately, the accounting-based model borrows the coefficients and thresholds in the Z' -score model rather than constructing from their own datasets. Moreover, for the Merton model, it is not clear from the paper whether the authors estimate the firm value, expected rate of return, and volatility or not. Hence, the results related to the Merton model are inconclusive.

Delisted firms due to financial distress

Geng et al. (2015) study the “special treatment” firms on China’s stock markets. These firms are considered as special ones due to several reasons including two years of losses, damaged business, or financially bankrupt. Hosaka (2019) considers delisted firms with the reasons of (1) bankruptcy or rehabilitation or reorganization procedures, (2) excessive debt, (3) suspension of bank transactions, (4) termination of business activities (excluding mergers) as bankrupt firms in this study.

Table 3.2: Delisted reasons for bankruptcy in several studies

Country	Study	Delisted reason
United States	Mai et al. (2019)	Bankruptcy and liquidation
Japan	Hosaka (2019)	Bankruptcy/rehabilitation/reorganization procedures, excessive debt, suspension of bank transactions, and termination of business activities
China	Geng et al. (2015)	Two years of losses, damaged business, financially bankrupt
Vietnam	This study	Negative profit in three consecutive years or cumulative loss (negative profit) is greater than authorized capital

Sample size of bankrupt vs. non-bankrupt firms

In the literature on financial distress and bankruptcy prediction, there are both studies with equal bankrupt (or distress) and non-bankrupt (or non-distress) firms. The good news for imbalanced data is that there are several techniques for balancing data (e.g. synthetic minority oversampling technique or SMOTE) or balancing results (e.g. balanced accuracy). In this study, we use SMOTE as a technique for balancing train data⁵. That is, by using SMOTE, the number of observations of delisted firms is equal to that of non-delisted firms. We will discuss more about SMOTE and how to use it for balancing data later.

Table 3.3: Number of bankrupt and non-bankrupt firms in the related literature

BR	NB	Matched-pairs design	Period	Years prior to bankruptcy	Method	Source
79	79	Yes	1954-1964	1-5	UDA	Beaver (1966)
33	33	Yes	1946-1965	1-2	MDA	Altman (1968)
162	162	Yes	1956-1976	1	LR	Collins (1980)
105	2058	No	1970-1976	1-2	Logit model	Ohlson (1980)
1600	81	No	1972-1978	NA	Probit model	Zmijewski (1984)
65	64	Yes	1975-1982	1	NN	Odom and Sharda (1990)
65	64	Yes	1975-1982	1	NN	Wilson and Sharda (1994)
1160	1160	Yes	1996-1999	NA	SVM	Shin et al. (2005)
58	142	No	1971-1981	NA	Decision trees	Gepp et al. (2010)
107	107	Yes	2008-2011	3-5	DT, SVM, NN	Geng et al. (2015)
102	2062	No	2002-2016	4	CNN	Hosaka (2019)
76	983	No	2011-2021	1-3	Logit, Merton, LDA, SVM, NN	This study

Notes: BR and NB stand for the number of bankrupt and non-bankrupt firms, respectively; UDA stands for univariate discriminant analysis; MDA stands for multivariate discriminant analysis; NN stands for neural networks; SVM stands for support vector machines; DT stands for decision trees; DA stands for discriminant analysis; LR stands for logistic regression.

Overall, our goal is to explore and compare the predictive performance of various models in predicting corporate financial distress for public firms in Vietnam. The main research question is: What are the differences between accounting-based, market-based, and machine-learning models in predicting corporate financial distress in Vietnam?

Contributions. Our paper has three main contributions. First, this is the first study employing three methods, including accounting-based, market-based, and machine learning models, to investigate the financial distress of public firms in Vietnam. Second, this is also the first study employing the synthetic minority oversampling technique (SMOTE) to tackle

⁵This technique was first proposed by [Chawla et al. \(2002\)](#).

the biased results caused by imbalanced data on financial distress in Vietnam. Third, we provide explicit and new data for the Merton model, which is helpful for future research.

The remainder of this chapter is organized as follows. Section 3.2 present all methods that we use in this chapter. Section 3.3 describes the data and variables of all models. The results of all models are presented in Section 3.4. We then investigate the effects of firm size and macroeconomic situation on predictive performances in Section 3.5. Hence, we discuss some noticeable points of the chapter in Section 3.6 before concluding in Section 3.7.

3.2 Methods

In nature, the corporate financial distress prediction is a classification problem. Therefore, the goal of the models employed to predict corporate financial distress is to classify the firms into a bankrupt and non-bankrupt class. In order to do that this study employs various models including logistic regression, support vector machines (SVM), linear discriminant analysis (LDA), neural networks, and Merton model. We choose logistic regression and SVM since these are the benchmark methods for classification problems. We choose LDA since this method is relevant to the classic method of multiple discriminant analysis (MDA) used in the seminal work (Altman 1968). We choose neural networks since this is the typical method in machine learning and deep learning. Finally, the Merton model is the standard market-based method in the bankruptcy and financial distress prediction literature.

Note that the first four methods will work with the accounting-based variables. Therefore, we can consider these four methods as accounting-based models. However, one can consider logistic regression as the accounting-based method in the context of Ohlson (1980) and the other three (LDA, SVM, and NN) as machine learning (ML) methods. In this context, this study employs three kinds of models, including accounting-based, market-based, and machine-learning models.

Note also that this study focuses on a transition economy therefore we do not use the standard coefficients of Altman’s Z-Score and Ohlson O-Score model since these models are built in the context of developed economies. Using the coefficients in Altman (1968) or Ohlson (1980) as the formulas and then applying them to data in transition economies (and also developing countries) might not be a good idea. The reason is that the MDA method used in Altman (1968) and logistic regression used in Ohlson (1980) are statistical models in nature and the coefficients of these models surely depend on the input data. Therefore, for example, using coefficients obtained from a sample of 66 manufacturing firms in the United States in the 1960s (Altman 1968) and then applying for example in the retail industry in Vietnam in the 2020s might be a misleading idea since the data and context are totally different. Surprisingly, there are many studies like that out there, including most of the studies in the bankruptcy and financial distress literature in Vietnam.

The good news is that while using the coefficients from Altman’s and Ohlson’s models might not be a good idea, one can employ the variables used in these two standard models. The reason is that the list of Altman’s variables (working capital/total assets, retained earnings/total assets, earnings before interest and taxes/total assets, total sales/total assets, and market value of equity/total liabilities) and Ohlson’s variables (nine-factor financial and economic variables) represent for the fundamental factors that affect the firm’s activities and performances, which then affect the probabilities of going bankrupt or being financial distress. This study employs Altman’s and/or Ohlson’s variables as the independent variables for our chosen methods.

3.2.1 Logistic regression

Logistic regression is a probabilistic model that takes the linear combination of a list of variables (linear regression) and maps it to a sigmoid function. For example, given n independent variables, says X_1, \dots, X_n , the logistic regression given by

$$p(X_1, \dots, X_n) = \frac{1}{1 + e^{-(\beta_0 + \beta_1 X_1 + \dots + \beta_n X_n)}},$$

where $\beta_0, \beta_1, \dots, \beta_n$ are the coefficients of the corresponding linear regression. One can consider logistic regression as the benchmark for the classification problem.

3.2.2 Linear discriminant analysis

Linear discriminant analysis (LDA) was pioneered by Ronald Fisher in 1936 ([Fisher 1936](#)) for discriminating data with two classes. Thus, it is generalized by C. R. Rao, a Fisher’s student, for more than two classes of the model in [Rao \(1948\)](#).

This is a linear classification model and is used to find linear combinations of variables (or features) that classify two or more classes or groups. In the LDA model, input variables are assumed to be normally distributed. Another assumption is that the input variables should not be correlated with each other. That is, we should deal with the severe multicollinearity if it appears. Note that, in practice, data should be transformed (standardized and normalized) before training with the LDA model.

It is important to note that the normally distributed assumption is crucial when we want to estimate the magnitude of the marginal effects of the predictor variables. However, for prediction or classification purposes (as in this study), this assumption is less sensitive ([Shayan et al. 2016](#)). That is why, in practice, the LDA model might perform well even though the normally distributed assumption is violated.

It is necessary to note that LDA is different compared to both linear regression and logistic regression. LDA and logistics are techniques used for classification problems where the dependent variable is discrete (e.g. binary variable) while linear regression is used for

prediction/causal inference where the dependent variable is continuous. LDA requires the multivariate normality and equality of covariance matrices among groups whereas logistic regression does not.

3.2.3 Support vector machines

Support Vector Machines (SVM) is a type of supervised learning algorithm that can be used for classification and regression tasks. In the context of bankruptcy or financial distress prediction, SVM can be used to classify firms as either bankrupt (or distressed) or non-bankrupt (or non-distress) based on a set of variables such as the firm's financial characteristics, market and economic variables.

SVM is pioneered by [Boser et al. \(1992\)](#) and [Cortes and Vapnik \(1995\)](#). There are several types of SVM that have different kernels such as linear, polynomial, radial basis function (RBF), and sigmoid. In this study, we employ RBF SVM since it has a number of advantages compared to other types of SVM such as handling nonlinear relation between class labels, few hyperparameters, and few numerical difficulties ([Hsu et al. 2016](#)).

Formally, as shown in [Hsu et al. \(2016\)](#), given a train data $(\mathbf{x}_i, y_i), i = 1, \dots, l$ where $\mathbf{x}_i \in \mathbb{R}^n$ and $y \in \{1, -1\}^l$. RBF SVM requires the solution of the following optimization problem

$$\begin{aligned} \min_{\mathbf{w}, b, \xi} \quad & \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^l \xi_i, \\ \text{subject to} \quad & y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + b) \geq 1 + \xi_i, \\ & \xi_i \geq 0, \end{aligned}$$

where $C > 0$ is the penalty parameter of the error term, \mathbf{w} is the vector of weights, and b is a scalar, and with RBF kernel given by $K(\mathbf{x}_i, \mathbf{x}_j) = \exp(-\gamma \|\mathbf{x}_i - \mathbf{x}_j\|^2)$, where $\gamma > 0$.

3.2.4 Neural networks

One of the most limitations of the MDA-based studies, for example, [Altman \(1968\)](#), is that this method requires the discriminating variables to be jointly multivariate normal ([Odom and Sharda 1990](#)). We can relax this restriction of multivariate normality by using several machine learning techniques including neural networks and decision trees. Neural networks are flexible since we can adjust the number of inputs, hidden layers, and neurons in each hidden layer. Neural networks can learn complex relationships between variables (predictors) and make predictions with a high degree of accuracy.

Note that, we choose threshold=0.5 to determine whether a firm predicted financial distress or not. It is clear that 0.5 is the standard threshold in the fields of forecasting and machine

learning. In fact, we also tried threshold=0.4 since we thought the firms in transition economies like Vietnam have weak financial structures and depend more on debt than firms in developed countries. In preparing the models, we find that 0.5 is a better threshold compared to 0.4 as most of the accuracy and Matthews coefficient correlations are higher than in the former case. One technical reason that we choose 0.5 as the threshold is that by choosing this threshold the accuracy from Keras and the accuracy from Sk-learn are the same. Another threshold, for example, 0.4, will lead to different accuracy when using Keras and when using Sk-learn. In that case, one needs to discuss which libraries that he or she prefers. Fortunately, by choosing threshold=0.5 we do not need to do so.

3.2.5 Merton model

Denote V_t^A as the dynamics for the value of the firm's assets at time $t \in [0, T_t]$. Thus, V_t^A is described by the following geometric Brownian motion

$$dV_t^A = (\mu_t^A V_t^A - D_t)dt + \sigma_t^A V_t^A dW_t, \quad (3.1)$$

where μ_t^A is the instantaneous expected rate of return at time t , σ_t^A is the instantaneous estimated volatility of the return on the firm per unit time, D_t is the amount of money that the firm pays for liabilities-holders (e.g. interest rates of corporate bonds) per unit time, dW_t is the standard Wiener process. The formal definition of default probability is defined as follows.

Definition 3.2.1. (*default probability*) *The probability of default of a firm is defined as*

$$PD = P(V_{t+m}^A < D_t), \quad (3.2)$$

where D_t is the financial obligations (or debts) that the firm needs to pay at time t , and V_{t+m}^A is the estimated market value of the firm at time $t + m$, where $t \in [0, T_t]$, $m \in [0, T_m]$, and $0 \leq T_t, T_m < \infty$.

In practice, it is usually to assume $m = 1$ year (Afik et al. 2016). That is, one might examine the debt at the current time t and estimate the value of a firm one year after that, i.e. at time $t + 1$. Therefore, we propose the following definition.

Definition 3.2.2. (*one-year probability of default*) *The probability of default of a firm in one year is defined as*

$$PD = P(V_{t+1}^A < D_t), \quad (3.3)$$

where D_t is the financial obligations (or debts) that the firm needs to pay at time $t + 1$, and V_{t+1}^A is the estimated value of the firm at time $t + 1$.

Note that the market value V_{t+m}^A in Definition 3.2.1 and V_{t+1}^A in Definition 3.2.2 are unknown. Therefore, we need to estimate it. Since we are at the current time t and want to estimate the probability of default in time $t + m$, we actually investigate the *implied* probability of default. Assume the forecasting horizon is one year, i.e. $m = 1$. For simplicity, we call the one-year probability of default as the probability of default from now on. Note that one year or less is the maturity date of short-term debt. Theoretically, if a firm cannot pay the short-term debt within a year to creditors, it will go bankrupt. In the standard finance literature (e.g. Vassalou and Xing 2004; Bharath and Shumway 2008), one normally takes into account total short-term debt and half of long-term debt to compute the book value of debt D_t . In this study, we will consider the book value of debts as a function of short-term debt and long-term debt

$$D_t = \text{Short-term debt} + k(\text{Long-term debt}), \quad (3.4)$$

where $k \in [0, 1]$. In this study, we choose $k = 0.5$.

Denote V_t^E be the market value of the firm's equity at time t , the Black-Scholes formula for call options is given by the following equation

$$V_t^E = V_t^A N(d_1) - D_t e^{-r_t m} N(d_2), \quad (3.5)$$

where r_t is the instantaneous risk-free interest rate at time t , D_t is the book value of the firm's debt at time t , N is the standard normal cumulative density function, and

$$d_1 = \frac{\ln(V_t^A/D_t) + (r + 0.5(\sigma_t^A)^2) m}{\sigma_t^A \sqrt{m}}, \quad d_2 = d_1 - \sigma_t^A \sqrt{m}.$$

Equation (3.5) implies that the value of a firm's equity V_t^E , which we can observe on the stock market by multiplying the current stock price by the total number of firm's shares outstanding, is a nonlinear function of the expected value of the firm V_t^A , which we cannot observe directly. Note that in equation (3.5), both the value of the firm V_t^A and the (implied) volatility of the underlying asset price σ_t^A are unobservable. Therefore, we need to find σ_t^A and V_t^A by solving equation (3.5).

Since the lack of comprehensive bankruptcy data in many transition economies like Vietnam, this study will work on corporate financial distress probability but still be based on the framework of the default probability.

3.3 The data

Since the data and variables for models using accounting-based variables are distinct from those for the Merton model, we describe the procedure of collecting data and preparing variables separately.

3.3.1 For accounting-based and machine learning models

Data collection

For non-delisted firms, we collect the data of the non-financial listed firms in Vietnam's stock market from 2009 to 2021. Although Vietnam's stock market was established in 2000, the scale of the market and the number of listed firms were pretty limited before 2009. Thus, this paper focused on the period from 2009. Note that since financial institutions such as banks, insurance, and hedge funds have different financial characteristics, therefore, are excluded from our data.

For the accounting-based and machine learning models⁶, the financial reports of both delisted and non-delisted firms are obtained from the Refinitiv Eikon database. We collect the delisted stocks due to financial reasons as the proxies for financial distress on the Ho Chi Minh Stock Exchange (HOSE) and Hanoi Stock Exchange (HNX). Note that financial reasons, according to Decree 155/2020/ND-CP, include (1) negative profit in three consecutive years and (2) cumulative loss (negative profit) is greater than authorized capital.

Table 3.4 summarizes the datasets and the corresponding sources that we use in this study. We employ data from five sources. For the variables of firms' characteristics and market value of equity of each firm, we get the data from the Refinitiv Eikon database. For Gross National Product (GNP), we get the data from the World Bank's website. We obtain the risk-free interest rate of Vietnam's 1-year government bond from www.investing.com, which is a reliable source for financial markets and investment. Finally, we get the list of delisted stocks from the Ho Chi Minh City Stock Exchange (HOSE) and the Hanoi Stock Exchange (HNX).

Table 3.5 shows, in the final sample of accounting-based and machine learning models, that there are 1,097 firms and 12,685 observations in total including 1,021 non-listed firms (with 12,154 observations) and 76 delisted firms (with 531 observations). It is clear that our sample is an imbalanced data with 12,154 observations (approximately 95.8%) of the majority group (non-delisted firms) and 531 observations (approximately 4.2%) of the minority group (delisted firms). The final sample of the Merton model has

⁶Note that the accounting-based model in this study means logistic regression that is widely used in accounting literature, for example, the seminal work of [Ohlson \(1980\)](#) and subsequent studies. Machine learning models in this study include LDA, SVM, and neural networks. In the next subsection, we will discuss the data and variables for the Merton model, which is a market-based model.

Table 3.4: The data and corresponding sources

Data	Source
Firm’s characteristics	Refinitiv Eikon database
Gross National Product (GNP)	World Bank
Market value of equity	Refinitiv Eikon database
Risk-free interest rate	www.investing.com
Delisted stocks	HOSE, HNX

7,707 observations with 6,967 observations (about 90.4%) of non-delisted firms and 740 observations (about 9.6%) of delisted firms. There are 1,059 firms in the final sample of the Merton model with 76 delisted firms and 983 non-delisted firms.

Table 3.5: Number of firms and observations in the final samples

	Accounting-based and ML models		Merton model	
	Number of firms	Number of obs	Number of firms	Number of obs
Delisted firms	76	531	76	740
Non-delisted firms	1,021	12,154	983	6,967
Total	1,097	12,685	1,059	7,707

Notes. Initially, there are 108 delisted stocks due to financial reasons on HOSE and HNX between 2011 and 2021 as shown in Appendix 2. However, there are only 76 firms (corresponding to 76 delisted stocks) having full data for estimating the financial distress models.

Data preprocessing

From the data collected from the Refinitiv Eikon database, we generate the independent variables as those in Altman (1968) and Ohlson (1980) as these are the standard accounting-based models of bankruptcy prediction. Altman’s variables include working capital on total assets (wcapat), retained earnings on total assets (reat), earnings before interest and taxes on total assets (ebitat), sales on total assets (saleat), and market value of equity on total liabilities (mvdebt). The Ohlson’s variables include size of the firm (size) (proxy by total assets), total liabilities on total assets (ltat), working capital on total assets (wcapat), total current liabilities on total current assets (lctact), dummy variable on whether total liabilities exceed total assets (OENEG), return on assets, the fund provided by operations (proxy by the cash flow of operating) on total liabilities (cfodebt), dummy variable whether net income is negative in the last two years (INTWO), and income growth (CHIN). For more details, please see Table 3.6.

We fill the missing values of each column with the mean of that column group by stock then we delete any left missing values. Hence, we winsorize the top 5% and bottom 5% of the data points by using the Winsorizing technique. Specifically, the data points in the top 5% of each column are replaced by the value at the 95th percentile and the data points in the bottom 5% of each column are replaced by the value at 5% percentile. Our final data includes 12,685 firm-year observations and 1,097 firms as shown in Table 3.5.

The variables

There are five variables in Altman’s variables and nine variables in Ohlson’s variables. Since there is one common variable (i.e. `wcapat`) in two lists, the combination has only thirteen variables. However, we have to remove two variables (`ebitat` and `lctact`) to avoid the multicollinearity problems in the combination model. We will present how to detect multicollinearity in Subsection 3.3.1. Finally, in the case of Altman’s and Ohlson’s variables (i.e. combination), there are only eleven variables as the inputs for bankruptcy prediction models. These indicators reflected five financial aspects of firms including liquidity, profitability, productivity, solvency, and management’s capability. All variables used for calculating these financial ratios are collected for financial statements, balance sheets, and cash flow statements of the firms.

Table 3.6: List of all independent variables in accounting-based and ML models

Variable	Type	Definition
<code>wcapat</code>	Liquidity	Working Capital/Total Assets
<code>reat</code>	Profitability	Retained Earnings/Total Assets
<code>ebitat</code>	Profitability	Earnings Before Interest and Taxes/Total Assets
<code>mvdebt</code>	Solvency	Market Value of Equity/Total debt
<code>saleat</code>	Management’s capability	Sales/Total Assets
<code>size</code>	Size	$\log(\text{total assets}/\text{GNP price-level index})$
<code>ltat</code>	Solvency	Total liabilities/ Total assets
<code>lctact</code>	Solvency	Total current liabilities/ Total current assets
<code>OENEG</code>	Solvency	Dummy: Total liabilities exceed total assets
<code>roa</code>	Profitability	Net income/Total assets
<code>cfodebt</code>	Solvency	Funds provided by operations/ Total liabilities
<code>INTWO</code>	Solvency	Net income < 0 for in the last 2 years
<code>CHIN</code>	Management’s capability	$\frac{\text{Net income}(t) - \text{Net income}(t-1)}{ \text{Net income}(t) + \text{Net income}(t-1) }$

Notes: In most cases, we keep the names of variables in this table as that in Altman (1968) and Ohlson (1980). For the variable `CHIN`, in the next sections of the paper we use income growth (denoted by `incgrowth`) as the alternative (yet more intuitive) variable name.

In order to determine the financial distress status, we create a dummy variable named `bankrupt_period` which takes the value of 1 from the delisted year to the current year and 0 for non-listed firms. Note that we define `bankrupt_period` equals to 1 from delisted year to the current year because the fact that it is very rare that once a firm is delisted from the two main stock markets (Ho Chi Minh City Stock Exchange - HOSE and Hanoi Stock Exchange - HNX), that firm would be listed again on these two stock markets after that⁷. We actually do not observe any cases like that at the moment.

⁷Those stocks are delisted from HOSE and HNX that will be moved to an informal market called Unlisted Public Company Market (or Upcom).

Table 3.7 illustrates the differences between delisted and non-delisted firms in several other factors including total debt, market values of equity, total assets, and cash flow from operations. The t -test method is normally used to determine whether there are significant differences between the means of two groups. The p -values of the t -test indicate that the differences of the four factors between two groups of firms are statistically significant at the significant level of $\alpha = 0.05$. Note that these four factors shown in Table 3.7 are not included in the list of variables of any models. However, we use them as the intermediate inputs to generate the final list of variables. The differences in these four factors imply that they might be the good features to predict bankruptcy then so are the final list of variables.

Table 3.7: Means of some factors of delisted vs. non-delisted firms

	debt	equity	at	cf_operating
Non-delisted firms	511.2294	657.3682	1716.3659	93.7074
Delisted firms	813.5192	111.8401	1441.8224	39.7954
p -value (t -test)	0.0000	0.0000	0.0256	0.0000

Notes: Debt stands for the total debt of firms in the balance sheet. Equity stands for the total equity in the balance sheet. ta is denoted for the total assets of firms, and $cf_operating$ stands for the operating cash flow from the cash flow statement. In Python, one can use the `ttest_ind` method in the `scipy.stats` package to calculate two-sampled t -test and get the corresponding p -value. This method calculates the t -test for the means of two independent samples. The null hypothesis is that two independent samples have identical averages. The t statistic is given by $t = \frac{\bar{X}_1 - \bar{X}_2}{s_p \sqrt{\frac{1}{n} + \frac{1}{m}}}$,

where $s_p = \sqrt{\frac{(n-1)s_1^2 + (m-1)s_2^2}{n+m-2}}$. Note that, by default, t -test assumes that the populations have identical variances.

Table 3.8 shows the differences between delisted and non-delisted firms in terms of the mean of Altman's variables. It can be seen that these two groups are significantly different in terms of $wcapt$, $reat$, $ebitat$, $mvdebt$, and $saleat$. The p -values of the t -test indicate that the differences of these five variables between two groups of firms are statistically significant. Note that in the t -test, the null hypothesis is that the means of variables in two groups are equal. Choosing the significant level of $\alpha = 0.05$. Since all p -values are smaller than 0.05, we can reject the null hypothesis. This indicates there are significant differences in characteristics between delisted and non-delisted firms. The differences between these two groups in terms of Altman's variables imply that these five variables might be good factors to predict whether a firm goes bankrupt or not. In this case, the t -test plays the role of a good selection method.

Table 3.9 shows the summary statistics of all Altman's variables and all Ohlson's variables. Note that in the combination of Altman's and Ohlson's variables, we do not use all variables in this table. Rather, we will eliminate some variables to avoid the multicollinearity issue.

Table 3.8: Means of the Altman's variables of delisted vs. non-delisted firms

	wcapat	reat	ebitat	mvdebt	saleat
Non-delisted firms	0.1779	0.0440	0.0683	14.8720	1.0204
Delisted firms	-0.0423	-0.1913	0.0063	7.1502	0.5001
<i>p</i> -value (<i>t</i> -test)	0.0000	0.0000	0.0000	0.0000	0.0000

Table 3.9: Summary statistics

Variable	count	mean	std	min	25%	50%	75%	max
bankrupt_period	12685	0.0418	0.2002	0.0000	0.0000	0.0000	0.0000	1.0000
wcapat	12685	0.1687	0.2106	-0.2234	0.0266	0.1473	0.3123	0.5800
reat	12685	0.0342	0.1173	-0.3163	0.0102	0.0435	0.0924	0.2209
ebitat	12685	0.0657	0.0623	-0.0426	0.0225	0.0578	0.1023	0.2022
mvdebt	12685	14.5488	32.7578	0.1041	0.5837	1.9153	8.3740	135.0364
saleat	12685	0.9986	0.7752	0.0780	0.3755	0.7934	1.4135	2.8690
size	12685	4.8465	1.4981	2.3140	3.7416	4.7473	5.8391	7.8813
ltat	12685	0.5279	0.2351	0.1166	0.3394	0.5397	0.7104	0.9375
lctact	12685	0.7929	0.4743	0.1604	0.4721	0.7316	0.9485	2.1409
OENEG	12685	0.0342	0.1819	0.0000	0.0000	0.0000	0.0000	1.0000
roa	12685	0.0438	0.0557	-0.0675	0.0088	0.0353	0.0751	0.1662
INTWO	12685	0.0732	0.2605	0.0000	0.0000	0.0000	0.0000	1.0000
incgrowth	12685	-0.0029	0.4921	-1.0000	-0.2197	0.0000	0.2049	1.0000
cfodebt	12685	1.2403	2.8983	-0.8524	-0.0311	0.2042	0.8976	11.529

Notes: This table shows the summary statistics of variables in this study. **wcapat** is the ratio of working capital to total assets. **reat** is the ratio of retained earnings to total assets. **ebitat** is the earnings before interest and taxes to total assets. **mvdebt** is the market value of equity to total debt. **saleat** is the ratio of sales to total assets. **size** is the logarithm of the ratio of total assets to GNP adjusted to the price-level index. **ltat** is the ratio of total liabilities to total assets. **lctact** is the total current liabilities to total current assets. **OENEG** is a dummy variable that takes value 1 when total liabilities exceed total assets and 0 otherwise. **roa** is the ratio of net income to total assets. **INTWO** is a dummy variable that takes value 1 when net income is negative in the last 2 years. **incgrowth** is the ratio between the change in net income between time $t - 1$ and t over the summation of net income in time $t - 1$ and t . **cfodebt** is the ratio of funds provided by operations to total liabilities.

Correlation matrix

We will show the correlation matrix of each list of variables using a heat map. Figure 3.2 shows the heat map of Altman's variables. It is clear that all correlation coefficients of Altman's variables are less than 0.8, which is usually used as an empirical threshold to detect highly correlation between each pair of variables. A striking point from the heat map is that all correlation coefficients of each pair of independent variables and dependent variables are negative.

Figure 3.2: The heat map for the Altman's variables

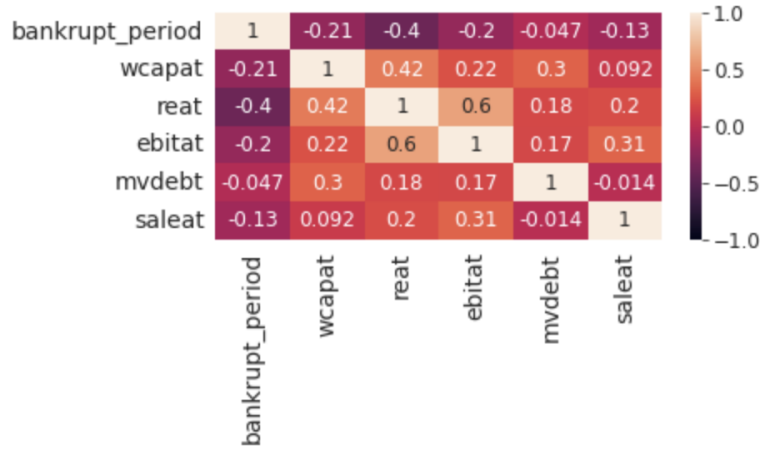


Figure 3.2 shows the heat map of Ohlson's variables. The absolute values of all correlation coefficients are less than 0.8, except that between lctact and wcapat. Since the completeness of the list of Ohlson's variables, we decide to keep both lctact and wcapat in the models for Ohlson's variables even though they are highly negatively correlated with each other.

Figure 3.3: The heat map for the Ohlson's variables

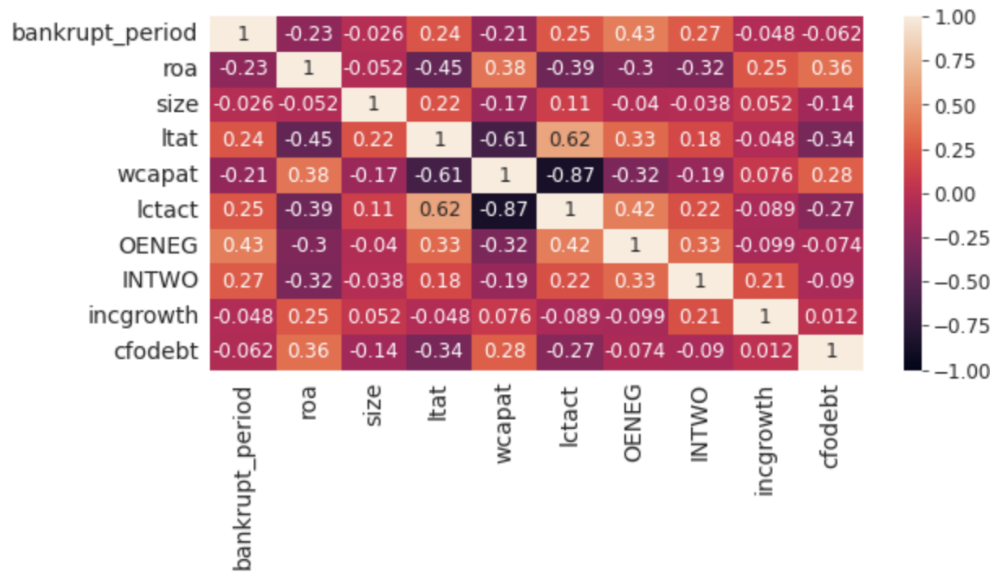
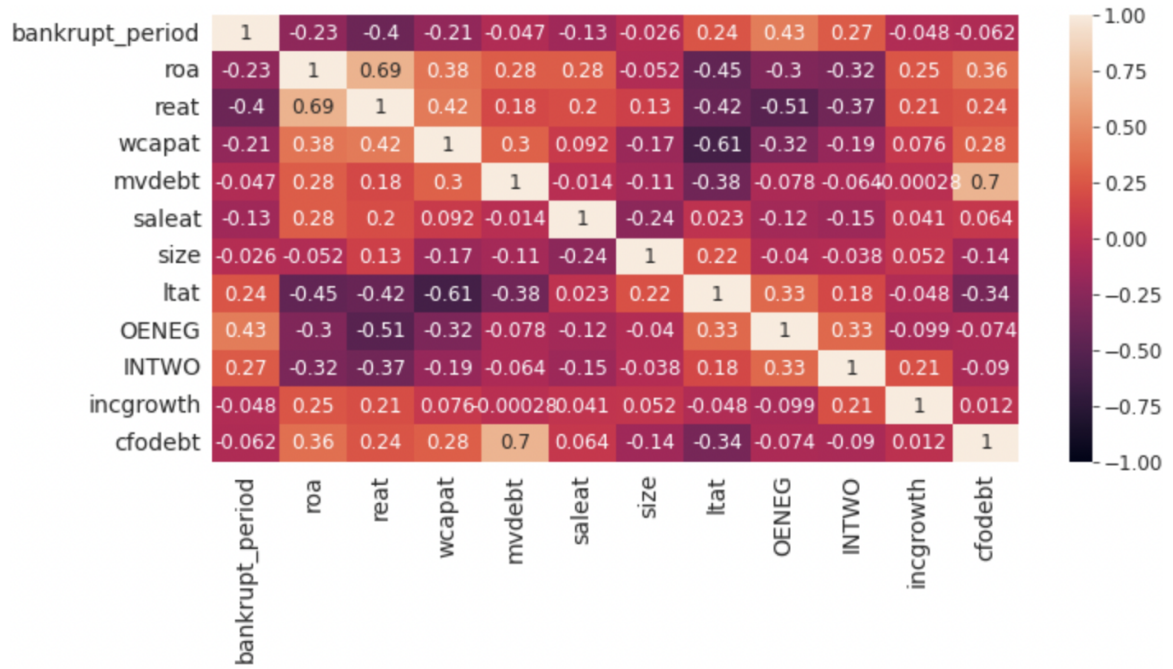


Figure 3.4 shows the correlation matrix among all eleven variables in the combination list of Altman's and Ohlson's variables as well as the dependent variable (i.e. bankrupt_period). We can see that all correlation coefficients are less than 0.8. Note that we have to remove ebitat and lctact since these variables have VIF's values greater than 10. Also,

the correlation coefficient between ebitat and roa is 0.87, and the correlation coefficient between lctact and wcapat is -0.87. We do not show the values of these two pair correlations in Figure 3.4 to avoid redundancy.

Figure 3.4: The heat map for the Altman's and Ohlson's variables



It can be seen that bankrupt_period has the negative correlation with roa, reat, wcapat, mvdebt, saleat, size, incgrowth, and cfodebt. This is rational and as our expectations. For example, the correlation coefficient between size and bankrupt_period is negative, -0.026 , which indicates that big firms are less likely to be delisted due to financial reasons than small firms. In addition, the correlation coefficient between incgrowth and bankrupt_period is -0.048 . This means that if income growth increases then bankrupt_period tends to decrease, i.e. likely to take value 0 rather than 1. The figure also shows that the correlation coefficients between ltat, OENEG, and INTWO and bankrupt_period are positive, which make sense too. For example, the correlation coefficient between ltat and bankrupt_period is positive, 0.24 , which indicates that firms with more debt relatively to total assets tend to be delisted due to financial reasons than those with small debt to total assets.

VIF test

This subsection will check the multicollinearity problem among independent variables in Table 3.6. Table 3.10 illustrates the VIF's values of all independent variables of the Altman's, Ohlson's, and combination variables. As the empirical rule, if VIF is greater than 10, then we will remove those variables.

Table 3.10 shows that all VIF's values are less than 10 except ltat in the list of Ohlson's variables. We decided to keep ltat due to two reasons. First, the VIF's value of this variable is 10.1650, which is just slightly greater than 10. Second, more importantly, we decide to keep this variable due to the completeness of the list of variables as in Ohlson (1980). Note that the multicollinearity issue is only a concern in logistic regression and LDA⁸. This is not a problem in other models, including SVM, neural networks, and the Merton model.

Table 3.10: The VIF's values

Altman's variables		Ohlson's variables		Combination	
Variable	VIF	Variable	VIF	Variable	VIF
ebitat	2.9395	ltat	10.1729	ltat	9.1657
saleat	2.1885	lctact	9.7887	size	9.0075
wcapat	1.8831	size	9.6289	roa	3.6757
reat	1.7289	wcapat	3.0244	saleat	3.0947
mvdebt	1.3321	roa	2.5652	reat	2.7760
		cfodebt	1.4525	cfodebt	2.4879
		OENEG	1.4449	mvdebt	2.4458
		INTWO	1.4092	wcapat	2.1995
		incgrowth	1.2177	OENEG	1.5290
				INTWO	1.4633
				incgrowth	1.2174

Scaling

Scaling variables before applying the models are very crucial in the cases of SVM and neural networks (Hsu et al. 2016). Since we want to compare the predictive results among all models, we normalize all features/independent variables for all models (except the Merton model since its inputs are different). In Python, we use the package `preprocessing.normalize` from scikit-learn to normalize the variables⁹.

3.3.2 For the Merton model

Data collecting

In the Refinitiv Eikon database, the market value of firms on the Vietnam's stock market is available from May 2009. Due to the missing data from January to April of 2009, our study period started from 2010 to 2021 for the Merton model.

⁸Note that the effects of multicollinearity issue on linear regression and LDA are not the same. In LDA, the goal is to find the linear combination of predictor variables (features) that maximizes the separation between different groups or classes. Multicollinearity can still be an issue if there is too much overlap between the predictor variables, but it is less of an issue than in linear regression because LDA is focused on the differences between groups rather than the individual effects of predictors.

⁹For more details, see the documentation at <https://scikit-learn.org/stable/modules/generated/sklearn.preprocessing.normalize.html>

Data processing

For the Merton model, the variables include the number of common shares, market value, debt, and risk-free interest rate. To represent the risk-free interest rate, we use the Vietnam 1-year bond yield¹⁰. The remaining variables are collected from the Refinitiv Eikon database. In the Merton model, bankruptcy probability is calculated daily and then averaged to get the yearly data. The missing values and the firms which have less than 200 trading days are excluded from the data.

Note that the Merton model works with daily datasets. Thus, we convert the debt, risk-free interest rates into the daily format. For the missing data in the market value of firms, we replace by the stock price multiplied by the common shares. In case the stock prices are also missing, the rolling mean of five periods is used to fill in the market value. A 5-period rolling mean is used with the meaning that today's market value is related to the market value within five trading days of the week.

The variables

For the Merton model, the variables include (1) market value, (2) short-term and long-term debt, and (3) risk-free interest rate. Note that the market value of each firm is calculated by multiplying the number of common shares (also known as outstanding shares or shares outstanding) and the price of the stock of that firm. In order to represent for a risk-free interest rate, we use the Vietnam 1-year bond yield data. The remaining variables are collected from the Refinitiv Eikon database. Table 3.11 shows all variables and the corresponding data sources for the Merton model.

Table 3.11: The Merton's variables and corresponding sources

Variable	Source
Market value of equity	Refinitive Eikon database
Debt	Refinitive Eikon database
Vietnam 1-year bond yield	www.investing.com

Notably, the Merton model bankruptcy probability is calculated daily and then converted to yearly data by mean. The missing data and the firms which have less than 200 trading days will be excluded from the data. There are 7,707 firm-year observations with 1,059 firms including 76 delisted firms and 983 non-delisted firms.

¹⁰See <https://www.investing.com/rates-bonds/vietnam-1-year-bond-yield-historical-data>

3.3.3 Synthetic minority oversampling technique

In order to get balanced data for training models we use the synthetic minority oversampling technique (SMOTE)¹¹. This is a data augmentation technique for oversampling the minority group. This technique was first introduced by Chawla et al. (2002). The idea of this technique is that first a random data point a of the minority class is chosen. Then one finds a k nearest data points (e.g. $k = 5$) of minority class. A randomly selected data point b is chosen among k nearest data points. Thus, a synthetic data point is generated at a randomly selected point between a and b .

There are two steps for using SMOTE in our study.

- Step 1: Split the data into train (80%) and test set (20%).
- Step 2: Apply SMOTE on the train set.

In Step 1, we split data into 80% of the train set and 20% of the test set. After this step, there are 10,148 firm-year observations (with 414 observations of delisted firms) in the train set and 2,537 firm-year observations (with 117 observations of delisted firms) in the test set.

In Step 2, we only apply SMOTE on the train set to get the balanced training data between non-delisted and delisted firms. After this step, our train set includes 9,734 firm-year observations of non-delisted firms (50%) and 9,734 firm-year observations of delisted firms (50%). The total observations in the train set increased from 10,148 to 19,468 after using SMOTE. Note that we keep the test set separate and only use it to validate the models. Notably, SMOTE technique is applied only for the accounting-based and machine-learning models but not for the Merton model. Since the Merton model is calculated independently for each firm, it is not impacted by imbalanced data.

Table 3.12 illustrates the number of observations of train data (Train), test data (Test), and their corresponding proportions before and after using SMOTE of delisted and non-delisted firms. Obviously, for the train data, the data before SMOTE (original data) is highly imbalanced with 4.08% number of observations of delisted firms and 95.92% number of observations of non-delisted firms. After using SMOTE, we get 50% observations of delisted firms and 50% observations of non-delisted firms in the train data. Meanwhile, the test data is the same before and after using SMOTE since this technique only applies on the train data.

¹¹Note that one can use other ways to deal with imbalanced data. One way is to balance the weights of the observations in two groups by adding `class_weight = 'balanced'` into the models. While this parameter now is available in logistic regression, SVM, and neural networks (one can calculate the weights from the number of observations in each group and then add these manual weights to the neural networks), it is not available for LDA and the Merton model.

Table 3.12: Number of observations before and after using SMOTE

	Before SMOTE				After SMOTE			
	Train	Percent	Test	Percent	Train	Percent	Test	Percent
Delisted firms	414	4.08%	117	4.61%	9,734	50%	117	4.61%
Non-delisted firms	9,734	95.92%	2,420	95.39%	9,734	50%	2,420	95.39%
All firms	10,148	100%	2,537	100%	19,468	100%	2,537	100%

3.4 Results

All the results in this section are based on the confusion matrices of relevant models. For more details about how to calculate accuracy, balanced accuracy, Matthew correlation coefficient, precision, recall, and F_1 score please see Appendix 1.

Note that in order to obtain good results for neural networks in this section we do hyperparameter tuning with `epochs` = 10, 20, 50, 100, 200, 300 and `batch size` = 1, 2, 4, 8, 16, 32, 64¹². We do not run models with epochs more than 300 to avoid overfitting problem. Also, we do not run models with batch size more than 64 since our final sample only contains 531 observations of delisted-firms, which is relatively small compared to the size of datasets in many neural networks models in the literature. We find that `epochs` = 200 and `batch size` = 32 are the optimal ones.

For the architects of the neural networks, we choose `optimizer='adam'` since this is popular and is one of the most powerful optimizers in machine learning and we choose `loss='binary_crossentropy'` since our target feature is binary one and this is also one of the most popular loss functions in machine learning. Note that we choose these two hyperparameters (optimizer adam and loss function binary_crossentropy) for convenience. But, of course, one can do hyperparameter tuning for these parameters to choose the optimal ones in other studies.

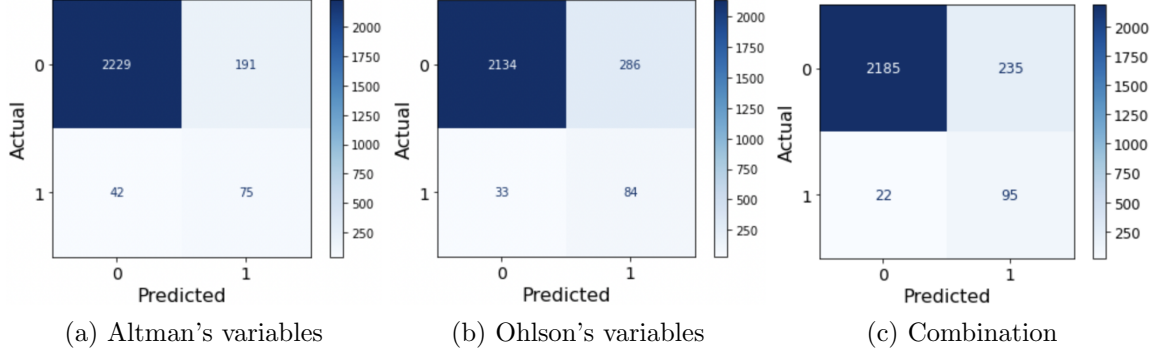
3.4.1 Confusion matrix

We denote 0 as non-delisted firms and 1 as delisted firms. Then, we derive the confusion matrix for all models. For example, the confusion matrices of the LDA models for the case of Altman's variables, Ohlson's variables, and the combination are respectively shown Figure 3.5. The top-left numbers mean that the firms are not delisted and the models correctly predict that they are not delisted. The bottom-right numbers mean that the firms are delisted and the models correctly predict that the firms are delisted. The top-right numbers mean that the firms are non-delisted but the models incorrectly predict that

¹²In convention, we choose the `batch size` = 2^k , where $k = 0, 1, 2, \dots$

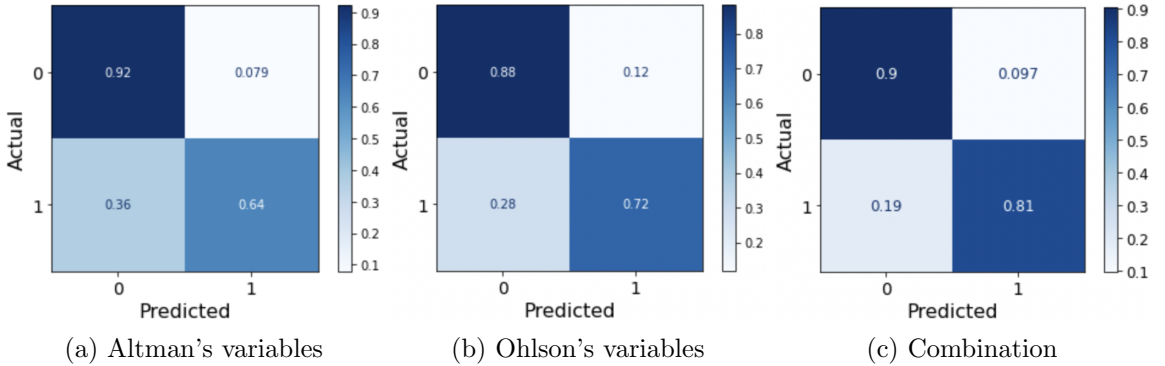
the firms are delisted. Finally, the bottom-left numbers mean that the firms are actually delisted but the models incorrectly predict that the firms are non-delisted.

Figure 3.5: Confusion matrices of the LDA models



Since we want to compare the confusion matrices among models (among LDA models and also among the LDA with other accounting-based models), it is useful to normalize the confusion matrices. Figure 3.6 shows the normalized confusion matrices of the LDA models, where we normalize by the sum of the horizontal values in Figure 3.5.

Figure 3.6: Normalized confusion matrices of the LDA models



We also derive the confusion matrix for other models (logistic regression, SVM, neural networks, and the Merton model). Note that for the SVM model, we choose the radial basis function kernel (or RBF kernel). Note also that one can choose other kernels, for example, linear kernel.

The confusion matrix of the Merton model is given in Table 3.13. From this table, we can calculate that the general accuracy is 0.5864, the accuracy for non-delisted firms and delisted firms are 0.5804 and 0.7168, respectively. Note that this general accuracy is also the balanced accuracy of the Merton model. The reason is that in the Merton model, we compute the bankruptcy probability for each firm independently compared to that for the

other firms. That is the estimated probability does not depend on the situation of the imbalanced data of the sample size.

Table 3.13: Confusion matrix of the Merton model

Actual	Predicted	
	Non-delisted	Delisted
	Non-delisted	Delisted
	4277	3091
	96	243

3.4.2 Balanced accuracy

One important reason that we use balanced accuracy besides accuracy is that machine learning algorithms tend to get biased toward the majority group. That is the algorithms perform well on the majority group and perform poorly on the minority group. In the case of imbalanced data, high accuracy is not necessarily a good score in evaluating models. Because of this reason balanced accuracy might be a better score compared to accuracy in evaluating models with imbalanced data since it captures the performances of both majority and minority groups.

Since our data is imbalanced (skewed distribution), each accuracy in the above section is actually imbalanced accuracy. One can use a balancing technique to generate another accuracy score, which is the so-called balanced accuracy. By definition, it equals the average of the recall of two groups. Similar to accuracy, the values of the balanced accuracy range from 0 to 1.

Table 3.14: Accuracy vs. Balanced accuracy

Model	Accuracy			Balanced accuracy		
	Altman's	Ohlson's	Combination	Altman's	Ohlson's	Combination
LDA	0.9082	0.8715	0.8967	0.7810	0.7984	0.8523
LR	0.9018	0.8746	0.9011	0.7940	0.8082	0.8790
SVM	0.9018	0.8916	0.8975	0.8590	0.8130	0.8771
NN	0.8849	0.8971	0.9373	0.8949	0.8444	0.9021

Note: Altman's stands for Altman's variables and Ohlson's stands for Ohlson's variables.

Table 3.14 shows that all models with both Altman's and Ohlson's variables (the combination case) consistently have the highest balanced accuracy compared to those with only Altman's variables or only Ohlson's variables. Note that we present accuracy in this table just for the purpose of comparison to balanced accuracy. We do not compare or explain the performances of the models in terms of accuracy.

The predictive accuracy of the Merton model is 0.5804¹³, which is lower than all given accounting-based models. The poor performance of the Merton model might be because

¹³Note that, similarly to the accounting-based and machine learning models, in order to evaluate the predictive power of the Merton model, we choose 0.5 as the threshold for predicted probability. That is, if

the efficiency of Vietnam's stock market is not clear. Further studies to verify the efficiency of Vietnam's stock market, as well as the predictive performance of the Merton model, are surely necessary.

The next natural step is to separately look at the balanced accuracy in the case of non-delisted and delisted firms in comparison with the case of all firms. It can be seen from Table 3.15 that the balanced accuracy performances for non-delisted firms are higher than those for delisted firms in all models, except in neural networks with Altman's variables.

Table 3.15: Balanced accuracy of the models for non-delisted vs. delisted firms

Model	All	Non-delisted	Delisted	All	Non-delisted	Delisted	All	Non-delisted	Delisted
		Altman's			Ohlson's			Combination	
LDA	0.7810	0.9211	0.6410	0.7984	0.8789	0.7179	0.8523	0.9012	0.8034
LR	0.7940	0.9128	0.6752	0.8082	0.8814	0.7350	0.8790	0.9033	0.8547
SVM	0.8590	0.9062	0.8119	0.8130	0.8996	0.7265	0.8771	0.8996	0.8547
NN	0.8949	0.8839	0.9059	0.8444	0.9025	0.7863	0.9021	0.9409	0.8632

In order to get metrics (e.g accuracy and balanced accuracy) to evaluate neural networks models, we need to set up the architects for neural networks models. In all the neural networks, we use the architects with two hidden layers, one input layer, and one output layer. Table 3.16, Table 3.17, and Table 3.18 respectively show the architect of the neural networks with the Altman's variables, Ohlson's variables, and the combination of both. Note that the number of inputs, which are not the same as the number of neurons in the input layer, of each neural network equals the number of variables in each model. We choose the number of neurons in the input layer that is double the number of neurons in the first hidden layer. Note that one can choose the number of neurons in the input layer differently.

Table 3.16: The architect of the neural networks for Altman's variables

Layer	Number of neurons	Number of parameters	Activation function
Input layer	10	60	ReLU
Hidden layer 1	5	55	ReLU
Hidden layer 2	5	30	ReLU
Output layer	1	6	Sigmoid
Total parameters		151	

Note that in the above architects for neural networks, we choose ReLU as the activation function in the input and hidden layers. For the output layer, we choose Sigmoid as the activation function. Note also that since the financial distress prediction is a classification problem in nature, one should not use linear as the activation function in the output layer. Linear activation function is suitable when the target variable is continuous while in our case the target variable is binary (distress or non-distress).

the predicted financial distress probability of a firm is greater than 0.5 then we label that firm as a financial distress firm. Otherwise, we label that firm as a non-financial distress firm.

Table 3.17: The architect of the neural networks for Ohlson's variables

Layer	Number of neurons	Number of parameters	Activation function
Input layer	18	180	ReLU
Hidden layer 1	9	171	ReLU
Hidden layer 2	9	90	ReLU
Output layer	1	10	Sigmoid
Total parameters		451	

Table 3.18: The architect of the neural networks for Altman's and Ohlson's variables

Layer	Number of neurons	Number of parameters	Activation function
Input layer	26	364	ReLU
Hidden layer 1	13	351	ReLU
Hidden layer 2	13	182	ReLU
Output layer	1	14	Sigmoid
Total parameters		911	

3.4.3 Matthews correlation coefficient

Table 3.19 illustrates the Matthews correlation coefficient (MCC) of several models with accounting-based variables. It is clear from Table 3.19 that the models with the combination variables are consistently the best compared to those with either Altman's or Ohlson's variables. Also, the models with Ohlson's variables have the least performance compared to those with either Altman's variables or the combination. Note that MCC's values range from -1 to 1. The higher MCC's values show a higher agreement between the predicted and actual values and vice versa. Note that, in contrast to accuracy, MCC itself is a measure that is less affected by the imbalanced dataset issue. However, we even do not need to worry about this since by using SMOTE our data is balanced already.

Another striking result is that neural networks consistently outperform other models in all of three cases, including Altman's variables, Ohlson's variables, and a combination of the two.

Table 3.19: MCC of the accounting-based and machine learning models

	Altman's variables	Ohlson's variables	Combination
LDA	0.3848	0.3519	0.4377
LR	0.3876	0.3651	0.4702
SVM	0.4524	0.3914	0.4627
NN	0.4607	0.4306	0.5721

In order to derive the Table 3.19 we choose 0.5 as the threshold to determine financial distress. Note that we choose 0.5 as the threshold in this study not only because this is the most popular threshold but also since we compared the results for the case of threshold=0.5 and 0.4 (we checked in the code but do not show the comparison here to avoid unnecessary

redundancy) and we find that threshold 0.5 generating better results in most models¹⁴. Note that choosing threshold between 0 and 1 (excluding 0 and 1) only affects neural networks models but not LDA, logistic regression, and SVM since the predicted values in the last three models are either 0 or 1 while that of neural networks can be any real values between 0 and 1.

The MCC for the Merton model is 0.1231, which is lower than any MCC of the accounting-based and machine-learning models. The MCC together with the predictive accuracy consistently shows that the Merton model underperforms any given model, including logistic regression, LDA, SVM, and neural networks. One possible reason can be explained for the poor predictive performances of the Merton model is that Vietnam's stock markets might not be efficient at the current time. Indeed, [Loc et al. \(2010\)](#) finds that Vietnam's stock market is not efficient in the weak form. Moreover, Vietnam's stock market is progressing towards weak form efficiency but the speed of transmission of information is slow ([Gupta et al. 2014](#)).

3.4.4 Precision, recall and F_1 score

Precision, recall, and F_1 score are metrics used to evaluate the performance of classification models. Precision is a metric that measures the percentage of correctly identified positive results out of all results that are classified as positive. Recall is a metric that measures the percentage of correctly identified positive results out of all actual positive results. The F_1 score is the harmonic mean of precision and recall. For more details, please see Appendix 1.

Table 3.20 compares the precision, recall, and F_1 score of the LDA and logistic regression models for three different cases with Altman's variables, Ohlson's variables, and its combination. Note that 0 and 1 in the second column of this table stand for the non-delisted, delisted, and all firms, respectively. Table 3.21 compares the precision, recall, and F_1 score of the SVM and neural networks models for three different cases with Altman's variables, Ohlson's variables, and its combination.

One striking result from Table 3.20 and Table 3.21 is that in most cases the predictive performances for non-delisted firms obviously outperform those for delisted firms in terms of precision, recall, F_1 score. One possible reason that can explain the differences in predictive performances between delisted and non-delisted firms is that delisted firms might report relatively unreliable financial ratios in their financial statements. The unreliable data, in turn, possibly affect the predictive performances of non-delisted firms. Further studies are needed to test this hypothesis (unreliable data) and possibly other reasons.

¹⁴The reason why we compare the results with different thresholds is that some studies, for example [Staňková \(2022\)](#), indicates that thresholds should be considered depending on the economic situation and estimation methods.

Table 3.20: Precision, recall, and F_1 score of the LDA and logistic regression models

		LDA			Logistic regression		
	Firms	Precision	Recall	F_1	Precision	Recall	F_1
Altman	0	0.98	0.92	0.95	0.98	0.91	0.95
	1	0.28	0.64	0.39	0.27	0.68	0.39
	All	0.63	0.78	0.67	0.63	0.79	0.67
Ohlson	0	0.98	0.88	0.93	0.99	0.88	0.93
	1	0.22	0.72	0.34	0.23	0.74	0.35
	All	0.60	0.80	0.63	0.61	0.81	0.64
Combination	0	0.99	0.90	0.94	0.99	0.90	0.95
	1	0.28	0.80	0.42	0.30	0.85	0.44
	All	0.64	0.85	0.68	0.65	0.88	0.69

Notes: The precision, recall, and F_1 measure of all firms (denoted by All) is the macro average precision, recall, and F_1 score. This is actually the average of the precision, recall, and F_1 score of both non-delisted and delisted groups, respectively.

Table 3.21: Precision, recall, and F_1 score of the SVM and neural networks

		SVM			Neural networks		
	Firms	Precision	Recall	F_1	Precision	Recall	F_1
Altman	0	0.99	0.91	0.95	0.99	0.88	0.94
	1	0.30	0.81	0.43	0.27	0.91	0.42
	All	0.64	0.86	0.69	0.63	0.89	0.68
Ohlson	0	0.99	0.90	0.94	0.99	0.90	0.94
	1	0.26	0.73	0.38	0.28	0.79	0.41
	All	0.62	0.81	0.66	0.63	0.84	0.68
Combination	0	0.99	0.90	0.94	0.99	0.94	0.97
	1	0.29	0.85	0.43	0.41	0.86	0.56
	All	0.64	0.88	0.69	0.70	0.90	0.76

3.4.5 Feature importance

We already quantified the predictive performances of several models. Now we go further to see which variables are the most important. We consider the coefficients in our logistic regression models as feature importance¹⁵. Since all variables are normalized, the coefficient values of these variables in the logistic regression models can be considered as feature importance.

Figure 3.7 shows the feature importance for the Altman's variables. The variables with negative coefficient values tend to lead the predicted outcome to be 0 (financially non-distress). Meanwhile, the variables with positive coefficient values tend to lead the predicted

¹⁵Note that coefficients only can be considered as feature importance in the case of linear models such as linear regression, logistic regression, and their extensions. Since there are no coefficients in some machine learning models (e.g. SVM and neural networks), we do not quantify coefficients as feature importance in these models.

outcome to be 1 (financial distress). All the signs of the coefficient values in this figure are consistent with the correlation coefficients in Figure 3.2, except that of two variables: ebitat and wcapat. One possible reason why the coefficient values of ebitat and wcapat are negative is because the minimum values of ebitat and wcapat in Table 3.9 are negative and the number of observations with negative ebitat and wcapat might be many, which thus affect the sign of the coefficient values. One striking point from Figure 3.7 is that reat is the most important variable among all Altman's variables.

Figure 3.7: Feature importance for the Altman's variables



Figure 3.8 shows the feature importance for Ohlson's variables. It is evident that the coefficient values of ltat, OENEG, and INTWO are positive while the rest of the coefficient values are negative. The signs of the coefficient values of feature importance in Figure 3.8 are almost consistent with the signs of correlation coefficients in Figure 3.3. The only unexpected sign is the case of ltact. This is possibly caused by the high correlation between ltact and wcapat.

Figure 3.8: Feature importance for the Ohlson's variables

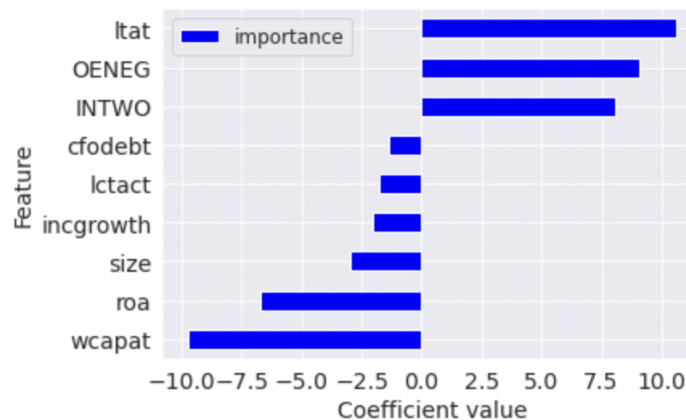
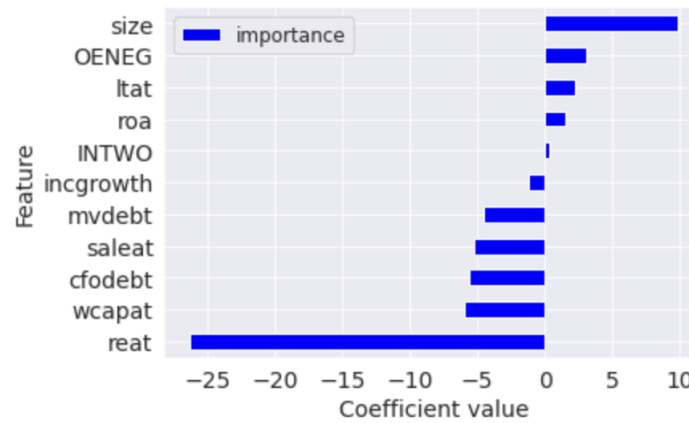


Figure 3.9 shows the feature importance for Altman’s and Ohlson’s variables. All of the signs of coefficient values in this figure are consistent with the correlation coefficients in Figure 3.4, except that of two variables: size and roa. The negative coefficient value of the variable “size” seems to contradict the fact in Table 3.22. However, this table is just a simple summary statistics. Also, the difference in delisted proportion between small and big firms is small (about 4.7% vs. 3.7%). Further research will be surely needed to quantify the effect of firm size on financial distress probability. One might consider the median of total assets to classify small and big firms rather than the mean to avoid the effects of extreme total assets. For “roa”, its positive coefficient value might be because of the fact that the minimum value of roa is negative in Table 3.9 and those negative roa might be many, which thus affects the sign of coefficient value. Overall, strikingly, reat is the most important variable among the list of Altman’s and Ohlson’s variables.

Figure 3.9: Feature importance for the Altman’s and Ohlson’s variables



An important result from feature importance is that reat is the most important variable in Altman’s variables as well as the combination of Altman’s and Ohlson’s variables. Also, ltat and wcapat are the most important variables in Ohlson’s variables.

3.5 The effects of firm size and macroeconomic situation

The outcomes of financial distress prediction might be different depending on firm size and whether firms are in an economic distress situation or not. It is worth exploring the effects of these aspects on predictive outcomes especially in Vietnam, where firms are significantly different in size and where as a transition economy the macroeconomic situations are often unstable.

3.5.1 Small firms vs. big firms

Since many public firms in Vietnam are small and medium ones, it is necessary to split all firms into two groups: small and big ones based on the median of the total assets. Small firms are those having total assets less than the median of the total assets of all firms while big firms are those having total assets more than the median of the total assets of all firms. Note that the median of total assets of all firms is approximately 588 billion VND (equivalent to 24.7 million USD).

After splitting, there are 6,344 big firms and 6,341 small firms. Table 3.22 compares the mean and median of variables between small and big firms. The p -values of the t -test indicate that most of the differences are statistically significant at the significance level of 1%, except INTWO. That is, the means of most variables are statistically different while for INTWO we cannot reject the null hypothesis, which states that the mean of INTWO of small firms equals the corresponding one of big firms. Note that since the means of most variables in Table 3.22 between small and big firms are different, this implies that our list of variables is the good one to potentially capture the differences in predictive performances between small and big firms. Note also that this is not necessarily the case that there are no more good variables that can explain the differences in predictive performances between small and big firms. Possibly, there are some more but we stick with this list of variables since they are the combination of the Altman's and Ohlson's variables.

Table 3.22 shows that the proportion of small firms, that are delisted due to financial reasons, is higher than that of big firms with 4.7% and 3.7%, respectively. This is consistent with the fact from Figure 3.4 that in general the size of a firm has a negative correlation with the likelihood that the firm can be delisted due to financial reasons. The difference in delisted proportion might be because of the difference in income growth. Table 3.22 indicates that the average income growth of the small firms is negative (about -3.14% per year) while that of big firms is positive (about 2.55% per year). Another possible explanation for the difference in the proportions of delisted firms between small and big firms is the sensitivity to long-term and short-term financial distress. Indeed, Cathcart et al. (2020) indicates that short-term debt is more sensitive to default probability than long-term debt. It can be seen from Table 3.22 that small firms have a proportion of short-term debt over total debt (lctlt) is approximately 86.62% which is moderately higher than that of big firms with the proportion around 72.97%. This difference is consistent with that in Cathcart et al. (2020).

Figure 3.10 compares the performances of the confusion matrices between small and big firms using Altman's variables, Ohlson's variables, and the combination of both. For non-delisted firms, there are no clear different patterns in predictive performances between small and big firms. For delisted firms, the predictive performances between small and big firms are clearer. Specifically, for delisted firms, the predictive performances of big firms consistently outperform those of small firms. Specifically, the proportions of

Table 3.22: Compare means of variables between big and small firms

Variable	Small firms			Big firms			p -value (t -test)
	Obs	Mean	Std	Obs	Mean	Std	
bankrupt_period	6,341	0.0469	0.2116	6,344	0.0367	0.1881	0.0038
at	6,341	246.63	152.0317	6,344	3162.42	3335.2545	0.0000
roa	6,341	0.0463	0.0614	6,344	0.0412	0.0492	0.0000
reat	6,341	0.0220	0.1320	6,344	0.0464	0.0989	0.0000
ebitat	6,341	0.0655	0.0668	6,344	0.0660	0.0576	0.6504
wcapat	6,341	0.2058	0.2219	6,344	0.1316	0.1916	0.0000
mvdebt	6,341	18.2814	36.2832	6,344	10.8179	28.3214	0.0000
saleat	6,341	1.1503	0.8154	6,344	0.8469	0.7008	0.0000
size	6,341	3.6683	0.8172	6,344	6.0240	1.0229	0.0000
ltat	6,341	0.4737	0.2435	6,344	0.5821	0.2130	0.0000
lctact	6,341	0.7292	0.4690	6,344	0.8565	0.4711	0.0000
lctl	6,341	0.8662	0.1955	6,344	0.7297	0.7976	0.0000
OENEG	6,341	0.0405	0.1972	6,344	0.0280	0.1651	0.0001
INTWO	6,341	0.0768	0.2662	6,344	0.0696	0.2546	0.1233
incgrowth	6,341	-0.0314	0.5072	6,344	0.0255	0.4749	0.0000
cfodebt	6,341	1.6364	3.3037	6,344	0.8445	2.3610	0.0000

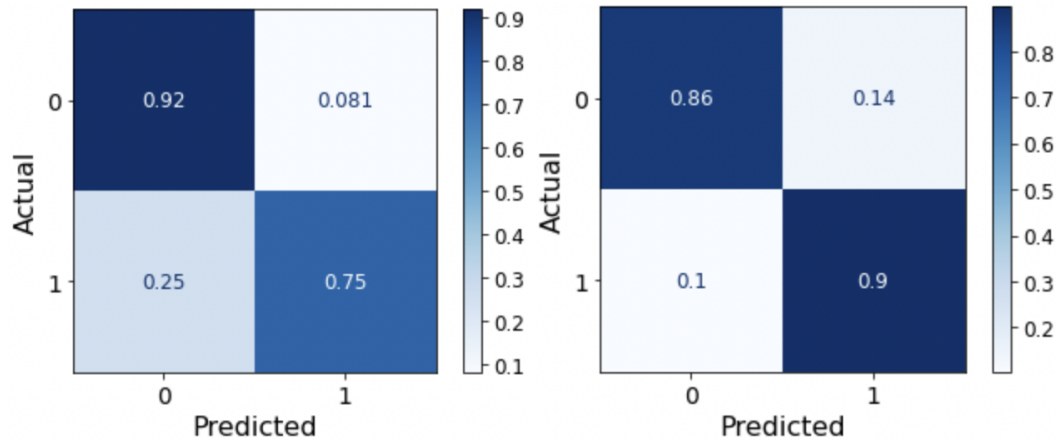
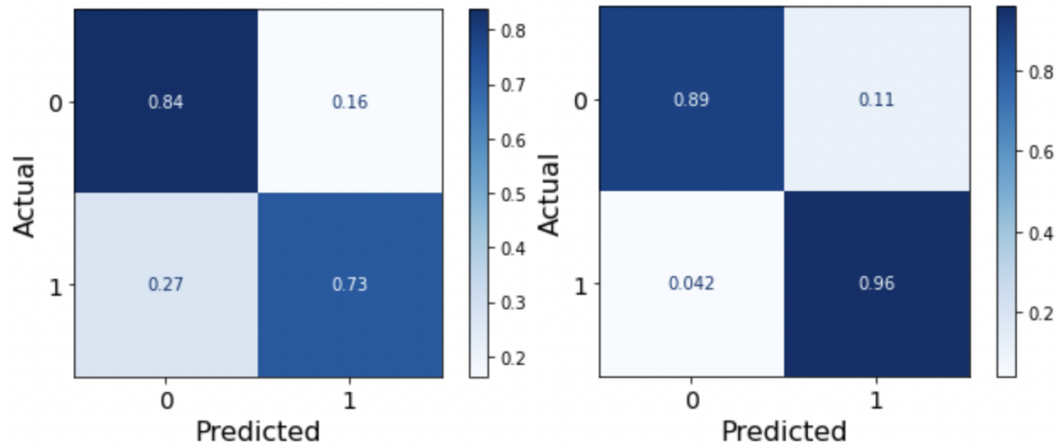
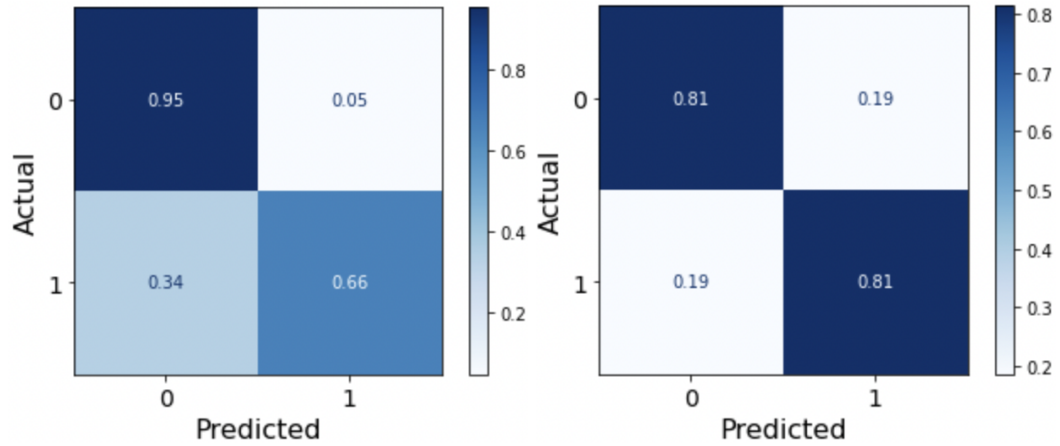
Notes: The last column in this table shows the p -values of the t -test with the null hypothesis that the mean of each variable of the small and big firms are equal. If we choose the significance level at 1%, then we can see that most (except ebitat and INTWO) of the differences in variables between small and big firms are statistically significant. Note that in this table, at and lctl are not variables in any models. But we show the descriptive statistics of these two variables with the purpose that we might understand the differences between the debt structure of small vs. big firms.

correct predictions of delisted small firms are 66%, 73%, and 75% while the corresponding proportions of correct predictions of delisted big firms are 81%, 94%, and 90%, respectively.

Table 3.23 compares accuracy, balanced accuracy, and Matthews coefficient correlation between small and big firms in the cases of Altman's, Ohlson's, and a combination of variables. In terms of Matthews coefficient correlation, there are no consistent differences in the predictive performances of the models for big vs. small firms. However, for each type of model, the patterns are clearer. For example, for the neural networks models the predictive performances of big firms consistently outperform those of small firms.

In terms of balanced accuracy, the predictive models for big firms are consistently better than those for small firms in most models. An exception is the case for the logistic regression model with Altman's variables. But note that even in this case the balanced accuracy for small and big firms are almost the same with 81.64% and 81.49%, respectively. One possible explanation for the differences in predictive performances between small and big firms is that financial reports and data of the big firms might be more reliable and accurate than those of small firms, thus leading to better predictive performances of big firms compared to small firms.

Figure 3.10: Normalized confusion matrices of the LDA models for small and big firms



(e) Small firms (Combination)

(f) Big firms (Combination)

Table 3.23: Comparison predictive performances between small and big firms

		Small firms			Big firms		
		Accuracy	Balanced	MCC	Accuracy	Balanced	MCC
LDA	Altman's	0.9369	0.8057	0.4800	0.8140	0.8132	0.2936
	Ohlson's	0.8361	0.7851	0.3090	0.8905	0.9131	0.4507
	Combination	0.9117	0.8328	0.4459	0.8597	0.8771	0.3828
LR	Altman's	0.9267	0.8164	0.4624	0.8171	0.8149	0.2968
	Ohlson's	0.8416	0.7557	0.2845	0.9031	0.8796	0.4399
	Combination	0.8968	0.8169	0.4042	0.8692	0.8719	0.3879
SVM	Altman's	0.9078	0.8146	0.4202	0.8818	0.8585	0.3902
	Ohlson's	0.8503	0.7844	0.3193	0.9086	0.9025	0.4703
	Combination	0.9054	0.8537	0.4548	0.8849	0.8702	0.4048
NN	Altman's	0.8952	0.8725	0.4560	0.9362	0.8868	0.5181
	Ohlson's	0.8810	0.8569	0.4213	0.9251	0.9211	0.5211
	Combination	0.9448	0.8582	0.5573	0.9693	0.8839	0.6551

Notes: Balanced stands for balanced accuracy and MCC stands for Matthews correlation coefficient.

3.5.2 Good years vs. bad years

We choose GDP growth at 6% as the cutoff to classify the study period into two periods: good years and bad years. This is a good cutoff since it captures three economic distress periods including the financial crisis (2008 and 2009), unstable macroeconomic fluctuation (2012, 2013, and 2014), and the Covid-19 pandemic (2020 and 2021) in the bad years. The other years are considered the good years (2010, 2011, 2015, 2016, 2017, 2018, 2019). Note that our delisted data is between 2011 and 2021 but we also have the firm's characteristics data in 2009 and 2010. In total, there are 5,513 observations in the bad years and 7,172 in the good years.

Table 3.24 shows the differences in the mean of variables between good and bad years of some variables. The last column shows the p -values of the t -test for the null hypothesis that the mean of each variable in bad years equals that in good years. Choose the significance level at 10%, we can observe that more than half of p -values are less than 0.1 while the other six p -values are greater than 0.1. This implies that for a number of variables including roa, reat, saleat, size, OENEG, INTWO, and incgrowth are statistically significant differences between bad and good years. One striking point in Table 3.24 is that the average income growth of firms during bad years is negative (-5.41% per year) while that during good years is positive (3.63% per year). It is reasonable to argue that those variables having significant p -values of t -test (smaller than 0.1) might play more important roles in explaining any differences in predictive performances of firms between bad and good years.

Figure 3.11 compares the confusion matrices of the LDA models for firms in bad and good years. It can be seen that, for delisted firms, the predictive performances for the case of Altman's and Ohlson's variables in the good years are better than the corresponding results

Table 3.24: Comparison means of variables between bad and good years

Variable	Bad years			Good years			<i>p</i> -value (<i>t</i> -test)
	Obs	Mean	Std	Obs	Mean	Std	
bankrupt_period	5,513	0.0417	0.1999	7,172	0.0419	0.2005	0.9446
at	5,513	1694.72	2790.70	7,172	1712.67	2762.84	0.7180
roa	5,513	0.0428	0.0569	7,172	0.0445	0.0547	0.0735
reat	5,513	0.0316	0.1197	7,172	0.0362	0.1153	0.0271
ebitat	5,513	0.0643	0.0639	7,172	0.0668	0.0611	0.0264
wcapat	5,513	0.1715	0.2113	7,172	0.1665	0.2100	0.1818
mvdebt	5,513	14.7565	32.8456	7,172	14.3891	32.6915	0.5312
saleat	5,513	0.9839	0.7790	7,172	1.0099	0.7722	0.0619
size	5,513	5.0956	1.5414	7,172	4.6549	1.4350	0.0000
ltat	5,513	0.5278	0.2352	7,172	0.5280	0.2350	0.9563
lctact	5,513	0.7917	0.4798	7,172	0.7938	0.4701	0.7998
OENEG	5,513	0.0373	0.1896	7,172	0.0319	0.1758	0.0953
INTWO	5,513	0.0440	0.2052	7,172	0.0956	0.2941	0.0000
incgrowth	5,513	-0.0541	0.5287	7,172	0.0363	0.4581	0.0000
cfodebt	5,513	1.2642	2.9195	7,172	1.2220	2.8819	0.4160

Notes: Bad years indicate the periods with economic distress while good years indicate the periods without economic distress. Note that total assets (denoted by at) is not official variables in any models but we want to do *t*-test to see whether there are significant differences between total assets during bad years compared to good years or not (the *p*-value shows that there is no difference).

for the bad years. However, interestingly, the predictive performance in bad years is better than that in good years for the combination of Altman’s and Ohlson’s variables. This implies the role of variables in influencing the predictive ability of the models.

Table 3.25 compares the financial distress prediction performances for bad and good years. In terms of MCC, the predictive performances of most models in the good years are better than those in the bad years. In terms of balanced accuracy, the differences between the predictive performances of LDA and logistic regression models do not have clear patterns. However, for SVM and neural network models, the predictive performances in good years consistently outperform those in bad years. One possible explanation for the outperforms in good years compared to bad years is that during the good years the data is less noisy compared to that in the bad years. Therefore, the predictive performances can be improved.

3.6 Discussion

In our study, we choose 0.5 as the threshold to predict bankruptcy probability after comparing the predictive performances between the threshold of 0.4 and 0.5. One can choose another threshold to evaluate the performances of neural networks and LDA models. Staňková (2022) argues that although the variables in traditional models are successful in predicting bankruptcy risk, the threshold may not necessarily be the same when carrying financial distress or bankruptcy prediction in different economies. Note that in our study,

Figure 3.11: Normalized confusion matrices of the LDA models for bad and good years

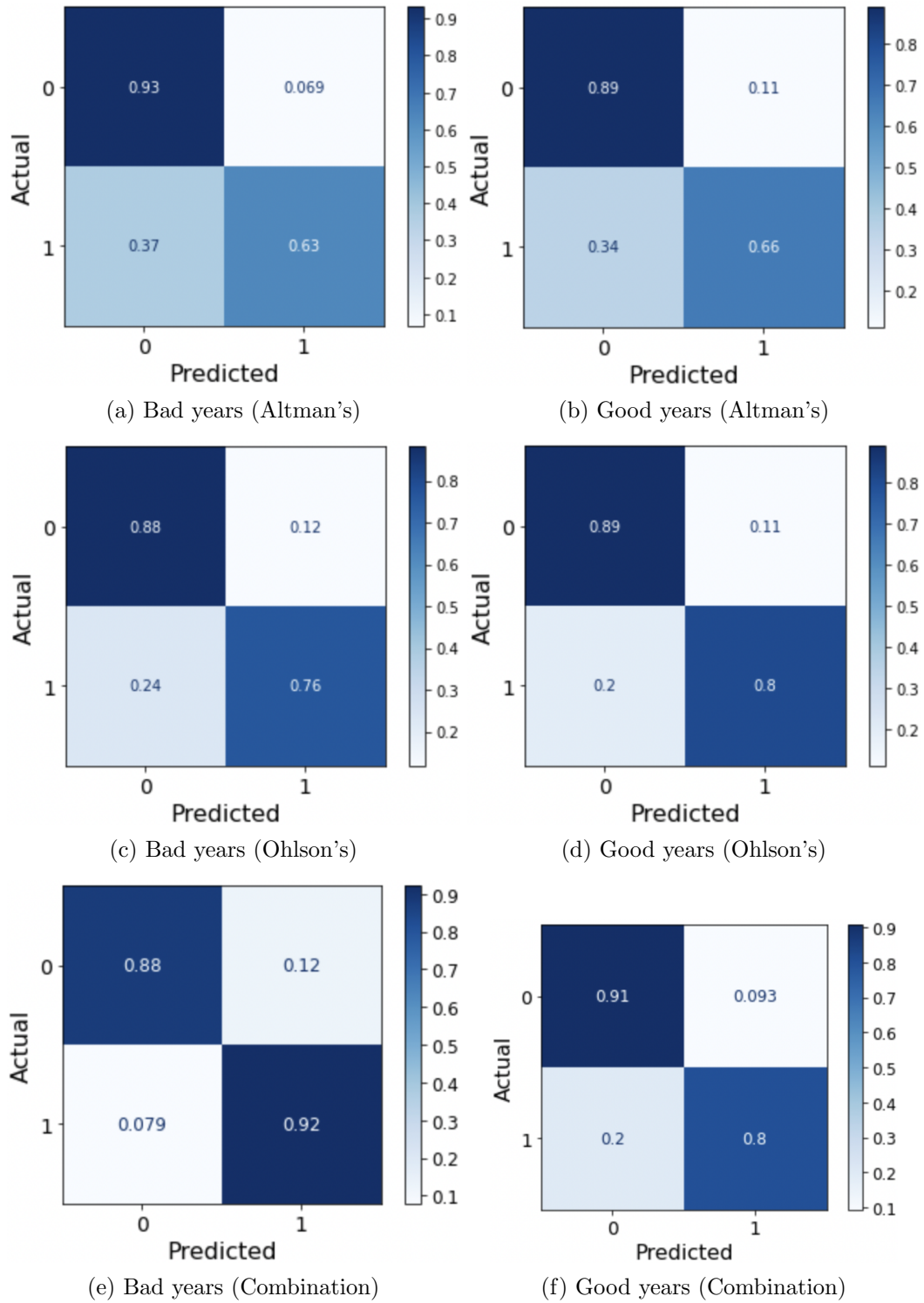


Table 3.25: Comparison predictive performances for bad and good years

		Bad years			Good years		
		Accuracy	Balanced	MCC	Accuracy	Balanced	MCC
LDA	Altman's	0.9211	0.7815	0.3626	0.8773	0.7714	0.3196
	Ohlson's	0.8731	0.7947	0.3081	0.8850	0.8459	0.4014
	Combination	0.8766	0.8981	0.4041	0.9003	0.8539	0.4312
LR	Altman's	0.9048	0.8238	0.3752	0.8940	0.8115	0.3804
	Ohlson's	0.8594	0.7749	0.2785	0.8822	0.8132	0.3664
	Combination	0.8758	0.8849	0.3917	0.9108	0.8673	0.4621
SVM	Altman's	0.9266	0.8478	0.4398	0.8913	0.8727	0.4351
	Ohlson's	0.8867	0.7764	0.3057	0.8934	0.8268	0.3944
	Combination	0.8867	0.8779	0.3988	0.9080	0.8815	0.4704
NN	Altman's	0.8912	0.8548	0.3842	0.9108	0.8986	0.4915
	Ohlson's	0.8948	0.8821	0.4137	0.9192	0.9108	0.5196
	Combination	0.9411	0.8553	0.4859	0.9652	0.8878	0.6557

Notes: Balanced stands for balanced accuracy and MCC stands for Matthews correlation coefficient.

only neural networks and LDA models are affected by the decision of choosing a threshold between 0 and 1 (excluding 0 and 1). The predictive performances of other models, including logistic regression, LDA, and SVM do not depend on the threshold since their predictive output is either 0 or 1.

We agree with both [Abinzano et al. \(2020\)](#) and [Cathcart et al. \(2020\)](#) that the structure of the sample has an important role on the accuracy of the predictive models. In particular, the firms' size is related to the prediction ability of the model ([Abinzano et al. 2020](#)). Also, the predictive performance of models is impacted by the debt structure of firms ([Cathcart et al. 2020](#)).

Regarding variables for the prediction models, our results on feature importance not only confirm the significant predictability of variables used in [Altman \(1968\)](#) and [Ohlson \(1980\)](#) but also support [Chen et al. \(2006\)](#) assertion that variables such as *reat*, *ltat*, and *wcapat* provide an overall picture of a firm's performance in terms of profitability, solvency, and liquidity. Indeed, feature importance results provide a general view of a firm's performance in terms of profitability (*reat*), solvency (*ltat*), and liquidity (*wcapat*). Specifically, a company with low profitability, high solvency, and illiquidity indicates early signals of financial distress.

Regarding neural networks, this method normally works well with large datasets, which might not be met in many financial distress and bankruptcy prediction studies due to the limited number of observations of the minority group (i.e. financial distress firms or bankrupt firms). If one can somehow increase the number of observations in the minority group, then the predictive performances of the neural network models might be better. Although with relatively small datasets, we find that neural networks might be more

suitable than traditional statistical methods (e.g. logistic regression) in predicting corporate financial distress. Our finding is consistent with [Chen and Du \(2009\)](#).

One important point is that most studies about financial distress or bankruptcy prediction in transition economies (not only in Vietnam) work on imbalanced data but they do not mention in detail their strategies to take into account their imbalanced data. As a result, their results and conclusions might be misleading. For example, [Vo et al. \(2019\)](#) work on two samples, one with about 87% of non-financial distress firms (and 13% of distress firms) and another one with about 73% non-financial distress firms (and 27% financial distress firms). In case they do not take imbalanced data into account their results about accuracy might not be accurate. This is because the models with imbalanced data tend to be biased toward the majority group. In our study, we use balanced accuracy rather than accuracy. Specifically, we assign the weight to one incorrect prediction of the minority group is higher than the weight of one incorrect prediction of the majority group. By doing so, our results are not biased due to imbalanced data.

Note that there are two types of comparisons among models in this study. One is a comparison among the models with the same accounting-based variables (features). The other one is a comparison between models with different input variables. Regarding the comparison between the Merton model and accounting-based models (i.e. logistic regression and machine learning models), the comparability between the results of these models should be considered with caution. One reason is that these models use really different input variables: one base frequent market values while the other ones base on periodic book values. Note that one key variable in the Merton model in our study is a 1-year interest of Vietnam’s government bond, which sometimes remains constant for days. Also, the efficiency of Vietnam’s stock markets is still not clear at the moment. If the market is inefficient, the Merton model might not predict financial distress well.

3.7 Conclusion

This paper compares the performances of the accounting-based, market-based, and machine learning models in predicting corporate financial distress in a transition economy, Vietnam. The results suggest that while all models perform reasonably well in predicting financial distress outcomes for non-delisted companies, their performance is poor when it comes to predicting outcomes for delisted companies, as measured by various accuracy metrics like balanced accuracy, precision, recall, and F1 score. The study shows that models that combine Altman’s and Ohlson’s variables outperform those that use only one of these variables when it comes to balanced accuracy. Moreover, the study finds that neural networks are consistently the most effective models, as measured by both balanced accuracy and Matthews correlation coefficient (MCC). The variable “reat” (retained earnings over total assets) is the most important variable in Altman’s variables as well as in the

combination of Altman's and Ohlson's variables, while "ltat" (total liabilities over total assets) and "wcapat" (working capital over total assets) are the most important variables in Ohlson's variables. The study also reveals that the models generally perform better in predicting financial distress outcomes for large companies than for small ones, and their predictive performance is typically better in good years than in bad years, as measured by MCC.

One limitation of this study is that we work on the given list of independent variables (Altman's variables, Ohlson's variables, and the combination). Future research might extend this work by working on a list of variables close to the context of transition economies instead of that base on a developed economy like the United States with Altman's variables and Ohlson's variables in 1968 and 1980, respectively.

Since we only consider the 80/20 split ratio of the train and test set, one potential direction for future research is to examine other split ratios. Also, one can study good years and bad years as a dummy variable to investigate whether this dummy variable affects the predictive performances. Another direction is to compare the predictive results in different sectors or different stock exchanges, including Ho Chi Minh City Stock Exchange (HOSE) and Hanoi Stock Exchange (HNX).

For the Merton model, as we argue in the results section since there is a lack of studies on the efficiency of Vietnam's stock market and the Merton model, further research on both topics is surely needed. Note that in order for the Merton model to work well, the stock market needs to be efficient, including one of weak-form, semi-strong-form, or strong-form efficiency in the sense of [Fama \(1970\)](#). Also, future research needs to verify the assumption of standard normal distribution of some components in the Merton model before carrying it with data. Once the standard distribution assumption and the efficiency of the market are satisfied, the Merton model might be a good model to predict corporate financial distress in a transition economy like Vietnam.

Appendices

Appendix 1: Confusion matrix, Matthews correlation coefficient, accuracy, balanced accuracy, recall (or sensitivity), and specificity

Given the following general confusion matrix as follows.

		Predicted		Total
		Positive (P)	Negative (N)	
Actual	Positive (P)	True Positive (TP)	False Negative (FN)	TP + FN
	Negative (N)	False Positive (FP)	True Negative (TN)	FP + TN
Total		TP + FP	FN + TN	P + N

The formulas of the Matthews correlation coefficient (MCC), accuracy, sensitivity, and specificity are derived based on the above confusion matrix.

- The Matthews correlation coefficient (MCC)

$$\text{MCC} = \frac{\text{TP} \times \text{TN} - \text{FP} \times \text{FN}}{\sqrt{(\text{TP} + \text{FP})(\text{TP} + \text{FN})(\text{TN} + \text{FP})(\text{TN} + \text{FN})}}$$

MCC has values between -1 and 1 , i.e.

$$-1 \leq \text{MCC} \leq 1.$$

- Accuracy (ACC)

$$\text{ACC} = \frac{\text{TP} + \text{TN}}{\text{TP} + \text{TN} + \text{FP} + \text{FN}}.$$

ACC has values between 0 and 1 (or 0% and 100% percent), i.e.

$$0\% \leq \text{ACC} \leq 100\%.$$

- Balanced accuracy for imbalanced data

$$\text{Balanced accuracy} = \frac{\text{Recall (majority group)} + \text{Recall (minority group)}}{2},$$

where the recall of each group is calculated from the confusion matrix of corresponding each group as follows

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}}.$$

The values of recall vary from 0 for no recall and 1 for perfect recall. Another score that goes side by side with recall is precision.

- Precision

$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}}.$$

- F1-score: A popular measure based on recall and precision is F1-score (aka F-score or F-measure). The formula of F1-score is given by

$$F_1 = 2 \frac{\text{Precision} * \text{Recall}}{\text{Precision} + \text{Recall}} = \frac{2\text{TP}}{2\text{TP} + \text{FP} + \text{FN}}.$$

- Sensitivity (or true positive rate - TPR)

$$\text{TPR} = \frac{\text{TP}}{\text{P}} = \frac{\text{TP}}{\text{TP} + \text{FN}}.$$

TPR has values between 0 and 1 (or 0% and 100% percent), i.e.

$$0\% \leq \text{TPR} \leq 100\%.$$

Note that the formulas for sensitivity and recall are exactly the same. In that sense, recall and sensitivity are the same.

- Specificity (or true negative rate - TNR)

$$\text{TNR} = \frac{\text{TN}}{\text{N}} = \frac{\text{TN}}{\text{TN} + \text{FP}}.$$

TNR has values between 0 and 1 (or 0% and 100% percent), i.e.

$$0\% \leq \text{TNR} \leq 100\%.$$

Some of the above criteria can be used to evaluate the ability of predictions of the Merton model approach as well as Altman model approach (Z-score).

Appendix 2: The list of delisted stocks on HOSE and HNX

Table 3.26: Delisted stocks on HOSE & HNX due to financial reasons between 2011-2021

Symbol	Delisted year	Symbol	Delisted year	Symbol	Delisted year
FPC	2011	HHL	2014	CTN	2016
SHN	2011	ILC	2014	VC5	2016
VT A	2011	MIC	2014	SRB	2016
DVD	2011	MMC	2014	DAC	2016
VSP	2012	NSN	2014	SQC	2016
AGC	2012	NVC	2014	CYC	2017
BAS	2012	PSG	2014	VNA	2017
CAD	2012	PVA	2014	VNH	2017
VKP	2012	SDB	2014	CPI	2017
CSG	2012	SJM	2014	STT	2018
SBS	2013	VCV	2014	ICF	2019
DDM	2013	VHH	2014	PPI	2019
IFS	2013	YBC	2014	VHG	2019
VES	2013	HLA	2015	ORS	2019
VSG	2013	HSI	2015	SDE	2019
FBT	2013	VNI	2015	SCJ	2019
STL	2013	NVN	2015	DLR	2019
THV	2013	DCT	2015	PCN	2019
TLC	2013	VST	2015	PVV	2019
SVS	2013	SSG	2015	VPK	2020
VCH	2013	BVG	2015	VCR	2020
SDJ	2013	V15	2015	CT6	2020
SHC	2013	VPC	2015	SCL	2020
SD8	2013	CTM	2015	SPP	2020
S27	2013	LM3	2015	MEC	2020
SCC	2013	PFL	2015	PVE	2020
DHI	2013	VNN	2015	DID	2020
AVS	2013	TSM	2015	NGC	2021
STL	2013	SD1	2015	S74	2021
CLP	2014	PID	2015	ATG	2021
CNT	2014	BTH	2015	LO5	2021
FDG	2014	VLF	2016	VT S	2021
PXM	2014	GTT	2016	HLY	2021
BHC	2014	PXL	2016	CLG	2021
BHV	2014	CID	2016	PXT	2021
GGG	2014	S12	2016	DPS	2021

Source: HOSE, HNX

Chapter 4

Finite and mean field games for optimal investment with HARA utility function and the presence of risk-seeking agents

Abstract

This study extends the work of [Lacker and Zariphopoulou \(2019\)](#) by considering the financial market with the presence of both risk-averse and risk-seeking agents. Specifically, the n -agent (finite) and mean field games for optimal investment with the family of the hyperbolic absolute risk aversion (HARA) utility function under relative performance concern/motivation are studied. Several specific forms of the HARA family, including exponential, power, and logarithmic form are investigated. We prove that there exists a unique constant Nash equilibrium and a unique constant mean field equilibrium in both the n -agent and mean field games for the case of strictly concave utility function. For the case of strictly convex utility function, there exists a unique corner solution in these games where agents invest all of their wealth in risky assets (e.g. stock) and invest nothing on riskless assets (e.g. bond). Furthermore, we discuss the qualitative effects of the personal and market coefficients on the optimal investment strategies.

Keywords: n -agent games, mean field games, optimal investment, risk-seeking agents.

JEL Codes: C70, D81, G11.

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4.1 Introduction

The most popular assumption in the relevant literature of optimal investment and portfolio optimization usually supposes that agents are uniform risk-averse or their utility functions are concave on the entire domain. The second popular assumption lying in the prospect theory is the S-shape utility function, which is convex in the domain of losses and concave in the domain of gains, and the slope in the domain of losses is steeper than that in the domain of gains. Instead of examining the variation of risk preferences *within* agents like the prospect theory or studying uniform risk-averse behavior like the mainstream economic literature, this study investigates risk preferences which may vary *between* agents depending on their characteristics. Meanwhile, we know a lot about the behavior of risk-averse agents who have uniformly concave or S-shape utility functions, there is a lack of understanding of the behavior of risk-seeking agents and the interaction between risk-averse and risk-seeking agents. In contrast to the prospect theory, this study assumes that the utility functional form is a characteristic of each individual rather than depends on whether she gains or losses. This implies that the individual risk preferences are stable over time and not easy to change during a short period of time.

4.1.1 Motivation: The presence of risk-seeking agents

Risk-seeking behavior of agents (e.g. investors) is examined theoretically and empirically by many previous studies in the literature (e.g., [Kahneman and Tversky 1979](#); [Wong and Li 1999](#); [Niendorf and Ottaway 2002](#); [Seel and Strack 2013](#); [Bai et al. 2014](#); [Hoang et al. 2015](#); [Guo et al. 2016](#); [Clark et al. 2016](#); [Wu and Jaimungal 2023](#)). Specifically, [Seel and Strack \(2013\)](#) shows that, in a declining industry, risk-loving agents might invest in projects with negative expected returns. In addition, [Niendorf and Ottaway \(2002\)](#) shows that during bear markets, agents have an incentive to act in a risk-seeking manner. Empirically, [Bai et al. \(2014\)](#) find that there exist two types of investors, risk-averse and risk-seeking agents, on the stock market. Moreover, [Clark et al. \(2016\)](#) find the existence of all four investor types corresponding to concave, convex, S-shape, and reverse S-shape on the Taiwan stock and stock index futures markets. Also, they figure out that risk-seeking agents prefer futures markets to spot markets.

In reality, there are many situations where risk-seeking behavior exists. Indeed, we know much about the investing activities on the traditional underlying assets (e.g., stock and bond) on the financial markets; meanwhile, our understanding of risk-seeking investing activities (e.g., playing the lottery, gambling, speculating, sports betting, and short selling) of risk-seeking agents is very limited. It is worth exploring some types of risk-seeking agents and their risk-seeking behavior.

Lottery players as risk-seeking agents

A lottery is a game involving drawing a number for a prize for which only few buyers win while a much greater number of buyers does not. That means this is risky entertainment. To examine, let's consider the California SuperLotto Plus¹. To play, a player picks five numbers between 1 and 47 and one Mega number between 1 and 27 and she needs to pay \$1 per play for each SuperLotto Plus ticket. The prize amounts and the game odds (the inverse of the probability of winning a prize) are described in Table 4.1.

Table 4.1: A description of the California SuperLotto Plus lottery

Matching numbers	Odds 1 in (1/winning probability)	Prize amounts
All 5 of 5 and Mega	41,416,353	\$15,000,000
All 5 of 5	1,592,937	\$33,622
Any 4 of 5 and Mega	197,221	\$1,400
Any 4 of 5	7,585	\$89
Any 3 of 5 and Mega	4,810	\$52
Any 3 of 5	185	\$9
Any 2 of 5 and Mega	361	\$10
Any 1 of 5 and Mega	74	\$2
None of 5, only Mega	49	\$1
Overall odds of winning	23	One (any) prize

Source: Calottery

The probability of winning a prize, for example, the first prize (all 5 of 5 and Mega), is

$$\binom{47}{5} \binom{27}{1} = \frac{1}{41,416,353},$$

and similarly for the probabilities for other prizes. From Table 4.1, the expected payoff of buying a California SuperLotto Plus ticket is

$$\frac{1}{41,416,353} \$15,000,000 + \frac{1}{1,592,937} \$33,622 + \dots + \frac{1}{74} \$2 + \frac{1}{49} \$1 \approx \$0.5367 \approx 54 \text{ (cents)}.$$

In general, not only the California SuperLotto Plus ticket that we mention here but it seems almost all (or probably all) real-world private or state lotteries have expected payoffs that are lower than the cost to purchase them.

Why do people play lotteries even though the expected payoff is less than the cost to play? One can use knowledge of behavioral economics to explain by assuming that lottery players

¹For more details, please see <https://www.calottery.com/draw-games/superlotto-plus#section-content-4-3>

are irrational. They might overestimate (or overweight) the small probability to win a lottery. Also, they might believe that their subjective confidence in their own ability to win a lottery is greater than the actual probability to win. This is the so-called overconfidence effect. This study, however, assumes that lottery players are rational. They play lotteries because they realize that by doing so they can gain benefits. We assume that lottery players are risk-seeking agents and have convex utility functions. Therefore, even though the expected payoff is negative, the utility they gain might be positive. Moreover, individuals might play lotteries not only because of the monetary value but also the non-monetary value (e.g. pleasure), which is not reflected in the expected payoff but the gaining utility (value). Assume that the lottery players are rational and their purpose is to maximize their utility levels. Thus, if a player prefers the California SuperLotto Plus ticket with the expected payoff is 54 cents than a sure lottery with a payoff \$1 (cost for each California SuperLotto Plus ticket), then she is a risk-seeker.

Gamblers as risk-seeking agents

Let's consider *Roulette*, which is a popular casino game. In this game, players choose to place finite bets on either a single integer number (from 1 to 36) or a group of several numbers, which are low (1-18), high (19-36), odd, even, black, or red on a wheel. The number zero might appear once (French/European style roulette) or twice (American style roulette) on the wheel and it is colored in green.

Suppose a European roulette model in which a player chooses the *straight up* (single number) bet strategy with the winning space being any single number. Thus, the probability space is $(\Omega, 2^\Omega, \mathbb{P})$, where $\Omega = \{0, 1, \dots, 36\}$, $\mathbb{P}(A) = |A|/37$ for any $A \in 2^\Omega$. Define a bet a triple $B = (A, s, p)$, where A is the set of chosen numbers, $s \in \mathbb{R}^+$ is the size of the bet, and $p : \Omega \rightarrow \mathbb{R}$ is the payoff function of the bet. Thus, the payoff function of the space $B = (w_0, s, p)$ for some $w_0 \in \Omega$ is defined by

$$p(w) = \begin{cases} -s, & w \neq w_0 \\ 35s, & w = w_0. \end{cases}$$

Thus, the expected payoff is

$$E[p(w)] = \frac{1}{37}(35s) + \frac{36}{37}(-s) = -\frac{s}{37} \approx -0.027s.$$

Suppose $s = \$10$, then $E[p(w)] \approx \$ - 0.27 = -27$ cents. That is, for each time of playing with the cost of \$10, the player loses approximately 27 cents after each game, which is equivalent to 2.7%.

Alternatively, suppose a player chooses even odd bet strategy in a European roulette game. The rule is that if the bet wins then that player gets double, if the bet loses the player gets

nothing. Since there are 37 numbers, $\Omega = \{0, 1, \dots, 36\}$ and the host always win if you choose 0, the probability that a player wins for each game is $p = 18/37 \approx 0.4864$, which is actually less than one-half. Moreover, suppose the size of the bet is $s = \$10$. Thus, the expected payoff for each game equals the sure lost minus expected gain, which is

$$10 - \left[\frac{18}{37}(2 \times 10) + \frac{1}{37}(0) \right] \approx -\$0.27 \quad (\text{or 27 cents}).$$

To sum up, in either straight up or even odd strategy, the player loses about 27 cents after each game. But why are there still many people playing roulette nowadays?

Sports betting players as risk-seeking agents

Sports betting is a gambling-like activity. Football betting, for instance, is now popular with the support of computers and the internet. Table 4.2 shows the betting odds for the top-10 football teams in the 2014 World Cup.

Table 4.2: The 2014 World Cup betting odds for the top-10 teams²

Country	Betting odds	Country	Betting odds
Brazil	3/1 ³	Italy	20/1
Argentina	5/1	Holland	25/1
Germany	5/1	France	25/1
Spain	6/1	Colombia	25/1
Belgium	16/1	England	28/1

Short-sellers as risk-seeking agents

Consider the financial market where short sales are allowed. In reality, approximately 1 of 35 (equivalently about 2.88%) traded stocks on Nasdaq is short selling and the average percentage of shorted shares of 100 most active stocks is 4.17% (Angel et al. 2003). One noticeable result is that short-sellers have preferences for the risky factors (Dechow et al. 2001). We will theoretically show later in this study that those who short stocks are risk-seeking. Short-sellers usually short the stocks that are relatively overvalued relative to its fundamentals or probably the stocks of acquiring firms in the mergers and acquisitions process (Dechow et al. 2001). They may also short the stocks of firms that misrepresent their financial statements (Karpoff and Lou 2010). Short-sellers might borrow an asset, for example, the shares of a stock, from the brokers and sell it and then buy it back at some period in the future. They make a profit when the price drops and make a loss when the price increases. Since the price can only drop to zero, then the profit is bounded.

²See more details at <https://www.businessinsider.com/world-cup-favorites-2014-4>

³3/1 odds means one bet \$1 and get \$4 if Brazil wins, giving her/him a profit of \$3.

Meanwhile, since the price can go up arbitrarily high then the potential loss is unbounded. Therefore, short-selling is a risky activity.

Speculators as risk-seeking agents

Speculators might utilize leverage to magnify gains (and losses). By using leverage, the potential gains are high but the potential losses are also high. They usually do not hold assets or derivative securities for a long period. Speculators aim at outperforming traditional longer-term investors by making gains that are large enough to offset the high risk. As risk-seeking agents, a common strategy for speculators is to invest in derivatives (e.g. futures). Specifically, [Lean et al. \(2010\)](#) discover in Malaysian markets that, for risk-averse agents, spot dominates futures under second-order stochastic dominance (SSD), while for risk-seeking agents, futures dominate spot under SSD. That is, risk-seeking agents prefer futures while risk-averse agents prefer spots to maximize their expected utility. Similarly, [Qiao et al. \(2013\)](#) find that, for the emerging markets, futures dominate the spot for risk-seeking agents while the spot dominates futures for risk-averse agents. As a result, there are potential gains for risk-seeking agents if they switch their investment from spot to futures and for risk-averse agents if they switch from futures to spot.

Entrepreneurs as risk-seeking agents

Entrepreneurs are willing to take many risks, particularly the risk of failure. Indeed, there are about 90% startups failing ([Cusumano 2013](#)). This is because of uncertainties and the lack in many aspects of the business at the early state including financing, hiring talents, pricing, knowledge of the market demand, and experience of competition ⁴.

In summary, Table 4.3 compares this study and standard optimal investment literature, expected utility theory, and prospect theory.

Table 4.3: Comparison the utility functional forms in the literature

	Standard optimal investment literature	Expected utility theory (EUT)	Prospect theory	This study
Utility functional form	concave	concave, convex, or linear	convex-concave (S-shape)	convex, concave
Agents	risk-averse	risk-averse, risk-seeking, and risk neutral	risk-seeking and risk-averse	risk-seeking, and risk-averse
Variation in risk preferences	NA	between agents	within agents	between agents

⁴For more details, please see <https://s3-us-west-2.amazonaws.com/cbi-content/research-reports/The-20-Reasons-Startups-Fail.pdf>

4.1.2 Mean field games

Mean field games (MFG) are the limiting version (or sometimes called the aggregated version) of the N -agent games. This is a kind of stochastic strategic decision game. MFG has been pioneered in [Lasry and Lions \(2006a,b, 2007a,b\)](#) and independently in [Huang et al. \(2006\)](#). MFG has a close relationship with infinite-player games in the game theory literature. Indeed, games with a continuum of infinite players have long been considered in game theory ([Shapiro and Shapley 1961](#); [Milnor and Shapley 1961](#); [Shapley 1961](#); [Aumann 1964](#); [Aumann and Shapley 1974](#); [Aumann 1975](#); [Jovanovic and Rosenthal 1988](#); [Myerson 1991](#); [Khan and Sun 2002](#); [Rauh 2003](#); [Huang 2013](#); [Chan and Sircar 2015](#)). In short, Table 4.4 compares the differences between infinite-player games and MFG.

Table 4.4: Comparison between infinite-player games and MFG

	Infinite-player games	MFG
Agents	Homogeneous or heterogeneous	Heterogeneous
Mean-field parameter	No	Yes
Tools for existence proof	Fixed-point theorem (Brouwer or Kakutani)	Optimal control (OC) problem, PDE, SDE
Strategies	Pure (discrete) and mixed strategies	Continuous controls (strategies)
Setting (model)	Optimization problem or OC problem	OC problem or Coupled system of two PDEs

4.1.3 Brownian motions as stochastic shocks

The price dynamics is described by the following stochastic differential equation, which includes two independent geometric Brownian motions as stochastic shocks: W_t (individual shocks) and B_t (market shocks),

$$\frac{dS_t}{S_t} = \mu dt + \nu dW_t + \sigma dB_t,$$

where μ is the trend, ν and σ are the individual and market volatility, respectively, and S_t is the price of a particular asset. The market shocks (e.g. pandemic, terrorism attacks, major natural disasters, or financial crisis) and individual shocks (e.g. company restructuring, cost shock, factory fire, or sudden change in dividend policies) can be arbitrarily small or large. We assume that the shocks are random (unpredictable) for typical investors. We also assume that all of the shocks reflect in the price in a short time via two Brownian motions (i.e. the efficient market hypothesis holds). Note that individual shocks mean that each

individual investor investing in an individual asset faces different shocks. Even though they face the same market shocks, they universally face different levels of shocks.

4.1.4 Relative performance: Individual investors vs. Fund managers

Utility function with relative performance criteria is developed to reflect the human psychology that people normally compare their performance with those of their peers. This kind of difference-like comparison affects people's well-being and behavior. The idea of utility with relative performance is not new in economic literature (Abel 1990; Fehr and Schmidt 1999).

In MFG, typical works assume that fund managers concern about the relative performance of their peers since incentive compensation (e.g. payment incentive, promotion incentive) is popular in the fund managers community (Chevalier and Ellison 1999; Espinosa and Touzi 2015; Huang and Nguyen 2016; Lacker and Zariphopoulou 2019; Fu and Zhou 2020). In contrast with these studies, our study focuses on individual investors rather than fund managers. It is noticeable that, besides incentive compensation, fund managers and individual investors are different in the sense that fund managers are normally involved in agent-principal problems in which the managers' benefits and the principal's benefits might be different. This is not the case for individual investors. As a result, these two groups (individual investors and fund managers) might not share the same investment behavior. Fund managers pay attention to relative performance concern while individual investors might pay attention to relative performance concern as well as relative performance motivation. The differences in the behavior of these two groups of agents are reflected in risk tolerance and relative performance parameter. Table 4.32 compares some recent related work with this study.

Table 4.5: Some studies related to relative performance

Literature	Espinosa and Touzi (2015)	Lacker and Zariphopoulou (2019)	Fu et al. (2020)	This study
Utility function	CARA	CARA, CRRA	Exponential	HARA
Agents (or players)	Portfolio managers	Fund managers	Fund managers	Individual investors
Risk preference	Risk aversion	Risk aversion	Risk aversion	Risk aversion and risk-seeking
Personal risk tolerance	Positive	Positive	Positive	Not equal zero
Relative performance (θ_i)	$\theta_i \in [0, 1)$	$\theta_i \in [0, 1]$	$\theta_i \in [0, 1)$	$\theta_i \in [-1, 1]$
Expected value	unclear	positive, unbounded	bounded	non-negative, bounded
Method	BSDE	PDE	FBSDE	PDE
Well-posedness	Yes	Yes	Yes	Yes

Why do we assume $\theta_i \in [-1, 1]$? We will explain it based on psychological perspectives. On the one hand, if comparison brings concern or worry or jealousy to agent i (if agent i compares her performance with higher earners, which is called upward social comparison), or

arrogance (if agent i compares her performance with lower earners, which is called downward social comparison) then it is not good for her. In this situation, it is described by the so-called *relative performance concern* and denoted by $\theta_i^+ \in [0, 1]$. In an experimental study about the effect of economic inequality on risk behavior, [Payne et al. \(2017\)](#) shows that there is 63% of participants choosing upward comparison while 37% of participants choosing downward comparison. Note that the term “relative performance concern” in this study is equivalent to the term “relative performance” in [Espinosa and Touzi \(2015\)](#) and [Lacker and Zariphopoulou \(2019\)](#).

On the other hand, if comparison brings motivation or inspiration (if upward social comparison), or pride (if downward social comparison) then it is good for agent i , which is illustrated by the so-called *relative performance motivation* and denote by $\theta_i^- \in [-1, 0]$. Some previous studies show that peer effects might help improve performance. [Eisenkopf \(2010\)](#) discovers that peers impact performance not just during interaction but also before and afterward. This implies that the performance of an individual might be affected just by comparison with peers. [Kaustia and Knüpfer \(2012\)](#) find that recent stock returns that local peers experience affect an individual’s stock market entry decision, especially in areas with better opportunities for social learning.

Briefly, this study aims to characterize the behavior of risk-seeking and risk-averse agents in n -agent games and MFG. Specifically, I will tackle the following questions: (i) Are there exist Nash equilibrium (NE) and mean field equilibrium (MFE) in n -agent games and MFG with the presence of risk-seeking agents? (ii) If NE and MFE exist, in which conditions are they unique? (iii) How do the NE and MFE depend on the personal and market parameters?

The remainder of the chapter is organized as follows. Section 4.2 will describe a functional form of HARA utility function. We then explore n -agent and mean field games for the exponential form in Section 4.3 and the power form in Section 4.4. Hence, we will discuss the effects of personal and market parameters on equilibrium in Section 4.5 and finally conclude the chapter in Section 4.6.

4.2 HARA utility function

The family of utility functions called the HARA family is first introduced by [Merton \(1971\)](#) and is studied extensively in the literature of portfolio selection ([Merton 1987](#); [Davis and Norman 1990](#); [Kim and Omberg 1996](#); [Duffie et al. 1997](#); [Benth et al. 2001](#); [Çanakoglu and Özekici 2010](#); [Escobar et al. 2017](#)). Before considering the explicit form of the HARA family for this study, we propose several necessary assumptions.

4.2.1 Assumptions

Some necessary assumptions for both n -agent games and mean field games are given as follows. These are the common (either implicit or explicit) assumptions of the standard models in mean field games.

Assumption 4.2.1 (Rationality). *In investing activities, agents are rational.*

Assumption 4.2.2 (Common knowledge). *The individual preference parameters and market parameters are common knowledge.*

As we will see in the next section, we will investigate models with complete information. Specifically, the personal preferences and market parameters in n -agent games and MFG are common knowledge for all agents and each agent knows that each other agent knows a common knowledge.

Assumption 4.2.3 (Zero transaction costs). *There are no or negligible transaction costs in trading assets.*

Assumption 4.2.4 (Complete market). *The market is complete, i.e. there exists the price for every asset in any state.*

Note that the Assumption 4.2.1-4.2.4 implies that the financial market in this study is a perfect market. Even though the perfect market might be not realistic in the current uncertain world, “the model may indeed provide the best description of the financial system in the long run” (Merton 1987).

Assumption 4.2.5 (Heterogeneous agents). *Agents are heterogeneous, i.e. each agent has the same utility functional form and dynamics but with different parameters.*

4.2.2 HARA utility functional form

Definition 4.2.1 (HARA utility function). *A utility function with nonnegative real domain \mathbb{R}^+ is said to exhibit the hyperbolic absolute risk aversion (HARA) if and only if the inverse of absolute risk aversion, $r(x) = 1/A(x) = -U'(x)/U''(x)$, is a linear function of wealth (level).*

In this study, the functional form of the family of HARA utility functions with relative performance is given by

$$U_i(X_T^i, \bar{X}_T) = a_i \left(\frac{1 - \alpha}{\alpha} \right) \left(\frac{X_T^i * f(\bar{X}_T, \theta_i)}{1 - \alpha} - \eta_i \right)^\alpha + b, \quad \alpha \neq 0, \alpha \neq 1 \quad (4.1)$$

where $\alpha, a_i, b, -1 \leq \theta_i \leq 1$, and η_i are constant; $*$ is an abstract operation, which can be subtraction or multiplication. Here, X_T^i is the agent i 's terminal wealth; \bar{X}_T is the

average terminal wealth of all agents including agent i . There are two cases: (i) X_T^i and \bar{X}_T have linear relationship (if $*$ is subtraction) and $f(\bar{X}_T, \theta_i)$ describes a linear relationship in terms of wealth, i.e. $f(\bar{X}_T, \theta_i) = \theta_i \bar{X}_T$; (ii) X_T^i and \bar{X}_T have nonlinear relationship (if $*$ is multiplication) and $f(\bar{X}_T, \theta_i)$ describes a nonlinear relationship with wealth with $f(\bar{X}_T, \theta_i) = \bar{X}_T^{-\theta_i}$. We can check that the HARA family of utility function (4.1) satisfies Definition 4.2.1.

If $*$ is subtraction and $f(\bar{X}_T, \theta_i) = \theta_i \bar{X}_T$, we can check that the inverse of absolute risk aversion, $1/A(X_T^i)$, is a linear function of wealth X_T^i . Indeed, take the first and second derivative of the utility function (4.1) with respect to X_T^i yields

$$U'_i = a_i \left(\frac{X_T^i - \theta_i \bar{X}_T}{1 - \alpha} - \eta_i \right)^{\alpha-1}, \quad U''_i = -a_i \left(\frac{X_T^i - \theta_i \bar{X}_T}{1 - \alpha} - \eta_i \right)^{\alpha-2}.$$

Thus, the linear form of the inverse of absolute risk aversion with respect to X_T^i is given by

$$\frac{1}{A(X_T^i)} = -\frac{U'_i}{U''_i} = \frac{1}{1 - \alpha} X_T^i - \left(\frac{\theta_i \bar{X}_T}{1 - \alpha} + \eta_i \right).$$

Similarly, if $*$ is multiplication and $f(\bar{X}_T, \theta_i) = \bar{X}_T^{-\theta_i}$, we can derive that

$$U'_i = a_i \left(\frac{X_T^i \bar{X}_T^{-\theta_i}}{1 - \alpha} - \eta_i \right)^{\alpha-1} \bar{X}_T^{-\theta_i}, \quad U''_i = -a_i \left(\frac{X_T^i \bar{X}_T^{-\theta_i}}{1 - \alpha} - \eta_i \right)^{\alpha-2} \left(\bar{X}_T^{-\theta_i} \right)^2.$$

Thus, obtain the linear expression on the right hand side as follows

$$r(X_T^i) = \frac{1}{A(X_T^i)} = -\frac{U'_i}{U''_i} = \frac{1}{1 - \alpha} X_T^i - \frac{\eta_i}{\bar{X}_T^{-\theta_i}}.$$

Remark 4.2.1. *By introducing the average terminal wealth \bar{X}_T , we can induce the n -dimensional n -agent games and infinite dimensional MFG to the 2-dimensional optimal control problem. That is, the utility function now only depends on two variables: the agent i 's terminal wealth X_T^i and the average terminal wealth of the population \bar{X}_T .*

The utility functional form (4.1) is explicitly a function of wealth level (a stock), or wealth for short, rather than a function of return (a flow). We will see in the next sections that the return will be a part of the price dynamics, which then affects the stock of wealth. That is, the return of stocks will indirectly affect the agent i 's utility level. We will explain the meaning of the parameters in the next sections. We are going to derive a number of utility functions, which are special cases of (4.1).

Exponential utility function. If $*$ is subtraction, and

$$f(\bar{X}_T, \theta_i) = \theta_i \bar{X}_T, \quad \eta_i = \frac{\alpha}{1-\alpha} \frac{1}{\gamma_i}, \quad a_i = \left(\frac{\alpha-1}{\alpha} \right)^{\alpha-1} \gamma_i^{\alpha-1}, \quad b = 0$$

then

$$\begin{aligned} U_i(X_T^i, \bar{X}_T) &= \left(\frac{\alpha-1}{\alpha} \right)^{\alpha-1} \gamma_i^{\alpha-1} \left(\frac{1-\alpha}{\alpha} \right) \left(\frac{X_T^i - \theta_i \bar{X}_T}{1-\alpha} - \frac{\alpha}{1-\alpha} \frac{1}{\gamma_i} \right)^\alpha \\ &= -\frac{1}{\gamma_i} \left(\frac{\alpha-1}{\alpha} \right)^\alpha \gamma_i^\alpha \left[\frac{1}{\alpha-1} \left(\frac{\alpha}{\gamma_i} - (X_T^i - \theta_i \bar{X}_T) \right) \right]^\alpha \\ &= -\frac{1}{\gamma_i} \left(1 - \frac{\gamma_i(X_T^i - \theta_i \bar{X}_T)}{\alpha} \right)^\alpha. \end{aligned}$$

Taking limit as $\alpha \rightarrow \infty$, we get the exponential functional

$$\begin{aligned} \lim_{\alpha \rightarrow \infty} U_i(X_T^i, \bar{X}_T) &= \lim_{\alpha \rightarrow \infty} -\frac{1}{\gamma_i} \left(1 - \frac{\gamma_i(X_T^i - \theta_i \bar{X}_T)}{\alpha} \right)^\alpha \\ &= -\frac{1}{\gamma_i} \lim_{\alpha \rightarrow \infty} \left(1 - \frac{\gamma_i(X_T^i - \theta_i \bar{X}_T)}{\alpha} \right)^\alpha \\ &= \frac{-e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)}}{\gamma_i}. \end{aligned}$$

For simplicity, we can write

$$U_i(X_T^i, \bar{X}_T) = \frac{-e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)}}{\gamma_i}. \quad (4.2)$$

Taking the first and second derivative of the utility function (4.2) with respect to X_T^i yields

$$U_i' = e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)} \quad \text{and} \quad U_i'' = -\gamma_i e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)}.$$

Thus, we get the constant Arrow-Pratt coefficient of absolute risk aversion (CARA)

$$A(X_T^i) = -\frac{U_i''}{U_i'} = \gamma_i, \quad \text{for all } X_T^i.$$

Therefore, we say (4.2) is a CARA utility function. Note that CARA agents invest a constant amount of dollars in risky assets regardless of wealth level. Also note that in this case the *inverse* of absolute risk aversion is also constant, $r(X_T^i) = 1/A(X_T^i) = -U_i'/U_i'' = 1/\gamma_i$, which is mathematically still a linear function with respect to wealth.

Power utility function: If $*$ is multiplication, and for all $i = 1, \dots, n$

$$f(\bar{X}_T, \theta_i) = \bar{X}_T^{-\theta_i}, \quad \gamma_i = 1 - \alpha, \quad a_i = (1 - \alpha)^{\alpha-1}, \quad b = 0, \quad \eta_i = 0$$

then

$$\begin{aligned}
U_i(X_T^i, \bar{X}_T) &= (1 - \alpha)^{\alpha-1} \frac{1 - \alpha}{\alpha} \left(\frac{X_T^i \bar{X}_T^{-\theta_i}}{1 - \alpha} \right)^\alpha \\
&= \frac{1}{\alpha} (X_T^i \bar{X}_T^{-\theta_i})^\alpha \\
&= \frac{(X_T^i \bar{X}_T^{-\theta_i})^{1-\gamma_i}}{1 - \gamma_i}, \quad \gamma_i \neq 1.
\end{aligned}$$

Thus,

$$U_i(X_T^i, \bar{X}_T) = \frac{(X_T^i \bar{X}_T^{-\theta_i})^{1-\gamma_i}}{1 - \gamma_i}, \quad \text{where} \quad \bar{X}_T = \left(\prod_{i=1}^n X_T^i \right)^{1/n}. \quad (4.3)$$

Here, \bar{X}_T is the geometric mean. Note that together with the arithmetic mean, geometric mean is also a popular measure for investors to evaluate a portfolio selection. Since arithmetic mean is always greater than or equal to geometric mean, using the later one might be a better tool in the sense of safety for investors.

From (4.3), taking the first and second derivatives with respect to X_T^i yields

$$U'_i = (X_T^i \bar{X}_T^{-\theta_i})^{-\gamma_i} \bar{X}_T^{-\theta_i} \quad \text{and} \quad U''_i = -\gamma_i (X_T^i \bar{X}_T^{-\theta_i})^{-\gamma_i-1} \bar{X}_T^{-2\theta_i}.$$

Thus, we can check that the power functional form (4.3) exhibits decreasing Arrow-Pratt measure of absolute risk aversion (DARA) and constant Arrow-Pratt measure of relative risk aversion (CRRA), respectively,

$$A(X_T^i) = -\frac{U''_i}{U'_i} = \frac{\gamma_i}{X_T^i} \quad \text{and} \quad R(X_T^i) = -X_T^i \frac{U''_i}{U'_i} = \gamma_i, \quad \text{for all } X_T^i.$$

Thus, the inverse of absolute risk aversion is

$$r(X_T^i) = \frac{1}{A(X_T^i)} = -\frac{U'_i}{U''_i} = \frac{1}{\gamma_i} X_T^i,$$

which is clearly a linear function of X_T^i . Therefore, it satisfies Definition 4.2.1 of the HARA family. Further, note that a DARA agent invests more amount of dollars in risky assets as wealth increases and a CRRA agent invests a constant fraction in risky assets regardless of the wealth level, which are two reasonable assumptions and are seemingly supported in the literature (Friend and Blume 1975; Graves 1979).

Logarithmic utility function. In this study, the logarithmic utility form is a special case of power utility form (4.3) when γ tends to 1. Explicitly, it has the form

$$U_i(X_T^i, \bar{X}_T) = \log(X_T^i \bar{X}_T^{-\theta_i}). \quad (4.4)$$

Taking the first and second derivative of (4.4) with respect to X_T^i yields

$$U_i' = \frac{1}{X_T^i} \quad \text{and} \quad U_i'' = -\frac{1}{(X_T^i)^2}.$$

Hence, we can check for all X_T^i that the Arrow-Pratt coefficient of absolute risk aversion is decreasing and the coefficient of relative risk aversion is constant as terminal wealth increases, respectively,

$$A(X_T^i) = -\frac{U_i''}{U_i'} = \frac{1}{X_T^i} \quad \text{and} \quad R(X_T^i) = -X_T^i \frac{U_i''}{U_i'} = 1 \quad (\text{constant}).$$

Thus, the *inverse* of absolute risk aversion is

$$r(X_T^i) = \frac{1}{A(X_T^i)} = X_T^i,$$

which is a linear function of X_T^i . So, the logarithmic utility function (4.4) satisfies Definition 4.2.1 of HARA utility function. Further, note that the logarithmic form (4.4) is a DARA as well as CRRA utility function.

Note that the power and logarithmic utility functions satisfy the Inada-type condition on the behavior at infinity, i.e. $U_i'(\infty) = 0$ but not zero. Zero is out of our domain since the assumption that $X_T^i \geq \varepsilon$ for some small $\varepsilon > 0$ so we do not need the condition $U_i'(0) = \infty$.

4.3 Exponential utility function

Dynamics. Consider a game with n agents (investors) investing on the financial market. Without loss of generality, one can work with the two-asset case in which each agent trades between a common risk-free asset (e.g. bond) and an individual risky asset (e.g. stock), which indicates asset specialization⁵. Similarly Lacker and Zariphopoulou (2019), here the bond is common to all agents and plays the role of the numeraire, and we assume it yields zero interest rate (zero-coupon bond). Specifically, the agent i invests in stock i whose price process $S_t^i, t \in [0, T]$, where T is the stopping time, with continuous paths, varies according to the following linear stochastic differential equation (SDE)

$$\frac{dS_t^i}{S_t^i} = \mu_i dt + \nu_i dW_t^i + \sigma_i dB_t, \tag{4.5}$$

where $0 \leq \mu_i \leq \bar{\mu}_i$ and $0 \leq \nu_i \leq \bar{\nu}_i$ and $0 \leq \sigma_i \leq \bar{\sigma}_i$ for some constants $\bar{\mu}_i, \bar{\nu}_i, \bar{\sigma}_i > 0$. Here, μ_i, ν_i , and σ_i are constant market coefficients. The parameter μ_i denotes the expected rate

⁵Many previous studies examine asset specialization, for example, Brennan (1975), Merton (1987), Coval and Moskowitz (1999), Liu (2014), Basak and Makarov (2015).

of return of the stock i which is assumed to be non-negative. The parameters ν_i and σ_i denote the volatility of some individual asset and the whole market, respectively.

Similarly to [Lacker and Zariphopoulou \(2019\)](#), in this study, the price process is driven by two independent 1-dimension standard Brownian motions W_t^i and B_t on a filtered probability space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$, where $\mathbb{F} = (\mathcal{F}_t)_{t \in [0, T]}$ is the complete filtration generated by $n + 1$ Brownian motions W_t^i , where $i = 1, \dots, n$, and B_t . Here, each W_t^i is called the idiosyncratic noise (idiosyncratic uncertainty) and B_t is called the common noise (aggregate uncertainty).

4.3.1 The n -agent games

We examine the games where n finite players trade between a common risk-free asset (e.g. bond) and an individual risky asset (e.g. stock) in a common time horizon $[0, T]$. Suppose that all agents have the same finite time horizon $[0, T]$. The exponential utility function⁶ for agent i at the terminal time T is given by

$$U_i(X_T^i, \bar{X}_T) = \frac{-e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)}}{\gamma_i}, \quad \gamma_i \neq 0, i = 1, 2, \dots, n \quad (4.6)$$

where $\bar{X}_T = \frac{1}{n} \sum_{k=1}^n X_T^k$ ⁷ is the arithmetic average terminal wealth invested in assets of the whole population. In the above utility function, $X_T^i \geq 0$ is the agent i 's individual wealth invested in assets (or just simply wealth for short) at the terminal period T ⁸, and \bar{X}_T is the average wealth of all agents at the terminal period T . Here, $\gamma_i \neq 0$ is a constant (but random) which represents the agent i 's Arrow-Pratt measure of absolute risk aversion. It does not depend on the types of assets and her wealth level. Note that the parameter γ_i can be positive or negative: $\gamma_i > 0$ represents the case of risk aversion while $\gamma_i < 0$ captures the case of risk-seeking behavior. Here, the relative performance parameter $\theta_i \in [-1, 1]$ for all $i = 1, \dots, n$ is a constant and it indicates that agent i takes into account her performance by comparison to her peers⁹ in which they usually assume $\theta_i \in [0, 1]$.

⁶This exponential utility function is more general than that in [Lacker and Zariphopoulou \(2019\)](#). In our study, γ_i can be positive or negative. Therefore, the utility function can be concave or convex to capture the case of risk-averse or risk-seeking agents, respectively. In [Lacker and Zariphopoulou \(2019\)](#), however, since the parameter $\delta_i > 0$ so it only captures the case that agents are risk-averse.

⁷Similarly to [Lacker and Zariphopoulou \(2019\)](#), here we consider the case that the average wealth of the population including the agent i for simplicity. The reason is that there is a one-to-one mapping between the case of including and excluding the agent i of the optimization problem (4.8).

⁸Many previous studies in the literature examine long-term investment strategies, for example, [Siegel \(2014\)](#).

⁹Note that in the utility function (4.6) the relative performance parameter θ_i can be negative, positive, or zero. This is different compared to many previous studies (e.g. [Espinosa and Touzi \(2015\)](#) and [Lacker and Zariphopoulou \(2019\)](#))

Taking the first and second-order derivative of the utility function (4.6) with respect to X_T^i , we obtain

$$U_i' = e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)} \quad \text{and} \quad U_i'' = -\gamma_i e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)}.$$

We can check whether the utility function U_i is strictly concave or convex depending on the sign of parameter γ_i . Specifically,

$$U_i(X_T^i, \bar{X}_T) \text{ is } \begin{cases} \text{strictly concave} & \text{if } \gamma_i > 0 \\ \text{strictly convex} & \text{if } \gamma_i < 0. \end{cases}$$

Definition 4.3.1 (Strategy). *A (trading) strategy (or portfolio) π_t at time t corresponding to the exponential utility function (4.6) is defined as $\pi_t := (x_t, y_t) \in \mathcal{F}_s, t < s \leq T$, where x_t and y_t denote the absolute value of wealth invested in stock i and in the numeraire, respectively.*

Note that the above definition is for the exponential utility function. For the case of the power and logarithmic utility function, as we will see in the next section, x_t and y_t denote the fraction of wealth invested in stock i and in the numeraire, respectively, instead of the absolute value of wealth in this section. Note also that $\pi_t \in \mathcal{F}_s, t < s \leq T$ means that investment strategy is adapted to the available information at any time s between the current time t and the terminal time T .

The wealth of agent i is described by the following dynamics

$$dX_t^i = \pi_t^i(\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t), \quad (4.7)$$

where $0 \leq \mu_i \leq \bar{\mu}_i, 0 \leq \nu_i \leq \bar{\nu}_i$, and $0 \leq \sigma_i \leq \bar{\sigma}_i$ for all $i = 1, \dots, n$; $X_0^i = x_0 \in \mathbb{R}$ is the initial wealth, π_t^i is the agent i 's investment strategy which indicates the amount of money that the agent i invests in stock i . Here, the investment strategy π_t^i only influences the change of wealth level X_t^i at any time $t \in [0, T]$. It thus indirectly (but not directly¹⁰) influences the utility level in the utility function (4.6).

Definition 4.3.2 (Self-financing strategy). *A self-financing strategy at time t is a strategy $\pi_t = (x_t, y_t) \in \mathcal{F}_s, t < s \leq T$, where the changes in the value of the portfolio are entirely due to trading gains and losses, rather than changes in the external sources.*

Similarly to [Lacker and Zariphopoulou \(2019\)](#) and [dos Reis and Platonov \(2021\)](#), we assume that each agent $i = 1, \dots, n$ trades using a self-financing strategy $\pi_t^i, t \in [0, T]$, which satisfies the mean square integrable property, i.e. $\mathbb{E}(\int_0^T |\pi_t^i|^2 dt) < \infty, \forall t \in [0, T]$. In other words,

¹⁰In the literature, the control might directly affect both the dynamics and the objective function, for example, see [Dorfman \(1969\)](#).

there is no borrowing and lending in this study. Note that π_t^i can be positive, negative, or zero which means the agent i buys, sells, or does nothing with asset i , respectively. Note also that if $\pi_t^i = 0$ then $dX_t^i = 0$. That is, if agent i does not invest in any assets then her level of wealth will remain unchanged. But in the case that she invests in some asset, i.e. $\pi_t^i \neq 0$, her wealth level might still remain unchanged if $\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t = 0$, which means the asset market is absorbed itself.

Suppose agent $i = 1, \dots, n$ chooses admissible trajectories $\pi^1, \dots, \pi^n \in \mathcal{A}$, where \mathcal{A} is the set of feasible strategies. The portfolio optimization problem is that the agent i aims to maximize her utility function (4.6) at the terminal period T

$$U_i(X_T^i, \bar{X}_T) = \sup_{\pi^i} \mathbb{E} \left[\frac{-e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)}}{\gamma_i} \right] \quad (4.8)$$

given by the dynamics constraint (4.7).

Rewriting the utility function (4.8), we get

$$U_i(\pi^1, \dots, \pi^n) = \sup_{\pi^i} \mathbb{E} \left[\frac{-e^{-\gamma_i \left((1-\theta_i)X_T^i + \theta_i(X_T^i - \bar{X}_T) \right)}}{\gamma_i} \right]. \quad (4.9)$$

Definition 4.3.3 (Nash equilibrium). *A vector of strategy profile $(\pi^{1,*}, \dots, \pi^{n,*})$ of admissible strategies \mathcal{A} constitutes a Nash equilibrium if for every $i = 1, \dots, n$ and for every $t \in [0, T]$,*

$$U_i(\pi_t^{1,*}, \dots, \pi_t^{i,*}, \dots, \pi_t^{n,*}) \geq U_i(\pi_t^{1,*}, \dots, \pi_t^{i-1,*}, \pi_t^i, \pi_t^{i+1,*}, \dots, \pi_t^{n,*})$$

for all $\pi^i \in \mathcal{A}$.

Here, we assume that the space of admissible strategies \mathcal{A} is a compact metric space. If the strategy is constant (but random) in the whole time horizon $[0, T]$, then we get the constant (but random) Nash equilibrium.

Definition 4.3.4 (Constant Nash equilibrium). *A vector of strategy profile $(\pi^{1,*}, \dots, \pi^{n,*})$ of the set of admissible strategies \mathcal{A} constitutes a constant Nash equilibrium if for every $i = 1, \dots, n$,*

$$U_i(\pi^{1,*}, \dots, \pi^{i,*}, \dots, \pi^{n,*}) \geq U_i(\pi^{1,*}, \dots, \pi^{i-1,*}, \pi^i, \pi^{i+1,*}, \dots, \pi^{n,*})$$

for all $\pi^i \in \mathcal{A}$.

The following theorem provides the conditions for the existence and uniqueness of a constant Nash equilibrium.

Theorem 4.3.1 (Existence and uniqueness of constant Nash equilibrium). *Given U_i is strictly concave utility function as in (4.6) with $\gamma_i > 0$. Define two constants*

$$\varphi_n = \frac{1}{n} \sum_{i=1}^n \frac{\mu_i}{\gamma_i} \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \quad \text{and} \quad \psi_n = \frac{1}{n} \sum_{i=1}^n \theta_i \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)}. \quad (4.10)$$

There are three cases:

(i) If $\psi_n \neq 1$, then there exists a unique constant Nash equilibrium given by

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i} \frac{1}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} + \theta_i \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{\varphi_n}{1 - \psi_n}. \quad (4.11)$$

Moreover, we have

$$\frac{1}{n} \sum_{k=1}^n \sigma_k \pi^{k,*} = \frac{\varphi_n}{1 - \psi_n}.$$

(ii) If $\psi_n = 1$ and $\varphi_n \neq 0$, there is no constant Nash equilibrium.

(iii) If $\psi_n = 1$ and $\varphi_n = 0$, there are infinitely many constant Nash equilibria.

Proof. We will prove the theorem by using PDE/optimal control approach¹¹. Let i be fixed. We denote $\alpha_k \in \mathbb{R}$ be the constant investment strategies followed by all other agents $k, k \neq i$. Let $X_t^k, t \in [0, T]$, be the associated wealth processes, given by

$$X_t^k = \alpha_k(\mu_k t + \nu_k W_t^k + \sigma_k B_t), \quad X_0^k = x_0^k$$

where x_0^k is the initial wealth of the agent k . Define

$$Y_t := \frac{1}{n} \sum_{k \neq i} X_t^k, \quad t \in [0, T].$$

Thus, we have

$$U_i(X_t^i, \bar{X}_t) = \frac{-e^{-\gamma_i(X_t^i - \theta_i \bar{X}_t)}}{\gamma_i} = \frac{-e^{-\gamma_i(X_t^i - \frac{\theta_i}{n}(X_t^i + \sum_{k \neq i} X_t^k))}}{\gamma_i} = \frac{-e^{-\gamma_i((1 - \frac{\theta_i}{n})X_t^i - \theta_i Y_t)}}{\gamma_i}.$$

The goal of the agent i is to solve the following optimization (optimal control) problem

$$\sup_{\pi^i \in \mathcal{A}} \mathbb{E} \left[\frac{-e^{-\gamma_i((1 - \frac{\theta_i}{n})X_t^i - \theta_i Y_t)}}{\gamma_i} \right] \quad (4.12)$$

¹¹This proof is largely inspired by the proof of Theorem 2.3 in [Lacker and Zariphopoulou \(2019\)](#).

for $t \in [0, T]$, with respect to the following two dynamics (one of agent i and one of all the other agents $k, k \neq i$)

$$\begin{aligned} dX_t^i &= \pi_t^i(\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t), & X_0^i &= x_0^i \\ dY_t &= \frac{1}{n} \sum_{k \neq i} \alpha_k (\mu_k dt + \nu_k dW_t^k + \sigma_k dB_t), & Y_0 &= \frac{1}{n} \sum_{k \neq i} x_0^k. \end{aligned}$$

By denote

$$\widehat{\mu\alpha} =: \frac{1}{n} \sum_{k \neq i} \mu_k \alpha_k \quad \text{and} \quad \widehat{\sigma\alpha} =: \frac{1}{n} \sum_{k \neq i} \sigma_k \alpha_k,$$

we get

$$dY_t = \widehat{\mu\alpha} dt + \widehat{\sigma\alpha} dB_t + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k.$$

Also, we denote

$$\widehat{(\nu\alpha)^2} =: \frac{1}{n} \sum_{k \neq i} \nu_k^2 \alpha_k^2.$$

Making the ansatz of the value function $V_i(X_t^i, Y_t, t)$, which we hope later on will solve the Hamilton-Jacobi-Bellman (HJB) equation, as follows

$$V_i(X_t^i, Y_t, t) = f(t) \frac{-e^{-\gamma_i \left((1 - \frac{\theta_i}{n}) X_t^i - \theta_i Y_t \right)}}{\gamma_i}, \quad \text{for } t \in [0, T]. \quad (4.13)$$

For simplicity, we write $V(X_t^i, Y_t, t) = V_i(X_t^i, Y_t, t)$ for all $i = 1, \dots, n$. Suppose $V(X_t^i, Y_t, t)$ is differentiable at least once in t and twice in X_t^i and Y_t . For simplicity, denote $x = X_t^i$ and $y = Y_t$, and

$$V_t = \frac{\partial V}{\partial t}, V_x = \frac{\partial V}{\partial X_t^i}, V_y = \frac{\partial V}{\partial Y_t}, V_{xx} = \frac{\partial^2 V}{\partial (X_t^i)^2}, V_{yy} = \frac{\partial^2 V}{\partial Y_t^2}, V_{xy} = \frac{\partial^2 V}{\partial X_t^i \partial Y_t}$$

Also, since we are looking for constant Nash equilibrium, we write $\pi_t^i = \pi^i$ for all $t \in [0, T]$. Denote dV as the total differential of $V(X_t^i, Y_t, t)$. Then, dV can be approximated by the

multivariate Taylor series expansion

$$\begin{aligned}
dV &= V_t dt + V_x dx + V_y dy + \frac{1}{2} V_{xx} (dx)^2 + \frac{1}{2} V_{yy} (dy)^2 + V_{xy} dx dy \\
&= V_t dt + V_x \left[\pi^i (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t) \right] + V_y \left[\widehat{\mu} \alpha dt + \widehat{\sigma} \alpha dB_t + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k \right] \\
&\quad + \frac{1}{2} V_{xx} \left[\pi^i (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t) \right]^2 + \frac{1}{2} V_{yy} \left[\widehat{\mu} \alpha dt + \widehat{\sigma} \alpha dB_t + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k \right]^2 \\
&\quad + V_{xy} \left[\pi^i (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t) \right] \left[\widehat{\mu} \alpha dt + \widehat{\sigma} \alpha dB_t + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k \right] \\
&= V_t dt + V_x \left[\pi^i \mu_i dt + \pi^i \nu_i dW_t^i + \pi^i \sigma_i dB_t \right] + V_y \left[\widehat{\mu} \alpha dt + \widehat{\sigma} \alpha dB_t + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k \right] \\
&\quad + \frac{1}{2} V_{xx} \left[(\pi^i \mu_i)^2 (dt)^2 + (\pi^i \nu_i)^2 (dW_t^i)^2 + (\pi^i \sigma_i)^2 (dB_t)^2 + 2(\pi^i)^2 \mu_i \nu_i dt dW_t^i \right. \\
&\quad \left. + 2(\pi^i)^2 \nu_i \sigma_i dW_t^i dB_t + 2(\pi^i)^2 \sigma_i \mu_i dB_t dt \right] + \frac{1}{2} V_{yy} \left[(\widehat{\mu} \alpha)^2 (dt)^2 + (\widehat{\sigma} \alpha)^2 (dB_t)^2 \right. \\
&\quad \left. + \frac{1}{n^2} \sum_{k \neq i} \alpha_k^2 \nu_k^2 (dW_t^k)^2 + 2\widehat{\mu} \alpha \widehat{\sigma} \alpha dt dB_t + 2\widehat{\mu} \alpha \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k dt + 2\widehat{\sigma} \alpha \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k dB_t \right] \\
&\quad + V_{xy} \pi^i \sigma_i \frac{1}{n} \sum_{k \neq i} \alpha_k \sigma_k (dB_t)^2.
\end{aligned}$$

According to the rules $dt \cdot dt = dt \cdot dB_t = dB_t \cdot dt = 0$, we obtain

$$\begin{aligned}
dV &= V_t dt + V_x \left[\pi^i \mu_i dt + \pi^i \nu_i dW_t^i + \pi^i \sigma_i dB_t \right] + V_y \left[\widehat{\mu} \alpha dt + \widehat{\sigma} \alpha dB_t + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k \right] \\
&\quad + \frac{1}{2} V_{xx} \left[(\pi^i \nu_i)^2 (dW_t^i)^2 + (\pi^i \sigma_i)^2 (dB_t)^2 + 2(\pi^i)^2 \nu_i \sigma_i dW_t^i dB_t \right] + \frac{1}{2} V_{yy} \left[(\widehat{\sigma} \alpha)^2 (dB_t)^2 \right. \\
&\quad \left. + \frac{1}{n} \left(\frac{1}{n} \sum_{k \neq i} \alpha_k^2 \nu_k^2 \right) (dW_t^k)^2 + 2\widehat{\sigma} \alpha \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k dB_t \right] + V_{xy} \pi^i \sigma_i \frac{1}{n} \sum_{k \neq i} \alpha_k \sigma_k (dB_t)^2.
\end{aligned}$$

Since $E[dW_t^i] = E[dB_t] = 0$, $E[(dW_t^i)^2] = E[(dB_t)^2] = dt$, and the fact that W_t^i, W_t^k and B_t are independent, taking expectations and rearranging the equality above, we get

$$dV = V_t dt + \frac{1}{2} [\sigma_i^2 + \nu_i^2] (\pi^i)^2 V_{xx} dt + \pi^i [\mu_i V_x + \sigma_i \widehat{\alpha} \sigma V_{xy}] dt + \frac{1}{2} \left[\widehat{\alpha} \sigma^2 + \frac{1}{n} (\widehat{\nu} \alpha)^2 \right] V_{yy} dt + \widehat{\alpha} \mu V_y dt.$$

Dividing both sides of the equality by dt and note the notation that $\dot{V} = \partial V / \partial t$, we get

$$\dot{V} = V_t + \frac{1}{2} [\sigma_i^2 + \nu_i^2] (\pi^i)^2 V_{xx} + \pi^i [\mu_i V_x + \sigma_i \widehat{\alpha} \sigma V_{xy}] + \frac{1}{2} \left[\widehat{\alpha} \sigma^2 + \frac{1}{n} (\widehat{\nu} \alpha)^2 \right] V_{yy} + \widehat{\alpha} \mu V_y.$$

At equilibrium, the value of V is optimal, and then is constant, thus $\dot{V} = 0$. Hence, we get the following HJB equation

$$V_t + \frac{1}{2}[\sigma_i^2 + \nu_i^2](\pi^i)^2 V_{xx} + \pi^i[\mu_i V_x + \sigma_i \widehat{\alpha} \sigma V_{xy}] + \frac{1}{2}[\widehat{\alpha} \sigma^2 + \frac{1}{n}(\widehat{\nu \alpha})^2] V_{yy} + \widehat{\alpha} \mu V_y = 0 \quad (4.14)$$

for $(x, y, t) \in \mathbb{R} \times \mathbb{R} \times [0, T]$, with the terminal condition

$$V(x, y, T) = f(T) \frac{-e^{-\gamma_i \left((1 - \frac{\theta_i}{n}) X_T^i - \theta_i Y_T \right)}}{\gamma_i}.$$

Taking the first-order condition of (4.14) with respect to π^i , then solving for π^i , we obtain the agent i 's implicit optimal investment strategy

$$\pi^{i,*} = -\frac{\mu_i V_x + \sigma_i \widehat{\sigma \alpha} V_{xy}}{(\sigma_i^2 + \nu_i^2) V_{xx}}. \quad (4.15)$$

Then, plug (4.15) into (4.14) yields

$$V_t - \frac{1}{2} \frac{(\mu_i V_x + \sigma_i \widehat{\sigma \alpha} V_{xy})^2}{(\sigma_i^2 + \nu_i^2) V_{xx}} + \frac{1}{2} \left(\widehat{\sigma \alpha}^2 + \frac{1}{n} (\widehat{\nu \alpha})^2 \right) V_{yy} + \widehat{\mu \alpha} V_y = 0. \quad (4.16)$$

Thus, taking derivatives the ansatz in (4.13) $V(X_t^i, Y_t, t)$ to get $V_t, V_x, V_{xy}, V_{xx}, V_y$, and V_{yy} , then plug into (4.16), we get

$$f'(t) - \rho f(t) = 0, \quad \forall t \in [0, T]$$

with $f(T) = 1$ and ρ is given by

$$\rho := \frac{(\mu_i + \theta_i \gamma_i \sigma_i \widehat{\sigma \alpha})^2}{2(\sigma_i^2 + \nu_i^2)} - \theta_i \gamma_i \widehat{\mu \alpha} - \frac{\theta_i^2 \gamma_i^2}{2} \left(\widehat{\sigma \alpha}^2 + \frac{2}{n} (\widehat{\nu \alpha})^2 \right).$$

Consequently, we get $f(t) = e^{-\rho(T-t)}$. Hence,

$$V(x, y, t) = e^{-\rho(T-t)} \frac{-e^{-\gamma_i \left[(1 - \frac{\theta_i}{n}) x - \theta_i y \right]}}{\gamma_i} = \frac{-e^{-\gamma_i \left[(1 - \frac{\theta_i}{n}) x - \theta_i y \right] - \rho(T-t)}}{\gamma_i}. \quad (4.17)$$

Taking derivatives $V(x, y, t)$ to get V_x, V_{xy} , and V_{xx} , then plug into (4.15), we get the agent i 's explicit optimal investment strategy of the optimal control problem (4.12)

$$\pi^{i,*} = \frac{\mu_i / \gamma_i + \theta_i \sigma_i \widehat{\sigma \alpha}}{(\sigma_i^2 + \nu_i^2)(1 - \theta_i / n)}, \quad (4.18)$$

which does not depend on t .

For an admissible portfolio vector $(\alpha_1, \dots, \alpha_n)$ to be a constant Nash equilibrium, we need $\alpha_i = \pi^{i,*}, \forall i = 1, \dots, n$. Define

$$\bar{\sigma}\alpha := \frac{1}{n} \sum_{k=1}^n \sigma_k \alpha_k = \frac{1}{n} \sum_{k \neq i}^n \sigma_k \alpha_k + \frac{1}{n} \sigma_i \alpha_i = \widehat{\sigma}\alpha + \frac{1}{n} \sigma_i \alpha_i.$$

Then,

$$\widehat{\sigma}\alpha = \bar{\sigma}\alpha - \frac{1}{n} \sigma_i \alpha_i.$$

Thus, plug into (4.18), we have

$$\alpha_i = \pi^{i,*} = \frac{\mu_i/\gamma_i + \theta_i \sigma_i \bar{\sigma}\alpha}{(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n)} - \frac{\theta_i \sigma_i^2}{n(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n)} \alpha_i.$$

Hence, we get

$$\begin{aligned} \alpha_i &= \frac{\mu_i/\gamma_i + \theta_i \sigma_i \bar{\sigma}\alpha}{(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n)} \left(1 + \frac{\theta_i \sigma_i^2}{n(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n)} \right)^{-1} \\ &= \frac{\mu_i/\gamma_i + \theta_i \sigma_i \bar{\sigma}\alpha}{(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n) + \sigma_i^2 \theta_i/n} \\ &= \frac{\mu_i/\gamma_i + \theta_i \sigma_i \bar{\sigma}\alpha}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)}. \end{aligned}$$

Multiplying both sides by σ_i yields

$$\sigma_i \alpha_i = \frac{(\sigma_i \mu_i)/\gamma_i + \theta_i \sigma_i^2 \bar{\sigma}\alpha}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)}.$$

Thus, averaging over $i = 1, \dots, n$, we get

$$\frac{1}{n} \sum_{i=1}^n \sigma_i \alpha_i = \frac{1}{n} \sum_{i=1}^n \frac{\mu_i}{\gamma_i} \frac{\sigma_i}{(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n)} + \frac{1}{n} \sum_{i=1}^n \theta_i \frac{\sigma_i^2}{(\sigma_i^2 + \nu_i^2)(1 - \theta_i/n)} \bar{\sigma}\alpha$$

and then

$$\bar{\sigma}\alpha = \varphi_n + \psi_n \bar{\sigma}\alpha, \tag{4.19}$$

where

$$\varphi_n = \frac{1}{n} \sum_{i=1}^n \frac{\mu_i}{\gamma_i} \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \quad \text{and} \quad \psi_n = \frac{1}{n} \sum_{i=1}^n \theta_i \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)}.$$

Note that since $\theta_i \in [-1, 1], \sigma_i \geq 0, \nu_i \geq 0$ and n is finite but large thus $-1 \leq \psi_n \leq 1$. There are three cases.

(i) If $\psi_n \neq 1$, then the equation (4.19) yields $\bar{\sigma}\alpha = \varphi_n/(1 - \psi_n)$. Thus, there exists a unique constant Nash equilibrium given by

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i \sigma_i^2 + \nu_i^2(1 - \theta_i/n)} + \theta_i \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{\varphi_n}{1 - \psi_n}.$$

(ii) If $\psi_n = 1$ (if and only if $\theta_i = 1$ and $\nu_i = 0$ for all $i = 1, \dots, n$) and $\varphi_n \neq 0$, thus the equation (4.19) has no solution and then no constant Nash equilibria exist.

(iii) If $\psi_n = 1$ and $\varphi_n = 0$, thus the equation (4.19) has infinitely many solutions and then there are infinitely many constant Nash equilibria. \square

Remark 4.3.1. *One necessary condition for Case (ii) and (iii) in Theorem 3.2 is $\psi_n = 1$. This only happens if and only if $\theta_i = 1$ and $\nu_i = 0$ for all $i = 1, 2, \dots, n$. That means each investor is extremely concerned about the performance of the rest of other investors and also the volatility of each individual stock is zero.*

One real-world example to explain the case that $\theta_i = 1$ and $\nu_i = 1$ for all $i = 1, \dots, n$ is the (centrally) planned economy where prices are fixed ($\nu_i = 0, \forall i$) and agents are totally concerned with others' wealth ($\theta_i = 1, \forall i$), thus $\psi_n = 1$ holds. Then, it does not matter if agents invest more or less to a specific asset. That means there are infinitely many solutions in this economic setting.

Remark 4.3.2. *The constant φ_n can be positive or negative depending on the sign of μ_i/γ_i . If $\mu_i/\gamma_i > 0$ for all i then $\varphi_n > 0$ and if $\mu_i/\gamma_i < 0$ for all i then $\varphi_n < 0$.*

Remark 4.3.3. *The case that $\varphi_n = 0$ can also happen. This might be the situation that $\gamma_i > 0$ for some i and $\gamma_i < 0$ for some i . This implies that there must be some risk-averse agents ($\gamma_i > 0$) and some risk-seeking agents ($\gamma_i < 0$) interacting on the same market.*

Theorem 4.3.2 (Unique corner solution for strictly convex exponential utility function). *Given U_i is utility function of agent i as in (4.6) with $\gamma_i < 0$. For the exponential case, the optimal solution is $\pi^{i,*} = C_i$ for risky asset (stock) and $\pi^{i,*} = 0$ for riskless asset (bond), where C_i is the total asset value that agent i has.*

Proof. First we need to show that the domain of U_i is bounded and closed. Since $t \in [0, T]$, where T is stopping time, W_t^i and B_t in dynamics (4.7) are bounded. Also, since μ_i, ν_i , and σ_i are bounded so X_t^i is bounded. Moreover, since t is closed, W_t^i and B_t are closed. In addition, since μ_i, ν_i , and σ_i are in closed intervals so X_t^i is closed.

For $\gamma_i < 0$, we can check the second order sufficient condition that

$$U''_{X_T^i} = -\gamma_i e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)} > 0,$$

which implies that U_i is a strictly convex utility function. Since U_i is a strictly convex function and the domain of U_i that is bounded and closed, there exists $m \in S$ such that $U_i(m)$ is global minimum. Suppose U_i attains maximum at $M \in S$ and $M \notin \partial S$. Thus, there exists $s \in S$ such that the line connecting m and M can be extended to s and $U_i(M) \neq U_i(s)$. If not, then M is on the boundary ∂S , which is contradict to the above assumption that $M \notin \partial S$.

Since $m, M, s \in S$, there exists $\lambda \in [0, 1]$ such that $M = \lambda m + (1 - \lambda)s$. Since U_i is strictly convex function,

$$U_i(M) = U_i(\lambda m + (1 - \lambda)s) < \lambda U_i(m) + (1 - \lambda)U_i(s) < \lambda U_i(s) + (1 - \lambda)U_i(s) = U_i(s),$$

which is contradict to the fact that M is maximum of U_i . Hence, $M \in \partial S$. That is, the maximum is on the boundary of the domain.

We have $U'_{X_T^i} = e^{-\gamma_i(X_T^i - \theta_i \bar{X}_T)} > 0$, which implies that U_i is a strictly increasing function in X_T^i . Thus, M must be on the upper boundary of the domain and M must be unique. This implies that $\pi^{i,*} = C_i$ for the risky asset (stock) and $\pi^{i,*} = 0$ for riskless asset (bond), where C_i is the total asset that agent i has. For agent i , C_i is unique so the corner solution is also unique. \square

Definition 4.3.5. *An agent shorts a stock if and only if $\pi^{i,*} < 0$.*

Remark 4.3.4. *Consider the case of relative performance concern, i.e. $\theta_i \in [0, 1]$. The constant Nash equilibrium now is*

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i} \frac{1}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} + \theta_i^+ \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{\varphi_n}{1 - \psi_n}.$$

If $\mu_i/\gamma_i > 0$ ($\mu_i > 0$ and $\gamma_i > 0$) for all i , then agent i does not short sell. If $\mu_i/\gamma_i < 0$ ($\mu_i > 0$ and $\gamma_i < 0$) for all i , then agent i short sells. This implies that risk-averse agents are unlikely to short sell stock while risk-seeking agents are likely to short sell stock.

Corollary 4.3.1 (Existence and uniqueness equilibrium for single stock). *Assume for all $i = 1, \dots, n$ that $0 \leq \mu_i = \mu < \bar{\mu}$, $0 \leq \sigma_i = \sigma \leq \bar{\sigma}$, and $\nu_i = 0$. Define δ_i and two constants*

$$\delta_i := \frac{1}{\gamma_i}, \quad \bar{\delta} := \frac{1}{n} \sum_{i=1}^n \delta_i \quad \text{and} \quad \bar{\theta} := \frac{1}{n} \sum_{i=1}^n \theta_i.$$

There are three cases:

(i) If $\bar{\theta} \neq 1$, then there exists a unique constant Nash equilibrium given by

$$\pi^{i,*} = \left(\delta_i + \theta_i \frac{\bar{\delta}}{1 - \bar{\theta}} \right) \frac{\mu}{\sigma^2}. \quad (4.20)$$

(ii) If $\bar{\theta} = 1$ and $\mu\bar{\delta} \neq 0$, there is no constant Nash equilibria.

(iii) If $\bar{\theta} = 1$ and $\mu\bar{\delta} = 0$, there exist infinitely many constant Nash equilibria.

Proof. With the assumptions of parameters that $\mu_i = \mu, \sigma_i = \sigma \geq 0$, and $\nu_i = 0$ for all $i = 1, \dots, n$, we now have

$$\varphi_n = \frac{1}{n} \sum_{k=1}^n \delta_k \frac{\mu}{\sigma} = \frac{\mu}{\sigma} \bar{\delta} \quad \text{and} \quad \psi_n = \frac{1}{n} \sum_{k=1}^n \theta_k \frac{\sigma^2}{\sigma^2} = \bar{\theta}.$$

By applying Theorem 4.3.1, (i) holds since

$$\pi^{i,*} = \delta_i \frac{\mu}{\sigma^2} + \frac{\theta_i}{\sigma} \frac{\varphi_n}{1 - \psi_n} = \left(\delta_i + \theta_i \frac{\bar{\delta}}{1 - \bar{\theta}} \right) \frac{\mu}{\sigma^2}.$$

Since $\psi_n = 1$ if and only if $\bar{\theta} = 1$ and $\varphi_n \neq 0$ if and only if $\mu\bar{\delta} \neq 0$, thus (ii) holds. Moreover, since $\varphi_n = 0$ if and only if $\mu\bar{\delta} = 0$, thus (iii) holds. \square

4.3.2 The mean field games

In this section, we examine the limiting behavior of n -player games as the number of agents tends to infinity, i.e. $n \rightarrow \infty$.

Assumption 4.3.1 (Continuum). *The population is made by the continuum of agents.*

Since the number of agents is continuous, we now no longer consider the agent $i = 1, \dots, n$ discretely as in the previous section. Instead, in this section, we are going to investigate the continuous representative agent.

Definition 4.3.6 (MFG). *The MFG corresponding to the exponential utility function (4.6) is defined by a type vector $\zeta = (\xi, \gamma, \theta, \mu, \nu, \sigma)$ of a representative agent i where ξ is the initial wealth of the representative agent.*

Here, since the parameters of risk preferences γ and θ are random, agents are not necessarily homogeneous.

The dynamics of wealth of the representative agent, for $t \in [0, T]$, is given by

$$dX_t = \pi_t(\mu dt + \nu dW_t + \sigma dB_t), \quad X_0 = \xi. \quad (4.21)$$

Given \bar{X} denoting the arithmetic average wealth of the continuum of agents and the dynamics (4.21), the goal of the representative agent is to maximize the expected utility in the following optimization problem

$$\sup_{\pi_t \in \mathcal{A}_{MF}} \mathbb{E} \left[\frac{-e^{-\gamma(X_T - \theta \bar{X})}}{\gamma} \right] \quad (4.22)$$

where \mathcal{A}_{MF} denotes the admissible set containing feasible strategies $\pi_t, t \in [0, T]$, of the mean field games.

The main goal of this section is to prove the existence of the mean field equilibrium (MFE), which is stated in the following definitions.

Definition 4.3.7 (MFE). *Given \bar{X} and let $\pi_t^* \in \mathcal{A}$ be an admissible strategy. Then, π_t^* is a MFE if it solves the optimization problem (4.22) given the dynamics (4.21).*

Definition 4.3.8 (Constant MFE). *The optimal strategy π^* is called a constant MFE if $\pi^* = \pi_t^*$ for all $t \in [0, T]$, where π_t^* is a MFE defined in Definition 4.3.7.*

Lemma 4.3.1. *Define two constants*

$$\varphi := \mathbb{E} \left(\frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2} \right) \quad \text{and} \quad \psi := \mathbb{E} \left(\theta \frac{\sigma^2}{\sigma^2 + \nu^2} \right). \quad (4.23)$$

Then these two expectations exist and are finite.

Proof. Denote two constant but random variables

$$\Xi = \frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2} \quad \text{and} \quad \Lambda = \theta \frac{\sigma^2}{\sigma^2 + \nu^2}.$$

By assumptions $\underline{\gamma} \leq \gamma \leq \bar{\gamma}, 0 \leq \mu \leq \bar{\mu}, 0 \leq \sigma \leq \bar{\sigma}$, and $0 \leq \nu \leq \bar{\nu}$. Then, Ξ must exist and be bounded. This implies that Ξ is finite, and so is φ .

Now, we will show that ψ exists and is finite. Since $\theta \in [-1, 1]$ and $\sigma^2/(\sigma^2 + \nu^2) \in [0, 1]$, then $-1 \leq \Lambda \leq 1$. We will show that $-1 \leq \mathbb{E}(\Lambda) \leq 1$. In fact, if one of two these inequalities does not hold, that is

$$\mathbb{E}(\Lambda) < -1 \quad \text{or} \quad \mathbb{E}(\Lambda) > 1.$$

Then, there must exist θ, σ , and ν such that

$$\Lambda < -1 \quad \text{or} \quad \Lambda > 1.$$

But it contradicts the fact that $-1 \leq \Lambda \leq 1$. So, there must exist ψ , which is finite and bounded in the closed interval $-1 \leq \psi \leq 1$. So, the proof is complete. \square

Theorem 4.3.3 (Existence and uniqueness of constant MFE). *Given strictly concave utility function U . Assume for a.s. that $-1 \leq \theta \leq 1, 0 \leq \mu \leq \bar{\mu}, 0 \leq \nu \leq \bar{\nu}$, and $0 \leq \sigma \leq \bar{\sigma}$. Define two constants φ and ψ as that in Lemma 4.3.1.*

There are three cases:

(i) If $\psi \neq 1$, there exists a unique constant MFE, given by

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi}. \quad (4.24)$$

Moreover, we have

$$\mathbb{E}(\sigma \pi^*) = \frac{\varphi}{1 - \psi}.$$

(ii) If $\psi = 1$ and $\varphi \neq 0$, there is no constant MFE.

(iii) If $\psi = 1$ and $\varphi = 0$, there are infinitely many constant MFE.

Proof. A representative agent will solve the optimization problem (4.22) with respect to the dynamics (4.21), given the average wealth of the population \bar{X} . Define $\bar{X}_t := \mathbb{E}(X_t^{\pi_t} | \mathcal{F}_t^B)$, $\forall t \in [0, T]$, where \mathcal{F}_t^B is the filtration generated by the common noise B_t .

The integral form of the dynamics (4.21) is

$$X_t = \xi + \mu \pi_t \int_0^t ds + \nu \pi_t \int_0^t dW_s + \sigma \pi_t \int_0^t dB_s, \quad \forall t \in [0, T] \quad (4.25)$$

Since we want to find the constant MFE, we need to find the corresponding constant strategy $\alpha = \pi_t, \forall t \in [0, T]$. Given $\alpha = \pi_t, \forall t \in [0, T]$, taking expectation (4.25) with the note that $(\xi, \mu, \nu, \sigma, \alpha), W_t$ and B_t are independent, we get

$$\bar{X}_t = \bar{\xi} + \bar{\mu} \alpha t + \bar{\sigma} \alpha B_t$$

where we use the following facts, for all $t \in [0, T]$,

$$B_0 = 0 \text{ a.s.}, \int_0^t ds = t, \mathbb{E}\left(\int_0^t dW_s\right) = \mathbb{E}(W_t) = 0, \int_0^t dB_s = B_t.$$

and the expectation of an integrable random variable S is denoted by $\bar{S} = \mathbb{E}(S)$.

Denote

$$Z_t^\pi := X_t^\pi - \theta \bar{X}_t, \quad \forall t \in [0, T].$$

Thus,

$$\begin{aligned} dZ_t^\pi &= dX_t^\pi - \theta d\bar{X}_t = \pi_t(\mu dt + \nu dW_t + \sigma dB_t) - \theta(\bar{\mu}\alpha t + \bar{\sigma}\alpha B_t) \\ &= (\mu\pi - \theta\bar{\mu}\alpha)dt + \nu\pi dW_t + (\sigma\pi - \theta\bar{\sigma}\alpha)dB_t \end{aligned}$$

The problem (4.22) now is equivalent to

$$V(Z_t^\pi, t) = \sup_{\pi \in \mathcal{A}_{MF}} \mathbb{E} \left[\frac{-e^{-\gamma Z_T^\pi}}{\gamma} \right] \quad (4.26)$$

where $V : \mathbb{R} \times [0, T] \rightarrow \mathbb{R}$ denotes the smooth and strictly increasing value function, which is expected to solve the HJB equation later on. Suppose $V(Z_t^\pi, t)$ is continuously at least twice differentiable in Z_t^π and once in t . For simplicity, denote

$$V_t = \frac{\partial V}{\partial t}, V_x = \frac{\partial V}{\partial X_t^\pi}, V_z = \frac{\partial V}{\partial Z_t^\pi}, V_{xx} = \frac{\partial^2 V}{\partial (X_t^\pi)^2}, V_{zz} = \frac{\partial^2 V}{\partial (Z_t^\pi)^2}$$

It is easy to see that $V_x = V_z$ and $V_{xx} = V_{zz}$. Now, the total differential form dV can be approximated by a Taylor series expansion with terms of order equal or less than dt or $(dW_t)^2$ or $(dB_t)^2$

$$\begin{aligned} dV &= V_t dt + V_x dZ_t^\pi + \frac{1}{2} V_{xx} (dZ_t^\pi)^2 \\ &= V_t dt + V_z [(\mu\pi - \theta\bar{\mu}\alpha)dt + \nu\pi dW_t + (\sigma\pi - \theta\bar{\sigma}\alpha)dB_t] \\ &\quad + \frac{1}{2} V_{xx} [(\mu\pi - \theta\bar{\mu}\alpha)dt + \nu\pi dW_t + (\sigma\pi - \theta\bar{\sigma}\alpha)dB_t]^2 \\ &= V_t dt + V_x [(\mu\pi - \theta\bar{\mu}\alpha)dt + \nu\pi dW_t + (\sigma\pi - \theta\bar{\sigma}\alpha)dB_t] \\ &\quad + \frac{1}{2} V_{xx} [(\nu\pi)^2 (dW_t)^2 + (\sigma\pi - \theta\bar{\sigma}\alpha)^2 (dB_t)^2 + 2(\mu\pi - \theta\bar{\mu}\alpha)\nu\pi dt dW_t \\ &\quad + 2(\mu\pi - \theta\bar{\mu}\alpha)(\sigma\pi - \theta\bar{\sigma}\alpha)dt dB_t + 2\nu\pi(\sigma\pi - \theta\bar{\sigma}\alpha)dW_t dB_t]. \end{aligned}$$

Since $E[dW_t] = E[dB_t] = 0$ and $(dW_t)^2 = (dB_t)^2 = dt$, taking expectation, we get

$$dV = V_t dt + (\mu\pi - \theta\bar{\mu}\alpha)V_x dt + \frac{1}{2} [(\nu\pi)^2 + (\sigma\pi - \theta\bar{\sigma}\alpha)^2] V_{xx} dt.$$

Dividing both sides of the equality above by dt and note that $\dot{V} = dV/dt$, we get

$$\dot{V} = V_t + (\mu\pi - \theta\bar{\mu}\alpha)V_x + \frac{1}{2} [(\nu\pi)^2 + (\sigma\pi - \theta\bar{\sigma}\alpha)^2] V_{xx}.$$

At equilibrium point, $\dot{V} = 0$, then we obtain the HJB equation

$$V_t + (\mu\pi - \theta\bar{\mu}\bar{\alpha})V_x + \frac{1}{2}[(\nu\pi)^2 + (\sigma\pi - \theta\bar{\sigma}\bar{\alpha})^2]V_{xx} = 0 \quad (4.27)$$

with the terminal condition $V(z, T) = -e^{-\gamma z}/\gamma$.

Taking the first-order condition (4.27) with respect to π , then after several manipulations, we get the representative agent's implicit optimal investment strategy

$$\pi = -\frac{\mu V_x - \theta\sigma\bar{\sigma}\bar{\alpha}V_{xx}}{(\sigma^2 + \nu^2)V_{xx}}. \quad (4.28)$$

Plugging back into (4.27), it derives to

$$V_t - \frac{1}{2} \frac{(\mu V_x - \theta\sigma\bar{\sigma}\bar{\alpha}V_{xx})^2}{(\sigma^2 + \nu^2)V_{xx}} - \theta\bar{\mu}\bar{\alpha}V_x + \frac{1}{2}(\theta\bar{\sigma}\bar{\alpha})^2V_{xx} = 0. \quad (4.29)$$

Making the ansatz $V(z, t) = f(t)\frac{-e^{-\gamma z}}{\gamma}$, and then taking derivatives with the note that $V_x = V_z$ and $V_{xx} = V_{zz}$. Thus, plug V_t, V_x and V_{xx} into (4.29), we get

$$f'(t) - \rho f(t) = 0, \quad \forall t \in [0, T]$$

with $f(T) = 1$ and ρ is given by

$$\rho := \frac{(\mu + \theta\gamma\sigma\bar{\sigma}\bar{\alpha})^2}{2(\sigma^2 + \nu^2)} - \theta\gamma\bar{\mu}\bar{\alpha} - \frac{(\theta\gamma\bar{\sigma}\bar{\alpha})^2}{2}.$$

Hence, we obtain

$$f(t) = e^{-\rho(T-t)}.$$

Plugging into the value function, we get

$$V(z, t) = e^{-\rho(T-t)} \frac{-e^{-\gamma z}}{\gamma} = -\frac{1}{\gamma} e^{-\rho(T-t) - \gamma z}.$$

Taking derivatives to get V_z and V_{zz} and note that $V_z = V_x$ and $V_{zz} = V_{xx}$. Plugging into (4.28), we get the explicit optimal investment strategy of the optimal control problem (4.26)

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{(\sigma^2 + \nu^2)} + \theta \frac{\sigma}{\sigma^2 + \nu^2} \bar{\sigma}\bar{\alpha}. \quad (4.30)$$

Note that π^* is a constant and does not depend on either z or t . The feasible control α is a constant MFE if $\alpha = \pi^*$, i.e. we need

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \frac{\sigma}{\sigma^2 + \nu^2} \sigma \bar{\pi}^*.$$

Multiplying both sides by σ and then taking expectation, we get

$$\sigma \bar{\pi}^* = \mathbb{E} \left[\frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2} \right] + \mathbb{E} \left[\theta \frac{\sigma^2}{\sigma^2 + \nu^2} \right] \sigma \bar{\pi}^* = \varphi + \psi \sigma \bar{\pi}^* \quad (4.31)$$

where $\sigma \bar{\pi}^* = \mathbb{E}(\sigma \pi^*)$. Note that since $0 \leq \theta \leq 1, \sigma \geq 0, \nu \geq 0$ then $0 \leq \psi \leq 1$. There are three cases:

(i) If $\psi \neq 1$, thus from (4.31) we get $\sigma \bar{\pi}^* = \varphi / (1 - \psi)$. Hence, there exists a unique constant MFE given by

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi}.$$

Note that $\sigma \bar{\pi}^*$ can be equals to zero since σ can be equal zero or π^* can be equal to zero.

(ii) If $\psi = 1$ (if and only if $\theta = 1$ and $\nu = 0$) and $\varphi \neq 0$, thus (4.31) has no solution and then no constant MFE exist.

(iii) If $\psi = 1$ and $\varphi = 0$, thus (4.31) has infinitely many solutions and then there are infinitely many constant MFE. \square

Remark 4.3.5 (No relative performance). *In the case there is no relative performance, i.e. $\theta = 0$, the MFE (4.24) and the NE (4.11) equal to*

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2}. \quad (4.32)$$

Note that (4.32) is exactly the classical Merton portfolio in Merton (1969) when there is only one Brownian process and bond (sure asset) offers zero interest rate.

Corollary 4.3.2 (Existence and uniqueness constant MFE for single stock). *Assume that (μ, σ, ν) are deterministic with $0 \leq \mu \leq \bar{\mu}, 0 \leq \nu \leq \bar{\nu}$, and $0 \leq \sigma \leq \bar{\sigma}$. Define three constants*

$$\delta := \frac{1}{\gamma}, \quad \bar{\delta} := \mathbb{E}(\delta) \quad \text{and} \quad \bar{\theta} := \mathbb{E}(\theta).$$

There are three cases:

(i) *If $\bar{\theta} \neq 1$, then there exists a unique constant MFE given by*

$$\pi^* = \left(\delta + \theta \frac{\bar{\delta}}{1 - \bar{\theta}} \right) \frac{\mu}{\sigma^2}. \quad (4.33)$$

- (ii) If $\bar{\theta} = 1$ and $\mu\bar{\delta} \neq 0$, there is no constant MFE.
(iii) If $\bar{\theta} = 1$ and $\mu\bar{\delta} = 0$, there are infinitely many constant MFE.

Proof. With the assumption $\nu = 0$, then the two later constants become

$$\varphi = \frac{\mu\sigma}{\sigma^2 + \nu^2}\bar{\delta} = \frac{\mu}{\sigma}\bar{\delta} \quad \text{and} \quad \psi = \frac{\sigma^2}{\sigma^2 + \nu^2}\bar{\theta} = \bar{\theta}.$$

Applying Theorem 4.3.3 and note that $\psi \neq 0$ if and only if $\bar{\theta} \neq 1$, thus (i) holds since

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi} = \delta \frac{\mu}{\sigma^2} + \frac{\theta}{\sigma} \frac{\varphi}{1 - \psi} = \left(\delta + \theta \frac{\bar{\delta}}{1 - \bar{\theta}} \right) \frac{\mu}{\sigma^2}.$$

Since $\psi = 1$ if and only if $\bar{\theta} = 1$ and $\varphi \neq 0$ if and only if $\mu\bar{\delta} \neq 0$, thus (ii) holds. Moreover, since $\varphi = 0$ if and only if $\mu\bar{\delta} = 0$, thus (iii) holds. \square

Remark 4.3.6. (Compare NE and MFE in our study with those in [Lacker and Zariphopoulou \(2019\)](#) for the case of strictly concave utility function.)

- Our setting take into account the case of relative performance motivation. This is not the case in [Lacker and Zariphopoulou \(2019\)](#).
- One difference between [Theorem 4.3.1](#) and [Theorem 4.3.3](#) in our study with the corresponding Theorem 2.3 and Theorem 2.10 in [Lacker and Zariphopoulou \(2019\)](#), respectively, is that the case $\psi = 1$ and $\varphi = 0$ cannot happen in the former study but it happens in our study. As a result, there are infinitely many constant MFE in such case.
- By assuming of the signs of parameters in [Lacker and Zariphopoulou \(2019\)](#), the optimal strategies must be positive. It contradicts to their comment on page 2 of their paper that “the value $\pi_t^{i,*}$ may be negative, indicating that the agent shorts the stock”. Indeed, the optimal control $\pi^{i,*}$ and π^* in their study cannot be negative. Consequently, it cannot take into account the case of short selling. In contrast, in our study, with several different assumptions of the signs of parameters, short selling can happen. That means the optimal strategy $\pi^{i,*}, \pi^*$ can be negative, i.e. $\pi^{i,*} < 0, \pi^* < 0$, which capture the popular transaction in the stock market that agents can short their stocks.

MFE for strictly convex exponential utility function. The optimal strategy for Theorem 4.3.2 does not depend on number of players n . Therefore, the optimal strategy for the case of n -agent games (Nash equilibrium) and that for the case of MFG (mean field equilibrium) should be similar. Only different point is that the optimal strategy in the case of MFG does not depend on i . That is, $\pi^* = C$ for risky asset (stock) and $\pi^* = 0$ for riskless asset (bond), where C is the total asset value that the representative agent has. For each representative agent, since C is unique so is the corner solution.

4.4 Power and logarithmic utility function

The power and logarithmic utility functions belong to the family of constant relative risk aversion (CRRA) utility functions. In this section, the CRRA utility function is given by

$$U_i(X_T^i, \bar{X}_T) = \begin{cases} \frac{1}{1-\gamma_i} \left(X_T^i \bar{X}_T^{-\theta_i} \right)^{1-\gamma_i} & \text{if } \gamma_i \neq 1 \\ \log(X_T^i \bar{X}_T^{-\theta_i}) & \text{if } \gamma_i = 1 \end{cases} \quad (4.34)$$

where $\bar{X}_T = \left(\prod_{i=1}^{n-1} X_T^i \right)^{\frac{1}{n-1}}$ is the geometric average wealth of the population excluding agent i . Note that, here, we consider the case of excluding agent i since, similar to the case of exponential form, there is a one-to-one map from excluding to including agent i case. Thus, the optimal strategy, if it exists, in both cases are the same. The model with including agent i is more tractable and simpler. Therefore, we employ this model in this study. Literally, the given CRRA utility function (4.34) has the power form if $\gamma_i \neq 1$ and logarithmic form if $\gamma_i = 1$. Since the logarithmic form is a special case of power form when γ_i tends to 1, we will not consider these two utility forms in two separate sections but rather consider the former case first, then naturally move to the later case within one section. Moreover, we assume that $\underline{\gamma}_i \leq \gamma_i \leq \bar{\gamma}_i$ for some $\underline{\gamma}_i < 0$ and $\bar{\gamma}_i > 0$.

4.4.1 The n -agent games

Suppose there are n agents trading on the stock market. They have the same investment horizon T , where $0 < T < \infty$. The dynamics of wealth of agent i at time t , $0 \leq t \leq T$, is given by

$$dX_t^i = \pi_t^i X_t^i (\mu_i dt + \nu_i dW_t^i + \sigma_i B_t), \quad X_0^i = x_0^i, \quad (4.35)$$

where $X_0^i = x_0 \in \mathbb{R}$ is the initial wealth, π_t^i is the fraction of wealth, rather than the absolute value of wealth in the case of exponential form, that agent i invests in the individual stock S^i at time t . Here, π_t^i satisfies the mean square integrable property, i.e. $\mathbb{E}(\int_0^T |\pi_t^i|^2 dt) < \infty$.

Definition 4.4.1 (Trading strategy). *A trading strategy (or portfolio) π_t at time t corresponding to the utility function (4.34) is defined as $\pi_t := (x_t, y_t) \in \mathcal{F}_s, t < s \leq T$, where x_t and y_t denote the fraction of wealth invested an individual stock i and a riskless bond, respectively.*

Theorem 4.4.1 (Existence and uniqueness of Nash equilibrium). *Given strictly concave utility function U_i as in (4.34) with $\gamma_i > 0$. Assume for all $i = 1, \dots, n$ that $-1 \leq \theta_i \leq 1, 0 \leq$*

$\mu_i \leq \bar{\mu}_i$ where $\bar{\mu}_i > 0$, $0 \leq \nu_i \leq \bar{\nu}_i$, and $0 \leq \sigma_i \leq \bar{\sigma}_i$. Define two constants

$$\varphi_n := \frac{1}{n} \sum_{i=1}^n \frac{\mu_i}{\gamma_i} \frac{\sigma_i}{\sigma_i^2 + \nu_i^2 \left[1 + \left(\frac{1}{\gamma_i} - 1 \right) \frac{\theta_i}{n} \right]} \quad (4.36)$$

and

$$\psi_n := \frac{1}{n} \sum_{i=1}^n \theta_i \left(\frac{1}{\gamma_i} - 1 \right) \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2 \left[1 + \left(\frac{1}{\gamma_i} - 1 \right) \frac{\theta_i}{n} \right]}. \quad (4.37)$$

There are four cases:

(i) If $\psi_n \neq 1$, $\gamma_i \neq 1$, and $\gamma_i \neq 0$, there exists a unique constant Nash equilibrium given by

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i} \frac{1}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i} \right)} + \theta_i \left(1 - \frac{1}{\gamma_i} \right) \frac{\sigma_i}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i} \right)} \frac{\varphi_n}{1 - \psi_n}. \quad (4.38)$$

Moreover, we have the identity given by

$$\mathbb{E}(\sigma_k \pi^{k,*}) = \bar{\sigma} \alpha = \frac{\varphi_n}{1 - \psi_n}.$$

(ii) If $\psi_n \neq 1$ and $\gamma_i = 1$, there exists a unique constant Nash equilibrium given by

$$\pi^{i,*} = \frac{\mu_i}{\sigma_i^2 + \nu_i^2}. \quad (4.39)$$

(iii) If $\psi_n = 1$ and $\varphi_n \neq 0$, there is no constant Nash equilibrium.

(iv) If $\psi_n = 1$ and $\varphi_n = 0$, there are infinitely many constant Nash equilibria.

Proof. Fix i . Denote $\alpha_k \in \mathbb{R}$, be the constant investment strategies followed by all other agents $k, k \neq i$. Let X_t^k be the associated wealth processes, given by

$$dX_t^k = \alpha_k X_t^k (\mu_k dt + \nu_k dW_t^k + \sigma_k dB_t), \quad X_0^k = x_0^k$$

where x_0^k is the initial wealth of agent k . Using Itô's formula, we get

$$\begin{aligned} d(\log X_t^k) &= \left(\mu_k \alpha_k - \frac{1}{2} (\nu_k^2 \alpha_k^2 + \sigma_k^2 \alpha_k^2) \right) dt + \nu_k \alpha_k dW_t^k + \sigma_k \alpha_k dB_t \\ &= \left(\mu_k \alpha_k - \frac{1}{2} \omega_k \alpha_k^2 \right) dt + \nu_k \alpha_k dW_t^k + \sigma_k \alpha_k dB_t \end{aligned}$$

where $\omega_k = \nu_k^2 + \sigma_k^2$. Define

$$Y_t := \left(\prod_{k \neq i} X_t^k \right)^{1/n}$$

where X_t^k solves (4.35) with constant fractions α_k . Thus, we have

$$\log Y_t = \frac{1}{n} \log \left(\prod_{k \neq i} X_t^k \right) = \frac{1}{n} \sum_{k \neq i} \log X_t^k.$$

Then,

$$\begin{aligned} d \log Y_t &= \frac{1}{n} \sum_{k \neq i} d \log X_t^k \\ &= \frac{1}{n} \sum_{k \neq i} \left[\left(\mu_k \alpha_k - \frac{1}{2} \omega_k \alpha_k^2 \right) dt + \nu_k \alpha_k dW_t^k + \sigma_k \alpha_k dB_t \right] \\ &= \left(\widehat{\mu \alpha} - \frac{1}{2} \widehat{\omega \alpha^2} \right) + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma \alpha} dB_t, \end{aligned}$$

where we denote

$$\begin{aligned} \widehat{\mu \alpha} &:= \frac{1}{n} \sum_{k \neq i} \mu_k \alpha_k, & \widehat{\sigma \alpha} &:= \frac{1}{n} \sum_{k \neq i} \sigma_k \alpha_k \\ \widehat{\omega \alpha^2} &:= \frac{1}{n} \sum_{k \neq i} \omega_k \alpha_k^2 & \text{and} & \quad \widehat{(\nu \alpha)^2} := \frac{1}{n} \sum_{k \neq i} \nu_k^2 \alpha_k^2 \end{aligned}$$

Hence, the process Y_t solves

$$\frac{dY_t}{Y_t} = \eta dt + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma \alpha} dB_t, \quad Y_0 = \left(\prod_{k \neq i} x_0^k \right)^{1/n},$$

where

$$\eta = \widehat{\mu \alpha} - \frac{1}{2} \left[\widehat{\omega \alpha^2} - \widehat{\sigma \alpha}^2 - \frac{1}{n} \widehat{(\nu \alpha)^2} \right].$$

From the first case of (4.34), we have

$$\begin{aligned}
U_i(X_T^i, \bar{X}_T) &= \frac{1}{1 - \gamma_i} \left(X_T^i \bar{X}_T^{-\theta_i} \right)^{1 - \gamma_i} \\
&= \frac{1}{1 - \gamma_i} \left(X_T^i \left[\left(X_T^i \prod_{k \neq i} X_T^k \right)^{1/n} \right]^{-\theta_i} \right)^{1 - \gamma_i} \\
&= \frac{1}{1 - \gamma_i} \left((X_T^i)^{1 - \theta_i/n} \left[\left(\prod_{k \neq i} X_T^k \right)^{1/n} \right]^{-\theta_i} \right)^{1 - \gamma_i} \\
&= \frac{1}{1 - \gamma_i} \left[(X_T^i)^{1 - \theta_i/n} Y_T^{-\theta_i} \right]^{1 - \gamma_i}.
\end{aligned}$$

The goal of the agent i is to solve the following optimization problem

$$\sup_{\pi^i \in \mathcal{A}} \mathbb{E} \frac{1}{1 - \gamma_i} \left[(X_T^i)^{1 - \theta_i/n} Y_T^{-\theta_i} \right]^{1 - \gamma_i}$$

with respect to the following two dynamics (one of agent i and one of all the other agents $k, k \neq i$)

$$\begin{aligned}
dX_t^i &= \pi_t^i X_t^i (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t), \quad X_0^i = x_0^i \\
dY_t &= Y_t \left(\eta dt + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma} \alpha dB_t \right), \quad Y_0 = \left(\prod_{k \neq i} x_0^k \right)^{1/n}.
\end{aligned}$$

Case 1: Suppose $\gamma_i \neq 1$. Making the ansatz of the value function $V(X_t^i, Y_t, t)$

$$V(X_t^i, Y_t, t) = f(t) \frac{1}{1 - \gamma_i} \left[(X_t^i)^{1 - \theta_i/n} Y_t^{-\theta_i} \right]^{1 - \gamma_i}, \quad t \in [0, T]. \quad (4.40)$$

For simplicity, denote $x = X_t^i$ and $y = Y_t$. Since we are looking for the constant Nash equilibrium, then $\pi_t^i = \pi^i$ for all $t \in [0, T]$. Similarly to that of Theorem 4.3.1, by using the

multivariable Taylor series expansion

$$\begin{aligned}
dV &= V_t dt + V_x dx + V_y dy + \frac{1}{2} V_{xx} (dx)^2 + \frac{1}{2} V_{yy} (dy)^2 + V_{xy} dx dy \\
&= V_t dt + V_x [\pi^i x (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t)] + V_y \left[y \left(\eta dt + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma} \alpha dB_t \right) \right] \\
&\quad + \frac{1}{2} V_{xx} [\pi^i x (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t)]^2 + \frac{1}{2} V_{yy} \left[y \left(\eta dt + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma} \alpha dB_t \right) \right]^2 \\
&\quad + V_{xy} [\pi^i x (\mu_i dt + \nu_i dW_t^i + \sigma_i dB_t)] \left[y \left(\eta dt + \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma} \alpha dB_t \right) \right] \\
&= V_t dt + \pi^i \mu_i x V_x + V_x (\nu_i dW_t^i + \sigma_i dB_t) + \eta y V_y + V_y \left[y \left(\frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma} \alpha dB_t \right) \right] \\
&\quad + \frac{1}{2} V_{xx} [(\sigma_i^2 (dB_t)^2 + \nu_i^2 (dW_t^i)^2)] (\pi^i)^2 x^2 + \frac{1}{2} V_{xx} (\mu_i \pi^i X_t^i)^2 (dt)^2 \\
&\quad + V_{xx} [(\pi^i x)^2 (\mu_i \nu_i dt dW_t^i + \mu_i \sigma_i dt dB_t + \nu_i \sigma_i dW_t^i dB_t)] + \frac{1}{2} V_{yy} \left[\widehat{\sigma} \alpha^2 + \frac{1}{n} \left(\frac{1}{n} \sum_{k \neq i} \nu_k^2 \alpha_k^2 \right) \right] y \\
&\quad + \frac{1}{2} V_{yy} (\eta y)^2 (dt)^2 + V_{yy} \left[\eta \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dt dW_t^k + \eta \widehat{\sigma} \alpha dt dB_t + \widehat{\sigma} \alpha \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k dB_t \right] y \\
&\quad + V_{xy} \pi^i \sigma_i \widehat{\sigma} \alpha x y (dB_t)^2 + V_{xy} \left[(\pi^i x y) \left(\mu_i \eta (dt)^2 + \mu_i \frac{1}{n} \sum_{k \neq i} dt dW_t^i + \mu_i \widehat{\sigma} \alpha dt dB_t + \nu_i \eta dt dW_t^i \right) \right] \\
&\quad + V_{xy} \left[(\pi^i x y) \left(\nu_i \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^i dW_t^k + \nu_i \widehat{\sigma} \alpha dW_t^i dB_t + \sigma_i \eta dt dB_t + \sigma_i \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dB_t dW_t^k \right) \right]
\end{aligned}$$

According to the rules $dt \cdot dt = dt \cdot dB_t = dB_t \cdot dt = 0$, we obtain

$$\begin{aligned}
dV &= V_t dt + \pi^i \mu_i x V_x + V_x (\nu_i dW_t^i + \sigma_i dB_t) + \eta y V_y + V_y \left[y \left(\frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k + \widehat{\sigma} \alpha dB_t \right) \right] \\
&\quad + \frac{1}{2} V_{xx} [(\sigma_i^2 (dB_t)^2 + \nu_i^2 (dW_t^i)^2)] (\pi^i)^2 x^2 + V_{xx} (\pi^i x)^2 (\nu_i \sigma_i dW_t^i dB_t) \\
&\quad + \frac{1}{2} V_{yy} \left[\widehat{\sigma} \alpha^2 + \frac{1}{n} \left(\frac{1}{n} \sum_{k \neq i} \nu_k^2 \alpha_k^2 \right) \right] y^2 + V_{yy} \left[\widehat{\sigma} \alpha \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^k dB_t \right] y^2 + V_{xy} \pi^i \sigma_i \widehat{\sigma} \alpha x y (dB_t)^2 \\
&\quad + V_{xy} \left[(\pi^i x y) \left(\nu_i \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dW_t^i dW_t^k + \nu_i \widehat{\sigma} \alpha dW_t^i dB_t + \sigma_i \frac{1}{n} \sum_{k \neq i} \nu_k \alpha_k dB_t dW_t^k \right) \right].
\end{aligned}$$

Since $E[dW_t^i] = E[dB_t] = 0$, $E[(dW_t^i)^2] = E[(dB_t)^2] = dt$, and the fact that W_t^i, W_t^k and B_t are independent, taking expectations and rearranging the equality above, we get

$$\begin{aligned} dV &= V_t dt + \pi^i \mu_i x V_x + \eta y V_y + \frac{1}{2} V_{xx} [(\sigma_i^2 dt + \nu_i^2 dt)] (\pi^i)^2 x^2 + V_{xy} \pi^i \widehat{\sigma \alpha} xy dt \\ &\quad + \frac{1}{2} \left[\widehat{\sigma \alpha}^2 + \frac{1}{n} \widehat{(\nu \alpha)^2} \right] y^2 V_{yy}. \end{aligned}$$

Divide both sides of above equality by dt and rearranging, we get

$$\dot{V} = V_t + \frac{1}{2} (\sigma_i^2 + \nu_i^2) (\pi^i)^2 x^2 V_{xx} + \pi^i (\mu_i x V_x + \sigma_i \widehat{\sigma \alpha} xy V_{xy}) + \eta y V_y + \frac{1}{2} \left[\widehat{\sigma \alpha}^2 + \frac{1}{n} \widehat{(\nu \alpha)^2} \right] y^2 V_{yy}.$$

At equilibrium, V is optimal and then $\dot{V} = 0$. Thus, we get the HJB equation

$$V_t + \frac{1}{2} (\sigma_i^2 + \nu_i^2) (\pi^i)^2 x^2 V_{xx} + \pi^i (\mu_i x V_x + \sigma_i \widehat{\sigma \alpha} xy V_{xy}) + \eta y V_y + \frac{1}{2} \left[\widehat{\sigma \alpha}^2 + \frac{1}{n} \widehat{(\nu \alpha)^2} \right] y^2 V_{yy} = 0. \quad (4.41)$$

for $(x, y, t) \in \mathbb{R}_+ \times \mathbb{R}_+ \times [0, T]$, with terminal condition

$$V(x, y, T) = f(t) \frac{1}{1 - \gamma_i} \left[(X_T^i)^{1 - \theta_i/n} Y_T^{-\theta_i} \right]^{1 - \gamma_i}.$$

Taking the first-order condition of (4.41) with respect to π^i , then solving for π^i , we obtain the agent i 's implicit optimal investment strategy

$$\pi^{i,*} = - \frac{\mu_i x V_x + \sigma_i \widehat{\sigma \alpha} xy V_{xy}}{(\sigma_i^2 + \nu_i^2) x^2 V_{xx}}. \quad (4.42)$$

Then, plug $\pi^{i,*}$ in the above equality into the HJB equation (4.41), we get

$$V_t - \frac{1}{2} \frac{(\mu_i x V_x + \sigma_i \widehat{\sigma \alpha} xy V_{xy})^2}{(\sigma_i^2 + \nu_i^2) x^2 V_{xx}} + \frac{1}{2} \left[\widehat{\sigma \alpha}^2 + \frac{1}{n} \widehat{(\nu \alpha)^2} \right] y^2 V_{yy} + \eta y V_y = 0. \quad (4.43)$$

Taking derivatives the ansatz (4.40) to get $V_t, V_x, V_y, V_{xx}, V_{xy}$, and V_{yy} then plugging into above equality, we get

$$\frac{1}{1 - \gamma_i} f'(t) + \rho f(t) = 0, \quad \forall t \in [0, T]$$

where

$$\rho = \frac{\left[\mu_i (1 - \frac{\theta_i}{n}) - \sigma_i \widehat{\sigma \alpha} \theta_i (1 - \frac{\theta_i}{n}) (1 - \gamma_i) \right]^2}{2(\sigma^2 + \nu_i^2) (1 - \frac{\theta_i}{n}) \left[1 - (1 - \frac{\theta_i}{n}) (1 - \gamma_i) \right]} + \frac{1}{2} \left(\widehat{\sigma \alpha}^2 + \frac{1}{n} \widehat{(\nu \alpha)^2} \right) \theta_i [1 + \theta_i (1 - \gamma_i)] - \eta \theta_i.$$

Thus, we get $f(t) = e^{\rho(1-\gamma_i)(T-t)}$. Hence,

$$V(x, y, t) = e^{\rho(1-\gamma_i)(T-t)} \frac{1}{1-\gamma_i} \left(x^{1-\theta_i/n} y^{-\theta_i} \right)^{1-\gamma_i}$$

Then, taking derivatives V_x, V_{xx} , and V_{xy} and plugging into (4.42), we obtain the agent i 's explicit optimal investment strategy

$$\pi^{i,*} = \frac{\mu_i - \sigma_i \widehat{\sigma} \alpha \theta_i (1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)]}. \quad (4.44)$$

Define

$$\bar{\sigma} \alpha := \frac{1}{n} \sum_{k=1}^n \sigma_k \alpha_k.$$

Then, we have

$$\bar{\sigma} \alpha = \frac{1}{n} \sum_{k \neq i} \sigma_k \alpha_k + \frac{1}{n} \sigma_i \alpha_i = \widehat{\sigma} \alpha + \frac{1}{n} \sigma_i \alpha_i \rightarrow \widehat{\sigma} \alpha = \bar{\sigma} \alpha - \frac{1}{n} \sigma_i \alpha_i.$$

We want to find the constant vector $(\alpha_1, \dots, \alpha_n)$, i.e. a constant strategy α_i for each agent i . So there must be $\alpha_i = \pi^{i,*}$ for every $i = 1, \dots, n$. Thus, we have

$$\begin{aligned} \alpha_i &= \frac{\mu_i - \sigma_i \widehat{\sigma} \alpha \theta_i (1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)]} \\ &= \frac{\mu_i - \sigma_i \bar{\sigma} \alpha \theta_i (1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)]} + \frac{\sigma_i^2 \alpha_i (\theta_i/n)(1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)]} \end{aligned}$$

Thus, we obtain

$$\begin{aligned} \alpha_i &= \frac{\mu_i - \sigma_i \bar{\sigma} \alpha \theta_i (1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)]} \left(1 - \frac{\sigma_i^2 (\theta_i/n)(1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)]} \right)^{-1} \\ &= \frac{\mu_i - \sigma_i \bar{\sigma} \alpha \theta_i (1 - \gamma_i)}{(\sigma_i^2 + \nu_i^2)[1 - (1 - \theta_i/n)(1 - \gamma_i)] - \sigma_i^2 (\theta_i/n)(1 - \gamma_i)} \\ &= \frac{\mu_i}{\sigma_i^2 \gamma_i + \nu_i^2 [1 - (1 - \theta_i/n)(1 - \gamma_i)]} - \frac{\sigma_i \bar{\sigma} \alpha \theta_i (1 - \gamma_i)}{\sigma_i^2 \gamma_i + \nu_i^2 [1 - (1 - \theta_i/n)(1 - \gamma_i)]} \\ &= \frac{\mu_i}{\gamma_i \sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n \gamma_i} \right)} + \theta_i \left(1 - \frac{1}{\gamma_i} \right) \frac{\sigma_i}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n \gamma_i} \right)} \bar{\sigma} \alpha. \quad (4.45) \end{aligned}$$

Multiplying both sides by σ_i and then averaging the above quality for $i = 1, \dots, n$, we get

$$\bar{\sigma} \alpha = \varphi_n + \psi_n \bar{\sigma} \alpha,$$

where φ_n and ψ_n defined in (4.36) and (4.37). There are three cases:

(i) If $\psi_n \neq 1$, $\gamma_i \neq 1$, and $\gamma_i \neq 0$, there exists a unique constant Nash equilibrium given by

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i} \frac{1}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i}\right)} + \theta_i \left(1 - \frac{1}{\gamma_i}\right) \frac{\sigma_i}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i}\right)} \frac{\varphi_n}{1 - \psi_n}.$$

Moreover, we have the identity given by

$$\mathbb{E}(\sigma_k \pi^{k,*}) = \sigma \bar{\alpha} = \frac{\varphi_n}{1 - \psi_n}.$$

(ii) If $\psi_n = 1$ and $\varphi_n \neq 0$, there is no constant Nash equilibrium.

(iii) If $\psi = 1$ and $\varphi_n = 0$, there are infinitely many constant Nash equilibria.

Case 2: Suppose $\gamma_i = 1$. Since $\gamma_i = 1 > 0$ then $U_{xx} < 0$. That means the logarithmic form utility function describes the behavior of risk-averse agents. Making the ansatz of the value function

$$V(x, y, t) = \log \left(x^{1-\theta_i/n} y^{-\theta_i} \right) + f(t) = \left(1 - \frac{\theta_i}{n} \right) \log x - \theta_i \log y + f(t).$$

Taking derivatives this ansatz to get $V_t, V_x, V_y, V_{xx}, V_{xy}$, and V_{yy} and then plugging into (4.43)¹², we get

$$f'(t) + \rho = 0,$$

where

$$\rho = \frac{1}{2} \frac{\mu_i^2 (1 - \theta_i/n)}{(\sigma_i^2 + \nu_i^2)} + \frac{1}{2} \theta_i \left(\widehat{\sigma \alpha}^2 + \frac{1}{n} \widehat{(\nu \alpha)^2} \right) - \theta_i \eta.$$

Thus, we obtain $f(t) = \rho(T - t)$. Plugging into the above value function, we get

$$V(x, y, t) = \left(1 - \frac{\theta_i}{n} \right) \log x - \theta_i \log y + \rho(T - t).$$

Taking derivatives V_x, V_{xx} , and V_{xy} and plugging into (4.42), we get the agent i 's explicit optimal investment strategy

$$\pi^{i,*} = \frac{\mu_i}{\sigma_i^2 + \nu_i^2} \quad \text{for all } i = 1, \dots, n,$$

which is a special case of (4.44) when $\gamma_i = 1$ and is exactly as (4.39). □

¹²Note that the equality (4.43) is the common result derived for both cases: power form and logarithmic form in (4.43). Therefore, it does still work for the case that $\gamma_i = 1$.

Theorem 4.4.2 (Unique corner solution for strictly convex power utility function). *Suppose U_i the utility function of agent i as in (4.34) with $\gamma_i < 0$. For the power case, the optimal solution is $\pi^{i,*} = 1$ for risky asset (stock) and $\pi^{i,*} = 0$ for riskless asset (bond).*

Proof. Most arguments in the proof of Theorem 4.3.2 for the exponential case are still correct in the power case. The only different point is the functional form of utility function.

For the power case, we have $U'_{X_T^i} = (X_T^i \bar{X}_T^{-\theta_i})^{-\gamma_i} \bar{X}_T^{-\theta_i} > 0$, which implies that U_i is a strictly increasing function in X_T^i . Moreover, for $\gamma_i < 0$, we can check the second order sufficient condition that

$$U''_{X_T^i} = -\gamma_i \left(X_T^i \bar{X}_T^{-\theta_i} \right)^{-\gamma_i - 1} \bar{X}_T^{-2\theta_i} > 0,$$

which implies that U_i is a strictly convex utility function. Thus, the maximum at M must be unique and be on the upper boundary of the domain and M must be unique. This implies that $\pi^{i,*} = 1$ for the risky asset (stock) and thus $\pi^{i,*} = 0$ for riskless asset (bond). Obviously, the corner solution is unique. \square

Remark 4.4.1 (Economic meaning of corner solution for strictly convex utility function). *Theorem 4.3.2 and Theorem 4.4.2 contribute to the literature of asset specialization in the sense that individual risk-seeking investors only invest their whole wealth in one stock as a risky asset (or small portfolio with few stocks as a whole) and do not invest in riskless assets (e.g. bond) in the case of strictly convex utility function.*

4.4.2 The mean field games

In this section, we examine the limiting behavior of n -player games in the previous section when $n \rightarrow \infty$. We use the same assumption of continuum of agents as Assumption 4.3.1 and the same definition of MFG as Definition 4.3.6.

The dynamics of wealth of the representative agent is given by

$$dX_t = \pi_t X_t (\mu dt + \nu dW_t + \sigma dB_t), \quad X_0 = \xi, \quad (4.46)$$

where the investment fraction π_t belongs to the admissible set \mathcal{A}_{MF} and satisfies the mean square integrable property $\mathbb{E} \int_0^T |\pi_t|^2 dt < \infty$. The goal of the representative agent is to maximize the following expected utility

$$\sup_{\pi_t \in \mathcal{A}_{MF}} \mathbb{E} \left[\frac{1}{1-\gamma} \left(X_T \bar{X}_T^{-\theta} \right)^{1-\gamma} \right] \quad (4.47)$$

given the dynamics (4.46). Here, \bar{X}_T is the geometric mean which is defined as follows

$$\bar{X}_T := \exp \mathbb{E} [\log X_T \mid \mathcal{F}_T^B], \quad (4.48)$$

where \mathcal{F}_T^B denotes the filtration generated by the Brownian motion B .

Definition 4.4.2 (MFG). *Given \bar{X}_T defined as (4.48) and let $\pi_t^* \in \mathcal{A}_{MF}$ be an admissible strategy. Then, π_t^* is a mean field equilibrium (MFE) if π_t^* solves the optimization problem (4.47).*

Definition 4.4.3 (Constant MFE). *The optimal control π^* is called a constant MFE if $\pi^* = \pi_t^*$ for all $t \in [0, T]$, where π_t^* is a MFE defined in Definition 4.4.2.*

Lemma 4.4.1. *Define two constants*

$$\varphi := \mathbb{E} \left[\frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2} \right] \quad \text{and} \quad \psi := \mathbb{E} \left[\theta \left(1 - \frac{1}{\gamma} \right) \frac{\sigma^2}{\sigma^2 + \nu^2} \right],$$

where $\gamma \neq 0$. We claim that these two expectations exist and are finite.

Proof. Denote

$$\Xi = \frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2} \quad \text{and} \quad \Lambda = \theta \left(1 - \frac{1}{\gamma} \right) \frac{\sigma^2}{\sigma^2 + \nu^2}.$$

By assumptions $0 \leq \mu \leq \bar{\mu}, \gamma \neq 0, 0 \leq \nu \leq \bar{\nu}$, and $0 \leq \sigma \leq \bar{\sigma}$ then Ξ must be exist and is finite, and so is φ .

By assumptions $-1 \leq \theta \leq 1$ and $\gamma \neq 0$, and note that $\sigma^2/(\sigma^2 + \nu^2) \leq 1$ then Λ must be exist and is finite, and so is ψ . \square

Theorem 4.4.3 (Existence and uniqueness of constant MFE). *Given strictly concave utility function U . Assume for a.s. that $-1 \leq \theta \leq 1, 0 \leq \mu \leq \bar{\mu}, 0 \leq \nu \leq \bar{\nu}$, and $0 \leq \sigma \leq \bar{\sigma}$. Define two constants φ and ψ as that in Lemma 4.4.1.*

There are four cases:

(i) *If $\psi \neq 1, \gamma \neq 1$, and $\gamma \neq 0$, then there exists a unique constant MFE given by*

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \left(1 - \frac{1}{\gamma} \right) \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi}. \quad (4.49)$$

Moreover, we have the identity given by

$$\mathbb{E}(\sigma \pi^*) = \frac{\varphi}{1 - \psi}.$$

(ii) If $\psi \neq 1$ and $\gamma = 1$, there is a unique constant MFE given by

$$\pi^* = \frac{\mu}{\sigma^2 + \nu^2}. \quad (4.50)$$

(iii) If $\psi = 1$ and $\varphi \neq 0$, there is no constant MFE.

(iv) If $\psi = 1$ and $\varphi = 0$, there are infinitely many constant MFE.

Proof. Define

$$Y_t := \exp \mathbb{E}(\log X_t^\alpha \mid \mathcal{F}_T^B),$$

where α is an admissible constant strategy. From the dynamics (4.46), using Itô's formula, we get

$$d(\log X_t^\alpha) = \left(\mu\alpha - \frac{1}{2}(\sigma^2 + \nu^2)\alpha^2 \right) dt + \nu\alpha dW_t + \sigma\alpha dB_t.$$

Define $\hat{X}_t^\alpha := \mathbb{E}(\log X_t^\alpha \mid \mathcal{F}_T^B)$. Denote $\omega = \sigma^2 + \nu^2$. Then, since $\zeta = (\xi, \gamma, \theta, \mu, \nu, \sigma), W$, and B are independent, we obtain

$$d\hat{X}_t^\alpha = \left(\bar{\mu}\alpha - \frac{1}{2}\omega\bar{\alpha}^2 \right) dt + \bar{\sigma}\alpha dB_t,$$

Using Itô's formula one more time, we get

$$\begin{aligned} dY_t &= de^{\hat{X}_t^\alpha} = Y_t \left(\left[(\bar{\mu}\alpha - \frac{1}{2}\omega\bar{\alpha}^2) + \frac{1}{2}\bar{\sigma}\alpha^2 \right] dt + \bar{\sigma}\alpha dB_t \right), \quad Y_0 = \bar{\xi}, \\ &= Y_t(\eta dt + \bar{\sigma}\alpha dB_t), \quad Y_0 = \bar{\xi}, \end{aligned} \quad (4.51)$$

where $\eta = \bar{\mu}\alpha - \frac{1}{2}(\omega\bar{\alpha}^2 - \bar{\sigma}\alpha^2)$.

The goal of the representative agent is to solve the following problem

$$\sup_{\pi \in \mathcal{A}_{MF}} \mathbb{E} \frac{1}{1-\gamma} \left(X_T Y_T^{-\theta} \right)^{1-\gamma}.$$

with the given dynamics

$$dX_t = \pi_t X_t (\mu dt + \nu dW_t + \sigma dB_t),$$

and $Y_t, t \in [0, T]$, solving the dynamics (4.51).

Note that when $n \rightarrow \infty$, we have $Y_T \approx \bar{X}_T$. We consider two cases.

Case 1: Suppose $\gamma \neq 1$. Denote $x = X_t, y = Y_t$. Making the ansatz of the value function

$$V(x, y, t) = f(t) \frac{1}{1-\gamma} x^{1-\gamma} y^{-\theta(1-\gamma)}, \quad \forall t \in [0, T] \quad (4.52)$$

and note that when $n \rightarrow \infty$, we have $\widehat{\sigma\alpha} = \bar{\sigma}\alpha - \frac{1}{n}\sigma_i\alpha_i \approx \bar{\sigma}\alpha$. Then, following the similar steps as the proof of Theorem 4.4.1, we derive the HJB equation

$$V_t + \frac{1}{2}(\sigma^2 + \nu^2)\pi^2 x^2 V_{xx} + \pi(\mu x V_x + \sigma \bar{\sigma} \alpha x y V_{xy}) + \eta y V_y + \frac{1}{2}\bar{\sigma}^2 \alpha^2 y^2 V_{yy} = 0 \quad (4.53)$$

with the terminal condition $V(x, y, T) = \frac{1}{1-\gamma}(xy)^{-\theta}$.

Taking the first-order condition (4.53) with respect to π and then manipulating, we get the implicit optimal investment strategy

$$\pi^* = -\frac{\mu x V_x + \sigma \bar{\sigma} \alpha x y V_{xy}}{(\sigma^2 + \nu^2)x^2 V_{xx}}. \quad (4.54)$$

Plugging back to (4.53), it reduces to

$$V_t - \frac{1}{2} \frac{(\mu x V_x + \sigma \bar{\sigma} \alpha x y V_{xy})^2}{(\sigma^2 + \nu^2)x^2 V_{xx}} + \eta y V_y + \frac{1}{2}\bar{\sigma}^2 \alpha^2 y^2 V_{yy} = 0. \quad (4.55)$$

Taking derivatives the ansatz (4.52) to get $V_t, V_x, V_y, V_{xx}, V_{xy}$, and V_{yy} then plugging into (4.55), we get $\frac{1}{1-\gamma}f'(t) + \rho f(t) = 0$, with $f(T) = 1$, where

$$\rho := \frac{[\mu - \theta(1-\gamma)\sigma\bar{\sigma}\alpha]^2}{2(\sigma^2 + \nu^2)\gamma} - \eta\theta + \frac{1}{2}\bar{\sigma}^2 \alpha^2 \theta(\theta(1-\gamma) + 1).$$

Thus, we obtain $f(t) = e^{\rho(1-\gamma)(T-t)}$. Plugging into (4.52), we get

$$V(x, y, t) = e^{\rho(1-\gamma)(T-t)} \frac{1}{1-\gamma} x^{1-\gamma} y^{-\theta(1-\gamma)}.$$

Then, taking derivatives V_x, V_{xx} , and V_{xy} and plugging into (4.54), we obtain the explicit optimal investment strategy

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma}{\sigma^2 + \nu^2} \bar{\sigma} \alpha \quad (4.56)$$

We want to find the constant vector $(\alpha_1, \dots, \alpha_n)$. So there must be $\alpha_i = \pi^*$ for every $i = 1, \dots, n$. Multiplying both sides by σ and averaging (4.56), we get

$$\sigma \bar{\pi}^* = \mathbb{E} \left[\frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2} \right] + \mathbb{E} \left[\theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma}{\sigma^2 + \nu^2} \right] \sigma \bar{\pi}^* = \varphi + \psi \sigma \bar{\pi}^*.$$

There are three cases:

(i) If $\psi \neq 1$, $\gamma \neq 1$, and $\gamma \neq 0$, there exists a unique constant MFE given by

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi}.$$

Moreover, we have the identity given by

$$\mathbb{E}(\sigma \pi^*) = \sigma \bar{\pi}^* = \sigma \bar{\alpha} = \frac{\varphi}{1 - \psi}.$$

(ii) If $\psi = 1$ and $\varphi \neq 0$, there is no constant MFE.

(iii) If $\psi = 1$ and $\varphi = 0$, there are infinitely many constant MFE.

Case 2: Suppose $\gamma = 1$. Note that in this case since the logarithmic utility function is concave, it only describes the behavior of risk-averse agents.

Making the ansatz of the value function

$$V(x, y, t) = \log x - \theta \log y + f(t).$$

Following the similar steps as the proof of Theorem 4.4.1, we obtain $f(t) = \rho(T - t)$. Hence, we get

$$V(x, y, t) = \log x - \theta \log y + \rho(T - t).$$

Taking derivatives V_x , V_{xx} , and V_{xy} and plugging into (4.54), we get the explicit optimal investment strategy

$$\pi^* = \frac{\mu}{\sigma^2 + \nu^2},$$

which is exactly (4.50). □

MFE for strictly convex power utility function. The optimal strategy for Theorem 4.4.2 does not depend on number of players n and also i . Therefore, the optimal strategy for the case of n -agent games (Nash equilibrium) and that for the case of MFG (mean field equilibrium) should be the same. That is, $\pi^* = 1$ for risky asset (stock) and $\pi^* = 0$ for riskless asset (bond). Obviously, the corner solution is unique.

4.4.3 Convergence of MFE to Nash equilibria

The important link between Nash equilibria and MFE in this study is that MFE of mean field games is the convergent result of the Nash equilibrium in the corresponding N -agent game when $n \rightarrow \infty$.

Theorem 4.4.4 (Convergence). *The MFE (4.24) and (4.49) are the limits as $n \rightarrow \infty$ of n -player Nash equilibria (4.11) and (4.38), respectively.*

Proof. It is obvious by the ways we have constructed the MFG based on the corresponding N -agent games. \square

In the case of the logarithmic utility function, the Nash equilibrium and the MFE have very similar structures, which respectively are

$$\pi^{i,*} = \frac{\mu_i}{\sigma_i^2 + \nu_i^2} \quad \text{and} \quad \pi^* = \frac{\mu}{\sigma^2 + \nu^2}.$$

These two optimal investment strategies are always positive. That means risk-averse agents with logarithmic utility functions always invest a positive fraction of their wealth in their individual stock either in games with finite or infinite agents.

We can observe that the optimal strategy (4.38) and (4.11), and (4.49) and (4.24) have similar structures, respectively. Note that in (4.11), ν_i^2 is scaled by $1 - \theta_i/n$ compared to that in (4.38) and in (4.24), ν_i^2 is scaled by $1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i}$ compared to that in (4.49). A noticeable point is that all of the above optimal strategies do not depend on wealth. Specifically, the MFE only depends on the representative individual preferences and market parameters. Meanwhile, the Nash equilibria depend on individual preferences and market parameters, and the number of players.

Note that in the case there is no relative performance, i.e. $\theta = 0$, the optimal investment strategy (4.49) is equal to

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2},$$

which is the classical Merton portfolio in Merton (1969) when there is only one Brownian process and bond (sure asset) offers zero interest rate.

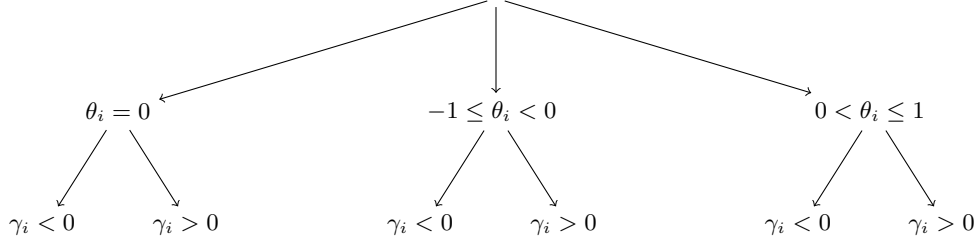
4.5 Discussion

Main theorems for the case of strictly concave utility function in this chapter including Theorem 4.3.1, Theorem 4.3.3, Theorem 4.4.1, Theorem 4.4.3 and their proofs are largely inspired by the frameworks of Theorem 2.3, Theorem 2.10, Theorem 3.1, and Theorem 3.6 and their proofs in Lacker and Zariphopoulou (2019), respectively, but our results are more general. The effects of the personal and market parameters in our study are much more complicated than the ideal case of risk aversion in Lacker and Zariphopoulou (2019). We employ this section to discuss the qualitative effects of the number of players in n -agent games, relative performance, and risk tolerance parameter on the optimal strategies.

4.5.1 The effects of the number agents in n -agent games

The stock market is a complex system. Therefore, the effects of the number of agents in n -agent games on optimal strategies in both exponential and power/logarithmic cases are not straightforward. There are six cases illustrated in the following tree.

Figure 4.1: Tree with 6 cases depending on personal parameters



Note that [Lacker and Zariphopoulou \(2019\)](#) only considers two cases among these six cases, which are $0 < \theta_i \leq 1, \gamma_i > 0$ and $\theta_i = 0, \gamma_i > 0$. That means, they only study the risk-averse agents. Rather, we analyze the behavior of both risk-averse and risk-seeking agents.

Exponential case

For the sake of convenient analysis, we restate the optimal strategy of the n -agent games in the exponential case.

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i \sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{1}{1 - \psi_n} + \theta_i \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{\varphi_n}{1 - \psi_n},$$

where

$$\varphi_n = \frac{1}{n} \sum_{i=1}^n \frac{\mu_i}{\gamma_i \sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \quad \text{and} \quad \psi_n = \frac{1}{n} \sum_{i=1}^n \left[\theta_i \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \right],$$

and $0 \leq \mu_i \leq \bar{\mu}_i$, $0 \leq \nu_i \leq \bar{\nu}_i$, $0 \leq \sigma_i \leq \bar{\sigma}_i$, and $-1 \leq \theta_i \leq 1$ for all $i = 1, \dots, n$.

We will only analyze some specific cases. For simplicity, denote

$$M_1 = \frac{\mu_i}{\gamma_i \sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \quad \text{and} \quad M_2 = \theta_i \frac{\sigma_i}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \frac{\varphi_n}{1 - \psi_n}.$$

Case 1: There is no relative performance, i.e. $\theta_i = 0$. Thus,

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i \sigma_i^2 + \nu_i^2} \frac{1}{1 - \psi_n}.$$

In this case, the optimal investment strategy does not depend on the number of agents. This makes sense since in this case agent i is not concerned or motivated by other agents (i.e. $\theta_i = 0$). Moreover, if $\gamma_i > 0$ then $\pi^{i,*} > 0$ and if $\gamma_i < 0$ then $\pi^{i,*} < 0$.

Case 2: $0 < \theta_i \leq 1, \gamma_i > 0$. This is the situation where risk-averse agents with relative performance concern. In this case, we can check that $\pi^{i,*} > 0$. Moreover, an increase in n leads to a decrease in the first term of $\pi^{i,*}$,

$$n \uparrow \longrightarrow \frac{\theta_i}{n} \downarrow \longrightarrow \left(1 - \frac{\theta_i}{n}\right) \uparrow \longrightarrow \frac{1}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \downarrow \longrightarrow M_1 \downarrow.$$

Since $\mu_i \geq 0$ and $\gamma_i > 0$, then $\varphi_n \geq 0$. Also, since $0 < \theta_i \leq 1$, then $0 < \psi_n < 1$, and then $1 - \psi_n > 0$. Consequently $\varphi_n/(1 - \psi_n) \geq 0$. Moreover,

$$\begin{cases} n \uparrow \longrightarrow \frac{\theta_i}{n} \downarrow \longrightarrow \left(1 - \frac{\theta_i}{n}\right) \uparrow \longrightarrow \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \downarrow \longrightarrow \sum_{i=1}^n \frac{\mu_i}{\gamma_i} \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \downarrow \\ n \uparrow \longrightarrow \frac{1}{n} \downarrow \end{cases} \longrightarrow \varphi_n \downarrow,$$

and

$$\begin{cases} n \uparrow \longrightarrow \frac{\theta_i}{n} \downarrow \longrightarrow \left(1 - \frac{\theta_i}{n}\right) \uparrow \longrightarrow \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \downarrow \longrightarrow \sum_{i=1}^n \theta_i \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2(1 - \theta_i/n)} \downarrow \\ n \uparrow \longrightarrow \frac{1}{n} \downarrow \end{cases} \longrightarrow \psi_n \downarrow \longrightarrow 1 - \psi_n \uparrow.$$

Thus, n increases leading to $\varphi_n/(1 - \psi_n)$ decreases. Hence, an increase in n leads to a decrease in the second term of $\pi^{i,*}$ (i.e. $M_2 \downarrow$) as well as the first term of $\pi^{i,*}$ (i.e. $M_1 \downarrow$). As a result, an increase in the number of agents n leads to a decrease in the absolute value of wealth that agent i invests in the individual risky stock i . This might be because an increase in the number of agents accelerates the level of competition in the market.

Case 3: $0 < \theta_i \leq 1, \gamma_i < 0$. This is the situation where risk-seeking agents concern with relative performance. Assume further that $\mu > 0$. In this case, since $\mu_i > 0$ and $\gamma_i < 0$ then $\mu_i/\gamma_i < 0$. Thus, $\varphi_n < 0$. Moreover, since $0 < \theta_i \leq 1$, then $0 < \psi_n \leq 1$, and then $0 \leq 1 - \psi_n < 1$. Since the optimal strategy requires that $\psi_n \neq 1$ or $1 - \psi_n \neq 0$, we get $\varphi_n/(1 - \psi_n) < 0$. As a result, $M_1 < 0$ and $M_2 < 0$, and then $\pi^{i,*} < 0$. Moreover,

$$n \uparrow \longrightarrow \begin{cases} |\pi^{i,*}| \uparrow & \text{if } |\Delta M_1| + |\Delta M_2| > 0 \\ |\pi^{i,*}| \downarrow & \text{if } |\Delta M_1| + |\Delta M_2| < 0. \end{cases}$$

Case 4: $-1 \leq \theta_i < 0, \gamma_i > 0$. Then, $M_1 > 0$ and $M_2 < 0$. Thus, $\pi^{i,*}$ can be positive or negative,

$$\pi^{i,*} \text{ is } \begin{cases} \text{positive ,} & \text{if } M_1 > |M_2| \\ \text{negative ,} & \text{if } M_1 < |M_2| \\ 0, & \text{if } M_1 = |M_2|. \end{cases}$$

An increase in n leads to

$$\pi^{i,*} \begin{cases} \text{increases,} & \text{if } \Delta M_1 > |\Delta M_2| \\ \text{decreases,} & \text{if } \Delta M_1 < |\Delta M_2| \\ \text{remains unchanged,} & \text{if } \Delta M_1 = |\Delta M_2|. \end{cases}$$

Power and logarithmic case

Recall the optimal strategy of the n -agent games in the power/logarithmic case given by

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i} \frac{1}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i}\right)} + \theta_i \left(1 - \frac{1}{\gamma_i}\right) \frac{\sigma_i}{\sigma_i^2 + \nu_i^2 \left(1 - \frac{\theta_i}{n} + \frac{\theta_i}{n\gamma_i}\right)} \frac{\varphi_n}{1 - \psi_n},$$

where

$$\varphi_n := \frac{1}{n} \sum_{i=1}^n \frac{\mu_i}{\gamma_i} \frac{\sigma_i}{\sigma_i^2 + \nu_i^2 \left[1 + \left(\frac{1}{\gamma_i} - 1\right) \frac{\theta_i}{n}\right]}, \quad \psi_n := \frac{1}{n} \sum_{i=1}^n \theta_i \left(\frac{1}{\gamma_i} - 1\right) \frac{\sigma_i^2}{\sigma_i^2 + \nu_i^2 \left[1 + \left(\frac{1}{\gamma_i} - 1\right) \frac{\theta_i}{n}\right]},$$

and $-1 \leq \theta_i \leq 1, 0 \leq \mu_i \leq \bar{\mu}_i, 0 \leq \nu_i \leq \bar{\nu}_i$, and $0 \leq \sigma_i \leq \bar{\sigma}_i$ for all $i = 1, \dots, n$, and with the conditions that $\psi_n \neq 1, \gamma_i \neq 1$, and $\gamma_i \neq 0$.

Case 1: $\theta_i = 0$, i.e. there is no relative performance parameter. Then,

$$\pi^{i,*} = \frac{\mu_i}{\gamma_i} \frac{1}{\sigma_i^2 + \nu_i^2}.$$

Obviously, this optimal strategy does not depend on the number of agents n . Moreover, it coincides with that of the exponential utility function case.

Case 2: $\gamma_i = 1$. The optimal strategy does not depend on n and is given by

$$\pi^{i,*} = \frac{\mu_i}{\sigma_i^2 + \nu_i^2}.$$

4.5.2 The effects of relative performance

In order to examine the effects of θ on π^* , we rewrite the MFE in the exponential and power case respectively as follows.

$$\pi^{*,\text{exp}} = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \frac{\theta}{1 - \mathbb{E}\left(\theta \frac{\sigma^2}{\sigma^2 + \nu^2}\right)} \frac{\sigma}{\sigma^2 + \nu^2} \varphi, \quad \text{where} \quad \varphi := \mathbb{E}\left(\frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2}\right)$$

and

$$\pi^{*,\text{pow}} = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} + \frac{\theta}{1 - \mathbb{E}\left[\theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma^2}{\sigma^2 + \nu^2}\right]} \left(1 - \frac{1}{\gamma}\right) \frac{\sigma}{\sigma^2 + \nu^2} \varphi, \quad \text{where} \quad \varphi := \mathbb{E}\left(\frac{\mu}{\gamma} \frac{\sigma}{\sigma^2 + \nu^2}\right).$$

For simplicity, assume

$$\mathbb{E}\left(\theta \frac{\sigma^2}{\sigma^2 + \nu^2}\right) = \theta \frac{\sigma^2}{\sigma^2 + \nu^2}, \quad \text{and} \quad \mathbb{E}\left[\theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma^2}{\sigma^2 + \nu^2}\right] = \theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma^2}{\sigma^2 + \nu^2}.$$

Thus, holding other things constant, we can write π^* as a function of θ , i.e. $\pi^* = \pi^*(\theta)$. Taking derivative with respect to θ for both exponential and power cases, respectively, yield

$$\pi_{\theta}^{*,\text{exp}} = \frac{\sigma}{(1 - \theta)\sigma^2 + \nu^2} \varphi \quad \text{and} \quad \pi_{\theta}^{*,\text{pow}} = \frac{1}{1 - \theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma^2}{\sigma^2 + \nu^2}} \left(1 - \frac{1}{\gamma}\right) \frac{\sigma}{\sigma^2 + \nu^2} \varphi.$$

Assume further that $\sigma > 0$. Thus,

$$\frac{\sigma}{(1 - \theta)\sigma^2 + \nu^2} > 0, \quad \frac{1}{1 - \theta \left(1 - \frac{1}{\gamma}\right) \frac{\sigma^2}{\sigma^2 + \nu^2}} > 0, \quad \text{and} \quad \frac{\sigma}{\sigma^2 + \nu^2} > 0.$$

Thus, the sign of $\pi_{\theta}^{*,\text{exp}}$ depends on the sign of φ and the sign of $\pi_{\theta}^{*,\text{pow}}$ depends on the sign of $(1 - 1/\gamma)\varphi$.

We now analyze some specific cases to see the effects of the relative performance parameter θ on the optimal investment strategy π^* in both exponential and power cases.

Case 1: $0 < \theta \leq 1, \gamma > 0$. In this case $\pi_{\theta}^{*,\text{exp}} > 0$. Thus, an increase in θ leads to an increase in $\pi^{*,\text{exp}}$ in the exponential case. If $\gamma > 1$, then an increase in θ leads to an increase in $\pi^{*,\text{pow}}$ in the power case.

Case 2: $0 < \theta < 1, \gamma < 0$. In this case, we can check that $\pi_{\theta}^{*,\text{exp}} < 0$. That is, an increase in θ leads to a decrease in $\pi^{*,\text{exp}}$.

Case 3: $-1 \leq \theta < 0, \gamma > 0$. Assume further that $\mu > 0$. Hence, since $\varphi > 0$, then $\pi_{\theta}^{*,\text{exp}} > 0$. Thus, an increase in θ leads to an increase in $\pi^{*,\text{exp}} > 0$. If $\gamma > 1$, then an increase in θ leads to an increase in $\pi^{*,\text{pow}} > 0$.

4.5.3 The effects of personal risk tolerance

We will analyze some specific cases to see the effects of the risk tolerance parameter γ on the optimal investment strategy π^* in MFG.

Case 1: Suppose there is no relative performance, i.e. $\theta = 0$. In this case, π^* in both exponential and power cases coincide and become

$$\pi^* = \frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2}.$$

Taking the derivative with respect to γ yields

$$\pi_\gamma^* = -\frac{\mu}{\gamma^2} \frac{1}{\sigma^2 + \nu^2},$$

which is negative if $\mu > 0$. This implies that an increase in risk tolerance γ tends to decrease the optimal investment strategy π^* .

Case 2: $\gamma > 0, 0 < \theta \leq 1$. In this case $\pi^* > 0$ in exponential case and $\pi^* > 0$ in power case if $\gamma > 1$. Thus, an increase in γ leads to a decrease in π^* . That means an investor with more risk aversion invests less in the risky asset.

Case 3: $0 < \gamma < 1, 0 < \theta \leq 1$. For the exponential case, the effect of γ on π^* is the same as in Case 2. However, for the power case, π^* can be positive, negative, or zero since the first summand of π^* is positive while the second summand is negative. Consequently, an increase in γ leads to

$$\pi^* = \begin{cases} \text{increases, if } \Delta \left(\frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} \right) > \Delta \left| \theta \left(1 - \frac{1}{\gamma} \right) \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi} \right| \\ \text{decreases, if } \Delta \left(\frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} \right) < \Delta \left| \theta \left(1 - \frac{1}{\gamma} \right) \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi} \right| \\ 0, \quad \text{if } \Delta \left(\frac{\mu}{\gamma} \frac{1}{\sigma^2 + \nu^2} \right) = \Delta \left| \theta \left(1 - \frac{1}{\gamma} \right) \frac{\sigma}{\sigma^2 + \nu^2} \frac{\varphi}{1 - \psi} \right|. \end{cases}$$

4.6 Conclusion

In this paper, each individual agent (or investor) faces the problem of allocating her terminal wealth in a portfolio including one risk-free asset (e.g. government bond) and one individual risky asset (e.g. stock). We model the games with finite and infinite agents, namely n -agent games and MFG, respectively. Each agent has a utility function that belongs to the family of HARA utility functions. The utility function depends on her terminal wealth as well as the average wealth of the population. The games are modeled in the context of the presence of risk-seeking agents and relative performance. We prove that there exists a unique constant Nash equilibrium and constant MFE for the case of strictly concave utility function. For the case of strictly convex utility function, there exists a corner solution for both n -agent and MFG in which risk-seeking agents invest all her asset value on risky asset (e.g. stock)

and invest nothing on riskless asset (e.g. bond). The qualitative effects of personal and market parameters on the optimal investment strategy are discussed deeply.

There are several limitations in this chapter which pay ways for future research. First, all personal and market parameters in this chapter are constant over time, one might assume these parameters vary over time. Some parameters depend on time imply that Nash equilibrium or MFE also depend on time rather than constant as in this chapter. Second, this study assumes that each individual investor only invests in one individual stock, which is not always the case in the real world. One might relax this assumption to allow each individual investor to invest in more than one stocks. Third, the setting in this study is the perfect market with no frictions (e.g. transaction costs, and borrowing and lending), one might take one or some frictions into account to make models more realistic. Fourth, this study only constructs and solves an investment-only problem, one might model and tackle an investment-consumption problem.

Chapter 5

Conclusions

The thesis comprises three essays on business analytics and game theory, with each chapter analyzing a particular type of shock.

Chapter 2 uses machine learning and text mining techniques to quantify natural disaster risk (climate shocks) effects on the US firm's performance. The first goal of this research is to create a new dictionary of terms associated with natural hazards and disasters. Text mining is used to determine how many of these words appear in Form 10-Ks. This information is then used to create an indicator of the perceived risk of natural disasters, which is combined with data on government-reported damages and other factors to investigate how natural disasters impact the performance of US firms between 1993 and 2021. The study reveals that self-reported perceived risk and government-reported damages of natural disasters in the current year are both linked to reduced profitability in the following year but have no impact on sales growth or Tobin's Q ratio. The services sector is more heavily impacted than the manufacturing sector. Additionally, there is a lag effect on profitability in the services sector related to the perceived risk of natural disasters but not for government-reported damages. The study suggests that CART and neural networks are better than linear regression for predicting firm performance during natural disasters. Ultimately, the study indicates that information from financial reports, such as Form 10-K filings, can be used to evaluate the perceived risk of natural disasters and predict their effects on firm performance, particularly profitability.

Chapter 3 explores firms as microeconomic agents regarding bankruptcy/financial distress probability prediction under periods with good and bad years (i.e., years with economic shocks). In particular, this study compares the effectiveness of three different models - accounting-based, market-based, and machine-learning - in predicting financial distress in Vietnam, a transition economy. The findings indicate that although all models perform reasonably well in predicting outcomes for companies that have not been delisted, they struggle to do so for delisted companies. The study also demonstrates that models combining variables from Altman's and Ohlson's approaches perform better than those using only one set of variables, as measured by balanced accuracy. Furthermore, the study

shows that neural networks are consistently the most effective models based on balanced accuracy and Matthews correlation coefficient. Among Altman's variables, the **reat** variable (retained earnings over total assets) is the most important, while **ltat** (total liabilities over total assets) and **wcapat** (working capital over total assets) are the most significant in Ohlson's variables. The study also reveals that the models are generally more effective at predicting outcomes for large companies than for small ones, and their performance tends to be better in good years than in bad ones, based on Matthews correlation coefficient (MCC).

Chapter 4 examines the allocation of wealth in portfolios with potential Brownian motions (as stochastic shocks) consisting of a risk-free asset, such as a government bond, and a single risky asset, like a stock. Each investor is considered an individual agent and must determine how to allocate their terminal wealth in this portfolio. The paper models two types of games: n -agent games and mean field games, each with a different number of players. The agents in these games have hyperbolic absolute risk aversion (HARA) utility functions that depend on their terminal wealth and the average wealth of the population. This chapter demonstrates that when the utility function is strictly concave, both the n -agent and mean field games have only one Nash equilibrium and one mean field equilibrium. On the other hand, when the utility function is strictly convex, a distinct corner solution exists in which all agents invest their wealth in risky assets and none in riskless assets. The paper also examines how the optimal investment strategy is affected by personal and market coefficients.

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