

# Spatial heterogeneity of seasonal grazing pressure created by herd movement patterns on hilly rangelands using GPS and GIS

A.I. Arnon<sup>1</sup>, E.D. Ungar<sup>2</sup>, T. Svoray<sup>1</sup>, A. Perevolotsky<sup>2</sup>, M. Shachak<sup>1</sup>, H. Baram<sup>2</sup>, R. Yonatan<sup>2</sup>, E. Ben-Moshe<sup>2</sup>, S. Brenner<sup>2</sup> and D. Barkai<sup>2</sup>

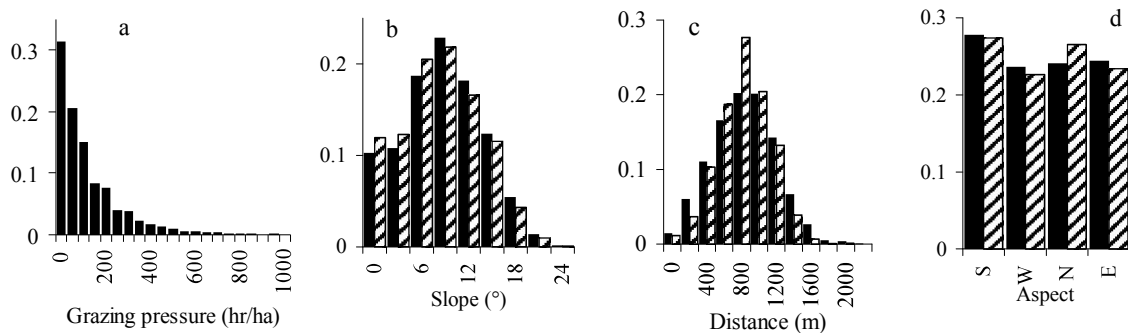
<sup>1</sup>Ben-Gurion University of the Negev, POB 653 Beer-Sheva, 84105 Israel, Email: amirisra@bgumail.bgu.ac.il, <sup>2</sup>Department of Agronomy and Natural Resources, the Volcani Center, POB 6 Bet Dagan 50250, Israel

**Keywords:** Bedouin, rangeland, heterogeneity, GPS, GIS

**Introduction** The spatial heterogeneity of grazing pressure on extensive rangelands has management implications (Adler *et al.*, 2001) but it has traditionally been difficult to quantify. Combination of technologies based on GPS (Global Positioning System) and GIS (Geographic Information Systems) is a quantum leap in our ability to address this issue. These tools were used to estimate the spatial heterogeneity of grazing pressure at a farm scale, and examine the relation between local landscape features and local grazing pressure.

**Materials and methods** The study site is in the hilly, semi-arid region of Israel (31°20' N 34°45' E), populated by a mixed herd of sheep and goats (400 animals) which is shepherded as a group across the landscape, with a fixed night corral and watering point. The herding route was tracked on 78 days in the green season of 2003 (Feb to June), using a tagged goat, harnessed with a GPS rover unit (Trimble GEII Explorer) that recorded a position every 0.5min. The routes were overlaid on GIS raster layers containing data on abiotic factors, at a resolution of 25x25m/cell. For each GPS location, 25min of animal presence was accrued to each of the 8 closest raster grid cells, based on animal number and the estimated area occupied by the stationary herd.

**Results** The area available to the herd was 9648 raster grid cells (627ha), of which 7312 (457ha) had non-zero animal presence. Average velocity based on adjacent GPS locations was 0.28m/s. The total animal presence time accrued was 65736h, yielding an average of 9h/cell, visited at least once, or 144hr/ha. The frequency distribution of grazing pressure for the area visited (Figure 1a) was highly skewed to the right, with a long tail (not all shown) reaching a maximum of 2000hr/ha. Of the area grazed, 67% was frequented less than the expected mean. Presence was greater on the shallower slopes (<9°) and lower on the steeper slopes (>13°) than expected randomly (Figure 1b). Presence according to distance from the night corral deviated strongly from random, with a strong preference for the 800-1000m category (Figure 1c). Presence according to aspect showed a small increase for North and decrease for East (Figure 1d).



**Figure 1** Frequency distributions of (a) grazing pressure, (b) slope, (c) distance from night corral, (d) aspect. Y axis is relative proportion of observations. In (b), (c) and (d), black = landscape, striped = animal presence

**Conclusions** Using GPS and GIS, it is feasible to map and analyse the cumulative seasonal grazing pressure imposed by a herd over an entire grazing season. These tools also enable expected spatial distributions for null hypotheses to be computed that are site-specific. The observed spatial use deviated strongly from random or highly systematic patterns. Statistical analyses of observed versus expected distributions are planned using filtered data sets to reduce autocorrelation.

## References

Adler, P. B., D. A. Raff & W. K. Lauenroth (2001) The effect of grazing on the spatial heterogeneity of vegetation. *Oecologia*, 128, 465-479.