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Prony's method on the sphere

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Abstract. Eigenvalue analysis based methods are well suited for the reconstruction of finitely supported measures from their moments up to a certain degree. We give a precise description when Prony's method succeeds in terms of an interpolation condition. In particular, this allows for the unique reconstruction of a measure from its trigonometric moments whenever its support is separated and also for the reconstruction of a measure on the unit sphere from its moments with respect to spherical harmonics. Both results hold in arbitrary dimensions and also yield a certificate for popular semidefinite relaxations of these reconstruction problems in the nonnegative case.

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1. Introduction

Prony's method [36], see also e.g. [35, 33], reconstructs the coefficients and distinct parameters $\hat{f}_j, x_j \in \mathbb{C}$, $j = 1, \ldots, M$, of the Dirac ensemble $\mu = \sum_{j=1}^M \hat{f}_j \delta_{x_j}$ from the 2M + 1 moments

$$f(k) = \int_{\mathbb{C}} x^k \mathrm{d}\mu(x) = \sum_{j=1}^M \hat{f}_j x_j^k, \quad k = 0, \dots, 2M.$$

The computation of the parameters x_j is done by setting up a certain Hankel or Toeplitz matrix of these moments and computing the roots of the polynomial with the monomial coefficients given by any non-zero kernel vector of this matrix. Afterwards, the coefficients \hat{f}_j can be computed by solving a Vandermonde linear system of equations.

This prototypical algorithm has been generalized to the multivariate case by realizing the parameters as common roots of *d*-variate polynomials belonging to the kernel of a certain multilevel Hankel or Toeplitz matrix [23, 37, 30]. In the present paper, we give a precise description when the parameters can be identified in terms of a simple interpolation condition, which in turn is equivalent to the surjectivity of a certain evaluation homomorphism and also to the full rank of a certain Vandermonde matrix. Since identifiability also implies full rank of a slightly larger Vandermonde matrix, we end up with a variant of the so-called flat extension property [10, 26]. Beyond this, our characterization with respect to the Vandermonde matrix allows to derive simple geometric conditions on the parameters: given the order of the moments is bounded from below by some explicit constant divided by the

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separation distance of the parameters, unique reconstruction is guaranteed. In particular, we get rid of the commonly stated technical condition that the order has to be larger than the number of parameters [41, 39, 11, 12, 23] and weaken the 'coordinate wise' separation condition as used in [27] to a truly multivariate separation condition. This can be understood as an sampling theorem for multivariate signals of finite rate of innovation. Moreover, studying the Vandermonde-like factorization of the Hankel-like matrix of moments allows for a transparent generalization to Dirac ensembles on the sphere where only moments with respect to the spherical harmonics are used for reconstruction.

Recently, the considered problem has also been studied as a constrained total variation minimization problem on the space of measures and attracted quite some attention, see e.g. [13, 7, 6, 8, 14, 5, 4, 16] and references therein. As a corollary to our results, we give a painless construction of a so-called dual certificate for the *nonnegative* total variation minimization problem on the *d*-dimensional torus and on the *d*-dimensional sphere. In this nonnegative case, explicit constructions have been known for orders larger than the number of parameters, see e.g. [5, Eq. (5.8)], and this is again weakened by our result. Recently, also the real signed case has been tackled by a Prony-type construction in [18, Lemma 3.3] but uses a polynomial degree which is an order of magnitude larger. We finally close by two small numerical examples, postpone a detailed study of stability and computational times to a future exposition, and give a short summary.

2. Preliminaries

Throughout the paper, \mathbb{K} denotes a field and $d \in \mathbb{N}$ denotes a natural number. For $x \in \mathbb{K}^d$, $k \in \mathbb{N}_0^d$, we use the multi-index notation $x^k := x_1^{k_1} \cdots x_d^{k_d}$. We start by defining the object of our interest, that is, multivariate exponential sums, as a natural generalization of univariate exponential sums.

Definition 2.1. A function $f: \mathbb{N}_0^d \to \mathbb{K}$ is a *d*-variate exponential sum if there are $M \in \mathbb{N}, \hat{f}_1, \ldots, \hat{f}_M \in \mathbb{K}$, and pairwise distinct $x_1, \ldots, x_M \in \mathbb{K}^d$ such that we have

$$f(k) = \sum_{j=1}^{M} \hat{f}_j x_j^k$$

for all $k \in \mathbb{N}_0^d$. In that case M, \hat{f}_j , and x_j , $j = 1, \ldots, M$, are uniquely determined, and f is called *M*-sparse, the \hat{f}_j are called *coefficients* of f, and x_j are called *parameters* of f. The set of parameters of f is denoted by $\Omega = \Omega_f := \{x_j : j = 1, \ldots, M\}$.

Let $f: \mathbb{N}_0^d \to \mathbb{K}$ be an *M*-sparse *d*-variate exponential sum with coefficients $\hat{f}_j \in \mathbb{K}$ and parameters $x_j \in \mathbb{K}^d$, $j = 1, \ldots, M$. Our objective is to reconstruct the coefficients and parameters of f given a finite set of samples of f at a subset of \mathbb{N}_0^d , see also [32].

The following notations will be used throughout the paper. For $k, n \in \mathbb{N}_0^d$ let $|k| = \sum_{j=1}^d k_j$ and $N := \binom{n+d}{d}$. The matrix

$$H_n := H_n(f) := (f(k+\ell))_{k,\ell \in \mathbb{N}_0^d, |k|, |\ell| \le n} \in \mathbb{K}^{N \times N}$$

will play a crucial role in the multivariate Prony method. Note that its entries are sampling values of f at a grid of $\binom{2n+d}{d}$ integer points and that it is a sub-matrix of the multilevel Hankel matrix $(f(k+\ell))_{k,\ell\in\{0,\dots,n\}^d}$.

Next we establish the crucial link between the matrix H_n and the roots of multivariate polynomials. To this end, let $\Pi := \mathbb{K}[X_1, \ldots, X_d]$ denote the \mathbb{K} -algebra of *d*-variate polynomials over \mathbb{K} and for $p = \sum_k p_k X_1^{k_1} \cdots X_d^{k_d} \in \Pi \setminus \{0\}$ let $\deg(p) := \max\{|k| : p_k \neq 0\}$. The *N*-dimensional sub-vector space of *d*-variate polynomials of degree at most *n* is

$$\Pi_n := \{ p \in \Pi \setminus \{0\} : \deg(p) \le n \} \cup \{0\}.$$

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For arbitrary $V \subset \mathbb{K}^d$, the evaluation homomorphism at V will be denoted by

$$\mathcal{A}^V \colon \Pi \to \mathbb{K}^V, \quad p \mapsto (p(x))_{x \in V},$$

and its restriction to the sub-vector space $\Pi_n \subset \Pi$ will be denoted by \mathcal{A}_n^V . Note that the representation matrix of $\mathcal{A}_n = \mathcal{A}_n^{\Omega}$ with $\Omega = \{x_1, \ldots, x_M\}$ w.r.t. the canonical basis of \mathbb{K}^M and the monomial basis of Π_n is given by the multivariate Vandermonde matrix

$$A_n = (x_j^k)_{\substack{j=1,\dots,M\\k\in\mathbb{N}_0^d, |k|\leq n}} \in \mathbb{K}^{M\times N}$$

The connection between the matrix H_n and polynomials that vanish on Ω lies in the observation that, using Definition 2.1, the matrix H_n admits the factorization

$$H_n = (f(k+\ell))_{k,\ell \in \mathbb{N}_0^d, |k|, |\ell| \le n} = A_n^\top D A_n,$$
(2.1)

with $D = \text{diag}(\hat{f}_1, \ldots, \hat{f}_M)$. Therefore the kernel of A_n , corresponding to the polynomials in Π_n that vanish on Ω , is a subset of the kernel of H_n .

In order to deal with the multivariate polynomials encountered in this way we need some additional notation. The *zero locus* of a set $P \subset \Pi$ of polynomials is denoted by

$$\mathcal{V}(P) := \{ x \in \mathbb{K}^d : p(x) = 0 \text{ for all } p \in P \},\$$

that is, $\mathcal{V}(P)$ consists of the *common* roots of all the polynomials in P. For a set $V \subset \mathbb{K}^d$, the kernel of \mathcal{A}^V (which is an ideal of Π) will be denoted $\mathcal{I}(V)$ and is called the *vanishing ideal* of V; it consists of all polynomials that vanish on V. Further, let $\mathcal{I}_n(V) := \ker \mathcal{A}_n^V = \mathcal{I}(V) \cap \Pi_n$ denote the \mathbb{K} -sub-vector space of polynomials of degree at most n that vanish on V. Subsequently, we identify Π_n and \mathbb{K}^N and switch back and forth between matrix-vector and polynomial notation. In particular, we do not necessarily distinguish between \mathcal{A}_n^{Ω} and its representation matrix A_n , so that e.g. " $\mathcal{V}(\ker A_n)$ " makes sense.

3. Main results

We proceed with a general discussion that the identifiability of the parameters and an interpolation at these parameters are almost equivalent. While this is closely related to the so-called flat extension principle [10, 26], we also give a refinement which is of great use when discussing the moment problem on the sphere. The second and third subsection study the trigonometric moment problem and the moment problem on the unit sphere, respectively. In both cases, appropriate separation conditions guarantee the above mentioned interpolation condition and thus identifiability of the parameters. As a corollary, we give a simple construction of a dual certificate for the nonnegative total variation minimization problem on the *d*-dimensional torus [7, 8] and on the *d*-dimensional sphere [5, 4].

3.1. Interpolation and vanishing ideals

We recall some notions from the theory of Gröbner bases which are needed in this section, see e.g. [3, 20, 9]. A *d*-variate term is a polynomial of the form $X^k = X_1^{k_1} \cdots X_d^{k_d}$ for some $k = (k_1, \ldots, k_d) \in \mathbb{N}_0^d$. The monoid of all *d*-variate terms will be denoted $\mathcal{M} := \{X^k : k \in \mathbb{N}_0^d\}$. A term order on \mathcal{M} is a linear order \leq on \mathcal{M} such that $1 \leq t$ for all $t \in \mathcal{M}$ and $t_1 \leq t_2$ implies $t_1 t_3 \leq t_2 t_3$ for all $t_1, t_2, t_3 \in \mathcal{M}$. For a polynomial $p = \sum_k p_k X^k \in \Pi \setminus \{0\}$ let $\operatorname{lt}_{\leq}(p) := \max_{\leq} \{X^k : p_k \neq 0\}$ and for an ideal $I \neq \{0\}$ of Π let $\operatorname{lt}_{\leq}(I) := \{\operatorname{lt}_{\leq}(p) : p \in I \setminus \{0\}\}$. The set $\mathcal{N}_{\leq}(I) := \mathcal{M} \setminus \operatorname{lt}_{\leq}(I)$ is called normal set of I. A term order \leq is degree compatible if $t_1 \leq t_2$ implies $\operatorname{deg}(t_1) \leq \operatorname{deg}(t_2)$, or equivalently, if $\operatorname{deg}(p) = \operatorname{deg}(\operatorname{lt}_{\leq}(p))$ for all $p \in \Pi \setminus \{0\}$. **Lemma 3.1** (see e.g. [15, Prop. 2]). Let \leq be a term order on \mathcal{M} . If I is an ideal of Π and $t \in \mathcal{N}_{\leq}(I)$, then t is the least element of $M_t := \{ \operatorname{lt}(p) : p \in \Pi \setminus \{0\}, \overline{p} = \overline{t} \text{ in } \Pi/I \}.$

Proof. Since $\operatorname{lt}(t) = t$, we have $t \in M_t$. Let $p \in \Pi \setminus \{0\}$ with $\overline{p} = \overline{t}$ in Π/I . We have to show $t \leq \operatorname{lt}(p)$. Without loss of generality we can assume $p \neq t$. Thus let $t - p = \sum_k c_k X^k \neq 0$ with $c_k \in \mathbb{K}$ and $X^m = \operatorname{lt}(t - p)$.

Case 1: For every $k, t \neq c_k X^k$. Then, since $p = t - \sum_k c_k X^k$, we have $t \leq \operatorname{lt}(p)$.

Case 2: There is a k such that $t = c_k X^k$. Then $c_k = 1$ and we have $t = X^k \leq X^m$ and since $t \in \mathcal{N}(I) = \mathcal{M} \setminus \operatorname{lt}(I)$ and $X^m = \operatorname{lt}(t-p) \in \operatorname{lt}(I)$, we have $t < X^m$. Therefore we have $t < X^m = \operatorname{lt}(t - \sum_k c_k X^k) = \operatorname{lt}(p)$.

Lemma 3.2. Let \leq be a degree compatible term order on \mathcal{M} . Let $\Omega \subset \mathbb{K}^d$ be finite and $n \in \mathbb{N}_0$ such that the evaluation homomorphism $\mathcal{A}_n^{\Omega} \colon \Pi_n \to \mathbb{K}^{\Omega}$ is surjective. Then $\mathcal{N}_{\leq}(\mathcal{I}(\Omega)) \subset \Pi_n$.

Proof. Since Ω is finite, $\mathcal{I}(\Omega) \neq \{0\}$. Let $t \in \mathcal{N}(\mathcal{I}(\Omega))$ and consider \overline{t} in $\Pi/\mathcal{I}(\Omega)$. Since $\mathcal{I}(\Omega) = \bigcap_{a \in \Omega} \mathcal{I}(a)$ and $\mathcal{I}(a)$, $a \in \Omega$, are pairwise co-prime, by the Chinese remainder theorem $\varphi \colon \Pi/\mathcal{I}(\Omega) \to \mathbb{K}^{\Omega}$, $\overline{p} \mapsto (p(a))_{a \in \Omega}$, is a bijection. Since $\mathcal{A}_n^{\Omega} \colon \Pi_n \to \mathbb{K}^{\Omega}$ is surjective, there is a $p \in \Pi_n$ with $\varphi(\overline{t}) = \mathcal{A}_n^{\Omega}(p) = (p(a))_{a \in \Omega} = \varphi(\overline{p})$, hence $\overline{p} = \overline{t}$. Since $t \notin \mathcal{I}(\Omega)$, in particular $p \neq 0$. Thus Lemma 3.1 together with the degree compatibility of \leq implies

 $\deg(t) = \deg(\min \{ \operatorname{lt} q : q \neq 0, \, \overline{q} = \overline{t} \text{ in } \Pi/\mathcal{I}(\Omega) \}) = \min \{ \operatorname{deg}(\operatorname{lt} q) : \overline{q} = \overline{t} \} \leq \operatorname{deg}(p) \leq n,$ i.e. $t \in \Pi_n$.

Theorem 3.3. Let $\emptyset \neq \Omega \subset \mathbb{K}^d$ be finite and $n \in \mathbb{N}_0$ such that $\mathcal{A}_n^{\Omega} \colon \Pi_n \to \mathbb{K}^{\Omega}$ is surjective. Then $\langle \mathcal{I}_{n+1}(\Omega) \rangle = \mathcal{I}(\Omega)$ and thus $\Omega = \mathcal{V}(\mathcal{I}_{n+1}(\Omega))$.

Proof. Let \leq be a degree compatible term order on \mathcal{M} and let

 $P := \{ t \in \operatorname{lt}(\mathcal{I}(\Omega)) : t \mid \text{-minimal in } \operatorname{lt}(\mathcal{I}(\Omega)) \}.$

We show that $P \subset \Pi_{n+1}$. Let $t \in P$. Since $\Omega \neq \emptyset$, $t \neq 1$. Thus $t = X_j t'$ for some $j \in \{1, \ldots, d\}$ and $t' \in \mathcal{M}$. By |-minimality of t in $\operatorname{lt}(\mathcal{I}(\Omega))$, we have $t' \notin \operatorname{lt}(\mathcal{I}(\Omega))$. Thus $t' \in \mathcal{N}(\mathcal{I}(\Omega))$ which implies $\operatorname{deg}(t') \leq n$ by Lemma 3.2 and hence $\operatorname{deg}(t) = \operatorname{deg}(X_j t') = \operatorname{deg}(X_j) + \operatorname{deg}(t') \leq n+1$, i.e. $t \in \Pi_{n+1}$. By Dickson's lemma (cf. [3, Thm. 5.2 and Cor. 4.43]), P is finite. Thus let $P = \{t_1, \ldots, t_r\}$ with pairwise different t_j and $g_1, \ldots, g_r \in \mathcal{I}(\Omega)$ with $\operatorname{lt} g_j = t_j$. Then $G = \{g_1, \ldots, g_r\}$ is a (Gröbner) basis for $\mathcal{I}(\Omega)$ (see e.g. Becker-Weispfenning [3, Prop. 5.38 (iv)]) and $\operatorname{deg}(g_j) = \operatorname{deg}(\operatorname{lt} g_j) = \operatorname{deg}(t_j) \leq n+1$, i.e. $G \subset \mathcal{I}_{n+1}(\Omega)$. In particular $\Omega \subset \mathcal{V}(\mathcal{I}_{n+1}(\Omega)) \subset \mathcal{V}(G) = \mathcal{V}(\langle G \rangle) = \mathcal{V}(\mathcal{I}(\Omega)) = \Omega$, since Ω is finite (as usual, $\langle G \rangle$ denotes the ideal generated by G).

Remark 3.4. In summary, for every subset $\Omega \subset \mathbb{K}^d$ with $|\Omega| = M \in \mathbb{N}$ we have the chain of implications

$$\operatorname{rank} \mathcal{A}_n^{\Omega} = M \quad \Rightarrow \quad \Omega = \mathcal{V}(\mathcal{I}_{n+1}(\Omega)) \quad \Rightarrow \quad \operatorname{rank} \mathcal{A}_{n+1}^{\Omega} = M,$$

where the second implication follows as in the proof of [23, Thm. 3.1]. Moreover note that the factorization (2.1) and Frobenius' rank inequality [17, 0.4.5 (e)] implies

$$2\operatorname{rank} \mathcal{A}_n^{\Omega} \leq \operatorname{rank} H_n + M \leq \operatorname{rank} \mathcal{A}_n^{\Omega} + M, \quad n \in \mathbb{N},$$

and thus the equivalence

$$\operatorname{rank} H_n = \operatorname{rank} H_{n+1} = M \quad \Leftrightarrow \quad \operatorname{rank} \mathcal{A}_n^\Omega = M,$$

where the left hand side is exactly the flat extension principle [10, 26]. We would like to note that considering \mathcal{A}_n allows for signed measures and yields simple *a-priori* conditions on the order of the

moments, see Lemmata 3.9 and 3.13, while the flat extension principle rank $H_n = \operatorname{rank} H_{n+1}$ can be used *a-posteriori* as a necessary condition when attempting to guess the (possibly unknown) number M of parameters.

In order to give a slight refinement of Theorem 3.3 in Corollary 3.6 we need the following notation. For a set $V \subset \mathbb{K}^d$ let $\Pi_V := \Pi/\mathcal{I}(V)$ and $\Pi_{V,n} := \Pi_n/\mathcal{I}_n(V)$. The map $\Pi_V \to \{p_{|V} : p \in \Pi\}$, $p + \mathcal{I}(V) \mapsto p_{|V}$, (where we use the same notation for a polynomial $p \in \Pi$ and its induced polynomial function $p \colon \mathbb{K}^d \to \mathbb{K}$) is a ring isomorphism. Thus we may identify the residue class $\overline{p} = p + \mathcal{I}(V)$ of $p \in \Pi$ with the function $p_{|V} \colon V \to \mathbb{K}$. Since the \mathbb{K} -vector space homomorphism $\Pi_n \to \Pi_V, p \mapsto \overline{p}$, has $\mathcal{I}_n(V)$ as its kernel, $\Pi_{V,n}$ is embedded in Π_V . The \mathbb{K} -vector space $\Pi_{V,n}$ is isomorphic to $\{p_{|V} : p \in \Pi_n\}$ by mapping $p + \mathcal{I}_n(V)$ with $p \in \Pi_n$ to $p_{|V}$. For $\Omega \subset V$ let $\mathcal{A}_V^{\Omega} \colon \Pi_V \to \mathbb{K}^{\Omega}, \ \overline{p} \mapsto \mathcal{A}^{\Omega}(p)$, which is well-defined by the above, and let $\mathcal{A}_{V,n}^{\Omega}$ denote the restriction of \mathcal{A}_V^{Ω} to the \mathbb{K} -sub-vector space $\Pi_{V,n}$ of Π_V . Further let $\mathcal{I}_{V,n}(\Omega) := \ker \mathcal{A}_{V,n}^{\Omega}$. For a set $Q \subset \Pi_V$ let $\mathcal{V}_V(Q) := \{a \in V : \overline{q}(a) = 0$ for all $\overline{q} \in Q\}$.

Lemma 3.5. Let $V \subset \mathbb{K}^d$, $\Omega \subset V$ and $n \in \mathbb{N}_0$. Then we have

$$\Omega \subset \mathcal{V}_V(\mathcal{I}_{V,n}(\Omega)) \subset \mathcal{V}(\mathcal{I}_n(\Omega)).$$

Proof. The first inclusion is clear. To prove the second inclusion, let $a \in \mathcal{V}_V(\mathcal{I}_{V,n}(\Omega))$ and $p \in \mathcal{I}_n(\Omega) = \ker \mathcal{A}_n^{\Omega}$. We have to show that p(a) = 0. Let $\overline{p} := p + \mathcal{I}_n(V)$. Since $p \in \prod_n, \overline{p} \in \prod_n/\mathcal{I}_n(V) = \prod_{V,n}$ and we have $\mathcal{A}_{V,n}^{\Omega}(\overline{p}) = \mathcal{A}_V^{\Omega}(\overline{p}) = \mathcal{A}^{\Omega}(p) = 0$, i.e. $\overline{p} \in \ker \mathcal{A}_{V,n}^{\Omega} = \mathcal{I}_{V,n}(\Omega)$. Since $a \in \mathcal{V}_V(\mathcal{I}_{V,n}(\Omega))$, that is, $a \in \mathcal{V}$ and $\overline{q}(a) = 0$ for all $\overline{q} \in \mathcal{I}_{V,n}(\Omega)$, it follows that $p(a) = \overline{p}(a) = 0$.

Combining this with Theorem 3.3 yields the following.

Corollary 3.6. Let $V \subset \mathbb{K}^d$, Ω be a non-empty finite subset of V and $n \in \mathbb{N}_0$ such that $\mathcal{A}_{V,n}^{\Omega}$ is surjective. Then

$$\Omega = \mathcal{V}_V(\mathcal{I}_{V,n+1}(\Omega)).$$

Proof. Since $\mathcal{A}_{V,n}^{\Omega}$: $\Pi_{V,n} \to \mathbb{K}^{\Omega}$ is surjective, \mathcal{A}_{n}^{Ω} : $\Pi_{n} \to \mathbb{K}^{\Omega}$ is clearly also surjective. Hence we can apply Theorem 3.3 which together with Lemma 3.5 yields $\Omega \subset \mathcal{V}_{V}(\mathcal{I}_{V,n+1}(\Omega)) \subset \mathcal{V}(\mathcal{I}_{n+1}(\Omega)) = \Omega$.

3.2. Trigonometric polynomials and parameters on the torus

Now let $\mathbb{K} = \mathbb{C}$ and restrict to parameters on the *d*-dimensional torus $\mathbb{T}^d := \{z \in \mathbb{C} : |z| = 1\}^d$ with parameterization $\mathbb{T}^d \ni z = e^{2\pi i t}$ for a unique $t \in [0, 1)^d$. Now, let $M \in \mathbb{N}$, coefficients $\hat{f}_j \in \mathbb{C} \setminus \{0\}$, and pairwise distinct $t_j \in [0, 1)^d$, $j = 1, \ldots, M$, be given. Then the trigonometric moment sequence of the complex Dirac ensemble $\tau : \mathcal{P}([0, 1)^d) \to \mathbb{C}, \tau = \sum_{j=1}^M \hat{f}_j \delta_{t_j}$, is the *d*-variate exponential sum

$$f: \mathbb{Z}^d \to \mathbb{C}, \quad k \mapsto \int_{[0,1)^d} e^{2\pi i k t} d\tau(t) = \sum_{j=1}^M \hat{f}_j e^{2\pi i k t_j},$$

with parameters $e^{2\pi i t_j} = (e^{2\pi i t_{j,1}}, \dots, e^{2\pi i t_{j,d}}) \in \mathbb{T}^d$.

A convenient choice for the truncation of this sequence is $|k|_{\infty} = \max\{|k_1|, \ldots, |k_d|\} \le n$. We define the multivariate Vandermonde matrix a.k.a. nonequispaced Fourier matrix

$$F_n := \left(e^{2\pi i k t_j} \right)_{\substack{j=1,\dots,M\\k\in\mathbb{N}_0^d, |k|_\infty \le n}} \in \mathbb{C}^{M\times(n+1)^d}$$

Lemma 3.7. Let $\Omega := \{e^{2\pi i t_j} : t_j \in [0,1)^d, j = 1, \ldots, M\} \subset \mathbb{T}^d$ and $n \in \mathbb{N}_0$ such that F_n has full rank M, then $\Omega = \mathcal{V}(\ker F_{dn+1})$.

Proof. First note that $\{k \in \mathbb{N}_0^d : |k|_{\infty} \leq n\} \subset \{k \in \mathbb{N}_0^d : |k| \leq dn\}$ and thus $\mathcal{A}_{dn}^{\Omega}$ is surjective and Theorem 3.3 yields $\Omega = \mathcal{V}(\ker \mathcal{A}_{dn+1}^{\Omega})$. Finally note that $\{k \in \mathbb{N}_0^d : |k| \leq dn+1\} \subset \{k \in \mathbb{N}_0^d : |k|_{\infty} \leq dn+1\}$ and thus the result follows from $\mathcal{V}(\ker \mathcal{A}_{dn+1}^{\Omega}) \supset \mathcal{V}(\ker F_{dn+1})$.

Remark 3.8. It is tempting to try to prove Lemma 3.7 with n + 1 instead of dn + 1 analogously to Theorem 3.3 by using "maxdeg-compatible" term orders instead of degree compatible term orders. However, for $d \ge 2$ there are no such term orders. To see this, let \le be a term order on \mathcal{M} and w.l.o.g. let $X_2 \le X_1$. Then $X_2^2 \le X_1 X_2$ and $\max \deg(X_2^2) = 2 > 1 = \max \deg(X_1 X_2)$. Moreover note that Lemma 3.7 can be strengthened to $\mathcal{I}(\Omega) = \langle \mathcal{I}_{dn+1}(\Omega) \rangle$ and while the direct

Moreover note that Lemma 3.7 can be strengthened to $\mathcal{I}(\Omega) = \langle \mathcal{I}_{dn+1}(\Omega) \rangle$ and while the direct argument [22, Thm. 2.8] gives $\Omega = \mathcal{V}(\mathcal{I}_{n+1}(\Omega))$, it is not clear to the authors if $\langle \mathcal{I}_{n+1}(\Omega) \rangle$ is radical and thus $\mathcal{I}(\Omega) = \langle \mathcal{I}_{n+1}(\Omega) \rangle$, see also [25, Rem. 1.8 und Ex. 3.7(b)].

Lemma 3.9 ([34, Lem. 3.1]). For $\Omega := \{e^{2\pi i t_j} : t_j \in [0, 1)^d, j = 1, \dots, M\} \subset \mathbb{T}^d$ let

$$\operatorname{sep}(\Omega) := \min_{r \in \mathbb{Z}^d, \ j \neq \ell} \| t_j - t_\ell + r \|_{\infty}$$

denote the separation distance and call the set of parameters q-separated if $sep(\Omega) > q$. Now if $n \in \mathbb{N}_0$ fulfills $n > \sqrt{d}/q$, then the matrix $F_n \in \mathbb{C}^{M \times (n+1)^d}$ has full rank M.

Remark 3.10. The semi-discrete Ingham inequality [19, Ch. 8] has been made fully discrete in [34, Lem. 3.1]. Equivalent results are given in [2, 24] as condition number estimates for Vandermonde matrices. More recently, a sharp condition number estimate for the univariate case d = 1 has been proven in [29], a multivariate generalization under 'coordinate wise separation' has been given in [27], and an improvement for $d \ge 6$ of Lemma 3.9 is available in [22].

Theorem 3.11. Let $f: \mathbb{Z}^d \to \mathbb{C}$ be an *M*-sparse *d*-variate exponential sum with parameters $x_j \in \mathbb{T}^d$, $j = 1, \ldots, M$. If the parameters are *q*-separated and $n > d^{3/2}/q + d + 1$, then

$$\Omega = \mathcal{V}(\ker T_n),$$

where the entries of the matrix are given by trigonometric moments of order up to n, i.e.,

$$T_n = (f(k-\ell))_{k,\ell \in \{0,\dots,n\}^d} \in \mathbb{C}^{(n+1)^d \times (n+1)^d}.$$

Proof. Setting $n_0 := \lfloor (n-1)/d \rfloor$ yields $n_0 > \sqrt{d}/q$ and Lemma 3.9 implies full rank of F_{n_0} . Thus $\Omega = \mathcal{V}(\ker F_n)$ is guaranteed by Lemma 3.7 and the factorization

$$T_n = F_n^* D F_n, \quad D = \operatorname{diag}(\hat{f}_1, \dots, \hat{f}_M)$$

being a variant of (2.1), together with the Frobenius' rank inequality [17, 0.4.5 (e)] $M = \operatorname{rank} E^* D$ | rank DE = rank $D \in \operatorname{rank} T \in \operatorname{rank} E = M$

 $M = \operatorname{rank} F_n^* D + \operatorname{rank} DF_n - \operatorname{rank} D \le \operatorname{rank} T_n \le \operatorname{rank} F_n = M,$

implies ker $F_n = \ker T_n$ from which the assertion follows.

This improves over [23, Thm. 3.1, 3.7] by getting rid of the technical condition $n \ge M$ and thus the number of used moments can be bounded from above by $(n+1)^d \le C_d M$ if the parameters are quasi-uniformly distributed. Finally, note that the sum of squares representation [23, Thm. 3.5] implies that $n > d^{3/2}/q + d + 1$ suffices that the semidefinite program in [8] indeed solves the total variation minimization problem for nonnegative measures in all dimensions d. In particular, this gives a sharp constant in [8, Thm. 1.2] and bypasses the relaxation from a nonnegative trigonometric polynomial to the sum of squares representation, known to possibly increase degrees for d = 2 and to possibly fail

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for d > 2, cf. [13, Remark 4.17, Theorem 4.24, and Remark 4.26]. Recently, also the real signed case been tackled in [18, Lemma 3.3] but requires $n > CM^2$.

3.3. Spherical harmonics and parameters on the sphere

Now let $\mathbb{K} = \mathbb{R}$, restrict to parameters on the unit sphere $\mathbb{S}^{d-1} = \{x \in \mathbb{R}^d : x^\top x = 1\} = \mathcal{V}(1 - \sum_{j=1}^d X_j^2)$ in the *d*-dimensional Euclidean space, and we refer to [31, 40, 1] for an introduction to approximation on the sphere and spherical harmonics. The polynomials in *d* variables of degree up to *n* restricted to the sphere can be decomposed into mutually orthogonal spaces

$$\Pi_n / \mathcal{I}_n(\mathbb{S}^{d-1}) = \bigoplus_{k=0}^n H_k^d$$

of real spherical harmonics of degree $k \in \mathbb{N}_0$ and we let $\{Y_k^{\ell} : \mathbb{S}^{d-1} \to \mathbb{C} : \ell = 1, \dots, \dim(H_k^d)\}$ denote an orthonormal basis for each H_k^d . The dimension of these spaces obeys $N_k := \dim(H_k^d) = (2k+d-2)\Gamma(k+d-2)/(\Gamma(k+1)\Gamma(d-1))$ for $k \ge 1$ and we let $N := \sum_{k=0}^n N_k = \mathcal{O}(n^{d-1})$ denote the dimension of $\prod_n / \mathcal{I}_n(\mathbb{S}^{d-1})$.

Now let $M \in \mathbb{N}$, coefficients $\hat{f}_j \in \mathbb{R} \setminus \{0\}$, and pairwise distinct $x_j \in \mathbb{S}^{d-1}$, $j = 1, \ldots, M$, be given. Then the moment sequence of the signed Dirac ensemble $\mu : \mathcal{P}(\mathbb{S}^{d-1}) \to \mathbb{R}$, $\mu = \sum_{j=1}^{M} \hat{f}_j \delta_{x_j}$, is the spherical harmonic sum

$$f: \{(k,\ell): k \in \mathbb{N}_0, \ell = 1, \dots, N_k\} \to \mathbb{R}, \quad (k,\ell) \mapsto \int_{\mathbb{S}^{d-1}} Y_k^\ell(x) \mathrm{d}\mu(x) = \sum_{j=1}^M \hat{f}_j Y_k^\ell(x_j),$$

with parameters $x_j \in \mathbb{S}^{d-1}$. Finally, we define the multivariate Vandermonde matrix a.k.a. nonequispaced spherical Fourier matrix

$$Y_n := \left(Y_k^{\ell}(x_j)\right)_{\substack{j=1,\dots,M\\k\in\mathbb{N}_0,k\leq n,\ell=1,\dots,N_k}} \in \mathbb{R}^{M\times N}$$

Regarding the reconstruction of the measure from its first moments, we have the following results.

Lemma 3.12. Let $\Omega := \{x_j : j = 1, ..., M\} \subset \mathbb{S}^{d-1}$ and $n \in \mathbb{N}_0$ such that Y_n has full rank M, then $\Omega = \mathcal{V}_{\mathbb{S}^{d-1}}(\ker Y_{n+1}).$

Proof. Note that $Y_n \in \mathbb{R}^{M \times N}$ is the matrix of the \mathbb{R} -linear map $\mathcal{A}_{\mathbb{S}^{d-1},n}^{\Omega} \colon \Pi_{\mathbb{S}^{d-1},n} \to \mathbb{R}^{\Omega} \cong \mathbb{R}^{M}$ w.r.t. the basis $\bigcup_{k=0}^{n} \left\{ Y_k^{\ell} : \ell = 1, \ldots, \dim(H_k^d) \right\}$ of $\Pi_{\mathbb{S}^{d-1},n}$ and the canonical basis of \mathbb{R}^M . Since rank $Y_n = M$ by assumption, $\mathcal{A}_{\mathbb{S}^{d-1},n}^{\Omega}$ is surjective and the assertion is an immediate consequence of Corollary 3.6.

Lemma 3.13 ([21, Thm. 2.4], [28, Thm. 1.5]). For $\Omega := \{x_j : j = 1, \dots, M\} \subset \mathbb{S}^{d-1}$ let

$$\operatorname{sep}(\Omega) := \min_{j \neq \ell} \arccos\left(x_j^\top x_\ell\right)$$

denote the separation distance and call the set of parameters q-separated if $sep(\Omega) > q$. Now if $n \in \mathbb{N}_0$ fulfills $n > 2.5\pi d/q$, then the matrix $Y_n \in \mathbb{C}^{M \times N}$ has full rank M.

Theorem 3.14. Let $f: \{(k, \ell) : k \in \mathbb{N}_0, \ell = 1, \dots, N_k\} \to \mathbb{R}$ be an *M*-sparse spherical harmonic sum with parameters $x_j \in \mathbb{S}^{d-1}, j = 1, \dots, M$. If the parameters are q-separated and $n > 2.5\pi d/q + 1$, then

$$\Omega = \mathcal{V}_{\mathbb{S}^{d-1}}(\ker H_n)$$

where the entries of the matrix

$$\tilde{H}_n := Y_n^\top D Y_n \in \mathbb{R}^{N \times N}, \qquad D = \operatorname{diag}(\hat{f}_1, \dots, \hat{f}_M),$$

mimicking (2.1), can be computed solely from the moments $f(k, \ell), k \leq 2n, \ell = 1, \ldots, N_k$.

Proof. We just combine Lemmata 3.12, 3.13, and proceed as in Theorem 3.11 to show ker $\tilde{H}_n = \ker Y_n$. Finally note that $Y_k^{\ell} \cdot Y_r^s = \sum_{t=0}^{k+s} \sum_{u=1}^{N_t} c_{k,r,t}^{\ell,s,u} Y_t^u$ with some Clebsch-Gordan coefficients and thus

$$(\tilde{H}_n)_{(k,\ell),(r,s)} = \sum_{j=1}^M \hat{f}_j Y_k^\ell(x_j) Y_r^s(x_j) = \sum_{t=0}^{k+s} \sum_{u=1}^{N_t} c_{k,r,t}^{\ell,s,u} f(t,u).$$

This improves over [11, 12] by getting rid of the technical condition $n \ge CM$ and by asking only for $n \ge C_d \sqrt[d]{M}$ if the parameters are quasi-uniformly distributed. Finally note that the semidefinite program in [5, 4, 38] indeed solves the total variation minimization problem for nonnegative measures on spheres in all dimensions d provided the order of the moments is large enough as shown by the following construction of a dual certificate and sum of squares representation.

Corollary 3.15. Let $d, n, M \in \mathbb{N}$, $\Omega = \{x_j \in \mathbb{S}^{d-1} : j = 1, ..., M\}$ be q-separated, and $n > 2.5\pi d/q+1$. Moreover, let $\hat{p}_r \in \mathbb{R}^N$, r = 1, ..., N, be an orthonormal basis with $\hat{p}_r \in \ker(Y_n)^{\perp}$, r = 1, ..., M, and $p_r : \mathbb{S}^{d-1} \to \mathbb{R}$, $p_r = \sum_{k=0}^n \sum_{\ell=1}^{N_k} \hat{p}_{r,k}^{\ell} Y_k^{\ell}$, then $p : \mathbb{S}^{d-1} \to \mathbb{R}$,

$$p(x) = \frac{2\pi^{d/2}}{\Gamma(d/2)N} \sum_{r=1}^{M} |p_r(x)|^2,$$

is a polynomial on the sphere of degree at most 2n and fulfills $0 \leq p(x) \leq 1$ for all $x \in \mathbb{S}^d$ and p(x) = 1 if and only if $x \in \Omega$.

Proof. First note that every orthonormal basis $\hat{p}_{\ell} \in \mathbb{R}^N$, $\ell = 1, \ldots, N$, leads to

$$\sum_{r=1}^{N} |p_r(x)|^2 = \sum_{k,u=0}^{n} \sum_{\ell,v=1}^{N_k} Y_k^{\ell}(x) Y_u^{\nu}(x) \sum_{r=1}^{N} \hat{p}_{r,k}^{\ell} \hat{p}_{r,u}^{\nu} = \sum_{k=0}^{n} \sum_{\ell=1}^{N_k} Y_k^{\ell}(x) Y_k^{\ell}(x) = \frac{\Gamma(d/2)N}{2\pi^{d/2}}$$

for $x \in \mathbb{S}^{d-1}$, where the last equality is due to the addition theorem for spherical harmonics and as in the proof of Theorem 3.14, the product $Y_k^{\ell} \cdot Y_k^{\ell}$ always is a polynomial on the sphere of degree at most 2k. Finally, Theorem 3.14 assures $\sum_{r=M+1}^{N} |p_r(x)|^2 = 0$ if and only if $x \in \Omega$.

Regarding the signed case, a detailed analysis for S^2 is given in [38] and requires $n > 20\pi/q$. For general $d \ge 3$, the construction [18, Lemma 3.3] might be used but requires $n \ge CM^2$.

Example 3.16. We conduct the following two small scale numerical examples. For M = 3 points on the unit sphere and a polynomial degree n = 2, we compute the N - M = 6 dimensional kernel of the nonequispaced spherical Fourier matrix Y_n , set up the corresponding kernel polynomials p_r , $r = 4, \ldots, 9$, as defined in Corollary 3.15 and plot the surface $q(x) = 1 + \frac{1}{2} \min_{r=M+1,\ldots,N} |p_r(x)|^{1/4}$, $x \in \mathbb{S}^2$, in Figure 3.1(a). The absolute value of each kernel polynomial forms a valley around its zero set which gets narrowed by the 4-th root and the minimum over all these valleys visualizes the common zeros as junction points in this surface.

In a second experiment, we consider M = 50 random points x_j on the unit sphere, an associated Dirac ensemble with random coefficients \hat{f}_j , and its moments up to order 60, i.e., n = 30. The *M*dimensional orthogonal complement of the kernel of the matrix \tilde{H}_n defines the so-called signal space. Figure 3.1(b) clearly shows that the dual certificate p, defined as in Corollary 3.15, peaks exactly at the points x_j .



(a) Visualization of the polynomials in the kernel of Y_n , M = 3 points, n = 2, plot of the surface $q(x) = 1 + \frac{1}{2} \min_{r=M+1,...,N} |p_r(x)|^{1/4}$, $x \in \mathbb{S}^2$.

(b) M = 50 random points on \mathbb{S}^2 are identified from the moments of order ≤ 60 . The dual certificate p is plotted as surface $1 + \frac{1}{2}p(x), x \in \mathbb{S}^2$.

FIGURE 3.1. Visualization of kernel polynomials and dual certificate on the sphere \mathbb{S}^2 .

4. Summary

We considered a recently developed multivariate generalization of Prony's method, characterized its succeeding in terms of an interpolation condition, and gave a generalization to the sphere. The interpolation condition is shown to hold for separated points in the trigonometric and the spherical case in arbitrary dimensions and also yield a certificate for popular semidefinite relaxations of the reconstruction problems. Beyond the scope of this paper, future research needs to address the actual computation of the points and the stability under noise.

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