

# Sediment Deposition Volume Assessment in Tropical Regions

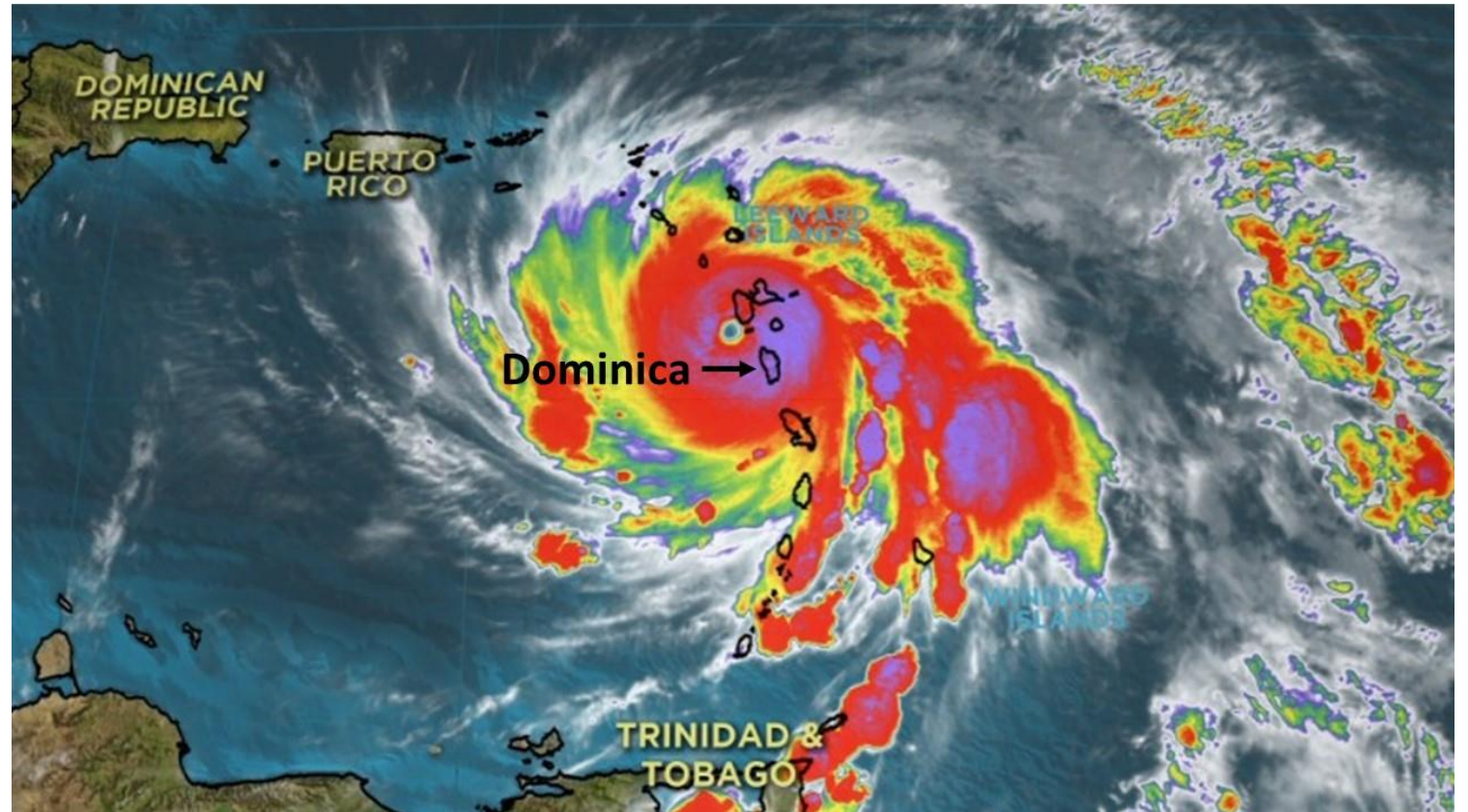
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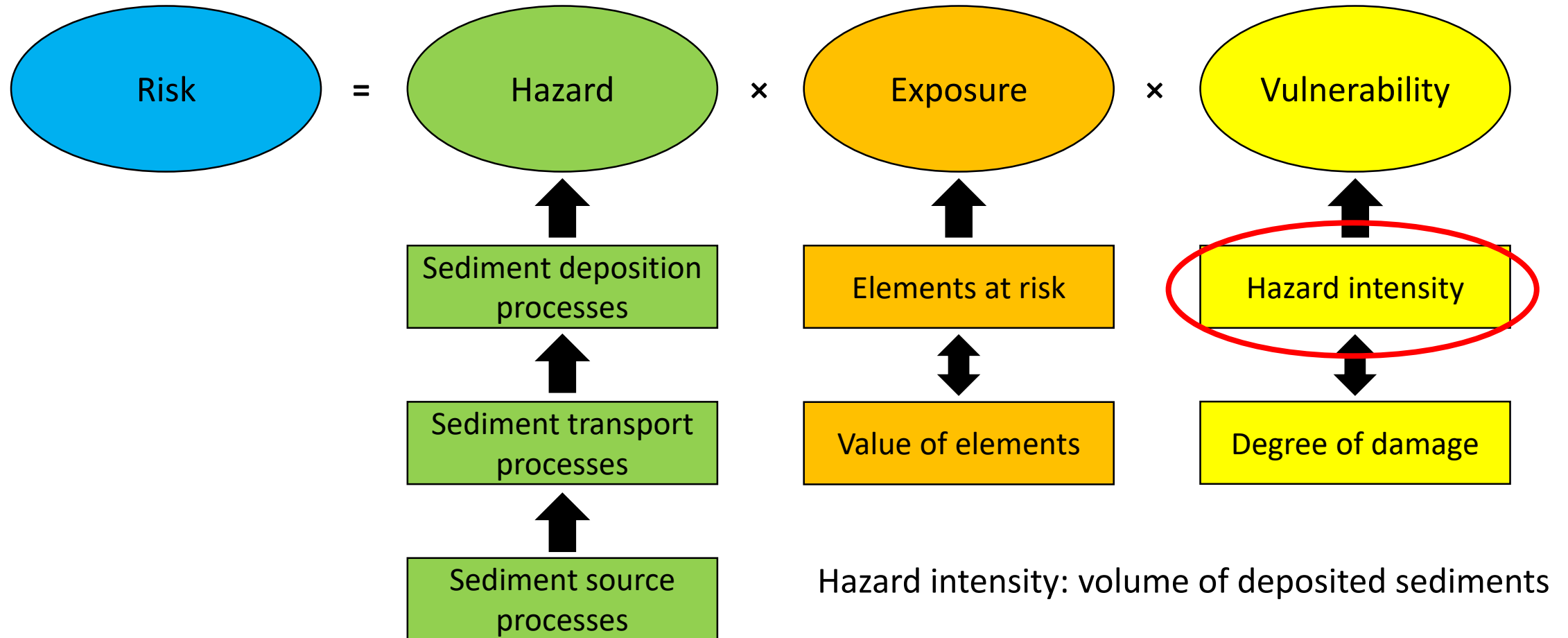
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# Risk assessment of sediment deposition





# Sediment hard to quantify compared to flood level



👉 Total additional cost of cleaning sediment after hurricane Maria in Dominica: 92 million US\$

👉 Mixture of flash floods, debris flows, trees, etc.



Source: Areal Dominica



# Objectives

## ☞ Assessment of:

- Sediment deposition volume
- Sediment deposition spatial variability

## ☞ Study area:

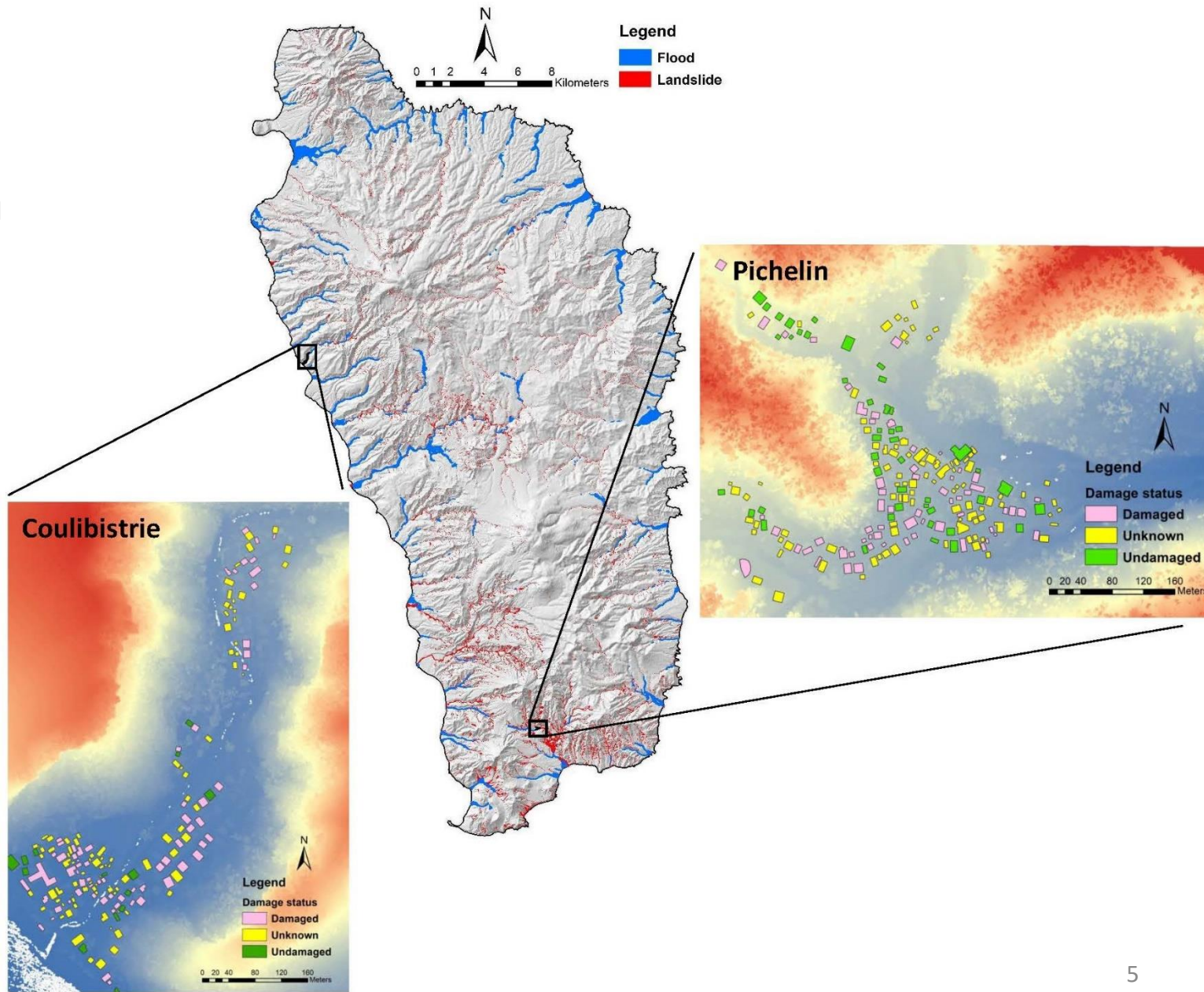
Dominica affected by hurricane Maria



Source: Areal Dominica

# Study area:

Two villages in Dominica



# Methods

1. In-situ investigations
2. Analyzing pre- and post-event UAV and LiDAR data
3. Creating deposition surface with trend interpolations





# In-situ investigations



- 👉 Deposition marks on the walls
- 👉 Remaining sediments in place
- 👉 Interviewing locals



# Pre- and post-event UAV and LiDAR Data

	Data	Time of acquisition	Resolution (m)	Vertical accuracy (m)
"UAV_DSM_Diff"	UAV pre-event DSM	August 22 <sup>nd</sup> to September 3 <sup>rd</sup> , 2017	0.02	0.10
	UAV post-event DSM	January 25 <sup>th</sup> to February 2 <sup>nd</sup> , 2018	0.04	0.10
"LiDAR_DSM_Diff"	LiDAR post-event DSM	February 19 <sup>th</sup> to May 5 <sup>th</sup> , 2018	0.50	0.05
	LiDAR post-event DEM	February 19 <sup>th</sup> to May 5 <sup>th</sup> , 2018	0.50	0.05

Hurricane Maria: Sep 18<sup>th</sup>, 2017

The diagram shows a vertical flow of data. A blue arrow points from the 'UAV pre-event DSM' row to the 'UAV post-event DSM' row. A red arrow points from the 'UAV post-event DSM' row to the 'LiDAR post-event DSM' row. Another red arrow points from the 'LiDAR post-event DSM' row to the 'LiDAR post-event DEM' row. A blue arrow points from the 'LiDAR post-event DEM' row to the 'LiDAR\_DSM\_Diff' label. A black bracket groups the 'UAV pre-event DSM' and 'UAV post-event DSM' rows, with a blue arrow pointing to the 'UAV\_DSM\_Diff' label. A red arrow points from the 'UAV post-event DSM' row to the 'LiDAR\_DSM\_Diff' label.

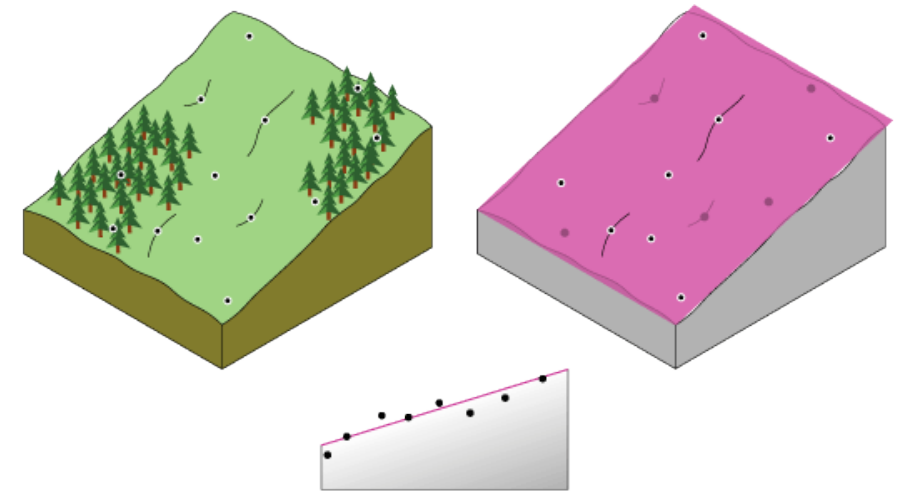
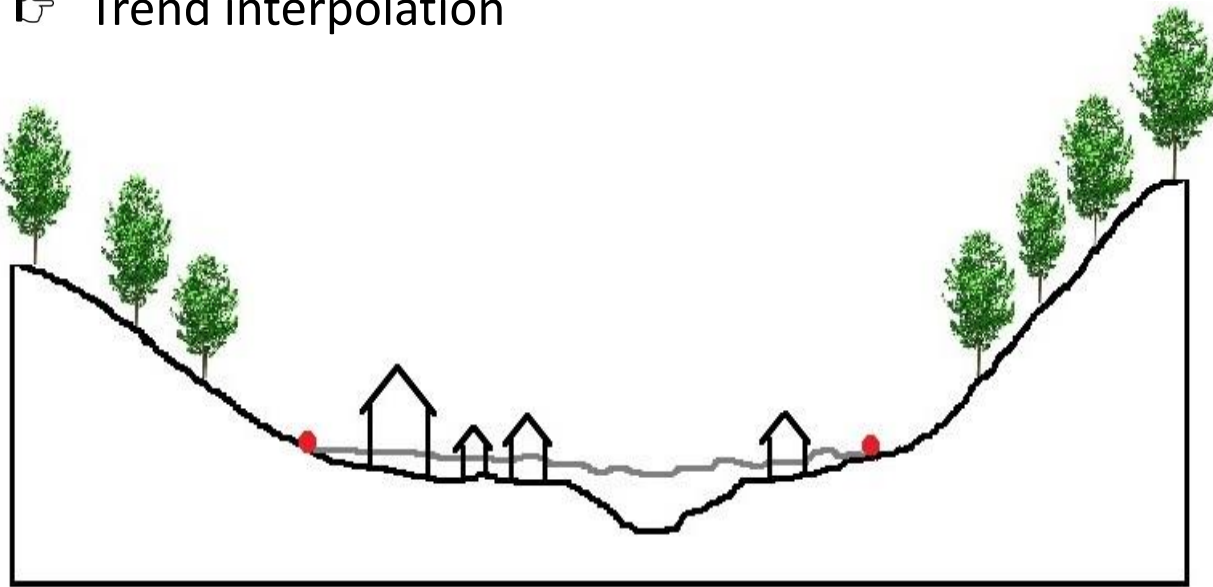
Sediment deposition = UAV post-event DSM – UAV pre-event DSM

Sediment removal = LiDAR post-event DEM – UAV post-event DSM



# Trend surfaces

- ↳ Elevation values extracted from DEM
- ↳ Trend interpolation



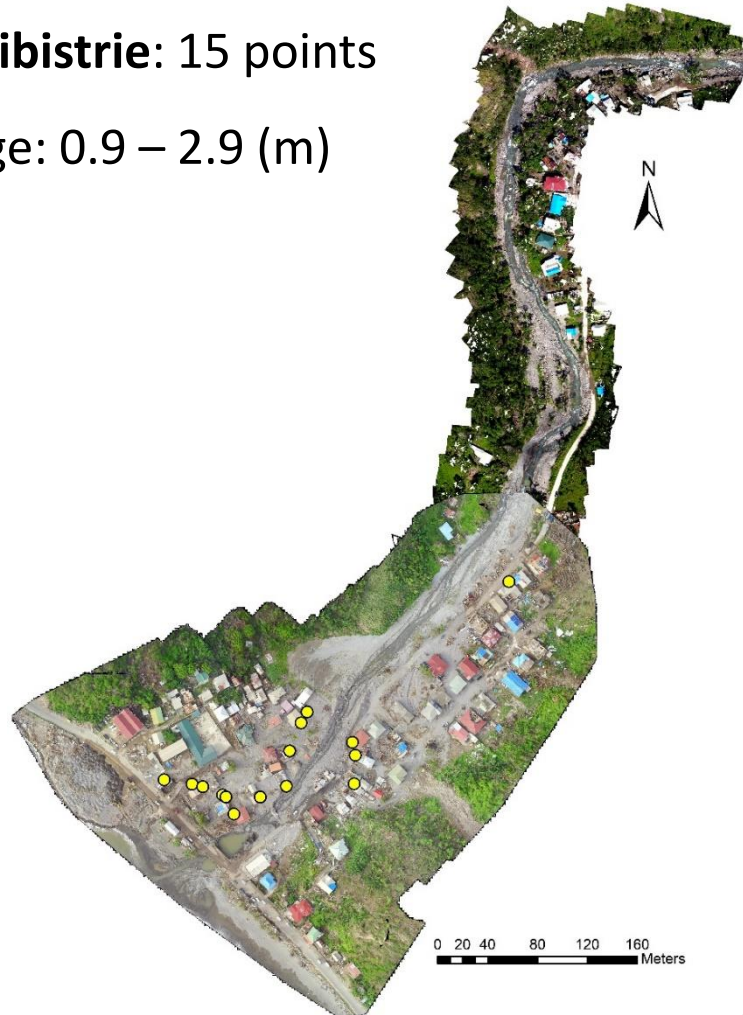
Trend interpolation  
Source: esri (2016)

$$\text{Deposition volume} = (\text{Trend surface} - \text{DEM}) \times \text{Cell area}$$

# In-situ investigations

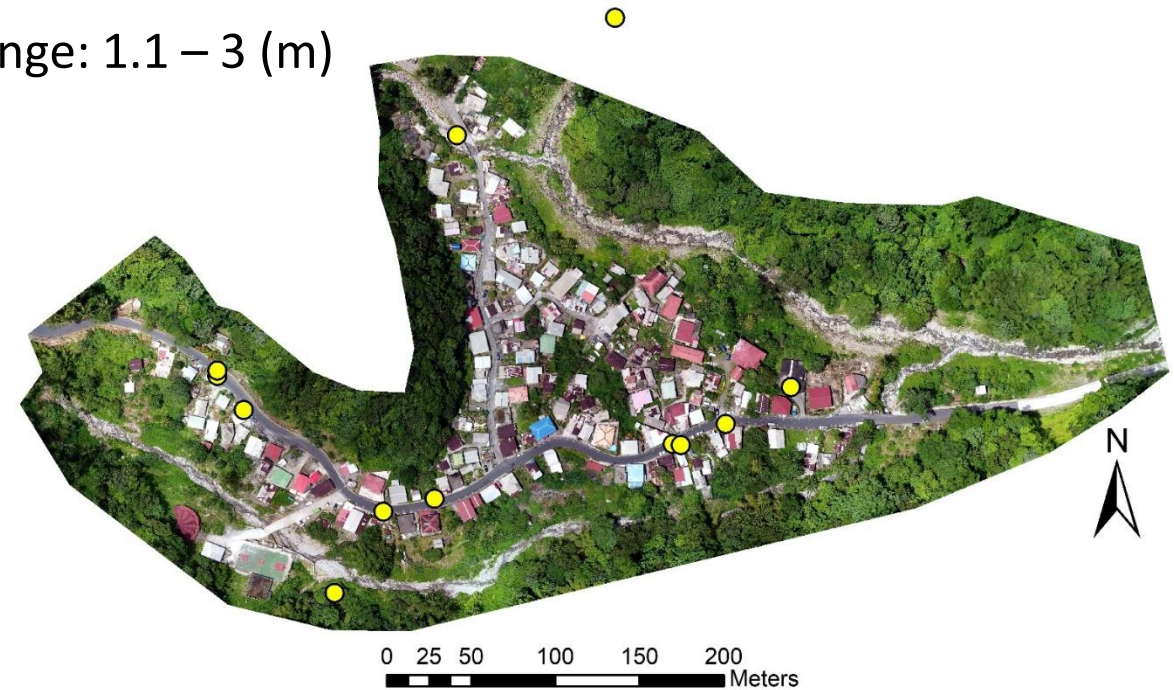
**Coulibistrie:** 15 points

Range: 0.9 – 2.9 (m)



**Pichelin:** 12 points

Range: 1.1 – 3 (m)

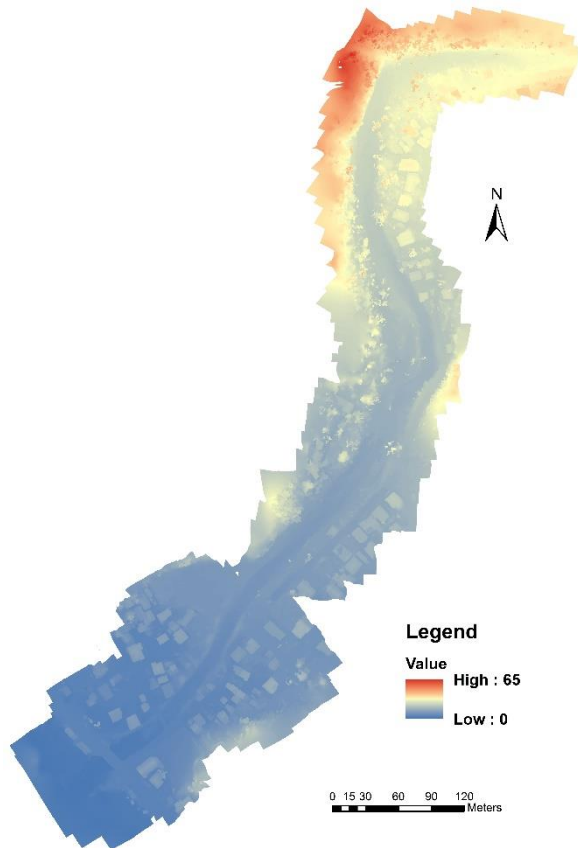


● → Location of data collection

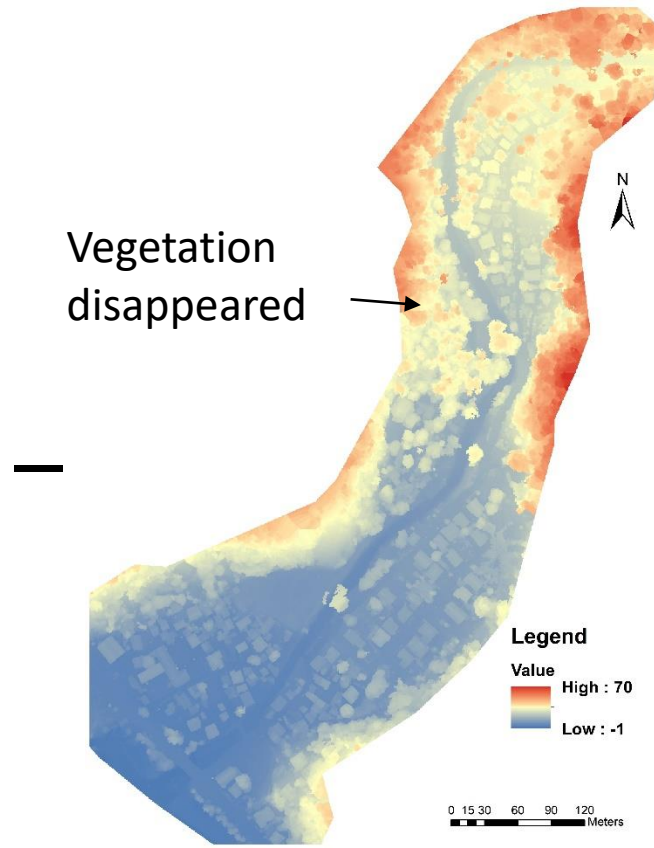


# Pre- and post-event DSMs and DEM

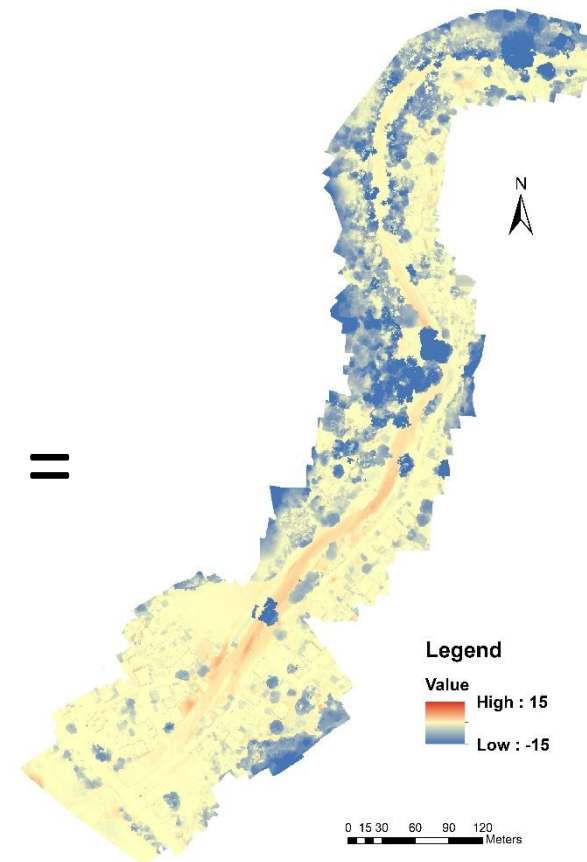
UAV Post-event DSM



UAV Pre-event DSM



UAV\_DSM\_Diff

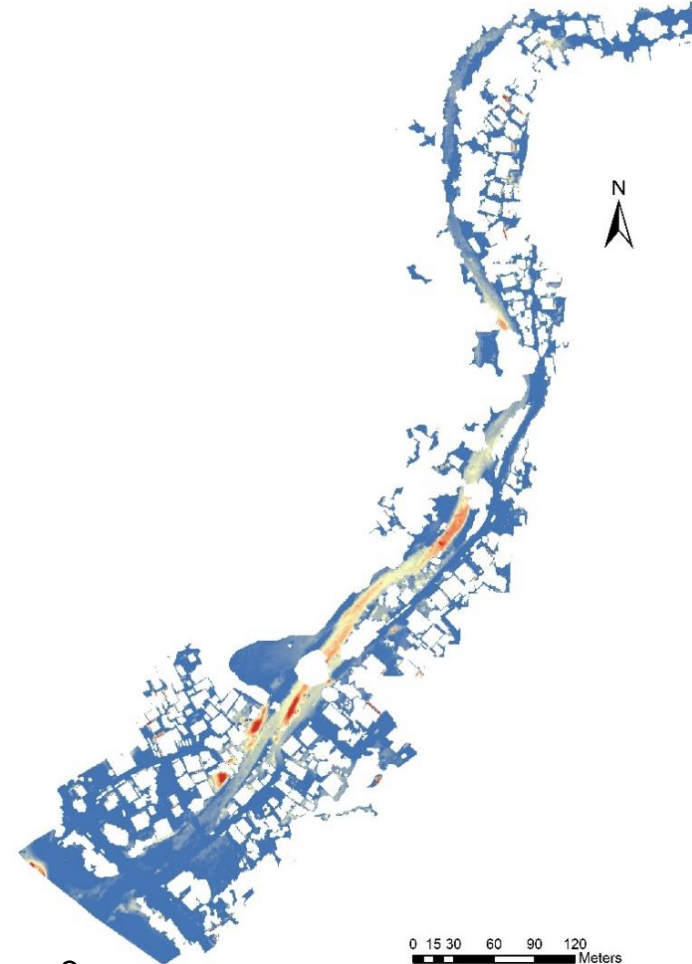
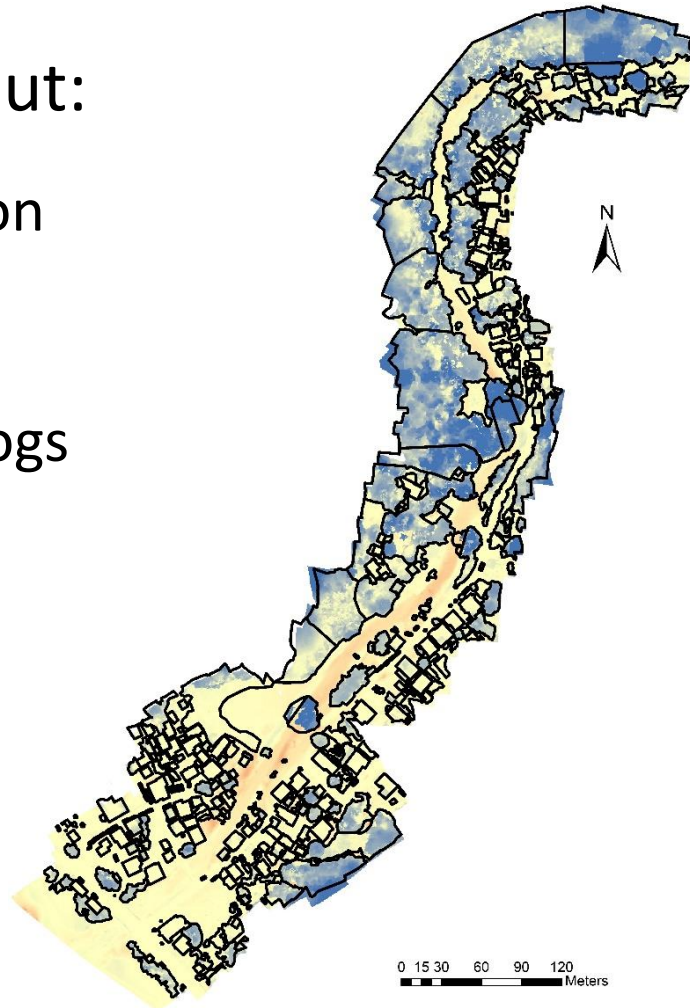


Problem:  
vegetation and  
some buildings  
disappeared  
during hurricane;  
causing negative  
values in  
UAV\_DSM\_Diff

# Pre- and post-event DSMs and DEM

Masking out:

- ☞ Vegetation
- ☞ Buildings
- ☞ Piles of logs
- ☞ Cars





# Pre- and post-event DSMs and DEM

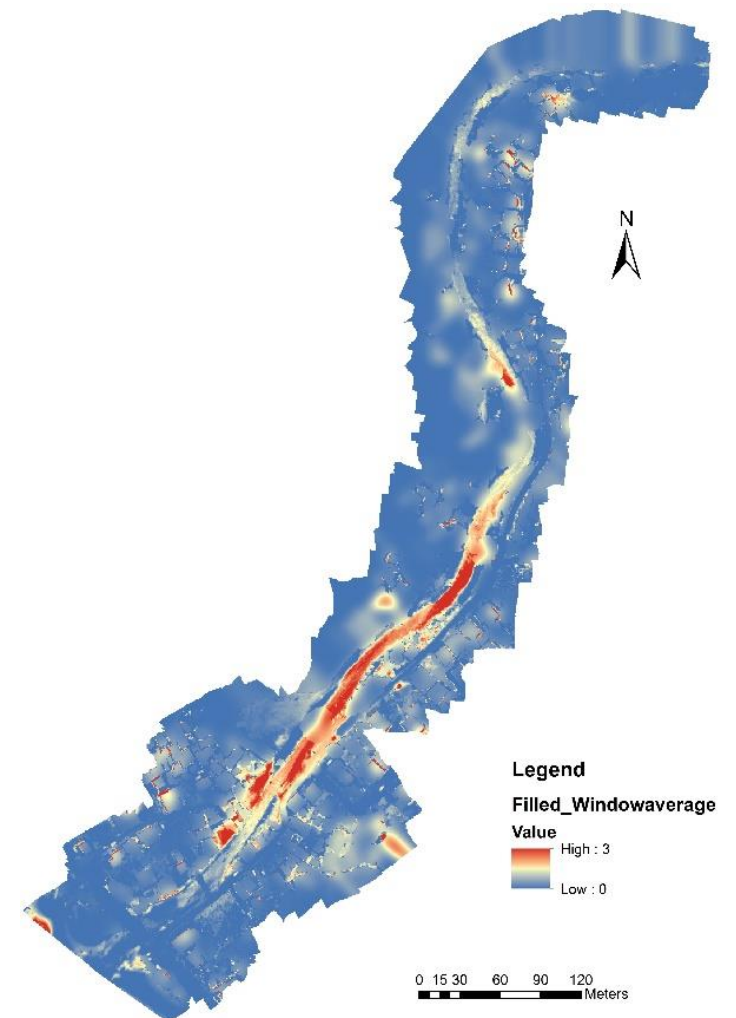
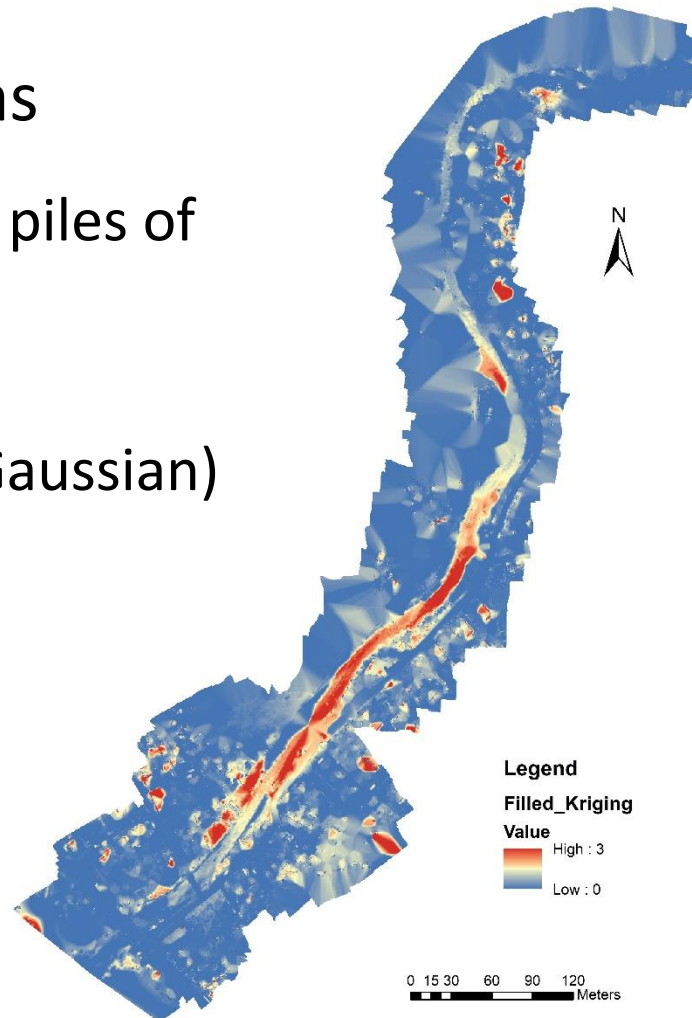
Filling of obscured areas

(vegetation, buildings, and piles of logs):

☞ Kriging interpolation (Gaussian)

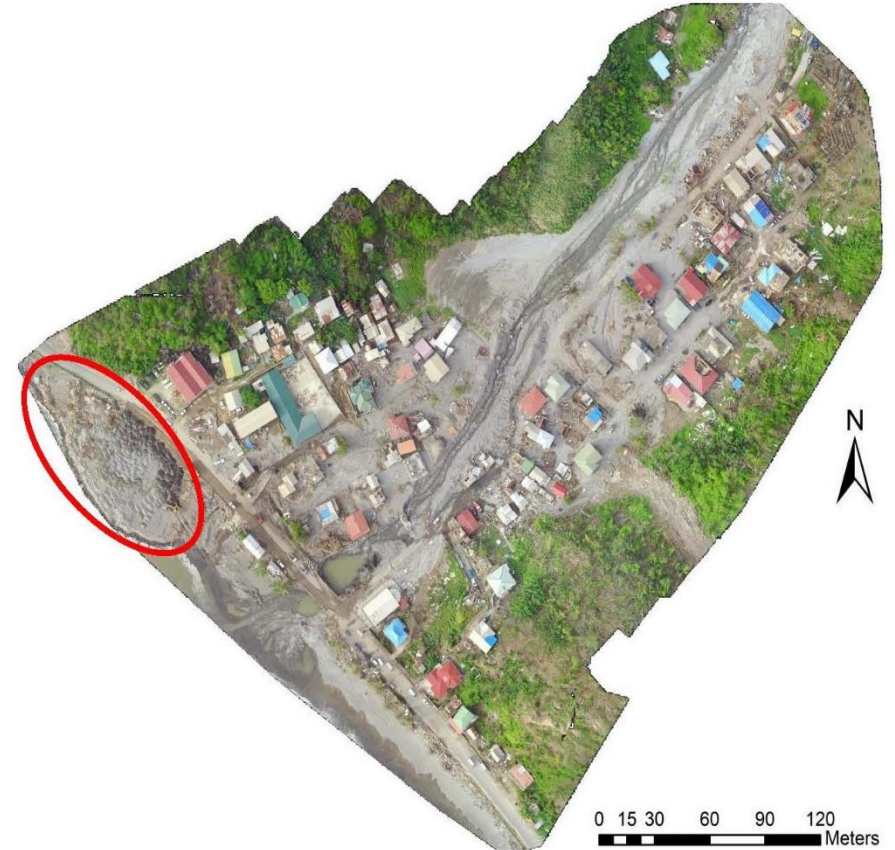
☞ Window average

using edge pixel elevation



2<sup>nd</sup> method results

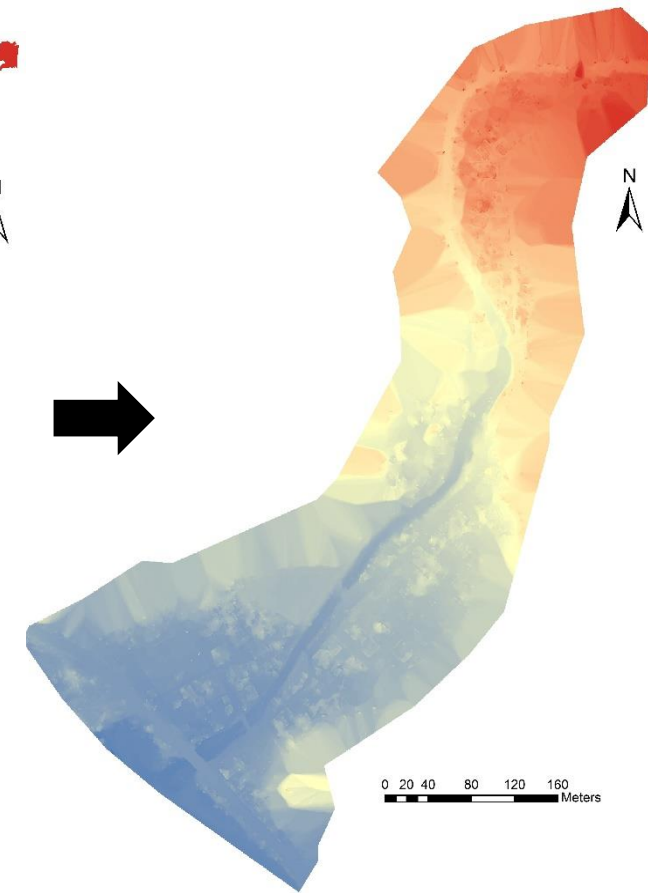
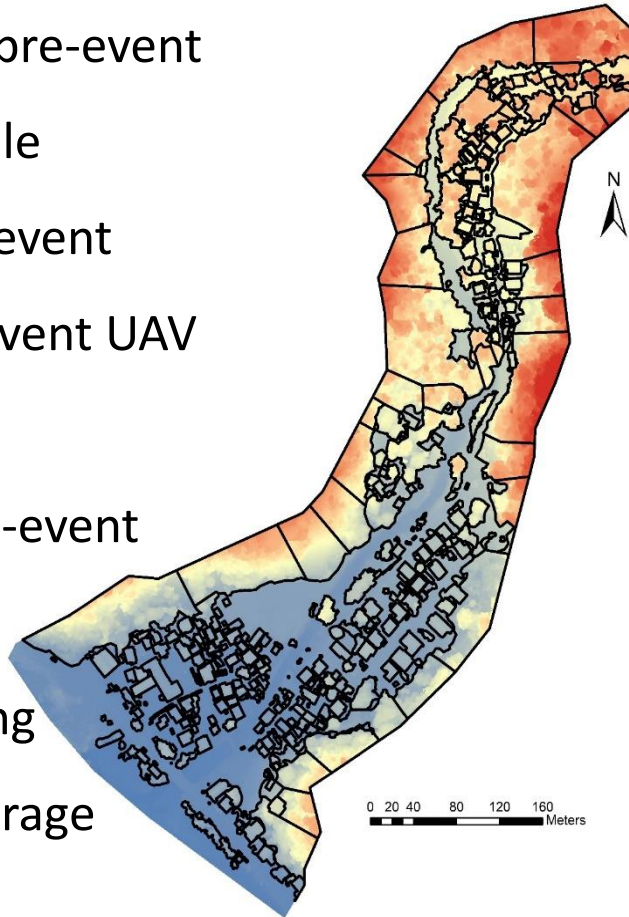
# Reference volume: sediment dump at Coulibistrie shoreline





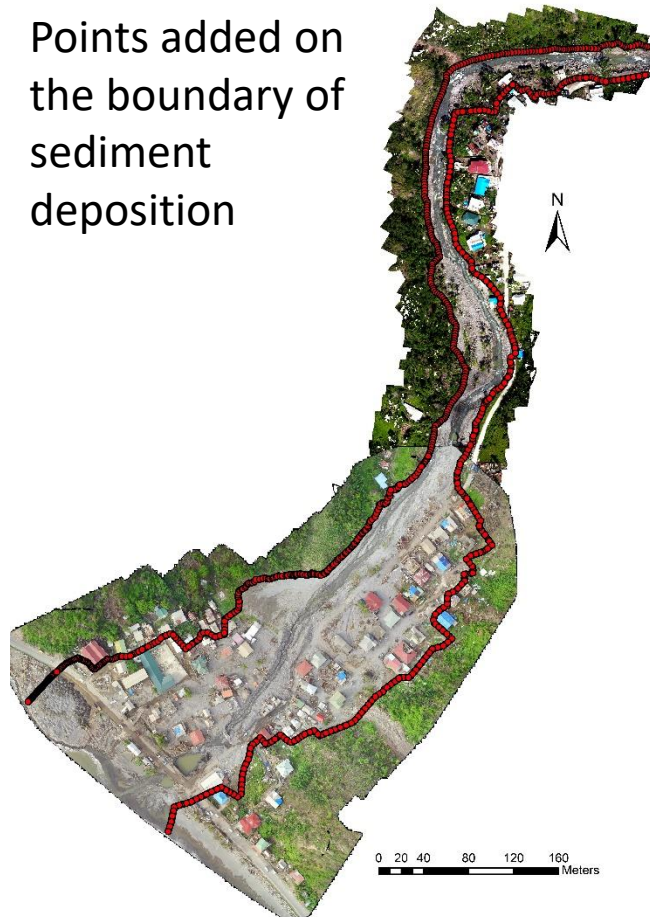
# Trend surfaces

- High resolution pre-event DEM not available
- Generating pre-event DEM from pre-event UAV DSM
- Masking out pre-event UAV DSM and filling with Kriging and window average

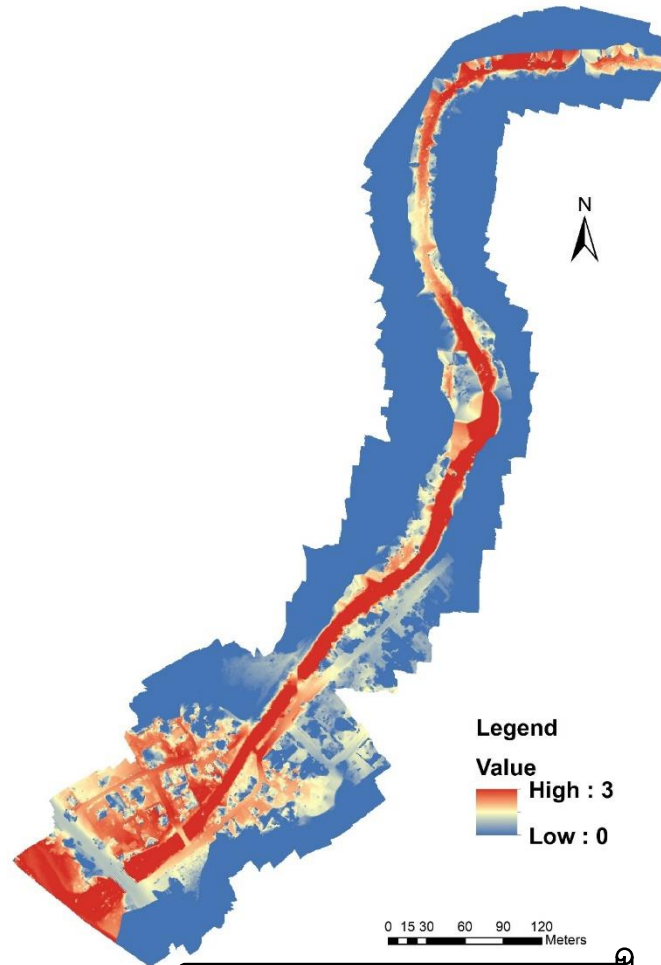


# Trend surfaces

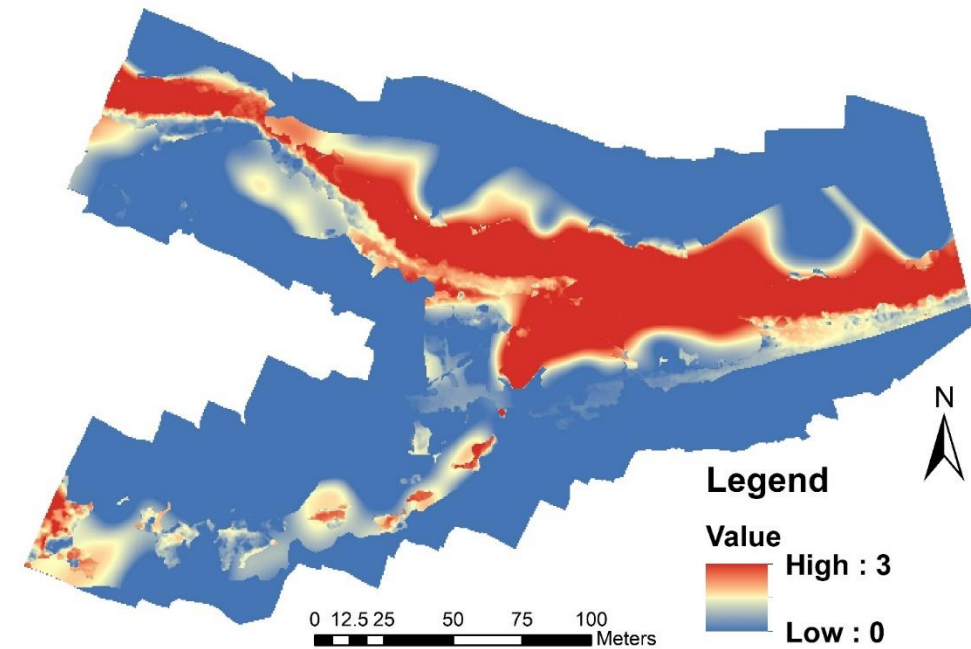
Points added on the boundary of sediment deposition



Trend surface minus DEM; Coulibistrie

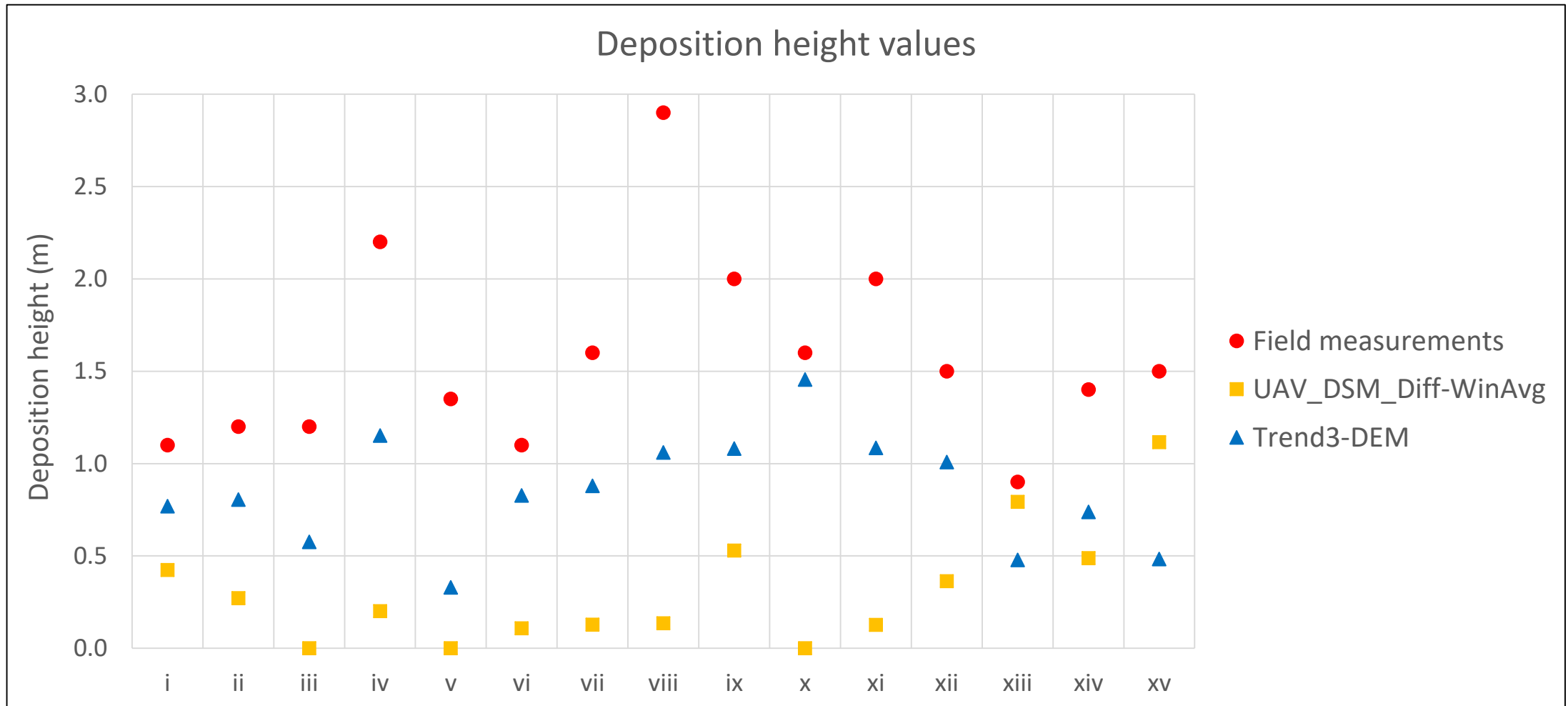


Trend surface minus DEM; Pichelin





# Deposition height value comparison



# Summary: sediment volume estimates ( $10^3 \text{ m}^3$ )

Methods			Coulibistrie	Pichelin	
1	In-situ investigations		-	-	
2	Analysis of UAV and LiDAR data	UAV_DSM_Diff (UAV DSM Post – UAV DSM Pre) (Jan 2018 - Aug 2017)	Masked-out parts filled with Kriging interpolation	42.47	22.20
			Masked-out parts filled with windowaverage	40.05	18.84
		LiDAR_DSM_Diff (LiDAR DEM Post – UAV DSM Post) (Apr 2018 – Jan 2018)	Masked-out parts filled with Kriging interpolation	-18.97	-
			Masked-out parts filled with windowaverage	-20.60	-
		Volume of sediment dump at the shoreline	Masked-out parts filled with Kriging interpolation	28.29	-
			Masked-out parts filled with windowaverage	28.31	-
3	Analysis of trend surfaces and DEM	1 <sup>st</sup> order trend surface minus DEM	77.70	42.64	
		2 <sup>nd</sup> order trend surface minus DEM	86.79	41.84	
		3 <sup>rd</sup> order trend surface minus DEM	86.79	41.84	





# Notes

- ☞ Due to presence of vegetation and buildings, analysis of UAV data is associated with high uncertainties.
- ☞ Marks on the wall might in fact belong to flooding level.
- ☞ Analysis of trend surfaces are in fact representing the flow surface.

# Conclusions

- ✚ A large number of field measurements with good distribution over the entire study area is required.
  - But it is very hard to characterize sediment volumes in the field because of the high spatial variability
  
- ✚ It is wise to inspect the places where the sediment deposition is hard to recognize from remotely sensed products.
  
- ✚ Pre- and post-event UAV and LiDAR products provide the most reliable results.
  - Corrections for vegetation and buildings are necessary





Thank you

