

# Additive manufacturing: state of the art and potential for insect science

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## Abstract

Additive Manufacturing has become an efficient tool to study insect-inspired biomimetic solutions. Indeed, it can build objects with intricate 3D-shapes and use materials with specific properties, such as soft materials. From biomaterials to biostructures or biosensors, Additive Manufacturing allows more possibilities in terms of design and functions. Reciprocally, insect-inspired technological solutions can be implemented to enhance Additive Manufacturing processes providing for example biocompatible structures that can successfully host living cells. We believe that, thanks to its continuous progress, Additive Manufacturing will play a growing role in the development of insect-inspired solutions.

## Introduction

Biological systems are a wonderful source of inspiration to find solutions for a large variety of problems. Nature had millions of years to develop efficient and original ways to deal with challenges, e.g. varying from all kinds of locomotion to group organization, from abiotic constraints to predator evasion. Even if not all these solutions might be relevant for human applications, they may reveal interesting phenomena or mechanisms.

Insects, and in a broader sense arthropods, have a large range of ecological conditions: they can crawl on the ground, swim, fly, live in caves in complete darkness [1] or even survive space conditions ([2], Panarthropoda clade). Moreover, being part of the same phylogenetic group, they had to evolve various solutions based on the same basic tools and materials, e.g. all the cuticles and hard parts of insects contain chitin [3] with various mechanical properties. Insects are thus a rich and promising group for biomimetics [4].

However, insects are of relatively small size so it is sometimes difficult to study them. As the 3D-shape of an organ or any other part of interest is also closely linked with its function, manufacturing small-size objects with specific 3D-shapes would be a great help to investigate insect-related mechanisms. Well-known photolithography based fabrication technologies such as MEMS, CNC milling or moulding are wonderful technologies to produce a variety of objects but they have their limitations, e.g. size-wise or in producing various kinds of 3D shapes (Table 1). On the other side, Additive Manufacturing (AM), with 3D printing its most well-known representative, produces highly customizable objects with far more freedom regarding their 3D-shapes than traditional manufacturing technologies.

Technology	Photolithography	Additive Manufacturing	CNC	Moulding
Dimensionality	2,5-D (stratified)	3D	3D, limited	3D, limited
Fabrication	Batchwise	Piecewise	Piecewise	Batchwise
Materials	Inorganic	Organic	Inorganic	Organic
	Mostly stiff	Stiff and flexible	Stiff	Stiff and flexible
	Linear	Creep, hysteresis	Linear	Creep, hysteresis
Resolution	nm - $\mu\text{m}$	$\mu\text{m}$ - mm	0.1 $\mu\text{m}$ - mm	$\mu\text{m}$ - mm
Initial costs	High	Low	Low	High
\$/piece	Low	Medium	High	Low
Customisation	None	Per piece	Per piece	None
Lead time	Long	Short	Short	Long

Table 1: Comparison of the characteristics of various traditional manufacturing processes with Additive Manufacturing, adapted from [5], CNC = Computer Numerical Control

## Additive manufacturing

AM literally entails the class of fabrication technologies that are based on adding materials, rather than removing (e.g. etching, milling, spark erosion, etc.) from a piece. It is best known for 3D printing, e.g. a layer-by-layer manufacturing process. Because of this particular process (fig1), 3D printing can produce all possible 3D-shaped objects as long as it does not collapse during building, e.g. by gravitational forces [6].

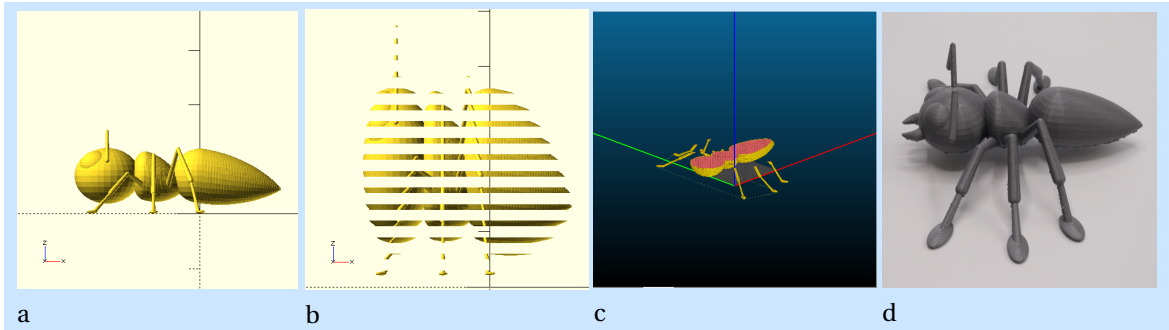


Fig. 1: Principle of Additive Manufacturing processes. a: 3D model of ant (Openscad v2015.03-2), b: Slicing of the 3D model (Openscad v2015.03-2), c: Layer-by-layer building process (Slic3r v1.2.9), d: Printed model

AM is divided in 7 kinds of processes depending on how each additional layer of material is created [7] (Table 2). The choice of process is a critical one as it defines which kind of materials can be used in the process, the resolution that can be obtained and if there are any limits on the range of possible 3D-shapes. For example, Stereolithography (SLA) is a process where the new layer of material is cured by UV light within a layer of liquid photopolymers. Materials are thus restricted to photopolymers or materials that can be functionalised using photopolymers. Also, overhanging structures may need support to be produced [8].

Besides classical SLA processes, it is worth noticing the existence of 2-photon polymerization technique (Nanoscribe, Eggenstein-Leopoldshafe, Germany) which allows very good accuracy ( $0.5\ \mu\text{m}$ ) for complex-shaped objects. Alternatively, FDM (Fused Deposition Modelling) is a highly customizable process: here molten material is extruded through a nozzle. By combining several nozzles, it is possible to use several materials with various properties or colors [9] or even to create one's own material [10]. Another process often used in biomimetics research is Polyjetting. Here, droplets of material are jetted by a printer head to create each new layer. By adding more print nozzles, it is possible to use multiple materials in the same print or even create materials by mixing various components [11].

Progress has also been made with respect to materials with special properties. Conductive materials are now available [12] as well as soft materials [13] or even piezoelectric materials [14]. These kinds of materials are critical to produce actuators and sensors.

Despite the resolution of AM getting close to the micrometric scale (table 2), it should be mentioned that high resolution alone is often insufficient to mimic insects, as a general aspect of biology is that its structures cover 7-9 orders of magnitude in size, from nanometers up to (centi)meters, largely surpassing even the most advanced 3D printers currently available.

Category	Description	Advantages and disadvantages	Material resolution	Capability of multiple materials printing
Stereolithography	Stereolithography Apparatus (SLA) and DLP (Digital Light Processing) cure a layer of photopolymers with laser light point-by-point or a surface all at once	+ High dimensional accuracy and transparent material available – Restricted to photopolymers, time consuming material changing, material contamination and need of support structure	Good	Poor
Material extrusion	Fused or room temperature materials are extruded through a nozzle. Ex: Fused Deposition Modeling (FDM) and 3D-bioprinting	+ Easy and cheap mechanisms, good materials properties, living cells can be incorporated – Relatively low dimensional accuracy and mechanical strength	Medium	Good
Powder bed fusion	Powder particles are fused together using a power source such as laser, heat or electron beam. Ex: Selective Laser Sintering (SLS) or Electron Beam Melting (EBM)	+ Wide range of materials, great material properties, high material strength, no need of support structure – Thermal stress, degradation, accuracy limited by the particle size of materials, material contamination when changing to other materials, require atmosphere control for metals	Low	Fair
Directed energy deposition	Materials, in the shape of powders or wires, are melted using a laser or electron beam and deposited according to a desired shape. Ex: direct metal deposition	+ Wide range of materials, great material properties – Low dimensional accuracy, thermal stress, requires atmosphere control, requires machining process to finish the part	High	Fair
Sheet lamination	Sheets of materials are cut and bound together. Ex: Ultrasonic Additive Manufacturing (UAM) uses ultrasounds to merge layers of metal	+ Fast process, high dimensional accuracy – Great amount of scrap, delamination, requires changeover when changing materials	Low	Fair
Material jetting	Material drops are jetted from printheads in a similar way as 2D-printing.	+ Fast process, wide range of materials, materials mixing on droplet scale, good accuracy – Limited to jettable materials, clogging problem	High	Excellent
Binder jetting	A binder is jetted on a bed of powder to stick particles together. This process was originally known under the name 3D-Printing	+ Low temperature and fast process – High porosity, low surface quality, accuracy limited by particle size, difficult to remove trapped materials	Medium	Good

Table 2: Characteristics of the different AM processes, adapted from [15] for the process description column [16] and its references for the advantages and disadvantages and the material resolution and [17] for the multi-material capabilities. The Nanoscribe (Eggenstein- Leopoldshafen, Germany) was put apart in the Stereolithography category because of its special technology which allows to reach sub- micrometer accuracy.

## Biomaterials and structure

Insects are small and lightweight and they can synthesize materials with a large range of differing properties depending on the needed functionality of the material. Some of them are termed composite materials and obtain their mechanical properties from both the properties and the spatial arrangement of their constituents. From a broader point of view, structures built by arthropods, such as spider webs, can give new ideas to architecture [18].

### Structural materials

Biomaterials possess properties that make them special in regards to their human-made counterparts. They are lightweight, synthesizable in water solutions and biodegradable [19]. Many biomaterials are also composite materials: they are composed of several materials that are deposited in such a way that the resulting composite material can have better mechanical properties than any of its constituents [20]. This is for ex-

ample the case of insect cuticle which is a mix of chitin nanofibers, water and various proteins and whose Young modulus varies from 1 kPa to 20 GPa [3].

AM and biomaterials can benefit from each other. Firstly, AM can play an important role in the development and use of composite and structural materials. Indeed, the possibility to produce and study such materials [20] has already been demonstrated. Water-repellent surface structures of springtails were also successfully reproduced and enhanced with AM to become repellent for almost any liquid [21]. Secondly, AM and more specifically FDM can produce materials with anisotropic properties by, for example, printing materials that are composed of a matrix and parallel fibers [22] as it is the case in silk [23]. The other way around, biomaterials can give new opportunities to AM, especially in 3D bio-Printing [24]. However, in traditional FDM, a filament of plastic is molten and made to flow through a nozzle. As 3D bio-printing concerns cells, a substance which can flow at room temperature and which is biocompatible and biodegradable is necessary. Bio-inks based on spider silk fibers have been created to meet these criteria [25].

On a larger scale, the two-way interaction still holds. AM can learn from insects how to design and produce 3D-shapes. This is especially the case for FDM which process is similar to the extrusion of silk by insects. An FDM nozzle put on a robot arm (Kukka arm) was shown to be able to mimick the cocoon construction process of a silkworm [26] (fig2e).

### *Architecture*

AM can help studying biostructures that have optimized load distribution such as honeycombs [27] and spiderwebs [28] (fig2c). Those bio-structures have concrete applications, in architecture for example. Frei Otto who popularized lightweight structures was inspired by spiderwebs among others [18]. On the micro-scale, geometries of the stings of mosquitoes [29] and bees [30] were reproduced to create high-quality needles (fig2b).

## **Bioinspired locomotion**

Insects live in very diverse ecological environments. Thus, they developed various strategies to move depending on whether they walk on solid or liquid surfaces, fly in the air or swim in water. Consequently, insects are a great source of inspiration for small-sized robots as they developed lightweight and efficient solutions to locomotion. The 3D-shape of organs such as wings or legs play a significant role in the performance of locomotion. AM can produce such complex 3D-objects and, thus, help to better understand the mechanisms of locomotion. These solutions can then be implemented to design better robots.

### *Actuators*

Before being able to produce a full robot, AM must develop the capability to produce actuation. To this end, fabrication of the required actuators is a challenge, as they are composed of mobile parts, need ample energy supply and effective and efficient transduction mechanisms. Thanks to the development of soft materials for AM, it is now possible to produce soft actuators [31]. Actuators inspired from biological fiber muscles have even been developed [32]. However, this is a new development and another solution is to embed traditional actuators within 3D-printed parts [33].

### *Bioinspired robots*

Locomotion is an important field for robotics [34]. Better understanding the physics of the various modes of locomotion of insects, such as walking and crawling, is crucial in designing better robots. In this regard, beetle [35] and leafhopper [36] legs have been investigated with the help of AM in order to understand how their shapes were linked to their functions (fig2g). A similar approach was conducted to better understand the physics of insect crawling [37, 38]. However, only the bodies of the crawling robots were built with AM technologies. Traditional actuators were then assembled with the robot. Cutkosky and his team [39] used another manufacturing process called Shape Deposition Manufacturing (SDM), a process which combines moulding, parts embedding and assembly, to produce their walking robot inspired from cockroach because it is a straightforward method to embed actuators. The recent development of Hybrid Deposition Manufacturing, a technology comparable to SDM but with more parts being produced by 3D printing [40], could give

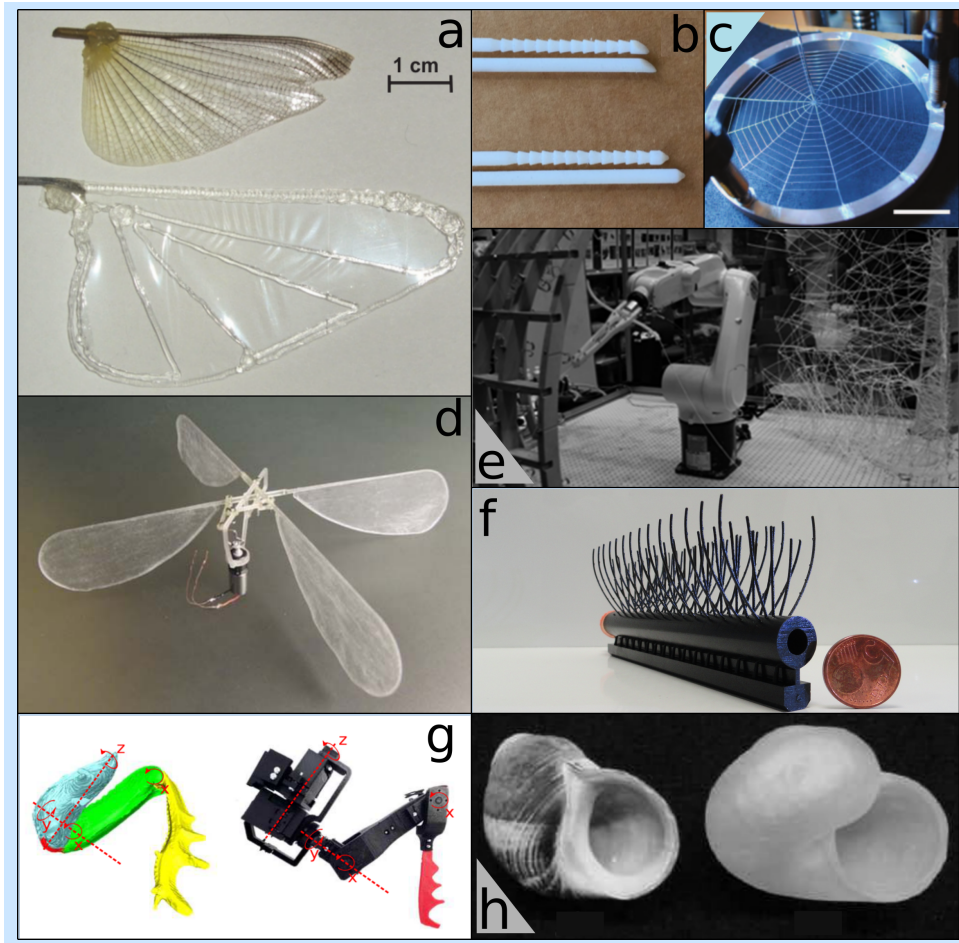


Fig. 2: Application of Additive Manufacturing to insect-inspired biomimetics. a: Dragonfly-inspired wing [41]; b: Honeybee-inspired needles [30]; c: Biomimetic spiderweb [28]; d: Micro air vehicle with insect-inspired wings [42]; e: Robot arm building a cocoon-like structure in a similar way as silkworm [26]; f: Artificial antenna structure inspired from moth [43]; g: Multifunction beetle-inspired leg [35]; h: Natural and artificial shells for hermit crab preference tests [44]

Additive Manufacturing an important role in this domain.

### Flying robots

Biomimetic flying robots have been under study for almost 30 years [45] and insects have gained a special focus as an effective source of inspiration [46]. Indeed, insects are small and some of them have excellent flying capabilities. They perform flapping-wing flight which requires flexible wings [47]. Most of the work about insect-inspired flying robots has thus been dealing with wing shape and flexibility. Although CNC milling [48] was also used, Additive Manufacturing is a more convenient tool to investigate how wing geometry is related to flight performance. Most of the time, only the frame of the wing was produced with AM and subsequently a film was applied to mimic the membrane [49, 41] (fig2a). Richter *et al* [42](fig2d) were the only ones to completely produce wings with AM technology. Wing flapping physics has received ample attention and AM can help produce customized mechanical parts [42, 50].

Insect-inspired biomimetic AM can have surprising applications, for example in a culinary context: inspired by the rove beetle, a cocktail boat was put into motion on a water surface using the Marangoni propulsion [51].

## Bioinspired sensors

Insects have evolved multiple sensors to interact with their environment. Here again, the 3D-shape of the sensors can have a profound importance and, thus, AM could be an efficient tool to investigate or reproduce biosensors [52].

Moth antennas are very sensitive olfactory sensors and they have a complex 3D-shape. Thanks to AM, it was possible to partly reproduce this shape and investigate its efficiency [53]. Arthropod eyes are also a good source of inspiration for biosensors. Studies and production of biomimetic eyes have been undertaken [54], showing the high interest in this kind of sensors. However, only during the last years was AM able to print micro-optics [55, 56] and a project to produce a biomimetic eye entirely through AM is currently in progress [57]. A last kind of biomimetic sensor developed with AM is an acoustic device inspired from a locust [58] thanks to the new possibility to use piezoelectric materials.

The literature about AM and insect-inspired sensors is actually quite recent. However, with the continuing technological developments of AM, accuracy is increased and a broader range of materials is available. We believe that this progress will help to accelerate design and study biosensors with AM in the near future.

## Discussion

Additive Manufacturing is a group of evolving technologies. Processes are improved, accuracy is increasing, printers become cheaper and an increasing variety of materials is now usable such as flexible and/or conductive materials. This progress gives AM an increasing potential to produce objects with specific properties. For example some biomaterials display gradient properties which may be reproduced by e.g. polyjetting. However, AM is not always used for its enabling capabilities: it may as well just be a method to conveniently and cheaply produce simple objects that help studying certain phenomena [59].

A dichotomy can be observed between the investigations aiming at mimicking the shape of an insect, or one of its organs, for technological applications, and those where the mechanisms are investigated in a biological context. In the former case, the challenge is usually a technical one: for example, Richter *et al* succeeded in manufacturing a flying robot [42]. In the latter case, AM is a very useful tool as it allows to produce similar objects with different parameters to better understand how they affect the performance of the real animal [41].

AM can also be used to investigate insect-environment interactions: artificial shells (fig2h) and flowers with various geometrical parameters were offered to respectively hermit crab [44] and tobacco hawk moth [60] to determine their preferred choice. However, the accuracy of the chosen AM process can have a strong influence as the result might not be detailed enough to lure real insects [61].

Products built with AM processes undergo changes overtime or during the cooling period. With the development of smart materials, 4D printing tries to increase this change and integrate it in the design of the object. The objective is to change the shape or the function of an object depending on time or on the environmental conditions [62]. 4D-printed biomimetic structures [63] may give access to new design opportunities in insect biomimetics in the future.

## Conclusion

As this survey shows, Additive Manufacturing using insects as templates is in its early days but is burgeoning. We expect to see major breakthroughs in a not too distant future. Indeed, the major technologies are already available: printing tiny details or huge structures, printing with different materials, or ones which change over time or over space. However, the challenge lies in the integration of technologies which may be principally not impossible but conceptually hard to realize in practice (e.g. extending photo polymerization technology, e.g. Nanoscribe (Eggenstein-Leopoldshafen, Germany), to multimaterial printing). The market will drive the speed of this evolution and, once this integration is achieved, we will see a flurry of very realistic and functional insect bio-inspired parts being produced, with levels of detail true to the real structures.

## Interesting articles

\*\*[8] : Stereolithography process was enhanced to generate water support structures which are easily removable.

\*[21] : The authors reproduced micro-structures at the surface of some insects called sprintails and that are known to be water-repellent. Thanks to Additive Manufacturing, they could modify the geometry of the structures so the surface would become repellent to any liquid.

\*\*[28] : With the use of Additive Manufacturing, the roles of single thread mechanical strength and spider web geometry in the overall mechanical strength of a spiderweb is better understood.

\*[30] : Needles with designed inspired from honeybee sting give less pain than traditional needles.

\*\*[32] : Pneumatic soft actuators designs were inspired by the arrangement of fiber in muscles and were fabricated through Additive Manufacturing.

\*[38] : Caterpillar locomotion is mimicked by a 3D-printed soft robot.

\*[49] : Thanks to Additive Manufacturing, very realistic dragonfly-inspired wings were fabricated and the authors showed the importance of the membrane of the wing in its overall mechanical resistance.

\*\*[55] : Micro-optics were successfully fabricated with Additive Manufacturing.

\*[58] : An acoustic device inspired by locust and built with Additive Manufacturing gave insights to better design frequency-selective devices.

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