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2	<b>Cutting Edge Influence on Machining</b>	<b>Theory and Application</b>	25
3	<b>Titanium Alloy</b>		
4	Juan Manuel Jauregui-Becker	A synthesis process comprehends a complex	26
5	Laboratoy of Design, Production and	combination of cognitive and mathematical	27
6	Management, University of Twente, Enschede,	mechanism (e.g., random generation, backward	28
7	The Netherlands	reasoning, abduction, case-based reasoning, and	29
		constraint-solving). Although no unified theory	30
		exists for explaining the nature of the synthesis	31
		process, the generally accepted FBS family of	32
8	<b>Synonyms</b>	frameworks allows for making some concrete	33
		statements on the nature of synthesis.	34
9	<b>Combination; Creation; Integration</b>		
		<b>The FBS Model</b>	35
10	<b>Definition</b>	FBS models a design artifact by distinguishing	36
		the following levels of object representation:	37
11	Generally speaking, synthesis can be defined	function, behavior/state, and structure, as shown	38
12	as the composition or combination of parts –	in Fig. 1. The basis of the FBS model is that	39
13	building blocks, elements – to create a new	the transition from function to structure is	40
14	whole product, artifact, technology, machine, or	performed via the synthesis of physical behav-	41
15	graphic, whose ruling behavior emerges from the	iors. Therefore, behaviors allow characterizing	42
16	interaction of its constituents parts. In the context	the implementation of a function. As many dif-	43
17	of design, synthesis follows different definitions	ferent views of the FBS model have been devel-	44
18	(Chakrabarti 2002). The two most relevant to this	oped and researched, the FBPSS model presented	45
19	work are “synthesis as designing” and “synthesis	by Zhang et al (2005) serves as a unifying	46
20	as solution generation.” In the first definition,	framework for the different FBS schools of	47
21	synthesis is defined as an iterative process of	thought. This model is based on the analysis and	48
22	solution generation and solution evaluation. The	generalization of the Japanese (Umeda and	49
23	second definition narrows its scope to that of	Tomiyama 1995), (Umeda and Tomiyama	50
24	generation solutions.	1997), European (Pahl et al. 2007), American	51
		(Chandrasekaran et al. 1993), and Australian	52
		(Gero and Kannengiesser 2004) schools of design	53
		theory and methodology.	54

55 The FBPSS model uses the following  
56 definitions:

- 57 • **Structure:** Is a set of entities and relations  
58 among entities connected in a meaningful  
59 way. Entities are perceived in the form of  
60 their attributes when the system is in  
61 operation. For example, in Fig. 1 the structure  
62 is represented by an electric motor and  
63 a crank mechanism. Here, the two possible  
64 entities (structures) are the lengths of the bars  
65  $L_1$  and  $L_2$ .
- 66 • **States:** Are quantities (numerical or categori-  
67 cal) of the behavioral domain (e.g., heat  
68 transfer, fluid dynamics, psychology). States  
69 change with respect to time, implying the  
70 dynamics of the system. For example, in  
71 Fig. 1, the states of the structure are  
72 represented by the distance  $L_0$  between the  
73 electric motor and the piston, the torque  $T$  of  
74 the electric motor, or the displacement of the  
75 pistons.
- 76 • **Principle:** Is the fundamental law that allows  
77 the development of a quantitative relation of  
78 the state variables. It governs behavior as the  
79 relationships among a set of state variables.  
80 For example, in Fig. 1, two possible principles  
81 are electromagnetism ruling the operation of  
82 the electric motor and solid mechanics ruling  
83 the function of the crank mechanism.
- 84 • **Behavior:** Represents the response of  
85 the structure when it receives stimuli. Since  
86 the structure is represented by state and  
87 structure variables, behaviors are quantified  
88 by the values of these variables. In the case  
89 presented in Fig. 1, the two behaviors are  
90 *Generate torque* and *Convert torque into*  
91 *force*.
- 92 • **Function:** It is about the usefulness of  
93 a system. For example, in Fig. 1, one possible  
94 function of this system is to compress gas.

95 Figure 2 shows how these definitions are  
96 related. The relationship between state and struc-  
97 ture is a one-to-many relation. The behavior is  
98 produced as the combination of state sets  
99 underlined by a given set of principles to  
100 the structure. Behavior and function have  
101 a many-to-many relation, which depends on the  
102 context and usefulness of the structure.

## Classification of Design According to Its Synthesis Process

103  
104  
105 Within this framework, one can classify  
106 top-down steps aiming at determining the struc-  
107 ture of an artifact given a functional representa-  
108 tion as synthesis processes, while their back  
109 reasoning counterpart of determining function  
110 characteristics given a known structure as  
111 analysis processes.

112 From this perspective, synthesis processes are Aut  
113 classified into three groups according to the type  
114 of representations:

- 115 • **Routine design:** One in which the space of  
116 functions, behaviors, and structures are  
117 known, and the problem consists of instantiat-  
118 ing structure variables.
  - 119 • **Innovative design:** One in which the functions  
120 and behaviors are known, and the design  
121 consists of generating new structures that sat-  
122 isfy them.
  - 123 • **Creative design:** One in which the functions  
124 are known, and the problem consists in  
125 determining the structures and behaviors  
126 required to satisfy them.
- 127 Furthermore, as nature encompasses a vast  
128 variety of behaviors (physical, chemical,  
129 human, etc), synthesis processes can also be clas-  
130 sified according to the types of behaviors being  
131 targeted:
- 132 • **Engineering design:** Behaviors are character-  
133 ized by principles stated in the laws of  
134 physics. Depending on the discipline of  
135 study, engineering design can be further  
136 classified into mechanical, electrical,  
137 chemical, geological, etc.
  - 138 • **Human-centered design:** Behaviors are char-  
139 acterized by physiological, psychological, and  
140 emotional human reactions. Two examples are  
141 architectural design and industrial design.

## Information Flow in Synthesis

142  
143 Figure 3 shows a well-accepted model of the  
144 design process (Schotborgh and van Houten  
145 2012). According to this model, a candidate  
146 solution is generated in a synthesis process. This  
147 candidate solution is then analyzed to calculate  
148 its performance. Finally, the evaluation process  
149 assesses whether the solution is to be adjusted

<sup>[Au2]</sup> 150 (path 1), rejected (path 2), or accepted (path 3). If  
 151 necessary during the adjustment process,  
 152 modifications (small) are made to the candidate  
 153 solution, i.e., without changing the solution  
 154 principle.

155 The flow of information through these pro-  
 156 cesses can be classified into three types of infor-  
 157 mation (Webber ; McMahon 1994): embodiment,  
 158 scenario, and performance. Embodiment regards  
 159 the information that describes the product being  
 160 designed (e.g., its topology, size, and shape).  
 161 Scenario regards the information that describes  
 162 the flow of energy, mass, and signals the  
 163 embodiment is exposed to. Finally, performance  
 164 regards the information that determines how the  
 165 embodiment behaves under a given scenario.

166 The relation between these three types of  
 167 information varies according to the four  
 168 processes of the design process model. In the  
 169 synthesis process, embodiment information is  
 170 generated (i.e., embodiment parameters are cho-  
 171 sen and a candidate solution is formed) such that  
 172 it meets certain performance parameters for  
 173 a given scenario, as shown in Fig. 4b. Conversely,  
 174 in the analysis process performance parameters  
 175 are quantified or qualified for an embodiment  
 176 undergoing a given scenario, as shown in  
 177 Fig. 4a. In the evaluation subprocess, the gener-  
 178 ated performance parameters are used to  
 179 determine what follow-up action should be  
 180 taken (paths 1–3). Finally, in the adjustment  
 181 subprocess small changes to some embodiment  
 182 parameters can be made in order to improve the  
 183 performance of the candidate solution.

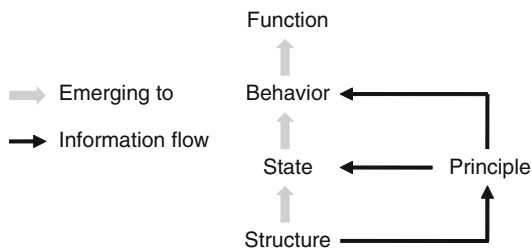
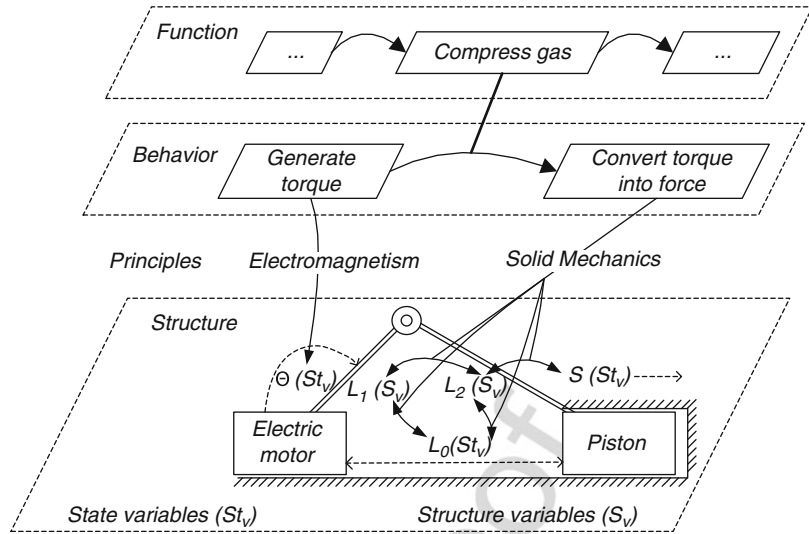
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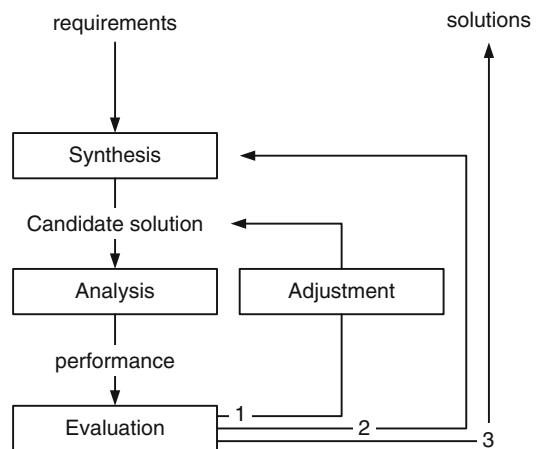
## 184 Cross-References

- 185 ▶ Design  
 186 ▶ Design Methodology  
 187 ▶ Model  
 188 ▶ Process  
 189 ▶ Product

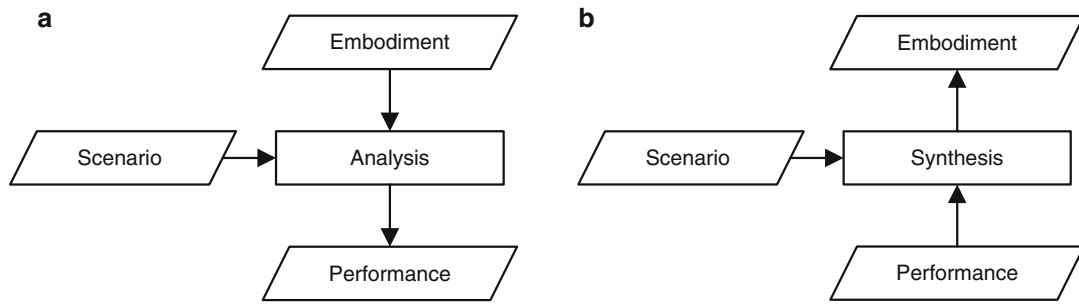
**Cutting Edge Influence on Machining Titanium Alloy, Fig. 1** FBS of a crank compression mechanism



**Cutting Edge Influence on Machining Titanium Alloy, Fig. 2** Relation between function-behavior-principle-state-structure (Zhang et al. 2005)



**Cutting Edge Influence on Machining Titanium Alloy, Fig. 3** Generic model of the design process (Tomiyaama et al. 2009)



**Cutting Edge Influence on Machining Titanium Alloy, Fig. 4** Information flow of analysis technique and synthesis process. (a) Analysis. (b) Synthesis

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