

An explicit solution to the weak Schottky problem

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Abstract

We give an explicit weak solution to the Schottky problem, in the spirit of Riemann and Schottky. For any genus g, we write down a collection of polynomials in genus gtheta constants such that their common zero locus contains the locus of Jacobians of genus g curves as an irreducible component. These polynomials arise by applying a specific Schottky–Jung proportionality to an explicit collection of quartic identities for genus g - 1 theta constants.

1. Introduction

We work throughout over the field of complex numbers. Our main result is the following explicit weak solution to the classical Schottky problem.

THEOREM 1.1 (Main theorem). For any $g \ge 4$, let S_{34} denote the following degree $2^{3 \cdot 2^{g-4}+1}$ polynomial in genus g theta constants, evaluated at some period matrix τ :

$$\begin{split} \prod_{\substack{a_{\varepsilon},b_{\varepsilon},c_{\varepsilon}=\pm 1\\a_{0,\ldots,0}=1}} \sum_{\varepsilon\in(\mathbb{Z}/2\mathbb{Z})^{g-4}} a_{\varepsilon} \left(\theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 1 & 1 & \varepsilon \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 1 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 0 & 1 & \varepsilon \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 1 & 0 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 0 & 1 & \varepsilon \\ 1 & 1 & 0 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 1 & 0 & 0 & \varepsilon \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 1 & \varepsilon \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 1 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 &$$

where $E := \varepsilon_1 + \cdots + \varepsilon_{g-4} \in \mathbb{Z}/2\mathbb{Z}$. For any $3 \leq j < k \leq g$, let S_{jk} be obtained from S_{34} by swapping columns 3 and j and columns 4 and k of the characteristics of all theta constants appearing in the expression.

Then the collection of equations $\{S_{jk} = 0\}_{3 \le j < k \le g}$ gives a weak solution to the Schottky problem; that is, the common zero locus of the modular forms $\{S_{jk}\}_{3 \le j < k \le g}$ contains the Jacobian

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locus as an irreducible component.

Here, and throughout the paper, we write $\mathbf{0}$ and $\mathbf{1}$ for strings of zeroes or ones of appropriate length.

One can say that the theory we deal with here began with Riemann's papers [Rie57, Rie66]. In [Rie66] in particular, it seems clear that Riemann was working towards understanding what we now think of as the Schottky problem, even though the main immediate application was a proof of the Jacobi inversion theorem. The field then blossomed, with a flurry of activity by Krazer, Wirtinger, Noether, Schottky, Frobenius, Baker, and many others—see the many references in [RF74]. In the middle of the twentieth century, the interest in the Schottky problem seems to have waned, probably due to the fact that the length of the identities increased exponentially, and not much new was discovered on the classical Schottky problem. The interest in the subject was then rekindled in the 1970s, in particular by Rauch's rediscovery of [SJ09], where what are now called the Schottky–Jung proportionalities were stated without proof. These were proven rigorously by the first author [Far70], and their connection with the Schottky problem was discussed in [FR70]. A period of intense activity followed, including Mumford's development of the algebraic theory of the theta function and the emergence of relations with integrable systems.

Various approaches to the Schottky problem were developed by the 1980s, and various geometric solutions to the problem were then obtained (surveyed, for example, in [vGe98, Gru12]). Igusa [Igu81] and Freitag [Fre83] showed that Schottky's original equation [Sch88] indeed gives the solution to the Schottky problem in genus 4. Accola [Acc83] gave a collection of equations in theta constants that characterize the Jacobian locus in genus 5, up to additional irreducible components. Arbarello and De Concini [AD84] showed that there exists a finite set of equations in theta constants and their derivatives that characterize Jacobians (however, making them explicit requires the elimination of 3g complex numbers from a system of equations). Shiota [Shi86] proved Novikov's conjecture characterizing Jacobians by their theta function satisfying the KP equation, and various other approaches were developed.

In a spirit closest to the current paper, Van Geemen [vGe84] and Donagi [Don87a] showed that the classical Schottky–Jung approach gave a weak solution to the Schottky problem—however, their results do not lead to explicit equations, as we will explain shortly.

More recently, Krichever [Kri10] proved the celebrated Welters' trisecant conjecture [Wel84], characterizing Jacobians by their Kummer varieties having trisecant lines. We hope that our explicit solution of the weak Schottky problem, motivated by the viewpoint of [RF74], may lead to a further rejuvenation of interest in this classical subject.

We now state the Schottky problem more precisely and motivate our main theorem. Denote by \mathcal{M}_g the moduli space of curves of genus g, denote by \mathcal{A}_g the moduli space of complex, principally polarized abelian varieties (ppavs) of dimension g, and denote by $J: \mathcal{M}_g \to \mathcal{A}_g$ the Torelli morphism. The *Schottky problem* is to characterize *the locus of Jacobians* \mathcal{J}_g , which is defined to be the closure of $J(\mathcal{M}_g)$ in \mathcal{A}_g .

The classical Schottky problem, studied by Riemann and Schottky, is to write down the defining equations for \mathcal{J}_g . More precisely, recall that theta constants with characteristics define an embedding $Th: \mathcal{A}_g(4, 8) \hookrightarrow \mathbb{P}^{2^{g-1}(2^g+1)-1}$ of the level cover of \mathcal{A}_g (see Section 2 for details), and the classical Schottky problem is to determine the defining ideal \mathcal{I}_g^J of $Th(\mathcal{J}_g(4, 8)) \subset Th(\mathcal{A}_g(4, 8))$. The weak Schottky problem is the problem of characterizing the locus of Jacobians up to extra irreducible components. Classically, this means finding an ideal I_g of polynomials in theta constants such that the zero locus of I_g within $Th(\mathcal{A}_g(4, 8))$ contains $Th(\mathcal{J}_g(4, 8))$ as an

irreducible component.

The Schottky problem is non-trivial for $g \ge 4$, and Schottky's original equation solves the classical Schottky problem in genus 4, as discussed above. Despite many approaches to the Schottky problem having been developed, a solution to the classical Schottky problem and its weak version have remained elusive for any genus $q \ge 5$.

The Schottky–Jung proportionalities (reviewed in Section 3) relate theta constants of a genus g Jacobian to the theta constants of its Prym which is a (g-1)-dimensional ppav. More precisely, denote by \mathcal{R}_g the moduli space of connected unramified double covers of smooth genus gcurves, thought of as pairs consisting of a curve $C \in \mathcal{M}_g$ and a non-zero 2-torsion point η on the Jacobian of C. The Prym construction is the map $Pr: \mathcal{R}_g \to \mathcal{A}_{g-1}$, and the Schottky–Jung proportionalities relate the theta constants of $Pr(C, \eta)$ and of C.

Let \mathcal{I}_g^A denote the defining ideal of $Th(\mathcal{A}_g(4,8)) \subset \mathbb{P}^{2^{g-1}(2^g+1)-1}$. Applying the Schottky–Jung proportionalities to each theta constant appearing in a polynomial $P \in \mathcal{I}_{g-1}^A$ yields an element $SJ^{\eta}(P) \in \mathcal{I}_g^J$, which we will call the corresponding Schottky–Jung identity. The *big Schottky* locus is the locus within $Th(\mathcal{A}_g(4,8))$ defined by the equations $SJ^{\eta}(P)$ for all $P \in \mathcal{I}_{g-1}^A$, for one fixed η , while the small Schottky locus is the locus defined by such equations for all possible η . Van Geemen [vGe84] and Donagi [Don87a] showed that the small and the big Schottky loci, respectively, give weak solutions to the Schottky problem, while in [Don87b], Donagi showed that already in genus 5, the big Schottky locus contains an extra irreducible component containing the locus of intermediate Jacobians of cubic threefolds. In the unpublished preprint [Sie13], it is shown that in genus 5, the small Schottky locus is in fact equal to the Jacobian locus.

Note, however, that for $g \ge 3$, the ideal \mathcal{I}_g^A of relations among the theta constants of a general ppav is not known—it is conjectured that it is generated by Riemann's quartic relations (see [FS19] for details), but no approaches to proving this are available. Thus for any $g \ge 5$, the results of Van Geemen and Donagi cannot be made explicit, as one cannot write down a set of generators of \mathcal{I}_{g-1}^A . Our main theorem is thus the first known explicit weak solution to the classical Schottky problem. After our paper appeared on the arXiv, our equations were investigated numerically in genus 5 by Agostini and Chua [AC19].

Our equations S_{jk} arise by applying the Schottky–Jung proportionalities to certain quartic identities in theta constants. We note, however, that while the usually applied case of the Schottky–Jung proportionalities is for the 2-torsion point $\eta_0 := \begin{bmatrix} 0 & \cdots & 0 \\ 1 & 0 & \cdots & 0 \end{bmatrix}$, it turns out (see Remark 5.2) that for our methods, we need to use the 2-torsion point $\eta_g := \begin{bmatrix} 0 & \cdots & 0 \\ 1 & \cdots & 0 \end{bmatrix}$. The polynomials S_{jk} arise by applying the Schottky–Jung proportionalities for η_g to the quartic identity in theta constants given in the following proposition.

PROPOSITION 1.2. For any $g \ge 3$, let R_{34} be the following quartic polynomial in theta constants, all evaluated at some period matrix τ :

$$R_{34} := \sum_{\varepsilon \in (\mathbb{Z}/2\mathbb{Z})^{g-3}} \left(\theta \begin{bmatrix} 0 & 0 & 0 & \varepsilon \\ 0 & 0 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 & \varepsilon \\ 0 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 1 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & \mathbf{0} \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 &$$

Let R_{jk} be obtained by permuting columns 2 and j-1 and columns 3 and k-1 in the expression of R_{34} . Then each R_{jk} vanishes identically in τ ; that is, $R_{jk} \in \mathcal{I}_g^A$.

This proposition is an immediate corollary of the generalized Riemann relations stated

in [Fay79]. See Remark 5.3 for an explanation of why the classical Riemann quartic relation cannot be used instead of R_{34} for our argument.

The Schottky–Jung proportionalities for η_g are given explicitly by (3.4), and since η_g is invariant under any permutation of columns (and this is one reason for our choice of η_g rather than η_0), we obtain Lemma 3.1, the statement that $S_{jk} = SJ^{\eta_g}(R_{jk})$ for any $3 \leq j < k \leq g$. As a corollary, we thus obtain an explicit proof of the main result of Donagi's paper [Don87a], which implies the main result of Van Geemen's paper [vGe84].

COROLLARY 1.3. The big Schottky locus gives a weak solution to the Schottky problem; that is, the common zero locus of $SJ^{\eta_g}(R)$, for all $R \in \mathcal{I}_{g-1}^A$, contains \mathcal{J}_g as an irreducible component.

(Of course we have in fact proven that it is enough to take Riemann's quartic relations, as a subset of \mathcal{I}_{q-1}^A , and among those, to only take those that imply all R_{jk}).

We prove our main theorem, Theorem 1.1, by expanding S_{jk} near the locus of diagonal period matrices and showing that the lowest-degree terms of the expansions give a collection of what are called Poincaré relations. These are infinitesimal (that is, up to terms of higher order) relations satisfied by period matrices of Jacobians that are close to being diagonal. The only such relation in genus 4 was proven by Poincaré [Poi95]. Poincaré states in [Poi95, End of § 11, pp. 298–299] that his relation generalizes to arbitrary genus. Our work gives a complete proof of Poincaré relations for arbitrary Riemann surfaces of arbitrary genus. A different proof is given by Fay [Fay73, Example 3.4, p. 45]. Rauch in [RF74, p. 228] asks whether, in general, one can find Schottky(–Jung) identities that imply Poincaré relations, and, in particular, our work answers this question in the affirmative. By analyzing these lowest-order terms of S_{jk} , we then show that in a neighborhood of a generic diagonal period matrix, these equations are functionally independent, and thus that the common zero locus of all S_{jk} is (3g - 3)-dimensional, which implies that it contains the Jacobian locus as an irreducible component.

The structure of the text is as follows. In Section 2, we fix the notation and review and extend the results of Fay [Fay79] and the third author [Sal85] on the linear span of Riemann's quartic relations. We also show that the identity R_{34} among theta constants holds. In Section 3, we recall the Schottky–Jung proportionalities and give the explicit formula (3.4) for them for the 2-torsion point η_g . In Section 4, we briefly recall the well-known expansion of theta constants near the locus of diagonal period matrices. In Section 5, we recall Poincaré's notion of "infinitesimal" relations for periods of Riemann surfaces near diagonal matrices and prove Theorem 5.1, proving the generalization of Poincaré's relations to arbitrary genus. The proof is by looking at the lowest-order terms of the expansions of our S_{jk} . Finally, in Section 6, we combine all of these ingredients to prove that the S_{jk} are locally functionally independent near \mathcal{D}_g , which implies our main theorem, Theorem 1.1.

2. Riemann's quartic relations and their linear combinations

In this section, we fix the notation for moduli spaces of curves, abelian varieties, and their covers. We then recall the theta constants, their properties, and relations among them; for the details on all of this, we refer to [Igu72] and [RF74].

We denote by $\mathcal{H}_g := \{\tau \in \operatorname{Mat}_{g \times g}(\mathbb{C}) \colon \tau^t = \tau; \operatorname{Im} \tau > 0\}$ the Siegel upper half-space. The quotient $\mathcal{A}_g := \mathcal{H}_g / \operatorname{Sp}(2g, \mathbb{Z})$ is the moduli space of complex principally polarized abelian varieties (ppavs).

For any even ℓ , let $\Gamma_g(\ell) \subset \operatorname{Sp}(2g,\mathbb{Z})$ be the normal subgroup that is the kernel of the map

to $\operatorname{Sp}(2g, \mathbb{Z}/\ell\mathbb{Z})$, and let $\Gamma_g(\ell, 2\ell)$ be the subgroup of $\Gamma_g(\ell)$ consisting of matrices such that the diagonals of A^tB and C^tD (where $\gamma \in \operatorname{Sp}(2g,\mathbb{Z})$ is written in block form $\gamma = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$) are congruent to zero modulo 2ℓ . The level covers of moduli of ppavs are then the quotients $\mathcal{A}_g(\ell) := \mathcal{H}_g/\Gamma_g(\ell)$ and $\mathcal{A}_g(\ell, 2\ell) := \mathcal{H}_g/\Gamma_g(\ell, 2\ell)$ by these level subgroups.

Given $\varepsilon, \delta \in \mathbb{Z}^{g}$, the theta function with characteristics $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$ is defined as

$$\theta\left[\begin{smallmatrix}\varepsilon\\\delta\end{smallmatrix}\right](\tau,z) := \sum_{n \in \mathbb{Z}^g} \exp\left(\pi i(n+\varepsilon/2)^t \left(\tau(n+\varepsilon/2)+z+\delta\right)\right).$$

The theta constant is the evaluation of the theta function at z = 0. We will be mostly concerned with theta constants and will write simply $\theta \begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$ for such, if the variable τ is understood, and z is set to be equal to zero. We will always write the z-variable when dealing with theta functions. The theta constants satisfy the identity $\theta \begin{bmatrix} \varepsilon + 2a \\ \delta + 2b \end{bmatrix} (\tau, 0) = (-1)^{\varepsilon^t b} \theta \begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} (\tau, 0)$ for any $a, b \in \mathbb{Z}^g$, and thus (up to sign) it is often convenient to work with characteristics lying in $(\mathbb{Z}/2\mathbb{Z})^{2g}$. However, we will follow [Fay73] in working with characteristics in \mathbb{Z}^{2g} , which accounts for some sign differences between our formulas and those in the literature. By an abuse of notation, we will write ε , δ as row vectors, but they will be treated as column vectors, as will be all vectors used in calculations. We call ε the top and δ the bottom characteristic, and we say (g)-characteristic when we want to emphasize the dimension in which we are working. A characteristic is called even or odd depending on whether $e(\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}) := \varepsilon^t \cdot \delta$ is even or odd, correspondingly. All theta constants with odd characteristics vanish identically in τ .

Notation 2.1. For convenience, we denote by $K_g = (\mathbb{Z}/2\mathbb{Z})^{2g}$ the set of characteristics, denote by $K_g^+, K_g^- \subset K_g$ the sets of even and odd characteristics, respectively, and let $k_g^{\pm} := 2^{g-1}(2^g \pm 1)$ be the cardinalities of the sets K_g^{\pm} .

We define the action of $\operatorname{Sp}(2g, \mathbb{Z})$ on characteristics via

$$\gamma \circ \begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} := \begin{pmatrix} D & -C \\ -B & A \end{pmatrix} \begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} + \begin{bmatrix} \operatorname{diag}(CD^t) \\ \operatorname{diag}(AB^t) \end{bmatrix};$$

the theta constants then satisfy the following transformation formula (see [Igu72]):

$$\begin{aligned} \theta\left[\gamma\circ\left[\begin{smallmatrix}\varepsilon\\\delta\end{smallmatrix}\right]\right](\gamma\circ\tau) &= \kappa(\gamma)\sqrt{\det(C\tau+D)}\theta\left[\begin{smallmatrix}\varepsilon\\\delta\end{smallmatrix}\right](\tau)\\ &\cdot\exp\left((-\pi i/4)\varepsilon^tD^tB\varepsilon - 2\delta C^tB\varepsilon + \delta^tC^tA\delta - 2(D\varepsilon^t - C\delta^t)\operatorname{diag}\left(AB^t\right)\right), \end{aligned}$$

where κ is some eighth root of unity independent of the characteristic $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$. It moreover turns out that $\kappa(\gamma) = 1$ for any $\gamma \in \Gamma_g(4, 8)$, and thus each theta constant is a modular form with respect to $\Gamma_g(4, 8)$, which is to say that

$$\theta\left[\begin{smallmatrix}\varepsilon\\\delta\end{smallmatrix}\right](\gamma\circ\tau)=\sqrt{\det(C\tau+D)}\theta\left[\begin{smallmatrix}\varepsilon\\\delta\end{smallmatrix}\right](\tau)$$

for any $\gamma \in \Gamma_g(4,8)$ (where the square root can in fact be chosen globally). The map sending a ppav to the set of all even theta constants then defines an embedding

$$Th: \mathcal{A}_q(4,8) \hookrightarrow \mathbb{P}^{2^{g-1}(2^g+1)-1}.$$

The classical, and still unsolved, question of determining all relations among theta constants is the question of determining the defining ideal \mathcal{I}_g^A of $Th(\mathcal{A}_g(4,8)) \subset \mathbb{P}^{2^{g-1}(2^g+1)-1}$. The only known relations among theta constants are Riemann's quartic relations. To write them, recall the Weil pairing of two characteristics $m = \begin{bmatrix} \varepsilon_1 \\ \delta_1 \end{bmatrix}$ and $n = \begin{bmatrix} \varepsilon_2 \\ \delta_2 \end{bmatrix}$ defined by

$$e(m,n) := (-1)^{\varepsilon_1^t \cdot \delta_2 - \varepsilon_2^t \cdot \delta_1}$$

We recall from [Fay79] the following special case of (the generalized) Riemann's theta formula. Let $A \subset K_g$ be a subgroup of order 2^{g-m} , and let B be the orthogonal group with respect to the symplectic form, that is, $B := \{m \in K_g : e(m, n) = 1 \text{ for all } n \in A\}$. Then the following identity holds:

$$2^{m} \sum_{\substack{\left[\begin{smallmatrix}\varepsilon\\\delta\right]\in A}} e(\left[\begin{smallmatrix}\varepsilon\\\delta\right]\right)(-1)^{\delta^{t}(\alpha+\sigma)}\theta\left[\begin{smallmatrix}\varepsilon\\\delta\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha\\\delta+\beta\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha\\\delta+\mu\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha+\sigma\\\delta+\beta+\mu\right]\right]$$
$$= \sum_{\substack{\left[\begin{smallmatrix}\varepsilon\\\delta\right]\in B}} e(\left[\begin{smallmatrix}\varepsilon\\\delta\right]\right)(-1)^{\delta^{t}(\alpha+\sigma)}\theta\left[\begin{smallmatrix}\varepsilon\\\delta\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha\\\delta+\beta\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha\\\delta+\beta\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha+\sigma\\\delta+\mu\right]\theta\left[\begin{smallmatrix}\varepsilon+\alpha+\sigma\\\delta+\beta+\mu\right]\right].$$
(2.1)

Proof of Proposition 1.2. To prove that R_{34} lies in \mathcal{I}_q^A , we simply apply (2.1) for

$$A := \left\{ \begin{bmatrix} 0 & 0 & 0 & \varepsilon \\ 0 & 0 & 0 & 0 \end{bmatrix} \text{ for all } \varepsilon \in (\mathbb{Z}/2\mathbb{Z})^{g-3} \right\},$$
$$\begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 & 0 & \dots & 0 \\ 1 & 0 & 0 & \dots & 0 \end{bmatrix}, \quad \begin{bmatrix} \sigma \\ \mu \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \end{bmatrix}.$$

Let V_0 be the 2-dimensional subspace of K_g spanned by $\begin{bmatrix} \alpha \\ \beta \end{bmatrix}$ and $\begin{bmatrix} \sigma \\ \mu \end{bmatrix}$, and set $V_1 := V_0 + \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \end{bmatrix}$, $V_2 := V_0 + \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \end{bmatrix}$, and $V = V_0 \cup V_1 \cup V_2$. Unless all theta constants appearing in the monomial in the sum in the right-hand side of (2.1) are even, such a summand vanishes. Thus the only non-vanishing summands are those when $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} \in A + V$; that is, $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$ can be written as the sum of a characteristic lying in A and a characteristic lying in V. Moreover, the summands in the right-hand-side are the same for all $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} \in V_i + m$, for $m \in A$ fixed.

This gives, up to a factor 4, precisely the expression for R_{34} given by formula (1.1), and thus R_{34} lies in \mathcal{I}_g^A . Furthermore, each R_{jk} is obtained from R_{34} by permuting some columns of the characteristics. This permutation can of course be obtained by the action of some element γ of the symplectic group, and since \mathcal{I}_g^A is invariant under $\operatorname{Sp}(2g,\mathbb{Z})$, it follows that also $R_{jk} = \gamma \circ R_{34} \in \mathcal{I}_q^A$.

As an example (and to highlight how sign conventions differ depending on whether one writes characteristics as elements of \mathbb{Z} or of $\mathbb{Z}/2\mathbb{Z}$), consider the case of genus g = 3. Equation (2.1) then reads

$$\begin{split} &8\theta \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix} \\ &+ 4\theta \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 2 \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 2 \end{bmatrix} . \end{split}$$

Converting to characteristics in $\mathbb{Z}/2\mathbb{Z}$, this gives the classical form of Riemann's quartic addition theorem, see [vGe98],

$$\theta \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$= \theta \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} - \theta \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} .$$

$$(2.2)$$

Remark 2.2. This genus 3 case of Riemann's quartic addition theorem can be considered as an alternative starting point for our constructions, using only Riemann's quartic addition theorem.

Consider the square matrix M(g) of size 2^{2g} whose entries are the Weil pairings of all pairs of characteristics $m, n \in K_q$, which we write as

$$M(g) := \begin{pmatrix} M^+(g) & N(g) \\ N(g)^t & M^-(g) \end{pmatrix},$$

where the set of characteristics is ordered in such a way that the k_g^+ even characteristics in the set K_g^+ appear before the k_g^- odd ones. Recall that by [Sal85], all quartic identities in theta constants are related to the eigenvectors of eigenvalue -2^{g-1} of the matrix $M^+(g)$.

It turns out that there is a simple procedure, which we call the *doubling principle*, that constructs these eigenvectors recursively from the eigenvectors of eigenvalue -2^{g-2} of the matrix $M^+(g-1)$. In fact, this -2^{g-1} -eigenspace of $M^+(g)$ is equal to the direct sum of vector spaces $U_1 \oplus U_2 \oplus U_3 \oplus U_4$, where

- U_1 and U_2 are spanned by the vectors of the form

 $u_1 := (X, X, 0, 0)^t$ and $u_2 := (X, 0, X, 0)^t$,

respectively, for X any -2^{g-2} -eigenvector of $M^+(g-1)$;

- U_3 is spanned by the vectors of the form $u_3 := (X, 0, 0, Y)^t$, for $\begin{pmatrix} X \\ Y \end{pmatrix}$ any -2^{g-1} -eigenvector of M(g-1); and
- U_4 is spanned by the vectors of the form $u_4 := (X, -X, -X, 0)^t$, for X any 2^{g-1} -eigenvector of $M^+(g-1)$.

It then turns out that the quartic relation R_{34} in any genus can be obtained by repeatedly applying this doubling principle starting from to (2.2) in genus 3, which gives an alternative proof of Proposition 1.2.

3. The Schottky–Jung proportionalities

We denote by $\mathcal{M}_g(4,8)$ the fiber product of \mathcal{M}_g and $\mathcal{A}_g(4,8)$ over \mathcal{A}_g under the Torelli map and the forgetful morphism. By an abuse of notation, we also denote by $J: \mathcal{M}_g(4,8) \to \mathcal{A}_g(4,8)$ the lift of the Torelli map.

The Schottky–Jung proportionalities relate the theta constants of the Jacobian and of the Prym. They were discovered in [SJ09], rigorously proven to hold in [Far70, FR70], and recast algebraically by Mumford in [Mum74]. See the surveys [Don88, Bea89] for the details of the Schottky–Jung approach and [Far12] for a survey on Pryms. The Schottky–Jung proportionalities for an arbitrary 2-torsion point η , as a relation between modular forms, is described explicitly in [vGe98].

Denote by \mathcal{R}_g the moduli space of pairs (C, η) , where $C \in \mathcal{M}_g$ and $\eta \in J(C)[2] \setminus \{0\}$ is a nonzero 2-torsion point on the Jacobian. Such a point η defines an unramified connected double cover $\tilde{C} \to C$, and the Prym $Pr(C, \eta)$ is then defined to be the connected component of the kernel of the map $J(\tilde{C}) \to J(C)$. The Prym turns out to have a natural principal polarization, so that the construction defines a morphism $Pr: \mathcal{R}_q \to \mathcal{A}_{q-1}$. For the 2-torsion point

$$\eta_0 := \begin{bmatrix} 0 & 0 & \dots & 0 \\ 1 & 0 & \dots & 0 \end{bmatrix}, \tag{3.1}$$

the Schottky–Jung proportionalities are the equalities

$$\theta^{2} \begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} (Pr(C, \eta_{0})) = c \theta \begin{bmatrix} 0 & \varepsilon \\ 0 & \delta \end{bmatrix} (J(C)) \theta \begin{bmatrix} 0 & \varepsilon \\ 1 & \delta \end{bmatrix} (J(C)), \qquad (3.2)$$

which hold for some non-zero constant c independent of $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$.

For our purposes, the combinatorics is such that we will need the explicit form of the Schottky– Jung proportionalities for the 2-torsion point

$$\eta_g := \begin{bmatrix} 0 & 0 & \dots & 0 \\ 1 & 1 & \dots & 1 \end{bmatrix}. \tag{3.3}$$

In [Far89], the case of Schottky–Jung proportionalities for $\eta' = \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 1 & 1 & 0 & \dots & 0 \end{bmatrix}$ was studied explicitly, and it turns out that additional signs depending on $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$ appear. We will not be able to track the signs anyway, and only the characteristics appearing in the proportionality will play a role. The Schottky–Jung proportionalities for arbitrary η , as relations between modular forms, are described explicitly by Van Geemen in [vGe98], as we now quickly recall.

Since $\operatorname{Sp}(2g, \mathbb{Z}/2\mathbb{Z})$ acts transitively on $J(C)[2] \setminus \{0\}$, acting on the Schottky–Jung proportionalities (3.2) for η_0 by an element of the symplectic group that sends η_0 to η , one obtains the general case of the Schottky–Jung proportionalities. For a given η , one has an isomorphism $j: Pr(C,\eta)[2] \to V/\eta$, where $Pr(C,\eta)[2]$ is the set of 2-torsion points of the Prym, and $V = \eta^{\perp} \subset K_g$ is the set of all v such that the symplectic pairing $e(\eta, v)$ is 0. Then for any $[\frac{\varepsilon}{\delta}] \in Pr(C,\eta)[2]$, the characteristics appearing in the right-hand-side of Schottky–Jung proportionalities for η would be $j([\frac{\varepsilon}{\delta}])$ and $\eta + j([\frac{\varepsilon}{\delta}])$.

Note that the proportionalities depend on the choice of j; as this was never explained in the literature, we make this precise. A choice of a basis of $J(\tilde{C})[2]$ gives the lifting (denoted by π^* by Mumford) $Pr(C,\eta)[2] \to J(\tilde{C})[2]$, and j is then obtained by composing this with the projection to J(C)[2]. Thus any choice of j can arise; the standard choice for η_0 is to embed $(\mathbb{Z}/2\mathbb{Z})^{2g-2}$ into K_g as the characteristics with first column equal to $\begin{bmatrix} 0\\0 \end{bmatrix}$.

For our choice of η_q , we will choose j to be

$$j\left(\begin{bmatrix}\varepsilon_1\dots\varepsilon_{g-1}\\\delta_1\dots\delta_{g-1}\end{bmatrix}\right) := \begin{bmatrix}\varepsilon_1+\dots+\varepsilon_{g-1}&\varepsilon_1\dots&\varepsilon_{g-1}\\0&\delta_1\dots&\delta_{g-1}\end{bmatrix}.$$

Then the Schottky–Jung proportionalities take the explicit form

$$\theta^{2} \begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} (Pr(C, \eta_{g})) = \pm c \, \theta \begin{bmatrix} \sum_{i} \varepsilon_{i} & \varepsilon_{i} & \cdots & \varepsilon_{g-1} \\ 0 & \delta_{1} & \cdots & \delta_{g-1} \end{bmatrix} (J(C)) \cdot \theta \begin{bmatrix} \sum_{i} \varepsilon_{i} & \varepsilon_{1} & \cdots & \varepsilon_{g-1} \\ 1 & 1+\delta_{1} & \cdots & 1+\delta_{g-1} \end{bmatrix} (J(C)) , \qquad (3.4)$$

which we will use from now on—where the sign depends on $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix}$.

The classical approach to the Schottky problem is as follows. Given any equation $P \in \mathcal{I}_{g-1}^A$, note that P is satisfied by the theta constants of $P(C, \eta)$ for any $(C, \eta) \in \mathcal{R}_g$. Replacing in the polynomial P each theta constant of $Pr(C, \eta)$ with the square root of the product of the two corresponding theta constants of J(C) given by the Schottky–Jung proportionalities gives a polynomial in the square roots of genus g theta constants of J(C). Since the square roots cannot be chosen globally, to make this a well-defined relation, we take the product of the results of such substitutions for all possible choices of the values of square roots of the monomials involved except choosing one square root of one monomial to be given (or otherwise one obtains each factor twice, once with plus and once with minus sign). We denote this product by $SJ^{\eta}(P)$ and call it the Schottky–Jung identity corresponding to P and η . It is then a polynomial in genus g theta constants, of degree equal to the degree of P times 2 raised to the power equal to the number of monomials in P minus 1, and Schottky–Jung proportionalities imply that $SJ^{\eta}(P) \in \mathcal{I}_q^J$.

The simplest non-trivial case of this is for g = 4: the genus 3 Riemann's quartic relation involves three monomials and has the form $r_1 - r_2 + r_3 = 0$, where each r_i is a product of four genus 3 theta constants. Applying the Schottky–Jung proportionalities gives $\sqrt{R_1} - \sqrt{R_2} - \sqrt{R_3} = 0$, where each R_i is a product of eight theta constants evaluated at $\tau \in J(C)$. To obtain a polynomial in theta constants, one needs to take the product $(\sqrt{R_1} + \sqrt{R_2} + \sqrt{R_3})(\sqrt{R_1} - \sqrt{R_2} + \sqrt{R_3})(\sqrt{R_1} - \sqrt{R_2} - \sqrt{R_3})(\sqrt{R_1} - \sqrt{R_2} - \sqrt{R_3})$, which is equal to

$$SJ^{\eta}(r_1 - r_2 + r_3) = R_1^2 + R_2^3 + R_3^2 - 2R_1R_2 - 2R_1R_3 - 2R_2R_3 = 0, \qquad (3.5)$$

which is a degree 16 *polynomial* in theta constants of the genus 4 Jacobian J(C). This equation was discovered by Schottky and was rigorously proven by Igusa [Igu81] and Freitag [Fre83] to

generate \mathcal{I}_4^J , that is, to be the unique defining equation for $Th(\mathcal{J}_4) \subset Th(\mathcal{A}_4)$.

In our case, applying Schottky–Jung proportionalities for η_g to R_{jk} gives the following.

LEMMA 3.1. For any $3 \leq j < k \leq g$, the identity $S_{jk} = SJ^{\eta_g}(R_{jk})$ holds.

Proof. Indeed, applying the Schottky–Jung proportionalities (3.4) to R_{34} , one obtains an expression in square roots of theta constants that is one of the factors in S_{34} , and then taking the product over all possible choices of square roots gives exactly the product given by S_{34} , so that $S_{34} = SJ^{\eta_g}(R_{34})$. Since the columns number $3, \ldots, g$ of η_g are all equal, permuting columns 3 and j and columns 4 and k gives the desired equality for all j and k.

4. Expansion of theta constants near the diagonal

The locus \mathcal{J}_g contains the locus of ppavs that are products of g elliptic curves. Explicitly, we think of this locus as the image in \mathcal{A}_g of the locus $\mathcal{D}_g \subset \mathcal{H}_g$ consisting of diagonal period matrices $\mathcal{D}_g := \{\tau = \text{diag}(t_1, t_2, \ldots, t_g)\}$. The proof of Theorem 1.1 will consist of showing that the S_{jk} are locally functionally independent near \mathcal{D}_g , by computing the lowest-order term of their expansions. We thus recall the expansion of theta constants near the diagonal, which was used by Rauch [Rau71] in his genus 4 computations.

First recall that the theta constant of a diagonal period matrix decomposes as a product:

$$\theta\left[\begin{smallmatrix}\varepsilon\\\delta\end{smallmatrix}\right]\left(\operatorname{diag}(t_1,t_2,\ldots,t_g)\right) = \theta\left[\begin{smallmatrix}\varepsilon_1\\\delta_1\end{smallmatrix}\right](t_1)\cdot\ldots\cdot\theta\left[\begin{smallmatrix}\varepsilon_g\\\delta_g\end{smallmatrix}\right](t_g).$$

Recall further for any j < k the heat equation

$$\frac{\partial \theta \left[\begin{smallmatrix} \varepsilon \\ \delta \end{smallmatrix}\right]}{\partial \tau_{jk}} = \frac{1}{2\pi i} \frac{\partial^2 \theta \left[\begin{smallmatrix} \varepsilon \\ \delta \end{smallmatrix}\right]}{\partial z_j z_k} \,.$$

We then evaluate for any j < k the partial derivative

$$\frac{\partial \theta\left[\frac{\delta}{\delta}\right]}{\partial \tau_{jk}}|_{\tau=\operatorname{diag}(t_{1},t_{2},\ldots,t_{g})} = \frac{1}{2\pi i} \theta\left[\frac{\varepsilon_{1}}{\delta_{1}}\right](t_{1})\cdot\ldots\cdot\theta\left[\frac{\varepsilon_{j-1}}{\delta_{j-1}}\right](t_{j-1})$$
$$\cdot \frac{\partial \theta\left[\frac{\varepsilon_{j}}{\delta_{j}}\right](t_{j},z)}{\partial z}|_{z=0}\cdot\theta\left[\frac{\varepsilon_{j+1}}{\delta_{j+1}}\right](t_{j+1})\cdot\ldots\cdot\theta\left[\frac{\varepsilon_{k-1}}{\delta_{k-1}}\right](t_{k-1})$$
$$\cdot \frac{\partial \theta\left[\frac{\varepsilon_{k}}{\delta_{k}}\right](t_{k},z)}{\partial z}|_{z=0}\cdot\theta\left[\frac{\varepsilon_{k+1}}{\delta_{k+1}}\right](t_{k+1})\cdot\ldots\cdot\theta\left[\frac{\varepsilon_{g}}{\delta_{g}}\right](t_{g}).$$

Since all genus 1 theta functions are even except that with characteristic $\begin{bmatrix} 1\\1 \end{bmatrix}$, this partial derivative vanishes unless $\begin{bmatrix} \varepsilon_j\\\delta_j \end{bmatrix} = \begin{bmatrix} \varepsilon_k\\\delta_k \end{bmatrix} = \begin{bmatrix} 1\\1 \end{bmatrix}$.

Thus, expanding theta constants in Taylor series in τ_{jk} near \mathcal{D}_g , for t_1, \ldots, t_g fixed, we see that the constant and linear terms are

$$\theta\begin{bmatrix}\varepsilon\\\delta\end{bmatrix}(\tau) = \theta\begin{bmatrix}\varepsilon_1\\\delta_1\end{bmatrix}(t_1)\cdot\ldots\cdot\theta\begin{bmatrix}\varepsilon_g\\\delta_g\end{bmatrix}(t_g) + \frac{1}{2\pi i}\sum_{\substack{j< k, \begin{bmatrix}\varepsilon_j\\\delta_j\end{bmatrix} = \begin{bmatrix}\varepsilon_k\\\delta_k\end{bmatrix} = \begin{bmatrix}1\\1\end{bmatrix}}}\tau_{jk}\cdot\frac{\partial\theta\begin{bmatrix}1\\1\end{bmatrix}(t_j,z)}{\partial z}|_{z=0}\cdot\frac{\partial\theta\begin{bmatrix}1\\1\end{bmatrix}(t_k,z)}{\partial z}|_{z=0}\cdot\prod_{m\neq j,k}\theta\begin{bmatrix}\varepsilon_m\\\delta_m\end{bmatrix}(t_m), \quad (4.1)$$

and the full Taylor series expansion includes further monomials in τ_{jk} that are of total degree 2 or higher. Note that if no column $\begin{bmatrix} \varepsilon_m \\ \delta_m \end{bmatrix}$ is equal to $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, then the Taylor series has a non-zero constant term and zero linear term. If precisely two different columns $\begin{bmatrix} \varepsilon_j \\ \delta_j \end{bmatrix}$ and $\begin{bmatrix} \varepsilon_k \\ \delta_k \end{bmatrix}$ are equal

to $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, then the Taylor series has zero constant term, and the linear term is a multiple of τ_{jk} . Finally, if more than two columns are equal to $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$, then both the constant and linear terms of the Taylor series are zero, and in fact the lowest-order term has degree equal to half the number of columns equal to $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

Furthermore, by Jacobi's triple product identity in genus 1

$$\frac{\partial \theta \begin{bmatrix} 1\\1 \end{bmatrix} (t,z)}{\partial z} \Big|_{z=0} = -\pi \theta \begin{bmatrix} 0\\0 \end{bmatrix} (t) \theta \begin{bmatrix} 0\\1 \end{bmatrix} (t) \theta \begin{bmatrix} 1\\0 \end{bmatrix} (t) , \qquad (4.2)$$

the linear term can be written in terms of theta constants of t_i and t_k .

5. Poincaré relations

The Poincaré relation in genus 4 was discovered by Poincaré [Poi95]; it is an infinitesimal relation for period matrices of Jacobians near \mathcal{D}_g —Poincaré calls it an "approximate identity." Rather than thinking of it as being the lowest-order terms of a suitable power series expansion, Poincaré derived it from something he called a "translation surface." Poincaré then stated that his proof in genus 4 could be easily generalized to higher genus but gave no details. Garabedian [Gar51] proved the Poincaré relations for some special Riemann surfaces, in arbitrary genus.

Rauch in [Rau71] reproved the original Poincaré relation in genus 4 by expanding a suitable genus 4 Schottky–Jung identity near \mathcal{D}_4 , and in [RF74, Appendix 2] asked whether Poincaré relations for any genus could be obtained in a similar way. While Fay [Fay73] proved the Poincaré relation in any genus, we give a new direct proof in the spirit of Rauch, obtaining it by expanding S_{jk} (see Remark 5.3 for a discussion of why using Riemann's quartic relations instead of R_{ik} would not work).

The Poincaré relations are the following equations for the off-diagonal elements of the period matrix, for all i < j < k < l:

$$(\tau_{ij}\tau_{jk}\tau_{kl}\tau_{li})^{1/2} \pm (\tau_{ik}\tau_{kl}\tau_{lj}\tau_{ji})^{1/2} \pm (\tau_{il}\tau_{lj}\tau_{jk}\tau_{ki})^{1/2} = O(\varepsilon^3).$$
(5.1)

Note that the Poincaré relations do not depend on the diagonal entries t_m of the period matrix, which is a priori surprising.

Similarly to the case of Schottky–Jung proportionalities, the signs of the square roots in the Poincaré relation may not be chosen globally, and to get a well-defined polynomial equation in the entries of the period matrix, one multiplies the relations (5.1) for all four possible choices of square roots—this was explained by Igusa [Igu82, § 1.5, p. 167]. As in the derivation of (3.5), if we denote the three terms in the Poincaré relation by $\sqrt{P_1}$, $\sqrt{P_2}$, $\sqrt{P_3}$, the resulting equation that is polynomial in the entries of the period matrix has the form

$$P_1^2 + P_2^2 + P_3^2 - 2P_1P_2 - 2P_1P_3 - 2P_2P_3 = O(\varepsilon^9).$$
(5.2)

We prove the Poincaré relations by expanding the factors of S_{jk} near \mathcal{D}_g .

THEOREM 5.1. Let C be any curve in \mathcal{M}_g sufficiently close to a union of g elliptic curves. Then after an appropriate choice of A and B cycles, the period matrix τ of J(C) satisfies all Poincaré relations (5.1).

In genus 4 there is a unique Poincaré relation, for the quadruple (ijkl) = (1234). We first present a streamlined version of Rauch's computation in [Rau71] deriving it from a Schottky–Jung identity.

Proof of Theorem 5.1 in genus 4. Applying the Schottky–Jung proportionalities for η_4 , given by (3.4), to relation (2.2) gives the identity

 $0 = s_{34} :=$

$$\begin{pmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0$$

Denoting by RR_1 , RR_2 , RR_3 the three degree 8 monomials in theta constants appearing here, we now use the expansion (4.1) for each theta constant involved in s_{34} , computing up to linear terms in τ_{ab} , for all t_m fixed. Note that for each monomial RR_i , four of the theta characteristics involved have all columns being even 1-characteristics, and the remaining four theta characteristics have precisely two columns equal to $\begin{bmatrix} 1\\1 \end{bmatrix}$. As discussed in the previous section, for those four theta constants where all columns are even, the lowest-degree term of the expansion is the constant term, while for the remaining four theta constants, the lowest-degree term is linear and equal to a multiple of τ_{ab} , with columns $\begin{bmatrix} \varepsilon_a \\ \delta_a \end{bmatrix} = \begin{bmatrix} \varepsilon_b \\ \delta_b \end{bmatrix} = \begin{bmatrix} 1\\1 \end{bmatrix}$. For example, for RR_1 in the sixth characteristic involved, we get the term with τ_{12} ; in the seventh characteristic, the term with τ_{24} ; in the fourth, τ_{34} ; and in the eighth, τ_{13} . We thus compute the lowest-degree term of the expansion of RR_1 near \mathcal{D}_4 to be the product of these four linear terms and the four constant terms from the expansion of the other theta constants. By checking that the number of times in each product RR_i that each column $\begin{bmatrix} \varepsilon_m \\ \delta_m \end{bmatrix}$ is equal to each of the even 1-characteristics is equal to two, this gives for the lowest-degree term

$$RR_{1} = (2\pi i)^{-4} \tau_{12} \tau_{24} \tau_{34} \tau_{13}$$
$$\cdot \prod_{m=1}^{4} \left(\theta \begin{bmatrix} 0 \\ 0 \end{bmatrix} (t_{m}) \theta \begin{bmatrix} 0 \\ 1 \end{bmatrix} (t_{m}) \theta \begin{bmatrix} 1 \\ 0 \end{bmatrix} (t_{m}) \right)^{2} \prod_{m=1}^{4} \left(\frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \right)^{2} \cdot \frac{\partial \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_{m}, z)}{\partial z} |_{z=0} \Big|_{z=0} \Big|_{z$$

The lowest-order terms of RR_2 and RR_3 are similar. They have exactly the same factor in theta constants and derivatives, while the entries of the period matrix that appear are

 $\tau_{13}\tau_{23}\tau_{24}\tau_{14}$

from the second, sixth, seventh, and fourth theta constants appearing in the product RR_2 , and similarly

$\tau_{14}\tau_{34}\tau_{12}\tau_{23}$

for RR_3 . Using Jacobi's triple product identity (4.2), we see that the overall theta factor in each of these is simply equal to the product

$$c := \prod_{m=1}^{4} \prod_{ \left[\begin{smallmatrix} \varepsilon \\ \delta \end{smallmatrix} \right] \in K_1^+} \theta^4 \left[\begin{smallmatrix} \varepsilon \\ \delta \end{smallmatrix} \right] (t_m) \,,$$

which is non-zero for any t_1 , t_2 , t_3 , t_4 in the upper half-plane. Up to this common factor, the square root of the lowest-degree term of the expansion of each RR_i is then equal to the corresponding summand in the Poincaré relation (5.1) for the quadruple (1234). Thus, altogether, we have computed the lowest-order term of the expansion

$$s_{34} = c \left(\pm (\tau_{34}\tau_{12}\tau_{24}\tau_{13})^{1/2} \pm (\tau_{13}\tau_{14}\tau_{23}\tau_{24})^{1/2} \pm (\tau_{12}\tau_{14}\tau_{23}\tau_{34})^{1/2} \right) + O(\varepsilon^3) \,.$$

Now recall that in genus 4, the identity S_{34} is obtained as a product of four factors of the form s_{34} , with different choices of signs. The expansion of each such factor near the diagonal is as above,

with suitable choices of signs, and thus the expansion of the product of the four factors gives exactly the Poincaré relation in its polynomial form (5.2).

Remark 5.2. Many other choices of 3-characteristics for the genus 3 Riemann's quartic relation, instead of (2.2), and different choices of η would also yield a Schottky–Jung identity that would work in the above proof. One just needs to make sure that in each resulting RR_i , precisely four theta characteristics have all columns even and the remaining four characteristics have precisely two columns equal to $\begin{bmatrix} 1\\1 \end{bmatrix}$. For generalizing to higher genus, to be able to deal with the small Schottky locus rather than the big Schottky, we need to use the same 2-torsion point η for all proportionalities, and thus in our approach the 3rd, 4th, ..., gth columns of η should all be equal, so that permuting them would leave η invariant. The computationally simplest choice of such a 2-torsion point could be $\begin{bmatrix} 000...0\\110...0\end{bmatrix}$, but using a computer, we checked that for all possible Riemann's quartic relations in genus 3, applying the Schottky–Jung identity where the columns of RR_1 , RR_2 , RR_3 satisfy this necessary combinatorial property. Thus our choice of η_g is the simplest possible.

We now generalize this computation to arbitrary genus; note that this of course uses the specifics of our choice of quartic identities R_{jk} and of the corresponding Schottky–Jung identities S_{jk} .

Proof of Theorem 5.1 for arbitrary genus. The proof is again by computing the lowest-order terms of the appropriate expansions and crucially noticing that the cases when some of the $\varepsilon_5, \ldots, \varepsilon_g$ are equal to 1 lead to higher-order terms, as some of the theta constants involved in s_{34} then have more $\begin{bmatrix} 1\\1 \end{bmatrix}$ columns. Recall that S_{34} is the product of $2^{3 \cdot 2^{g-4}-1}$ terms of the form

$$s_{34} := \sum_{\varepsilon \in (\mathbb{Z}/2\mathbb{Z})^{g-4}} \left(a_{\varepsilon} \left(\theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 1 & 1 & \varepsilon \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 1 & 1 & 1 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 0 & 1 & 0 & 1 & 0 & 1 \end{bmatrix} \right)^{1/2} \\ + b_{\varepsilon} \left(\theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 0 & 1 & \varepsilon \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 1 & 0 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 0 & 1 & 0 & \varepsilon \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \right)^{1/2} \\ \cdot \theta \begin{bmatrix} E & 1 & 1 & 0 & \varepsilon \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 1 & 1 & 0 & \varepsilon \\ 1 & 1 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 1 & 0 & 1 & \varepsilon \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 1 & 0 & 1 & \varepsilon \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \right)^{1/2} \\ + c_{\varepsilon} \left(\theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 0 & \varepsilon \\ 0 & 1 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 0 & 1 & \varepsilon \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix} \theta \begin{bmatrix} E & 0 & 1 & 1 & \varepsilon \\ 0 & 1 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 0 & 0 & \varepsilon \\ 1 & 0 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 1 & 0 & 1 & 1 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 0 & 1 & 1 & 0 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \theta \begin{bmatrix} 1+E & 1 & 1 & 1 & \varepsilon \\ 1 & 0 & 0 & 1 & 1 \end{bmatrix} \right)^{1/2}$$

for different choices of the signs a_{ε} , b_{ε} , c_{ε} . If $\varepsilon = \mathbf{0}$, then for all theta constants involved in the three corresponding summands in s_{34} , in columns $5, \ldots, g$ only characteristics $\begin{bmatrix} 0\\0 \end{bmatrix}$ and $\begin{bmatrix} 0\\1 \end{bmatrix}$ appear. Thus the lowest-order term for the expansion near \mathcal{D}_g of each theta constant involved is simply equal to the lowest term of the expansion of the genus 4 theta constant with the first four columns as characteristics, times the suitable product of theta constants of t_5, \ldots, t_g . Since in each of the three summands, each of the columns $5, \ldots, g$ takes each of the values $\begin{bmatrix} 0\\0 \end{bmatrix}$ and $\begin{bmatrix} 0\\1 \end{bmatrix}$ exactly four times, the lowest-order term of the expansion near \mathcal{D}_g of each of the three terms with $\varepsilon = \mathbf{0}$ is equal to the expansion near \mathcal{D}_4 of the corresponding term in genus 4, times a factor of $\prod_{m=5}^g \theta^2 \begin{bmatrix} 0\\0 \end{bmatrix} (t_m) \theta^2 \begin{bmatrix} 0\\1 \end{bmatrix} (t_m)$ —which is the same for these three terms.

If any of the $\varepsilon_5, \ldots, \varepsilon_g$ are equal to 1, then in each of the three summands appearing in the expression for s_{34} for such ε , four of the theta characteristics—those that have 1 on the

bottom—will have extra columns equal to $\begin{bmatrix} 1\\1 \end{bmatrix}$. Thus the lowest-order term for the expansion of such a summand near \mathcal{D}_g would be of higher order, as explained after formula (4.1).

Hence, in the expansion of s_{34} near \mathcal{D}_g , the only terms of degree 4 in $\tau_{ab}^{1/2}$ arise from the case $\varepsilon_5 = \cdots = \varepsilon_g = 0$, and they are equal to the expansion of the expression for s_{34} in genus 4, times $\prod_{m=5}^{g} \theta^2 \begin{bmatrix} 0 \\ 0 \end{bmatrix} (t_m) \theta^2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} (t_m)$. Thus, the lowest-order term of the expansion near \mathcal{D}_g of S_{34} —which is a product of $2^{3 \cdot 2^{g-4}-1}$ terms of the form s_{34} , with different choices of signs—is equal to the lowest-order term of the expansion of S_{34} in genus 4, taken to the power $2^{3 \cdot 2^{g-4}-3}$ (corresponding to the choices of signs a_{ε} , b_{ε} , c_{ε} for all $\varepsilon \neq \mathbf{0}$, which do not change the lowest-order term of s_{34}), times a power of $\prod_{m=5}^{g} \theta \begin{bmatrix} 0 \\ 0 \end{bmatrix} (t_m) \theta \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_m)$. Since this product of genus 1 theta constants is never zero, the vanishing of the lowest-order term of the expansion near \mathcal{D}_g of S_{34} implies the vanishing of the power of the lowest-order term of the expansion near \mathcal{D}_g of S_{34} implies the vanishing of the power of the lowest-order term of the expansion near \mathcal{D}_g of S_{34} implies the vanishing of the power of the lowest-order term of the expansion near \mathcal{D}_g of S_{34} implies the vanishing of the power of the lowest-order term of the expansion near \mathcal{D}_g of S_{34} implies the vanishing of the power of the lowest-order term that appears in the Poincaré relation for (1234). Thus the Poincaré relation for the quadruple (1234) holds, up to terms of higher order. By interchanging the columns (1234) and (*ijkl*) of the characteristics involved, we see that the correspondingly permuted Schottky–Jung identity implies the Poincaré identity for any given quadruple (*ijkl*).

Remark 5.3. The proof above shows why applying the Schottky–Jung proportionalities for η_g to Riemann's quartic relations directly would not work. Indeed, if one were to take the genus 3 Riemann's quartic relation (2.2) and extend the genus 3 characteristics $\begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \begin{bmatrix} 011 \\ 100 \end{bmatrix}$ and $\begin{bmatrix} \sigma \\ \mu \end{bmatrix} = \begin{bmatrix} 100 \\ 001 \end{bmatrix}$ to genus g - 1 simply by zero characteristics (or in fact in any other way), then instead of R_{34} , where only the sum over top genus (g - 4)-characteristics ε is taken, we would have a quartic identity where the sum over all $\begin{bmatrix} \varepsilon \\ \delta \end{bmatrix} \in K_{g-4}$ is taken. Then the lowest-degree terms of the expansion of s_{34} near the diagonal would arise if no column $\begin{bmatrix} \varepsilon_m \\ \delta_m \end{bmatrix}$ or $\begin{bmatrix} \varepsilon_m \\ \delta_m + 1 \end{bmatrix}$ is equal to $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$; thus, the lowest-degree terms would arise from the cases when all $\begin{bmatrix} \varepsilon_m \\ \delta_m \end{bmatrix}$ are equal to $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ or $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

But then for two monomials appearing in s_{34} , where all columns are the same, except say for $\begin{bmatrix} \varepsilon_g \\ \delta_g \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in one monomial versus $\begin{bmatrix} \varepsilon_g \\ \delta_g \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ in the other, the lowest-degree term of the expansion is exactly the same. Indeed, these two lowest-degree terms give the same expression in τ_{ab} , for $1 \leq a < b \leq 4$, times the same product of theta constants in variables t_5, \ldots, t_{g-1} , but also times the same factor of $\theta^2 \begin{bmatrix} 0 \\ 0 \end{bmatrix} (t_g) \theta^2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} (t_g)$ in both cases—as in each case both of these characteristics appear four times under the square root. However, as the signs of the individual square roots of degree 8 monomials cannot be determined, it could be that these two lowestdegree terms simply cancel. Thus, it could be that the desired lowest-degree term of s_{34} would cancel out, and the argument above would fail. Using Fay's (generalized) Riemann theta formula, or equivalently the doubling trick (see Remark 2.2), to obtain R_{34} allows us to overcome this crucial difficulty.

For arbitrary genus g, there are $\binom{g}{4}$ Poincaré relations. In particular, already for g = 5 only three out of the five Poincaré relations can be locally independent for dimension reasons. Following Rauch's ideas [RF74, p. 228] for g = 5, one can exhibit for any $g \ge 4$ a collection of

$$\frac{1}{2}(g-3)(g-2) = \frac{1}{2}g(g+1) - (3g-3) = \dim \mathcal{A}_g - \dim \mathcal{J}_g.$$

Poincaré relations that are locally functionally independent.

PROPOSITION 5.4. For any $g \ge 4$, the (g-3)(g-2)/2 Poincaré relations (5.1) corresponding to the quadruples of the form (12jk) for all $3 \le j < k \le g$ are functionally independent in a neighborhood of a generic $\tau \in \mathcal{D}_q$.

In particular, the codimension of the locus in \mathcal{A}_q determined by these Poincaré relations is

locally equal to (g-3)(g-2)/2 near such τ , and the dimension at τ of the locus of period matrices satisfying these Poincaré relations is equal to 3g-3.

While it is possible to give a direct proof of this statement by showing that, locally, given $t_1, \ldots, t_g, \tau_{12}, \tau_{13}, \tau_{23}, \ldots, \tau_{1g}, \tau_{2g}$, all the τ_{ab} can be determined from this set of Poincaré relations, this proposition follows from the proof of local functional independence of the corresponding S_{jk} , given in the next section.

6. Schottky–Jung and Poincaré: Proof of the main theorem

In this section, we will prove the main theorem, Theorem 1.1, by showing that the lowest-order terms of the expansion of S_{jk} near \mathcal{D}_g give a collection of functionally independent relations.

Proof of Theorem 1.1. We first consider the genus 4 case. In this case, we only have one identity S_{34} , and Lemma 3.1 yields $S_{34} = SJ^{\eta_4}(R_{34})$. The full Taylor series expansion of S_{34} in the variables τ_{jk} , near the point $\tau = \text{diag}(t_1, t_2, t_3, t_4) \in \mathcal{D}_g$, for all t_m fixed, is a series such that its lowest-degree term has degree 8 in the τ_{jk} . By the computations in Section 5, this lowest-degree term is equal to a non-zero multiple of the symmetrization (5.2) of the Poincaré relation. Thus, the whole series is not identically zero, and consequently its zero locus is of codimension 1 in $Th(\mathcal{A}_g(4, 8))$ —hence of dimension 9. Since the zero locus of S_{34} contains the irreducible 9-dimensional locus \mathcal{J}_4 , it follows that \mathcal{J}_4 must be an irreducible component of this zero locus.

For arbitrary genus g, by the proof of Theorem 5.1 we know that the lowest-order terms of the expansions of S_{jk} near \mathcal{D}_g are non-zero multiples of powers of the Poincaré relations for quadruples (12jk). To prove that the S_{jk} are functionally independent near a generic point of \mathcal{D}_g , we can follow the idea of the argument given in [RF74, p. 227ff] (which is possible now that we have found Schottky–Jung identities whose expansions give Poincaré relations, and now that we have handled the issue of signs and ascertained suitable non-vanishing correctly).

Consider the Jacobian matrix of derivatives of the S_{jk} with respect to the variables τ_{ab} with $3 \leq a < b \leq g$, evaluated very close to a generic point of \mathcal{D}_g , that is, for $\tau_{ii} = t_i$ generic, for all $1 \leq i \leq g$, and for $0 < |\tau_{ab}| < \varepsilon \ll 1$, for any $1 \leq i < j \leq g$. To compute $\partial S_{34}/\partial \tau_{ab}$ for $3 \leq a < b \leq g$, note that the lowest-degree term is always zero except for the case of $\partial S_{34}/\partial \tau_{34}$. Since each S_{jk} is obtained from S_{34} by permuting the columns, it follows that to lowest order, the only non-zero partial derivative is $\partial S_{jk}/\partial \tau_{jk}$. Thus, the Jacobian matrix is diagonal, plus terms of higher order in the off-diagonal entries τ_{ab} of the period matrix. Since we have assumed that all $|\tau_{ab}| < \varepsilon$, the determinant of this Jacobian matrix is equal to the Jacobian of the lowest-order diagonal matrix, plus some $O(\varepsilon)$. Since the determinant of the diagonal matrix is non-zero, for sufficiently small ε , it thus follows that the Jacobian determinant det $(\partial S_{jk}/\partial \tau_{ab})$ is non-zero, and thus that the equations S_{jk} are functionally independent.

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