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## Biodiversity and environmental stressors along urban walking routes

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1 **Title:** Biodiversity and environmental stressors along urban walking routes

## 2 **1 Abstract**

3 There is increasing focus on designing liveable cities that promote walking. However, urban walking routes  
4 can expose people to adverse environmental conditions that reduce health, well-being and biodiversity.  
5 Our primary objective is to assess how urban form is associated with environmental quality, including  
6 biodiversity, for people moving through urban spaces. We assess a range of environmental conditions that  
7 influence human health and biodiversity (temperature, noise and particulate pollution) and biodiversity  
8 of three taxa (trees, butterflies and birds) along 700m public walking routes embedded in 500m x 500m  
9 grid cells across three UK towns. Cells are selected using random stratification across an urbanisation  
10 intensity gradient. Walking routes in more built-up areas were noisier and hotter; noise levels further  
11 increased in areas with more industrial land-use and large roads. There was no evidence of vegetation  
12 mitigating noise or temperature, but there was some evidence that increased vegetation cover mitigated  
13 small particulate pollution. Walking routes in more built-up environments had lower butterfly, bird and  
14 native tree species richness, and reduced butterfly abundance. Large roads were associated with reduced  
15 bird species richness and increased noise was associated with reduced bird abundance. Most specific  
16 measures of vegetation in the surrounding matrix (median patch size, structural complexity at 1.5m  
17 resolution) were not detectably associated with biodiversity along walking routes, indicating minimal  
18 beneficial spill-over. Increased garden cover in the surrounding matrix was associated with less abundant  
19 and less species-rich butterfly communities. Our results highlight considerable heterogeneity in the  
20 environmental quality of urban walking routes and pedestrians' potential to experience biodiversity along  
21 these routes, driven by reduced quality in areas with more built cover. A greater focus is needed on  
22 mitigating adverse effects of specific features of the built environment (roads, industrial areas, noise)

23 surrounding walking routes to enhance the co-benefits of more biodiversity and healthier conditions for  
24 pedestrians.

25 **2 Key words**

26 green infrastructure; sustainable cities; walkability; pedestrian experience; luxury effect; habitat

27 fragmentation

### 28 **3 Introduction**

29 Urbanisation alters many aspects of the environment, including temperature, air quality, hydrology, and  
30 habitat type and availability, which in turn affect the extent to which urban areas can support biodiversity  
31 and provide high-quality, healthy, environments for people (Beninde et al., 2015, Haines-Young and  
32 Potschin, 2010). For example, urban air pollution (World Health Organization, 2013), noise pollution  
33 (Hankey and Marshall, 2017, Xie and Kang, 2009) and high temperatures (Kovats and Hajat, 2008) lead to  
34 poor human health and premature mortality, and negatively impact many species (Salmón et al., 2018,  
35 Davis et al., 2018, Johnson et al., 2019). It is thus crucial to understand the consequences of urban form  
36 for the way in which people experience both the physical and biological environment if we are to plan,  
37 build and manage cities and towns in ways that support and sustain human wellbeing.

38 In the twentieth century, city design primarily focused on the efficiency of vehicle movement at the  
39 expense of effective planning for pedestrians (Lo, 2009). The ‘walkability’ of cities has, however, come  
40 under increasing scrutiny in recent years, given the now widely recognised health benefits of walking  
41 (Smith et al., 2008). The walkability of an area is concerned with the extent to which walking is supported  
42 by features of the urban environment (Shashank and Schuurman, 2019); a ‘walkable’ urban area provides  
43 routes that are convenient and health-promoting for pedestrians (Tight, 2018, Zuniga-Teran et al., 2017).  
44 Walkability has frequently been assessed based on the structural features of the urban landscape (e.g.  
45 “Density, Diversity and Design”, Cervero and Kockelman, 1997, Lu et al., 2017), although there is no single  
46 agreed measure (Fonseca et al., 2021, Shields et al., 2021). Increasingly, measures of the experience of  
47 the environment are incorporated when assessing walkability (Zuniga-Teran et al., 2016, Zuniga-Teran et  
48 al., 2017), including consideration of thermal comfort and availability of amenity facilities (Labdaoui et al.,  
49 2021, Zuniga-Teran et al., 2017). Similarly, urban walking routes can have high concentrations of air  
50 pollution that limit their potential to promote health, thus reducing their walkability (Hankey and

51 Marshall, 2017, Howell et al., 2019, James et al., 2015). Although walkability measures are often  
52 integrative, detailed studies of the benefits of each aspect tend to be addressed separately and there are  
53 few studies addressing their interrelationships (James et al., 2017).

54 Despite the well-recognised health benefits of engaging with urban greenspace (World Health  
55 Organization, 2016), greenspace is not well integrated into measures of walkability. The term greenspace  
56 takes diverse meanings between and within disciplines (Taylor and Hochuli, 2017). In this study,  
57 greenspace refers to any vegetated area, public or private, deliberately planted or self-sown. Indeed,  
58 much of the research on walkability ignores greenspace (Tobin et al., 2022) although it can influence  
59 walking patterns and behaviour (Zuniga-Teran et al., 2017). As an example, greater tree cover can reduce  
60 the perceived walking time of a route (Jia and Wang, 2021). More specifically, the potential for pedestrians  
61 to experience biodiversity along walking routes is very poorly understood – despite evidence that  
62 exposure to biodiversity can enhance peoples’ enjoyment and well-being (Douglas and Evans, 2022, Lai et  
63 al., 2019, Southon et al., 2018), and recognition that enhancing biodiversity can enrich the walking  
64 experience (Brierley and Cockett, 2017).

65 Spatial patterns in urban land cover and land use are very fine-grained (Norton et al., 2016). To reflect  
66 these, sampling strategies that focus on walking routes should capture biodiversity and environmental  
67 characteristics across a complex mixture of greenspace patches that vary in their type, size and  
68 composition, and are embedded within a matrix of variable built environments. Whilst environmental  
69 conditions are often measured in built-up areas and greenspace, such sampling does not always occur at  
70 scales that appropriately capture local and landscape-scale variation (Pope and Wu, 2014), or the  
71 experience of urban residents (Nerriere et al., 2005). Furthermore, we are not aware of any previous  
72 research that integrates field-based measurements of biodiversity and environmental conditions at the  
73 scales relevant to human experience along urban walking routes. Such studies are needed to enable urban

74 planners to understand which attributes of urban environments determine conditions along these walking  
75 routes.

76 Here, we examine existing publicly accessible walking routes in urban areas and sample both  
77 environmental conditions and biodiversity on these routes. We aim to understand what features of urban  
78 environments are associated with environmental conditions that are known to benefit people's  
79 experience of the walking route – i.e. enhanced biodiversity and reduced urban stressors (air pollution,  
80 noise and heat). Specifically, we ask what characteristics of the urban environment in which walking  
81 routes are embedded can predict: (1) biodiversity (abundance and species richness of butterflies, birds  
82 and trees) and (2) environmental conditions (particulate matter, temperature, noise), on publicly  
83 accessible walking routes in diverse urban areas. This approach enables identification of features of the  
84 urban environment of joint benefit for pedestrians and biodiversity that are amenable to modifications  
85 through planning and design. Our sampling is focused on three adjacent towns in southern England,  
86 comprising an urban area of approximately 253 km<sup>2</sup> and containing most of the typical urban forms and  
87 development history found in the UK.

## 88 **4 Methods**

### 89 **4.1 Study area and site selection**

90 This study was conducted in three towns in southern England that share similar topographical and climatic  
91 features. Milton Keynes (52°0' N, 0°47' W; 89 km<sup>2</sup>; population 229,941 in 2011 (Office for National  
92 Statistics, 2013)) is a planned 'new town' that was established in the 1960s and built up around villages  
93 dating from the medieval period. The extensive development is set around a grid network of roads and  
94 large areas of well-connected public greenspace. Luton (51°52' N, 0°25' W; 58 km<sup>2</sup>; population 258,018)  
95 developed rapidly during the nineteenth century as an industrial centre; the inner town is dominated by

96 terraced housing. Bedford (52°8' N, 0°27' W; 36 km<sup>2</sup>; population 106,940) developed in the Middle Ages  
97 as a market town and has subsequently developed around a road network radiating from the town centre.

98 The combined urban areas of the three towns were overlaid with a 500 m x 500 m grid (referred to as  
99 'tiles'). Survey areas were selected using random stratification to represent a range of urban forms. Each  
100 tile was categorised as one of 25 urban forms using remotely sensed data from airborne LiDAR (see section  
101 4.4.2) and OS MasterMap® data to generate five categories of building cover (<5%; 5% to 9.99%; 10% to  
102 14.99%; 15% to 19.99%; ≥ 20%) and five categories of vegetation cover 0.5 m or taller (10%; 10% to  
103 19.99%; 20% to 29.99%; 30% to 39.99%; ≥40). MasterMap is a comprehensive mapping layer produced  
104 by the UK's Ordnance Survey. Five tiles of each urban form were randomly selected for surveying, ensuring  
105 no tiles were directly adjacent to each other, nor included unusual features (e.g. an airport). This yielded  
106 112 survey tiles (<125 because there were fewer than five tiles in four of the urban form categories).

107 Transect routes were established along publicly accessible walking routes in order to sample biodiversity  
108 and environmental conditions in areas available for any mobile pedestrian to experience. The routes  
109 incorporated influence from private greenspace, including residential gardens, as many ran along  
110 footpaths adjacent to residential front gardens or along alleyways or linear parks adjacent to residential  
111 back gardens. Transect length was set at 700 m as this enabled us to sample the major land cover types  
112 within each tile with sufficient replication of individual sampling points (see below) whilst being  
113 sufficiently short to enable us to maximise the number of grid cells that could be covered. Data were  
114 collected during spring and summer 2014. Surveys of butterflies, trees and environmental conditions were  
115 undertaken along the transect routes. Due to their greater mobility, bird surveys were undertaken at four  
116 points across the tile, thereby capturing the full extent of the birdlife people might experience along the  
117 walking route. Three tiles were excluded from all analyses, as access issues meant a full complement of  
118 surveys could not be completed. An additional two tiles had complete surveys for bird points, but full

119 transect walks could not be completed. So, a maximum of 107 tiles from a pool of 109 were surveyed for  
120 any taxon or environmental conditional, although some data were further excluded from analysis (for  
121 details, see: 4.2 Biodiversity surveys; 4.3 Environmental condition surveys).

## 122 **4.2 Biodiversity surveys**

123 Butterfly species richness and total abundance were recorded along each transect route (Table S1), in  
124 suitable weather conditions (defined following UKBMS, 2014). Surveys used the standard Pollard Walk  
125 method, i.e. a 5 m cube ahead of the surveyor (Pollard and Yates, 1993) on one visit between 27<sup>th</sup> June  
126 and 7<sup>th</sup> August 2014, starting between 10 am and 5 pm. This represents the period of maximum butterfly  
127 activity, and includes the flight periods of most butterfly species in the region (Balmer, 2014).

128 Tree data were collected at eight fixed survey points spaced 100 m apart along the transect routes. Trees  
129 (>2 m tall) within a 10-m radius of each survey point (which incorporated public and private land) were  
130 identified to species level (Table S2), and classified as native or exotic using definitions from PLANTATT  
131 (Hill et al., 2004) and Stace (2010), supported by expert advice. Tile-level tree abundance and species  
132 richness were calculated for all trees and only native trees.

133 Bird surveys were conducted at four publicly accessible points in each tile in May and June 2014, all points  
134 fell on, or very close to, the transect routes. Eight tiles were excluded from analysis because fewer than  
135 four points were surveyed due to access issues or coverage by unsuitable habitat (e.g. open water). At  
136 each point, two 10-minute counts (one in May and one in June) of all species seen and heard were  
137 conducted between 06:00 am and 10:00 am (Table S3). All birds detected within a 60-m radius of the  
138 points were recorded, and the maximum abundance of each species at each point across the two surveys  
139 was calculated as an estimate of true abundance of species that are more detectable both earlier and  
140 later in the season. Surveys were timed to maximise bird detectability; complete detection of large, vocal



141 and territorial species (i.e. the vast majority of the bird community) present within the limited radius  
142 considered was expected. Pooled data across survey points were used to calculate indices of total  
143 abundance and species richness per tile.

#### 144 **4.3 Environmental condition surveys**

145 Environmental recording equipment was mounted on aluminium backpack frames designed to avoid  
146 interference from the wearer's body. Noise and temperature data were recorded at the eight fixed survey  
147 points (see tree data description, above), plus two additional points, as environmental condition data  
148 were more time-efficient to collect than the tree data. Environmental data were collected under the same  
149 conditions as the butterfly surveys, and usually at the same time, and always on weekdays to minimise  
150 the influence of day of the week on the results. The additional points were in dominant land covers along  
151 the transect, or, when appropriate, in rarer land-cover types that were not sufficiently captured by the  
152 other survey points.

153 Noise was measured for 60 seconds, whilst standing still, at each of the ten survey points, using an  
154 Optimus Red Sound Level Meter (CR:160 series, Cirrus). We measured the A-weighted, equivalent sound  
155 level (LAeq, measured as dBA) which integrates sound energy over time and is weighted towards 500 Hz  
156 to 6 kHz, i.e. the frequencies to which human hearing is most sensitive (Cirrus Research plc, 2015) and  
157 within which the frequency range of the local avifauna's vocalisations fall (Xeno-canto Foundation and  
158 Naturalis Biodiversity Center, 2018). For each tile, we then calculated mean noise.

159 Temperature (°C) was recorded at each point using the median of two readings over a 30-second period  
160 from each of two ThermoChron® iButtons (model DS1923), following a two-minute stabilisation period (as  
161 per manufacturer guidelines). When modelling air temperature as a response variable, we expressed  
162 these measurements as a temperature anomaly relative to the median of readings during the transect

163 walk period recorded at the nearest meteorological station (Wolfson station, Cranfield University;  
164 52°04'27.4"N, 0°37'41.5"W; data recorded at five-minute intervals) which is located in a rural setting. A  
165 tile-level mean value was calculated across the point-level anomalies. The median temperature recorded  
166 at the Wolfson station for the period the transect was walked was used as a predictor variable in one  
167 model.

168 Particulate matter (particles per 0.1 cubic foot) was recorded along the entire transect at a rate of one  
169 reading per minute using a laser particle counter (Dylos DC1700). Readings separated small particles (>0.5  
170  $\mu\text{m}$ ; small particulate pollution and bacteria, fungal spores, etc.) and large particles (>2.5  $\mu\text{m}$ ; larger  
171 particulate pollution and pollen). Eight tiles were dropped from analysis for particulate matter due to  
172 missing data. Tile-level mean concentrations from recordings along the full transect.

#### 173 **4.4 Characterising the urban environment**

174 We used field-collected data and additional metrics derived from secondary data to characterise the  
175 urban environment within our focal survey tiles to use as predictors when modelling biodiversity and  
176 environmental conditions. These predictors characterised the built environment, the quality and extent  
177 of greenspace, abiotic stressors and socio-economic variables. Table 1 provides the rationale for the  
178 selection of the suite of predictor variables used when modelling each response variable.

179 **Table 1:** Predictor variables and rationale for inclusion in each linear model. Variables are grouped as: built cover metrics, greenspace metrics, abiotic stressor,  
 180 socio-economic variable and control variables. The distribution of each variable is in Figure S1. For references supporting the rationale, refer to Table S4.  
 181 When variables were transformed for analysis, the transformation used is provided in the second column.

Variable	Transformation?	Butterfly (richness, abundance)	Birds (richness, abundance)	Trees – all (richness, abundance)	Trees – native (richness, abundance)	Temperature (mean, standardised)	Noise (LAeq) (mean)	Particulates – Large PM (mean)	Particulates – Small PM (mean)	Rationale for inclusion
<b>Built cover metrics</b>										
Distance to urban edge (m)	Square root	X	X	X	X	X	X	X	X	A common measure of urbanisation, related to biodiversity patterns and environmental conditions in some cities and habitats.
Impervious surface cover (% cover)		X	X	X	X	X	X	X	X	A standard metric of urbanisation intensity and absence of greenspace.
Industrial land use (% cover)	Natural log						X	X	X	Industry is a source of noise and particulate pollutants directly and due to increased vehicle traffic in the vicinity.
Large road density (m/m <sup>2</sup> )	Natural log	X	X				X	X	X	A measure of urbanisation intensity, fragmentation and expected to increase conditions (such as noise and pollution) that may adversely influence butterflies and birds. Large road density is used rather than total road density as smaller roads provide limited dispersal barriers for mobile taxa, and typically have smaller impacts on noise and pollution.
Road density (all roads) (m/m <sup>2</sup> )				X	X					Trees are frequently planted along roads, especially smaller residential roads, thus a

										measure of total road density is more appropriate than a measure of large road density.
Greenspace metrics										
Median foliage height diversity (FHD)		X	X			X	X	X	X	A greater diversity of foliage heights indicates more structurally complex vegetation which is hypothesised to benefit bird and butterfly assemblages. More complex vegetation structures may also enhance removal of particulates and ameliorate temperature and noise. Not included in models of tree diversity due to circularity that would result.
Median patch size (m <sup>2</sup> )		X	X	X	X	X	X	X	X	A measure of habitat fragmentation. Large and continuous areas of green cover are typically expected to be more effective at supporting biodiversity (at least for species specialising on the core habitat type), and potentially at reducing noise, particulate matter, and temperatures
Residential gardens (% cover)		X	X	X	X					Gardens can enhance habitat and food provision for butterflies and birds. Gardens can also influence tree cover and composition (with a greater number of non-natives) than in other urban land uses.
Tree diversity (Shannon index)						X	X	X	X	Diversity enhances the range of growth forms and range of species traits which may increase overall capacity to remove pollutants, and screen noise.
Abiotic stressor										

Noise (LAeq) (dBA)			X							Noise can disrupt bird vocal communications and change community composition. Current research suggests limited direct effects of noise on butterflies and no effects on trees.
Socio-economic variable										
Index of Multiple Deprivation		X	X	X	X					The luxury effect refers to observations that there is typically higher biodiversity in wealthier areas. Some taxa, however, find greater availability of key resources in less wealthy and less intensively managed areas.
Control variables										
Air temperature (°C)		X								Median air temperature recorded at the Wolfson weather station (Cranfield University; 52°04'27.4"N, 0°37'41.5"W) as matched field recorded data were not always available. The median rather than mean was used due to skew in the data. Will influence activity and thus detectability of endothermic butterflies but not our other taxonomic groups.
Day of season (day 1 = first transect visit, 27 <sup>th</sup> June)		X				X	X	X	X	Takes seasonal variation into account. Not included for birds as data are aggregated in a manner that takes seasonal variation into account (see main text).
Hour of day						X	X	X	X	Takes diurnal variation in temperature and human activity patterns into account.
Interaction effects										
Median foliage height diversity (FHD) * Large road density								X		In models of noise levels and particulate matter (large and small), interactions with FHD and large roads were tested. Vegetation



#### 183 **4.4.1 Built cover metrics**

184 We used five metrics of the built-up environment that broadly relate to urbanisation intensity: (i) distance  
185 to the urban edge; (ii) percentage impervious surface cover; (iii) percentage cover of industrial land use;  
186 (iv) total road density; (v) total density of large roads. Road density, especially of large roads, provides an  
187 index of habitat fragmentation given the considerable barriers to animal movement generated by such  
188 infrastructure. Distance of the tile from the urban edge was calculated from the tile centroid to the nearest  
189 edge of the built-up area of the focal town. This was identified using 0.5 m resolution colour infrared (CIR)  
190 2007 and 2009 aerial photography acquired from Landmap (<http://landmap.mimas.ac.uk/>). Percentage  
191 impervious surface cover was obtained from a land-cover layer (Grafius et al., 2016) that identified  
192 vegetation, buildings, water, and other non-vegetated (mostly paved) surfaces by classifying the CIR aerial  
193 images based on Normalised Difference Vegetation Index (NDVI) and using OS MasterMap® data.  
194 Industrial land-use percentage cover was acquired from a land-use layer generated from  
195 OpenStreetMap®, OS AddressBase Plus© and OS MasterMap® (for details see Section S1). Total road  
196 density and density of large roads were obtained from the OS Mastermap® Integrated Transport Layer  
197 (May 2016 release) (OS ITN). Large roads were defined as the OS ITN descriptors ‘Dual Carriageways’,  
198 ‘Collapsed Dual Carriageways’, and ‘Slip Roads’ and capture those with heavy traffic flows.

#### 199 **4.4.2 Greenspace metrics (quality and extent of vegetation)**

200 We used four greenspace metrics: (i) median foliage height diversity; (ii) median patch size; (iii) residential  
201 garden cover (the outdoor area associated with private residences, including vegetated and unvegetated  
202 surfaces); (iv) tree species diversity. Percentage vegetation cover was not used as it is essentially the  
203 inverse of impervious surface cover.

204 Foliage height diversity (FHD) is a measure of structural complexity of vegetation (MacArthur and  
205 MacArthur, 1961), which is often a key determinant of urban biodiversity (Beninde et al., 2015). It was  
206 calculated from full-waveform LiDAR data, collected between June and September 2012, by processing to

207 a high-resolution voxel map (1.5 m horizontal and 25 cm vertical) of canopy cover. This processing used  
208 the deconvolution method described in Hancock *et al.* (2017). The Shannon diversity index was then  
209 calculated for each vertical stack of canopy cover voxels (Goetz *et al.*, 2007) to produce a 1.5 m resolution  
210 FHD map. LiDAR data were missing for 13 tiles, which were dropped from models that included FHD. The  
211 median FHD measure was calculated for green areas across the tile.

212 Median patch size provides an additional measure of fragmentation (in addition to road density) and size  
213 of urban habitat patches is frequently associated with biodiversity (Lepczyk *et al.*, 2017), although this  
214 relationship can vary between taxa and ecosystems (Fahrig, 2003). We used Fragstats 4.2 (McGarigal *et al.*,  
215 2012, Grafius *et al.*, 2018) to measure the size of individual greenspaces that were delimited using the  
216 land cover layer (see 'Built cover metrics'). Patches were defined using an 8-cell neighbourhood rule.  
217 Residential gardens can provide substantial resources for wildlife, although are often not managed to  
218 prioritise this function (Gaston *et al.*, 2007). Residential garden percentage cover was calculated from the  
219 'Mixed Surfaces' category in the OS MasterMap® Topography Layer. Tree species diversity was measured  
220 as the Shannon diversity index using our field data.

#### 221 **4.4.3 Other variables**

222 Within urban areas, anthropogenic noise can be a strong determinant of avian species richness and  
223 community structure (Arévalo *et al.*, 2022, Barbosa *et al.*, 2020) so, when modelling avian richness and  
224 abundance, we used mean LAeq, as measured in the field, as a measure of this abiotic stressor. Socio-  
225 economic conditions can influence biodiversity via the luxury effect, where species richness tends to be  
226 higher in more affluent areas due to, for example, more, and higher quality, greenspace (Hope *et al.*,  
227 2003). Socio-economic conditions were measured using the Index of Multiple Deprivation (IMD), which is  
228 the official small-area deprivation measure for England. It is a weighted composite index of seven domains  
229 of deprivation (income, employment, education, health, crime, barriers to housing and services, living  
230 environment) calculated for Census Lower-layer Super Output Areas (LSOAs), reported in deciles (Office



231 for National Statistics, 2015). As LSOAs did not spatially coincide with the survey tiles, we used the IMD  
232 (2012-13 Smith et al., 2015) covering the largest proportion of the tile. We also took three additional  
233 variables (date, ambient temperature and time of surveys) into account that could influence one or more  
234 of our response variables (Table 1; Table S4).

#### 235 **4.5 Statistical analysis**

236 Statistical modelling was undertaken using R v3.4.2 (R Core Team, 2017). For each response variable, we  
237 constructed a generalised least squares (GLS) model using the nlme package (v. 3.1, Pinheiro et al., 2017),  
238 with the objective of determining which characteristics of urban environments are associated with  
239 biodiversity and environmental conditions along the walking routes. Predictor variables for each statistical  
240 model were selected *a priori* to test pre-specified hypotheses whilst taking other potentially influential  
241 variables into account and not over-specifying the models (Table 1; Table S4 for supporting citations). We  
242 adopted a full model approach, following Whittingham *et al.* (2006). All response variables were  
243 standardised (mean-centred and SD-scaled, following transformation where indicated, see Tables S5, S6  
244 and Figures S2, S3) to assist interpretation of parameter estimates. Preliminary checks confirmed all  
245 models met the assumptions of normality (following transformation of response variables in some cases;  
246 Table 1) and that including predictors' polynomial terms did not improve model fit. We also conducted  
247 several robustness checks. First, for spatial autocorrelation (for details, see Section S2). Second, we  
248 ensured that correlations between predictor variables used in each model were below the threshold (0.7)  
249 at which model results can be unduly influenced by collinearity (Dormann et al., 2013), and checked the  
250 influence of using alternative predictors that were highly correlated with those included in our core  
251 models (for details, see Section S2). Finally, we checked for the influence of interactions between  
252 predictors (where interactions could plausibly arise). In models of noise and air pollution we checked for  
253 interactions between vegetation structural complexity (FHD) and industrial land use, and between FHD

254 and large roads; we did this because structurally complex vegetation could mitigate adverse impacts of  
255 industrial land use and large roads on noise levels (Fang and Ling, 2003, Jang et al., 2015) and particulate  
256 pollution (Abhijith et al., 2017, Janhäll, 2015). Only the interaction between FHD and large roads on large  
257 particulate matter was significant and thus included in the final models.

## 258 **5 Results**

259 Across our study area we detected 22 butterfly species (all native; Table S1), 174 tree-species (41 native;  
260 Table S2), and 65 bird species (61 native; Table S3).

### 261 **5.1 Which predictors are associated with biodiversity along walking routes?**

262 Butterfly species richness and abundance, bird species richness and native tree species richness all  
263 decreased as impervious surface cover increased (Table 2A; Figure 1). In addition, bird species richness  
264 was negatively associated with the density of large roads, and bird abundance was negatively associated  
265 with noise levels (L<sub>Aeq</sub>), an abiotic stressor (Table 2A; Figure 1). Butterfly richness and abundance were  
266 negatively associated with garden cover (Table 2A; Figure 1).

267 The socio-economic predictor variable (IMD) was not significantly ( $p < 0.05$ ) associated with any of our  
268 biodiversity outcome variables, but was marginally positively associated with total tree species richness  
269 ( $p = 0.065$ ), and marginally negatively associated with butterfly richness ( $p = 0.089$ ) and abundance  
270 ( $p = 0.061$ ).

271

272 **Table 2:** Linear model results. Table A shows the model output for the biodiversity response variables.  
273 Table B shows the model output for the environmental condition response variables. Distributions of  
274 these variables are available in Tables S5 and S6, Figures S2 and S3. Response variables are listed  
275 vertically, with the number of observations included in the model (n) and a measure of goodness-of-  
276 fit (Pearson's correlation coefficient (r)). Predictor variables are listed horizontally in the order  
277 presented in Table 1. Blank cells indicate that the predictor variable was not used in the model (see  
278 Table 1). The top value is the parameter estimate, with the standard error below, and the p-value  
279 listed third. Bold values in cells with dark grey shading are significant at  $p < 0.05$ . Cells with light grey  
280 shading are significant at  $p < 0.10$ . Models do not include spatial structure unless indicated; \*Ratio  
281 spatial structure, \*\*Linear spatial structure, \*\*\*Exponential spatial structure.

282

283



















A	Intercept	Built cover metrics				Greenspace metrics			Abiotic	Socioeconomic	Control	
		Distance to urban edge	Impervious surface cover	Large road density	Road density (all roads)	Foliage height diversity	Median patch size	Residential gardens	Noise (LAeq)	Index of Multiple Deprivation	Air temperature	Day of season
Butterfly species richness (sqrt) n = 96; r = 0.51	<b>1.921</b> (±0.069) <0.001	0.043 (±0.077) 0.583	<b>-0.226</b> (±0.08) <b>0.006</b>	-0.084 (±0.077) 0.278		-0.062 (±0.078) 0.433	-0.032 (±0.079) 0.685	<b>-0.161</b> (±0.079) <b>0.044</b>		-0.132 (±0.076) 0.089	<b>0.258</b> (±0.080) <b>0.002</b>	-0.034 (±0.079) 0.668
Butterfly abundance (sqrt) n = 96; r = 0.51	<b>3.163</b> (±0.175) <0.001	-0.098 (±0.195) 0.618	<b>-0.528</b> (±0.202) <b>0.011</b>	-0.113 (±0.195) 0.563		-0.207 (±0.198) 0.298	-0.172 (±0.201) 0.394	<b>-0.416</b> (±0.199) <b>0.039</b>		-0.366 (±0.193) 0.061	<b>0.626</b> (±0.203) <b>0.003</b>	-0.230 (±0.198) 0.250
Bird species richness n = 89; r = 0.66	<b>18.045</b> (±0.276) <0.001	0.338 (±0.311) 0.280	<b>-1.788</b> (±0.334) <0.001	<b>-0.711</b> (±0.329) <b>0.034</b>		-0.139 (±0.313) 0.658	0.032 (±0.328) 0.924	-0.343 (±0.325) 0.296	0.160 (±0.343) 0.641	0.187 (±0.308) 0.547		
Bird abundance n = 89; r = 0.45	<b>102.494</b> (±2.698) <0.001	4.903 (±3.039) 0.111	-2.102 (±3.266) 0.522	-3.544 (±3.211) 0.273		-1.102 (±3.056) 0.719	-1.293 (±3.207) 0.688	4.600 (±3.180) 0.152	<b>-6.901</b> (±3.352) <b>0.043</b>	-3.249 (±3.015) 0.284		
Tree species richness n = 107; r = 0.30	<b>9.114</b> (±0.392) <0.001	0.402 (±0.442) 0.365	-0.714 (±0.531) 0.181		-0.044 (±0.616) 0.943		0.474 (±0.438) 0.281	0.242 (±0.496) 0.627		0.764 (±0.409) 0.065		
Tree abundance (sqrt)* n = 107; r = 0.38	<b>7.059</b> (±0.582) <0.001	0.118 (±0.387) 0.761	-0.324 (±0.382) 0.399		-0.715 (±0.45) 0.115		-0.004 (±0.329) 0.989	-0.269 (±0.403) 0.506		0.233 (±0.334) 0.488		
Native tree species richness (sqrt) n = 107; r = 0.35	<b>1.999</b> (±0.064) <0.001	-0.021 (±0.072) 0.767	<b>-0.216</b> (±0.087) <b>0.014</b>		0.016 (±0.101) 0.876		0.089 (±0.071) 0.214	-0.047 (±0.081) 0.560		0.019 (±0.067) 0.779		
Native tree abundance (ln)** n = 107; r = 0.42	<b>2.773</b> (±0.176) <0.001	0.015 (±0.158) 0.926	-0.136 (±0.156) 0.385		-0.192 (±0.185) 0.302		0.086 (±0.125) 0.494	-0.193 (±0.164) 0.240		0.054 (±0.141) 0.702		

B	Intercept	Built cover metrics				Greenspace metrics			Interaction	Control	
		Distance to urban edge	Impervious surface cover	Industrial cover	Large road density	Foliage height diversity	Median patch size	Tree diversity	FHD * large road density	Day of season	Hour of day
Temperature (°C) mean standardised* n = 96; r = 0.35	2.104	0.118	<b>0.320</b>			-0.040	-0.101	0.000		<b>-0.341</b>	<b>0.330</b>
	(±3.809)	(±0.116)	(±0.105)			(±0.113)	(±0.132)	(±0.104)		(±0.107)	(±0.106)
	0.582	0.311	<b>0.003</b>			0.723	0.447	0.999		<b>0.002</b>	<b>0.003</b>
Noise (LAeq) mean n = 96; r = 0.63	<b>51.854</b>	0.154	0.902	<b>1.676</b>	<b>1.721</b>	-0.542	0.018	-0.375		-0.443	0.337
	(±0.419)	(±0.465)	(±0.487)	(±0.482)	(±0.470)	(±0.476)	(±0.472)	(±0.45)		(±0.431)	(±0.439)
	<0.001	0.741	0.068	<b>0.001</b>	<0.001	0.258	0.971	0.407		0.307	0.445
Large PM mean (ln) n = 88; r = 0.66	<b>8.904</b>	-0.065	-0.066	0.014	<b>0.136</b>	-0.041	-0.023	0.012	<b>0.124</b>	<b>0.178</b>	-0.050
	(±0.034)	(±0.037)	(±0.04)	(±0.04)	(±0.038)	(±0.041)	(±0.042)	(±0.037)	(±0.041)	(±0.035)	(±0.035)
	<0.001	0.088	0.105	0.731	<b>0.001</b>	0.314	0.583	0.744	<b>0.003</b>	<0.001	0.156
Small PM mean (ln)*** n = 88; r = 0.43	<b>11.482</b>	0.101	0.004	-0.019	0.084	-0.127	0.013	0.014		<b>0.294</b>	<b>-0.143</b>
	(±0.184)	(±0.086)	(±0.070)	(±0.072)	(±0.070)	(±0.065)	(±0.075)	(±0.063)		(±0.079)	(±0.065)
	<0.001	0.244	0.957	0.787	0.231	0.053	0.862	0.822		<0.001	<b>0.031</b>

285

286

287 **Figure 1:** Summary of responses (Resp.) of biodiversity variables and environmental conditions, to built cover and greenspaces, as well as abiotic  
 288 conditions and socioeconomic variables (Expl.; full model results in Table 2). Not all variables are included in all models (Table 1). Box shading  
 289 indicates the model coefficient direction: green=positive, orange=negative. Icons (from the Microsoft Office collection) indicate the p-value and  
 290 response variable. Black icons: p<0.05; Grey icons: p<0.1. The single tree icon indicates native trees; the cluster of trees icon indicates all tree  
 291 species; the water drop icon indicates humidity; the thermometer icon indicates temperature; the loudspeaker icon indicates noise; the  
 292 smokestacks icon indicates particulate matter. Note that air temperature and day of season are taken into account for butterfly models, and day  
 293 of season and hour of day were taken into account for all environmental condition models (Tables 1, 2, S4).

Expl. →	Effect (Table 2)	Grey space					Green space				Interxn	Abiotic	Socio economic
		Distance to urban edge	Grey cover	Industrial cover	Large road density	Road density (all roads)	Foliage height diversity	Median patch size	Residential gardens	Tree diversity	FHD*Large road density	Noise (LAeq)	Deprivation (1=high; 10=low)
Biodiversity	+ve (biodiversity increases as the variable increases)											 richness Higher richness with lower deprivation	
	-ve (biodiversity decreases as the variable increases)		 richness  richness  richness		 richness				 richness  abundance		 abundance	 richness  abundance Higher rich & abund with higher deprivation	
Environmental conditions	+ve (noise, temperature etc increases as the variable increases)		 mean  mean	 mean	 mean  large PM mean					 large PM mean			
	-ve (noise, temperature etc decreases as the variable increases)	 large PM mean					 small PM mean						

294

## 295 **5.2 Which predictors are associated with environmental conditions along walking routes?**

296 After taking into account time of day and date, walking routes located in more built-up areas were  
297 warmer, with an increase in percentage impervious surface cover of 10% points predicted to increase  
298 mean temperature by 3.2°C (Table 2B, Table S6, Figure 1). Noise levels increased with increased industrial  
299 cover and the density of large roads, and marginally significantly increased ( $p=0.068$ ) with increased  
300 percentage impervious surface cover (Table 2B, Table S6, Figure 1). Both large and small particulate  
301 matter concentrations increased throughout our sampling period (from late June to early August). Large  
302 particular matter concentrations were higher along walking routes in locations with a greater density of  
303 large roads. There was a significant, positive interaction between large road density and foliage height  
304 diversity, indicating that the rate of increase in particulate matter as large road density increased was  
305 steeper in areas with more structurally complex vegetation. There was also a marginally negative,  
306 significant relationship ( $p=0.088$ ) between large particulate matter and distance to the urban edge. Small  
307 particulate matter concentrations exhibited a marginally significant ( $p=0.053$ ), negative relationship with  
308 foliage height diversity.

## 309 **6 Discussion**

310 We used field-based transect sampling to capture variation in the biodiversity and environmental  
311 conditions along urban walking routes at scales relevant to human experiences. We found that  
312 biodiversity (birds, trees, butterflies) increased and potentially adverse environmental conditions, such as  
313 noise and air pollution, decreased in areas with less built infrastructure. These findings were in line with  
314 expectations. The positive role of vegetation was less evident from our models, and residential gardens  
315 were negatively associated with butterfly biodiversity on walking routes. The methodological approach

316 provides a potentially useful way of collecting data across a range of parameters influencing the conditions  
317 on walking routes, which is rarely undertaken.

## 318 **6.1 Biodiversity**

319 Walking routes with the greatest species richness of native trees, birds and butterflies occurred in grid  
320 cells with reduced impervious surface cover, and, by implication, higher amounts of vegetation. This is  
321 consistent with many previous studies (e.g. Chace and Walsh, 2006, Steenberg, 2018, Dallimer et al.,  
322 2012b, Kurylo et al., 2020). Overall, there was a somewhat poorer fit for the tree models (richness and  
323 abundance) than for other diversity measures. This could be due to the static nature of trees and their  
324 longer lifespans slowing their responses to changed conditions such as increased impervious surface cover  
325 (Le Roux et al., 2014), and more direct influences of human activity on tree species composition (via  
326 planting and felling decisions), compared to mobile taxa (Bourne and Conway, 2014). The dominant role  
327 of human planting decisions in determining patterns of non-native tree species richness may explain why  
328 only native tree species richness was associated with impervious surface cover and not all trees. The  
329 mental health and well-being benefits people derive from biodiversity can arise from increased  
330 abundance (Marselle et al., 2020, Cox et al., 2017) or richness (Cameron et al., 2020, Southon et al., 2018)  
331 of organisms. Relationships between biodiversity and well-being are, however, complex (Lovell et al.,  
332 2014, Pett et al., 2016); perceived increases in biodiversity can lead to increased enjoyment of the area,  
333 and sometimes increased well-being (Cameron et al., 2020, Southon et al., 2018, Douglas and Evans,  
334 2022). Whilst people can sometimes accurately detect differences in species richness across locations,  
335 this is, however, not always the case (Cameron et al., 2020, Southon et al., 2018, Dallimer et al., 2012a),  
336 and the realised wellbeing benefits of increases in actual richness along walking routes need further  
337 exploration.



338 Walking routes had fewer bird species when located in areas with a higher density of large roads. This  
339 could be driven by adverse effects of roads on habitat fragmentation, as many bird species are reluctant  
340 to cross large roads (Johnson et al., 2017, Cox et al., 2016). Roads can also have adverse impacts on insect  
341 populations (Baxter-Gilbert et al., 2015) that comprise an essential component of most bird species'  
342 nestlings' diets. Notably, we found that, when taking road effects into account, walking routes embedded  
343 in noisier locations had reduced avian abundance. Noise is a well-known stressor of birds associated with  
344 roads that can influence community composition, abundance and behaviour (Francis, 2015, Merrall and  
345 Evans, 2020), but finding negative effects when accounting for roads suggests that other sources of urban  
346 noise pollution are also detrimental. Anthropogenic noise can affect detectability by surveyors (Cooke et  
347 al., 2020). Such effects are likely to be limited in our study, however, as bird surveys primarily occurred  
348 early in the morning when anthropogenic noise is limited. Most pedestrians using walking routes do so  
349 when anthropogenic activity and noise is high. Consequently, in noisy environments pedestrians are likely  
350 to experience a 'double jeopardy' with noise reducing the numbers of birds present, and reducing their  
351 ability to experience the songs of those present. This will thus limit their ability to gain enjoyment and  
352 other benefits that experiments indicate arise from experiencing avian vocalisations (Douglas and Evans,  
353 2022).

354 Measures of the characteristics of greenspace in the area surrounding our focal walking routes were often  
355 not significantly associated with biodiversity along the walking routes. Foliage height diversity (measured  
356 at 1.5 m resolution in this study) is a measure of vegetation structural complexity, which is often  
357 associated with greater biodiversity (Beninde et al., 2015, Grafius et al., 2019), but was not significantly  
358 related to biodiversity of birds or butterflies in this study. The lack of a relationship with birds is surprising  
359 given that urban birds typically exhibit positive responses to increased woodland cover (Plummer et al.,  
360 2020). FHD has been the traditional measure of structural diversity (MacArthur and MacArthur, 1961),  
361 which has been shown to correlate with biodiversity in some biomes (Goetz et al., 2007), but some recent

362 work suggests that it is not universally related to biodiversity at all scales and biomes (Ehbrecht et al.,  
363 2016). Therefore, while this study shows that FHD is not a strong model predictor, a number of studies  
364 published since the mapping of these sites was completed have proposed new metrics of structural  
365 complexity which may be stronger predictors of biodiversity (Ehbrecht et al., 2016, Liu et al., 2022). Patch  
366 size also typically correlates positively with biodiversity (Beninde et al., 2015, Grafius et al., 2019), but was  
367 not significant in any model in this study. Our results suggest that, for our focal taxa, biodiversity along  
368 the local area of the walking routes is not beneficially impacted by spill-over effects from nearby patches  
369 of suitable habitat in the surrounding landscape. Rather, the environmental conditions along the walking  
370 routes themselves may exert greater influence on the biodiversity that can be experienced on the routes.  
371 Other factors probably also contribute, for example urban biotas are dominated by generalist species  
372 (Evans et al., 2011) and animals with high dispersal ability (Jung and Threlfall, 2018, Martinson and Raupp,  
373 2013). These are likely to be able to use the fragmented network of urban greenspace and associated  
374 matrix effectively, and thus reduce the influence of patch size and vegetation structural complexity in the  
375 surrounding area on biodiversity along the walking routes.

376 Walking routes in areas with more residential garden cover had lower butterfly richness and abundance,  
377 and increased garden cover was never positively associated with species richness and abundance. These  
378 results may appear surprising given that gardens can provide important resources for wildlife. Gardens,  
379 however, are not always managed to maximise wildlife benefits (Gaston et al., 2007), for example  
380 gardeners may intensively manage vegetation, keeping grasses short, and remove weeds that can provide  
381 crucial food or larval host plants for butterflies (Goddard et al., 2013, Öckinger et al., 2009), or replace  
382 areas of vegetation with impervious surfaces or other artificial structures (Perry and Nawaz, 2008). While  
383 gardens are beneficial for some taxa (Baldock et al., 2019), this is not the case for all taxa (Mata et al.,  
384 2017) and the benefits depend on garden features (Olivier et al., 2016). In the back gardens observed  
385 from the transects, lawn was a dominant feature, in line with UK trends (54% of gardens contain mown

386 lawns, which occupy approximately 43% of garden area (Loram et al., 2008)). Paved areas are present in  
387 86% of UK gardens (Loram et al., 2008), but, as observed on the transects, are a particularly prominent  
388 and growing feature of front gardens, consistent with wider UK trends (Perry and Nawaz, 2008). Both  
389 mown lawn and hard surfacing have limited value for butterflies. Our results suggest that whatever the  
390 locally positive effects of domestic gardens (Goddard et al., 2010), these seem to have limited spill over  
391 into the wider public landscape, as sampled by our walking routes. This may include limited spill over of  
392 biodiversity from back gardens to public-facing front gardens, parts of which were captured in our  
393 sampling.

394 The frequently observed luxury effect – species richness being higher in more affluent areas – is often  
395 attributed to such areas having more, and higher quality, greenspace (Chamberlain et al., 2020). Our  
396 analyses, which account for the amount of greenspace, do not find evidence for a luxury effect when  
397 considering bird species richness. Total, but not native, tree species richness was higher (marginally  
398 significantly) in less deprived areas – perhaps reflecting more planting of ornamental trees in affluent  
399 areas. Luxury effects have not previously been examined in butterflies (Leong et al., 2018) but, here, we  
400 find a suggestion of the opposite pattern – greater diversity (marginally significantly) in more deprived  
401 areas. This may be due to greater availability of butterflies’ larval host plants in ruderal vegetation in either  
402 unmanaged, or derelict, land, which is likely to be commoner in deprived areas. These findings suggest  
403 the potential for positive biodiversity experiences being potentially available in all socioeconomic settings,  
404 but that the nature of these might differ, although more work is required to confirm these trends.

## 405 **6.2 Environmental conditions**

406 Environmental conditions that can negatively impact people’s health (warmer temperatures in the  
407 summer, more noise and greater concentrations of particulate matter) occurred along walking routes  
408 embedded in locations with more impervious surface cover. Greater coverage of industrial areas and

409 higher densities of large roads further increased noise levels, with road density also further increasing  
410 concentrations of large particulate matter. Small particulate matter did not show a significant response  
411 to built cover metrics, possibly because its concentration, even adjacent to pollution sources, is very  
412 variable due to the particles' capacity to disperse (Nerriere et al., 2005). Many of these built cover metrics  
413 are also negatively associated with biodiversity (see above), which can deliver substantial wellbeing  
414 benefits (Marselle et al., 2020), meaning that the adverse impacts of the urban features reflected in the  
415 metrics could both directly and indirectly reduce the benefits for pedestrians using walking routes  
416 embedded in such locations.

417 Greenspace characteristics had few detectable associations with environmental conditions, but, where  
418 present, these seem to be mitigating effects. Firstly, areas with less vegetation were hotter, illustrating  
419 the buffering effect of greenspace against the urban heat island at the landscape scale (Coutts and Harris,  
420 2013). Secondly, more complex vegetation structure affected exposure to particulate matter. Specifically,  
421 increased foliage height diversity was associated with lower mean concentrations of small particulates,  
422 which is consistent with previous work suggesting that vegetation can be effective at trapping such  
423 particles (Abhijith et al., 2017, Janhäll, 2015, Brantley et al., 2014). A more complex result was the effect  
424 on large particle density of the interaction between large roads and foliage height diversity. Areas with  
425 more large roads and greater foliage height diversity had higher levels of large particulates. This is  
426 consistent with observations that dense tree canopies can trap pollutants within the street canyon, as a  
427 result of lower wind speeds (Wania et al., 2012) and complex wind flow patterns (Janhäll, 2015), increasing  
428 their local concentrations (Abhijith et al., 2017), and potentially outweighing effects of particle removal  
429 (Vos et al., 2013). Appropriate choices of species and planting design are therefore essential to ensure  
430 pollution reduction using vegetation (Chen et al., 2016).

### 431 **6.3 Limitations and implications**

432 Our conclusions relate to measured biodiversity in three example (but important) taxa, and to the  
433 particular conditions prevalent in the spring and summer. The first of these factors means that our  
434 assessment is of the potential experience of biodiversity along the walking routes. People's perception of  
435 biodiversity will vary with their existing knowledge of, and interest in, the natural world (Southon et al.,  
436 2018). The second means that our findings are primarily relevant to periods when vegetation is fully  
437 developed and biological activity is high. Environmental conditions, biodiversity experience and use of  
438 walking routes by pedestrians will be substantially different at other times, particularly in winter.  
439 Nonetheless this study both demonstrates an approach for developing an integrated assessment of  
440 factors determining the walkability of urban walking routes, and provides a clear analysis of their effects  
441 over the period of the year when pedestrian activity is likely to be at its maximum.

442 The purpose of this sampling strategy was to capture conditions across a wide range of urban forms and  
443 a variety of environmental conditions and biodiversity. The trade-off of this holistic approach is that the  
444 variables are not assessed in depth, in particular the collection of data at each site from one visit limits  
445 how well the sites were characterised. There is a trade-off between spatial and temporal replication and  
446 in this study we focused on spatial replication, and used statistical controls such as survey date and time  
447 in the models to account partially for short-term temporal variation.

448 The overarching finding from this study is that areas with lower amounts of grey space at the landscape  
449 scale are associated with more biodiversity and more favourable conditions for people. The shared drivers  
450 of variation in conditions for biodiversity and people can provide insight into designing or retrofitting  
451 urban areas at landscape scales to benefit people and biodiversity. A correlation matrix showing  
452 covariation between the biodiversity and environmental condition measures (Table S7) suggests the  
453 biodiversity measures are typically positively correlated with each other, albeit sometimes weakly. In  
454 contrast, there was less correlation amongst the environmental response variables, with only small and

455 large particulate matter levels being significantly correlated. This suggests that while improving conditions  
456 for one type of biodiversity is likely to have positive effects on other components of the community,  
457 modifying the environment to reduce the effects of one environmental condition may not achieve change  
458 in other environmental conditions. Consequently, and despite the overarching negative impact of grey-  
459 space on numerous metrics, multiple mitigating actions are likely to be required to simultaneously  
460 enhance environmental conditions that pedestrians are exposed to along walking routes and enhance the  
461 biodiversity that is available for them to experience. The lack of positive spill-over effects from green-  
462 space features embedded in the wider landscape, suggests that such mitigating actions will need to  
463 include improving habitat features for biodiversity at very fine spatial scales in close proximity to walking  
464 routes.

#### 465 **6.4 Conclusions**

466 Users of urban walking routes can experience substantial biodiversity that has the potential to enhance  
467 their environmental experience. This biodiversity, however, varies considerably depending on the  
468 intensity of urban development in the surrounding area and environmental conditions along the walking  
469 routes. There is limited evidence for beneficial spill-over effects on biodiversity along walking routes of  
470 features in the wider landscape typically associated with high quality habitats for biodiversity. We provide  
471 evidence for a double jeopardy for pedestrians arising from low quality urban environments (increased  
472 impervious surface cover, high density of large roads and industrial areas), as these directly increase  
473 exposure to factors detrimental to human health and have additional indirect impacts by reducing  
474 exposure to biodiversity that can promote human well-being.

475

476

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