Effective Memory Diversification in Legacy Systems

Original Scientific Paper

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Abstract – Memory corruption error is one of the critical security attack vectors against a wide range of software. Addressing this problem, modern compilers provide multiple features to fortify the software against such errors. However, applying compiler-based memory defense is problematic in legacy systems we often encounter in industry or military environments because source codes are unavailable. In this study, we propose memory diversification techniques tailored for legacy binaries to which we cannot apply state-of-the-art compiler-based solutions. The basic idea of our approach is to automatically patch the machine code instructions of each legacy system, attackers must create a specific attack payload for each target by analyzing the particular firmware, thus significantly increasing exploit development time and cost. Our approach is evaluated by applying it to a stack and heap of multiple binaries, including PX4 drone firmware and other Linux utilities.

Keywords: Legacy System, Diversification, Memory Layout Randomization, UAV Firmware

1. INTRODUCTION

Memory corruption vulnerabilities are caused by unexpected changes or reference of memory values, and there are various categories of them [1,2]. Generally, the existence and detailed structures of specific memory regions vary by application, but the stack and heap memory regions of most applications, including legacy binaries, are composed based on a general and common memory layout; thus, its exploitation steps are fairly similar from one to another [3-5].

For instance, memory corruption vulnerabilities in a stack such as buffer overflow vulnerability often target to corrupt a specific/common data so-called return address. Defending such memory corruption-based exploitation is also well established by security researchers: use stack canary and check if the canary value has changed [6]. However, such defense (stack canary) is applied by compilers; thus, it is difficult to apply such defense to legacy binary which cannot be re-compiled.

Various vulnerabilities are also likely to exist in the heap memory area as the heap is dynamically allocated at runtime and it is usually more complicatedly constructed than the stack memory buffers [7]. Similarly, to stack situations, multiple defense systems including address space layout randomization (ASLR) are proposed as a part of the compiler feature or heap-allocator's runtime verification logic [8].

All such state-of-the-art defenses are inapplicable to legacy binaries as they cannot be re-compiled [9]. However, we claim that applying the ASLR effects (even partially) to stack and heap memory regions would apply to some extent solely based on binary analysis and in-place instruction patching [10,11]. This is the part where our idea comes in.

To apply the memory diversification effect to legacy binaries, we use binary analysis techniques and in-place instruction patching to change the runtime memory layout of binary without re-compiling the source code.

The goal is to create different memory layouts for each physical device, without altering the original functionality. More specifically, we patch the binary/firmware to differentiate the size/distance of unused memory paddings in stack and heap. As a result, when our diversification technology is applied to drones, even if the software system is prone to memory corruption, the attacker must adjust the attack payload differently each time when attacking an instance because diversification renders the memory layout of each physical instance differently. As a result, an attacker must create multiple attack payloads by analyzing the instance of each machine, which significantly increases attack time and cost.

Several related works also consider the lack-ofsource-code situation. For example, [9] also fortifies the binary to prevent exploitation. The key idea of such work is to patch the ROP-gadget instruction instead of changing the memory layout as our system does. We have surveyed previous studies to this end and summarized more details in section 2.

In short, we proposed binary-patch-based memory layout randomization technique that does not require source code and is thus suitable for legacy systems. The main contributions of this paper are as follows.

- 1. Our system provides a way to change the memory layout without re-compiling the binary. This is useful to fortify outdated system binaries when their source code is intentionally or unintentionally unavailable.
- 2. Our system effectively raises the bar of applying memory corruption attacks against multiple physical devices using the same firmware. Because our approach diversifies the memory layout of each target, the attacker must develop different exploit payloads (e.g., ROP payload for buffer overflow vulnerability) for each target device.
- 3. We implemented and deployed our idea against commercial-off-the-shelf (COTS) software such as Intel PX4 aero drone firmware and popular Binutils binaries in the Linux system.
- 4. We provide academic analysis and discussion that our approach must consider data alignment issues and code/data interleaving problems in ARM-like CPU architectures. This is a thought-provoking discussion for additional future research to this end.

The rest of the paper is structured as follows. Section 2 covers various related works regarding our research direction. Section 3 proposes a system theory about the legacy system and memory safety. Next, we describe the design of our framework in section 4, and the implementation of algorithms in section 5. Afterward, we present the evaluation results in section 6. Finally, we summarize our paper and conclude in section 7.

2. RELATED WORK

2.1. BINARY PATCH

Because many commercial software applications are developed based on closed-source code, it is difficult to apply security patches to their vulnerable parts. Various researches are addressing this limitation. [12] conducted a study to prevent return-oriented programming (ROP) attacks based on the return instruction without based on debugging symbol information in a Linux 64-bit environment without source code. [13] conducted a patch for a buffer overflow vulnerability by automating the security patch for the Windows x86 binary without the use of source code, debugging information or human intervention. [14] considers a closed-source code patching environment in PowerPC-based binaries. [9] achieves security effectiveness by patching the binary to prevent code reuse attacks. [15] identified vulnerabilities in closed-source code software based on the bug signature. [16] performed a static binary patch to prevent vulnerabilities in ARM-based Internet of Things (IoT) device firmware.

Additionally, many studies aim to better identify the causes of security vulnerabilities in binary. [17], [18] enabled finding similar patches or vulnerabilities in different binaries by identifying code portions changed by a binary patch through basic block analysis. [19] detected software vulnerabilities in the binary codes of patched and unpatched programs using the patch diffing technology. Previous studies primarily aimed at preventing specific security vulnerabilities in an environment with binary-only approach without source code. To some extent, our study is similar to these studies in that patch is performed in a binary-only environment, but our framework is mainly focused on diversifying the memory layout and hindering memory corruption exploitation for physical instances (e.g., each drone machine).

2.2. MEMORY RANDOMIZATION

As attacks that exploit memory corruption vulnerabilities have been launched against several commercial software applications, the latest security technologies for memory protection, such as ASLR, have been implemented in most software applications. ASLR is a technology that can defend against attacks using a fixed address by randomly changing the address of the data area whenever a binary is executed. Thus, research to prevent external attacks by randomizing part of the memory is being actively conducted. [20] proposed a technology to randomize the stack layout based on the LLVM compiler to prevent memory corruption vulnerabilities. The position of each object was randomized using source code information so that attackers cannot predict the stack layout. [8] performed randomization for the entire heap memory area by proposing a random memory block allocation algorithm. It is similar to our study in that randomization is performed in the heap memory area, but the detailed process to obtain the randomization effect is different. [21] proposed a solution to prevent just-in-time (JIT) code reuse attacks using memory randomization technology that is subdivided for each process so that code sharing is not disturbed. [22] conducted a study on the kernel defense mechanism by performing device driver randomization and proposed a solution to prevent ROP attacks on the Linux kernel by increasing the KASLR entropy. [11] proposed a method for randomizing the memory layout in user-end machines to prevent buffer overflow attacks. As shown in the above examples, memory randomization to reinforce security is being extensively researched. Although some studies do not use source code and symbols, many studies perform memory randomization using the source code information. Our study performed effective memory randomization only for binaries without source code information.

2.3. LEGACY SYSTEM

A legacy system is one that uses software applications from older versions or works in uncommon ways. Currently, the latest software updates and distributions are done guickly based on open sources, but many legacy systems are still being used in military or space exploration systems. Because these legacy systems are mostly based on closed-source code, it is difficult to apply security patches to them. In this situation, research into the reinforcement of the security of legacy systems is indispensable. [23] generates randomized instruction addresses whenever a legacy x86 binary is executed without source code or symbol information. [9] proposed a binary-based rewriting technology for patching legacy binary to prevent code reuse attacks. [24] proposed a solution for detecting control flow integrity (CFI) attacks, such as buffer overflow and ROP attacks. It detected CFI attacks with high accuracy by inserting performance counters and instrumentation hooks through binary editing in the ELF file, which is legacy software.

3. PROPOSED SYSTEM THEORY

3.1. LEGACY SYSTEM

A legacy computer system in this paper refers to a computer device with old software application/firmware that differs from the recent standard. Currently, the development and distribution of software are done quickly based on state-of-the-art compilers, yet many legacy systems are still used as old version binaries in various fields. Because most legacy systems are closedsourced, and not properly updated, they can be a good target for attackers to abuse system vulnerabilities such as memory errors.

3.2. ASLR

ASLR is a memory layout diversification technology that changes the address of the data whenever a program is executed by randomly placing memory layouts such as stack, heap, and library codes in the unpredicted address space to make memory exploitation attacks difficult. As memory exploitation technologies such as return oriented programming (ROP) are becoming more popular, memory protection techniques such as ASLR are now widely used in most software systems.

3.3. BASIC BLOCK

A basic block in computing is a straight-line code sequence with no branches other than the entry and exit. Because of this characteristic, computer science researchers often analyze binaries based on basic blocks as a unit of algorithm testing/measure.

3.4. MEMORY ALIGNMENT

When data structures or classes are stored in memory in programming languages such as C++, paddings are sometimes inserted in between variables. These paddings are dummy values added by the compiler. The memory is aligned in 4-byte units to optimize the performance when the CPU accesses the memory. Because of the data bus structure between the CPU and memory, all variables that enter the memory must be placed in consideration of memory alignment to improve system performance [25]. In some cases, if data is accessed to an address without considering memory alignment, it can cause an alignment fault rather than causing a performance issue [26]. In our paper, we consider memory alignment problems while applying our patch for memory diversification.

4. DESIGN

4.1. OVERVIEW

The overall framework of this study is shown in Fig. 1. The firmware binary of the legacy system is (1) disassembled using the Capstone [27] library and (2)functions are extracted based on binary analysis. Afterward, (3) we analyze basic blocks in the function to run our code detection algorithm for proper diversification patch. For the next step, (4) our patch tool performs a diversification patch to the corresponding assembly instructions to adjust the memory layout. After our algorithm is applied, (5) all the basic blocks are reassembled into a diversified version of binary. We applied this approach to PX4 drone firmware to confirm its effectiveness and stability. However, in the case of Windows CE binaries, we could not apply the final re-assembly step because the underlying tool only considers Linuxbased binary. In such a case, we applied in-place binary patching directly against machine codes with additional heuristics.

4.2. STACK DIVERSIFICATION

The overall methodology for stack memory diversification is to insert a random-sized dummy padding inside each stack frame. Because each binary might have unique compiler options, the details of the stack memory layout may differ from one instance to another. However, the main structure of the stack frame and its uses are mostly similar. To launch a successful attack via buffer overflow vulnerability in the stack; the return address, buffer position, layouts, and offsets among local variable data must be precisely calculated. A general

defense technology against such attacks is to place a stack canary between a local variable and the return address. then check whether the stack canary has been changed before exiting the function. If the canary value has been changed, it indicates that unintended data overwrites occurred during the execution of the function.

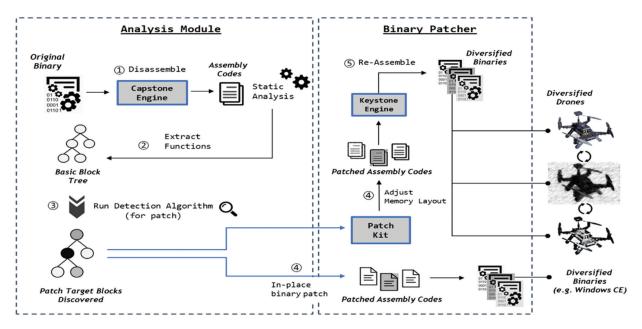


Fig. 1. System Overview. Analysis module spots patch targets based on various pattern detection algorithms. Binary patcher is responsible for modifying and re-assembling the target binary.

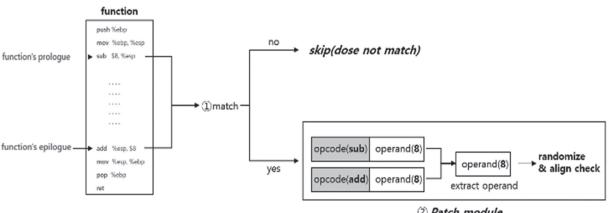




Fig. 2. demonstrates how our patch algorithm checks whether the function's prologue and epilogue match each other. If the condition is satisfied, the patch module performs randomization patch. The patch module extracts the operand from the assembly

However, without re-compiling, the source code, adding stack canary features to legacy systems is difficult. Fig. 3 and 4 show the codes before and after applying the stack canary. Lines 81 to 90 in Fig. 4 represent the stack canary part. The figure shows the same program, but with/without additional assembly codes as the stack canary defense feature. The problem with legacy systems is that it is difficult to insert additional assembly code without breaking the other codes. However, it is feasible to in-place modify the assembly codes without breaking other codes. Therefore, instead of using a stack canary; in this study, we diversify the distance between the local variable of the stack and the return address via inserting a random-sized padding by

modifying the stack-offset related variables embedded in the assembly instruction. This can be done relatively simply based on a binary patch, considering how the compiler allocates the stack frame.

The compiler adds the stack allocation and deallocation codes as function prologue and epilogue. Our algorithm detects this code via binary analysis and randomly modifies the size of the stack frame dummy padding differently for each legacy instance. The point of our idea is that we can make this modification solely based on in-place binary patching. To build our system, our patch framework analyzes each binary architecture of the target binary, such as ARM and Intel, and applies a tailored algorithm to each CPU architecture. For example, ARM uses fixed-length instruction encoding, while Intel uses variable-length instruction encoding.

0x080491b6 <+0>:	endbr3	2
0x080491ba <+4>:	push	ebp
0x080491bb <+5>:	MOV	ebp,esp
0x080491bd <+7>:	push	ebx
0x080491be <+8>:	sub	esp,0x100
0x080491c4 <+14>:	call	0x80490f0 <x86.get_pc_thunk.bx></x86.get_pc_thunk.bx>
0x080491c9 <+19>:	add	ebx,0x2e37
0x080491cf <+25>:	lea	eax,[ebp-0x104]
0x080491d5 <+31>:	push	eax
0x080491d6 <+32>:	call	0x8049080 <gets@plt></gets@plt>
0x080491db <+37>:	add	esp,0x4
0x080491de <+40>:	lea	eax,[ebp-0x104]
0x080491e4 <+46>:	push	eax
0x080491e5 <+47>:	lea	eax,[ebx-0x1ff8]
0x080491eb <+53>:	push	eax
0x080491ec <+54>:	call	0x8049070 <printf@plt></printf@plt>
0x080491f1 <+59>:	add	esp,0x8
0x080491f4 <+62>:	MOV	eax,0x0
0x080491f9 <+67>:	MOV	ebx,DWORD PTR [ebp-0x4]
0x080491fc <+70>:	leave	
0x080491fd <+71>:	ret	

Fig. 3. Typical disassembly result w/o stack canary

0x080491d6 <+0>:	endbr3	2
0x080491da <+4>:	push	ebp
0x080491db <+5>:	MOV	ebp,esp
0x080491dd <+7>:	push	ebx
0x080491de <+8>:	sub	esp,0x104
0x080491e4 <+14>:	call	0x8049110 <x86.get_pc_thunk.bx< td=""></x86.get_pc_thunk.bx<>
0x080491e9 <+19>:	add	ebx,0x2e17
0x080491ef <+25>:	mov	eax,gs:0x14
0x080491f5 <+31>:	mov	DWORD PTR [ebp-0x8],eax
0x080491f8 <+34>:	хог	eax,eax
0x080491fa <+36>:	lea	eax,[ebp-0x108]
0x08049200 <+42>:	push	eax
0x08049201 <+43>:	call	0x8049090 <gets0plt></gets0plt>
0x08049206 <+48>:	add	esp,0x4
0x08049209 <+51>:	lea	eax,[ebp-0x108]
0x0804920f <+57>:	push	eax
0x08049210 <+58>:	lea	eax,[ebx-0x1ff8]
0x08049216 <+64>:	push	eax
0x08049217 <+65>:	call	0x8049080 <printf@plt></printf@plt>
0x0804921c <+70>:	add	esp,0x8
0x0804921f <+73>:	MOV	eax,0x0
0x08049224 <+78>:	mov	edx.DWORD PTR [ebp-0x8]
0x08049227 <+81>:	хог	edx,DWORD PTR gs:0x14
0x0804922e <+88>:	je	0x8049235 <main+95></main+95>
0x08049230 <+90>:	call	<pre>0x80492c0 <stack_chk_fail_loca< pre=""></stack_chk_fail_loca<></pre>
0x08049235 <+y>>:	MOV	ebx, UWUKU MIK [ebp-0x4]
0x08049238 <+98>:	leave	
0x08049239 <+99>:	ret	

Fig. 4. Typical disassembly result w/o stack canary.

The compiler adds the stack allocation and deallocation codes as function prologue and epilogue. Our algorithm detects this code via binary analysis and randomly modifies the size of the stack frame dummy padding differently for each legacy instance. The point of our idea is that we can make this modification solely based on in-place binary patching. To build our system, our patch framework analyzes each binary architecture of the target binary, such as ARM and Intel, and applies a tailored algorithm to each CPU architecture. For example, ARM uses fixed-length instruction encoding, while Intel uses variable-length instruction encoding.

Fig. 5 shows the general function prologue and epilogue for stack frame allocation and de-allocation. In Fig. 5, the size of the local variable is 0x10. Because 0x10 is part of the 32-bit operand encoding (10 00 00 00) of the instruction, this instruction can be changed in-place without reducing or expanding the code. The essence of our idea is to randomly increase this size to make the distance between the stack buffer and the return address unpredictable. The unnecessarily

increased buffer size can be considered as a dummy padding inside memory space which has no harm to program execution. However, if this value is decreased, the program may be damaged as the original buffer cannot hold the given data.

Dump of assembler code for f	unction ma	ain:
0x0000000000402d50 <+0>:	push	r12
0x0000000000402d52 <+2>:	push	rbp
0x0000000000402d53 <+3>:	push	rbx
0x0000000000402d54 <+4>:	sub	rsp.0x10
0x0000000000402d58 <+8>:	mov	OWORD PTR [rsp],rsi
0x0000000000402d5c <+12>:	mov	DWORD PTR [rsp+0xc].edi
0x0000000000402d60 <+16>:	mov	rdi.OWORD PTR [rsi]
0x0000000000402d63 <+19>:	mov	QWORD PTR [rip+0x3109e6],rdi #
0x0000000000402d6a <+26>:	call	0x4b7220 <xmalloc_set_program_name></xmalloc_set_program_name>
0x0000000000402d6f <+31>:	mov	rdi,QWORD PTR [rip+0x3109da] #
0x0000000000402d76 <+38>:	call	0x405190 <bfd_set_error_program_name></bfd_set_error_program_name>
0x000000000402d7b <+43>:	lea	rdi,[rsp+0xc]
0x000000000402d80 <+48>:	mov	rsi,rsp
0x000000000402d83 <+51>:	call	0x4af230 <expandargv></expandargv>
0x000000000402d88 <+56>:	mov	rsi,QWORD PTR [rsp]
0x0000000000402d8c <+60>:	mov	edi,DWORD PTR [rsp+0xc]
0x000000000402d90 <+64>:	хог	r8d,r8d
0x0000000000402d93 <+67>:	mov	ecx,0x4b7b20
0x0000000000402d98 <+72>:	mov	edx,0x4b78df
0x0000000000402d9d <+77>:	call	0x401f00 <getopt_long@plt></getopt_long@plt>
0x0000000000402da2 <+82>:	стр	eax,0xffffffff
0x000000000402da5 <+85>:	je	0x402e65 <main+277></main+277>
0x0000000000402dab <+91>:	sub	eax,0x3f
0x0000000000402dae <+94>:	cmp	eax,0x37
0x000000000402db1 <+97>:	ja	0x402d88 <main+56></main+56>
0x0000000000402db3 <+99>:	jmp	QWORD PTR [rax*8+0x4b7960]
0x0000000000402dba <+106>	: mov	edi,0x4b78d7
0x0000000000402dbf <+111>	: call	0x404550 <print_version></print_version>
0x0000000000402dc4 <+116>	: хог	eax,eax
0x0000000000402dc6 <+118>	: add	rsp,0x10
0x0000000000402dca <+122>		rbx
0x0000000000402dcb <+123>		rbp
0x0000000000402dcc <+124>		r12
0x0000000000402dce <+126>	: ret	

Fig. 5. Typical function's prologue and epilogue code (Binutils cxxfilt). Such code patterns can change depending on compiler options.

The patch appears simple if the stack frame allocation and de-allocation code are symmetric (e.g., add a value and subtract the same value later). However, there are cases where the stack allocation codes are more complicated. For example, when a stack frame of size 100 is allocated by subtracting 100 from to stack pointer and then de-allocated twice with the size of 50, it is difficult to determine which value is the stack frame size because the correspondence of allocation and deallocation codes do not match based on the same operand size. Therefore, we use additional heuristics to filter out exceptional cases of stack frame allocation.

Furthermore, an additional check is performed to determine whether the changed size is appropriate for the diversification patch. The stack size must be increased with 4-byte granularity considering the CPU word alignment, which improves performance when the CPU accesses the memory and prevents alignment faults [25,28].

4.3. HEAP DIVERSIFICATION

The overall concept of applying diversification to heap memory is similar to the previous stack case (binary analysis and finding the appropriate patch call site), but the detailed method is quite different. Heap memory corruption vulnerabilities are generally related to use-after-free and type confusion. Use-after-free refers to a vulnerability that can occur when a dynamically allocated heap space is freed and reused, whereas type confusion refers to a vulnerability that occurs when the instance of an object confuses the type. The heap is a memory segment with complex data dependency based on multiple pointer chains. The code pointer in the stack only needs to consider the return address, whereas, in the heap, it is relatively difficult to find a code pointer based on their memory location. Hence, even slight diversification of the heap memory layout can have a significant impact on exploit development.

Our binary analysis algorithm for heap memory diversification differs from the stack analysis. Generally, heap layout can be dynamically changed using standard methods such as IAT hooking in Windows and LD_PRELOAD in Linux. However, this approach is only possible for *dynamically linked binaries*. However most legacy binaries are based on static linking. This raises the question of how the heap allocation call site can be detected based on a generic algorithm. In this paper, we consider the binary has symbols to indicate the

heap allocation function. Based on such a premise, our algorithm tracks down heap memory allocation sites in the legacy binary by parsing the symbol table. Then, the call site is backtracked to find the memory allocation size parameter (to modify it). However, a few problems occur while finding this size information.

The first is the data interleaving problem. In Fig. 7, the address 0x807f378 represents a heap allocation call site (malloc). To find the allocation size parameter, the instruction must be backtracked, but there are interleaved data inside the code (0x807f370). This data can be misinterpreted as instruction and hinder the analysis. To solve this problem, our algorithm additionally traces the boundary of each basic-blocks and runs backtrace only within the scope inside the block. However, even within the same basic block, there are exceptional cases.

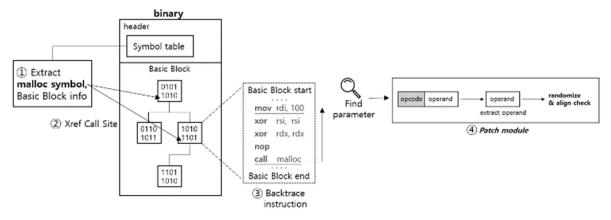


Fig.6. shows the malloc symbol and basic block information extracted from the symbol table in the header of the binary. After extracting the symbol information, the call site information is obtained from the symbol, and the parameter information is obt.

.text:0807F368 .text:0807F36A .text:0807F36A .text:0807F36A .text:0807F36A	; End of functio	BCC B n _ram_:	loc_807F30A loc_807F320 flash_wait(sem_s	*)
		DCD 71	18dm_operations	data
.text:0807F36C	011_807F38C	DCD _2L.	ream_operations_	: DATA
.text:0807F36C				; dm or
	dword 807F370	DCD 0xF	1240	; DATA
.text:0807F370	uworu_00/1/5/10	DCD VAR	230	; ram
.text:0807F374				/
.text:0807F374	:	S U B	ROUTINE =	
.text:0807F374	,			
.text:0807F374				
.text:0807F374	; DWORD fastc	all rar	n initialize(uns	igned in
.text:0807F374			-	; CODE
.text:0807F374				; DATA
.text:0807F374		PUSH	{R4-R6,LR}	
.text:0807F376		MOV	R5, R0	
.text:0807F378		BL	malloc	
.text:0807F37C		LDR	R6, =_ZL18dm_op	erations
.text:0807F37E		MOV	R4, R0	
.text:0807F380		STR	RO, [R6]	; dm_or

Fig. 7. Example case of data interleaving in ARM binary.

🔛 🐋 🖼						
08019D46	83	68			LDR	R3, [R0,#8]
08019D48	1F	69			LDR	R7, [R3,#0x10]
08019D4A	38	46			MOV	R0, R7
08019D4C	01	FO	9C	FA	BL	fat_semtake
08019D50	38	46			MOV	R0, R7
08019D52	01	FO	FB	FA	BL	fat_checkmount
08019D56	06	46			MOV	R6, R0
08019D58	30	BB			CBNZ	R0, loc_8019DA8

Fig. 8. Exceptional case for tracking function parameter. In the example, it is ambiguous to determine which R0 is the actual parameter for the function fat_checkmount.

Fig. 8 shows two function parameters in the same basic block. Because function parameters are stored in a stack and restored immediately before they are used, it is difficult to determine which parameter is the actual size parameter based on static code analysis.

5. IMPLEMENTATION

To implement our algorithms, we use Patchkit [29], for ELF binary patch, and Capstone [27], Radare2 [30], and Keystone [31] tools for binary analysis and disassembly/reassembly. Overall, implementations are written in 979 lines of Python and 1,495 lines of additional Docker/management codes.

5.1. ARM STACK

Algorithm 1 – The ARM Stack pseudo code. Prefixes/ Postfixes such as "BB" denotes the basic block of function, "dis" denotes the dissemble result of the Capstone library, "ins" denote each instruction, and "SP" denotes the stack pointer.

0: function PATCH(binary)

1: for func in binary_funcs() do

2:	startBB \leftarrow func_startBB_dis			
3:	for ins in startBB do			
4:	<pre>if ins_OpcodeName = "sub" then</pre>			
5:	src, dst \leftarrow ins_operands			
6:	else			
7:	Skip			
8:	end if			
9:	<pre>if src = SP_reg & dst = stack_size then</pre>			
10:	prologue \leftarrow ins_addr			
11:	end if			
12:	end for			
13:	for ins in reversed(endBB) do			
14:	<pre>if ins_OpcodeName = "add" then</pre>			
15:	src, dst \leftarrow ins_operands			
16:	else			
17:	Skip			
18:	end if			
19:	<pre>if src = SP_reg & dst = stack_size then</pre>			
20:	epilogue ← ins_addr			
21:	end if			
22:	end for			
23:	if prologue = epilogue then			
24:	function RANDOMIZE(stack_size)			
25:	get (alignment info)			
26:	ran_num ← random.randrange(0, 0x10)			
27:	$new_stack_size \leftarrow stack_size +ran_num$			
28:	Patch()			
29:	end function			
30:	end if			
31:	end for			
32:	32: end function			
ть	o overall flow of the stack randomization for A			

The overall flow of the stack randomization for ARM 32bit is shown in Algorithm 1. The disassembly result for the first basic block of each function is initially processed, and this result includes instructions such as push and *mov*. To find the address of the subtraction instruction of the stack (e.g., memory allocation), each instruction in the basic block is analyzed, and if the opcode is *sub*, the operand is remembered. If this value is constant (e.g., immediate type value), we conclude this is the stack frame size corresponds to the function prologue. Next, we scan each instruction to find the corresponding add instruction as the match for stack

memory deallocation. Afterward, a new stack size is generated using the diversification algorithm, and the stack size is randomly increased respecting the CPU word alignment. Finally, the stack-frame size related instructions are patched in-place.

5.2. X86 STACK

The x86 stack randomization evaluation is performed using the Windows CE binary. Because the Windows CE binary cannot use the Patchkit library [29], our framework implemented a custom code detection for our algorithm. For patching, our tool traces instructions starting from the entry point and applies the same algorithm as ARM stack. In the Windows binary, it was more difficult to identify the function location, size, and internal structure compared to ARM. However, it was easy to apply the patch if the function frame used *leave* instruction for function epilogue as the instruction automatically calculates the required stack size for deallocation.

5.3. ARM HEAP

Algorithm 2 – The ARM Heap pseudo code. Prefixes/ Postfixes such as "BB" denotes the basic block of function, "dis" denotes the dissemble result of the Capstone library, "ins" denote each instruction.

0: function PATCH(binary)

1: for target_addr in malloc_BB do

- 2: bb ← malloc_BB[target_addr]
- 3: startpos \leftarrow target_addr len(bb) + 4
- 4: **for** ins **in** dis(bb, startpos) **do**
- 5: if ins_mnemonic is "movs" then
- 6: **if** ins_operands is register **then**
- 7: Reg \leftarrow ins_reg_name
- 8: end if
- 9: **if** Reg = "r0" **then**
- 10: MRU ← (ins_addr, ins_str, bb[offset|opcode])
- 11: end if
- 12: end if
- 13: end for
- 14: **if** MRU \neq None **then**
- 15: get(alignment info)
- 16: pad \leftarrow random.randrange(0xf0 imm)
- 17: Patch(MRU, pad)
- 18: end if
- 19: end for

20: end function

The overall flow of the heap randomization for ARM 32bit is shown in Algorithm 2. Before performing randomization, the malloc position is first found by parsing the symbol table of the target binary. Then, all the basic blocks that contain the malloc address are loaded and saved. At this point, analysis is performed considering the ARM and THUMB modes.

The core of the algorithm is to find a pattern corresponding to the heap size allocation of malloc. When movs instruction is found, we check if the target register corresponds to r0 because r0 is the register used as the first function parameter. We determine that the value for r0 is the malloc size based on heuristics and save all the size data. All values that contain r0 inside the basic block are collected, and if there are multiple values, the closest value to the malloc call site is used as the malloc size parameter. The randomization patch is then performed. In the heap, memory alignment must follow 16-byte (128bit) granularity because of the ARM NEON instructions.

5.4. X86 & X64 HEAP

To perform the heap randomization on x86 and x64, we use the malloc address from the symbol table and *basic block border* information of the entire functions based on binary analysis. We use basic block border information to apply our algorithm solely to a single block. Similarly to the ARM case, if the *mov* instruction operand is the immediate type and is closest to the call site, we consider the information as a size parameter. Finally, we also respect the memory alignment of 16-byte (128-bit) granularity considering the use of SIMD instructions using 128-bit MMX registers.

6. EVALUATION

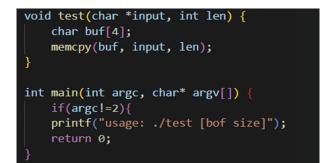
In this study, experiments were performed by porting all related codes into a Docker container image for efficiency. The server environment for our evaluation is composed of 16GB RAM, and 1TB SSD, based on Ubuntu 16.04 64bit server. The Intel PX4 Autopilot Drone firmware (ARM 32-bit) was mainly used for stack diversification testing. The soundness of patched drone firmware was checked with basic system functionalities after the booting process.

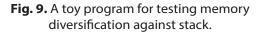
6.1. STACK

1) Buffer overflow Toy example

We evaluated our system using a simple x86-based toy binary that has memory vulnerability. In the experiment, we used a general stack buffer overflow vulnerability exploitation as a test case.

When the example code is executed, buffer overflow is triggered, and a segmentation fault error occurs because the return address is broken. However, when a buffer overflow vulnerability was triggered for a binary with diversified stack sizes using our patch tool, the result of the attack was unpredictable.





		fer-overf ine 15:				
===:			======	===:		
	running test	buffer-o	verflow	to	patched	varients
no t	oof					

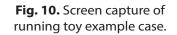




Fig. 11. Result after applying stack memory diversification against PX4-based drone. The screen on the left side indicates internal command/ communication operates without problem after patching. Right side of the picture shows LED blinking of the UAV that indicates its normal operation.

We evaluated our system using PX4 Autopilot Drone firmware (ARM 32-bit) binary as a test case of ARM binary. When the stack memory layout in the PX4 firmware was randomized using our patch tool and then executed in the same manner as the firmware before the patch, all functions worked normally despite thousands of codes being modified for diversification. Fig. 11 shows *nsh* program, the shell interpreter of the drone. All the commands in *nsh* shell operated correctly before/after our patch.

3) Windows CE binary

We evaluated our system using a collection of 42 binaries, including *pmkdir*, *pmemmap*, and *pdebug*, which are tools that can be used in Windows CE provided by [32]. Wine [33] was used for compatibility to run Windows-exclusive programs on the Linux operating system. All functions worked normally when the diver-

sification-patched binaries were executed. Randomization patch was performed in several tens of places in the case of the Windows CE binary.

6.2. HEAP

1) Toy example

We use a simple toy example to evaluate our heap diversification patch. Fig. 13 shows the before/after result of the diversification patch to the example program. The randomization result showed that the heap allocation address was all changed, however all *printf()* functions in the example code were executed normally. The top portion of the allocation address was changed because of the ASLR effect (not because of our diversification), however, and the bottom offset portion (marked with a red box) was also changed by our patch tool (this part should not change in the normal case). We used gcc and clang with multiple optimization levels ranging from zero to three, and Fig. 13 is based on the optimization level zero.

```
void f1(){
    char* ptr = malloc(100);
    ptr[5] = 1;
    printf("heap buffer at %p\n", ptr);
void f2(){
    char* ptr = malloc(40);
ptr[5] = 1;
    printf("heap buffer at %p\n", ptr);
void f3(){
    char* ptr = malloc(256);
    ptr[5] = 1;
printf("heap buffer at %p\n", ptr);
void f4(){
    unsigned int size = getpid()*1000;
    size = size%1000;
    char* ptr = malloc(size);
    memset(ptr, 0xff, size);
    printf("heap buffer? at %p\n", ptr);
3
int main(){
    f1();
    f2();
    f2();
    f2();
    f3();
    f4();
    printf("end\n");
    return 0;
```

Fig. 12. A toy program for testing memory diversification against heap.

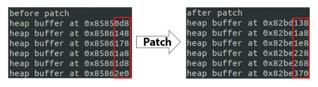


Fig. 13. Before/after applying heap randomization patch. The red box indicates the internal heap offset is changed across the patch (the upper part of the address is changed due to ASLR).

2) Binutils

We applied our system to the GNU Binutils binaries for performance evaluation. The Binutils version in our evaluation is based on 2.31.1 and the architecture is 64-bit Intel. After the randomization patch, all binaries are executed as originally intended. To measure the execution time delay due to the unnecessarily expanded memory layout, we repeatedly tested the execution time of various Binutils programs before/after we applied our system. The program execution time is measured based on a simple python script.

Table 1 summarizes the result (program execution time) of the comparison between binaries before and after patching. We noticed that there was tiny degradation in the execution time before and after the patch. However, the overall amount of performance degradation is negligible.

Table 1. This table is organized by comparing the binary execution time before and after randomizing to the Binutils binary using our tool. Table 1 is the result of 1000 runs each, and the following options were used to test.

Binary	Before	After	Option
addr2line	0.809s	0.732s	Check the file related to the execution file address and the line information
ar	0.877s	1.014s	Generate an archive
nm-new	0.916s	0.921s	Check the symbol information of the file
objcopy	0.751s	0.749s	Generate a new file after extracting the instructions and data of the file
objdump	1.113s	0.867s	Check all contents of the object file
ranlib	0.826s	0.825s	Register the library so that it can be used
readelf	3.516s	3.682s	Output the dependency of 'ld' including type
size	0.805s	0.848s	Output the file size
strings	1.874s	1.904s	Output the offset of the execution file
strip-new	0.879s	0.938s	Remove the symbol

3) PX4 drone

We used the PX4 Autopilot Drone firmware binary for heap diversification evaluation as well. Similarly to the stack experiment, all functions worked normally when the heap memory layout in the PX4 firmware was randomized with our patch tool and the binary was executed in the same manner as the firmware before the patch.

7. CONCLUSION

With the emergence of memory corruption vulnerabilities, defense technologies that apply diversification to software systems, such as stack canary and isolated heap, are being extensively researched. However, because the source codes are unavailable, such defense technologies cannot be applied to very old legacy systems. To remedy such a problem, this study presents an alternative approach to apply memory layout adjustment solely based on binary analysis and patching. We mainly apply diversification against two memory components: stack and heap. As an experimental approach, we chose stack and heap as diversification targets because they are the most common memory section of any computer system. By applying our idea, it is expected that the attack time and cost will increase significantly as the attacker must adjust the attack payload differently each time when attacking an instance. We conducted experiments using real-world programs such as Intel PX4 Autopilot Drone firmware (ARM 32bit) binary, and Binutils in the Linux system. The results demonstrated our diversification did not break any original semantics of the program yet successfully changed the memory layout for the attacker.

8. ACKNOWLEDGMENT

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