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#### MQ-25A Manned/Unmanned Teaming

Miller, Scot A.; McGuire, Mollie R.; Boger, Dan C.

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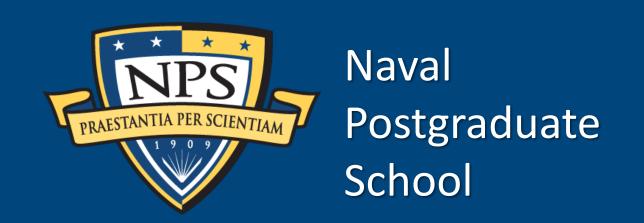


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## MQ-25A Human Machine Teaming (HMT) in Non Permissive Environment



#### **Problem Statements**

- F/A-18 have short unrefueled mission ranges
- No organic tanker on CVs today
- F/A-18s are used as tankers
- Removes strike aircraft from strike mission;
   adds stress to aircrew
- MQ-25 designed to eliminate these issues



MQ-25A in action



MQ-25 with F-35

#### **MQ-25A**

- First unmanned tanker; carrier based; IOC 2024
- Supports mission and recovery refueling; ISR is secondary mission
- Operates in permissive environment
- Expect operations in non permissive environments
- Operated by Air Vehicle Operators (AVOs)
- AVOs will be Warrant Officers (WO-1)

### **Approach and Findings**

- Use Co-Active Design and Interdependence Analysis (IA) to determine observability, predictability, and directability requirements for HMT
- For operational realism, move away from assumption of permissive environment
- Give AVO's JICO like training so they are flexible across primary, alternate, contingency, and emergency comm paths
- Non permissive environments require E-2s and receiver aircraft as MQ-25 teammates
- Add digital interoperable planning and after action review systems that promote machine learning and HMT trust

# Figure 6-13. Tanker Rendezvous Pattern

CV Recovery Refueling
Pattern

### **Next Steps**

- Explore human machine teaming options which support refueling operations in non permissive environment
- Investigate human machine teaming options for an enhanced ISR capability
- Develop considerations for building trust in the human machine relationship



Researchers: CAPT Scot Miller, USN (ret), IS; Dr Dan Boger, IS

Student: Capt Andrew Benton, USMC, IS **Topic Sponsor:** CAPT Greg Machi, PMA-268

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