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Bipartite Graph Learning for Autonomous Task-to-Sensor Optimization

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Monterey, California: Naval Postgraduate School

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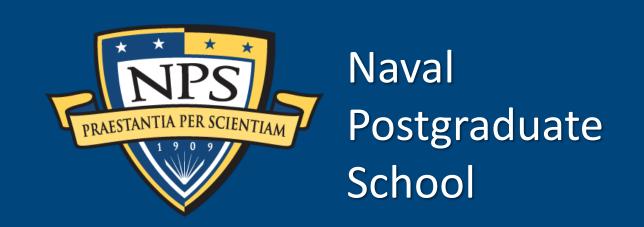


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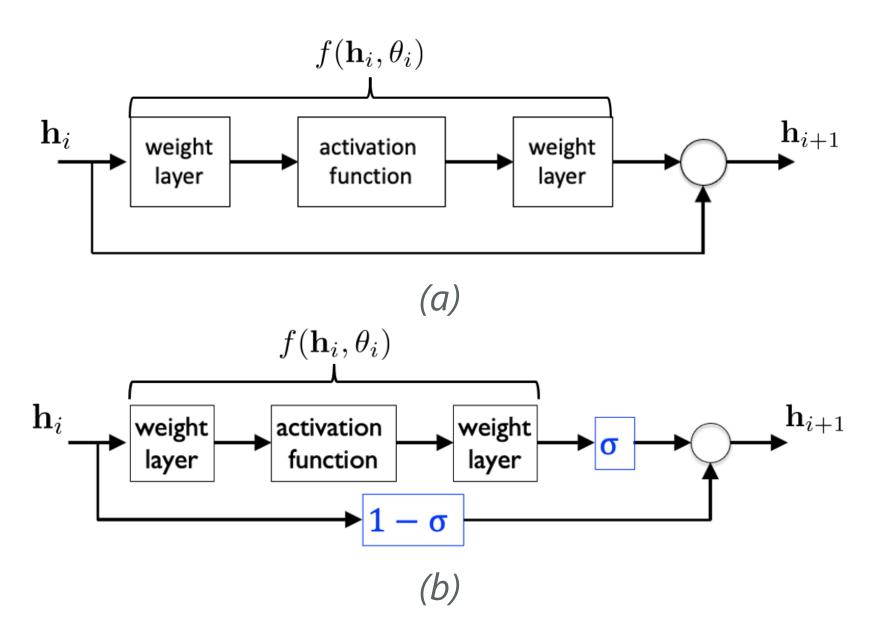
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Bipartite Graph Learning for Task-to-Sensor Optimization

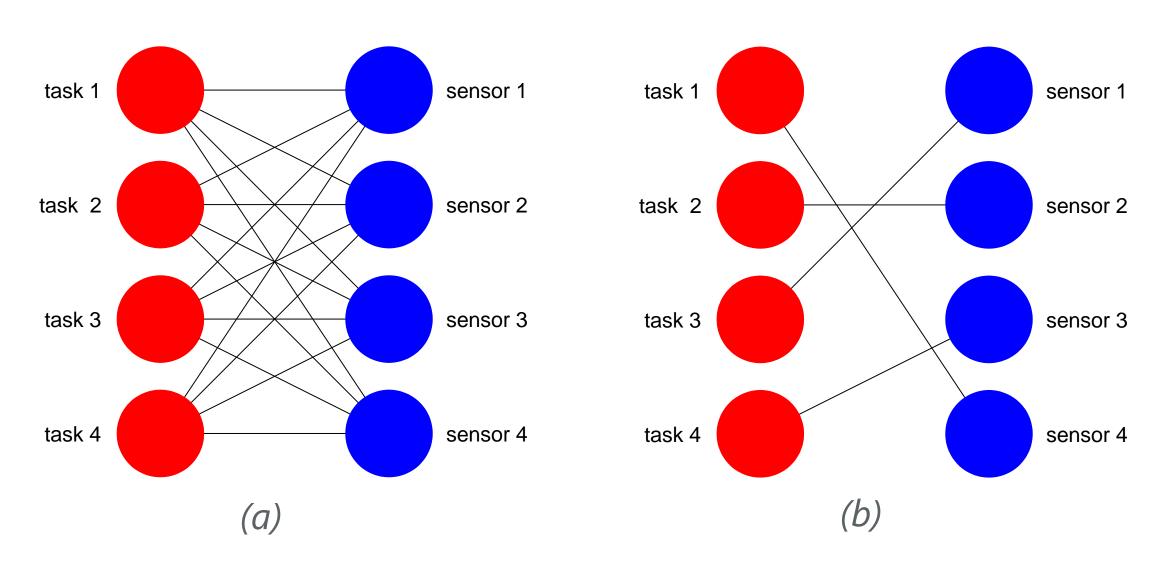


Background/Objective

- •The concept of a bipartite graph provides a mathematical framework for task-to-sensor mapping by establishing connectivity between various high-level tasks and the specific sensors and/or processes that must be invoked to fulfil the task requirements.
- •This project studies how machine learning can be used to perform autonomous bipartite matching for task-to-sensor optimization.
- •The results can be applied for various DoD applications including joint targeting and fires.



Conventional residual network layer (a) and the 'weighted residual' network layer (b) used for solving bipartite matching problems



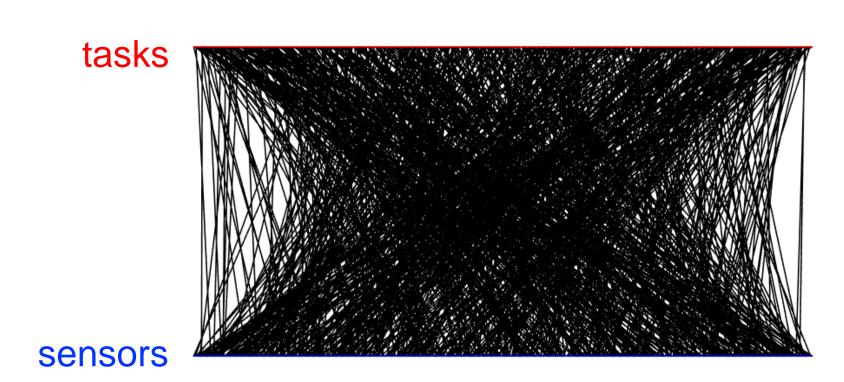
Task-to-sensor allocation can be posed as a bipartite graph matching problem (a) where the goal is to match each task to a sensor in a way that minimizes cost or maximizes value (b).

Network Architecture

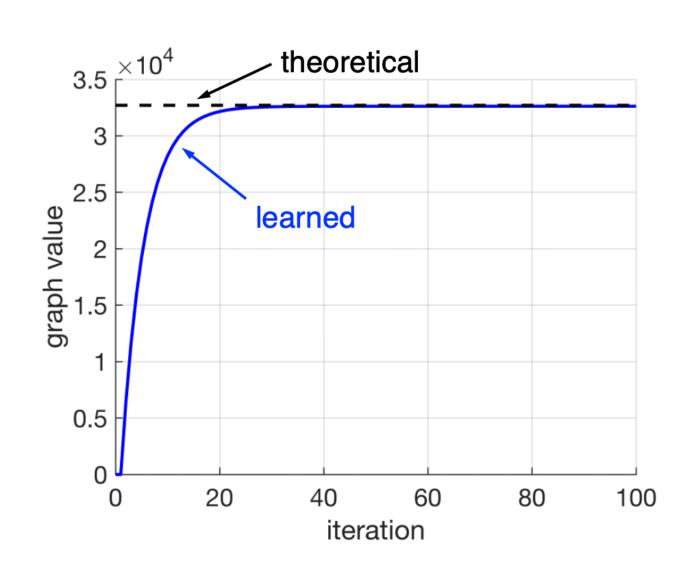
- •A deep network of weighted residual layers was studied for solving the bipartite graph problem.
- •A conventional residual network, uses 'skip' connections to add the input of a layer together with its output. By weighting the skip connection, the feedforward term can be modulated to influence the signal evolution within the network equations to solve the matching problem
- •The proposed architecture can be used for finding minimum cost or maximum value mappings (depending on the objective of the user)

Example Results

The machine learning-based approach is scalable to large problem sets



Example bipartite
matching solution for
n=m=800 (left) and
the evolution of the
'learned' graph value
(right)



Conclusion

- This study shows that machine learning concepts can be used to autonomously perform bipartite matching for task-to-sensor planning/optimization problems.
- As the state of knowledge evolves, the approach can be used to periodically and rapidly re-solve allocation problems to reflect changes in resource availability and/or task completion.



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