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Zhaoyang Zhang University of Massachusetts Medical School

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A New MI-Based Visualization Aided Validation Index for Mining Big Longitudinal Web Trial Data

Zhaoyang Zhang¹, Hua Fang¹, and Honggang Wang²

¹Department of Quantitative Health Science, University of Massachusetts Medical School, Worcester, MA 01605, USA

²Department of Electrical and Computer Engineering, University of Massachusetts Dartmouth, North Dartmouth, MA 02747, USA

Abstract

Web-delivered clinical trials generate big complex data. To help untangle the heterogeneity of treatment effects, unsupervised learning methods have been widely applied. However, identifying valid patterns is a priority but challenging issue for these methods. This paper, built upon our previous research on multiple imputation (MI)-based fuzzy clustering and validation, proposes a new MI-based Visualization-aided validation index (MIVOOS) to determine the optimal number of clusters for big incomplete longitudinal Web-trial data with inflated zeros. Different from a recently developed fuzzy clustering validation index, MIVOOS uses a more suitable overlap and separation measures for Web-trial data but does not depend on the choice of fuzzifiers as the widely used Xie and Beni (XB) index. Through optimizing the view angles of 3-D projections using Sammon mapping, the optimal 2-D projection-guided MIVOOS is obtained to better visualize and verify the patterns in conjunction with trajectory patterns. Compared with XB and VOS, our newly proposed MIVOOS shows its robustness in validating big Web-trial data under different missing data mechanisms using real and simulated Web-trial data.

INDEX TERMS

Multiple imputation; clustering validation; pattern recognition; visualization; longitudinal web trial data

I. INTRODUCTION

The big data have been massively generated from web-delivered clinical trials $[1^{j-l}4]$. These complex data provide valuable information for disentangling the heterogeneity of treatment effect (HTE). HTE refers to the fact that patients exposed to a common influence (such as tobacco exposure or randomization to a treatment) often experience very different outcomes $[5^{j-l}7]$. HTE is common in translational research, especially in complex, multi-component interventions, such as Phase III trials designed to move evidence-based guidelines into practice. Even in a randomized controlled trial (RCT), outcomes differ

Corresponding author: H. Fang (hua.fang@umassmed.edu).

among patients within treated and control groups. Methods that can extract the full information implicit in HTE hold great promise for delivering patient-centered care [8]–[12].

In 2011, the NIH Comparative Effectiveness Research Key Function Committee and Patient-Centered Outcome Research Institute (PCORI) specifically called for methods to address HTE for improving the design, conduct, and analyses of patient-oriented research [13]. A "holistic" approach to HTE considers the full domain of HTE demographics, pre-treatment risks (e.g., psychological, physiological, genotype, environmental), experience of side effects, differential responses to treatment, and health utility preferences as well as its relationship with outcomes. Implementing such an approach has been described as "the next great task of clinical research in the 21st century" [14].

Standard approaches to HTE use either a simple "exposed" or "non-exposed" grouping to describe a complex treatment procedure for detecting binary effects (yes/no), or subgroups based on arbitrarily determined cut-scores (e.g., quintiles or percentages), generating possibly spurious false-positive findings [15]. Going beyond standard approaches, unsupervised learning methods have been applied to HTE studies. Among them, our MI-Fuzzy model has been developed $[12^], [16]^{-}[20]$. It uses all collected big trial data and actual values of patients' responses to characterize variations and changes in treatment over time. This method can reduce the uncertainty of imputation and the uncertainty of the clustering accuracy compared to non- or single-imputed methods commonly used in unsupervised learning [17] and generate salient patterns from real-world data that are longitudinal, non-normal, high dimensional and contain missing values. These salient patterns represent different treatment "doses" patients received, which increase the predictive power and facilitate detecting "gradient effects," that is, varying degrees of patients' responses to treatment ("treatment uptake") will lead to differences in outcomes (e.g., severe, normal, mild).

However, in this line of research, a key problem is to determine the number of patterns or clusters in these big complex data. Under the framework of fuzzy clustering, Xie & Beni (XB) index is widely used, but its performance depends on the choice of the fuzzifiers, therefore sensitive to some data types [21[]], [[]22[]]. Another recently developed overlap and separation index (VOS) [23] is also designed for fuzzy clustering and independent of the choice of fuzzifiers. However, it has the worst performance for the longitudinal web trial data where the inflated zeros and missing values are common as shown in our numerical analyses in this paper. Additionally, no matter how robust a validation index is, it might not perform well for all data types. Since comparing different indexes may not always result in consistent findings based on our empirical research, visualization may help verify, tease out trivial clusters and determine the optimal number of patterns in addition to the validation indices [19]. Using visualization technique is intuitively reasonable because of the way the human brain processes data. How to design a visualization-aided validation, thus, becomes an intriguing and challenging task.

In this paper, building upon our multiple imputation (MI) based validation framework [17[]], [[]24], we propose a MI-based visualization-aided validation index (called MIVOOS) to

determine the optimal number of clusters or trajectory patterns for big incomplete longitudinal web trial data. The validation index is defined as the weighted sum of overlap and separation measures. By optimizing the viewing angles for the 3D Sammon-projections and linking with MIVOOS, we obtain the optimal number of clusters. The proposed algorithm is evaluated using real and simulated big incomplete longitudinal web trial data. The major contributions of this paper are threefold. First, a new multiple-imputation based overlap over separation index (MIVOOS) is proposed to identify patterns in zero-inflated longitudinal web trial data with missing values. The proposed MIVOOS index outperforms the existing VOS validation index in real and simulated data and unlike XB, it does not depend on the choice of fuzzifiers. Second, a visualization aided MI based validation framework and algorithm is generated to verify and determine the optimal number of patterns. Third, a joint zero-inflated Poisson and autoregressive mixture model (JZARM) is built up to simulate the mixtures of zero-inflated longitudinal web trial data.

Table 1 shows the symbols and notations used in this paper. The rest of this paper is organized as follows: Section II discusses the proposed MI-based VOOS validation and its algorithm. Section III illustrates the visualization aided validation framework; Section IV presents numerical results from real and simulated big web trial data under three missing mechanisms; and Section V concludes the paper.

II. VALIDATION INDEX FOR WEB TRIAL ENGAGEMENT PATTERNS

The key problem in pattern recognition is to decide the optimal number of patterns. Unlike the data structure studied in text, human brain or various networks, longitudinal behavioral trial data, although fluctuating and complex with missing values, typically follow (non-) linear trends. Based on our research, probability or statistical model-based (e.g., Gaussian mixture or Bayesian), hierarchical or neural network-related clustering did not work well or failed for this type of non-normal data, although they are popular in other study domains [25]. Our previous research on fuzzy clustering also shows Xie and Beni (XB) index performs consistently well in validating clusters of behavioral trial data, while the Partition Coefficient with decreasing monotonicity (smaller is better), and Partition Entropy with increasing monotonicity (larger is better) do not. Nevertheless, XB is dependent on the choice of fuzzifiers and needs evaluation before selecting the optimal number of clusters [21]. XB is widely used in fuzzy clustering validation, and expressed as,

$$XB = \frac{\sum_{i=1}^{N} \sum_{k=1}^{K} u_{ij}^{m} ||x_{i} - v_{k}||^{2}}{N \cdot \min_{i,k} ||x_{i} - v_{k}||^{2}},$$
 (1)

in which u_{ij} *U* is the fuzzy degree of membership, x_i is a vector of the observations of the *i*-th case, and v_k is the mean trajectory of the *k*-th cluster. However, our empirical results indicate that web trial data are likely to be zero-inflated count data, in other words, it is likely to find a pattern where patients are not or rarely engaged in trial components over time. In this case, especially with the increase of the number of clusters *k*, the denominator of XB will become zeros, leading to the infinity of XB values. Therefore, it is possible that XB cannot point to an optimal number of clusters for zero-inflated data.

Another recently-designed validation index in fuzzy clustering is called overlap and separation index (VOS) [23], Using VOS on the simulated zero-inflated longitudinal web trial data, we found no matter how the parameters and the actual number of clusters are, VOS always pointed to three clusters. This finding indicates that the VOS may not be suitable for zero-inflated longitudinal web trial data. Due to the disadvantages of these two indexes, we proposed a new validation index, overlap over separation index (OOS) to find the optimal number of clusters using MIFuzzy for such trial data. When no missing values exist in the data, OOS can be expressed as

$$OOS(k,U) = \frac{O(k,U)}{S(k,U)}.$$
 (2)

Definition 1: If a dataset is clustered to k clusters with a membership matrix U, let Z_{ki} and Z_{kj} be two fuzzy sets, the relative degree of sharing of Z_{ki} and Z_{kj} at x_i is defined as [23],

$$f(x_i:Z_{ki}, Z_{kj}) = \min(U_{Z_{ki}}(x_i), U_{Z_{ki}}(x_i)), \quad (3)$$

the overlap measure is defined as [23],

$$O(k,U) = \frac{2}{k(k-1)} \sum_{ki \neq k}^{k} \sum_{j=1}^{n} h(x_i) f(x_i; Z_{ki}, Z_{kj}),$$
(4)

 $h(x_i) = -\sum_{1}^{k} U_{Z_j}(x_i) \log U_{Z_j}(x_i), U_{Z_j}(x_i), U_{Z_{ki}}(x_i) \text{ and } U_{Z_{kj}}(x_i) \text{ denote the fuzzy membership degree where } x_i \text{ belongs to clusters } Z_{ki} \text{ and } Z_{kj}, \text{ respectively.}$

Definition 2: If a dataset is clustered to k clusters with a membership matrix U, let Z_{ki} and Z_{kj} be two fuzzy sets, the separation measure is defined as

$$S(k,U) = \frac{1}{k} (1 - \min_{ki \neq kj} (\max_{i} f(x_i; Z_{ki}, Z_{ki}))).$$
(5)

The number of clusters in the data can be inferred by minimizing the OOS index,

$$\hat{k} = \arg \min_{k} OOS(k, U).$$
 (6)

Although both VOS and our OOS use the concepts of overlap and separation, the differences between the two indices are: 1) The overlap and separation measures used in OOS are not normalized, while VOS uses normalized overlap and separation measures; 2) Unlike VOS, OOS index uses a different separation measure with the number of clusters k as a factor.

The real-world longitudinal web trial studies, such as QuitPrimo [26^{], [27]}, often have incomplete data [24], which make it impossible to directly apply the OOS and other existing validation indexes such as XB. Built upon on our MI-based validation framework [17^{], [24]}, ^[28], we propose a MI-based OOS validation index (MIVOOS) to find the optimal number of clusters for longitudinal web trial data with missing values. Briefly, multiple imputation is conducted for an incomplete dataset and MI-based clustering is implemented for each imputed complete data set. Specifically for MIVOOS, the MIFuzzy procedure is conducted to obtain the fuzzy degree of cluster membership *U* for each *k* = 2, 3, …, *K*, then the MIVOOS is calculated as

$$MIVOOS(k) = \frac{1}{M} \sum_{m=1}^{M} OOS_m(k, U_m),$$
(7)

in which *M* is the number of imputations, U_m is the matrix of fuzzy degree of membership of the *m*-th imputed data. $OOS_m(k, U_m)$ shows the OOS validation for clustering the *m*-th imputed dataset into *k* groups. The optimal number of cluster is decided when MIVOOS reaches its minimal value,

$$\hat{k} = \arg\min_{k} MIVOOS(k).$$
 (8)

III. VISUALIZATION AIDED MI-VALIDATION FOR BIG INCOMPLETE WEB TRIAL DATA

Big data visualization, although challenging, can help us better understand the structure (patterns) of the dataset, through a direct presentation of the trends, gaps, overlaps, or outliers of data $[29^{]-[}35]$. In this section, we designed a visualization aided algorithm to implement the newly-proposed MIVOOS in order to decide the optimal number of clusters in the zero-inflated longitudinal web trial data with missing values. The algorithm works as follows: 1) Conduct MIFUZZY to obtain fuzzy membership for k = 2, 3, ..., K; 2) apply the visualization aided MIVOOS to determine the optimal number of clusters \hat{k} ; 3) output the optimal 2-dimensional projection when $k = \hat{k}$. The procedure of the proposed visualization aided MIVOOS validation is demonstrated in Figure 1.

In this algorithm, the optimal number of clusters \hat{k} is first calculated by finding the minimal MIVOOS values, then the optimal 2-dimensional projection for \hat{k} . The linkage of MIVOOS and our newly-improved Sammon-mapping-based visualization algorithm [19], [36], [37], called projection-overlap measure (PO) can be calculated as

$$PO(\hat{k}) = \frac{1}{N} \sum_{i=1}^{N} \left(\max_{k=1,\dots,K} \left\{ (u_{ij} < \gamma) + 1/j \right\} \right), \quad (9)$$

in which $\gamma = 0.2$ is a constant value. If $PO(\hat{k})$ is larger than a predefined threshold, the optimal number of cluster decreases by 1 and the optimal 2-dimensional projections need to be updated. The threshold of projection-overlap measure is set to be 0.1 in this work based on our empirical evaluation and simulation studies. The algorithm of visualization aided validation is shown in Algorithm 1.

Algorithm 1

Visualization of Identified Patterns

Require: MIVOOS
Ensure: \hat{k} and optimized 2D projections $X_{\alpha,\beta}$
1: Determine the number of clusters \hat{k} by finding the location of the minimal MIVOOS value
2: Get optimized 2D projections $Y_{\alpha,\beta}$ for \hat{k} clusters,
3: Calculate the PO measure for k clusters PO_k ;
4: if PO_k is bigger than a predefined threshold then
5: $\hat{k} = \hat{k} - 1$,
6: Go to step 2,
7: end if
8: Output number of clusters and optimized 2D projections.

To detect the optimal 2D projection, the viewing angles of 3D Sammon's projections need to be optimized because even if the validation index points to a minimal value, the 2D visual graphs may not well present the number of clusters. In addition, the visualization can help verify and determine the number of clusters because any validation index does not always show consistent results no matter how robust it is. The Sammon's stress can be calculated by [36], [38]

$$S = \frac{1}{\sum_{i < j} D_{ij}^*} \sum_{i < j} \frac{\left(D_{ij}^* - D_{ij}\right)^2}{D_{ij}^*},$$
(10)

in which D_{ij}^* and D_{ij} are the Euclidean distance between cases *i* and *j* in the original highdimensional space and the projected low-dimensional space, respectively. By Sammon's mapping algorithm, a high-dimensional data can be projected onto a lower dimensional space, such as 2-dimensional (2D) plane and 3-dimensional (3D) Space. 3D scatters show better visualization results because it has one more dimension (i.e., with more information) than 2D scatters. However, the 3D scatters have different patterns if viewed from different angles. Therefore, to obtain the best view of the 3D scatters and the corresponding best 2-D view, we need to optimize the angles from which we view the scatters. There are two parameters for the viewing angles, α and β , indicating the degrees of the horizontal rotation and the elevation of view-point, respectively.

To optimize the viewing angles, α and β , of the 3D scatters, we first transform the 3D scatters to 2D projections using orthographic transformation with parameters α and β , and then we minimize the sum of squared error (SSE), which is calculated by,

$$SSE = \sum_{k=1}^{K} \sum_{x \in c_k} \left\| x - v'_k \right\|^2, \quad (11)$$

in which $x = c_k$ represents all cases in the *k*-th cluster, v'_k is the mean trajectory of the projected *k*-th cluster. The optimal viewing angles are obtained by minimizing the SSE for each pair of α and β ,

$$(\alpha,\beta) = \arg\min_{\alpha,\beta} SSE(X_{\alpha,\beta}), \quad (12)$$

in which $\alpha = [0, 2\pi)$ and $\beta = [-\pi, \pi)$, $X_{\alpha,\beta}$ is a 2D projection of the 3D Sammon scatters viewed from the α and β ,

$$X_{\alpha,\beta} = H_{\alpha,\beta} \times X_3, \quad (13)$$

in which

$$H_{\alpha,\beta} = \begin{bmatrix} \cos(\alpha) & \sin(\alpha) & 0\\ -\sin(\alpha)\sin(\beta) & \cos(\alpha)\sin(\beta) & \cos(\beta) \end{bmatrix}.$$
 (14)

By optimizing the view angles, we can obtain the best 2D projections of the 3D Scatters X_3 using Sammon's mapping. Additionally, the trajectory visualization is further used to verify these longitudinal web trial data patterns. A smooth function, such as the Shape-Preserving Piecewise Cubic Interpolation (pchip) [39[]], [40] can be used to display the mean trajectory pattern which represents the trend of each cluster.

The performance of pchip is shown in Figure 2. The circled red line stands for the mean trajectory of the first cluster in QP, smoothed by the pchip method. Compared to the spline function, pchip is more robust, because the spline method showed negative values which are not true for the non-negative web data as highlighted in the squares.

IV. PERFORMANCE ANALYSIS OF VISUALIZATION-AID MIVOOS VALIDATION

This section evaluates the proposed visualization-aided MIVOOS on real and simulated zero-inflated longitudinal web trial data under three missing data mechanisms, missing completely at at random (MCAR), missing at random (MAR) and missing not at random (MNAR) [17].

A. BIG WEB TRIAL DATA

The real big data (N = 1320; d = 18) was collected from is a two-arm longitudinal web trial study designed to assist in the smoking cessation of a general smoker population. The intervention arm was engaged with three extra components which the control arm cannot see, My Mail (MM), Online Community (OC), and Our Advice (OA). The first intervention component, MM, describes how often smokers communicate with a tobacco treatment specialist in a secure form. The second component, OC, measures how often the smokers are engaged or encouraged by experts. The third main component, OA, describes how many times smokers view messages and dialogue from peers and ex-smokers through a resource website. As shown in Figure 3, both MI-based XB (*fuzzifier* = 1.1) and MIVOOS (not depending on fuzzifier) indicate four clusters while VOS (not depending on fuzzifier) points to two clusters. Although the optimal number of clusters \hat{k} could be four based on MI-XB and MIVOOS, the visualization could help validate this result as illustrated above.

The 2D and 3D projection of QP data were further implemented according to Equation 10– 15. Figure 4(a) shows the scatters of the identified four clusters with the optimal viewing angles, and Figure 4(b) shows its corresponding 2D projection. Figure 5(a) and 5(b) display the 3D scatters with random viewing angles and the corresponding 2D projections, respectively. Clearly, a random 3D projection and resulting 2D plot will mislead the clustering results even with both MIVOOS and MI-XB pointing to 4 clusters.

To verify the optimal number of clusters, the 2D five clusters from the best view angle was further examined for the QP data. As shown in Figure 6, Cluster 5 is likely a trivial pattern, as it contains very few cases and is likely parsed out from Cluster 4. Figure 7 further exhibits clear trajectory patterns (smoothed mean trajectory against individuals) representing distinct web engagement patterns of each cluster.

B. SIMULATION RESULTS

A joint zero inflated Poisson and Autoregressive mixture model (JZARM) is proposed to simulate the longitudinal web trial data with missing values, given the hidden patterns, zero inflation and time correlation in such data.

$$X_{\rm kit} = \mu_{\rm kit} + \Phi_{\rm kit} X_{ki(t-1)} + \varepsilon_{\rm kit}, \quad (15)$$

where $\Pr(X_{ki0}=h)=I(h)\pi+(1-\pi)\frac{\lambda^h e^{-h}}{h!}$, *h* is a parameter of zero-inflated Poisson model (ZIP) and $h \ge 1, \lambda$ is the expected Poisson count, π is the probability of extra zeros. k = 1, ..., K denotes the number of clusters, $i = 1, 2, ..., n_k$, and n_k denotes the number of cases in the *k*-th cluster, μ_{kit} is a vector of intercepts associated with *i*-th case for cluster *k*, Φ_{kit} is the time matrix for the *k*-th cluster, ε_{kit} represents white noises.

Let *X* be longitudinal web trial data, which consists of observed data X_{obs} and missing values X_{miss} , $X = X_{obs}$, X_{miss} and ϕ denotes unknown parameters. Under three missing mechanisms, missing complete at random (MCAR), missing at random (MAR), and missing

not at random (MNAR), we simulated incomplete web trial data using the parameters learnt from QuitPrimo data (see Table 2 and Table 4):

1. MCAR: Simulate data assuming X_{miss} does not depend on observed or unobserved X_{obs} or X_{miss} ,

$$f_{JZARM}(X_{\text{miss}}|X,\phi) = f_{JZARM}(X_{\text{miss}}|\phi), \quad \forall X,\phi.$$
(16)

2. MAR: Simulate data assuming the missing values depend on the observed data X_{obs} ,

$$f_{JZARM}(X_{\text{miss}}|X,\phi) = f_{JZARM}(X_{\text{miss}}|X_{\text{obs}},\phi), \quad \forall X_{\text{miss}},\phi.$$
(17)

3. MNAR: Simulate data assuming missing observations relate to X_{miss} or unobserved attributes, i.e., MAR assumption is violated.

Under each missing mechanism, we varied the number of cases *N*, dimensions *d*, and the missing rate *r* to test our proposed algorithm. The simulation conditions are shown in Table 5. Overall, as demonstrated in Table 3, the MIVOOS always points to the correct number of clusters, while the MI-VOS shows an incorrect number of clusters, three, under all conditions. These results demonstrated the feasibility and robustness of the proposed MIVOOS in zero-inflated longitudinal web trial data with missing values.

V. CONCLUSION

Big complex data are generated from web-delivered trials. Unsupervised learning methods are helpful in disentangling heterogeneity of treatment effects for such trials. However, identifying valid patterns is a priority but challenging issue for these methods. This paper, built upon our previous research on MI-based fuzzy clustering and validation, proposes a new MI-based Visualization-aided validation index (MIVOOS) in comparison to widelyused fuzzy clustering validation indexes, XB and VOS, to determine the optimal number of clusters from big incomplete longitudinal web trial data with inflated zeros. Different from XB, this index does not rely on fuzzifiers. Similar in the concepts, MIVOOS are different in the form of computing the overlap and separation measures. Through optimizing the view angles of 3D projections using Sammon's mapping, the optimal 2D projection is obtained to better visualize and can further verify the patterns identified by the MIVOOS in conjunction with trajectory pattern visualization. Although XB identifies the same number of clusters as MIVOOS, it needs to adjust the fuzzifiers and its formula shows the possible failure for such zero-inflated data, although not happening on our included data. However, VOS cannot identify the correct number of patterns for this type of web trial data in real and simulated conditions. The findings from this project suggest that our newly-proposed MIVOOS seems to be robust in validating big web trial data under different missing data mechanisms. Our simulation model, called joint Zero-inflated Poisson Autoregressive Mixture (JZARM) model, can be further utilized to simulate big web trial data to evaluate different validation algorithms. Our future work will focus on increasing the computational efficiency of MIFuzzy clustering and validation for big data.

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Biographies



ZHAOYANG ZHANG received the B.S. degree in science and the M.S. degree in electrical engineering from Xidian University, Xi'an, China, in 2007 and 2010, respectively. He is currently pursuing the Ph.D. degree with the Department of Electrical and Computer Engineering, University of Massachusetts Dartmouth, MA, USA. His research interests include wireless healthcare, wearable computing, wireless body area networks, and cyber-physical systems.



HUA FANG is an Associate Professor with the Division of Biostatistics and Health Services Research, and a PI of Computational Statistics and Data Science Lab. Her major research area is in computational statistics and behavioral science, specialized in behavioral trajectory pattern recognition in longitudinal RCT and observational studies. She is interested in developing novel methods and applying emerging robust techniques from statistics, economics, computer science, and engineering to enable or improve the health studies that can have potential impact on the treatment or prevention of human diseases. Her current interests include statistical learning of wearable biosensor data. Her research is applied in data science, substance use, infectious diseases, immunology, nutritional epidemiology, behavioral medicine, and E-/M-health.



Nebraska-Lincoln, in 2009. He is currently an Assistant Professor with the Department of Electrical and Computer Engineering, University of Massachusetts Dartmouth, USA.

He has authored over 90 papers in his research areas. His research interests include wireless communication and networking, sensor networks, multimedia communications, social networks and wireless healthcare. He serves as a Chair/Co-Chair of several international conferences and on the Editorial Board of several journals. He is a Lead Guest Editor of the IEEE Journal of Biomedical and Health Informatics and special issue on Emerging Wireless Body Area Networks (WBANs) for Ubiquitous Healthcare in 2013.





The proposed MI-based visualization aided validation framework.

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Smoothed mean trajectory of cluster 1 in QP.

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FIGURE 3.

Comparing MI based validation on QP. (a) MI-based XB. (b) MI-based VOS. (c) MI-based OOS.



FIGURE 4.

Projections of QP with the optimal view angles. (a) 3D scatters with the optimal viewing angles. (b) 2D projections.





Projections of QP with random view angles. (a) 3D scatters with random viewing angles. (b) 2D projections.

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FIGURE 6.

Best 2D projections for 5 clusters of QP data.





Identified trajectory patterns and estimated mean and trend areas in QuitPrimo. (a) Cluster 1. (b) Cluster 2. (c) Cluster 3. (d) Cluster 4.

TABLE 1

Notations.

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Symbols	Definitions
X	Longitudinal web trial data
X_{obs}	Observations of X
X _{miss}	Missing values of X
Ν	Number of observations
М	Number of imputations
U	Fuzzy degree of cluster membership
Z_{ki}, Z_{kj}	Two fuzzy sets
d	Number of dimension
Miss	Missing mechanisms
r	Missing rate
k	Number of clusters
<i>k</i> Î	Optimal number of clusters
D _{ij}	Distance between projected data
D_{ij}^*	Distance between raw data
α	Horizontal rotation
β	Elevation of viewpoint
S	Samson's stress
μ_{kt}	a vector of intercepts of cluster k at time t
Φ_{kt}	Time variate matrix
ε _{kt}	Serially uncorrelated innovations
λ	A parameter in ZIP model
x _i	A vector of the observations of the <i>i</i> -th case
v_k	Centroid vector of k-th cluster
v_k^{\prime}	Centroid vector of projected k-th cluster
φ	Unknown parameters of JZARM Model

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TABLE 2

The μ_{kt} of QuitPrimo data.

	k	t_1	t_2	<i>t</i> ₃	t_4	t_5	t_6
	-	0.747	0.154	0.017	0.025	0.006	0.000
	0	1.091	0.465	0.139	0.080	0.139	0.043
MIM	З	0.047	0.000	0.000	0.000	0.000	0.000
	4	0.659	0.157	0.003	0.000	0.000	0.000
	-	5.708	8.601	8.736	6.902	3.997	3.638
Č	0	5.708	8.601	8.736	6.902	3.997	3.638
N	З	0.888	0.100	0.000	0.000	0.000	0.000
	4	6.345	8.686	5.857	1.213	0.007	0.000
	-	0.284	0.020	0.006	0.006	0.003	0.006
	7	0.455	0.080	0.011	0.021	0.021	0.000
3	З	0.006	0.000	0.000	0.000	0.000	0.000
	4	0.275	0.031	0.014	0.000	0.000	0.000

TABLE 3



Comparing new MIVOOS to MI-VOS validation under MCAR, MAR and MNAR.

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TABLE 4

The matrix Φ of QuitPrimo data.

	k	<i>t</i> ₂	<i>t</i> 3	<i>t</i> ₄	ts	t_6
	-	0.226	0.029	-0.007	-0.001	0.000
MM	0	0.442	0.360	0.549	0.881	0.143
MIM	З	0.000	0.000	0.000	0.000	0.000
	4	0.399	0.000	0.000	0.000	0.000
	-	-1.051	-0.561	-0.110	-0.189	0.540
č	0	-0.026	-0.471	-0.609	-0.035	-0.144
PO O	б	0.000	0.000	0.000	0.000	0.000
	4	-0.064	-0.777	0.228	0.007	0.000
	-	0.075	0.286	-0.006	-0.001	-0.006
	0	0.180	0.021	0.484	0.324	0.000
3	Э	0.000	0.000	0.000	0.000	0.000
	4	0.000	0.113	0.000	0.000	0.000

TABLE 5

Simulation conditions.

Variables	Ranges
Missing mechanism (Miss)	MCAR; MAR; MNAR
Number of cases (N)	1000; 2000
Number of dimensions (d)	20; 30; 40
Missing rate (<i>r</i>)	0.05; 0.1; 0.2; 0.4