# Attractors for Nonautonomous Nonhomogeneous Navier-Stokes Equations 

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# Attractors for nonautonomous nonhomogeneous Navier-Stokes equations 

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#### Abstract

In this paper our aim is to derive an upper bound on the dimension of the attractor of the family of processes associated to the Navier-Stokes equations with nonhomogeneous boundary conditions depending on time. We consider two-dimensional flows with prescribed quasiperiodic (in time) tangential velocity at the boundary, and obtain an upper bound which is polynomial with respect to the viscosity.


AMS classification scheme numbers: 35, 76

## 0. Introduction

In this paper, we continue the study initiated in [8] of the global attractor associated to the two-dimensional Navier-Stokes equations with prescribed tangential velocity at the boundary. The readers are referred to [11] for a comprehensive review on the subject of attractors and the first work on the attractor for boundary driven flows. In [8], we proved that the fractal and Hausdorff dimensions of the global attractor are bounded by $c R e^{3 / 2}$, where $R e$ is the Reynolds number and $c$ a nondimensional constant independent of $R e$ in the autonomous case. This is a significant improvement on previous bounds which were exponential with respect to the Reynolds number (see [11]).

Recently, Chepyzhov and Vishik [1] presented a simple approach for the investigation of nonautonomous infinite-dimensional dynamical systems that was well suited for the study of equations arising in mathematical physics (see also Haraux [5] and Smiley [9]). In this approach, to an equation of the type

$$
\begin{equation*}
\frac{\mathrm{d} u}{\mathrm{~d} t}=A_{\sigma_{0}(t)}(u) \tag{*}
\end{equation*}
$$

where $u \in E$ and $\sigma_{0}(t)$ is called the time symbol, the authors associated a two-parametric family of operators $\left\{U_{\sigma_{0}(t)}(t, \tau), t \geqslant \tau \in \mathbb{R}\right\}$ defined by $U_{\sigma_{0}(t)}(t, \tau) u_{\tau}=u(t)$, where $u$ is the solution of $(*)$ with initial data $u_{\tau}$, and called the process associated to $(*)$. To construct the attractors, they considered, together with $(*)$, a family of equations $(*)$ with the symbol $\sigma(t)$ belonging to a space $\Sigma$, called the symbol space.
§ On leave from Iowa State University.

When $E$ is a Banach space, $\Sigma$ a complete metric space, then if some invariant semigroup $\{T(s), s \geqslant 0\}$ (for instance but not necessarily the translation semigroup) acts on $\Sigma$ (i.e. $T(s) \Sigma=\Sigma, s \geqslant 0)$ and the translation identity $U_{T(s) \sigma}(t, \tau)=U_{\sigma}(t+s, \tau+s), \sigma \in \Sigma$, $t \geqslant \tau, \tau \in \mathbb{R}, s \geqslant 0$ is valid, then the problem can be reduced to an autonomous system on the extended phase space $E \times \Sigma$. The uniform (with respect to $\sigma$ ) attractor of the family of processes will then be the projection on $E$ of the global attractor of this autonomous system, if it exists. Furthermore, if the time symbol is quasiperiodic, then it is possible to obtain an upper bound on the dimension of the attractor.

In this paper, we consider two-dimensional flows with prescribed, quasiperiodic in time, tangential velocity at the boundary. In section 1 we present the equations and obtain a priori estimates. Then, in section 2 we construct the family of processes associated to these equations and prove the existence of the uniform attractor. Finally, in section 3 we obtain an upper bound on the Hausdorff dimension of the attractor. This bound is of the same order as the one obtained in the autonomous case.

## 1. Setting of the problem

Let $\Omega$ be a smooth (at least $\mathcal{C}^{3}$ ) bounded domain in $\mathbb{R}^{2}$. We consider the Navier-Stokes equations on $\Omega$ :

$$
\begin{align*}
& \frac{\partial u}{\partial t}-v \Delta u+(u \cdot \nabla) u+\nabla p=f  \tag{1}\\
& \operatorname{div} u=0  \tag{2}\\
& u=\varphi \quad \text { on } \partial \Omega \tag{3}
\end{align*}
$$

where $f=f(x, t)$ and $\varphi=\varphi(x, t)$ are quasiperiodic in $t$.
Unless otherwise stated throughout this paper, $c, c^{\prime}$ and $c^{\prime \prime}$ will denote various generic nondimensional constants (which may depend on the shape of the domain).

Moreover, we make the following assumptions on $f$ and $\varphi$ :

$$
\begin{align*}
& f(\cdot, t)=f\left(\cdot, \alpha_{1} t, \ldots, \alpha_{k} t\right)  \tag{4}\\
& \varphi(\cdot, t)=\varphi\left(\cdot, \alpha_{1} t, \ldots, \alpha_{k} t\right) \tag{5}
\end{align*}
$$

where $f\left(\cdot, \omega_{1}, \ldots, \omega_{k}\right)$ and $\varphi\left(\cdot, \omega_{1}, \ldots, \omega_{k}\right)$ are $2 \pi$-periodic in each argument $\omega_{i}$, the $\left\{\alpha_{i}\right\}$ being rationally independent;

$$
\begin{align*}
& f \in \mathcal{C}_{b}^{1}\left(\mathbb{R} ; L^{2}(\Omega)^{2}\right)  \tag{6}\\
& \varphi \in \mathcal{C}_{b}^{2}\left(\mathbb{R} ; \mathcal{C}^{3}(\partial \Omega)^{2}\right) \tag{7}
\end{align*}
$$

where $b$ means that we consider bounded functions;

$$
\begin{equation*}
\varphi \cdot n=0 \tag{8}
\end{equation*}
$$

where $n$ denotes the unit outer normal on $\partial \Omega$.
For the mathematical setting of (1)-(3) we consider the spaces

$$
\begin{aligned}
& H=\left\{u \in L^{2}(\Omega)^{2}, \operatorname{div} u=0, u \cdot n=0 \text { on } \partial \Omega\right\} \\
& V=\left\{u \in H^{1}(\Omega)^{2} \cap H, u=0 \text { on } \partial \Omega\right\}
\end{aligned}
$$

which are endowed with their usual scalar products and norms which we denote $(\cdot, \cdot)$ and $|\cdot|$ for $H$ and $((\cdot, \cdot))$ and $\|\cdot\|$ for $V$.

Based on a construction by Temam and Wang [12] which improves Hopf's original construction of divergence-free functions with a given velocity field at the boundary we have the following result.

Lemma 1. For every $\varepsilon>0$, there exists a smooth function $\phi=\phi_{\varepsilon}(x, t)$ satisfying:
(i) $\operatorname{div} \phi=0$;
(ii) $\phi=\varphi$ on $\partial \Omega$;
(iii) $\left|\int_{\Omega}(u \cdot \nabla) \phi \cdot u \mathrm{~d} x\right| \leqslant c \varepsilon|\nabla \varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}|\Omega|^{1 / 2}\|u\|^{2}, \forall u \in V$;
(iv) $\|\phi\| \leqslant \frac{c^{\prime}}{\varepsilon^{1 / 2}}|\nabla \varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}$;
(v) $\left|\frac{\partial \phi}{\partial t}\right| \leqslant c^{\prime \prime}|\Omega|^{1 / 2} \varepsilon^{1 / 2} \max \left(\left|\frac{\partial \varphi}{\partial t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)},\left|\nabla \frac{\partial \varphi}{\partial t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)} \operatorname{diam} \Omega\right)$
where $c, c^{\prime}$ and $c^{\prime \prime}$ are nondimensional constants, independent of $\varepsilon$ and $\operatorname{diam} \Omega$ denotes the diameter of $\Omega$.

Proof. The proof here is similar to the one performed in [8], lemma 2.1. Since $\Omega$ is bounded and regular there exists $\delta_{0}>0$ such that all normals from $\partial \Omega$ do not intersect in a neighbourhood of width $2 \delta_{0}$ (which we denote $\mathcal{O}_{2 \delta_{0}}(\partial \Omega)$ ) (see for instance [6, page 354]). Moreover, for every $(x, y) \in \mathcal{O}_{2 \delta_{0}}(\partial \Omega)$, there exists a unique point $b(x, y) \in \partial \Omega$ such that

$$
\operatorname{dist}((x, y), \partial \Omega)=\operatorname{dist}((x, y), b(x, y))
$$

Let $T_{b(x, y)}$ denote the clockwise tangent vector to $\partial \Omega$ at the point $b(x, y)$. We consider a function $\rho \in \mathcal{C}^{\infty}([0,+\infty))$ such that

$$
\begin{align*}
& \text { supp } \rho \subset[0,1]  \tag{9}\\
& \rho(0)=1  \tag{10}\\
& |\rho(s)| \leqslant 1 \quad \forall s \in[0,1]  \tag{11}\\
& \int_{0}^{1} \rho(s) \mathrm{d} s=0 \tag{12}
\end{align*}
$$

and we set
$\psi=\psi_{\varepsilon}=\varphi(b(x, y), t) \cdot T_{b(x, y)} \int_{0}^{\operatorname{dist}((x, y), b(x, y))} \rho\left(\frac{s}{|\Omega|^{1 / 2} \varepsilon}\right) \mathrm{d} s$ if $(x, y) \in \mathcal{O}_{2 \delta_{0}}(\partial \Omega)$
$\psi=\psi_{\varepsilon}=0 \quad$ elsewhere.
We finally set

$$
\phi=\phi_{\varepsilon}(x, y, t)=\operatorname{curl}(\psi)=\binom{-\frac{\partial \psi}{\partial y}}{\frac{\partial \psi}{\partial x}} .
$$

We then prove, exactly as in [8], that (i)-(iv) are true. To obtain (v), we note that if $\phi=\left(\phi_{1}, \phi_{2}\right)$, then

$$
\begin{aligned}
& \frac{\partial \phi_{1}}{\partial t}=- \frac{\partial}{\partial y}( \\
&\left.\frac{\partial \varphi}{\partial t}(b(x, y), t) \cdot T_{b(x, y)}\right) \int_{0}^{\operatorname{dist}((x, y), \partial \Omega)} \rho\left(\frac{s}{|\Omega|^{1 / 2} \varepsilon}\right) \mathrm{d} s \\
&-\frac{\partial \varphi}{\partial t}(b(x, y), t) \cdot T_{b(x, y)} \rho\left(\frac{\operatorname{dist}((x, y), \partial \Omega)}{|\Omega|^{1 / 2} \varepsilon}\right) \frac{\partial}{\partial y} \operatorname{dist}((x, y), \partial \Omega) \\
& \frac{\partial \phi_{2}}{\partial t}= \frac{\partial}{\partial x}\left(\frac{\partial \varphi}{\partial t}(b(x, y), t) \cdot T_{b(x, y)}\right) \int_{0}^{\operatorname{dist}((x, y), \partial \Omega)} \rho\left(\frac{s}{|\Omega|^{1 / 2} \varepsilon}\right) \mathrm{d} s \\
&+\frac{\partial \varphi}{\partial t}(b(x, y), t) \cdot T_{b(x, y)} \rho\left(\frac{\operatorname{dist}((x, y), \partial \Omega)}{|\Omega|^{1 / 2} \varepsilon}\right) \frac{\partial}{\partial x} \operatorname{dist}((x, y), \partial \Omega)
\end{aligned}
$$

and if $(x, y) \notin \mathcal{O}_{|\Omega|^{1 / 2} \varepsilon}(\partial \Omega)$ (i.e. $\left.\operatorname{dist}((x, y), \partial \Omega)>|\Omega|^{1 / 2} \varepsilon\right)$ then

$$
\begin{aligned}
& \rho\left(\frac{\operatorname{dist}((x, y), \partial \Omega)}{|\Omega|^{1 / 2} \varepsilon}\right)=0 \\
& \int_{0}^{\operatorname{dist}((x, y), \partial \Omega)} \rho\left(\frac{s}{|\Omega|^{1 / 2} \varepsilon}\right) \mathrm{d} s=0
\end{aligned}
$$

We then proceed as in [8] lemma 2.1 to verify that (i)-(v) are satisfied. This is straightforward. We omit the details.

We now set $u=v+\phi$, and we obtain the following equation for $v$ :
$\frac{\partial v}{\partial t}-v \Delta v+(v \cdot \nabla) v+(\phi \cdot \nabla) v+(v \cdot \nabla) \phi+\nabla p=f+v \Delta \phi-(\phi \cdot \nabla) \phi-\frac{\partial \phi}{\partial t}$
$\operatorname{div} v=0$
$v=0 \quad$ on $\partial \Omega$
which can be written in functional form (see for instance [11])

$$
\begin{equation*}
\frac{\mathrm{d} v}{\mathrm{~d} t}+v A v+B(v, v)+R v=\bar{f} \tag{16}
\end{equation*}
$$

where $\bar{f}=P f-v A \phi-B(\phi, \phi)-P \frac{\partial \phi}{\partial t}, P$ is the orthogonal projector from $L^{2}$ into $H$, $A=-P \Delta, B(u, v)=P((u \cdot \nabla) v)$ and $R v=B(v, \phi)+B(\phi, v)$.

As in [8], we prove that for every $\tau \in \mathbb{R}$ and for every $v_{\tau} \in H$, there exists a unique solution $v$ of (16) with initial data $v_{\tau}$ (i.e. $v(\tau)=v_{\tau}$ ) such that:

$$
v \in L^{2}(\tau,+\infty ; V) \cap L^{\infty}(\tau,+\infty ; H) \cap C(\tau,+\infty ; H)
$$

We take the scalar product in $L^{2}$ of (13) by $v$ and obtain, by integration by parts and recalling that $(B(u, v), v)=0$ :
$\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}|v|^{2}+v\|v\|^{2}+\int_{\Omega}(v \cdot \nabla) \phi \cdot v \mathrm{~d} x=(f, v)-v((\phi, v))-\int_{\Omega}(\phi \cdot \nabla) \phi \cdot v \mathrm{~d} x-\left(\phi_{t}, v\right)$.

Therefore, taking $\varepsilon=\frac{\nu}{2 c|\Omega|^{\frac{1}{2}}|\varphi|_{L^{\infty}}}$, where $c$ is the constant in lemma 1, (iii),

$$
\begin{gathered}
\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}|v|^{2}+\frac{v}{2}\|v\|^{2} \leqslant \frac{v}{16}\|v\|^{2}+c v\|\phi\|^{2}+\frac{v}{16}\|v\|^{2}+\frac{c}{v \lambda_{1}}|f|^{2}+\frac{v}{8}\|v\|^{2} \\
+\frac{c}{v \lambda_{1}}\left|\phi_{t}\right|^{2}+\left|\int_{\Omega}(\phi \cdot \nabla) \phi \cdot v \mathrm{~d} x\right|
\end{gathered}
$$

where $\lambda_{1}>0$ is the first eigenvalue of the Stokes operator $A$ on $\Omega$ with zero Dirichlet boundary condition (see for instance [11]).

As in [8] we have

$$
\left|\int_{\Omega}(\phi \cdot \nabla) \phi \cdot v \mathrm{~d} x\right| \leqslant c|\phi|_{L^{\infty}}|\phi|\|v\|
$$

and thus

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}|v|^{2}+\frac{v}{2}\|v\|^{2} \leqslant \frac{c}{v \lambda_{1}}|f|^{2}+\frac{c^{\prime}}{v \lambda_{1}}\left|\phi_{t}\right|^{2}+\frac{c^{\prime \prime}}{v}|\phi|^{2}|\phi|_{L^{\infty}}^{2}+c^{\prime \prime \prime} v\|\phi\|^{2} . \tag{18}
\end{equation*}
$$

Integrating (18) between $\tau$ and $T$, we obtain

$$
\begin{align*}
&|v(T)|^{2}+\frac{v}{2} \int_{\tau}^{T}\|v\|^{2} \mathrm{~d} t \leqslant|v(\tau)|^{2}+\frac{c}{v \lambda_{1}} \int_{\tau}^{T}|f|^{2} \mathrm{~d} t+\frac{c}{v \lambda_{1}} \int_{\tau}^{T}\left|\phi_{t}\right|^{2} \mathrm{~d} t \\
&+\frac{c^{\prime \prime}}{v} \int_{\tau}^{T}|\phi|_{L^{\infty}}^{2}|\phi|^{2} \mathrm{~d} t+c^{\prime \prime \prime} v \int_{\tau}^{T}\|\phi\|^{2} \mathrm{~d} t \tag{19}
\end{align*}
$$

Moreover, using the Gronwall lemma and Poincaré inequality, we find

$$
\begin{align*}
&|v(t)|^{2} \leqslant|v(\tau)|^{2} \mathrm{e}^{-\frac{v \lambda_{1}}{2}(t-\tau)}+\frac{c}{v^{2} \lambda_{1}^{2}}|f|_{L^{\infty}(\mathbb{R}, H)}^{2}+\frac{c^{\prime}}{v^{2} \lambda_{1}^{2}}\left|\phi_{t}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2} \\
&+\frac{c^{\prime \prime}}{v^{2} \lambda_{1}}|\phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2} \times|\phi|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}+\frac{c^{\prime \prime \prime}}{\lambda_{1}}|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2} \tag{20}
\end{align*}
$$

Finally, taking the scalar product of (16) with $(t-\tau) A v$, we find

$$
\begin{equation*}
(t-\tau)\|v\|^{2} \leqslant c_{1}(\phi, f, T, \tau, v)|v(\tau)|^{2}+(t-\tau) c_{2}(\phi, f, T, \tau, v) \tag{21}
\end{equation*}
$$

## 2. Existence of the global attractor

### 2.1. Preliminary results

In this section we consider the framework of Chepyzhov and Vishik [1]. We recall here the results that will be used in the sequel.

We consider a Banach space $E$ and a two-parametric family of mappings acting on $E$ :

$$
U(t, \tau): E \rightarrow E
$$

$t \geqslant \tau, \tau \in \mathbb{R}$. The mapping $U$ is called a process if:
(i) $U(\tau, \tau)=I$ (identity operator);
(ii) $U(t, s) \circ U(s, \tau)=U(t, \tau), \forall t \geqslant s \geqslant \tau, \tau \in \mathbb{R}$.

We denote by $\mathcal{B}(E)$ the set of all bounded sets in $E$. The process is bounded if for any set $B \in \mathcal{B}(E)$, the set $\cup_{\tau \in \mathbb{R}} \cup_{t \geqslant \tau} U(t, \tau) B \in \mathcal{B}(E)$. A set $B_{0} \in \mathcal{B}(E)$ is absorbing if for any set $B \in \mathcal{B}(E)$, there exists $T=T(\tau, B)$ such that $U(t, \tau) B \subset B_{0}$ for $t \geqslant T$. Finally, a set $\mathcal{A}$ is attracting for the process if for any $\tau \in \mathbb{R}$ and any $B \in \mathcal{B}(E), \operatorname{dist}(U(t, \tau) B, \mathcal{A}) \rightarrow 0$ as $t \rightarrow+\infty$.

We now consider a family of processes $\left\{U_{\sigma}(t, \tau)\right\}$ depending on a functional parameter $\sigma \in \Sigma$. The parameter $\sigma$ is called the symbol of the process, and $\Sigma$ is called the symbol space, which is here assumed to be a complete metric space. The family of processes is said to be uniformly (with respect to $\sigma \in \Sigma$ ) bounded if for any $B \in \mathcal{B}(E)$, the set $\cup_{\sigma \in \Sigma} \cup_{\tau \in \mathbb{R}} \cup_{t \geqslant \tau} U_{\sigma}(t, \tau) B \in \mathcal{B}(E)$. A set $B_{0} \in E$ is said to be uniformly absorbing for the family of processes if for any $\tau \in \mathbb{R}$ and any $B \in \mathcal{B}(E)$, there exists $T=T(\tau, B)$ such that $\cup_{\sigma \in \Sigma} U_{\sigma}(t, \tau) B \subset B_{0}, \forall t \geqslant T$. Finally, a set $\mathcal{A}$ is said to be uniformly attracting for the family of processes if

$$
\lim _{t \rightarrow+\infty} \sup _{\sigma \in \Sigma} \operatorname{dist}\left(U_{\sigma}(t, \tau) B, \mathcal{A}\right)=0 \quad \forall \tau \in \mathbb{R}, \forall B \in \mathcal{B}(E)
$$

A family of processes possessing a compact uniformly absorbing set is said to be uniformly compact and one possessing a compact uniformly attracting set, uniformly asymptotically compact.

A closed set $\mathcal{A}_{\Sigma} \subset E$ is said to be the uniform (with respect to $\sigma \in \Sigma$ ) attractor of the family of processes if it is uniformly attracting and it is contained in any closed uniformly attracting set $\mathcal{A}^{\prime}$ of the family of processes (minimality). We have the following result which is proved in [1].
Proposition 1. If a family of processes is uniformly asymptotically compact then it possesses a uniform attractor $\mathcal{A}_{\Sigma}$.

We now assume that an invariant semigroup $\{T(t)\}_{t \geqslant 0}$ acts on $\Sigma: T(t) \Sigma=\Sigma, \forall t \geqslant 0$, and that:
(iii) $U_{\sigma}(t+s, \tau+s)=U_{T(s) \sigma}(t, \tau), \forall \sigma \in \Sigma, \forall t \geqslant \tau, \tau \in \mathbb{R}, s \geqslant 0$.

We then set

$$
\begin{aligned}
& S(t): E \times \Sigma \rightarrow E \times \Sigma \\
& (u, \sigma) \mapsto=\left(U_{\sigma}(t, 0) u, T(t) \sigma\right) \quad t \geqslant 0 .
\end{aligned}
$$

The family of mappings $\{S(t)\}$ acting on $E \times \Sigma$ forms a semigroup on $E \times \Sigma$ (see [1]).

## Definitions.

(a) A family of processes is said to be $(E \times \Sigma, E)$-continuous if for fixed $t$ and $\tau$, $t \geqslant \tau, \tau \in \mathbb{R}$, the mapping $(u, \sigma) \rightarrow U_{\sigma}(t, \tau) u$ is continuous from $E \times \Sigma$ into $E$.
(b) A curve $u(s), s \in \mathbb{R}$ is a complete trajectory of the process $\{U(t, \tau)\}$ if

$$
U(t, \tau) u(\tau)=u(t) \quad \forall t \geqslant \tau \quad \tau \in \mathbb{R}
$$

(c) The kernel $K$ of the process $\{U(t, \tau)\}$ consists of all bounded trajectories of the process. The set $K(s)=\{u(s), u \in K\}$ is called the kernel section at time $t=s$.

We end this section with the following result, which is proved in [1].
Proposition 2. We consider a family of processes $\left\{U_{\sigma}(t, \tau)\right\}, \sigma \in \Sigma$, where $\Sigma$ is a compact metric space. Let $\{T(t)\}$ be a continuous-invariant semigroup on $\Sigma$ satisfying (iii). We assume that the family of processes is uniformly asymptotically compact and ( $E \times \Sigma, E$ )continuous. Then the semigroup $\{S(t)\}$ associated with the family of processes possesses a compact, invariant attractor $\mathcal{A}$. Furthermore:
(a) $\mathcal{A}_{\Sigma}=\Pi_{1} \mathcal{A}$ is the uniform attractor of the family of processes;
(b) $\Pi_{2} \mathcal{A}=\Sigma$;
(c) $\mathcal{A}=\cup_{\sigma \in \Sigma} K_{\sigma}(0) \times\{\sigma\}$;
(d) $\mathcal{A}_{\Sigma}=\cup_{\sigma \in \Sigma} K_{\sigma}(0)$,
where $\Pi_{1}$ and $\Pi_{2}$ denote the projectors from $E \times \Sigma$ into $E$ and $\Sigma$ respectively.

### 2.2. Construction of the global attractor

We write (16) in the form

$$
\begin{equation*}
\frac{\mathrm{d} v}{\mathrm{~d} t}=\mathcal{G}_{\sigma_{0}(t)}(v) \tag{22}
\end{equation*}
$$

where $\sigma_{0}(t)=\left(f(t), \phi(t), \phi_{t}(t)\right)$. Using the a priori estimates derived in section 1 , we easily prove that (22) possesses a unique solution with initial data $v_{\tau} \in H$ satisfying

$$
v \in L^{\infty}(\tau,+\infty ; H) \cap L^{2}(\tau, T ; V) \cap C(\tau,+\infty ; H) \quad \forall T \geqslant \tau
$$

We now consider the family of problems

$$
\begin{align*}
& \frac{\mathrm{d} v}{\mathrm{~d} t}=\mathcal{G}_{\sigma(t)}(v)  \tag{23}\\
& v(\tau)=v_{\tau} \tag{24}
\end{align*}
$$

$\sigma(t) \in \Sigma$, where $\Sigma=\mathcal{H}\left(\sigma_{0}\right)$ is the hull of $\sigma_{0}$. We have here

$$
\mathcal{H}=\left\{\sigma_{0}\left(\alpha_{1} t+\omega_{01}, \ldots, \alpha_{k} t+\omega_{0 k}\right),\left(\omega_{01}, \ldots, \omega_{0 k}\right)=\omega_{0} \in \mathbb{T}^{k}\right\}
$$

where $\mathbb{T}^{k}$ denotes the $k$-dimensional torus. Therefore it is convenient to consider $\mathbb{T}^{k}$ as the symbol space of our problem. We also introduce the translation group $\{T(h), h \in \mathbb{R}\}$ which acts on $\mathbb{T}^{k}$ by the formula

$$
T(h) \omega=(\alpha h+\omega) \quad\left(\bmod \mathbb{T}^{k}\right) \quad \omega \in \mathbb{T}^{k}
$$

Now, it is easy to check that for every $\sigma \in \mathcal{H}\left(\sigma_{0}\right)$, (23)-(24) possess a unique solution $v(t)$. Moreover, estimates (19)-(21) hold with the same constants, since, for instance,
$\left|f\left(\alpha_{1} t+\omega_{01}, \ldots, \alpha_{k} t+\omega_{0 k}\right)\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}=|f(t)|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}$. Therefore, we can consider the family of processes $\left\{U_{\sigma}(t, \tau)\right\}, \sigma \in \Sigma$ defined by

$$
\begin{equation*}
v(t)=U_{\sigma}(t, \tau) v_{\tau} \tag{25}
\end{equation*}
$$

where $v$ is the solution of (23), (24). We have the following result.
Proposition 3. The family of processes defined by (15) is uniformly bounded, uniformly compact and $\left(H \times \mathcal{H}\left(\sigma_{0}\right), H\right)$-continuous.

Proof. To prove that the family of processes is uniformly bounded in $H$, we use (20). This inequality also enables us to prove the existence of a uniformly absorbing set $B_{0}$ in $H$.

Now the set $\cup_{\sigma \in \Sigma} \cup_{\tau \in \mathbb{R}} U_{\sigma}(\tau+1, \tau) B_{0}$ is also uniformly absorbing in $H$. Using (21), we prove that this set is also bounded in $H^{1}$ and hence precompact in $H$. Therefore, the family of processes is uniformly compact.

It remains to check that the family of processes is $\left(H \times \mathcal{H}\left(\sigma_{0}\right), H\right)$-continuous. We consider two symbols $\sigma_{1}$ and $\sigma_{2}$ and their corresponding solutions $v_{1}$ and $v_{2}$. Setting $v=v_{1}-v_{2}, f=f_{1}-f_{2}$ and $\phi=\phi_{1}-\phi_{2}$, we obtain the following equation for $v$ :

$$
\begin{align*}
\frac{\mathrm{d} v}{\mathrm{~d} t}+v A v+ & B\left(v, v_{1}\right)+B\left(v_{2}, v\right)+B\left(\phi_{1}, v\right)+B\left(\phi, v_{2}\right)+B\left(v, \phi_{1}\right)+B\left(v_{2}, \phi\right) \\
& =f-v A \phi-B\left(\phi, \phi_{1}\right)-B\left(\phi_{2}, \phi\right)-P \frac{\partial \phi}{\partial t}  \tag{26}\\
\left.v\right|_{t=\tau}=v_{1 \tau} & -v_{2 \tau} \tag{27}
\end{align*}
$$

Taking the scalar product of (26) with $v$ we obtain

$$
\begin{aligned}
\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}|v|^{2}+v\|v\|^{2} & =(f, v)-\left(B\left(v, v_{1}\right), v\right)-\left(B\left(\phi, v_{2}\right), v\right)-\left(B\left(v, \phi_{1}\right), v\right) \\
- & \left(B\left(\phi, \phi_{1}\right), v\right)-\left(B\left(\phi_{2}, \phi\right), v\right)-\left(B\left(v_{2}, \phi\right), v\right)-v((\phi, v))-\left(\phi_{t}, v\right) .
\end{aligned}
$$

Therefore
$\frac{\mathrm{d}}{\mathrm{d} t}|v|^{2}+v\|v\|^{2} \leqslant c|f|^{2}+c^{\prime}\|\phi\|^{2}+c^{\prime \prime}\left|\phi_{t}\right|^{2}+\left\|v_{1}\right\||v|_{L^{4}}^{2}+\left\|\phi_{1}\right\||v|_{L^{4}}^{2}+|\phi|_{L^{4}}\left\|v_{2}\right\||v|_{L^{4}}$

$$
+|\phi|_{L^{4}}\left\|\phi_{1}\right\||v|_{L^{4}}+\left|\phi_{2}\right|_{L^{4}}\|\phi\||v|_{L^{4}}+\left|v_{2}\right|_{L^{4}}\|\phi\||v|_{L^{4}}
$$

We then deduce, using Ladyzhenskaya's inequality $\left(|v|_{L^{4}}^{2} \leqslant c|v|\|v\|\right)$

$$
\begin{gathered}
\frac{\mathrm{d}}{\mathrm{~d} t}|v|^{2} \leqslant c|f|^{2}+c^{\prime}\left(1+\left\|\phi_{1}\right\|^{2}+\left\|\phi_{2}\right\|^{2}+\left\|v_{2}\right\|^{2}\right)\|\phi\|^{2}+c^{\prime \prime}\left|\phi_{t}\right|^{2} \\
+c^{\prime \prime \prime}\left(\left\|v_{1}\right\|^{2}+\left\|\phi_{1}\right\|^{2}+\left\|v_{2}\right\|^{2}\right)|v|^{2}
\end{gathered}
$$

which yields:

$$
\begin{gathered}
|v(t)|^{2} \leqslant c\left(|v(\tau)|^{2}+\int_{\tau}^{t}\left(c^{\prime}|f|^{2}+c^{\prime \prime}\left(1+\left\|\phi_{1}\right\|^{2}+\left\|\phi_{2}\right\|^{2}+\left\|v_{2}\right\|^{2}\right)\|\phi\|^{2}+c^{\prime \prime \prime}\left\|\phi_{t}\right\|^{2}\right) \mathrm{d} \theta\right) \\
\quad \times \exp \left(c_{0} \int_{\tau}^{t}\left(\left\|v_{1}\right\|^{2}+\left\|\phi_{1}\right\|^{2}+\left\|v_{2}\right\|^{2}\right) \mathrm{d} \theta\right)
\end{gathered}
$$

and using (21) (the bound on $\|v\|$ ), we finally find
$|v(t)|^{2} \leqslant c\left(\left|v_{1 \tau}-v_{2 \tau}\right|^{2}+c^{\prime}(t-\tau) \max \left(|f|_{\mathcal{C}(\mathbb{R} ; H)},\left|\phi_{t}\right|_{\mathcal{C}\left(\mathbb{R} ; L^{2}\right)},|\phi|_{\mathcal{C}\left(\mathbb{R} ; H^{1}\right)}\right)^{2} \mathrm{e}^{c^{\prime \prime}(t-\tau)}\right)$
hence the result.

Now let $\{S(t)\}$ be the semigroup associated with the family of processes defined above. The family of processes satisfies all the conditions of proposition 2. Therefore the following theorem follows.

Theorem 1. The semigroup $\{S(t)\}$ possesses a global attractor $\mathcal{A}$. Moreover $\mathcal{A}_{\Sigma}=\Pi_{1} \mathcal{A}$ is the uniform attractor for the family of processes defined by (25) and $\mathcal{A}_{\Sigma}=\cup_{\sigma \in \Sigma} K_{\sigma}(0)$, where $K(0)$ is the kernel of the process $\left\{U_{\sigma}(t, \tau)\right\}$.

Remark 1. We can also consider almost periodic and asymptotically almost periodic symbols (see [1]). In these two cases, we also obtain a result similar to theorem 1. However, we would not be able to obtain estimates on the dimension of the attractor in these two cases.

## 3. Upper bound on the dimension of the attractor

### 3.1. Preliminary results

We give here a general result for the estimation of the dimension of the attractor associated to a nonautonomous system with quasiperiodic symbol. We saw that in that case the symbol space can be identified with the $k$-dimensional torus $\mathbb{T}^{k}$. We consider the following system:
$\frac{\mathrm{d} u}{\mathrm{~d} t}=\mathcal{G}(u, \omega(t)) \quad \omega(t)=\left[\alpha t+\omega_{0}\right] \quad \omega_{0} \in \mathbb{T}^{k} \quad \alpha=\left(\alpha_{1}, \ldots, \alpha_{k}\right) \in \mathbb{R}^{k}$
$\left.u\right|_{t=\tau}=u_{\tau} \quad u_{\tau} \in H \quad t \geqslant \tau \quad \tau \in \mathbb{R}$
where $\mathcal{G}(u, \omega)$ is a family of nonlinear operators depending on $\omega \in \mathbb{T}^{k}$ with domain $H_{1}$ and with values in $H_{0}, H_{1} \hookrightarrow H \hookrightarrow H_{0}$ being Hilbert spaces.

We assume that (28), (29) is well posed. It thus generates a family of processes $\left\{U_{\omega_{0}}(t, \tau)\right\}, \omega_{0} \in \mathbb{T}^{k}$. We also consider the semigroup

$$
\begin{aligned}
& S(t): H \times \mathbb{T}^{k} \rightarrow H \times \mathbb{T}^{k} \\
& \left(u_{0}, \omega_{0}\right) \mapsto\left(U_{\omega_{0}}(t, 0) u_{0}, \alpha t+\omega_{0}\right)
\end{aligned}
$$

where $t \geqslant 0$. This semigroup can be constructed by considering the following autonomous system

$$
\begin{align*}
& \frac{\mathrm{d} u}{\mathrm{~d} t}=\mathcal{G}(u, \omega)  \tag{30}\\
& \frac{\mathrm{d} \omega}{\mathrm{~d} t}=\alpha  \tag{31}\\
& \left.u\right|_{t=0}=u_{0}  \tag{32}\\
& \left.\omega\right|_{t=0}=\omega_{0} \tag{33}
\end{align*}
$$

where $u_{0} \in H, \omega_{0} \in \mathbb{T}^{k}$, which can be rewritten in the form

$$
\begin{align*}
& \frac{\mathrm{d} y}{\mathrm{~d} t}=M(y)  \tag{34}\\
& \left.y\right|_{t=0}=y_{0} \tag{35}
\end{align*}
$$

where $y=(u, \omega)$ and $M(y)=(\mathcal{G}(u, \omega), \alpha)$. We assume that the family of processes is uniformly asymptotically compact and $\left(H \times \mathbb{T}^{k}, H\right)$-continuous. Therefore the semigroup $\{S(t)\}$ possesses a compact attractor $\mathcal{A}$ in $H \times \mathbb{T}^{k}$. Moreover, $\mathcal{A}_{\mathbb{T}^{k}}=\Pi_{1} \mathcal{A}$ is the uniform attractor of the family of processes. Since

$$
\operatorname{dim} \mathcal{A}_{\mathbb{T}^{k}} \leqslant \operatorname{dim} \mathcal{A}
$$

where $\operatorname{dim}$ denotes the Hausdorff dimension, it suffices to find an upper bound for $\operatorname{dim} \mathcal{A}$ in order to obtain an upper bound on the dimension of $\mathcal{A}_{\mathbb{T}^{k}}$. We finally make the following assumptions ((i)-(iii)).
(i) The semigroup is uniformly quasidifferentiable in $H \times \mathbb{T}^{k}$ on $\mathcal{A}$ (see [11]).
(ii) The quasidifferential $S^{\prime}\left(t, y_{0}\right) z_{0}=z(t), t \geqslant 0$, satisfies the first variation equation of (34) and (35):

$$
\begin{align*}
& \frac{\mathrm{d} z}{\mathrm{~d} t}=M^{\prime}(y(t)) z  \tag{36}\\
& \left.z\right|_{t=0}=z_{0} \tag{37}
\end{align*}
$$

where $z=(v, \mu)$, which can be written in the form

$$
\begin{align*}
& \frac{\mathrm{d} v}{\mathrm{~d} t}=\mathcal{G}_{u}^{\prime}(u(t), \omega(t)) v+\mathcal{G}_{\omega}^{\prime}(u(t), \omega(t)) \mu  \tag{38}\\
& \frac{\mathrm{d} \mu}{\mathrm{~d} t}=0  \tag{39}\\
& \left.v\right|_{t=0}=v_{0}  \tag{40}\\
& \left.\mu\right|_{t=0}=\mu_{0} \tag{41}
\end{align*}
$$

where $u(t)=U_{\omega_{0}}(t, \tau) u_{0}, \omega(t)=\left[\alpha t+\omega_{0}\right]$.
(iii) We have

$$
\begin{align*}
\left(M^{\prime}(y(t)) z, z\right) & =\left(\mathcal{G}_{u}^{\prime}(u(t), \omega(t)) v, v\right)+\left(\mathcal{G}_{\omega}^{\prime}(u(t), \omega(t)) \mu, \mu\right) \\
& \leqslant\left(L_{1}\left(t, y_{0}\right) v, v\right)+\left(L_{2}\left(t, y_{0}\right) \mu, \mu\right) \equiv\left(M_{1}\left(t, y_{0}\right) z, z\right) \tag{42}
\end{align*}
$$

for every $y_{0} \in \mathcal{A}, t \geqslant 0$ and $z=(v, \mu) \in H_{1} \times \mathbb{R}^{k}$, where $L_{1}$ is (for fixed $\left(t, y_{0}\right) \in \mathbb{R} \times \mathcal{A}$ ) a selfadjoint operator in $H, L_{1}: H_{2} \rightarrow H, H_{2} \subset \subset H$, with a discrete spectrum
$\lambda_{1}\left(t, y_{0}\right) \geqslant \lambda_{2}\left(t, y_{0}\right) \geqslant \cdots \geqslant \lambda_{i}\left(t, y_{0}\right) \geqslant \ldots \quad \lambda_{i} \rightarrow-\infty \quad$ as $i \rightarrow \infty$
and with orthonormal (in $H$ ) eigenfunctions $w_{i}\left(t, y_{0}\right)$, and $L_{2}: \mathbb{R}^{k} \rightarrow \mathbb{R}^{k}$ is selfadjoint, with eigenvalues $\eta_{i}=\eta_{i}\left(t, y_{0}\right)$ and corresponding orthonormal in $\mathbb{R}^{k}$ eigenfunctions $p_{i}\left(t, y_{0}\right)$, $i=1, \ldots, k$. Moreover, we assume that $L_{1}$ and $L_{2}$ are uniformly (with respect to $\left.\left(t, y_{0}\right) \in \mathbb{R}^{+} \times \mathcal{A}\right)$ semibounded from above.

We have $M_{1}=\left(\begin{array}{cc}L_{1} & 0 \\ 0 & L_{2}\end{array}\right), M_{1} z=L_{1} v+L_{2} \mu$, and the eigenvectors of $M_{1}$ are $\varphi_{j}^{(1)}=\left(w_{j}, 0\right), M_{1} \varphi_{j}^{(1)}=\lambda_{j} \varphi_{j}^{(1)}, j \in \mathbb{N}$, and $\rho_{i}^{(2)}=\left(0, \zeta_{i}\right), M_{1} \rho_{i}^{(2)}=\eta_{i} \rho_{i}^{(2)}, i=1, \ldots, k$.

We have the following result which is proved in [1].
Proposition 4. We assume that (i)-(iii) are satisfied. Then if

$$
q_{d}=\liminf _{t \rightarrow+\infty} \sup _{y_{0} \in \mathcal{A}}\left(\frac{1}{t} \int_{0}^{t} \sum_{j=1}^{d}\left(M_{1} \zeta_{j}, \zeta_{j}\right) \mathrm{d} \tau\right)<0
$$

where $\zeta_{j}$ are the eigenfunctions corresponding to the d greatest eigenvalues of $M_{1}$, we have

$$
\operatorname{dim} \mathcal{A} \leqslant d
$$

where dim denotes the Hausdorff dimension.

### 3.2. Application to the nonautonomous nonhomogeneous Navier-Stokes equations

We write (23), (24) as an autonomous system (i.e. in the form (34),(35)):

$$
\begin{align*}
& \frac{\mathrm{d} y}{\mathrm{~d} t}=M(y)  \tag{43}\\
& \left.y\right|_{t=0}=y_{0} \tag{44}
\end{align*}
$$

where $y=(v, \omega)$ and $M(y)=(-v A v-B(v, v)-B(v, \phi)-B(\phi, v)+f-v A \phi-B(\phi, \phi)-$ $\left.\frac{\partial \phi}{\partial t}, \alpha\right)$.

The proof of (i) and (ii) is classical (see for instance [11]). It remains to check that (iii) is satisfied. In order to do so, we need to estimate $\left(M^{\prime}(y) z, z\right)$, where

$$
z=\left(w, \frac{1}{U L} \mu\right)
$$

and

$$
\begin{aligned}
M^{\prime}(y) z=(-v & A w-B(v, w)-B(w, v)+f_{\omega}^{\prime}(x, \omega(t)) \frac{1}{U L} \mu-B(w, \phi) \\
& -B\left(v, \phi_{\omega}^{\prime}(x, \omega(t)) \frac{1}{U L} \mu\right)-B(\phi, w)-B\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, v\right) \\
& -v A\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}\right)-B\left(\phi, \phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}\right) \\
& -B\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, \phi\right)-\frac{\partial}{\partial t}\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, 0\right) .
\end{aligned}
$$

Here $U$ is a velocity and $L$ a length that will be fixed later and are considered for dimensional reasons. Therefore

$$
\begin{aligned}
\left(M^{\prime}(y) z, z\right)= & -v\|w\|^{2}-(B(w, v), w)+\left(f_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, v\right)-(B(w, \phi), w) \\
& -\left(B\left(v, \phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}\right), w\right)-\left(B\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, v\right), w\right) \\
& -v\left(\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, w\right)\right)-\left(B\left(\phi, \phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}\right), w\right) \\
& -\left(B\left(\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, \phi\right), w\right)-\left(\frac{\partial}{\partial t} \phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}, w\right) .
\end{aligned}
$$

We then obtain, since $|(B(w, \phi), w)| \leqslant \frac{v}{2}\|w\|^{2}$ (by lemma 1 (iii) and our choice of $\varepsilon$ at the end of section 1)

$$
\begin{aligned}
\left(M^{\prime}(y) z, z\right) \leqslant & -\frac{v}{2}\|w\|^{2}+\int_{\Omega}|\nabla v||w|^{2} \mathrm{~d} x+\int_{\Omega}\left|f_{\omega}^{\prime} \frac{\mu}{L U}\right||v| \mathrm{d} x \\
& +\int_{\Omega}\left|\frac{\partial}{\partial t} \phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}\right||w| \mathrm{d} x+v\left\|\phi_{\omega}^{\prime}(x, \omega(t)) \frac{\mu}{U L}\right\|\|w\| \\
& +\int_{\Omega}|\nabla \phi||w|^{2} \mathrm{~d} x+|\phi|_{L^{\infty}}\left\|\phi_{\omega}^{\prime} \frac{\mu}{U L}\right\||w|+\left|\phi_{\omega}^{\prime} \frac{\mu}{U L}\right|_{L^{\infty}}\|\phi\||w| \\
& +\left|\left(B\left(\phi_{\omega}^{\prime} \frac{\mu}{U L}, v\right), w\right)\right|+\left|\left(B\left(v, \phi_{\omega}^{\prime} \frac{\mu}{U L}\right), w\right)\right|
\end{aligned}
$$

We have

$$
\left|\left(B\left(v, \phi_{\omega}^{\prime} \frac{\mu}{U L}\right), w\right)\right| \leqslant\left|\nabla \phi_{\omega}^{\prime} \frac{\mu}{L U}\right|_{L^{\infty}}|v||w| .
$$

Moreover $v \in \mathcal{A}_{\mathbb{T}^{k}} \subset B_{0}$, where $B_{0}$ is the absorbing set in $H$, thanks to the minimality property. Thanks to (20), $B_{0}=B_{H}\left(0,2 R_{0}\right)$, where
$R_{0}^{2}=\frac{c}{v^{2} \lambda_{1}^{2}}|f|_{L^{\infty}(\mathbb{R}, H)}^{2}+\frac{c^{\prime}}{v^{2} \lambda_{1}^{2}}\left|\phi_{t}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{c^{\prime \prime}}{v^{2} \lambda_{1}}|\phi|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}|\phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{c^{\prime \prime \prime}}{\lambda_{1}}|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}$
is an absorbing set in $H$. Therefore

$$
\left|\left(B\left(v, \phi_{\omega}^{\prime} \frac{\mu}{L U}\right), w\right)\right| \leqslant 2 R_{0}\left|\nabla \phi_{\omega}^{\prime} \frac{\mu}{L U}\right|_{L^{\infty}}|w| .
$$

Similarly we obtain, by integration by parts

$$
\left|\left(B\left(\phi_{\omega}^{\prime} \frac{\mu}{L U}, v\right), w\right)\right| \leqslant 2 R_{0}\left|\nabla \phi_{\omega}^{\prime} \frac{\mu}{L U}\right|_{L^{\infty}}|w|+2 R_{0}\left|\phi_{\omega}^{\prime} \frac{\mu}{L U}\right|_{L^{\infty}}\|w\| .
$$

Therefore

$$
\begin{aligned}
\left(M^{\prime}(y) z, z\right) \leqslant & -\frac{v}{4}\|w\|^{2}+\int_{\Omega}|\nabla v \| w|^{2} \mathrm{~d} x+\int_{\Omega}|\nabla \phi||w|^{2} \mathrm{~d} x \\
& +\frac{c}{L^{2} U^{2}}\left(\frac{1}{v \lambda_{1}}\left|f_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{1}{v \lambda_{1}}\left|\frac{\partial}{\partial t} \phi_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+v\left|\nabla \phi_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}\right. \\
& +\frac{1}{v \lambda_{1}}|\phi|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}\left|\nabla \phi_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{1}{v \lambda_{1}}\left|\phi_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2} \\
& \left.+\frac{R_{0}^{2}}{v \lambda_{1}}\left|\nabla \phi_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}+\frac{R_{0}^{2}}{v}\left|\phi_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}\right) \mu^{2}
\end{aligned}
$$

which can be rewritten as

$$
\begin{equation*}
\left(M^{\prime}(y) z, z\right) \leqslant-\frac{v}{4}\|w\|^{2}+\int_{\Omega}|\nabla v \| w|^{2} \mathrm{~d} x+\int_{\Omega}|\nabla \phi||w|^{2} \mathrm{~d} x+K \mu^{2} . \tag{45}
\end{equation*}
$$

We then find

$$
\left(M^{\prime}(y) z, z\right) \leqslant\left(M_{1} z, z\right)=\left(L_{1} w, w\right)+\left(L_{2} \mu, \mu\right)
$$

where

$$
L_{1} w=-\frac{v}{4} A w+P(|\nabla v|+|\nabla \phi|) w
$$

and

$$
L_{2} \mu=K I_{k} \mu
$$

where $I_{k}$ is the identity operator in $\mathbb{R}^{k}$.
Since $y_{0} \in \mathcal{A}$, the function $|\nabla v(x, t)|$ is smooth (see for instance [11, ch 4 , section 6]) and consequently $L_{1}$ is selfadjoint with a discrete spectrum, each eigenvalue having a finite multiplicity. We then have $M_{1}=\left(\begin{array}{cc}L_{1} & 0 \\ 0 & L_{2}\end{array}\right)$, and the eigenfunctions are $\varphi_{j}^{(1)}=\left(w_{j}, 0\right)$ and $\varphi_{i}^{(2)}=\left(0, \zeta_{i}\right)$, where $\left\{w_{j}\right\}$ is orthonormal in $H, L_{1} w_{j}=\lambda_{j} w_{j}$, and $\left\{\zeta_{i}\right\}$ is an arbitrary basis of $\mathbb{R}^{k}, i=1, \ldots, k, L_{2} \zeta_{i}=K \zeta_{i}$. We note that the $d$ greatest eigenvalues of $M_{1}$ can be written in the form

$$
\lambda_{d-k} \leqslant \cdots \leqslant \lambda_{p} \leqslant K \leqslant \cdots \leqslant K \leqslant \lambda_{p-1} \leqslant \cdots \leqslant \lambda_{1}
$$

for $d$ large enough. Moreover, we have

$$
\begin{aligned}
\sum_{j=1}^{d}\left(M_{1} \varphi_{j}, \varphi_{j}\right) & =-\frac{v}{4} \sum_{j=1}^{d-k}\left\|w_{j}\right\|^{2}+\int_{\Omega}|\nabla v| \sum_{j=1}^{d-k}\left|w_{j}\right|^{2} \mathrm{~d} x \\
& +\int_{\Omega}|\nabla \phi| \sum_{j=1}^{d-k}\left|w_{j}\right|^{2} \mathrm{~d} x+K \sum_{j=1}^{k}\left|\zeta_{j}\right|^{2} \\
= & -\frac{v}{4} \sum_{j=1}^{d-k}\left\|w_{j}\right\|^{2}+\int_{\Omega}|\nabla v| \sum_{j=1}^{d-k}\left|w_{j}\right|^{2} \mathrm{~d} x+\int_{\Omega}|\nabla \phi| \sum_{j=1}^{d-k}\left|w_{j}\right|^{2} \mathrm{~d} x+K k .
\end{aligned}
$$

Using the Lieb-Thirring inequality (see [11], appendix, theorem 4.1) we find

$$
\sum_{j=1}^{d}\left(M_{1} \varphi_{j}, \varphi_{j}\right) \leqslant-\frac{v}{8} \sum_{j=1}^{d-k}\left\|w_{j}\right\|^{2}+\frac{c}{v}\left(\|v\|^{2}+|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}\right)+K k .
$$

Moreover

$$
d-k=\int_{\Omega} \rho \mathrm{d} x \leqslant|\Omega|^{\frac{1}{2}}|\rho|
$$

where $\rho(x)=\sum_{j=1}^{d-k}\left|w_{j}\right|^{2}$. Therefore, we obtain

$$
q_{d} \leqslant-\frac{c v}{|\Omega|}(d-k)^{2}+\frac{c}{v}\left(\gamma+|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}\right)+K k
$$

where

$$
\gamma=\liminf _{t \rightarrow+\infty} \sup _{y_{0} \in \mathcal{A}}\left\{\frac{1}{t} \int_{0}^{t}\|v\|^{2} \mathrm{~d} \tau\right\} .
$$

Therefore $q_{d}<0$ if

$$
d-k>c\left(\frac{|\Omega|}{v^{2}}\left(\gamma+|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}\right)+\frac{K|\Omega|}{v} k\right)^{1 / 2} .
$$

That is to say

$$
d>k+c\left(\frac{|\Omega|}{v^{2}}\left(\gamma+|\nabla \phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}\right)+\frac{K|\Omega|}{v} k\right)^{1 / 2} .
$$

Using (19) we find

$$
\gamma \leqslant \frac{c}{v^{2} \lambda_{1}}|f|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{c^{\prime}}{v^{2} \lambda_{1}}\left|\phi_{t}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{c^{\prime \prime}}{v^{2}}|\phi|_{L^{\infty}\left(\mathbb{R}, L^{\infty}\right)}^{2}|\phi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+c^{\prime \prime \prime}|\nabla \phi|_{L^{\infty}\left(0, T ; L^{2}\right)}^{2} .
$$

Therefore

$$
\begin{aligned}
& \frac{|\Omega|}{v^{2}} \gamma \leqslant c\left(\frac{|\Omega|}{\nu^{4} \lambda_{1}}|f|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{|\Omega|^{2}}{v^{4} \lambda_{1}} \max \left(\left|\varphi_{t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2},\left|\nabla \frac{\partial \varphi}{\partial t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \operatorname{diam}^{2} \Omega\right) \varepsilon\right. \\
&\left.+\frac{c^{\prime \prime}|\Omega|}{\nu^{4} \lambda_{1}}\left(|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \cdot|\nabla \varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \operatorname{diam}^{2} \Omega|\Omega| \varepsilon\right)+\frac{c^{\prime \prime \prime}}{\varepsilon} \frac{|\Omega|}{v^{2}}|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2}\right) .
\end{aligned}
$$

Similarly, we have

$$
\begin{aligned}
& R_{0}^{2} \leqslant \frac{c}{\nu^{2} \lambda_{1}^{2}}|f|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}+\frac{c^{\prime}|\Omega|}{\nu^{2} \lambda_{1}^{2}} \max \left(\left|\varphi_{t}\right|_{L^{\infty}(\mathbb{R}, \partial \Omega)}^{2},\left|\nabla \varphi_{t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \operatorname{diam}^{2} \Omega\right) \varepsilon \\
&+\frac{c^{\prime \prime}|\Omega|}{\nu^{2} \lambda_{1}} \max \left(|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2},|\nabla \varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \operatorname{diam}^{2} \Omega\right)^{2} \varepsilon+\frac{c^{\prime \prime \prime}}{\varepsilon}|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2}
\end{aligned}
$$

and we then find (the computations are similar to those performed in lemma 1) (note that $K$ is as defined by (45))

$$
\begin{aligned}
\frac{|\Omega|}{v} K \leqslant \frac{c}{L^{2} U^{2}} & \left(\frac{|\Omega|}{v^{2} \lambda_{1}}\left|f_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2}\right. \\
& +\frac{|\Omega|^{2}}{v^{2} \lambda_{1}} \max \left(\left|\frac{\partial}{\partial t} \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2},\left|\nabla \frac{\partial}{\partial t} \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \operatorname{diam}^{2} \Omega\right) \varepsilon \\
& +\frac{1}{\varepsilon}|\Omega|\left|\varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2}+\frac{|\Omega|}{v^{2} \lambda_{1}} \max \left(|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2},|\nabla \varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2}\right. \\
& \left.\times \operatorname{diam}^{2}|\Omega|\right)\left|\varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \frac{1}{\varepsilon}+\frac{|\Omega|}{v^{2} \lambda_{1}} \max \left(\left|\varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2},\left|\nabla \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2}\right. \\
& \left.\times \operatorname{diam}^{2}|\Omega|\right)|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \frac{1}{\varepsilon}+\frac{R_{0}^{2}}{v^{2} \lambda_{1}}\left|\varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \frac{1}{\varepsilon^{2}}+\frac{R_{0}^{2}|\Omega|}{v^{2}} \\
& \left.\times \max \left(\left|\varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2},\left|\nabla \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}^{2} \operatorname{diam}^{2} \Omega\right)\right) .
\end{aligned}
$$

We now set
$U=\max \left(|\varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)},|\nabla \varphi|_{L^{\infty}(\mathbb{R} \times \partial \Omega)} \operatorname{diam} \Omega,\left|\varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)},\left|\nabla \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)} \operatorname{diam} \Omega\right)$
$L=\max \left(|\Omega|^{1 / 2},\left(\frac{1}{\lambda_{1}}\right)^{1 / 2}\right)$
$G_{1}=\frac{L^{2}}{v^{2}}|f|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}$
$G_{2}=\frac{L}{\nu U}\left|f_{\omega}^{\prime}\right|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}$
$R e_{1}=\frac{U L}{v}$
$R e_{2}=\max \left(\left|\varphi_{t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)}\left|\nabla \varphi_{t}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)} \operatorname{diam} \Omega\right)^{1 / 2} \frac{L^{3 / 2}}{v}$
$R e_{3}=\max \left(\left|\frac{\partial}{\partial t} \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)},\left|\nabla \frac{\partial}{\partial t} \varphi_{\omega}^{\prime}\right|_{L^{\infty}(\mathbb{R} \times \partial \Omega)} \operatorname{diam} \Omega\right) \frac{L^{2}}{U v}$
$R e=\max \left(R e_{1}, R e_{2}, R e_{3}\right)$.
We then find, taking $\varepsilon=c R e^{-1}, c$ being a nondimensional constant, independent of $R e$,

$$
\begin{aligned}
& \frac{|\Omega|}{v^{2}} \gamma \leqslant\left(G_{1}^{2}+R e^{3}\right) \\
& \frac{|\Omega|}{v^{2}}|\nabla \varphi|_{L^{\infty}\left(\mathbb{R}, L^{2}\right)}^{2} \leqslant c^{\prime} R e^{3} \\
& R_{0}^{2} \leqslant \frac{c v^{2}}{L^{4}}\left(G_{1}^{2}+R e^{3}\right) \\
& \frac{|\Omega| K}{v} \leqslant c\left(G_{2}^{2}+R e+G_{1}+R e^{3}\right)
\end{aligned}
$$

we finally deduce that the Hausdorff dimension of $\mathcal{A}_{\mathbb{T}^{k}}$ is bounded, as follows

$$
\begin{equation*}
\operatorname{dim} \mathcal{A}_{\mathbb{T}^{k}} \leqslant k+c\left(G_{1}+\operatorname{Re}^{3 / 2}\right)+c^{\prime}\left(G_{1}+G_{2}+R e^{3 / 2}\right) k^{1 / 2} \tag{46}
\end{equation*}
$$

where $c$ and $c^{\prime}$ are nondimensional constants, independent of $G_{1}, G_{2}$, and $R e$.

Roughly speaking, the Reynolds numbers are nondimensional numbers illustrating the ratio of (in this case) the strength of external forcing via boundary velocity and the viscous force strength while the generalized Grashoff numbers are nondimensional numbers illustrating the ratio of the strength of body force and the the strength of the viscous force. Since both the boundary velocity and the body force are time and space dependent in general, we may define different Reynolds numbers and Grashoff numbers to emphasize different effects of different scales of the external forcing. Of course, we may always define one single Reynolds number, $R e$, as above and one single Grashoff number as the sum of $G_{1}$ and $G_{2}$.

Remark 2. If $k=0$ (autonomous case), then (46) becomes the estimate derived in [8]. Moreover, it was proved in [1] that the term $k$ is optimal if we consider the dependence in $k$. Now if $\varphi=0$, (46) reduces to the estimates derived in [1]

Thanks to (46), we find

$$
\begin{equation*}
\operatorname{dim} \mathcal{A}_{\mathbb{T}^{k}} \leqslant \frac{c}{v^{2}} \tag{47}
\end{equation*}
$$

if $f \neq 0$ and,

$$
\begin{equation*}
\operatorname{dim} \mathcal{A}_{\mathbb{T}^{k}} \leqslant \frac{c^{\prime}}{v^{3 / 2}} \tag{48}
\end{equation*}
$$

if $f=0$, where $c$ and $c^{\prime}$ are independent of $v$. These estimates are of the same order as those derived in [8] for the autonomous case. Moreover, if $f=0$, (48) agrees with Kolmogorov's heuristical estimate of the number of degrees of freedom of a two-dimensional turbulent flow (see [11]), when the dependence on $v$ is considered.

Remark 3. We can also obtain similar bounds for the fractal dimension of $\mathcal{A}_{\mathbb{T}^{k}}$ just as in the autonomous case.

Remark 4. For optimal bounds on the dimension of attractors for two-dimensional periodic flows, the readers are referred to [3]. For more general boundary conditions, see [2].

Remark 5. In the case of shear driven channel flow we may sort out the dependence of the dimension of the attractor on the shape of the domain (aspect ratio $=$ length/width) in the same way as was done by Doering and Wang [4] where the authors proved that the dimension of the attractor for two-dimensional autonomous shear driven channel flows has an upper bound of the form an absolute constant times the aspect ratio times $R e^{3 / 2}$.

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