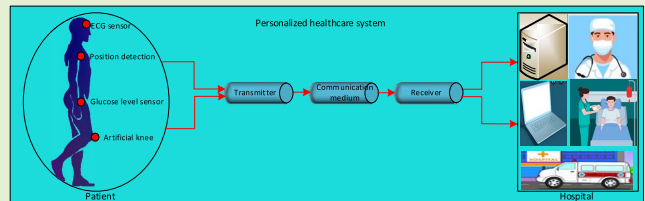


Energy-Aware Hybrid MAC Protocol for IoT Enabled WBAN Systems

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Abstract—Energy efficiency is an important quality-of-service requirement that needs to be considered when designing an efficient MAC protocol for a WBAN system due to the limited power resources of biomedical sensor devices. To address this, an energy-aware multi-group hybrid MAC (MG-HYMAC) protocol is proposed in this work to improve energy efficiency as well as the lifetime of the biomedical sensor devices in a personalized healthcare system. The proposed protocol combines both the advantages of the CSMA/CA and the TDMA schemes to enable the biomedical sensors to efficiently contend for transmission opportunities and to allow them to efficiently transmit health data. The MG-HYMAC protocol is combined with a transmission scheduling technique to duty cycle the operations of the biomedical devices with less critical data to determine when and how the biomedical sensor devices will transmit their health data packets in order to reduce collisions to save energy and prolong the battery lifetime of the biomedical sensor devices so as to improve the overall network lifetime. Also, a stochastic probability model and a heuristic-based power control scheme are developed to solve time allocation and power control problems to improve energy efficiency and the biomedical sensor devices lifetime. To validate the MG-HYMAC protocol, it was compared with other related protocols (including HyMAC and CPMAC) and simulated in MATLAB. The simulation results proved that the proposed MG-HYMAC protocol outperformed the existing MAC protocols using standard metrics like energy efficiency, biomedical sensor devices lifetime, and convergence speed.

Index Terms—WBAN, MAC protocols, personalization, stochastic probability, CSMA/CA, TDMA, Internet of Things, transmission scheduling scheme.



I. INTRODUCTION

WITH the increasing advances of the internet of things (IoT) technologies and smart devices, wireless body area network (WBAN) technology design has received significant attention from both the academia and industry [1]–[3]. The IoT technology is a communication

paradigm that can be integrated into many wireless systems [4] such as the WBAN systems to seamlessly connect different types of devices, over the internet to accomplish the critical tasks of such systems ubiquitously [5]–[8].

In the health domain, IoT technologies can be incorporated into WBANs to enable real-time monitoring of patients' health conditions, patients' information management, process control, and to also enable decision making with or without the intervention of humans remotely [9] and [10]. Additionally, combining an IoT technology with a WBAN system could help to provide a cost-effective service as well as help to minimize patients' frequent hospital visits. Therefore, integrating IoT technologies into WBANs are advantageous for healthcare monitoring purposes to achieve a better productivity [11] and [12].

An IoT enabled WBAN system is a body-focused type of wireless network that is composed of various IoT biomedical sensors which are characterized as smart, tiny, light-weight, wearable, and low powered devices. These IoT biomedical sensors are usually positioned in the body, on the body or placed around the human body, they include the gyroscope sensor, electromyography (EMG) sensor,

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electroencephalogram (EEG) electrocardiography (ECG) sensor, pulse oximeter sensor, heart-rate monitoring sensor, blood pressure sensor, temperature sensor, mental health sensor and so on. The IoT biomedical sensors are used for diagnosing, monitoring, and treating patients with health challenges such as obesity, cancer, diabetes, strokes, myocardial infarction, and tropical diseases [13] seamlessly. They also gather and communicate sensed health data through an access point (AP) such as a smart phone [14] in the body area to designated healthcare centers [15], [16].

However, despite the unique properties of the WBAN systems, they are still confronted with an energy scarcity issue [17] and [18] because the WBAN biomedical sensors are usually configured to use batteries which have limited power capacities and they are sometime impractical to replace or recharge especially when they are implanted in a patient's body. Also, it is well established that the energy consumed by the biomedical devices during data communication to the AP is typically significant. Because of the limited battery power concern and the long lifetime requirement of the biomedical sensors, hence, the need to minimize energy consumption during health data communications is very important, but then, this poses a great challenge in designing robust MAC protocols for a WBAN system [19]–[21]. Therefore, to address this power consumption issue, we propose a new MAC protocol that is energy-aware for an effective patient's health condition sensing and data communication.

The proposed energy-aware MAC protocol is composed of two major phases that include the transmission phase (TP) and the receiving phase (RP). During health data communication phase, i.e., the transmission and the receiving phases, the biomedical sensors waste energy through unnecessary idle listening, collisions, overhearing, and control overhead. To address this and save energy, we employ a sleep-wakeup scheduling mechanism, and we also assign the major transmission overhead to the AP since it can be charged easily unlike the biomedical sensors. Also, we allocate a specific time slot to each of the biomedical sensors for their health data transmission to prevent collisions. A waiting order (WO) state was introduced as a specific type of idle state that only occur during the TP of the TDMA period to save energy. Furthermore, based on the WBAN application requirements, we classify the health data of the biomedical sensors into two groups, namely the critical health data and the less critical health data. To save energy, we as well employ a transmission scheduling technique to duty cycle the operations of the biomedical sensor devices with less critical data packets to determine when and how the biomedical sensor devices will transmit their health data packets to reduce collisions. The major contributions of this paper are outlined below:

- The design of an energy-aware hybrid MAC protocol to reduce the power consumption of WBAN biomedical sensors during data communication was proposed.
- We introduced the idea of a multi-variate concept based on the WBAN application requirements to classify the health data of the biomedical sensors into critical and less critical data according to their priority level.

- To address the longstanding energy efficiency design concern related to the WBAN systems, a transmission scheduling technique is applied to duty cycle the operations of the WBAN biomedical devices with less critical data packets to determine when and how the devices will transmit their health data packets to reduce collisions in order to save energy and prolong the battery lifetime of the biomedical sensor devices to improve the overall network lifetime.
- Since the major sources of energy wastage issues during health data communications are idle listening, control overhead, and collisions, therefore, to save energy and extend the lifetime of the biomedical sensors, we assign the major transmission overhead to the AP side. To conserve energy during idle listening state, we introduced a waiting order state to enable only the synchronous clock of the biomedical sensors to work, while all other operations are disabled. Also, we adopted a sleep-wakeup scheduling mechanism to reduce energy wastage issue to prolong the network lifetime.
- In addition, the biomedical sensors that have health data to transmit are assigned a specific time slot to prevent collisions and thereby reducing energy wastage due to frequent re-transmissions.
- We harnessed the advantages of the CSMA/CA and TDMA schemes as well as the state division of the biomedical sensors to achieve energy efficiency during health data sensing and communication.
- We developed a stochastic probability model and a heuristic-based power control scheme to solve time allocation and power control problems to enhance energy efficiency and prolong the lifetime of the devices.

There is no existing work that has considered a multi-group hybrid MAC (MG-HYMAC) in WBANs that studied this issue in literature to the best of authors' knowledge.

This work is organized in the following manner: The related works is presented in Section II. Section III presents the system model. Section IV presents the analysis of time spent in different states of the proposed MG-HYMAC protocol. The proposed power control scheme and power consumption model for the MG-HYMAC protocol is discussed in Section V. Section VI presents the operations of the proposed MG-HYMAC protocol. Simulation results are discussed in Section VII, while we conclude the work in Section VIII.

II. RELATED WORKS

In this section, we discuss some existing articles in literature that considered MAC protocols to improve the energy efficiency of the WBAN systems. Examples are [2], [22]–[32]. They are discussed and compared with this work in [Table I](#).

III. SYSTEM MODELLING

The proposed system model presents the details on the system architecture and mathematical modelling. In the modelling of the proposed hybrid MAC protocol, the following assumptions are made:

- We assume that not all the biomedical sensors in the network have data to transmit.

TABLE I
COMPARISON OF THE EXISTING MAC PROTOCOLS AND THE PROPOSED MAC PROTOCOL

Reference	Contribution of the existing MAC protocol	Contribution of the newly proposed MAC protocol
[2]	A hybrid multi-class MAC protocol that adopts slotted ALOHA and TDMA mechanisms was proposed. The proposed protocol consists of two main processes, namely contention phase and transmission phase. An optimization problem was formulated to maximize the system sum-throughput, packet success-access-ratio, and the reservation ratio to determine the trade-off between the two processes. The paper employed a concept that efficiently divided the devices in the network into two classes. In each class, not all the devices have data to transmit. This helped to improve the network performance. However, the energy efficiency of the system was not considered in this work.	Different from [2], an energy-aware MAC protocol that adopts a CSMA/CA scheme and a TDMA scheme was proposed. The proposed protocol consists of two main processes, namely the reception phase and the transmission phase. We developed a stochastic probability model and a heuristic-based power control scheme to solve time allocation and power control problems. Unlike [2], the focus of this work is to improve energy efficiency and to prolong the lifetime of the biomedical devices by addressing energy wastage and energy consumption problems during data communication. Here, we employ a multi-variate concept to classify the devices in the network into two groups. The devices in the first group were all assumed to have data to transmit, while a few out of the second group have data to transmit.
[22]	An energy harvesting hybrid MAC protocol that adopts a dynamic scheduling method to improve energy efficiency was proposed. But then, the latency of the proposed system is relatively high and could still be improved on.	In contrast to [22], we proposed a new hybrid MAC protocol that exploit the CSMA/CA scheme and the TDMA scheme to improve energy efficiency. Also, we tackle energy wastage problems that are generally common during data communication by introducing some power saving mechanisms such as low power listening, contention, and transmission scheduling mechanisms.
[23]	An out-of-band wake-up radio was introduced to save energy during idle listening and the transmission of control overhead. However, more efficient mechanisms could still be investigated to reduce energy consumption and energy wastage issues so as to increase the lifetime of the system.	Contrary to [23], we assign the major transmission overhead to the AP side since it has sufficient power resource and can be charged. Also, to cater for energy wastage during idle listening we employ a sleep-wake-up scheduling mechanism as well as introduce a waiting order state which works by only allowing the synchronous clock of the biomedical sensors to function while other operations are disabled.
[24]	An investigation on a hybrid MAC protocol in the context of energy efficiency and delay was carried out in [24]. However, more investigations that focus on the development of new mechanisms are required to address energy wastage and energy consumption issues.	Different from [24], a multi-variant hybrid MAC protocol which combines the benefits of the CSMA/CA and the TDMA schemes was introduced to enhance energy efficiency. The operations of the WBAN biomedical sensors were divided into different states to tackle energy wastage issues such as collisions, idle listening, and control overhead during data communication. Furthermore, we apply a transmission scheduling and a sleep-wake-up scheduling mechanism to conserve energy.
[25]	A SmartBAN. hybrid MAC protocol was introduced to mix the slotted ALOHA and the TDMA scheme to improve energy efficiency and minimize delay in the network in an attempt to enhance periodic and emergency traffic. However, the proposed system is not scalable and this calls for further improvements.	In contrast to [25], we exploited both the CSMA/CA and the TDMA schemes. For instance, the CSMA/CA scheme was employed to handle collision problem during data communication to reduce the energy wastage associated with frequent retransmissions of health data. In addition, to reduce energy wastage issues we allocate specific time slots to the biomedical sensors to prevent collisions. Also, a transmission scheduling technique was employed to duty cycle the operations of the biomedical sensors to save energy.
[26]	A MAC protocol that is based on the IEEE 802.15.6 protocol was proposed to handle normal and emergency traffic. A slot reallocation technique was employed to conserve energy. However, this has a negative influence on the latency of the system. Therefore, the latency of the system needs to be improved on.	Contrary to [26], we introduced a multi-variant technique based on the WBAN application requirements to classify the health data of the biomedical sensors into critical and less critical data according to their priorities. We introduce some power saving mechanisms such as a low power listening, contention and transmission scheduling mechanisms to minimize energy consumption.
[27]	An energy efficient MAC protocol that exploits the advantages of the body area network static nature was introduced to implement a TDMA scheme that saved a reasonable amount of energy with a little idle listening and overhead. But then, the data transfer reliability and the flexibility of the system are still considered low and could still be improved on.	Unlike [27], the advantages of the CSMA/CA and the TDMA schemes were combined to improve energy efficiency and extend the lifetime of the network. To achieve an energy efficient WBAN system, the major transmission overhead was observed at the AP side, a waiting order state which only allow the synchronous clock of the biomedical sensors to work was introduced while other operations are turned off.
[28]	Authors proposed a RFID-enabled MAC protocol to adjust the wakeup and the sleep state of the body nodes dynamically based on their traffic pattern to address energy consumption problem. However, the proposed system is yet to fully address energy wastage and energy consumption concerns. Hence, the work is still limited in terms of the lifetime of the system.	In contrast to [28], we introduced the idea of a multi-variant technique which harness the CSMA/CA and the TDMA benefits to address energy consumption problems. Furthermore, a transmission scheduling technique was employed to duty cycle the operations of the biomedical sensors such that only the biomedical sensors that have data to transmit are assigned specific time slots, while others go into a sleep mode to conserve energy.
[29]	A traffic adaptive MAC protocol that is based on the traffic information of the sensor nodes was designed. To conserve energy, the duty cycles of the nodes were adjusted based on their traffic pattern. Unfortunately, the proposed system has a relatively high latency that resulted to energy wastage issues. Therefore, the energy efficiency of the proposed system could still be improved on.	Contrary to [29], we addressed the energy consumption issues during data communication by dividing the operations of the biomedical sensors into different states and minimizing the energy consumed in each state, for example, we employ a transmission scheduling mechanism to duty cycle the operations of the biomedical sensors based on their data type.
[30]	Here, authors designed a MAC protocol based on a TDMA scheme where nodes are allocated time slots to transmit packets and goes into a Q-sleep mode at others time slot to	Different from [30], we designed a new MAC protocol that is based on the CSMA/CA and the TDMA mechanisms which adopts a sleep-wake-up

TABLE I
(Continued.) COMPARISON OF THE EXISTING MAC PROTOCOLS AND THE PROPOSED MAC PROTOCOL

	save energy. But then, the throughput and lifetime of the system decreased due to time slot wastage. As a consequence, the utilization of time slot could still be improved on.	scheduling method. We introduced some power saving mechanisms such as low power listening, contention and transmission scheduling mechanisms.
[31]	Authors proposed a polling-based MAC protocol where sensors can efficiently utilize the channel in such a way that the sensors are waked up to transmit their packets only when the channel is strong to enable a fast and reliable transmission to enhance energy efficiency, transmission reliability as well as data rate performance. But then, this resulted to a high latency which technically led to energy wastage and a decrease in the lifetime of the system.	Unlike [31], we proposed the idea of a multi-variant technique which harness the advantages of the CSMA/CA and the TDMA mechanisms to address energy consumption problem due to collisions, idle listening, overhearing, and control overhead. In addition, we employ a transmission scheduling technique to duty cycle the operations of the biomedical sensors such that a particular time slot is assigned to a biomedical sensor device that have data to transmit, while others go into a sleep mode to save energy.
[32]	A homogenous hybrid MAC protocol involving the CSMA/CA protocol and the TDMA protocol was proposed to improve energy efficiency. An awaiting order state was considered to save energy. Also, energy wastage due to packet overload was addressed by setting the major overhead transmission at the PS side. However, the mechanisms proposed are yet to fully tackle the longstanding energy consumption and energy wastage issues. Hence, there are still needs for improvements.	In contrast to [32] that only considered a homogenous WBAN system, i.e., they do not provide any scheme to cater for a heterogeneous network, where the biomedical sensors in a network may have different properties like the consideration of critical health data and less critical health data. For this reason, we extend the work done in [32] by introducing the idea of a multi-variant concept to cater for network heterogeneity. To further improve energy efficiency and extend the battery lifetime of the biomedical sensors, we apply a transmission scheduling technique to duty cycle the operations of the WBAN biomedical sensors with less critical data packets to determine when and how the biomedical sensor devices will transmit their health data packets to reduce collisions in order to save energy and prolong the battery lifetime of the biomedical sensor devices so as to improve the overall network lifetime. Also, we developed a stochastic probability model and a heuristic-based power control scheme to solve time allocation and power control problems to enhance energy efficiency and prolong the lifetime of the devices. Furthermore, we employed a sleep-wake-up scheduling mechanism which helped in saving a reasonable amount of power and increasing the network lifetime. Thus, the protocol design, proposed algorithmic methods, and the mathematical formulation proposed in this work are different compared to [32].

- We assume that the system uses a sense-and-send approach.
- The data packet arrival is based on a Poisson process, while the retransmission of the data packets is considered as a truncated Poisson distribution process.
- We assume two types of events for the biomedical sensor devices (i.e., the transmission of data packets to the AP and the reception of control signals from the AP) data in the TP and the amount of energy consumed in these events are different in a fixed TP.
- We also assume that a biomedical sensor device consumes different amount of power across the states, but then, all the biomedical sensors in the network operates using a fixed power in a particular state.

A. System Architecture

Here, we introduce a new personalized WBAN system architecture that is made up of a low power AP device (i.e., a mobile cell phone) that can be charged easily as well as various biomedical devices that are uniformly distributed all over a patient's body for health condition(s) monitoring as shown in Fig 1. Each of the biomedical devices perform health condition(s) sensing and send their sensed health data to the AP. The AP acts as the coordinator as well as an intermediary between the biomedical devices and other components of the system, including the medical experts, health centers, and the health data analysis platforms.

B. Mathematical Modelling

Let K denote the total number of the biomedical sensor devices in the network. The biomedical sensor devices within

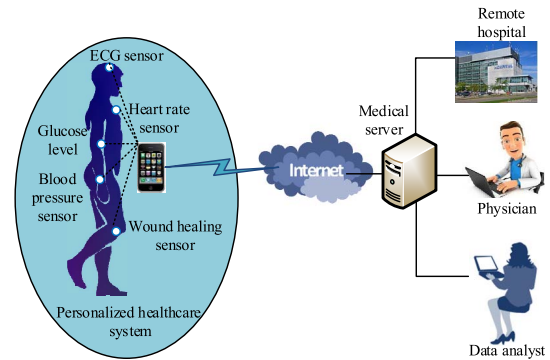


Fig. 1. A typical personalized WBAN system architecture.

this network are classified into a multi-group (for example, group P , group Q , and so on) using a multi-variate concept according to their health data priority-level using (1). Note, we assume that each device will have to assign a priority-level (η) to its health data to provide a high priority and a low priority to the critical health data and less critical health data respectively based on (1) [33].

$$\eta = \frac{D_T}{\lambda_{rate} \times P_{len}} \quad (1)$$

where D_T is the health data type, λ_{rate} is the traffic arrival rate, and P_{len} is the packet length. Based on the priority-level, the devices and the AP takes decision during the allocation of resources and transmission.

As a consequence, the biomedical devices with critical health data packets are categorized into group P and are

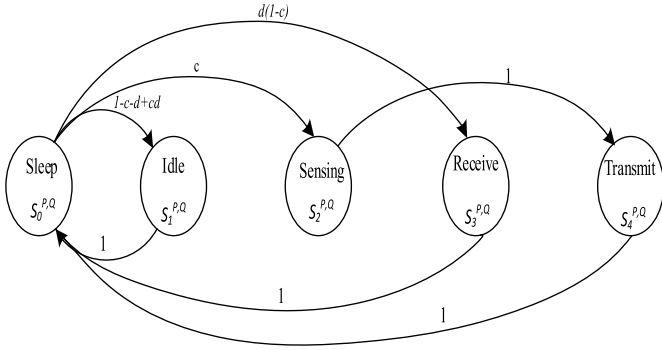


Fig. 2. Proposed state transition probability of the biomedical sensor devices.

denoted as A in a set of $A = \{m_1, m_2, m_3, \dots, m_A\}$, while the biomedical devices with less critical health data packets are categorized into group Q and are denoted as B in a set of $B = \{n_1, n_2, n_3, \dots, n_B\}$.

In each TP, we assume that not all the biomedical devices with less critical health data packets in group Q have data packets to send based on the applied transmission scheduling method. Meanwhile, only the ones that have data packets to send are enabled to contend for channel utilization opportunities for transmission purposes. While we assume that all the biomedical devices in group P all have health data packets to send to the AP, hence, all of them are allowed to contend for channel utilization opportunities.

It was assumed that each of the biomedical devices in the network follows a stochastic process with five states. Consequently, $S_n^{P,Q} = \{S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}, S_4^{P,Q}\}$ was used to represent the five states of a biomedical sensor device, where we denote the set of all the device states as $S_n^{P,Q}$ while $S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}$, and $S_4^{P,Q}$ represents the sleep, idle, sensing, receiving, and transmitting states respectively in groups P and Q as shown in Fig. 2.

IV. ANALYSIS OF TIME SPENT IN DIFFERENT STATES

In this section, we present the analysis of the average time spent in each state of the proposed MG-HYMAC protocol. For this to be achieved, we use a continuous-time Markov chain to estimate the time a device spent in each state [34].

Therefore, the probability that there is at least a sensing event occurrence is expressed in (2) and the probability that there is at least one transmission event occurrence is expressed in (3) respectively as:

$$c = 1 - e^{-\lambda_{sen} T_t} \quad (2)$$

$$d = 1 - e^{-\lambda_{tran} T_t} \quad (3)$$

where T_t represent the maximum time spent by a device in the idle state during the CSMA/CA period of the TP, while λ_{sens} and λ_{tran} denotes the average arrival rate of the health data packets for the Poisson process in the sensing as well as the transmission phases, respectively.

Recall that the biomedical devices in the network are classified into multi-groups including group P that contains

the critical health data packets and group Q that contains the less critical health data packets. Hence, the time spent by a device in group P on the S_n^P state is denoted as $T_{S_n^P}$, while $E[T_{S_n^P}] = \mu_{S_n^P}^P$ represents the $T_{S_n^P}$ mean value.

For example, the time a biomedical sensor spends in the sleep state is represented as $T_{S_0^P}$. The expected value of $T_{S_0^P}$ is assumed to be equal to its mean value as expressed in (4):

$$E[T_{S_0^P}] = \mu_{S_0^P}^P \quad (4)$$

If a device switches from S_0^P to S_1^P , then, the time spent in S_1^P , is denoted as $T_{S_1^P}$. For each transmission event occurrence, the $T_{S_1^P}$ mean value is expressed in (5) as:

$$E[T_{S_1^P} | event] = \mu_{S_1^P}^P | event = \int_{\aleph_t}^{\aleph_t + T_t} (\varphi - \aleph_t) / T_t \partial \varphi = \left(\frac{1}{2} T_t\right) \quad (5)$$

In (6), \aleph_t denotes the period that the biomedical sensor device switches from S_1^P to an active state, i.e., either the transmitting or the receiving state.

We denote the maximum time and the minimum time a biomedical sensor device spends in S_2^P as ζ_{max}^P and ζ_{min}^P , respectively. Thus, the mean value of $T_{S_2^P}$ is computed in (6) as:

$$E[T_{S_2^P}] = \mu_{S_2^P}^P = \frac{1}{2} (\zeta_{max}^P + \zeta_{min}^P) \quad (6)$$

While, for the receiving and transmitting states, we denote the time spent in each state as $T_{S_3^P}$ and $T_{S_4^P}$, respectively and their mean values are expressed in (7) and (8) as:

$$E[T_{S_3^P}] = \mu_{S_3^P}^P \quad (7)$$

$$E[T_{S_4^P}] = E[T_{prep}^P] + E[T_{data}^P + T_{beacon}^P + T_{ACK}^P] \quad (8)$$

In (8), $T_{prep}^P, T_{data}^P, T_{beacon}^P$, and T_{ACK}^P denotes the time a biomedical sensor device prepares to transmit, the time spent on health data packet transmission, the time spent on sending all end-beacons, and the time spent on sending all ACKs, respectively. Note, we assume that the T_{prep}^P begins from when a biomedical sensor device enters the transmitting state till when it successfully delivers its health data packets. Thus, the $T_{prep}^P, T_{data}^P, T_{beacon}^P$, and T_{ACK}^P can all be determined using P_{len} / \aleph , where \aleph is the transmission rate.

From (4) – (8), the total time spent by a biomedical sensor device in group P on the transition states is modelled in (9) as:

$$T_{Total}^P = T_{S_0^P} + (c + d - cd) T_{S_1^P} | event + c (T_{S_2^P} + T_{proc}^P) + d (T_{S_3^P}) + (c + d - cd) T_{S_4^P} \quad (9)$$

where T_{proc} is the processing time.

And the mean value of T_{Total}^P is determined in (10) as:

$$E[T_{Total}^P] = T_{S_0^P} - (c + d - cd) \left(\frac{1}{2} T_t\right) + c \left(\mu_{S_1^P}^P + \frac{1}{a}\right) + d \mu_{S_3^P}^P + (c + d - cd) \mu_{S_4^P}^P \quad (10)$$

For group Q , the time spent by a biomedical sensor device on the S_n^Q state is denoted as $T_{S_n^Q}$ and its mean value is $E[T_{S_n^Q}] = \mu_{S_n^Q}$. Consequently, $T_{S_0^Q}$ is the time spent in S_0^Q and the expected value of $T_{S_0^Q}$ is assumed to be equal to its mean value as given in (11):

$$E[T_{S_0^Q}] = \mu_{S_0^Q} \quad (11)$$

The time spent in S_1^Q is denoted as $T_{S_1^Q}$. If \exists a transmission event occurrence, then, the $T_{S_1^Q}$ mean value is determined in (12) as:

$$E[T_{S_1^Q}|\text{event}] = \mu_{S_1^Q}|\text{event} = \int_{\mathfrak{R}_t}^{\mathfrak{R}_t+T_t} (\varphi - \mathfrak{R}_t) / T_t \partial\varphi = \left(\frac{1}{2}T_t\right) \quad (12)$$

Recall that not all the biomedical devices in group Q have data packets to send and/or will not participate in data transmission in each TP cycle, hence, for no transmission occurrence, we model the mean value of $T_{S_1^Q}$ in (13) as:

$$E[T_{S_1^Q}|\text{none}] = \mu_{S_1^Q}|\text{none} = T_t \quad (13)$$

The time a biomedical sensor device spend in the sensing state is $T_{S_2^Q}$ and the mean value is expressed in (14) as:

$$E[T_{S_2^Q}] = \mu_{S_2^Q} = \frac{1}{2}(\varsigma_{max}^Q + \varsigma_{min}^Q) \quad (14)$$

While the time spent by a biomedical sensor device in either the receiving and transmitting states are represented as $T_{S_3^Q}$ and $T_{S_4^Q}$, respectively and their mean values are modelled in (15) and (16) as:

$$E[T_{S_3^Q}] = \mu_{S_3^Q} \quad (15)$$

$$E[T_{S_4^Q}] = E[T_{prep}^Q] + E[T_{data}^Q + T_{beacon}^Q + T_{ACK}^Q] \quad (16)$$

To determine the total time spent by a biomedical sensor device in group Q , we combine (11) – (14) to model (17) as:

$$T_{Total}^Q = T_{S_0^Q} + (1 - (c + d - cd)) T_{S_1^Q}|\text{none} + (c + d - cd) T_{S_1^Q}|\text{event} + c(T_{S_2^Q} + T_{proc}^Q) + d(T_{S_3^Q}) + (c + d - cd) T_{S_4^Q} \quad (17)$$

While the mean value of T_{Total}^Q is computed in (18) as:

$$E[T_{Total}^Q] = T_{S_0^Q} + T_t - (c + d - cd) \left(\frac{1}{2}T_t\right) + c \left(\mu_{S_1^Q} + \frac{1}{b}\right) + d\mu_{S_3^Q} + (c + d - cd)\mu_{S_4^Q} \quad (18)$$

The total time spent by all the biomedical devices A and B is computed from (9) and (17) in (19) and (20), respectively as:

$$\sum_{a=1}^A T_{Total}^P \quad \forall a, a = 1, 2, \dots, A \quad (19)$$

$$\sum_{b=1}^B T_{Total}^Q \quad \forall b, b = 1, 2, \dots, B \quad (20)$$

The total mean value of the time spent by all the biomedical devices A and B is computed from (10) and (18) in (21) and (22) respectively as:

$$\sum_{a=1}^A (E[T_{Total}^P]) \quad \forall a, a = 1, 2, \dots, A \quad (21)$$

$$\sum_{b=1}^B (E[T_{Total}^Q]) \quad \forall b, b = 1, 2, \dots, B \quad (22)$$

Furthermore, to calculate the overall time spent by group P and group Q , we add (19) and (20). The overall time spent by all the biomedical devices in both groups P and Q is defined by Θ_{sum} and expressed in (23) as:

$$\Theta_{sum} = \sum_{a=1}^A T_{Total}^P + \sum_{b=1}^B T_{Total}^Q \quad (23)$$

Also, their overall mean value (i.e., groups P and Q) is defined by \mathfrak{H}_{sum} and computed in (24) by adding (21) and (22).

$$\mathfrak{H}_{sum} = \sum_{a=1}^A (E[T_{Total}^P]) + \sum_{b=1}^B (E[T_{Total}^Q]) \quad (24)$$

To solve the problem of the overall time spent by all the biomedical devices in the system, we employed the proposed stochastic probability scheme presented in Algorithm 1.

V. PROPOSED POWER CONTROL SCHEME AND POWER CONSUMPTION MODEL FOR THE MG-HYMAC PROTOCOL

In this section, we propose a power control scheme for the MG-HYMAC protocol and model the power consumption of the biomedical sensor devices in the network. The amount of power allocated to each biomedical sensor device in the five states by the AP is controlled by the power control scheme. The schemes apply a set of $\varrho_n^{P,Q} = \{\varrho_0^{P,Q}, \varrho_1^{P,Q}, \varrho_2^{P,Q}, \varrho_3^{P,Q}, \varrho_4^{P,Q}\}$ and a set of $S_n^{P,Q} = \{S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}, S_4^{P,Q}\}$ to process the optimal control and the allocation of power during each TP cycle.

The biomedical devices in the network have their operational power fixed for each state and we denote the power consumed by each biomedical sensor device when switching from $S_0^{P,Q}$ to $S_1^{P,Q}$ as $\varepsilon_{01}^{P,Q}$ and as $\varepsilon_{13}^{P,Q}$ when switching from $S_1^{P,Q}$ to $S_3^{P,Q}$. Following this, the total power consumed is represented as Φ_{Total} and modelled in (25) and (26) for both groups P and Q , respectively as:

$$\Phi_{Total}^P = T_{S_0^P}^P \varrho_0^P + T_{S_1^P}^P \varrho_1^P + \varepsilon_{01}^P + \tau_s (T_{S_2^P}^P \varrho_2^P + T_{S_4^P}^P \varrho_4^P) + \varepsilon_{13}^P + \tau_r T_{S_3^P}^P \varrho_3^P \quad (25)$$

$$\Phi_{Total}^Q = T_{S_0^Q}^Q \varrho_0^Q + T_{S_1^Q}^Q \varrho_1^Q + \varepsilon_{01}^Q + \tau_s (T_{S_2^Q}^Q \varrho_2^Q + T_{S_4^Q}^Q \varrho_4^Q) + \varepsilon_{13}^Q + \tau_r T_{S_3^Q}^Q \varrho_3^Q \quad (26)$$

In (25) and (26), τ_s and τ_r are used to show the occurrence of transmission event in the sensing and receiving states, respectively. So, if \exists a transmission occurrence it turns to 1 otherwise it turns to 0. The mean value of the total power consumption for both groups P and Q is modelled in (27) and (28) respectively as:

$$E[\Phi_{Total}^P] = T_{S_0^P}^P \varrho_0^P (c + d - cd) \left(\frac{1}{2}T_t \varrho_1^P\right) + \varepsilon_{01}^P$$

Algorithm 1 MG-HYMAC Stochastic Probability Scheme

Require: $A, B \triangleright$ biomedical sensors in group P and group Q , $S_n^{P,Q} = \{S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}, S_4^{P,Q}\} \triangleright$ transition states, $\mathcal{A}P$, Θ_{sum} && \mathfrak{H}_{sum}

- 1: Initialize: biomedical devices with data packets to transmit
- 2: Assign η to each group based on their data type using (1)
- 3: **for** $a = 1, \dots, A$ **do**
- 4: let $T_{S_n^P}^P$ denote time spent by each a in S_n^P states
- 5: **for** S_0^P **do**
- 6: calculate mean value of $T_{S_0^P}^P$ as (4)
- 7: **end for**
- 8: **if** a switches from S_0^P to S_1^P **then**
- 9: time spent in $S_1^P == T_{S_1^P}^P$
- 10: **for** each transmission event **do**
- 11: calculate mean value of $T_{S_1^P}^P$ as (5)
- 12: **end for**
- 13: **end if**
- 14: **for** S_2^P **do**
- 15: assign the $\varsigma_{max}^P, \varsigma_{min}^P$ in S_2^P
- 16: compute mean value of $T_{S_2^P}^P$ using (6)
- 17: **end for**
- 18: **for** S_3^P && S_4^P **do**
- 19: calculate mean value of $T_{S_3^P}^P$ && $T_{S_4^P}^P$ using (7) && (8)
- 20: **end for**
- 21: **for** each a in $\mathcal{A} = \{m_1, m_2, m_3, \dots, m_A\}$ **do**
- 22: compute total time spent in the transition states as (9)
- 23: compute total mean as (10)
- 24: **end for**
- 25: **end for loop**
- 26: **for** $b = 1, \dots, B$ **do**
- 27: let $T_{S_n^Q}^Q$ denote time spent by each b in S_n^Q states
- 28: **for** S_0^Q **do**
- 29: compute mean value of $T_{S_0^Q}^Q$ using (11)
- 30: **end for**
- 31: **if** b switches from S_0^Q to S_1^Q **then**
- 32: time spent in $S_1^Q == T_{S_1^Q}^Q$
- 33: **if** \exists a transmission event **then**
- 34: compute mean value of $T_{S_1^Q}^Q$ as (12)
- 35: **else**
- 36: compute mean value of $T_{S_1^Q}^Q$ as (13)
- 37: **end if**
- 38: **end if**
- 39: **for** S_2^Q **do**
- 40: assign the $\varsigma_{max}^Q, \varsigma_{min}^Q$ in S_2^Q
- 41: calculate mean value of $T_{S_2^Q}^Q$ using (14)
- 42: **end for**
- 43: **for** $T_{S_3^Q}^Q$ && $T_{S_4^Q}^Q$ **do**
- 44: compute mean value of $T_{S_3^Q}^Q$ && $T_{S_4^Q}^Q$ using (15) && (16)
- 45: **end for**
- 46: **for** each b in $\mathcal{B} = \{n_1, n_2, n_3, \dots, n_B\}$ **do**
- 47: compute total time spent on the transition states as (17)
- 48: compute total mean value as (18)
- 49: **end for**
- 50: **for** all biomedical sensor devices in \mathcal{A} && \mathcal{B} **do**
- 51: compute total time spent on the transition states using (19) && (20)
- 52: compute total mean using (21) && (22)
- 53: **end for**
- 54: **for** all the biomedical devices in the two groups **do**
- 55: calculate Θ_{sum} using (23)
- 56: calculate \mathfrak{H}_{sum} using (24)
- 57: **end for**
- 58: **end for**
- 59: **end**
- 60: return Θ_{sum}
- 61: return \mathfrak{H}_{sum}

$$+ \varepsilon_{13}^P + (c + d - cd) \mu_{S_4^P}^P \varrho_4^P \quad (27)$$

$$E[\Phi_{Total}^Q] = T_{S_0^Q}^Q \varrho_0^Q + T_t \varrho_1^Q - (c + d - cd) \left(\frac{1}{2} T_t \varrho_1^Q \right) \quad (27)$$

$$+ \varepsilon_{01}^Q + c \left(\mu_{S_2^Q}^Q \varrho_2^Q + \frac{1}{B} \varrho_{Proc} \right) + \mu_{S_3^Q}^Q \varrho_3^Q \quad (28)$$

$$+ \varepsilon_{13}^Q + (c + d - cd) \mu_{S_4^Q}^Q \varrho_4^Q \quad (28)$$

Therefore, the total power consumed by all the biomedical devices A and B is computed from (25) and (26) in (29) and (30) as:

$$\sum_{a=1}^A \Phi_{Total}^P \quad \forall a, a = 1, 2, \dots, A \quad (29)$$

$$\sum_{b=1}^B \Phi_{Total}^Q \quad \forall b, b = 1, 2, \dots, B \quad (30)$$

Then, the total mean value of the power consumed by all the biomedical devices A and B is computed from (27) and (28) in (31) and (32) as:

$$\sum_{a=1}^A E[\Phi_{Total}^P] \quad \forall a, a = 1, 2, \dots, A \quad (31)$$

$$\sum_{b=1}^B E[\Phi_{Total}^Q] \quad \forall b, b = 1, 2, \dots, B \quad (32)$$

To calculate the overall power (\mathcal{J}_{sum}) consumed by all the biomedical devices in both groups P and Q , we combine (29) and (30) to derive (33).

$$\mathcal{J}_{sum} = \sum_{a=1}^A \Phi_{Total}^P + \sum_{b=1}^B \Phi_{Total}^Q \quad (33)$$

And the overall mean value (Υ_{sum}) of both group P and group Q is calculated in (34) as:

$$\Upsilon_{sum} = \sum_{a=1}^A E[\Phi_{Total}^P] + \sum_{b=1}^B E[\Phi_{Total}^Q] \quad (34)$$

To optimize the time spent by each biomedical sensor device in states $S_n^{P,Q} = \{S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}, S_4^{P,Q}\}$, we set a time constraint in (35) to allocate different time (t) to a biomedical device in the different state of $S_n^{P,Q}$ as:

$$t = t_0 + t_1 + t_2 + t_3 + t_4 = 1 \quad (35)$$

Also, to reduce the power spent by the devices in each state of $S_n^{P,Q} = \{S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}, S_4^{P,Q}\}$, we compute a power resource allocation solution to allocate an optimal power to a device in the different $S_n^{P,Q}$ states based on Algorithm 2.

Also, the power consumption computation scheme for the MG-HYMAC is present in Algorithm 3.

A. Complexity Analysis

To improve the proposed scheme (MG-HYMAC stochastic probability scheme), we optimize the time spent by each device in the different states of the system to reduce power consumption and increase the lifetime of the devices using Algorithm 2.

To investigate the implementation of the proposed scheme (i.e., MG-HYMAC) in real health devices, we analyze the time complexity of Algorithm 2. Basically, the time complexity of an algorithm is used to determine the execution time (i.e., speed) of an algorithm of an input size n [35].

$$+ c \left(\mu_{S_2^P}^P \varrho_2^P + \frac{1}{A} \varrho_{Proc} \right) + d \mu_{S_3^P}^P \varrho_3^P$$

Algorithm 2 A Heuristic-Based Power Control Scheme

```

1: Require: States  $S_n^{P,Q} = \{S_0^{P,Q}, S_1^{P,Q}, S_2^{P,Q}, S_3^{P,Q}, S_4^{P,Q}\}$  power allocation solution
 $\ell_n^{P,Q} = \{\ell_0^{P,Q}, \ell_1^{P,Q}, \ell_2^{P,Q}, \ell_3^{P,Q}, \ell_4^{P,Q}\}$ 
2: Initialize biomedical sensors in the five states
3: for  $a = 1, \dots, A$  in  $S_n^P = \{S_0^P, S_1^P, S_2^P, S_3^P, S_4^P\}$  do
4:   set  $t = t_0 + t_1 + t_2 + t_3 + t_4 = 1$ 
5:   compute  $\ell_0^P \ni t_0 = [0, 1]$  &&  $P_{min} \leq \ell_0^P \leq P_{max}, \forall a \in S_0^P$ 
6:   compute  $\ell_1^P \ni t_1 = [0, 1]$  &&  $P_{min} \leq \ell_1^P \leq P_{max}, \forall a \in S_1^P$ 
7:   compute  $\ell_2^P \ni t_2 = [0, 1]$  &&  $P_{min} \leq \ell_2^P \leq P_{max}, \forall a \in S_2^P$ 
8:   compute  $\ell_3^P \ni t_3 = [0, 1]$  &&  $P_{min} \leq \ell_3^P \leq P_{max}, \forall a \in S_3^P$ 
9:   compute  $\ell_4^P \ni t_4 = [0, 1]$  &&  $P_{min} \leq \ell_4^P \leq P_{max}, \forall a \in S_4^P$ 
10: end for
11: for  $b = 1, \dots, B$  in  $S_n^Q = \{S_0^Q, S_1^Q, S_2^Q, S_3^Q, S_4^Q\}$  do
12:   set  $t = t_0 + t_1 + t_2 + t_3 + t_4 = 1$ 
13:   compute  $\ell_0^Q \ni t_0 = [0, 1]$  &&  $P_{min} \leq \ell_0^Q \leq P_{max}, \forall b \in S_0^Q$ 
14:   compute  $\ell_1^Q \ni t_1 = [0, 1]$  &&  $P_{min} \leq \ell_1^Q \leq P_{max}, \forall b \in S_1^Q$ 
15:   compute  $\ell_2^Q \ni t_2 = [0, 1]$  &&  $P_{min} \leq \ell_2^Q \leq P_{max}, \forall b \in S_2^Q$ 
16:   compute  $\ell_3^Q \ni t_3 = [0, 1]$  &&  $P_{min} \leq \ell_3^Q \leq P_{max}, \forall b \in S_3^Q$ 
17:   compute  $\ell_4^Q \ni t_4 = [0, 1]$  &&  $P_{min} \leq \ell_4^Q \leq P_{max}, \forall b \in S_4^Q$ 
18: end for
19: end

```

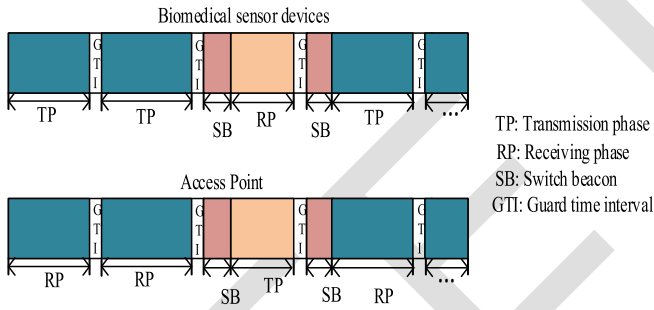


Fig. 3. The proposed MG-HYMAC protocol slot allocation.

421 For this to be achieved, we applied the Big-O (O) notation
422 and the time complexity of Algorithm 2 is $O(A + B)$. Thus,
423 Algorithm 2 has a linear time complexity. Now, we further
424 validate our contribution with respect to HyMAC and CPMAC
425 and we discovered that our proposed scheme has a similar lin-
426 ear time complexity with both HyMAC and CPMAC. But then,
427 the proposed scheme requires a smaller computational time
428 compared to both HyMAC and CPMAC. This contribution
429 makes the proposed scheme more efficient for implementation
430 in real health devices.

VI. DESCRIPTION OF THE PROPOSED MG-HYMAC PROTOCOL OPERATIONS

433 In this section, we describe the operations of the pro-
434 posed MG-HYMAC protocol and the wake-up scheme that
435 we employed to reduce energy consumption. The biomedical
436 sensor in the network performs two major operations such
437 as the transmission of health data to the AP as well as the
438 reception of control signals from the AP. Consequently, the
439 AP acts as a gateway to the internet and can also send
440 data, including health data, query requests/health alert or
441 configuration changes from the healthcare service providers
442 to the biomedical sensors [36]. In this work, we assume that

Algorithm 3 MG-HYMAC Power Consumption Computation Scheme

```

1: Require:  $\ell_n^{P,Q} = \{\ell_0^{P,Q}, \ell_1^{P,Q}, \ell_2^{P,Q}, \ell_3^{P,Q}, \ell_4^{P,Q}\}$  power  

consumed by the devices,  $\varepsilon_{01}^{P,Q}, \varepsilon_{13}^{P,Q}, \tau_s, \tau_r, \Phi_{Total}^P$  &&  $\Phi_{Total}^Q$   

total power consumed by a device in group  $P$  and group  $Q$ 
2: Initialize biomedical sensors in the five states ( $S_n^{P,Q}$ )
3: for  $a = 1, \dots, A, b = 1, \dots, B$  do
4:   compute the total power consumption using (22) && (26)
5:   compute the mean value of  $\Phi_{Total}^P$  &&  $\Phi_{Total}^Q$  using (27)  

&& (28)
6:   if  $\exists$  a transmission event then
7:     assign 1
8:   else
9:     assign 0
10:  end if
11:  for  $A$  &&  $B$  do
12:    compute the total power consumed using (29) && (30)
13:    compute the mean of the total power consumed  

using (31) && (32)
14:  end for
15:  for the overall power consumption of group  $P$  && group  

 $Q$  do
16:    compute  $\mathcal{J}_{sum}$  using (33)
17:    compute  $\Upsilon_{sum}$  (34)
18:  end for
19: end for
20: end
21: return  $\mathcal{J}_{sum}$ 
22: return  $\Upsilon_{sum}$ 

```

443 the major function of the biomedical devices is to transmit
444 sensed health data to the AP, and so we assign most of the time
445 slots to the biomedical devices for health data communication.
446 However, to guard against overlapping in time slots when the
447 AP tries to send control signals to the biomedical sensors,
448 a GTI is applied, and a SB message is sent first at the end
449 of AP's receiving phase before transmission can take place as
450 described in Fig. 3.

451 The two major operations of the biomedical sensor devices
452 are discussed in detail in the following subsection.

A. Wake-Up Scheme

453 A wake-up radio is a special type of radio attachable with
454 the main radio circuit of the biomedical device to trigger off
455 its main radio when it is not transmitting data to circumvent
456 unnecessary power wastage, such as idle listening. A wake-up
457 radio can be used to monitor the environment as well as sense
458 any incoming control signals from the AP and generate an
459 interrupt signal to switch on/off the main radio [37] and [38].

460 There are two types of wake-up radios, namely active and
461 passive wake-up radios. The active wake-up radio consumes
462 more energy compared to the passive wake-up radio. The
463 passive wake-up radio can harvest energy from the incoming
464 wake-up signals and does not use the energy of the biomedical
465 sensors [3] and [39]. A passive wake-up radio only consumes
466 about $50 \mu W$ energy [3] and [40] which makes it reasonable
467 for a WBAN system.

468 In our proposed system, we equipped the biomedical devices
469 with a passive wake-up radio to improve the efficiency of the
470 biomedical devices and we assume the power of the wake-up
471

radio to be negligible since it relies on power harvesting. Note, at the beginning of a cycle we assume that all the biomedical devices are in the sleep state and when the AP sends the request to receive (RTR) beacon, the wake-up radio immediately generate an interrupt signal to switch on the main radio of the biomedical devices, then the devices that have health data packet to transmit contend for transmission slots, while others with no health data packets goes into the sleep state.

B. Transmission Phase of the Biomedical Sensors

In this phase, we discuss the operations of the hybrid CSMA/CA+TDMA scheme as follows.

1) *CSMA/CA Period*: At the beginning of the CSMA/CA period which can also be called the contention period, RTR beacon is sent by the AP to all the biomedical sensor devices in the network informing them of its availability to receive health data. Thereafter, only the biomedical devices that have health data to transmit will contend for transmission opportunities based on their own CW length. Other biomedical devices that have no packets to transmit goes into the sleep state to save energy.

The contending biomedical devices will send a request to transmit (REQ-T) message randomly to the AP. If more than one device sends the REQ-T messages simultaneously to the AP without a GTI, there is a likelihood of collision occurrence. However, if only one device sends the REQ-T message to the AP at a given time, contention is successful.

Each successful contended device's health data contains its own information, such as the device ID number. This unique number is useful during communication with the AP. To conserve energy, the AP broadcast an overall acknowledgment (O_{ACK}) message to all the biomedical devices at the end of the contention period or CSMA/CA period informing them about the reception of their health data packets rather than sending the message each time it received their data packets. In addition, the O_{ACK} message contains the biomedical sensor devices order of transmission such that each device is given a specific time slot by the AP for its health data transmission during the TDMA phase. Furthermore, the O_{ACK} sent by the AP helps to reduce the delay often experienced at the biomedical sensor's side, such as the transmission congestions and waiting time, resulting to a shorter delay compared to the conventional ACK used in most literature.

2) *TDMA Period*: As said earlier, we introduce a WO state in this phase. The WO state is regarded as a kind of idle state in which only the synchronous clock of a biomedical sensor device in this state is enabled while all other operations are disabled to save energy. A device is activated from the WO state to any other active states only through active beacons with the device ID. A biomedical sensor device switches to an active state promptly immediately it receives an active message from the AP or when it wants to transmit health data packets to the AP.

During health data packet transmission, the biomedical sensor devices are modelled using a transmission queue and they transmit their health data after a successful contention. The AP knows all the biomedical sensor devices in the network

within its coverage zone, just like a Wi-Fi router having knowledge of all the biomedical devices connected to it, and therefore serves as a global controller.

Consequently, each biomedical sensor device sends an end beacon to the AP at the end of its health data packet transmission and the AP sends them an ACK-order message upon a successfully received health data packet, while no ACK-order message will be sent in the case of a failed health data packet transmission.

In the case of a failed health data packet transmission, a biomedical sensor device will transmit a retransmission beacon to prepare the AP for the retransmission process and the AP sends an ACK-order message after receiving an end beacon from a device. Once the transmitting biomedical sensor device receives an ACK-order message, the next device in the transmission queue starts its data packet transmission and the process continues until the end of operations of the CSMA+TDMA scheme when all the biomedical devices having health data packets to transmit have successfully send their health data packets to the AP.

C. Reception Phase of the Biomedical Sensor Devices

In this phase, the AP is the one transmitting command messages/signals to the devices. The phase can be described as the TP of the AP and the receiving phase of the devices. The TDMA scheme with WO slots is employed for transmissions in this phase. The AP starts its operation in this phase by broadcasting a wake to receive (WTR) beacon to all the biomedical devices to ensure they are in the active state as well as to prepare them for data reception.

To save energy in this phase, only the first biomedical device in the WO slots will be active to receive the WTR beacon and is set ready to receive data from the AP, while others remain in the WO state. Note, each device ID is included in the WRT. Following the reception of this signal, the biomedical device transmits an ACK message to the AP and thereafter enters the sleep state to conserve energy.

An interval guard time is introduced to prevent overlapping of any two adjacent transmission slots, i.e., overlapping between two data transmissions. For the next biomedical device in the WO slot to receive data from and/or communicate with the AP, the AP will first have to send a switching WO (SWO) beacon containing the device's ID and an active beacon to the biomedical device. Thereafter, the device will switch from the WO state to the receiving state.

In the case of a failed data reception, the biomedical device enters the WO state and no ACK message will be sent to the AP and thus, the AP knows that the transmission has failed. Afterward, the AP sends the SWO to the next biomedical device in the WO slot before transmitting another data. After the completion of all data transmissions, the AP then starts the retransmission process. The retransmission process is done at the end of all transmissions to reduce the WO time and to also minimize the overall wake-up time to save energy.

For further insights into the operation of the proposed multi-group hybrid MAC protocol, Algorithm 4 details the process of the protocol.

Algorithm 4 Operation of the Proposed MG-HYMAC

```

1: Initialize biomedical devices that have data to send in groups
    $P$  and  $Q$ 
2: Ensure an optimal CW length:  $CW_{min} \leq CW \leq CW_{max}$ 
3: for the beginning of a cycle do
4:   apply a CSMA/CA protocol
5:   assign a WO to successfully contended devices
6: end for
7: Go to TP
8: for successfully contended biomedical devices in  $A$  and  $B$  do
9:   allocate a TDMA slot based on the WO/transmission queue
10:  transmit health data packets to the AP
11:  for each successfully received health data packets do
12:    send an ACK-order message to the device
13:  end for
14:  for each failed transmission do
15:    set a back-off time
16:    let the device stay in the WO state
17:  end for
18: end for
19: if this is the end of the TP then
20:   enable retransmission process
21: repeat step 7 to 15 for all failed transmissions
22:   until an ACK-order message is received
23: end if
24: end

```

VII. SIMULATION RESULTS

We present and discuss the simulation results of the proposed MG-HYMAC protocol in this section.

A. Simulation Configuration

The proposed system follows a typical WBAN system with several biomedical devices implanted or deployed around a patient's body. In the simulation experiments, we considered different number of biomedical devices in a star topology to connect them directly to an AP. The proposed MG-HYMAC protocol was simulated in MATLAB and compared with the HyMAC and the CPMAC protocols.

The same simulation configuration values employed in the baseline HyMAC protocol (i.e., [32]) as shown in Table II are also assumed in this work to configure and evaluate the performance of proposed MG-HYMAC protocol.

We considered different number of devices such as 3, 5, 7, 9 in proposed MG-HYMAC protocol. Fig. 4 shows the star topology and the location of the biomedical sensor devices deployed in a random manner in the coverage area of an AP with a radius of 500 m using a coordinate system.

Furthermore, the proposed system comprises of a multi-group, including groups P and Q . We assume that group P contains A biomedical sensors with h_A critical health data packets while, group Q contains B biomedical sensors with h_B less-critical health data packets.

For evaluation and validation, we compare the proposed MG-HYMAC protocol with the existing HyMAC and CPMAC protocols and standard metrics like the convergence speed, energy efficiency, and the lifetime of the devices are applied.

B. Convergence Comparison

In this section, the performance of the proposed MG-HYMAC protocol and the existing protocols are inves-

TABLE II
SIMULATION PARAMETER VALUES [32]

Parameter	Value
AP radius	500m [3]
Number of biomedical sensors	(3-15)
Battery power	1200 J
Transmission rate (\mathfrak{R})	5 Mbps
ACK packet size	64 bits
Guard time interval	0.00003 sec
Beacon size	64 bits
Minimum CW	32
Maximum CW	256
Maximum power consumed in $S_0^{P,Q}(\varrho_0^{P,Q})$	0.5 mW
Maximum power consumed in $S_1^{P,Q}(\varrho_1^{P,Q})$	10.5 mW
Maximum power consumed in $S_2^{P,Q}(\varrho_2^{P,Q})$	28 mW
Maximum power consumed in $S_3^{P,Q}(\varrho_3^{P,Q})$	30 mW
Maximum power consumed in $S_4^{P,Q}(\varrho_4^{P,Q})$	50 mW
$\epsilon_{01}^{P,Q}$	0.02 mJ
$\epsilon_{13}^{P,Q}$	0.03 mJ
Noise	-100dBm

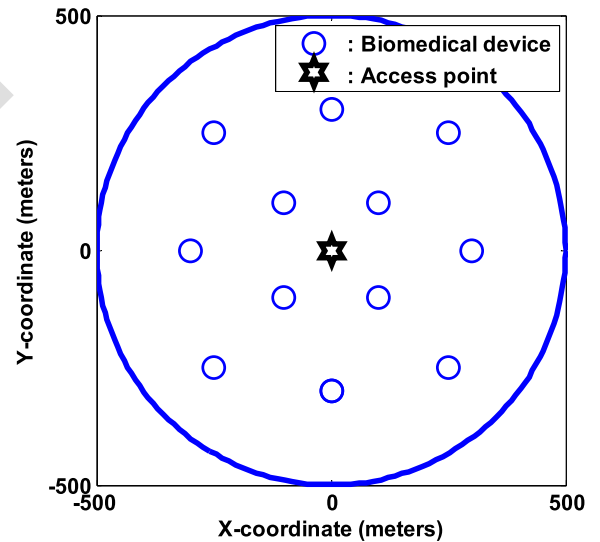


Fig. 4. Proposed network topology of biomedical devices and an access point.

tigated based on convergence speed. The convergence performance evaluation of the three protocols were carried out by investigating the energy consumption of the three protocols versus the number of iterations. To achieve this, we configure the proposed MG-HYMAC protocol with $K = 9$ devices, and we set $A = 5$ devices and $B = 4$ devices for groups P and Q respectively, while the existing protocols were configured with 9 devices in parallel. In addition, we consider different number of iterations, and based on the configurations we performed some simulation experiments and the results generated are presented in Fig. 5. From Fig. 5, we observed that the proposed MG-HYMAC algorithm outperformed the existing algorithms as it converges after about 60 iterations unlike the HyMAC and the CPMAC algorithms that converged

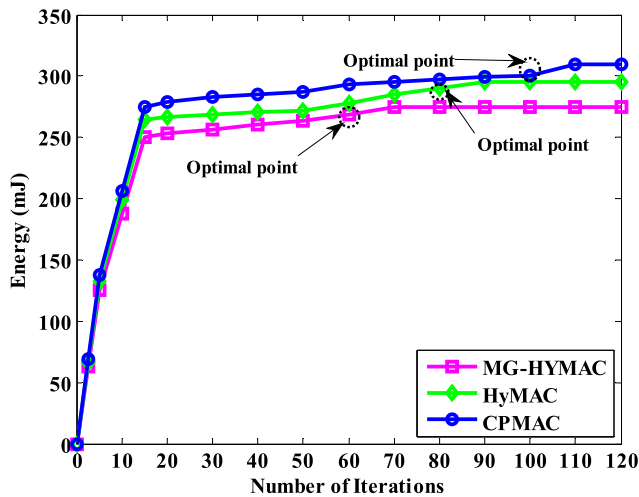


Fig. 5. Convergence of the MG-HYMAC, HyMAC, and CPMAC algorithms.

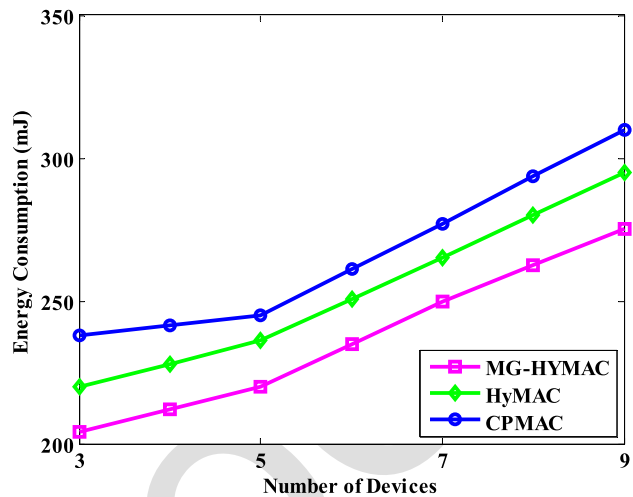


Fig. 6. Energy consumption versus number of devices.

631 after about 80 and 100 iterations, respectively. Therefore,
 632 it is evident that the MG-HYMAC algorithm has a better
 633 convergence speed compared to the existing protocols and has
 634 performance improvements of about 12% over the HyMAC
 635 and 3% over the CPMAC and this emphasize the efficiency
 636 of the proposed protocol in terms of fast convergence.

637 **C. Investigation of Energy Efficiency Performance Based**
 638 **on the Number of Devices**

639 In this section, we carried out some simulation investiga-
 640 tions on the proposed MG-HYMAC protocol and the existing
 641 protocols, i.e., HyMAC and CPMAC to study their perfor-
 642 mance in terms of energy efficiency. For this reason, we stud-
 643 ied and compared the energy consumption of the devices in
 644 a complete transmission cycle, including both the TP and
 645 the RP. For this to be achieved, we configure the proposed
 646 MG-HYMAC and the existing protocols with different number
 647 of biomedical devices, including $K = 3, 5, 7,$ and 9 devices.
 648 For the proposed MG-HYMAC protocol, when $S = 9$ devices,
 649 A was set to 5 devices for group P and B was set to 4 devices
 650 for group Q and we assume that not all the devices in group
 651 Q have data packets to send. In addition, the transmission
 652 probability for the three protocols were set to $c = 0.8$ and $d =$
 653 0.8 . Based on these configurations, we enabled the proposed
 654 algorithms for the MG-HYMAC protocol and disabled them
 655 for the HyMAC and CPMAC protocols and simulated the three
 656 protocols. The obtained simulation results are presented for the
 657 three protocols in Fig. 6. From Fig. 6, it was noticed that the
 658 more we increase the number of devices in the network from 3,
 659 5, 7 to 9 devices, the more the energy consumption. But then,
 660 the proposed MG-HYMAC protocol was able to achieve a
 661 reasonable reduction in the amount of energy consumed by the
 662 biomedical devices compared to the HyMAC and the CPMAC
 663 protocols. For instance, when the number of devices in the
 664 network was set to 3, about 204 mJ energy was consumed
 665 using the proposed MG-HYMAC protocol, while using the
 666 HyMAC and the CPMAC protocols about 220 mJ and 238 mJ
 667 energy were consumed, respectively. This is an indication that
 668 the proposed MG-HYMAC protocol is more energy efficient

669 by achieving an energy reduction of about 7% when compared
 670 to the HyMAC protocol and about 14% energy reduction
 671 when compared to the CPMAC protocol. The performance
 672 improvement of the MG-HYMAC protocol over the HyMAC
 673 and CPMAC protocol was due to the introduced transmission
 674 scheduling policy used to duty cycle the operations of the
 675 biomedical devices with less critical data packets. It helped
 676 to reduce energy wastage due to collisions and idle listening
 677 and consequently assisted in saving energy and prolonging
 678 the battery lifetime of the biomedical sensor devices as well
 679 as improving the overall network lifetime. Also, the intro-
 680 duced sleep-wake-up scheduling mechanism helped to address
 681 energy wastage due to overhearing by only switching on the
 682 biomedical devices for data transmission and reception and
 683 goes into sleep mode afterward.

684 **D. Investigation of Energy Efficiency Performance Based**
 685 **on Transmission Probability**

686 This section presents the simulation investigations of the
 687 MG-HYMAC protocol and the baseline protocols on energy
 688 consumption against the transmission probability of the
 689 devices. To achieve this, we configure the MG-HYMAC
 690 and the baseline protocols with $K = 7$ devices. For the
 691 MG-HYMAC protocol, when $K = 7$ devices, A was set to
 692 4 devices for group P and B was set to 3 devices for group
 693 Q , but we assume that not all the devices in group Q have
 694 data packets to send. The outcomes of the simulations are
 695 presented in Fig. 7. From Fig. 7, it can be inferred that the
 696 higher the transmission probability the more the energy
 697 consumed. However, the proposed MG-HYMAC protocol outper-
 698 forms the existing protocols as it achieves a significant
 699 reduction in the amount of energy consumed by the devices.
 700 For example, when the transmission probability of the devices
 701 was set to 0.1 and 0.2, about 190 mJ and 205 mJ energy
 702 were consumed respectively using the proposed MG-HYMAC
 703 protocol, when the HyMAC protocol was applied, about 205
 704 mJ and 220 mJ energy were consumed respectively, while
 705 about 206 mJ and 222 mJ energy were consumed respectively
 706 using the CPMAC protocol. Also, we noticed that at the
 transmission probability

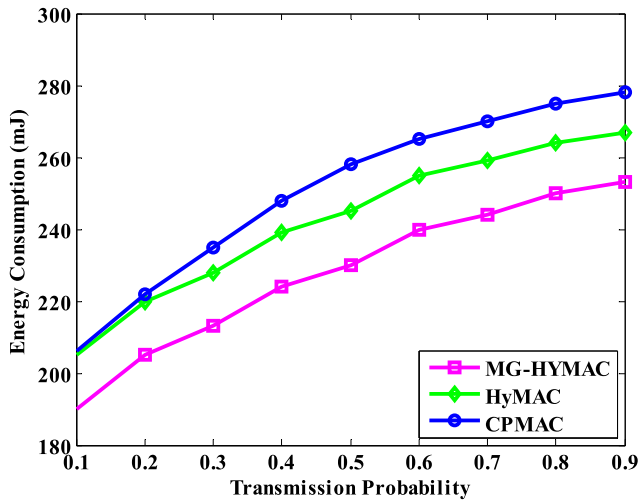


Fig. 7. Energy consumption versus transmission probability.

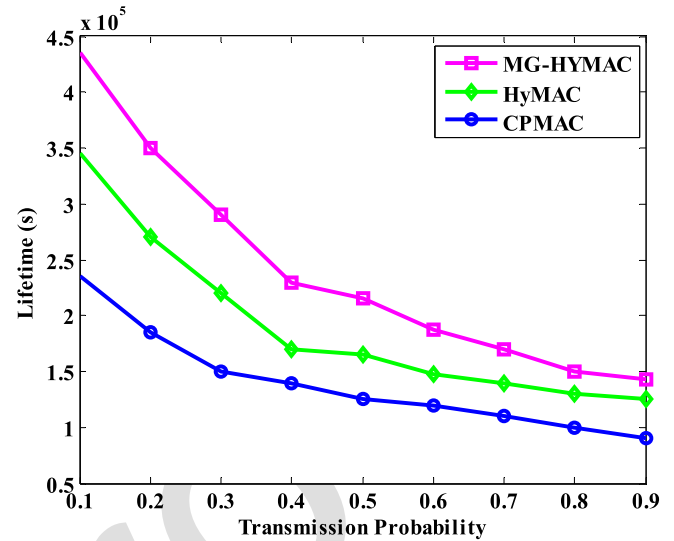


Fig. 8. Devices lifetime versus transmission probability.

of 0.1 and 0.2, the existing protocols have almost the same amount of energy consumption. Following this, we could infer that the proposed protocol is advantageous in terms of saving energy as it is able to achieve an energy reduction of about 7% compared to the HyMAC protocol and about 8% compared to the CPMAC protocol. These energy efficiency performance improvements are attributed to the proposed algorithms which were able to minimize energy wastage issues, such as collision, idle listening, and overhearing during data communication. Furthermore, the obtained improvements by the proposed MG-HYMAC protocol could be attributed to its efficiency in harnessing the advantages of both the CSMA/CA protocol and the TDMA protocol to efficiently make use of each time slot to reduce collisions during data communications for small scale network. In addition, energy wastage is reduced, and energy efficiency is improved by assigning most transmission overhead to the AP side since it can be charged easily.

E. Comparison of Devices Lifetime Based on Transmission Probability

In this section, we studied the lifetime performance of the biomedical devices against the transmission probability. Simulation investigations were performed on the proposed MG-HYMAC and the existing protocols (i.e., HyMAC [32] and CPMAC [31]) using different values of transmission probability to study its impact on the lifetime of the biomedical sensor devices. We set $K = 7$ devices and the battery power to be 1200 J for the three protocols. While we configure the proposed protocol with $A = 4$ devices for group P and $B = 3$ devices for group Q . Based on these configurations, the three protocols were simulated, and the obtained results are presented in Fig. 8. According to Fig. 8, we noticed that high transmission probability resulted into a decrease in the lifetime of the devices for the three protocols. But then, the proposed protocol improved the lifetime performance of the biomedical devices. For example, when the transmission probability was set to 0.4, our proposed protocol was able to achieve a prolonged lifetime of about 230,000 seconds, when the HyMAC protocol was applied, a lifetime of about 170,000

seconds was achieved, also, when the CPMAC protocol was applied, a lifetime of about 140,000 was achieved. This implies that significant improvements of about 35% and 64% were achieved by the MG-HYMAC over the HyMAC and the CPMAC protocols, respectively. The achieved improvements are attributable to the developed stochastic probability model and the heuristic-based power control scheme that were employed to solve time allocation and power control problems to enhance energy efficiency and prolong the lifetime of the devices. In addition, the introduced transmission scheduling technique for duty cycling the operations of the biomedical sensor devices with less critical data packets helped to reduce collisions in order to save energy and prolong the battery lifetime of the biomedical sensor devices so as to improve the overall network lifetime.

F. Impact of High Number of Devices on Energy Efficiency

In this section, we perform different experiments on the MG-HYMAC protocol and the existing protocols to investigate the performance of the MG-HYMAC protocol in terms of energy efficiency based on the impact of high number of biomedical sensor devices. To achieve this, we configure the proposed MG-HYMAC and the existing protocols with $K = 9, 11, 13,$ and 15 devices. For the proposed MG-HYMAC protocol, when $K = 9, 11, 13,$ and 15 devices, we set $A = 5, 6, 7,$ and 8 devices, respectively for group P and we set $B = 4, 5, 6,$ and 7 devices, respectively for group Q . Also, the transmission probability for the three protocols was set to $c = 1$ and $d = 1$. Following this, we enabled the proposed algorithms for the MG-HYMAC protocol and disabled them for the HyMAC and CPMAC protocols during the experiments. The obtained results are presented in Fig. 9 and we observed from the figure that the number of devices in the network directly influences the amount of energy consumed. For a large-scale network, the energy consumption of the devices tends to increase more due to the possibility of an increase in the number of collisions. However, the proposed MG-HYMAC

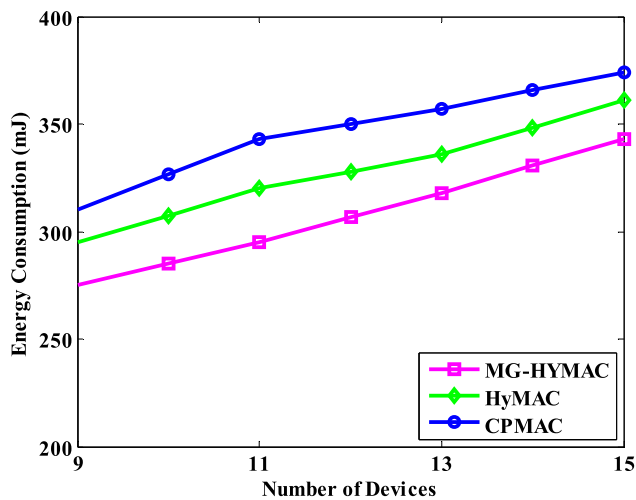


Fig. 9. Energy consumption versus number of devices for $K = 15$ devices.

782 protocol outperformed the existing protocols based on the
 783 proposed algorithms which were able to allocate efficiently
 784 specific time slots to the devices to reduce collisions and
 785 save energy. For instance, when the number of devices in the
 786 network was increased from 9 to 11, about 295 mJ energy
 787 was consumed using the proposed MG-HYMAC protocol,
 788 when the HyMAC and the CPMAC protocols were used
 789 about 320 mJ and 343 mJ amount of energy were consumed,
 790 respectively. This indicates that the proposed MG-HYMAC
 791 protocol achieved improvements of about 8% over the HyMAC
 792 protocol and about 14% over the CPMAC protocol. These
 793 improvements emphasize the efficiency of the proposed MG-
 794 HYMAC protocol.

795 **G. Impact of Low Transmission Probability on Energy**
 796 **Efficiency**

797 In this section, we investigate the impact of low transmission
 798 probability on energy efficiency for the proposed protocol and
 799 the existing protocols. During the experiments, we set $K = 9$
 800 devices for the three protocols, and for the MG-HYMAC
 801 protocol we set $A = 5$ devices for group P and $B = 4$
 802 devices for group Q . Based on the simulation performed,
 803 the obtained results are described in Fig. 10. We tried to
 804 compare the results in Fig. 10 involving a low transmission
 805 probability to when the transmission probability is high in
 806 Fig. 8 and we noticed that the energy consumed by the
 807 devices for a low transmission probability is reduced. Also,
 808 from Fig. 10, it is noticed that the proposed MG-HYMAC
 809 protocol performs better than the existing protocols in the
 810 context of energy efficiency. For example, at a transmission
 811 probability of 0.05, about 107 mJ energy was consumed when
 812 the proposed protocol was applied, while about 119 mJ and
 813 120 mJ energy were consumed when the HyMAC and CPMAC
 814 protocols were applied, respectively. This shows that the pro-
 815 posed protocol is energy efficient with improvements of about
 816 10% and 11% over the HyMAC protocol and the CPMAC
 817 protocol, respectively. These improvements are contributed by
 818 the algorithms we proposed as well as the introduced WO state
 819 for saving energy without incurring any transmission delay.

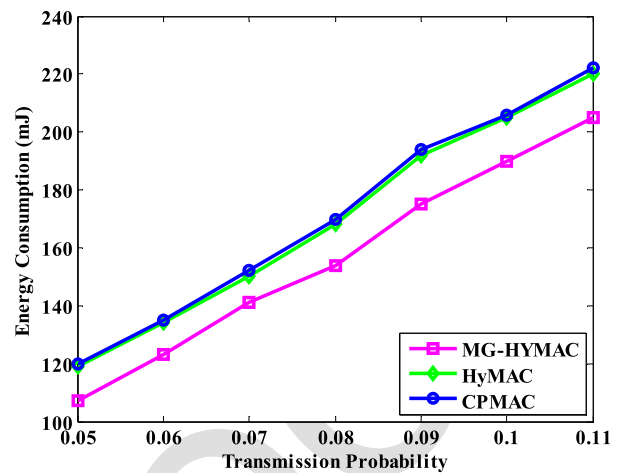


Fig. 10. Energy consumption versus low transmission probability.

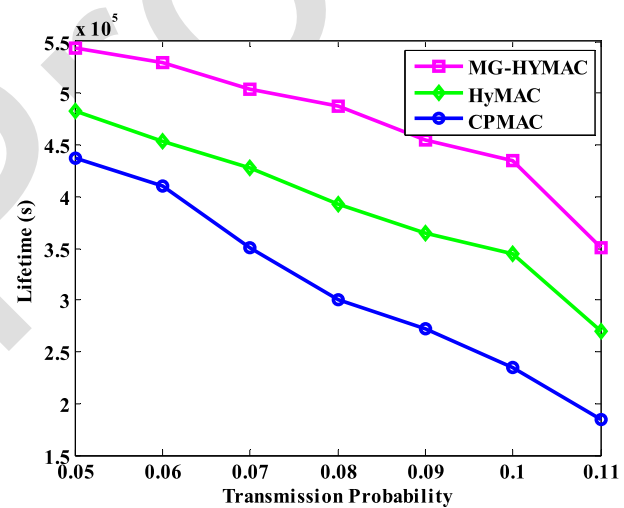


Fig. 11. Device Lifetime versus low transmission probability.

820 **H. Impact of Low Transmission Probability on the**
 821 **Lifetime of the Devices.**

822 The impact of low transmission probability on the lifetime
 823 of the proposed protocol and the existing protocols are studied
 824 in this section. We consider a configuration of $K = 9$ devices
 825 and a battery power of 1200 J for the three protocols. The
 826 proposed protocol was configured with $A = 5$ devices for
 827 group P and $B = 4$ devices for group Q when $K =$
 828 9. Based on these, the three protocols were simulated, and
 829 the obtained results are reported in Fig. 11. Comparing the
 830 results in Fig. 11 to the results of when the traffic in the
 831 network was high as in Fig. 9, we noticed a rapid increase
 832 in the lifetime of the biomedical sensor devices for the three
 833 protocols. Note, for low traffic, the energy efficiency of the
 834 network is enhanced and this in turn prolongs the lifetime of
 835 the biomedical sensor devices. We also observe from Fig. 11
 836 that the proposed protocol outperforms the existing protocols.
 837 As an example, when the transmission probability was set to
 838 0.05, the proposed protocol had a lifetime of about 544,000
 839 seconds compared to the HyMAC protocol with a lifetime
 840 of about 483,000 seconds and the CPMAC protocol with a
 841 lifetime of about 437,000 seconds. This means that the pro-
 842 posed MG-HYMAC is more efficient with performance gains

of about 13% and 24% over the HyMAC protocol and CPMAC protocol, respectively. These performance gains are engineered by the stochastic probability model and the heuristic-based power control scheme we employed to solve time allocation and power control problems to enhance energy efficiency and prolong the lifetime of the devices. Also, the introduction of a transmission scheduling technique to duty cycle the operations of the biomedical sensor devices with less critical data packets to determine when and how the biomedical sensor devices will transmit their health data packets to reduce collisions in order to save energy and prolong the battery lifetime of the biomedical sensor devices so as to improve the overall network lifetime.

VIII. CONCLUSION

An energy-aware multi-group hybrid MAC protocol for health data communications has been proposed for a personalized WBAN system in this paper. To achieve an energy efficient data communication, we combined the benefits of the CSMA/CA protocol and the TDMA protocol, set the major transmission overhead to the AP side, and introduced a WO state. Also, we employed a sleep-wake-up scheduling mechanism which helped in saving a significant amount of energy and increasing the devices lifetime. A transmission scheduling technique was introduced to duty cycle the operations of the devices that have less critical data packets to determine when and how the biomedical sensor devices will transmit their health data packets to optimize their power consumption and prolong their battery lifetime in an attempt to improve the overall network lifetime. Furthermore, we developed a stochastic probability model and a power control model to solve time allocation and power control problems to enhance energy efficiency and prolong the lifetime of the devices. We validated the proposed MG-HYMAC protocol based on energy efficiency, lifetime of the biomedical sensor devices, and speed of convergence. Going by the simulation results, the proposed MG-HYMAC protocol proved to be more efficient when compared to the HyMAC and CPMAC protocols using the above-mentioned metrics.

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