

# Void-creating algorithms for fixed packet length in OPS/OBS

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# Overview presentation

- Contention resolution & scheduling basics
- Void-creating scheduling algorithm
- Performance results
- Conclusions

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# The optical backbone

demand for bandwidth ↗



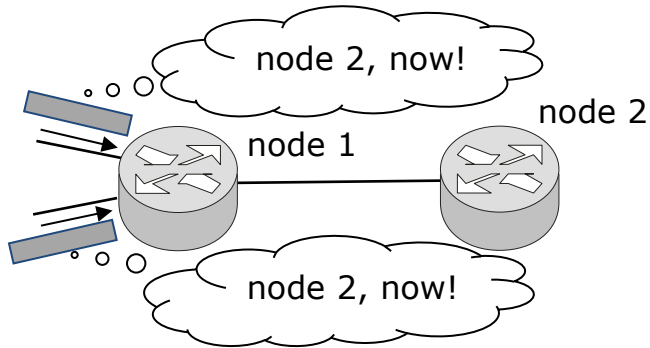
**Future:** packet-based switching

- shared links
  - ✓ improved usage of fiber capacity
- contention possible
    - ✗ potentially, packet loss
    - ✗ no fixed delay
    - ✗ potentially, substantial delay



**main motivation of this work:  
improving contention resolution**

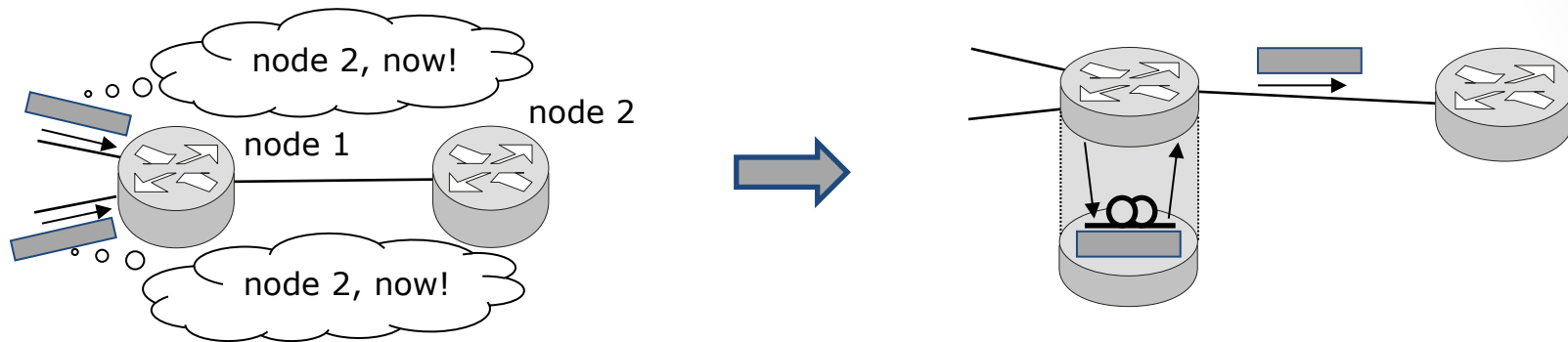
# Contention & resolution



## Arrival process

- single wavelength
- fixed packet lengths  $B$
- exponentially distributed interarrival times (Poisson)

# Contention & resolution



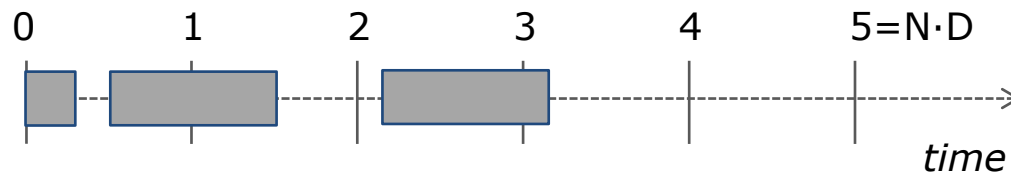
## Arrival process

- single wavelength
- fixed packet lengths  $B$
- exponentially distributed interarrival times (Poisson)

## Fiber Delay Lines ( FDLs)

- set of fibers,  $\# = N+1$
- lengths  $j \cdot D$ ,  $j=0 \dots N$
- $N$ = buffer size
- $D$ = granularity = packet length =  $B$

# Provisional schedule



- shows already scheduled packets upon arrival of a packet
- horizontal axis: future time
- vertical lines: delays of FDLs ( $N=5$ ,  $D=1$ )
- updated at every arrival
- choppy but uniform movement of all packets to the left

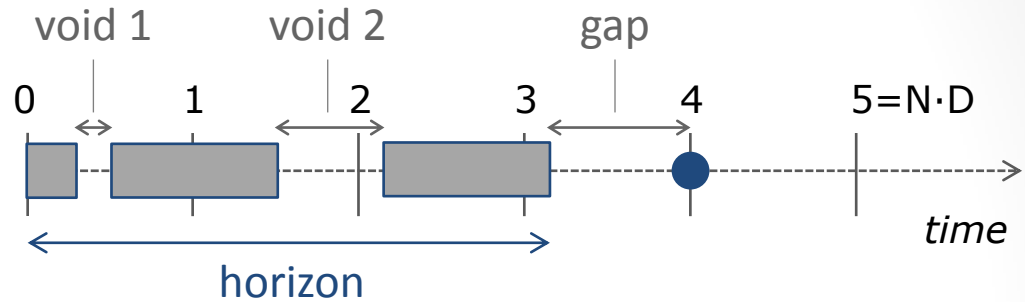
# Provisional schedule

## choose:

- delay line  $j$  ( $j=0\dots N$ )

## constraints:

- no overlap



**current algorithms:** ● : first FDL after horizon



no fillable voids are created  
(=voids larger than packet length  $B=D$ )



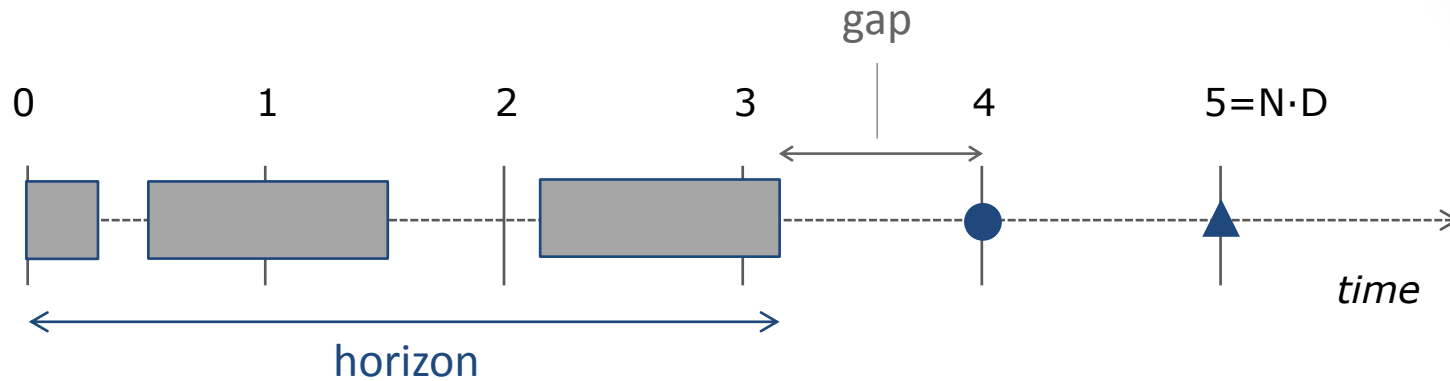
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# Void-creating scheduling algorithms



choose between

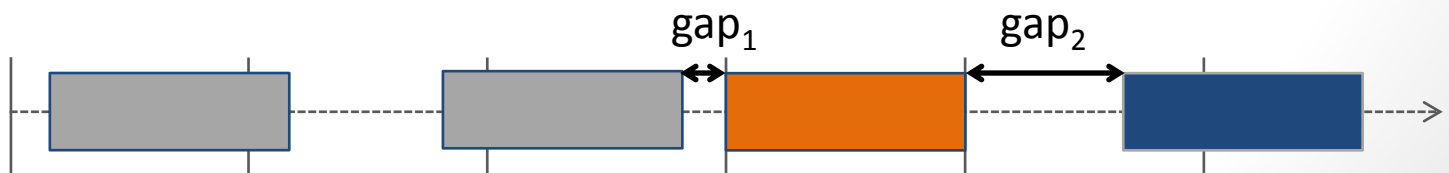
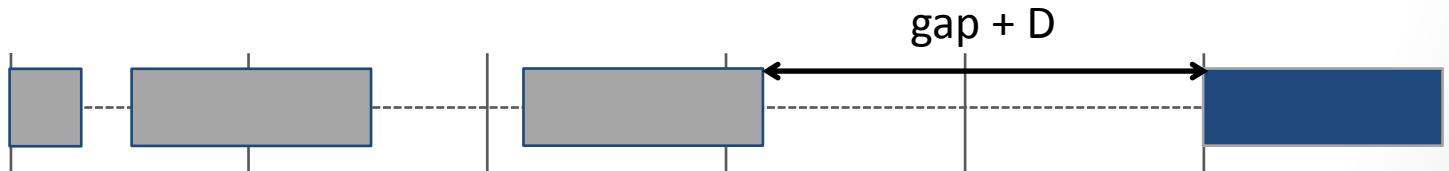
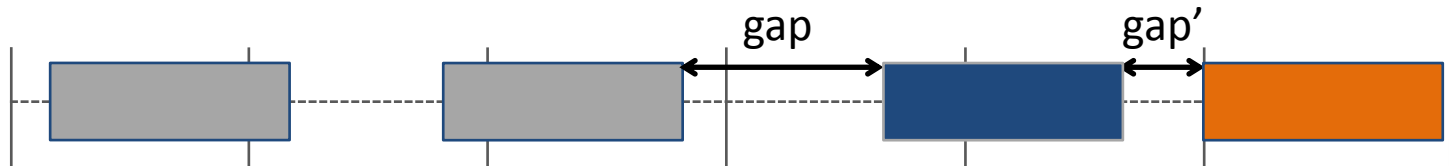
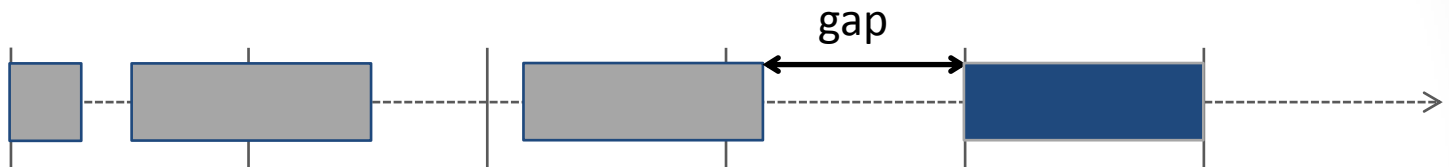
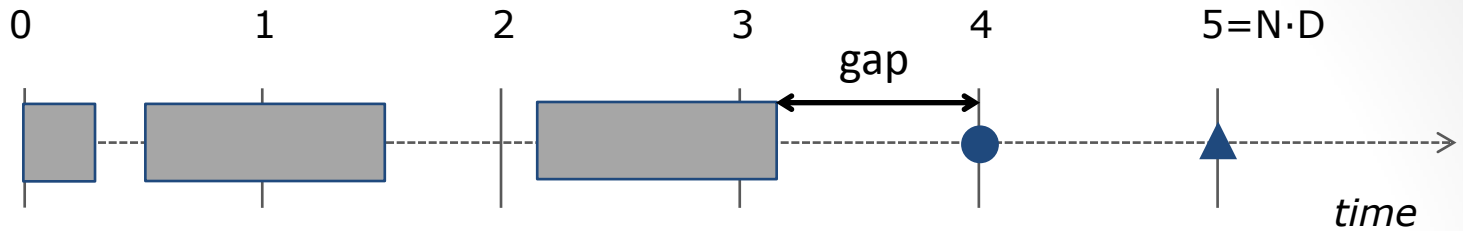


- normal scheduling point
- first FDL after horizon
- creates unfillable void

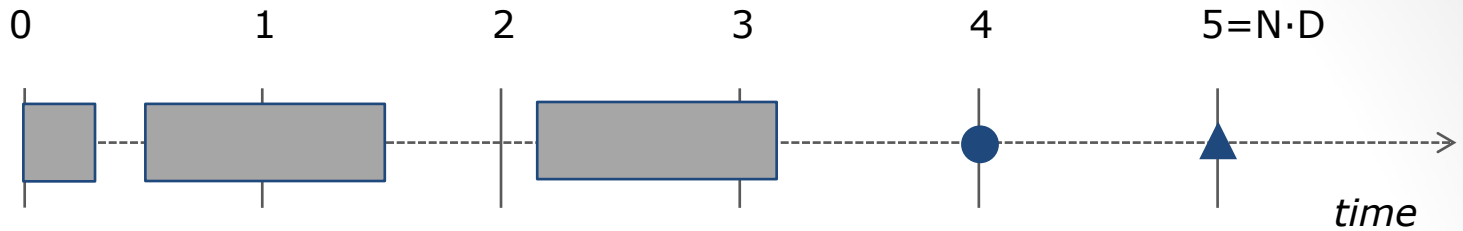


- alternative scheduling point
- second FDL after horizon
- creates fillable void

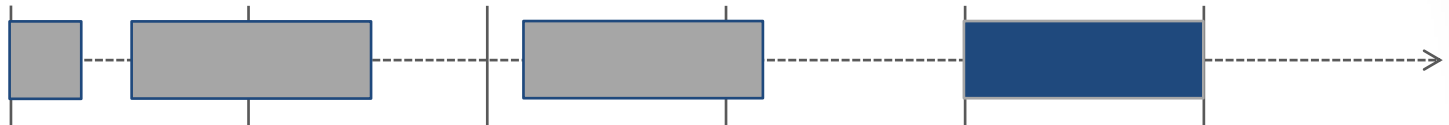
# Why ▲ instead of ● ?



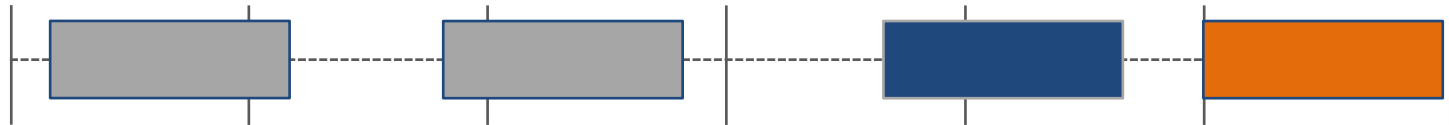
# Why ▲ instead of ● ?



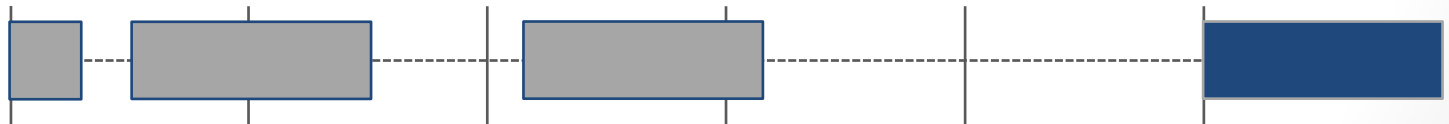
**delay = 4**



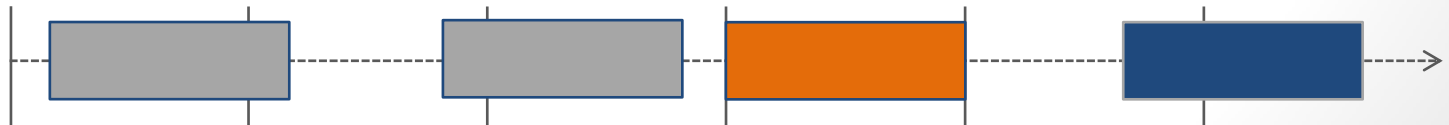
**delay = 5**



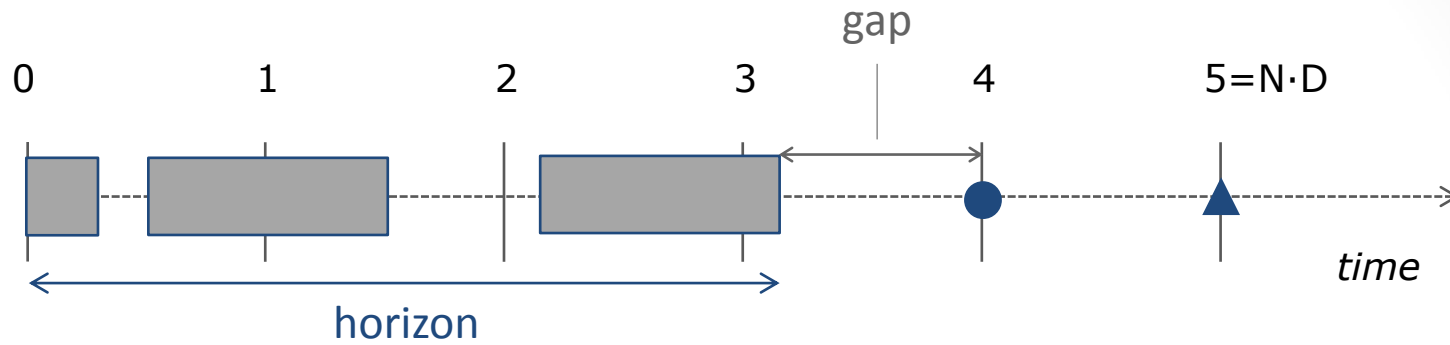
**delay = 5**



**delay = 3**



# Why ▲ instead of ● ?



**IF** fillable void is filled:

- average gap / packet: ↘
- average delay / packet: ↘

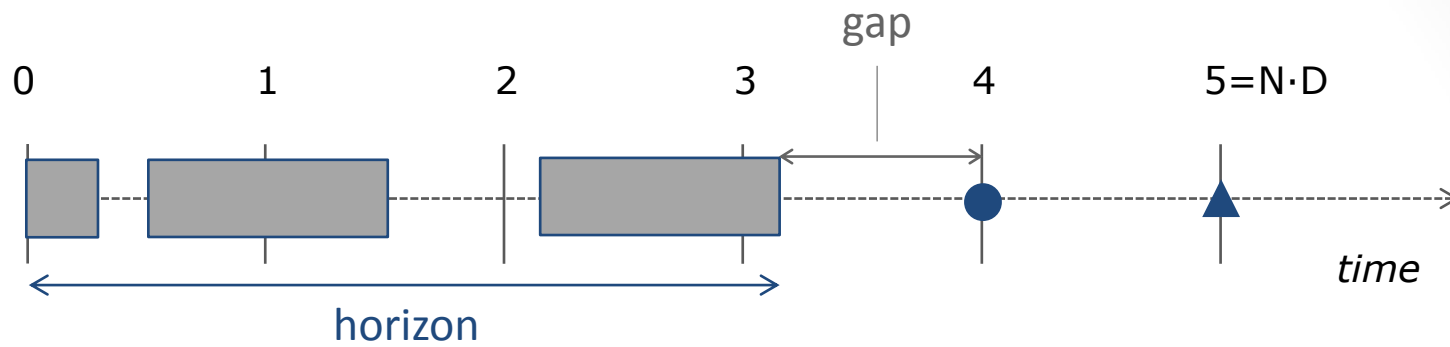


stacking becomes more dense



**loss probability** ↘

# Why ▲ instead of ● ?



Ⓜ fillable void is filled:

- average gap / packet: ↘
- average delay / packet: ↘



stacking becomes more dense



**loss probability** ↘

not all fillable voids will be filled:

- position with respect to FDL has to be favorable
- depends on arrival instances future packets (stochastic arrival process)
- gap ↗ : chance of filling ↗  
horizon ↗ : chance of filling ↗

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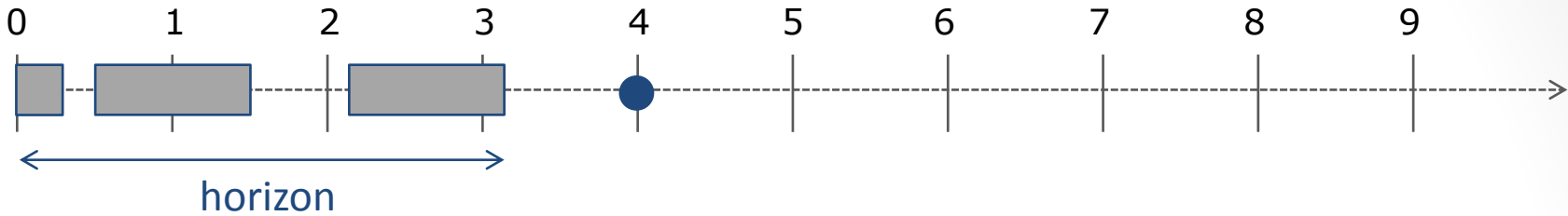
# Assumptions

- **inter-arrival time packets** = exponentially distributed,  $E[T]$
- **fixed packet size** =  $B = 100$
- **D** = granularity = 100
- **N+1** = # Fiber Delay Lines = 10
- **load** =  $\rho = \frac{B}{E[T]} = 80\% \text{ AND } 60\%$

3 sets of simulations:

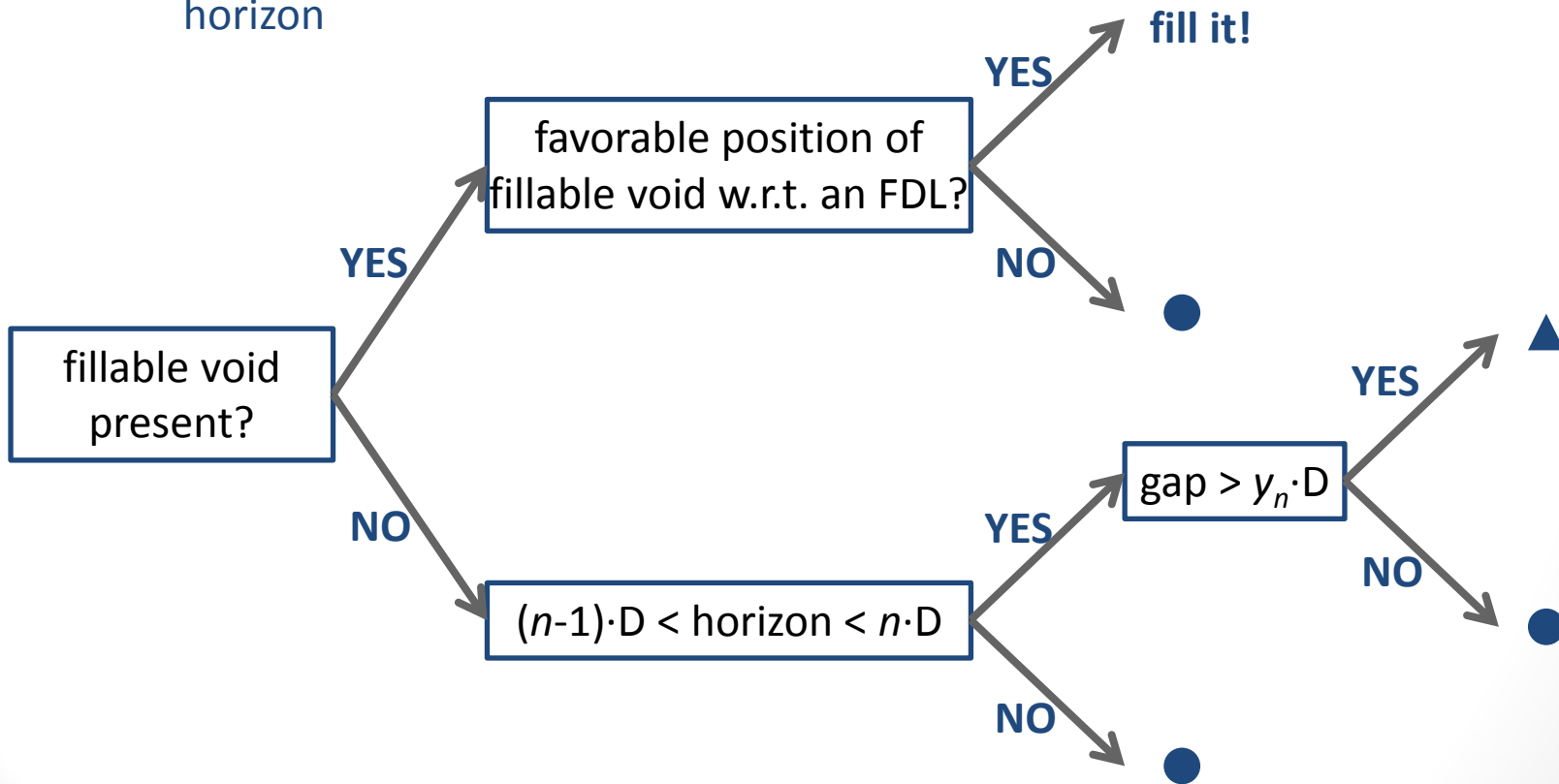
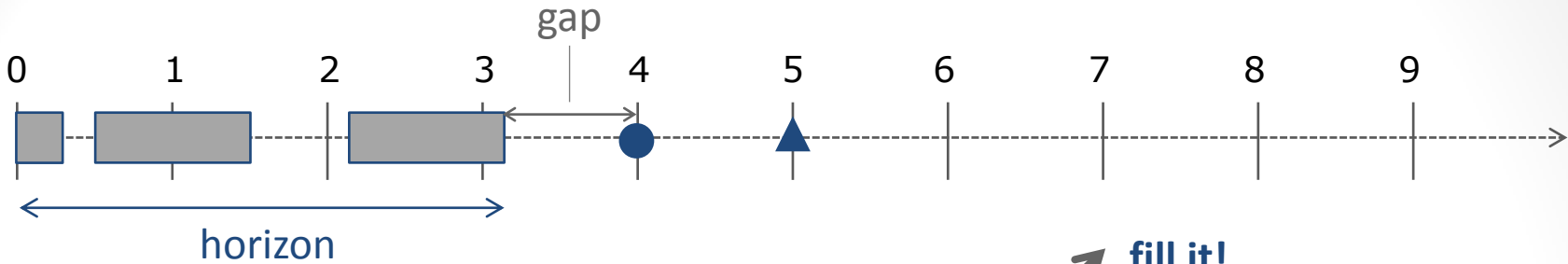
- without void creation
- single creation point
- actual void-creating algorithm

# set 1: without void creation

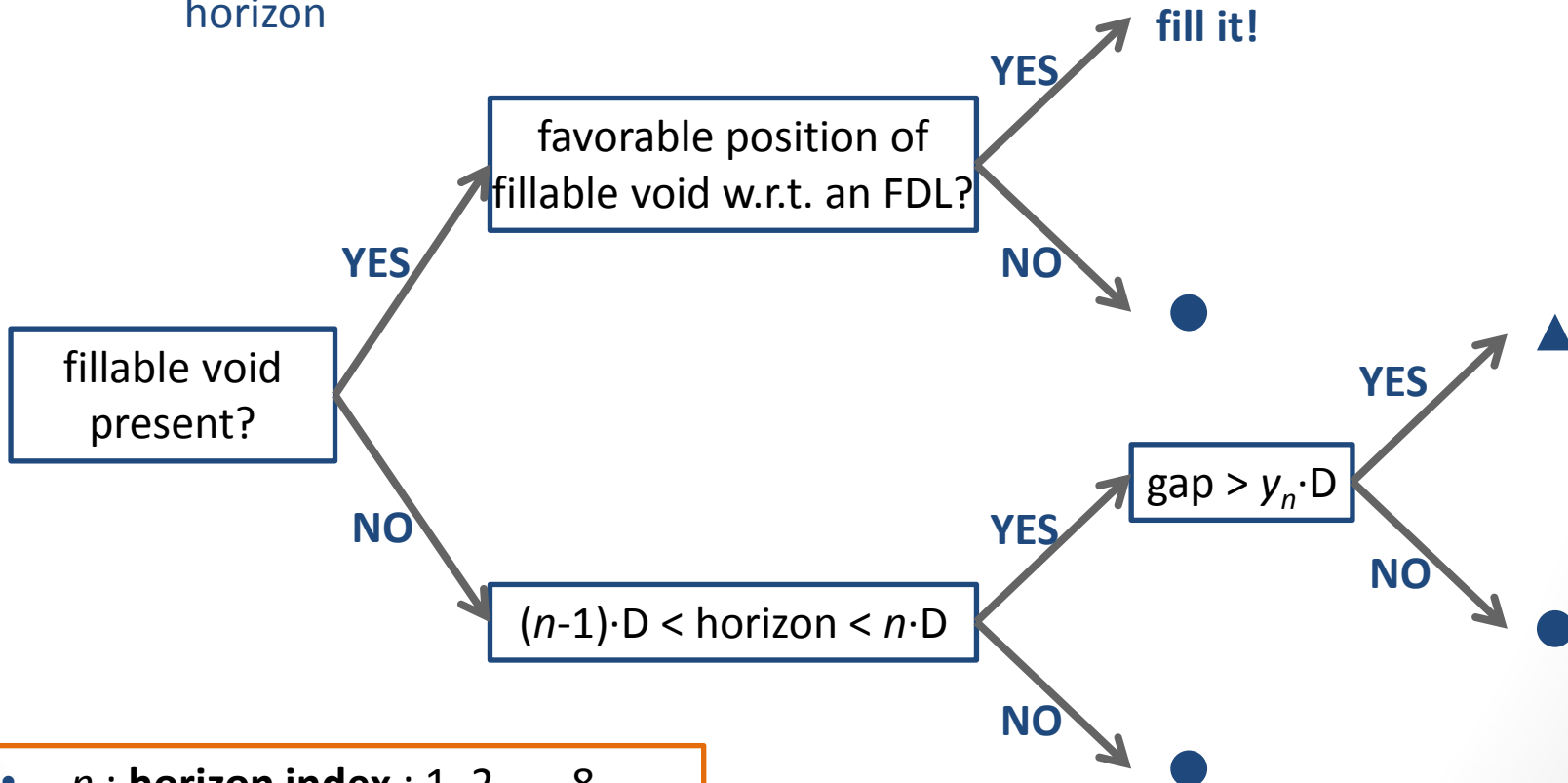
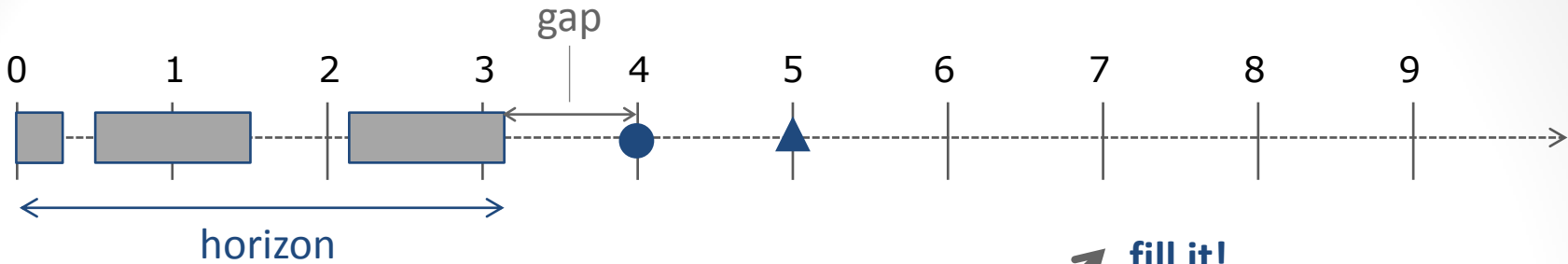


- always ● : first position after horizon
- no fillable voids are created
- $\rho = 80\%$  : loss probability = 14,46 %
- $\rho = 60\%$  : loss probability = 2,08 %

# set 2: single creation point

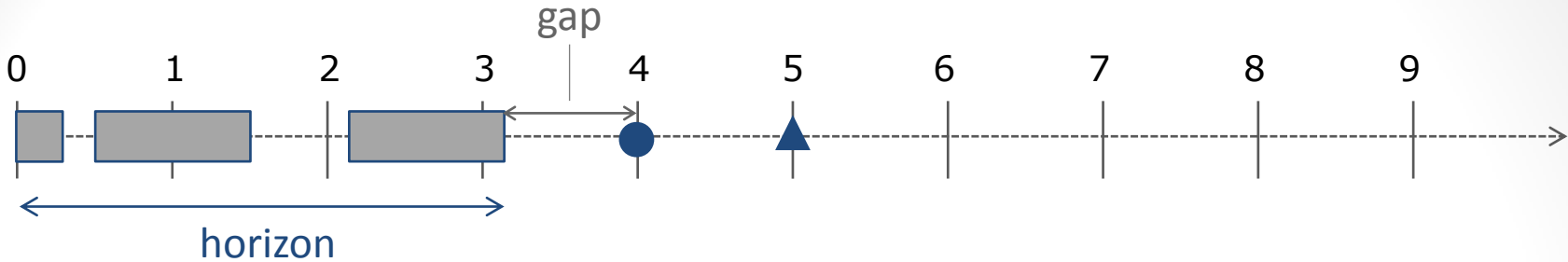


# set 2: single creation point

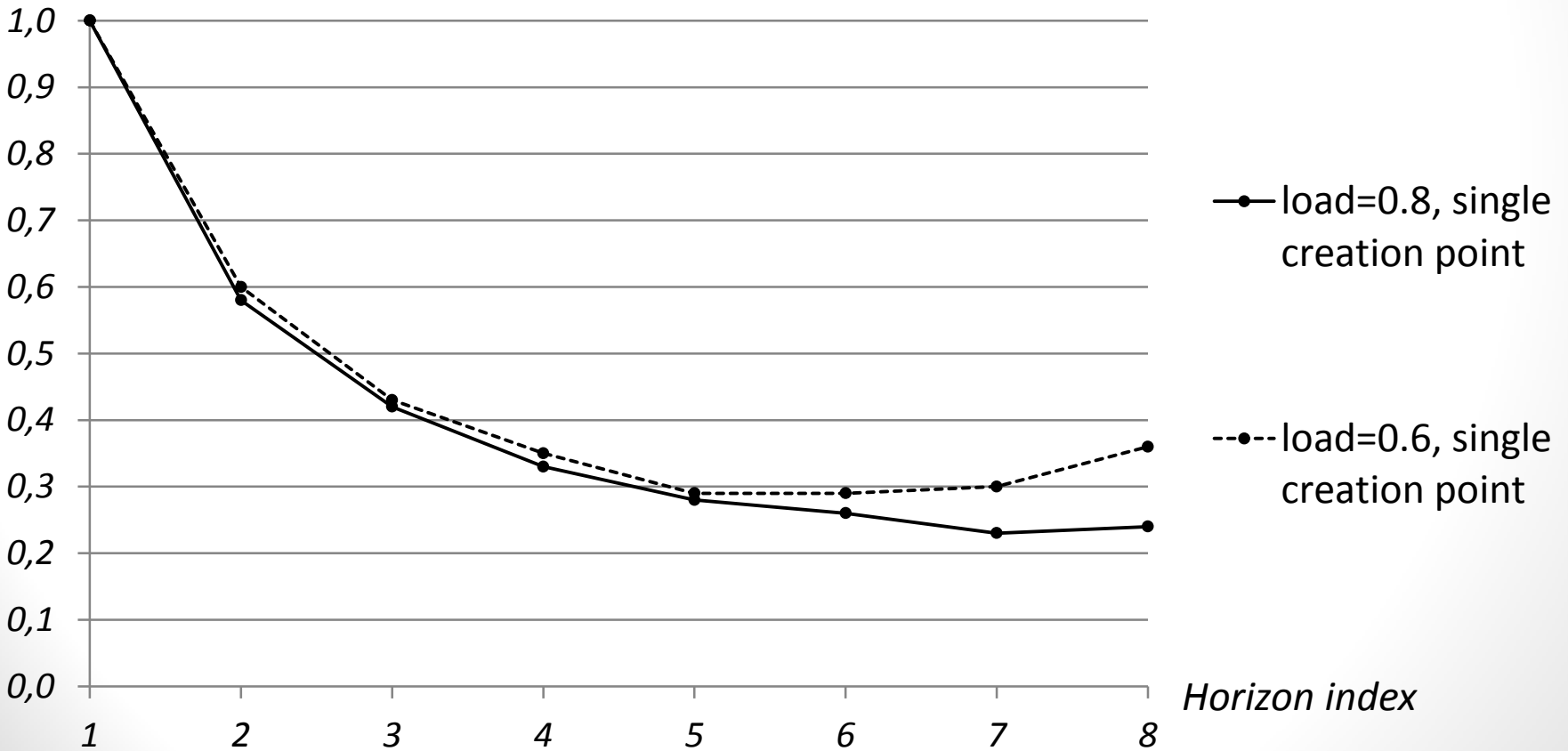


- $n$  : horizon index : 1, 2, ..., 8
- $y_n$  : gap threshold : 0, 0.01, ..., 1

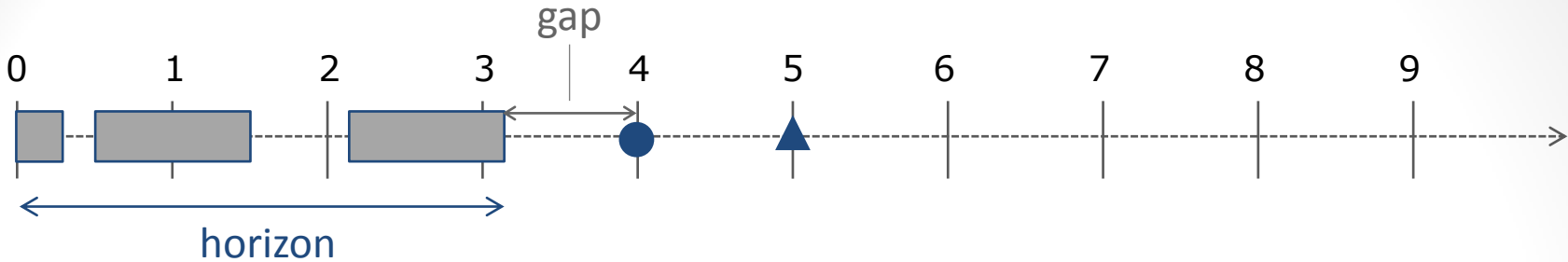
# set 2: single creation point



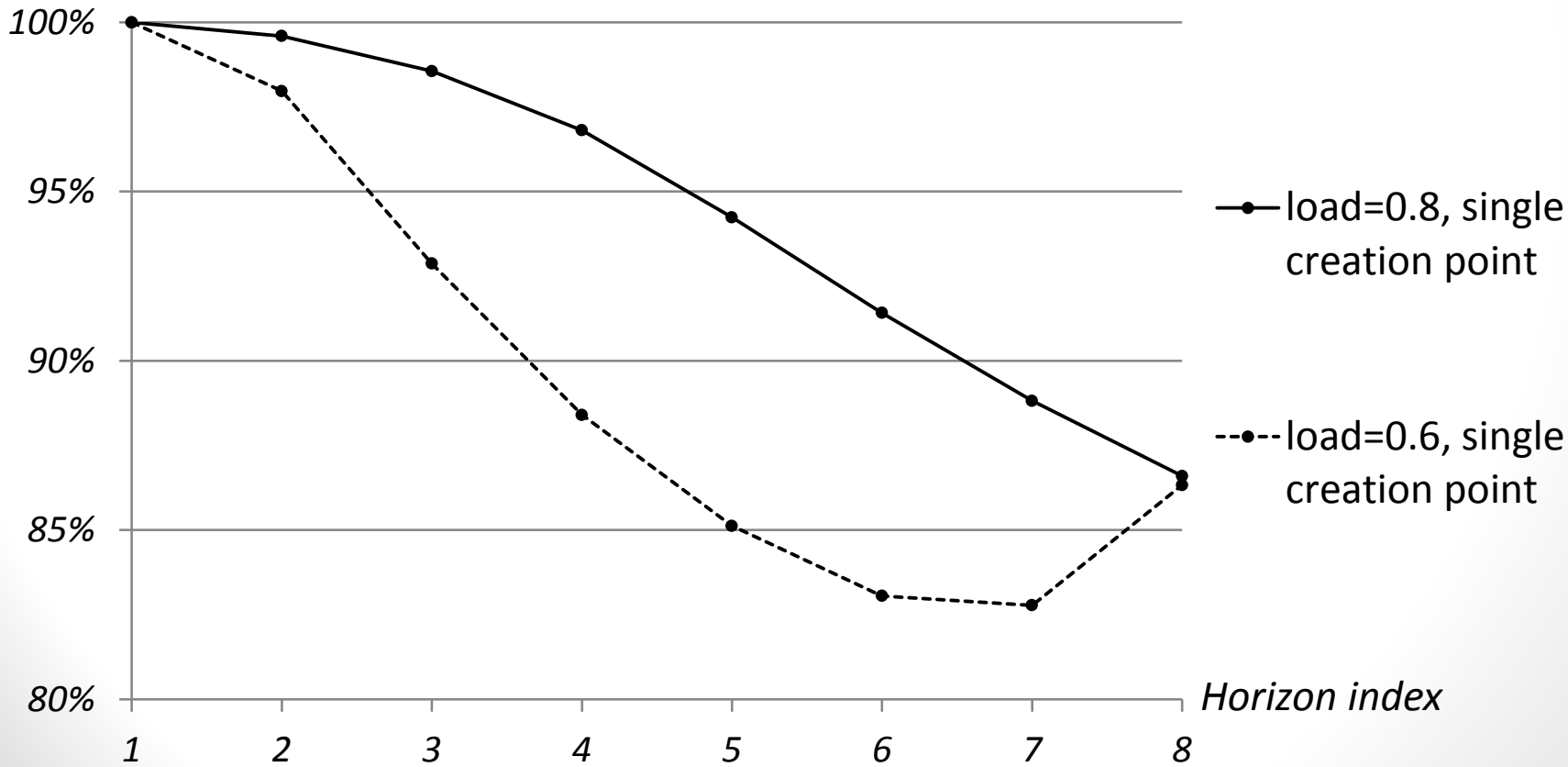
*Optimal gap threshold*



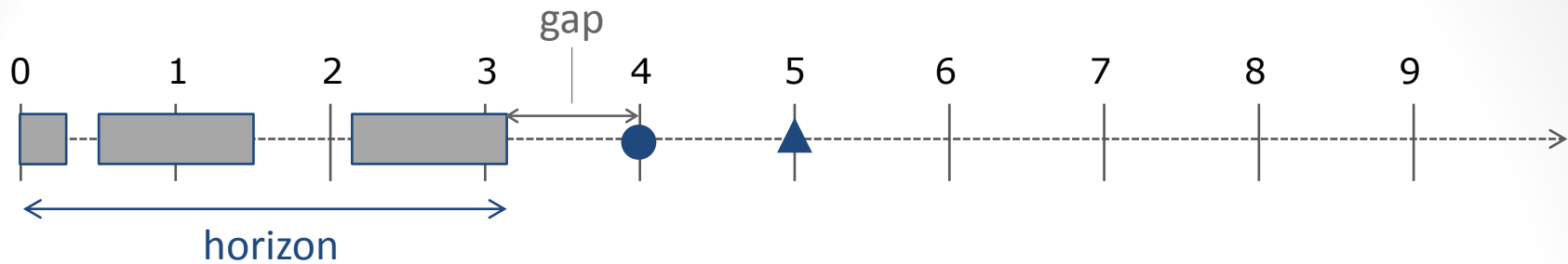
# set 2: single creation point



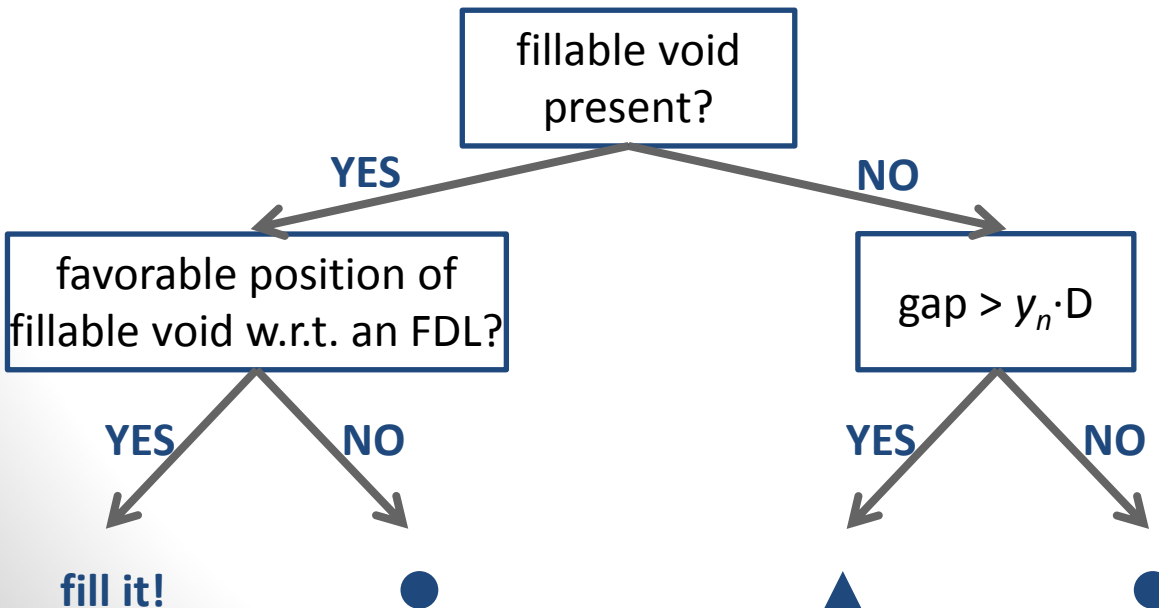
Relative loss probability



# set 3: actual void-creating algorithm

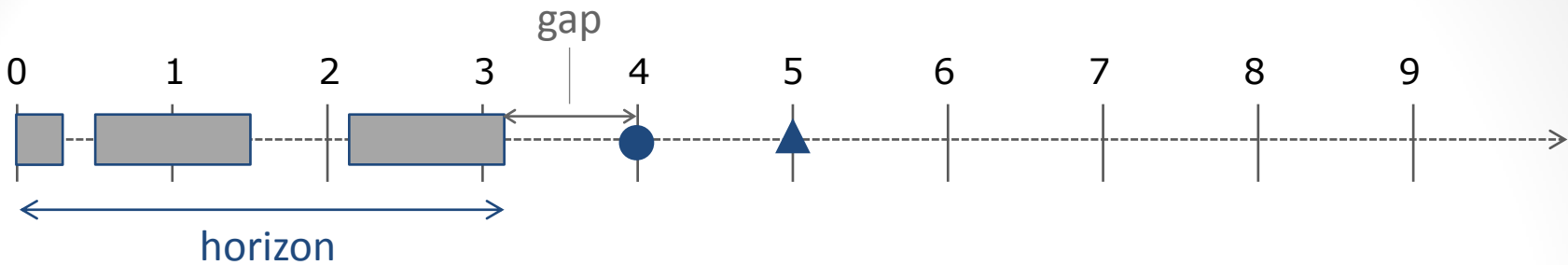


- void creation allowed for all horizon indexes
- optimal gap threshold determined for each horizon index

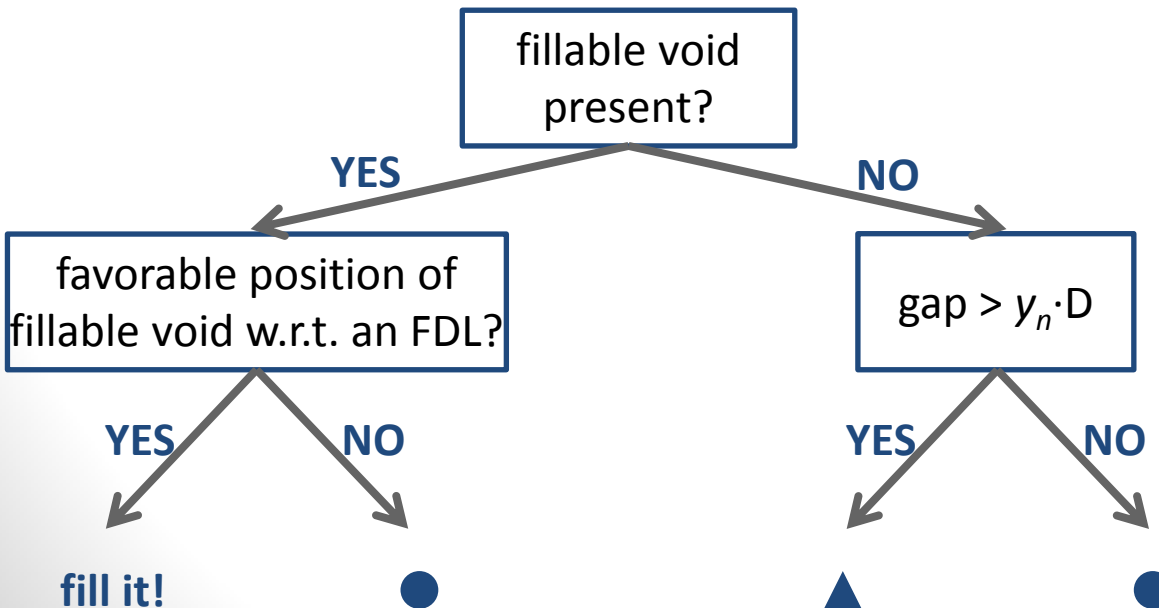




# set 3: actual void-creating algorithm



- void creation allowed for all horizon indexes
- optimal gap threshold determined for each horizon index



- $y_n : 0, 0.01, \dots, 1$
- parameter space too large ( $\sim 100^8$ )

# set 3: actual void-creating algorithm

8 optimal gap thresholds single creation point



keep 7 fixed,  
optimize 1  
(do this 8 times)



8 new gap thresholds (iteration 1)



keep 7 fixed,  
optimize 1  
(do this 8 times)



8 new gap thresholds (iteration 2)

# set 3: actual void-creating algorithm

8 optimal gap thresholds single creation point



keep 7 fixed,  
optimize 1  
(do this 8 times)



**8 new gap thresholds (iteration 1)**



keep 7 fixed,  
optimize 1  
(do this 8 times)



**8 new gap thresholds (iteration 2)**

little difference



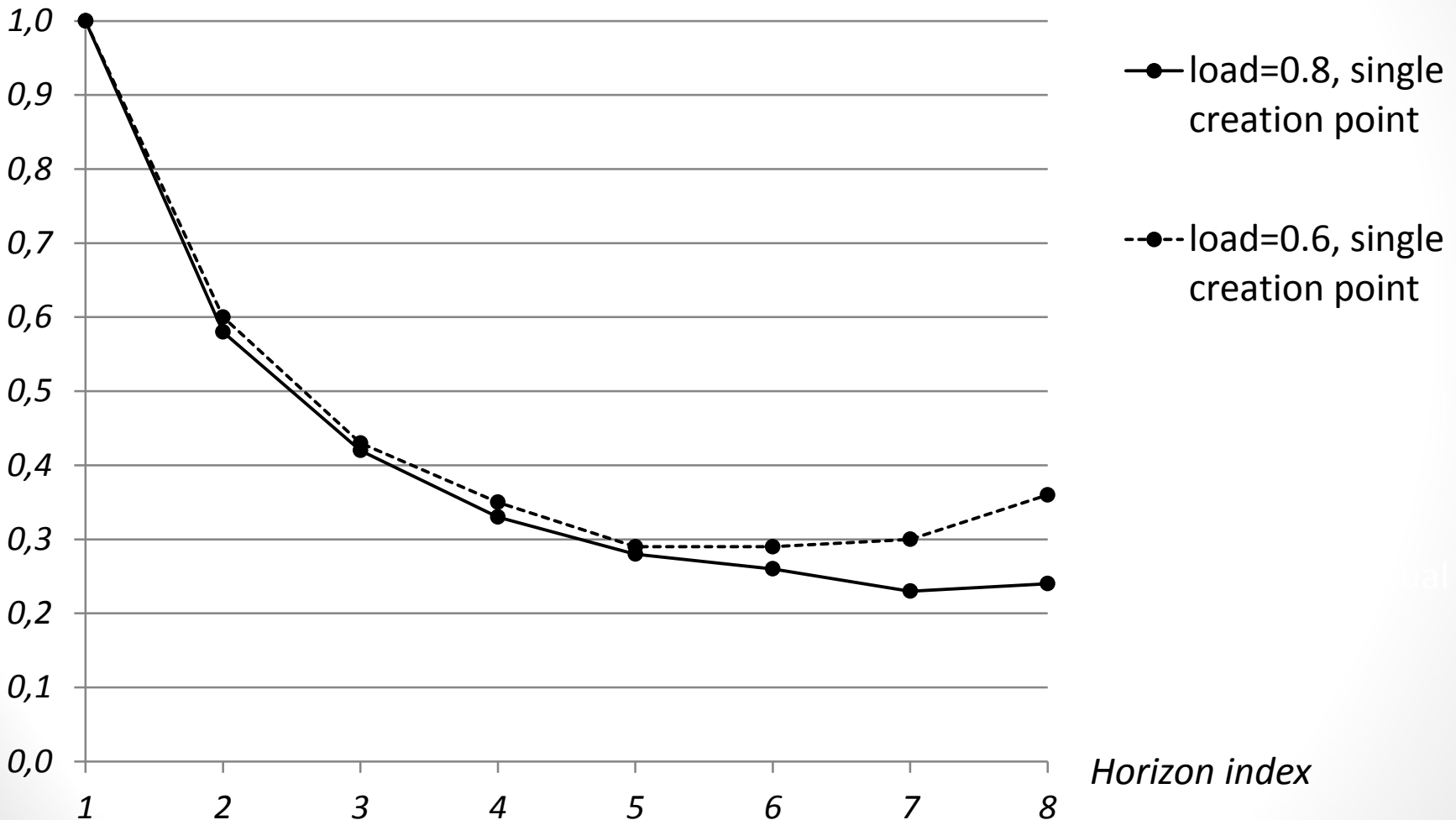
~ convergence



accept iteration 2 as  
approximation true  
optimal gap thresholds

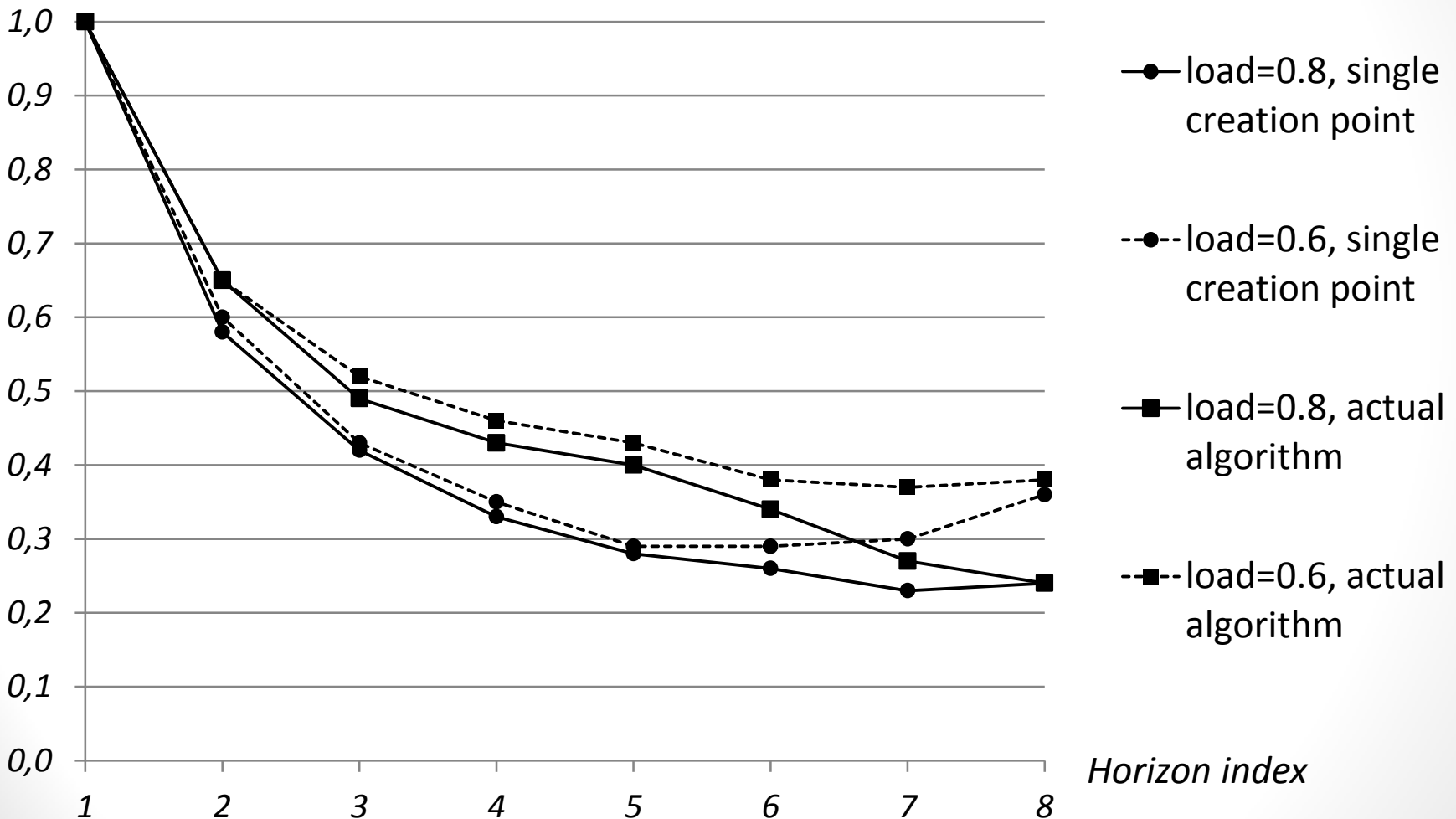
# set 3: actual void-creating algorithm

*Optimal gap threshold*

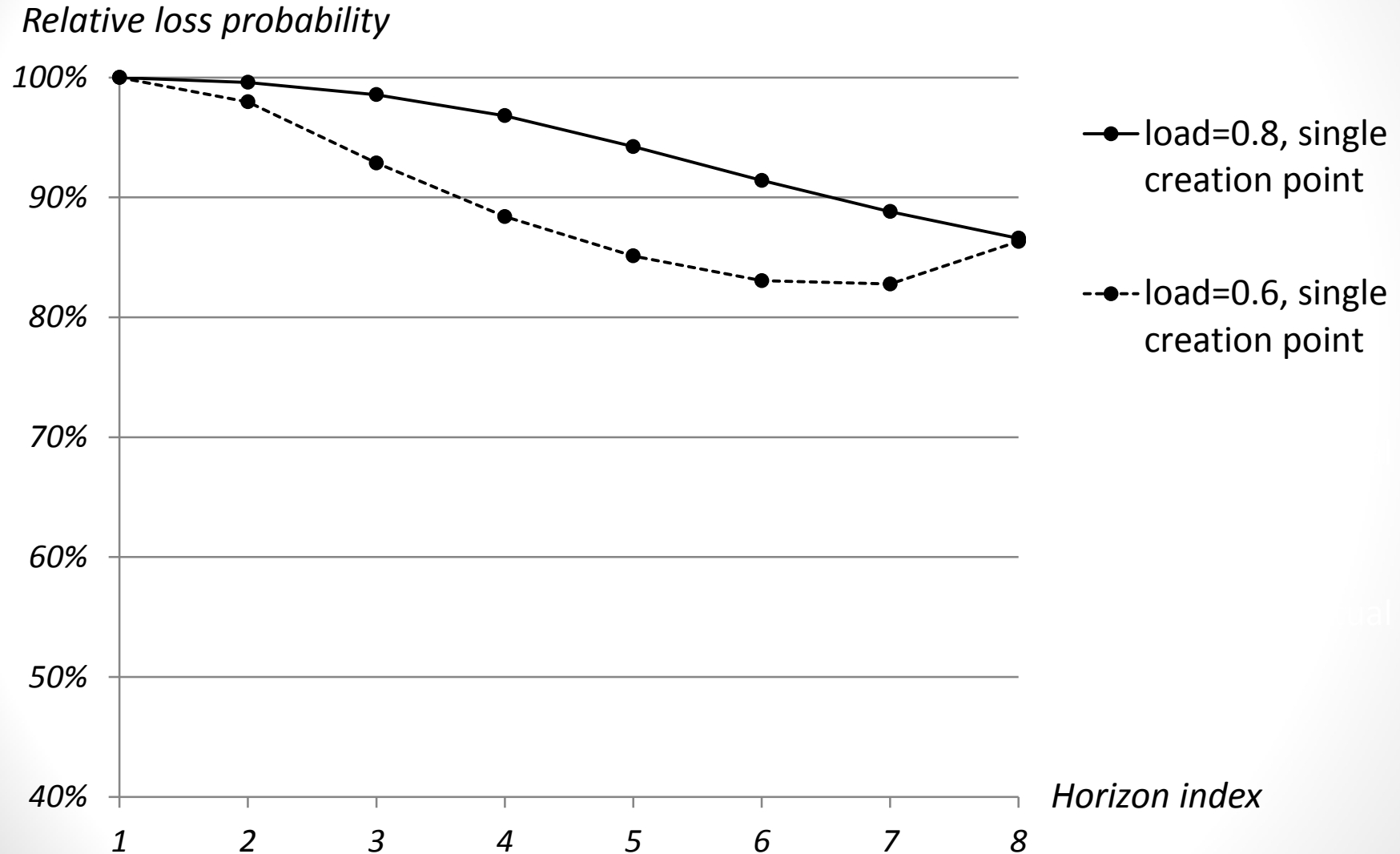


# set 3: actual void-creating algorithm

*Optimal gap threshold*

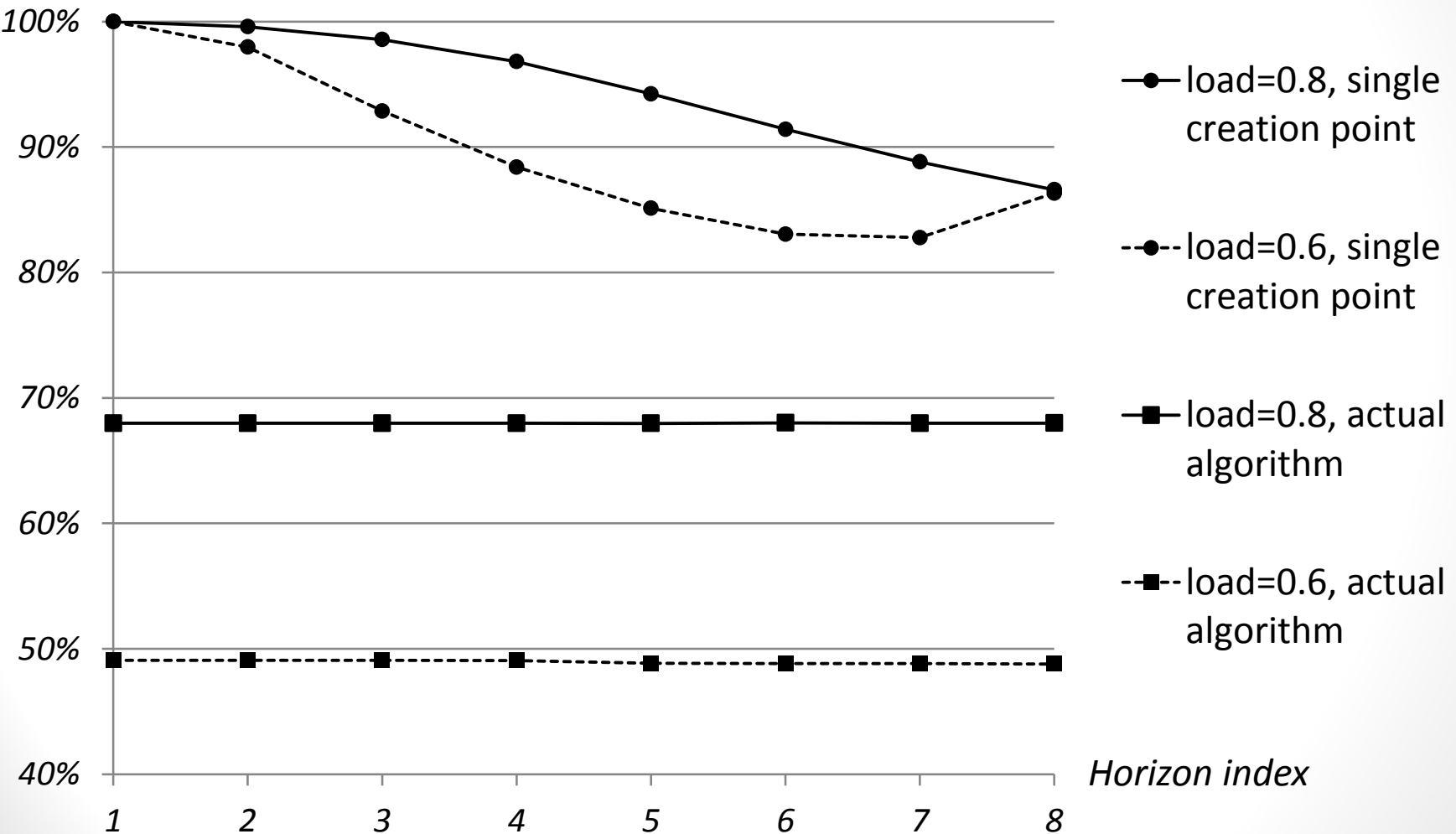


# set 3: actual void-creating algorithm



# set 3: actual void-creating algorithm

*Relative loss probability*



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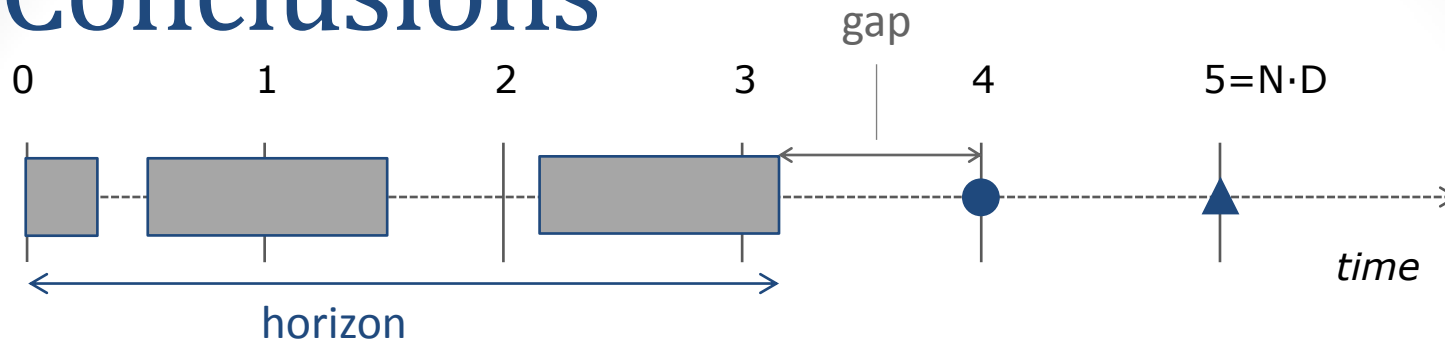
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# Conclusions



- current algorithms: ●
- void creating algorithms: ● or ▲
- ▲ : creates **fillable void** (1 allowed)
- if filled: more dense stacking ➡ loss probability ↘
- optimize void creation via **gap threshold** and **horizon index**
- **LP reduction**: load = 80 %: 32 %                      load = 60 %: 51 %
- **future work**: more complex settings, mathematical approximation

# Questions

?