

Robustness in Queueing Systems

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Robustness

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What do we mean?

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What do we mean? \Rightarrow Bounds of the system

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Why robustness?

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Why robustness? \Rightarrow Model uncertainty

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Our Purpose? \Rightarrow Lower & Upper expected values of various performance measures

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Which performance measures?

Robustness

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Why robustness? \Rightarrow Model uncertainty

Our Purpose? \Rightarrow Lower & Upper expected values of various performance measures

Which performance measures?

- ▶ Expected queue length
- ▶ Probability of a certain length
- ▶ Turning on the server (probability having 1 given 0)
- ▶ Averages

Our Queueing System

Our model \rightarrow *Geo/Geo/1/L*

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Probability of arrival a and probability of departure d
(independent at each time point!)

Discrete Time, Single-server (1) queue with finite capacity (L)

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Other assumptions

Our Queueing System

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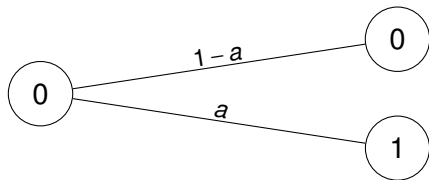
Probability of arrival *a* and probability of departure *d*
(independent at each time point!)

Discrete Time, Single-server (1) queue with finite capacity (*L*)

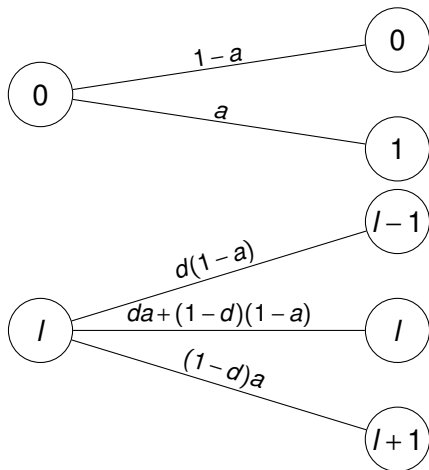
Other assumptions

- ▶ A departure occurs prior to an arrival
- ▶ Service obeys the *FCFS* principle
- ▶ Item stays till served!

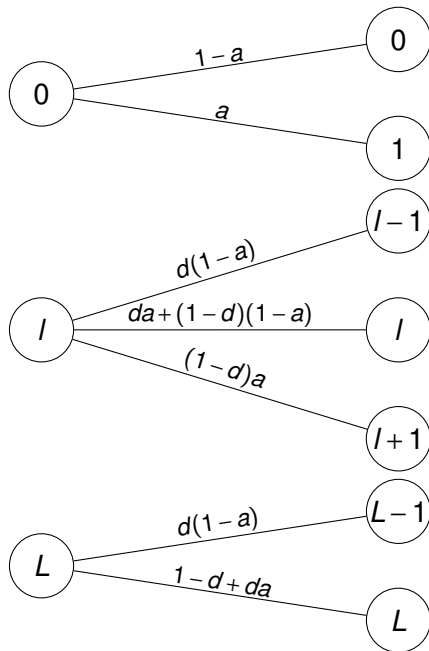
Our Queueing System



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Our Queueing System



Notation

State space $\Rightarrow \mathcal{X} = \{0, \dots, L\}$

local/conditional probability $\Rightarrow p(\cdot | x_n, \mathbf{a}, \mathbf{d})$ with $x_n \in \mathcal{X}$ at any time point n

probability mass functions

$$p(x_1) \prod_{i=1}^{n-1} p(x_{i+1} | x_{1:i}) = p(x_1) \prod_{i=1}^{n-1} p(x_{i+1} | x_i, \mathbf{a}, \mathbf{d})$$

denoted by $p_{1:n, \mathbf{a}, \mathbf{d}}$

Expectations

Let f be a function on $\mathcal{X}^n := \underbrace{\mathcal{X} \times \dots \times \mathcal{X}}_n$ then,

$$E(f) = \sum_{x_{1:n} \in \mathcal{X}^n} f(x_{1:n}) p(x_{1:n}) = \sum_{x_{1:n} \in \mathcal{X}^n} f(x_{1:n}) p(x_1) \prod_{i=1}^{n-1} p(x_{i+1} | x_{1:i})$$

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which is the Law of Iterated Expectation ([LIE](#))

$$E_{1:n}(f) = E(f) = E(E(\dots E(f | X_{1:n-1}) \dots | X_1) | \square)$$

with \square being the initial state

Expectations

Functions on \mathcal{X} will be denoted by h

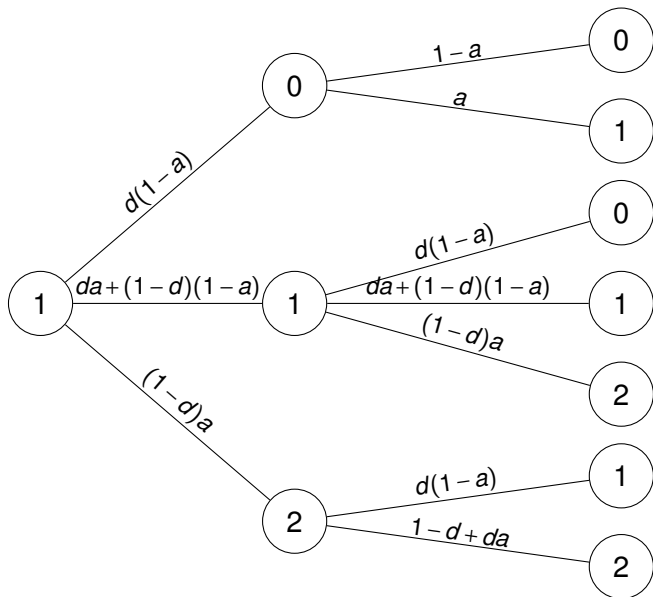
$$E_n(h) = \sum_{x_n \in \mathcal{X}} h(x_n) p(x_1) \prod_{i=1}^{n-1} p(x_{i+1} | x_i) =$$

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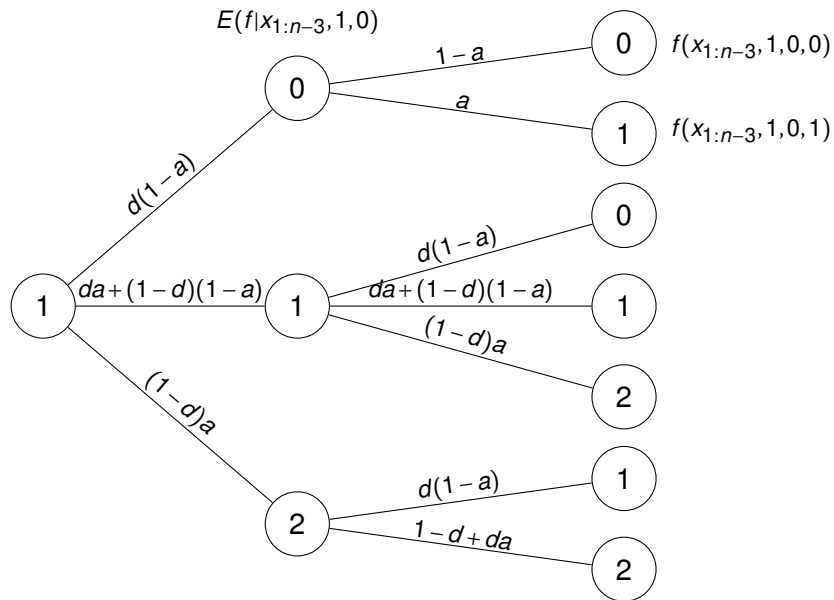
For probabilities we use *indicator functions*

i.e. $\mathbb{1}_A$ assigns 1 when A happens else 0

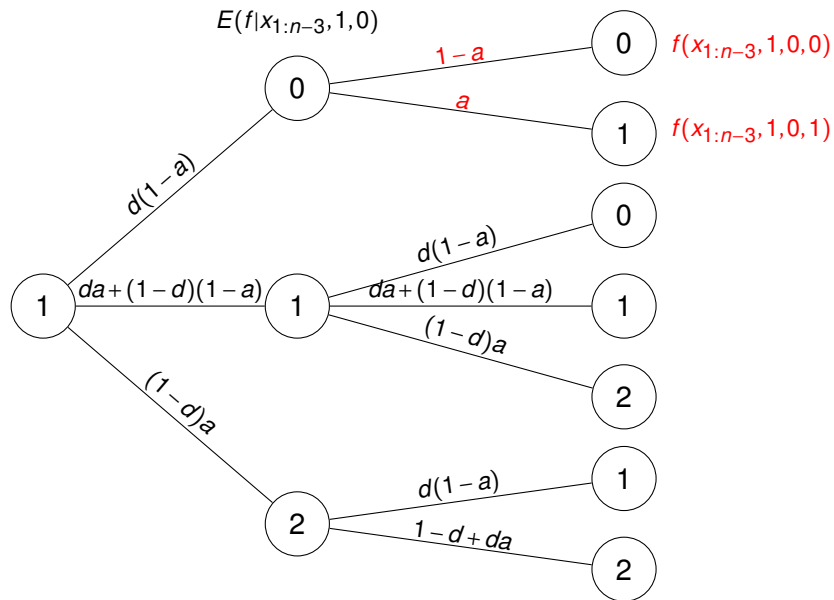
Calculating with Backwards Recursion



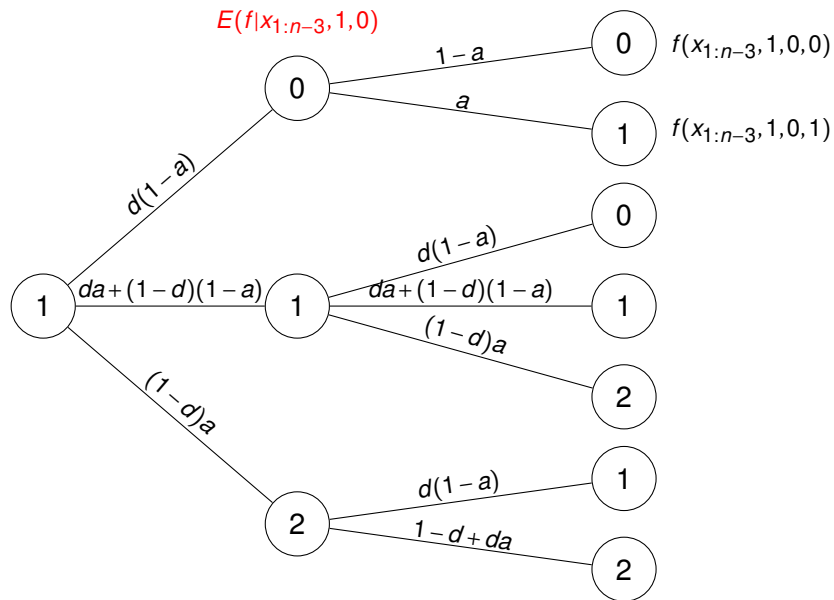
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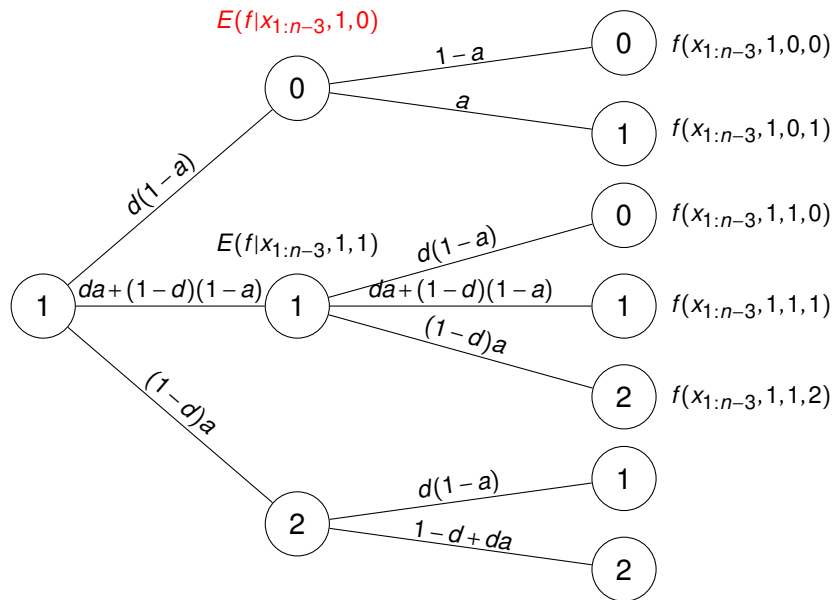
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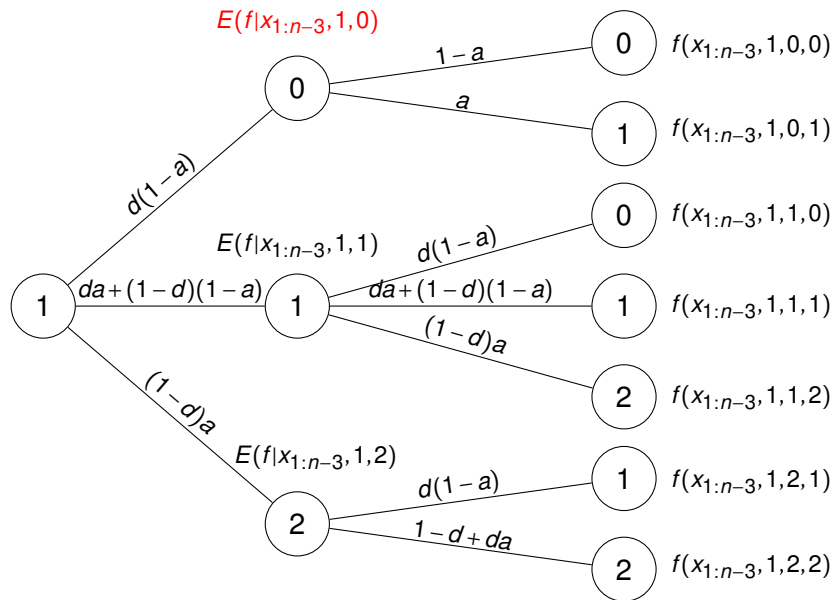
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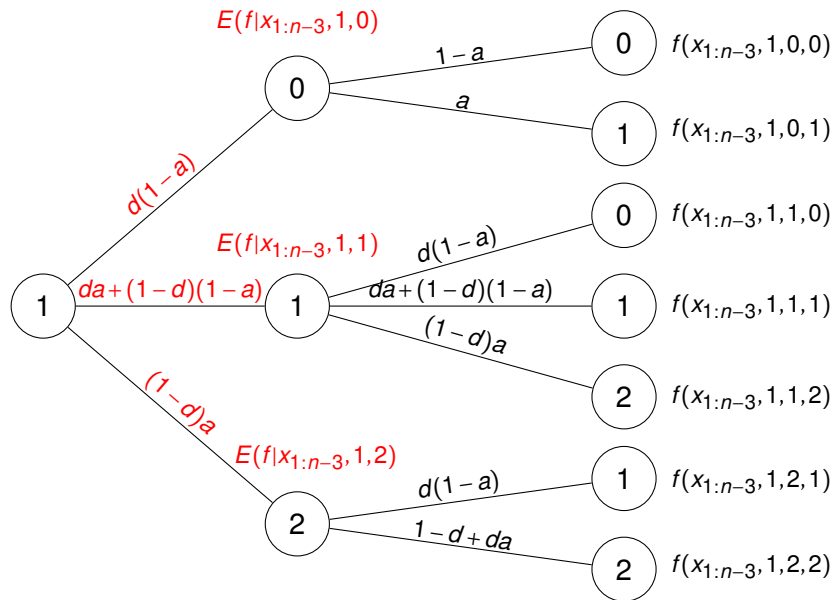
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Uncertainty

Uncertainty in the parameters of the model

Calculate bounds (Lower & Upper Expectations)

$$\underline{E}^{\mathcal{P}}(g) := \min \{E^P(g) : P \in \mathcal{P}\} \quad \text{and} \quad \bar{E}^{\mathcal{P}}(g) := \max \{E^P(g) : P \in \mathcal{P}\}$$

Combining with our notation $\Rightarrow \underline{E}_n, \bar{E}_n$ & $\underline{E}_{1:n}, \bar{E}_{1:n}$

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Geo/Geo/1/L \Rightarrow interval probabilities $a \rightarrow [\underline{a}, \bar{a}]$ & $d \rightarrow [\underline{d}, \bar{d}]$

where each P has form

$$p(x_1) \prod_{i=1}^{n-1} p(x_{i+1} | x_{1:i}, a_{x_{1:i}}, d_{x_{1:i}}) \quad \text{with} \quad a_{x_{1:i}} \in [\underline{a}, \bar{a}], \quad d_{x_{1:i}} \in [\underline{d}, \bar{d}] \quad (p_{1:n, A, D})$$

Two approaches to deal with uncertainty

1st approach - Strong independence

Tree corresponding to lower (or upper) expectation consists of **time-homogeneous/stationary** probabilities of arrival and departure

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$$\underline{E}_{1:n}^s(f) = \min \left\{ E^{p_{1:n,a,d}}(f) : a \in [\underline{a}, \bar{a}], d \in [\underline{d}, \bar{d}] \right\}$$

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We are mainly interested in $n \rightarrow \infty$

Calculations under strong independence

Given a function h on \mathcal{X} , w.r.t to lower expectation in the limit

$$\lim_{n \rightarrow \infty} \underline{E}_n^S(h) = \min \left\{ \sum_{x \in \mathcal{X}} h(x) P[X_n = x] : a \in [\underline{a}, \bar{a}], d \in [\underline{d}, \bar{d}] \right\} \quad (1)$$

$$P[X = 0] = \frac{d - a}{d - \frac{(1-d)^L a^{L+1}}{(d(1-a))^L}}. \quad (2)$$

$$P[X = l] = \frac{(1-d)^{l-1} a^l}{(d(1-a))^l} P[X = 0] \quad (3)$$

We solve (1), where the parameters of (2) and (3) vary in $[\underline{a}, \bar{a}]$ and $[\underline{d}, \bar{d}]$

Calculations under strong independence

For functions on \mathcal{X}^n which represent averages of a function h on $\mathcal{X} \Rightarrow$ the lower expectation in the limit approaches the value of (1)

For general f on \mathcal{X}^n it is difficult to formulate and solve a similar to (1) optimization problem

We approximate lower and upper expectations by

- ▶ choosing a number of probabilities from $[\underline{a}, \bar{a}]$ and $[\underline{d}, \bar{d}]$
- ▶ and calculating for all combinations using LIE in backwards recursion in combination with formulas (2) and (3)

2nd Approach - Epistemic Irrelevance

We **drop stationarity**

The tree corresponding to lower (or upper) expectation can have any probability of arrival and departure, from the respective sets, at any time point and given any sequence of queue lengths

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$$\underline{E}_{1:n}^{ei}(f) = \min \left\{ E^{P_{1:n,A,D}}(f) : (\forall i \leq n)(\forall x_{1:i} \in \mathcal{X}^i) a_{x_{1:i}} \in [\underline{a}, \bar{a}], d_{x_{1:i}} \in [\underline{d}, \bar{d}] \right\}$$

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Calculations under epistemic irrelevance

What is important...

- ▶ for any n (approaching or not infinity)
- ▶ for any function (on \mathcal{X} or \mathcal{X}^n)

we can always use LIE for calculating efficiently lower and upper expectations

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we can always use LIE for calculating efficiently lower and upper expectations

Proposition

For any real-valued function f on \mathcal{X}^n , with $n \in \mathbb{N}_0$

$$\underline{E}_{1:n}^{ei}(f) = \underline{E}_1(\underline{E}_2(\dots \underline{E}_n(f|X_{1:n-1}) \dots |X_1)|\square)$$

- ▶ Linear complexity in the number of steps n
- ▶ In each iteration we can calculate conditional expectations by using only the extreme points $(\underline{a}, \bar{a}, \underline{d}, \bar{d})$

Lemma

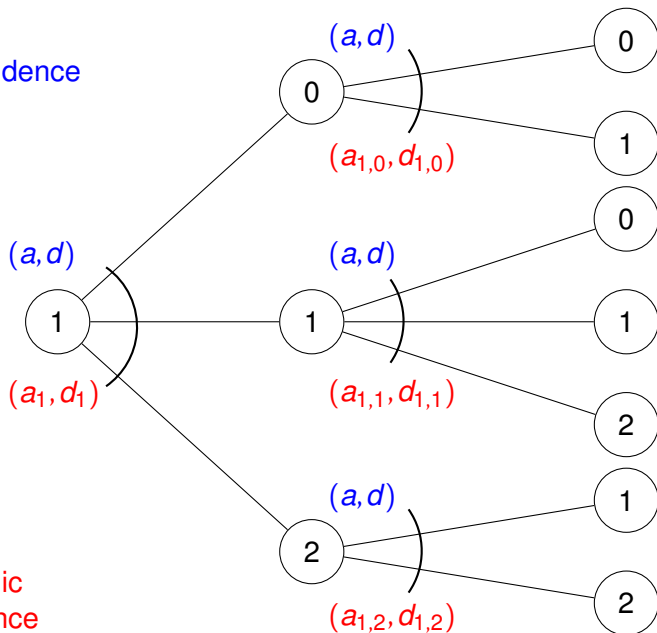
For any real-valued map f on \mathcal{X}^n , with $n \in \mathbb{N}_0$, and any $x_{1:i} \in \mathcal{X}^i$ with $i \in \{1, \dots, n\}$, it holds that

$$\underline{E}_{i:n}^{ei}(f|x_{1:i}) \leq \underline{E}_{i:n}^s(f|x_{1:i}) \text{ and } \overline{E}_{i:n}^{ei}(f|x_{1:i}) \geq \overline{E}_{i:n}^s(f|x_{1:i}).$$

Epistemic irrelevance is associated with all the possible probability trees, whereas the first one only with the stationary ones

Probability trees under both approaches

Strong
Independence



Experiments and Discussion

Some useful properties

Interested in $n \rightarrow \infty$

Under strong independence

For functions on \mathcal{X} we have convergence independent of the initial model

Functions on \mathcal{X}^n convergence to a value affected by the initial model

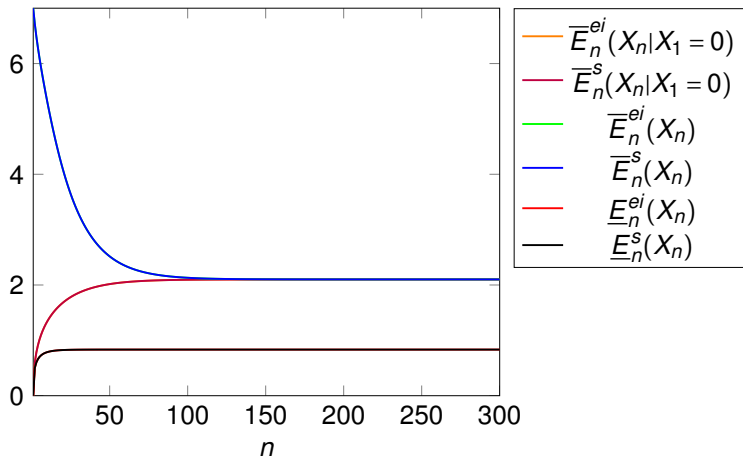
Under epistemic irrelevance

The same convergence properties hold, but for the bounds

Our setting

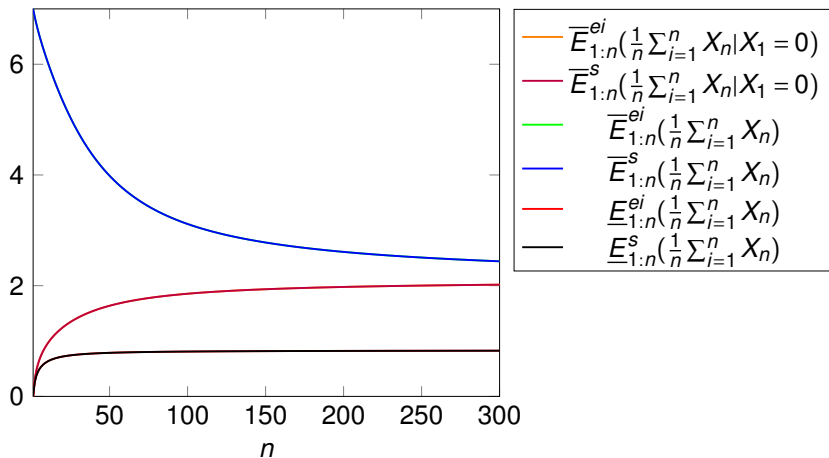
- ▶ queue length = 7
- ▶ arrival $\in [0.5, 0.6]$
- ▶ departure $\in [0.7, 0.8]$
- ▶ for the initial model, we use the *vacuous* one

Expected (Average) Queue Length



Lower and upper expected queue length

Expected (Average) Queue Length



Lower and upper expected average queue length

Expected (Average) Queue Length

Both approaches lead to the same corresponding tree

- ▶ For lower expected (average) queue length largest departure rate, lowest arrival rate
- ▶ For upper expected (average) queue length lowest departure rate, largest arrival rate

Due to the monotonicity of the function

(Average) Probability of queue length

k	0	1	2	7
$\underline{E}_n^{ei}(\mathbb{1}_k(X_n))$	0.148638	0.290906	0.108098	0.000114
$\underline{E}_{1:n}^{ei}(\frac{1}{n} \sum_{i=1}^n \mathbb{1}_k(X_i))$	0.148301	0.308642	0.109882	0.000114
$\bar{E}_n^{ei}(\mathbb{1}_k(X_n))$	0.375014	0.534395	0.268357	0.022481
$\bar{E}_{1:n}^{ei}(\frac{1}{n} \sum_{i=1}^n \mathbb{1}_k(X_i))$	0.375084	0.517315	0.257773	0.022987
$\underline{E}_n^s(\mathbb{1}_k(X_n))$	0.148638 (0.6,0.7)	0.31815 (0.6,0.7)	0.117192 (0.5,0.8)	0.000114 (0.5,0.8)
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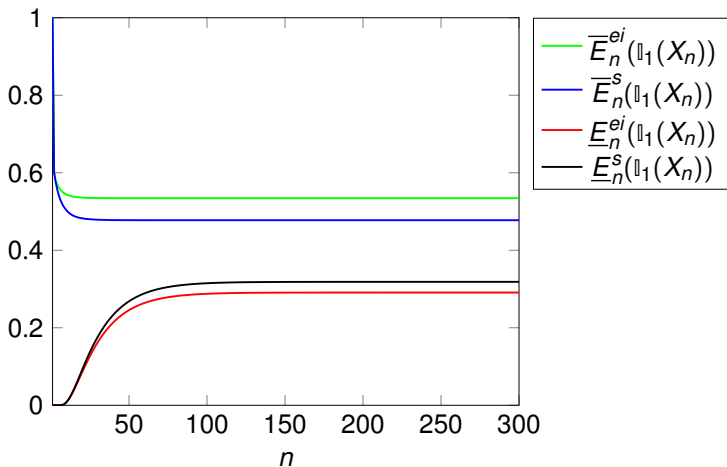
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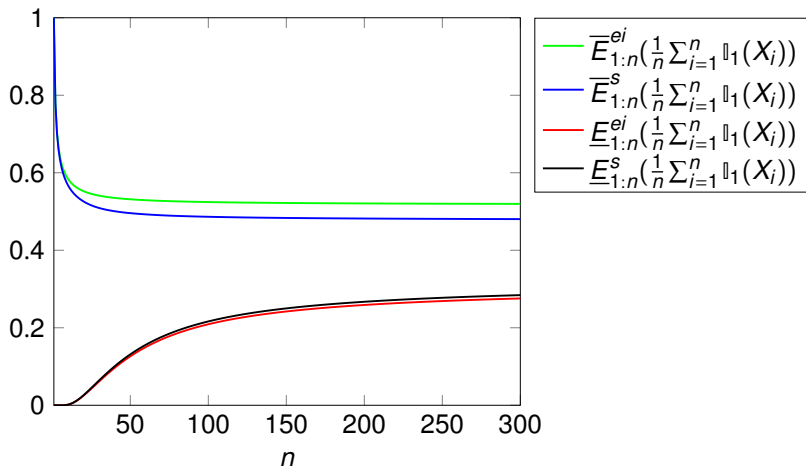
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$\underline{E}_n^s(\mathbb{1}_k(X_n))$	0.148638 (0.6,0.7)	0.31815 (0.6,0.7)	0.117192 (0.5,0.8)	0.000114 (0.5,0.8)
$\underline{E}_{1:n}^s(\frac{1}{n} \sum_{i=1}^n \mathbb{1}_k(X_i))$	0.148301 (0.6,0.7)	0.317824 (0.6,0.7)	0.117162 (0.5,0.8)	0.000114 (0.5,0.8)
$\bar{E}_n^s(\mathbb{1}_k(X_n))$	0.375014 (0.5,0.8)	0.477512 (0.55,0.8)	0.206501 (0.6,0.72)	0.022481 (0.6,0.7)
$\bar{E}_{1:n}^s(\frac{1}{n} \sum_{i=1}^n \mathbb{1}_k(X_i))$	0.375084 (0.5,0.8)	0.477569 (0.55,0.8)	0.206624 (0.6,0.72)	0.022987 (0.6,0.7)

Probability of queue length 1



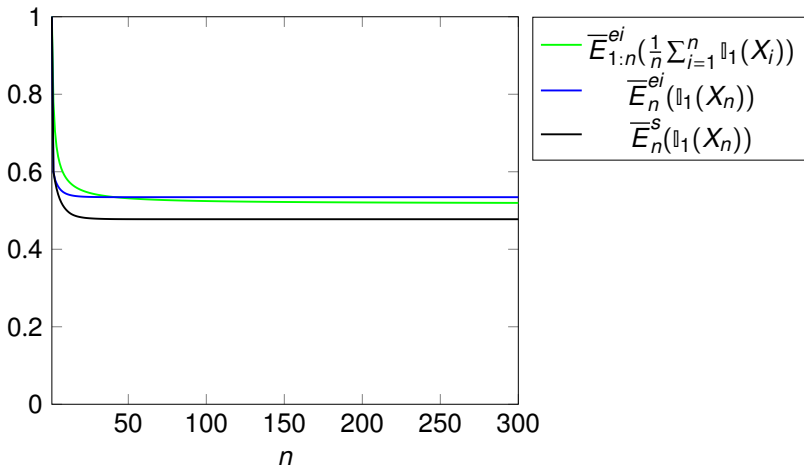
Lower and upper probability of queue length 1

Average Probability of queue length 1



Lower and upper average probability of queue length 1

(Average) Probability of queue length 1



Upper (average) probability of queue length 1

A useful theorem

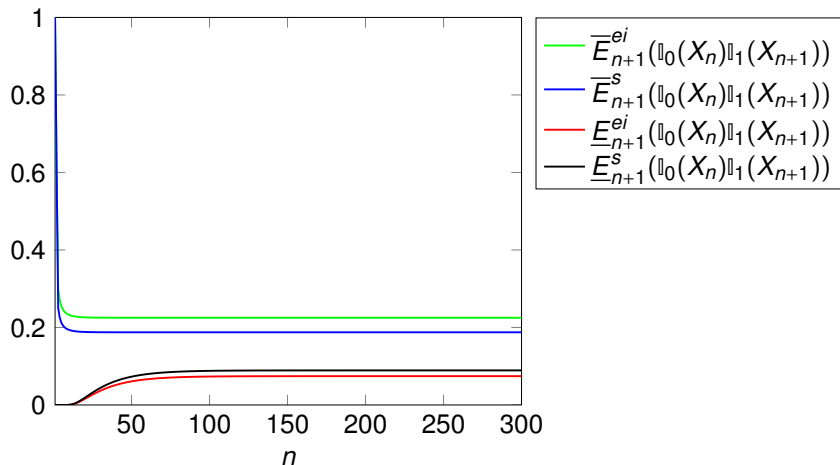
Theorem

Let $L \in \mathbb{N}_0$. Then, for all $k \in \{1, \dots, L-1\}$ it holds that

$$\lim_{n \rightarrow \infty} \underline{E}_n^{ej}(\mathbb{1}_k(X_n)) \leq \lim_{n \rightarrow \infty} \underline{E}_{1:n}^{ej} \left(\frac{1}{n} \sum_{i=1}^n \mathbb{1}_k(X_i) \right) \text{ and}$$

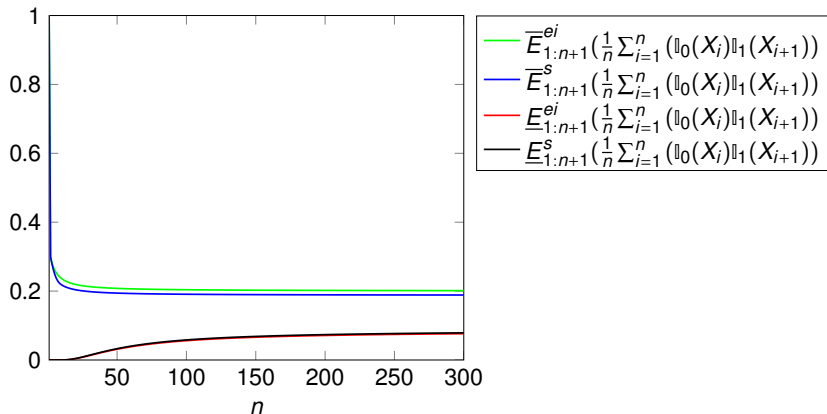
$$\lim_{n \rightarrow \infty} \overline{E}_n^{ej}(\mathbb{1}_k(X_n)) \geq \lim_{n \rightarrow \infty} \overline{E}_{1:n}^{ej} \left(\frac{1}{n} \sum_{i=1}^n \mathbb{1}_k(X_i) \right)$$

Turning on the server



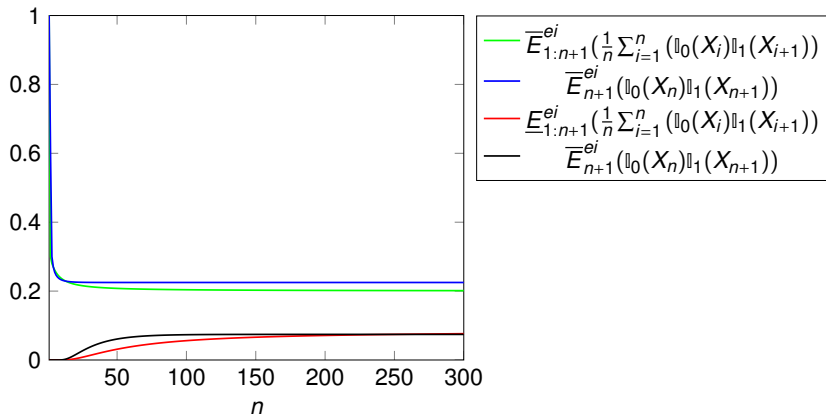
Lower and upper probability of turning on the server

Turning on the server



Lower and upper average probability of turning on the server

Turning on the server



Lower and upper (average) probability of turning on the server

Conclusions & Future (Ongoing) work

When we are uncertain about the model, an average might not represent the actual situation

Compare the approaches with the state dependent model