Proceedings of the 15th International Conference on Computational and Mathematical Methods in Science and Engineering, CMMSE 2015 6–10 July, 2015.

## Identification of a memory kernel in a nonlinear parabolic integrodifferential problem

K. Van Bockstal<sup>1</sup>, M. Slodička<sup>1</sup> and F. Gistelinck<sup>1</sup>

<sup>1</sup> Research Group NaM<sup>2</sup>, Department of Mathematical Analysis, Ghent University, Belgium

emails: Karel.VanBockstal@UGent.be, Marian.Slodicka@UGent.be, Fien.Gistelinck@UGent.be

## Abstract

The reconstruction of a solely time-dependent convolution kernel K in the following nonlinear parabolic equation with unknowns  $\langle K, u \rangle$  is studied:

$$\partial_t u(\mathbf{x},t) - \nabla \cdot (\nabla \beta(u(\mathbf{x},t))) + \int_0^t K(t-s)u(\mathbf{x},s) \, \mathrm{d}s = \dots,$$
(1)

with  $\mathbf{x} \in \Omega \subset \mathbb{R}^d$  and  $t \in [0, T]$ . The right-hand side (RHS) of (1) is not specified yet. The missing kernel is recovered from a global measurement over the domain, i.e.

$$\int_{\Omega} u(\mathbf{x}, t) \, \mathrm{d}\mathbf{x} = m(t), \qquad t \in [0, T].$$
(2)

Note that in [1], the reconstruction of K based on the same measurement is studied in the semilinear equation

$$\partial_t u(\mathbf{x},t) - \Delta u(\mathbf{x},t) + K(t)h(\mathbf{x},t) + \int_0^t K(t-s)u(\mathbf{x},s) \, \mathrm{d}s = f(u(\mathbf{x},t), \nabla u(\mathbf{x},t)).$$

The main differences are that equation (1) is nonlinear and does not contain the term Kh. This term was crucial in the analysis made in [1]. The implications of this removal on the analysis of problem (1)-(2) and in particular on the choice of the RHS of (1) are discussed. After a specific choice for the RHS of (1), using observation (2), the inverse problem (1)-(2) can be reformulated in a direct setting. Afterwards, using Rothe's method [2], the existence and uniqueness of a weak solution is shown and a numerical algorithm based on this method is illustrated by numerical experiments.

## References

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- [2] J. Kačur. Method of Rothe in evolution equations, volume 80 of Teubner Texte zur Mathematik. Teubner, Leipzig, 1985.