CORE

# Shortcut Fusion Rules for the Derivation of Circular and Higher-order Monadic Programs 

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#### Abstract

Functional programs often combine separate parts using intermediate data structures for communicating results. These programs are modular, easier to understand and maintain, but suffer from inefficiencies due to the generation of those gluing data structures. To eliminate such redundant data structures, some program transformation techniques have been proposed. One such technique is shortcut fusion, and has been studied in the context of both pure and monadic functional programs.

Recently, we have extended standard shortcut fusion: in addition to intermediate structures, the program parts may now communicate context information, and it still is possible to eliminate those structures. This is achieved by transforming the original function composition into a circular program. This new technique, however, has been studied in the context of purely functional programs only. In this paper, we propose an extension to this new form of fusion, but in the context of monadic programming: we derive monadic circular programs from strict ones, maintaining the global effects. Later, the circularities in the derived programs are traded by highorder definitions, using a well-known program transformation technique. We finally obtain very efficient deforested programs.

An important feature of our extensions is that they can be uniformly defined for a wide class of data types and monads, using


 generic calculation rules.Categories and Subject Descriptors D.3.4 [Programming Languages]: Processors - Compilers, Optimization; D.1.1 [Programming Techniques]: Applicative (Functional) Programming; D.3.3 [Programming Languages]: Language Constructs and Features; F.3.3 [Logics and Meanings of Programs]: Studies of Program Constructors - Program and Recursion Schemes

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## 1. Introduction

Functional programs often combine separate parts of the program using intermediate structures for communicating results. In general, we have programs such as prog $=$ cons $\circ$ prod, where prod is called the producer function and cons is called the consumer function. Programs so defined are modular and have many benefits, such as clarity and maintainability, but suffer from inefficiencies caused by the generation of the intermediate data structures that glue functions cons and prod together.

In response to this problematic, some program transformation techniques have been studied aiming at the elimination of intermediate data structures. One of these techniques is known as shortcut fusion, or shortcut deforestation [14]. This technique eliminates the generation of the intermediate structure, of type $b$, when prod $:: a \rightarrow b$, cons $:: b \rightarrow c$ and prog $=$ cons $\circ$ prod. Shortcut fusion has recently been studied and applied also in the context of monadic functional programs [11, 18].

In [9], we have proposed circular programs as an extension to standard shortcut fusion. Circular programs were first studied by Bird [4] as an elegant and efficient technique to eliminate multiple traversals of data structures. As the name suggests, circular programs are characterized by having what appears to be a circular definition: arguments in a function call depend on results of that same call. That is, they contain definitions of the form:

$$
(\ldots, x, \ldots)=f(\ldots, x, \ldots)
$$

Circular programs have also been studied as an optimization technique to deforest in accumulating parameters [24]. Furthermore, circular programs are a powerful, elegant and concise technique to express multiple traversal algorithms and attribute grammars [10].

In [9], we have shown how circular programs can be used to achieve intermediate structure deforestation in programs such as prog $=$ cons $\circ$ prod, but where prod $:: a \rightarrow(b, z)$ and cons $::$ $(b, z) \rightarrow c$. This means that the producer function may generate, besides the intermediate structure $b$, an additional value, of type $z$, that the consumer function may need to compute its result. Later, a calculation rule is applied to prog, which is transformed into an equivalent circular program that does not construct any intermediate structure and that traverses the input data (of type a) only once. The rule applied to prog is generic in the sense that it can be applied to a wide range of programs and datatypes. However, it does not handle monadic functional programs, that is, programs that, for example, rely on a global state or perform I/O operations. Thus, the rule has a limited applicability scope since several programs, like compilers, pretty-printers or parsers do rely on global effects.

Our motivation for the present work is to extend shortcut fusion to the kind of programs we studied in [9], but in the context of monadic programming. The goal is to achieve fusion of monadic
programs, maintaining the global effects. We study two cases: the case where the producer function is monadic and the consumer is given by a pure function, and the case where both functions are monadic. For both cases, fusion is achieved by transforming the original program into a circular one. We do not consider the case where the producer is given by a pure function (and the consumer is given by a monadic one) since it can already be fused using the shortcut fusion rule we presented in [9].

An alternative solution to achieve intermediate structure deforestation for programs such as prog is to transform them into higher-order programs using a well-known program transformation technique called lambda abstraction [20]. In our particular context, the idea of the transformation is to derive a new function $\operatorname{prog}^{\prime}:: a \rightarrow(z \rightarrow c, z)$, which returns a function and the same value of type $z$ that would be generated by prod, such that prog $a=f z$ where $(f, z)=$ prog $^{\prime} a$. Obtaining such higherorder programs is interesting since its execution is not restricted to a lazy evaluation setting as it happens with the execution of the circular ones. Based on this idea, Voigtländer [25] introduced a shortcut fusion rule for the derivation of pure, higher-order programs from compositions like prog when lists are the intermediate structure. In this paper, we extend this result in two ways. First, we present a generic formulation of the shortcut fusion rule for the derivation of pure higher-order programs that can be applied to a wide range of datatypes as intermediate structure. Second, we extend the generic rule to the context of monadic programming, obtaining shortcut fusion rules for the derivation of monadic higher-order programs.

Experimental benchmarks we have conducted in [10] show that the performance of the higher-order programs derived from programs like prog is significantly better (up to 3 times) than the performance of their circular or original equivalents, both in terms of time and memory consumption, whereas the performance between circular programs and the ones from which they are derived is essentially the same.

Although the higher-order programs we finally derive in this paper are the ones with the best running performances, the calculation of circular programs is of great importance to our future work, and has strong relations with some of our previous studies [10]. Indeed, there is a close relationship between circular programs and Attribute Grammars (AGs): circular programs are the natural representation of AGs in a lazy setting. In the past [10], we have applied well-known AG techniques to circular programs, in order to derive efficient equivalent implementations. The correctness of such techniques, however, has not been formally proved yet, although they are widely used by the AG community. In order to be able to prove their correctness, we, therefore, would like to be able to express such techniques in calculational form. The calculation of circular programs, in the way presented in this paper and in a previous work [9], also brings us closer to that goal.

Throughout we will use Haskell notation, assuming a cpo semantics (in terms of pointed cpos), but without the presence of the seq function [17].

This paper is organized as follows. Sections 2 and 3 present two motivating examples that serve to illustrate the applicability of our techniques. The generic constructions that give rise to the specific program schemes and laws presented in those examples are developed in Sections 4 and 5. Finally, in Section 6 we draw some conclusions and describe directions for future work.

## 2. Bit String Transformation

To illustrate our technique we first consider an example based on a simple bit string conversion that has applications in cryptography [15]. Suppose we want to transform a sequence of bits into a new one, of the same length, by applying the exclusive or between each bit and the binary sum (sum modulo 2) of the sequence. We
will consider that the input sequence is given as a string of bits, which will be parsed into a list and then transformed. It is in the parsing phase that computational effects will come into play, as we will use a monadic parser.

Suppose we are given the string "101110110001". To transform this string of bits, we start by parsing it, computing as result a list of bits $[1,0,1,1,1,0,1,1,0,0,0,1]$, and its binary sum ( 1 in this case). Having the list and the binary sum, the original sequence is transformed into this one [ $0,1,0,0,0,1,0,0,1,1,1,0$ ] after applying the exclusive or of each bit with 1 (the binary sum).

To construct the parser, we adopt a usual definition of parser monad (see [16] for more details):

$$
\begin{aligned}
& \text { newtype Parser } a=P(\text { String } \rightarrow[(a, \text { String })]) \\
& \text { instance Monad Parser where } \\
& \text { return } a=P(\lambda c s \rightarrow[(a, c s)]) \\
& p \gg f=P\left(\lambda c s \rightarrow \text { concat } \left[\text { parse }(f a) c s^{\prime} \mid\right.\right. \\
& \left.\left.\left(a, c s^{\prime}\right) \leftarrow \text { parse } p c s\right]\right) \\
& \text { parse }:: \text { Parser } a \rightarrow \text { String } \rightarrow[(a, \text { String })] \\
& \text { parse }(P p)=p \\
& (\langle\mid\rangle):: \text { Parser } a \rightarrow \text { Parser } a \rightarrow \text { Parser } a \\
& (P p)\langle\mid\rangle(P q)=P(\lambda c s \rightarrow \text { case } p c s+q c s \text { of } \\
& \text { [] } \rightarrow \text { [] } \\
& (x: x s) \rightarrow[x])
\end{aligned}
$$

pzero :: Parser a
pzero $=P(\lambda c s \rightarrow[])$

$$
\begin{aligned}
& \text { item }:: \text { Parser Char } \\
& \text { item }=P(\lambda c s \rightarrow \text { case } c s \text { of } \\
& \qquad \quad[] \quad \rightarrow[] \\
& \quad(c: c s) \rightarrow[(c, c s)])
\end{aligned}
$$

Alternatives are represented by a deterministic choice operator $(\langle\mid\rangle)$, which returns at most one result. The parser pzero is a parser that always fails. The item parser returns the first character in the input string.

We can use these simple parser combinators to define parsers for bits and bit strings. The binary sum is calculated as the exclusive or of the bits of the parsed sequence. We write $\oplus$ to denote exclusive or over the type Bit.

$$
\begin{aligned}
& \text { data } \text { Bit }=Z \mid O \\
& \text { bit :: Parser Bit } \\
& \text { bit }=\text { do } c \leftarrow i t e m \\
& \text { case } c \text { of ' } 0 \text { ' } \rightarrow \text { return } Z \\
& \text { '1' } \rightarrow \text { return } O \\
& -\quad \rightarrow \text { pzero } \\
& \text { bitstring :: Parser ([Bit], Bit) } \\
& \text { bitstring }=\text { do } b \quad \leftarrow \text { bit } \\
& (b s, s) \leftarrow \text { bitstring } \\
& \text { return }(b: b s, b \oplus s) \\
& \langle\mid\rangle \text { return ([], Z) }
\end{aligned}
$$

Now, we implement the transformation function:

```
transform :: \(([\) Bit \(]\), Bit \() \rightarrow[\) Bit \(]\)
transform ([],_) \(=\) []
transform \((b: b s, s)=(b \oplus s):\) transform \((b s, s)\)
```

In summary, the transformation consists of:

```
shift :: Parser [Bit]
shift \(=\mathbf{d o}(b s, s) \leftarrow\) bitstring
    return (transform (bs,s))
```

We may notice that the above solution constructs an intermediate list of bits that we would like to eliminate with fusion. The fusion law to be used is a law in the style of shortcut fusion, similar to that conceived for the derivation of purely functional circular programs [9], but with the difference that now it deals with monadic functions. Below, we present the specific instance for lists (which is the type of the intermediate structure), and in Section 4 we show that both the law and the programs schemes respond to generic definitions that can be formulated for several datatypes.

Like in standard shortcut fusion [14], our law assumes that the producer and the consumer (bitstring and transform in this case) are expressed in terms of certain program schemes. In standard shortcut fusion the consumer is required to be given by a structural recursive definition in terms of a recursion scheme called fold (usually called foldr in the case of lists [2]). In our law, we also require the consumer to be given by a structural recursive definition, but in terms of a variation of fold, called pfold, which admits as input an additional constant parameter to be used along the recursive calls:

$$
\begin{aligned}
\operatorname{pfold}_{L}:: & (z \rightarrow b, a \rightarrow b \rightarrow z \rightarrow b) \rightarrow([a], z) \rightarrow b \\
\operatorname{pfold}_{L}(h n i l, h c o n s)= & p_{L} \\
\text { where } p_{L}([], z) & =\text { hnil } z \\
p_{L}(a: a s, z) & =\text { hcons a }\left(p_{L}(a s, z)\right) z
\end{aligned}
$$

Like in standard shortcut fusion, we require the producer to be able to show that the list constructors can be abstracted from the process that generates the intermediate list. The difference with the standard case is that we consider producers that generate the intermediate list as part of a pair which in turn is the result of monadic computation. This is expressed by a function called mbuildp $p_{L}$ :

$$
\begin{aligned}
& \operatorname{mbuildp}_{L}:: \text { Monad } m \\
& \quad \Rightarrow(\forall b \cdot(b, a \rightarrow b \rightarrow b) \rightarrow m(b, z)) \rightarrow m([a], z) \\
& m b u i l d p_{L} g=g([],(:))
\end{aligned}
$$

Having stated the forms required to the producer and the consumer it is now possible to formulate the law.

LAW 2.1 (PFOLD/MBUILDP FOR LISTS). Let $m$ be a recursive monad.

$$
\begin{aligned}
& \text { do }(x s, z) \leftarrow{\text { mbuild } p_{L} g} \\
& \quad \text { return }\left(\text { pfold }_{L}(\text { hnil }, \text { hcons })(x s, z)\right) \\
& = \\
& \text { mdo }(v, z) \leftarrow \text { let knil }=\text { hnil } z \\
& \quad \text { kcons } x y=\text { hcons } x \text { y } z \\
& \text { in } g(\text { knil, kcons })
\end{aligned}
$$

This law transforms a monadic composition, where the producer is an effectful function but may not necessarily the consumer be, into a single monadic function with a circular argument $z$. Indeed, $z$ is a value computed by $g$ (knil, kcons) but in turn used by knil and kcons. An interesting feature of this law is the fact that the introduction of the circularity needs the use of a recursive binding within a monadic computation, and therefore require the monad to be recursive [8]. A recursive do (mdo-notation) is supported by Haskell for those monads that are declared an instance of the MonadFix class.

$$
\begin{aligned}
& \text { class Monad } m \Rightarrow \text { MonadFix } m \text { where } \\
& \quad m f i x::(a \rightarrow m a) \rightarrow m a
\end{aligned}
$$

The parsing monad presented above can be declared an instance of this class:

```
instance MonadFix Parser where
    \(m f i x f=P\left(\lambda c s \rightarrow \operatorname{mfixL}\left(\lambda^{\sim}(x, y) \rightarrow\right.\right.\) parse \(\left.\left.(f x) c s\right)\right)\)
        where
            \(\begin{aligned} \text { mfixL } f=\text { case } f i x & (f \circ \text { head }) \text { of } \\ {[] \quad } & \rightarrow[] \\ \left.(x:)_{-}\right) & \rightarrow x: m f i x L(\text { tail } \circ f)\end{aligned}\)
```

To see the law in action, we write transform and bitstring in terms of $p f o l d_{L}$ and $m b u i l d p_{L}$, respectively:

$$
\begin{aligned}
& \text { transform }=\text { pfold }_{L} \text { (hnil, hcons) } \\
& \text { where hnil_ }=[] \\
& h \text { cons brs }=(b \oplus s): r \\
& \text { bitstring }=\text { mbuild }_{L} g \\
& \text { where } g \text { (nil, cons })=\text { do } b \quad \leftarrow \text { bit } \\
& (b s, s) \leftarrow g(\text { nil }, \text { cons }) \\
& \text { return (cons b bs, } b \oplus s \text { ) } \\
& \langle\mid\rangle \text { return (nil, Z) }
\end{aligned}
$$

Then, by applying Law 2.1 we obtain:

$$
\begin{aligned}
& \text { shift }=\mathbf{m d o}(b s, s) \leftarrow g([], \lambda b r \rightarrow(b \oplus s): r) \\
& \text { return bs }
\end{aligned}
$$

Inlining, we get the following circular monadic program:

$$
\begin{aligned}
& \text { shift }=\mathbf{m d o}(b s, s) \leftarrow \text { let } g k=\text { do } b \leftarrow b i t \\
&\left(b s^{\prime}, s^{\prime}\right) \leftarrow g k \\
& \operatorname{return}\left((b \oplus s): b s^{\prime},\right. \\
&\left.b \oplus s^{\prime}\right)
\end{aligned} \quad \begin{aligned}
& \text { in } g k \\
& \langle\mid\rangle \text { return }([], Z)
\end{aligned}
$$

The above program avoids the construction of the intermediate list of bits, by introducing a circular definition. Indeed, we may notice that $s$ (the modulo 2 sum of an input sequence of bits) is used (in $b \oplus s$ ) in the function call to $g k$. However, $s$ is also a result of that same call, hence the circularity.

## 3. A Simple Programming Environment

Let us now consider that we wish to construct a program to deal with the scope rules of a simple programming language ${ }^{1}$.

A program in our language, such as the one presented below, consists in a sequence of instructions, where each instruction may either be the declaration or the use of a variable.
[use $x ; \operatorname{decl} x ; \operatorname{decl} x ;$ use $y ;$ ]
In order to be well formed, programs in our language must follow these scope rules:

1. all used variables must be declared. The declaration of a variable, however, may occur after its first use;
2. a variable must be declared at most once.

We aim to develop a semantic function that analyzes a sequence of instructions and computes a list containing the variable identifiers of the instructions which do not obey to the rules of the language. When such an instruction is found, we also want to output

[^1]an error message explaining the programming error encountered. In order to make the problem more interesting, and also to make it easier to detect which identifiers are incorrect, we require that the list of invalid identifiers follows the sequential structure of the input program. Thus, the semantic meaning of processing the example sentence is $[x, y]$ : variable $x$ has been declared twice, and the use of variable $y$ has no binding occurrence at all. As a sideeffect of computing this list, the following error messages must be displayed:

## Duplicate: decl $x$ <br> Missing: decl $y$

Because we allow an use-before-declare discipline, a conventional implementation of the required analysis naturally leads to a program which traverses the abstract syntax tree twice: once for accumulating the declarations of identifiers and constructing the environment, and once for checking the uses of identifiers, according to the computed environment.

The uniqueness of names is detected in the first traversal: for each newly encountered declaration it is checked whether that identifier has already been declared. In this case an error is computed. The second traversal receives the global environment of the program and detects the variables that are used without being declared.

In a straightforward implementation of the semantic function, this strategy has two important consequences: the first is that a "gluing" data structure has to be constructed to explicitly pass the detected errors from the first to the second traversal in order to compute the final list of errors in the desired order; the second is that, in order to be able to compute the missing declarations of a program, it is necessary to pass from the first to the second traversal the names of the variables that are used in the program.

The abstract syntax of the language may be described by the following data type definitions:

$$
\begin{array}{r}
\text { type } \operatorname{Prog}=[I t] \quad \text { data } I t=\text { Decl String } \\
\mid \text { Use String }
\end{array}
$$

In order to pass the necessary information from the first to the second traversal of a program, we define:

$$
\begin{array}{r}
\text { type } \operatorname{Prog}_{2}=\left[I t_{2}\right] \quad \text { data } I t_{2}=D u p l_{2} \text { String } \\
\mid U s e_{2} \text { String }
\end{array}
$$

Errors resulting from duplicate declarations are passed using constructor $\mathrm{Dupl}_{2}$.

According to the strategy defined earlier, we compute the semantic errors that occur in a program as follows:

$$
\begin{gathered}
\text { semantics }:: \text { Prog } \rightarrow I O[\text { String }] \\
\text { semantics } p=\mathbf{d o}\left(p^{\prime}, \text { env }\right) \leftarrow \text { duplicate }[] p \\
\text { missing }\left(p^{\prime}, \text { env }\right)
\end{gathered}
$$

The function duplicate detects duplicate variable declarations by collecting all the declarations occurring in a program. It is a monadic function since it needs to output error messages resulting from the errors it detects. The definition of such function is as follows ${ }^{2}$ :

```
duplicate \(::[\) String \(] \rightarrow \operatorname{Prog} \rightarrow I O\left(\operatorname{Prog}_{2},[\right.\) String \(\left.]\right)\)
duplicate \(d s[]=\) return \(([], d s)\)
duplicate ds (Decl v:p)
    \(=\mathbf{d o}\left(p^{\prime}, d s^{\prime}\right) \leftarrow\) duplicate \((v: d s) p\)
        if \((v \in d s)\)
            then do put ("Duplicate: decl" \(+v\) )
                    return \(\left(D u p l_{2} v: p^{\prime}, d s^{\prime}\right)\)
```

$$
\begin{gathered}
\text { else return }\left(p^{\prime}, d s^{\prime}\right) \\
\text { duplicate } d s(\text { Use } v: p) \\
=\operatorname{do}\left(p^{\prime}, d s^{\prime}\right) \leftarrow d u p l i c a t e ~ d s ~ \\
\text { return }\left(U s e_{2} v: p^{\prime}, d s^{\prime}\right)
\end{gathered}
$$

Besides detecting the invalid declarations, function duplicate also computes a data structure, of type $\operatorname{Prog}_{2}$, that is later traversed in order to detect variables that are used without being declared. This detection is performed by function missing, which is monadic as it also outputs error messages:

```
missing \(::\left(\operatorname{Prog}_{2},[\right.\) String \(\left.]\right) \rightarrow I O[\) String \(]\)
\(\operatorname{missing}([],-)=\operatorname{return}[]\)
missing (Dupl \(\left.l_{2} v: p, e n v\right)\)
    \(=\mathbf{d o} r \leftarrow \operatorname{missing}(p, e n v)\)
            return \((v: r)\)
missing (Use \(\left.{ }_{2} v: p, e n v\right)\)
    \(=\) do \(r \leftarrow \operatorname{missing}(p, e n v)\)
            if \((v \in e n v)\)
                then return \(r\)
            else do put ("Missing: decl" \(+v\) )
                return \((v: r)\)
```

We would like to eliminate the intermediate structure of type $\mathrm{Prog}_{2}$ generated by duplicate. If we attempted to directly apply Law 2.1 for that aim, then we would see that in this case the result of the law is a function that returns a monadic computation which in turn yields a monadic computation (and not a value) as result, that is, something of type $m\left(\begin{array}{ll}m & a\end{array}\right)$, for some $a$. This is because the consumer is also monadic. To obtain a value and not a computation as final result, it is simply necessary to run the computation. This gives the following shortcut fusion law, which requires the same schemes for consumer and producer as Law 2.1 but is able to fuse effectful functions.

LAW 3.1 (EFFECTFULL PFOLD/MBUILDP FOR LISTS). Let $m$ be a recursive monad.

$$
\begin{aligned}
& \text { do }(x s, z) \leftarrow \text { mbuild }_{L} g c \\
& \quad \text { pfold }_{L}(\text { hnil, hcons })(x s, z) \\
& = \\
& \text { mdo }(m, z) \leftarrow \text { let knil }=\text { hnil } z \\
& k c o n s x y=h \text { cons } x y z \\
& \quad \text { in } g(\text { knil, kcons }) c
\end{aligned}
$$

Observe that, in this case, hnil :: $z \rightarrow m b$ and hcons :: $a \rightarrow m b \rightarrow z \rightarrow m b$, for some monad $m$, and therefore pfold $_{L}$ (hnil, hcons) :: $([a], z) \rightarrow m b$. Also, notice that,

$$
\begin{aligned}
& \text { mbuildp } L_{L}:: \text { Monad } m \\
& \quad \Rightarrow(\forall b \cdot(b, a \rightarrow b \rightarrow b) \rightarrow c \rightarrow m(b, z)) \\
& \quad \rightarrow c \rightarrow m([a], z)
\end{aligned}
$$

that is, $m b u i l d p_{L} g$ is a function of type $c \rightarrow m([a], z)$. It is in this way that it will be considered in Section 4 when we will define the generic formulation of the laws. However, in Section 2 it was defined as a value of type $m([a], z)$ because that form is more appropriate for writing monadic parsers.

For the present example we do not need to provide the instance of the MonadFix class for the $I O$ monad as it is automatically provided by the Glasgow Haskell Compiler (GHC), which is the reference compiler we are using.

[^2]Now, if we write missing and duplicate in terms of pfold $_{L}$ and mbuild $_{L}$, respectively,

```
missing \(=\) pfold \(_{L}(\) hnil, hcons \()\)
    where
        hnil _ = return []
        hcons ( Dupl \(_{2}\) v) mr env
                \(=\mathbf{d o} r \leftarrow m r\)
                    return ( \(v: r\) )
        \(h c o n s\left(U s e_{2} v\right) m r e n v\)
            \(=\boldsymbol{d o} r \leftarrow m r\)
                if \((v \in e n v)\)
                        then return \(r\)
                        else do put ("Missing:decl" + v)
                        return ( \(v: r\) )
duplicate ds \(p=\) mbuildp \(_{L}(g d s) p\)
    where
            \(g d s(\) nil, cons \()[]=\) return (nil, ds)
            \(g d s\) (nil, cons) (Decl v:p)
            \(=\mathbf{d o}\left(p^{\prime}, d s^{\prime}\right) \leftarrow g(v: d s)(\) nil, cons \() p\)
                if \((v \in d s)\)
                    then do put ("Duplicate: decl" \(+v\) )
                    return (cons \(\left(\right.\) Dupl \(\left.\left._{2} v\right) p^{\prime}, d s^{\prime}\right)\)
                    else return \(\left(p^{\prime}, d s^{\prime}\right)\)
            \(g d s(n i l\), cons \()(U s e v: p)\)
                \(=\mathbf{d o}\left(p^{\prime}, d s^{\prime}\right) \leftarrow g d s\) (nil, cons) \(p\)
                return (cons \(\left.\left(U s e_{2} v\right) p^{\prime}, d s^{\prime}\right)\)
```

we can apply Law 3.1 to semantics obtaining a deforested circular definition, which, when inlined, gives the following:

```
semantics p
= mdo{
    (m,env)}\leftarrow\mathrm{ let
        gk ds [] = return (return [],ds)
        gk ds (Decl v:p)
            = do ( }\mp@subsup{p}{}{\prime},d\mp@subsup{s}{}{\prime})\leftarrowgk(v:ds)
                if (v\inds)
                then do put ("Duplicate:decl" + v)
                        return (do r}\leftarrow\mp@subsup{p}{}{\prime
                        return (v:r)
                            ,ds')
                else return ( }\mp@subsup{p}{}{\prime},d\mp@subsup{s}{}{\prime}
        gk ds (Use v:p)
            = do }(\mp@subsup{p}{}{\prime},d\mp@subsup{s}{}{\prime})\leftarrowgkds
                    return (do r}\leftarrow\mp@subsup{p}{}{\prime
                            if (v\inenv)
                            then return r
                            else do put ("Missing:" # v)
                                return (v:r)
                        ,ds')
            in gk [] p;
        m;}
```

Regarding the above program we may notice that it does not construct the intermediate $\operatorname{Prog}_{2}$ structure that was used in the original semantics program to glue the functions duplicate and missing together. The deforestation of such structure was achieved introducing a circular definition on the global environment of an input program (i.e., on the list of all the variables declared in such
program). Indeed, env is used, in the call to $g k$, whenever an instruction Use $v$ is found in an input program, to check whether $v$ is an element of $e n v$ or not. However, $e n v$ is also a result of the same $g k$ call, which means that $e n v$ is used at the same time it is being constructed, hence the circular definition.

## 4. Calculating circular programs, generically

In this section, we show that the definition of the program schemes pfold and mbuildp, and the pfold/mbuildp laws, presented for lists in the previous sections, are instances of generic definitions valid for a wide class of datatypes.

We write $\pi_{1}::(a, b) \rightarrow a$ and $\pi_{2}::(a, b) \rightarrow b$ to denote the product projections. Let $(f \times g)(x, y)=(f x, g y)$.

### 4.1 Data types

Generically, the structure of datatypes can be captured using the concept of a functor. A functor consists of a type constructor $F$ and a function $\operatorname{map}_{F}::(a \rightarrow b) \rightarrow(F a \rightarrow F b)$, which preserves identities and compositions: $\operatorname{map}_{F} \quad i d=i d$ and $\operatorname{map}_{F}(f \circ g)=$ $\operatorname{map}_{F} f \circ \operatorname{map}_{F} g$. A standard example of a functor is that formed by the list type constructor and the well-known map function.

Semantically speaking, recursive datatypes correspond to least fixed points of functors. Given a datatype declaration it is possible to derive a functor $F$ such that the datatype is the least solution to the equation $\tau \cong F \tau$. It is usual to write $\mu F$ to denote the type corresponding to that solution. The isomorphism between $\mu F$ and $F \mu F$ is provided by two strict functions, called $i n_{F}:: F \mu F \rightarrow$ $\mu F$ and out $::: \mu F \rightarrow F \mu F$, inverses of each other, and that pack the constructors and destructors of the datatype, respectively (see $[1,12]$ for details).

Let us consider, for example, a datatype for simple arithmetic expressions:

$$
\text { data } \operatorname{Exp}=\text { Num Int } \mid \text { Add Exp Exp }
$$

Corresponding to this datatype we can derive a functor $E$ such that:
data $E a=$ FNum Int $\mid$ FAdd $a \operatorname{a}$

$$
\begin{aligned}
& \operatorname{map}_{E}::(a \rightarrow b) \rightarrow E a \rightarrow E b \\
& \operatorname{map}_{E} f(F N u m n)=F N u m n \\
& \operatorname{map}_{E} f\left(F A d d \quad a a^{\prime}\right)=F A d d(f a)\left(f a^{\prime}\right)
\end{aligned}
$$

In this case, $\mu E \cong E x p$ and

$$
\begin{aligned}
& \text { in }_{E}:: E \mu E \rightarrow \mu E \\
& \text { in }_{E}(F N u m n)=\text { Num } n \\
& \text { in }_{E}\left(F A d d e e^{\prime}\right)=A d d \text { e } e^{\prime} \\
& \text { out }_{E}:: \mu E \rightarrow E \mu E \\
& \text { out }_{E}(\text { Num } n)=F N u m n \\
& \text { out }_{E}\left(\text { Add } e e^{\prime}\right)=F A d d e e^{\prime}
\end{aligned}
$$

In the case of lists, the structure is captured by a bifunctor $L$ (a functor on two variables) because of the presence of the type parameter. That is, $\mu(L a) \cong[a]$.

$$
\begin{aligned}
& \text { data } L a b=F N i l \mid \text { FCons ab } \\
& \operatorname{map}_{L a}::(b \rightarrow c) \rightarrow L a b \rightarrow L a c \\
& \text { map }_{L a} f F N i l \\
& \text { map }_{L a} f(\text { FCons } a b)=\text { FNil } \\
& =\text { FCons } a(f b)
\end{aligned}
$$

### 4.2 Fold

Given a functor $F$ (signature of a datatype) and a function $h:$ : $F a \rightarrow a$,fold (or catamorphism) $[3,12]$ is defined as the least function such that

$$
\begin{aligned}
& \text { fold }::(F a \rightarrow a) \rightarrow \mu F \rightarrow a \\
& \text { fold } h \circ i n_{F}=h \circ \operatorname{map}_{F}(\text { fold } h)
\end{aligned}
$$

A function $h:: F \quad a \rightarrow a$ is called an $F$-algebra. If functor $F$ is given by $n$ constructors,

$$
\operatorname{data} F a=F C_{1} \sigma_{1,1} \cdots \sigma_{1, r_{1}}|\cdots| F C_{n} \sigma_{n, 1} \cdots \sigma_{n, r_{n}}
$$

then an algebra $h:: F a \rightarrow a$ has $n$ component functions $\left(h_{1}, \ldots, h_{n}\right)$, each with type $h_{i}:: \sigma_{i, 1} \rightarrow \cdots \rightarrow \sigma_{i, r_{i}} \rightarrow a$. For example, an algebra corresponding to the functor $E$ is a function $h:: E a \rightarrow a$ of the form:

$$
\begin{aligned}
& h(F N u m n)=\operatorname{num} n \\
& h\left(F A d d a a^{\prime}\right)=a d d a a^{\prime}
\end{aligned}
$$

with component functions num $::$ Int $\rightarrow a$ and $a d d:: a \rightarrow a \rightarrow a$. In the specific instance of fold for this datatype,

$$
\begin{aligned}
& \text { fold }_{E}::(\text { Int } \rightarrow a, a \rightarrow a \rightarrow a) \rightarrow \operatorname{Exp} \rightarrow a \\
& \text { fold }_{E}(\text { num }, \text { add })(\text { Num a) } \\
& \quad=\text { num } a \\
& \text { fold }_{E}(\text { num, add })(\text { Add e e e }) \\
& \quad=\text { add }\left(\text { fold }_{E}(\text { num }, \text { add }) e\right)\left(\text { fold }_{E}(\text { num }, \text { add }) e^{\prime}\right)
\end{aligned}
$$

we write an $E$-algebra simply as a pair (num, add).
For the list datatype we can do something similar, we can write an algebra $h:: L a b \rightarrow b$ as a pair (nil, cons). Then,

$$
\begin{array}{ll}
\text { fold }_{L} & ::(b, a \rightarrow b \rightarrow b) \rightarrow[a] \rightarrow b \\
\text { fold }_{L}(\text { nil }, \text { cons })[] & =\text { nil } \\
\text { fold }_{L}(\text { nil }, \text { cons })(a: a s) & =\text { cons } a\left(\text { fold }_{L}(\text { nil }, \text { cons }) a s\right)
\end{array}
$$

The same can be done with algebras associated to other datatypes.
Fold enjoys many algebraic laws that are useful for program transformation. A well-known example is shortcut fusion [14, 13, 23] (also known as the fold/build rule), a law that is derived from a free theorem [26].

Law 4.1 (FOLD/build). For strict $h$,

$$
\text { fold } h \circ \text { build } g=g h
$$

where

$$
\begin{aligned}
& \text { build }::(\forall a .(F a \rightarrow a) \rightarrow c \rightarrow a) \rightarrow c \rightarrow \mu F \\
& \text { build } g=g \text { in }
\end{aligned}
$$

The standard example is the case for lists:

## LAW 4.2 (FOLD/BUILD FOR LISTS).

$$
\text { fold }_{L}(\text { nil }, \text { cons }) \circ \text { build }_{L} g=g(\text { nil, cons })
$$

where

$$
\begin{aligned}
& \text { build }_{L}::(\forall b \cdot(b, a \rightarrow b \rightarrow b) \rightarrow c \rightarrow b) \rightarrow c \rightarrow[a] \\
& \text { build }_{L} g=g([],(:))
\end{aligned}
$$

### 4.3 Fold with parameters

Some recursive functions use context information in the form of constant parameters for their computation. We are interested in functions of the form $f::(\mu F, z) \rightarrow a$, defined by structural recursion on $\mu F$ and with context information of type $z$. Our method will assume that consumers are functions of this kind.

Such functions can be defined in different ways. One alternative consists of fixing the value of the context information; this can be written as a fold, $f(t, z)=$ fold $h t$, such that a reference to the value $z$ may eventually occur in the algebra $h$. Another alternative
is to define a function of type $\mu F \rightarrow(z \rightarrow a)$ in terms of a higherorder fold.

In this work, we consider a third alternative consisting of defining $f::(\mu F, z) \rightarrow a$ in terms of a program scheme called pfold (a fold with parameters) [19]. The definition of pfold relies on the concept of strength of a functor $F$, a polymorphic function $\tau_{F}::(F a, z) \rightarrow F(a, z)$ that satisfies certain coherence axioms (see [19, 6] for details). The strength distributes the value of type $z$ to the variable positions (of type $a$ ) of the functor. For instance, the strength corresponding to functor $E$ is given by:

```
\(\tau_{E}::(E a, z) \rightarrow E(a, z)\)
\(\tau_{E}(\) FNum \(n, z)=\) FNum n
\(\tau_{E}\left(\right.\) FAdd \(\left.a a^{\prime}, z\right)=\operatorname{FAdd}(a, z)\left(a^{\prime}, z\right)\)
```

The strength plays an important role in the definition of pfold as it represents the distribution of the context information to the recursive calls.

Let $(f \Delta g) x=(f x, g x)$. Given a functor $F$ and a function $h::(F a, z) \rightarrow a$, pfold [19] is defined as the least function such that:

$$
\text { pfold } h \circ\left(i n_{F} \times i d\right)=h \circ\left(\left(\operatorname{map}_{F}(\text { pfold } h) \circ \tau_{F}\right) \Delta \pi_{2}\right)
$$

A function $h$ is something similar to an algebra, but it also accepts the value of the parameters. In fact, if functor $F$ is given by $n$ constructors,

$$
\operatorname{data} F a=F C_{1} \sigma_{1,1} \cdots \sigma_{1, r_{1}}|\cdots| F C_{n} \sigma_{n, 1} \cdots \sigma_{n, r_{n}}
$$

then, similar to an algebra, $h::(F a, z) \rightarrow a$ has $n$ component functions $\left(h_{1}, \ldots, h_{n}\right)$, now each with type $h_{i}:: \sigma_{i, 1} \rightarrow \cdots \rightarrow$ $\sigma_{i, r_{i}} \rightarrow z \rightarrow a$. Like with the algebras, in the specific instances of pfold we write the tuple of components functions instead of $h$. For example, for the $E$ functor,

$$
\begin{aligned}
& h::(E a, z) \rightarrow a \\
& h(\text { FNum } n, z)=\text { hnum } n z \\
& h\left(\text { FAdd } a a^{\prime}, z\right)=\text { hadd } a a^{\prime} z
\end{aligned}
$$

where hnum :: Int $\rightarrow z \rightarrow a$ and hadd $:: a \rightarrow a \rightarrow z \rightarrow a$ are the component functions. Pfold for expressions is then defined by:

```
pfold \(_{E}::(\) Int \(\rightarrow z \rightarrow a, a \rightarrow a \rightarrow z \rightarrow a) \rightarrow(E x p, z) \rightarrow a\)
pfold \(_{E}(\) hnum, \(h a d d)=p_{E}\)
    where
        \(p_{E}(\) Num \(n, z)=\) hnum \(n z\)
        \(p_{E}\left(\operatorname{Add} e e^{\prime}, z\right)=\operatorname{hadd}\left(p_{E}(e, z)\right)\left(p_{E}\left(e^{\prime}, z\right)\right) z\)
```

The following equation shows one of the possible relationships between pfold and fold. For $h$ with component functions $\left(h_{1}, \ldots, h_{n}\right)$, fixing the value $z$ we have that:

$$
\begin{equation*}
\text { pfold } h(t, z)=\text { fold } k t \text { where } k_{i} \bar{x}=h_{i} \bar{x} z \tag{1}
\end{equation*}
$$

Observe that $k$ is an algebra with components $\left(k_{1}, \ldots, k_{n}\right)$. We denote by $\bar{x}$ a sequence of values $x_{1} \cdots x_{r_{i}}$.

The laws for deriving monadic circular programs we are proposing are a monadic extension of the following one, devoted to the derivation of purely functional circular programs [9]. It takes a composition of a producer $p:: a \rightarrow(t, z)$ followed by a consumer $c::(t, z) \rightarrow b$, and returns an equivalent deforested, circular program that performs a single traversal over the input value. The law assumes that $t$ is a recursive datatype, the consumer $c$ is defined by structural recursion on $t$, and the intermediate value of type $z$ is a constant parameter for $c$; in other words, it assumes that $c$ is a pfold. In addition, it is required that $p$ is a "good producer", in the sense that it is possible to express it in terms of a kind of build. Examples of the use of this law and a proof can be found in [9].

LAW 4.3 (PFOLD/BUILDP). Let $h$ with components $\left(h_{1}, \ldots, h_{n}\right)$.

$$
\begin{aligned}
& \text { pfold } h(\text { buildp } g c) \\
& =\operatorname{let}(v, z)=g k c \\
& k_{i} \bar{x}=h_{i} \bar{x} z \\
& \quad \operatorname{in} v
\end{aligned}
$$

where
buildp $::(\forall a .(F a \rightarrow a) \rightarrow c \rightarrow(a, z)) \rightarrow c \rightarrow(\mu F, z)$
buildp $g=g i n_{F}$

### 4.4 Extended shortcut fusion

Shortcut fusion laws for monadic programs can be obtained as a special case of an extended form of shortcut fusion that captures the case when the intermediate data structure is generated as part of another structure given by a functor $[18,11]$. Such extension is based on an extended form of build: Given a functor $F$ (signature of a datatype) and another functor $N$, we can define

$$
\begin{aligned}
& \text { build }_{N}::(\forall a .(F a \rightarrow a) \rightarrow c \rightarrow N a) \rightarrow c \rightarrow N \mu F \\
& \text { build }_{N} g=g \text { in }_{F}
\end{aligned}
$$

This is a natural extension of the standard build. In fact, build can be obtained from build ${ }_{N}$ by considering the identity functor as $N$. Moreover, buildp is also a particular case obtained by considering the functor $N a=(a, z)$.

Using build $d_{N}$ it is possible to state an extended form of shortcut fusion (see $[18,11]$ for a proof):

Law 4.4 (EXTENDED FOLD/buILD). For strict $h$ and strictness preserving $N$,

$$
\operatorname{map}_{N}(f o l d h) \circ b_{i l d}^{N}, g=g h
$$

Similarly, we can also consider an extension for buildp:

$$
\begin{aligned}
\text { buildp }_{N}: & :(\forall a .(F a \rightarrow a) \rightarrow c \rightarrow N(a, z)) \\
& \rightarrow c \rightarrow N(\mu F, z) \\
\text { buildp }_{N} g= & g \text { in }_{F}
\end{aligned}
$$

with the following shortcut fusion law:
Law 4.5 (EXTENDED FOLD/buILDP). For strict $h$ and strictnesspreserving $N$,

$$
\operatorname{map}_{N}(\text { fold } h \times i d) \circ \operatorname{buildp}_{N} g=g h
$$

Proof By considering $N^{\prime} a=N(a, z)$, we have that build $p_{N} g=$ build $_{N^{\prime}} g$ and $\operatorname{map}_{N^{\prime}} f=\operatorname{map}_{N}(f \times i d)$. Then, the lefthand side of the equation can be rewritten as: $\operatorname{map}_{N^{\prime}}($ fold $h) \circ$ build $_{N^{\prime}} g$. Finally, we apply Law 4.4.

### 4.5 Monadic shortcut fusion

The case we are interested in is when the functor $N$ is the composition of a monad $m$ with a product: For some type $z$,

$$
N a=m(a, z) \quad \text { and } \quad \operatorname{map}_{N} f=\operatorname{mmap}(f \times i d)
$$

where

$$
\begin{aligned}
& \text { mmap } \quad:: \text { Monad } m \Rightarrow(a \rightarrow b) \rightarrow(m a \rightarrow m b) \\
& \text { mmap } f m=\operatorname{do}\{a \leftarrow m ; \operatorname{return}(f a)\}
\end{aligned}
$$

is the map function for the monad $m$. The producer then corresponds to a monadic version of buildp:

$$
\begin{aligned}
& \text { mbuildp }:: \text { Monad } m \\
& \quad \Rightarrow(\forall a \cdot(F a \rightarrow a) \rightarrow c \rightarrow m(a, z)) \\
& \quad \rightarrow c \rightarrow m(\mu F, z) \\
& \text { mbuildp } g=g \text { in }_{F}
\end{aligned}
$$

A monadic shortcut fusion law can be directly obtained as an instance of Law 4.5. We unfold the definition of mmap so that we get a formulation in terms of do-notation:

LAW 4.6 (FOLD/MBUILDP). For strict $k$ and strictness preserving mmap,

$$
\text { do }\{(t, z) \leftarrow \text { mbuildp } g c ; \text { return }(\text { fold } k t, z)\}=g k c
$$

This is a version for mbuildp of the shortcut fusion law introduced by Manzino and Pardo [18].

Using this law we can state a first monadic extension of the pfold/buildp rule. Observe that the introduction of the circularity on $z$ requires the monad to be recursive [8] as it is necessary the use of a circular binding within a monadic computation. In Haskell terms, this can be expressed using the mdo-notation provided that the monad is an instance of the MonadFix class.

LAW 4.7 (PFOLD/MBUILDP). Let $m$ be a recursive monad with strictness-preserving mmap. For $h$ with components $\left(h_{1}, \ldots, h_{n}\right)$ and strict,

$$
\begin{aligned}
& \quad \text { do }\{(t, z) \leftarrow \text { mbuildp } g c ; \text { return }(\text { pfold } h(t, z))\} \\
& = \\
& \quad \boldsymbol{\operatorname { m d o }}\left\{(v, z) \leftarrow \operatorname{let} k_{i} \bar{x}=h_{i} \bar{x} z \operatorname{in} g k c ; \text { return } v\right\}
\end{aligned}
$$

## Proof

$$
\left.\begin{array}{rl} 
& \left.\left.\begin{array}{c}
\text { do }\{(t, z) \leftarrow \text { mbuildp } g \text { c; return }(p f o l d ~
\end{array}(t, z)\right)\right\} \\
= & \{(1)\}
\end{array}\right\}
$$

The circularity introduced is safe and therefore computations can be ordered under lay evaluation. In fact, to compute $v$ it is necessary to compute $z^{\prime}$, which in turn depends on $z$. That is, even with the introduction of the circularity, the computation of the final value depends on the computation of the second value computed by the mbuildp $g c$.

When the consumer is also an effectful function, it is possible to state two other laws, similar to Laws 4.6 and 4.7, respectively, but that deal with fusion of effectful functions. The formulation of these laws follow the approach presented by Chitil [5] and Ghani and Johann [11].

LAW 4.8 (EFFECTFUL FOLD/MBUILDP). For strict $k:: F(m a) \rightarrow$ $m a$ and strictness preserving mmap,

$$
\begin{aligned}
& \quad \text { do }\{(t, z) \leftarrow \text { mbuildp } g c ; v \leftarrow \text { fold } k t ; \text { return }(v, z)\} \\
& = \\
& \quad \text { do }\{(m, z) \leftarrow g k c ; v \leftarrow m ; \operatorname{return}(v, z)\}
\end{aligned}
$$

## Proof

```
do \(\{(t, z) \leftarrow\) mbuildp \(g c ; v \leftarrow\) fold \(k t\); return \((v, z)\}\)
    \(=\mathbf{d o}(t, z) \leftarrow\) mbuildp \(g c\)
        \(\left(m,{ }_{-}\right) \leftarrow\) return \((\) fold \(k t, z)\)
        \(v \quad \leftarrow m\)
        return \((v, z)\)
    \(=\mathbf{d o}(m, z) \leftarrow \mathbf{d o}(t, z) \leftarrow\) mbuildp \(g c\)
                return (fold \(k t, z\) )
        \(v \quad \leftarrow m\)
        return \((v, z)\)
    \(=\operatorname{do}\{(m, z) \leftarrow g k c ; v \leftarrow m ; \operatorname{return}(v, z)\}\)
```

Using this law we can now state a shortcut fusion law for the derivation of monadic circular programs in those cases when both the producer and consumer are effectful functions. Again, like in Law 4.7, the monad is required to be recursive because of the introduction of a recursive binding within the monadic computation.

LAW 4.9 (EFFECTFUL PFOLD/MBUILDP). Let $m$ be a recursive monad with strictness-preserving mmap. For $h::\left(F\left(\begin{array}{ll}m & a\end{array}\right), z\right) \rightarrow$ $m$ a with components $\left(h_{1}, \ldots, h_{n}\right)$ and strict,

$$
\begin{aligned}
& \operatorname{do}\{(t, z) \leftarrow \operatorname{mbuild} p g c ; \text { pfold } h(t, z)\} \\
&= \\
& \quad \operatorname{mdo}\left\{(m, z) \leftarrow \operatorname{let} k_{i} \bar{x}=h_{i} \bar{x} z \operatorname{in} g k c ; m\right\}
\end{aligned}
$$

## Proof

do $\{(t, z) \leftarrow$ mbuildp $g$ c;pfold $h(t, z)\}$
$=$
do $(t, z) \leftarrow$ mbuildp $g c$

$$
m \leftarrow \operatorname{return}(\text { pfold } h(t, z))
$$

$m$

```
= { Law 4.7 }
    mdo}{(m,z)\leftarrow\operatorname{let}\mp@subsup{k}{i}{}\overline{x}=\mp@subsup{h}{i}{}\overline{x}z\mathrm{ in }gkc;m
```


## 5. Higher-order shortcut fusion

There exists an alternative way to transform compositions between pfold and buildp such that, instead of circular programs, higherorder programs are obtained as result. Obtaining higher-order programs is attractive since the execution of such programs is not restricted to a lazy evaluation setting. Furthermore, the running performance of a higher-order program is often better than the performance of its circular equivalent.

The alternative transformation presented in this section is based on the fact that every pfold can be expressed in terms of a higherorder fold: For $h::(F a, z) \rightarrow a$,

$$
\begin{equation*}
\text { pfold } h=\text { apply } \circ\left(\text { fold } \varphi_{h} \times i d\right) \tag{2}
\end{equation*}
$$

where $\varphi_{h}:: F(z \rightarrow a) \rightarrow(z \rightarrow a)$ is given by

$$
\varphi_{h}=\operatorname{curry}\left(h \circ\left(\left(\operatorname{map}_{F} \text { apply } \circ \tau_{F}\right) \Delta \pi_{2}\right)\right)
$$

and apply $::(a \rightarrow b, a) \rightarrow b$ by apply $(f, x)=f x$. Therefore, fold $\varphi_{h}:: \mu F \rightarrow(z \rightarrow a)$ is the curried version of $p$ fold $h$.

With this relationship at hand we can state the following shortcut fusion law, which is the instance to our context of a more general program transformation technique called lambda abstraction [20]. The specific case of this law when lists are the intermediate structure was recently introduced by Voigtländer [25].

LAW 5.1 (HIGHER-ORDER PFOLD/BUILDP). For left-strict $h,{ }^{3}$

$$
\text { pfold } h \circ \text { buildp } g=\text { apply } \circ g \varphi_{h}
$$

Like in the derivation of circular programs, $g \varphi_{h}$ returns a pair, but now composed by a function of type $z \rightarrow a$ and an object of type $z$. The final result then corresponds to the application of the function to the object. That is,

$$
\text { pfold } h(\text { buildp } g c)=\operatorname{let}(f, z)=g \varphi_{h} c \operatorname{in} f z
$$

Of course, this law can be generalized in the sense of extended shortcut fusion.

LAW 5.2. For left-strict $h$ and strictness-preserving $N$,

$$
\operatorname{map}_{N}(\text { pfold } h) \circ b u i l d p_{N} g=\operatorname{map}_{N} \text { apply } \circ g \varphi_{h}
$$

## Proof

$\operatorname{map}_{N}($ pfold $h) \circ$ buildp ${ }_{N} g$
$=\{(2)\}$
$\operatorname{map}_{N} \operatorname{apply} \circ \operatorname{map}_{N}\left(\right.$ fold $\left.\varphi_{h} \times i d\right) \circ b u i l d p_{N} g$
$=\quad\{$ Law 4.5$\}$
$m a p_{N}$ apply $\circ g \varphi_{h}$

Like in Subsection 4.5, we can consider the particular case when $N$ is the functor of a monad. Unlike the transformation to circular programs, now we do not need to require the monad to be recursive. Again, in first place we state the case when the pfold is a pure function.

LAW 5.3 (HIGHER-ORDER PFOLD/MBUILDP). For left-strict $h$ and strictness-preserving mmap,

$$
\begin{aligned}
& \text { do }\{(t, z) \leftarrow \text { mbuildp } g \text { c; return }(\text { pfold } h(t, z))\} \\
= & \\
& \text { do }\left\{(f, z) \leftarrow g \varphi_{h} c ; \text { return }(f z)\right\}
\end{aligned}
$$

To see an example of the application of this law we consider again function shift from Section 2:

$$
\begin{aligned}
& \text { shift }:: \text { Parser }[\text { Bit }] \\
& \text { shift }=\mathbf{d o}(b s, s) \leftarrow \text { bitstring } \\
& \qquad \text { return }(\text { transform }(b s, s))
\end{aligned}
$$

and write the higher-order fold corresponding to transform:

$$
\begin{aligned}
& \text { transform }_{h o}::[\text { Bit }] \rightarrow(\text { Bit } \rightarrow[\text { Bit }]) \\
& \text { transform }_{h o}=\text { fold }_{L}\left(\varphi_{n}, \varphi_{c}\right) \\
& \\
& \left.\qquad \begin{array}{rl}
\text { where } \varphi_{n} & =\lambda_{-} \rightarrow[] \\
\varphi_{c} & b r
\end{array}\right] \lambda s \rightarrow(b \oplus s): r s
\end{aligned}
$$

Then, by applying Law 5.3 we obtain:

$$
\begin{gathered}
\text { shift }_{h o}=\operatorname{do}(f, s) \leftarrow g\left(\varphi_{n}, \varphi_{c}\right) \\
\text { return }(f s)
\end{gathered}
$$

[^3]Inlining,

$$
\begin{aligned}
& \text { shift }_{h o}=\mathbf{d o}(f, s) \leftarrow g_{\varphi} \\
& \qquad \begin{array}{r}
\text { return }(f s) \\
\text { where } g_{\varphi}= \\
\text { do } b \quad \leftarrow \text { bit } \\
\\
(f, s) \leftarrow g_{\varphi} \\
\text { return }\left(\lambda s^{\prime} \rightarrow\left(b \oplus s^{\prime}\right): f s^{\prime}, b \oplus s\right) \\
\langle\mid\rangle \text { return }\left(\lambda_{-} \rightarrow[], Z\right)
\end{array}
\end{aligned}
$$

Finally, we present the case when the consumer is also an effectful function.

LAW 5.4 (EFFECTFUL HIGHER-ORDER PFOLD/MBUILDP). For left-strict $h::\left(\begin{array}{ll}F & (m a), z) \rightarrow m a n d ~ s t r i c t n e s s-p r e s e r v i n g ~\end{array}\right.$ mmap,

$$
\begin{aligned}
& \quad \text { do }\{(t, z) \leftarrow \text { mbuildp } g \text { c; pfold } h(t, z)\} \\
& = \\
& \\
& \text { do }\left\{(f, z) \leftarrow g \varphi_{h} c ; f z\right\}
\end{aligned}
$$

## Proof

do $\{(t, z) \leftarrow$ mbuildp $g c$; pfold $h(t, z)\}$
$=$
do $(t, z) \leftarrow$ mbuildp $g c$
$m \leftarrow \operatorname{return}(p f o l d h(t, z))$
$m$
$=\quad\{$ Law 5.3$\}$
do $m \leftarrow$ do $\left\{(f, z) \leftarrow g \varphi_{h} c ;\right.$ return $\left.(f z)\right\}$
$m$
$=$

$$
\text { do }\left\{(f, z) \leftarrow g \varphi_{h} c ; f z\right\}
$$

We conclude this section with an example of the application of this law. To this end we consider again the function semantics presented in Section 3:

```
semantics \(::\) Prog \(\rightarrow I O[\) String \(]\)
semantics \(p=\mathbf{d o}\left(p^{\prime}\right.\), env \() \leftarrow\) duplicate [] \(p\)
    \(\operatorname{missing}\left(p^{\prime}, e n v\right)\)
```

To apply the law we need the expression of the algebra of the higher-order fold, which corresponds to the curried version of missing:

$$
\begin{aligned}
& \text { missing }_{h_{o}}:: \text { Prog }_{2} \rightarrow([\text { String }] \rightarrow I O[\text { String }]) \\
& \text { missing }_{\text {ho }}=\text { fold }_{L}\left(\varphi_{n}, \varphi_{c}\right) \\
& \varphi_{n}=\lambda_{-} \rightarrow \text { return [] } \\
& \varphi_{c}\left(D u p l_{2} v\right) m r \\
& =\lambda e n v \rightarrow \text { do } r \leftarrow m r \text { env } \\
& \text { return ( } v: r \text { ) } \\
& \varphi_{c}\left(U s e_{2} v\right) m r \\
& =\lambda e n v \rightarrow \mathbf{d o} r \leftarrow m r \text { env } \\
& \text { if }(v \in e n v) \\
& \text { then return } r \\
& \text { else do put ("Missing:decl" }+v \text { ) } \\
& \text { return }(v: r)
\end{aligned}
$$

Then, by Law 5.4 we obtain:

$$
\begin{gathered}
\text { semantics }_{h o}=\mathbf{d o}\left(\underset{f \text { env }}{ }(\mathrm{env}) \leftarrow g\left(\varphi_{n}, \varphi_{c}\right)\right. \\
\hline
\end{gathered}
$$

Inlining this definition, we finally derive the higher-order program:

$$
\begin{gathered}
\text { semantics }_{h o}=\mathbf{d o}(f, e n v) \leftarrow g_{\varphi} \\
f \text { env }
\end{gathered}
$$

where

$$
\begin{aligned}
& g_{\varphi} d s[]=\text { return }\left(\lambda_{-} \rightarrow \text { return }[], d s\right) \\
& g_{\varphi} d s(\text { Decl } v: p) \\
& =\operatorname{do}\left(p^{\prime}, d s^{\prime}\right) \leftarrow g_{\varphi}(v: d s) p \\
& \quad \text { if }(v \in d s) \\
& \text { then do put ("Duplicate }: \operatorname{decl} "+v) \\
& \text { return }\left(\lambda e n v \rightarrow \operatorname{do} r \leftarrow p^{\prime}\right. \text { env } \\
& \quad \text { return }(v: r)
\end{aligned}
$$

else return $\left(p^{\prime}, d s^{\prime}\right)$
$g_{\varphi} d s($ Use $v: p)$

$$
=\boldsymbol{d o}\left(p^{\prime}, d s^{\prime}\right) \leftarrow g_{\varphi} d s p
$$

return (
$\lambda e n v \rightarrow$

$$
\text { do } r \leftarrow p^{\prime} e n v
$$

if $(v \in e n v)$
then return $r$
else do put ("Missing:decl" $+v$ )
return ( $v: r$ )
,$\left.d s^{\prime}\right)$

## 6. Conclusions and Future Work

### 6.1 Contributions

In this paper, we have presented shortcut fusion rules for the derivation of circular and higher-order monadic programs. The rules are generic, as they can be instantiated for a wide class of algebraic data types and monads. We have also shown two example applications which demonstrate the practical interest of the rules.

It is possible to obtain a prototype implementation of the rules using the rewrite rules (RULES pragma) of the Glasgow Haskell Compiler (GHC). Experimental results showing time and space comparisons for a set of examples are available in the webpage http://www.fing.edu.uy/~~pardo/ExtendedShortcut/.

The main contributions of this paper can be summarized as follows:
(i) using an extension to shortcut fusion that captures the cases when the intermediate structures are generated as part of another structure given by a functor, we obtained shortcut fusion rules that transform compositions of monadic programs into circular programs. This extends to monadic programs the work we have presented for pure programs in [9].
(ii) we generalized the shortcut fusion rule for deriving pure higherorder programs presented in [25] so that it can be applied to compositions of programs with an arbitrary data type as intermediate structure.
(iii) we presented an extension of the above rule for the derivation of higher-order programs to the case of monadic programs.

The following diagram summarizes the results that have been achieved so far:


The arrow from cons $\circ$ prod to circular programs corresponds to the rules developed in this work and in [9]. The arrow from cons o prod to higher-order programs corresponds to (ii) and (iii) above. The arrows from circular programs to cons $\circ$ prod and higher-order programs correspond to the transformations based on Attribute Grammar techniques presented in [10].

### 6.2 Future work

Various aspects of the ideas presented in this paper deserve further elaboration.

Multiple intermediate structure elimination The examples we presented in this paper consist of compositions of a single producer and consumer functions. We would like, however, to be able to achieve the same fusion goals for programs consisting in an arbitrary number of function compositions. Indeed, we are now studying how to generalize our work in order to optimize programs of the form $f_{n} \circ \ldots \circ f_{1}$ such that in each composition a data structure $t_{i}$ and a value $z_{i}$ are produced. We will describe such a generalization in a forthcoming paper, already under preparation.

Relation with Attribute Grammars Circular programs, monads and attribute grammars (AGs) are closely related [21]. Indeed, AG techniques are used to model and manipulate circular programs in order to derive efficient non-lazy equivalent programs [10], and several circular-based AG systems have been developed [22, 28]. In particular, we would like to express the transformations in [10] (the dashed arrows in the diagram above) in a calculational form, so that their correctness can be proved. Indeed, although these techniques are largely used by the AG community, their correctness remains to be formally proved! The techniques studied in this paper also serve the purpose of increasing the knowledge on the relation between circular programs and AGs, and, therefore, bring us close to our goal of building a proved correct AG system.

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[^1]:    ${ }^{1}$ Due to space limitations, we consider a simplified version of the Algol 68 rules only. The complete definition may be found in [7], and is used as a generic library for the name analysis task of the Eli system [27].

[^2]:    ${ }^{2}$ We abbreviate putStrLn as put.

[^3]:    ${ }^{3}$ By left-strict we mean strict on the first argument, that is, $h(\perp, z)=\perp$.

