



A New Approach to Evaluate and Reduce Uncertainty of Model-Based Biodiversity Projections for Conservation Policy Formulation

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Biodiversity projections with uncertainty estimates under different climate, land-use, and policy scenarios are essential to setting and achieving international targets to mitigate biodiversity loss. Evaluating and improving biodiversity predictions to better inform policy decisions remains a central conservation goal and challenge. A comprehensive strategy to evaluate and reduce uncertainty of model outputs against observed measurements and multiple models would help to produce more robust biodiversity predictions. We propose an approach that integrates biodiversity models and emerging remote sensing and in-situ data streams to evaluate and reduce uncertainty with the goal of improving policy-relevant biodiversity predictions. In this article, we describe a multivariate approach to directly and indirectly evaluate and constrain model uncertainty, demonstrate a proof of concept of this approach, embed the concept within the broader context of model evaluation and scenario analysis for conservation policy, and highlight lessons from other modeling communities.

Keywords: biodiversity conservation, predictive modeling, biodiversity policy, remote sensing, Essential Biodiversity Variables

Among the most urgent challenges for society and conservation today are predicting and mitigating loss of biodiversity and ecosystem services (IPBES 2019). With the potential of 1 million species to go extinct in the coming decades, developing better tools for projecting biodiversity change is vital (IPBES 2019). Currently, no single model can capture all the dimensions of biodiversity change resulting from environmental and anthropogenic impacts (Pereira et al. 2010). Consequently, modelers have developed a range of biodiversity models and scenarios to predict change across multiple dimensions of biodiversity (IPBES 2016). The diversity of models enhances researchers' ability to predict change in a myriad of individual biodiversity variables, including species distribution and abundance, species traits and genetic composition, community composition, and ecosystem structure and function (Fulton et al. 2011, Lacy et al. 2013, Pacifici et al. 2015, Ikeda et al. 2017, Landguth et al. 2017). This array of possible predicted variables makes it challenging to integrate model predictions to better understand large-scale biodiversity change. However, the

diversity in models can be advantageous and also presents an opportunity to develop new strategies to evaluate, reduce uncertainty, and increase confidence in model predictions for decision-makers (Araújo et al. 2005, Akçakaya et al. 2016, Honrado et al. 2016, IPBES 2016).

Decision-makers use biodiversity projections to develop and implement policy actions for biodiversity conservation and must make decisions despite uncertainty in the projections (Wilson 2002, CBD 2010). Model-based projections can be used both to inform the formulation of targets and to identify and prioritize actions (e.g., target implementation; Dietze et al. 2018). High-accuracy biodiversity estimates increase decision-makers' confidence in model outputs (Regan et al. 2005, Akçakaya et al. 2016). To evaluate model performance, researchers can compare model outputs with observations and from multiple models to quantify the precision and accuracy of multimodel predictions (Zurell et al. 2016). For example, Morin and Thuiller (2009) compared uncertainty in range shift predictions from niche-based and process-based models. These multimodel predictions

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improved understanding of species range shifts (Morin and Thuiller 2009). Other efforts to improve model predictions have focused on comparing similar biodiversity variables (e.g., range shifts and species distributions) from different model types (Araújo et al. 2005, Morin and Thuiller 2009, Zurell et al. 2016). The biodiversity modeling community continues to make strides in quantifying and reducing uncertainty ~~for models~~ through model intercomparison efforts (Rosa et al. 2020). However, additional approaches to evaluate and reduce uncertainty in model-based biodiversity projections to improve model outputs is a priority (Akçakaya et al. 2016). We identified a pressing need for improved model–data fusion approaches to evaluate and constrain uncertainty using multiple data streams (e.g., remote sensing and in-situ observations). We also expand on Akçakaya and colleagues' (2016) charge to use diverse biodiversity models to improve model outputs.

The challenges in improving biodiversity models are unique compared with other modeling communities (e.g., climate modeling). For one, biological and ecological processes, such as changes in species interactions and adaptation to a stressor, can be complex and difficult to predict (Ibáñez et al. 2006, Jackson et al. 2009, Purves et al. 2013, Harfoot et al. 2014, Bay et al. 2018). Second, there is currently no standard means to compare biodiversity model outputs, which creates challenges when comparing outputs to estimate uncertainty (Rosa et al. 2020). Finally, there is no consistent process to take advantage of the multiple monitoring and varied data streams for improving model outputs (Akçakaya et al. 2016, Honrado et al. 2016). Biodiversity researchers and decision-makers are actively addressing these issues. For example, the Group on Earth Observations Biodiversity Observation Network (GEO BON) is developing Essential Biodiversity Variables (EBVs), defined as the derived measurements required to study and report on biodiversity change (Pereira et al. 2013). EBVs include common biodiversity variables such as species distributions, abundance, trait diversity, genetic diversity, and taxonomic diversity. The EBV framework was developed to harmonize observations and model outputs into comparable and monitorable variables (Pereira et al. 2013, Navarro et al. 2017). Recent efforts have used the EBV framework to combine outputs from multiple models to quantify uncertainty across models (Rosa et al. 2020). Therefore, this is a particularly opportune time to explore novel approaches to evaluate and reduce uncertainty in model-based biodiversity projections and contribute to this active field of research.

Given these challenges and opportunities, clearer strategies are needed for biodiversity model evaluation to inform future formulation of biodiversity policy (Tittensor et al. 2014, IPBES 2016). International science-policy efforts such as the Convention on Biological Diversity's (CBD) post-2020 biodiversity agenda (CBD 2017), continued identification of EBVs, and the Intergovernmental Science-Policy Platform on Biodiversity and Ecosystem Services (IPBES) global assessment report have highlighted the urgency of biodiversity

forecasting and conservation to society (Essential biodiversity 2019, IPBES 2019). In addition, there has been a rapid increase in the quantity and diversity of data available to inform biodiversity assessments, including a wide array of remote sensing, field observations (e.g., the TRY trait database), metagenomics, and citizen science (Silvertown 2009, Theobald et al. 2015, Balasingham et al. 2018). Evaluating and using these data streams requires expertise as well as advanced modeling approaches to harness the abundance of available observations (Akçakaya et al. 2016).

In the present article, we address these stated biodiversity community and strategic needs by proposing a novel multivariate approach to directly and indirectly evaluate and reduce uncertainty of multiscale model predictions. First, we use multiple data sources to directly constrain model-based predictions of biodiversity variables. We then combine this step with a multivariate indirect constraint between models that predict related biodiversity variables to evaluate and jointly reduce uncertainty. Our approach leverages distinct models and allows for the evaluation and reduction of uncertainty across multiple dimensions of biodiversity in an ecosystem. Collectively, we describe the proposed multivariate approach to evaluate and directly and indirectly reduce model uncertainty, outline a proof of concept application to illustrate this approach and how it could be applied to other models and variables, embed the concept within the broader context of model testing and scenario analysis for conservation policy, and highlight lessons from other modeling communities that could be applied to improve biodiversity model outputs.

Multivariate approach to evaluating and reducing uncertainty in model-based biodiversity projections

Biodiversity variables are linked by physical, biological, and ecological processes, many of which are described quantitatively in models (Harfoot et al. 2014). We used this interdependency among biodiversity variables to develop a multivariate approach to evaluate and reduce uncertainty in model-based biodiversity projections. We illustrate the two-step process conceptually in figure 1 using a generic EBV and a biodiversity variable. The approach is flexible in that modelers can apply any two models predicting related biodiversity variables, but we used EBVs in our example to better link to ongoing biodiversity monitoring processes. Our approach involves two main steps to reduce uncertainty in biodiversity projections. Step 1 illustrates a univariate constraint on uncertainty in initial conditions via remote sensing and in-situ observations of a biodiversity variable (figure 1, step 1). Step 2 applies a novel multivariate constraint on uncertainty via model overlap using the same models from step 1 of two biologically or ecologically related biodiversity variables (figure 1, step 2). Following step 2, we can repeat the process iteratively to directly constrain the biodiversity variables using remote sensing or in-situ observations and indirectly constrain the related biodiversity variables through reanalysis (figure 1, steps 1–2). The direct

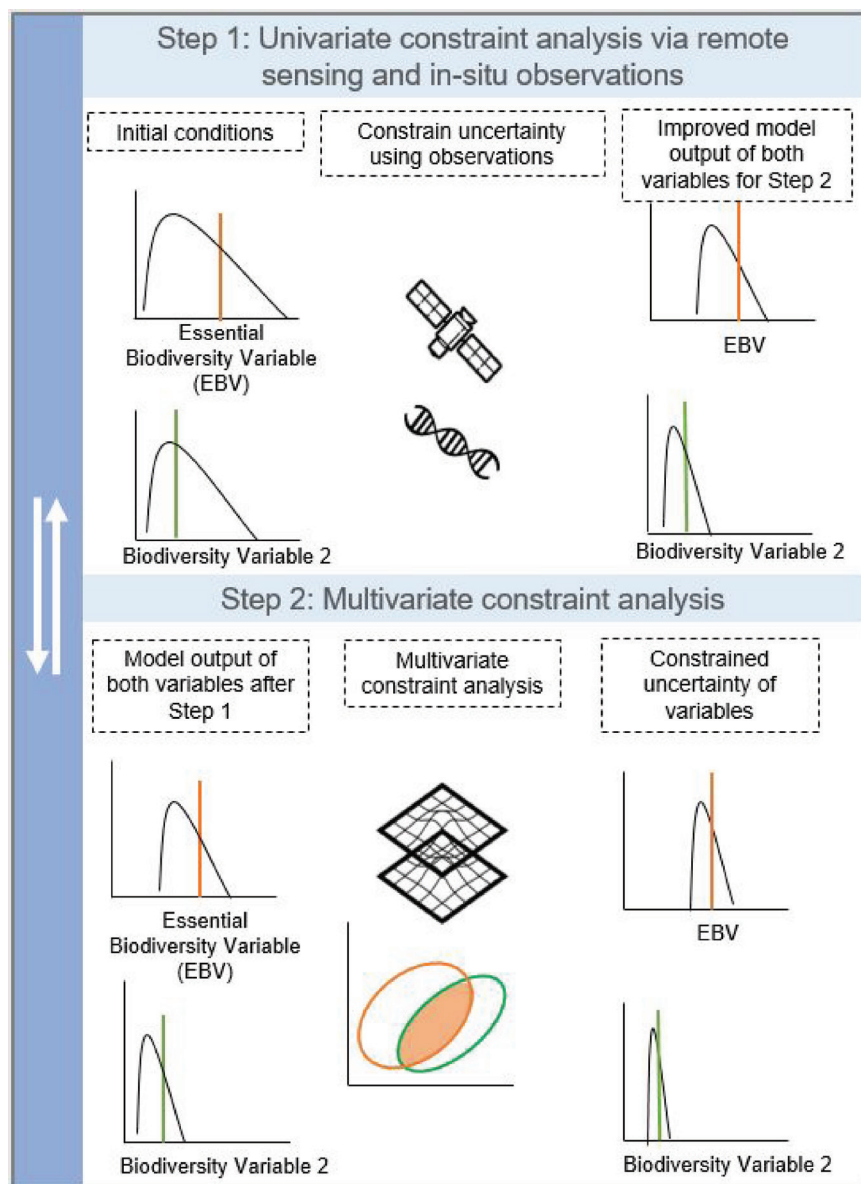


Figure 1. Schematic leveraging multiple biodiversity model outputs, remote sensing, and in-situ observations to evaluate and constrain uncertainty of biodiversity variables. Step 1 illustrates direct constraints using remote sensing and in-situ observations of an EBV and a related biodiversity variable. Step 2 illustrates a multivariate constraint of EBV uncertainty and the related biodiversity variable 2 output from two different models via model overlap.

constraint of uncertainty using remote sensing and in-situ observations of a predicted biodiversity variable in step 1 is common practice in modeling (Pasetto et al. 2018); the novelty of our approach lies in the indirect constraint outlined in step 2 and described in more detail below.

The relationship between the two related biodiversity model outputs is key in step 2. We argue that overlap of model-based predictions of different but related biodiversity variables can be used to indirectly constrain uncertainty of combined multiple model outputs (figure 1, step 2). Conceptually, if one biodiversity model predicts a

biodiversity variable and another predicts a related biodiversity variable, and a set of observations is capable of constraining model predictions of one of those variables, then that set of observations can indirectly constrain model predictions of both variables (figure 1). This is based on the model predictions of the related biodiversity variables being biologically or ecologically linked, and the two variables having a mechanistic connection in one of the models. This link allows for joint probability density functions of the related biodiversity predictions (see the proof of concept below). Using this link, our approach can inform predictions in areas with sparse observations. That is, if an area has missing data (e.g., high cloud cover in remote sensing images) but there is strong internal model covariance between related variables with another model variable, then that undersampled area would still receive informed predictions from the multivariate constraint step and not be based purely on a uniformed base model estimate. Modelers can use this process iteratively to both directly and indirectly constrain uncertainty by integrating new remote sensing, in situ, or emerging biodiversity relevant technologies that become available (figure 1). Repeated improvement iterations can be done even when new observations become available for only one of the related variables in the multivariate process. Therefore, new observations for one variable would reduce uncertainty for both related biodiversity variables using this approach.

For the multivariate constraint approach to function effectively, indirect constraints must have strong covariances (i.e., if two variables are only weakly related in a model then they will be ineffective constraints on each other). Covariances can be positive or negative depending on the relationship between the variables. If the covariance is 0 or weak, then the multivariate constraint approach will be less informative and is not recommended. Furthermore, confidence in these constraints depends on confidence that models are capturing relationships between variables accurately (Zurell et al. 2016). Therefore, effective model–data integration within the approach will work best with diverse models and diverse data sets. The models should have adequately described

uncertainties in their measurements, and account for the predictive variance introduced by competing hypotheses about relevant processes as well as errors, biases, and scaling issues of different data sources. This approach also relies on obtaining accurate observed measurements of biodiversity variables and their uncertainty estimates. We propose that such remote sensing observation data could also fine-tune model structure or reparameterize initial conditions where appropriate. This two-step multivariate approach could facilitate the evaluation and could reduce the uncertainty of a single model or a diverse array of biodiversity models against wide-ranging observations, including those derivable from hyperspectral or lidar-based remote sensing, environmental metagenomics, and long-term monitoring programs. Our proposed two-step multivariate approach results would yield improved biodiversity predictions for policy formulation, including for the next generation of biodiversity targets and EBVs (Bush et al. 2017). In our conceptual diagram, the EBV is linked to a related biodiversity variable physically, biologically, or ecologically (figure 1). We highlight one of the biodiversity variables as an EBV in figure 1; however, our approach could be applied to any two related biodiversity variables regardless if they are considered EBVs. Modelers or decision-makers can choose the relevant models and variables for their needs.

Proof of concept: MstMIP, Madingley model, and in-situ observations of moose density

Using various remote sensing and other observations to directly constrain initial conditions and assess accuracy of model-based predictions is fairly straightforward (Pasetto et al. 2018). Although we demonstrate the direct constraint of initial conditions with observations, in the proof of concept, we focus primarily on the novel aspect of our approach, which is the multivariate constraint of uncertainty via model overlap (figure 1, step 2). As a proof of concept of the multivariate constraint approach, we developed a simple joint analysis of live aboveground vegetation biomass and population density of moose (*Alces alces*) in North America. This analysis uses information from a combination of models and observations and demonstrates how a model that jointly predicts moose density and aboveground vegetation biomass allows us to use information from one variable to indirectly constrain other variables (figures 2–5).

First, we obtained aboveground vegetation biomass estimates from the North American Carbon Program Multi-Scale Synthesis and Terrestrial Model Intercomparison Project (MstMIP; Huntzinger et al. 2018). The complete data set includes global gridded 0.5×0.5 degree simulations from 15 different terrestrial biosphere models at monthly and yearly time steps for the period 1900–2010. For each model and each pixel within North America, we calculated the mean biomass estimate from the monthly estimates for the period 1990–2010. We then generated a normal distribution of biomass for each pixel by taking the sample mean and standard deviation across the 15

models. A map of the resulting mean estimates is shown in figure 2a.

Second, we obtained estimates of aboveground vegetation biomass and moose population density from existing global gridded ensemble simulations of the Madingley model (Harfoot et al. 2014). The ensemble consisted of six different simulations with varying parameters and initial conditions. The Madingley model provides estimates of the total foliar biomass. To derive live aboveground vegetation biomass, we first extracted the predicted autotroph biomass density from each ensemble member for each pixel in North America. To convert the total foliar biomass to total live aboveground vegetation biomass, we multiplied these values by 10, on the basis of allometric relationships between foliar and total biomass in Bond-Lamberty and colleagues (2002). A map of the resulting mean estimates of vegetation biomass is shown in figure 2b. The Madingley model produces population estimates of terrestrial herbivores on the basis of diet and body mass. To get moose density from the Madingley model, we extracted the predicted adult population of each cohort of terrestrial herbivores whose body mass was greater than 400 kilograms (kg) for each pixel. Our criteria effectively excluded the other two largest wild herbivores in North America: white-tailed deer *Odocoileus virginianus*, whose adult mass is typically less than 100 kg, and most subspecies of elk *Cervus canadensis*, whose adult mass is typically less than 350 kg (Webb et al. 2014, Murie 2017). Adult mass of Roosevelt elk *Cervus canadensis roosevelti* can reach as high as 400 kg, but their geographic extent is relatively limited compared with moose and they only occasionally exceed a body mass of 400 kg (Brunt 1990). We then calculated the population density within each pixel by taking the sum of the populations of all cohorts meeting the criteria above and dividing by the area of each pixel. A map of the resulting mean estimates of moose density is illustrated in figure 3.

Finally, we obtained a separate gridded estimate of moose density from the North Dakota Fish and Game Department (Jensen et al. 2018). We first converted the shapefile of moose density to a raster matching the grid of the above using the “rasterize” function in the R package “raster” (Hijmans 2020). This data set did not come with uncertainty estimates, so we assumed a uniform relative standard deviation of 10% of the stated value for every pixel.

For each of the four modeled and observed data sets above—vegetation biomass (X_1) from MstMIP and the Madingley model and moose density (X_2) from the Madingley model and Jensen and colleagues (2018)—we have rasters of means (μ) and standard deviations (σ) from each pixel shown in equation 1 below. The rasters of means are shown in figure 2a and 2b and in figure 3a and 3b. For an initial evaluation of agreement between these estimates, we calculated the probability of overlap of the corresponding distributions as follows: For each pixel and each variable, we calculated

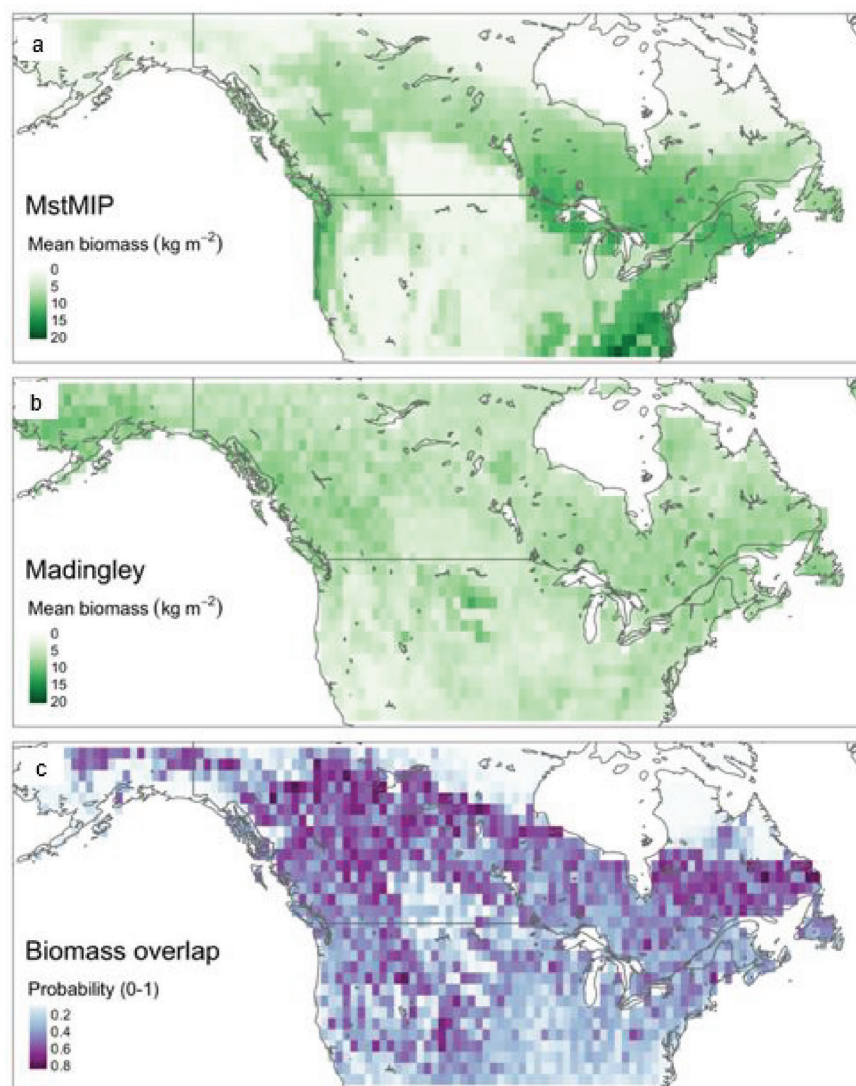


Figure 2. Mean estimates of vegetation biomass (in kilograms per square meter) from the MstMIP multimodel ensemble (a), the Madingley model ensemble (b), and the fraction of distribution overlap of the vegetation biomass estimates and their uncertainties for each pixel (c).

the minimum of the corresponding probability density function (equation 2) and numerically integrated the resulting values over all regions of nontrivial probability density (equation 3):

$$X_1 \sim N(\mu_1, \sigma_1), X_2 \sim N(\mu_2, \sigma_2) \quad (1)$$

$$P(\text{overlap}|x) = \min(N(x|\mu_1, \sigma_1), N(x|\mu_2, \sigma_2)) \quad (2)$$

$$P(\text{overlap}) = \int_{-\infty}^{\infty} P(\text{overlap}|x) dx \quad (3)$$

The resulting gridded estimates of overlap for vegetation biomass and moose density are shown in the figures 2c and 3c, respectively.

We performed two different kinds of constraint on the output variables: A univariate constraint where moose density and biomass were each constrained independently of one another highlighting step 1 in figure 1, and a multivariate constraint whereby they were constrained jointly illustrating step 2 in figure 1. In the univariate constraint, because we assume both variables are normally distributed, we can analytically calculate the best estimate of each variable (X_{best}) from the distributions of its estimates (equation 4):

$$X_{\text{best}} \sim N(\mu_{\text{best}}, \sigma_{\text{best}}) \quad (4)$$

$$\mu_{\text{best}} = \frac{\mu_1 \tau_1 + \mu_2 \tau_2}{\tau_1 + \tau_2}$$

$$\sigma_{\text{best}} = \sqrt{\frac{1}{\tau_{\text{best}}}}$$

$$\tau_{\text{best}} = \tau_1 + \tau_2$$

$$\tau_1 = \frac{1}{\sigma_1^2}, \tau_2 = \frac{1}{\sigma_2^2}$$

τ_n represents the Kendall rank correlation coefficient for variable n in the equation above, where σ^2 represents the variance of the variable estimates. The results of the independent univariate constraints on each variable are shown in figure 4.

The multivariate distribution of the six Madingley ensemble members was not well approximated by a multivariate normal distribution. Therefore, we performed this constraint numerically, by weighting each Madingley ensemble member according to its agreement with MstMIP vegetation biomass and observed moose density. Our final best estimate of vegetation biomass and moose density was the weighted average of predictions across all Madingley ensemble members. The highest weights were assigned to Madingley ensemble members that agree closely with MstMIP vegetation biomass or observed moose density. Ensemble members that agree with only one of these two data sets are given lower weight, and ensemble members that agree with neither data set are given the lowest weights. Importantly, this weighting scheme considers differences between Madingley predictions and the data relative to the uncertainties in the data.

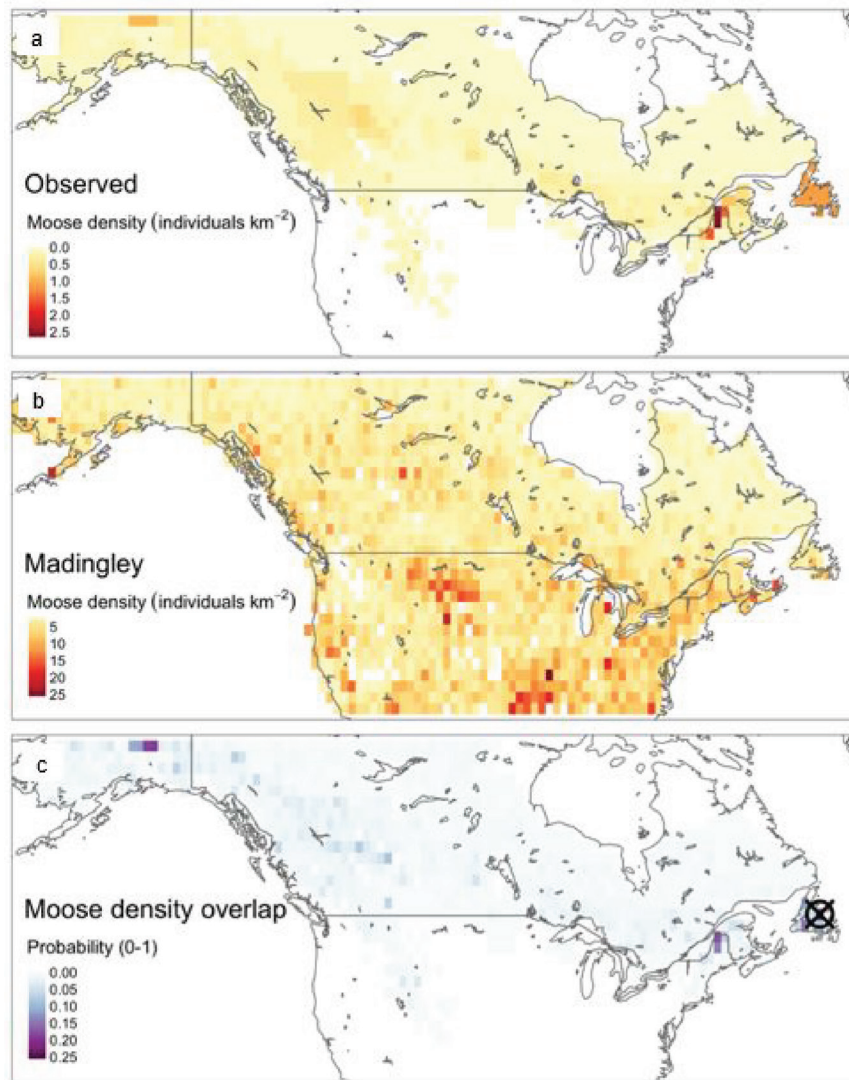


Figure 3. Moose density (in individuals per square kilometer) from in-situ observations (a). Mean estimates of moose density from a six-member ensemble simulation of the Madingley model (b). The agreement between moose density observations (a) and Madingley estimates (b) for each pixel (c), expressed as the overlap between the pixel-specific probability distributions (equation 1). The pixel used for the multivariate constraint analysis is indicated by the symbol in panel c.

Formally, d_i and b_i represent the estimates of moose density and biomass, respectively, by Madingley ensemble member i . Also, μ_b and σ_b represent the mean and standard deviation of the distribution of MstMIP biomass estimates, μ_d and σ_d represent the analogous quantities for observed moose density, and n be the number of Madingley ensemble members. The likelihood, $P(i)$, of the Madingley ensemble member i given the MstMIP vegetation biomass predictions and moose density observations is therefore given by the following equation:

$$P(i) = N(d_i | \mu_d, \sigma_d) N(b_i | \mu_b, \sigma_b) \quad (5)$$

We define the weight w_i of each ensemble member as the normalized likelihood:

$$w_i = \frac{P(i)}{\sum_i^n P(i)} \quad (6)$$

The general solution to determining the final best estimates of variables constrained using such a multivariate approach is to use these weights to do weighted random sampling of the model ensemble predictions and then calculate summary statistics (e.g., sample mean, variance, covariance) from these samples. However, in our specific example, because we assume both terms in the earlier equation are normally distributed, the final jointly constrained marginal distribution of biomass also follows a normal distribution with analytical solutions for the mean μ_b^* (calculated as the weighted average of biomass estimates) and standard deviation σ_b^* (calculated as the weighted standard deviation of biomass estimates):

$$\mu_b^* = \sum_i^n w_i b_i \quad (7)$$

$$\sigma_b^* = \sqrt{\sum_i^n w_i (b_i - \mu_b^*)^2} \quad (8)$$

Analogous equations were used for moose density.

For the joint constraint to produce meaningful and useful results, the distributions of the underlying variables need to have nontrivial overlap for both variables of interest. In practice, this means that the subset of model ensemble members that produce values within the range of observations (and vice versa) should be large enough to allow statistical inference.

If there is no overlap between the model and observations, that strongly suggests that there is a problem with the model. In our proof of concept, although this was often true for vegetation biomass (figure 2), overlap in moose density estimates was poor in all but a few specific locations (figure 3), resulting in poor joint constraint results in most places. Therefore, we show the joint constraint analysis described above for one specific pixel.

We recognize that the above procedure includes many simplistic assumptions, both scientifically and statistically, and therefore the results of this analysis should only be taken as a proof-of-concept illustration and are not meant to be robust. Rather, our objective is to show a simple example

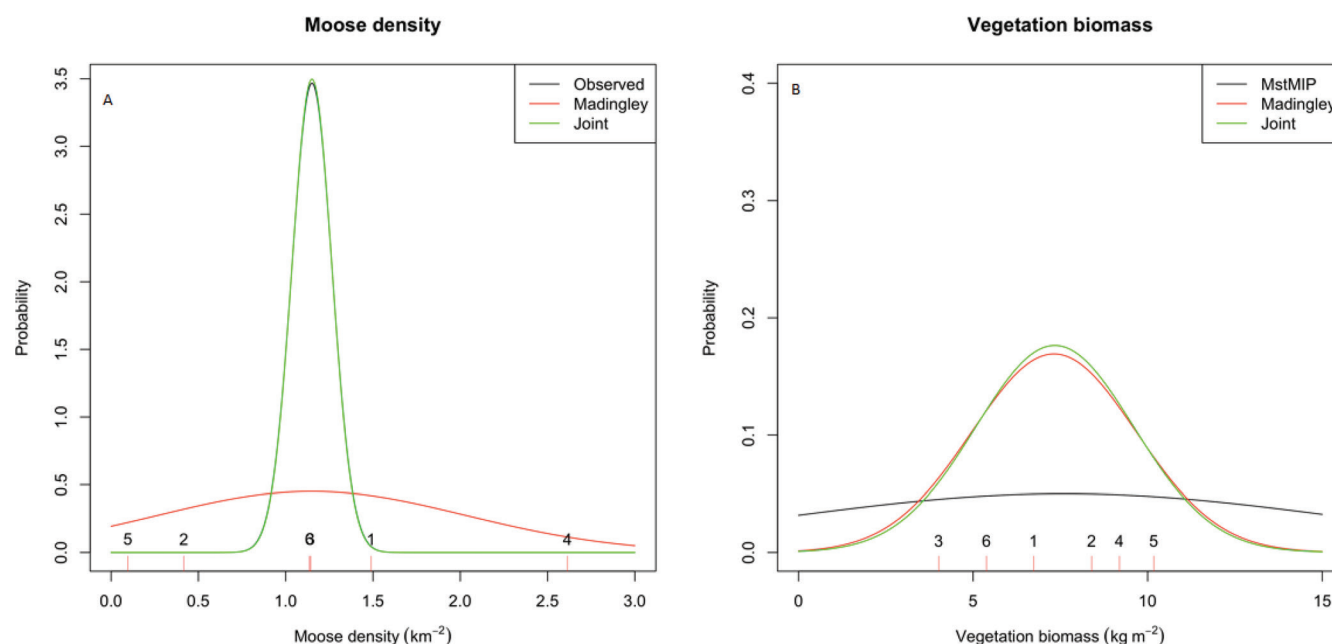


Figure 4. Results of the univariate constraint analysis. The black lines are the distribution of observed moose density (a) and the MstMIP ensemble estimates of vegetation biomass (b). The labeled red dashes indicate individual predictions from the six Madingley ensemble members, and the red line in each figure is the normal distribution approximated by this six-member ensemble (i.e., parameterized according to the sample mean and standard deviation calculated from the six-member ensemble). The green lines show the best-estimate distribution from combining the model estimates and observations for moose density and the MstMIP and Madingley model estimates of vegetation biomass. In panel (a), the black moose density line tracks the green line (described below) almost perfectly making it difficult to distinguish on the graph.

of reducing uncertainty via indirect constraints from output variables of different models and with observations. In real settings, more careful consideration should be given to the choice of distributions (or, nonparametric techniques such as bootstrapping can be used) and to the processing steps used to align different variables. Where possible, we recommend running large model ensembles (100s or 1000s of members), much more than our six, so that calculations of summary statistics (e.g., sample mean and variance) on even relatively small subsets of these ensembles are as robust as possible. Where distributions have to be assumed, practitioners should try to pick distributions appropriate to the data; for instance, a Poisson distribution is a good choice for discrete count data, although a rescaled beta distribution is good choice for data that have both lower and upper bounds (e.g., fractions). In comparing models with data, it is important to remember that every transformation that requires some assumptions about the data (e.g., our assumptions about the ratio of foliar biomass to total vegetation biomass, interpolation, spatial or temporal disaggregation) introduces additional uncertainties, so such transformations should be avoided wherever possible.

Proof of concept results. Uncertainty was reduced using our two-step multivariate approach. The univariate step (step 1) directly constrained uncertainty of the Madingley

model predictions of moose density and vegetation biomass (figure 4). The univariate observed moose density estimates when combined with the Madingley model prediction reduced uncertainty in the probability distribution, which tracked with the in-situ observations (figure 4). The joint estimates of MstMIP and Madingley also improved the vegetation biomass estimates compared with MstMIP alone. The multivariate joint analysis of both moose density and vegetation biomass further constrained both variable outputs (figure 5). Overall, the proof of concept showed the utility of the multivariate approach in evaluating and reducing model uncertainty by leveraging multiple data streams and different model outputs (figure 5).

Role in iterative biodiversity model testing and improvement.

Biodiversity model testing, comparison, and improvement using multiple data streams is an active field of research that is continuously and rapidly advancing (Akçakaya et al. 2016, Honrado et al. 2016, Ferrier et al. 2017, Dietze et al. 2018, Rosa et al. 2020). Model-based projections of biodiversity change used in policy and decision support are generated by combining scenarios of drivers (e.g., land use and climate change) with policy options for addressing these drivers (IPBES 2016, Ferrier et al. 2017). Our proposed multivariate approach fits into a broader model testing and improvement framework where models translate policy scenarios

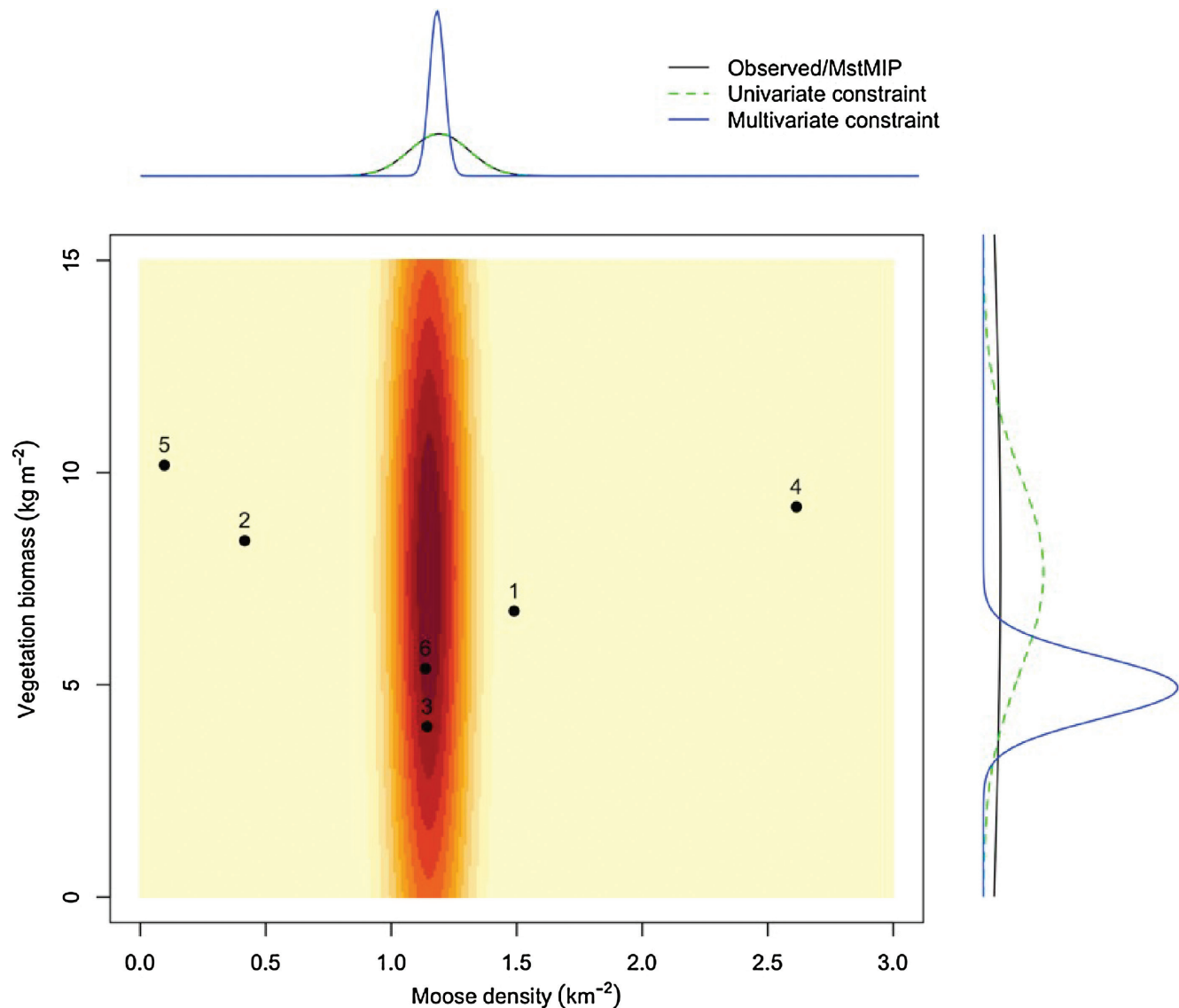


Figure 5. Results of the multivariate constraint analysis outlined in figure 1 step 2. The labeled black dots are the six Madingley ensemble joint estimates of moose density (in individuals per square kilometer) and vegetation biomass (in kilograms per square meter). The shading indicates the joint probability of moose density and vegetation biomass based on the MstMIP/observed distributions represented by the black lines in the marginal density plot. The blue lines in the marginal density plot represent the marginal distribution of the two variables after the multivariate constraint has been applied. The green dashed lines in the marginal plots show the distribution of the estimates from figure 4 if only the univariate constraint step is applied.

into expected consequences for biodiversity with clear error envelopes to convey the range of potential outcomes (figure 6). The approach can be applied at different stages in this process, from assessing how well past models performed to reducing uncertainty in future projections.

First, we recommend rerunning previously developed models using observed drivers of change and applying the two-step multivariate constraint approach to assess model performance. This would provide insight into how well the models, either individually or collectively, predicted the past. For example, researchers could rerun a model of

predicted biodiversity change in response to climate and land use change variables as the dominant drivers, with reconstructions of the actual changes over a certain time period (e.g., 1950–2000) by applying step 1 (figure 6). The same strategy could also predict how well models predict the present status of EBVs and other biodiversity variables (figure 6; Ferrier et al. 2017). In some cases, model predictions could be compared with observed biodiversity changes (e.g., remote sensing-enabled EBVs or the subset of EBVs that have features capable of being characterized using satellite-based remote sensing; figure 6; Pettorelli et al. 2016a, 2016b).

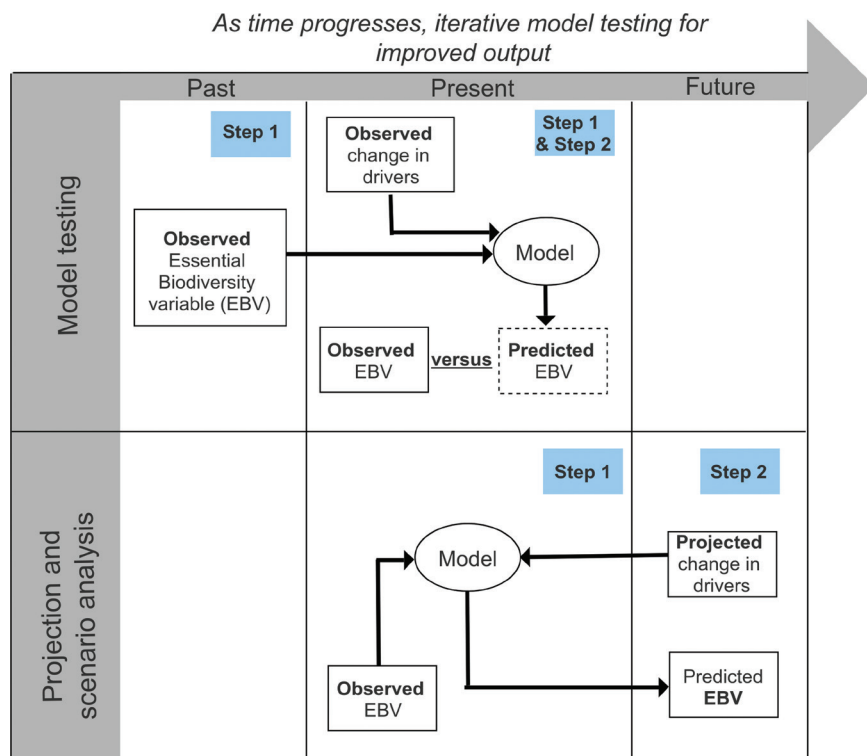


Figure 6. Framing of the multivariate approach to evaluating and reducing uncertainty in model-based biodiversity projections within a broader model testing and biodiversity policy and decision-making context. The approach to constrain biodiversity uncertainty via both univariate (step 1 from figure 1) and multivariate constraints (step 2 from figure 1) are mapped in the present article to show at what time step (past, present, or future) remote sensing, in-situ observations, and multimodel overlap of related biodiversity variables can directly constrain initial conditions of an EBV (past), directly and indirectly constrain EBV uncertainty to improve and refine model output (present), and indirectly constrain uncertainty of EBV projections (future).

This model evaluation and uncertainty analysis can also be performed iteratively over time using updated observations to continuously improve predictions of EBVs or other biodiversity variables and refine models.

Secondly, projection and scenario analysis that informs policy and decision-making could also benefit from applying our multivariate approach. For example, the observed EBV in figure 6 would provide the starting condition to project changes in biodiversity on the basis of projected drivers of change. The multivariate constraint approach could then be applied to reduce uncertainty in the projected EBVs (figures 1 and 6). Using different projections of drivers, depending on policy decisions, projected changes in biodiversity could be compared to inform the best policy alternatives to conserve biodiversity (Kim et al. 2018). These two components of iterative model testing could be run in parallel, at regular intervals in time to determine if actual changes in biodiversity aligned with projections based on which policy was selected. Although we focus on climate and land use as the main drivers of biodiversity change, these

are not the sole drivers that influence species populations. For example, commercial exploitation, recreational and subsistence hunting and fishing, invasive species, disease, and other use and nonuse drivers of biodiversity change are important factors to take into consideration when using this approach in the broader context of scenario analysis (IPBES 2019).

Throughout this article, we have placed a particular focus on remotely sensed EBVs. This is because satellite-based remote sensing is valuable for monitoring large-scale biodiversity change because of its global and repeated coverage (Pettorelli et al. 2016b). Therefore, the remote sensing-enabled EBVs may serve to link model-based projections to observed variables (e.g., aboveground vegetation biomass) and non-remote sensing observable variables (e.g., mammal densities) using multivariate model constraints. Satellite-based remote sensing technology can be especially useful for understanding ecosystem function and structure and these capabilities continue to expand (Jetz et al. 2016, Murray et al. 2018, Pettoelli et al. 2018). In addition, remotely sensed EBVs may be a useful way to provide more time-series data for model calibration and validation (Rosa et al. 2020). Thus far, scientists have focused mainly on identifying satellite data that can help detect past-to-present change in ecosystems and

thereby support reporting requirements on target achievement. However, in addition to assessing and reporting on biodiversity change, multiscale (i.e., tower, drone, aircraft, satellite) remote sensing observations could also serve as a rapid-response, cost-effective means to test and improve model-based projections with observed data (Shiklomanov et al. 2019).

In the present article, we presented one potential application of our proposed approach, but this approach could be applied to other remote sensing variables beyond biodiversity variables, as long as the models or variables are physically, biologically, or ecologically linked. Other emerging technologies, such as eDNA could also be used in our approach. Recent advances in genetic technologies provide novel opportunities to detect distribution and abundance of organisms that leave traces of DNA in the environment, including seawater, fresh water, soil, snow, and air (Pilliod et al. 2013, Lacoursiere-Roussel et al. 2016). For example, metabarcoding and next-generation sequencing of eDNA was used to detect three species at risk, an

invasive species, and 78 native species from two tributary rivers to the Great Lakes in Canada (Balasingham et al. 2018). More case studies would reveal best practices in using the multivariate approach and would be a valuable exercise. Care needs to be taken, because a key component of this approach is that the models accurately capture the unique biological, ecological, and physical links in ecosystems and accurately predict biodiversity variables; our multivariate constraint depends on the strength of the relationships in the models (Harfoot et al. 2014). However, the iterative approach that we propose, including using in situ or remote-sensing observations to constrain model output, will allow the update of models as understanding of these relationships improves.

Strategies from other modeling communities. Biodiversity modeling has already and could continue to benefit from building on successes from other communities by learning from what worked and did not work to avoid similar pitfalls as advances are made (McMahon et al. 2011). Applying lessons from climate, agricultural, and other modeling communities for improving models could ultimately improve our multivariate approach by increasing overall model accuracy. These lessons fall into three categories: strengthening the community of practice, improving cooperation across relevant disciplines, and better adaptation of remote sensing products.

First, leveraging existing communities of practice (e.g., GEO BON; Navarro et al. 2017), and establishing a cross-community network can facilitate solutions that use appropriate expertise, address challenges and goals, and prevent the need to overcome established institutional frameworks. Much of the advances in climate modeling have been facilitated by the World Climate Research Programme, which organizes working groups to encourage engagement and systematic development across research and application groups. Through these interactions, models are often developed with goals of integration into larger climate and earth system models, allowing nested models to share boundary variables or creating interchangeable modules and parameterizations. Groundwork for common variables, formal documentation, scenario design, and the dissemination of outputs allow for coordinated climate projections (Taylor et al. 2012, Eyring et al. 2016a), stakeholder-relevant applications (Ruane et al. 2016), and user-oriented evaluation metrics (Eyring et al. 2016b). In recent years, the biodiversity modeling community has made strides through IPBES and The Inter-Sectoral Impact Model Intercomparison Project to conduct intercomparison efforts. For example, these model intercomparison efforts projected global biodiversity change in marine and terrestrial ecosystems under different climate change and economic scenarios (Kim et al. 2018, Tittensor et al. 2018, Rosa et al. 2020). These efforts identified ongoing challenges in producing biodiversity projections. Biodiversity model intercomparisons and related efforts to improve models could benefit from engaging and coordinating with other disciplines to develop best practices. Such efforts could include

the Agricultural Model Intercomparison and Improvement Project (AgMIP) within the agricultural modeling community, Observations for Model Intercomparison Projects initiative (Obs4MIPS; Teixeira et al. 2014), and the International Land Model Benchmarking (ILAMB) framework to formulate curated data sets with similar grids and variable specifications to the Coupled Modeled Intercomparison Project (CMIP) model outputs (Collier et al. 2004). AgMIP developed tools to connect disciplines and scales for model inputs and outputs and to allow consistently nested driving scenarios (Valdivia et al. 2015, Rosenzweig et al. 2016). AgMIP underscored the importance of protocol-based analyses centered on clear questions and observations for validation along with inclusive leadership efforts (Rosenzweig et al. 2013, Rosenzweig et al. 2016). It was most successful when pilot intercomparisons framed a specific question, spatial domain, set of data for model configuration, driving scenarios, and output template.

Finally, adaptation or development of remote sensing specific to biodiversity models could improve model accuracy. In the cryospheric science community, remote sensing data product scientists have interacted with cryospheric climate modelers to adapt remote sensing data products toward climate model requirements (e.g., Hall et al. 2018). Designing observational tools, networks, and easily accessible data portals to provide information for model ingestion and validation would also be helpful. A greater push to make model code and forecasts publicly available would help the biodiversity modeling community test projections (Mislán et al. 2016, Dietze et al. 2018). EBV development could benefit from some of the approaches used by ILAMB and Obs4MIPs. These projects translate observations to be directly comparable with model outputs in a way that allows improved validation exercises. A similar “Obs4Impacts” was proposed by the Vulnerability, Impacts, Adaptation and Climate Services Advisory Board for CMIP6, which would locate and process remote sensing and related observational data sets to make them useful for model applications that could include components of biodiversity (Ruane et al. 2016). Strengthening the community of practice, cross collaboration, and adaptation and application of new remote sensing products could contribute to improved biodiversity model accuracy for target formulation and implementation.

Policy relevance. Policymakers use biodiversity goals and targets, such as the CBD Aichi Biodiversity Targets, to define agreed outcomes for biodiversity to be achieved in a given time period (CBD 2010). Although the aim is for these targets to be science based, previous targets have been adopted even when biodiversity information was lacking. The proposed process could be most useful for increasing confidence in target setting and decision-making, because it would provide more accurate model-based information on current and future changes in biodiversity and improve the models used for these projections (Regan et al. 2005).

Most of the current Aichi targets were not met by the 2020 target (CBD 2020). As the CBD develops the post-2020 biodiversity framework, there has been a push to consider lessons learned from the Aichi targets. One important lesson is that the next round of targets should “be ambitious but realistic, recognizing that ambition without realism can undermine confidence in the ability to deliver on targets” (CBD 2018). In addition to increased realism, targets should also encourage meaningful conservation outcomes (Di Marco et al. 2016). By improving the scenarios and models used to predict future states of biodiversity and assess the impact of policy interventions, the approach described in the present article would contribute to the development of biodiversity predictions with less uncertainty. More trusted scenarios and models are necessary for effective conservation policy (Akçakaya et al. 2016) and could help identify a range of plausible targets in conjunction with other aspects and interests policymakers consider.

Finally, because we have reached the end of the Strategic Plan for Biodiversity 2011–2020, we need a better mechanism to assess progress, such as addressing what policies worked and which models effectively projected the observed changes in biodiversity. This task is hampered by the fact that several Aichi targets had indicators that were not well aligned with the goal or lack indicators altogether (Tittensor et al. 2014). Using remote sensing-enabled EBVs to test, evaluate, and improve future projections from models used to formulate and implement targets is an important extension of the current EBV agenda. However, for this to happen, agreement is needed on which EBVs to monitor to better align with model-based biodiversity projections (Skidmore and Pettorelli 2015) and coordination is needed to expand monitoring in conservation (Honrado et al. 2016). Former, current and forthcoming government and commercial high spectral, spatial and temporal resolution sensors hold promise for establishing benchmarks on the state of the world’s ecosystems against which future changes can be compared (Transon et al. 2018). Our approach could drive model development toward specific key EBVs and guide resource allocation to monitoring programs or remote sensing capabilities to continuously gather EBV observations to improve the predictive accuracy of models.

Conclusions

The IPBES global assessment report on biodiversity and ecosystem services stresses the urgency of continuing to improve on biodiversity forecasting under future scenarios (IPBES 2019). The wealth of remote sensing, metagenomics, and citizen science data would help scientifically establish data-informed biodiversity conservation targets. Our approach illustrates the power of linking observations with multiple biodiversity model outputs to directly and indirectly evaluate and reduce uncertainty of model-based predictions. The novelty of this approach is that uncertainty is jointly constrained for biodiversity variables of different taxa and functional groups, providing improvements of

outputs from multiple dimensions of biodiversity—a need for future biodiversity model intercomparison efforts (Rosa et al. 2020). The approach also fits into the broader context of model testing and projection and scenario analysis for identification of alternative policies. Applying lessons from other modeling communities, such as climate and agriculture, coupled with the use of our approach could improve model-based biodiversity predictions for future policy actions. We highlighted the need for reliable, data-driven, and continuously improved forecasts of biodiversity to assess policy options and make science-based decisions in an ever-changing world (IPBES 2016). The proposed process meets this crucial requirement by providing a data-driven method to evaluate and improve biodiversity model outputs to better inform biodiversity conservation policy.

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