

ACCEPTED VERSION

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Evolutionary computation for digital art

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Evolutionary Computation for Digital Art

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seekLIGHT

Introduction and Motivation

Link to the Current Version

The current version is available at:

<https://researchers.adelaide.edu.au/profile/aneta.neumann>

<https://vimeo.com/anetaneumann>

Motivation

- Evolutionary Computation (EC) techniques have been frequently used in the context of computational creativity.
 - Various techniques have been used in the context of music and art (see EvoMusArt conference and DETA track at GECCO).
-

Motivation

- Evolutionary algorithms have been frequently used to optimize complex objective functions.
 - This makes them well suitable for generative art where fitness functions are often hard to optimize.
 - Furthermore, objective functions are often subjective to the user.
-

This Tutorial

- Summary of results in the areas of
 - 2d and 3D artifacts
 - Animations
 - Overview on our recent work to create unique generative art using evolutionary computation to carry out
 - Image transition and animation
 - Image composition
 - Diversity optimization for images
-

Motivation

- In terms of novel design, evolutionary computation techniques can be used to explore new solutions in terms of different characteristics.
 - Evolutionary algorithms are able to adapt to changing environments.
 - This makes them well suited to be used in the context of artistic work where the desired characteristics may change over time.
-

Outline

- Introduction and Motivation
 - Evolving 2D and 3D Artifacts
 - Aesthetic Features
 - Evolutionary Image Transition
 - Quasi-random Image Animation
 - Evolutionary Image Composition
 - Evolutionary Image Diversity Optimization
 - Conclusions
-

Evolving 2D and 3D Artifacts

Evolving 2D and 3D Artifacts

- *Blind Watchmaker* (Dawkins, 1986) evolved 2D biomorph graphical objects from sets of genetic parameters (combined with Darwinism theory).
 - Latham (1985) created *Black Form Synth*. These are hand-drawn “evolutionary trees of complex forms” using a set of transformation rules.
-

Evolving 2D and 3D Artifacts

- In 1991, Sims published his seminal SIGGRAPH paper.
 - He introduced the expression-based approach of evolving images.
 - He created images, solid textures, and animations using mutations of symbolic lisp expressions.
-

Evolving 2D and 3D Artifacts

- The mathematical expression is represented as a tree graph structure and used as the genotype.
 - The tree graph consists of mathematical functions and operators at the nodes, and constants/variables at the leaves (similar to genetic programming).
 - The resulting image is the phenotype.
 - To evolve sets of images, it uses crossover and mutation.
-

Evolving 2D and 3D Artifacts (Sims, 1997)

- *In Galápagos* (Sims, 1997) created an interactive evolution of virtual "organisms" based on Darwinian theory.
 - Several computers simulate the growth and characteristic behaviours of a population of abstract organisms.
 - The results are displayed on computer screens.
-

Evolving 2D and 3D Artifacts (Latham, Todd, 1992)

- Latham, Todd (1992) introduced *Mutator* to generate art and evolve new biomorphic forms.
 - The *Mutator* creates complex branching organic forms through the process of "surreal" evolution.
 - At each iteration the artist selects phenotypes that are "breed and grow", and the solutions co-interact.
-

EC System (Sims, 1997)

- The EC system allows users to express their preferences by selecting their preferred display by standing on step sensors in front of those displays.
 - The selected display is used for reproduction using mutation/crossover. The other solutions are removed when the new offspring is created.
-

Other Selected Contributions

- Unemi (1999) developed *SBART*. This is a design support tool to create 2-D images based on user selection.
 - Takagi (2001) describes in the survey research on interactive evolutionary computation (IEC) which categorises different application areas.
 - Machado and Cardoso (2002) introduced *NEvAr*. This is an evolutionary art tool, using genetic programming and automatic fitness assignment.
-

Other Selective Contributions

- Gary Greenfield (1998-2005) evolved simulated ant and robot parameters, and investigated image co-evolution.
 - Draves (2005) introduced *Electric Sheep*. The system allows a user to approve or disapprove phenotypes.
 - Hart (2009) evolved different expression-based images with a focus on colours and forms.
-

Aesthetic Measures

Image Morphing (Banzhaf, Graf 1995)

- Banzhaf and Graf (1995) used interactive evolution to help determine parameters for image morphing.
 - They combine IEC with the concepts of warping and morphing from computer graphics to evolve images.
 - They used recombination of two bitmap images through image interpolation.
-

Aesthetic Measures

- Computational aesthetic is a subfield of artificial intelligence dealing with the computational assessment of aesthetic forms of visual art.
 - Some general image features that have been used are:
 - Hue
 - Saturation
 - Symmetry
 - Smoothness
-

Aesthetic Measures

- Examples of aesthetic measurements:
 - Benford's Law
 - Global Contrast Factor
 - Reflectional Symmetry
 - Colorfulness
-

Evolutionary Image Transition

A. Neumann, Alexander, F. Neumann, EvoMusArt 2017

Aesthetic Measures (den Heijer, Eiben 2014)

- den Heijer and Eiben (2014) investigated aesthetic measures for unsupervised evolutionary art.
 - The *Art Habitat* System uses genetic programming and evolutionary multi-objective optimization.
 - They compared aesthetic measurements and gave insights into the correlation of aesthetic scores.
-

Evolutionary Image Transition

- The main idea comprises of using well-known evolutionary processes and adapting these in an artistic way to create an innovative sequence of images (video).
 - The evolutionary image transition starts from given image **S** and evolves it towards a target image **T**.
 - Our goal is to maximise the fitness function where we count the number of the pixels matching those of the target image.
-

Example Images



Starting image S (Yellow-Red-Blue, 1925 by Wassily Kandinsky) and target image T (Soft Hard, 1927 by Wassily Kandinsky).

Video - Image Transition

<https://vimeo.com/anetaneumann>



Evolutionary Image Transition

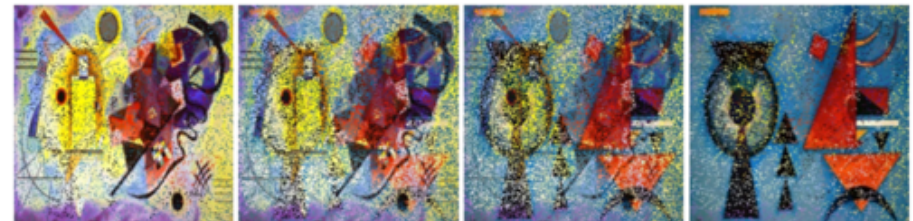
Algorithm 1 Evolutionary algorithm for image transition

- Let S be the starting image and T be the target image.
- Set $X := S$.
- Evaluate $f(X, T)$.
- while (not termination condition)
 - Obtain image Y from X by mutation.
 - Evaluate $f(Y, T)$
 - If $f(Y, T) \geq f(X, T)$, set $X := Y$.

Fitness function: $f(X, T) = |\{X_{ij} \in X \mid X_{ij} = T_{ij}\}|$.

Asymmetric Mutation

- We consider a simple evolutionary algorithm that has been well studied in the area of runtime analysis, namely variants of (1+1) EA.
- We adapt an asymmetric mutation operator used in Neumann, Wegener (2007) and Jansen, Sudholt (2010).



Asymmetric Mutation

Algorithm 2 Asymmetric mutation

- Obtain Y from X by flipping each pixel X_{ij} of X independently of the others with probability $c_s/(2|X|_S)$ if $X_{ij} = S_{ij}$, and flip X_{ij} with probability $c_t/(2|X|_T)$ if $X_{ij} = T_{ij}$, where $c_s \geq 1$ and $c_t \geq 1$ are constants, we consider $m = n$.

- for our experiments we set $c_s = 100$ and $c_t = 50$.

Video: Asymmetric Mutation



Video – Uniform Random Walk



Uniform Random Walk

- A *Uniform Random Walk* - the classical random walk chooses an element $X_{kl} \in N(X_{ij})$ uniformly at random.
- We define the neighbourhood $N(X_{ij})$ of X_{ij} as

$$N(X_{ij}) = \{X_{(i-1)j}, X_{(i+1)j}, X_{i(j-1)}, X_{i(j+1)}\}$$



Uniform Random Walk

Algorithm 3 Uniform Random Walk

- Choose the starting pixel $X_{ij} \in X$ uniformly at random.
 - Set $X_{ij} := T_{ij}$.
 - while (not termination condition)
 - Choose $X_{kl} \in N(X_{ij})$ uniformly at random.
 - Set $i := k, j := l$ and $X_{ij} := T_{ij}$.
 - Return X .
-

Biased Random Walk

- A *Biased Random Walk* - the probability of choosing the element X_{kl} is dependent on the difference in RGB-values for T_{ij} and T_{kl} .



Video – Biased Random Walk



Biased Random Walk

Algorithm 4 Biased Random Walk

- Choose the starting pixel $X_{ij} \in X$ uniformly at random.
 - Set $X_{ij} := T_{ij}$.
 - while (not termination condition)
 - Choose $X_{kl} \in N(X_{ij})$ according to probabilities $p(X_{kl})$.
 - Set $i := k, j := l$ and $X_{ij} := T_{ij}$.
 - Return X .
-

Biased Random Walk

We denote by T_{ij}^r , $1 \leq r \leq 3$, the r th RGB value of T_{ij} and define

$$\gamma(X_{kl}) = \max \left\{ \sum_{r=1}^3 |T_{kl}^r - T_{ij}^r|, 1 \right\}$$

$$p(X_{kl}) = \frac{(1/\gamma(X_{kl}))}{\sum_{X_{st} \in N(X_{ij})} (1/\gamma(X_{st}))}$$

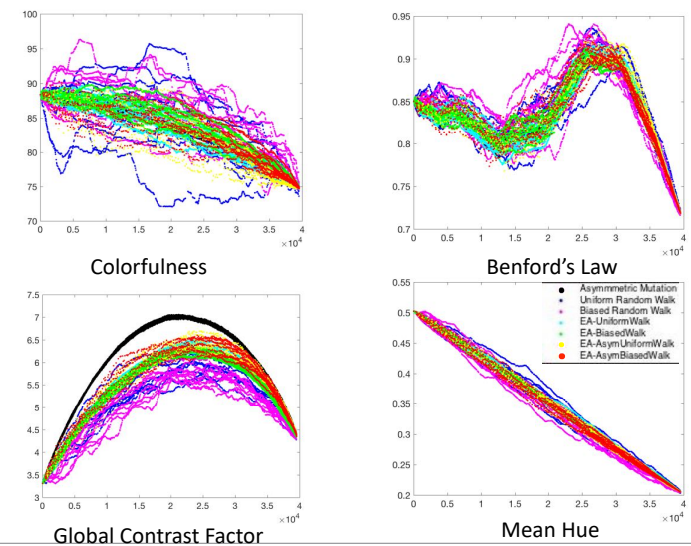
Videos - Biased Random Walk Evolutionary Algorithm



Mutation Based on Random Walks

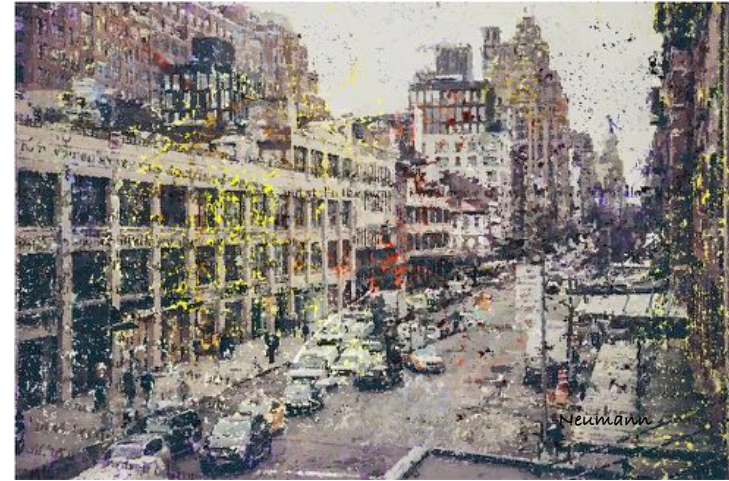
- We use the random walk algorithms as part of our mutation operators.
- Each mutation picks a random pixel and runs the (biased) random walk for t_{\max} steps.
- For our experiments we use 200x200 images and set $t_{\max}=100$.

Feature Values During Transition:



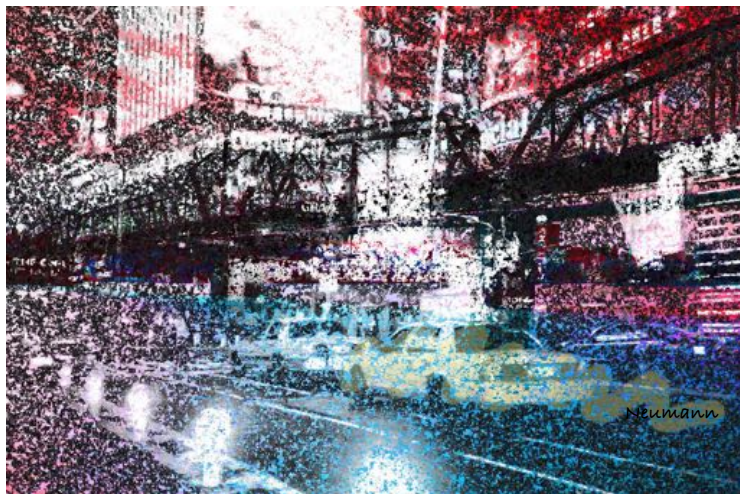
SALA 2016 – Art Exhibition, Australia

SALA 2016 – Art Exhibition



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Quasi-random Transition and Animation

A. Neumann, F. Neumann Friedrich, 2017

Quasi-random Walks

- So far: Random walks as main operators for mutation and transition process.
- Quasi-random walks give a (deterministic) alternative which is easy to control by a user.

Example Video: 4 Agents Symmetric Sequences



Quasi-random Transition and Animation

General setting:

- There are k agents each of them painting their own image I^k through a quasi random walk. Quasi-random walk is determined by the sequence that the agent uses.
- Process starts with a common image X .
- All agents paint on this image overriding X and previous painting of other agents.
- This leads to complex animation processes.
- Image transition is a special case where all agents paint the same image I .

Agent Moves

Move of an agent:

- Each pixel has a sequence of directions out of from {left, right, up, down}.
- At each iteration, the agent moves from its current pixel p to the neighbor pixel p' determined by the current position in the sequence at p .
- It paints pixel p' with the current pixel in its sequence and increases the position counter at p by 1 (modulo sequence length).

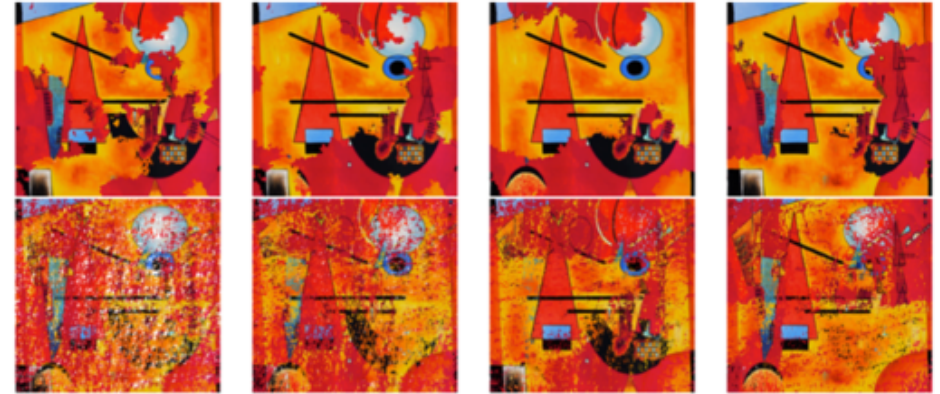
Algorithm

Algorithm 1 QUASI-RANDOM ANIMATION

Require: Start image Y of size $m \times n$. For each agent k , $1 \leq k \leq r$, an image I^k of size $m \times n$, sequence S^k and position counters $c^k(i, j) \in \{0, \dots, |S^k|\}$, $1 \leq i \leq m$, $1 \leq j \leq n$.

```
1:  $X \leftarrow Y$ 
2: for each agent  $k$ ,  $1 \leq k \leq r$  do
3:   choose  $P^k \in m \times n$  and set  $X(P^k) := I^k(P^k)$ .
4: end for
5:  $t \leftarrow 1$ 
6: while ( $t \leq t_{\max}$ ) do
7:   for each agent  $k$ ,  $1 \leq k \leq r$  do
8:     Choose  $\hat{P}^k \in N(P^k)$  according to  $S_k(c(P^k))$ .
9:      $X(\hat{P}^k) \leftarrow I^k(\hat{P}^k)$ 
10:     $c^k(P^k) \leftarrow (c^k(P^k) + 1) \bmod |S^k|$ .
11:     $P^k \leftarrow \hat{P}^k$ .
12:   end for
13:    $t \leftarrow t + 1$ 
14: end while
```

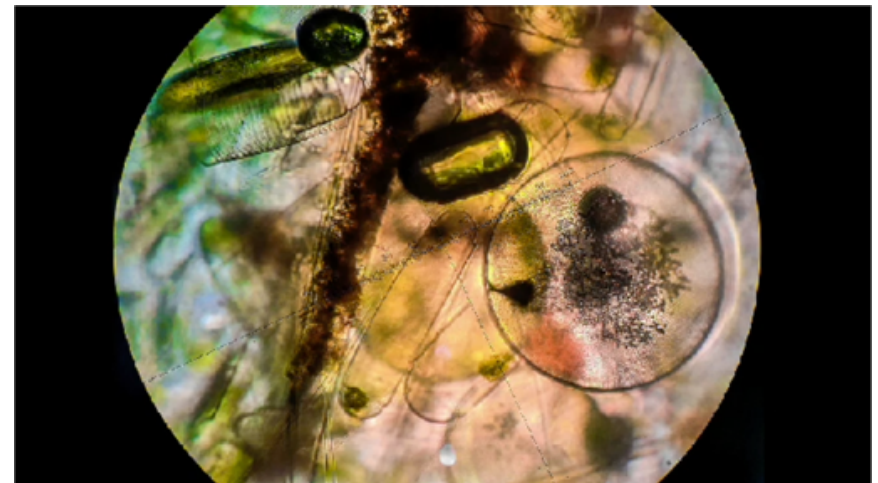
2 Agents Symmetric and Asymmetric Sequences



Example Video: 4 Agents Asymmetric Sequences



Video Quasi-random Walks



Evolutionary Image Composition

A. Neumann, Szpak, Chojnacki, F. Neumann, GECCO 2017

Evolutionary Image Composition Using Feature Covariance Matrices

- Evolutionary algorithms that create new images based on a fitness function that incorporates feature covariance matrices associated with different parts of the images.
- Population-based evolutionary algorithm with mutation and crossover operators based on random walks.

Key Idea

- Create a composition of two images using a region covariance descriptor.
- Incorporate region covariance descriptors into fitness function.
- Use evolutionary algorithms to optimize the fitness such that a composition of the given two images based on the considered features is obtained.

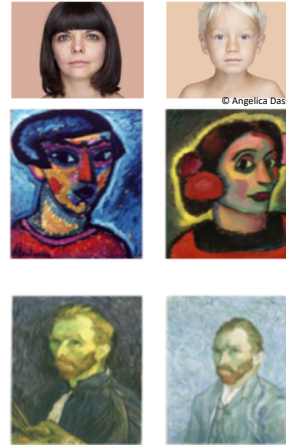
Algorithm 1 ($\mu + 1$) GA for evolutionary image composition

Require: S and T are images

```
1: Initialise population  $\mathcal{P} = \{P_1, \dots, P_\mu\}$ 
2: while not termination condition do
3:   Select an individual  $P_i \in \mathcal{P}$  uniformly at random
4:   if  $\text{rand}() < p_c$  then ▷ Crossover
5:     Select  $P_j \in \mathcal{P} \setminus P_i$  uniformly at random
6:     if  $\text{rand}() < 0.5$  then ▷ See Section 4.2 for  $t_{cr}$ 
7:        $Y \leftarrow \text{RANDOMWALKMUTATION}(X, Z, t_{cr})$ 
8:     else
9:        $Y \leftarrow \text{RECTANGULARCROSSOVER}(P_i, P_j)$ 
10:     $P_i \leftarrow \text{SELECTION}(P_i, Y)$ 
11:  else ▷ Mutation
12:    if  $\text{rand}() < 0.5$  then
13:       $Y \leftarrow \text{RANDOMWALKMUTATION}(P_i, S, t_{\max})$ 
14:    else
15:       $Y \leftarrow \text{RANDOMWALKMUTATION}(P_i, T, t_{\max})$ 
16:     $P_i \leftarrow \text{SELECTION}(P_i, Y)$ 
17:    Adapt  $t_{\max}$  ▷ See Section 4.1.
18: return  $\mathcal{P}$  ▷ Result is a population of evolved images.
```

$$f(X, S, T) = \sum_{(c, d) \in \mathcal{G}} \left(w_{(c, d)}^S \text{dist} \left(\Lambda_{\mathcal{R}(c, d)}^X, \Lambda_{\mathcal{R}(c, d)}^S \right) + w_{(c, d)}^T \text{dist} \left(\Lambda_{\mathcal{R}(c, d)}^X, \Lambda_{\mathcal{R}(c, d)}^T \right) \right),$$

#1
covariance-based
fitness function



#1
pixel-based mutation

#2
self adaptive random
walk mutation

[A. Neumann, Alexander, F. Neumann, EvoMusArt 2017]

[B. Doerr, C. Doerr, GECCO 2015]

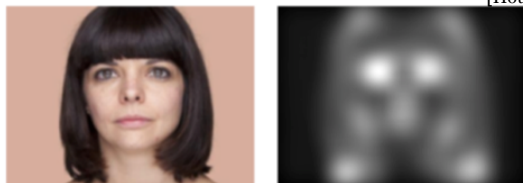
#3
square region of interest



$$\mathcal{G} = \left\{ (c, d) \left| \begin{array}{l} c = (l+1) + pl, p = 0, 1, \dots, \left\lfloor \frac{m-l}{l} \right\rfloor - 1 \\ d = (l+1) + ql, q = 0, 1, \dots, \left\lfloor \frac{n-l}{l} \right\rfloor - 1 \end{array} \right. \right\}$$

#4
saliency mask

[Hou, Harel, Koch, IEEE 2012]



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#5
set of features

$$\begin{aligned} \text{Set 1: } & \left[i, j, r, g, b, \sqrt{\left(\frac{\partial I}{\partial i}\right)^2 + \left(\frac{\partial I}{\partial j}\right)^2}, \tan^{-1} \left(\left| \frac{\partial I}{\partial i} \right| / \left| \frac{\partial I}{\partial j} \right| \right) \right]^T; \\ \text{Set 2: } & [i, j, h, s, v]^T; \\ \text{Set 3: } & \left[h, s, v, \sqrt{\left(\frac{\partial I}{\partial i}\right)^2 + \left(\frac{\partial I}{\partial j}\right)^2}, \tan^{-1} \left(\left| \frac{\partial I}{\partial i} \right| / \left| \frac{\partial I}{\partial j} \right| \right) \right]^T. \end{aligned}$$

Experiments

- Investigate the impact of different region covariance features on the resulting images .
- Discover how different weighting schemes for covariance matrices influence the results.
- Understand the influence that the distance measures have on the final results.

Impact of Different Features



Image composition with different features. Rows 1, 2 and 3 correspond to Feature Sets 1, 2 and 3, respectively.

Impact of Different Weightings



Rows 1, 2 and 3 correspond to $w_{(c,d)}^s$ set to \$0.25\$, \$0.5\$ and \$0.75\$ and $w_{(c,d)}^T$ set to \$0.75\$, \$0.5\$ and \$0.25\$, respectively. In the last row the weights were set using an image saliency algorithm. The saliency algorithm strikes a consistent balance between notable regions in both images.

Impact of Distance Metrics



Rows 1, 2 and 3 correspond to distance metrics dist_E , dist_A and dist_L , respectively.

Variants of Image Composition



Image composition with Feature Set 1, saliency-based weighting and a Log-Euclidean distance measure.

Evolutionary Diversity Optimisation for Images

Alexander, Kortman, A. Neumann, GECCO 2017

SALA 2017 Art Exhibition Adelaide, Australia



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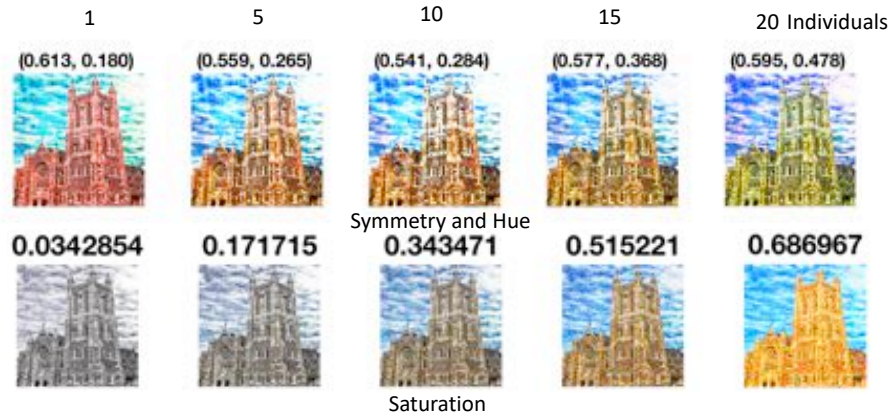
Diversity

- Majority of approaches consider diversity in the objective space.
- Ulrich/Thiele considered diversity in the search space (Tamara Ulrich's PhD thesis).
- Diversity with respect to other properties (features) could be useful in various domains.
- **Goal:** Compute a set of good solutions that differ in terms of interesting properties/features.

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Key Idea

- Produce diverse image sets using evolutionary computation methods.
- Use the $(\mu + \lambda)$ -EA_D for evolving image instances
- Select the individuals based on their contribution to diversity of the image.



Algorithm 1 The $(\mu + \lambda)$ -EA_D algorithm $\mu = 20$ and $\lambda = 10$

```

1: input: an image  $S$ .
2: output: a population  $P = \{I_1, \dots, I_\mu\}$  of image variants.
   {Initialise with  $\mu$  mutated copies of source image}
3:  $P = \{\text{mutate}(S), \dots, \text{mutate}(S)\}$ 
4: repeat
5:   randomly select  $C \subseteq P$  where  $|C| = \lambda$ 
6:   for  $I \in C$  do
7:     produce  $I' = \text{mutate}(I)$ 
8:     if  $\text{valid}(I')$  then
9:       add  $I'$  to  $P$ 
10:    end if
11:  end for
12:  while  $|P| > \mu$  do
13:    remove an individual  $I = \arg \min_{J \in P} d(J, P)$ 
14:  end while
15: until Termination condition reached
  
```

Evolution of Artistic Image Variants Through Feature Based Diversity Optimisation

- We use $(\mu + \lambda)$ -EA_D to evolve diverse image instances.
- Knowledge on how we can combine different image features to produce interesting image effects.
- Study how different combinations of image features correlate when images are evolved to maximise diversity.



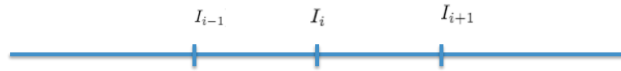
#1
starting image

#2
pixel-based mutation

#3
image validity check

Image has mean squared error to starting image less than 10

#4 feature diversity measure



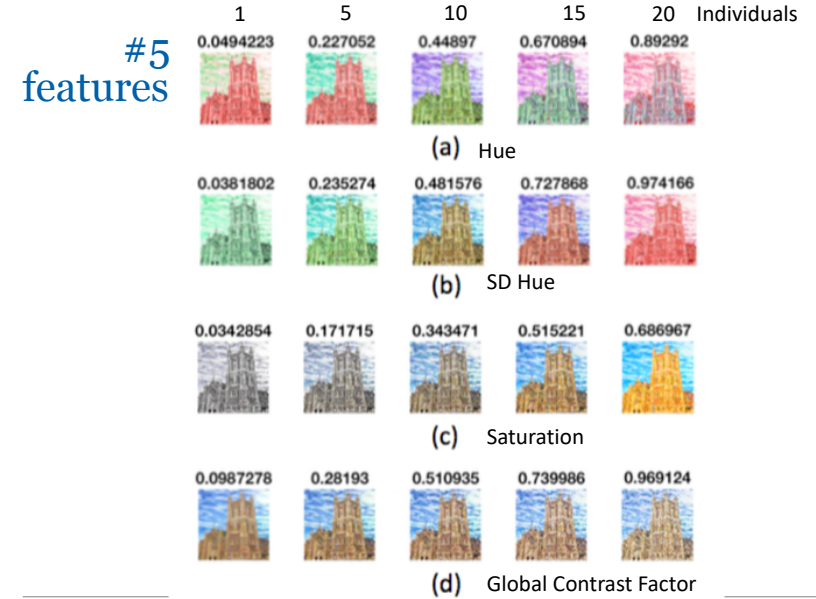
$$f(I_1) \leq f(I_2) \leq \dots \leq f(I_k), f(I_i) \neq f(I_1) \neq f(I_k)$$

$$d_{f_i}(I_i, P) = (f(I_i) - f(I_{i-1})) \times (f(I_{i+1}) - f(I_i))$$

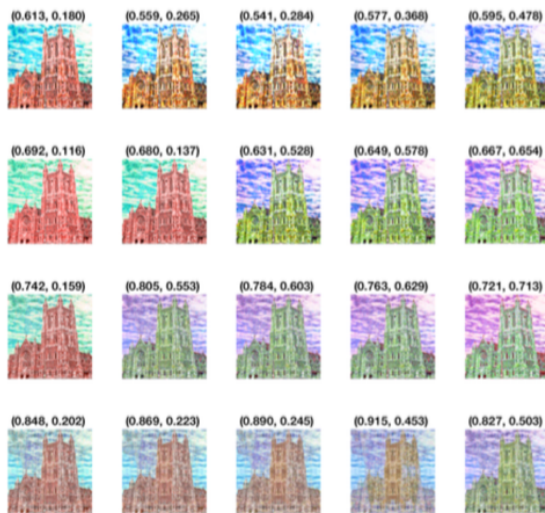
$$d'(I, P) = \sum_{i=1}^k (w_i \times d_{f_i}(I, P))$$

[Gao, Nallaperuma, F. Neumann, PPSN 2016, arxiv2016]

Single Dimensional Feature Results



Two-Dimensional Feature Experiments



a) Symmetry and Hue 20 Individuals

Discrepancy-Based Evolutionary Diversity Optimization for Images

A. Neumann, Gao, Doerr, F. Neumann, Wagner, GECCO 2018

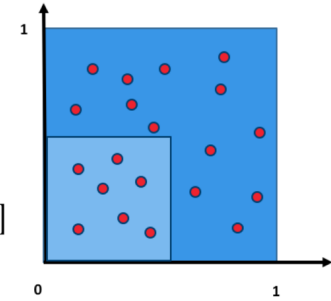
Discrepancy-Based Evolutionary Diversity Optimization

- New approach for discrepancy-based evolutionary diversity optimization
- Investigate the use of the star discrepancy measure for **diversity optimization** for images
- Introduce an **adaptive random walk mutation** operator based on random walks
- Compared the previously approach for images

[Alexander, Kortman, A. Neumann, GECCO 2017]

Motivation and Background

Given a set of points $X := \{s^1, \dots, s^n\}$ with $S = [0, 1]^d, s^i \in S$



$$[a, b] := [a_1, b_1] \times \dots \times [a_d, b_d]$$

$$\text{Vol}([a, b]) - |X \cap [a, b]|/n$$

$$D(X, \mathcal{B}) := \sup\{\text{Vol}([a, b]) - |X \cap [a, b]|/n \mid a \leq b \in [0, 1]^d\}$$

Discrepancy-Based Evolutionary Diversity Optimization for Images

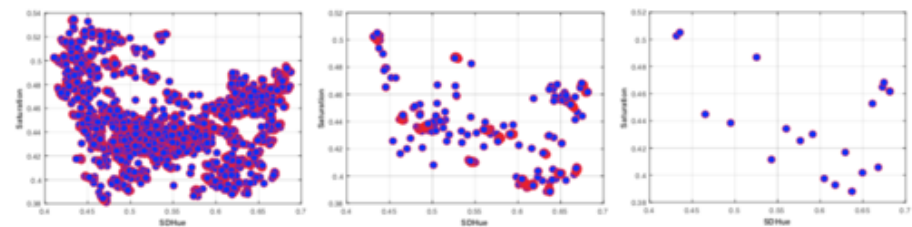
#1

Self-Adjusting Offset Random Walk Mutation

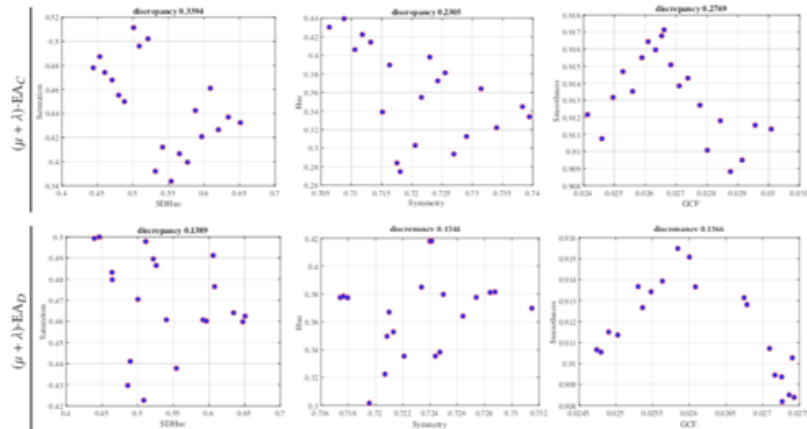
$$N(X_{ij}) = \{X_{(i-1)j}, X_{(i+1)j}, X_{i(j-1)}, X_{i(j+1)}\}$$

#2

Features



Results



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Evolutionary diversity optimization using multi-objective indicators

A. Neumann, Gao, Wagner, F. Neumann, GECCO 2019

Results

	$(\mu + \lambda)$ -EA _C (1)				$(\mu + \lambda)$ -EA _D (2)				$(\mu + \lambda)$ -EA _F (3)			
	min	mean	std	stat	min	mean	std	stat	min	mean	std	stat
(f1, f2)	0.2014	0.3234	0.0595	2 ⁽⁻⁾ 3 ⁽⁻⁾	0.1272	0.2038	0.1157	1 ⁽⁺⁾	0.1119	0.1530	0.0269	1 ⁽⁺⁾
(f3, f4)	0.1964	0.2945	0.0497	2 ⁽⁻⁾ 3 ⁽⁻⁾	0.1574	0.2280	0.0592	1 ⁽⁺⁾ 3 ⁽⁻⁾	0.1051	0.1417	0.0179	1 ⁽⁺⁾ 2 ⁽⁺⁾
(f5, f6)	0.1997	0.2769	0.0344	2 ⁽⁻⁾ 3 ⁽⁻⁾	0.1363	0.2025	0.0538	1 ⁽⁺⁾	0.1457	0.1800	0.0234	1 ⁽⁺⁾
(f1, f2, f3)	0.3389	0.4327	0.0613	2 ⁽⁻⁾ 3 ⁽⁻⁾	0.1513	0.3335	0.1062	1 ⁽⁺⁾	0.2253	0.2814	0.0422	1 ⁽⁺⁾
(f1, f4, f3)	0.2754	0.3395	0.0483	2 ⁽⁻⁾ 3 ⁽⁻⁾	0.2100	0.3118	0.1309	1 ⁽⁺⁾	0.2224	0.2600	0.0123	1 ⁽⁺⁾
(f5, f4, f2)	0.4775	0.6488	0.0841	2 ⁽⁻⁾ 3 ⁽⁻⁾	0.2021	0.3007	0.1467	1 ⁽⁺⁾	0.1983	0.2229	0.0125	1 ⁽⁺⁾

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Indicator-Based Diversity Optimisation

- Let I be a search point
 - $f: X \rightarrow \mathbb{R}^d$ a function that assigns to each search point a feature vector
 - $q: X \rightarrow \mathbb{R}$ be a function assigning a quality score to each $I \in X$
 - Require $q(I) \geq \alpha$ for all "good" solutions (constraint)
- Define $D: 2^X \rightarrow \mathbb{R}$ which measures the diversity of a given set of search points.

Goal:

Compute set $P = \{I_1, \dots, I_\mu\}$ of μ solutions maximizing (minimizing) D among all sets of μ solutions under the condition that $q(I) \geq \alpha$ holds for all $I \in P$, where α is a given quality threshold.

Indicator-based Multi-Objective Optimization

- Let I be a search point
 - $f: X \rightarrow \mathbb{R}^d$ a function that assigns to each search point I an objective vector
 - $q: X \rightarrow \mathbb{R}$ a function measures constraint violations
- An indicator $I: 2^X \rightarrow \mathbb{R}$ measures the quality of a given set of search points.

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Results Images Using Multi-Objective Indicators

	EA _{HYP} 2D (1)			EA _{HYP} (2)			EA _{IGD} (3)			EA _{EPS} (4)			EA _{ABS} (5)			
	mean	st	stat	mean	st	stat	mean	st	stat	mean	st	stat	mean	st	stat	
HYP	f_1, f_2	0.347	0.004	4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.382	0.007	3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.335	0.003	2 ⁽⁺⁾ ,5 ⁽⁺⁾	0.198	0.019	1 ⁽⁻⁾ ,2 ⁽⁻⁾	0.112	0.030	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾
	f_3, f_4	0.344	0.004	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.268	0.014	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.339	0.004	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.221	0.015	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾	0.105	0.025	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾
	f_5, f_6	0.350	0.007	2 ⁽⁺⁾ ,3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.342	0.004	1 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.332	0.004	1 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.220	0.045	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾	0.134	0.016	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾
IGD	f_1, f_2	0.525	0.012	3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.693	0.013	3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.374	0.006	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,4 ⁽⁺⁾	0.344	0.003	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾	0.363	0.014	1 ⁽⁻⁾ ,2 ⁽⁻⁾
	f_3, f_4	0.500	0.007	3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.681	0.010	3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.268	0.072	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.280	0.010	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾	0.267	0.014	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾
	f_5, f_6	0.518	0.012	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.663	0.010	1 ⁽⁺⁾ ,3 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.335	0.004	2 ⁽⁻⁾ ,4 ⁽⁺⁾	0.317	0.006	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾	0.327	0.008	1 ⁽⁻⁾ ,2 ⁽⁻⁾
EPS	f_1, f_2	0.001	0.335	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.003	0.000	1 ⁽⁻⁾ ,3 ⁽⁻⁾	0.001	0.000	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.003	0.000	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁺⁾	0.005	0.001	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁻⁾
	f_3, f_4	0.001	0.339	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.004	0.000	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁺⁾	0.001	0.000	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.003	0.000	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁺⁾	0.005	0.001	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁻⁾
	f_5, f_6	0.002	0.352	2 ⁽⁺⁾ ,5 ⁽⁺⁾	0.007	0.000	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.001	0.000	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.005	0.001	2 ⁽⁺⁾ ,3 ⁽⁻⁾	0.004	0.001	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾
DIS	f_1, f_2	0.190	0.198	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.498	0.011	1 ⁽⁻⁾ ,3 ⁽⁻⁾	0.194	0.032	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.402	0.039	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁺⁾	0.600	0.106	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁻⁾
	f_3, f_4	0.198	0.221	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.569	0.016	1 ⁽⁻⁾ ,3 ⁽⁻⁾	0.208	0.035	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.418	0.036	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁺⁾	0.615	0.069	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁻⁾
	f_5, f_6	0.125	0.220	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.946	0.001	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁻⁾	0.225	0.064	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.397	0.110	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾	0.587	0.063	1 ⁽⁻⁾ ,3 ⁽⁻⁾
DIS	f_1, f_2	0.171	0.018	2 ⁽⁺⁾ ,4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.257	0.010	1 ⁽⁻⁾ ,4 ⁽⁺⁾	0.201	0.031	4 ⁽⁺⁾ ,5 ⁽⁺⁾	0.686	0.064	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁻⁾	0.204	0.116	1 ⁽⁻⁾ ,3 ⁽⁻⁾ ,4 ⁽⁺⁾
	f_3, f_4	0.234	0.031	4 ⁽⁺⁾	0.273	0.041	3 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁻⁾	0.198	0.017	2 ⁽⁺⁾ ,4 ⁽⁺⁾	0.606	0.054	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁻⁾	0.228	0.059	2 ⁽⁺⁾ ,4 ⁽⁺⁾
	f_5, f_6	0.221	0.026	4 ⁽⁺⁾	0.263	0.070	3 ⁽⁻⁾ ,4 ⁽⁺⁾ ,5 ⁽⁻⁾	0.205	0.055	2 ⁽⁺⁾ ,4 ⁽⁺⁾	0.633	0.158	1 ⁽⁻⁾ ,2 ⁽⁻⁾ ,3 ⁽⁻⁾ ,5 ⁽⁻⁾	0.203	0.054	2 ⁽⁺⁾ ,4 ⁽⁺⁾

For details: GA1 (best paper session) on Monday
Evolutionary Diversity Optimization Using Multi-Objective Indicators, 17:00-17:25

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Multi-Objective Indicators

Popular indicators in multi-objective optimization:

- Hypervolume (HYP)

$$HYP(S, r) = VOL \left(\cup_{(s_1, \dots, s_d) \in S} [r_1, s_1] \times \dots \times [r_d, s_d] \right)$$

- Inverted generational distance (IGD) (with respect to reference set R)

$$IGD(R, S) = \frac{1}{|R|} \sum_{r \in R} \min_{s \in S} d(r, s),$$

- Additive epsilon approximation (EPS) (with respect to reference set R)

$$\alpha(R, S) := \max_{r \in R} \min_{s \in S} \max_{1 \leq i \leq d} (s_i - r_i).$$

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Conclusions

- Evolutionary algorithms provide a flexible approach to the creation of artistic work.
- A lot of algorithmic approaches have been shown to be able to create artistic work.
- Evolutionary process itself can be used to create artistic digital work.
- Random processes exhibit in interesting sources of inspiration.
- Evolutionary diversity optimization can be used to create a diverse set of designs that vary with respect to given features.

Thank you!

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