

Skip Graph Convolutional Networks (Skip-GCN)

A Framework for Hierarchical Graph Representation Learning

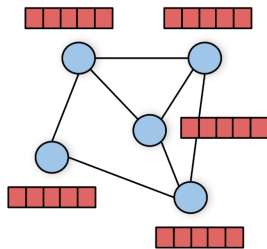
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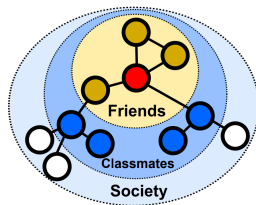
Introduction - Graph Theory

- Recently there has been great interest in graph representation learning. Graphs are known to be complex data structures because it contains both topological information and features.
- A graph $G = (V, E)$ where $|V| = n$ contains an adjacency matrix $A \in \mathbb{R}^{n \times n}$ that represents the edges.
- Node contain f features are represented with a feature matrix $X \in \mathbb{R}^{n \times f}$.



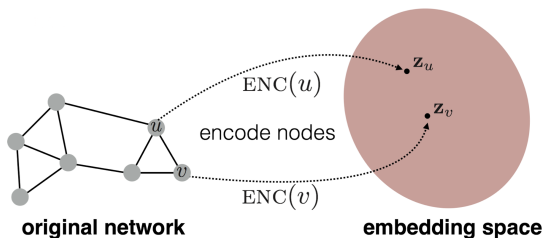
Applications

- One application of graph representation learning is the analysis and prediction of social networks. Examples include:
 - ▶ Contact tracing or contagion spread
 - ▶ Disinformation detection
 - ▶ Social media community detection
 - ▶ Covert network detection/prediction
- Social networks are known to be challenging to analyze because of topology. Local and global information can be equally important.



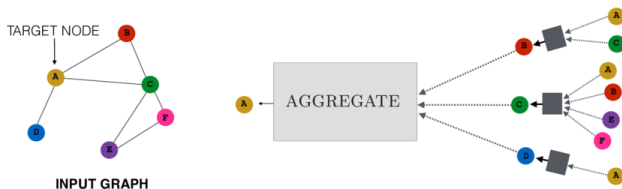
Node Embeddings

- Typically, node embeddings are used to perform machine learning tasks.
 - ▶ Node embedding is where we encode a node $u \in V$ to a vector $\text{ENC}(u) = x \in \mathbb{R}^d$.
- The goal is that if nodes u and v are similar, then they will be close in the embedding space.



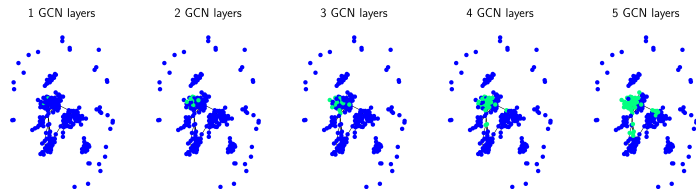
Graph Convolutional Networks (GCN)

- One popular method to compute node embeddings is through GCNs by averaging node features based on neighbors.
- A GCN layer is computed by $H_{i+1} = \sigma(\tilde{A}H_iW)$, where $\tilde{A} = D^{-\frac{1}{2}}(A + I)D^{-\frac{1}{2}}$ is the normalized adjacency matrix with D as the diagonal degree matrix of $A + I$, and $W \in \mathbb{R}^{f \times d}$ is a parameter matrix. For the first layer we use the features matrix $H_0 = X$.



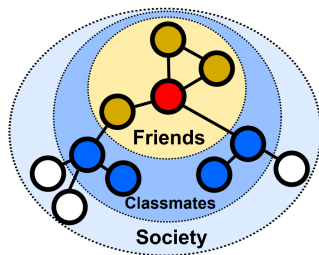
GCNs in Social Networks

- GCNs perform well for capturing local information, but lack in capturing both local and global information.
- More global information can be captured by adding more GCN layers, however at the sacrifice of diluting local node features.



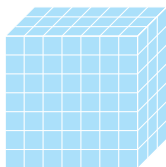
Our Proposed Method - Skip-GCN

- Our goal is to create a family of representations that capture the full range of an individual's community, both local and global.
- We aim to expand the GCN by allowing skipping in its convolutions, aptly named the skip graph convolutional network (Skip-GCN).



Multilinear Algebra

- In order to fully capture the features along all ranges within an individual's community, we will utilize a multilinear algebra framework, utilizing *tensors*.
- A tensor $\mathcal{A} \in \mathbb{R}^{n \times n \times k}$ in this context is a multi-dimensional array, where we denote $\mathcal{A}^{(k)} \in \mathbb{R}^{n \times n}$ as a frontal slice at index k .



Tensor Products

- Fundamental to the results of the current research is the product of two tensors.

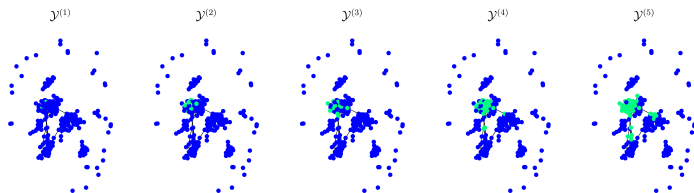
Definition

Let $\mathcal{A} \in \mathbb{R}^{\ell \times n \times m}$ and $\mathcal{B} \in \mathbb{R}^{n \times p \times m}$ be tensors. The tensor-tensor product based on the L invertible linear transform $\mathcal{A} *_L \mathcal{B} \in \mathbb{R}^{\ell \times p \times m}$ is computed by applying matrix multiplication to the frontal slices of \mathcal{A} and \mathcal{B} in the transform domain.



Skipping

- We aim to capture the full representation of an individual's community by performing skipping in graph convolutions.
- To capture the full range, we will convolve nodes that have a walk length of i , up to a maximum parameter k , for $i = 1, \dots, k$.
- We will then collect that into a tensor $\mathcal{Y} \in \mathbb{R}^{n \times f \times k}$, where each frontal slice is a convolution $\mathcal{Y}^{(i)} = \tilde{A}^i X$.



Skip-GCN Architecture

- After performing convolutions, we can also add a parameter tensor $\mathcal{W} \in \mathbb{R}^{f \times d \times k}$.
- Formally, our Skip-GCN layer is $\sigma(\mathcal{Y} *_L \mathcal{W}) = \mathcal{Z} \in \mathbb{R}^{n \times d \times k}$ where $\mathcal{Y}^{(i)} = \tilde{A}^i X$.
- \mathcal{Z} is our node embedding for each node at each skipping size. To perform node classification, we can now flatten \mathcal{Z} to a matrix in $\mathbb{R}^{n \times dk}$ and apply a simple dense layer for the embeddings.

Experimental Datasets

- We will compare our framework with other methods in the literature on benchmark social network datasets.
 - ▶ Profiles of Individual Radicalization in the United States (PIRUS) dataset
 - ★ A 2226 node network that contains violent and non-violent extremists in the US from 1948-2018. Connections to individuals are based on their involvement of extremist groups. Node features contain ideology, crime history, and demographic information.

Experimental Results

Table: K-fold cross-validation for the PIRUS dataset.

Fold	GCN	GraphSAGE	Skip-GCN
1	0.748	0.735	0.776
2	0.728	0.713	0.748
3	0.753	0.763	0.771
4	0.749	0.743	0.757
5	0.766	0.753	0.764
Avg. \pm Std.	0.749 ± 0.014	0.742 ± 0.019	0.763 ± 0.011

Note all numbers report F1 score. Higher is better.



Future Steps

- Perform experiments with more datasets.
- Explore how to incorporate edge features.
- Explore link prediction.
- Explore different aggregate methods, possibly multiple at once.
 - ▶ Min
 - ▶ Max
 - ▶ Pooling
- Explore temporal networks by adding LSTM layers.

Acknowledgments



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