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## SPECIALTY SECTION

This article was submitted to Smart  
Grids, a section of the journal  
Frontiers in Energy Research

RECEIVED 02 November 2022

ACCEPTED 25 November 2022

PUBLISHED 23 January 2023

## CITATION

Fan R, Ming Z, Xu W, Li T, Han Y, Ma R,  
Liu J and Wu Y (2023), Optimization of  
photovoltaic panel deployment in  
centralized photovoltaic power plant  
under multiple factors.  
*Front. Energy Res.* 10:1087487.  
doi: 10.3389/fenrg.2022.1087487

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# Optimization of photovoltaic panel deployment in centralized photovoltaic power plant under multiple factors

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Solar energy is one of the main renewable energy sources and has rapidly developed in many countries. However, the photovoltaic (PV) output power will be different under various meteorological and geographical conditions. Therefore, this paper presents an optimization method for the deployment of PV panels in a centralized PV power plant considering multiple factors. Firstly, the whole planning area is divided into a certain amount of sub-areas according to a given area, and fuzzy C-means algorithm is used for terrain clustering according to the geographical characteristics of the sub-areas. Secondly, the correlation analysis between each meteorological factor and PV output power is carried out separately to select the main factors affecting PV output power, and then the expected annual PV output power under the joint action of several main meteorological factors in each terrain is calculated by dual-stage attention mechanism based long short-term memory algorithm. Finally, according to the expected annual PV output of each terrain, considering the constraints including cost, area and so on, the deployment optimization of PV panels is obtained to maximize the annual PV output of the whole PV power plant and minimize the construction cost. The results of case studies show that the proposed methods effectively improve the expected PV output power of the PV power plant and reduce the construction cost.

## KEYWORDS

centralized PV power plant, DA-LSTM, PV output power, PV panel deployment, solar energy, terrain clustering

## 1 Introduction

Rapid development of renewable energy technologies such as solar is required due to climate change mitigation strategies worldwide (Dong et al., 2021). Moreover, the development of photovoltaic (PV) power technologies plays an important role in achieving the goals of emission peak and carbon neutrality (Zhang et al., 2021), and poverty alleviation (Zhang et al., 2020). However, the performance of PV systems is generally affected by the meteorological conditions (Hachicha et al., 2019; Li et al., 2021),

and geographical location (Al-Rousan et al., 2018; Cotfas and Cotfas, 2019). Furthermore, the centralized PV power plant covers a large area, and its continuous expansion also causes the problem of insufficient land. Therefore, it is necessary to make full use of the meteorological and geographical conditions in different regions to develop PV.

Different meteorological factors effect on PV output power to different extent. Therefore, the first step of centralized PV plant planning is to start with the effect caused by meteorological factors. Mekhilef et al. (2012) studied the effect of dust deposition, wind speed and relative humidity on the efficiency of solar cells. Li et al. (2020) analyzed the impacts of wind speed, wind direction, ambient temperature and solar radiation on PV considering dynamic line parameters. The main factors in the PV power calculation are the solar insolation. Ambient temperature and wind speed have transitive relation with PV power through irradiance, and the humidity and the atmospheric pressure have a negative correlation with PV output (Ziane et al., 2021). Dust is a cause of PV output power reduction, and models of dust deposition on PV modules using local meteorological events were developed in (Sengupta et al., 2021). Gowid and Massoud (2020) developed a PV maximum power point identification tool considering temperature and solar insolation. Mayer (2021) revealed the effects of the meteorological data resolution on the of simulation and optimization reliability of PV power plants. Those studies points out what and how meteorological factors affect PV output power, but most of them did not consider enough kinds of meteorological factors.

After confirming what and how meteorological factors affect the PV output power, PV output power calculation or prediction based on multiple meteorological factors has become a hot topic in recent years. Correlation analysis and regression analysis are basic methods to calculate PV power. A model of PV output power was obtained through regression analysis by selecting main factors that affect PV power in (Kim et al., 2019). Agoua et al. (2018) proposed a statistical spatio-temporal model based on correlation analysis to improve short-term forecasting of PV production. However, the methods mentioned above have relatively low efficiency and accuracy. To overcome this problem, a widely-used kind of method for PV calculation or prediction is deep learning. Considering solar radiation, sunlight, wind speed, temperature, cloud cover, and humidity, a modified long short-term memory (LSTM) is used to predict PV power in medium and long term (Son and Jung, 2020). There are also many other deep learning based methods such as methods based on convolutional neural network (Yan et al., 2021), spatiotemporal feedforward neural network (Rodríguez et al., 2022) and so on. Besides, graph modeling method is a novel method for PV power prediction. The graph modeling method is used to describe the relationship between various meteorological factors and PV power and predict the PV power, but the graph modeling method is more complex (Cheng et al., 2021). There are already various practical PV calculation

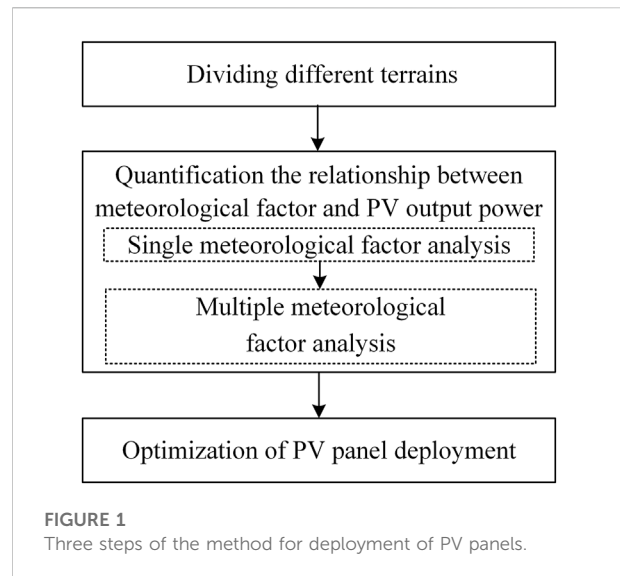


FIGURE 1  
Three steps of the method for deployment of PV panels.

methods taking meteorological factors into account, but there are few studies considering geographical conditions which also affect PV output power. To sum up, the method for PV output power calculation still needs to develop.

As mentioned above, the performance of PV is also affected by geographical conditions. For example, according to a study in a water pumping system with PV installation in Brazil, when the ratio between flow and radiation was taken into account, the monocrystalline PV system was more efficient (Nogueira et al., 2015). Polycrystalline solar module showed a better performance in semi-arid Region (Ettah et al., 2021). Ingenhoven et al. (2019) analyzed the performance loss rate of six different PV module types in five locations in Italy. Huld (2017) promoted a set of tool and data named PVMAPS, which could calculate PV performance in any region covered by the data. Due to the relationship between geographical conditions and PV performance, site selection became an important factor of PV power plant execution. To find the best location, many researches presented methods based on geographical information system (Hashemizadeh et al., 2019; Mensour et al., 2019). Although some literature dealt with the site selection of PV power plant, there were not many literature focus on the deployment of PV panels in centralized PV power plant.

In summary, the existing works lack an optimization method for the deployment of PV panels in a centralized PV power plant considering not only the geographical difference but the meteorological difference. To solve the above problems, this paper proposes an optimization method for the deployment of PV panels in a centralized PV power plant considering multiple factors. By optimizing the deployment position and quantity of PV panels, the method aims at higher PV output power and lower cost under certain capacity and approximate planning area

for a centralized PV power plant. It also provides possibility for more efficient application of PV.

The remainder of the paper is organized as follows. Section 2 introduces terrain clustering, quantification of the relationship between meteorological factors and PV output, and optimization model. Section 3 shows the result of case studies. Section 4 makes a conclusion for this paper.

## 2 Methodologies

As shown in Figure 1, the method for optimizing the deployment of PV panels in a centralized PV power plant under multiple factors is divided into three steps: dividing different terrains in the PV power plant according to geographical characteristics, modeling and quantifying the relationship between meteorological factors and PV output power in each terrain (including single meteorological factor and multiple meteorological factor analysis), optimizing the deployment of PV panels in the centralized PV power plant.

### 2.1 Terrain clustering

Before studying meteorological factors, we should first explore the influence of geographical factors. This is because the meteorological conditions in different locations are obviously different. Thus, to carefully study the relationship among PV output power, meteorological factors and geographical factors, it is necessary to combine the sub-areas with similar geographical locations to a terrain first. Moreover, the installation of PV panels is also affected by geographical factors. For example, according to the different slope direction and gradient, the installation area of unit PV panels varies, and the unit installation area will affect the subsequent optimal deployment of PV panels. Therefore, based on the above considerations, this section first divides the surrounding area of a planned centralized PV power station into several terrains according to the geographical characteristics.

Noted that the PV panels in a centralized PV power plant are often orderly concentrated in a certain area, the distance and direction between the terrain center and the gathering station (GS) are included in the geographical characteristics, so as to make each sub-area within the divided terrain roughly similar in location and more accord with the actual situation of the centralized PV power plant construction. Firstly, PV power plant are divided into several sub-areas from west to east and from north to south according to a rectangular area with the same area of  $A_N$  (determined according to the actual cases). Then the annual sunshine durations, average altitude, slope direction, slope, distance between the terrain center and the GS, the direction of the terrain center relative to the GS are used as the geographical features for dividing different terrains. Define the geographical feature of the  $i$ th sub-area as  $X_i^{terrain}$  and

establish the dataset  $X_i^{terrain} = \{x_{i1}^{terrain}, x_{i2}^{terrain}, \dots, x_{i6}^{terrain}\}$ . Subscripts  $i1$  to  $i6$  represent the annual sunshine durations, average altitude, slope direction, slope, distance between the terrain center and the GS, the direction of the terrain center relative to the GS in the  $i$ th sub-area, respectively.

As one of the main unsupervised machine learning technologies, fuzzy clustering analysis is a method of analyzing and modeling important data using fuzzy theory, which establishes the uncertainty description of sample categories. The vector of fuzzy clustering algorithm can belong to multiple clusters at the same time, which can objectively reflect the real world. It has been effectively applied in many fields such as large-scale data analysis, data mining, vector quantization and so on, which is proved to have important theoretical and practical application value. With the further development of application, the research of fuzzy clustering algorithm is constantly enriched. In this section, we have chosen fuzzy c-means (FCM) algorithms due to its good performance (Benmouiza et al., 2016), and the FCM algorithm introduced by Dunn and improved by Bezdek (Nayak et al., 2015).

Using the FCM algorithm, a total of  $K$  sub-areas in the whole planning area of the PV power plant are classified into  $N$  terrains. The idea of FCM algorithm is to calculate the membership matrix  $U = [u_{ij}]_{N \times K}$  and the cluster centers  $V = \{v_1, v_2, \dots, v_N\}$  from the terrain geographic feature dataset  $X^{terrain} = \{X_1^{terrain}, X_2^{terrain}, \dots, X_K^{terrain}\}$  through continuous iteration, and to minimize the function value in Eq. 1.

$$J(U, V) = \sum_{i=1}^K \sum_{j=1}^N u_{ij}^m d_{ij}^2 \tag{1}$$

$$d_{ij} = \|X_i^{terrain} - v_j\| \tag{2}$$

In Eq. 1,  $u_{ij}$  is the membership degree of the  $i$ th sub-area belonging to the  $j$ th terrain;  $m$  is the membership factor;  $d_{ij}$  is the Euclidean distance from the  $i$ th sub-area to the  $j$ th cluster center, which is calculated by Eq. 2.

The calculation steps of the FCM algorithm are as follows:

**Step 1.**  $N$  cluster centers are randomly selected and the initial membership matrix  $U^{(0)}$  is calculated. Let  $l = 1$  and start the first iteration.

**Step 2.** Calculate the cluster center  $V^{(l)}$  and membership matrix  $U^{(l)}$  of the  $l$ th iteration, and calculate the function value of  $J^{(l)}$ , as shown in follows.

$$v_j^{(l)} = \frac{\sum_{i=1}^K (u_{ij}^{(l-1)})^m X_i^{terrain}}{\sum_{i=1}^K (u_{ij}^{(l-1)})^m}, j = 1, 2, \dots, N \tag{3}$$

$$u_{ij}^{(l)} = \frac{1}{\sum_{k=1}^K \left(\frac{d_{ij}^{(l)}}{d_{ik}^{(l)}}\right)^{\frac{2}{m-1}}}, i = 1, 2, \dots, K; j = 1, 2, \dots, N \tag{4}$$

$$J^{(l)}(U^{(l)}, V^{(l)}) = \sum_{i=1}^K \sum_{j=1}^N ((u_{ij}^{(l)})^m ((d_{ij}^{(l)})^2) \tag{5}$$

$$d_{ij}^{(l)} = \|X_i^{terrain} - v_j^{(l)}\| \tag{6}$$

**Step 3.** Set the termination value. Membership termination value  $\epsilon_u > 0$  or function termination value  $\epsilon_f > 0$  can be used. If  $\max\{|u_{ij}^{(l)} - u_{ij}^{(l-1)}|\} < \epsilon_u$  or  $|J^{(l)} - J^{(l-1)}| < \epsilon_f$ , the iteration stops, otherwise, increase  $l$  and go to step 2.

When  $u_{ij} = \max_{1 \leq j \leq N}\{u_{ij}\}$ , the  $i$ th sub-area belongs to the  $j$ th terrain and can be expressed as follows:

$$X_i^{terrain} \in D_j \tag{7}$$

## 2.2 Single meteorological factor analysis

Quantification the relationships between meteorological factors and PV output power in each terrain includes single meteorological factor and multiple meteorological factor analysis. There are many kinds of meteorological factors, and the impact of various meteorological factors on PV output power may be significantly different. Therefore, in order to accurately measure the relationship between meteorological factors and PV output power, and simplify the calculation complexity and time of subsequent multiple meteorological factors analysis without losing accuracy, a single meteorological factor analysis of PV output power is conducted first. The single meteorological factor analysis is to select the daily output data of an existing PV power plant near the planning area and various meteorological data collected by the corresponding meteorological station as historical data, preliminarily analyze the relationships between PV output power and various meteorological factors through Pearson correlation coefficient, and select several major meteorological factors that have a great impact on the PV output.

$$r = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2 \cdot \sum_{i=1}^n (y_i - \bar{y})^2}} \tag{8}$$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i \tag{9}$$

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i \tag{10}$$

Where  $x_i$  is the  $i$ th time component of the meteorological factor  $x$ ,  $y_i$  is the  $i$ th time component of PV output  $y$ ,  $r$  is the correlation coefficient,  $r \in [-1, 1]$ , and the closer the absolute value is to 1, the stronger the correlation between the meteorological factor  $x$  and PV output.

According to the value of correlation coefficient,  $k$  meteorological factors with the strongest correlation with PV output are selected for further mining the relationship between meteorological factors and PV output. Considering that the dimensions of various meteorological factors and PV output are not uniform, the MinMaxScaler method is used to normalize

the data to improve the convergence speed of the subsequent deep learning model and reduce the error. MinMaxScaler method is shown in Eq. 11:

$$x' = \frac{x - x_{min}}{x_{max} - x_{min}} \tag{11}$$

where,  $x'$  is the normalized data,  $x$  is the original data,  $x_{min}$  and  $x_{max}$  are the minimum and maximum of the original data.

After normalizing the  $k$  main meteorological factors and PV output data, sequential feature  $X^{me} = (x_1^{me}, x_2^{me}, \dots, x_T^{me}) = (x^{me1}, x^{me2}, \dots, x^{mek})^T$ , containing  $k$  main meteorological factors, is constructed. It can be expressed by the following matrix:

$$X^{me} = \begin{bmatrix} x_1^{me1} & x_1^{me2} & \dots & x_1^{mek} \\ x_2^{me1} & x_2^{me2} & \dots & x_2^{mek} \\ \vdots & \vdots & \ddots & \vdots \\ x_T^{me1} & x_T^{me2} & \dots & x_T^{mek} \end{bmatrix} \tag{12}$$

where,  $x_t^{me} = (x_t^{me1}, x_t^{me2}, \dots, x_t^{mek})$  is expressed as the above  $k$  meteorological feature sets at time  $t$ , and  $x^{me p} = (x_1^{me p}, x_2^{me p}, \dots, x_T^{me p})$  is expressed as the each value of the  $p$ th relevant meteorological variable for the whole period  $T$ .

## 2.3 Multiple meteorological factor analysis

The multiple meteorological factor analysis uses the dual-stage attention mechanism based LSTM (DA-LSTM). LSTM is an improved recurrent neural network. Each hidden layer is no longer a single neural network, but consists of four interconnected neural networks (forget gate, input gate, update gate and output gate). It compares the memory information with the current information and learns through self-evaluation and selectively forgetting mechanism, which can alleviate the problem of gradient vanishing and exploding in general recurrent neural network (Greff et al., 2017; Shewalkar, 2019).

### 2.3.1 Overview of long short-term memory

In the general LSTM networks, the long-term memory information at time  $t$  is defined as the cell state  $C_t$ . The LSTM cell receives the meteorological feature set  $x_t^{me}$  at time  $t$  and the short-term memory information  $h_{t-1}$  of cells at the previous time, and inputs the cell state  $C_{t-1}$  at the previous time into each gate as internal information. Through the forget gate  $f_t$ , the input gate  $i_t$  and the output gate  $o_t$ , the cell information is read and modified as follows:

$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t^{me}] + b_f) \tag{13}$$

$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t^{me}] + b_i) \tag{14}$$

$$C_t' = \tanh(W_c \cdot [h_{t-1}, x_t^{me}] + b_c) \tag{15}$$

$$o_t = \sigma(W_o \cdot [h_{t-1}, x_t^{me}] + b_o) \tag{16}$$

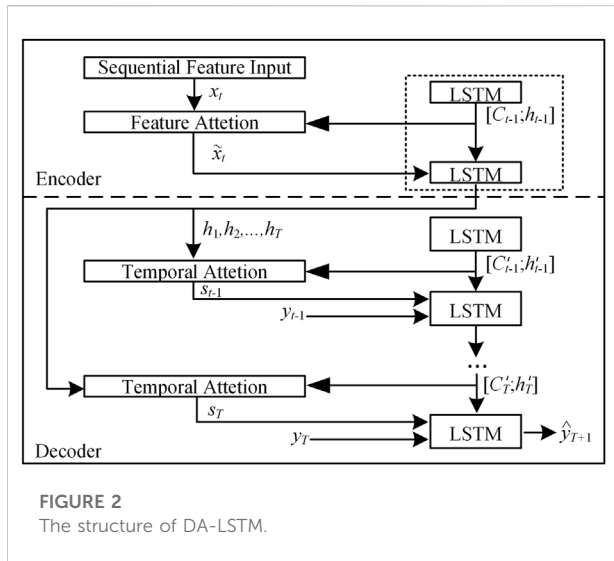


FIGURE 2 The structure of DA-LSTM.

where,  $W_f$ ,  $W_i$  and  $W_o$  are the weight matrices of forget gate, input gate and output gate respectively, and  $b_f$ ,  $b_i$  and  $b_o$  are the corresponding biases.  $W_C$  is the input cell state weight matrix, and  $b_C$  is the bias of the input cell state.  $\sigma$  is the sigmoid activation function, which transforms the output into  $[0,1]$  interval,  $\tanh$  is a hyperbolic tangent activation function, which transforms the output into the  $[-1,1]$  interval. Eq. 13 represents a forget gate for judging whether the previous information is retained. Eq. 14 represents an input gate that determines whether the current information is written to the cell state at time  $t$ ; Eq. 15 creates a new vector containing all possible values through the tanh activation function and adds it to the cell state; Eq. 16 represents an output gate that determines the information to be included in the output content. Input the hidden layer output  $h_t$  to obtain the PV output  $y_t$ , and the calculation is as shown in Eqs. 17–19.

$$C_t = f_t * C_{t-1} + i_t * C'_t \tag{17}$$

$$h_t = o_t * \tanh(C_t) \tag{18}$$

$$y_t = W_d h_t + b_d \tag{19}$$

where,  $*$  denotes the multiplication of matrix elements.  $W_d$  and  $b_d$  are the adjustable weight matrix and the bias of the output layer, respectively.

### 2.3.2 Dual-stage attention

The performance of only using ordinary LSTM under sudden weather and extreme weather conditions is often poor, so the attention mechanism is introduced. The attention mechanism imitates how the human brain processes information, which improves the performance of the neural network (Qu et al., 2021). In this paper, the feature attention mechanism is introduced at the encoder side, and the time attention mechanism is introduced at the decoder side to build a dual-

stage attention mechanism, so as to obtain a more accurate relationship between PV output power and meteorological factors and historical information. The dual-stage attention structure can be shown in Figure 2.

Feature attention models the importance of each feature and assigns different attention to each dimension of the input (Zeng et al., 2022). In order to obtain the contribution rate of each meteorological feature to the PV output at the current time, the relevant meteorological features at time  $t$  are input into the feature attention mechanism to obtain the attention weight vector  $e_t$ :

$$e_t = V_e^T \tanh(W_e [h_{t-1}, C_{t-1}] + U_e x^{meP} + b_e) \tag{20}$$

where,  $e_t = (e_t^1, e_t^2, \dots, e_t^k)$  is the combination of attention weight coefficients corresponding to each meteorological feature at time  $t$ ;  $V_e$ ,  $W_e$  and  $U_e$  are the weight matrix of attention mechanism, and  $b_e$  is the bias. Normalization is performed according to Eq. 21, using the Softmax function so that the sum of the feature attention weights is 1. The normalized feature attention weight is expressed as  $\alpha_t = (\alpha_t^1, \alpha_t^2, \dots, \alpha_t^p, \dots, \alpha_t^k)$ , where  $\alpha_t^p$  is the feature attention weight value of the  $p$ th relevant meteorological feature at time  $t$ .

$$\alpha_t^p = \frac{\exp(e_t^p)}{\sum_{i=1}^k \exp(e_t^i)} \tag{21}$$

Multiplying the feature attention weight value  $\alpha_t^p$  with the corresponding meteorological feature value  $x_t^{meP}$  to obtain the correlation feature  $\tilde{x}_t^{meP}$  considering the contribution rate of different meteorological features:

$$\tilde{x}_t = (\alpha_t^1 x_t^{me1}, \alpha_t^2 x_t^{me2}, \dots, \alpha_t^k x_t^{mek}) \tag{22}$$

By introducing the feature attention mechanism, the input to the LSTM network is no longer the original meteorological feature value, but the correlation feature weighted by the contribution rate. It adaptively strengthens the key factors affecting the PV output, weakens the less relevant meteorological factors, and improves the modeling accuracy.

Temporal attention mechanism is introduced for finding the characters of trend and cycle and determining the key node for the current PV output power adaptively (Zhu et al., 2022). In order to obtain the contribution rate of the sequential state in a period of time on the PV output at the current time, obtain the weight of the hidden state of the corresponding time sequence, and extract the historical key node, introduce the temporal attention mechanism at the decoding output side. The temporal attention weight of the hidden layer state at the current time depends on the hidden layer state  $h_t = (h_t^1, h_t^2, \dots, h_t^T)$  of the selected historical time sequence of LSTM,  $T$  is the time length of the input sequence. Taking it as an input, the temporal attention weight coefficient  $l_t = (l_t^1, l_t^2, \dots, l_t^r, \dots, l_t^T)$  at the current time  $t$  is obtained, as shown in the Eq. 23:

$$l_t^r = V_d^T \tanh(W_d [h'_{t-1}, C'_{t-1}] + U_d h_t^r) \tag{23}$$

where,  $V_d$  and  $W_d$  are the corresponding weights of the temporal attention, and  $U_d$  is the bias. The temporal attention weight is also obtained by normalizing with the Softmax function, and the comprehensive information  $s_t$ , related to the sequential state characteristics, at time  $t$  is obtained by considering the contribution rate of the information at each time in the input sequence.

$$\beta_t^r = \frac{\exp(l_t^r)}{\sum_{j=1}^T \exp(l_j^r)} \tag{24}$$

$$s_t = \sum_{\tau=1}^T \beta_\tau^r h_\tau^r \tag{25}$$

Combine comprehensive information  $s_t$  with original output  $y_t$ :

$$y'_t = \tilde{W} [y_t, s_t] + \tilde{b} \tag{26}$$

where,  $\tilde{W}$  and  $\tilde{b}$  are the weights and bias input by the front-end fusion of the LSTM network. Considering the contribution rate of historical information, the hidden layer state at time  $t$  is obtained:

$$h'_t = f_1(h'_{t-1}, y'_{t-1}) \tag{27}$$

where,  $f_1$  is the LSTM network. The PV output at time  $T+1$  can be expressed as:

$$\hat{y}_{T+1} = V_y^T (W_y [h'_T, s_T] + b_w) + b_y \tag{28}$$

where,  $W_y$  and  $b_w$  are the weights and bias of the LSTM network.  $V_y$  and  $b_y$  are the weights and bias of the whole network before dimensional transformation.

## 2.4 Optimization of photovoltaic panel deployment in the power plant

### 2.4.1 Objective function

The optimization of PV panel deployment in the power plant takes the actual output power of the whole PV power plant and the lowest cost of PV panel deployment as the optimization objective, takes the whole year as the time scale, and makes full use of the meteorological advantages of each terrain to improve the efficiency and economy of the whole power plant.

$$F_1 = \max \sum_{j=1}^N n_j y_{j,year} \tag{29}$$

$$y_{j,year} = \sum_d^{365} y_{j,d} \tag{30}$$

Eq. 29 is the objective function that maximizes total of the annual PV output power in each terrain, that is, the annual

expected output of the whole planning PV power plant, where  $n_j$  represents the number of PV panels installed in the  $j$ th terrain.  $y_{j,year}$  is the annual expected output power of a single PV panel in the  $j$ th terrain. The LSTM model is trained using historical data, and then the annual expected output of the unit PV panel in each terrain is calculated separately based on the actual meteorological conditions of each terrain and on the time scale of day. The annual output in the  $j$ th terrain can be expressed by Eq. 30, where  $y_{j,d}$  represents the expected output of a single PV panel in the  $j$ th terrain on day  $d$ .

$$F_2 = \min \sum_{j=1}^N C_j \tag{31}$$

$$C_j = n_j C_{sj} + C_{lj} \tag{32}$$

Eq. 31 is the objective function to minimize the deployment cost of all PV panels in the whole PV power plant, where  $C_j$  represents the total cost of installing PV panels in the  $j$ th terrain. Eq. 32 represents the installation cost of a single PV panel. Because the purchase cost of each PV panel is the same, the purchase cost can be ignored.  $C_{sj}$  represents the cost of occupying land for the installation of a single PV panel in the  $j$ th terrain, and  $C_{lj}$  represents the cost required for the line routing between the PV field in the  $j$ th terrain and the GS.

### 2.4.2 Constraint conditions

Since the total amount of PV panels is unchanged, only the cost required for the line routing from each terrain to the GS is considered when calculating the total line routing cost. It is assumed that the  $j$ th terrain contains  $J$  sub-areas, that is,  $D_j = \{X_1^{terrain}, X_2^{terrain}, \dots, X_J^{terrain}\}$ . The line routing cost can be calculated as follows:

$$C_{lj} = C_{line,j} D_{j5} \tag{33}$$

$$C_{line,j} = \sum_{u=1}^L z_u C_{line,j,u} \tag{34}$$

$$\sum_{u=2}^L n_{u-1,limit} z_u \leq n_j \leq \sum_{u=1}^L n_{u,limit} z_u \tag{35}$$

$$\sum_{u=1}^L z_u \leq 1 \tag{36}$$

$$D_{j5} = \frac{1}{J} \sum_{i=1}^J x_{i5}^{terrain} \tag{37}$$

$$C_{sj} = C_{space,j} A_j \tag{38}$$

Eq. 33 shows that the line routing cost  $C_{lj}$  is related to the distance from each terrain to the GS and the unit cost of the line, and  $C_{line,j}$  is the unit cost of line routing per kilometer of the  $j$ th terrain. Eq. 34 is the calculation method of line routing cost per kilometer for the  $j$ th terrain. When the number of PV panels installed in a terrain exceeds a certain limit, the voltage level of the line needs to be increased to meet its maximum transmission power, and then the unit cost of the line will increase accordingly.

After the preliminary evaluation, it is assumed that there may be  $L$  voltage levels in the whole planning area.  $n_{u,limit}$  represents the maximum number of PV panels that can be accessed with the  $u$ th voltage level. By introducing a set of 0–1 variables  $z_u$ , the range to which  $n_j$  belongs can be defined, as shown in Eqs. 35, 36.  $D_{j5}$  is the distance from the  $j$ th terrain to the GS, which is the average of the distance from the  $J$  sub-areas included in the  $j$ th terrain to the GS, as shown in Eq. 37. Eq. 38 calculates the cost of land consumption, where  $A_j$  is the actual area occupied by a unit of PV panel installed in the  $j$ th terrain.

The deployment of PV panels is also constrained by certain geographical conditions as follows:

$$n_j A_j \leq A_{j, sum} \tag{39}$$

$$A_j = A_{PV} A_{slope} \tag{40}$$

$$A_{j, sum} = J A_N \tag{41}$$

$$D_{jA} \leq D_{jA, limit} \tag{42}$$

Eq. 39 is the area constraint. The actual area of PV panel installation is related to the gradient and slope direction of the installation site, as shown in Eq. 40, where  $A_{PV}$  is the area of a PV panel itself, and  $A_{slope}$  is the area coefficient affected by the gradient and slope direction.  $A_{j, sum}$  is the total area of the  $j$ th terrain, which is calculated by Eq. 41, and is the sum of the total  $J$  sub-areas included in the  $j$ th terrain. Also, when the gradient of a terrain is too steep, it is not proper to install a PV panel there, as shown in Eq. 42.

According to the planned capacity of PV power plant, the number of PV panels installed in the power plant can be obtained as follows:

$$n_{sum} = \sum_{j=1}^N n_j \tag{43}$$

### 3 Case studies

#### 3.1 Parameter setting and dataset description

The case studied in this paper is the planning area of a large-scale centralized PV power plant in Southwest China, and the estimated installed capacity of the whole PV power plant is 210 MW. Obtain the PV output power data of an existing PV power plant near the planning area in 2021 and the meteorological data during the same period and at the same place. The temporal resolution of the data is 1 day. The meteorological data of each terrain in the planning area are obtained through interpolation due to the lack of actual weather station. The geographical data are obtained through SRTM data released by NASA (Jarvis et al., 2008). The parameters of the selected PV panel are: the power is 600 W and the size is 2172 mm × 1303 mm.

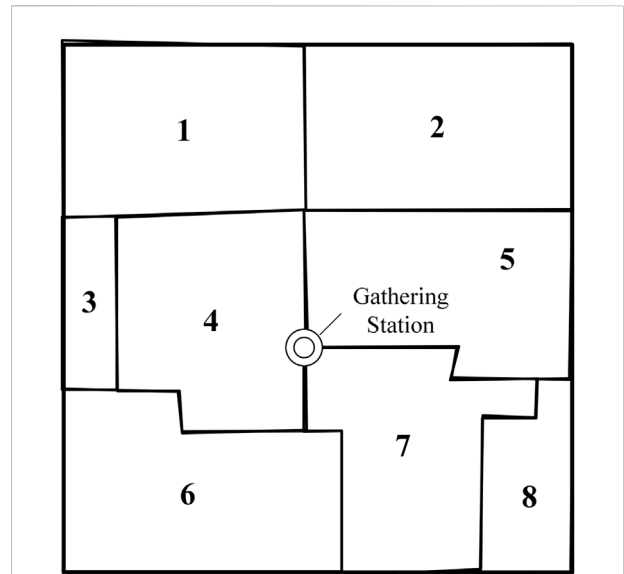


FIGURE 3 The results of terrain division.

#### 3.2 Terrain division

The terrain in the planning area is divided by FCM algorithm. The annual sunshine durations, average altitude, slope direction, slope, the distance between the terrain center and the GS, and the direction of the terrain center relative to the GS in each sub-area are used to complete the terrain clustering. The result is shown in Figure 3.

After the terrain division, the geographic conditions of each terrain are collected and counted in Table 1. From the Table 1, it can be seen that there are great differences in geographical conditions among the terrains in the planning area. After the terrain is divided, the relationship between meteorological factors and PV output power can be analyzed more accurately, and then more accurate PV expected annual output power can be obtained.

#### 3.3 Main meteorological factors selection

The first step of meteorological analysis is single factor analysis which is aimed to select main meteorological factors. Table 2 presents the results of single meteorological factor analyzed by Pearson correlation. As mentioned in Section 2.2, the Pearson correlation coefficient is a value between -1 and 1. The closer the absolute value of Pearson correlation coefficient is to 1, the stronger the correlation between this meteorological factor and PV output power is. If the value is positive, the meteorological factor is positively related to the PV output power, otherwise, it is negatively related.

TABLE 1 The geographic conditions of each terrain.

Terrain	N/°	E/°	Total Area/km <sup>2</sup>	Distance to GS/km	Gradient/°	Slope direction	Average altitude/m
1	28.851	99.394	4.66	2.487	10.3	North	4565
2	28.851	99.417	5.00	2.493	22.6	South	4349
3	28.834	99.394	1.06	2.071	35.1	North	4401
4	28.830	99.399	4.34	0.875	6.9	North	4584
5	28.835	99.417	4.50	1.320	7.4	North	4321
6	28.817	99.394	4.95	1.810	32.4	South	4213
7	28.817	99.417	4.04	1.391	7.8	South	4477
8	28.817	99.434	1.75	2.578	37.8	South	4248

TABLE 2 The Pearson correlation coefficient of each meteorological factor.

Meteorological factors	Pearson correlation coefficient
Total radiation intensity	0.821
Average temperature	0.311
Relative humidity	-0.691
Wind speed	0.410
Total cloud cover	-0.526
Sea level pressure	-0.108
Precipitation	-0.165
Snowfall	-0.215
Surface pressure	-0.087

Five main meteorological factors are selected depending on the Pearson correlation coefficient. In this case, the total radiation intensity, average temperature, relative humidity, wind speed and total cloud cover are selected as the main meteorological factors. Among them, the total sunshine intensity, average temperature and wind speed are positively correlated with PV output power, and the relative humidity and total cloud cover are negatively correlated with PV output power. Moreover, the total sunshine intensity is the most important factors.

### 3.4 Photovoltaic output power calculation

The PV output power and five main meteorological factors data are analyzed by using the DA-LSTM model, and then compared with the ordinary LSTM model. The accuracy of the model is verified by using the root mean square error (RMSE)  $e_{RMSE}$  and the mean absolute error (MAE)  $e_{MAE}$ . In order to analyze the performance of the DA-LSTM model, this paper firstly calculates the output power of the existing PV power plant. This paper compares the calculation results of the DA-LSTM model for PV output power 1 day in advance with the

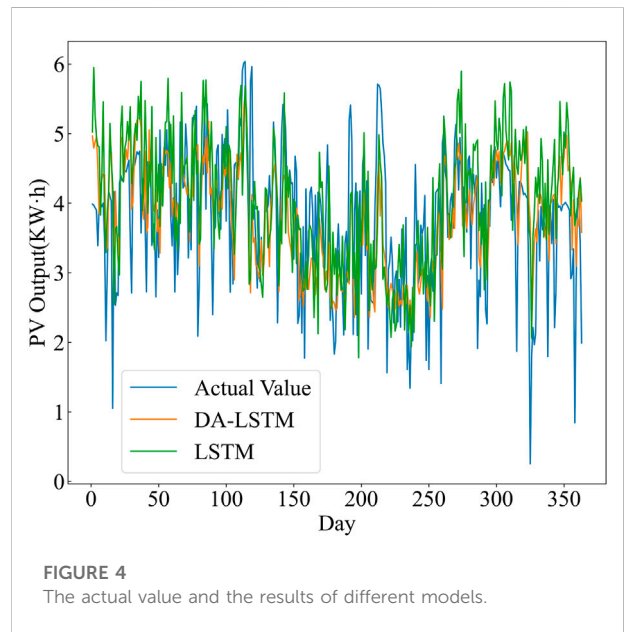


FIGURE 4 The actual value and the results of different models.

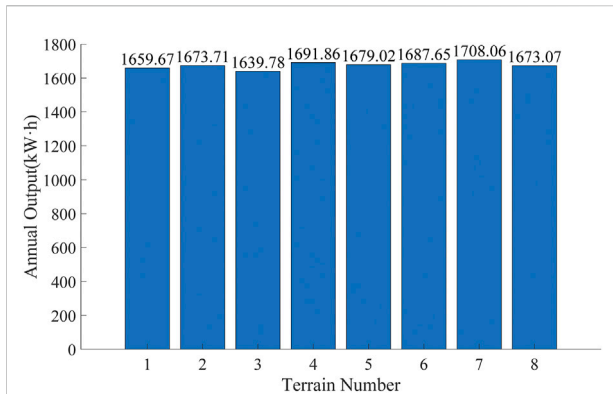
TABLE 3 The performances of different models.

Model	$e_{RMSE}$	$e_{MAE}$
DA-LSTM	0.896	0.697
LSTM	1.316	1.025

calculation results of the LSTM model without attention mechanism, as shown in Figure 4. It is obvious from Figure 4 that the calculation results of the DA-LSTM model are closer to the real value. Table 3 presents the RMSE and the MAE  $e_{MAE}$  of two different models. The RMSE and MAE produced by DA-LSTM model is smaller than ordinary LSTM, which means the DA-LSTM model performs better in PV output power calculation considering multiple meteorological factors.

After verifying the accuracy of the DA-LSTM model, the annual expected output power of a single PV panel in each





**FIGURE 5**  
The annual expected output power of a single PV panel in each terrain.

terrain in the planning area is calculated, as shown in Figure 5. It can be seen that there is a certain difference in the output power of PV panels in different terrain. Considering the annual total sunshine intensity and annual sunshine durations of each terrain, it can be found that places with good solar resources are not necessarily the regions with the largest PV output power. That is because other meteorological factors do have a visible impact on PV output. In addition, terrain 7 has the highest PV output power. Moreover, since there are a large number of PV panels in a PV power plant, the priority of the installation site has a great impact on the output power of the final PV power plant.

### 3.5 Results of photovoltaic panel deployment

The deployment method proposed in this paper also considers conventional capacity constraints, area constraints and so on. However, its characteristic is that its

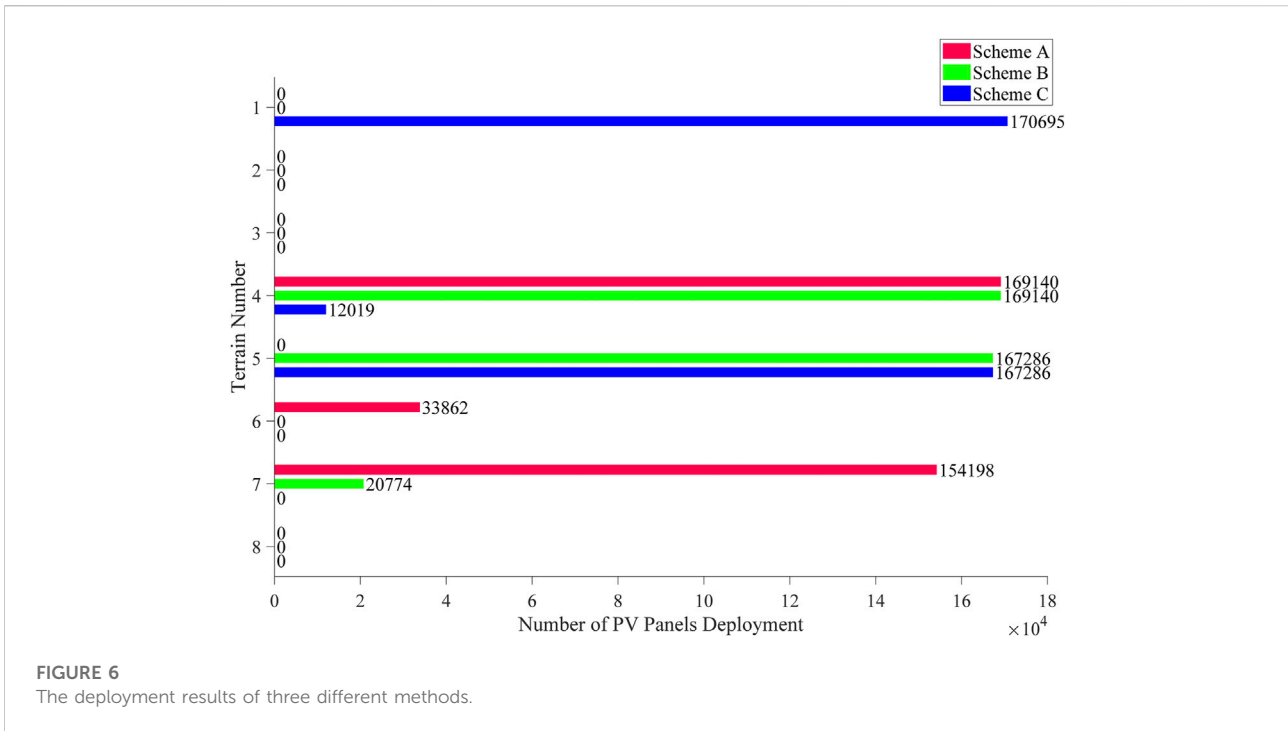
objective function considers the maximum actual PV output power. To analyze the benefits of the method proposed in this paper, scheme B and C are set as comparison, and the proposed method is scheme A. The difference between the comparison methods is mainly in the objective function, which considers the maximum total sunshine intensity and the maximum total sunshine durations respectively. The PV resource parameters required by the three different methods are shown in Table 4. The parameters required by the two methods for comparison are easy to obtain.

Figure 6 shows the deployment results of three different methods. Obviously, the installation location and quantity of PV panels are different under three methods. Also, it is not difficult to understand that, considering the minimum cost, all deployment method will prefer to select the terrain nearest to the collection station. Terrain 4, 5, 7 are the nearest, therefore, these terrains are given high priority to install PV panels. But the actual deployment of each terrain depends on constraints and different objective functions. It is worth noting that all three methods choose to install a certain number of PV panels on terrain 4, which also proves that terrain four is the best comprehensively.

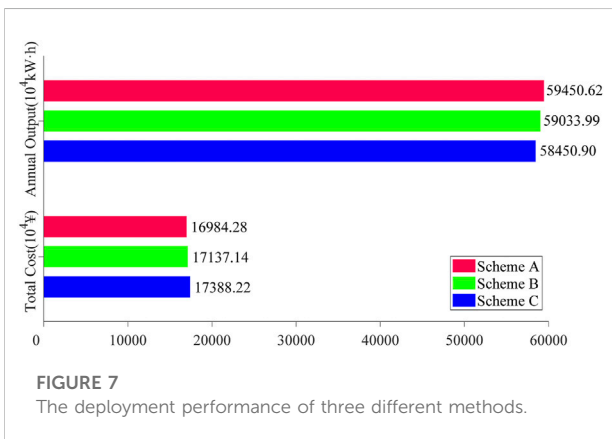
Figure 7 shows the deployment performance of three different methods. Obviously, the installation location and quantity results of three different methods are different. When the estimated PV installed capacity is given, it can be seen that the PV expected output of the purposed method is higher than that of the methods for comparison. The proposed method increases the expected output power by 0.71% and 1.71% compared with scheme B and scheme C respectively. Scheme A also lower the cost, which reduces the cost by 0.89% and 2.32% compared with scheme B and scheme C, respectively. Comparing the effects of the three deployment schemes, we can see that the method proposed in this paper improves the annual PV output power and reduces the total construction cost. In other words, the proposed method effectively improves the efficiency of solar energy

TABLE 4 The PV resource parameters of each terrain.

Terrain	Annual output/kW·h	Annual solar irradiation/MJ·m <sup>-2</sup>	Annual sunshine duration/h
1	1659.67	6594	2655
2	1673.71	6586	2646
3	1639.78	6632	2622
4	1691.86	6635	2642
5	1679.02	6635	2672
6	1687.65	6628	2635
7	1708.06	6622	2605
8	1673.07	6632	2600



**FIGURE 6**  
The deployment results of three different methods.



**FIGURE 7**  
The deployment performance of three different methods.

utilization and creates higher economic and environmental value.

## 4 Conclusion

An optimization method for the deployment of PV panels in a centralized PV power plant under multiple meteorological and geographical factors is proposed. When deploying PV panels, the geographical and meteorological condition differences in various terrains of the planning area are fully considered, so as to obtain the

maximum PV output power. Taking a planning area and an nearby existing PV power plant as examples, the data of interest are collected for case studies and the results of case studies are analyzed.

Considering that the PV panels in the centralized PV power plant are densely arranged during installation, the connectivity between the sub-areas is taken into account when dividing the different terrain in the PV power plant, so that the sub-areas in each terrain are not only similar in geographical characteristics, but also adjacent in geographical locations. The proposed terrain division method meets the needs of the PV power plant planning.

Then, Pearson correlation analysis succeeds in main meteorological selection. Moreover, DA-LSTM model has shown acceptable results in PV output power calculation, and successfully calculates the annual PV output power of various terrains in the planning area.

Finally, the advantages of the optimization method based on terrain division and PV output power calculated by DA-LSTM are proved. Compared with the comparison method, the proposed method has higher output power and less construction cost. The application of this method can improve the efficiency of PV resources utilization and create economic and environmental benefits, which promotes the use of PV technology.

## Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author.

## Author contributions

All authors have made substantial contributions to the conception, design of the work; analysis; and drafting of the paper. All authors read and approved the final manuscript.

## Funding

This research is supported by the Science and Technology Project of State Grid Sichuan Economic Research Institute (Grant No. SGSCJY00GHJS2200046).

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## Conflict of interest

Author ZM was employed by the company State Grid Sichuan Electric Power Company.

The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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