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# THERMOELASTICITY WITH TEMPERATURE AND MICROTEMPERATURES WITH FADING MEMORY 

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#### Abstract

In this paper, we investigate a model of poro-thermoelasticity with microtemperatures where the behavior of the body is influenced by the history of both temperature and microtemperatures. Mathematically, this translates into a system of partial integro-differential equations. Under suitable condition on the tensors appearing in the model, we prove that the resulting system is well posed. In the one-dimensional case, the exponential decay of the energy is proved.


## 1. Introduction

1.1. Thermoelasticity of porous materials. The classical theory of thermoelasticity is especially well-suited for the description of macroscopic phenomena related to elastic deformations. Notwithstanding, there are many physical situations in which microscopic phenomena play a big role and, therefore, cannot be ignored. From a modeling perspective, this requires to take into account the microstructure of the material. Perhaps the first to allow for such effects were the Cosserat brothers, who proposed micropolar theories at the beginning of the 20th century [6]. However, it was not until the Sixties that materials with microstructure started to be investigated in a significant way. For a thorough description of these models we refer to [11, 21].

Among the several theories that appeared during this period, we want to focus on the theory of materials with voids (also known as porous materials), first introduced by Cowin and Nunziato in $[7,8,33]$. The fundamental concept underlying this model is the decomposition of the bulk density as the product of two fields, namely, the density field of the matrix material and the volume fraction field. The latter expresses the idea that the material point might have some small voids, and ultimately introduces an additional degree of freedom in the model. Let aside its undisputed mathematical interest, porous materials have soon found application in many fields of technology, ranging from the building industry, where they are used for their appealing properties of lightness and resistance, to medicine, to repair injuries in bones. For some extensive comments regarding the applicability of this theory, we suggest to look at [40, p.307-308]. Nowadays, porous materials have been considered and studied in such a large number of situations that it would not be possible to mention all of the contributions in the field. For an introduction to the subject and its applications, we direct the interested reader to [2, 14, 15, 41], and references therein, while for some works concerning the dynamical aspect of the theory we refer to $[4,12,13,29,31,36,39]$, but the list is far from being exhaustive.

[^0]Between all the aspects which have been considered when studying deformations at the microstructural level (micropolar, microstretch, etc.), we are mostly interested in the concept of microtemperatures, which is related to the temperature distribution in porous materials. Materials with a microstructure are usually thought as composed of microelements. In turn, each of these microelements is modeled itself as a material with deformations and temperature. If we denote by $\mathbf{x}$ the center of mass of a microelement and denote by $\tilde{\theta}$ the absolute temperature, we can consider the approximation

$$
\tilde{\theta}\left(\mathbf{x}^{\prime}, t\right)=\tilde{\theta}(\mathbf{x}, t)+T_{i}\left(x_{i}^{\prime}-x_{i}\right)+O\left(d^{2}\right),
$$

where $O\left(d^{2}\right)$ is a second order term in the diameter $d$ of the microelement. The terms $T_{i}$ determine the temperature variation in the microelement and is what we call microtemperatures. Historically, this notion was proposed for the first time in the works of Grot, Riha and Verma [19, 37, 38, 42], even though it did not receive much attention until the article [25] was published in 2000. The latter represented a turning point in the study of materials with microtemperatures and sparked a lot of interest in the subject. Today we can say that there is an important amount of scientific work related to this phenomenon, see, e.g., [22, 23, 24, 26, 27, 30].
1.2. A causality issue. Most of the studies carried out on the topic of thermoelasticity with microtemperatures over the last decade assume both the temperature and the microtemperatures to follow the parabolic structure related to the Fourier law of heat conduction. It has been verified that, similarly to how the usual thermal dissipation acts as a damping mechanism on the deformations, the microthermal dissipation has the same effect on the microstructure. Although this behavior is certainly significant from a physical standpoint, from a mathematical perspective this is somewhat expected. Indeed, the regularizing nature of the Fourier law is well known, and usually endows a physical system of good dissipative properties. Nevertheless, the Fourier law has a strong disadvantage, since it predicts an instantaneous propagation of thermal waves. This fact is incompatible with the causality principle, and has prompted physicists and mathematicians alike to propose alternative laws for the description of heat conduction in the theory of thermoelasticity. For these reasons, the notion of microtemperatures has been recently extended to the case in which the Fourier law is replaced, first, by the (hyperbolic) Cattaneo law [3], and then by Tzou's theory [28]. In both situations, the authors have observed similar behaviors and dissipative properties to the Fourier case.
1.3. Main results. Another classical way to get rid of the paradox of infinite speed of propagation is to relax the constitutive law for the thermal flux by means of a convolution integral. This makes the dynamics nonlocal in time, meaning that the evolution of the heat flux at time $t$ depends also on its history up time $t$. This idea was originally introduced by Gurtin and Pipkin in [20]. An interesting study about materials with memory (also on the thermal variables) can be found at [1]. Today, the literature on the subject is quite rich and active, and we refer the interested reader to the works of $[5,16,32]$, just to name a few. The present work fits into the above setting. Indeed, our goal is threefold. First and foremost, we want to define a theory for poro-thermoelasticity with microtemperatures that considers the history of both the temperature and that of the microtemperatures. To
be more specific, we will start from the model of poro-thermoelasticity with microtemperatures proposed in [3], and show how this can be interpreted (and generalized) by means of the theory of materials with memory. This extension makes it possible to consider a wider range of problems, depending on the choice of the different memory kernels. Secondly, we want to propose some adequate conditions that will allow us to say that the problem is well posed in the Hadamard sense (that is, existence, uniqueness and continuous dependence of solutions). Finally we will restrict ourselves to the one-dimensional case and demonstrate (under suitable conditions) the exponential decay of solutions.

The mathematical tool best suited to treat partial differential equations with memory terms is the well known past history framework, first introduced by Dafermos in the seminal work [9]. This setting will allow us to exploit results from the theory of linear semigroups. More in detail, we will prove the well-posedness of our system by means of the Lumer-Phillips corollary to the Hille-Yosida theorem, and use the classical characterization of exponentially stable semigroups due to Gearhart, Greiner, Huang and Prüss (see, e.g, [10]) to demonstrate the exponential decay of the solutions in the one-dimensional case. The main mathematical difficulty of the problem at hand resides in the fact that we have to handle more than one memory term. As we will see, this requires some form of uniform control over the memory kernels, along the lines of the work [32].
1.4. Plan of the paper. In the next section we propose the new model that we are going to work with as well as the general assumptions on the constitutive fields. In Section 3 we propose the abstract setting for our problem and in Section 4 we rephrase the equations in the past history framework. The existence and uniqueness theorem is stated and proved in Section 5. In the last section we restrict our attention to the one dimensional case and obtain the exponential stability of the solutions.

## 2. The Model System

We consider a nonhomogeneous porous material occupying a smooth, bounded domain $\Omega \subset \mathbb{R}^{3}$. First, let us state the evolution equations for the theory of poro-thermoelasticity with microtemperatures for a centrosymmetric material. These equations are:

$$
\begin{gather*}
\rho \ddot{u}_{i}=t_{i j, j},  \tag{2.1}\\
J \ddot{\phi}=h_{j, j}+g,  \tag{2.2}\\
\rho \dot{\eta}=q_{j, j},  \tag{2.3}\\
\rho \dot{\epsilon}_{i}=q_{j i, j}+q_{i}-Q_{i} . \tag{2.4}
\end{gather*}
$$

The first two equations represent, respectively, the balances of the linear momentum and of the first stress moment. Here $\rho$ is the mass density, $u_{i}$ is the displacement vector, $t_{i j}$ is the stress tensor, $J$ is the equlibrated inertia, $\phi$ is the volume fraction, $h_{j}$ is the equilibrated stress and $g$ is the equilibrated body force. Next, we have the balances of the energy and of its first moment, where $\eta$ is the entropy, $q_{i}$ is the heat flux vector, $\epsilon_{i}$ is the first moment of the energy vector, $q_{i j}$ is the first heat flux moment tensor and $Q_{i}$ is the microheat flux average vector.

In order to obtain the final model, we complement the above relations with the constitutive equtions in the case of the Lord-Shulman theory. These are given by (see [3]):

$$
\begin{aligned}
& t_{i j}=A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \theta \\
& h_{i}=A_{i j} \phi_{, j}-N_{i j} T_{j} \\
& g=-D_{i j} u_{i, j}-\xi \phi+F \theta, \\
& \rho \eta=a_{i j} u_{i, j}+F \phi+a \theta, \\
& \rho \epsilon_{i}=-N_{j i} \phi_{, j}-B_{i j} T_{j} \\
& \tau \dot{q}_{i}+q_{i}=k_{i j} \theta_{, j}+H_{i j} T_{j} \\
& \tau \dot{q}_{i j}+q_{i j}=-P_{i j r s} T_{r, s} \\
& \tau \dot{Q}_{i}+Q_{i}=\left(k_{i j}-K_{i j}\right) \theta_{, j}+\left(H_{i j}-\Lambda_{i j}\right) T_{j},
\end{aligned}
$$

where we recall that $\theta$ is the temperature and $T_{i}$ are the microtemperatures. It is understood that all the tensors appearing in the above equations might depend on the space variable $\boldsymbol{x}$ and on time. However, to simplify the notation we will omit this dependence for the forthcoming computations. We can now formally solve the constitutive equations for $q_{i}, q_{i j}$ and $Q_{i}$. Multiplying by $\mathrm{e}^{t / \tau}$ the constitutive equation for $q_{i}$ we get

$$
\frac{d}{d t}\left(q_{i} \mathrm{e}^{t / \tau}\right)=\frac{1}{\tau} \mathrm{e}^{t / \tau}\left(k_{i j} \theta_{, j}+H_{i j} T_{j}\right) .
$$

Integrating and making the reasonable assumption that

$$
\lim _{t \rightarrow-\infty} q_{i}(t) \mathrm{e}^{t / \tau}=0
$$

we have

$$
\begin{aligned}
q_{i}(t) & =\int_{-\infty}^{t} \frac{\mathrm{e}^{-(t-s) / \tau}}{\tau}\left(k_{i j} \theta_{, j}(s)+H_{i j} T_{j}(s)\right) d s \\
& =\int_{-\infty}^{t} \frac{\mathrm{e}^{-(t-s) / \tau}}{\tau}\left(k_{i j} \dot{\alpha}_{, j}(s)+H_{i j} \dot{R}_{j}(s)\right) d s \\
& =\int_{0}^{\infty} \frac{\mathrm{e}^{-s / \tau}}{\tau}\left(k_{i j} \dot{\alpha}_{, j}(t-s)+H_{i j} \dot{R}_{j}(t-s)\right) d s,
\end{aligned}
$$

where we denote by (see [17, 18])

$$
\alpha(t)=\alpha(0)+\int_{0}^{t} \theta(s) d s, \quad R_{i}(t)=R_{i}(0)+\int_{0}^{t} T_{i}(s) d s
$$

respectively the thermal displacement and the microthermal displacement. Assuming now

$$
\lim _{t \rightarrow-\infty} \alpha_{, i}(t) \mathrm{e}^{t / \tau}=\lim _{t \rightarrow-\infty} R_{i}(t) \mathrm{e}^{t / \tau}=0
$$

we can integrate by parts to obtain

$$
q_{i}(t)=\frac{1}{\tau}\left(k_{i j} \alpha_{, j}(t)+H_{i j} R_{j}(t)\right)-\frac{1}{\tau^{2}} \int_{0}^{\infty} \mathrm{e}^{-s / \tau}\left(k_{i j} \alpha_{, j}(t-s)+H_{i j} R_{j}(t-s)\right) d s
$$

Calling

$$
\begin{aligned}
k_{i j}^{*}(s) & =\frac{\mathrm{e}^{-s / \tau}}{\tau} k_{i j} \\
H_{i j}^{*}(s) & =\frac{\mathrm{e}^{-s / \tau}}{\tau} H_{i j}
\end{aligned}
$$

and substituting into the above equation, we finally arrive to

$$
q_{i}(t)=k_{i j}^{*}(0) \alpha_{, j}(t)+H_{i j}^{*}(0) R_{j}(t)+\int_{0}^{\infty}\left(\frac{\partial}{\partial s} k_{i j}^{*}(s) \alpha_{, j}(t-s)+\frac{\partial}{\partial s} H_{i j}^{*}(s) R_{j}(t-s)\right) d s
$$

Now we can follow the same procedure for the constitutive equations of $q_{i j}$ and $Q_{i}$. This yields

$$
q_{i j}(t)=-P_{i j r s}^{*}(0) R_{r, s}(t)-\int_{0}^{\infty} \frac{\partial}{\partial s} P_{i j r s}^{*}(s) R_{r, s}(t-s) d s
$$

and

$$
\begin{aligned}
Q_{i}(t)= & \left(k_{i j}^{*}(0)-K_{i j}^{*}(0)\right) \alpha_{, j}(t)+\left(H_{i j}^{*}(0)-\Lambda_{i j}^{*}(0)\right) R_{j}(t) \\
& \int_{0}^{\infty}\left(\frac{\partial}{\partial s}\left(k_{i j}^{*}(s)-K_{i j}^{*}(s)\right) \alpha_{, j}(t-s)+\frac{\partial}{\partial s}\left(H_{i j}^{*}(s)-\Lambda_{i j}^{*}(s)\right) R_{j}(t-s)\right) d s .
\end{aligned}
$$

We note that $q_{i}, q_{i j}$ and $Q_{i}$ are given in terms of the history of the thermal displacement and the microthermal displacement. This represents an advantage with respect to consider the history of the temperature and the microtemperatures since we can define a larger class of materials (see Remark 2.1). In fact we can recover the materials proposed at [5] as a sub-class when the microtemperatures are not present.

Plugging the newly derived constitutive equations for $q_{i}, q_{i j}$ and $Q_{i}$ into those of porothermoelasticity, we have the system of field equations:

$$
\begin{gather*}
\rho \ddot{u}_{i}=\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \theta\right)_{, j},  \tag{2.5}\\
J \ddot{\phi}=\left(A_{i j} \phi_{, j}-N_{i j} T_{j}\right)_{, i}-D_{i j} u_{i, j}-\xi \phi+F \theta,  \tag{2.6}\\
a \ddot{\alpha}=-a_{i j} \dot{u}_{i, j}-F \dot{\phi}+\left(k_{i j}(0) \alpha_{, j}+H_{i j}(0) R_{j}\right)_{, i} \\
+\int_{0}^{\infty}\left(k_{i j}^{\prime}(s) \alpha_{, j}(t-s)+H_{i j}^{\prime}(s) R_{j}(t-s)\right)_{, i} d s,  \tag{2.7}\\
B_{i j} \ddot{R}_{j}=-N_{j i} \dot{\phi}_{, j}+\left(P_{i j r s}(0) R_{r, s}\right)_{, j}+\int_{0}^{\infty}\left(P_{i j r s}^{\prime}(s) R_{r, s}(t-s)\right)_{, j} d s \\
-K_{i j}(0) \alpha_{, j}(t)-\Lambda_{i j}(0) R_{j}(t)-\int_{0}^{\infty}\left(K_{i j}^{\prime}(s) \alpha_{, j}(t-s)+\Lambda_{i j}^{\prime}(s) R_{j}(s)\right) d s, \tag{2.8}
\end{gather*}
$$

where we have omitted the star to simplify the notation and used the standard writing $f^{\prime}(s)$ to indicate the derivative $\frac{\partial f}{\partial s}$. Our goal will be to study the well-posedness and asymptotic dynamics of system (2.5)-(2.8), supplemented with the Dirichlet boundary conditions

$$
u_{i}(\boldsymbol{x}, t)_{\mid \boldsymbol{x} \in \partial \Omega}=\phi(\boldsymbol{x}, t)_{\mid \boldsymbol{x} \in \partial \Omega}=\alpha(\boldsymbol{x}, t)_{\mid \boldsymbol{x} \in \partial \Omega}=R_{i}(\boldsymbol{x}, t)_{\mid \boldsymbol{x} \in \partial \Omega}=0
$$

2.1. General assumptions. In greater generality, we will consider the system of equations (2.5)-(2.8) with general memory kernels

$$
k_{i j}=k_{i j}(s), \quad K_{i j}=K_{i j}(s), \quad H_{i j}=H_{i j}(s), \quad \Lambda_{i j}=\Lambda_{i j}(s), \quad P_{i j r s}=P_{i j r s}(s),
$$

which we will assume independent of $\boldsymbol{x} \in \Omega$. This assumption, albeit non necessary, greatly simplifies the exposition. Furthermore, we require that
(i) There exist positive contants $\rho_{0}, J_{0}, \alpha_{0}, B_{0}$ such that

$$
\rho(\boldsymbol{x}) \geq \rho_{0}, J(\boldsymbol{x}) \geq J_{0}, a(\boldsymbol{x}) \geq a_{0}, B_{i j}(\boldsymbol{x}) T_{i} T_{j} \geq B_{0} T_{i} T_{i} .
$$

(ii) There exists a positive constant $A_{0}$ such that

$$
A_{i j r s} \eta_{i j} \eta_{r s}+2 D_{i j} \eta_{i j} \phi+\xi \phi^{2} \geq A_{0}\left(\eta_{i j} \eta_{i j}+\phi^{2}\right)
$$

for every $\boldsymbol{\eta}=\left(\eta_{i j}\right)$, and $\phi \in \mathbb{R}$.
(iii) The functions $k_{i j}, \Lambda_{i j}, P_{i j r s}$ are symmetric in the sense that

$$
k_{i j}=k_{j i}, \quad \Lambda_{i j}=\Lambda_{j i}, \quad P_{i j r s}=P_{r s i j} .
$$

Furthermore, we assume that

$$
\begin{equation*}
K_{i j}=H_{j i} . \tag{2.9}
\end{equation*}
$$

(iv) There exists a positive constant $g_{0}$ such that for every $\boldsymbol{\xi}=\left(\xi_{i}\right), \boldsymbol{\zeta}=\left(\zeta_{i}\right)$ and $\boldsymbol{\eta}=\left(\eta_{i j}\right)$,

$$
\begin{aligned}
k_{i j}(\infty) \xi_{i} \xi_{j} & +\left(K_{i j}(\infty)+H_{j i}(\infty)\right) \zeta_{i} \xi_{j}+\Lambda_{i j}(\infty) \zeta_{i} \zeta_{j}+P_{i j r s}(\infty) \eta_{i j} \eta_{r s} \\
& \geq g_{0}\left(\xi_{i} \xi_{i}+\zeta_{i} \zeta_{i}+\eta_{i j} \eta_{i j}\right),
\end{aligned}
$$

where

$$
k_{i j}(\infty)=\lim _{s \rightarrow \infty} k_{i j}(s)
$$

and similarly for the other kernels.
(v) There exists a positive decreasing continuous and integrable scalar function $\ell(s)$ and a constant $\kappa \geq 1$ such that

$$
\begin{aligned}
& \ell(s)\left(\xi_{i} \xi_{i}+\zeta_{i} \zeta_{i}+\eta_{i j} \eta_{i j}\right) \\
& \quad \leq-k_{i j}^{\prime}(s) \xi_{i} \xi_{j}-\left(K_{i j}^{\prime}(s)+H_{j i}^{\prime}(s)\right) \zeta_{i} \xi_{j}-\Lambda_{i j}^{\prime}(s) \zeta_{i} \zeta_{j}-P_{i j r s}^{\prime}(s) \eta_{i j} \eta_{r s} \\
& \quad \leq \kappa \ell(s)\left(\xi_{i} \xi_{i}+\zeta_{i} \zeta_{i}+\eta_{i j} \eta_{i j}\right)
\end{aligned}
$$

for every $\boldsymbol{\xi}=\left(\xi_{i}\right), \boldsymbol{\zeta}=\left(\zeta_{i}\right)$ and $\boldsymbol{\eta}=\left(\eta_{i j}\right)$. We denote by

$$
\varkappa=\int_{0}^{\infty} \ell(s) d s
$$

the resultant of $\ell$.
(vi) It holds

$$
k_{i j}^{\prime \prime}(s) \xi_{i} \xi_{j}+\left(K_{i j}^{\prime \prime}(s)+H_{j i}^{\prime \prime}(s)\right) \zeta_{i} \xi_{j}+\Lambda_{i j}^{\prime \prime}(s) \zeta_{i} \zeta_{j}+P_{i j r s}^{\prime \prime}(s) \eta_{i j} \eta_{r s} \geq 0
$$

for every $\boldsymbol{\xi}=\left(\xi_{i}\right), \boldsymbol{\zeta}=\left(\zeta_{i}\right)$ and $\boldsymbol{\eta}=\left(\eta_{i j}\right)$.

Assumptions (i)-(iii) are natural in the context of thermoelasticity. Indeed, the meaning of (i) is clear, while (ii) is saying that the mechanical energy of the system is positive definite. This hypothesis plays a critical role in the context of elastic stability. On the other hand, assumptions (iv)-(vi) arise naturally in the study of equations with memory terms (see e.g. [35]).

Remark 2.1. The observant reader will have noticed that assumption (iv) is in contrast with the exponential memory kernels that we have found integrating the constitutive equations, where, for instance, $k_{i j}^{*}(\infty)=0$. However, in order to consider the general problem we must allow for the case $k_{i j}(\infty) \neq 0$ (and the same for the other kernels). In this way, for example, we recover the model analyzed in [5]. The case of kernels vanishing at infinity will be the object of future works.

Assumption (2.9) is related with Onsager's postulate in the case of the classical theory. From now on we will always write $K_{i j}$ instead of $H_{j i}$. We note that $K_{i j}+H_{j i}=2 K_{i j}$. We conclude this section with a technical lemma, which will be useful in the sequel.
Lemma 2.2. Let assumptions (iii) and (v) hold. Then for every $i, j=1,2,3$ we have

$$
-k_{i j}^{\prime}(s) \leq \kappa \ell(s) \quad \forall s \in \mathbb{R}^{+}
$$

and the same holds for $-\Lambda_{i j}^{\prime},-K_{i j}^{\prime}$ and $-P_{i j r s}^{\prime}$.
Proof. Setting in (2.10)

$$
\xi_{1}=1 \text { and } \xi_{2}=\xi_{3}=\zeta_{i}=\eta_{i j}=0 \quad \text { for } i, j=1,2,3,
$$

we see at once that

$$
-k_{11}^{\prime}(s) \leq \kappa \ell(s)
$$

In a similar fashion, we can show that the same holds for $-k_{22}^{\prime},-k_{33}^{\prime}$ and $-\Lambda_{i i}^{\prime},-P_{i j i j}^{\prime}$ for every $i, j$. Now consider the matrix

$$
\left(\begin{array}{ll}
-k_{11}^{\prime}(s) & -k_{12}^{\prime}(s) \\
-k_{21}^{\prime}(s) & -k_{22}^{\prime}(s)
\end{array}\right) .
$$

By assumption (iii) we have $-k_{12}^{\prime}(s)=-k_{21}^{\prime}(s)$. Moreover, it is easy to see that, by assumption (v), this matrix is actually positive definite. Therefore

$$
k_{12}^{\prime}(s) k_{21}^{\prime}(s)=\left(k_{12}^{\prime}(s)\right)^{2}=\left(k_{21}^{\prime}(s)\right)^{2} \leq k_{11}^{\prime}(s) k_{22}^{\prime}(s),
$$

from which we infer

$$
-k_{12}^{\prime}(s) \leq \kappa \ell(s)
$$

By the same token, one can show that all the off-diagonal entries of $-k_{i j}^{\prime},-\Lambda_{i j}^{\prime}$ and $-P_{i j r s}^{\prime}$ are also bounded by $\kappa \ell(s)$. Finally, let us turn to $-K_{i j}^{\prime}$. Observe first that it is not difficult to prove that $-k_{i i}^{\prime},-\Lambda_{i i}^{\prime}$ and $-P_{i j i j}^{\prime}$ are positive functions, by choosing $\boldsymbol{\xi}, \boldsymbol{\zeta}$ and $\boldsymbol{\eta}$ in a suitable way in (2.10). Now let us take

$$
\xi_{1}=\zeta_{1}=1 \text { and } \xi_{2}=\xi_{3}=\zeta_{2}=\zeta_{3}=\eta_{i j}=0 \quad \text { for } i, j=1,2,3
$$

Then, in view of (2.9), we have

$$
-k_{11}^{\prime}(s)-2 K_{11}^{\prime}(s)-\Lambda_{11}^{\prime}(s) \leq 2 \kappa \ell(s)
$$

By the positivity of $-k_{11}^{\prime}$ and $-\Lambda_{11}^{\prime}$ we finally get

$$
-K_{11}^{\prime}(s) \leq \kappa \ell(s)
$$

With the same reasoning we can show that the same holds for $-K_{i j}^{\prime}$ for every $i, j$, and this concludes the proof.

## 3. Functional Setting and Notation

We indicate by $(H,\langle\cdot, \cdot\rangle,\|\cdot\|)$ the usual Hilbert space $L^{2}(\Omega)$ and by $\left(V,\langle\cdot, \cdot\rangle_{1},\|\cdot\|_{1}\right)$ the standard Sobolev space $H_{0}^{1}(\Omega)$ of functions in $H^{1}$ vanishing on $\partial \Omega$. We denote by

$$
\boldsymbol{H}=\left[L^{2}(\Omega)\right]^{3}, \quad \boldsymbol{V}=\left[H_{0}^{1}(\Omega)\right]^{3}
$$

the corresponding vectorial versions, keeping the same scalar notation for their norms. We would like to rephrase equations (2.5)-(2.8) in the so-called past history framework. To this end, let us preliminarily introduce the Hilbert spaces

$$
\mathcal{M}=L_{\ell}^{2}\left(\mathbb{R}^{+}, V\right), \quad \boldsymbol{\mathcal { M }}=L_{\ell}^{2}\left(\mathbb{R}^{+}, \boldsymbol{V}\right)
$$

of square summable functions with respect to the measure $\ell(s) d s$, endowed with the scalar products

$$
\begin{aligned}
\left\langle\omega, \omega^{*}\right\rangle_{\mathcal{M}} & =\int_{0}^{\infty} \int_{\Omega} \ell(s) \omega_{, i}(\boldsymbol{x}, s) \omega_{, i}^{*}(\boldsymbol{x}, s) d \boldsymbol{x} d s \\
\left\langle\eta_{i}, \eta_{i}^{*}\right\rangle_{\mathcal{M}} & =\int_{0}^{\infty} \int_{\Omega} \ell(s)\left(\eta_{i}(\boldsymbol{x}, s) \eta_{i}^{*}(\boldsymbol{x}, s)+\eta_{i, j}(\boldsymbol{x}, s) \eta_{i, j}^{*}(\boldsymbol{x}, s)\right) d \boldsymbol{x} d s
\end{aligned}
$$

and norms

$$
\begin{aligned}
\|\omega\|_{\mathcal{M}}^{2} & =\int_{0}^{\infty} \int_{\Omega} \ell(s)\left|\omega_{, i}(\boldsymbol{x}, s)\right|^{2} \boldsymbol{x} d s \\
\left\|\eta_{i}\right\|_{\mathcal{M}}^{2} & =\int_{0}^{\infty} \int_{\Omega} \ell(s)\left(\left|\eta_{i}(\boldsymbol{x}, s)\right|^{2}+\left|\eta_{i, j}(\boldsymbol{x}, s)\right|^{2}\right) d \boldsymbol{x} d s
\end{aligned}
$$

Next, we define the Hilbert space

$$
\mathcal{N}=\mathcal{M} \times \mathcal{M}
$$

endowed with the standard product norm. Observe that, omitting for simplicity the explicit dependence of the involved functions on $s$ and $\boldsymbol{x}$, in view of assumption (v),

$$
\left\|\left(\omega, \eta_{i}\right)\right\|_{\mathcal{N}}^{2}=-\int_{0}^{\infty} \int_{\Omega} k_{i j}^{\prime} \omega_{, i} \omega_{, j}+2 K_{i j}^{\prime} \eta_{i} \omega_{, j}+\Lambda_{i j}^{\prime} \eta_{i} \eta_{j}+P_{i j r s}^{\prime} \eta_{i, j} \eta_{r, s} d \boldsymbol{x} d s
$$

is an equivalent norm on $\mathcal{N}$, with corresponding scalar product

$$
\left\langle\left(\omega, \eta_{i}\right),\left(\omega^{*}, \eta_{i}^{*}\right)\right\rangle_{\mathcal{N}}=-\int_{0}^{\infty} \int_{\Omega} k_{i j}^{\prime} \omega_{, i} \omega_{, j}^{*}+K_{i j}^{\prime}\left(\eta_{i} \omega_{, j}^{*}+\eta_{i}^{*} \omega_{, j}\right)+\Lambda_{i j}^{\prime} \eta_{i} \eta_{j}^{*}+P_{i j r s}^{\prime} \eta_{i, j} \eta_{r, s}^{*} d \boldsymbol{x} d s
$$

Finally, we introduce the phase space associated to our problem

$$
\mathcal{H}=\boldsymbol{V} \times \boldsymbol{H} \times V \times H \times V \times H \times \boldsymbol{V} \times \boldsymbol{H} \times \mathcal{N}
$$

endowed with the norm

$$
\begin{aligned}
\|\boldsymbol{u}\|_{\mathcal{H}}^{2} & =\int_{\Omega}\left(A_{i j r s} u_{i, j} u_{r, s}+2 D_{i j} u_{i, j} \phi+\xi|\phi|^{2}+A_{i j} \phi_{, i} \phi_{, j}+\rho\left|v_{i}\right|^{2}+J|\psi|^{2}+a|\theta|^{2}+B_{i j} T_{i} T_{j}\right) d \boldsymbol{x} \\
& +\int_{\Omega}\left(k_{i j}(\infty) \alpha_{, i} \alpha_{, j}+2 K_{i j}(\infty) R_{i} \alpha_{, j}+\Lambda_{i j}(\infty) R_{i} R_{j}+P_{i j r s}(\infty) R_{i, j} R_{r, s}\right) d \boldsymbol{x} \\
& -\int_{0}^{\infty} \int_{\Omega}\left(k_{i j}^{\prime} \omega_{, i} \omega_{, j}+2 K_{i j}^{\prime} \eta_{i} \omega_{, j}+\Lambda_{i j}^{\prime} \eta_{i} \eta_{j}+P_{i j r s}^{\prime} \eta_{i, j} \eta_{r, s}\right) d \boldsymbol{x} d s
\end{aligned}
$$

where

$$
\boldsymbol{u}=\left(u_{i}, v_{i}, \phi, \psi, \alpha, \theta, R_{i}, T_{i}, \omega, \eta_{i}\right)
$$

Thanks to assumptions (i), (ii), (iv) and (v), this is equivalent to the standard product norm defined on $\mathcal{H}$. We will also consider the infinitesimal generator of the righttranslation semigroup on $\mathcal{N}$, that is, the linear operator $\mathcal{T}$ given by

$$
\mathcal{T}\left(\omega, \eta_{i}\right)=-\left(\omega^{\prime}, \eta_{i}^{\prime}\right),
$$

with domain

$$
\mathfrak{D}(\mathcal{T})=\left\{\left(\omega, \eta_{i}\right) \in \mathcal{N}:\left(\omega^{\prime}, \eta_{i}^{\prime}\right) \in \mathcal{N},\left(\omega, \eta_{i}\right)(0)=0\right\}
$$

In light of assumption (vi), a straightforward integration by parts yields the dissipative estimate

$$
\begin{align*}
\left\langle\mathcal{T}\left(\omega, \eta_{i}\right),\left(\omega, \eta_{i}\right)\right\rangle_{\mathcal{N}} & =-\frac{1}{2} \int_{0}^{\infty} \int_{\Omega} k_{i j}^{\prime \prime} \omega_{, i} \omega_{, j}+2 K_{i j}^{\prime \prime} \eta_{i} \omega_{, j}+\Lambda_{i j}^{\prime \prime} \eta_{i} \eta_{j}+P_{i j r s}^{\prime \prime} \eta_{i, j} \eta_{r, s} d \boldsymbol{x} d s  \tag{3.1}\\
& \leq 0
\end{align*}
$$

for every $\left(\omega, \eta_{i}\right) \in \mathfrak{D}(\mathcal{T})$. We refer the interested reader to [35] for a thorough discussion on the mathematical properties of $\mathcal{T}$ and of the semigroup of right translation on memory spaces.

## 4. Basic Equations in linear Heat Conduction with Memory

In the same spirit of [9], we introduce the variables (omitting the dependence on $\boldsymbol{x}$ )

$$
\begin{aligned}
\omega^{t}(s) & =\alpha(t)-\alpha(t-s) \\
\eta_{i}^{t}(s) & =R_{i}(t)-R_{i}(t-s),
\end{aligned}
$$

modeling the histories of the thermal and microtermal displacements. Then, we can rewrite equations (2.5)-(2.8) as

$$
\begin{gather*}
\rho \ddot{u}_{i}=\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \theta\right)_{, j},  \tag{4.1}\\
J \ddot{\phi}=\left(A_{i j} \phi_{, j}-N_{i j} T_{j}\right)_{, i}-D_{i j} u_{i, j}-\xi \phi+F \theta,  \tag{4.2}\\
a \ddot{\alpha}=-a_{i j} \dot{u}_{i, j}-F \dot{\phi}+\left(k_{i j}(\infty) \alpha_{, j}+K_{j i}(\infty) R_{j}\right)_{, i} \\
-\int_{0}^{\infty}\left(k_{i j}^{\prime}(s) \omega_{, j}(s)+K_{j i}^{\prime}(s) \eta_{j}(s)\right)_{, i} d s, \tag{4.3}
\end{gather*}
$$

$$
\begin{gather*}
B_{i j} \ddot{R}_{j}=-N_{j i} \dot{\phi}_{, j}+\left(P_{i j r s}(\infty) R_{r, s}\right)_{, j}-\int_{0}^{\infty}\left(P_{i j r s}^{\prime}(s) \eta_{r, s}(s)\right)_{, j} d s \\
-K_{i j}(\infty) \alpha_{, j}-\Lambda_{i j}(\infty) R_{j}+\int_{0}^{\infty}\left(K_{i j}^{\prime}(s) \omega_{, j}(s)+\Lambda_{i j}^{\prime}(s) \eta_{j}(s)\right) d s  \tag{4.4}\\
\left(\dot{\omega}, \dot{\eta}_{i}\right)=\mathcal{T}\left(\omega, \eta_{i}\right)+\left(\theta, T_{i}\right) \tag{4.5}
\end{gather*}
$$

Introducing the state vector

$$
\boldsymbol{u}(t)=\left(u_{i}(t), \dot{u}_{i}(t), \phi(t), \dot{\phi}(t), \alpha(t), \dot{\alpha}(t), R_{i}(t), \dot{R}_{i}(t), \omega, \eta_{i}\right),
$$

we view system (4.1)-(4.4) as the ODE on $\mathcal{H}$

$$
\frac{d}{d t} \boldsymbol{u}(t)=\mathbb{A} \boldsymbol{u}(t)
$$

Here $\mathbb{A}$ is the linear operator defined as

$$
\mathbb{A}\left(\begin{array}{c}
u_{i}  \tag{4.6}\\
v_{i} \\
\phi \\
\psi \\
\alpha \\
\theta \\
R_{i} \\
T_{i} \\
\omega \\
\eta_{i}
\end{array}\right)=\left(\begin{array}{c}
v_{i} \\
\frac{1}{\rho}\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \theta\right)_{, j} \\
\psi \\
\frac{1}{J}\left[\left(A_{i j} \phi_{, j}-N_{i j} T_{j}\right)_{, i}-D_{i j} u_{i, j}-\xi \phi+F \theta\right] \\
\theta \\
a^{-1} \mathrm{M} \\
T_{i} \\
C_{i j} \mathrm{~N}_{j} \\
\mathcal{T} \omega+\theta \\
\mathcal{T} \eta_{i}+T_{i}
\end{array}\right),
$$

where $C_{i j}$ is the inverse matrix of $B_{i j}$ (which certainly exists in view of assumption (i)) and

$$
\begin{align*}
\mathrm{M}=- & a_{i j} v_{i, j}-F \psi+\left(k_{i j}(\infty) \alpha_{, j}+K_{j i}(\infty) R_{j}\right)_{, i} \\
& -\int_{0}^{\infty}\left(k_{i j}^{\prime}(s) \omega_{, j}(s)+K_{j i}^{\prime}(s) \eta_{j}(s)\right)_{, i} d s, \tag{4.7}
\end{align*}
$$

while

$$
\begin{align*}
\mathrm{N}_{i}=- & N_{j i} \psi_{, j}+\left(P_{i j r s}(\infty) R_{r, s}\right)_{, j}-K_{i j}(\infty) \alpha_{, j}-\Lambda_{i j}(\infty) R_{j} \\
& -\int_{0}^{\infty}\left(P_{i j r s}^{\prime}(s) \eta_{r, s}(s)\right)_{, j} d s+\int_{0}^{\infty}\left(K_{i j}^{\prime}(s) \omega_{, j}(s)+\Lambda_{i j}^{\prime}(s) \eta_{j}(s)\right) d s \tag{4.8}
\end{align*}
$$

The operator $\mathbb{A}$ has dense domain $\mathfrak{D}(A)$ defined by

$$
\mathfrak{D}(\mathbb{A})=\left\{\boldsymbol{u} \in \mathcal{H} \left\lvert\, \begin{array}{c}
v_{i}, \psi, \theta, T_{i} \in V \\
\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \theta\right)_{, j} \in H \\
\left(A_{i j} \phi_{, j}-N_{i j} T_{j}\right)_{, i} \in H \\
\mathrm{M}, \mathrm{~N}_{i} \in H \\
(\omega, \eta) \in \mathfrak{D}(\mathcal{T})
\end{array}\right.\right\}
$$

## 5. Existence and Uniqueness

This section is devoted to the proof of the generation of a solution semigroup for system (4.1)-(4.5). Let us state the main result.

Theorem 5.1. The operator $\mathbb{A}$ is the infinitesimal generator of a strongly continuous linear semigroup $S(t)$ on the phase space $\mathcal{H}$. Besides, $S(t)$ is contractive with respect to the norm of $\mathcal{H}$.

The proof of Theorem 5.1 is obtained exploiting the well known Lumer-Phillips Theorem. In turn, this amounts in proving the following two lemmas. Before delving into details, we remark that since we are dealing with real Banach spaces, in what follows $\mathbb{A}$ will actually denote the complexification of the infinitesimal generator $\mathbb{A}$, that is, the operator acting on the complex Hilbert space $\mathcal{H}+i \mathcal{H}$ by the rule

$$
\boldsymbol{u}+i \boldsymbol{v} \mapsto \mathbb{A} \boldsymbol{u}+i \mathbb{A} \boldsymbol{v}
$$

Lemma 5.2. The operator $\mathbb{A}$ is dissipative, that is,

$$
\mathfrak{R e}\langle\mathbb{A} \boldsymbol{u}, \boldsymbol{u}\rangle_{\mathcal{H}} \leq 0, \quad \forall \boldsymbol{u} \in \mathfrak{D}(\mathbb{A})
$$

Proof. By means of the divergence theorem and exploiting the boundary conditions, a direct computation reveals that

$$
\begin{aligned}
\langle\mathbb{A} \mathcal{U}, \mathcal{U}\rangle_{\mathcal{H}} & =-\int_{0}^{\infty} \int_{B}\left[\left(k_{i j}^{\prime} \mathcal{T} \omega_{, i} \omega_{, j}+K_{i j}^{\prime}\left(\mathcal{T} \eta_{i} \omega_{, j}+\mathcal{T} \omega_{, j} \eta_{i}\right)+\Lambda_{i j}^{\prime} \mathcal{T} \eta_{i} \eta_{j}+P_{i j r s}^{\prime}\left(\mathcal{T} \eta_{i, j} \eta_{r, s}\right)\right] d s d v\right. \\
& =\left\langle\mathcal{T}\left(\omega, \eta_{i}\right),\left(\omega, \eta_{i}\right)\right\rangle_{\mathcal{M}} \\
& \leq 0
\end{aligned}
$$

where the inequality follows from (3.1). Therefore, the operator $\mathbb{A}$ is dissipative.
Lemma 5.3. The operator $\mathbb{I}-\mathbb{A}$ is onto from $\mathfrak{D}(\mathbb{A})$ into $\mathcal{H}$.
Proof. For every vector

$$
\boldsymbol{f}=\left(f_{i}^{(0)}, f_{i}^{(1)}, f^{(2)}, f^{(3)}, f^{(4)}, f^{(5)}, f_{i}^{(6)}, f_{i}^{(7)}, f^{(8)}, f_{i}^{(9)}\right) \in \mathcal{H}
$$

we look for a unique solution $\boldsymbol{u} \in \mathfrak{D}(\mathbb{A})$ to the resolvent equation

$$
(\mathbb{I}-\mathbb{A}) \boldsymbol{u}=\boldsymbol{f}
$$

Equivalently, we try to solve in $\mathfrak{D}(\mathbb{A})$ the following system

$$
\begin{align*}
& u_{i}-v_{i}=f_{i}^{(0)}  \tag{5.1}\\
& \rho v_{i}-\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \theta\right)_{, j}=\rho f_{i}^{(1)}  \tag{5.2}\\
& \quad \phi-\psi=f^{(2)}  \tag{5.3}\\
& J \psi-\left(A_{i j} \phi_{, j}-N_{i j} T_{i}\right)_{, j}+D_{i j} u_{i, j}+\xi \phi-F \theta=J f^{(3)}  \tag{5.4}\\
& \alpha-\theta=f^{(4)}  \tag{5.5}\\
& a \theta-\mathrm{M}=a f^{(5)}  \tag{5.6}\\
& R_{i}-T_{i}=f_{i}^{(6)}  \tag{5.7}\\
& B_{i j} T_{j}-\mathrm{N}_{i}=B_{i j} f_{i}^{(7)}  \tag{5.8}\\
& \omega-\mathcal{T} \omega-\theta=f^{(8)}  \tag{5.9}\\
& \eta_{i}-\mathcal{T} \eta_{i}-T_{i}=f_{i}^{(9)} . \tag{5.10}
\end{align*}
$$

where M and $\mathrm{N}_{i}$ were defined at (4.7) and (4.8). Integrating (5.9) and (5.10) we obtain

$$
\begin{aligned}
& \omega(s)=\int_{0}^{s} \mathrm{e}^{-(s-y)} f^{(8)}(y) d y+\left(1-\mathrm{e}^{-s}\right) \theta=\left(E * f^{(8)}\right)(s)+\left(1-\mathrm{e}^{-s}\right) \theta, \\
& \eta_{i}(s)=\int_{0}^{s} \mathrm{e}^{-(s-y)} f_{i}^{(9)}(y) d y+\left(1-\mathrm{e}^{-s}\right) T_{i}=\left(E * f_{i}^{(9)}\right)(s)+\left(1-\mathrm{e}^{-s}\right) T_{i},
\end{aligned}
$$

where $E(s)=\mathrm{e}^{-s}$ and $*$ denotes the convolution product on $(0, s)$. Making use of the standard properties of the convolution, we have

$$
\|\omega\|_{\mathcal{M}}^{2} \leq 2\left\|E * f^{(8)}\right\|_{\mathcal{M}}^{2}+2 \kappa\|\theta\|_{1}^{2} \leq 2\left\|f^{(8)}\right\|_{\mathcal{M}}^{2}+2 \varkappa\|\theta\|_{1}^{2}
$$

so that $\omega \in \mathcal{M}$. In a similar way, one is able to show that $\boldsymbol{\eta}=\left(\eta_{i}\right) \in \boldsymbol{\mathcal { M }}$. Substituting (5.1), (5.3), (5.5) and (5.7) into the main system, we arrive at

$$
\begin{align*}
& \rho u_{i}-\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \alpha\right)_{, j}=\Psi_{i}^{(1)} \\
& J \phi-\left(A_{i j} \phi_{, j}-N_{i j} R_{i}\right)_{, j}+D_{i j} u_{i j}+\xi \phi-F \alpha=\Psi^{(2)} \\
& a \alpha+a_{i j} u_{i, j}+F \phi-\left(k_{i j}(\infty) \alpha_{, i}+K_{j i}(\infty) R_{i}\right)_{, j}+{\widehat{k^{\prime}}}_{i j} \alpha_{, i j}+{\widehat{K^{\prime}}}_{j i} R_{i, j}=\Psi^{(3)},  \tag{5.11}\\
& B_{i j} R_{j}+N_{i j} \phi_{, j}-\left(P_{i j r s}(\infty) R_{r, s}\right)_{, j}+K_{i j}(\infty) \alpha_{, j}+\Lambda_{i j}(\infty) R_{j} \\
& \quad+{\widehat{P^{\prime}}}_{i j r s} R_{r, s j}-{\widehat{K^{\prime}}}_{i j} \alpha_{, j}-\widehat{\Lambda}_{i j}^{\prime} R_{j}=\Psi_{i}^{(4)}
\end{align*}
$$

Here

$$
\widehat{k}_{i j}^{\prime}=\int_{0}^{\infty} k_{i j}^{\prime}(s)\left(1-\mathrm{e}^{-s}\right) d s
$$

and in the same way we define ${\widehat{K^{\prime}}}_{i j},{\widehat{P^{\prime}}}_{i j r s}$ and $\widehat{\Lambda}_{i j}^{\prime}$. Moreover

$$
\begin{aligned}
& \Psi_{i}^{(1)}=\rho f_{i}^{(0)}+\rho f_{i}^{(1)}+a_{i j} f_{, j}^{(5)}, \\
& \Psi^{(2)}=J f^{(2)}+J f^{(3)}+N_{i j} f_{i, j}^{(6)}-F f^{(4)}, \\
& \Psi^{(3)}=a f^{(4)}+a f^{(5)}+a_{i j} f_{i, j}^{(0)}+F f^{(2)}+\widehat{k}_{i j} f_{, i j}^{(4)} \\
& -\int_{0}^{\infty} k_{i j}^{\prime}(s)\left(E * f^{(8)}\right)_{, i j}(s) d s-\int_{0}^{\infty} K_{j i}^{\prime}(s)\left(E * f_{i}^{(9)}\right)_{, j}(s) d s, \\
& \Psi_{i}^{(4)}=B_{i j}\left(f_{j}^{(6)}+f_{j}^{(7)}\right)+N_{i j} f_{, j}^{(3)}+{\widehat{K^{\prime}}}^{\prime}{ }_{i j} f_{j}^{(4)} \\
& -\int_{0}^{\infty} K_{i j}^{\prime}(s)\left(E * f^{(8)}\right)_{, j}(s) d s-\int_{0}^{\infty} P_{i j r s}^{\prime}(s)\left(E * f_{r}^{(9)}\right)_{, s j}(s) d s-\int_{0}^{\infty} \Lambda_{i j}^{\prime}(s)\left(E * f_{j}^{(9)}\right)(s) d s .
\end{aligned}
$$

In order to prove the existence of $\boldsymbol{u} \in \mathfrak{D}(\mathbb{A})$ satisfying the resolvent equation, we make use of the Lax-Milgram theorem. To this end, we define the following bilinear form

$$
\begin{aligned}
\mathbf{a}\left(\left(u_{i}, \phi, \alpha, R_{i}\right),\left(\tilde{u}_{i}, \tilde{\phi}, \tilde{\alpha}, \tilde{R}_{i}\right)\right)= & \rho u_{i} \tilde{u}_{i}+\left(A_{i j r s} u_{r, s}+D_{i j} \phi-a_{i j} \alpha\right) \tilde{u}_{i, j} \\
& +J \phi \tilde{\phi}+\left(A_{i j} \phi_{, j}-N_{i j} R_{i}\right) \tilde{\phi}_{, j}+D_{i j} u_{i j} \tilde{\phi}+\xi \phi \tilde{\phi}-F \alpha \tilde{\phi} \\
& +a \alpha \tilde{\alpha}-a_{i j} u_{i} \tilde{\alpha}_{, j}+F \phi \tilde{\alpha}+\left(k_{i j}(\infty) \alpha_{, i} \tilde{\alpha}+K_{j i}(\infty) R_{i}\right) \tilde{\alpha}_{, j} \\
& -{\widehat{k^{\prime}}}_{i j} \alpha_{, i} \tilde{\alpha}_{, j}-{\widehat{K^{\prime}}}_{j i} R_{i} \tilde{\alpha}_{, j}+B_{i j} R_{j} \tilde{R}_{i}+N_{i j} \phi_{, j} \tilde{R}_{i} \\
& +\left(P_{i j r s}(\infty) R_{r, s}\right) \tilde{R_{i, j}}+K_{i j}(\infty) \alpha_{, j} \tilde{R}_{i}+\Lambda_{i j}(\infty) R_{j} \tilde{R}_{i} \\
& -{\widehat{P^{\prime}}}_{i j r s} R_{r, s} \tilde{R_{i, j}}-{\widehat{K^{\prime}}}_{i j} \alpha_{, j} \tilde{R}_{i}-\widehat{\Lambda}_{i j}^{\prime} R_{j} \tilde{R}_{i} .
\end{aligned}
$$

In particular, a : $V^{8} \times V^{8} \rightarrow \mathbb{R}$. We need to show that $\mathbf{a}$ is continuous and coercive. Moreover, we need to prove that $\Psi^{i} \in V^{-1}$ for every $i=1, \ldots, 4$, where $V^{-1}$ is the dual space of $V$. Continuity is a straightforward consequence of the Cauchy-Schwarz and Young inequalities. For what concerns coercivity, by direct computations and making use of assumption (v), we have

$$
\mathbf{a}\left(\left(u_{i}, \phi, \alpha, R_{i}\right),\left(u_{i}, \phi, \alpha, R_{i}\right)\right) \geq \rho\left\|\left(u_{i}, \phi, \alpha, R_{i}\right)\right\|_{V^{4}}^{2}
$$

Finally, with the help of Lemma 2.2 we have

$$
\begin{aligned}
\left\|-\int_{0}^{\infty} k_{i j}^{\prime}(s)\left(E * f^{(8)}\right)(s) d s\right\|_{1} & \leq \int_{0}^{\infty}-k_{i j}^{\prime}(s)\left(E *\left\|f^{(8)}\right\|_{1}\right)(s) d s \\
& \leq \kappa \int_{0}^{\infty} \ell(s)\left(E *\left\|f^{(8)}\right\|_{1}\right)(s) d s \\
& \leq \kappa \int_{0}^{\infty} \sqrt{\ell(s)}\left(E * \sqrt{\ell}\left\|f^{(8)}\right\|_{1}\right)(s) d s \\
& \leq \kappa \sqrt{\varkappa}\|E * \sqrt{\ell}\| f^{(8)}\left\|_{1}\right\|_{L^{2}\left(\mathbb{R}^{+}\right)} \\
& \leq \kappa \sqrt{\varkappa}\|\sqrt{\ell}\| f^{(8)}\left\|_{1}\right\|_{L^{2}\left(\mathbb{R}^{+}\right)} \\
& =\kappa \sqrt{\varkappa}\left\|f^{(8)}\right\|_{\mathcal{M}}
\end{aligned}
$$

Similarly, we can show that

$$
-\int_{0}^{\infty} K_{j i}^{\prime}(s) F_{i}(s) d s \in H^{1}
$$

Therefore, $\Psi_{3} \in V^{-1}$. By the same token, we have $\Psi_{4} \in V^{-1}$. An application of LaxMilgram theorem yields $u_{i}, \phi, \alpha, R_{i} \in V$ satisfying (5.11). Thanks to (5.1), (5.3), (5.5) and (5.7) we immediately find also $v_{i}, \psi, \theta$ and $T_{i}$. The last step to conclude the proof consists in showing that the solution we have found belongs to $\mathfrak{D}(\mathbb{A})$. The only thing we need to check is that $\left(\omega, \eta_{i}\right) \in \mathfrak{D}(\mathcal{T})$. However, using the fact that $\omega \in \mathcal{M}$ and $\boldsymbol{\eta} \in \mathcal{M}$ we see at once that

$$
\left(\mathcal{T} \omega, \mathcal{T} \eta_{i}\right)=\left(\omega, \eta_{i}\right)-\left(\theta, T_{i}\right)-\left(f^{(8)}, f_{i}^{(9)}\right) \in \mathcal{N}
$$

Besides, it is straightforward to check that $\omega(s), \eta_{i}(s) \rightarrow 0$ in $V$ as $s \rightarrow 0$. Hence $\left(\omega, \eta_{i}\right) \in$ $\mathfrak{D}(\mathcal{T})$ and the proof is finished.

## 6. Exponential Stability: the One-Dimensional System

In this section we focus on the exponential stability of (4.1)-(4.5) in one space dimension. In particular, the system becomes

$$
\begin{gather*}
\rho u_{t t}=A u_{x x}+D \phi_{x}-a^{*} \alpha_{t x},  \tag{6.1}\\
J \phi_{t t}=A^{*} \phi_{x x}-N R_{t x}-D u_{x}-\xi \phi+F \alpha_{t},  \tag{6.2}\\
a \alpha_{t t}=k_{\infty} \alpha_{x x}-a^{*} u_{t x}-F \phi_{t}+K_{\infty} R_{x}-\int_{0}^{\infty}\left(k^{\prime}(s) \omega_{x x}(s)+K^{\prime}(s) \eta_{x}(s)\right) d s  \tag{6.3}\\
B R_{t t}=P_{\infty} R_{x x}-N \phi_{t x}-K_{\infty} \alpha_{x}-\Lambda_{\infty} R \\
+\int_{0}^{\infty}\left(K^{\prime}(s) \omega_{x}(s)+\Lambda^{\prime}(s) \eta(s)-P^{\prime}(s) \eta_{x x}(s)\right) d s  \tag{6.4}\\
\left(\omega_{t}, \eta_{t}\right)=\mathcal{T}(\omega, \eta)+\left(\alpha_{t}, R_{t}\right) . \tag{6.5}
\end{gather*}
$$

To obtain the exponential stability, we need an additional hypothesis. Namely, we assume there exists $\delta>0$, such that

$$
\begin{align*}
& \left(k^{\prime \prime}(s)+\delta k^{\prime}(s)\right) \xi^{2}+2\left(K^{\prime \prime}(s)+\delta K^{\prime}(s)\right) \zeta \xi \\
& +\left(\Lambda^{\prime \prime}(s)+\delta \Lambda^{\prime}(s)\right) \zeta^{2}+\left(P^{\prime \prime}(s)+\delta P^{\prime}(s)\right) \eta^{2} \geq 0 \tag{6.6}
\end{align*}
$$

for every $s \geq 0$ and $\xi, \zeta, \eta \in \mathbb{R}$.
Remark 6.1. Assumption (6.6) plays the same role of the well known Dafermos inequality, which is usually stated for a generic memory kernel $\mu(s)$ as

$$
\begin{equation*}
\mu^{\prime}(s)+\delta \mu(s) \leq 0, \quad \forall s \geq 0 \tag{6.7}
\end{equation*}
$$

For many equations with memory (6.7) is sufficient to obtain the exponential stability. In our case, upon choosing $\xi, \zeta$ and $\eta$ in a suitable way, it is not difficult to show that the kernels $-k^{\prime}(s),-\Lambda^{\prime}(s)$ and $-P^{\prime}(s)$ satisfy (6.7).

The following theorem holds
Theorem 6.2. Under assumption (6.6), the semigroup $S(t)$ is exponentially stable.
The proof of Theorem 6.2 relies on the following abstract result, which is a simplified version of the famous characterization of Gearhart, Greiner, Huang and Prüss. We refer the interested reader to [16] for the proof.

Proposition 6.3. Let $\mathbb{A}$ be the infinitesimal generator of a linear contraction semigroup $S(t)=\mathrm{e}^{\mathbb{A} t}$ on a Banach space $\mathcal{X}$. Then, $S(t)$ is exponentially stable if and only if there exists $\sigma>0$ such that

$$
\inf _{\lambda \in \mathbb{R}}\|(i \lambda-\mathbb{A}) x\|_{\mathcal{X}} \geq \sigma\|x\|_{\mathcal{X}}, \quad \forall x \in \mathfrak{D}(\mathbb{A})
$$

We are now in position to prove the main result of this section. We proceed by contradiction and assume that $S(t)$ does not decay exponentially. On account of Proposition 6.3 , this means that there exist sequences $\lambda_{n} \in \mathbb{R}$ and

$$
\boldsymbol{u}_{n}=\left(u_{n}, v_{n}, \phi_{n}, \psi_{n}, \alpha_{n}, \theta_{n}, R_{n}, T_{n}, \omega_{n}, \eta_{n}\right) \in \mathfrak{D}(\mathbb{A})
$$

such that

$$
\begin{equation*}
\left\|\boldsymbol{u}_{\boldsymbol{n}}\right\|_{\mathcal{H}}^{2}=1 \tag{6.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|i \lambda_{n} \boldsymbol{u}_{n}-\mathbb{A} \boldsymbol{u}_{n}\right\|_{\mathcal{H}} \rightarrow 0 \tag{6.9}
\end{equation*}
$$

Without loss of generality, we set all coefficients to be equal to 1 . In components, (6.9) reads

$$
\begin{align*}
& i \lambda_{n} u_{n}-v_{n} \rightarrow 0 \quad \text { in } V,  \tag{6.10}\\
& i \lambda_{n} v_{n}-\partial_{x x} u_{n}-\partial_{x} \phi_{n}+\partial_{x} \theta_{n} \rightarrow 0 \quad \text { in } H,  \tag{6.11}\\
& i \lambda_{n} \phi_{n}-\psi_{n} \rightarrow 0 \quad \text { in } V,  \tag{6.12}\\
& i \lambda_{n} \psi_{n}-\partial_{x x} \phi_{n}+\partial_{x} T_{n}+\partial_{x} u_{n}+\phi_{n}-\theta_{n} \rightarrow 0 \quad \text { in } H,  \tag{6.13}\\
& i \lambda_{n} \alpha_{n}-\theta_{n} \rightarrow 0 \quad \text { in } V,  \tag{6.14}\\
& i \lambda_{n} \theta_{n}-\mathrm{M}_{n} \rightarrow 0 \quad \text { in } H,  \tag{6.15}\\
& i \lambda_{n} R_{n}-T_{n} \rightarrow 0 \quad \text { in } V  \tag{6.16}\\
& i \lambda_{n} T_{n}-\mathrm{N}_{n} \rightarrow 0 \quad \text { in } H,  \tag{6.17}\\
& i \lambda_{n} \omega_{n}-\mathcal{T} \omega_{n}-\theta_{n} \rightarrow 0 \quad \text { in } \mathcal{M},  \tag{6.18}\\
& i \lambda_{n} \eta_{n}-\mathcal{T} \eta_{n}-T_{n} \rightarrow 0 \quad \text { in } \mathcal{M}, \tag{6.19}
\end{align*}
$$

where we recall that

$$
\mathrm{M}_{n}=-\partial_{x} v_{n}-\psi_{n}+\partial_{x x} \alpha_{n}+\partial_{x} R_{n}-\int_{0}^{\infty}\left(k^{\prime}(s) \partial_{x x} \omega_{n}(s)+H^{\prime}(s) \partial_{x} \eta_{n}(s)\right) d s
$$

and
$\mathrm{N}_{n}=-\partial_{x} \psi_{n}+\partial_{x x} R_{n}-\partial_{x} \alpha_{n}-R_{n}-\int_{0}^{\infty}\left(P^{\prime}(s) \partial_{x x} \eta_{n}(s)-H^{\prime}(s) \partial_{x} \omega_{n}(s)-\Lambda^{\prime}(s) \eta_{n}(s)\right) d s$.
The contradiction will be obtained by showing that $\left\|\boldsymbol{u}_{n}\right\|^{2} \rightarrow 0$. First of all, we observe that, by the dissipativity of $\mathbb{A}$

$$
\left\langle\mathbb{A} \boldsymbol{u}_{n}, \boldsymbol{u}_{n}\right\rangle_{\mathcal{H}}=\left\langle\mathcal{T}\left(\omega_{n}, \eta_{n}\right),\left(\omega_{n}, \eta_{n}\right)\right\rangle_{\mathcal{N}} \leq-\delta\left\|\left(\omega_{n}, \eta_{n}\right)\right\|_{\mathcal{N}}^{2}
$$

where the inequality follows from assumption (6.6). Then, since

$$
\mathfrak{R e}\left\langle i \lambda_{n} \boldsymbol{u}_{n}-\mathbb{A} \boldsymbol{u}_{n}, \boldsymbol{u}_{n}\right\rangle_{\mathcal{H}}=-\mathfrak{R e}\left\langle\mathbb{A} \boldsymbol{u}_{n}, \boldsymbol{u}_{n}\right\rangle_{\mathcal{H}} \rightarrow 0
$$

we have

$$
\delta\left\|\left(\omega_{n}, \eta_{n}\right)\right\|_{\mathcal{N}}^{2} \leq-\mathfrak{R e}\left\langle\mathbb{A} \boldsymbol{u}_{n}, \boldsymbol{u}_{n}\right\rangle_{\mathcal{H}} \rightarrow 0
$$

In the same spirit as [34], we now distinguish two cases.

Case 1: $\boldsymbol{\lambda}_{\boldsymbol{n}} \nrightarrow \mathbf{0}$. Up to a subsequence, we can assume that

$$
\begin{equation*}
\inf _{n}\left|\lambda_{n}\right|>0 \tag{6.20}
\end{equation*}
$$

The proof will be carried out with the help of some technical lemmas.
Lemma 6.4. Up to a subsequence, we have that

$$
\lim _{n \rightarrow \infty}\left\|\theta_{n}\right\|_{H}=0
$$

and

$$
\lim _{n \rightarrow \infty}\left\|T_{n}\right\|_{H}=0
$$

Proof. We will prove the lemma only for $\theta_{n}$. The proof for $T_{n}$ is identical and therefore omitted. We preliminary show that

$$
\sup _{n \in \mathbb{N}}\left|\lambda_{n}\right|\left\|\theta_{n}\right\|_{V^{-1}}<\infty
$$

where $V^{-1}$ is the dual space of $V$. Henceforth, we will denote by $\|\cdot\|_{-1}$ the norm in $V^{-1}$, coherently with the notation used for $V$. We can write

$$
i \lambda_{n} \theta_{n}=i \lambda_{n} \theta_{n}+\mathrm{M}_{n}-\mathrm{M}_{n}
$$

Hence,

$$
\left\|i \lambda_{n} \theta_{n}\right\|_{-1} \leq\left\|i \lambda_{n} \theta_{n}+\mathrm{M}_{n}\right\|_{-1}+\left\|\mathrm{M}_{n}\right\|_{-1} .
$$

The first term of the sum is clearly bounded, being infinitesimal. On the other hand, $\left\|\mathbf{M}_{n}\right\|_{-1} \leq\left\|v_{n}\right\|+\left\|\psi_{n}\right\|_{-1}+\left\|\alpha_{n}\right\|_{1}+\left\|R_{n}\right\|+\left\|\int_{0}^{\infty}-k^{\prime}(s) \partial_{x x} \omega_{n}(s) d s\right\|_{-1}+\left\|\int_{0}^{\infty}-H^{\prime}(s) \partial_{x} \eta_{n}(s) d s\right\|_{-1}$.
We can bound the last two terms on the right hand side in the following way

$$
\begin{aligned}
\left\|\int_{0}^{\infty}-k^{\prime}(s) \partial_{x x} \omega_{n}(s) d s\right\|_{-1} & \leq \int_{0}^{\infty}-k^{\prime}(s)\left\|\omega_{n}(s)\right\|_{1} d s \\
& \leq \kappa \int_{0}^{\infty} \ell(s)\left\|\omega_{n}(s)\right\|_{1} d s \\
& =\kappa \int_{0}^{\infty} \sqrt{\ell(s)} \sqrt{\ell(s)}\left\|\omega_{n}(s)\right\|_{1} d s \\
& \leq \kappa \sqrt{\varkappa}\left\|\omega_{n}\right\|_{\mathcal{M}} .
\end{aligned}
$$

By the same token, one can show that the other integral term is also bounded. We rephrase (6.18) as

$$
i \lambda_{n} \omega_{n}-\mathcal{T} \omega_{n}-\theta_{n}=\varepsilon_{n}
$$

with $\varepsilon_{n} \rightarrow 0$ in $\mathcal{M}$. Since $\omega_{n} \in \mathfrak{D}(\mathcal{T})$, we can solve the above equation to obtain the explicit representation

$$
\begin{equation*}
\omega_{n}(s)=\frac{1}{i \lambda_{n}}\left(1-\mathrm{e}^{-i \lambda_{n} s}\right) \theta_{n}+\int_{0}^{s} \mathrm{e}^{-i \lambda_{n}(s-y)} \varepsilon_{n}(y) d y . \tag{6.21}
\end{equation*}
$$

Now observe that

$$
\left|i \lambda_{n}\left\langle\omega_{n}, A^{-1} \theta_{n}\right\rangle_{\mathcal{M}}\right| \leq\left|\lambda_{n}\right|\left\|\theta_{n}\right\|_{-1} \int_{0}^{\infty} \ell(s)\left\|\omega_{n}\right\|_{1} d s \rightarrow 0
$$

since $\omega_{n} \rightarrow 0$ in $\mathcal{M}$ and $\left\|\theta_{n}\right\|_{-1}$ was bounded. Hence, we have

$$
\begin{equation*}
\left|i \lambda_{n}\left\langle\omega_{n}, A^{-1} \theta_{n}\right\rangle_{\mathcal{M}}\right|=a_{n}\left\|\theta_{n}\right\|^{2}+b_{n} \rightarrow 0 \tag{6.22}
\end{equation*}
$$

having set

$$
\begin{aligned}
& a_{n}=\int_{0}^{\infty} \ell(s)\left(1-\mathrm{e}^{-i \lambda_{n} s}\right) d s \\
& b_{n}=i \lambda_{n} \int_{0}^{\infty} \ell(s)\left(\int_{0}^{s} \mathrm{e}^{-i \lambda_{n}(s-y)}\left\langle\varepsilon_{n}(y), A^{-1} \theta_{n}\right\rangle_{V} d y\right) d s
\end{aligned}
$$

Following exactly the same reasoning of [34, Lemma 5.5] we see that $b_{n} \rightarrow 0$. For what concerns $a_{n}$, we consider two separate cases. Let $\lambda_{\star}$ be a limit point of the sequence $\lambda_{n}$. From (6.20) we have

$$
\lambda_{\star} \in[-\infty, \infty] \backslash\{0\}
$$

If $\lambda_{\star} \in\{-\infty, \infty\}$, then by the Riemann-Lebesgue lemma we have the convergence (up to a subsequence)

$$
a_{n} \rightarrow \int_{0}^{\infty} \ell(s) d s>0
$$

On the other hand, if $\lambda_{\star} \in \mathbb{R} \backslash\{0\}$,

$$
a_{n} \rightarrow \int_{0}^{\infty} \ell(s)\left(1-\mathrm{e}^{-i \lambda_{\star} s}\right) d s
$$

and

$$
\mathfrak{R e} \int_{0}^{\infty} \ell(s)\left(1-\mathrm{e}^{-i \lambda_{\star} s}\right) d s=\int_{0}^{\infty} \ell(s)\left(1-\cos \lambda_{\star} s\right) d s>0
$$

In both cases, in order for (6.22) to hold, it must be $\left\|\theta_{n}\right\| \rightarrow 0$.
Lemma 6.5. Up to a subsequence,

$$
\lim _{n \rightarrow \infty}\left\|R_{n}\right\|_{1}=\lim _{n \rightarrow \infty}\left\|\alpha_{n}\right\|_{1} \rightarrow 0
$$

Proof. Define

$$
\rho_{n}(s)=\frac{1}{i \lambda_{n}}\left(1-\mathrm{e}^{-i \lambda_{n} s}\right)\left(\theta_{n}-i \lambda_{n} \alpha_{n}\right) .
$$

In view of (6.14), it is clear that $\rho_{n} \rightarrow 0$ in $\mathcal{M}$. We can then rewrite (6.21) as

$$
\omega_{n}(s)=\left(1-\mathrm{e}^{-i \lambda_{n} s}\right) \alpha_{n}+\int_{0}^{s} \mathrm{e}^{-i \lambda_{n}(s-y)} \varepsilon_{n}(y) d y+\rho_{n}(s)
$$

which, on account of Step 1, entails

$$
\left\langle\omega_{n}, \alpha_{n}\right\rangle_{\mathcal{M}}=a_{n}\left\|\alpha_{n}\right\|_{1}^{2}+c_{n}+\left\langle\rho_{n}, \alpha_{n}\right\rangle_{\mathcal{M}} \rightarrow 0
$$

with $a_{n}$ as above and

$$
c_{n}=\int_{0}^{\infty} \ell(s)\left(\int_{0}^{s} \mathrm{e}^{i \lambda_{n}(s-y)}\left\langle\varepsilon_{n}(y), \alpha_{n}\right\rangle_{1} d y\right) d s
$$

Clearly,

$$
\left\langle\rho_{n}, \alpha_{n}\right\rangle_{\mathcal{M}} \rightarrow 0
$$

Besides, with the same reasoning of Lemma 6.4, $c_{n} \rightarrow 0$. Hence, we obtain that $\left\|\alpha_{n}\right\|_{1} \rightarrow 0$. This proof can then be repeated to show that $\left\|R_{n}\right\|_{1} \rightarrow 0$.

Conclusion of the proof. At this point we proceed as in [3]. We multiply equation (6.17) by $\lambda_{n}^{-1} \partial_{x} \phi_{n}$. In view of (6.12), and exploiting the convergences obtained above, we get

$$
i\left\|\phi_{n}\right\|_{1}^{2}+\left\langle\partial_{x} R_{n}, \frac{\partial_{x x} \phi_{n}}{\lambda_{n}}\right\rangle \rightarrow 0
$$

Thanks to equation (6.13) we see that $\partial_{x x} \phi_{n} / \lambda_{n}$ is bounded. In turn, this yields that

$$
\left\|\phi_{n}\right\|_{1}^{2} \rightarrow 0 .
$$

In a similar fashion, using equations (6.15) and (6.11) it is possible to show that $\left\|u_{n}\right\|_{1} \rightarrow 0$ too, as $n \rightarrow \infty$. Finally, a straightforward application of equations (6.10) and (6.12) yields the convergence of $v_{n}, \psi_{n} \rightarrow 0$ in $H$.

Case 2: $\boldsymbol{\lambda}_{\boldsymbol{n}} \boldsymbol{\rightarrow} \boldsymbol{0}$. In this case, in light of (6.8), (6.10), (6.14) and (6.16) we have

$$
\begin{aligned}
v_{n} \rightarrow 0 & \text { in } V, \\
\theta_{n} \rightarrow 0 & \text { in } V, \\
T_{n} \rightarrow 0 & \text { in } V .
\end{aligned}
$$

In turn, due to (6.11) and (6.13), this entails

$$
\begin{align*}
-\partial_{x x} u_{n}-\partial_{x} \phi_{n} \rightarrow 0 & \text { in } H  \tag{6.23}\\
-\partial_{x x} \phi_{n}+\partial_{x} u_{n}+\phi_{n} & \rightarrow 0 \tag{6.24}
\end{align*} \quad \text { in } H .
$$

Multiplying (6.23) by $u_{n}$, (6.24) by $\phi_{n}$, and summing up the two, we get

$$
\begin{equation*}
\left\|\partial_{x} u_{n}\right\|^{2}+\left\langle\phi_{n}, \partial_{x} u_{n}\right\rangle+\left\langle\partial_{x} u_{n}, \phi_{n}\right\rangle+\left\|\phi_{n}\right\|^{2}+\left\|\partial_{x} \phi_{n}\right\|^{2} \rightarrow 0 \tag{6.25}
\end{equation*}
$$

Since

$$
\left\|\partial_{x} u_{n}\right\|^{2}+\left\langle\phi_{n}, \partial_{x} u_{n}\right\rangle+\left\langle\partial_{x} u_{n}, \phi_{n}\right\rangle+\left\|\phi_{n}\right\|^{2}=\left\|\partial_{x} u_{n}+\phi_{n}\right\|^{2} \geq 0
$$

by (6.25) we have $\left\|\phi_{n}\right\| \rightarrow 0$ in $V$. In turn, this gives us the convergence of $u_{n} \rightarrow 0$ in $V$. An almost identical reasoning yields the convergence of $R_{n}$ and $\alpha_{n}$ to 0 in the space $V$.

Remark 6.6. If we do not assume all the constants to be equal to 1 , we do not obtain a perfect square in (6.25). However, the thesis follow in the same way thanks to assumption (ii).

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