

System Design Results for an Air Taxi Concept in HorizonUAM

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Air Taxi Vehicle, Systems and Cabin Concepts

Presentation Overview



Fabian Reimer, Thomas-M. Bock, Line Winkler, Frank Meller, Björn Nagel

“Urban Air Mobility – Insights into the Virtual and User Centric Design Process for a Future eVTOL Cabin Concept”



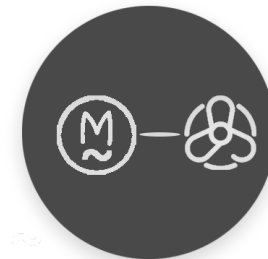
Patrick Ratei, Nabih Naeem, Prajwal Shiva Prakasha

“Fleet-Centric Vehicle Design Space Explorations of Urban Air Mobility by System of Systems Simulations”



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“System Design Results for an Air Taxi Concept in HorizonUAM”



Florian Jäger, Oliver Bertram

“Development of a Safe Powertrain System Architecture for the HorizonUAM Air Taxi Concept”

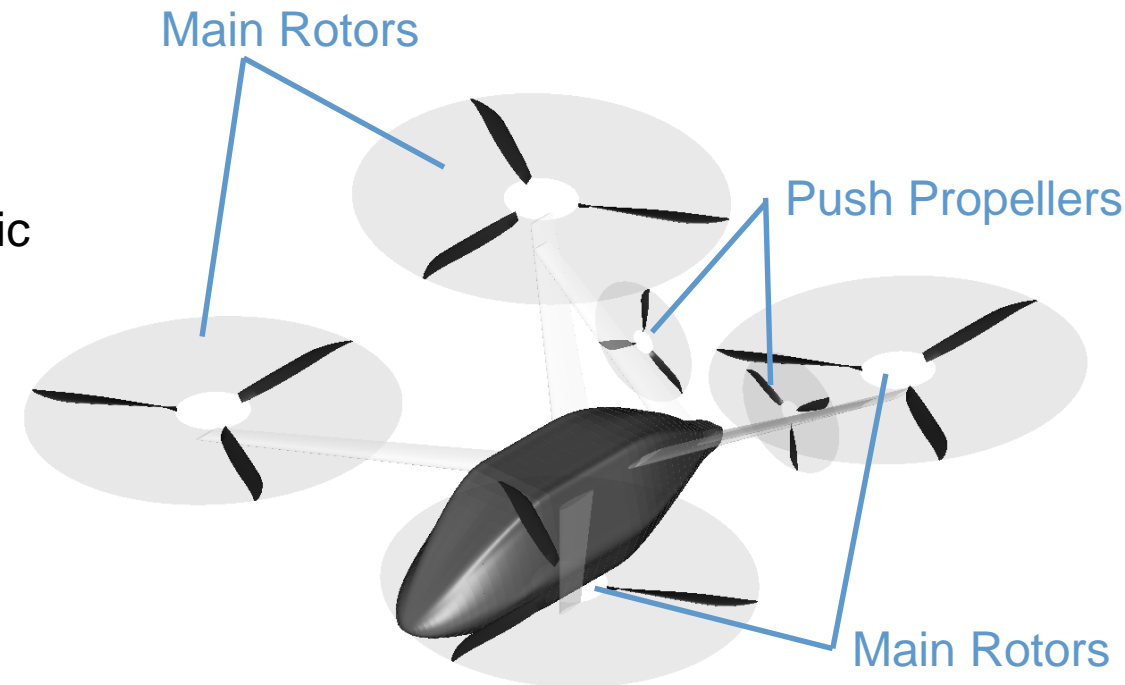
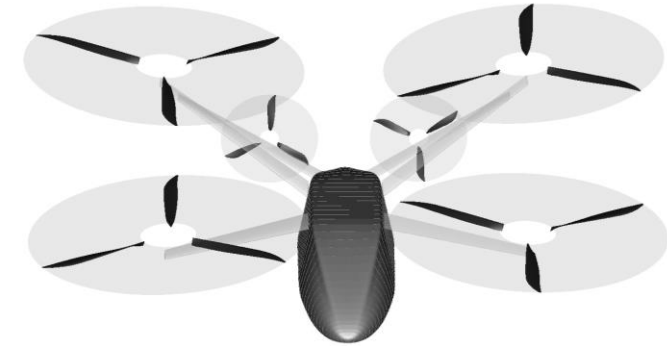


Patrick Sieb

“Maintenance Considerations for Urban Air Mobility Vehicles”

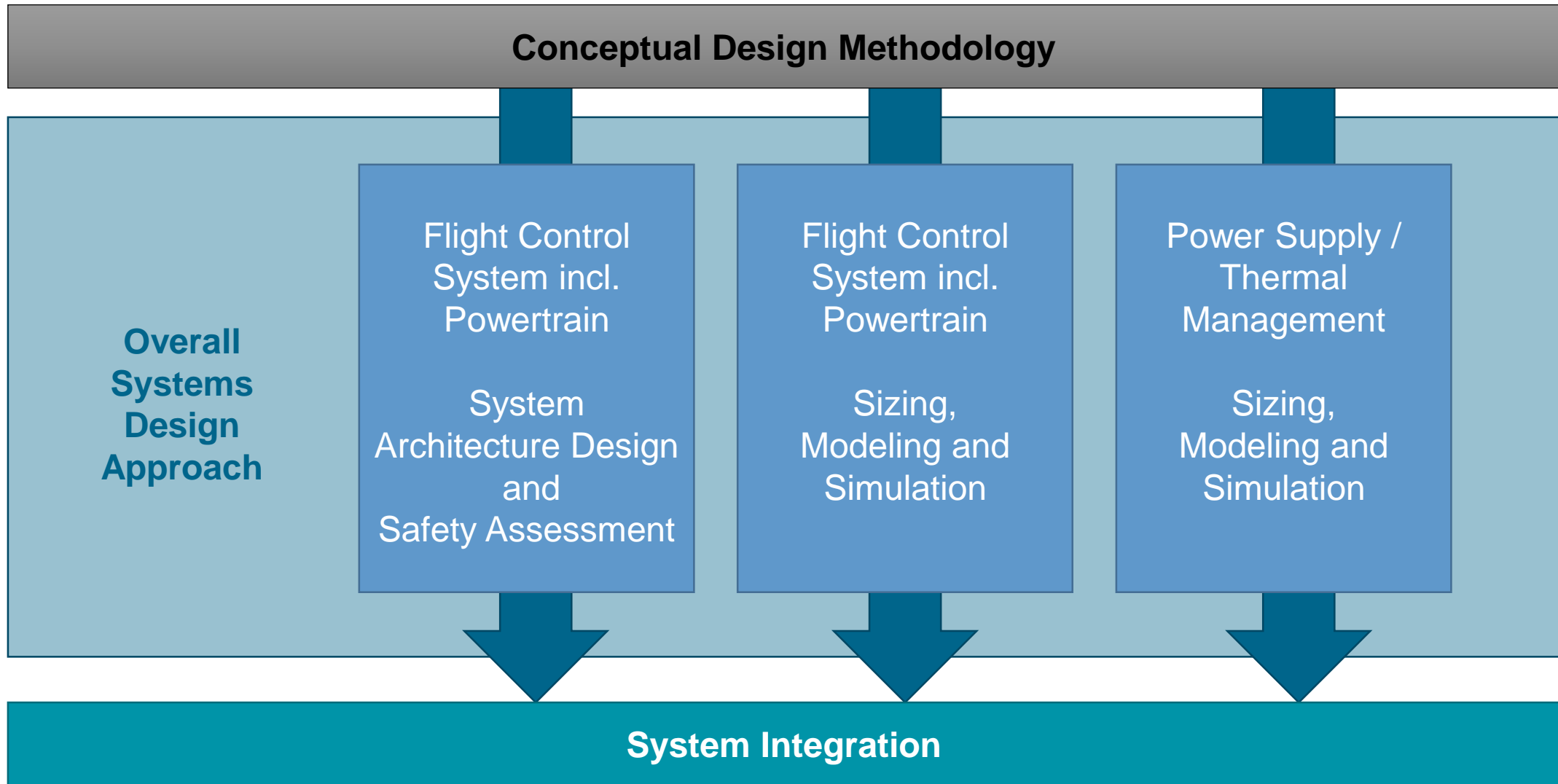


- Within the HorizonUAM project, a concept for an air taxi is being worked on
- The Institute of Flight Systems contributes with research activities in the field of the onboard systems
 - Onboard systems: Vehicle systems and avionics, their interfaces to airframe, cabin, environment, vertiport, pilot, passengers,.....
 - During the project a special focus was on the full-electric flight control system (FCS) incl. the powertrain and power supply incl. the thermal management
 - A multicopter with 4 main rotors and 2 push propellers was considered as starting configuration for the investigations
- **Goal: Overview of current status in the system design and its results**

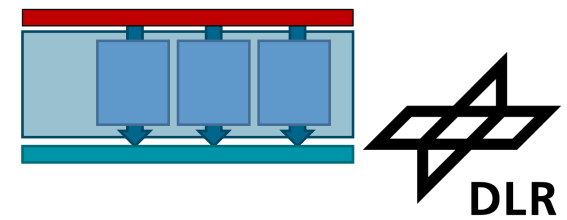


Initially developed as Medical Personnel Deployment Vehicle (Project Urban Rescue) and adapted as an air taxi vehicle for HorizonUAM.

Onboard Systems - Design Streams



Conceptual Design Methodology

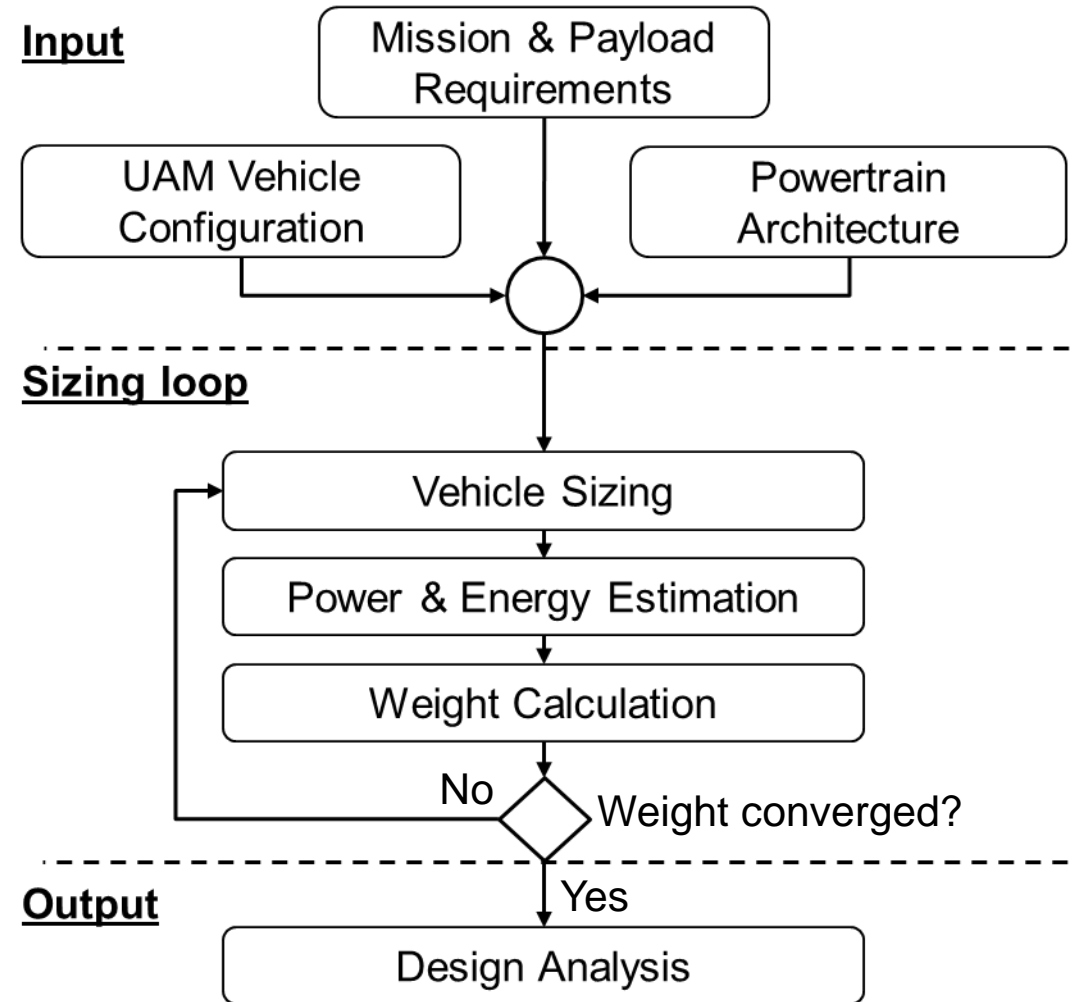


Conceptual Multirotor Design*

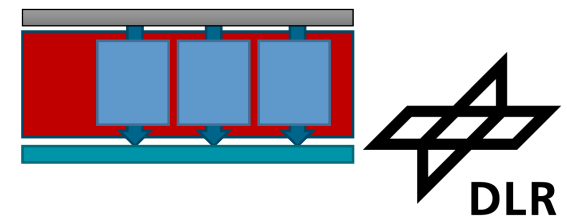
- Enables the examination of full-electric, turbo-electric and hybrid-electric powertrain systems
- Based on simple models and assumptions → Uncertainties; results should be used with a certain amount of caution
- Quantitative results and qualitative differences in the results of the various powertrain architectures are credible

Key results

- Battery and fuel cell systems are important design drivers (Maximum take-off mass, overall efficiency,...)
- 3 most promising architectures were selected:
 - Full-electric with battery,
 - Full-electric with fuel cell system and
 - Hybrid-electric with battery and fuel cell system
- Provide estimated flight performance for system sizing

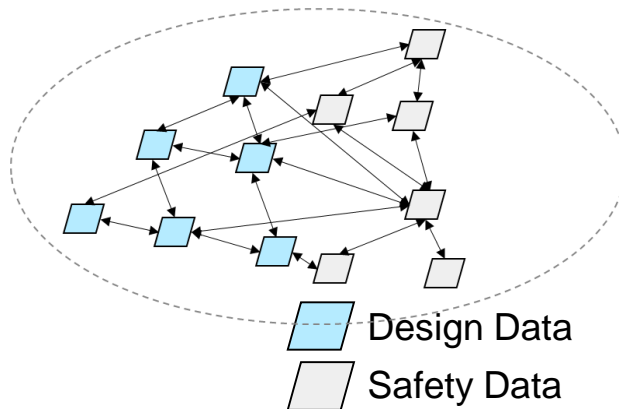


Overall Systems Design Approach



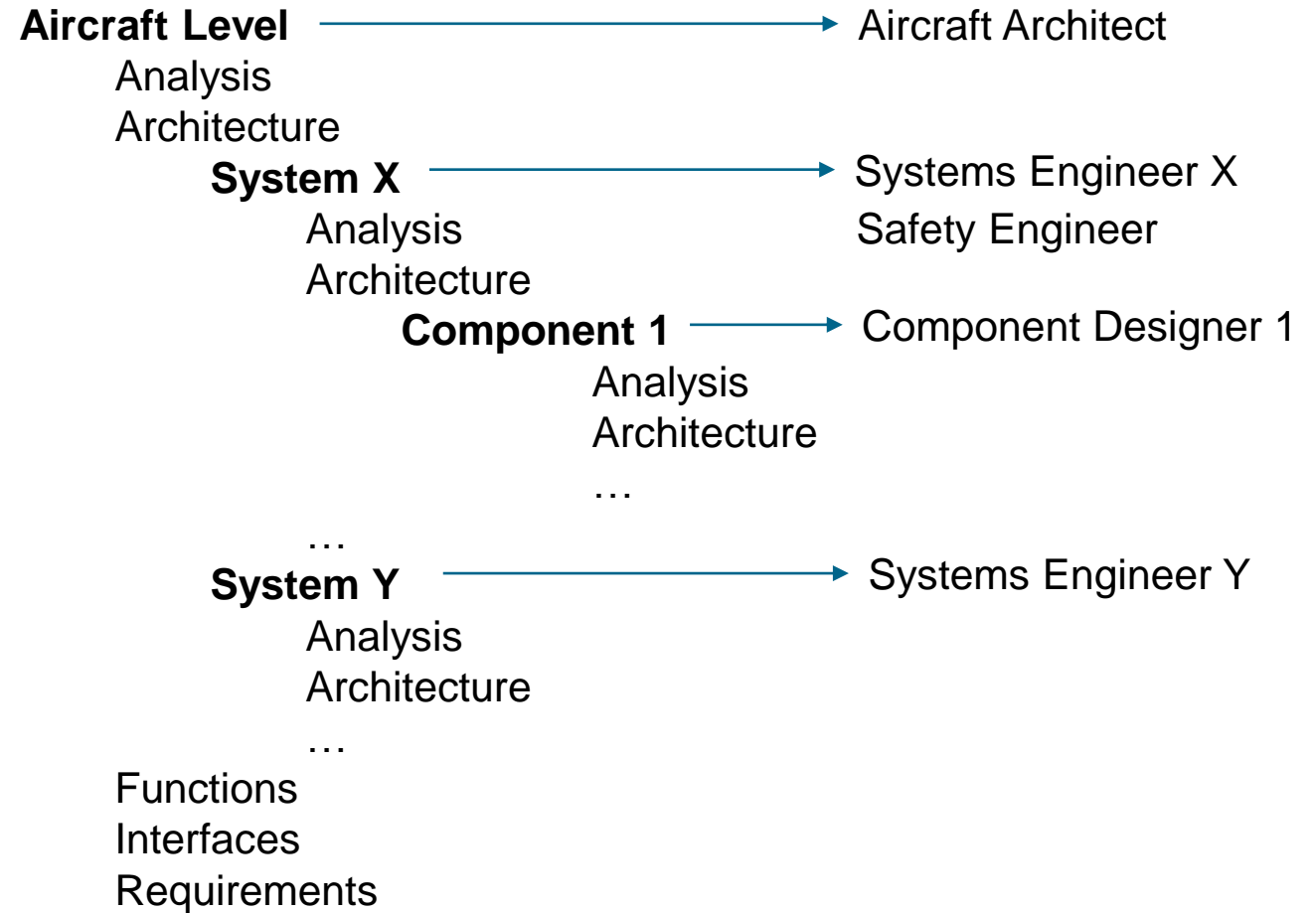
Model-Based Systems Engineering (MBSE) Approach

- Centralized system model with recursive model structure enables model segregation and distributed, collaborative design
- System architecture design and safety assessment acc. to design standards (e.g. ARP4754A) incl. traceability of requirements
- Integration of analysis models and impact analysis of design decisions

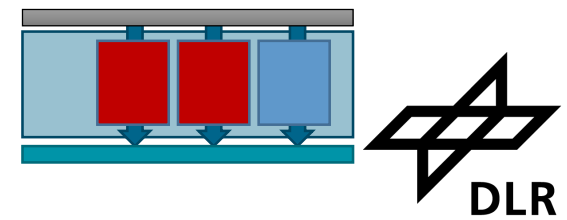


Recursive Model Structure

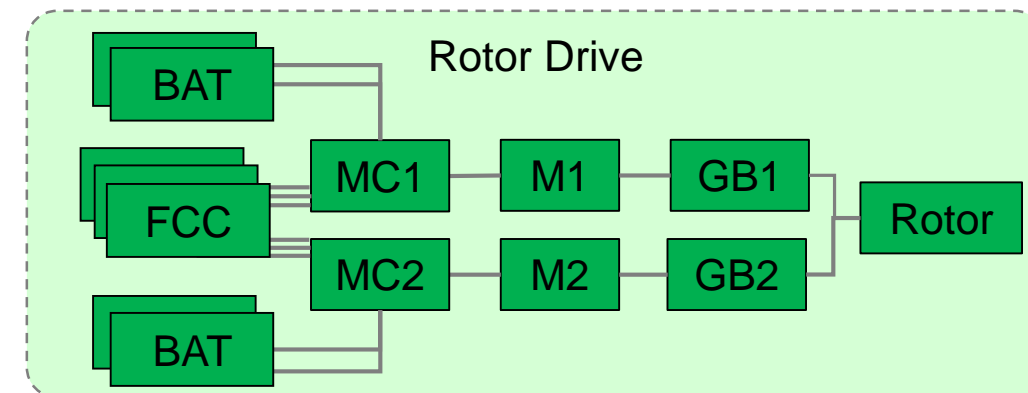
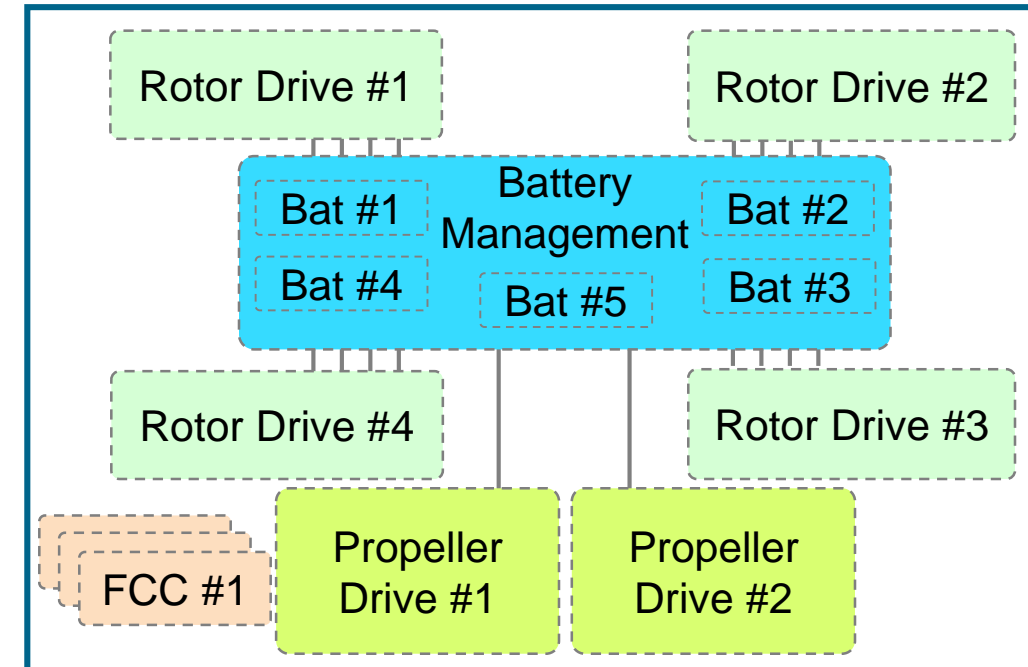
Design Role



FCS / Powertrain: System Architecture Design and Safety Assessment



- SC-VTOL* / Category Enhanced: “The aircraft is capable of continued safe flight and landing...”
 - Safe and redundant design of each main rotor and
 - the ability to compensate for the loss of one main rotor with the remaining main rotors and the two push propellers
- **Key results 1:** Safety assessment methods (acc to. ARP4761) were applied to architect the powertrain / flight control system
 - Safety goals are basically achievable and safety mechanisms were identified
 - Different design requirements are derived, e.g. two redundant electric motors per rotor, five battery packs, at least three FCCs,...
- **Key results 2:** Sizing, modeling and simulation
 - Direct rotor drive (w/o gearbox) is possible, but poor efficiency and high heat losses, higher weight
 - Rotor drive with gearbox is more complex and expensive, but increases the powertrain efficiency
 - Propeller drive not yet sized

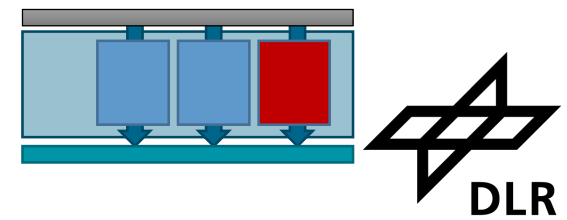


VTOL: Vertical Takeoff and Landing
 SC-VTOL: EASA Special Condition VTOL

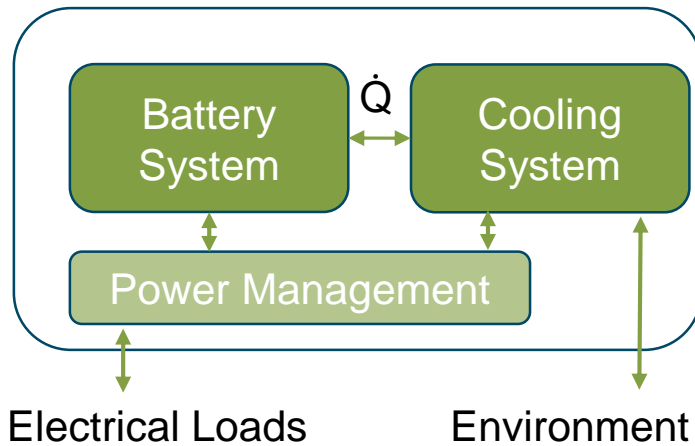
BAT: Battery
 FCC: Flight Control Computer

M: Motor
 MC: Motor Controller
 GB: Gearbox

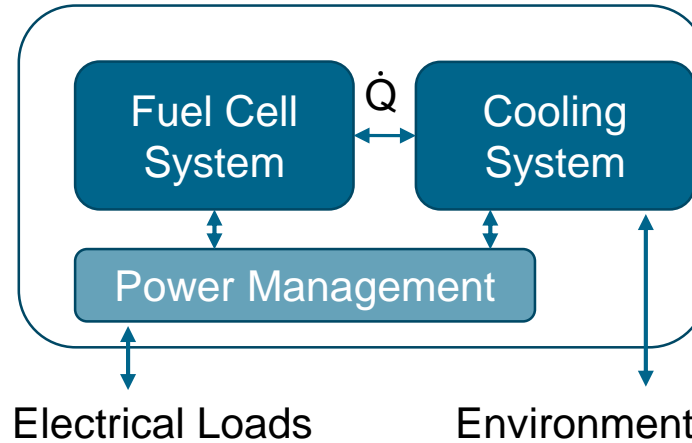
Power Supply – Architectures and Design Steps



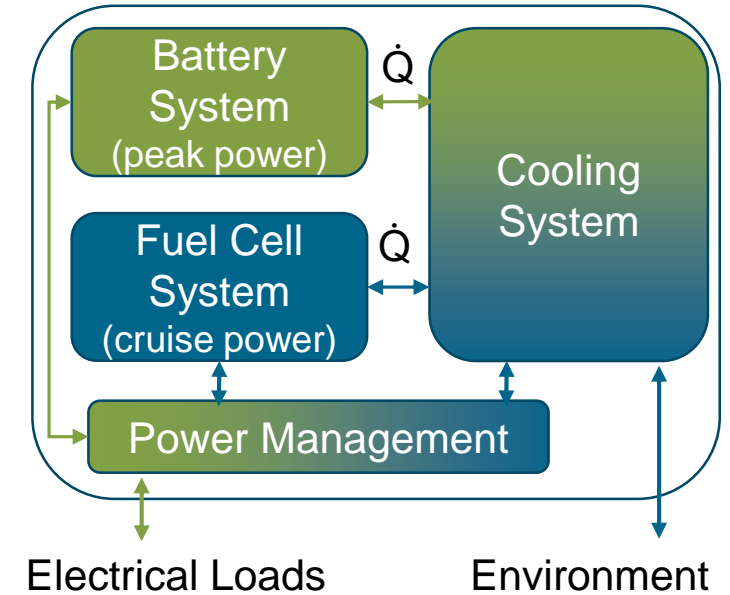
1. Full-Electric with Battery



2. Full-Electric with Fuel Cell System

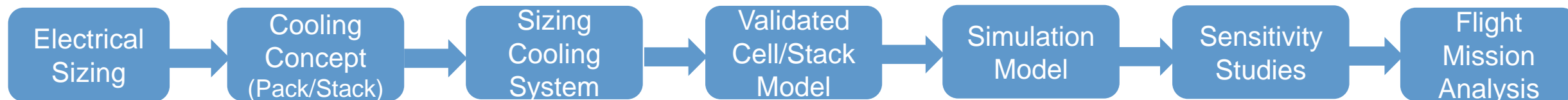


3. Hybrid-Electric with Battery and Fuel Cell System

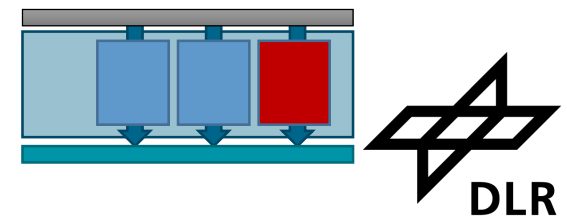


Three different power supply systems were designed and analysed due to their electrical and thermal behaviour

- Electrical loads were estimated using the flight performance calculation and powertrain architecture efficiencies
- Power management and controller design not yet considered
- Similar design steps for battery pack/system and fuel cell stack/system



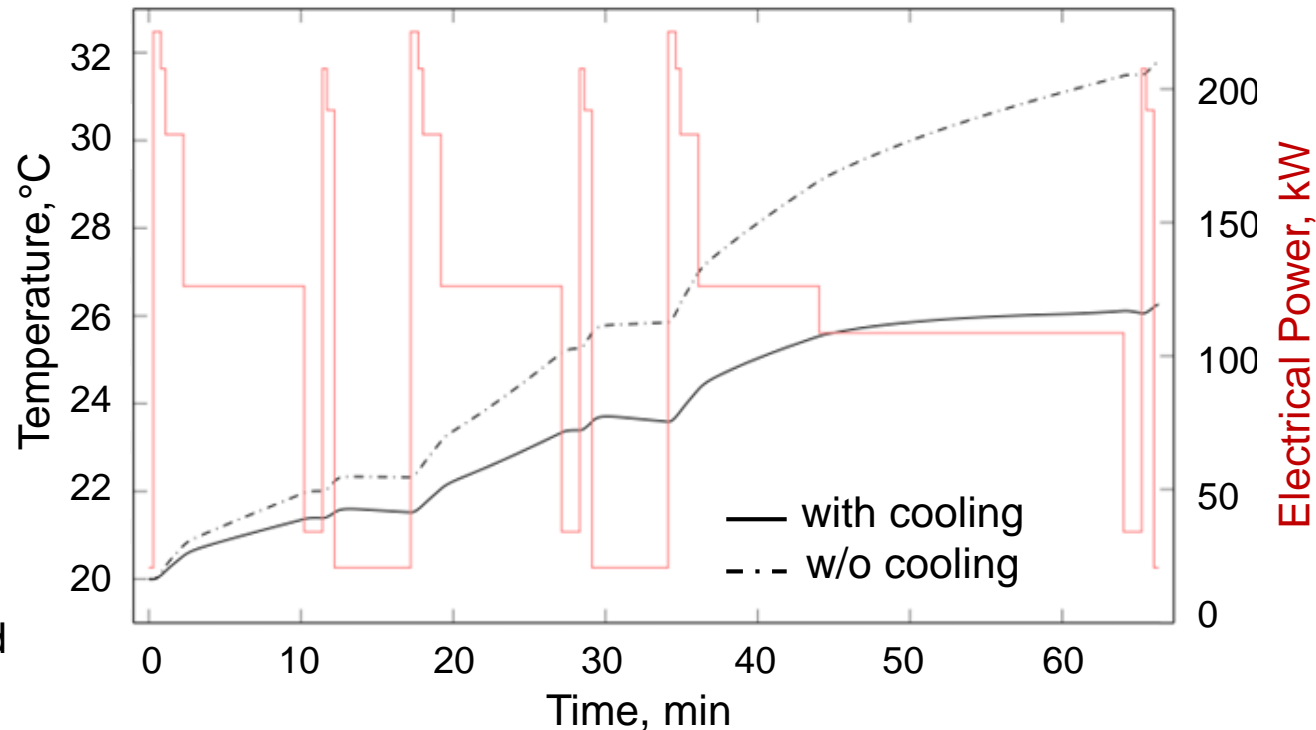
Power Supply – Results



Key Results

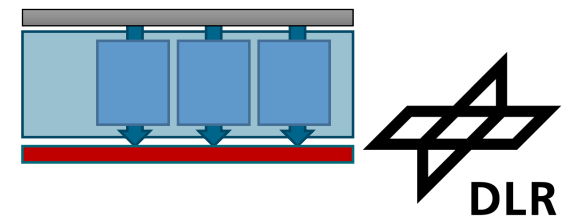
- For normal conditions the systems are adequately dimensioned: The cooling system lowers the temperature for the entire mission
- The ambient temperature has a significant impact on the cooling performance
- The temperature can be easily regulated with the volume flow of the air
- The water flow will influence the temperature distribution in the battery pack (more detailed investigations needed)
- Based on sensitivity studies a specific cooling geometry for the battery pack and fuel cell stack could be defined
- Similar results for battery cooling in the hybrid-electric power supply system
- Fuel cell system without cooling is not possible, it heats up too fast and too much

Example: Flight mission analysis with and without battery cooling



→ Feasibility of the different power supply systems was checked and verified

Summary and Outlook



- Onboard systems are an essential part of the air taxi concept which is under investigation in the HorizonUAM project
- A special focus was on the flight control system incl. the powertrain as well as the power supply incl. the thermal management concept
- The designs and results shown were reached in different parallel design streams
- Each design stream could verify the basic feasibility of the system
- Although an attempt was made to proceed from same assumptions, this was not always possible
- The “System Integration” will harmonize the different system designs (and models) to reach consistent design results

