

Robust Estimation of Heterogeneous Treatment Effects: An Algorithm-based Approach

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Abstract

Heterogeneous treatment effect estimation is an essential element in the practice of tailoring treatment to suit the characteristics of individual patients. Most existing methods are not sufficiently robust against data irregularities. To enhance the robustness of the existing methods, we recently put forward a general estimating equation that unifies many existing learners. But the performance of model-based learners depends heavily on the correctness of the underlying treatment effect model. This paper addresses this vulnerability by converting the treatment effect estimation to a weighted supervised learning problem. We combine the general estimating equation with supervised learning algorithms, such as the gradient boosting machine, random forest, and artificial neural network, with appropriate modifications. This extension retains the estimators' robustness while enhancing their flexibility and scalability. Simulation shows that the algorithm-based estimation methods outperform their model-based counterparts in the presence of nonlinearity and non-additivity. We developed an **R** package, **RCATE**, for public access to the proposed methods. To illustrate the methods, we present a real data example to compare the blood pressure-lowering effects of two classes of antihypertensive agents.

Keywords: Causal inference, machine learning, robust estimation, heterogeneous treatment effect, least absolute deviation

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1 Introduction

The practice of precision medicine relies on a sound causal understanding of treatment effects varying with patient characteristics. Estimating such effects, known as the heterogeneous treatment effects, from observational data is typically done within the Neyman-Rubin causal framework with appropriate assumptions (Sekhon, 2008). Popular approaches include the *Quality* or Q-learning that directly regresses the outcomes on patient characteristics (Watkins and Dayan, 1992; Watkins, 1989) and the *Advantage* or A-learning that models the contrasts among treatments (Murphy, 2003; Robins, 2004).

Despite the general applicability of these estimation methods, practical challenges abound:

(1) Few existing estimators are designed to deal with data irregularities and high dimensionality. (2) Model-based methods remain vulnerable to model misspecification. (3) Few software packages are available for practical use in an off-the-shelf fashion and can handle the above issues. The lack of ready-made robust analytical tools has hindered the practical use of these methods because practitioners are rarely in a position to implement and test sophisticated causal inference methods.

Efforts have been made to alleviate the impact of data irregularities. For example, Xiao et al. (2019) extended the L_2 -based R-learner (Nie and Wager, 2017), a method under the general A-learning umbrella, to the pinball loss function. More recently, our research team has put forward a general estimating equation for robust estimation of heterogeneous treatment effects, supported by strong theoretical and empirical evidence (Li et al., 2021). This estimating equation unifies many of the existing methods, including the R-learner (Nie and Wager, 2017), inverse propensity weighting (Hirano et al., 2003; Horvitz and Thompson,

47 1952), various modified outcome and covariate methods (with and without efficiency aug-
48 mentation) (Chen et al., 2017; Tian et al., 2014), and the augmented inverse propensity
49 weighting method (Robins and Rotnitzky, 1995). We showed that under fairly general reg-
50 ularity conditions, the robust estimators ascertained from the general estimating equation
51 are asymptotic normal to allow for valid inference. Despite its broad coverage and good the-
52 oretical properties, the general estimating equation estimators are not robust against model
53 misspecifications, nor are they easy to implement in practical data analyses.

54 This paper extends our previous work by combining the A-learner from the general esti-
55 mating equation with supervised learning algorithms to further enhance its robustness again
56 model misspecifications. This modification also frees analysts from the tedious and error-
57 prone work of model building. We implement the causal inferences tools in the form of an
58 **R** package - **RCATE**, short for Robust Estimation of the Conditional Average Treatment
59 Effects, for a scalable solution to heterogeneous treatment estimation.

60 2 Methods

61 2.1 Notation and assumptions

Let T be a binary variable for treatment assignment: $T = 1$ if a patient is in the treatment group, and $T = -1$ otherwise. We define $Y^{(1)}$ and $Y^{(-1)}$ as the potential outcomes under treatments $T = 1$ and $T = -1$, respectively. Here, $Y^{(1)}$ and $Y^{(-1)}$ are assumed to be univariate and continuous. Let \mathbf{X} be the p -dimensional pre-treatment covariates. In an observational study, one observes T , \mathbf{X} , and $Y = I(T = 1)Y^{(1)} + I(T = -1)Y^{(-1)}$, where

$I(\cdot)$ is an indicator function. We assume that the data $\{(Y_i, T_i, \mathbf{X}_i)\}_{i=1}^n$ are independent and identically distributed (i.i.d.). The estimation target is the treatment effect $\tau_0(\mathbf{x})$, commonly known as the conditional average treatment effect (CATE)

$$\tau_0(\mathbf{x}) = E[Y^{(1)} - Y^{(-1)} | \mathbf{X} = \mathbf{x}] = E[Y | \mathbf{X} = \mathbf{x}, T = 1] - E[Y | \mathbf{X} = \mathbf{x}, T = -1],$$

62 where the last part follows from the ignorability assumption below. With a binary treatment
 63 indicator, one can always express the conditional mean outcome as $E(Y | \mathbf{X}, T) = b_0(\mathbf{X}) +$
 64 $\frac{T}{2}\tau_0(\mathbf{X})$, with $b_0(\mathbf{x}) = \frac{1}{2}(E[Y^{(1)} | \mathbf{X} = \mathbf{x}] + E[Y^{(-1)} | \mathbf{X} = \mathbf{x}])$. This leads to a general interaction
 65 model

$$Y_i = b_0(\mathbf{X}_i) + \frac{T_i}{2}\tau_0(\mathbf{X}_i) + \varepsilon_i. \quad (1)$$

66 We further define $\mu(\mathbf{x}) = E[Y | \mathbf{X} = \mathbf{x}]$, $\mu^{(1)}(\mathbf{x}) = E[Y | \mathbf{X} = \mathbf{x}, T = 1]$, and $\mu^{(-1)}(\mathbf{x}) =$
 67 $E[Y | \mathbf{X} = \mathbf{x}, T = -1]$.

68 To estimate $\tau_0(\mathbf{X}_i)$, we operate under the following assumptions: (1) *Ignorability* —
 69 Treatment assignment T_i is independent of the potential outcomes $(Y_i^{(1)}, Y_i^{(-1)})$ given the
 70 covariates \mathbf{X}_i , i.e., $\{Y_i^{(1)}, Y_i^{(-1)} \perp\!\!\!\perp T_i | \mathbf{X}_i\}$; (2) *Positivity* — The propensity score is strictly
 71 between 0 and 1, i.e., $p(\mathbf{x}) := P(T = 1 | \mathbf{X} = \mathbf{x}) \in (0, 1)$; (3) *Stable Unit Treatment Values*
 72 *Assumption (SUTVA)* — the potential outcome in one individual is only affected by the
 73 treatment he receives; (4) *Conditional Independence Error* — The error is independent of
 74 the treatment assignment, conditional on the covariates, i.e., $\{\varepsilon_i \perp\!\!\!\perp T_i | \mathbf{X}_i\}$. We further
 75 assume that the conditional expectation of the error exists. The commonly seen assumption
 76 of $E[\varepsilon] = 0$ is sufficient but not necessary.

77 2.2 The existing methods

78 There is a sizable literature on the estimation of CATE using observational data. Caron
79 et al. (2020) and Zhang et al. (2020) provided state-of-the-art reviews of the methods for
80 CATE estimation. We summarize the existing methods in Table 1, along with the available
81 analytical software. Importantly, most of these methods are based on the L_2 -loss function,
82 whose performance deteriorates with data irregularity.

83 (Table 1 goes here)

84 The estimating equation that we proposed (Li et al., 2021), while not covering all methods
85 in Table 1, does accommodate many loss functions, including the L_1 -loss, Huber loss, and Bi-
86 square loss, and thus greatly enhancing the estimators' robustness against data irregularities.
87 In the next section, we briefly review this formulation and the methods it covers.

88 2.3 A unified estimating equation for CATE

89 We previously described the general estimating equation that covers many of the existing
90 methods for CATE estimation. An important feature of the estimating equation is that it
91 readily accommodates the L_1 loss function so that robust estimation can be derived; see Li
92 et al. (2021) for detailed derivation and theoretical development. Briefly, we consider the
93 following estimating equation

$$\min_{\tau(\cdot) \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n w(\mathbf{X}_i, T_i) M(Y_i - g(\mathbf{X}_i) - c(\mathbf{X}_i, T_i) \tau(\mathbf{X}_i)), \quad (2)$$

94 where \mathcal{F} is the treatment effect function space subject to predefined assumptions such as
95 smoothness, $M(\cdot)$ is a user-specified loss function, and the two weight functions $w(\mathbf{x}, t)$ and

96 $c(\mathbf{x}, t)$ are subject to the following constraints:

97 C1. $p(\mathbf{x})w(\mathbf{x}, 1)c(\mathbf{x}, 1) + (1 - p(\mathbf{x}))w(\mathbf{x}, -1)c(\mathbf{x}, -1) = 0;$

98 C2. $c(\mathbf{x}, 1) - c(\mathbf{x}, -1) = 1;$

99 C3. $w(\mathbf{x}, t)c(\mathbf{x}, t) \neq 0.$

100 Equation (2) covers many existing popular methods for heterogeneous treatment effect
101 estimation, including the modified covariate methods (MCM) (Chen et al., 2017; Tian et al.,
102 2014), MCM with efficiency augmentation (MCM-EA) (Chen et al., 2017; Tian et al., 2014),
103 inverse propensity score weighting (IPW) (Hirano et al., 2003; Horvitz and Thompson, 1952),
104 augmented inverse propensity score weighting (AIPW) (Robins and Rotnitzky, 1995), and
105 the R-learner (RL) (Nie and Wager, 2017). In Table 2, we list the functions c , w , and g that
106 meet the constraints for popular A-learning methods.

107 (Table 2 goes here)

108 An important appeal of the general formulation is its flexibility in specifying M , a feature
109 that enhances the robustness against various forms of data irregularities through the use of
110 L_1 and Huber loss functions. Here, we used the L_1 -loss for illustration purpose. With the
111 L_1 -loss and under the above [conditions](#), we have

$$\tau_0(\cdot) = \arg \min_{\tau(\cdot)} E[w(\mathbf{X}_i, T_i) \cdot |Y_i - g(\mathbf{X}_i) - c(\mathbf{X}_i, T_i)\tau(\mathbf{X}_i)| | \mathbf{X}_i]. \quad (3)$$

112 In the present research, we estimate $\tau(\mathbf{X})$ using modified supervised learning algorithms,
113 [which side-step the need to specify \$\tau\$, and thus enhancing the method's flexibility and scal-](#)
114 [ability without sacrificing its robustness against data irregularities.](#)

2.4 Supervised learning algorithms for robust CATE Estimation

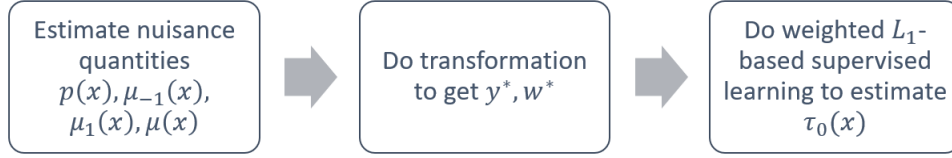
Through a transformation, CATE estimation in (3) under the L_1 -loss function can be seen as an optimization problem of ordinary least absolute deviation (LAD),

$$\hat{\tau}(\cdot) = \arg \min_{\tau(\cdot) \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n w_i^*(\mathbf{X}_i, T_i) |Y_i^* - \tau(\mathbf{X}_i)|, \quad (4)$$

where $Y_i^* = \frac{Y_i - g(\mathbf{X}_i)}{c(\mathbf{X}_i, T_i)}$ and $w_i^*(\mathbf{X}_i, T_i) = w_i(\mathbf{X}_i, T_i) |c(\mathbf{X}_i, T_i)|$. We now show how to adapt three supervised learning algorithms for this purpose.

Depending on the structured assumptions one chooses for \mathcal{F} , one can select an appropriate learning algorithm for estimation, while taking care of the high dimensionality in \mathbf{X} . In Section 3, we compare the L_1 and L_2 -based algorithms. For the L_2 -based methods, the transformed weight is $w_i^*(\mathbf{X}_i, T_i) = w_i(\mathbf{X}_i, T_i) c(\mathbf{X}_i, T_i)^2$.

With the objective function in (4), different supervised learning algorithms can be used to estimate CATE - the optimization becomes a weighted supervised learning problem, where Y_i^* and w_i^* are the new outcome and new weight of each sample. The nuisance quantities in Y_i^* and w_i^* need to be pre-estimated and plugged in. Here we use L_1 -based gradient boosting machine (GBM) with $Y|T = -1$, $Y|T = 1$, Y as outcomes to estimate $\mu^{(-1)}(\mathbf{x})$, $\mu^{(1)}(\mathbf{x})$, and $\mu(\mathbf{x})$. Note that $\mu^{(1)}(\mathbf{x})$ and $\mu^{(-1)}(\mathbf{x})$ are only needed for AIPW. And we use L_2 -based GBM with $D = (T + 1)/2$ to estimate $p(\mathbf{x})$. Any supervised learning algorithm with a weighted L_1 loss can be used to optimize (4) for robust CATE estimation. In this section, we describe three different algorithms for this purpose. The algorithms we describe are based on Random Forest (RF), GBM, and artificial neural network (ANN). The common process underlying these algorithms is graphically depicted in the following figure.



135 To achieve robust estimates of τ , we modified the existing supervised learning algorithms
 136 by incorporating the L_2 -loss function. For example in RF, we used a weighted LAD splitting
 137 rule and the mean-of-medians to aggregate the trees, as opposed to the L_2 -loss function
 138 and mean-of-means in the standard RF. Similarly in GBM, we used the L_1 -loss to compute
 139 the working response and we calculated the weighted medians for prediction of the terminal
 140 nodes. In ANN, we used weighted LAD in back-propagation, and an L_1 regularization
 141 in high-dimensional situations to ascertain the sparse weights; here we used the adaptive
 142 moment estimation (Adam) to avoid being stuck at a local optimum (Kingma and Ba,
 143 2014). We describe the algorithmic details in the following subsections.

144 2.4.1 A Robust Random Forest Learner

145 We first use RF for robust estimation of CATE. The building blocks of random forests
 146 are regression trees (Breiman et al., 1984). The tree structure comes from the recursively
 147 partitioning of the sample by covariates to minimize heterogeneity in the outcomes. The
 148 partition that minimizes the heterogeneity in child nodes is chosen, so that variables reducing
 149 heterogeneity most have the best chance of being selected than the background noise variables
 150 (Biau, 2012). Binary splits lead to trees, and then aggregated results within the terminal
 151 nodes are used for prediction. The random forest creates a more stable structure and reduces

152 the variance by combining a large number of de-correlated regression trees (Breiman, 2001).

153 The standard regression trees minimize the mean squared error (MSE) in child nodes
154 (i.e., $MSE = \sum_{i \in L_l} (y_i - \bar{y}_l)^2 + \sum_{i \in L_r} (y_i - \bar{y}_r)^2$, where \bar{y}_l and \bar{y}_r are the average values
155 within the left and right child nodes) (Hastie et al., 2009). And robust random forests
156 for regression have been studied to gain robustness against outliers, including using mean-
157 of-medians (Meinshausen and Ridgeway, 2006) or median-of-means as estimators, and the
158 LAD-based splitting rule (Roy and Larocque, 2012). Empirical studies have demonstrated
159 that these modifications offer more protection against outliers than the standard RF.

160 The robust RF-based CATE estimation splits the samples by using the weighted LAD
161 (WLAD) rule, a variant of the LAD rule. The WLAD rule is

$$WLAD = \sum_{i \in L_l} w_i^* |y_i^* - \tilde{y}_l^{*'}| + \sum_{i \in L_r} w_i^* |y_i^* - \tilde{y}_r^{*'}|, \quad (5)$$

162 where $\tilde{y}_l^{*'}$ and $\tilde{y}_r^{*'}$ are the leaf node medians to increase robustness and w_i^* is the transformed
163 weight of each observation. For prediction, we use the mean-of-medians that is consistent
164 with the WLAD rule (Meinshausen and Ridgeway, 2006) instead of the median of means as
165 advocated by Roy and Larocque (2012).

Algorithm 1: Robust RF-based CATE estimating algorithm

Input: Data $\{(Y_i, T_i, \mathbf{X}_i)\}_{i=1}^n$, number of trees T , fraction of features used in splitting

$p_{fraction} \in (0, 1)$, minimum node size k , and bootstrap sample size N .

Estimate nuisance quantities $p(\mathbf{x}), \mu(\mathbf{x}), \mu^{(1)}(\mathbf{x}), \mu^{(-1)}(\mathbf{x})$ using (robust) GBM;

Calculate w_i^* and y_i^* according to Table 2 and Formulation (4);

for t in $1, \dots, T$ **do**

- a. Randomly select N observations with replacement from the dataset as the bootstrap sample and randomly select a subset of variables with size $p_{fraction} \times p$;
- b. Fit a regression tree by repeating following steps until we reach the minimum node size k :
 - b.1 Find the variable and the cutoff value that best split the data into two child nodes based on (5);
 - b.2 Split the current node into two child nodes;
- c. Calculate the median of the transformed outcomes in each terminal node as CATE estimator;

end

Output: Mean-of-medians as the final CATE estimation $\hat{\tau}(\mathbf{x})$ and splitting criterion of trees.

The tuning parameters $T, p_{fraction}, k$, and N can be selected by cross validation.

2.4.2 The robust gradient boosting machine learner

Gradient boosting machine is a supervised learning technique that produces a prediction model $\hat{f}(\mathbf{x})$ in the form of sequential weak-learners, typically regression trees, so that it performs better in high-dimensional settings (Friedman et al., 2000; Friedman, 2001, 2002).

GBM builds the model in a step-wise fashion by allowing optimization of a differentiable loss

173 function $\Psi(y, f)$. The principle idea behind this algorithm is to construct weak-learners that
174 are maximally correlated with the negative gradient of the loss function, associated with the
175 whole ensemble.

Friedman’s GBM algorithm initializes $\hat{f}(\mathbf{x})$ to be a constant. Then, in each iteration, it
computes the negative gradient as the working response

$$z_i = -\frac{\partial}{\partial f(\mathbf{x}_i)}\Psi(y_i, f(\mathbf{x}_i))\Big|_{f(\mathbf{x}_i)=\hat{f}(\mathbf{x}_i)}.$$

176 A regression model $g(\mathbf{x})$ is fitted to predict z from the covariates \mathbf{x} . Finally, it updates the
177 estimate of $f(\mathbf{x})$ as $\hat{f}(\mathbf{x}) \leftarrow \hat{f}(\mathbf{x}) + \lambda g(\mathbf{x})$, where λ is the step size. Friedman also proposed
178 the LAD-TreeBoost algorithm (Friedman, 2001), a variation of GBM, which is highly robust
179 against outliers. Ridgeway (2007) later extended the LAD-TreeBoost algorithm to a weighted
180 version.

181 In the proposed robust GBM for CATE estimation, we further extended Ridgeway’s
182 algorithm by combining it with the unified CATE estimation formulation as follows:

Algorithm 2: Robust GBM-based CATE estimating algorithm

Input: Data $\{(Y_i, T_i, \mathbf{X}_i)\}_{i=1}^n$, number of trees T , fraction of observations used in splitting

$p_{sample} \in (0, 1)$, interaction depth c , and step size λ .

Estimate nuisance quantities $p(\mathbf{x}), \mu(\mathbf{x}), \mu^{(1)}(\mathbf{x}), \mu^{(-1)}(\mathbf{x})$ using (robust) GBM;

Calculate w_i^* and y_i^* according to Table 2 and Formulation (4);

Initialize $\hat{\tau}(\mathbf{x})$ to be a constant, $\hat{\tau}(\mathbf{x}) = \text{median}_{w^*}(y^*)$;

for t in $1, \dots, T$ **do**

a. Compute the negative gradient as the working response $z_i = -\text{sign}(y_i^* - \hat{\tau}(\mathbf{x}_i))$;

b. Randomly select $p_{sample} \times n$ observations without replacement from the dataset;

c. Fit a regression tree to predict z_i using covariates \mathbf{x}_i with interaction depth c and the number of leaf nodes K ;

d. Compute the optimal predictions for feature \mathbf{x} as

$$\rho_k(\mathbf{x}) = \text{argmin}_{\rho} \sum_{\mathbf{x}_i \in S_k} \Psi(y_i^*, \hat{\tau}(\mathbf{x}_i) + \rho, w_i^*), \text{ where } \Psi(y, x, w) = w|y - x| \text{ and } k$$

indicates the index of the terminal node S_k into which an observation with feature x would fall;

e. Update $\hat{\tau}(\mathbf{x})$ as $\hat{\tau}(\mathbf{x}) \leftarrow \hat{\tau}(\mathbf{x}) + \lambda \rho_k(\mathbf{x})$, where λ is step size.

end

Output: Splitting criterion and CATE estimates as the resulted $\hat{\tau}(\mathbf{x})$ from the above

iteration.

For robust estimation, the terminal node estimate is the weighted median $\text{median}_{w^*}(z)$,

defined as the solution ρ to the equation $\frac{\sum w_i^* I(y_i^* \leq \rho)}{\sum w_i^*} = \frac{1}{2}$. Tuning parameters T , λ , c , and K

can be selected via cross validation.

187 2.4.3 A robust artificial neural network learner

188 Artificial neural network (ANN) is a computer program designed to simulate the way the
189 human brain processes information (Goodfellow et al., 2016). A no-hidden-layer ANN with
190 identity activation function is similar to linear regression in its modeling structure. But an
191 ANN with multiple hidden layers offers **more enhanced** modeling flexibility. A feed-forward
192 neural network with two hidden layers can be written as $g(\mathbf{x}) := f^3(W^3 f^2(W^2 f^1(W^1 \mathbf{x})))$,
193 where $W^l = (w_{jk}^l)$ are the weights between layer $l - 1$ and l , and w_{jk}^l is the weight between
194 the k -th node in layer $l - 1$ and the j -th node in layer l , and f^l is the activation function at
195 layer l .

196 Multi-layer networks use a variety of techniques to learn the weights. The most popular
197 approach is backpropagation (Rumelhart et al., 1986). In training, the loss of the model is
198 defined based on the difference between the outcome y and the predicted output \hat{y} . The most
199 popular loss function is the Root Mean Squared Error (RMSE) (i.e., $\sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2}$).
200 However, numerous studies have shown that the presence of outliers poses a serious threat to
201 the standard least squares analysis (Liano, 1996). The L_1 -loss provides an effective remedy
202 that can be applied to ANN (i.e., $\frac{1}{n} \sum_{i=1}^n |y_i - \hat{y}_i|$). An empirical study shows that L_1 -based
203 estimator had an improved performance than that of the L_2 -based algorithm when outliers
204 exist (El-Melegy et al., 2009).

205 As typical for CATE estimation, the activation functions of the hidden layers are rectified
206 linear activation units (ReLU) and the last activation function is the identity function (Nair
207 and Hinton, 2010). ReLU is a piecewise linear function that outputs the input directly if it
208 is positive; otherwise, it outputs zero. Models that use ReLUs are easier to train and often

209 have better performance.

210 To ensure robustness, we propose to use the weighted Mean Absolute Error (MAE)
211 $\frac{1}{n} \sum_{i=1}^n w_i^* |y_i^* - \hat{y}_i^*|$ as the loss function, where w^* and y^* are the transformed weight and
212 outcome in the unified formulation (4). We use the adaptive moment estimation (Adam),
213 a gradient-based optimization algorithm, which runs averages of both the gradients and the
214 second moments of the gradients (Kingma and Ba, 2014), to train the ANN. We add an L_1
215 regularization term $\lambda \|W\|_1$ to the loss function in high-dimensional settings in the first layer
216 to achieve sparsity by driving some weights to zero (Feng and Simon, 2017; Girosi et al.,
217 1995), where λ is the tuning parameter.

218 The algorithm is as follows:

Algorithm 3: Robust ANN-based CATE estimating algorithm

Input: Data $\{(Y_i, T_i, \mathbf{X}_i)\}_{i=1}^n$, number of iterations T , batch size \mathcal{B} , Adam parameters

β_1, β_2, η , and ε , and L_1 regularization parameter λ in high-dimensional case.

Estimate nuisance quantities $p(\mathbf{x}), \mu(\mathbf{x}), \mu^{(1)}(\mathbf{x}), \mu^{(-1)}(\mathbf{x})$ using (robust) GBM;

Calculate w_i^* and y_i^* according to Table 2 and Formulation (4);

Initialize an ANN with weights W , the decaying average of past gradients m to a zero

vector, and the decaying average of past squared gradients v to a zero vector;

219

for t in $1, \dots, T$ **do**

a. Sample a mini-batch of data $\{y_i^*, \mathbf{x}_i, w_i^*\}$ without replacement with size \mathcal{B} ;

b. Compute the negative gradients $g^{(t)}$ based on weighted MAE;

c. Update m and v by $m^{(t)} = \beta_1 m^{(t-1)} + (1 - \beta_1)g^{(t)}, v^{(t)} = \beta_2 v^{(t-1)} + (1 - \beta_2)g^{(t)2}$;

d. Compute bias correction terms $\hat{m}^{(t)} = \frac{m^{(t)}}{1 - \beta_1^t}, \hat{v}^{(t)} = \frac{v^{(t)}}{1 - \beta_2^t}$;

e. Update the weights by $W^{(t)} = W^{(t-1)} - \eta \frac{\hat{m}^{(t)}}{\sqrt{\hat{v}^{(t)} + \varepsilon}}$.

end

Output: Weights W in the ANN and the resulted $\hat{\tau}(\mathbf{x})$ represented by the network.

220

Key advantages of the algorithm-based CATE estimators, in comparison with their

221

model-based counterparts, are their automated implementation and scalability, as well as

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their accommodation of the non-additive effects and the high-dimensionality of X . For dif-

223

ferent algorithm-based CATE learners, we summarize the advantages and disadvantages in

224

Table 3. Generally speaking, RF is easier to tune and it performs well in low dimensional

225

cases. But a well-tuned GBM tends to outperforms RF in a high-dimensional data situation.

226

ANN usually outperforms GBM and RF for image and text data because ANN is more flex-

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ible. For CATE estimation, however, when we have structured non-image or non-text data,

228

the representation problem is easier to solve, and ANN might not offer added advantages.

229 (Table 3 goes here)

230 **2.4.4 An R package for implementation**

231 To make the proposed algorithms more accessible, we implemented the three CATE-learning
232 algorithms in an **R** package **RCATE**. Each of the algorithms can be combined with MCM-
233 EA, RL, and AIPW to achieve robust CATE estimation. For input data, we only require
234 specification of the outcome, treatment assignment, and pre-treatment covariates. There is
235 no need for users to estimate the nuisance quantities. A more detailed description of the **R**
236 package **RCATE** and example code are provided in Appendix A.

237 **3 Simulation Studies**

238 **3.1 Design and implementation**

239 We conducted three sets of simulations to evaluate the performance of the proposed methods.

240 **Simulation Study 1:** We compared the additive-model-based and algorithm-based learn-
241 ers under both L_1 and L_2 loss functions when the true treatment effect model involved
242 interactions, i.e., non-additive.

243 **Simulation Study 2:** We compared the proposed L_1 -based algorithms with other machine
244 learning algorithms in high-dimensional settings.

245 **Supplemental Simulation Study (S):** We compared the algorithm-based robust estima-
246 tors against model-based ones when the true treatment effect models were indeed additive;
247 see details in Appendix B.

248 The methods considered in each of the three simulation studies are described in Table 4,

249 where the numbers in the parentheses indicate the specific simulation studies.

250 (Table 4 goes here)

251 We designed the simulation settings followed the structure of the real data in Section 4.

252 The binary treatment levels (i.e., $T \in \{-1, 1\}$) and continuous outcome were used through-

253 out. And we set the number of replications to $R = 1,000$ and the size of the validation set

254 to $n_v = 1,000$.

We assessed the performance of these methods using mean squared error (MSE), mean absolute error (MAE), and coverage probability (CP). The MSE and MAE were defined as follows:

$$MAE_v = \frac{1}{R} \sum_{r=1}^R |\hat{\tau}^{(r)}(\mathbf{x}_v) - \tau_0(\mathbf{x}_v)|, \quad MSE_v = \frac{1}{R} \sum_{r=1}^R [\hat{\tau}^{(r)}(\mathbf{x}_v) - \tau_0(\mathbf{x}_v)]^2,$$

255 where \mathbf{x}_v is the v -th observation from the validation set, $\hat{\tau}^{(r)}(\mathbf{x})$ is the estimator of $\tau(\mathbf{x})$

256 based on the r -th data replicate. We summarized the performance over the whole validation

257 set by taking the average (i.e., $\overline{MSE} = \frac{1}{n_v} \sum_{v=1}^{n_v} MSE_v$). For simplicity, we reported MSE

258 and MAE.

We calculated the CP as the proportion of the times that 95% bootstrap percentile intervals contained the true value of interest, out of the total number of simulating iterations ($R = 1,000$), i.e.,

$$CP = \frac{1}{R} \sum_{i=1}^R I(\text{C.I. covers the true value}),$$

259 The tuning parameters were summarized in Appendix B.

260 **3.1.1 Simulation 1: ML vs. model-based methods when τ_0 is not additive**

We generated the outcome from the following model

$$Y_i = b_0(\mathbf{X}_i) + \frac{T_i}{2}\tau_0(\mathbf{X}_i) + \varepsilon_i, \quad \varepsilon_i \sim (1 - p_o)N(0, 1) + p_oP.$$

We used two different error distributions $P = N(0, 100)$ and $P = Laplace(0, \sqrt{50})$. The covariates were continuous variables ($\mathbf{X}_i \sim N_{10}(0, 1)$). The treatment assignment followed a logistic model

$$D_i | \mathbf{X}_i \sim Bernoulli(p(\mathbf{X}_i)), \quad T_i = 2D_i - 1, \quad \text{logit}(p(\mathbf{X}_i)) = X_{i1} - X_{i2}.$$

Functions $b_0(\mathbf{X}_i)$ and $\tau_0(\mathbf{X}_i)$ in the response surface were

$$b_0(\mathbf{X}_i) = 100 + 4X_{i1} + X_{i2} - 3X_{i3},$$

$$\tau_0(\mathbf{X}_i) = 6\sin(2X_{i1}) + 3(X_{i2} + 3)X_{i3} + 9\tanh(0.5X_{i4}) + 3X_{i5}(2I(X_{i4}) - 1),$$

261 where the true treatment effect function included an interaction term, and thus violating the
 262 additive model assumption.

263 We compared all methods indicated by “(1)” in Table 4 while altering two design fac-
 264 tors: The proportions of outliers p_o and the outlier generating mechanisms: (1) $p_o \in$
 265 $\{0, 0.05, 0.1, 0.15, 0.2, 0.3, 0.5\}$, $n = 1000$, and $P = N(0, 100)$, and (2) $p_o \in \{0, 0.05, 0.1, 0.15,$
 266 $0.2, 0.3, 0.5\}$, $n = 1000$, and $P = Laplace(0, \sqrt{50})$.

267 (Figure 1 goes here)

268 We reported the MSE and MAE of the CATE estimators graphically in Figure 1. The
269 figure showed that all L_1 -based algorithms outperformed the L_2 -based ones. Advantage of
270 the robust algorithms, as measured by MSE and MAE, increased with the proportion of
271 outliers. Because the true treatment effect function was non-additive, when $p_o < 0.2$, the
272 proposed machine learning algorithms outperformed additive models in MSE and CP; CPs
273 were summarized in tabular form in [Appendix Table B.3](#). The performance of robust GAMs
274 was better than robust QL when the proportion of outliers was close to the breakdown point
275 of LAD regression, i.e., $p_o = 0.5$.

276 There were little practical differences among the robust GBM, robust ANN and robust
277 RF when combined with MCM-EA and R-learning. But the robust GBM didn't work well
278 together with AIPW transformation because AIPW tended to generate transformed weights
279 with a large variability, and GBM was more likely to overfit when the data were noisy ([Park
280 and Ho, 2019](#)).

281 **3.1.2 Simulation 2: Performance in high-dimensional settings**

282 Here, we only considered the methods that performed well in Simulation Study 1, and we
283 focused on the methods' performance in high-dimensional settings and when outliers existed.

284 We generated data sets with the same outlier distributions P , baseline function, and
285 propensity score function as in Simulation Study 1. And we fixed the proportion of outliers
286 at 0.15, sample size at $n = 1,000$, and the data dimension at $p \in \{100, 2000\}$.

The true treatment effect functions when $p = 100$ and $p = 2000$ were

$$\begin{aligned} \tau_0(\mathbf{X}_i) = & 6\sin(2X_{i1}) + 3(X_{i2} + 3)X_{i3} + 9\tanh(0.5X_{i4}) + 3X_{i5}(2I(X_{i4}) - 1) + \\ & 3X_{i6} + 2X_{i7} + X_{i8} - 2X_{i9} - 4X_{i10}, \end{aligned}$$

and

$$\begin{aligned} \tau_0(\mathbf{X}_i) = & 6\sin(2X_{i1}) + 3(X_{i2} + 3)X_{i3} + 9\tanh(0.5X_{i4}) + 3X_{i5}(2I(X_{i4}) - 1) + \\ & \sum_{j=6}^{50} \beta_j X_{ij}, \beta_j \sim Unif(-2, 2), \end{aligned}$$

287 Figure 2 (A) and (C) showed that when $p = 100$, the robust GBM and robust ANN
 288 combined with AIPW and MCM-EA outperformed all other methods when outliers exist.
 289 Among the existing algorithms, causal MARS had the best performance. The performance
 290 of robust RF and robust ANN combined with RL tied with that of the causal MARS. The
 291 boosting algorithms generally performed better than RFs, because a single deep tree tended
 292 to struggle to reduce bias on high dimensional data, so did the forests. When we increased
 293 the dimension to $p = 2000$ Figure 2 (B) and (D) showed that the robust GBMs had the best
 294 performance when the data dimension was much larger than the sample size.

295 (Figure 2 goes here)

296 We additionally compared the computational speed of the proposed algorithms and ad-
 297 ditive models under difference sample sizes and dimensions of data. The robust RF was
 298 implemented in **R**, so that the speed was relatively slow and was not included in the com-
 299 parisons here. The CPU time was collected on a personal computer with Intel Core i7-7700
 300 CPU @3.60Ghz and 32 GB RAM. Table 5 showed that the robust GBM was the most ef-

301 ficient algorithms among all those considered in the comparison. Its advantage was most
302 prominent when the sample size or dimension was high.

303 (Table 5 goes here)

304 4 Real data application

305 To illustrate the use of the proposed algorithms, we assessed the treatment effects of two
306 different antihypertensive therapies by analyzing recorded clinical data set from the “All
307 of Us” research program. Sponsored by NIH, the program collected research data from
308 multiple sources, including health surveys, health records, and digital health technologies
309 (All of Us Research Program Investigators, 2019). Research data are publicly accessible at
310 <https://workbench.researchallofus.org/> through web-based Jupyter Notebook.

311 In this analysis, we compared the monotherapeutic effects of angiotensin-converting-
312 enzyme inhibitors (ACEI) and thiazide diuretics on systolic blood pressure (SBP). We con-
313 sidered those receiving thiazide as in treatment group A ($n = 504$), and those receiving
314 ACEI as in group B ($n = 1040$). The primary outcome of interest is the clinically recorded
315 SBP in response to these therapies. Covariates of interest included the demographic and
316 clinical characteristics of the participants; see Table 6.

We expressed the treatment effect as a function of the patient characteristics \mathbf{x}

$$\tau_0(\mathbf{x}) = E[Y^{(B)} - Y^{(A)} | \mathbf{X} = \mathbf{x}],$$

317 where $Y^{(A)}$ and $Y^{(B)}$ represented the potential outcome of the two treatment groups. Since

318 the treatment effect of a therapy is measured by its ability to lower SBP, a positive $\hat{\tau}(\mathbf{x})$
319 indicates a superior effect of the thiazide diuretics, for a given \mathbf{x} . An important covariate is
320 the baseline SBP.

321 In this analysis, we included individuals that were only on thiazide diuretic or ACEI for
322 at least a month. Their first SBP within three months after the initiation of thiazide or
323 ACEI was used as the outcome. The pre-treatment characteristics were measured within
324 three months before the initiation of thiazide or ACEI, and they were presented in Table 6.
325 Missing lab values were imputed by multiple imputation (Rubin, 2004).

326 (Table 6 goes here)

327 Preliminary data examination showed that the observed outcome was right-skewed. See
328 Figure 3. The Shapiro–Wilk’s test confirmed that the SBP was not normally distributed
329 (thiazide diuretic: $W = 0.9739$, $p = 8.011e - 08$; ACEI: $W = 0.9763$, $p = 5.422e - 12$).
330 We, therefore, used the L_1 -based algorithms to analyze the data. Here the weighted super-
331 vised learning algorithms were used to accommodate the possible complex treatment effect
332 function.

333 (Figure 3 goes here)

334 A closer examination of the patient characteristics revealed that patients on thiazide
335 had higher sodium and high density lipid (HDL) levels, lower albumin level and glomerular
336 filtration rate (GFR), and more likely to be female. Using GBM, we examined the mean
337 function of SBP $\hat{\mu}(\mathbf{x})$, $\hat{\mu}^{(1)}(\mathbf{x})$, $\hat{\mu}^{(-1)}(\mathbf{x})$ and the propensity of patient receiving ACEI $\hat{p}(\mathbf{x})$.
338 The estimated propensity score distributions were clearly different for the two treatment
339 groups, whereas the mean functions were similar. See Figure 4. The different propensity
340 score distributions of the two groups clearly showed the non-random nature of treatment

341 assignment, and that a naive comparison should not be trusted.

342 (Figure 4 goes here)

343 We then analyzed the data with the proposed algorithms: the robust RF and robust GBM
344 combined with MCM-EA and R-learning. We use these four methods to estimate the CATE.
345 Estimated treatment effects conditioning on pre-treatment SBP were shown graphically in
346 Figure 5. To plot these marginal effects, we fixed the continuous covariates at their mean
347 values, and categorical covariates at their mode levels.

348 Results showed that the SBP lowering effects of thiazide diuretics and ACEI were similar
349 when the pre-treatment SBP were below 160 mmHg. But for individuals with baseline SBP
350 greater than 160 mmHg, diuretics tended to have a stronger SBP-lowering effect. This obser-
351 vation was largely consistent with the findings of the Antihypertensive and Lipid-Lowering
352 Treatment to Prevent Heart Attack Trial (ALLHAT), which showed a comparable effect
353 of thiazide-like diuretic chlorthalidone and ACEI lisinopril (The ALLHAT Officers and Co-
354 ordinators for the ALLHAT Collaborative Research Group, 2002). Diuretics reduce blood
355 pressure through their natriuretic actions – increase urinary excretion of sodium and re-
356 duce extracellular fluid volume (ECFV). It works particularly well in patients with greatly
357 expanded ECFV, and thus explaining the greater SBP reduction in patients with higher
358 pre-treatment SBP (Duarte and Cooper-DeHoff, 2010).

359 (Figure 5 goes here)

360 To verify the conditional independence error assumption, we performed the invariant
361 residual distribution test (IRD-test), invariant environment prediction test (IEP-test), in-
362 variant conditional quantile prediction test (ICQP-test), invariant targeted prediction test
363 (ITP-test) (Heinze-Deml et al., 2018). The conditional independence error assumption held

364 for both proposed methods at the significant level of 0.05.

365 (Table 7 goes here)

366 **5 Discussion**

367 The practice of precision medicine relies on a sound understanding of the causal effects of
368 specific treatments in patients with different characteristics. By expressing the treatment
369 effect as a function of patient characteristics, the heterogeneous treatment effect provides
370 a useful quantification of the unknown causal effect. Among the existing methods for esti-
371 mating heterogeneous treatment effects, few have considered the conditions of the data from
372 which the estimates are derived - outliers and other forms of data irregularities could severely
373 undermine the validity of the causal estimation. We described a general estimating equation
374 that produces robust estimates against such data irregularities in recent work. However, the
375 method requires the correct specification of the treatment effect function. From a practical
376 perspective, such a requirement represents a significant constraint. Even when flexible addi-
377 tive models are used to accommodate the potential nonlinear effects, there is no assurance
378 that such an additive structure would be adequate. To address this issue, we introduced a set
379 of modified machine learning algorithms for treatment effect estimation. We also presented
380 the necessary computational tools for practical data analysis.

381 When implemented within the framework of the previously proposed estimating equation
382 for heterogeneous causal effects, we show that supervised learning algorithms could signifi-
383 cantly reduce the risk of model misspecification without losing the method's robustness. In
384 a sense, the work presents a data-driven analytical approach that reduces the users' burden

385 of model specification while retaining good theoretical properties of the general estimating
386 equation. A critical ingredient of this approach is the use of machine learning techniques to
387 optimize the objective function. Simulation results confirmed that the new procedures' good
388 performance. As a result of this development, we improved the general estimating equation's
389 scalability in real data applications, making the methods more readily usable in practical
390 data analysis.

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Table 1: Summary of existing popular CATE estimation algorithms

Base-learner/ Algorithm	Description	Pros(+) and Cons(-)	Available R packages
The single-learner (or S-learner)	Fits a single-model for the outcome with the covariates and treatment assignment indicator.	(+) If the treatment effect is simple, then pooling the data together will be beneficial. (-) Performs bad if the treatment effect is strongly heterogeneous and the response surfaces of two groups are very different.	rlearner causalToolbox
The two-learner (or T-learner)	Fits two models for the outcome of two treatment groups separately with the covariates.	(+) Performs well if the treatment effect is strongly heterogeneous and the response surfaces of two groups are very different. (-) Uses the data inefficiently.	rlearner causalToolbox
The X-learner (Künzel et al., 2019)	A three step approach to crossover the information in the control and treated subjects.	(+) Has the advantages of both S and T-learner. (-) The three-step estimator increases the risk of over-fitting and the difficulty in tuning parameter.	rlearner causalToolbox
Inverse propensity score weighting (IPW)	Transforms the outcome by inverse propensity score weighting, then the conditional expectation of the transformed outcome is the treatment effect.	(+) After transformation, the IPW provides the flexibility in choosing off-the-shelf supervised learning algorithms. (-) Relies on the accurate estimation of the propensity score.	
Augmented inverse propensity score weighting (AIPW)	Augmented IPW is robust to mis-specified mean or propensity score model.	(+) In addition to the advantage of IPW, AIPW has the property of double robustness.	RCATE
The R-learner (RL)	Decomposes the outcome by subtracting the mean model and gets an estimating equation.	(+) In addition to the advantage of IPW, R-learner has quasi-oracle property.	rlearner RCATE
The modified covariate method with efficiency augmentation (MCM-EA)	Transforms the covariates to get an estimating equation.	(+) Same as IPW. (-) Relies on the accurate estimation of mean and propensity score.	RCATE
The Q-learner	Fits the interaction model and the slope is the treatment effect function.	(+) No nuisance parameter need to be estimated. (-) Lacks of flexibility in algorithm choosing and sensitive to model mis-specification.	
Causal tree (Athey and Imbens, 2016)	Uses regression tree that splits by maximizing the difference between treatment effects in child nodes to fit the outcome.	(+) Easy to interpret and provides the grouping of subjects. (-) Suffers from the problem of high variance.	causalTree

Causal forest (Athey et al., 2019)	Uses randomly selected subsample and covariates to build causal trees, then aggregate the results.	(+) Addresses the high variance problem. (-) Lose the interpretability.	grf
Causal boosting (Powers et al., 2018)	An adaption of gradient boosting algorithm with causal trees as weak-learner.	(+) Well-tuned causal boosting outperforms the causal forest. (-) Takes longer to train than causal forest and could overfit the training data.	causalLearning
Causal MARS (Powers et al., 2018)	Fits two multivariate adaptive regression spline models in parallel in two arms of the data. In each step, it chooses the same basis function to add to each model.	(+) Alleviates the bias problem of tree-based algorithms because they use the average treatment effect within each leaf as the prediction for that leaf.	causalLearning

501

Table 2: Parameters of some popular methods in the framework

Method	$w(\mathbf{X}_i, T_i)$	$g(\mathbf{X}_i)$	$c(\mathbf{X}_i, T_i)$
MCM	$\{T_i p(\mathbf{X}_i) + (1 - T_i)/2\}^{-1}$	0	$\frac{T_i}{2}$
MCM-EA	$\{T_i p(\mathbf{X}_i) + (1 - T_i)/2\}^{-1}$	$\mu(\mathbf{X}_i)$	$\frac{T_i}{2}$
RL	1	$\mu(\mathbf{X}_i)$	$\{T_i - 2p(\mathbf{X}_i) + 1\}/2$
IPW	$\left\{ \frac{T_i - 2p(\mathbf{X}_i) + 1}{2p(\mathbf{X}_i)(1 - p(\mathbf{X}_i))} \right\}^2$	0	$\frac{2p(\mathbf{X}_i)(1 - p(\mathbf{X}_i))}{T_i - 2p(\mathbf{X}_i) + 1}$
AIPW	$\left\{ \frac{T_i - 2p(\mathbf{X}_i) + 1}{2p(\mathbf{X}_i)(1 - p(\mathbf{X}_i))} \right\}^2$	$(1 - p(\mathbf{X}_i))\mu_1(\mathbf{X}_i) + p(\mathbf{X}_i)\mu_{-1}(\mathbf{X}_i)$	$\frac{2p(\mathbf{X}_i)(1 - p(\mathbf{X}_i))}{T_i - 2p(\mathbf{X}_i) + 1}$

Table 3: Supervised learning algorithms for CATE estimation

Algorithm	Advantages	Disadvantages	Main Hyperparameters
Random Forests	Hard to overfit, easy to tune, good for parallel computing	Model can get large	Number of trees, number of features used in splitting
GBM	High-performing in high-dimensional case	Harder to tune than RF, take longer to train than RF	Number of trees, depth of trees, learning rate
Neural Network	Can handle extremely complex task	Hard and slow to train	Number of neurons in the hidden layer, number of epochs, learning rate

Table 4: Methods considered in the simulation studies. Numbers in the parentheses indicate the specific simulation studies in which the methods were assessed.

	Methods under the Unified Formulation			Other Candidate Methods	
	MCM-EA	RL	AIPW	Method	
Robust RF	(1)(2)(S)	(1)(2)(S)	(1)(2)(S)	Robust QL	(1)
Robust GBM	(1)(2)(S)	(1)(2)(S)	(1)(2)(S)	Causal BART	(2)
Robust ANN	(1)(2)(S)	(1)(2)(S)	(1)(2)(S)	Causal Boosting	(2)
RF	(1)	(1)	(1)	Causal Forest	(2)
GBM	(1)	(1)	(1)	Causal MARS	(2)
ANN	(1)	(1)	(1)	X-learner+RF	(2)
Robust GAM	(1)(S)	(1)(S)	(1)(S)		

Table 5: Comparison of the CPU time (s) of RF/GBM/ANN and additive model

Dimension	Algorithm	$n = 1000$	$n = 3000$	$n = 5000$	$n = 8000$
$p = 10$	Random Forests	0.30	1.67	3.34	7.41
	GBM	0.28	0.79	1.29	2.13
	Robust GBM	0.29	0.99	1.63	2.58
	ANN	4.72	12.87	21.43	35.89
	Robust ANN	4.51	12.63	20.90	35.25
	Robust GAM	1.65	18.94	38.23	86.18
$p = 100$	Random Forests	2.54	12.99	28.71	60.51
	GBM	2.27	6.64	11.33	18.75
	Robust GBM	2.29	7.13	12.13	19.02
	ANN	5.24	14.29	25.05	39.13
	Robust ANN	5.24	14.22	24.63	42.04
	Robust GAM	33.65	243.24	N/A	N/A

Table 6: Demographic and Clinical Characteristics of Study Subjects

Variable	Thiazide diuretic (n=504)	ACEI (n=1040)	p-value
	mean (sd)		
Systolic BP (mmHg)	134.19 (17.22)	133.97 (21.61)	0.838
Pre-treatment Systolic BP (mmHg)	140.17 (18.46)	138.46 (21.96)	0.131
Age (year)	54.10 (12.19)	54.08 (11.94)	0.975
BMI	38.97 (9.26)	37.57 (33.09)	0.350
Potassium (mmol/L)	4.06 (0.45)	4.03 (0.47)	0.375
Sodium (mmol/L)	139.06 (2.78)	138.60 (3.08)	0.005*
Cholesterol in LDL (mg/dL)	111.44 (42.24)	111.15 (53.06)	0.914
Cholesterol in HDL (mg/dL)	47.51 (13.89)	45.32 (16.68)	0.011*
Albumin (g/dL)	11.21 (14.09)	20.00 (17.24)	<0.001*
Triglyceride (mg/dL)	171.03 (114.82)	181.31 (188.53)	0.260
Hemoglobin A1c (%)	7.25 (2.03)	7.25 (1.99)	0.993
Glomerular filtration rate (ml/min/1.73m ²)	58.49 (18.56)	63.12 (18.04)	<0.001*
	n (percentage)		
Female	324 (64.3)	589 (56.6)	0.008*
Male	174 (34.5)	425 (40.9)	
Not answered	6 (1.2)	26 (2.5)	
Black	113 (22.4)	366 (35.2)	<0.001*
White	279 (55.4)	415 (39.9)	
More than one race or not answered	112 (22.2)	259 (24.9)	
Hispanic	91 (18.1)	215 (20.7)	0.254

Table 7: Conditional independence test results (p-value)

Method	IRD-test	IEP-test	ICQP-test	ITP-test
Robust RF + MCM-EA	0.17	0.50	1.00	0.38
Robust RF + RL	0.22	0.54	0.95	0.49
Robust GBM + MCM-EA	0.06	0.57	0.69	0.29
Robust GBM + RL	0.29	0.50	0.32	0.55

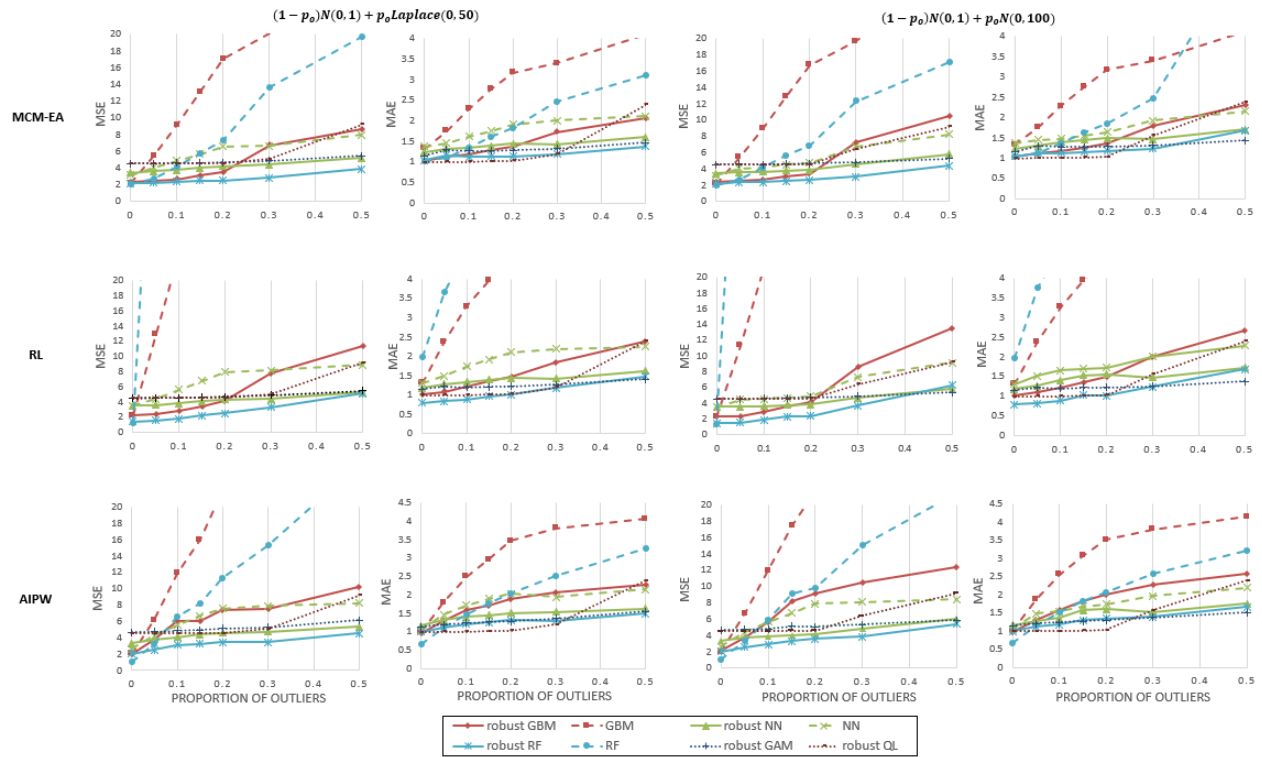


Figure 1: Results of Simulation Study 1 - MSE and MAE of different methods under various proportions of outliers and error generating mechanisms. The robust GBMs were indicated by red solid lines, the robust RFs were indicated by blue solid lines, the robust ANNs were indicated by green solid lines. The GBMs, RFs, and ANNs were indicated by dashed red, blue, and green lines. The robust GAMs were indicated by blue dotted line, and robust QL was indicated by brown dotted line.

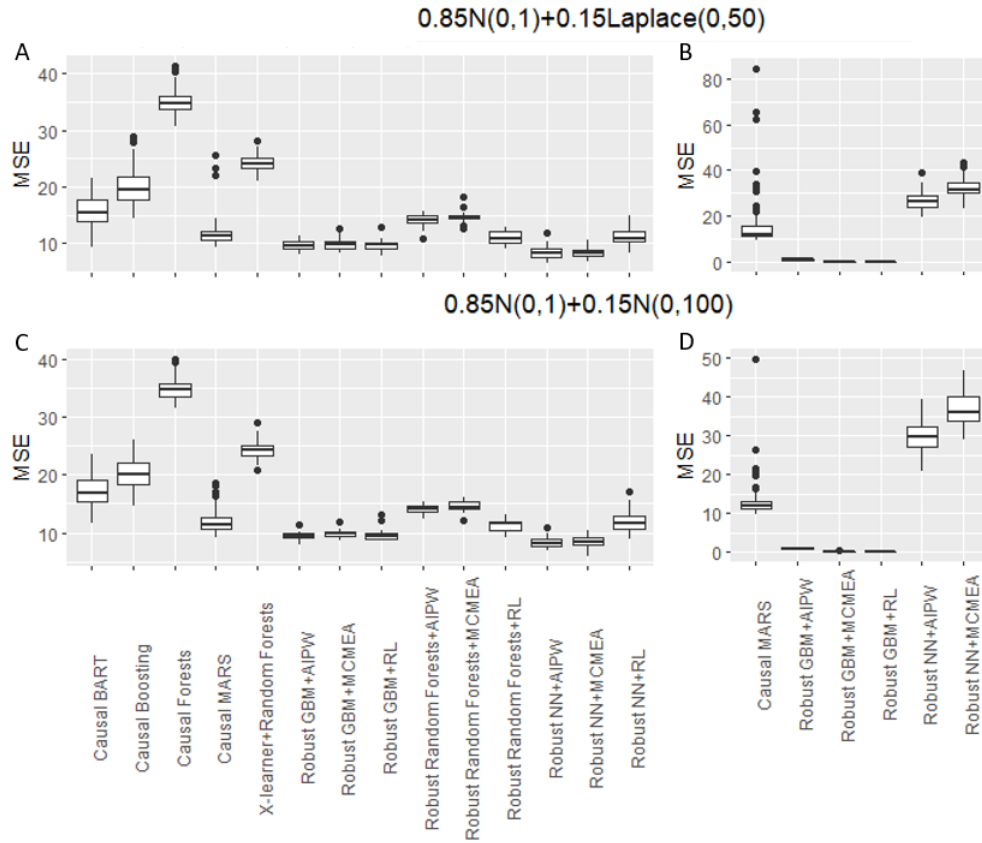


Figure 2: Simulation Study 2 - Mean squared error (MSE) of different algorithms when outliers exist. Figures A and C show the results when $p = 100$, Figures B and D show the results when $p = 2000$.

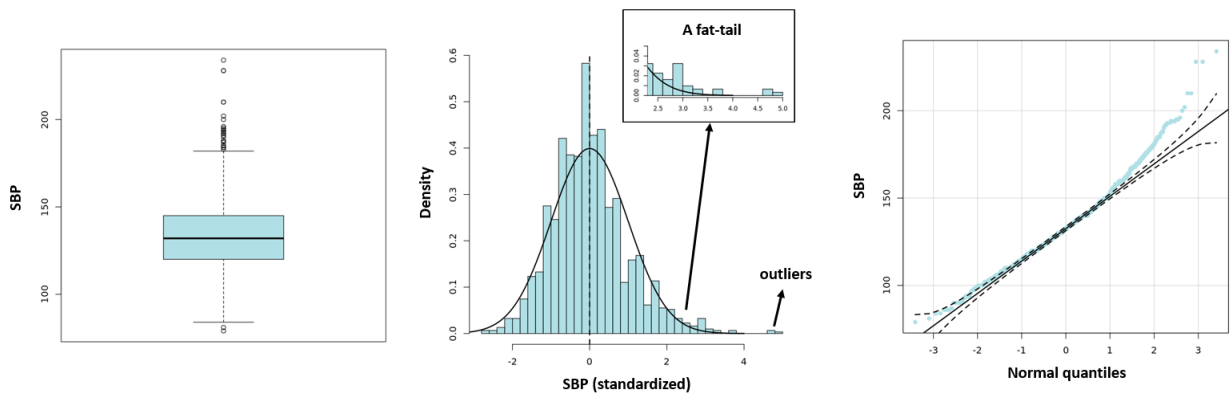


Figure 3: Heavy-tailed and Skewed Systolic Blood Pressure Distribution.

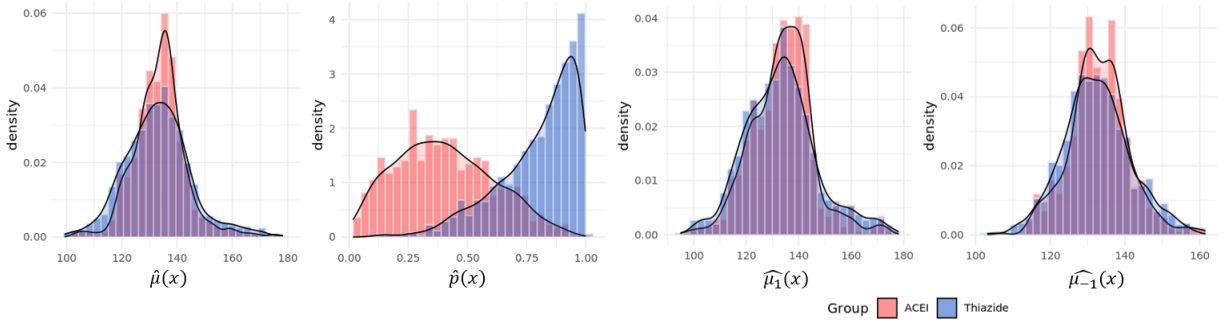


Figure 4: Data example: Estimated nuisance parameters by treatment group.

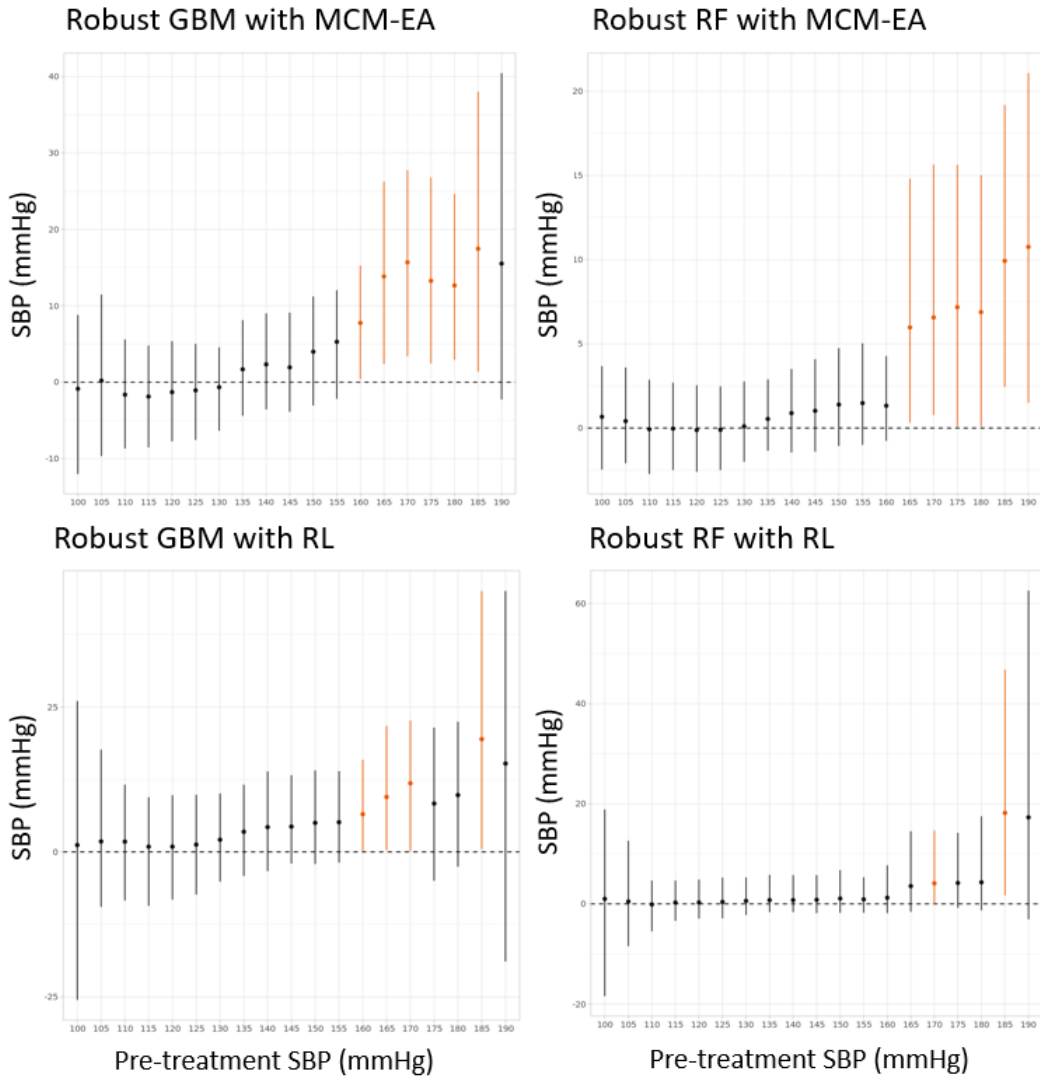


Figure 5: Data example: Marginal treatment effect of pre-treatment SBP. If the empirical 95% pointwise C.I. does not cover zero, the interval segment is colored in orange.

SUPPLEMENTAL MATERIALS

503 Appendix A: Implementation

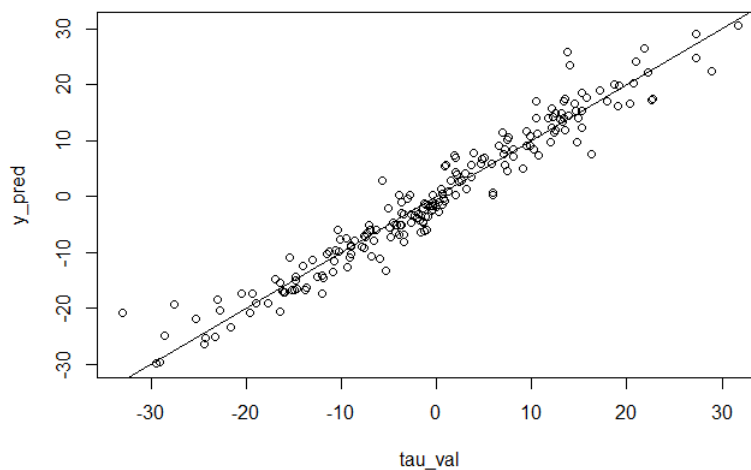
504 **Title:** RCATE package

505 **R-package for robust estimation of CATE:** R package **RCATE** containing code for 9 robust estimation algorithms of CATE described in the article and also the methods based on additive B-spline LAD regression in R.Li. The package also contains the dataset used as example in the article.

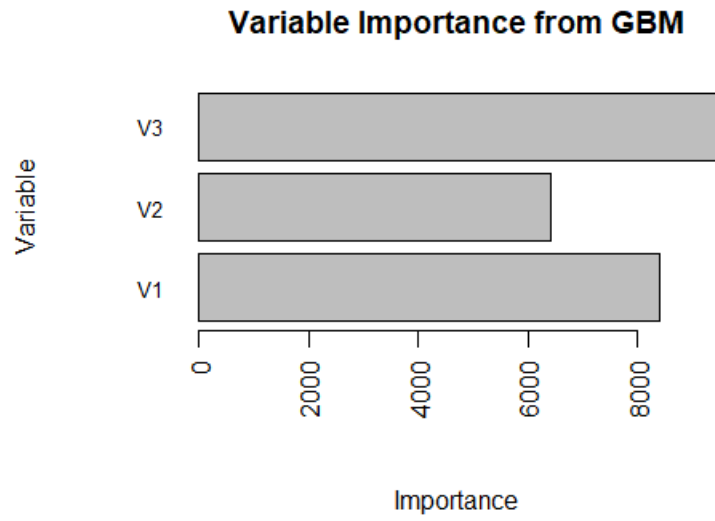
508 **Hypertension dataset:** Data set used in the illustration of robust estimation of CATE algorithms in Section 4.
509

510 Example of usage:

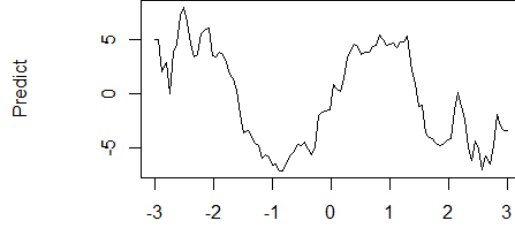
```
511 ## Install package
512 require(devtools)
513 devtools::install_github("rhli-Hannah/RCATE")
514 library(RCATE)
515
516 ## Data generation
517 n <- 1000; p <- 3; set.seed(2223)
518 X <- as.data.frame(matrix(runif(n*p, -3, 3), nrow=n, ncol=p))
519 tau = 6*sin(2*X[, 1]) + 3*(X[, 2] + 3)*X[, 3]
520 p = 1/(1+exp(-X[, 1] + X[, 2]))
521 d = rbinom(n, 1, p)
522 t = 2*d-1
523 y = 100+4*X[, 1] + X[, 2] - 3*X[, 3] + tau*t/2 + rnorm(n, 0, 1)
524 set.seed(2223)
525 x_val = as.data.frame(matrix(rnorm(200*3, 0, 1), nrow=200, ncol=3))
526 tau_val = 6*sin(2*x_val[, 1]) + 3*(x_val[, 2] + 3)*x_val[, 3]
527
528 ## Use robust GBM + R-learning to estimate CATE
529 fit <- rcate.ml(X, y, d, method='RL', algorithm='GBM')
530 y_pred <- predict(fit, x_val)$predict
531 plot(tau_val, y_pred); abline(0, 1)
```



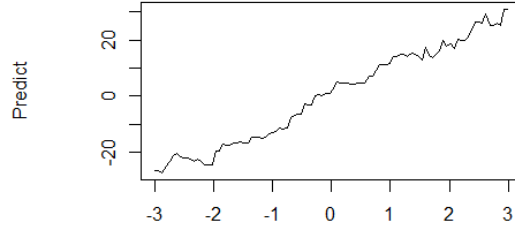
```
532
533 ## Variable importance level
534 importance <- importance.rcate(fit)
```



```
535
536 ## Marginal treatment effect plot
537 marginal.rcate(fit , 'V1')
538 marginal.rcate(fit , 'V3')
```



V1



V3

539 **Appendix B: Supplemental Simulation Study Results**

540 **Supplemental Simulation Study (S):** We compared the algorithm-based robust estimators against the
 541 model-based ones when the true treatment effect models were correctly specified. Here we assumed that the
 542 true effect effect τ was an additive function of \mathbf{X} . In such a situation, robust methods based on generalized
 543 additive models (GAM) should provide correct estimates. We also included in the simulation an L_1 -based
 544 Q-learner (robust QL) for comparison.

Specifically, we defined the last two methods as follows:

$$\text{Robust GAM: } \hat{\beta} = \underset{\beta}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n w_i^*(X_i, T_i) |Y_i^* - B(X_i)^T \beta| + \Lambda_n(\beta),$$

$$\text{Robust QL: } \hat{\gamma}, \hat{\beta} = \underset{\gamma, \beta}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n |Y_i - B(X_i)^T \gamma - \frac{T_i}{2} B(X_i)^T \beta| + \Lambda_n(\gamma, \beta),$$

545 where Λ is a smoothness-sparsity penalty for group-wise variable selection and for smoothness of the regres-
 546 sion line.

547 Model-based estimators can be more efficient when they depict the treatment effect with the right
 548 function. We simulated a situation where the true treatment effect τ is an additive function of \mathbf{X} . Since
 549 the model-based estimators used GAM to depict $\tau(\mathbf{X})$, we expect them to perform well. Algorithm-based
 550 estimators, on the other hand, may have reduced efficiency while offering a greater protection against model
 551 misspecification. Here we used model-based methods as a benchmark, and compared the performance of the
 552 algorithm-based estimators as sample size increased.

553 We compared all methods indicated by “(S)” in Table 4. We considered two scenarios: (1) For the
 554 robust GAMs, we fixed the sample size at $n_0 = 200$, and for robust GBMs, robust RFs, and robust ANNs,

555 we increased the sample size from 200 to 1000 by an increment of 200; (2) For the robust GAMs, we fixed
 556 the sample size at $n_0 = 1000$; for the proposed robust algorithms, we increased the sample size from 1000
 557 to 7000 by an increment of 2000. Specifically, we used two different error distributions $P = N(0, 100)$ and
 558 $P = Laplace(0, \sqrt{50})$, while fixing the proportion of outliers at $p_o = 0.15$. The covariates were continuous
 559 variables ($\mathbf{X}_i \sim N_{10}(0, 1)$).

Functions $b_0(\mathbf{X}_i)$ and $\tau_0(\mathbf{X}_i)$ in the response surface were

$$b_0(\mathbf{X}_i) = 100 + 4X_{i1} + X_{i2} - 3X_{i3},$$

$$\tau_0(\mathbf{X}_i) = 6\sin(2X_{i1}) + 3X_{i2} + X_{i3} + 9\tanh(0.5X_{i4}) + 3X_{i5},$$

560 where the true treatment effect function was an additive model of covariates. We reported the MSE of the
 561 CATE estimates graphically in Figure B.1.

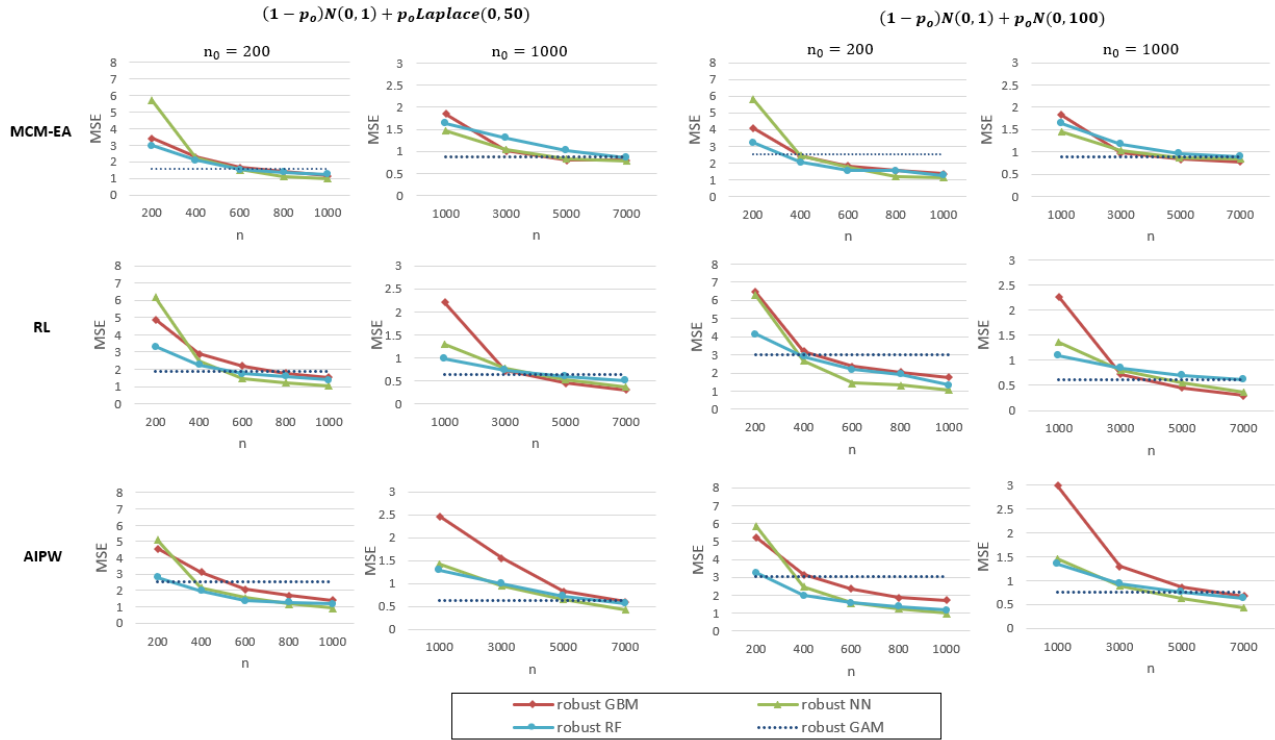


Figure B.1: Simulation results of Simulation S - MSE of different methods under different sample sizes. The robust GBMs were indicated by red solid line, the robust RFs were indicated by blue solid line, the robust ANNs were indicated by green solid line. The robust GAMs were indicated by blue dotted line. In the first and third columns of figures, the sample size of robust GAMs methods was $n_0 = 200$; in the second the fourth columns of figures, the sample size of robust GAMs methods was $n_0 = 1000$.

562 Figure B.1 showed that machine-learning algorithms' performance improved with the sample size.

Table B.1: Simulation Results of Simulation S ($n_0 = 200$)

		MCM-EA									
		$Laplace(0, \sqrt{50})$					$N(0, 100)$				
	n	200	400	600	800	1000	200	400	600	800	1000
MSE	robust GBM	3.43	2.28	1.66	1.39	1.14	4.08	2.43	1.80	1.55	1.37
	GBM	19.96	13.87	10.95	8.99	7.69	21.64	14.18	11.33	9.36	7.33
	robust NN	5.70	2.25	1.54	1.12	1.00	5.84	2.45	1.74	1.21	1.14
	NN	6.50	3.95	3.01	2.60	2.17	6.79	4.09	3.01	2.69	2.23
	robust RF	2.96	2.10	1.53	1.37	1.24	3.21	2.05	1.55	1.54	1.25
	RF	11.12	9.94	8.77	7.94	7.75	10.05	9.37	8.33	8.38	7.23
	robust GAM	1.54					2.54				
	n	200	400	600	800	1000	200	400	600	800	1000
MAE	robust GBM	1.44	1.32	0.99	0.90	0.80	1.57	1.21	1.03	0.94	0.87
	GBM	3.40	3.56	2.49	2.23	2.05	3.62	2.91	2.58	2.34	2.06
	robust NN	1.86	1.14	0.93	0.80	0.75	1.89	1.19	0.98	0.83	0.79
	NN	1.99	1.53	1.33	1.23	1.14	2.04	1.57	1.34	1.26	1.14
	robust RF	1.27	0.99	0.90	0.84	0.79	1.32	1.03	0.89	0.89	0.80
	RF	2.02	3.56	1.80	1.73	1.70	2.08	4.08	1.89	1.83	1.75
	robust GAM	0.83					1.13				
		RL									
		$Laplace(0, \sqrt{50})$					$N(0, 100)$				
	n	200	400	600	800	1000	200	400	600	800	1000
MSE	robust GBM	4.87	2.88	2.19	1.77	1.52	6.46	3.19	2.36	2.05	1.77
	GBM	36.93	22.98	17.28	14.28	11.88	38.67	24.42	17.34	16.77	11.55
	robust NN	6.19	2.48	1.48	1.23	1.04	6.28	2.67	1.44	1.33	1.07
	NN	6.78	4.28	3.45	2.87	2.60	7.30	4.39	3.51	3.10	2.62
	robust RF	3.32	2.24	1.76	1.59	1.39	4.14	2.92	2.20	1.92	1.34
	RF	49.57	49.48	9.36	43.16	47.60	133.48	92.12	40.54	68.37	50.74
	robust GAM	1.87					3.03				
	n	200	400	600	800	1000	200	400	600	800	1000
MAE	robust GBM	1.71	1.32	1.07	1.01	0.93	1.95	1.38	1.18	1.08	1.00
	GBM	4.56	3.56	2.50	2.73	2.48	4.78	3.71	3.16	2.97	2.53
	robust NN	1.94	1.19	0.91	0.83	0.77	1.96	1.23	0.92	0.87	0.78
	NN	2.03	1.60	1.43	1.31	1.24	2.12	1.63	1.44	1.36	1.26
	robust RF	1.27	0.99	0.86	0.81	0.72	1.36	1.03	0.87	0.85	0.77
	RF	3.61	3.56	1.81	3.57	3.67	4.61	4.08	3.64	4.35	3.89
	robust GAM	0.79					1.10				
		AIPW									
		$Laplace(0, \sqrt{50})$					$N(0, 100)$				
	n	200	400	600	800	1000	200	400	600	800	1000
MSE	robust GBM	4.55	3.13	2.09	1.70	1.41	5.23	3.15	2.36	1.87	1.73
	GBM	19.10	14.01	11.75	8.61	7.32	20.36	13.40	12.07	9.90	7.52
	robust NN	5.12	2.17	1.57	1.18	0.94	5.88	2.48	1.58	1.24	0.99
	NN	1.97	3.77	2.91	2.46	2.23	6.86	4.24	3.14	2.57	2.34
	robust RF	2.80	1.98	1.36	1.29	1.18	3.25	1.98	1.56	1.37	1.18
	RF	10.57	9.66	9.36	8.58	8.33	9.98	8.81	9.21	9.86	8.66
	robust GAM	2.52					3.04				
	n	200	400	600	800	1000	200	400	600	800	1000
MAE	robust GBM	1.65	1.33	1.07	0.94	0.84	1.77	1.33	1.13	0.99	0.92
	GBM	3.35	2.78	2.50	2.13	1.98	3.50	2.81	2.59	2.31	2.05
	robust NN	1.76	1.11	0.93	0.81	0.73	1.89	1.19	0.96	0.84	0.76
	NN	1.97	1.50	1.31	1.20	1.15	2.05	1.59	1.37	1.23	1.17
	robust RF	1.21	0.99	0.86	0.82	0.78	1.32	1.01	0.89	0.84	0.77
	RF	1.98	1.89	1.81	1.73	1.68	2.09	1.94	1.92	1.87	1.76
	robust GAM	0.99					1.11				

Table B.2: Simulation Results of Simulation S ($n_0 = 1000$)

		MCM-EA							
		$Laplace(0, \sqrt{50})$				$N(0, 100)$			
n		1000	3000	5000	7000	1000	3000	5000	7000
MSE	robust GBM	1.85	1.01	0.80	0.80	1.83	0.97	0.83	0.77
	GBM	11.22	2.71	1.99	1.55	11.10	2.83	2.03	1.59
	robust NN	1.48	1.04	0.84	0.78	1.46	1.03	0.86	0.84
	NN	2.76	2.61	2.18	1.88	2.74	2.76	2.20	1.95
	robust RF	1.63	1.31	1.01	0.84	1.62	1.17	0.96	0.88
	RF	5.12	5.00	4.28	4.13	5.26	4.85	4.11	3.81
	robust GAM	0.87				0.88			
n		1000	3000	5000	7000	1000	3000	5000	7000
MAE	robust GBM	1.06	0.75	0.67	0.61	1.06	0.74	0.68	0.68
	GBM	2.56	1.23	1.05	0.93	2.58	1.28	1.07	0.94
	robust NN	0.94	0.77	0.69	0.62	0.93	0.77	0.70	0.72
	NN	1.28	1.23	1.13	1.04	1.28	1.27	1.13	1.07
	robust RF	0.94	0.84	0.72	0.67	0.92	0.79	0.71	0.68
	RF	1.51	1.48	1.40	1.36	1.58	1.53	1.44	1.37
	robust GAM	0.60				0.63			
		RL							
		$Laplace(0, \sqrt{50})$				$N(0, 100)$			
n		1000	3000	5000	7000	1000	3000	5000	7000
MSE	robust GBM	2.21	0.72	0.45	0.30	2.27	0.72	0.45	0.30
	GBM	29.31	4.55	3.01	2.14	27.49	5.02	3.04	1.80
	robust NN	1.29	0.77	0.53	0.36	1.36	0.80	0.55	0.37
	NN	3.58	3.26	2.58	1.90	3.66	3.51	2.55	1.93
	robust RF	0.98	0.73	0.60	0.50	1.09	0.85	0.70	0.62
	RF	107.18	91.18	91.12	72.19	127.63	91.68	81.65	70.37
	robust GAM	0.64				0.61			
n		1000	3000	5000	7000	1000	3000	5000	7000
MAE	robust GBM	1.14	0.64	0.50	0.40	1.15	0.63	0.49	0.40
	GBM	3.80	1.51	1.20	0.97	3.75	1.59	1.25	0.96
	robust NN	0.88	0.67	0.55	0.46	0.90	0.68	0.56	0.46
	NN	1.45	1.37	1.22	1.04	1.47	1.42	1.22	1.06
	robust RF	0.71	0.62	0.54	0.46	0.70	0.60	0.51	0.47
	RF	5.44	4.89	4.61	4.04	5.73	4.96	4.65	4.19
	robust GAM	0.56				0.53			
		AIPW							
		$Laplace(0, \sqrt{50})$				$N(0, 100)$			
n		1000	3000	5000	7000	1000	3000	5000	7000
MSE	robust GBM	2.46	1.55	0.82	0.60	2.99	1.29	1.07	0.98
	GBM	14.43	3.98	2.47	1.54	15.25	3.51	4.17	1.88
	robust NN	1.43	0.94	0.66	0.43	1.46	0.89	0.63	0.43
	NN	3.83	3.27	2.54	2.04	3.61	3.15	2.67	2.06
	robust RF	1.28	1.00	0.73	0.57	1.35	0.93	0.75	0.63
	RF	7.80	7.76	7.51	6.20	7.97	7.39	7.09	6.72
	robust GAM	0.63				0.75			
n		1000	3000	5000	7000	1000	3000	5000	7000
MAE	robust GBM	1.48	0.77	0.59	0.48	1.15	0.76	0.61	0.48
	GBM	2.82	1.37	1.10	0.85	2.87	1.37	1.11	0.85
	robust NN	0.92	0.73	0.61	0.49	0.93	0.72	0.60	0.49
	NN	1.46	1.35	1.20	1.07	1.46	1.34	1.23	1.07
	robust RF	0.81	0.71	0.59	0.47	0.83	0.69	0.60	0.53
	RF	1.65	1.64	1.56	1.45	1.69	1.69	1.59	1.55
	robust GAM	0.52				0.53			

Table B.3: Simulation Results (Coverage Probabilities) of Simulation 1

	MCM-EA													
	$Laplace(0, \sqrt{50})$							$N(0, 100)$						
p_o	0.00	0.05	0.10	0.15	0.20	0.30	0.50	0.00	0.05	0.10	0.15	0.20	0.30	0.50
Robust GBM	0.95	0.94	0.91	0.93	0.93	0.95	0.97	0.95	0.94	0.95	0.94	0.94	0.98	0.97
GBM	0.95	0.93	0.96	0.96	0.94	0.97	0.96	0.95	0.96	0.97	0.99	0.99	0.91	0.95
Robust NN	0.95	0.94	0.96	0.92	0.94	0.99	0.98	0.95	0.92	0.98	0.92	0.95	0.98	0.93
NN	0.96	0.76	0.87	0.47	0.83	0.79	0.89	0.96	0.39	0.43	0.27	0.32	0.35	0.29
Robust RF	0.94	0.96	0.97	0.94	0.92	0.93	0.98	0.94	0.95	0.94	0.93	0.92	0.96	0.98
RF	0.96	0.96	0.98	0.97	0.97	0.89	0.96	0.96	0.90	0.92	0.92	0.93	0.89	0.87
Robust GAM	0.23	0.38	0.49	0.54	0.57	0.66	0.74	0.23	0.39	0.48	0.54	0.59	0.66	0.76
Robust QL	0.47	0.49	0.49	0.52	0.53	0.53	0.00	0.47	0.49	0.50	0.51	0.53	0.33	0.00
	RL													
	$Laplace(0, \sqrt{50})$							$N(0, 100)$						
p_o	0.00	0.05	0.10	0.15	0.20	0.30	0.50	0.00	0.05	0.10	0.15	0.20	0.30	0.50
Robust GBM	0.95	0.94	0.95	0.96	0.95	0.97	0.97	0.95	0.95	0.96	0.94	0.96	0.91	0.98
GBM	0.93	0.97	0.98	0.98	0.97	0.96	0.95	0.93	0.99	0.98	0.99	1.00	1.00	0.99
Robust NN	0.94	0.95	0.93	0.96	0.92	0.93	0.96	0.94	0.95	0.96	0.93	0.97	0.91	0.98
NN	0.96	0.82	0.94	0.95	0.88	0.85	0.91	0.96	0.94	0.93	0.94	0.85	0.82	0.36
Robust RF	0.95	0.96	0.97	0.94	0.98	0.95	0.94	0.95	0.92	0.91	0.90	0.87	0.82	0.72
RF	0.94	0.89	0.98	0.97	0.87	0.93	0.94	0.94	0.82	0.93	0.89	0.95	0.89	0.86
Robust GAM	0.27	0.48	0.57	0.61	0.65	0.71	0.80	0.27	0.49	0.58	0.64	0.65	0.72	0.81
Robust QL	0.47	0.49	0.49	0.52	0.53	0.53	0.00	0.47	0.49	0.50	0.51	0.53	0.33	0.00
	AIPW													
	$Laplace(0, \sqrt{50})$							$N(0, 100)$						
p_o	0.00	0.05	0.10	0.15	0.20	0.30	0.50	0.00	0.05	0.10	0.15	0.20	0.30	0.50
Robust GBM	0.96	0.93	0.92	0.91	0.90	0.89	0.90	0.96	0.94	0.93	0.92	0.90	0.98	0.93
GBM	0.96	0.92	0.98	0.97	0.95	0.95	0.98	0.96	0.97	0.96	0.99	0.97	0.90	0.91
Robust NN	0.94	0.92	0.95	0.93	0.92	0.96	0.98	0.94	0.98	0.96	0.93	0.95	0.93	0.98
NN	0.95	0.74	0.89	0.96	0.80	0.73	0.88	0.95	0.44	0.88	0.84	0.87	0.83	0.78
Robust RF	0.93	0.94	0.98	0.91	0.97	0.96	0.98	0.93	0.96	0.97	0.94	0.95	0.96	0.95
RF	0.94	0.98	0.97	0.93	0.93	0.82	0.96	0.94	0.94	0.91	0.87	0.95	0.86	0.82
Robust GAM	0.54	0.57	0.59	0.61	0.62	0.64	0.70	0.54	0.58	0.59	0.61	0.64	0.66	0.73
Robust QL	0.47	0.49	0.49	0.52	0.53	0.53	0.00	0.47	0.49	0.50	0.51	0.53	0.33	0.00

Table B.4: Tuning parameters of considered methods in simulation

Method	Parameter	Value
RF-based algorithms	Number of trees	50
	Fraction of features used in splitting	0.8
	Minimum node size	3
Boosting-based algorithms	Number of trees	1000
	Depth of trees	2
	Learning rate	0.1
Robust ANN	Number of hidden layers	2
	Number of neurons in hidden layers	p and $p/2$
	Adam optimization	$\alpha = 0.001, \beta_1 = 0.9, \beta_2 = 0.999$
	L_1 regularization ($p = 100, 2000$)	0.1, if $p = 100$; 0.02, if $p = 2000$.
Robust GAM and QL	Number of neurons in hidden layers ($p = 2000$)	$p/10$ and $p/40$
	Number of knots	$\sqrt{n}/2$
	Number of degree	3
	γ in SCAD	3.7