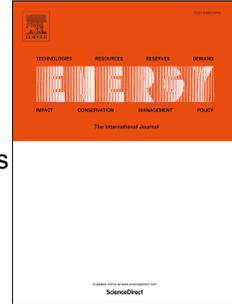


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Inventory control assessment for small scale sCO₂ heat to power conversion systems

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Highlights

- Development of inventory system model considering finite capacity tanks
- Effects of inventory tanks main parameters on power block performance
- Design and analysis of Inventory PI controller
- Inventory control able to optimise system performance at part-load conditions

Keywords

Supercritical CO₂ power cycles; waste heat recovery; inventory control; transient analysis; sCO₂ power cycle controls; control design

Abstract

1 The control of the main cycle parameters in supercritical CO₂ (sCO₂) systems during off-design and transient
2 operation is crucial for advancing their technological readiness level. In smaller scale power units (<0.5-5 MW),
3 costs and complexity constraints limit the number of auxiliary components in the power loop, making the design
4 of the control system even more challenging.

5 Among the possible strategies, the regulation of system inventory, which consists in varying the CO₂ fluid mass
6 in the power loop to achieve a given control target, represents a promising alternative. Such technique however
7 poses several technical challenges that are still to be fully understood. To fill this gap, this work presents a
8 comprehensive steady-state and transient analysis of inventory control systems, referring in particular to a 50 kW
9 sCO₂ test facility being commissioned at Brunel University.

10 Stability implications (e.g. pressure gradients in the loop) and the effects of variable inventory tank size are
11 discussed. Tank volumes 3 times higher than the one of the power loop (including the receiver) can lead to a
12 higher controllability range ($\pm 30\%$ of the nominal turbine inlet temperature) and an extended availability of the
13 control action (slower tank discharge). A PI controller is also designed to regulate the turbine inlet temperature
14 around the target of 465°C in response to waste heat variations.

Nomenclature:*Symbols:*

ξ	Pressure loss coefficient	[-]
ρ	Density	[kg/m ³]
σ	Surface tension	[Pa]
ν	Dynamic viscosity	[m ² /s]
dx	Displacement	[m]
f	Fanning friction factor	[-]
h	Heat transfer coefficient	[W/(m ² K)]
m	Mass	[kg]
\dot{m}	Mass flow rate	[kg/s]
p	Pressure	[bar]
t	Time	[s]
v	Velocity	[m/s]
A	Area	[m ²]
C_1	Pressure drop calibration coefficient	[-]
C_d	Discharge coefficient	[-]
D	Diameter	[m]
H	Specific enthalpy	[kJ/kg]
L	Length	[m]
Nu	Nusselt number	[-]
Pr	Prandtl number	[-]
R	Radius	[m]
Ra	Surface roughness	[μ m]
Re	Reynolds number	[-]
T	Temperature	[°C]

subscripts:

b	bubble
wl	wall
wf	working fluid
0	total
∞	boundaries

Acronyms:

CBV	Compressor By-pass Valve
CGT	Compressor-Generator-Turbine
EXTV	Inventory Extraction Valve
GWP	Global Warming Potential
HP	High Pressure
INJV	Inventory Injection Valve
LP	Low Pressure
ODP	Ozone Depletion Potential
PCHE	Printed Circuit Heat Exchanger
PHE	Plate Heat Exchanger
PHX	Primary heat exchanger
PI	Proportional-Integral
sCO ₂	Supercritical carbon dioxide
SS 316L	Stainless steel 316L
TBV	Turbine By-pass Valve
WHR	Waste Heat Recovery

16 1. Introduction

17 Recently, power cycles with carbon dioxide in the supercritical state (sCO₂) as the working fluid have received a
18 strong interest by academia and industry [1]. Compared to state-of-the-art technologies such as steam and organic
19 Rankine systems, sCO₂ systems have the following advantages: global conversion efficiency up to 10% higher
20 (compared to other technologies) thanks to reduced compression work near the critical point (33.0 °C, 74bar);
21 better heat utilisation (exergy efficiency) due to absence of phase change during the heat recovery process; less
22 cycle temperature limitations; higher power flexibility, along with smaller footprint, better water utilisation and
23 higher thermal stability. Furthermore, CO₂ is an environmentally friendly working fluid, having unitary Global
24 Warming Potential (GWP) and zero Ozone Depletion Potential (ODP).

25 The interest in sCO₂ technology goes beyond high temperature waste heat to power conversion [2] and covers
26 the whole spectrum of power generation, from fossil fuel to nuclear and renewable applications. The high
27 efficiency potential and extremely compact turbomachinery make it also an attractive alternative propulsion
28 technology [3].

29 Research on sCO₂ power systems is currently focused on thermodynamic and techno-economic analyses to
30 identify the optimal cycle layouts both using pure CO₂ or blends (mixtures of CO₂ and other fluids, often called
31 dopants [4]) with additional focus areas related to investigations of performance at component level, i.e.
32 turbomachinery and heat exchangers as well as at fundamental scale, i.e. flow topology in converging-diverging
33 nozzles or heat transfer [1].

34 Studies on off-design and transient operating regimes of sCO₂ power systems are limited due to low availability
35 of experimental datasets from the small pool of test facilities whose total world count is below 15 [2]. These
36 reasons also reflect the scarce literature on the control of sCO₂ power cycles. In general, the sCO₂ control
37 narratives are derived from closed loop Brayton cycle experiences with helium or argon [5]. However, the highly
38 non-ideal nature of sCO₂ differentiates it from other Brayton cycles and introduces additional control
39 considerations close to the critical point. For this reason, the majority of the works are focused on regulating the
40 inlet conditions of the compressor and turbine to ensure the optimal and stable operation of the system.

41 Deviation in inlet density conditions can cause significant changes to flow conditions in the compressor leading
42 to overall cycle performance and controllability issues. To operate the compressor in an optimal and safe
43 operating region, different methods have been proposed, such as regulation of the heat sink conditions [6] or the
44 action on the flow split ratio between compressor and recompressor [7]. For the turbine, the use of throttling or
45 by-pass valves is being considered [8,9].

46 Alongside turbomachinery bypass and throttling, inventory control is a key strategy to modulate the power output
47 of sCO₂ power systems to enhance their flexibility [9], i.e. their ability to promptly and efficiently adapt to
48 variations in operating conditions imposed by the heat source (e.g. industrial manufacturing process), the heat
49 sink (environmental factors) or the grid (demand variability, volatility of renewable energy sources in the power
50 mix).

51 Such advantages have been demonstrated by [9,10], whose research concerned the development of mixed control
52 strategies involving a conjunct use of by-pass, throttling and inventory control to follow the generator load of a

53 sCO₂ recompression power unit for nuclear applications. The author in [11] presented different inventory control
54 schemes and compared them in terms of response time and effectiveness. This included the adoption of a single
55 inventory tank connected to both the low- and high-pressure side of the circuit or the use of multiple tanks
56 connected to different charging/discharging points. However, stability implications (e.g. pressure gradients in the
57 loop) due to the withdrawals/additions of CO₂ and the implications of having finite storage capacity in the
58 inventory storage tanks have not been adequately considered in the literature.

59 To fill the literature gap, this research advances the state of the art through a numerical assessment of the effects
60 of inventory control on the dynamic response of a small-scale sCO₂ heat to power system. A unique feature of
61 this study is the modelling methodology that combines the dynamics of the sCO₂ heat to power unit (calibrated
62 against real equipment data) with those of the inventory control system using finite capacity tanks. Insights on the
63 dynamic behaviour of the inventory system to support the design and thermal management of the CO₂ storage
64 tanks are provided. A Proportional Integral (PI) inventory controller has been designed to regulate the turbine
65 inlet temperature following variations of the waste heat loads. Its response and effect on system performance and
66 main cycle parameters are then analysed and discussed.

67 2. System description

68 The modelled sCO₂ system refers to a plug and play 50 kWe sCO₂ unit for Waste Heat Recovery (WHR)
69 applications available at Brunel University London. The sCO₂ facility in Figure 1 is based on a simple regenerative
70 Joule-Brayton cycle (Figure 1.a) and it is equipped with three heat exchanger technologies: a micro-tube gas/sCO₂
71 heat exchanger for direct heat recovery from the heat source; a Printed Circuit Heat Exchanger (PCHE) employed
72 as recuperator; and a Plate Heat Exchanger (PHE) as gas cooler. PCHEs are commonly used in the oil and gas
73 sector because of their reliability in operating at high pressures and temperatures [12], For this reason, they have
74 also been adopted in sCO₂ power applications [13] as recuperators and also gas coolers [14]. For the Brunel test
75 facility a plate heat exchanger (PHE) has been selected as gas cooler to reduce cost. This is of paramount
76 importance in WHR applications.

77 Other components include a radial turbine, a radial compressor and a synchronous brushless generator/motor
78 mounted on the same single shaft, and motorised compressor and turbine by-pass globe valves (CBV and TBV
79 respectively shown in Figures 1.a and 1.c) to control the system at nominal, startup, shutdown and emergency
80 operations. The CBV valve is located between the compressor outlet and gas cooler inlet while TBV is placed
81 between the turbine inlet and outlet (Figure 1.c). All such components are packaged in a standard 20 ft container
82 (Figure 1.c) except for the micro-tube heat exchanger, also known as primary heater, which is located along the
83 exhaust line of the Process Air Heater (Figure 1.b). The Process Air Heater simulates the industrial waste heat
84 source and provides flue gases up to 1.0 kg/s and temperatures up to 800 °C. The facility is also equipped with a
85 500 kW dry cooler system that rejects heat from the gas cooler to the ambient. Variable speed drives for the water
86 pump and fans of the dry cooler allow variation of heat removal from the gas cooler.

87 A data acquisition and control system has been also installed (left-hand side of Figure 1.c) to enable remote control
88 and monitoring of the unit. Two 10-meter pipes connect the loop packaged in the container to the primary heater,
89 which has been specifically designed to enhance the gas/sCO₂ heat transfer without causing an excessive pressure
90 drop on the flue gas side. The sCO₂ test facility has been designed for small scale waste heat recovery applications

91 (with an estimated net power output in the range of 50-75 kWe at design conditions). At these operating
 92 conditions, the turbomachinery impellers become very small and high speed which impacts negatively on their
 93 efficiency. Another challenge of small-scale sCO₂ systems is the cost per kilowatt installed. Their capital
 94 expenditure (CAPEX) is not linear with the power size especially in the case of the heat exchangers, which
 95 typically are responsible for the majority of the equipment budget [14].

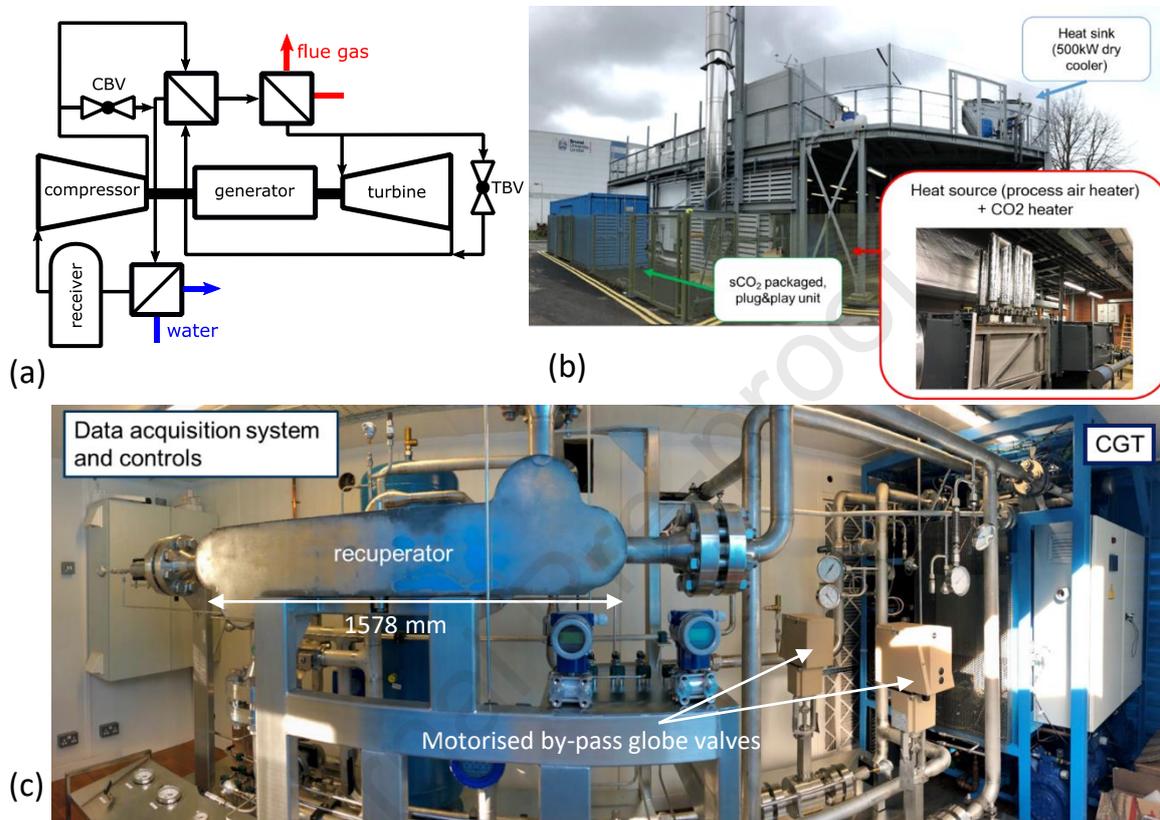


Figure 1 – sCO₂ facility at Brunel University London: (a) system layout, (b) facility overview, (c) sCO₂ loop inside the blue container shown in (b).

96 Unless costs are significantly reduced, sCO₂ technology is primarily competitive for applications beyond 1 MWe
 97 power output and heat-source temperatures above 350°C. Despite the low power output, this pilot scale research
 98 is expected to advance the knowledge in the field of sCO₂ power research and further support the uptake of sCO₂
 99 technology. Furthermore, as reported in [17] sCO₂ turbomachinery will still have to be radial as long as the system
 100 power output stays below 12 MWe. For these reasons, the analysis reported in the following sections should be
 101 transposable to the design and operation of full-scale sCO₂ power systems. Further details on Brunel's high-
 102 temperature heat to power conversion (HT2C) facility are available in [18]. Figure 2 shows a simplified P&ID of
 103 the facility detailing in particular the location of pressure, temperature and mass flow rate sensors in the unit.
 104 Tables 1 and 2 detail the sensors installed and the estimated uncertainty of efficiencies and power for each system
 105 component..

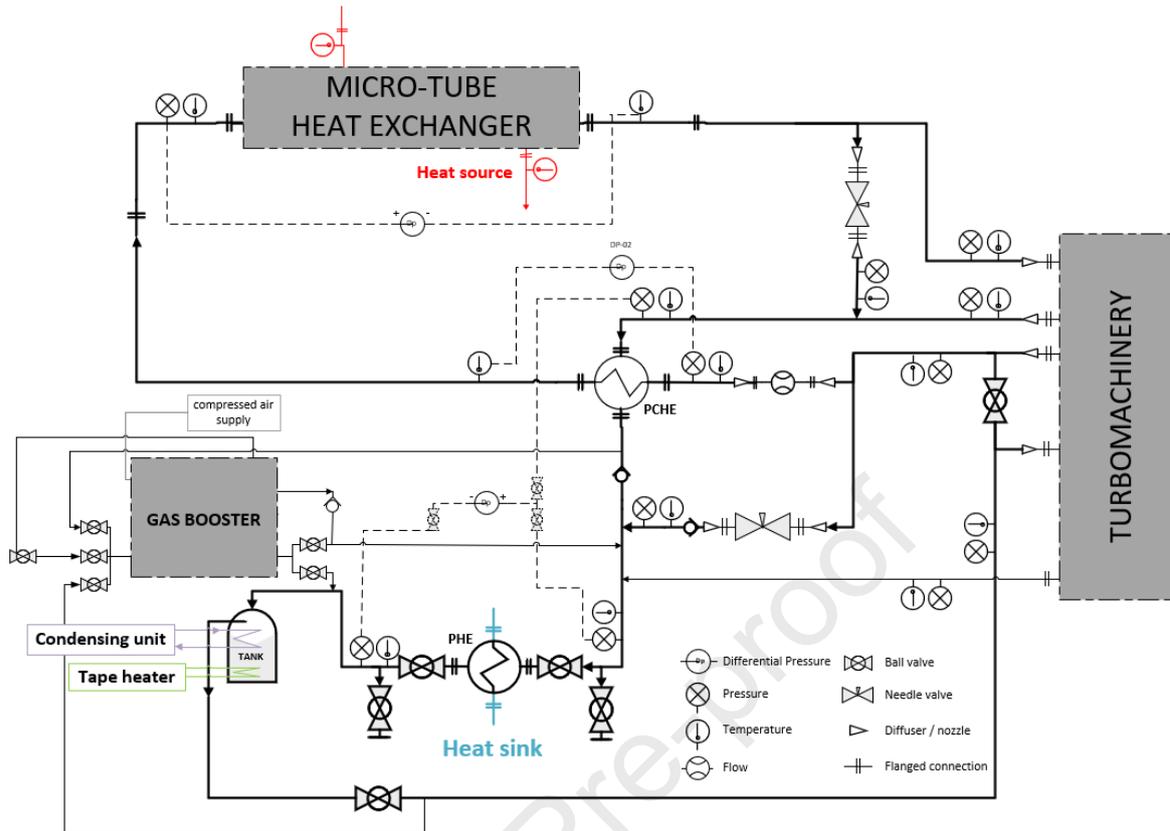


Figure 2 – Simplified P&ID of the sCO₂ facility at Brunel University London (Adapted from [16])

Table 1 – Summary of transducers accuracies [16].

Accuracy	High	Standard
High pressure transducers	0.17 bar	0.52 bar
Low pressure transducers	0.10 bar	0.34 bar
Temperature transducers (RTD)	0.03K	0.06K
DP transducers	1.9mbar	
Mass flow rate (Coriolis)	0.35% of measured value	

Table 2 – Estimated measurement uncertainty at design conditions [16].

Uncertainty	Power	Efficiency
Compressor	2.66%	3.32%
Turbine	0.43%	0.47%
Heater	0.36%	
Recuperator (cold/hot side)	0.36%/0.35%	
Cooler	0.61%	

106

107 3. Modelling methodology

108 The model of the sCO₂ heat to power conversion system has been developed in the commercial software GT-
 109 SUITE™. This tool is based on a one-dimensional (1D) formulation of Navier-Stokes equations and on a staggered

110 grid spatial discretization [19]. Each component can be independently modelled through input data relating to
 111 geometrical features as well as their performance.

112 The components modelled as equivalent 1D objects are heat exchangers and pipes while the turbomachines, valves
 113 and the receiver are treated with a lumped approach. The 1D models discretise the components into a series of
 114 capacities such that manifolds are represented by single volumes while pipes are divided into one or more volumes.
 115 These volumes are connected by boundaries. The scalar variables (pressure, temperature, density, internal energy,
 116 enthalpy, etc.) are assumed to be uniform in each volume. On the other hand, vector variables (mass flux, velocity,
 117 mass fraction fluxes, etc.) are calculated for each boundary [19]. Each capacity considers the algebraic sum of all
 118 the incoming and outgoing mass flow rate contributions occurring at the boundaries (B), as per the continuity
 119 equation (1).

$$120 \quad \frac{dm}{dt} = \sum_{i=1}^B \dot{m}_i \quad (1)$$

121 The pressure dynamics in the system is calculated through the momentum equation (2), which neglects body forces
 122 and considers the algebraic sum of momentums through the boundaries, pressure forces and dissipations due to
 123 friction and pressure drops [19]. In pipes, the latter two terms are respectively related to distributed (i.e. due to
 124 surface roughness) or concentrated (i.e. due to bends) pressure losses.

$$125 \quad \frac{d(\dot{m}v)}{dt} = \frac{1}{dx} \left(dpA + \sum_{i=1}^B (\dot{m}v)_i - 4f \frac{\rho v |v|}{2} \frac{dxA}{D} - \xi \left(\frac{\rho v |v|}{2} \right) A \right) \quad (2)$$

127 The energy equation (3) is expressed in terms of total enthalpy. This formulation is required for the further implicit
 128 integration scheme employed by the solver for the analysis of energy systems whereas resolving fast dynamics
 129 (e.g. indicating pressure in positive displacement machines) is not the end goal [19]. Neglecting variations of
 130 potential energy, for a given capacity, the rate of change of total enthalpy depends on the volume capacity
 131 variations, the enthalpy fluxes and the heat transfer phenomena. The solution of the energy equation requires the
 132 computation of the local heat transfer coefficient through calibrated heat transfer correlations.

$$133 \quad \frac{d(\rho H_0 V)}{dt} = \sum_{i=1}^B (\dot{m} H_0)_i + V \frac{dp}{dt} - hA(T_{wf} - T_{wl}) \quad (3)$$

134 3.1. Heat exchangers

135 The properties of the equivalent 1D channels of heat exchangers are defined starting from the geometrical inputs
 136 of the component. The performance data, which refer to different operating conditions of the heat exchangers, are
 137 used to compute the best fitting coefficients of the Nusselt-Reynolds (Nu-Re) correlations along the equivalent
 138 1D networks [19]. Such data are provided by the manufacturers or calculated from more complex models (e.g. 3D
 139 CFD).

140 Table 3 summarises the geometrical features of the PCHE recuperator as well as the number of sub-volumes in
 141 which the different heat exchangers have been discretized. Their time constants have been also reported, calculated
 142 as the ratio between the heat exchanger mass multiplied by the specific heat capacity (m^*cp) of the material and

143 conductance (UA) of the heat exchanger. It can be seen that the primary heater (PHX) has the lowest thermal
 144 inertia and the recuperator the highest due to its much higher thermal mass of the material used for its manufacture.
 145 The results of the regression analyses carried out to calibrate the several heat exchangers are detailed in Table 4,
 146 which compares the Re-Nu curve interpolation of the different data provided by the manufacturer against the ones
 147 obtained by using the Gnieliski [20] and Dittus-Boelter [21] heat transfer correlations. It can be observed that the
 148 Gnieliski correlation provides better predictions of the manufacturer data. For this reason, in the absence of data
 149 on heat exchanger performance from experimental tests, the Gnieliski correlation for the calculation of the heat
 150 transfer coefficients was employed in this study [22]. The full modelling methodology is available at [22].

151

Table 3 – Heat exchangers specifics.

Flow parameters		PHX	PCHE	PHE
Nominal heat duty	kW	388.3	630.0	237.5
Nominal UA value	kW/K	1.3	20.3	16.8
Hot side pressure drop	kPa	1.1	128.0	8.7
Cold side pressure drop	kPa	64.0	120.0	89.1
Geometrical features				
Heat transfer surface	m ²	3.92	12.00	6.21
Hydraulic diameter	mm	2.00	1.22	
Dry weight	kg	305.0	305.0	52.4
Material	-	Inconel 718	SS 316L	
Model details		HX	PCHE	PHE
Time constant	s	1.55	7.25	2.38
Channel sub-volumes	#	25	50	50

152

153 The pressure drops are computed using a modified version of the Colebrook relationship in Equation (4). In this
 154 expression, the Fanning factor is calculated using the explicit approximation of the Colebrook equation proposed
 155 by Serghides [23], which is valid for the turbulent regime ($Re_D > 2100$). The quantities C_2 and C_3 , which can be
 156 calculated using Equations (5) and (6), account for the roughness of the heat exchanger channels R_a . The term C_1
 157 is the calibration coefficient used to adapt the simulation results to the performance data provided by the heat
 158 exchanger manufacturer.

159 Even though this modelling methodology is common to all the three heat exchangers considered, the gas cooler
 160 requires an additional correlation to account for possible condensation of CO_2 . In this case, to predict the phase
 161 change, the formation of vapor bubbles or liquid droplets is addressed by evaluating the fluid density in each sub
 162 volume, while the two-phase area is computed using the vapour Rayleigh-Plesset formulation in Equation (7)
 163 [24].

164

$$f = C_1 \left(\frac{1}{4} \left(4.781 - \frac{(C_2 - 4.781)^2}{C_3 - 2C_2 + 4.781} \right)^{-2} \right) \quad (4)$$

$$C_2 = -2.0 \log_{10} \left(\frac{Ra/D}{3.7} + \frac{12}{Re_D} \right) \quad (5)$$

$$C_3 = -2.0 \log_{10} \left(\frac{Ra/D}{3.7} + \frac{2.51C_2}{Re_D} \right) \quad (6)$$

$$\frac{p_b - p_\infty}{\rho} = R \frac{d^2 R}{dt^2} + \frac{3}{2} \left(\frac{dR}{dt} \right)^2 + \frac{4\nu}{R} \frac{dR}{dt} + \frac{2\sigma}{\rho R} \quad (7)$$

Table 4 - Heat exchanger calibration data (Cal) and comparison with model interpolation (Int), Gnieliski (Gn) and Dittus-Boelter (DB) correlations.

		Re=20000		Re=25000		Re=30000	
		Nu	Err%	Nu	Err%	Nu	Err%
Heater	Cal	73.0	N/A	92.2	N/A	106.8	N/A
	Int	73.4	1.3	92.5	0.3	107.2	0.4
	Gn	75.7	2.7	90.9	1.4	101.9	4.8
	DB	80.1	8.7	96.5	4.4	108.6	1.6
Recuperator	Cal	596.2	N/A	767.6	N/A	876.9	N/A
	Int	596.2	0.0	756.8	1.4	878.1	0.1
	Gn	596.9	0.1	735.6	4.2	886.2	1.0
	DB	629.4	5.3	779.9	1.6	944.7	7.2
Cooler	Cal	371.5	N/A	464.0	N/A	560.1	N/A
	Int	373.4	0.5	454.6	2.1	554.5	1.0
	Gn	376.5	1.3	445.4	4.2	544.7	2.8
	DB	369.1	0.6	437.0	6.2	533.2	5.0

170

171 3.2. Turbomachines

172 The turbomachines have been modelled as lumped components by using performance maps. The performance
 173 maps use the boundary conditions (temperature/pressure and shaft speed) to evaluate the performance of the
 174 machine and outlet conditions. The advantage of modelling the turbomachinery with performance maps is that it
 175 allows faster calculation results as the model is reduced order and also the dynamics of turbomachinery is relatively
 176 faster compared to the heat exchangers and other components with higher volume and high thermal inertia. Their
 177 aerothermal design is detailed in Table 5. Performance maps have been calculated by performing 3D RANS CFD
 178 simulations whose modelling methodology has been discussed in [26,27]. The 3D modelling approach has been
 179 validated through experimental data available from the Sandia National Laboratories [28], with an uncertainty
 180 lower than 5% [26,27]. The inlet boundary conditions of the 3D model are the total pressure and temperature as
 181 well as the flow direction, which is considered normal to the boundary. Outlet average static pressure has been
 182 chosen as outlet boundary condition.

183 The turbine operating and isentropic efficiency maps have been expressed through reduced quantities (pressure
 184 ratio versus reduced mass flow rates and reduced revolution speed) in order to account the variation of turbine
 185 performance on a change of the inlet conditions. Representation of turbine maps can be also found in [22].

186 Table 5: Summary of the turbomachinery aerothermal design.

	Turbine	Compressor
Diameter	72 mm	55 mm
No. of blades (Rotor)	14	7
No. of blades (Nozzle)	17	11
Isentropic efficiency (total-to-static)	70%	76%

187 Although this approach is fine for the turbine, which operates in a region where the CO₂ behaviour can be
 188 considered similar to the one of an ideal gas, this does not hold for the compressor, which operates near the fluid
 189 critical condition. Furthermore, the use of maps based on reduced quantities for the compressor leads to numerical
 190 instabilities when dealing with the inventory control action.

191 Therefore, the compressor map has been condensed to one curve using non-dimensional parameters, following the
 192 approach detailed in [29]. This allowed to solve numerical instabilities following the simulation of the inventory
 193 control action and to better account the effect of variable compressor inlet conditions on its performance. The
 194 inertia of the shaft has been modelled but the electrical machine characteristics have not been covered in scope of
 195 current work. The losses and consumptions of auxiliary equipment for turbomachinery lubrication and cooling
 196 have also been neglected.

197 3.3. Valves and other equipment

198 The valves have been modelled as orifices with variable area. A look-up table provides a series of forward and
 199 reverse discharge coefficients as a function of the lift position of the valve actuator. Such data have been retrieved
 200 by the manufacturer of the needle valves [30], which have been designed to follow an equal percentage
 201 characteristic curve. These discharge coefficients are then used to compute the effective flow area at the throat,
 202 while the pressure ratio across the valves allows to calculate the velocity at the throat. The velocity multiplied by
 203 the fluid density and the throat flow area gives then the mass flow rate passing through the valve. Equation (8)
 204 shows the correlation relating the valve discharge coefficient to the ratio between the actuator lift L and the valve
 205 diameter D [30].

$$206 \quad C_d = 0.0112e^{0.196\frac{L}{D}} \quad (8)$$

207 The 1D modelling approach used to simulate heat exchanger behaviour has been adopted as well for straight pipes
 208 and bends. Bends introduce concentrated pressure drops while pipes have been considered as smooth and
 209 insulated, which means thermal losses are neglected. This assumption is reasonable based on the relatively large
 210 value of pipe diameters used in the Brunel sCO₂ test facility to minimise pressure drop as well as their insulation
 211 with ceramic wool layer wrapped between an inner layer of silica wash treated glass cloth and an outer layer of
 212 grey PTFE coated glass cloth to reduce heat losses.

213 The receiver, situated downstream the gas cooler (Figure 2) to absorb the thermal expansion of the fluid in the
 214 circuit, has been modelled as a container (capacity) with fixed volume. Its volume is 0.165 m^3 and accounts for
 215 almost 50% of the overall system capacity.

216 3.4. Inventory system

217 The inventory control system considers two tanks, modelled as finite volumes, whose value can be set as inputs
 218 to the model. The arrangement of the two tanks is shown in the schematic representation of the system in Figure
 219 3. The inventory tank connected downstream of the compressor (on the high pressure, HP, side of the circuit, point
 220 15 in Figure 3) has always a pressure lower than the one on the discharging point on the circuit (point 2, Figure
 221 3). Such pressure difference between the tank and the loop drives the withdrawal and storage of the working fluid
 222 from the loop to the tank respectively. The variable opening of a valve (namely the extraction valve, EXTV) allows
 223 to regulate the amount of fluid flowing from the loop to the tank. The other inventory tank connected upstream of
 224 the compressor (on the low pressure, LP, side of the circuit, point 1 in Figure 3) enables the injection of additional
 225 CO_2 to the loop. In this case, to drive the fluid injection from the tank to the loop, the tank pressure (point 13,
 226 Figure 3) is higher than the one at the charging point (point 1, Figure 3). Another valve (namely the injection
 227 valve, INJV) can be actuated to regulate the fluid injection into the circuit.

228 Both valves are modelled as orifices as detailed in the previous section. The inventory tank sub-models require as
 229 boundary conditions the tank volume, the initial tank fluid temperature and initial pressure. An initialization
 230 process starts then, based on these three variables, the initial mass of fluid in the tanks at the beginning of the
 231 simulation (point 12 and 14, Figure 3).

232 Figure 3 also shows the general model boundary conditions required for the simulations, which are indicated with
 233 lower case letters. These boundary conditions are the revolution speed of the compressor-generator-turbine unit
 234 along with the inlet temperatures, pressures and mass flow rates of the hot and cold sources. The thermodynamic
 235 properties of the fluids are computed using an interface between the solver and the NIST database [31].

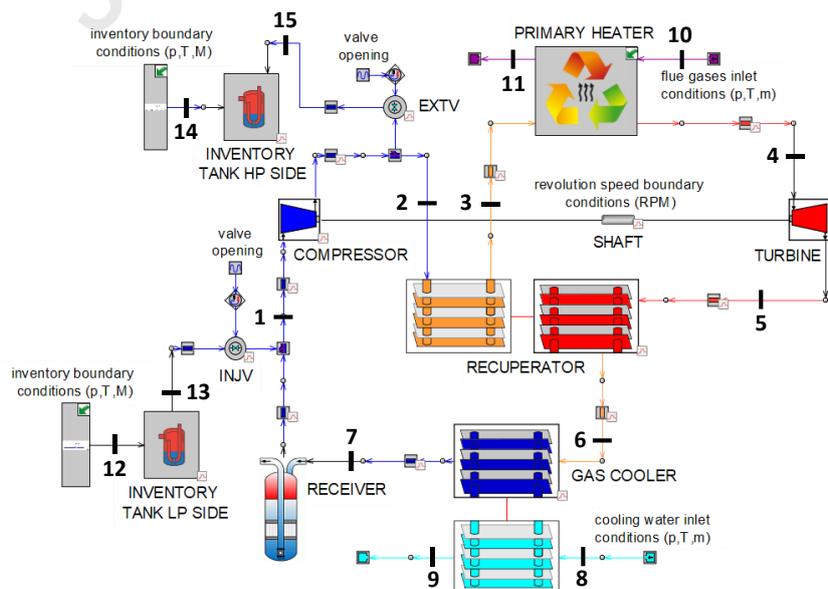


Figure 3 – Model diagram of the full sCO_2 heat to power conversion block including inventory system

236 4. Inventory tank assessment

237 To broadly assess the impact of potential inventory control actions on the main thermodynamic variables of the
 238 tanks and the loop, the injection and the withdrawal of CO₂ into and from the circuit has been simulated assuming
 239 different inventory tank initial pressures and volumes. For each of the simulations the inlet conditions of the heat
 240 source and sink as well as the revolution speed of the turbomachines has been kept constant and equal to the
 241 nominal values (Table 6).

242 A pre-defined opening profile for the EXTV and INJV valves has been set and maintained constant for all the
 243 simulations. Such opening profile has been selected considering a valve opening time required to allow the
 244 achievement of steady-state conditions in the loop and in the tanks after the CO₂ injection/withdrawal actions are
 245 performed.

246 Table 6 – Nominal operating conditions and performance of the sCO₂ heat to power conversion loop.

Supercritical CO ₂		Design	Model I/O
Mass flow rate	kg/s	2.2	Output
Highest pressure	bar	137.5	Output
Lowest pressure	bar	75.0	Output
Highest temperature	°C	465	Output
Lowest temperature	°C	33	Output
Heat source: flue gas			
Mass flow rate	kg/s	1.0	Input
Inlet temperature	°C	650	Input
Inlet pressure	bar	1.0	Input
Cold source: Water			
Mass flow rate	kg/s	1.6	Input
Inlet temperature	°C	15	Input
Inlet pressure	bar	3.0	Input
sCO ₂ unit			
Net thermal power output	kW	75	Output
Overall efficiency	%	24	Output
Turbomachinery speed	RPM	86000	Input
Mass charge	kg	61	Input

247

248 4.1. Inventory tank dynamics

249 Figure 4 shows the inventory tank dynamics following the injection and withdrawal of CO₂ in the loop assuming
 250 an inventory tank capacity equal to the one of power loop (0.243 m³). Each different initial tank pressure is
 251 represented by a different line. The range of pressures analysed varies from 82.5 bar up to 112.5 bar for both
 252 inventory tanks. The initial mass and temperature levels of the CO₂ in the tanks are correlated to the initial pressure
 253 and tank capacity considered (Table 7) across a range between 88-152 kg and 38-45°C respectively.

254

Table 7 – Main simulation parameters of inventory system

Initial conditions at both inventory tanks		Min	Max
Pressure (Model input)	bar	82.5	112.5
Volume (Model input)	m ³	0.073	0.729
Temperature (Model output)	°C	38	45
Mass (Model output)	kg	88	152

255

256 Figure 4.a-c shows the pressure, temperature and mass transient profiles of the inventory tank connected to the
 257 low-pressure side of the system after the INJV valve opening. During the 50s transient, the CO₂ stored in the tank
 258 is injected into the loop, causing an expansion and thus cooling the gas contained in the tank. The temperature
 259 does not fall below the critical point, eliminating the risk of condensation (Figure 4.b). However, more detailed
 260 numerical simulations or experimental analyses may be required to assess local heat transfer phenomena and
 261 potential risks of blowdown, at least in the most extreme cases where the pressure of the CO₂ goes from 112.5 bar
 262 down to 89 bar with a resulting temperature drop of 8°C (Figures 4.b and 4.c).

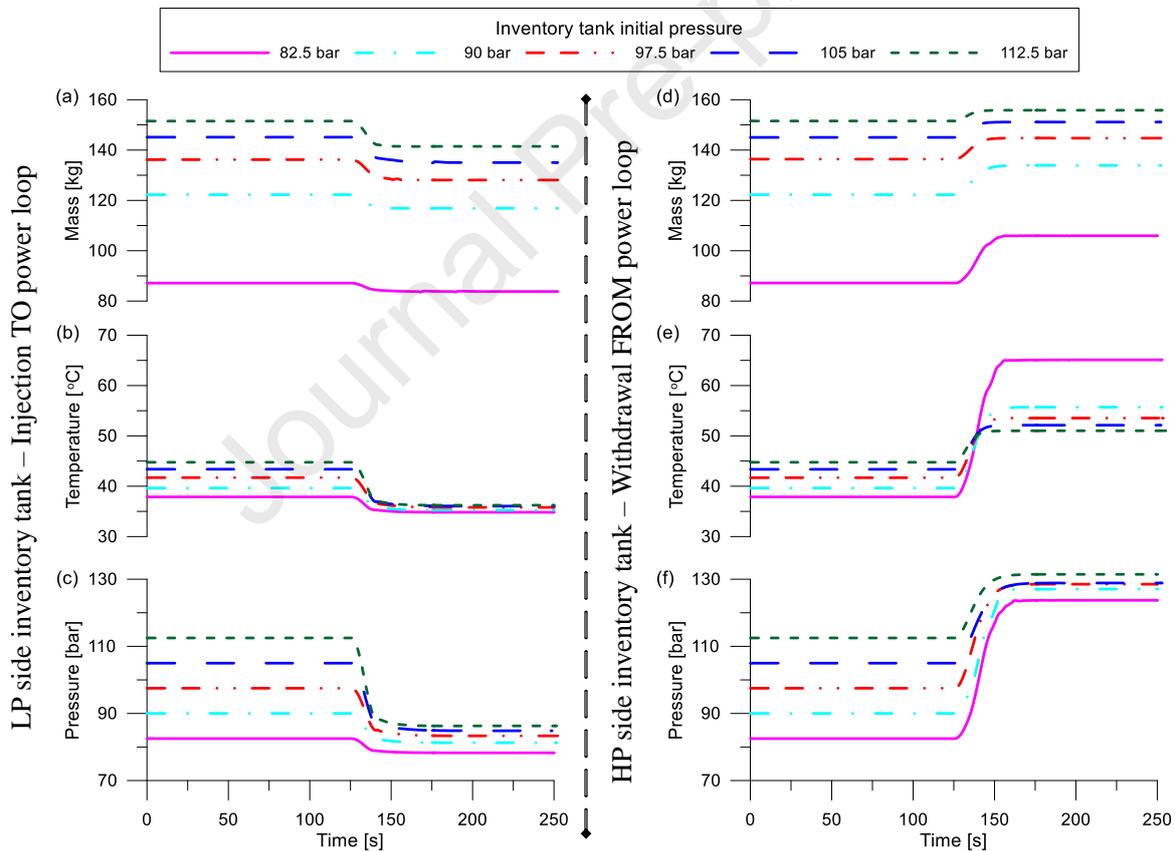


Figure 4 – Effects on tank mass (a), temperature (b) and pressure (c) following the injection of CO₂ into the power loop (left-hand side) or an extraction of CO₂ from the power loop (right-hand side) for a tank volume equal to the one of the loop

263 Symmetric trends can be observed during the extraction of fluid from the CO₂ loop to inventory tanks connected
 264 to the high-pressure side of the loop (downstream the compressor, Figure 4.d-f). The only slight difference can be
 265 noticed in the temperature profiles, where the larger temperature variation, from 38°C to 65°C, occurs when the
 266 initial pressure level of the HP side tank is set to 82.5 bar. In this case, the mass of CO₂ contained in the vessel is

267 lower compared to the other cases, and therefore the stream of CO₂ flowing at higher temperature from
 268 downstream the compressor has a higher impact in warming up the tank (Figure 4.e).

269 The results also show that both the injection and withdrawal processes cannot be considered isothermal, given the
 270 relevant temperature variations occurring during the fluid expansion (CO₂ injection) and during the fluid
 271 compression in the tank following mixing with the higher temperature and pressure CO₂ stream flowing from the
 272 loop (CO₂ extraction). This assumption in the sizing stage of the tanks could lead to errors in the predictions of
 273 the control action outcomes, given the high dependency of the thermophysical properties of CO₂ on pressure and
 274 temperature changes.

275 Figures 4.a and 4.d show the working principle of the inventory control action. Transferring part of the mass
 276 contained in the inventory tank to the CO₂ circuit (CO₂ injection, Figure 4.a) and vice versa (CO₂ withdrawal,
 277 Figure 4.d), enables the mass of CO₂ in the circuit to be altered in order to adapt the system electric output to the
 278 grid load, but also, for a given heat load, decreasing/increasing the temperature at the turbine inlet. This effect is
 279 shown in Figure 5.

280 In particular, Figure 5.a shows that injection of CO₂ into the loop leads to a decrease in the CO₂ turbine inlet
 281 temperature from the nominal level of 460°C down to 414°C, 381°C, 372°C, 363°C and 350°C for a LP side
 282 inventory tank initial pressure of 82.5 bar, 90.0 bar, 97.5 bar, 105.0 bar and 112.5 bar respectively. Lower initial
 283 tank pressures lead to lower injection of CO₂ mass into the system and therefore to higher turbine inlet
 284 temperatures. The opposite holds for the temperature at the compressor inlet (Figure 5.a), since in the same way,
 285 higher mass in the circuit for a given cooling load leads to higher temperature at the gas cooler outlet and therefore
 286 at the compressor inlet.

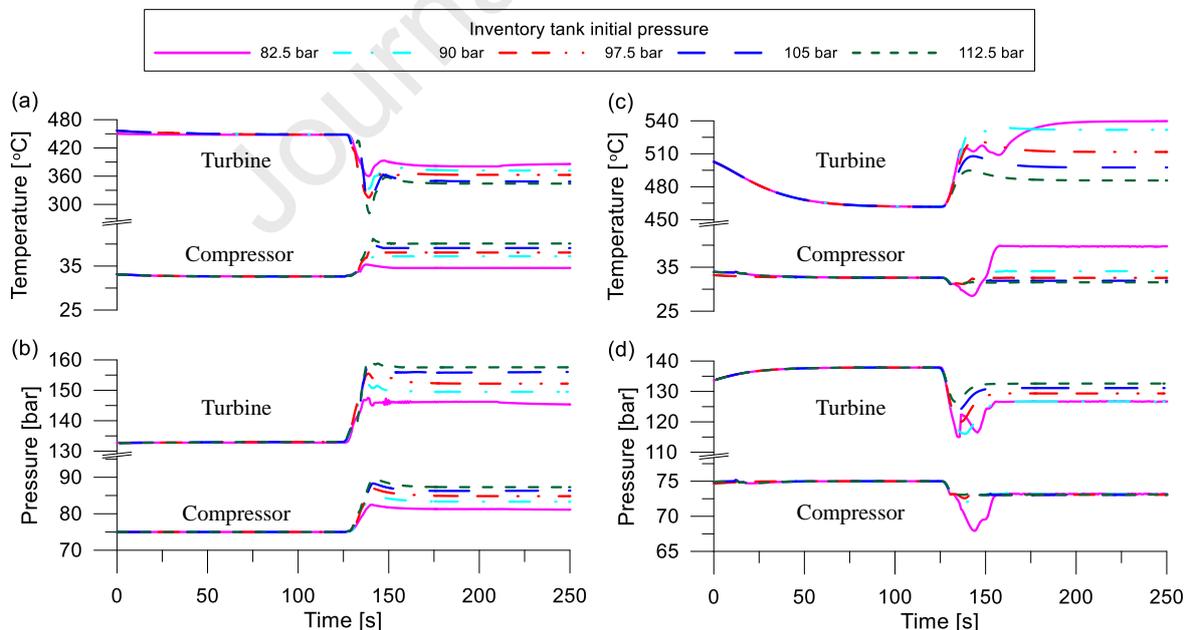


Figure 5 – Effects on compressor and turbine inlet temperature (a) and pressure (b) following the injection of CO₂ into the power loop (left-hand side figure) or an extraction of CO₂ from the power loop (right-hand side figure) for a tank volume equal to the one of the loop

287 The compressor inlet pressure adapts to the tank pressure level when the initial tank pressure is equal to 82.5 bar,
 288 for higher initial pressure levels the equilibrium pressure in the loop achieves slightly lower values (from 84 bar

289 to 89 bar, Figure 5.b). The pressure at the turbine inlet follows the same trend, rising from the nominal value of
290 132 bar to 139 bar, 145 bar, 149 bar, 152 bar and 156 bar for increasing tank initial pressure levels (82.5 bar, 90
291 bar, 97.5 bar, 105 bar and 112.5 bar respectively).

292 Withdrawing CO₂ from the circuit, leads to a drop in the CO₂ pressure both at inlet to the compressor and turbine
293 (Figure 5.d). It can also be noticed that large amount of fluid withdrawn, introduce small instabilities in lead to
294 undesirable conditions for some system components (i.e. condensation occurring at the compressor inlet, Figures
295 5.c and 5.d). Further investigations into best locations in the loop for charging/discharging may improve the
296 system pressure response during such transient operating conditions.

297 4.2. Inventory tank volume effect

298 The same analysis has been carried out considering different volumes for the inventory tanks. Figure 6.a shows
299 the pressure values achieved in the circuit after CO₂ injection/withdrawal considering inventory tanks with a
300 volume (capacity) equal to 30%, 100% and 300% of the total loop one (including the receiver). The equilibrium
301 pressure in the power loop gets closer to the initial pressure of the tank when its capacity increases, since for
302 higher volume of the inventory tanks, the mass injected into the loop is higher. Such higher mass in the circuit
303 also leads to the achievement of lower temperatures at turbine inlet, since the heat input from the waste heat source
304 is kept constant during the simulation. For instance, a turbine inlet temperature equal to 300°C is achieved for a
305 tank volume of 0.729 m³ and an initial pressure of 112.5 bar (Figure 6.b). Similar effects are also noticeable in
306 case of CO₂ withdrawal from the power loop.

307 Higher tank volumes lead to an extended controllability range, e.g. lower temperatures achievable at the turbine
308 inlet, and can ensure a more prolonged availability of the control action (slower tank discharging/charging). On
309 the other hand, larger tank volumes would lead to challenging designs for the inventory tank thermal management
310 system, because of the increased fluid thermal inertia. This is a challenging scenario, since the thermal
311 management of inventory control tanks is among the possible solutions to restore the availability of the inventory
312 controller after use (i.e. providing/removing heat to increase/decrease the tank pressure after usage). The adoption
313 of large inventory tanks would then require auxiliary mechanical systems (i.e. additional pumps, gas booster and
314 valves) to promptly restore the initial tank pressure level.

315 Figure 7 shows that the same amplifying effects are noticeable on turbine inlet pressure (Figure 7.a) and on the
316 CO₂ mass flow rate circulating in the power loop (Figure 7.b). In case of CO₂ injection, having a high capacity
317 inventory tank leads to much higher level of mass in the circuit which increases substantially the pressure at inlet
318 of the turbine (maximum level of 180 bar for an inventory tank initial pressure and volume of 112.5 bar and 0.729
319 m³ respectively). The increased pressure level may overcome pressure design limits of the system, imposing
320 constrains on the maximum mass of fluid injectable in the power loop.

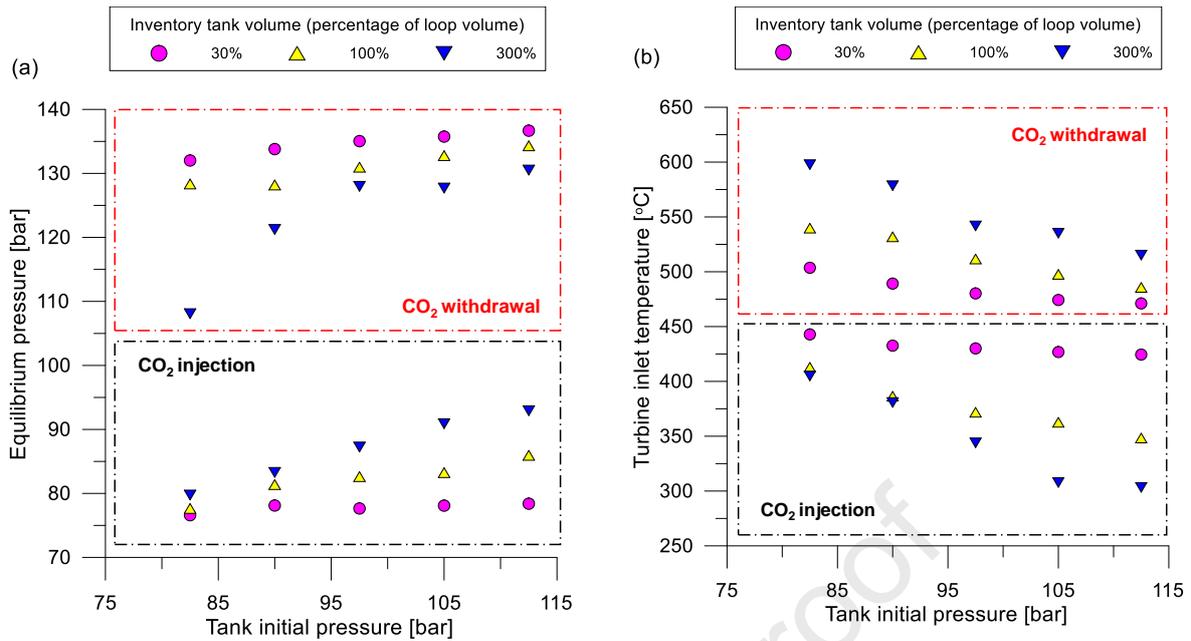


Figure 6 – Effects on system equilibrium pressure (a) and turbine inlet temperature (b) following the injection or withdrawal of fluid into and from the power loop for different inventory tank volumes (expressed as percentage of the loop capacity)

321 In case of CO₂ withdrawal, having a large volume inventory tank (300 % of power loop volume) allows to achieve
 322 larger decrease in system pressure level (minimum turbine pressure of 110 bar for a tank initial pressure of 82.5
 323 bar, Figure 7.a) which may be a key feature for the implementation of less complex and more autonomous
 324 shutdown control strategies (isolating valves between low and high pressure side of the systems can indeed be
 325 avoided since the inventory control system can lower the equalizing cycle pressure in case of compressor
 326 shutdown).

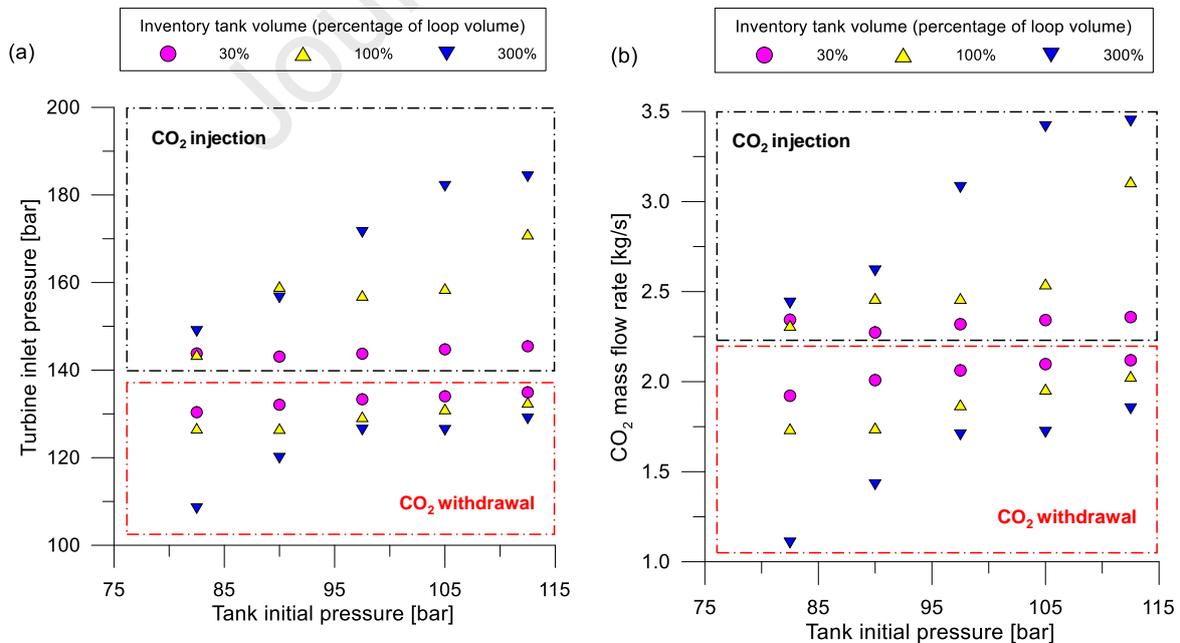


Figure 7 – Turbine inlet pressure (a) and CO₂ mass flow rate (b) following the injection or withdrawal of fluid into and from the power loop for different inventory tank volumes (expressed as percentage of the loop capacity)

327 CO₂ injection/withdrawal can substantially increase and decrease respectively the mass flow rate of CO₂
 328 circulating in the loop (Figure 7.b), leading to a change also in the pressure drops across heat exchangers.

329 All the above effects are due to the increased or decreased level of fluid mass in the system, as showed in Figure
 330 8. Figure 8.a shows the additional mass injected to the power loop for different initial pressure levels and inventory
 331 tank volumes while Figure 8.b shows the mass removed from the power loop. Increasing the capacity of inventory
 332 tank from 100% to 300% of the power loop volume can lead to an increase in injected fluid mass from 9 kg to
 333 almost 18 kg for an inventory tank initial pressure of 115 bar (Figure 8.a).

334 During the extraction, for the same volume increase, the removed mass from the power loop can vary from 19 kg
 335 to 31 kg for an initial pressure of the inventory tank of 82.5 bar (Figure 8.b). These results suggest that there is a
 336 difference among controllability ranges between CO₂ injection and extraction. Assuming same values for the
 337 initial pressure levels of both inventory tanks connected to the low- and high-pressure side of the circuit, leads to
 338 asymmetric pressure differences between inventory tank and extraction/injection points, with a consequent
 339 different effect of the control action. Therefore, inventory sizing should consider this aspect and assume different
 340 initial pressure levels for the tanks connected to the low- and high-pressure side of the system.

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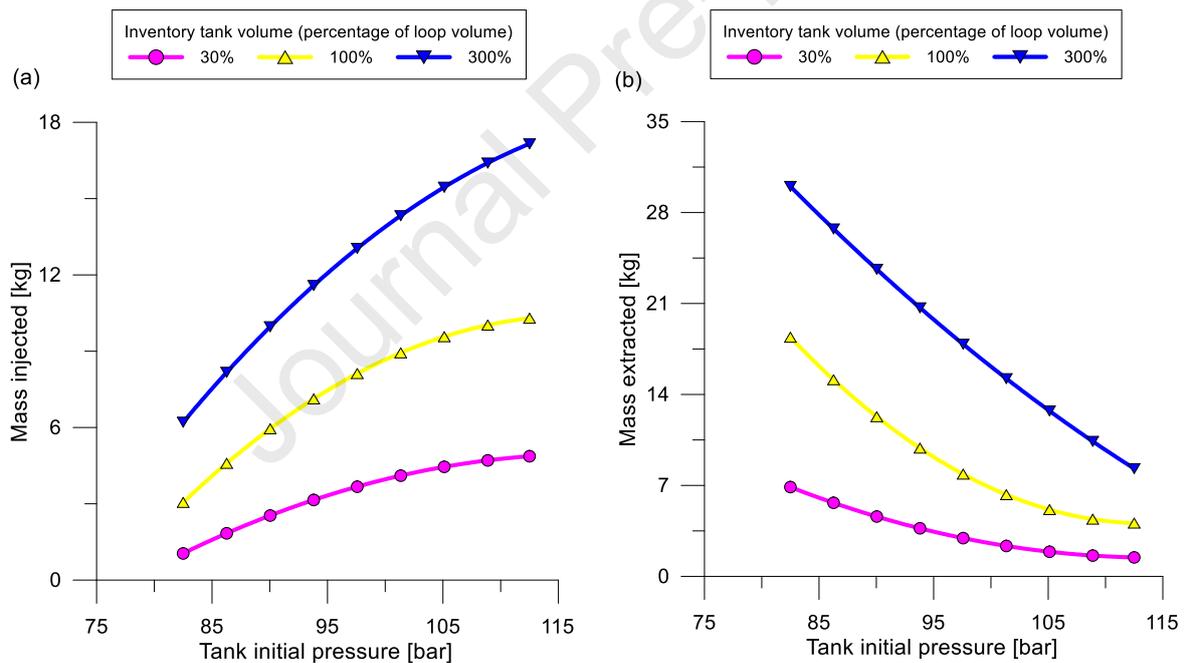


Figure 8 - Compressor inlet temperature as a function of pressure (a) and pressure (b) following the injection of CO₂ into the power loop (left-hand side figure) or an extraction of CO₂ from the power loop (right-hand side figure) for a tank volume equal to the one of the loop

342 4.3. Inventory effect on system performance

343 Figures 9 and 10 show the variation of system performance as a function of initial pressure and volume of the
 344 inventory tank following an injection and extraction of fluid. Figure 9 reports the variation of system net power
 345 output and Figure 10 the change in cycle efficiency. In particular, Figure 9.a shows the system net power output
 346 as the fluid is injected in the power loop. When the volume of the inventory tanks increases the mass injected in
 347 the loop for each initial pressure level increases as well, since more working fluid mass transfer is required to

348 equalize the differential pressure between the tanks and the circuit. Small mass injections improve the system
 349 power output, because higher mass flow rates are circulating in the circuit. This allows to recover additional
 350 thermal power from flue gases without increasing excessively pressure drops across heat exchangers and changing
 351 excessively the thermodynamic conditions at turbine and compressor inlet as showed in Figure 6.b, Figure 7.a and
 352 Figure 11.a (whose efficiency then remain approximately constant).

353 Further additions of mass, however, can change significantly the thermodynamic conditions in the cycle and the
 354 CO₂ mass flow rate, which can impact negatively the efficiency of turbomachinery and the power generated by
 355 the power block. Simulation results showed the system power output drops to 77 kW and 66 kW for large amounts
 356 of CO₂ mass injected, occurring for a tank initial pressure of 112.5 bar and an inventory tank volume of 0.243 m³
 357 and 0.729 m³ respectively (Figure 9.a).

358 There is then an optimal value of mass injected which maximises the power generated and it is different from the
 359 optimal charge that guarantees the system maximum thermal efficiency. Such condition, when the system is
 360 slightly overcharged occurs for a volume of the inventory tank equal to 0.243 m³ and an initial pressure level of
 361 97.5 bar (Figure 9.a), corresponding to 8 kg of CO₂ mass injected (Figure 8.a).

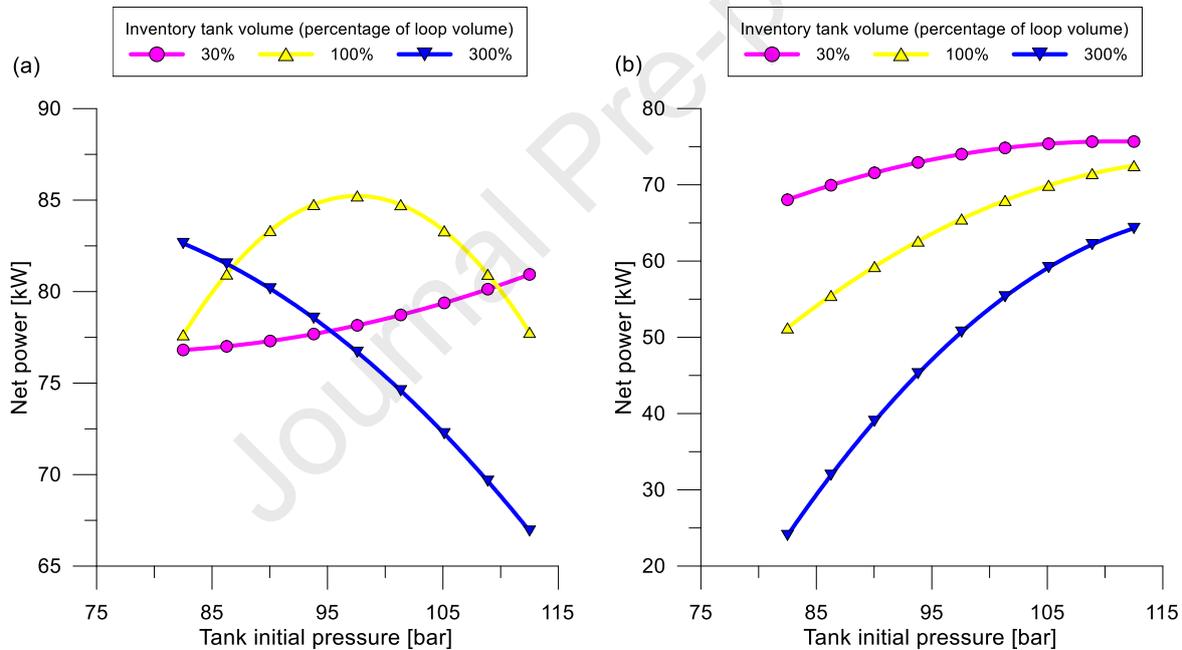


Figure 9 – Net power output of the system as a function of the inventory tank initial pressure level and volume following the injection of CO₂ into the power loop (a) or the extraction of CO₂ from the power loop (b)

362 CO₂ extraction from the power loop only decreases the system net power output, as shown in Figure 9.b. This is
 363 mainly due to the decrease of the turbine inlet pressure and the increase of the temperature at the compressor inlet
 364 (as showed in Figure 11.b) which leads to less efficient compression since the machine is operating far from the
 365 CO₂ critical point.

366 Similar trends can be observed from the system cycle efficiency results reported in Figure 10, with the only
 367 exception occurring during fluid extraction. In Figure 10.b it can be seen that the cycle efficiency slightly improves
 368 for small fluid extractions before decreasing substantially for larger removed amounts. Small reductions of fluid
 369 mass can lead to steeper drops in the heat recovered rather than on system net power output, causing the efficiency

370 to increase. It can also be seen that the optimal charge for maximum efficiency may be different from the one
 371 required to achieve maximum power output.

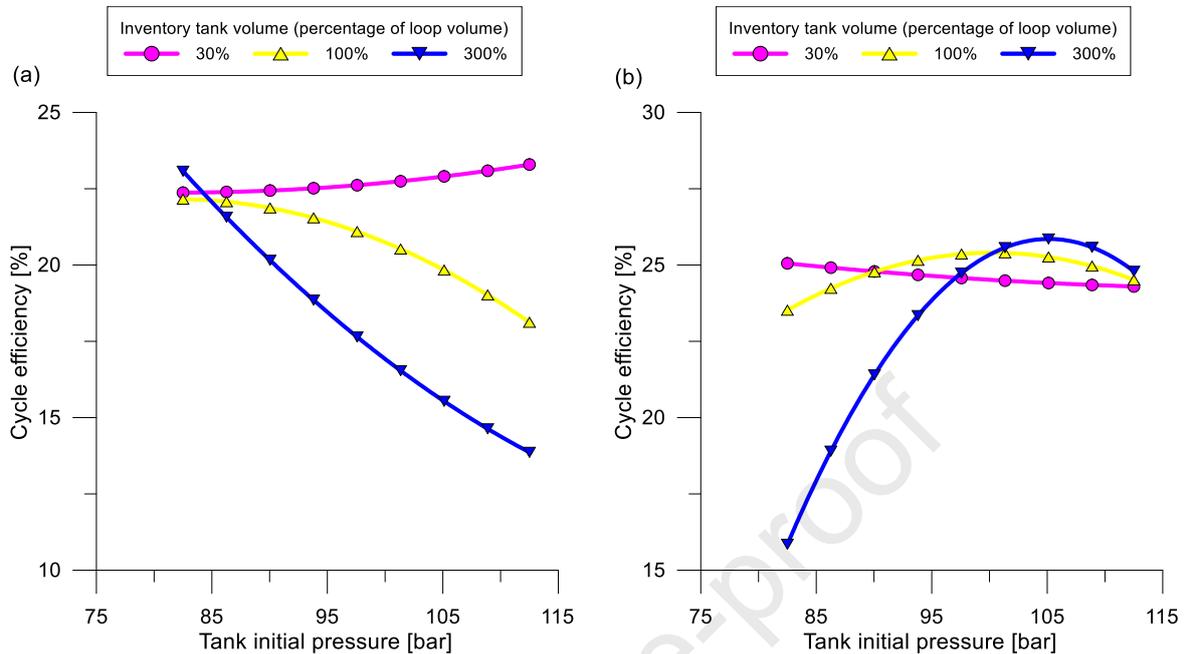


Figure 10 – Cycle efficiency of the system as a function of the inventory tank initial pressure level and volume following the injection of CO₂ into the power loop (a) or the extraction of CO₂ from the power loop (b)

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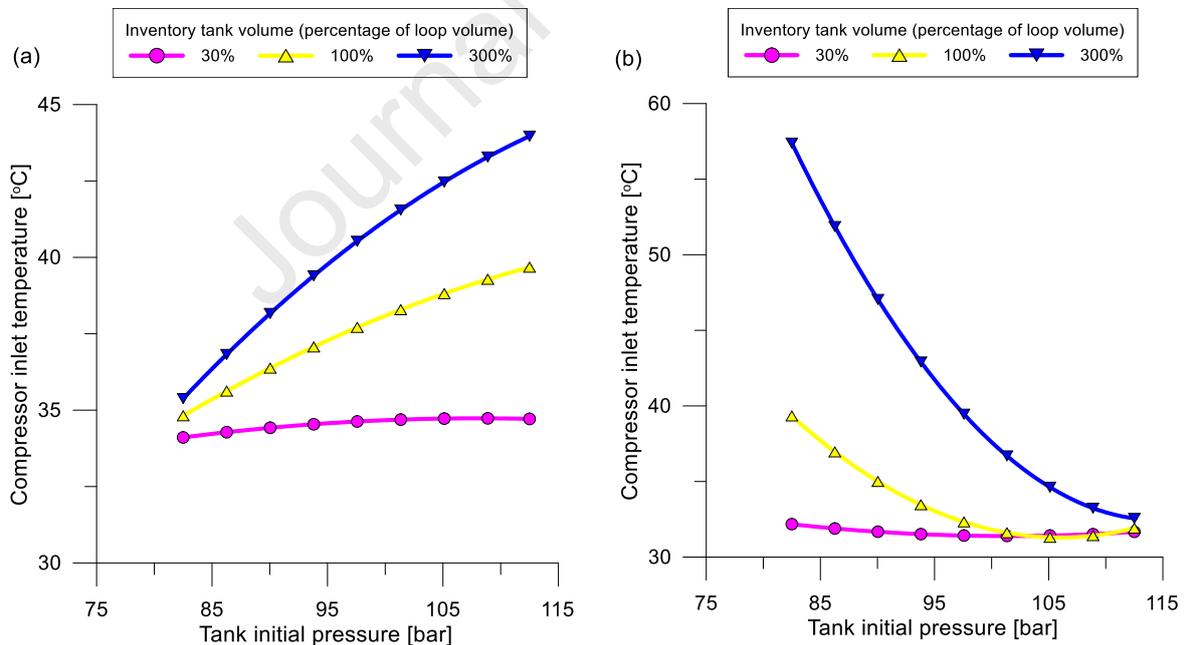


Figure 11 - Compressor inlet temperature as a function of pressure (a) and pressure (b) following the injection of CO₂ into the power loop (left-hand side figure) or an extraction of CO₂ from the power loop (right-hand side figure) for a tank volume equal to the one of the loop

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377 5. Inventory control simulations

378 After the analysis of the effects of inventory main parameters on system variables and performance, an inventory
 379 controller was designed to regulate the temperature at the turbine inlet. The temperature at the inlet of the turbine
 380 is a crucial parameter to avoid critical thermal stresses on system components and ensure a safe operation of the
 381 system and turbomachine auxiliaries (i.e. sealing, bearings) during transients. Because the sCO₂ facility has been
 382 designed for waste heat recovery applications, the objective is to assess the controller response to a heat load
 383 variation. In this study in particular, the case of a heat load drop and increase have been simulated by considering
 384 a decrease and increase respectively of the flue gas inlet temperature.

385 The controller is a Proportional Integral (PI) one acting on the valve actuator lift position. Two such controllers
 386 have been connected to the inventory extraction and injection valves (EXTV and INJV respectively, Figure 3).
 387 The controller on the EXTV, which connects one inventory tank to the high-pressure side of the power loop
 388 (downstream the compressor, point 2 in Figure 3), is activated by a state machine controller when the primary
 389 heater sees a decrease in the heat load provided by the flue gases (which may occur for a temperature or flow rate
 390 decrease). In such case, fluid mass is removed from the power loop to counterbalance the decrease in thermal
 391 energy available.

392 On the contrary, the controller on the INJV, which connects the other inventory tank to the low-pressure side of
 393 the power loop (upstream the compressor, point 1 in Figure 3), is activated by the state machine following a rise
 394 in heat source temperature or mass flow rate. Higher thermal energy is therefore balanced by an increase in the
 395 mass of fluid in the power loop. The state machine is thus regulated depending on the difference between the
 396 actual and the nominal level of temperature or mass flow rate of the heat source. If the difference is positive,
 397 means that the heat load provided by the flue gas is higher and then the controller acting on the INJV is activated.
 398 If the difference is negative, the controller on the EXTV is used.

399 A lambda tuning procedure has been used to calculate the proportional (P) and integral (I) terms of the controllers
 400 [32]. By considering a first order relationship between the mass injected/extracted into/from the power loop and
 401 the controlled process variable (turbine inlet temperature), the control output (valve actuator lift) has been
 402 modified in the entire admissible range and the process variable response analysed. From the time constant (τ)
 403 and process gain (K), the proportional and integral coefficients of the two controllers have been retrieved by
 404 setting an appropriate settling time and damping ratio to smooth the controller response. Table 8 reports PI values
 405 for the two controllers with the respective settling time and damping ratio. In the following sections the controller
 406 performance and response are discussed in relation to a simulated decrease and increase of the heat load.

407 Table 8 – Proportional (P) and integral (I) coefficients for controllers acting on the extraction valve (EXTV) and
 408 the injection valve (INJV)

Controller coefficients		EXTV	INJV
P coefficient	[-]	0.31	-0.37
I coefficient	[-]	0.09	-0.07
Settling time	[s]	21	
Damping ratio	[-]	0.8	

409

410 5.1. Heat load decrease

411 Figure 12 shows the results of the system uncontrolled and controlled responses to a decrease in the heat load
 412 provided by the waste heat source, simulated through a decrease of 10% in the inlet temperature, from 650 °C
 413 down to 580 °C (grey continuous line, Figure 12.a). The temperature control set point (dashed red line in Figure
 414 12.a) at the turbine inlet has been set equal to the turbine nominal temperature of 465 °C. The inventory tank
 415 volume was assumed equal to 0.243 m³ (same for the power loop), while its initial pressure has been set to 82.5
 416 bar. Without control action, the turbine inlet temperature decreases from 465 °C to 400 °C, leading to a 65 °C
 417 temperature drop in approximately 50s. Turbine pressure, compressor inlet conditions, and mass flow rate remain
 418 on the contrary unchanged (Figure 12.a, 12.c and 12.d). Once the inventory control system is active, the regulation
 419 of the turbine temperatures is effective and the reference set point is achieved thanks to the removal of 11 kg of
 420 fluid mass from the power loop (dark brown continuous line in Figure 12.b).

421 As a result of the mass removal, the turbine and compressor inlet pressures decrease from the nominal value of
 422 137.5 bar and 75 bar down to 126 bar and 72 bar respectively (blue and light brown line respectively in Figure
 423 12.c). The mass flow rate also decreases from the nominal value of 2.2 kg/s down to 1.8 kg/s (pastel blue line in
 424 Figure 12.d). This is a consequence of the reduced pressure ratio across the cycle induced by the lower fluid mass
 425 in the circuit, which changes the characteristic of the loop and reduces the mass flow provided by the compressor.

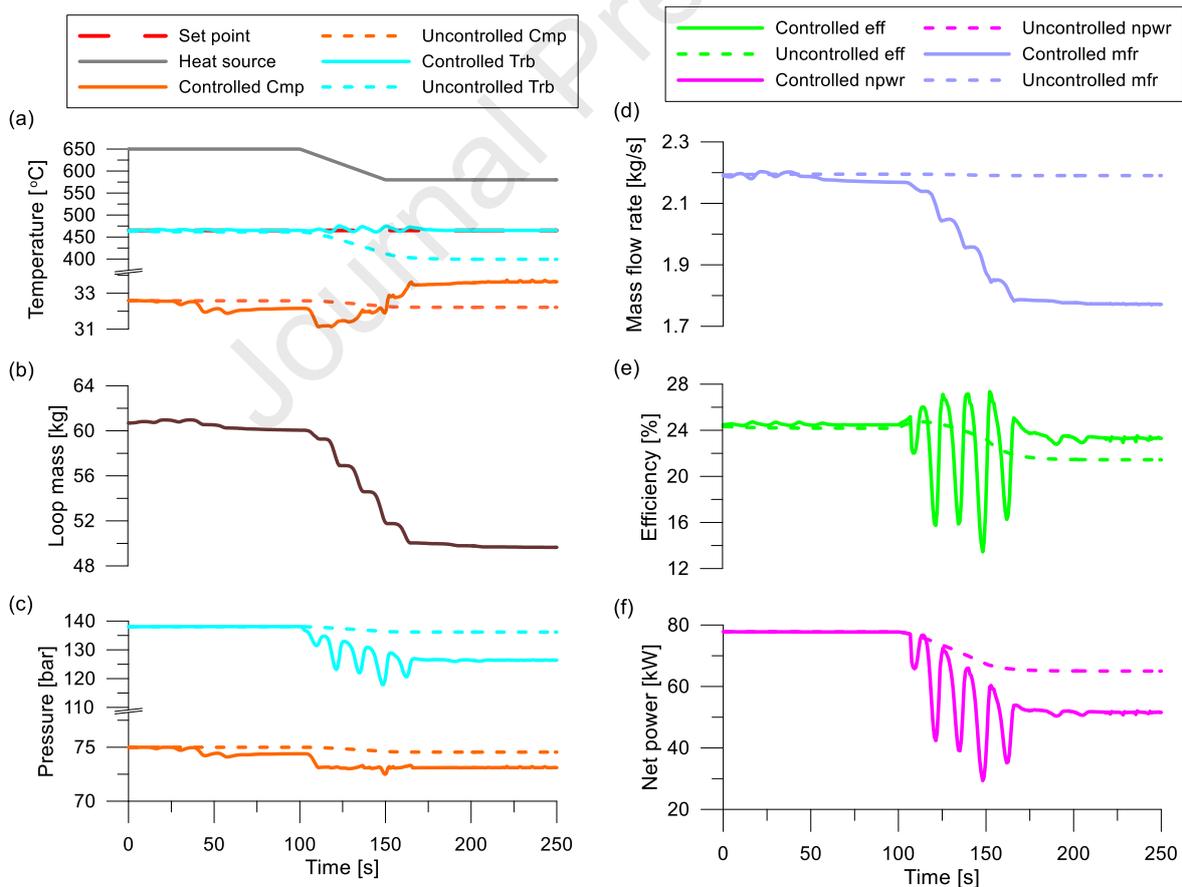


Figure 12 – Controlled and uncontrolled system response to a decrease in the heat source (hs) temperature: (a) set point, compressor (cmp) and turbine (trb) inlet temperatures; (b) mass in the power loop; (c) compressor and turbine inlet pressures; (d) CO₂ mass flow rate (mfr); (e) cycle efficiency (eff); (f) net power output (npwr)

426 The removal of CO₂ from the power loop causes the compressor to operate close to the surge region, with
427 oscillations at the outlet pressure which consequently result in oscillation in all the cycle calculated quantities,
428 from the mass flow rate to the efficiency and net power output. More detailed analyses of the compressor
429 operations (both numerical and experimental) would be required in future work to understand if an anti-surge
430 valve can help to overcome the issue.

431 Figure 12.e and Figure 12.f show the effect of the inventory control action on the system performance. In particular
432 the cycle efficiency is showed in Figure 12.e while the system net power output in Figure 12.f. The decrease in
433 heat load has a detrimental effect on both efficiency and net power output. When the control system is not
434 considered the efficiency of the cycle drops from 24% down to 22% (dark green line in Figure 12.e) following a
435 decrease in the heat source temperature. The thermal power recovered from the flue gases stays the same, but the
436 net power decreases from 78 kW to 65 kW (purple line in Figure 12.f).

437 The action of the inventory controller despite leading to a lower net power output of 52 kW (magenta line in
438 Figure 12.f), 20% lower compared to the uncontrolled system, allows to achieve a higher cycle efficiency after
439 the heat source temperature decrease (light green line in Figure 12.e). The less mass of fluid in the power loop
440 indeed leads to a lower power production, but also to a much lower waste heat recovered compared to the
441 uncontrolled system case, allowing to maintain a constant efficiency in part load conditions. Such results suggest
442 that inventory control strategies for regulating the power unit in part-load conditions should be preferred in power
443 generation applications rather than waste heat recovery, where the net power generated has a higher value (since
444 the heat source is a waste product).

445 5.2. Heat load increase

446 Figure 13 shows system uncontrolled and controlled response for an increase of the heat load provided by the flue
447 gases, simulated through an increase of 10% in the inlet temperature, which goes from the nominal value of 650°C
448 up to 725°C (grey continuous line, Figure 13.a). In this case as well the temperature control set point has been
449 kept equal to the turbine nominal temperature of 465°C (Figure 13.a). The inventory initial pressure to 112.5 bar
450 while the volume of the inventory tank has been set equal to 0.729 m³. Simulations adopting a volume of 0.243
451 m³, in fact, revealed the inability of the controller to achieve the target due to the saturation of control action. The
452 available mass before the equalization of pressure between tank and power loop was not sufficient to cause an
453 adequate drop in turbine inlet temperature.

454 When the system is not controlled, the turbine inlet temperature increases from 465°C to 532°C, leading also in
455 this case to approximately 65°C temperature difference in 50s. The pressure at the turbine and compressor inlet
456 along with the compressor inlet temperature and CO₂ mass flow rate remains unchanged (Figure 13.a, 13.c and
457 13.d). The inventory controller instead even in this case is able to keep the turbine inlet temperature equal to the
458 established set point (blue line in Figure 13.a) by adding 7 kg of fluid mass into the power loop (dark brown line
459 in Figure 13.b). After the injection of the additional fluid mass, the pressure at turbine and compressor inlet
460 increase from the nominal value of 137.5 bar and 75 bar up to 155 bar and 82 bar respectively (blue and light
461 brown line respectively in Figure 13.c). The mass flow rate increases as well from the nominal value of 2.2 kg/s
462 up to 2.5 kg/s (pastel line in Figure 13.d) following the increased cycle pressure ratio.

463 In this case, the inventory controller actually allows not only to promptly regulate the system but also to achieve
 464 better performance in terms of net power output, which goes from 77 kW up to 92 kW against the increase from
 465 77 kW to 88 kW obtained in the uncontrolled case (Figure 13.f). In terms of cycle efficiency, Figure 13.e shows
 466 that for an increase in the heat load the inventory controller allows to keep the system efficiency unchanged but
 467 lower compared to the one achieved by the uncontrolled power unit 26% when the waste heat source temperature
 468 achieves 725°C (dark green light in Figure 13.e). Such results show that for increases of heat load provided by the
 469 waste heat source, the inventory controller is actually very effective also in optimizing system performance. Either
 470 in this case oscillating transients can be noticed due to the particular region of operation of the compressor.

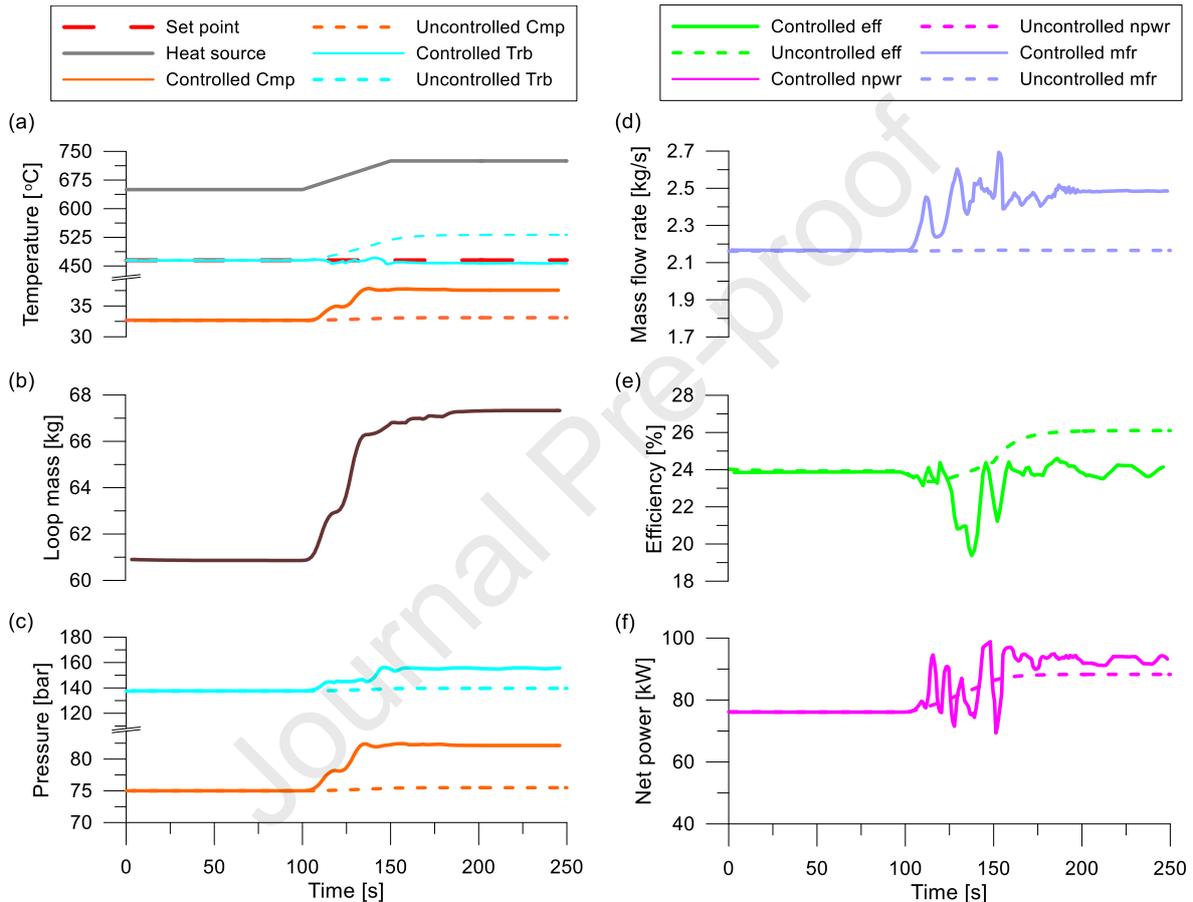


Figure 13 – Controlled and uncontrolled system response to an increase in the heat source (hs) temperature: (a) set point, compressor (cmp) and turbine (trb) inlet temperatures; (b) mass in the power loop; (c) compressor and turbine inlet pressures; (d) CO₂ mass flow rate (mfr); (e) cycle efficiency (eff); (f) net power output (npwr)

471

472 6. Conclusions

This work provides insights on the dynamics of inventory control on a small scale sCO₂ heat to power conversion unit. The numerical methodology combines a one-dimensional CFD model of the sCO₂ power loop calibrated against real equipment data with a model of an inventory control system. The results show that, with respect to inventory design procedures available in the literature, the sizing of the inventory tanks cannot be carried out assuming CO₂ injection and withdrawal processes are isothermal. The simulations reported a maximum tank temperature change of 22% and 76% when the CO₂ is injected and withdrawn from the system respectively.

Such temperature change could lead to variation of fluid thermophysical properties with consequent errors in the prediction of the control action outcomes. As inventory tank capacity is mainly related to the controllability range of the cycle, increasing the volume to 3 times that of the power loop led to $\pm 30\%$ variation in turbine inlet temperature compared to the nominal value. Larger tank volume could also lead to greater control flexibility but also to increased complexity in inventory thermal management, potentially requiring the use of mechanical systems (i.e. pumps, gas boosters, valves or multiple tanks) to restore the initial tank pressure level and therefore the control margin after multiple fluid injections/withdrawals to and from the power loop.

In general, even if the inventory controller can effectively regulate the turbine inlet temperature by injecting/withdrawing CO₂ into/from the power loop, such action influences several cycle parameters, with consequent complexity in predicting the outcome on system performance. For example, a decrease of 10% in the waste heat source temperature, the extraction of 11 kg of CO₂ mass from the power loop enacted by the PI inventory controller enables the turbine inlet temperature to remain constant at the nominal value of 465°C but causes a 11 bar and a 2 bar reduction in the turbine and compressor inlet pressures respectively.

This combined with a decrease in CO₂ mass flow rate of 0.4 kg/s leads to a reduction in net power output of 13 kW but to an increase in efficiency of 2% compared to the performance of the uncontrolled system. Therefore, despite a small detrimental action on the power output, at part-load the controller is able to keep unchanged the cycle efficiency when the heat source temperature decreases. For a heat source temperature increase the controller is able to optimise the system net power output while keeping a constant cycle efficiency. Future work will be focused on assessing the relationship between mass injected/extracted and cycle performance as well as identifying strategies to improve transients occurring during the actuation of the control action.

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Declaration of interests

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests:

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