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# Attractors and a “strange term” in homogenized equation

## *Attracteurs et un « terme étrange » dans les équations homogénéisées*

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**Abstract.** We study the behavior of attractors of the reaction–diffusion equation in a perforated domain as the small parameter characterizing the perforation tends to zero.

**Résumé.** Nous étudions le comportement des attracteurs de l'équation de réaction–diffusion dans le domaine perforé car le petit paramètre caractérisant la perforation tend vers zéro.

**Keywords.** Homogenization, Attractors, Reaction–diffusion equation, Boundary value problem, Perforated domain.

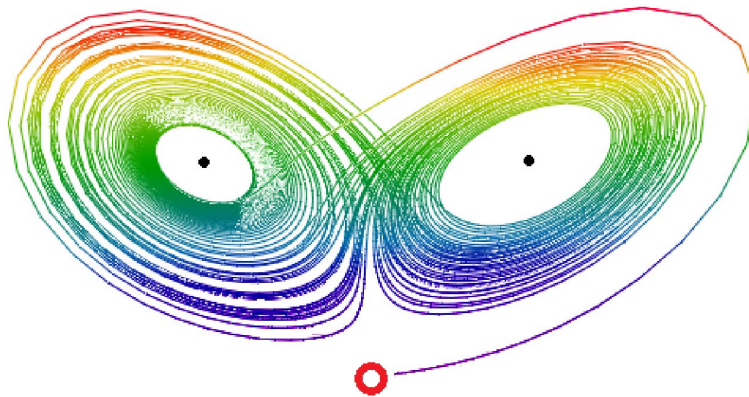
**Mots-clés.** Homogénéisation, Attracteurs, Équation de réaction–diffusion, Problème de valeur limite, Domaine perforé.

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**Figure 1.** Attractor.

**1. Introduction**

Homogenization in a perforated domain in critical cases leads to the appearance of an additional potential (“strange term”) in the limit (homogenized) equation (see [1–6]). We discovered the same phenomenon in the homogenization of attractors (see Figure 1<sup>1</sup> for example) for the reaction–diffusion equation.

**2. Notation and settings**

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$ ,  $n \geq 3$ , with a piecewise smooth boundary  $\partial\Omega$ . Let  $G_0$  be a domain in  $Y = (-1/2, 1/2)^n$  such that  $\bar{G}_0$  is a compact set diffeomorphic to a ball.

For  $\delta > 0$  and  $B$ , we denote  $\delta B = \{x : \delta^{-1}x \in B\}$ . Assume that  $\varepsilon$  is small enough so that

$$\varepsilon^{n/(n-2)}G_0 \subset \varepsilon Y.$$

For  $j \in \mathbb{Z}^n$ , we define

$$P_\varepsilon^j = \varepsilon j, \quad Y_\varepsilon^j = P_\varepsilon^j + \varepsilon Y, \quad G_\varepsilon^j = P_\varepsilon^j + \varepsilon^{n/(n-2)}G_0.$$

We define the domain  $\tilde{\Omega}_\varepsilon = \{x \in \Omega : \rho(x, \partial\Omega) > \sqrt{n}\varepsilon\}$  and the set of admissible indexes as

$$\Upsilon_\varepsilon = \{j \in \mathbb{Z}^n : G_\varepsilon^j \cap \tilde{\Omega}_\varepsilon \neq \emptyset\}.$$

Note that  $|\Upsilon_\varepsilon| \cong d\varepsilon^{-n}$ , where  $d > 0$  is a constant. Consider the following domain:

$$\Omega_\varepsilon = \Omega \setminus \bar{G}_\varepsilon, \quad \text{where } G_\varepsilon = \bigcup_{j \in \Upsilon_\varepsilon} G_\varepsilon^j.$$

Denote

$$Q_\varepsilon = \Omega_\varepsilon \times (0, +\infty), \quad Q = \Omega \times (0, +\infty).$$

We study the asymptotic behavior of attractors of the problem

$$\begin{cases} \frac{\partial u_\varepsilon}{\partial t} = \Delta u_\varepsilon - f(u_\varepsilon) + g(x), & x \in \Omega_\varepsilon, \\ \frac{\partial u_\varepsilon}{\partial \nu} + \varepsilon^{n/(2-n)} b_\varepsilon^j(x) u_\varepsilon = 0, & x \in \partial G_\varepsilon^j, j \in \Upsilon_\varepsilon, t \in (0, +\infty), \\ u_\varepsilon = 0, & x \in \partial\Omega, \\ u_\varepsilon = U(x), & x \in \Omega_\varepsilon, t = 0. \end{cases} \tag{1}$$

<sup>1</sup><http://docplayer.ru/32107834-Lekciya-5-haoticheskoe-povedenie-dinamicheskikh-sistem-sistema-lorenca.html>.

Here,  $\nu$  is the outward unit vector to the boundary,  $g(x) \in L_2(\Omega)$ ,

$$b_\varepsilon^j(x) = b\left(x, \frac{x - P_\varepsilon^j}{\varepsilon^{n/(n-2)}}\right),$$

where  $b(x, y) \in C(\Omega \times \mathbb{R}^n)$ , such that  $0 < b_0 \leq b(x, y) \leq B_0$  for some constants  $b_0$  and  $B_0$ ,  $b(x, y)$  is one-periodic in  $y$ , and  $f(v) \in C(\mathbb{R})$  satisfies the following inequalities:

$$f(v) \cdot v \geq K|v|^p - C, \quad |f(v)| \leq C_1(|v|^{p-1} + 1), \quad p \geq 2. \tag{2}$$

Note that we *do not assume* that the nonlinear function  $f(v)$  satisfies the Lipschitz condition with respect to  $v$ .

We denote the spaces  $\mathbf{H} := L_2(\Omega)$ ,  $\mathbf{H}_\varepsilon := L_2(\Omega_\varepsilon)$ ,  $\mathbf{V} := H_0^1(\Omega)$ , and  $\mathbf{V}_\varepsilon := H^1(\Omega_\varepsilon; \partial\Omega)$ —set of functions from  $H^1(\Omega_\varepsilon)$  with zero trace on  $\partial\Omega$ —and  $\mathbf{L}_p := L_p(\Omega)$  and  $\mathbf{L}_{p,\varepsilon} := L_p(\Omega_\varepsilon)$ . The norms in these spaces are denoted, respectively, by

$$\begin{aligned} \|v\|^2 &:= \int_\Omega |v(x)|^2 dx, & \|v\|_\varepsilon^2 &:= \int_{\Omega_\varepsilon} |v(x)|^2 dx, & \|v\|_1^2 &:= \int_\Omega |\nabla v(x)|^2 dx, \\ \|v\|_{1\varepsilon}^2 &:= \int_{\Omega_\varepsilon} |\nabla v(x)|^2 dx, & \|v\|_{\mathbf{L}_p}^p &:= \int_\Omega |v(x)|^p dx, & \|v\|_{\mathbf{L}_{p,\varepsilon}}^p &:= \int_{\Omega_\varepsilon} |v(x)|^p dx. \end{aligned}$$

Recall that  $\mathbf{V}' := H^{-1}(\Omega)$  and  $\mathbf{L}_q$  are the dual spaces of  $\mathbf{V}$  and  $\mathbf{L}_p$ , respectively, where  $q = p/(p - 1)$ . Moreover,  $\mathbf{V}'_\varepsilon$  is the dual space for  $\mathbf{V}_\varepsilon$ .

As in [7, 8], we study weak solutions of the initial boundary value problem (1), that is, the functions

$$u_\varepsilon(x, s) \in L_\infty^{\text{loc}}(\mathbb{R}_+; \mathbf{H}_\varepsilon) \cap L_2^{\text{loc}}(\mathbb{R}_+; \mathbf{V}_\varepsilon) \cap L_p^{\text{loc}}(\mathbb{R}_+; \mathbf{L}_{p,\varepsilon}),$$

which satisfy problem (1) in the distributional sense, that is,

$$\begin{aligned} - \int_{Q_\varepsilon} u_\varepsilon \frac{\partial \psi}{\partial t} dx dt + \int_{Q_\varepsilon} \nabla u_\varepsilon \nabla \psi dx dt + \int_{Q_\varepsilon} f(u_\varepsilon) \psi dx dt \\ + \varepsilon^{n/(2-n)} \sum_{j \in Y_\varepsilon} \int_0^{+\infty} \int_{\partial G_\varepsilon^j} b_\varepsilon^j u_\varepsilon \psi dx dt = \int_{Q_\varepsilon} g(x) \psi dx dt \end{aligned} \tag{3}$$

for any  $\psi \in C_0^\infty(\mathbb{R}_+; \mathbf{H}_\varepsilon)$ .

If  $u_\varepsilon(x, t) \in L_p(0, M; \mathbf{L}_{p,\varepsilon})$ , then it follows from condition (2) that  $f(u_\varepsilon(x, t)) \in L_q(0, M; \mathbf{L}_{q,\varepsilon})$ . At the same time, if  $u_\varepsilon(x, t) \in L_2(0, M; \mathbf{V}_\varepsilon)$ , then  $\Delta u_\varepsilon(x, t) + g(x) \in L_2(0, M; \mathbf{V}'_\varepsilon)$ . Therefore, for an arbitrary weak solution  $u_\varepsilon(x, s)$  of problem (1), we have

$$\frac{\partial u_\varepsilon(x, t)}{\partial t} \in L_q(0, M; \mathbf{L}_{q,\varepsilon}) + L_2(0, M; \mathbf{V}'_\varepsilon).$$

The Sobolev embedding theorem implies that

$$L_q(0, M; \mathbf{L}_{q,\varepsilon}) + L_2(0, M; \mathbf{V}'_\varepsilon) \subset L_q(0, M; \mathbf{H}_\varepsilon^{-r}),$$

where the space  $\mathbf{H}_\varepsilon^{-r} := H^{-r}(\Omega_\varepsilon)$  and  $r = \max\{1, n(1/2 - 1/p)\}$ . Hence, for any weak solution  $u_\varepsilon(x, t)$  of (1), we have  $\partial u_\varepsilon(x, t)/\partial t \in L_q(0, M; \mathbf{H}_\varepsilon^{-r})$ .

**Remark 1.** The existence of a weak solution  $u(x, s)$  to problem (1) for every  $U \in \mathbf{H}_\varepsilon$  and fixed  $\varepsilon$  such that  $u(x, 0) = U(x)$  can be proved by the standard approach (see for instance [7, 9]). This solution is not necessarily unique because we do not assume the Lipschitz condition for  $f(v)$  with respect to  $v$ .

The following lemma can be proved similarly to Proposition XV.3.1 from [8].

**Lemma 2.1.** *Let  $u_\varepsilon(x, t) \in L_2^{\text{loc}}(\mathbb{R}_+; \mathbf{V}_\varepsilon) \cap L_p^{\text{loc}}(\mathbb{R}_+; \mathbf{L}_{p,\varepsilon})$  be a weak solution of problem (1). Then*

- (i)  $u \in C(\mathbb{R}_+; \mathbf{H}_\varepsilon)$ ;

(ii) the function  $\|u_\varepsilon(\cdot, t)\|_\varepsilon^2$  is absolutely continuous on  $\mathbb{R}_+$  and, moreover,

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|u_\varepsilon(\cdot, t)\|_\varepsilon^2 + \int_{\Omega_\varepsilon} |\nabla u_\varepsilon(x, t)|^2 dx + \int_{\Omega_\varepsilon} f(u_\varepsilon) u_\varepsilon dx \\ & + \varepsilon^{\frac{n}{2-n}} \sum_{j \in Y_\varepsilon} \int_{\partial G_\varepsilon^j} b_\varepsilon^j |u_\varepsilon(x, t)|^2 dx = \int_{\Omega_\varepsilon} g(x) u_\varepsilon dx \end{aligned}$$

for almost every  $t \in \mathbb{R}_+$ .

In further analysis, we shall omit the index  $\varepsilon$  in the notation of spaces, where it is natural. We now apply the scheme described in [10] to construct the trajectory attractor for problem (1).

To describe the trajectory space  $\mathcal{K}_\varepsilon^+$  for problem (1), we follow the general framework of Section 3 from [10] and define the Banach spaces for every  $[t_1, t_2] \in \mathbb{R}$ ,

$$\mathcal{F}_{t_1, t_2} := L_p(t_1, t_2; \mathbf{L}_p) \cap L_2(t_1, t_2; \mathbf{V}) \cap L_\infty(t_1, t_2; \mathbf{H}) \cap \left\{ v \left| \frac{\partial v}{\partial t} \in L_q(t_1, t_2; \mathbf{H}^{-r}) \right. \right\}, \tag{4}$$

with norm

$$\|v\|_{\mathcal{F}_{t_1, t_2}} := \|v\|_{L_p(t_1, t_2; \mathbf{L}_p)} + \|v\|_{L_2(t_1, t_2; \mathbf{V})} + \|v\|_{L_\infty(0, M; \mathbf{H})} + \left\| \frac{\partial v}{\partial t} \right\|_{L_q(t_1, t_2; \mathbf{H}^{-r})}. \tag{5}$$

It is clear that the condition

$$\|\Pi_{t_1, t_2} f\|_{\mathcal{F}_{t_1, t_2}} \leq C(t_1, t_2, \tau_1, \tau_2) \|f\|_{\mathcal{F}_{\tau_1, \tau_2}}, \quad \forall f \in \mathcal{F}_{\tau_1, \tau_2}, \tag{6}$$

where  $[t_1, t_2] \subseteq [\tau_1, \tau_2]$ ,  $\Pi_{t_1, t_2}$  denotes the restriction operator onto the interval  $[t_1, t_2]$ , and the constant  $C(t_1, t_2, \tau_1, \tau_2)$  is independent of  $f$ , holds for norm (5) and the translation semigroup  $\{S(h)\}$  satisfies

$$\|S(h)f\|_{\mathcal{F}_{t_1-h, t_2-h}} = \|f\|_{\mathcal{F}_{t_1, t_2}}, \quad \forall f \in \mathcal{F}_{t_1, t_2}. \tag{7}$$

The space  $\mathcal{F}_{t_1, t_2}$  consists of functions  $f(s), s \in [t_1, t_2]$  such that  $f(s) \in E$  for almost all  $s \in [t_1, t_2]$ , where  $E$  is a Banach space.

Setting  $\mathcal{D}_{t_1, t_2} = L_q(t_1, t_2; \mathbf{H}^{-r})$ , we have that  $\mathcal{F}_{t_1, t_2} \subseteq \mathcal{D}_{t_1, t_2}$ , and if  $u(s) \in \mathcal{F}_{t_1, t_2}$ , then  $A(u(s)) \in \mathcal{D}_{t_1, t_2}$ . We can consider a weak solution of problem (1) as a solution of the equation in the general scheme of Section 3 from [10].

Define the spaces

$$\begin{aligned} \mathcal{F}_+^{\text{loc}} &= L_p^{\text{loc}}(\mathbb{R}_+; \mathbf{L}_p) \cap L_2^{\text{loc}}(\mathbb{R}_+; \mathbf{V}) \cap L_\infty^{\text{loc}}(\mathbb{R}_+; \mathbf{H}) \cap \left\{ v \left| \frac{\partial v}{\partial t} \in L_q^{\text{loc}}(\mathbb{R}_+; \mathbf{H}^{-r}) \right. \right\}, \\ \mathcal{F}_{\varepsilon, +}^{\text{loc}} &= L_p^{\text{loc}}(\mathbb{R}_+; \mathbf{L}_{p, \varepsilon}) \cap L_2^{\text{loc}}(\mathbb{R}_+; \mathbf{V}_\varepsilon) \cap L_\infty^{\text{loc}}(\mathbb{R}_+; \mathbf{H}_\varepsilon) \cap \left\{ v \left| \frac{\partial v}{\partial t} \in L_q^{\text{loc}}(\mathbb{R}_+; \mathbf{H}_\varepsilon^{-r}) \right. \right\}. \end{aligned}$$

We denote by  $\mathcal{K}_\varepsilon^+$  the set of all weak solutions of problem (1). Recall that for any  $U \in \mathbf{H}$ , there exists at least one trajectory  $u(\cdot) \in \mathcal{K}_\varepsilon^+$  such that  $u(0) = U(x)$ . Therefore, the trajectory space  $\mathcal{K}_\varepsilon^+$  of problem (1) is not empty and is sufficiently large.

It is clear that  $\mathcal{K}_\varepsilon^+ \subset \mathcal{F}_+^{\text{loc}}$  and the trajectory space  $\mathcal{K}_\varepsilon^+$  is translation-invariant; that is, if  $u(s) \in \mathcal{K}_\varepsilon^+$ , then  $u(h+s) \in \mathcal{K}_\varepsilon^+$  for all  $h \geq 0$ . Therefore,

$$S(h)\mathcal{K}_\varepsilon^+ \subseteq \mathcal{K}_\varepsilon^+, \quad \forall h \geq 0.$$

We now define metrics  $\rho_{t_1, t_2}(\cdot, \cdot)$  on the spaces  $\mathcal{F}_{t_1, t_2}$  using the norms of the spaces  $L_2(t_1, t_2; \mathbf{H})$ :

$$\rho_{0, M}(u, v) = \left( \int_0^M \|u(s) - v(s)\|^2 ds \right)^{1/2}, \quad \forall u(\cdot), v(\cdot) \in \mathcal{F}_{0, M}.$$

These metrics generate the topology  $\Theta_+^{\text{loc}}$  in  $\mathcal{F}_+^{\text{loc}}$  (respectively,  $\Theta_{\varepsilon,+}^{\text{loc}}$  in  $\mathcal{F}_{\varepsilon,+}^{\text{loc}}$ ). Recall that a sequence  $\{v_k\} \subset \mathcal{F}_+^{\text{loc}}$  converges to  $v \in \mathcal{F}_+^{\text{loc}}$  as  $k \rightarrow \infty$  in  $\Theta_+^{\text{loc}}$  if  $\|v_k(\cdot) - v(\cdot)\|_{L_2(0,M;\mathbf{H})} \rightarrow 0$  ( $k \rightarrow \infty$ ) for each  $M > 0$ . The topology  $\Theta_+^{\text{loc}}$  is metrizable using, for example, the Fréchet metric

$$\rho_+(f_1, f_2) := \sum_{m \in \mathbb{N}} 2^{-m} \frac{\rho_{0,m}(f_1, f_2)}{1 + \rho_{0,m}(f_1, f_2)}, \tag{8}$$

and the corresponding metric space is complete. We consider this topology in the trajectory space  $\mathcal{K}_\varepsilon^+$  of (1). The translation semigroup  $\{S(t)\}$  acting on  $\mathcal{K}_\varepsilon^+$  is continuous in the considered topology  $\Theta_+^{\text{loc}}$ .

Following the general scheme, we define bounded sets in  $\mathcal{K}_\varepsilon^+$  using the Banach space  $\mathcal{F}_+^b := \{f(s) \in \mathcal{F}_+^{\text{loc}} \mid \|f\|_{\mathcal{F}_+^b} < +\infty\}$ . We clearly have

$$\mathcal{F}_+^b = L_p^b(\mathbb{R}_+; \mathbf{L}_p) \cap L_2^b(\mathbb{R}_+; \mathbf{V}) \cap L_\infty(\mathbb{R}_+; \mathbf{H}) \cap \left\{ v \mid \frac{\partial v}{\partial t} \in L_q^b(\mathbb{R}_+; \mathbf{H}^{-r}) \right\}, \tag{9}$$

and  $\mathcal{F}_+^b$  is a subspace of  $\mathcal{F}_+^{\text{loc}}$ .

Consider the translation semigroup  $\{S(t)\}$  on  $\mathcal{K}_\varepsilon^+$ ,  $S(t) : \mathcal{K}_\varepsilon^+ \rightarrow \mathcal{K}_\varepsilon^+$ ,  $t \geq 0$ .

Let  $\mathcal{K}_\varepsilon$  be the kernel of problem (1), which consists of all weak complete solutions  $u(s)$ ,  $s \in \mathbb{R}$ , of the equation bounded in the space

$$\mathcal{F}^b = L_p^b(\mathbb{R}; \mathbf{L}_p) \cap L_2^b(\mathbb{R}; \mathbf{V}) \cap L_\infty(\mathbb{R}; \mathbf{H}) \cap \left\{ v \mid \frac{\partial v}{\partial t} \in L_q^b(\mathbb{R}; \mathbf{H}^{-r}) \right\}.$$

**Definition 2.1** ([8]). *A set  $\mathfrak{A} \subseteq \mathcal{K}^+$  is called the TRAJECTORY ATTRACTOR of the translation semigroup  $\{S(t)\}$  on  $\mathcal{K}^+$  in the topology  $\Theta_+^{\text{loc}}$  if (i)  $\mathfrak{A}$  is bounded in  $\mathcal{F}_+^b$  and compact in  $\Theta_+^{\text{loc}}$ , (ii) the set  $\mathfrak{A}$  is strictly invariant with respect to the semigroup  $S(t)\mathfrak{A} = \mathfrak{A}$  for all  $t \geq 0$ , and (iii)  $\mathfrak{A}$  is an attracting set for  $\{S(t)\}$  on  $\mathcal{K}^+$  in the topology  $\Theta_+^{\text{loc}}$ ; that is, for each  $M > 0$ ,*

$$\text{dist}_{\Theta_{0,M}}(\Pi_{0,M}S(t)\mathfrak{B}, \Pi_{0,M}\mathfrak{A}) \rightarrow 0 \quad (t \rightarrow +\infty).$$

Here, we assume that  $\Theta_{0,M} = L_2(0, M; \mathbf{H})$ .

**Proposition 2.2.** *Under hypotheses (2), problem (1) has the trajectory attractors  $\mathfrak{A}_\varepsilon$  in the topological space  $\Theta_+^{\text{loc}}$ . The set  $\mathfrak{A}_\varepsilon$  is uniformly (w.r.t.  $\varepsilon \in (0, 1)$ ) bounded in  $\mathcal{F}_+^b$  and compact in  $\Theta_+^{\text{loc}}$ . Moreover,*

$$\mathfrak{A}_\varepsilon = \Pi_+ \mathcal{K}_\varepsilon,$$

where the kernel  $\mathcal{K}_\varepsilon$  is non-empty and is uniformly (w.r.t.  $\varepsilon \in (0, 1)$ ) bounded in  $\mathcal{F}^b$ . Recall that the spaces  $\mathcal{F}_+^b$  and  $\Theta_+^{\text{loc}}$  depend on  $\varepsilon$ .

The proof of this proposition almost coincides with the proof given in [8] for a particular case. The existence of an absorbing set that is bounded in  $\mathcal{F}_+^b$  and compact in  $\Theta_+^{\text{loc}}$  is proved using Lemma 2.1 similarly to [8].

We note that

$$\mathfrak{A}_\varepsilon \subset \mathcal{B}_0(R), \quad \forall \varepsilon \in (0, 1),$$

where  $\mathcal{B}_0(R)$  is a ball in  $\mathcal{F}_+^b$  with a sufficiently large radius  $R$ . The Aubin–Lions–Simon lemma (see [11]) implies that

$$\mathcal{B}_0(R) \Subset L_2^{\text{loc}}(\mathbb{R}_+; \mathbf{H}^{1-\delta}), \quad \mathcal{B}_0(R) \Subset C^{\text{loc}}(\mathbb{R}_+; \mathbf{H}^{-\delta}), \quad 0 < \delta \leq 1. \tag{10}$$

Using compact inclusions (10), we strengthen the attraction to the constructed trajectory attractor.

**Corollary 2.2.** *For any set  $\mathfrak{B} \subset \mathcal{K}_\varepsilon^+$  bounded in  $\mathcal{F}_+^b$ , we have*

$$\begin{aligned} \text{dist}_{L_2(0,M;H^{1-\delta})}(\Pi_{0,M}S(t)\mathfrak{B}, \Pi_{0,M}\mathfrak{A}_\varepsilon) &\rightarrow 0 \quad (t \rightarrow \infty), \\ \text{dist}_{C([0,M];H^{-\delta})}(\Pi_{0,M}S(t)\mathfrak{B}, \Pi_{0,M}\mathfrak{A}_\varepsilon) &\rightarrow 0 \quad (t \rightarrow \infty), \end{aligned}$$

where  $M$  is an arbitrary positive number.

### 3. Homogenization of attractors to a problem for reaction–diffusion equations in perforated domain

In this section, we study the limit behavior of trajectory attractors  $\mathfrak{A}_\varepsilon$  of reaction–diffusion equations (1) as  $\varepsilon \rightarrow 0+$  and their relation to the trajectory attractor of the corresponding homogenized equation.

To define the “strange term” (the potential in the limit equation), we consider the following problem:

$$\begin{cases} -\Delta_y v = 0, & y \in \mathbb{R}^n \setminus G_0, \\ \frac{\partial v}{\partial \nu_y} + b(x, y)v = b(x, y), & y \in \partial G_0, \\ v \rightarrow 0, & |y| \rightarrow \infty. \end{cases}$$

In this problem, the variable  $x$  plays the role of slow parameter. The limit potential  $V(x)$  can be determined by the formula

$$V(x) = \int_{\partial G_0} \frac{\partial}{\partial \nu_y} v(x, y) \, d\sigma_y. \tag{11}$$

The homogenized (limit) problem reads as follows:

$$\begin{cases} \frac{\partial u}{\partial t} = \Delta u - f(u) - V(x)u + g(x), & x \in \Omega, \\ u = 0, & x \in \partial\Omega, \\ u = U(x), & t = 0. \end{cases} \tag{12}$$

Clearly, problem (12) also has a trajectory attractor  $\overline{\mathfrak{A}}$  in the trajectory space  $\overline{\mathcal{K}}^+$  corresponding to problem (12), and

$$\overline{\mathfrak{A}} = \Pi_+ \overline{\mathcal{K}},$$

where  $\overline{\mathcal{K}}$  is the kernel of problem (12) in  $\mathcal{F}^b$ .

Let us formulate the main theorem regarding the initial boundary value problem for a reaction–diffusion system.

**Theorem 3.1.** *The following limit holds in the topological space  $\Theta_+^{\text{loc}}$ :*

$$\mathfrak{A}_\varepsilon \rightarrow \overline{\mathfrak{A}} \quad \text{as } \varepsilon \rightarrow 0+. \tag{13}$$

Moreover,

$$\mathcal{K}_\varepsilon \rightarrow \overline{\mathcal{K}} \quad \text{as } \varepsilon \rightarrow 0+ \text{ in } \Theta^{\text{loc}}. \tag{14}$$

**Remark 2.** Recall that the spaces in the theorem depend on  $\varepsilon$ . All the functions can be continued inside the holes keeping the respective norms (see details in [12]).

The proof is based on the following. It is clear that (14) implies (13). Therefore, it is sufficient to prove (14); that is, for every neighborhood  $\mathcal{O}(\overline{\mathcal{K}})$  in  $\Theta^{\text{loc}}$ , there exists  $\varepsilon_1 = \varepsilon_1(\mathcal{O}) > 0$  such that

$$\mathcal{K}_\varepsilon \subset \mathcal{O}(\overline{\mathcal{K}}) \quad \text{for } \varepsilon < \varepsilon_1. \tag{15}$$

Suppose that (15) is not true. Then there exist a neighborhood  $\mathcal{O}'(\overline{\mathcal{K}})$  in  $\Theta^{\text{loc}}$ , a sequence  $\varepsilon_k \rightarrow 0+$  ( $k \rightarrow \infty$ ), and a sequence  $u_{\varepsilon_k}(\cdot) = u_{\varepsilon_k}(s) \in \mathcal{K}_{\varepsilon_k}$  such that

$$u_{\varepsilon_k} \notin \mathcal{O}'(\overline{\mathcal{K}}) \quad \text{for all } k \in \mathbb{N}. \tag{16}$$

The function  $u_{\varepsilon_k}(s)$ ,  $s \in \mathbb{R}$  is the solution to the problem

$$\begin{cases} \frac{\partial u_{\varepsilon_k}}{\partial t} = \Delta u_{\varepsilon_k} - f(u_{\varepsilon_k}) + g(x), & x \in \Omega_{\varepsilon_k}, \\ \frac{\partial u_{\varepsilon_k}}{\partial \nu} + \varepsilon_k^{n/(2-n)} b_{\varepsilon_k}^j(x) u_{\varepsilon_k} = 0, & x \in \partial G_{\varepsilon_k}^j, j \in \Upsilon_{\varepsilon_k}, \\ u_{\varepsilon_k} = 0, & x \in \partial\Omega, \end{cases} \tag{17}$$

on the whole time axis  $t \in \mathbb{R}$ . Now we prove the uniform estimate of the family of solutions (see [13] for such estimates). The  $\varepsilon$ -uniform estimate of the solution follows from the results in [14, Ch. III, §5] and [6]. More precisely, the sequence  $\{u_{\varepsilon_k}(s)\}$  is bounded in  $\mathcal{F}^b$ , that is,

$$\begin{aligned} \|u_{\varepsilon_k}\|_{\mathcal{F}^b} &= \sup_{t \in \mathbb{R}} \|u_{\varepsilon_k}(t)\| \\ &+ \sup_{t \in \mathbb{R}} \left( \int_t^{t+1} \|u_{\varepsilon_k}(s)\|_1^2 ds \right)^{1/2} + \sup_{t \in \mathbb{R}} \left( \int_t^{t+1} \|u_{\varepsilon_k}(s)\|_{L^p}^p ds \right)^{1/p} \\ &+ \sup_{t \in \mathbb{R}} \left( \int_t^{t+1} \left\| \frac{\partial u_{\varepsilon_k}}{\partial t}(s) \right\|_{\mathbf{H}^{-r}}^q ds \right)^{1/q} \leq C \quad \text{for all } k \in \mathbb{N}. \end{aligned} \tag{18}$$

Hence, there exists a subsequence  $\{u_{\varepsilon'_k}(s)\} \subset \{u_{\varepsilon_k}(s)\}$ , which we label the same, such that

$$u_{\varepsilon_k}(s) \rightharpoonup \bar{u}(s) \quad \text{as } n \rightarrow \infty \quad \text{in } \Theta^{\text{loc}}, \tag{19}$$

where  $\bar{u}(s) \in \mathcal{F}^b$  and  $\bar{u}(s)$  satisfies (18) with the same constant  $C$ . Due to (18), we have  $u_{\varepsilon_k}(s) \rightharpoonup \bar{u}(s)$  ( $n \rightarrow \infty$ ) weakly in  $L_2^{\text{loc}}(\mathbb{R}; \mathbf{V}_\varepsilon)$ , weakly in  $L_p^{\text{loc}}(\mathbb{R}; \mathbf{L}_{p,\varepsilon})$ , and  $*$ -weakly in  $L_\infty^{\text{loc}}(\mathbb{R}_+; \mathbf{H}_\varepsilon)$  and  $\partial u_{\varepsilon_k}(s)/\partial t \rightharpoonup \partial \bar{u}(s)/\partial t$  ( $k \rightarrow \infty$ ) weakly in  $L_{q,w}^{\text{loc}}(\mathbb{R}; \mathbf{H}_\varepsilon^{-r})$ . We claim that  $\bar{u}(s) \in \overline{\mathcal{K}}$ . We have already proved that  $\|\bar{u}\|_{\mathcal{F}^b} \leq C$ . Therefore, we have to establish that  $\bar{u}(s)$  is a weak solution to (12). Using (18), we obtain that

$$\frac{\partial u_{\varepsilon_k}}{\partial t} - \Delta u_{\varepsilon_k} - g(x) \longrightarrow \frac{\partial \bar{u}}{\partial t} - \Delta \bar{u} - g(x) \quad \text{as } k \rightarrow \infty \tag{20}$$

in the space  $D'(\mathbb{R}; \mathbf{H}_\varepsilon^{-r})$  because the derivative operators are continuous in the space of distributions.

Since the function  $f(v)$  is continuous with respect to  $v \in \mathbb{R}$ , we conclude that

$$f(u_{\varepsilon_k}(x, s)) \rightarrow f(\bar{u}(x, s)) \quad \text{as } k \rightarrow \infty \quad \text{a.e. in } (x, s) \in \Omega \times (-M, M). \tag{21}$$

Following [5, 15], we can prove the following statement.

**Lemma 3.2.** *We have*

$$\left| \varepsilon^{\frac{n}{n-2}} \sum_{j \in \Upsilon_\varepsilon} \int_{\partial G_\varepsilon^j} b_\varepsilon^j(x) \varphi ds - \int_\Omega V(x) \bar{\varphi} dx \right| \leq M\varepsilon \|\varphi\|_{\mathbf{H}_\varepsilon} \tag{22}$$

for  $\varphi \in \mathbf{H}_\varepsilon$ , and for all  $t$ ,

$$\varepsilon^{\frac{n}{n-2}} \sum_{j \in \Upsilon_\varepsilon} \int_{\partial G_\varepsilon^j} b_\varepsilon^j(x) u_\varepsilon \psi ds \longrightarrow \int_\Omega V(x) \bar{u} \psi dx \tag{23}$$

as  $\varepsilon \rightarrow 0$  for any  $\psi \in \mathcal{F}^b$ , where  $V(x)$  is defined in (11) and the constant  $M$  is independent of  $\varepsilon$ .

Using (20), (21), and (23) and passing to the limit in the equation of problem (17) as  $k \rightarrow \infty$  in the space  $D'(\mathbb{R}_+; \mathbf{H}^{-r})$ , we obtain that the function  $\bar{u}(x, s)$  satisfies the problem

$$\begin{cases} \frac{\partial \bar{u}}{\partial t} = \Delta \bar{u} - f(\bar{u}) - V(x) \bar{u} + g(x), & x \in \Omega, \\ \bar{u} = 0, & x \in \partial\Omega. \end{cases} \tag{24}$$



Consequently,  $\bar{u} \in \overline{\mathcal{K}}$ . We have proved above that  $u_{\varepsilon_k}(s) \rightarrow \bar{u}(s)$  as  $k \rightarrow \infty$  in  $\Theta^{\text{loc}}$ . The hypothesis  $u_{\varepsilon_k}(s) \notin \mathcal{O}'(\mathcal{K})$  implies that  $\bar{u} \notin \mathcal{O}'(\mathcal{K})$ ; moreover,  $\bar{u} \notin \overline{\mathcal{K}}$ . We arrive at a contradiction. The theorem is proved.

Using compact inclusions (10), we can strengthen convergence (13).

**Corollary 3.3.** *For every  $0 < \delta \leq 1$  and for any  $M > 0$ ,*

$$\text{dist}_{L_2([0,M];\mathbf{H}^{1-\delta})}(\Pi_{0,M}\mathfrak{A}_\varepsilon, \Pi_{0,M}\overline{\mathfrak{A}}) \rightarrow 0, \quad (25)$$

$$\text{dist}_{C([0,M];\mathbf{H}^{-\delta})}(\Pi_{0,M}\mathfrak{A}_\varepsilon, \Pi_{0,M}\overline{\mathfrak{A}}) \rightarrow 0 \quad (\varepsilon \rightarrow 0+). \quad (26)$$

To prove (25) and (26), we just repeat the proof of Theorem 3.1, replacing the topology  $\Theta^{\text{loc}}$  with  $L_2^{\text{loc}}(\mathbb{R}_+; \mathbf{H}^{1-\delta})$  or  $C^{\text{loc}}(\mathbb{R}_+; \mathbf{H}^{-\delta})$ .

Finally, we consider the reaction–diffusion equations for which the uniqueness theorem of the Cauchy problem is formulated. It is sufficient to assume that the nonlinear term  $f(u)$  in (1) satisfies the condition

$$(f(v_1) - f(v_2), v_1 - v_2) \geq -C|v_1 - v_2|^2 \quad \text{for } v_1, v_2 \in \mathbb{R} \quad (27)$$

(see [7, 8]). In [7], it was proved that if (27) holds, then (1) and (12) generate the dynamical semigroups in  $\mathbf{H}$ , which have the global attractors  $\mathcal{A}_\varepsilon$  and  $\overline{\mathcal{A}}$  bounded in the space  $\mathbf{V} = H_0^1(\Omega)$  (see also [9, 16]). We have

$$\mathcal{A}_\varepsilon = \{u(0) \mid u \in \mathfrak{A}_\varepsilon\}, \quad \overline{\mathcal{A}} = \{u(0) \mid u \in \overline{\mathfrak{A}}\}.$$

Convergence (26) implies the following corollary.

**Corollary 3.4.** *Under the assumptions of Theorem 3.1, the following limit holds:*

$$\text{dist}_{\mathbf{H}^{-\delta}}(\mathcal{A}_\varepsilon, \overline{\mathcal{A}}) \rightarrow 0 \quad (\varepsilon \rightarrow 0+).$$

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