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Probability Theory / *Probabilités*

# Gaussian lower bounds for the density via Malliavin calculus

*Bornes inférieures gaussiennes pour la densité par le  
calcul de Malliavin*

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**Abstract.** In this paper, based on a known formula, we use a simple idea to get a new representation for the density of Malliavin differentiable random variables. This new representation is particularly useful for finding lower bounds for the density.

**Résumé.** Dans cet article, à partir d'une formule connue, nous utilisons une idée simple pour obtenir une nouvelle représentation de la densité des variables aléatoires différentiables de Malliavin. Cette nouvelle représentation est particulièrement utile pour trouver des bornes inférieures de la densité.

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## 1. Introduction

In this paper, we use the techniques of Malliavin calculus to investigate the density of Malliavin differentiable random variables. In particular, we are going to focus on the problem of finding a Gaussian lower bound for the density. This problem was first discussed by Kusuoka & Stroock [3], and up to date, it is still a subject that is worth studying. In the last two decades, there have been several papers devoted to the study of densities by means of Malliavin calculus. Among others, we mention the works [4, 8] and the references therein for sufficient conditions for a random variable to have a density bounded from below. Another fruitful contribution is Nourdin & Viens' density formula ([6, Theorem 3.1]) that can be restated as follows.

**Proposition 1.** *Let  $F \in \mathbb{D}^{1,2}$  be such that  $E[F] = 0$ . We define the random variable*

$$G_F := \langle DF, -DL^{-1}F \rangle_{\mathfrak{H}} \tag{1}$$

*and the function  $g_F(x) := E[G_F|F = x]$ . Then, the law of  $F$  has a density  $\rho_F$  with respect to the Lebesgue measure if and only if  $g_F(F) > 0$  a.s. In this case  $\text{supp } \rho_F$  is a closed interval of  $\mathbb{R}$  containing 0 and we have, for almost all  $x \in \text{supp } \rho_F$ :*

$$\rho_F(x) = \frac{E|F|}{2g_F(x)} \exp\left(-\int_0^x \frac{z}{g_F(z)} dz\right). \tag{2}$$

The definition of the Malliavin derivative  $D$  and the operator  $L^{-1}$  will be given in Section 2. The formula (2) has been effectively applied to various stochastic equations (see e.g. [2] and the references therein). However, its use requires both lower and upper bounds of  $G_F$ . In fact, if  $\sigma_{\min}^2 \leq G_F \leq \sigma_{\max}^2$  a.s. then the density of  $F$  satisfies

$$\frac{E|F|}{2\sigma_{\max}^2} \exp\left(-\frac{x^2}{2\sigma_{\min}^2}\right) \leq \rho_F(x) \leq \frac{E|F|}{2\sigma_{\min}^2} \exp\left(-\frac{x^2}{2\sigma_{\max}^2}\right), \quad x \in \mathbb{R}.$$

The aim of the present paper is to answer the following question: Can we prove a Gaussian lower bound for the density if we only suppose that  $G_F \geq \sigma_{\min}^2$ ? (similarly, a Gaussian upper bound if  $0 < G_F \leq \sigma_{\max}^2$ ).

The rest of this article is organized as follows. In Section 2, we briefly recall some of the relevant elements of the Malliavin calculus. In Section 3, based on a density formula provided in [7], we use a simple idea to obtain a new representation formula for densities. As a consequence, under some additional assumptions, we are able to give an affirmative answer to the above question. In Section 4, we provide some examples to illustrate the applicability of our abstract results.

## 2. Malliavin Calculus

Let us recall some elements of Malliavin calculus that we need in order to perform our proofs (for more details see [7]). Suppose that  $\mathfrak{H}$  is a real separable Hilbert space with scalar product denoted by  $\langle \cdot, \cdot \rangle_{\mathfrak{H}}$ . We denote by  $W = \{W(h) : h \in \mathfrak{H}\}$  an isonormal Gaussian process defined in a complete probability space  $(\Omega, \mathcal{F}, P)$ ,  $\mathcal{F}$  is the  $\sigma$ -field generated by  $W$ . Let  $\mathcal{S}$  be the set of all smooth cylindrical random variables of the form

$$F = f(W(h_1), \dots, W(h_n)), \tag{3}$$

where  $n \in \mathbb{N}$ ,  $f \in C_b^\infty(\mathbb{R}^n)$  the set of bounded and infinitely differentiable functions with bounded partial derivatives,  $h_1, \dots, h_n \in \mathfrak{H}$ . If  $F$  has the form (3), we define its Malliavin derivative with respect to  $W$  as the element of  $L^2(\Omega, \mathfrak{H})$  given by

$$DF = \sum_{k=1}^n \frac{\partial f}{\partial x_k}(W(h_1), \dots, W(h_n)) h_k.$$

More generally, we can define the  $k$ th order derivative  $D^k F \in L^2(\Omega, \mathfrak{H}^{\otimes k})$  by iterating the derivative operator  $k$  times. For any integer  $k \geq 1$  and any  $p \geq 1$ , we denote by  $\mathbb{D}^{k,p}$  the closure of  $\mathcal{S}$  with respect to the norm

$$\|F\|_{k,p}^p := E|F|^p + \sum_{i=1}^k E\|D^i F\|_{\mathfrak{H}^{\otimes i}}^p.$$

An important operator in the Malliavin calculus theory is the divergence operator  $\delta$ , it is the adjoint of the derivative operator  $D$  characterized by

$$E\langle DF, u \rangle_{\mathfrak{H}} = E[F\delta(u)]$$

for any  $F \in \mathcal{S}$  and  $u \in L^2(\Omega, \mathfrak{H})$ . The domain of  $\delta$  is the set of all processes  $u \in L^2(\Omega, \mathfrak{H})$  such that

$$E|\langle DF, u \rangle_{\mathfrak{H}}| \leq C(u) \|F\|_{L^2(\Omega)},$$

where  $C(u)$  is some positive constant depending only on  $u$ . Let  $F \in \mathbb{D}^{1,2}$  and  $u \in \text{Dom } \delta$  such that  $Fu \in L^2(\Omega, \mathfrak{H})$ . Then  $Fu \in \text{Dom } \delta$  and we have the following relation

$$\delta(Fu) = F\delta(u) - \langle DF, u \rangle_{\mathfrak{H}}, \tag{4}$$

provided the right-hand side is square integrable.

It is known that any random variable  $F$  in  $L^2(\Omega, \mathcal{F}, P)$  can be expanded into an orthogonal sum of its Wiener chaos:

$$F = \sum_{n=0}^{\infty} J_n F,$$

where  $J_0 F = E(F)$  and  $J_n$  denotes the projection onto the  $n$ th Wiener chaos. From this chaos expansion one may define the Ornstein–Uhlenbeck operator  $L$  by  $LF = \sum_{n=0}^{\infty} -n J_n F$  when  $F \in \mathbb{D}^{2,2}$  and its pseudo-inverse by  $L^{-1}F = \sum_{n=1}^{\infty} -\frac{1}{n} J_n F$ . Note that, for any  $F \in L^2(\Omega)$ , we have  $L^{-1}F \in \text{Dom } L$  and  $LL^{-1}F = L^{-1}LF = F - E[F]$ . Moreover, the operators  $D, \delta$  and  $L$  satisfy the following relationship:  $F \in \text{Dom } L$  if and only if  $F \in \mathbb{D}^{2,2}$  and, in this case,

$$\delta DF = -LF. \tag{5}$$

### 3. Representation and lower bounds for the density

This section contains our abstract results, we first provide a representation formula for densities.

**Proposition 2.** *Let  $F \in \mathbb{D}^{1,2}$  and  $u : \Omega \rightarrow \mathfrak{H}$ , and suppose that  $\langle DF, u \rangle_{\mathfrak{H}} \neq 0$  a.s. and  $\frac{u}{\langle DF, u \rangle_{\mathfrak{H}}}$  belongs to the domain of  $\delta$ . Then the law of  $F$  has a continuous density given by*

$$\rho_F(x) = \rho_F(a) \exp\left(-\int_a^x w(z) dz\right), \quad x \in \text{supp } \rho_F, \tag{6}$$

where  $a$  is a point in the interior of  $\text{supp } \rho_F$  and

$$w(z) := E\left[\delta\left(\frac{u}{\langle DF, u \rangle_{\mathfrak{H}}}\right) \middle| F = z\right].$$

**Proof.** According to Exercise 2.1.3 in [7], the law of  $F$  has a continuous density given by

$$\rho_F(x) = E\left[\mathbf{1}_{\{F > x\}} \delta\left(\frac{u}{\langle DF, u \rangle_{\mathfrak{H}}}\right) \middle| F\right], \quad x \in \text{supp } \rho_F. \tag{7}$$

Note that the proof of (7) is similar to that of Proposition 2.1.1 in [7]. Since  $F \in \mathbb{D}^{1,2}$ , this implies that  $\text{supp } \rho_F$  is a closed interval of  $\mathbb{R}$  (see [7, Proposition 2.1.7]):  $\text{supp } \rho_F = [\alpha, \beta]$  with  $-\infty \leq \alpha < \beta \leq \infty$ . It follows from (7) that

$$\begin{aligned} \rho_F(x) &= E\left[\mathbf{1}_{\{F > x\}} E\left[\delta\left(\frac{u}{\langle DF, u \rangle_{\mathfrak{H}}}\right) \middle| F\right]\right] \\ &= E[\mathbf{1}_{\{F > x\}} w_F(F)] \\ &= \int_x^\beta w_F(y) \rho_F(y) dy. \end{aligned}$$

Let  $a$  be a point in the interior of  $\text{supp } \rho_F$ . Solving the above equation with initial condition  $\rho_F(a)$  gives us (6). This completes the proof.  $\square$

A general representation like the above conveys no meaning unless provided at least a way to use it. The following corollary provides such a way.

**Corollary 3.** Let  $F \in \mathbb{D}^{2,4}$  be such that  $E[F] = 0$  and  $G_F$  be the random variable defined by (1). Assume that  $G_F \neq 0$  a.s. and the random variables  $\frac{F}{G_F}$  and  $\frac{1}{G_F^2} \langle DG_F, -DL^{-1}F \rangle_{\mathfrak{H}}$  belong to  $L^2(\Omega)$ . Then the law of  $F$  has a continuous density given by

$$\rho_F(x) = \rho_F(0) \exp\left(-\int_0^x h_F(z) dz\right) \exp\left(-\int_0^x w_F(z) dz\right), \quad x \in \text{supp } \rho_F, \quad (8)$$

where the functions  $w_F$  and  $h_F$  are defined by

$$w_F(z) := E\left[\frac{F}{G_F} \middle| F = z\right], \quad h_F(z) := E\left[\frac{1}{G_F^2} \langle DG_F, -DL^{-1}F \rangle_{\mathfrak{H}} \middle| F = z\right].$$

**Proof.** Since  $E[F] = 0$ , this implies that  $\alpha < 0 < \beta$  and hence, we can take  $a = 0$  in Theorem 2. On the other hand, we choose  $u = -DL^{-1}F$ . By the relation (5) we have

$$\delta(u) = -\delta(DL^{-1}F) = LL^{-1}F = E - E[F] = F.$$

The conditions on  $F$  and  $G_F$  allow us to use the relation (4) and we obtain

$$\begin{aligned} \delta\left(\frac{u}{\langle DF, u \rangle_{\mathfrak{H}}}\right) &= \delta\left(\frac{u}{\langle DF, -DL^{-1}F \rangle_{\mathfrak{H}}}\right) \\ &= \delta\left(\frac{u}{G_F}\right) \\ &= \frac{\delta(u)}{G_F} + \frac{1}{G_F^2} \langle DG_F, u \rangle_{\mathfrak{H}} \\ &= \frac{F}{G_F} + \frac{1}{G_F^2} \langle DG_F, -DL^{-1}F \rangle_{\mathfrak{H}}. \end{aligned}$$

Hence, we obtain  $w(F) = w_F(F) + h_F(F)$ . Inserting this relation into (6) gives us (8). This completes the proof.  $\square$

We now are ready to provide Gaussian lower bounds for the density.

**Theorem 4.** Let  $F \in \mathbb{D}^{2,4}$  be such that  $E[F] = 0$ . Suppose that  $G_F \geq \sigma_{\min}^2$  a.s. for some deterministic constant  $\sigma_{\min} \neq 0$ . Then, the density of  $F$  exists and satisfies

$$\rho_F(x) \geq \rho_F(0) \exp\left(-\int_0^x h_F(z) dz\right) \exp\left(-\frac{x^2}{2\sigma_{\min}^2}\right), \quad x \in \mathbb{R}. \quad (9)$$

Moreover, if for some real number  $m_1$ ,  $h_F(F) \geq m_1$  a.s. then

$$\rho_F(x) \geq \rho_F(0) \exp\left(-\frac{x^2}{2\sigma_{\min}^2} - m_1 x\right), \quad x \leq 0. \quad (10)$$

If for some real number  $m_2$ ,  $h_F(F) \leq m_2$  a.s. then

$$\rho_F(x) \geq \rho_F(0) \exp\left(-\frac{x^2}{2\sigma_{\min}^2} - m_2 x\right), \quad x \geq 0. \quad (11)$$

If for some real number  $M > 0$ ,  $|h_F(F)| \leq M$  a.s. then

$$\rho_F(x) \geq \rho_F(0) \exp\left(-\frac{x^2}{2\sigma_{\min}^2} - M|x|\right), \quad x \in \mathbb{R}. \quad (12)$$

**Proof.** We first recall that the fact  $G_F \geq \sigma_{\min}^2$  implies  $\text{supp } \rho_F = \mathbb{R}$ , see [6, Corollary 3.3]. When  $x \geq 0$ , we have

$$\begin{aligned} -\int_0^x w_F(z) dz &\geq -\int_0^x E \left[ \frac{F}{\sigma_{\min}^2} \middle| F = z \right] dz \\ &= -\int_0^x \frac{z}{\sigma_{\min}^2} dz = -\frac{x^2}{2\sigma_{\min}^2}. \end{aligned}$$

Similarly, when  $x \leq 0$ , we also have

$$-\int_0^x w_F(z) dz = \int_x^0 E \left[ \frac{F}{G_F} \middle| F = z \right] dz \geq \int_x^0 E \left[ \frac{F}{\sigma_{\min}^2} \middle| F = z \right] dz = -\frac{x^2}{2\sigma_{\min}^2}.$$

Thus (9) is verified for all  $x \in \mathbb{R}$ . The proof of (10), (11) and (12) is straightforward, so we omit it.  $\square$

**Remark 5.** Similarly, if  $0 < G_F \leq \sigma_{\max}^2$  a.s. we also have an upper bound for the density that reads

$$\rho_F(x) \leq \rho_F(0) \exp \left( -\int_0^x h_F(z) dz \right) \exp \left( -\frac{x^2}{2\sigma_{\max}^2} \right), \quad x \in \text{supp } \rho_F.$$

However, because of appearance of  $G_F$  in the denominators, it will be non-trivial to check the square integrable property of  $\frac{F}{G_F}$  and  $\frac{1}{G_F} \langle DG_F, -DL^{-1}F \rangle_{\mathfrak{H}}$  and the boundedness of  $h_F$ . That is why we only provide lower bounds as in Theorem 4. To evaluate an upper bound, a popular method is to use the formula (7) with  $u = DF$ . The reader can consult Proposition 2.1.2 in [7] for such a evaluation.

**Remark 6.** If the random variable  $G_F$  satisfies  $\sigma_{\min}^2 \leq G_F \leq \sigma_{\max}^2$  a.s. the formula (8) will provide us lower and upper bounds for the density. However, in this case, we should use the formula (2) to get Gaussian estimates for the density because Proposition 1 only requires  $F \in \mathbb{D}^{1,2}$ .

We end up this section by providing a variant of density formula (8) which can be of interest for the readers who are not used to working with the Ornstein–Uhlenbeck operator. Let  $(W_t)_{t \in [0, T]}$  be a standard Brownian motion defined on a complete probability space  $(\Omega, \mathcal{F}, \mathbb{F}, P)$ , where  $\mathbb{F} = (\mathcal{F}_t)_{t \in [0, T]}$  is a natural filtration generated by  $W$ . Now Malliavin derivative operator is with respect to  $W$  and  $\mathfrak{H} = L^2[0, T]$ . We consider the stochastic process  $u_s := E[D_s F | \mathcal{F}_s]$ . Then, by the Clark–Ocone formula we have

$$\delta(u) = \int_0^T E[D_s F | \mathcal{F}_s] dW_s = F - E[F].$$

Hence, with the exact proof of Corollary 3, we obtain the following.

**Theorem 7.** Let  $F \in \mathbb{D}^{2,4}$  be such that  $E[F] = 0$ . Define the random variable

$$\Phi_F := \int_0^T D_s F E[D_s F | \mathcal{F}_s] ds.$$

Assume that  $\Phi_F \neq 0$  a.s. and the random variables  $\frac{F}{\Phi_F}$  and  $\frac{1}{\Phi_F^2} \int_0^T D_s \Phi_F E[D_s F | \mathcal{F}_s] ds$  belong to  $L^2(\Omega)$ . Then the law of  $F$  has a continuous density given by

$$\rho_F(x) = \rho_F(0) \exp \left( -\int_0^x \bar{h}_F(z) dz \right) \exp \left( -\int_0^x \bar{w}_F(z) dz \right), \quad x \in \text{supp } \rho_F, \tag{13}$$

where the functions  $\bar{w}_F$  and  $\bar{h}_F$  are defined by

$$\bar{w}_F(z) := E \left[ \frac{F}{\Phi_F} \middle| F = z \right], \quad \bar{h}_F(z) := E \left[ \frac{1}{\Phi_F^2} \int_0^T D_s \Phi_F E[D_s F | \mathcal{F}_s] ds \middle| F = z \right].$$

**Remark 8.** The conclusion of Theorem 4 still holds true if we replace  $G_F$  by  $\Phi_F$  and  $h_F$  by  $\bar{h}_F$ .

**Remark 9.** The following problem will be interesting to investigate: Find other choices for  $u$  in Proposition 2.

## 4. Examples

In this section, we provide some examples to illustrate the applicability of our abstract results.

### 4.1. Additive functional of Gaussian processes

Let  $(X_t)_{t \in [0, T]}$  be a centered Gaussian process with continuous paths. It is known from Section 3.2.2 in [6] that the Gaussian space generated by  $X$  can be identified with an isonormal Gaussian process of the type  $X = \{X(h) : h \in \mathfrak{H}\}$ , where the real and separable Hilbert space  $\mathfrak{H}$  is defined as follows:

- (i) denote by  $\mathcal{E}$  the set of all  $\mathbb{R}$ -valued step functions on  $[0, T]$ ,
- (ii) define  $\mathfrak{H}$  as the Hilbert space obtained by closing  $\mathcal{E}$  with respect to the scalar product

$$\langle \mathbb{1}_{[0, s]}, \mathbb{1}_{[0, t]} \rangle_{\mathfrak{H}} = E(X_s X_t).$$

In particular, with such a notation, we identify  $X_t$  with  $X(\mathbb{1}_{[0, t]})$ . We now consider the functional

$$Y_T := \int_0^T f(X_s) ds - \int_0^T E[f(X_s)] ds. \quad (14)$$

The density of  $Y_T$  has been discussed by Nourdin and Viens, see [6, Proposition 3.10]. In order to be able to obtain Gaussian estimates, they require the condition  $c \leq f'(x) \leq C$  for all  $x \in \mathbb{R}$  and for some  $C, c > 0$ . Our Theorem 4 allows us to address the case, where  $f'(x)$  is not bounded above, and we obtain the following.

**Theorem 10.** *Assume that  $E[X_s X_v] \geq 0$  for all  $s, v \in [0, T]$ , and  $f : \mathbb{R} \rightarrow \mathbb{R}$  is a twice differentiable function satisfying  $|f'(x)| \geq c$  for all  $x \in \mathbb{R}$ . Then, the random variable  $Y_T$  admits a density, which satisfies*

- (1) *If  $f''(x) \geq 0$  for all  $x \in \mathbb{R}$ , then*

$$\rho_{Y_T}(x) \geq \rho_{Y_T}(0) \exp\left(-\frac{x^2}{2c^2 \sigma_T^2}\right), \quad x \leq 0. \quad (15)$$

- (2) *If  $f''(x) \leq 0$  for all  $x \in \mathbb{R}$ , then*

$$\rho_{Y_T}(x) \geq \rho_{Y_T}(0) \exp\left(-\frac{x^2}{2c^2 \sigma_T^2}\right), \quad x \geq 0, \quad (16)$$

where  $\sigma_T^2 := \int_0^T \int_0^T E[X_s X_v] ds dv$ .

**Proof.** We only consider the case  $f'(x) \geq c$  for all  $x \in \mathbb{R}$  because the case  $f'(x) \leq -c$  can be treated similarly. The Malliavin derivative of  $Y_T$  with respect to  $X$  is given by

$$D_r Y_T = \int_0^T f'(X_s) \mathbb{1}_{[0, s]}(r) ds, \quad r \in [0, T].$$

Thanks to Proposition 3.7 in [6] we have

$$-D_r L^{-1} Y_T = \int_0^\infty e^{-u} \int_0^T E[f'(e^{-u} X_s + \sqrt{1 - e^{-2u}} X'_s)] \mathbb{1}_{[0, s]}(r) ds du, \quad r \in [0, T].$$

and

$$G_{Y_T} = \int_0^\infty e^{-u} \int_0^T \int_0^T f'(X_s) E[f'(e^{-u} X_v + \sqrt{1 - e^{-2u}} X'_v)] E[X_s X_v] ds dv du,$$

where  $X'$  stands for an independent copy of  $X$  and  $E'$  is the expectation with respect to  $X'$ . Hence, it holds that

$$\begin{aligned} G_{Y_T} &\geq \int_0^\infty e^{-u} \int_0^T \int_0^T c^2 E[X_s X_v] ds dv du \\ &= c^2 \int_0^T \int_0^T E[X_s X_v] ds dv = c^2 \sigma_T^2 \quad a.s. \end{aligned}$$

Furthermore, we have, for  $r, \theta \in [0, T]$ ,

$$\begin{aligned} D_\theta D_r Y_T &= \int_0^T f''(X_s) \mathbb{1}_{[0,s]}(r) \mathbb{1}_{[0,s]}(\theta) ds, \\ -D_\theta D_r L^{-1} Y_T &= \int_0^\infty e^{-2u} \int_0^T E'[f''(e^{-u} X_s + \sqrt{1 - e^{-2u}} X'_s)] \mathbb{1}_{[0,s]}(r) \mathbb{1}_{[0,s]}(\theta) ds du. \end{aligned}$$

Thus, if  $f''(x) \geq 0$  for all  $x \in \mathbb{R}$ , then  $D_\theta D_r Y_T \geq 0$  and  $-D_\theta D_r L^{-1} Y_T \geq 0$ . As a consequence, by its definition,  $h_F(F) \geq 0$  a.s. So (15) follows from (10).

Similarly, if  $f''(x) \leq 0$  for all  $x \in \mathbb{R}$ , then  $h_F(F) \leq 0$  a.s. and (16) follows from (11). This completes the proof.  $\square$

#### 4.2. SDEs with fractional noise

We consider stochastic differential equations driven by fractional Brownian motion of the form

$$X_t = x_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s^H, \quad t \in [0, T], \tag{17}$$

where  $x_0 \in \mathbb{R}$ ,  $B^H = (B^H)_{t \in [0, T]}$  is a fractional Brownian motion (fBm) of Hurst parameter  $H \in (\frac{1}{2}, 1)$  and the stochastic integral is interpreted as a pathwise Riemann–Stieltjes integral, see e.g. [9]. Recall that  $B^H$  is a centered Gaussian process and it admits the so-called Volterra representation (see e.g. [7, pp. 277–279])

$$B_t^H = \int_0^t K_H(t, s) dW_s, \tag{18}$$

where  $(W_t)_{t \in [0, T]}$  is a standard Brownian motion,

$$K_H(t, s) := c_H s^{1/2-H} \int_s^t (u-s)^{H-\frac{3}{2}} u^{H-1/2} du, \quad s \leq t$$

and  $c_H = \sqrt{\frac{H(2H-1)}{\beta(2-2H, H-1/2)}}$ , where  $\beta$  is the Beta function.

By different approaches, the density estimates for the solutions to the equation (17) have been recently obtained in [1, 5]. In both these two papers, the authors require  $c \leq |\sigma(t, x)| \leq C$  for all  $(t, x) \in [0, T] \times \mathbb{R}$  and for some  $C, c > 0$ . When  $H = \frac{1}{2}$ ,  $B^H$  reduces to a Brownian motion and in this case, Nualart [8, Theorem 2.3] only requires  $|\sigma(t, x)| \geq c$  to get a Gaussian lower bound. Here we are able to obtain such a similar result for the case  $H > \frac{1}{2}$ .

For a differentiable function  $f$ , we denote

$$f'_1(t, x) := \frac{\partial f}{\partial t}(t, x), \quad f'_2(t, x) := \frac{\partial f}{\partial x}(t, x).$$

**Lemma 11.** *Suppose that  $b, \sigma \in \mathcal{C}^{1,1}([0, T] \times \mathbb{R})$  and there exists a constants  $c > 0$  so that  $|\sigma(t, x)| \geq c$  for all  $(t, x) \in [0, T] \times \mathbb{R}$ . In addition, we assume that the function*

$$m(t, x) := \left( b'_2 - \frac{b\sigma'_2}{\sigma} - \frac{\sigma'_1}{\sigma} \right)(t, x)$$

*is bounded on  $[0, T] \times \mathbb{R}$ . Then, the Malliavin derivative of  $X_t$  with respect to Brownian motion  $W$  is given by*

$$D_s X_t = \sigma(t, X_t) \left( \int_s^t (K_H)'_1(v, s) \exp\left( \int_v^t m(u, X_u) du \right) dv \right) \mathbb{1}_{[0,t]}(s).$$



**Proof.** The proof is the same as that of Lemma 5.3 in [5]. Notice that the boundedness of  $m$  ensures that the equation (5.6) in [5] satisfies the global Lipschitz and linear growth conditions and hence, its solution is Malliavin differentiable.  $\square$

**Theorem 12.** *Suppose the assumption of Lemma 11. In addition, we assume that there exists  $M > 0$  so that  $|m(t, x)|, |m'_2(t, x)\sigma(t, x)|, |\sigma'_2(t, x)| \leq M$  for all  $(t, x) \in [0, T] \times \mathbb{R}$ . Then, for each  $t \in (0, T]$ , the density of  $X_t$  exists and*

$$\rho_{X_t}(x) \geq c_1 \exp\left(-\frac{(x - E[X_t])^2}{2c_2 t^{2H}}\right), \quad x \in \mathbb{R},$$

where  $c_1, c_2$  are positive constants.

**Proof.** We assume  $\sigma(t, x) \geq c$ , the case  $\sigma(t, x) \leq -c$  can be treated similarly. Thus we always have  $D_s X_t \geq 0$  a.s. For the simplicity, we write  $D_s X_t = \sigma(t, X_t)\varphi(t, s)$ , where

$$\varphi(t, s) := \left(\int_s^t (K_H)'_1(v, s) \exp\left(\int_v^t m(u, X_u) du\right) dv\right) \mathbb{1}_{[0, t]}(s).$$

We have

$$D_r \varphi(t, s) = \left(\int_s^t (K_H)'_1(v, s) \left(\int_v^t m'(u, X_u)\sigma(u, X_u)\varphi(u, r) du\right) dv \exp\left(\int_v^t m(u, X_u) du\right) dv\right) \mathbb{1}_{[0, t]}(s).$$

The boundedness of  $m$  yields

$$e^{-MT} K_H(t, s) \leq \varphi(t, s) \leq e^{MT} K_H(t, s), \quad 0 \leq s \leq t \leq T.$$

Since  $m'\sigma$  is bounded, this implies that  $|\int_v^t m'(u, X_u)\sigma(u, X_u)\varphi(u, r) du| \leq M \int_v^t e^{MT} K_H(u, r) du \leq MTe^{MT} K_H(t, r)$ , and hence,

$$|D_r \varphi(t, s)| \leq MTe^{MT} K_H(t, r)\varphi(t, s), \quad 0 \leq r, s \leq t \leq T.$$

We have

$$\begin{aligned} D_r D_s X_t &= \sigma'_2(t, X_t) D_r X_t \varphi(t, s) + \sigma(t, X_t) D_r \varphi(t, s) \\ &= \sigma'_2(t, X_t) \varphi(t, r) D_s X_t + \sigma(t, X_t) D_r \varphi(t, s) \end{aligned}$$

and

$$\begin{aligned} |D_r D_s X_t| &\leq Me^{MT} K_H(t, r) D_s X_t + \sigma(t, X_t) MTe^{MT} K_H(t, r) \varphi(t, s) \\ &= M(1 + T)e^{MT} K_H(t, r) D_s X_t, \quad 0 \leq r, s \leq t \leq T. \end{aligned}$$

Fixed  $t \in (0, T]$ . We now apply Theorem 7 to  $F := X_t - E[X_t]$ . We have

$$\begin{aligned} \Phi_F &= \int_0^t D_s X_t E[D_s X_t | \mathcal{F}_s] ds \\ &= \int_0^t \sigma(t, X_t) \varphi(t, s) E[\sigma(t, X_t) \varphi(t, s) | \mathcal{F}_s] ds \\ &\geq c^2 e^{-2MT} \int_0^t K_H^2(t, s) ds = c^2 e^{-2MT} t^{2H} \quad a.s. \end{aligned}$$

Furthermore, for  $0 \leq r \leq t$ ,

$$D_r \Phi_F = \int_0^t D_r D_s X_t E[D_s X_t | \mathcal{F}_s] ds + \int_0^t D_s X_t E[D_r D_s X_t | \mathcal{F}_s] \mathbb{1}_{[0, s]}(r) ds,$$

which leads us to

$$|D_r \Phi_F| \leq 2M(1 + T)e^{MT} K_H(t, r) \int_0^t D_s X_t E[D_s X_t | \mathcal{F}_s] ds = 2M(1 + T)e^{MT} K_H(t, r) \Phi_F.$$

Consequently, we deduce

$$\begin{aligned} \left| \int_0^t D_r \Phi_F E[D_r F | \mathcal{F}_r] dr \right| &\leq 2M(1+T)e^{MT} \int_0^t \Phi_F K_H(t,r) E[D_r F | \mathcal{F}_r] dr \\ &\leq 2M(1+T)e^{MT} \Phi_F \int_0^t e^{MT} \varphi(t,r) E[D_r F | \mathcal{F}_r] dr \\ &= 2M(1+T)e^{2MT} \Phi_F \int_0^t \frac{D_r X_t}{\sigma(t, X_t)} E[D_r F | \mathcal{F}_r] dr \\ &\leq \frac{2M(1+T)e^{2MT}}{c} \Phi_F^2 \quad a.s. \end{aligned}$$

Recalling the definition of  $\bar{h}_F$ , we obtain

$$|\bar{h}_F(F)| \leq \frac{2M(1+T)e^{2MT}}{c} \quad a.s.$$

So we can conclude that

$$\rho_F(x) \geq \rho_F(0) \exp\left(-\frac{x^2}{2c^2 e^{-2MT} t^{2H}} - \frac{2M(1+T)e^{2MT}}{c} |x|\right), \quad x \in \mathbb{R}.$$

Now it is easy to see that there exist positive constants  $c_1, c_2$  such that

$$\rho_F(x) \geq c_1 \exp\left(-\frac{x^2}{2c_2 t^{2H}}\right), \quad x \in \mathbb{R}.$$

This finishes the proof because  $\rho_{X_t}(x) = \rho_F(x - E[X_t])$ . □

**Remark 13.** A simple example verifying Theorem 12 is when  $b(t, x) = \sigma(t, x) = f(x)$ , where  $f \in \mathcal{C}^1(\mathbb{R})$  with bounded derivative and  $|f(x)| \geq c$  for all  $x \in \mathbb{R}$ .

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