

On a Class of Time-Fractional Continuous-State Branching Processes

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Abstract. We propose a class of non-Markov population models with continuous or discrete state space via a limiting procedure involving sequences of rescaled and randomly time-changed Galton–Watson processes. The class includes as specific cases the classical continuous-state branching processes and Markov branching processes. Several results such as the expressions of moments and the branching inequality governing the evolution of the process are presented and commented. The generalized Feller branching diffusion and the fractional Yule process are analyzed in detail as special cases of the general model.

KEYWORDS: continuous-state branching processes, time-change, subordinators

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1. Introduction

Since the seminal paper of Galton–Watson [24], branching structures are subject to intensive theoretical and applied researches. The most studied applications of branching phenomena concern population growth models. In this context, in 1958, M. Jiřina [9] introduced the so-called continuous-state branching processes (shortly CSBPs) that represent a general class of linear branching processes in which jumps of any finite size and a continuous state space are permitted (see also [15] and the references therein). The original definition of CSBPs is very similar to that of Lévy processes (with which they are linked by means of a random time change, the Lamperti transform). However, an

alternative definition, dating back to the work of J. Lamperti [12] considers CSBPs as limit processes of sequences of rescaled Galton–Watson processes (GWPs in the following) or Markov branching processes (see also [1, 5] for further references). Due to their simple definition, generalizations of the GWPs and CSBPs have arisen in several directions, leading for example to the introduction of population-size-dependent GWPs and CSBPs [10, 14], and controlled branching processes [21], where the independence of individuals’ reproduction is modified allowing dependence on the size of the current population. In this paper we aim to extend the definition of GWPs and CSBPs in a different direction. Indeed, the Markov property characterizing these processes, although is mathematically appealing, determines a limitation for their actual application; furthermore, non-Markov branching processes would present interesting mathematical properties that constitute a reason of study by itself. Here we introduce a general class of non-Markov population models characterized by persistent memory and constructed by means of a limiting procedure on a sequence of suitably rescaled Galton–Watson processes time-changed by a specific random process. In order to clarify our approach, we briefly recall how time-changes play a fundamental role in the definition of models for anomalous diffusion. We will take inspiration from them. Roughly speaking, the basic framework is the following. Take a standard Brownian motion, say $\{B(t), t \geq 0\}$, and an independent stable subordinator $d = \{D(t), t \geq 0\}$, that is a spectrally positive increasing Lévy process with stable unilateral probability density function. Define the inverse process to D as

$$\mathcal{E}(t) := \inf\{u > 0: D(u) > t\}, \quad t \geq 0.$$

Then, the time-changed process $\{B(\mathcal{E}(t)), t \geq 0\}$ is a non-Markov process with continuous sample paths and exhibiting a sub-diffusive behaviour. Furthermore, if $\mathbf{P}(B(\mathcal{E}(t)) \in dx)/dx = l(x, t)$ is the marginal probability density function of the time-changed Brownian motion, then $l(x, t)$ solves the fractional PDE

$$\partial_t^\beta l(x, t) = \frac{1}{2} \frac{\partial^2}{\partial x^2} l(x, t), \quad t \geq 0, x \in \mathbb{R}, \beta \in (0, 1).$$

The above operator acting on time is a non-local integro-differential operator called Džrbašjan–Caputo derivative (see Section 2 for prerequisites and specific information) and β is the stability parameter. The main consequence of the presence of the fractional derivative is that, due to non-locality, it furnishes the model with a long memory.

Hence, in this paper we build via a limiting procedure and specific time-changes a large class of processes with branching structure also exhibiting non-locality and long memory. This is actually carried out in Section 3.2. Specific cases of interest being part of this class are, amongst others, the generalized Feller branching diffusion and the fractional Yule process.

Due to the nature of the considered problem, the paper fits exactly in-between two classical topics of probability, namely population models (processes exhibiting a branching structure) and models for anomalous diffusion (frequently associated to fractional diffusion).

The paper is organized as follows: in Section 2 we introduce the notation and recall the basic definitions and properties that we use in the sequel; in Section 3 we define the time-changed processes both in the discrete and the continuous setting and we prove the scaling limit; in Section 4 we focus on the time-changed CSBPs with the proof of some properties and some examples.

2. Backgrounds

The aim of this section is to give a brief overview of the processes we are interested in. We recall the definition and some basic properties of GWPs and of CSBPs; in particular the branching property is of fundamental importance. Moreover, basic information on fractional calculus and fractional diffusion is also recalled.

2.1. From GWPs to CSBPs

GWPs are classical discrete-time branching processes, where each individual of a population reproduces independently and according to the same offspring distribution \mathbf{p} , see [2] for a complete introduction. Rigorously, given a probability measure \mathbf{p} on \mathbb{N} , a GWP $\{Z_n\}_{n \geq 0}$ with offspring distribution \mathbf{p} is the Markov chain such that, for all $n \geq 0$,

$$Z_{n+1} \stackrel{d}{=} \sum_{i=1}^{Z_n} \xi_i,$$

where ξ_i are i.i.d. random variables with common distribution \mathbf{p} . Let us indicate with $m = \sum_{k=0}^{\infty} kp(k)$ the first moment of the distribution of the offspring. It classifies GWPs into three classes: subcritical if $m < 1$, supercritical if $m > 1$ and critical if $m = 1$. The following characteristic feature of GWPs is the branching property. Let us call ${}_{(j)}Z$ the GWP starting with j individuals, i.e. ${}_{(j)}Z_0 = j$ almost surely. Then the GWP is the only discrete-time and discrete-space Markov process such that for all $j, k \geq 0$,

$${}_{(j+k)}Z \stackrel{d}{=} {}_{(j)}Z^{(1)} + {}_{(k)}Z^{(2)}, \quad (2.1)$$

where Z , $Z^{(1)}$ and $Z^{(2)}$ are independent GWPs with the same offspring distribution. From a modelling point of view, this property underlines the fact that each individual in the population reproduces independently from the others according to the same offspring distribution \mathbf{p} .

Since the seminal works of Jiřina and Lamperti [9, 11, 12], there has been interest in defining branching processes in a continuous state-space setting and in identifying them as scaling limits of GWPs. The simplest way to extend the definition of branching processes to describe the evolution in continuous time of a population with values in \mathbb{R}^+ is by means of the branching property. Indeed, we define the CSBPs as the continuous time-continuous space processes satisfying an analogue of the branching property (2.1) as follows. Rigorously, a stochastic process $X = \{X(t) : t \geq 0\}$ is a CSBP if it is a Markov process characterized by a family of transition kernels $\{P_t(x, dy), t \geq 0, x \in \mathbb{R}^+\}$ satisfying, for all $t > 0$ and $x, x' \in \mathbb{R}^+$ (see e.g. [11]),

$$P_t(x, \cdot) * P_t(x', \cdot) = P_t(x + x', \cdot).$$

Let $\mathbb{D}(\mathbb{R}^+)$ be the set of càdlàg functions defined on \mathbb{R}^+ with values on \mathbb{R}^+ , a CSBP is a random variable in $\mathbb{D}(\mathbb{R}^+)$. From now on we will consider $\mathbb{D}(\mathbb{R}^+)$ as a topological space endowed with the usual Skorokhod topology. For a complete description see [8]. Further, we denote by \mathbf{E}_x the expectation with respect to the law of the process X starting from the initial value $x \in \mathbb{R}^+$. Let us underline that CSBPs are characterized by their Laplace transform, i.e. for all $\lambda > 0$ we have

$$\mathbf{E}_x \left[e^{-\lambda X(t)} \right] = \int_0^\infty e^{-\lambda y} P_t(x, dy) = e^{-x \nu_t(\lambda)},$$

where $\nu_t(\lambda)$ is the unique nonnegative solution to the equation

$$\nu_t(\lambda) + \int_0^t \psi(\nu_s(\lambda)) ds = \lambda. \quad (2.2)$$

Here ψ can be written as

$$\psi(u) = bu + cu^2 + \int (e^{-zu} - 1 + zu)m(dz),$$

where $b \in \mathbb{R}$, $c \geq 0$ and m is a σ -finite measure on $(0, \infty)$ such that $\int (z \wedge z^2)m(dz) < \infty$. The function ψ is called the branching mechanism of the CSBP and, at the same time, it is the characteristic function of a Lévy process without negative jumps killed at the first time it becomes negative. This identifies a relationship between CSBPs and the latter class of Lévy processes that is known as Lamperti transform. Indeed, also the converse property holds true, i.e. the characteristic function ψ of every Lévy process without negative jumps and killed at zero is the branching mechanism of a CSBP (see [13, 22]). The branching mechanism ψ , in addition to the Lamperti transform, plays a role in classifying CSBPs in three categories: critical, subcritical and supercritical

processes. A CSBP is supercritical when $b < 0$, critical when $b = 0$ and subcritical when $b > 0$. Moreover, in [12] we see that the parameters of ψ appear in the explicit form of the first two moments of a CSBP X , that is

$$\begin{aligned} \mathbf{E}_x[X(t)] &= xe^{-bt}, \\ \mathbf{E}_x[X(t)^2] &= \begin{cases} x^2 + x\tilde{\beta}t, & b = 0, \\ x^2e^{-2bt} - \frac{\tilde{\beta}x}{b}(e^{-2bt} - e^{-bt}), & b \neq 0, \end{cases} \end{aligned} \tag{2.3}$$

where $\tilde{\beta} = (2c + \int_0^\infty u^2 m(du))$. Let us mention that, despite CSBPs in general have discontinuous sample paths, the Feller branching diffusion (introduced in [4]) which is a CSBP whose branching mechanism has the form $\psi(u) = bu + cu^2$, exhibits continuous sample paths.

Results on convergence of suitably rescaled sequences of GWPs to CSBPs appeared first in [12] and, subsequently, in several other papers such as [1, 5, 15]. In the following we briefly state the results and the approach. Consider a sequence of GWPs

$$Z^{(k)} = \{Z_n^{(k)}\}_{n \in \mathbb{N}}, \quad k = 1, 2, 3, \dots,$$

defined through their offspring distribution $p^{(k)}$. Define a sequence of positive integers $\{c_k\}_{k \in \mathbb{N}}$, tending to infinity, and the Markov process

$$\{X_k(t)\}_{t \geq 0} = \left\{ \frac{Z_{\lfloor kt \rfloor}^{(k)}}{c_k} \right\}_{t \geq 0}, \quad Z_0^{(k)} = c_k \quad \text{a.s.}, \tag{2.4}$$

where for each $y \in \mathbb{R}$ we denote with $\lfloor y \rfloor$ its integer part. If the sequence of processes $\{X_k\}_{k \geq 0}$ has a weak limit in the sense of finite-dimensional distributions, then this limit is a CSBP. This result is extended to convergence in the Skorokhod space $\mathbb{D}(\mathbb{R}^+)$ in [5]. Briefly, let μ_k be the probability measure on $\{-1/c_k, 0, 1/c_k, 2/c_k, \dots\}$ defined as follows: for all $n \in \mathbb{N}$,

$$\mu_k \left(\frac{n-1}{c_k} \right) = p^{(k)}(n),$$

and assume that there exists a measure μ such that $(\mu_k)^{*kc_k} \rightarrow \mu$, weakly as $k \rightarrow \infty$. Then the sequence of GWPs $Z^{(k)}$ with offspring distribution $p^{(k)}$ and normalized as in (2.4), has a weak limit as a sequence of random variables on $\mathbb{D}(\mathbb{R}^+)$; this limit, say X , is a CSBP with initial condition $X(0) = 1$ almost surely. Conversely, for every CSBP X there exists a sequence of GWPs $\{Z^{(k)}\}_{k \in \mathbb{N}}$ and a sequence of positive integers $\{c_k\}_{k \in \mathbb{N}}$ such that X is the limit of the sequence rescaled as in (2.4).

2.2. Random times and stable subordinators

Let us consider a sequence i.i.d. real positive random variables J_1, J_2, \dots representing for us a sequence of random waiting times. We define for all $n \geq 0$ the process $T_n := \sum_{i=1}^n J_i$. Its inverse, for all $t \geq 0$, is the renewal process

$$N_t := \max\{n \geq 0: T_n \leq t\}. \quad (2.5)$$

We assume now that these waiting times belong to the strict domain of attraction of a certain completely skewed stable random variable D with stability parameter $\beta \in (0, 1)$. Note that due to the extended central limit theorem there exists a sequence $\{b_n\}_{n \geq 0}$ such that the following convergence holds in distribution [17]:

$$b_n T_n \Rightarrow D.$$

As a consequence, the rescaled process $\{b_n T_{[nt]}\}_{t \geq 0}$ converges in $\mathbb{D}(\mathbb{R}^+)$ to the stable subordinator $\{D(t)\}_{t \geq 0}$ of parameter β , i.e. a Lévy process such that $D(t) \stackrel{d}{=} t^{1/\beta} D$ for all $t \geq 0$ and with Laplace transform

$$\mathbf{E}[e^{-sD(t)}] = \exp\{-s^\beta t\}, \quad s > 0.$$

Similarly, the scaling limit for the renewal process $\{N_t\}_{t \geq 0}$ is the hitting time process of $\{D(t)\}_{t \geq 0}$, that we define below. Indeed, let $\{\tilde{b}_n\}_{n \geq 0}$ be a regularly varying sequence with index β such that $\lim_{n \rightarrow \infty} n \tilde{b}_{[bn]} = 1$, then the following limit holds:

$$\left\{ \frac{N_{nt}}{\tilde{b}_n} \right\}_{t \geq 0} \Rightarrow \{\mathcal{E}(t)\}_{t \geq 0}, \quad (2.6)$$

where the process $\{\mathcal{E}(t)\}_{t \geq 0}$ is known as the inverse β -stable subordinator, defined as

$$\mathcal{E}(t) := \inf\{u > 0: D(u) > t\}, \quad t \geq 0.$$

The process $\{\mathcal{E}(t)\}_{t \geq 0}$ is a non-Markov process with non-decreasing continuous sample paths and plays a role in models of phenomena exhibiting long memory; for instance \mathcal{E} has a fundamental importance in the study of time-fractional subdiffusions [18]. Let us now denote by $h(u, t)$ the probability density function of the random variable $\mathcal{E}(t)$ for a fixed time $t \geq 0$. It is known that the Laplace transform of $h(u, t)$ w.r.t. variable t is

$$\mathcal{L}(h(u, t))(s) = s^{\beta-1} \exp\{-us^\beta\}, \quad s > 0. \quad (2.7)$$

Furthermore, the Laplace transform w.r.t. variable u reads

$$\mathbf{E}[e^{-\lambda \mathcal{E}(t)}] = E_\beta(-t\lambda^\beta), \quad \lambda > 0,$$

where $E_\nu(z)$ is the Mittag-Leffler function defined as the convergent series

$$E_\nu(x) = \sum_{r=0}^{\infty} \frac{x^r}{\Gamma(r\nu + 1)}, \quad x \in \mathbb{R}, \nu > 0. \tag{2.8}$$

Moreover, the dynamic of this process is driven by a fractional evolution, i.e. $h(\mathbf{u}, t)$ evolves according a governing equation involving a fractional derivative in the t variable and a first order derivative in the \mathbf{u} variable. This means that $h(\mathbf{u}, t)$, for all $t \geq 0$ and $\mathbf{u} > 0$, solves the fractional PDE

$$\partial_t^\beta h(\mathbf{u}, t) = -\partial_{\mathbf{u}} h(\mathbf{u}, t),$$

where ∂_t^β stands for the Džrbašjan–Caputo fractional derivative of order β which is defined as follows:

Definition 2.1 (Džrbašjan–Caputo derivative). Let $\alpha > 0$, $m = \lceil \alpha \rceil$, and $f \in AC^m(0, b)$. The Džrbašjan–Caputo derivative of order $\alpha > 0$ is defined as

$$\partial_t^\alpha f(t) = \frac{1}{\Gamma(m - \alpha)} \int_a^t (t - s)^{m-1-\alpha} \frac{d^m}{ds^m} f(s) ds. \tag{2.9}$$

3. Time fractional branching processes

Following the approach used in [16] to define time-fractional diffusions, we introduce in this section a time-changed GWP and we prove that there exists a certain scaling such that its limit is exactly a time-changed CSBP.

3.1. Time-changed GWPs

Let us consider a GWP Z , we want to define a GWP with random waiting times between successive generations. Further, let $\{J_1, J_2, \dots\}$ be a sequence of i.i.d. random variables. The time-changed GWP is defined as

$$Z_t := Z_{N_t}, \tag{3.1}$$

for all $t \geq 0$, where N_t , independent of Z , is the renewal process defined in (2.5). As soon as the waiting times $\{J_1, J_2, \dots\}$ are not exponentially distributed, the process $\{Z_t\}_{t \geq 0}$ is not a Markov process anymore. The following property holds.

Proposition 3.1 (Branching inequality). *We have, for all $j, k \in \mathbb{N}$ and all $\lambda \geq 0$,*

$$\mathbf{E}_{j+k} [e^{-\lambda Z_t}] \geq \mathbf{E}_j [e^{-\lambda Z_t}] \mathbf{E}_k [e^{-\lambda Z_t}]. \tag{3.2}$$

Proof. Let us consider the function

$$K_{j,k}(t) = \mathbf{E}_{j+k} [e^{-\lambda Z_t}] - \mathbf{E}_j [e^{-\lambda Z_t}] \mathbf{E}_k [e^{-\lambda Z_t}]. \tag{3.3}$$

By taking conditional expectation with respect to $N(t)$, we get

$$K_{j,k}(t) = \mathbf{E} [\mathbf{E}_{j+k} [e^{-\lambda Z_{N(t)}} | N(t)]] - \mathbf{E} [\mathbf{E}_j (e^{-\lambda Z_{N(t)}} | N(t))] \mathbf{E} [\mathbf{E}_k (e^{-\lambda Z_{N(t)}} | N(t))]. \tag{3.4}$$

Observe that $\mathbf{E}_x [\exp\{-\lambda Z_{N(t)}\} | N(t)]$ and $\mathbf{E}_y [\exp\{-\lambda Z_{N(t)}\} | N(t)]$ are positively correlated being functions of the same random variable $N(t)$. Indeed, if we denote by f the generating function of the GWP Z and f_n its n -th iterate, we know that we have

$$\begin{aligned} \mathbf{E}_x [e^{-\lambda Z_{N(t)}} | N(t)] &= f_{N(t)} (e^{-\lambda})^x; \\ \mathbf{E}_y [e^{-\lambda Z_{N(t)}} | N(t)] &= f_{N(t)} (e^{-\lambda})^y. \end{aligned}$$

Hence

$$K_{j,k}(t) = \text{Cov} (f_{N(t)} (e^{-\lambda})^j, f_{N(t)} (e^{-\lambda})^k).$$

Being positive powers of the same positive function of $N(t)$, positive correlation follows and we obtain the inequality (3.2). \square

Remark 3.1. In a GWP, when we start with an initial population $Z_0 = j + k$, the number of individuals Z_n in the n -th generation is the sum of two independent copies of the process with initial size equal to j and k respectively. By introducing a random time change between the generations, we create a positive correlation between the sizes of subgroups of a given initial population.

Remark 3.2. In the special case of deterministic time-change, that is when $\mathbb{P}(N_t = \mathfrak{l}) = 1$, with $g: \mathbb{N} \rightarrow \mathbb{N}$, $\mathfrak{l} = g(\lfloor t \rfloor)$ a suitable non decreasing function, the inequality (3.2) becomes the classical equality that expresses the branching property of GWPs, i.e.

$$\mathbf{E}_{j+k} [e^{-\lambda Z_t}] = \mathbf{E}_j [e^{-\lambda Z_t}] \mathbf{E}_k [e^{-\lambda Z_t}], \tag{3.5}$$

for all $j, k \in \mathbb{N}$ and all $\lambda \geq 0$.

3.2. Time-changed CSBP and scaling limit

Let us consider a CSBP X and an inverse β -stable subordinator \mathcal{E} independent of X . Consider the time-changed process

$$\mathcal{X}(t) := X(\mathcal{E}(t)),$$

for all $t \geq 0$. It is possible to show that there exists a sequence of time-changed GWPs $\{Z_t^{(n)}\}_{t \geq 0}$, such that, suitably rescaled, converges to the process $\{\mathcal{X}(t)\}_{t \geq 0}$ in $\mathbb{D}([0, \infty))$.

Theorem 3.1. *Let $\{X(t)\}_{t \geq 0}$ be a CSBP and $\{\mathcal{E}(t)\}_{t \geq 0}$ be the inverse of a β -stable subordinator, $\beta \in (0, 1]$, independent of $\{X(t)\}_{t \geq 0}$. Consider the process $\{\mathcal{X}(t) := X(\mathcal{E}(t))\}_{t \geq 0}$; there exists a sequence of time-changed GWPs $\{z_t^{(\tilde{b}_n)}\}_{t \geq 0}$ and two increasing sequences $\{\tilde{b}_n\}_{n \geq 0}$ and $\{c_n\}_{n \geq 0}$ with $\lim_{n \rightarrow \infty} \tilde{b}_n = \lim_{n \rightarrow \infty} c_n = \infty$, such that for $n \rightarrow \infty$*

$$\left\{ \begin{array}{l} z_{nt}^{(\tilde{b}_n)} \\ c_{\tilde{b}_n} \end{array} \right\}_{t \geq 0} \implies \{\mathcal{X}(t)\}_{t \geq 0}, \tag{3.6}$$

where the convergence is in $\mathbb{D}([0, \infty))$.

Proof. Consider J_1, J_2, \dots , i.i.d. waiting times in the domain of attraction of a stable law of index β , (see Section 2.2). Then there exists a sequence of positive real numbers $\{\tilde{b}_n\}$, diverging to infinity, such that the limit (2.6) holds. At the same time, we consider a sequence of GWPs $\{Z^{(k)}\}_{k \geq 0}$ such that (2.4) holds. Since the waiting times and the GWPs are independent, it follows that, for all $n \geq 0$,

$$\left(X_{\tilde{b}_n}(t), \frac{T(nt)}{b_n} \right) = \left(\frac{Z^{(\tilde{b}_n)}(\lfloor \tilde{b}_n t \rfloor)}{c_{\tilde{b}_n}}, \frac{T(nt)}{b_n} \right) \implies (X(t), D(t))$$

in the product space $\mathbb{D}([0, \infty)) \times \mathbb{D}([0, \infty))$, where $Z^{(k)}(0)/c_k \rightarrow x$, $X(t)$ is a CSBP with transition semigroup $P_t(x, \cdot)$ and $D(t)$ is the stable subordinator of parameter β . Let us write $\mathbb{D}_{\uparrow, u}(\mathbb{R}^+)$ for the subset of unbounded non decreasing càdlàg functions and $\mathbb{D}_{\uparrow\uparrow, u}(\mathbb{R}^+)$ for the subset of unbounded strictly increasing ones. We see that, for all $n \geq 0$, the pair

$$\left(\frac{Z^{(\tilde{b}_n)}(\lfloor \tilde{b}_n t \rfloor)}{c_{\tilde{b}_n}}, \frac{T(nt)}{b_n} \right)$$

belongs to the product space $\mathbb{D}(\mathbb{R}^+) \times \mathbb{D}_{\uparrow, u}(\mathbb{R}^+)$ and the limit $(X(t), D(t))$ belongs to $\mathbb{D}(\mathbb{R}^+) \times \mathbb{D}_{\uparrow\uparrow, u}(\mathbb{R}^+)$. Then, following the approach in [23], we define the function $\Psi: \mathbb{D}(\mathbb{R}^+) \times \mathbb{D}_{\uparrow, u}(\mathbb{R}^+) \rightarrow \mathbb{D}(\mathbb{R}^+) \times \mathbb{D}(\mathbb{R}^+)$ mapping $(x(t), d(t))$ to $(x(e(t)), t)$, where $e(t)$ is the inverse of $d(t)$. In general the function Ψ is not continuous, however, in our case, since the limit point $(X(t), D(t))$ actually belongs to $\mathbb{D}(\mathbb{R}^+) \times \mathbb{D}_{\uparrow\uparrow, u}(\mathbb{R}^+)$, as stated in [23, Proposition 2.3], the function Ψ is continuous at $(X(t), D(t))$. This implies that the following limit holds, where π_1 is the projection on the first coordinate,

$$\begin{aligned} \frac{z_{nt}^{(\tilde{b}_n)}}{c_{\tilde{b}_n}} &= X_{\tilde{b}_n}(N(nt)) = \pi_1 \left(\Psi \left(X_{\tilde{b}_n}(t), \frac{T(nt)}{b_n} \right) \right) \\ &\implies \pi_1 (\Psi(X(t), D(t))). \end{aligned}$$

This proves (3.6). □

4. Some properties of the time-fractional CSBP

In the previous section we have characterized the process $\{\mathcal{X}(t)\}_{t \geq 0}$ as the limit of a rescaled sequence of time-changed GWPs, where in the discrete case the time between two generations is substituted by random variables that produce a slowed-down dynamics. In the limit this is modeled by the inverse stable subordinator. We are now interested in capturing the main features of the time-changed process \mathcal{X} and in underlining the differences between it and the classical CSBP. Note that the tree structure underlying Markov branching processes and CSBPs, although randomly stretched and squashed, it is still a characterizing feature of the corresponding time-changed processes.

4.1. Branching property

Let us consider $\beta \in (0, 1]$. We expect the time-changed CSBP $\{\mathcal{X}(t)\}_{t \geq 0}$ to satisfy the classical branching property only when $\beta = 1$. Indeed, in general, it holds

$$\mathbf{E}_{x+y} [e^{-\lambda \mathcal{X}(t)}] \geq \mathbf{E}_x [e^{-\lambda \mathcal{X}(t)}] \mathbf{E}_y [e^{-\lambda \mathcal{X}(t)}] \tag{4.1}$$

and

$$\lim_{\beta \rightarrow 1} \mathbf{E}_{x+y} [e^{-\lambda \mathcal{X}(t)}] = \mathbf{E}_x [e^{-\lambda \mathcal{X}(t)}] \mathbf{E}_y [e^{-\lambda \mathcal{X}(t)}]. \tag{4.2}$$

Similarly to Section 3.1, this is based on the following:

$$\begin{aligned} & \mathbf{E}_{x+y} [e^{-\lambda \mathcal{X}(t)}] - \mathbf{E}_x [e^{-\lambda \mathcal{X}(t)}] \mathbf{E}_y [e^{-\lambda \mathcal{X}(t)}] \\ &= \mathbf{E} [\mathbf{E}_{x+y} (e^{-\lambda \mathcal{X}(\mathcal{E}(t))} \mid \mathcal{E}(t))] \\ & \quad - \mathbf{E} [\mathbf{E}_x (e^{-\lambda \mathcal{X}(\mathcal{E}(t))} \mid \mathcal{E}(t))] \mathbf{E} [\mathbf{E}_y (e^{-\lambda \mathcal{X}(\mathcal{E}(t))} \mid \mathcal{E}(t))] \\ &= \mathbf{E} [e^{-(x+y)\nu_{\mathcal{E}(t)}(\lambda)}] - \mathbf{E} [e^{-x\nu_{\mathcal{E}(t)}(\lambda)}] \mathbf{E} [e^{-y\nu_{\mathcal{E}(t)}(\lambda)}] \\ &= \text{Cov}(e^{-x\nu_{\mathcal{E}(t)}(\lambda)}, e^{-y\nu_{\mathcal{E}(t)}(\lambda)}). \end{aligned}$$

Then, by positive correlation, we see that

$$\text{Cov}(\exp\{-x\nu_{\mathcal{E}(t)}(\lambda)\}, \exp\{-y\nu_{\mathcal{E}(t)}(\lambda)\}) \geq 0.$$

Moreover, since $\mathcal{E}(t) \rightarrow t$ in distribution as $\beta \rightarrow 1$, by dominated convergence and the continuity of $\nu_t(\lambda)$ in t (which is a consequence of (2.2)), we see that

$$\lim_{\beta \rightarrow 1} \text{Cov}(\exp\{-x\nu_{\mathcal{E}(t)}(\lambda)\}, \exp\{-y\nu_{\mathcal{E}(t)}(\lambda)\}) = 0,$$

proving (4.2). Note that the random time-change introduces a positive correlation between the evolution of the subgroups of the initial population that is not present in the classical CSBP. However, for any $\beta \in (0, 1)$, we still have a conditional branching property, i.e.

$$\mathbf{E} [\mathbf{E}_{x+y} [e^{-\lambda \mathcal{X}(\mathcal{E}(t))} \mid \mathcal{E}(t)]] = \mathbf{E} [\mathbf{E}_x [e^{-\lambda \mathcal{X}(\mathcal{E}(t))} \mid \mathcal{E}(t)] \mathbf{E}_y [e^{-\lambda \mathcal{X}(\mathcal{E}(t))} \mid \mathcal{E}(t)]].$$

4.2. First and second moment

Here we obtain the expression for the first and the second moment of the process $\{\mathcal{X}(t)\}$, when they exist. To this aim, we exploit the computations in [12] for the explicit formula of first and second moment of a CSBP, see equation (2.3), and the properties of the Mittag–Leffler function defined in (2.8), see [3].

Theorem 4.1. *Let $\{X(t)\}_{t \geq 0}$ be a CSBP with Laplace exponent $v_t(\lambda)$ and branching mechanism $\psi(z)$ and let $\{\mathcal{E}(t)\}_{t \geq 0}$ be an inverse stable subordinator with index $\beta \in (0, 1)$ and with density function $h(\cdot, t)$, for every fixed time $t \geq 0$. If $\partial v_t(0^+)/\partial \lambda$ exists and is finite and $\psi'(0^+) = b \geq \sigma_h$, where σ_h is the abscissa of convergence for the Laplace transform of the function $h(\cdot, t)$, then the time-changed process $\{\mathcal{X}(t)\}_{t \geq 0}$ has finite first moment that takes the form*

$$\mathbf{E}_x[\mathcal{X}(t)] = xE_\beta(-bt^\beta), \quad t \geq 0. \tag{4.3}$$

Proof. For the independence of $\{\mathcal{E}(t)\}_{t \geq 0}$ from $\{X(t)\}_{t \geq 0}$, together with the formula for the first moment of a CSBP, we get

$$\mathbf{E}_x[\mathcal{X}(t)] = \int_0^\infty \mathbf{E}_x[X(u)]h(u, t)du = \int_0^\infty xe^{-bu}h(u, t)du. \tag{4.4}$$

Since $b \geq \sigma_h$ the last integral is finite and it is essentially the Laplace transform of $h(u, t)$ with respect to the variable u . To obtain an explicit form of the integral, we apply again the Laplace transform to (4.4), this time with respect to the variable t , obtaining

$$\mathcal{L}[\mathbf{E}_x[\mathcal{X}(\cdot)]](\mu) = x \int_0^\infty e^{-bu} \int_0^\infty e^{-\mu t} h(u, t) dt du.$$

Formula (2.7) leads to

$$\mathcal{L}[\mathbf{E}_x[\mathcal{X}(\cdot)]](\mu) = x\mu^{\beta-1} \int_0^\infty e^{-u(b+\mu^\beta)} du = x \frac{\mu^{\beta-1}}{\mu^\beta + b}.$$

Since the latter expression is the Laplace transform of the Mittag–Leffler function $E_\beta(-bt^\beta)$ we immediately obtain formula (4.3). □

Theorem 4.2. *Let $\{X(t)\}_{t \geq 0}$ be a CSBP with Laplace exponent $v_t(\lambda)$ and branching mechanism $\psi(z)$ and let $\{\mathcal{E}(t)\}_{t \geq 0}$ be an inverse stable subordinator with index $\beta \in (0, 1)$ and with density function $h(\cdot, t)$ for every fixed time $t \geq 0$. If $\partial v_t(0^+)/\partial \lambda$ and $\partial^2 v_t(0^+)/\partial \lambda^2$ exist and are finite and $\psi'(0^+) = b \geq \sigma_h$ as in*

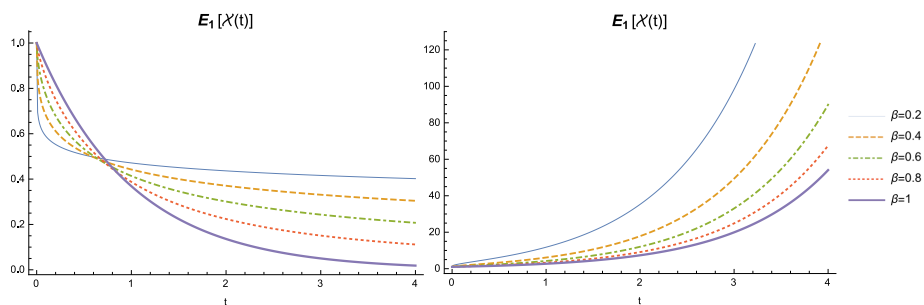


Figure 1. Plots of the first moment $\mathbf{E}_1[\mathcal{X}(t)]$ of a time-changed CSBP for $t \in [0, 4]$ and different values of β , from 0.2 to 1. The time-changed CSBP has initial condition $\mathcal{X}(0) = 1$ a.s.; on the left the subcritical case with $b = 1$, and on the right the supercritical case with $b = -1$.

Theorem 4.1, then the time-changed process $\{\mathcal{X}(t)\}_{t \geq 0}$ has the following finite second moment:

$$\mathbf{E}_x [\mathcal{X}(t)^2] = \begin{cases} x^2 + x\tilde{\beta} \frac{\Gamma(2)}{\Gamma(\beta+1)} t^\beta, & b = 0, \\ x^2 \mathbf{E}_\beta(-2bt^\beta) - \frac{\tilde{\beta}x}{b} (\mathbf{E}_\beta(-2bt^\beta) - \mathbf{E}_\beta(-bt^\beta)), & b \neq 0, \end{cases} \quad (4.5)$$

where $\tilde{\beta} = (2c + \int_0^\infty u^2 m(du))$.

Proof. Fix $t \geq 0$, we divide the proof into two different cases.

- Case $b = 0$: We know that

$$\begin{aligned} \mathbf{E}_x [\mathcal{X}(t)^2] &= \mathbf{E} [\mathbf{E}_x [X(\mathcal{E}(t))^2 | \mathcal{E}(t)]] \\ &= \int_0^\infty (x^2 + x\tilde{\beta}u) h(u, t) du = x^2 + x\tilde{\beta} \mathbf{E}[\mathcal{E}(t)]. \end{aligned}$$

It is known, see [16], Corollary 3.1, that the first moment of the process $\{\mathcal{E}(t)\}_{t \geq 0}$, for a fixed time $t \geq 0$, takes the form

$$\mathbf{E} [(\mathcal{E}(t))] = \frac{\Gamma(2)t^\beta}{\Gamma(\beta + 1)}.$$

Hence we obtain

$$\mathbf{E}_x [\mathcal{X}(t)^2] = x^2 + x\tilde{\beta} \frac{\Gamma(2)t^\beta}{\Gamma(\beta + 1)}.$$

- Case $b \neq 0$: In this case we write

$$\begin{aligned} \mathbf{E}_x [\mathcal{X}(t)^2] &= \int_0^\infty \left(x^2 e^{-2bu} - \frac{\tilde{\beta}x}{b} (e^{-2bu} - e^{-bu}) \right) h(u, t) du \\ &= x^2 \mathbf{E}_\beta(-2bt^\beta) - \frac{\tilde{\beta}x}{b} (\mathbf{E}_\beta(-2bt^\beta) - \mathbf{E}_\beta(-bt^\beta)). \end{aligned}$$

□

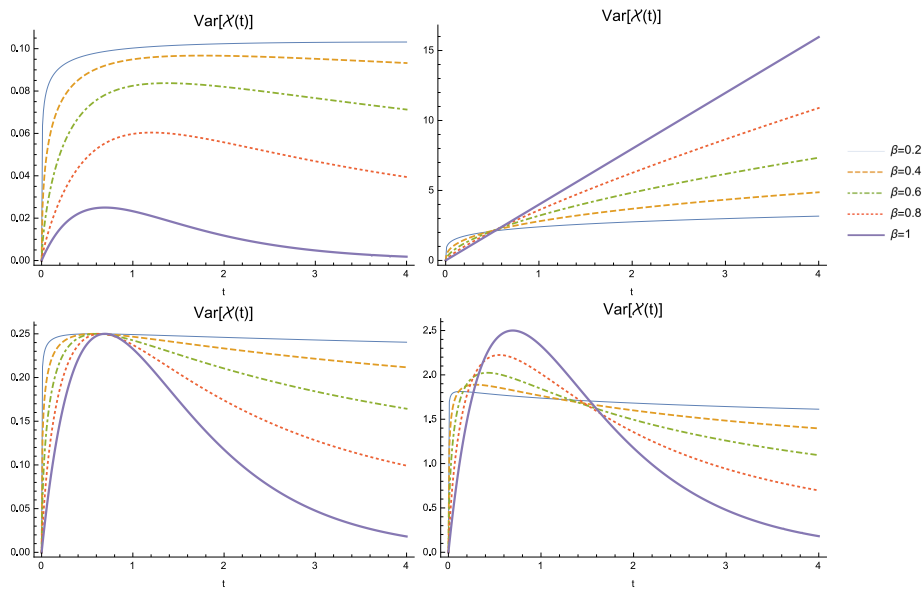


Figure 2. Plots of $\text{Var}(\mathcal{X}(t))$ for $t \in [0, 4]$ and β from 0.2 to 1. The time-changed CSBP has initial condition $\mathcal{X}(0) = 1$ a.s. and the pair of parameters $(b, \tilde{\beta})$, clockwise from the upper-left, equal to $(1, 0.1)$, $(1, 0.5)$, $(1, 10)$ and $(0, 1)$, respectively.

Note that the Mittag–Leffler function is a generalization of the exponential function, with which it coincides for $\beta = 1$. Comparing the moments of our generalized model, in (4.3) and (4.5), to those of the CSBP in (2.3), it is easy to see that the Mittag–Leffler function in the generalized case plays the same role as the exponential in the classical case. See in Figure 1 and Figure 2 the effect of the time-change on the mean and variance of the process \mathcal{X} .

4.3. Some examples

In the previous sections we have described in full generality the time-changed CSBP $\{\mathcal{X}(t)\}_{t \geq 0}$, now let us focus on some specific cases of interest in order to better illustrate our framework.

4.3.1. Time-changed Feller branching diffusion

Consider the Feller branching diffusion [4] and recall that it is the diffusion process solving the SDE

$$dX_t = -bX_t dt + \sqrt{2cX_t} dW_t \quad (4.6)$$

where W_t is a standard Brownian motion, $b \in \mathbb{R}$ and $c > 0$. This is the only diffusion process in the class of CSBPs and its corresponding Fokker–Planck equation is

$$\frac{\partial}{\partial t} p(y, t) = \frac{\partial}{\partial y} (byp(y, t)) + \frac{\partial^2}{\partial y^2} (cyp(y, t)).$$

The scaling limit of GWPs that leads to Feller branching diffusion is well-known, see Pardoux [20] for a nice review on it; this is one of the few cases in which this scaling scheme is known explicitly.

Consider thus a time-changed Feller branching diffusion $\{\mathcal{X}(t)\}_{t \geq 0}$ with stability parameter $\beta \in (0, 1)$. Since the process $\{X(t)\}_{t \geq 0}$ is a diffusion, its composition with $\{\mathcal{E}(t)\}_{t \geq 0}$ fits in the framework of SDE driven by time-changed Lévy processes, see [6]. Therefore, it is possible to write an analogue of the Fokker–Planck equation solved by the marginal probability density function $m_x(y, t)$ of $\{\mathcal{X}(t)\}_{t \geq 0}$. The following proposition shows that the equation involves Džrbašjan–Caputo derivatives of order $\beta \in (0, 1)$, hence it classifies the time-changed Feller branching diffusion in the class of subdiffusions.

Proposition 4.1. *Let $\{\mathcal{X}(t)\}_{t \geq 0}$ be a time-changed Feller branching diffusion with branching mechanism $\psi(u) = bu + cu^2$, for $b \in \mathbb{R}$ and $c > 0$ and parameter $\beta \in (0, 1)$. Let $\mathcal{X}(0) = x > 0$ a.s. and $m_x(y, t)$ be the marginal probability density function of $\mathcal{X}(t)$, for all $t \geq 0$. Then $m_x(y, t)$ satisfies the equation*

$$\partial_t^\beta m_x(y, t) = \frac{\partial}{\partial y} (bym_x(y, t)) + \frac{\partial^2}{\partial y^2} (cym_x(y, t)),$$

where ∂_t^β is the Džrbašjan–Caputo derivative.

Moreover, note that it is possible to write explicitly the SDE solved by the process $\{\mathcal{X}(t)\}_{t \geq 0}$. Let $(\Omega, \mathcal{F}, \mathbb{G} = \{\mathcal{G}_t\}_{t \geq 0}, \mathbf{P})$ be a filtered probability space and let $\mathbf{D} = \{\mathbf{D}(t)\}_{t \geq 0}$ be a \mathbb{G} -adapted stable subordinator of parameter $\beta \in (0, 1)$. Furthermore, let $\mathbb{F} = \{\mathcal{F}_t\}_{t \geq 0}$ be the filtration defined by means of time-change

with the process $\{\mathcal{E}(t)\}_{t \geq 0}$, inverse of D , such that, for all $t \geq 0$, $\mathcal{F}_t = \mathcal{G}_{\mathcal{E}(t)}$ (see [7], page 312). Consider the filtered space $(\Omega, \mathcal{F}, \mathbb{F}, \mathbf{P})$ and suppose $\{X(t)\}_{t \geq 0}$ is a \mathbb{G} -adapted Feller branching diffusion. Then the process $\{X(t)\}_{t \geq 0}$ is solution of the SDE

$$dX(t) = -bX(t)d\mathcal{E}(t) + \sqrt{2cX(t)}dW_{\mathcal{E}(t)},$$

where $\{W_{\mathcal{E}(t)}\}_{t \geq 0}$ is an \mathbb{F} -adapted time-changed Brownian motion, also known as grey Brownian motion.

4.3.2. Time-changed Yule process

Let us consider a homogeneous Poisson process $\{Y(t)\}_{t \geq 0}$ with rate $\theta > 0$ and shifted upwards by 1. By relation (2.2), it is transformed into a CSBP $\{X(t)\}_{t \geq 0}$ with Laplace exponent

$$\nu_t(\lambda) = \log(1 - (1 - e^\lambda)e^{\theta t}), \quad t \geq 0, \lambda \geq 0.$$

This is the Laplace exponent of a Yule process $\{X(t)\}_{t \geq 0}$, that is a pure birth process with linear birth rate. If $X(0)$ is supported on the strictly positive integers, then the law of X at every time $t \geq 0$ is a probability measure $\{p(\cdot, t)\}$ satisfying

$$\frac{\partial}{\partial t} p(n, t) = \theta(n - 1)p(n - 1, t) - \theta n p(n, t), \quad n \geq 1.$$

The time-changed Yule process $\{X(t)\}_{t \geq 0}$ is studied in [19], where amongst other properties it is proved that for each $t \geq 0$ its law is a probability measure $p_\beta(\cdot, t)$ that satisfies the time-fractional difference-differential equations

$$\partial_t^\beta p_\beta(n, t) = \theta(n - 1)p_\beta(n - 1, t) - \theta n p_\beta(n, t), \quad n \geq 1,$$

and whose explicit form is

$$p_\beta(n, t) = \sum_{j=1}^n \binom{n-1}{j-1} (-1)^{j-1} E_\beta(-\theta j t^\beta), \quad n \geq 1,$$

that is consistent with our results in Section 4.2.

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